Central compact objects and the hidden magnetic field scenario

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ABSTRACT

Central compact objects (CCOs) are X-ray sources lying close to the centre of supernova remnants, with inferred values of the surface magnetic fields significantly lower ($\leq 10^{11}$ G) than those of standard pulsars. In this paper, we revise the hidden magnetic field scenario, presenting the first 2D simulations of the submergence and re-emergence of the magnetic field in the crust of a neutron star. A post-supernova accretion stage of about 10^{-4} – 10^{-3} M_☉ over a vast region of the surface is required to bury the magnetic field into the inner crust. When accretion stops, the field re-emerges on a typical time-scale of 1–100 kyr, depending on the submergence conditions. After this stage, the surface magnetic field is restored close to its birth values. A possible observable consequence of the hidden magnetic field is the anisotropy of the surface temperature distribution, in agreement with observations of several of these sources. We conclude that the hidden magnetic field model is viable as an alternative to the antimagnetar scenario, and it could provide the missing link between CCOs and the other classes of isolated neutron stars.

Key words: stars: magnetic field – stars: neutron – pulsars: general.

1 INTRODUCTION

The handful of reported central compact objects (CCOs) form a class of X-ray sources (see de Luca 2008; Halpern & Gotthelf 2010 for recent reviews), located close to the centre of \sim kyr old supernova (SN) remnants. CCOs are supposed to be young, isolated, radio-quiet neutron stars (NSs). They show very stable, thermal-like spectra, with hints of temperature anisotropies, in terms of large pulsed fraction, or small emitting regions for hot (0.2–0.4 keV) blackbody components.

The period is known for only three cases: P = 424 ms for 1E 1207.4–5209 in G296.5+10.0 (Zavlin et al. 2000), P = 112 ms for RX J0822.0–4300 in Puppis A (Gotthelf & Halpern 2009) and P = 105 ms for CXOU J185238.6+004020 in Kes 79 (Gotthelf, Halpern & Seward 2005) (hereafter 1E 1207, Puppis A and Kes 79, respectively). For Kes 79, Halpern & Gotthelf (2010) reported a period derivative of $\dot{P} \simeq 8.7 \times 10^{-18}$ ss⁻¹; for 1E 1207, Halpern & Gotthelf (2011) gave two equally good timing solutions, with $\dot{P} = 2.23 \times 10^{-17}$ and 1.27×10^{-16} ss⁻¹. Only an upper limit $\dot{P} < 3.5 \times 10^{-16}$ ss⁻¹ is available for the CCO in Puppis A (Gotthelf, Perna & Halpern 2010; de Luca et al. 2012). Applying the classical dipole-braking formula gives an estimate for the dipolar component of the *external* magnetic field (MF) of $B_p \sim 10^{10}-10^{11}$ G (at the pole). This low value has led to the interpretation of CCOs as 'antimagnetars', i.e. NSs born with very low MFs, which have

not been amplified by dynamo action due to their slow rotation at birth (Bonanno, Urpin & Belvedere 2005).

An alternative scenario to the 'antimagnetar' model that explains the low values of B_p is to consider the fallback of the debris of the SN explosion on to the newborn NS. During a time interval of few months after the explosion, it accretes material from the reversed shock at a rate far superior than Eddington limit (Colgate 1971; Blondin 1986; Chevalier 1989; Houck & Chevalier 1991; Colpi, Shapiro & Wasserman 1996). This episode of hypercritical accretion could bury the MF into the NS crust, resulting in an external MF (responsible for the spin-down of the star) much lower than the internal 'hidden' MF.

When accretion stops, the screening currents localized in the outer crust are dissipated on Ohmic time-scales and the MF eventually re-emerges. The process of re-emergence has been explored in past pioneer works (Muslimov & Page 1995; Young & Chanmugam 1995; Geppert, Page & Zannias 1999) with simplified 1D models and always restricted to dipolar fields. It was found that, depending on the depth at which the MF is submerged (the submergence depth), MF diffuses back to the surface on radically different time-scales of $10^3 - 10^{10}$ yr. Thus, the key issue is to understand the submergence process and how deep one can expect to push the field during the accretion stage. This latter issue has only been studied (also in 1D and for dipolar fields) by Geppert et al. (1999) in the context of Supernova 1987A. They concluded that the submergence depth depends essentially on the total accreted mass. More recently, Ho (2011) has revisited the same scenario in the context of CCOs, using a 1D cooling code and studying the re-emergence phase of a buried, purely dipolar field, with similar conclusions to previous works.

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The *hidden MF scenario* has also been proposed by Shabaltas & Lai (2012) for the CCO in Kes 79. They can explain the observed high pulsed fraction ($f_p \approx 60$ per cent) of the X-ray emission with a sub-surface MF of $\approx 10^{14}$ G that causes the required temperature anisotropy.

In this paper, we further explore the viability of this scenario with improved calculations that can account for temperature anisotropies. We present the first results from 2D simulations of the submergence and rediffusion of the MF, using the recent extension (Viganò, Pons & Miralles 2012) of the magneto-thermal evolution code of Pons, Miralles & Geppert (2009). The new code is able to follow the coupled long-term evolution of MF and temperature including the non-linear Hall term in the induction equation. This allows us to follow the evolution for any MF geometry (not restricted to dipoles) and includes state-of-the-art microphysical inputs.

2 BASIC EQUATIONS AND INITIAL MODEL

We assume spherical symmetry for our background star (very small deformations induced by the MF or rotation are neglected) with redshift and other metric factors only depending on the radial coordinate, and we adopt the standard static metric

$$ds^{2} = -c^{2}e^{2\nu(r)} dt^{2} + e^{2\lambda(r)} dr^{2} + r^{2} d\Omega^{2}, \qquad (1)$$

where $e^{-\lambda(r)} = (1 - 2 Gm(r)/c^2 r)^{1/2}$. The density, pressure, enclosed mass m(r) and v(r) profiles are obtained by solving the hydrostatic equilibrium equations. We consider a 1.4 M_☉ NS (see section 2 in Pons et al. 2009, section 4 of Aguilera, Pons & Miralles 2008, and references within for all details about the equation of state and other microphysical input), with two different initial configurations, shown in Fig. 1. Model A has an initial dipolar component of the MF extended to the core, with a toroidal component to mimic



Figure 1. Initial configuration of model A (left) and model B (right). Poloidal field lines (solid) smoothly match a vacuum solution outside the star. Upper panels: global configuration; the dashed line indicates the corecrust interface (denoted by R_c) and the colour scale represents the toroidal MF intensity. Lower panels: planar representation of the MF in the crust ($r \in [R_c, R]$) as a function of the polar angle θ ; the grey-scale is normalized to the maximum value of B_t , and the white/black regions indicate positive/negative values.

a typical magnetohydrodynamic (MHD) equilibrium configuration (Ciolfi et al. 2009; Lander & Jones 2009), in which the toroidal field is confined in the internal region defined by the last closed poloidal field line. Model B is a crustal-confined MF, with an extended (in the angular direction) quadrupolar toroidal field. The upper panels of Fig. 1 show the global initial MF geometry, which in both cases matches with an external vacuum dipolar solution, with $B_p^0 = 10^{14}$ G. The toroidal field is $B_t^0 = 10^{14}$ G at its maximum. As we are interested in the evolution in the crustal region, for visualization purposes we show in the lower panels (and hereafter) a planar representation of the MF in the crust.

When the temperature of the NS drops below the melting temperature (Baiko & Yakovlev 1996) a solid crust is formed. Within a few days, the inner crust up to the neutron drip density is crystallized, while the outer crust is formed within weeks or months (van Riper 1991; Aguilera et al. 2008; Ho, Glampedakis & Andersson 2012). The evolution of the MF in the solid crust is described by the Hall induction equation that, including relativistic corrections, has the following form,

$$\frac{\partial \boldsymbol{B}}{\partial t} = -\nabla \times \left[\eta \nabla \times (\mathbf{e}^{\nu} \boldsymbol{B}) - \boldsymbol{v}_{\mathbf{e}} \times (\mathbf{e}^{\nu} \boldsymbol{B}) \right], \qquad (2)$$

where η is the magnetic diffusivity, and v_e is the 'electron fluid' velocity given by

$$\boldsymbol{v}_{\mathrm{e}} = -\frac{\mathrm{e}^{-\nu}c}{4\pi e n_{\mathrm{e}}} \nabla \times (\mathrm{e}^{\nu} \boldsymbol{B}), \tag{3}$$

with n_e being the electron number density. The differential operator ∇ associated with the spatial metric includes the corresponding metric factors, i.e. $e^{-\lambda(r)} \frac{\partial}{\partial r}$. In the core, the field is practically frozen because of the high conductivity of nuclear matter. In the solid crust, in the absence of accretion, the evolution of MF is governed by Ohmic dissipation (the first term on the right-hand side of equation 2) and the Hall term (term proportional to \mathbf{v}_e).

To compare the relative importance of the two terms, we denote by $\omega_B \tau_e = cB/4\pi e n_e \eta$ the so-called magnetization parameter, usually found in the literature of plasma physics, where ω_B is the gyro-frequency and τ_e the electron relaxation time. Note that this quantity gives an estimate of the ratio between the characteristic Ohmic dissipation time-scale $\tau_d = L^2/\eta$ and the Hall time-scale $\tau_h = 4\pi e n_e L^2/cB = \tau_d/(\omega_B \tau_e)$. This ratio strongly depends on temperature. Typical values in NSs vary in a large range $\tau_d \sim 10^4 - 10^9$ yr and $\tau_h \sim (10^4 - 10^6) \frac{10^{14} \text{ G}}{B}$ yr. In previous works (Pons & Geppert 2007; Pons et al. 2009; Viganò et al. 2012), we have discussed in detail the time-scales, the mathematical character (equation 2) and the numerical method to solve it.

Following Geppert et al. (1999), we introduce a new velocity term ($v_e \rightarrow v_e + v_a$) in the induction equation to model the effect of accretion. This new term represents the sinking velocity of the accreted matter as it piles up on top of the crust, with

$$\boldsymbol{v}_{a} = -\frac{\dot{m}(\theta)}{\rho} e^{-\nu} \hat{\boldsymbol{r}}, \qquad (4)$$

where \dot{m} is the mass accretion rate per unit normal area, which in general depends on the latitude (θ) and \hat{r} is the unit vector in the radial direction. This expression is a result of the continuity equation (conservation of mass) together with the assumption that the accreted mass steadily piles up pushing the crust towards the interior without spreading (pure radial displacements, thus with \dot{m} being constant at any depth within a vertical column).

3 MAGNETO-ROTATIONAL EVOLUTION

Our code follows the evolution of the MF inside the star. We impose as a boundary condition at the surface the continuous matching with general vacuum solutions (Viganò et al. 2012). From the values of the MF at the surface, we can reconstruct the external configuration. In particular, we can follow the evolution of the external dipolar component, B_p , responsible for the spin-down of the star.

3.1 Submergence of the magnetic field

We study the accretion phase by exploring the sensitivity of the results to two key parameters: the total accreted mass, M_a , and the angular dependence of $\dot{m}(\theta)$ in equation (4). Neither the final geometry nor the submergence depth at the end of the accretion stage depends on the duration and time dependence of the fallback accretion period that follows an SN explosion because of its short duration (~ months), much shorter than the other relevant time-scales shown in Fig. 2.

It should be noted that our simulations follow the submergence of the MF in the solid crust, as matter piles up on top of the crust, not the dynamical process of accretion outside. This would require MHD simulations of the accretion process in the exterior (see e.g. Bernal, Lee & Page 2010), which is out of the scope of this paper. Thus, we assume that any details about the dynamics of the accretion process are included in the phenomenological form of $\dot{m}(\theta)$ that describes the rate at which matter reaches the top of the crust at each latitude. How the complex external dynamics leads to a particular form of $\dot{m}(\theta)$ should be the purpose of separate studies. We also note that at relatively high temperatures (2–3 × 10⁹ K) during the early accretion stage in our simulations, fast thermonuclear burning is likely to bring the composition close to the ground state, unlike what happens in accreting, old, cold NSs in binary systems. Therefore, we assume that our crust is composed of matter in the ground state.

We begin by discussing how our results depend on the value of M_a for three representative cases:

- *s* spherically symmetric, $\dot{m}(\theta) = k$;
- p channelled on to a polar cap, $\dot{m}(\theta) = k e^{-(\theta/\theta_w)^2}$;
- e channelled on to the equator, $\dot{m}(\theta) = k e^{-(\frac{\theta \pi/2}{\theta_w})^2}$.

where k is the normalization that fixes M_a . Hereafter, we discuss our results with $\theta w = 0.4$ rad. In Fig. 3 we compare the MF configurations in the crustal region immediately after accretion stops for models with $M_a = 10^{-4} M_{\odot}$. We first look at the simple case



Figure 2. Radial profile at the equator of the Ohmic time-scale (solid) and Hall time-scale (dashed) for initial model A, with $B_p^0 = 10^{14}$ G and L = 1 km.



Figure 3. MF in the solid part of the crust after accreting $10^{-4} \,\mathrm{M_{\odot}}$. First (upper) panel: model A with $B_p^0 = 10^{12} \,\mathrm{G}$ and spherical accretion. Second, third and fourth panels: model A with $B_p^0 = 10^{14} \,\mathrm{G}$, and *s*, *p* and *e* accretion rate geometry, respectively. Fifth panel: model B with $B_p^0 = 10^{14} \,\mathrm{G}$ and spherical accretion.

of spherical accretion (upper two panels) for $B_p^0 = 10^{12}$ and 10^{14} G for model A. During the accretion stage, field lines are advected towards the interior, and screening currents are developed in the outer layers. The reduction in the surface field strength is compensated by the local amplification of B_{θ} at the submergence depth, where it can reach values up to a few 10^{16} G. The geometry at the end of the submergence phase is not affected by the initial field strength (it simply scales with B_p^0), because the evolution is governed by the term in v_a (equation 4), in equation (2). However, anisotropic accretion flows cause the irregular submergence of the MF (middle and bottom panels). Strong screening currents also appear, but now they are localized in the regions where $\dot{m}(\theta)$ is larger. This has an important consequence: the external, large-scale, dipolar component is not reduced as much as in the spherically symmetric case.

In Table 1 we summarize our results for model A, for different values of M_a and varying the accretion geometry, as listed above. Here ρ_d denotes the density at the submergence depth and B_p^s the final strength of the dipolar component of the MF (in all models $B_p^0 = 10^{14}$ G). We point out that the exact value of B_p^s is very sensitive to the boundary conditions, i.e. the magnetic flux exchanges with the exterior. We match it with a general vacuum solution, while a more consistent approach should consider again the MHD accretion process in the exterior. On the contrary, we found that our results for ρ_d , B_p^r and re-emergence time-scales are not sensitive

Table 1. Properties for different accretion geometries and total accreted mass (M_a) for model A, with $B_p^0 = 10^{14}$ G. The density at which the maximum compression of lines is reached is ρ_d . B_p^s and B_p^r stand for the values of B_p at the end of the submergence stage and the maximum value reached during re-emergence, respectively.

Geometry	$M_{\rm a}$ (M _☉)	$\rho_{\rm d}$ (g cm ⁻³)	$B_{\rm p}^{\rm s}$ (10 ¹⁴ G)	$B_{\rm p}^{\rm r}$ (10 ¹⁴ G)
S	1×10^{-3}	1.6×10^{13}	10^{-5}	0.84
S	5×10^{-4}	9.0×10^{12}	0.005	0.90
S	2×10^{-4}	4.5×10^{12}	0.12	0.93
S	1×10^{-4}	2.5×10^{12}	0.34	0.95
е	1×10^{-4}	6.0×10^{12}	0.52	0.92
p	1×10^{-4}	3.5×10^{13}	0.96	0.98
S	1×10^{-5}	1.5×10^{11}	0.86	0.98

to the external boundary conditions. For spherical accretion (*s*), we found that if $M_a \lesssim 10^{-5} \,\mathrm{M_{\odot}}$, the submergence depth is shallow. We observe a sharp transition from $M_a < 10^{-4} \,\mathrm{M_{\odot}}$, with at most a factor of 3 decrease in the surface strength, to $M_a > 10^{-3} \,\mathrm{M_{\odot}}$, characterized by a very deep submergence, well within the inner crust.

Model B (fifth panel) shows a similar behaviour: the submergence depth is the same as in model A. No differences in the submergence process arise from the geometry or intensity of the MF. The details of the $M_a - \rho_d$ relation depend mainly on the particular structure and mass of the NS. As a matter of fact, in agreement with the induction and continuity equations, the enclosed mass between ρ_d and the surface is M_a , so that for $M_a \gtrsim 10^{-2} \,\mathrm{M_{\odot}}$ the accreted mass has completely replaced the outer crust.

The rotational behaviour of the star would also be radically different, because the external dipole (third column) regulates the spindown of the star. For $M_a \gtrsim 10^{-3} \,\mathrm{M_{\odot}}$, and spherical (or nearly isotropic) accumulation of matter on top of the crust, B_p is largely reduced and therefore the spin-down rate of the star becomes unusually small. Although estimates of the MF based on timing properties suggest a very low field, the internal field could be orders of magnitude larger, since it is simply screened by currents in the crust that will be dissipated on longer time-scales. Note also that equatorial accretion (*e*) produces a similar reduction in the external dipolar field as for spherical accretion, but the submergence is rather anisotropic (deeper in the equator). In contrast, accretion concentrated in the polar cap (*p*) barely modifies the MF strength or geometry.

We have also found that adding an azimuthal component of velocity $v_{\phi} \neq 0$ in equation (4) does not affect the submergence process, driven solely by the radial inflow. Instead, its effect is the twisting of field lines and the creation of toroidal field, which in turn enhances the Hall activity on longer time-scales, during the re-emergence process.

3.2 Re-emergence of the magnetic field

After accretion stops, the re-emergence process begins. It is mainly driven by Ohmic diffusion (screening currents are concentrated in the outer crust, where the resistivity is relatively high), but also by the Hall term when the MF strength locally exceeds $2-3 \times 10^{14}$ G. In this latter case, there may be significant changes in the geometry of the MF, including the generation of higher order multipoles in both poloidal and toroidal components, and the launching of whistler waves towards the poles (Pons & Geppert 2007; Viganò et al. 2012).



Figure 4. Re-emergence of MF. Configurations at t = 5 kyr after the accretion episode, for the same cases as shown in Fig. 3.

In Fig. 4 we show the MF configuration at t = 5 kyr for the same five models as in Fig. 3. In the weak field case (top panel) the field simply re-emerges by diffusion. It shows very little Hall activity, seen as generation of toroidal field (white/black spots) and deformation of poloidal field in a small equatorial region of the outer crust. In the other four cases ($B_p^0 = 10^{14}$ G), the local generation of strong toroidal field and the creation of non-trivial structures are clearly seen, but these small-scale features are mainly localized in the inner crust, which makes it difficult to predict possible observational consequences. At the same time, the global, large-scale field at the surface is being restored to a shape closer to the original geometry shown in Fig. 1, with additional small-scale multipoles near the surface.

The importance of Hall activity is shown in Fig. 5. Here we plot the radial profile of the magnetization parameter at the equator, at



Figure 5. Radial profile at the equator of $\omega_B \tau_e$ for initial model A (left) and model B (right), with $B_p^0 = 10^{14}$ G, at three different times: at the beginning (solid), after spherical accretion of 10^{-4} M_{\odot} (dashed) and at t = 5 kyr, during re-emergence (dot–dashed).



Figure 6. Evolution of B_p and \dot{P} during the re-emergence phase after spherical accretion, for $B_p^0 = 10^{14}$ G, assuming $P_0 = 0.1$ s. Different cases are shown: model B, $M_a = 10^{-4} M_{\odot}$ (long dashes); model A, $M_a =$ $[1, 5, 10, 20] \times 10^{-4} M_{\odot}$ (other lines from top to bottom, respectively). Observational data are shown with two rhomboids and an arrow (upper limit). Estimates and errors of the ages of the associated SN remnants are shown (Ho 2011, and references within).

different stages for model A (left-hand panel) or model B (righthand panel), both with $B_p^0 = 10^{14}$ G. The solid line corresponds to the initial configuration, for which $\omega_B \tau_e$ is initially of order 1 for model A, while it is 10 times larger for model B due to the larger mean value of MF. After the submergence (dashed), in both models $\omega_B \tau_e$ reaches much larger values in the region where the field has been compressed. After 5 kyr, the diffusion of the field and the lower temperature make $\omega_B \tau_e > 1$ in the whole crust. As $\omega_B \tau_e$ scales with *B*, the same models, but with $B_p^0 = 10^{12}$ G, give a rescaling of $\omega_B \tau_e$ by two orders of magnitude, providing $\omega_B \tau_e \lesssim 1$ always. Thus, for such initially low fields almost no Hall activity is expected.

In the top panel of Fig. 6 we show the evolution of $B_{\rm p}$ as a function of time after a spherical fallback episode, with different $M_{\rm a}$, for model B (long dashes) or model A (other line styles), together with the inferred values (or upper limit) of observed CCOs. The re-emergence time-scale, on which the surface MF grows, depends basically on ρ_d . For total accreted matter in the range of interest, there is an initial delay of about 10³ yr before appreciable re-emergence is observed. The re-emergence process takes between 10^3 and few 10^5 , and it is determined by the local conditions (in particular, the resistivity) where the screening currents are located. The MF will never reach the original strength, since some Joule dissipation is always expected. Generally speaking, B_p is restored to close to its initial value for the core-extended configurations (model A). Only for the extreme case of $M_a \gtrsim 10^{-2} \,\mathrm{M_{\odot}}$, when the reemergence process lasts for a long time, $B_{\rm p}^{\rm r}$ is significantly reduced (see Table 1). In model B (long dashes), crustal currents are much stronger than in model A, so both Ohmic and Hall time-scales are shorter. This implies that the re-emerged field has been more dissipated, in agreement with 1D studies (Geppert et al. 1999; Ho 2011). Furthermore, as the field is more compressed, the Hall activity is more intense (see the dot-dashed line in Fig. 5), and the transfer of



Figure 7. Comparison between surface temperature distributions of an antimagnetar (solid) and two models of hidden magnetars (dashed and dotdashed) after accreting $M_a = 10^{-3} M_{\odot}$. All three models are shown in an evolutionary phase when the external dipolar field is $B_p = 10^{10} \text{ G}$.

magnetic energy from the dipolar component to higher multipoles (i.e. small-scale structures) is faster.

The re-emergence stage has a strong imprint on timing properties. Assuming a small period at the end of the accretion stage, $P_0 = 0.1$ s, we follow the evolution of the timing properties (*P* and \dot{P}) using the classical formula for an orthogonal rotator: $B_p = (6.4 \times 10^{19} \sqrt{P \dot{P} I_{45}}/R_{10}^3)$ G, where $R_{10} = R/10$ km and $I_{45} = I/10^{45}$ g cm² are given by the radius and moment of inertia of the star model. The bottom panel of Fig. 6 shows the evolution of \dot{P} as a function of the real age for several values of M_a in the sensitivity range $[10^{-4}-10^{-3}] M_{\odot}$. Variations of a factor of a few in M_a within this range result in an extremely low value of \dot{P} during the first thousands of years of an NS life. In terms of the spin-down age, $\tau_c = P/2 \dot{P}$, this means that it overestimates the real age also by the same factor. Observational data reported for CCOs are consistent with $M_a \gtrsim 10^{-3} M_{\odot}$.

A possible observable to distinguish between an 'antimagnetar' and the hidden MF scenario is the surface temperature distribution, $T_{\rm s}(\theta)$, that determines the average luminosity and light curve in the X-ray band. Fig. 7 shows $T_s(\theta)$ for two high-field NSs during the re-emergence phase after a $10^{-3}\,M_{\bigodot}$ accretion episode and an antimagnetar. The dot-dashed line refers to model A (Fig. 1) at $t_1 = 3$ kyr, while the dashed line corresponds to a crustal-confined MF model, with a larger toroidal component ($B_p^0 = 10^{13} \text{ G}, B_t^0 =$ 10^{15} G), at $t_2 = 6$ kyr. In both cases, the field has partially re-emerged and has the same value as for the antimagnetar model (solid lines), $B_{\rm p} = 10^{10} \,\rm G$. Model A has a slightly warmer surface than the antimagnetar model, but both are almost isotropic. In contrast, the crustal-confined model shows a distinctive feature consisting of a lower average T_s with hot polar caps. This is produced by the buried toroidal field that keeps the equatorial surface region insulated from the warmer core. The anisotropy depends on the accreted mass and the natal MF, and it varies with time depending on the location of currents during the re-emergence process.

4 FINAL REMARKS

We have presented results from detailed simulations of one of the possible scenarios proposed to explain the low inferred external MFs of CCOs. For the first time, a consistent, coupled magneto-thermal evolution in 2D including the Hall term has been used to model the evolution of the MF in both submergence and re-emergence phases, under the effect of different accretion flow geometries. Our study confirms the qualitative results obtained by previous works (Geppert et al. 1999) for 1D simplified models, in what concerns

the relation between submergence depth and total accreted mass. However, for large MFs, the dynamics of the re-emergence phase is more complex in our models, since we are not restricted to one particular component (dipole) and the interplay between toroidal and poloidal fields is allowed.

We have confirmed that the *hidden magnetar* model is a possible solution, but it requires that, immediately following the SN explosion, 10^{-3} M_{\odot} be able to reach a large fraction of the top of the crust. Under this circumstance, the accretion flow is able to push the field lines deep inside the crust. Other choices, with channelled accretion on to a polar cap or on to the equatorial region, have a more local effect that will barely modify the large-scale MF. If the NS is born as a typical pulsar (10^{12} G) , rather than a magnetar, a reduction of only one to two orders of magnitude in the external MF is easily accomplished with less accreted matter. Chevalier (1989) suggested a value of $M_{\rm a} \sim 0.1\,{\rm M}_{\odot}$ for Supernova 1987A, while $M_{\rm a} \lesssim 10^{-3} \,\mathrm{M_{\odot}}$ is expected for a more typical Type II SN. Interestingly, this estimate lies in our range of interest. Independent work for modelling the MHD accretion process in the exterior of an NS surrounded by the dirty environment of the SN explosion is needed to provide more realistic boundary conditions and to explain the required values of M_a for a deep submergence of the field.

We have also explored the subsequent evolution of the crustal MF during re-emergence by Ohmic dissipation of screening currents. If the hidden MF is of the order of 1014 G, non-linear dynamics driven by the Hall term are also expected, with the generation of toroidal field and multipolar components. This activity is, however, localized in the inner crust, and it remains unclear if the surface field (and therefore timing properties) can reflect in some way these non-trivial structures. In any case, the re-emergence process by diffusion has a clear imprint on the timing properties of the NS. The temporary low values of \dot{P} may point to weak inferred MFs, but that is simply an artefact of the complex field geometry. The re-emergence phase, for the explored range of M_a , may last from 10³ to 10⁵ yr, after which we expect that the field has almost completely re-emerged, although it is partially dissipated. Another important observational consequence of this scenario is the effect on the braking index, n. During re-emergence, the field appears to be growing to an external observer, which means n < 3. Interestingly, this is in agreement with all reported values measured for young pulsars ($<10^4$ yr) (Hobbs, Lyne & Kramer 2010; Espinoza et al. 2011), perhaps pointing to hypercritical accretion in the aftermath of SN explosions as a very common scenario.

Lastly, the thermal evolution during the re-emergence phase in the hidden MF scenario can yield to totally different degrees of anisotropy in the surface temperature, depending on the initial MF and the accreted mass. A hidden magnetar with a large, extended toroidal field buried in the crust could qualitatively explain the surface temperature anisotropies inferred in several CCOs: the large pulsed fraction observed in Kes 79 (Halpern & Gotthelf 2010; Shabaltas & Lai 2012), the antipodal hotspots seen in Puppis A (de Luca et al. 2012) and the small emitting region of the blackbody components needed to fit the spectra of 1E 1207 (De Luca et al. 2004). Instead, the weaker (or less extended) hidden toroidal MF provides low pulsed fractions.

We conclude that the hidden MF scenario for CCOs is not in contradiction with any observational data, and it would not be surprising that one of these objects displays magnetar-like activity in the form of bursts or flares, as it has happened for the *low-field magnetar* SGR 0418+5729 (Rea et al. 2010; Turolla et al. 2011). We also consider the possibility that not all the CCO candidates are of the same nature; large, magnetar-like hidden MFs are particularly suitable for those CCOs that are displaying temperature anisotropies. On the other hand, some of the standard, young rotation-powered pulsars (RPPs) could be in their final stage of re-emergence, representing the connection between CCOs and RPP/magnetar population.

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