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A Fuzzy-Based CAC Scheme for Wireless Cellular Networks Considering Different Priorities

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Abstract—The mobile cellular systems are expected to support multiple services with guaranteed Quality of Service (QoS). But, the ability of wireless systems to accommodate expected growth of traffic load and broadband services is limited by available radio frequency spectrum. Call Admission Control (CAC) is one of the resource management functions, which regulates network access to ensure QoS provisioning. However, the decision for CAC is very challenging issue due to user mobility, limited radio spectrum, and multimedia traffic characteristics. In our previous work, we proposed a fuzzybased CAC system by considering the priority of the on-going connections. As priority parameter, we considered only one parameter (service request). In this work, we extend our work by adding different priorities. We call this system FACS-MP. We evaluate by simulations the performance of the proposed system. From the simulations results, we conclude that the FACS-MP can differentiate better different services compared with previous system.

Keywords-Wireless Cellular Networks; CAC; Fuzzy Logic; Priorities.

I. Introduction

As the demand for multimedia services over the air has been steadily increasing over the last few years, wireless multimedia networks have been a very active research area [1]. To support various integrated services with a certain Quality of Service (QoS) requirement in these wireless networks, resource provisioning is a major issue.

To guarantee the QoS, Call Admission Control (CAC) is a good strategy. CAC is a provisioning strategy that limits the number of connections into the network in order to reduce the network congestion and call dropping.

CAC is not a problem that is unique to wireless networks. It is applicable to almost every type of networks, but in cellular wireless networks due to users' mobility the CAC becomes much more complicated. While in wired networks the resources are reserved for the call at set-up time and are not changed after that, in cellular wireless networks when



the mobile node moves from one cell to another one, the bandwidth must be requested in the new cell. During this process, the call may not be able to get a channel in the new cell to continue its service due to the limited resource in wireless networks, which will lead to the call dropping. Thus, the new and handoff calls have to be treated differently in terms of resource allocation. Since users are much more sensitive to call dropping than to call blocking, the handoff calls are assigned higher priority than new calls [2].

CAC techniques are required to guarantee that all traffic types meet their QoS requirements. In order to improve the system performance at the call level (fairness in blocking), a CAC strategy may block additional calls even if there are enough resources for their service. CAC is based on the knowledge of the statistical characteristics of ongoing and arriving calls [2]. The decision to accept an additional call involves the calculation or estimation of the consequences of the call acceptance on blocking and delay of itself and other incoming calls [3].

Several schemes have been proposed for CAC in wireless cellular networks. However, during the complexity of CAC in wireless environment, many simplified models and assumptions are made. Some schemes consider that each mobile node will make hand-over to neighboring cells with equal probability, which may be not accurate in general. For this reason, the intelligent and heuristic methods are needed.

Use of intelligent methods based on Fuzzy Logic (FL), Neural Networks (NN) and Genetic Algorithms (GA) can prove to be efficient for traffic control in telecommunication networks [4-13].

In our previous work, in order to deal with CAC in wireless cellular networks, we proposed a CAC scheme based on FL [14,15]. We implemented and evaluated the proposed system by comparing its performance with Shadow Cluster Concept (SCC) [16].

In another previous work, we proposed another FL-based CAC scheme by considering the priority of the on-going connections. However, as priority parameter, we considered only one parameter (service request). In this work, we extend our work by adding different priorities. We evaluate by simulations the proposed system and compare its performance with our previous work.

The structure of this paper is as follows. In Section 2, we present the previous work. In Section 3, we introduce the proposed system. In Section 4, we discuss the simulation results. Finally, some conclusions are given in Section 5.

II. PREVIOUS WORK

A. SCC

One of the previous work on CAC is SCC [16]. The fundamental idea of the SCC is that every mobile terminal with an active wireless connection exerts an influence upon the cells and their Base Stations (BSs) in the vicinity of its current location and along its direction of travel. As an

active mobile terminal travels to other cells, the region of influence also moves, following the active mobile terminal to its new location. The BSs (and their cells) currently being influenced are said to form a shadow cluster, because the region of influence follows the movements of the active mobile terminal like a shadow, as shown in Fig. 1. The shadow (and therefore the level of influence) is strongest near the active mobile terminal, and fades away depending on factors such as the distance to the mobile terminal, current call holding time and priority, bandwidth resources being used, and the mobile terminal's trajectory and velocity. Because of these factors, the shape of a shadow cluster is usually not circular and can change over time. The center of a shadow cluster is not the geometric center of the area described by the shadow, but the cell where the mobile terminal is currently located. This cell is considered as the mobile terminal's current home cell. A bordering neighbor is a cell that shares a common border with the shadow cluster's center cell. In contrast, a non-bordering neighbor cell, although being a part of the shadow cluster, does not share a border with the shadow cluster's center cell.

Conceptually, the number and "darkness" of the shadows covering a cell reflect the amount of resources that the cell's BS needs to reserve in order to support the active mobile terminals currently in its own and in neighboring cells. With the information provided by shadow clusters, BSs can determine, for each new call request, whether the request can be supported by the wireless network. In practice, a shadow cluster is a virtual message system where BSs share probabilistic information with their neighbors on the likelihood that their active mobile terminals will move to neighbor cells (while remaining active) in the near future. With the information provided by shadow clusters, BSs project future demands and reserve resources accordingly. BSs reserve resources by denying network access to new call requests, and by "waiting" for active users to end their calls.

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The decision process for the acceptance of a new call request also involves a shadow cluster. Every new call request results in the implementation of a tentative shadow cluster. BSs exchange information on their new call requests, and decide, based on this and other information, which requests should be accepted and which requests should be denied.

After a handoff, BSs within the old shadow cluster are notified about this movement, and the mobile terminal's new current BS has to assume the responsibility of supplying the

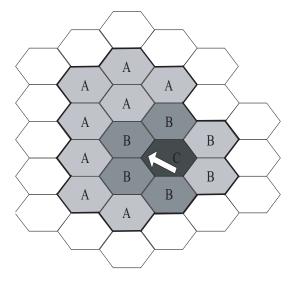


Figure 1. SCC.

appropriate information to the BSs within the new shadow cluster. BSs which were in an old shadow cluster that has just moved away must delete any entries corresponding to the active mobile terminal that established the shadow cluster, and free reserved resources if appropriate. BSs which become part of the influence region of a shadow cluster must be given appropriate information on the shadow cluster's active mobile terminal, such as the respective QoS requirements, e.g., bandwidth demands, call dropping probabilities, and any other useful information such as the wireless connection's elapsed time, for the establishment of the new shadow cluster.

B. FL-based CAC

In our previous work, in order to deal with CAC in wireless cellular networks, we proposed a CAC scheme based on FL [14,15]. Conventional CAC schemes for wireless networks must consider some measured parameters to make the decision. However, in wireless networks due to the user mobility and varying of channel condition the measurement obtained are not accurate. Also, it is very difficult to obtain the complete statistics of the input traffic. Therefore, the CAC decision must be made based on the uncertain or inaccurate information. This is why we use FL. We implemented and evaluated the proposed system by comparing its performance with SCC [16]. We showed that the proposed scheme could achieve a better prediction of the user behavior and a good admission decision compared with SCC.

In [17,18], we proposed another FL-based CAC system called FACS-P, which considered the following parameters for acceptance decision: user Speed (Sp), user Angle (An), Service request (Sr), Correction value (Cv), Required bandwidth (Rq), Counter state (Cs), Accept or Reject decision

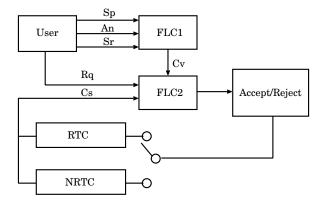


Figure 2. FACS-P model.

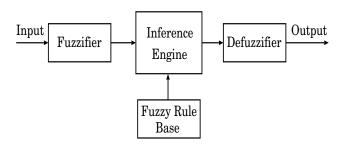


Figure 3. FLC structure.

(A/R), Differentiated service (Ds), Real Time Counter (RTC), and Non Real Time Counter (NRTC). The structure of the FACS-P is shown in Fig. 2. In FACS-P, as the only priority parameter is considered the Service request (Sr).

III. PROPOSED FUZZY ADMISSION CONTROL SYSTEM

In our previous work, we found that when using only one parameter for the priority, the FCAC-P system did not differentiate well different services. For this reason, in the new implemented system, we consider different priorities during the CAC decision.

The Fuzzy Logic Controller (FLC) is the main part of the proposed Fuzzy Admission Control System with Many Priorities (FACS-MP) and its basic elements are shown in Fig. 3. They are the fuzzifier, inference engine, Fuzzy Rule Base (FRB) and defuzzifier. As membership functions, we use triangular and trapezoidal membership functions because they are suitable for real-time operation [19-22]. The membership functions are shown in Fig. 4.

The proposed FACS-MP considers the following parameters for acceptance decision: user Speed (S), user Angle (A), Correction value (Cv), User priority (Up), Service priority (Sp), Connection priority (Cp), Priority (P), Counter state (Cs), Accept or Reject decision (A/R), Differentiated service (Ds), Real Time Counter (RTC), and Non Real Time Counter (NRTC). The structure of the proposed FACS-MP is shown in Fig. 5.

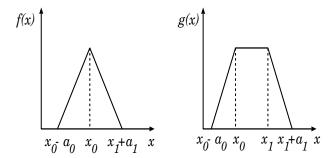


Figure 4. Triangular and trapezoidal membership functions.

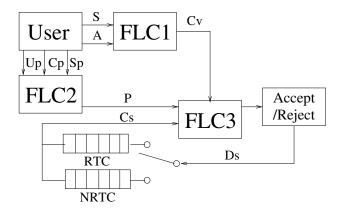


Figure 5. FACS-MP model.

A. FLC1 Design

The input parameters for FLC1 are: user Speed (S) and user Angle (A), while the output linguistic parameter is Correction value (Cv). The term sets of S, and A are defined respectively as:

```
\begin{split} T(S) &= \{Slow, Middle, Fast\} = \{Sl, M, F\}; \\ T(A) &= \{Back1, Left1, Left2, Straight, Right1, Right2, \\ Back2\} &= \{B1, L1, L2, St, R1, R2, B2\}. \end{split}
```

The membership functions for input parameters of FLC1 are defined as follows:

```
g(S; Sl_0, Sl_1, Sl_{w0}, Sl_{w1});
 \mu_{Sl}(S)
                  f(S; M_0, M_{w0}, M_{w1});
\mu_M(S)
 \mu_F(S)
                  g(S; F_0, F_1, F_{w0}, F_{w1});
                  g(A; B1_0, B1_1, B1_{w0}, B1_{w1});
\mu_{B1}(A)
                  f(A; L1_0, L1_{w0}, L1_{w1});
\mu_{L1}(A)
\mu_{L2}(A)
                  f(A; L2_0, L2_{w0}, L2_{w1});
                  f(A; St_0, St_{w0}, St_{w1});
\mu_{St}(A)
                 f(A; R1_0, R1_{w0}, R1_{w1});
\mu_{R1}(A)
            = f(A; R2_0, R2_{w0}, R2_{w1});
\mu_{R2}(A)
                  g(A; B2_0, B2_1, B2_{w0}, B2_{w1}).
\mu_{B2}(A) =
```

Table I FRB1.

Rule	Speed	Angle	Cv
1	Sl	B1	Cv2
2	Sl	L1	Cv3
3	Sl	L2	Cv4
4	Sl	S	Cv7
5	Sl	R1	Cv4
6	Sl	R2	Cv3
7	Sl	B2	Cv2
8	M	B1	Cv1
9	M	L1	Cv3
10	M	L2	Cv3
11	M	St	Cv9
12	M	R1	Cv3
13	M	R2	Cv3
14	M	B2	Cv1
15	Fa	B1	Cv1
16	Fa	L1	Cv2
17	Fa	L2	Cv3
18	Fa	S	Cv9
19	Fa	R1	Cv3
20	Fa	R2	Cv2
21	Fa	B2	Cv1

The small letters w0 and w1 mean left width and right width, respectively.

The term set of the output linguistic parameter T(Cv) is defined as $\{Correction\ value\ 1, Correction\ value\ 2, ...,\ Correction\ value\ 9\} = \{Cv1, Cv2, ..., Cv9\}$. The membership functions for the output parameter Cv are defined as follows:

```
g(Cv; Cv1_0, Cv1_1, Cv1_{w0}, Cv1_{w1});
\mu_{Cv1}(Cv)
                    f(Cv; Cv2_0, Cv2_{w0}, Cv2_{w1});
\mu_{Cv2}(Cv)
                    f(Cv; Cv3_0, Cv3_{w0}, Cv3_{w1});
\mu_{Cv3}(Cv)
                   f(Cv; Cv4_0, Cv4_{w0}, Cv4_{w1});
\mu_{Cv4}(Cv)
                  f(Cv; Cv5_0, Cv5_{w0}, Cv5_{w1});
\mu_{Cv5}(Cv)
                   f(Cv; Cv6_0, Cv6_{w0}, Cv6_{w1});
\mu_{Cv6}(Cv)
\mu_{Cv7}(Cv)
                    f(Cv; Cv7_0, Cv7_{w0}, Cv7_{w1});
                   f(Cv; Cv8_0, Cv8_{w0}, Cv8_{w1});
\mu_{Cv8}(Cv)
\mu_{Cv9}(Cv) =
                   g(Cv; Cv9_0, Cv9_1, Cv9_{w0}, Cv9_{w1}).
```

The membership functions of FLC1 are shown in Fig. 6. The FRB forms a fuzzy set of dimensions $|T(S)| \times |T(A)|$, where |T(x)| is the number of terms on T(x). The FRB1 shown in Table 1 has 21 rules. The control rules have the following form: IF "conditions" THEN "control action".

B. FLC2 Design

The input parameters for FLC2 are: User priority (Up), Connection priority (Cp), and Service priority (Sp), while the output linguistic parameter is user Priority (P). The term sets of Up, Cp, and Sp are defined respectively as:

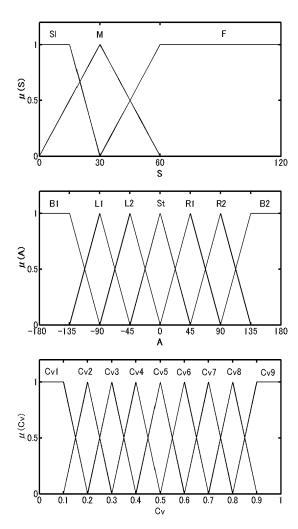


Figure 6. FLC1 membership functions.

```
\begin{array}{lll} T(Up) & = & \{Low\ priority, Middle\ priority, High\ priority\} \\ & = & \{Lp, Mp, Hp\}; \\ T(Cp) & = & \{Short, Middle, Long\} = \{Sh, Mi, Lo\}; \\ T(Sp) & = & \{Text, Voice, Video\} = \{T, Vo, Vi\}. \end{array}
```

The term set of the output linguistic parameter T(P) is defined as $\{Priority\ 1, Priority\ 2, ..., Priority\ 9\} = \{P1, P2, ..., P9\}$. The membership functions for the output parameter P are defined as follows:

```
\begin{array}{lcl} \mu_{P1}(P) & = & g(P;P1_0,P1_1,P1_{w0},P1_{w1}); \\ \mu_{P2}(P) & = & f(P;P2_0,P2_{w0},P2_{w1}); \\ \mu_{P3}(P) & = & f(P;P3_0,P3_{w0},P3_{w1}); \\ \mu_{P4}(P) & = & f(P;P4_0,P4_{w0},P4_{w1}); \\ \mu_{P5}(P) & = & f(P;P5_0,P5_{w0},P5_{w1}); \\ \mu_{P6}(P) & = & f(P;P6_0,P6_{w0},P6_{w1}); \\ \mu_{P7}(P) & = & f(P;P7_0,P7_{w0},P7_{w1}); \end{array}
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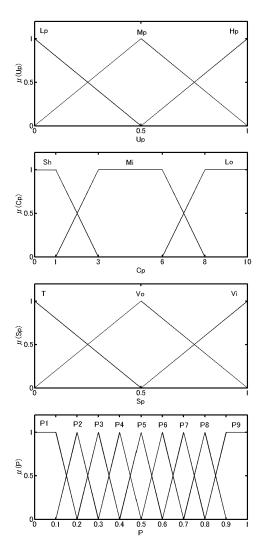


Figure 7. FLC2 membership functions.

```
\begin{array}{lcl} \mu_{P8}(P) & = & f(P; P8_0, P8_{w0}, P8_{w1}); \\ \mu_{P9}(P) & = & g(P; P9_0, P9_1, P9_{w0}, P9_{w1}). \end{array}
```

The membership functions of FLC2 are shown in Fig. 7. The FRB2 shown in Table 2 has 27 rules.

C. FLC3 Design

For the design of FLC3, we keep the same parameters with our previous work. The input parameters for FLC3 are: the output parameter of the FLC1 (Cv), user Priority (P), and the Counter state (Cs), which shows the capacity of the system. While, the output linguistic parameter is the Accept/Reject decision (A/R).

The term sets of Cv, P, and Cs are defined as:

Table II FRB2.

Rule	Up	Cp	Sp	P
1	Lp	Sh	T	P6
2	Lp	Sh	Vo	P5
3	Lp	Sh	Vi	P4
4	Lp	Mi	T	P5
5	Lp	Mi	Vo	P3
6	Lp	Mi	Vi	P2
7	Lp	Lo	T	P4
8	Lp	Lo	Vo	P2
9	Lp	Lo	Vi	P1
10	Mp	Sh	T	P5
11	Mp	Sh	Vo	P6
12	Mp	Sh	Vi	P5
13	Mp	Mi	T	P4
14	Mp	Mi	Vo	P5
15	Mp	Mi	Vi	P4
16	Mp	Lo	T	P3
17	Mp	Lo	Vo	P4
18	Mp	Lo	Vi	P3
19	Hp	Sh	T	P8
20	Hp	Sh	Vo	P9
21	Hp	Sh	Vi	P9
22	Нp	Mi	T	P7
23	Нp	Mi	Vo	P8
24	Hp	Mi	Vi	P9
25	Hp	Lo	T	P6
26	Hp	Lo	Vo	P7
27	Нp	Lo	Vi	P8

```
\begin{split} T(Cv) &= \{Bad, Normal, Good\} = \{B, N, G\}; \\ T(P) &= \{Low\ priority, Middle\ priority, High\ priority\} \\ &= \{Lwp, Mdp, Hgp\}; \\ T(Cs) &= \{Small, Middle, Full\} = \{Sm, Md, Fu\}. \end{split}
```

In order to have a soft admission decision, for the output linguistic parameter (*A/R*), we considered not only "accept" and "reject" but also "weak accept", "weak reject", and "not accept not reject" for the accept/reject decision. The membership functions for input and output linguistic parameters of FLC3 are shown in Fig. 8. The FRB3 shown in Table 3 has 27 rules.

The membership functions for input parameters of FLC3 are defined as follows:

```
\begin{array}{rcl} \mu_B(Cv) & = & f(Cv; B_0, B_{w0}, B_{w1}); \\ \mu_N(Cv) & = & f(Cv; N_0, N_{w0}, N_{w1}); \\ \mu_G(Cv) & = & f(Cv, G_0, G_{w0}, G_{w1}); \\ \mu_{Lwp}(P) & = & f(P; Lwp_0, Lwp_{w0}, Lwp_{w1}); \\ \mu_{Mdp}(P) & = & f(P; Mdp_0, Mdp_{w0}, Mdp_{w1}); \\ \mu_{Hgp}(P) & = & f(P; Hgp_0, Hgp_{w0}, Hgp_{w1}); \\ \mu_{Sm}(Cs) & = & f(Cs; Sm_0, Sm_{w0}, Sm_{w1}); \\ \mu_{Md}(Cs) & = & f(Cs; Md_0, Md_{w0}, Md_{w1}); \\ \mu_{Fu}(Cs) & = & f(Cs; Fu_0, Fu_{w0}, Fu_{w1}). \end{array}
```

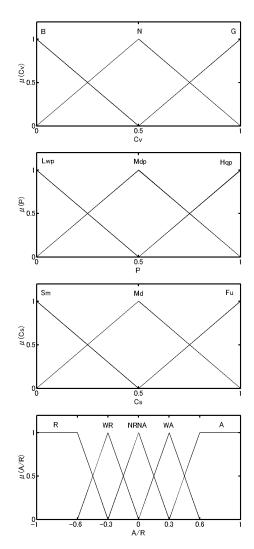


Figure 8. FLC3 membership functions.

The term set of the output linguistic parameter T(A/R) is defined as {Reject, Weak Reject, Not Reject Not Accept, Weak Accept, Accept}. We write for short as {R, WR, NRNA, WA, A}. The membership functions for the output parameter A/R are defined as follows:

```
\begin{array}{rcl} \mu_R(A/R) & = & g(A/R;R_0,R_1,R_{w0},R_{w1}); \\ \mu_{WR}(A/R) & = & f(A/R;WR_0,WR_{w0},WR_{w1}); \\ \mu_{NRNA}(A/R) & = & f(A/R;NRNA_0,NRNA_{w0},NRNA_{w1}); \\ \mu_{WA}(A/R) & = & f(A/R;WA_0,WA_{w0},WA_{w1}); \\ \mu_{A}(A/R) & = & g(A/R;A_0,A_1,A_{w0},A_{w1}). \end{array}
```

IV. SIMULATION RESULTS

The simulation were carried out in Linux Ubuntu 9.10 computer. We considered the following parameters for simulations:

Table III FRB3.

	Rule	Cv	P	Cs	A/B	
Ī	1	В	Lwp	Sm	WA	
	2	В	Lwp	Md	NRNA	
	3	В	Lwp	Fu	WR	
	4	В	Mdp	Sm	A	
	5	В	Mdp	Md	NRNA	
	6	В	Mdp	Fu	WR	
	7	В	Hgp	Sm	A	
	8	В	Hgp	Md	NRNA	
	9	В	Hgp	Fu	NRNA	
	10	N	Lwp	Sm	WA	
	11	N	Lwp	Md	NRNA	
	12	N	Lwp	Fu	NRMA	
	13	N	Mdp	Sm	A	
	14	N	Mdp	Md	NRNA	
	15	N	Mdp	Fu	NRNA	
	16	N	Hgp	Sm	A	
	17	N	Hgp	Md	NRNA	
	18	N	Hgp	Fu	NRNA	
	19	G	Lwp	Sm	A	
	20	G	Lwp	Md	A	
	21	G	Lwp	Fu	R	
	22	G	Mdp	Sm	A	
	23	G	Mdp	Md	A	
	24	G	Mdp	Fu	WR	
	25	G	Hgp	Sm	A	
	26	G	Hgp	Md	A	
	27	G	Hgp	Fu	NRMA	
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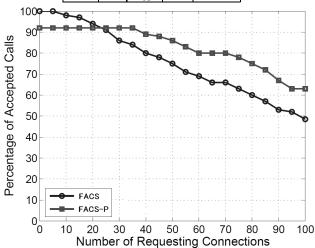


Figure 9. Comparison of FACS-P with FACS.

- the user speed was from 0 to 120 km/h,
- the user direction was changed from -180 degree to +180 degree,
- the requested size was 1, 5 and 10 Bandwidth Units (BU) for text, voice and video, respectively,
- the bandwidth of the BS was considered 40 BU.

In Fig. 9, we show the performance of the previous FL-based CAC systems. When the number of requesting

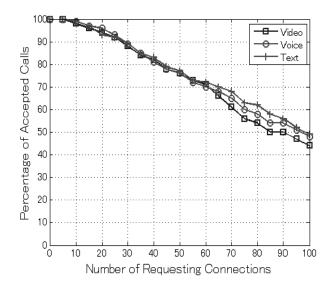


Figure 10. Performance of FACS-P for different services.

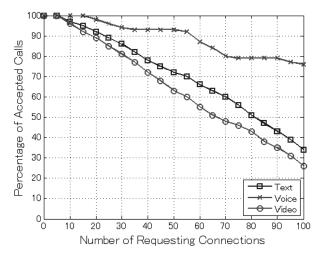


Figure 11. Performance of FACS-MP for different services.

connections is less than 25, the percentage of accepted calls for FACS system is higher than FACS-P system. However, when the number of requesting connections is larger than 25, the FACS-P system accepts less number of connections. This is because, the FACS-P system guarantees the QoS of on-going calls, thus decreasing the acceptance ratio of the requesting connections. However, by using only one priority parameter, the FACS-P system can not differentate well different services as shown in Fig. 10.

In Fig.11, we show the performance of FACS-MP. As can be seen by this figure, the proposed system shows a good behaviour, by making a good differentation for different services.

V. Conclusions

In this paper, we proposed a FL-based CAC system with different priorities called FACS-MP. We evaluated the performance of the proposed system for different services. We also compared the performance of the proposed system FACS-MP with our previous system FACS-P. From the simulations results, we conclude that the proposed FACS-MP make a good differentation for different services.

In the future, we would like to evaluate the proposed FACS-MP by extensive simulations.

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