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# Assessment of 3-D Printing Technologies for Millimeter-Wave Reflectors

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Abstract-Three different 3-D printing technologies-5 stereolithography, fused deposition modeling, and HP Multi 6 Jet Fusion technology-are compared to build a parabolic 7 reflector operating at 100 GHz. Fabrication tolerance and surface 8 9 roughness before and after metallization are accurately measured. The performance of the reflectors is measured in the near field, 10 and it is compared against an optical grade reflector. In this way, 11 the performance of the final product is thoroughly assessed. 12

*Index Terms*—Millimeter-wave devices, reflector antennas,
three-dimensional printing.

# I. INTRODUCTION

DDITIVE manufacturing technologies have become an 16 effective alternative for the manufacturing of antennas. 17 The major challenge in producing antennas in millimeter- and 18 submillimeter-wave regions is to ensure the accuracy in the 19 manufacturing [1], [2]. In addition, in the particular case of 20 reflector manufacturing, the metallization process has to be also 21 taken into account. Surface reflector roughness is a major source 22 of gain reduction in a reflector. The well-known Ruze's formula 23 [3] expresses the gain loss or reflector surface efficiency as 24

$$\Delta G = -685.81 \left(\frac{\epsilon}{\lambda}\right)^2 (dB) \tag{1}$$

where  $\varepsilon$  is the root mean square (rms) surface error and  $\lambda$  is 25 the wavelength. It means that at a frequency of 100 GHz, the 26 rms error has to be smaller than 36  $\mu$ m to have a gain loss 27 smaller than 0.1 dB. Three-dimensional (3-D) printers have res-28 olutions of the order of 10–100  $\mu$ m; therefore, it is interesting to 29 measure the accuracy of different printing technologies to deter-30 mine the upper frequency limit in which they can be used to print 31 reflectors. To this end, three different printing technologies-32 stereolithography (SLA), fused deposition modeling (FDM), 33 34 and HP Multi Jet Fusion (MJF) technology-are compared.

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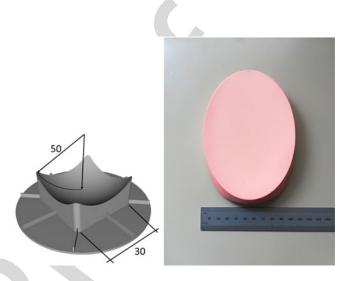


Fig. 1. Test object (left) and the metallized reflector (right).

A 90° offset parabolic reflector has been printed and metallized. 35 The geometry of the reflector has been chosen to be the same 36 as a commercial optical grade reflector, so their performance 37 can be benchmarked against it. The mechanical accuracy of the 38 printed and metallized surfaces has been measured by a confo-39 cal optical profiler that is able to provide accurate contactless 40 surface profiles. Finally, a planar near-field scan of the reflectors 41 has been done to assess their electromagnetic performance. The 42 paper is organized as follows. In Section II, the 3-D printing, 43 metallization, and mechanical verification of the printed reflec-44 tors are described. In Section III, the electromagnetic behavior 45 of the reflectors is presented, and finally, the conclusions are 46 presented in Section IV. 47

# II. MANUFACTURING PROCESS

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## A. 3-D Printing and Metallization

Two sets of objects have been printed and metallized. The first is the test object shown in Fig. 1 (left). It is a sphere of radius 50 mm intersected with a cube of 30 mm side. This test object has the advantage that its measured profile can be easily compared with the theoretical one. 54

The second object shown in Fig. 1 (right) is a 90° offset reflector of 101.6 mm diameter with a parent focal length of 76.2 mm. This geometry has been chosen to be the same as commercial optical grade reflector made by Edmund Optics that will be used as a benchmark for the 3-D-printed reflectors. The reference parabolic reflector has nominal rms roughness smaller than 0.01  $\mu$ m and has an Aluminum 6061-T6 coating with a

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TABLE I SURFACE ERROR FOR THE TEST OBJECT

Name	Printing Technology	Material	Finishing	Surface error rms
				(µm)
FDM	FDM	PLA	None	27.6
FDM+Cu	FDM	PLA	Sanding,	13.8
SLA+Cu	SLA	Therma	Metallization Metallization	8.8
MJF1	MJF	PA 12	Sand Blasting	24.5
MJF2	MJF	PA 12	Tumbling	12.2
MJF3	MJF	PA 12 GB	Sand Blasting	36
			U	
MJF4	MJF	PA 12 GB	Tumbling	25.6

conductivity of 2.5  $10^7$  S/m. The SLA objects have been printed

using a XFAB Stereolithographic 3-D printer from DWS. The 63 base material is a nanoceramic-filled photopolymer Therma 64 294 that allows high resolution modeling (10–100  $\mu$ m layer 65 66 thickness). For the FDM, a SIGMA 3-D printer manufactured by BCN3D with a step resolution of 100  $\mu$ m has been used and 67 the objects have been printed on polylactide (PLA). Finally, an 68 HP 3-D MJF 4200 has been used to print the objects on two 69 different materials PA 12 and PA 12 GB. These are thermoplas-70 71 tics the second one with a loading of glass beads to increase the 72 mechanical stability. The MJF printed objects have been given 73 two different finishing processes, sandblasting and tumbling, to reduce the surface roughness. The metallization process is by 74 copper electrodeposition by electrolysis. A 17  $\mu$ m thick layer 75 of copper is deposited following the process described in [4]. 76 Further testing has shown that this method provides surface 77 resistances close to the ones obtained from copper, in particular 78 79 accurate cavity measurements at 9 GHz have shown a surface

resistance of  $35.93 \text{ m}\Omega$  for electrodeposited copper on PLA compared to  $25.68 \text{ m}\Omega$  for pure copper [5].

# 82 B. Mechanical Verification

The accuracy of the printed objects has been verified by a 83 Plu Neox Optical Profiler manufactured by Sensofar Metrol-84 ogy [6]. The measurement principle is described in [7] and it 85 allows contactless high accuracy profile measurements that in-86 87 clude submicron surface roughness measurements. The goal of 88 the mechanical verification is to have a measurement of the surface roughness as well as deviations from the specified nominal 89 shape. To this end, accurate profiles of the test object of Fig. 1 90 (left) have been measured before and after metallization. The 91 description of each object is shown in Table I and the measured 92 results are shown in Fig. 2. For each one of the test objects, the 93 94 measured profile compared to the theoretical one is shown on the left of the figure. On the right, the surface error is shown. From 95 this error curve, the rms surface error is found and it is shown 96 in Table I. The results show that the best roughness is obtained 97 by the SLA printed object that has a roughness of 8  $\mu$ m after 98 metallization. The profile measurements of Fig. 2 also show the 99 100 effects on the surface of the applied surface treatment. In the 101 case of the MJF samples, sandblasting or tumbling has been applied. It is observed that these surface treatments smoothen 102 the surface, but they can leave residual surface errors. In the 103

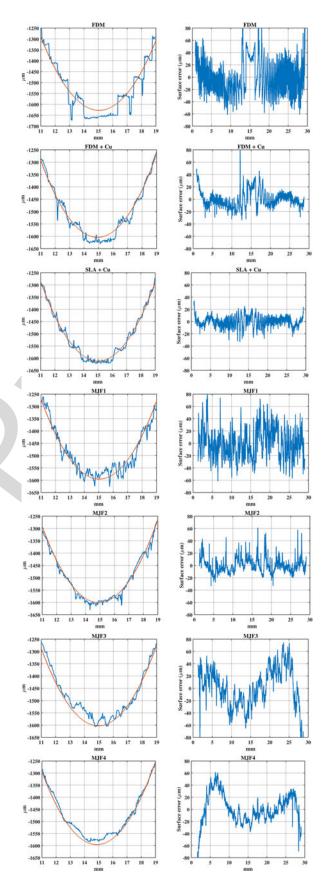


Fig. 2. Profile measurement results for the test object (left) and surface error (right).

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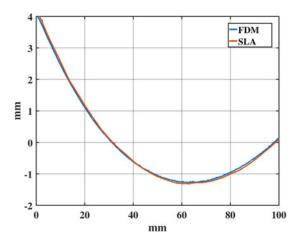


Fig. 3. Profile measurement of the metallized FDM and SLA printed reflectors.

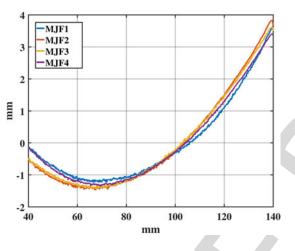


Fig. 4. Profile measurement of the metallized MJF printed reflectors.

case of the FDM object, the 100  $\mu$ m vertical steps of the printer are clearly observable. For this object, prior to the metallization, it has been smoothened with a fine grain sandpaper. Therefore, the resulting metallized object has a smoother texture. In all cases, the surface roughness is below the 36  $\mu$ m design goal for a 100 GHz reflector.

Once the reflectors have been printed and metallized, and be-10 fore proceeding to the EM testing, their profile has also been 11 measured with the optical profiler. Due to the large dimension 12 of the reflector, a partial profile along the vertical dimension 113 114 has been measured. In Fig. 3, the profiles for the FDM and SLA printed and metallized reflectors are compared. In Fig. 4, 115 the profiles for the four MJF reflectors are compared. The first 116 evident conclusion is that the four MJF reflectors present clear 117 differences in their profiles. It is also evident that their rough-118 ness is higher than in the FDM and SLA printed reflectors. For 119 unknown reasons, that has to be further investigated as some of 120 the MJF reflectors have suffered some deformation during the 121 printing process. 122

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#### III. EM TESTING

In order to assess the performance of the reflectors, their radiation pattern has been measured using a planar near field scanning technique at a frequency of 100 GHz. The measurement setup

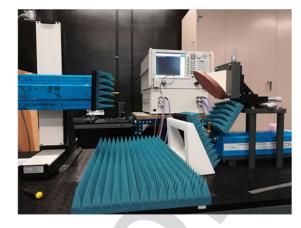


Fig. 5. Near-field scanning of a printed reflector.

is shown in Fig. 5 where one of the 3-D printed reflectors is 127 tested.

The *H* plane pattern (horizontal cut according to the measure-129 ment setup of Fig. 5) for all the reflectors is shown in Fig. 6. In 130 Table II, the directivity and the normalized radiated power for 131 each reflector compared to the reference optical grade reflector 132 is shown. Notice that, in this case, all the printed reflectors have 133 been metallized. The observation of the radiation patterns shows 134 similar cross-polar level in all cases. The changes in directiv-135 ity can be as high as -0.80 dB compared to the optical grade 136 reflector and the reflector that better matches the performance 137 of the optical grade reflector is the FDM. The total radiated 138 power has been compared from the integration of the field com-139 ponents in the near-field measurements. It is interesting to note 140 that the radiated power for the 3-D printed reflectors is higher 141 than the power radiated by the optical grade reflector in all 142 cases. 143

This fact can be explained due to the lower surface resistance 144 of the copper metallization compared to the aluminum coating 145 of the optical reflector. In addition, the thickness of the alu-14 minum coating of the optical grade reflector is not known, but it 14/ is also possible that the coating thickness is smaller than 30  $\mu$ m, 148 which is the penetration depth at 100 GHz, finally the fact 149 that the optical grade reflector has sharper edges that probably 150 contribute to higher edge diffraction. The radiated power is 151 obtained from the planar near-field measurement; therefore, the 152 scattered power is not properly taken into account. In Table II, 153 the measured roughness for each reflector is also shown. This 154 roughness has been measured following the procedure of [8]. 155 The roughness is the rms height after removing the primary sur-156 face. The specific way in which it has been computed involves 157 two steps. First an error function is obtained by subtracting the 158 desired parabolic curve from the measured profile. Then the rms 159 value of the error function is obtained after applying a spatial 160 low pass filter of 2 mm cutoff length. It is observed that after 161 metallization, the surface roughness is below 21  $\mu$ m in all cases. 162 As expected from the results of Figs. 3 and 4, the roughness for 163 the SLA and FDM reflectors is smaller. It is also observed that 164 the *H* plane 3 dB beam width (horizontal plane) is practically 165 the same in all cases, and differences of the order of 0.1° can be 166 observed in the E plane. Of course the larger beam width incre-167 ments correspond to the largest decrements in directivity. Due 168 to the similar surface roughness, we think that the directivity 169 reduction is produced by larger scale surface errors. As shown 170

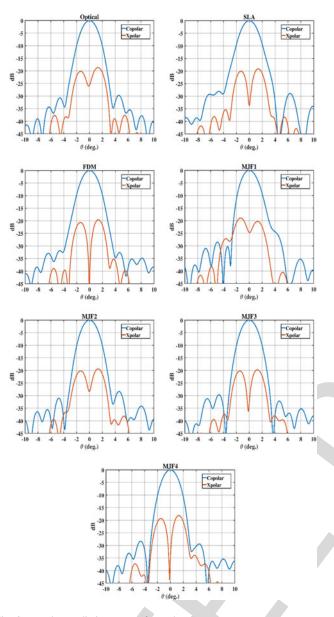


Fig. 6. *H* plane radiation pattern for each reflector.

in Fig. 4, the profiles of the MJM-printed reflectors exhibit 171 large differences. As a matter of fact, MJM2 and MJM3 have 172 similar profiles and their directivity loss compared to the optical 173 reflector is similar. On the other hand, MJM1 and MJM4 have 174 175 more different profiles that we must infer that have higher deviation from the nominal surface that result in higher directivity 176 losses. 177

Assuming that the FDM reflector is the one that better re-178 produces the nominal reflector shape, the comparison of Fig. 3 179 shows that the SLA profile has a ripple around the nominal 180 shape. For practical reason, the SLA reflector was printed verti-181 cally and that resulted in this ripple that can be the cause of the 182 directivity reduction. 183

TABLE II MEASURED RADIATION PARAMETERS

Name	D (dB)	$\Delta \theta_{3dB}$ E- plane (°)	$\Delta \theta_{3dB}$ H-plane (°)	Relative Directivity (dB)	Relative Radiated Power (dB)	Roughness (µm)
Optical	38.84	2.02	2.22	0	0	$0.01^{1}$
FDM	38.83	2.03	2.26	-0.01	0.21	9.6
SLA	38.33	2.13	2.27	-0.51	0.56	8
MJF1	38.39	2.13	2.23	-0.45	0.34	17
MJF2	38.61	2.07	2.23	-0.23	0.2	14
MJF3	38.69	2.05	2.23	-0.15	0.4	21
MJF4	38.04	2.18	2.22	-0.80	0.36	14

<sup>1</sup> Nominal value

# **IV. CONCLUSION**

The potentiality of 3-D printing of parabolic reflectors for 185 being used in frequencies in the 100 GHz band has been shown. 186 Accurate surface measurements have shown that the metallized 187 reflectors can achieve surface roughness of the order of 10  $\mu$ m. 188 According to Ruze's equation, a reflector with such rough-189 ness could be used for frequencies up to 300 GHz with gain 190 losses of 0.1 dB. Nevertheless, the measurements have shown 191 that although the local roughness can achieve these low values, 192 there may be other larger scale surface errors that can degrade 193 the performance of the reflector. In particular, the best results 194 have been obtained with the FDM reflector that has almost the 195 same performance as the optical grade reflector. In this case, 196 although the printing resolution is not the best, the fact that 197 the printing material is relatively soft leads to easy smooth-198 ing by hand sanding. Also the printing material PLA does not 199 need high temperatures and that may explain the smaller de-200 formation of the printed reflector as compared to the HP MJF 201 reflectors. 202

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for ref [5] it has been accepted but not published yet (the conference is in September '18) so we do not have the page number yet. Please cite it as "accepted to the 2018 48th European Microwave Conference (EuMC), Madrid, 2018"

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