

EXPERT KNOWLEDGE FOR COMPUTERIZED
ECG INTERPRETATION

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EXPERT-KENNIS VOOR GEAUTOMATISEERDE
ECG-INTERPRETATIE

Proefschrift

ter verkrijging van de graad van doctor
aan de Erasmus Universiteit Rotterdam
op gezag van de rector magnificus
prof.dr. C.J. Rijnvos
en volgens besluit van het College van Dekanen.

De openbare verdediging zal plaatsvinden op
woensdag 1 april 1992 om 15.45 uur

door

Jan Alexander Kors

geboren te Delft

universiteits
Erasmus
DRUKKERIJ

1992

Promotiecommissie

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Financial support by the Netherlands Heart Foundation for the publication of this thesis is gratefully acknowledged.

ISBN 90-9004788-3

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CHAPTER 1

Introduction

This study was aimed at finding ways to improve the diagnostic performance of computer programs for the interpretation of the electrocardiogram (ECG) and the vectorcardiogram (VCG). To that end, two main directions were explored. First, we developed tools to facilitate the translation of cardiological knowledge into computer algorithms. Second, we investigated whether a better performance could be achieved by combining different sources of cardiological knowledge. In doing this research, we had a special interest in improving our interpretation program MEANS (Modular ECG Analysis System) [1,2].

In this chapter, we will briefly introduce the field of computerized ECG interpretation, describe the difficulties in improving the performance of ECG computer programs, and indicate the aims and scope of our investigations.

Computerized ECG interpretation

Computer interpretation of the ECG during rest started in the early sixties, at that time on bulky, inconvenient equipment [3,4]. Since then, large research efforts combined with technological breakthroughs resulted in relatively inexpensive, portable electrocardiographs which render an interpretation of the ECG almost instantly; a historical review was given by Macfarlane [5].

ECG computer programs generally consist of a measurement part and a diagnostic interpretation part [6]. The measurement part takes care of data acquisition, artefact detection and correction, wave detection, determination of onsets and ends of the various waves, and computation of a set of measurements, such as wave amplitudes, durations, etc. Based on these measurements, the interpretation part of the program generates a diagnostic (contour) classification. Additionally, other types of classification may be provided, e.g., rhythm analysis, Minnesota coding [7], and serial comparison of ECGs.

Two methods are currently being used for the construction of the classification parts of ECG computer programs: a heuristic or deterministic one and a statistical one. In the heuristic approach, the knowledge that a cardiologist uses in interpreting ECGs is elucidated and incorporated in classification algorithms, usually in the form of decision trees. In the statistical approach, a classifier is constructed from a learning set of labelled ECGs using multivariate statistical techniques.

In this study, MEANS has been used to test and evaluate many of our ideas. When the development of MEANS was started, the analysis and interpretation of ECGs was split into fourteen more or less self-contained tasks [8,9]. Each task was implemented as a separate module. This modular set-up has over the years greatly facilitated the development, testing, and maintenance of the system [10].

In the past, most research on MEANS has been devoted to the measurement part, the rationale being that improving the classification part is only worthwhile if the measurement part provides reliable and accurate measurements. We concluded that the measurement part was at this level when we started the present study; evaluation results of most signal analysis modules are reported in Chapter 2 of this thesis.

The classification part of MEANS contains modules for contour classification of the ECG and the VCG [11], rhythm classification [12], and Minnesota coding [13]. A heuristic approach has been followed to develop these classification modules. The pros and cons of the heuristic approach compared with the statistical approach are discussed in Chapter 3. Briefly, there are two main reasons why the heuristic approach was chosen: (1) The statistical approach requires a very large validated database to construct a classifier. The collection of such a database was practically infeasible in our situation; (2) We wanted to be able to explain to cardiologists the reasons for a particular classification made by the program. Heuristic classifiers are more fit to provide such explanations than statistical classifiers.

Why computerized ECG interpretation?

The relative merits and deficiencies of computerized ECG interpretation depend on the role of computers in the interpretation process. Computer involvement in interpreting ECGs can be separated into four stages. In the first stage, electrocardiographs are equipped with a computer to perform quality control and determine and display a set of diagnostically important measurements, i.e., the signal analysis part of an ECG computer program is on-line available. In the second step, the interpretation part of the ECG computer program is also implemented in the electrocardiograph, providing automatic interpretation of the ECG shortly after it is recorded. In a third stage, one or more electrocardiographs are connected to an ECG management system. Such a system typically enables the on-line storage and retrieval of large numbers of ECGs, provides overreading facilities, and facilitates archiving. In a fourth stage, the ECG management system may be connected to other systems, e.g., a hospital information system, for the exchange of other patient data with departments within or outside the hospital.

Today, several biomedical industries offer systems which encompass the first three stages mentioned above. Progress is being made in the definition of standards for the fourth stage [14]. Another recent development is the implementation of ECG computer programs on personal computer systems that are equipped with dedicated hardware to record an ECG (ECG amplifiers and A/D conversion). These PC-based systems are also able to provide much of the functionality of ECG management systems.

The main advantages of computerized ECG interpretation are: (1) Improved quality control of the ECG recording. Computer analysis enables, for example, baseline correction, removal of mains interference, artefact detection, etc. (2) Time savings. The time spent by physicians and clerical staff in interpreting and archiving ECGs may be reduced, mainly because ECG readers only need to initial ECGs that were correctly interpreted by the computer and because the storage and retrieval of ECGs, e.g., for serial comparison, is much easier. (3) Reduced inter- and intraobserver variability. Computerized ECG analysis and interpretation does not suffer from fatigue, time pressure, etc. Furthermore, observer variability may be reduced by the use of standard reports and terminology. (4) Increased availability. A computer interpretation of the ECG can be provided when there is no easy access to cardiological expertise, e.g., in rural communities, or when a routine screening is performed, e.g., by general practitioners. (5) Assistance to research projects. Specific patient groups are easily retrieved from a database of ECGs. Other clinical data may then more easily be correlated with the ECG [15].

Computerized ECG interpretation may have the disadvantage that users will rely on it uncritically which may result in deterioration of the quality of teaching electrocardiography. On the other hand, ECGs which are interesting from a teaching point of view may easily be retrieved. Furthermore, some computer programs explain a given classification by providing the main criteria that were fulfilled.

These advantages and disadvantages are somewhat speculative as no pertinent data are available. Furthermore, several of the advantages are conditional on adequate performance of the interpretation program. For instance, time savings will only materialize when the computer interpretations of most ECGs are acceptable for the cardiologist without requiring corrective action. Computerized ECG interpretation in an environment where cardiological expertise is not readily available will only be possible when the good quality of the diagnostic interpretation has been proven.

Difficulties in computerized ECG interpretation

In this paragraph, three problems are addressed that have to be dealt with when trying to improve the diagnostic performance of an ECG interpretation program based on heuristic knowledge.

Formalization of knowledge

Cardiological knowledge needs to be formalized in order to be implemented into computer algorithms. Assuming that classification algorithms are represented by means of binary decision trees, three steps may be discerned in the formalization process: (1) Selection of diagnostically important measurements, e.g., the amplitude of a Q wave in certain leads, and definition of

standards, e.g., minimum wave requirements; (2) Specification of threshold values for comparison with the measurements, the outcome of the comparison being true or false; (3) Definition of a decision tree, structuring the decision criteria specified in the previous step.

This formalization process does not guarantee that the resulting classifier will be optimal with respect to some performance criterion. In practice, the initially specified classifier is refined by trial and error, on the basis of expert knowledge.

Inter- and intraobserver variability

Cardiologists have been shown to exhibit considerable inter- and intraobserver variability in their diagnostic classifications [16,17]. Such variability can partly be explained by differences in training and experience. Therefore, an important issue in the development of heuristic ECG classifiers is what cardiological knowledge will be translated into computer algorithms. In practice, the most prevalent approach is to select one expert cardiologist who has proven to be able to follow sound cardiological reasoning. Alternatively, one may try to combine the knowledge of multiple cardiologists. At least two ways of combination can be envisaged, a direct one and an indirect one. In the direct approach, cardiologists must make their knowledge explicit and resolve any differences, e.g., by using a procedure aimed at finding a consensus. In the indirect approach, different heuristic classifiers representing different sources of knowledge are to be constructed. Such classifiers can then be combined, either by selecting those parts which have proven to perform best, or by merging the classification results of different classifiers into one 'combined' classification.

Evaluation

ECG classifiers are generally evaluated by assessing their performance on a test set of ECGs. In order to avoid an optimistically biased outcome, the test set must be different from the learning set which was used to train the classifier. Important choices in the evaluation of a classifier are the reference against which performance is tested, and the kind of classification output to be evaluated.

Two reference standards for performance testing of ECG classifiers have been used in the past. One standard is based on visual inspection: a cardiologist judges the ECGs and his classifications are taken as the reference. Instead of one cardiologist, a panel of cardiologists could judge each case and an aggregate or combined classification be derived. This approach has been criticized because of its said lack of 'objectiveness' [18]. Therefore, several investigators are proponents of a standard that is based upon ECG-independent evidence, such as catheterization, autopsy, echocardiographic data, enzyme levels, etc.

ECG interpretive statements are generally distinguished into three different categories [6]: type-A statements which refer to abnormalities that can be validated by ECG-independent

evidence (e.g., left and right ventricular hypertrophy, myocardial infarction); type-B statements which denote abnormalities in the electrical conduction system of the heart and for which criteria are derived from the ECG itself (e.g., conduction defects, arrhythmias); type-C statements which are descriptive and do not relate to a specific diagnosis (e.g., non-specific ST-T changes, axis deviations).

For long, the need for well-validated databases has been recognized [6,18]. An important and influential effort in this respect has been made by the project 'Common Standards for Quantitative Electrocardiography' (CSE), an international cooperative study for standardization and evaluation of ECG computer programs [19]. In the framework of CSE, a database of 1,220 cases was collected, the cases being validated by means of ECG-independent clinical evidence. Nine cardiologists also judged the cases, and a combination of their interpretation results served as another yardstick [20]. In this study, the CSE database has been used as an independent test set.

Aims and scope of this study

In this study, two main questions are addressed: (1) Can the time consuming and cumbersome development and refinement of (heuristic) ECG classifiers be alleviated, and (2) Is it possible to increase diagnostic performance of ECG computer programs by combining knowledge from multiple sources?

Chapters 2 and 3 are of an introductory character. In Chapter 2, the measurement part of MEANS is described and evaluated. This research largely depends on the earlier work of Talmon [11]. In Chapter 3, different methods of diagnostic ECG classification are described and their pros and cons discussed. The issue is raised whether or not the ECG should be classified using as much prior information as possible, and our position is made clear.

The first question, how to ease the transfer of cardiological knowledge into computer algorithms, is addressed in Chapters 4 and 5. The development and refinement of heuristic ECG classifiers is impeded by two problems: (1) It generally requires a computer expert to translate the cardiologist's reasoning into computer language without the average cardiologist being able to verify whether his diagnostic intentions were properly realized, and (2) The classifiers are often so complex as to obscure insight into their doings when a particular case is processed by the classification program. To circumvent these problems, we developed a dedicated language, DTL (Decision Tree Language), and an interpreter and compiler of that language. In Chapter 4, a comprehensive description of the DTL environment is given. In Chapter 5, the use of the environment to optimize MEANS, following a procedure of stepwise refinement, is described.

The second question, whether it is feasible to combine knowledge from multiple sources in order to increase diagnostic performance of an ECG computer program, is explored from several perspectives in Chapters 6 through 9.

In Chapter 6, we investigated whether the Delphi method can be applied to increase the agreement among multiple cardiologists, based both on their classifications and their reasons for these classifications. It was hoped that the latter should reveal knowledge that would be useful in improving the classification part of MEANS.

In Chapters 7 and 8, we investigated whether the combined interpretations of the ECG and the VCG classification parts of MEANS would yield a better result than that of either part separately. A drawback of this approach is that a VCG must always be recorded in addition to the ECG. Therefore, we studied different methods for reconstructing the VCG from the ECG and evaluated their performance. This research is reported in Chapter 7. The performance of the combination of the ECG classification part and the VCG classification part - either processing the original VCG or the reconstructed one - is given in Chapter 8, and the requirements for improvement to occur, are discussed.

Yet another form of the multiple 'sources for knowledge' may be found in the ECG itself. In Chapter 9, we investigated whether the variability of separate complexes in the same ECG recording exhibits information that is of diagnostic importance. Signal analysis techniques that are used in today's ECG computer programs ignore or filter such information. We propose a method which can take into account the intrinsic variability of the ECG. In evaluating this method with MEANS, we also assessed the stability of measurements and classifications.

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CHAPTER 2

Multilead ECG Analysis

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Computers and Biomedical Research 1986;19:28-46

Abstract

This paper describes the results of our recent research in computer-assisted ECG/VCG interpretation. It comprises new developments which were initiated by the advent of relatively inexpensive microcomputers. Our previous systems performed an off-line analysis of ECGs. Currently, there is a trend to move computer power near to the patient and to provide on-line analysis of ECGs. Besides the advantage of the direct availability of the ECG interpretation, quality control will reduce the number of uninterpretable ECGs and hence the number of repeated recordings. This paper describes the requirements that were established for a system for on-line ECG analysis. The system is based on our modular approach, just like our off-line system, Modular ECG Analysis System (MEANS). Changes in the methods and software had to be made mainly because of the simultaneity of all ECG leads and the concurrency of the processing tasks. Other modifications and extensions of the algorithms necessary to meet the requirements of on-line ECG interpretation especially those related to processing speed, are discussed, and evaluation results are presented.

Introduction

In the past, computerized ECG analysis was not integrated within the data acquisition station. During the last few years, a number of systems have become commercially available which have ECG/VCG analysis software incorporated in the cardiograph itself. Only a few of them perform virtually real-time ECG/VCG analysis. For the other electrocardiographs, existing processing systems as they were running on centralized computer facilities have been implemented on a microcomputer system with the often overlaid program structure residing on floppy disks. In such systems, the analysis starts just after data acquisition, resulting in a delay of one to three minutes between the completion of data acquisition and the printing of the analysis.

Such an approach is not a real step forward in computerized ECG analysis. The disadvantages of off-line ECG analysis, such as the lack of quality control during data acquisition and hence the less accurate analysis of noisy records, are transferred to the electrocardiograph, and no attempt is made to improve the performance of such systems, e.g., by feedback to the technician. Furthermore, these systems will in general analyze the four lead groups, rather than take advantage of the fact that modern technology facilitates the recording of the eight independent ECG leads simultaneously.

Our first experience in computerized ECG/VCG analysis dates from the mid-1960s. In 1974 we reported on a modularly structured system for VCG/ECG analysis [1]. Several stages in the development of the algorithms of this modular system were reported before. Among other publications on our system, one can find descriptions of the QRS detection algorithm [2,3], of artifact detection [4], of QRS typification [3,5], of P-wave detection [6,7], and of the waveform-recognition procedure [8-10]. A complete description of the algorithms currently implemented in our Modular ECG Analysis System (MEANS) together with an extensive evaluation of their performance can be found in [11].

Recently, we started the development of an ECG analysis system to be integrated in an electrocardiograph. We defined the starting points for such a development as follows:

- The system should be based on the algorithms which are used in MEANS because the good performance of this system has been proven.
- The cardiograph should simultaneously record the eight independent leads of the 12-lead ECG because this procedure may reveal yet-unknown diagnostic information. Both the phase relations between the leads and the presence of isoelectric segments not seen in conventional ECGs may be of diagnostic importance; for example, with respect to the diagnosis of inferior myocardial infarction. Furthermore, such a recording technique will provide all information simultaneously, so that for each processing step an optimal choice of leads can be made, and hence the processing time can be minimized while the performance is maximized.

- Processing should be done virtually in real time. This means that the electrocardiograph should start writing the processed data and printing the analysis results as soon as possible after the collection of a segment of reliable data is completed. In other words, the delay between data collection and report generation should be on the order of seconds rather than minutes. The processing speed should be such that the results of the interpretation should become available on the same document as that on which the processed data are written.
- Extensive signal quality control should take place during data acquisition in order to be able to guide the technician in the recording of ECGs of acceptable quality for analysis.

In order to meet the requirements of processing speed, it is essential that both the data and the programs reside in central memory during analysis and not on an auxiliary storage device. Furthermore, speed is only obtained when a minimal number of operations on the signals is performed. Our main concern has been to adapt the algorithms of MEANS in such a way that only the essential parts remained, while a good performance is still achieved; this required, in some instances, a compromise between what is theoretically possible and what is practically feasible. Another way to obtain speed is to perform certain operations only on selected leads rather than on all leads simultaneously. For example, when a cardiac event is detected in one of a few leads, it may be assumed that it is present in all leads. So, proper lead selection is of importance as well.

In the next section of this paper we discuss lead selection. Thereafter, some of the modifications of the algorithms of MEANS are described, and finally we present the evaluation results based on the 250 cases of the multilead CSE library [12], which were analyzed by both MEANS and our multilead program.

Lead selection

It has been shown before [11] that algorithms for the detection and typification of QRS complexes perform better for the VCG than for the conventionally recorded four lead groups of the 12-lead ECG. The main reason for this is the dependency between leads. Lead groups I-II-III and aVR-aVL-aVF, for example, do not display any electrical activity in the anterior-posterior direction, and hence abnormalities in the electrical activity in that direction are not detected. This phenomenon is shown in Figure 1. The abnormal shape of the premature ventricular beat is best seen in leads that point in an anterior direction.

When the VCG is not simultaneously available with the leads of the ECG, a better performance of the detection and typification algorithms can only be achieved when the leads of the ECG are recorded simultaneously, and when a more or less orthogonal set of leads is

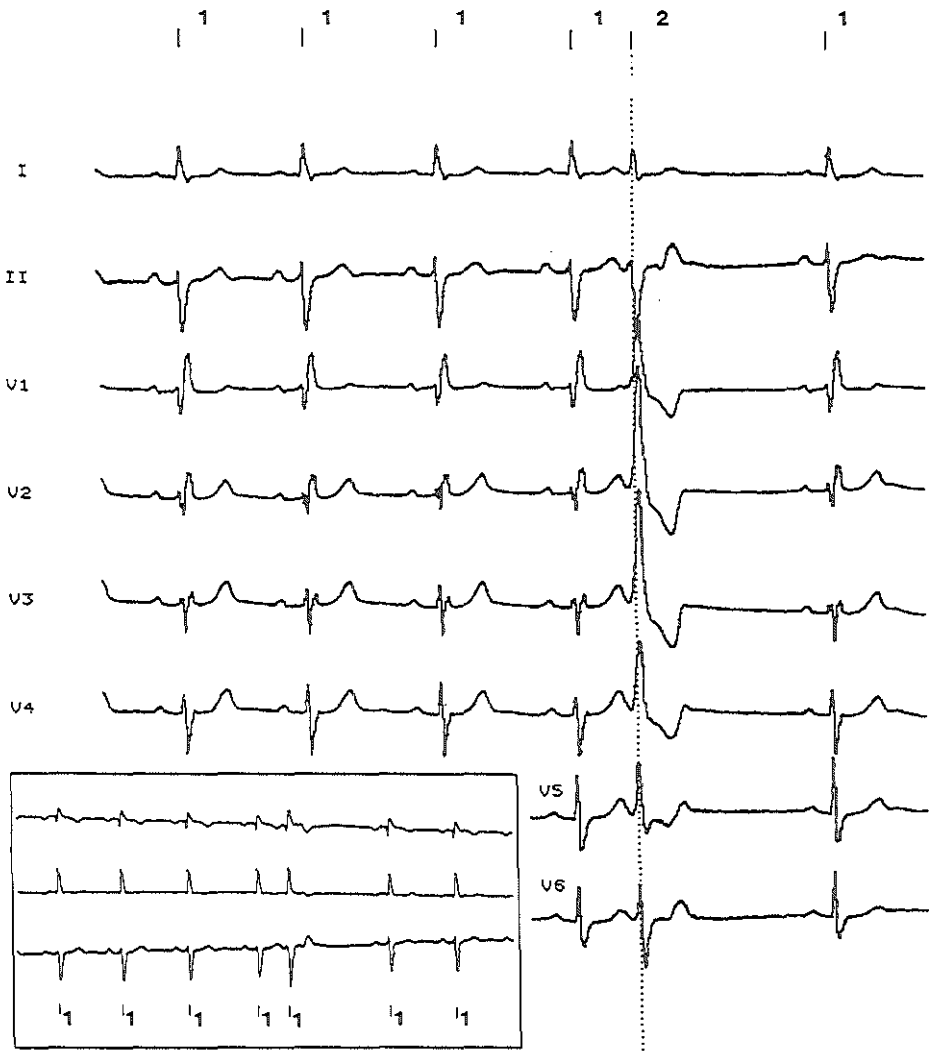


Figure 1. An example of a multilead ECG in which the extrasystole can best be distinguished from the normal complexes in leads V1-V4. MEANS failed to typify the extrasystole as such in lead groups I-II-III and aVR-aVL-aVF.

reconstructed or selected from the eight independent ones. It has been shown before by several research workers (see [13], for example) that considerable differences between original leads and reconstructed ones will occur when general transformation coefficients are used. Others [14] have shown that even with individual transformation coefficients, large reconstruction errors may occur in some parts of the P-QRS-T complex. In addition, it takes quite a lot of computational effort to generate such a lead set in real time. However, an exact reconstruction of the waveshapes of the VCG is not our aim. The purpose of the lead selection is to have 'spatial' information of the cardiac events for detection and typification purposes.

For these reasons, we tried to find a set of three quasi-orthogonal leads out of the 12-lead ECG that best represented the X, Y, and Z leads of the Frank VCG, instead of using some general transformation matrix to derive a semi-Frank VCG from the 12-lead ECG. From the multilead CSE library [12] in which the 12-lead ECG and the Frank leads are all recorded simultaneously, the averaged QRS complexes of the 12-lead ECGs and of the Frank VCGs were computed. The correlations between 10 amplitudes in the bandpass-filtered representative QRS complex in each ECG lead and the three Frank leads were determined for each case. The computation of the correlations is identical to that in the algorithm for the QRS typification of MEANS [3]. Also, scaling factors between the bandpass-filtered complexes were determined

*Table 1. The 10, 50, and 90 percentiles of the correlations between the QRS complexes in the VCG leads and QRS complexes in each of the 12 leads of the ECG.**

	X			Y			Z		
	10%	50%	90%	10%	50%	90%	10%	50%	90%
I	0.58	0.96	0.99	-0.69	0.54	0.93	-0.71	0.26	0.90
II	0.10	0.84	0.98	0.63	0.98	0.99	-0.79	0.09	0.74
III	-0.85	0.07	0.87	-0.09	0.87	0.99	-0.87	-0.17	0.77
aVR	-0.99	-0.96	-0.72	-0.99	-0.89	-0.07	-0.86	-0.16	0.69
aVL	-0.47	0.64	0.96	-0.93	-0.42	0.66	-0.84	0.17	0.90
aVF	-0.53	0.62	0.95	0.60	0.98	0.99	-0.85	-0.03	0.73
V1	-0.95	-0.71	0.08	-0.96	-0.58	0.42	-0.98	-0.86	-0.35
V2	-0.87	-0.30	0.70	-0.90	-0.43	0.52	-0.99	-0.92	-0.57
V3	-0.66	0.43	0.93	-0.80	0.06	0.83	-0.99	-0.91	-0.27
V4	-0.10	0.90	0.99	-0.53	0.61	0.93	-0.95	-0.56	0.43
V5	0.73	0.98	0.99	-0.24	0.73	0.97	-0.84	-0.13	0.71
V6	0.88	0.98	0.99	-0.02	0.83	0.97	-0.70	0.19	0.86

*These data were obtained from the 250 cases of the CSE multilead library [12].

by means of a least-squares fit procedure. Tables 1 and 2 give the results of this experiment. The 10, 50, and 90 percentile values are given for the correlations and scaling factors, respectively, for each combination of the three leads of the VCG and the ECG leads.

The best lead is found by taking the highest 50-percentile value (in the absolute sense) for the correlation with the smallest range. It is clear that lead X is best represented by lead V6. Although for leads Y and Z the correlations are more scattered, the selection of a lead from the ECG could easily be made. Lead V2 gave superior results for lead Z as compared to the other leads. For lead Y, two alternatives are available, namely II and aVF. The input system needs only to record two extremity leads since the other four can be computed from these two. Two out of leads I, II, and III can be recorded by using one of the electrodes (in general the left foot) as a reference. Leads aVR, aVL, and aVF need additional computations, and therefore lead II was selected as a representation of lead Y. Later on, only the representative P-QRS-T complexes of the four dependent leads are computed.

With respect to the scaling, it is clear that lead V2 has considerably more power than lead Z, resulting in a more favorable SNR, at least for the QRS complexes. Furthermore, by definition, its polarity is the opposite of the Z lead. In order to bring the magnitude of lead V2 in the proper range with respect to leads II and V6, a scaling factor of $-1/2$ is used.

Table 2. The 10, 50, and 90 percentiles of the scaling factors between the three VCG leads and the twelve ECG leads.*

	X			Y			Z		
	10%	50%	90%	10%	50%	90%	10%	50%	90%
I	0.62	1.69	3.03	-0.89	0.49	1.81	-4.08	1.65	9.88
II	0.04	1.11	2.28	0.42	0.80	1.15	-4.26	0.39	7.91
III	-2.00	0.03	1.72	-0.18	0.76	1.46	-8.52	-0.84	5.24
aVR	-2.50	-1.58	-0.92	-1.78	-0.91	0.01	-9.42	-0.94	4.76
aVL	-1.73	1.17	3.10	-2.26	-0.37	1.05	-7.62	1.60	11.64
aVF	-1.10	0.75	2.52	0.45	0.90	1.47	-7.10	-0.10	7.46
V1	-1.60	-0.60	0.06	-1.15	-0.30	0.30	-5.40	-2.81	-0.77
V2	-0.85	-0.18	0.54	-0.63	-0.14	0.25	-3.44	-2.23	-0.81
V3	-0.53	0.24	0.91	-0.40	0.02	0.52	-3.42	-2.11	-0.63
V4	-0.13	0.63	1.00	-0.23	0.21	0.72	-4.20	-1.04	0.95
V5	0.48	0.78	1.04	-0.13	0.33	0.94	-3.14	-0.01	3.23
V6	0.65	0.97	1.28	-0.08	0.43	1.00	-2.32	0.62	6.09

*Derived from the CSE multilead library.

Sampling-rate reduction

Besides by a proper selection of the leads, the computational effort can be lessened by a reduction of the sampling rate. In order to acquire accurate measurements for the rhythm and the contour classification programs, the leads should preferably be sampled at a rate of 500/s [15]. It is, however, not necessary to use all samples in the different processing steps. In MEANS, the QRS and P-wave detection algorithms and the QRS typification procedure all work on signals that are in sampling rate reduced to 100 Hz.

In our multilead program, the sampling rate in the three quasi-orthogonal leads is also reduced to 100 Hz. An 11-point, recursively programmed moving averager is used. Apart from the lowpass-filtered output, the high-frequency residuals are also easily available. These high-frequency components are used in the artifact detection scheme described below. Since artifacts can occur in each of the leads without a simultaneous distortion in the selected leads, artifact detection must be performed in all leads. Therefore, the 11-point moving averager is applied to each of the leads in order to obtain the high-frequency components for artifact detection while the low-frequency components are only used in the three selected leads. Before storage of every fifth sample of the lowpass-filtered signal of the selected leads, it is differentiated according to $y(i) = x(i) - x(i-2)$

in which $x(i)$ is a 100-Hz sample of one of the leads.

QRS detection

The QRS detection of MEANS is basically an off-line detection procedure. It requires that the complete signal is available and that all local extrema in the spatial velocity are determined before the labelling of these extrema can be done [3].

In our on-line QRS detection algorithm, a pseudo spatial velocity is computed from the quasi-orthogonal leads by taking the sum of the absolute values of the differentiated 100-Hz signals. This pseudo spatial velocity is equivalent to the detection function used in MEANS. In a learning period of 1.6 s the maximum value of the spatial velocity is determined. This extremum is considered to belong to a QRS complex and the threshold for the detection of the next complex is set as a percentage of this maximum. An improved performance - in terms of speed - of the detector is achieved by looking only for those local extrema in the spatial velocity that exceed the detection threshold.

In order to be able to reject local extrema from P and T waves, the decision whether a local extremum is from a QRS complex or not has to be postponed until no large local extrema are

found in a sufficiently long time interval. In order to make the real-time detector compatible with the QRS detector in MEANS, the following criteria were used:

- When two extrema, both larger than the threshold, occur within 200 ms of each other, the largest is taken and the other is discarded.
- When two extrema, both larger than the threshold, occur within 400 ms of each other, the smallest of the two is discarded when its amplitude is less than 60% of the amplitude of the largest one. Otherwise, the first extremum is considered to be a QRS complex.

Consequently, when no extremum has been found or when all extrema are eliminated within an interval of 400 ms after a local extremum, that extremum can be labelled as resulting from a QRS complex. After the detection of a QRS complex, the threshold for detecting QRS complexes is updated. This threshold is set as a percentage of the average of the local extrema in the spatial velocity which were labelled as QRS complexes.

With the multilead CSE library, the number of false-positive and false-negative detections were determined as a function of the threshold for the detection of QRS complexes (Figure 2). This data revealed that the same threshold could be used as in the QRS detector of MEANS for the VCG (about one-third of the average).

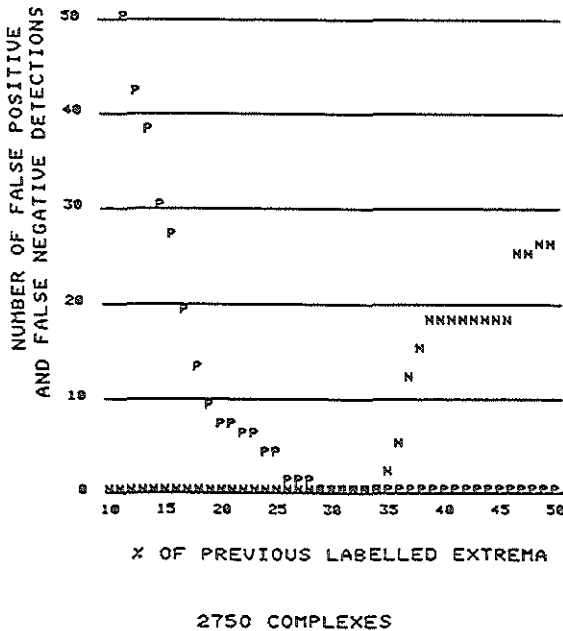


Figure 2. The number of false-positive (P) and false-negative (N) detections as a function of the threshold for accepting a local extremum as QRS complex.

QRS typification

In MEANS, the reference points for the QRS typification and complex averaging are determined in the bandpass-filtered QRS complexes of the 500-Hz signals. When such a procedure is used for on-line analysis, the three quasi-orthogonal leads must be filtered twice: once for detection and once for typification. Since one of our requirements was a high processing speed, the performance of the typification algorithm using the differentiated 100-Hz signals was investigated.

As will be shown shortly, a reliable QRS typification procedure based on 100-Hz samples can be designed. An accurate reference point for complex averaging is determined from a small portion of the 500-Hz signal in the vicinity of the approximate reference point found with the typification algorithm.

According to the typification procedure of MEANS, a reference point is determined for each reference complex by searching for the largest of the extrema in the three differentiated leads. Ten amplitudes in the differentiated 100-Hz signals for each QRS complex and for each lead are used to compare the complexes. With the aid of a rough estimate of the onset and endpoint of the QRS complex, the position of these amplitudes is determined in such a way that they cover the reference QRS complex best. From these amplitudes, the same similarity measures as in MEANS [3,16] are determined. These similarity measures, SIM1 and SIM2, reflect the similarity in shape and power, respectively.

The major difference between MEANS and the on-line procedure is the resolution of the reference point: 2 ms for MEANS but 10 ms for the on-line procedure. Due to this reduced resolution, two complexes which are compared with each other may not be accurately aligned. In Figure 3, an example is shown where a considerable shift in the reference point occurs due to this reduced resolution. Aligning the complexes at the extreme values does not yield the maximum correlation. In order to cope with this problem, the typification procedure was slightly modified.

Similar to the procedure in MEANS, a three-way classification scheme is used: two complexes can either be similar or different or no definite decision can be made. For the latter case, an additional test is performed when both similarity measures are not too far from the region for the classification of similar complexes. When one of the sample points adjacent to the reference point has an amplitude of at least 50% of the amplitude of the reference point, either in the reference complex or in the complex that is compared with the reference complex, both complexes are compared using such a point for alignment. When a shift is made, again the three-way classifier is used. Only one relative shift to the left and one to the right is made.

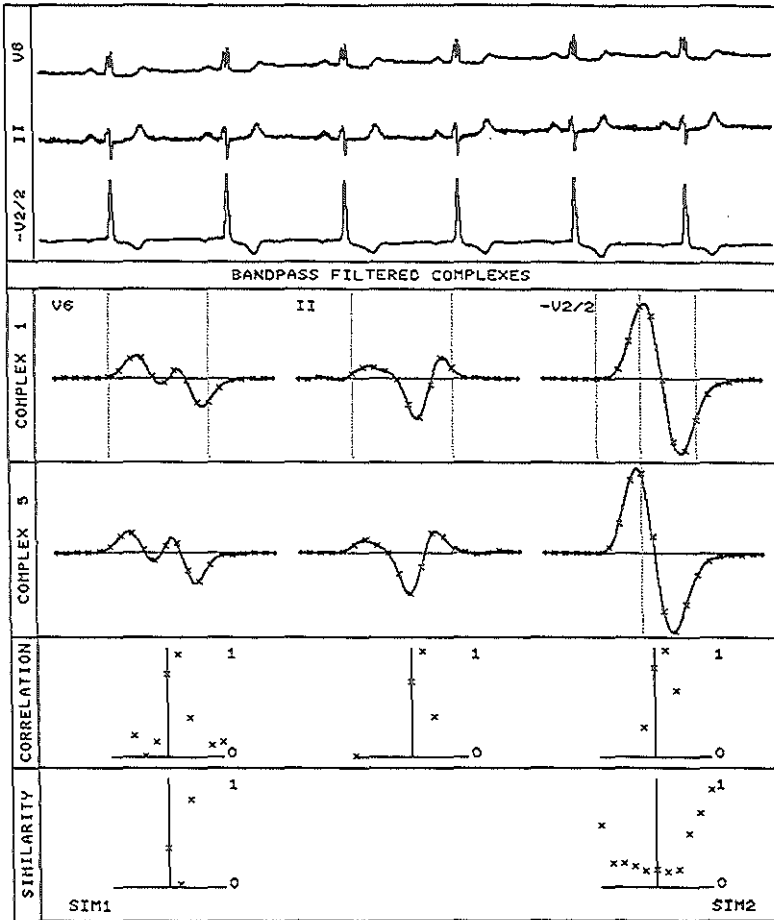


Figure 3. An example of an ECG in which the reduced accuracy of the reference point results in a nonoptimal alignment of the QRS complexes. The correlation as a function of the shift between the two complexes shows that the maximum value is not achieved at the point where both extrema in the selected lead coincide.

Figure 4 shows the decision regions that are used in the real-time QRS typification procedure. In order to have the procedure running in real time, a lot of bookkeeping is necessary since a complex may either certainly belong to one of the created classes or possibly belong to (a subset of) the already created classes.

When a new incoming complex is assigned to a class, one has to compare all complexes that possibly belong to that class with this newly classified complex. Also complexes which are found to be similar to this new complex should serve as a reference complex for not-yet-labelled complexes. Furthermore, when it is decided that one of the already processed complexes does certainly not belong to the created classes, this complex can now serve as a reference for a new class, and all not-yet-typified complexes have to be compared with this new class of complexes.

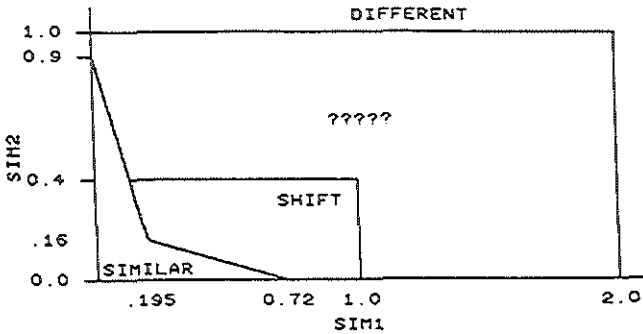


Figure 4. The decision region of the three-way classifier used in the real-time typification procedure.

Artifact detection

The real-time detection of artifacts is very important in on-line ECG analysis. When an excessive amount of artifacts is detected, the technician should be given feedback about the leads in which poor signal quality is present and be assisted in the recording of good quality ECGs.

Of the commonly seen artifacts, powerline interference is routinely corrected using a filter described in [17]. A more detailed analysis of this filter is found in [11].

Baseline sways are not detected in real time, except when the sample values are reaching the maximum or minimum amplitudes that the A/D convertor can handle. The remaining baseline wandering may be corrected in the beat averaging, using a linear correction procedure [11]. Heavily disturbed ST-T segments are detected by means of the ST-T typification procedure [11] and are not taken into account in the beat-averaging procedure.

The remaining types of disturbances are spikes and muscle artifacts. The high-frequency disturbances are detected by using the residuals from the 11-point moving averager which is

also used for the sampling-rate reduction. An average of the absolute values of five consecutive residuals is determined and stored in a delay line. The exponentially weighted sum of the averages determines the amount of noise in a lead. The QRS complexes themselves also give quite large residuals. It is even possible that these residuals become larger than those from too-noisy TP segments. However, when a QRS complex is detected, one can skip the residuals of the QRS complex and use only those from the signal segments between the QRS complexes in the combination of the weighted average. Since there is a delay of 400 ms between the occurrence of a QRS complex and the time at which it is detected, a delay line of 500 ms has to be used, because a signal segment of 200 ms around the point where the QRS complex is detected is discarded in the noise detection. A threshold of 35 μV proved to be an acceptable threshold for the detection of excessive noise.

The noise-detection procedure operates on all eight leads. Whenever excessive noise is detected in one or more leads, the data-acquisition program is reinitialized and the operator is informed of the leads in which the noise occurs.

We suggested an off-line detection procedure for spikes that works reasonably well [11]. This procedure, however, requires a lot of computer cycles and hence is not suitable for on-line application. However, spikes which are too small to trigger the QRS detector are sufficiently detected by means of the noise-detection algorithm (see Figure 5 for an example).

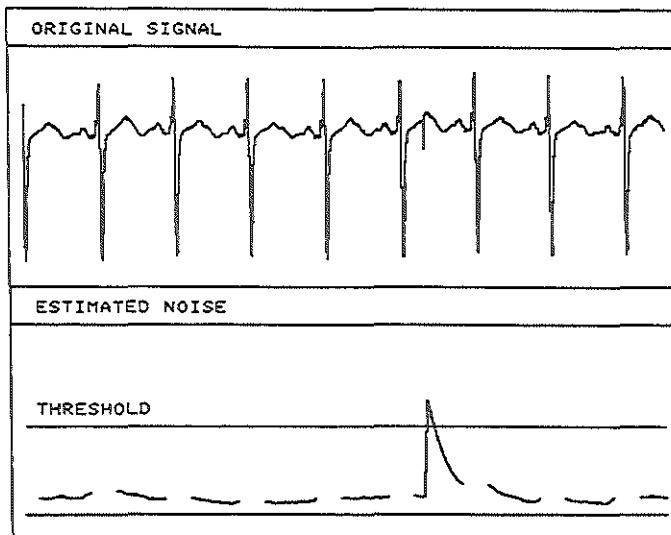


Figure 5. An example of a spike that is detected by means of our detection procedure for high-frequency disturbances.

Therefore, only those disturbances which give rise to false-positive detections have to be dealt with. Since we may assume that each of such disturbances has a unique waveshape, one can investigate those detected events that were given a nondominant label by the QRS typification and that occur only once. Although such false-positive detections occurred only in a few cases in the multilead CSE library, we established the criterion that an event occurring only once must be considered an artifact when the maximum over the leads of the maximum first derivative - in an absolute sense - in such an event is at least 2.5 times as high as the maximum over the leads of the averaged values of the maximal derivatives of the dominant complexes. The validity of this criterion was checked with the aid of the VCGs and ECGs of data sets 1 and 2 of the CSE project.

P-wave detection

With respect to the P-wave detection, no changes were made in the algorithms of MEANS [7,11]. During the development and subsequent improvements of the P-wave detector, much attention was already given to speed and performance. All preprocessing steps and all criteria of MEANS as used for the VCG were implemented for the analysis of leads V6, II, and $-V2/2$.

Waveform recognition

The estimation of the onsets and endpoints of the QRS complexes and P waves, as well as the estimation of the endpoint of the T wave, can be done with the complete set of 8 or 12 simultaneous leads. It is known that the onsets and endpoints of the various components of the P-QRS-T complex in different leads do not occur at the same instants. Using all leads for the estimation of the earliest onset and latest end involves the use of highly redundant information, and therefore early activity in only one or two leads may be considered noise because the activity in the other leads starts later. It is to be expected that there will be some optimal combination of leads for the wave recognition.

Without further research, the quasi-orthogonal lead set consisting of leads V6, II, and V2 - the latter divided by 2 - was chosen as the lead set for waveform recognition. The template waveform-recognition procedures of MEANS [5,8,10] are also used in the multilead program.

Evaluation results

Our package for on-line ECG/VCG analysis has been evaluated on the multilead CSE library. This library consists of 250 simultaneously recorded ECG and VCG leads. The duration of the recordings varies between 8 and 10 s. The four cases with artificial pacemaker pulses

were not taken into account for the evaluation results. These ECGs and VCGs were also processed with MEANS, and hence a comparison between the performances of both systems can be made.

QRS detection

Table 3 gives the evaluation results for the QRS detection procedures of both MEANS and the multilead program. Although each lead group contains the same number of complexes, differences in the total number of correctly detected and missed complexes may occur because the first and/or last complex in a lead group may be missed due to slight differences in the reference points. Furthermore, there is also a small difference in the QRS detection routines of MEANS and our multilead program with respect to the first and last time instant where a complex may be detected. The missing of such a complex was, of course, not considered to be an error.

*Table 3. Evaluation results of the QRS detection algorithm of MEANS and the multilead program.**

Ref	I II III		aVRLF		V1 V2 V3		V4 V5 V6		X Y Z		MULTI	
	+	-	+	-	+	-	+	-	+	-	+	-
+	2831	10	2830	11	2845	0	2821	21	2845	2	2889	0
-		1		0		0		8		1		0

*ECGs and VCGs are of the multilead CSE library.

It is clear that the multilead program performs very well in comparison with the performance of the algorithm in MEANS in the four lead groups of the 12-lead ECG and even in comparison with the performance for the VCG. The performance of the algorithm of MEANS for the VCG is better than for three of the four lead groups of the ECG. The errors in the VCG were due to the fact that one spike was falsely identified as a QRS complex and two interpolated ventricular beats were missed.

QRS typification

Table 4 gives the evaluation results of the QRS typification algorithms for the various lead groups. The errors of the multilead program occurred only in one record. In this case, the wrong complex was labelled as the 'normal' QRS complex (see Figure 6). In the analysis of the VCG with MEANS, the first complex was also taken into account for the typification. Now, enough complexes of the 'normal' type were detected to label them as such, although one type of

ventricular beat occurred more frequently. For the multilead program only two 'normal' complexes were found and were given the label 3. Note that the performance of the multilead program is better than the performance of MEANS in each of the lead groups of the 12-lead ECG. The criteria used in the QRS typification were derived from another data set, and hence the multilead CSE database served as a truly independent test set for this evaluation.

Table 4. Evaluation results of the QRS typification procedure of MEANS for the four lead groups of the 12-lead ECG, the VCG, and the multilead program.

Ref	I II III				aVRLF				V1 V2 V3			
	1	2	3	4	1	2	3	4	1	2	3	4
TYPE 1	2592	9	1	0	2592	9	1	0	2649	2	0	0
TYPE 2	3	59	0	0	3	54	0	0	3	65	0	0
TYPE 3	1	0	8	0	1	2	7	0	1	1	6	0
TYPE 4	1	0	0	0	0	1	0	0	0	0	0	0
	V4 V5 V6				X Y Z				MULTI			
TYPE 1	2598	13	0	0	2696	0	0	0	2514	0	2	0
TYPE 2	2	59	0	0	2	64	0	0	0	56	0	0
TYPE 3	10	1	1	0	1	0	8	0	6	0	4	0
TYPE 4	1	0	0	0	0	0	0	1	0	0	0	1

P-wave detection

The most interesting aspect of the evaluation of the P-wave detector is its performance in the ECG as compared to the performance in the VCG. In our previous evaluation, the performance for the lead groups of the 12-lead ECG was never considered because of the short duration (approximately 5 s) of those lead groups. The current data set, however, provides a lead-group duration of 8 or 10 s, also when the data are formatted in the conventional way.

Table 5 gives the evaluation results of the P-wave detector. It is surprising to see that the results for the multilead ECG are even better than those for the VCG. The only explanation for these differences is that, in comparison with the VCG, P waves are more detectable in the selected leads. This may be especially true for lead II, which is often used for the diagnosis of atrial enlargement because of the considerable amplitude of the P wave in that lead.

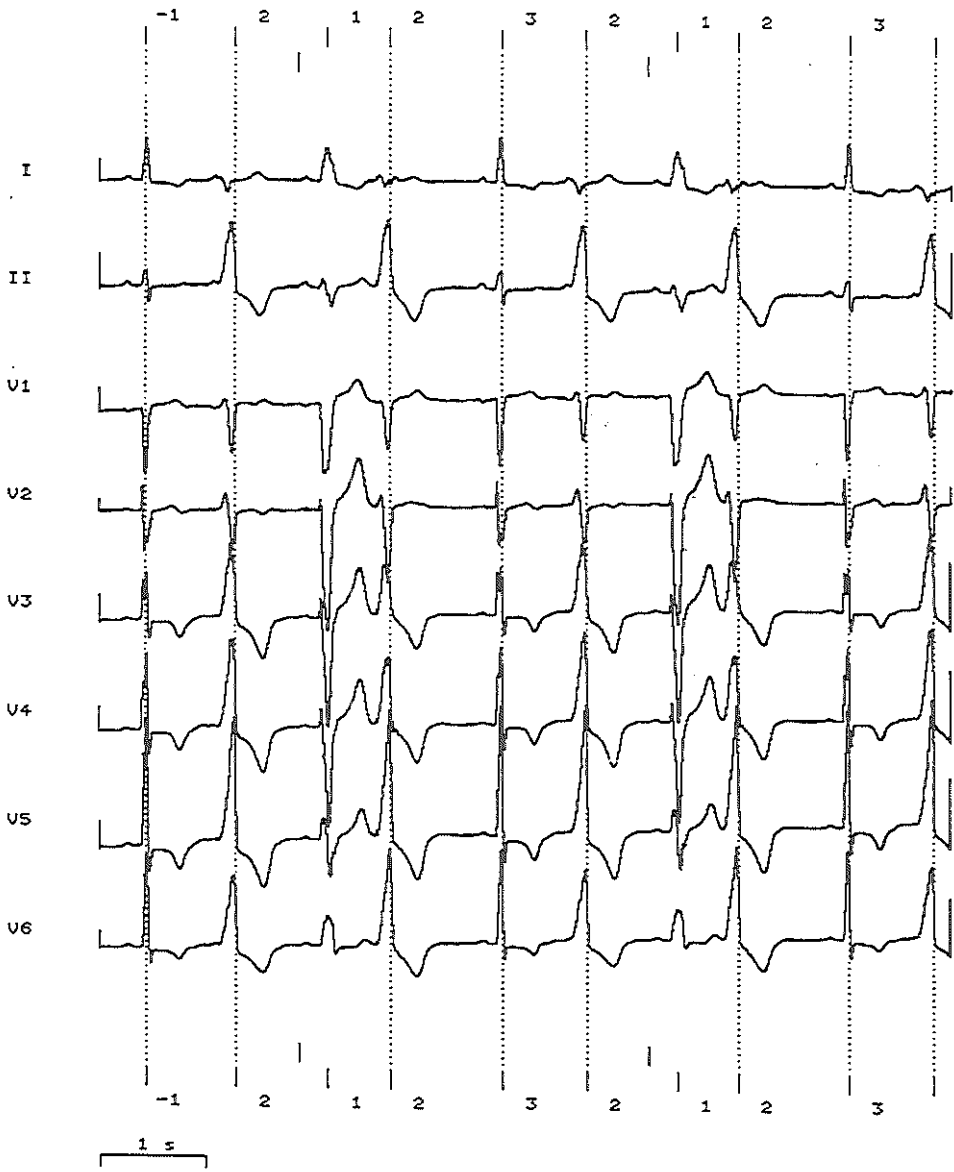


Figure 6. The only ECG of the multilead library in which the QRS typification procedure made an error. Note that the 'normal' complexes were given label 3.

Table 5. Evaluation results of the P-wave detector for the four lead groups of the 12-lead ECG, the VCG, and the multilead program.*

Ref	I II III		aVRLF		V1 V2 V3		V4 V5 V6		X Y Z		MULTI	
	+	-	+	-	+	-	+	-	+	-	+	-
+	2152	17	2104	23	2121	48	1879	83	2143	50	2040	39
-	45		32		53		18		29		2	

*Only cases in which no flutter waves were detected, were used in this evaluation.

The results presented in Table 5 are based on those cases in which no flutter waves were detected. The performance of the flutter-wave detector does differ considerably for the different lead groups. In the VCG, three cases were missed and one false-positive detection occurred. For the multilead ECG, four false-positive detections were made and no false-negative ones. The program seems to be more sensitive in a lead combination of V6, II, and V2/2 than in the VCG. The number of cases in which real flutter waves are present is limited, and therefore the collection of more multilead cases with flutter waves is necessary in order to have reliable evaluation results for the flutter-wave detector.

Waveform recognition

Until now, there is no objective and generally accepted reference for the multilead CSE library with respect to the waveform-recognition points. In order to assess the performance of the waveform-recognition procedure for the multilead program in a more subjective way, the following experiment was performed. The multilead ECGs were processed with our multilead program. Subsequently, the averaged P-QRS-T complexes were formatted in the conventional four lead groups of the 12-lead ECG. The waveform-recognition procedure of MEANS was then applied to these lead groups and a comparison was made of the waveform-recognition points found by both programs.

The aim of the multilead analysis is to find the earliest onset and the latest endpoint of the different parts of the P-QRS-T complex. A first assessment of the achievement of this goal was to make histograms of the differences between the waveform-recognition points found with MEANS and the waveform-recognition points found with the multilead program. Figure 7 shows the distribution of the differences between both programs, taking the multilead waveform-recognition points as a reference. It is clear that, in general, the assumption with respect to the detection of the earliest onset is correct. In all lead groups except V1-V3, the onset is on the average later than in the multilead program, while in V1-V3 the modus of the distribution is at

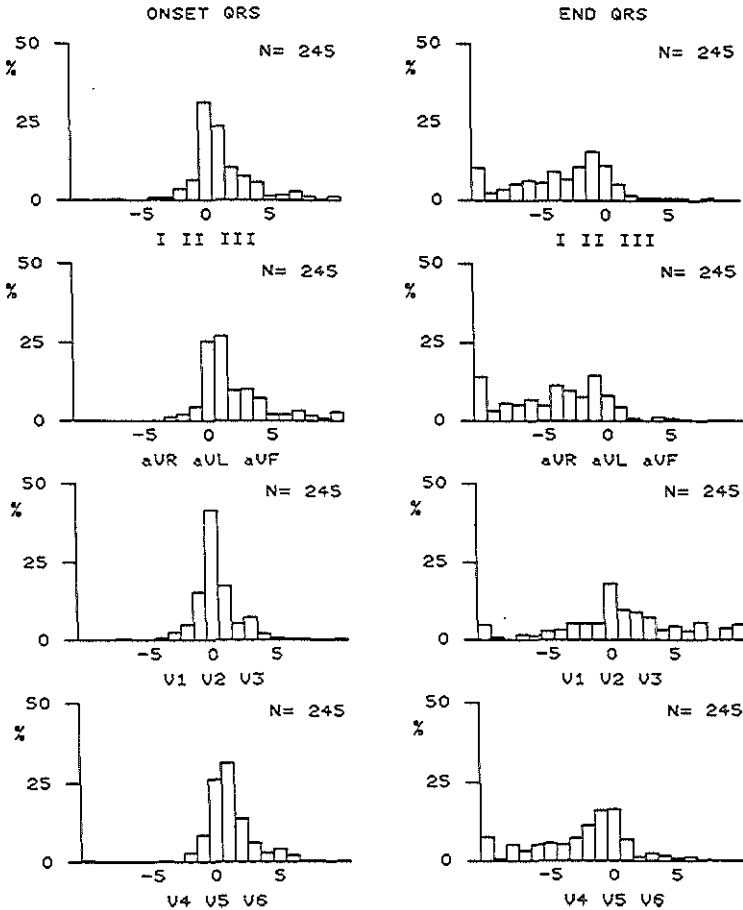


Figure 7. Histograms of the differences between the waveform-recognition points found with the multilead program and those found with MEANS in the various lead groups of the 12-lead ECG. The multilead onsets and endpoints were taken as a reference. Hence a positive difference indicates a point that is found at a later time instant than with the multilead program.

zero difference and the variance is within acceptable limits. With respect to the endpoint of the QRS, a different situation exists. The differences between the multilead program and MEANS are much larger than for the onset points. The scatter in lead group V1-V3 is extremely large. A visual analysis of these cases reveals that this large scatter can be attributed to a specific type of QRS complex in leads V1-V2-V3. In Figure 8, a typical example is shown where two points

are candidates for the endpoint of the QRS complex. When we also take into account the information of the other lead groups, it becomes clear that the first point is most likely the end of the QRS complex.

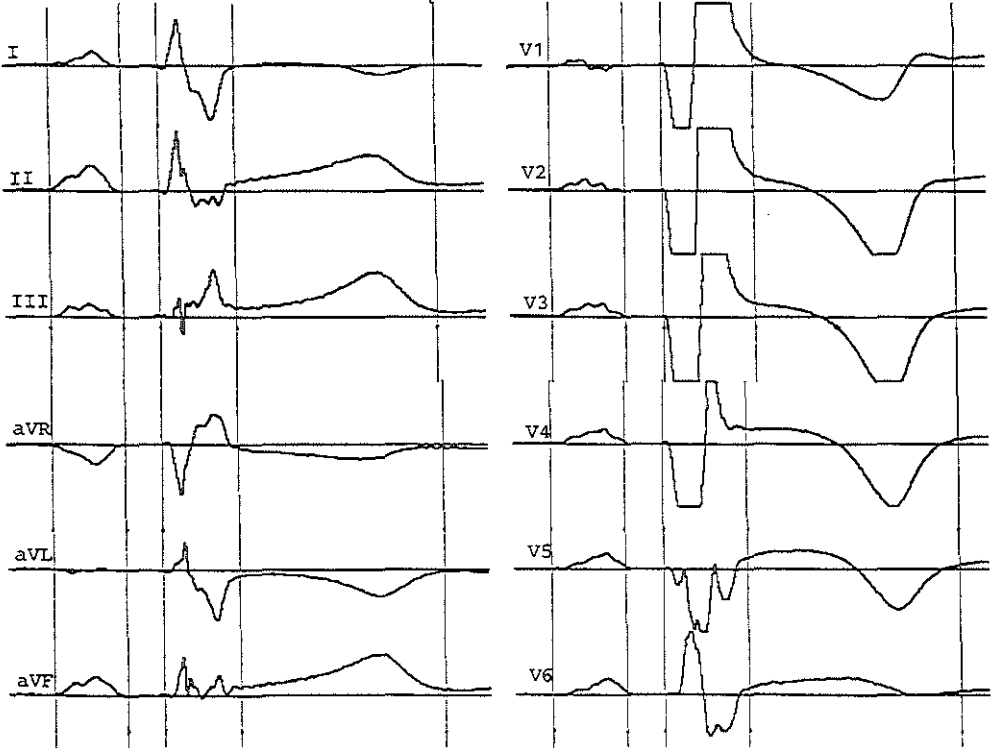


Figure 8. An example of an ECG in which the end of the QRS complex in lead group V1-V3 is ambiguously defined. Taking into account also the information of the other lead groups, the first point where a distinct change of slope occurs seems to be the most likely point for the estimation of the end of the QRS complex.

In order to assess more quantitatively the performance of the waveform-recognition procedure of the multilead program, those cases in which the onset point found with MEANS was more than 4 ms earlier in at least one of the lead groups as compared with the result of the multilead program as well as the cases in which the onsets found with MEANS were 4 ms later in at least three lead groups as compared with the multilead onset were selected for visual examination. This selection was made to identify those cases in which the multilead program found the onset too late or too early, respectively. A similar procedure was used for the endpoint estimates, but with a threshold of 8 ms. The selection criteria of 4 and 8 ms for onset

and endpoint, respectively, were both 2 ms less than the thresholds used by the referees of the CSE project for differences between an individual reading, and the median of the readings of the referees for the selection of cases that needed to be reviewed.

With the aid of this procedure, we identified four cases in which the onset found by the multilead program was too early and eight cases in which the onset was too late. Of the latter eight cases, four errors were due to the limitations of the template waveform-recognition method. In the other four cases one or more leads showed earlier activity than the leads used for the computation of the detection function. The endpoint estimate was too early in 7 cases. In 20 cases this endpoint was too late. In the majority of the cases in which the endpoint was too late, this was due to the fact that the endpoint in lead V2 was ill defined, as in the case shown in Figure 8.

With the aid of the referee waveform-recognition points for data set 1 of the CSE project [18], we are currently trying to establish criteria for the identification of the problem cases such as shown in Figure 8 in order to improve the performance of our waveform-recognition procedure.

Summary and conclusions

We have described the modifications to MEANS, our modular ECG analysis system for off-line analysis, that were necessary to transform this system into a software package for real-time ECG analysis. The evaluation studies with the aid of the multilead CSE library have shown that good performance is maintained, as compared with MEANS, and that for some modules the performance appears to be improved.

The modularity of the software has been maintained. It has eased the development of the modifications because both the structure of the system and the requirements, with respect to the input and output of each of the modules, were again clearly defined.

The modifications have been developed on a minicomputer. Hence no data are available as yet on the true processing time of the different algorithms for a microprocessor implementation of the system. Our current work is directed toward the implementation of the routines on a microprocessor system. The performance of the prototype system will reveal whether a multiprocessor approach is necessary.

Acknowledgment

We are grateful to J.L. Willems, Ph.D., coordinator of the CSE project for his permission to use the multilead CSE library for our studies.

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CHAPTER 3

Classification Methods for Computerized Interpretation of the Electrocardiogram

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Methods of Information in Medicine 1990;29:330-6

Abstract

Two methods for diagnostic classification of the electrocardiogram are described: a heuristic one and a statistical one. In the heuristic approach, the cardiologist provides the knowledge to construct a classifier, usually a decision tree. In the statistical approach, probability densities of diagnostic features are estimated from a learning set of ECGs and multivariate techniques are used to attain diagnostic classification. The relative merits of both approaches with respect to criteria selection, comprehensibility, flexibility, combined diseases, and performance are described. Optimization of heuristic classifiers is discussed.

It is concluded that heuristic classifiers are more comprehensible than statistical ones; encounter less difficulties in dealing with combined categories; are flexible in the sense that new categories may readily be added or that existing ones may be refined stepwise. Statistical classifiers, on the other hand, are more easily adapted to another operating environment and require less involvement of cardiologists. Further research is needed to establish differences in performance between both methods. In relation to performance testing the issue is raised whether the ECG should be classified using as much prior information as possible, or whether it should be classified on itself, explicitly discarding information other than age and sex, while only afterwards other information will be used to reach a final diagnosis. Consequences of taking one of both positions are discussed.

Key words: ECG classification, optimization, gold standard

Introduction

The interpretation of the electrocardiogram (ECG) is a pattern recognition task. Computer programs that perform this task consist of a measurement part and a classification part. In the measurement part, the ECG signal is analyzed and features are extracted, i.e., a set of measurements is computed containing all information that is necessary for classification. In the classification part, a diagnostic interpretation is performed, i.e., based on the features a classification procedure allocates the ECG to one or more diagnostic categories.

The classification part of ECG computer programs is the subject of this paper. The different methods of diagnostic classification that are being used in computerized ECG interpretation will be described and their relative merits will be considered. Several issues related to the optimization of diagnostic methods will be discussed.

Methods

Basically, two methods for diagnostic classification of the ECG can be discerned: a heuristic one and a statistical one. In the heuristic approach one attempts to simulate the reasoning of the cardiologist in interpreting the ECG. In the statistical approach multivariate statistical techniques are used.

Willems [1] has pointed out that the classification parts of most ECG computer programs are a mixture of both approaches. Most programs that primarily use heuristic methods employ uncertainty qualifiers for their main diagnostic categories. Statistical classification programs, on the other hand, use heuristic knowledge to discriminate sets of disease classes prior to the application of statistical techniques.

Most ECG computer programs currently available predominantly use heuristic classification methods. Table 1 gives the methods which are employed in programs participating in the CSE study [2]. Some programs only analyze the vectorcardiogram (VCG). The classification methods to be described, however, are applicable to both the ECG and the VCG.

Heuristic approach

In the heuristic approach the objective is to simulate the reasoning and decision making of a skilled cardiologist. Heuristic knowledge is provided by one or more cardiologists. Two heuristic classification methods will be described: decision-tree classifiers and fuzzy classifiers.

Table 1. Classification methods used by programs in the CSE diagnostic study.

program	principal investigators	lead systems	classification method
AVA (USA)	Pipberger	VCG	statistical
Glasgow (UK)	Macfarlane	ECG	heuristic
HES (D)	Zywietz	ECG+VCG	statistical
HP (USA)	Monroe	ECG	heuristic
Leuven (B)	Willems	ECG	statistical
Louvain (B)	Brohet	VCG	heuristic
Lyon (F)	Arnaud, Rubel	VCG	heuristic
Marquette (USA)	Rowlandson	ECG	heuristic
MEANS (NL)	Van Bommel	ECG+VCG	heuristic
MEDIS (D)	Pöppel	ECG	heuristic
Nagoya (J)	Okajima, Ohsawa	ECG	heuristic
Padova (I)	Degani	ECG	heuristic
Porto (P)	Abreu-Lima	VCG	heuristic

Decision trees

Decision trees are the most common type of classifiers for ECG interpretation. A decision tree consists of a hierarchy of decision nodes which are connected by branches. Each node contains a test, the outcome of which determines the branch to be taken. In its simplest form the decision tree is binary, i.e., each decision node has only two descendants. The test usually compares a feature value with a threshold. To classify an ECG, decision nodes are tested sequentially, starting at the top node until a leaf is reached. Each leaf of the tree assigns the ECG to a certain diagnostic category.

To express heuristic knowledge, representations other than decision trees may be used, for instance decision tables or 'if-then' rules. These representations, however, can in principle all be converted to decision trees. In the following, therefore, only decision trees will be considered.

ECG interpretation programs that use decision-tree type classifiers are often far more complex than the above scheme suggests. First, in general not only one but many trees will be constructed. It is often conceptually simpler to define one or more trees for a specific diagnostic class than having to take all classes into account in a single tree. Additional trees may be required to deal with interactions if multiple categories are involved.

Second, the assignment to a class will often be qualified by an uncertainty statement. Common qualifiers are: 'consistent with', 'probable' or 'possible'. In effect, since each qualified

category constitutes a separate category, the number of categories increases and thus the size and complexity of the decision trees.

Third, decision nodes may contain tests which are more comprehensive than the comparison of a feature value with a threshold. For instance, several simple threshold tests may be combined by logical conjunctions and/or disjunctions, or the test may operate on a set of leads, e.g., the Q duration should be greater than 20 ms in at least two leads from II, III or aVF. The test may also have to execute special algorithms, e.g., a point scoring algorithm for the determination of left ventricular hypertrophy.

Fourth, the heuristic classifier may contain procedural knowledge. Exclusion rules will often be specified which inhibit certain categories in the presence of others.

The construction of a decision tree is generally guided by heuristics. No clear-cut rules are available to select the tree structure, the features, and the threshold values. However, once the tree structure and the features are selected, threshold values may be derived from a database of ECGs, thus supplementing human experience [3,4].

Given a database of labelled ECGs and their feature values, it is possible to generate decision trees automatically. Algorithms exist which recursively partition the feature space yielding a decision tree [5,6]. Talmon [7] used this technique to derive decision trees for the typification of QRS complexes; it has not yet been used for the diagnostic classification of ECGs.

Fuzzy classifiers

In expressing heuristic knowledge, cardiologists often use imprecise descriptions, e.g., "prolonged QRS duration" or "large Q wave". Zadeh [8] proposed a theoretical framework for the classification problem in case of such fuzzy descriptions: fuzzy-set theory. A central notion in this theory is the 'intensity' with which an object belongs to a set. It is expressed by a number, the degree of membership, which may vary between 0 (complete exclusion) and 1 (complete inclusion).

Fuzzy-set theory has also been applied to computerized ECG classification by Degani and coworkers [9,10]. They distinguish three steps: (1) Transformation of feature values in fuzzy linguistic terms resulting in a fuzzy description of the ECG; (2) Determination of the degree of membership of the fuzzy description to each diagnostic category; (3) Ranking of the degrees of membership in order to choose the best alternative.

Two types of heuristic knowledge need to be provided by a cardiologist. First, for the value range of each feature three membership functions have to be specified: normal, borderline, and abnormal. Second, tables have to be provided for each diagnostic category linking all possible fuzzy descriptions of an ECG to three qualifiers of that category: present, possible, and absent.

The degree of membership of a description to a certain qualifier is specified in fuzzy terms: very low, low, medium, high, and very high.

Statistical approach

The main objective of the statistical approach is the allocation of an ECG to one of a set of diagnostic categories with minimum probability of misclassification. This approach has been advocated by Pipberger and coworkers [11-13]. They used linear discriminant analysis to arrive at a seven-group classification.

More recently, Lesaffre and Willems [14,15] proposed a logistic discrimination procedure. The main advantage of the logistic approach is that many different assumptions about the distribution of the features are allowed.

Linear discriminant analysis

Let $\mathbf{x}^T = (x_1, \dots, x_p)$ denote the feature vector, g the number of diagnostic classes, and D_i a particular class. The g diagnostic classes are assumed to be exhaustive and mutually exclusive. According to Bayes' rule the posterior probability of \mathbf{x} belonging to class D_i is given by:

$$P(D_i | \mathbf{x}) = \frac{f_i(\mathbf{x})P_i}{\sum_j f_j(\mathbf{x})P_j} \quad (1)$$

in which $f_i(\mathbf{x})$ is the probability density of the feature vector given diagnostic class D_i , and P_i is the prior probability of class D_i .

Assuming that the density functions $f_i(\mathbf{x})$ are multivariate normal distributed with common covariance matrix Σ , (1) reduces to

$$P(D_i | \mathbf{x}) = \frac{1}{1 + \sum_{j \neq i} \exp(-L_j)P_j} \quad (2)$$

with:

$$L_i = (\mathbf{x} - \boldsymbol{\mu}_i)^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}_i). \quad (3)$$

The mean vectors $\boldsymbol{\mu}_i$ and the covariance matrix Σ are substituted by their corresponding estimates from a database.

The probability of misclassification is minimized by assigning an ECG to the category for which its posterior probability is largest.

Logistic discrimination

Now, let $x^T = (1, x_1, \dots, x_p)$ denote the feature vector, g the number of diagnostic classes, and D_i a particular class. The g diagnostic classes are assumed to be exhaustive and mutually exclusive. The logistic approach to discrimination is to assume that the posterior probabilities have the form

$$P(D_i | x) = \frac{\exp(\alpha_i^T x)}{\sum_j \exp(\alpha_j^T x)}, \quad (4)$$

with:

$$\alpha_i^T = (\alpha_{0i}, \dots, \alpha_{pi}), \text{ and } \alpha_g = 0. \quad (5)$$

This assumption is satisfied by many distributions, including multivariate normal distributions with equal and unequal covariance matrices and several families of distributions of multivariate dichotomous variables [14,16]. Estimates of the parameter vector α are supplied by a database of ECGs. Minimum probability of misclassification is attained by assigning an ECG to the category for which the posterior probability is largest.

Comparison of methods

In the literature, a number of advantages and disadvantages of the above classification methods have been put forward [1,7,13,17,18]. Several items will be reviewed here and discussed.

Criteria selection

Decision nodes in a heuristic classifier contain criteria which in their simplest form consist of a feature value being tested against a threshold. The selection of criteria to be used by heuristic methods remains somewhat arbitrary [1,13]. Criteria may have been proposed by a single cardiologist or a group of cardiologists. However, ECG criteria are by no means standardized, which may impede the acceptance of a certain set. On the positive side, the huge experience with ECG classification, which has been accumulated in the literature, is potentially available for incorporation.

One of the aspects of the definition of criteria, the selection of features, is an important step also in the design of statistical classifiers. Often, statistical techniques are used to determine the most discriminating features [14]. However, judgmental knowledge of cardiologists is also used to reduce the number of features [12,15].

Comprehensibility

Heuristic programs are designed to simulate the cardiologist's interpretation process. Thus, the criteria employed are familiar to cardiologists. The classification of ECGs by these programs is relatively easy to follow and comprehend [1]. Some programs provide the user with the most relevant criteria that were fulfilled in a particular classification [17]. Statistical programs, on the other hand, provide less insight in the classification procedure. To improve the comprehensibility of their statistical classifier, Matthes et al. [19] developed an interactive analysis package. The user may request the values of important features used in the classification and compare them with the values that were used in training the classifier. Furthermore, discriminant values are shown and the relative importance of the features contributing to the final classification is indicated. However, considerable statistical knowledge will still be needed to appreciate the information provided by the system. This approach seems to be most worthwhile as a tool in program development.

Flexibility

Modification and maintenance of heuristic programs is relatively easy [17]. They may be refined step by step [7]. Statistical programs have to be based on a large database of ECGs. A modification necessitates the recompilation of the entire material. Direct involvement of cardiologists, however, is much less. Once a database has been acquired, construction of the classifier is straightforward.

Statistical classifiers may readily be adapted to another operating environment, for instance, when changing from a cardiological clinic to a health-screening situation. Only prior probabilities pertaining to the new situation need to be inserted, assuming that the conditional probabilities remain the same.

Combined diseases

An ECG may exhibit symptoms of more than one diagnostic category, e.g., hypertrophy and infarction may both be present. In principle, combinations of diagnostic categories present no problem to either heuristic or statistical methods. Since the latter, however, assume the categories to be mutually exclusive, combined diseases have to be handled as separate categories. This straightforward solution is often impracticable because the number of categories then increases exponentially. As a result, the size of the database to construct the classifier soon becomes prohibitive, let alone the difficulty of acquiring enough ECGs for each category. Statistical programs, therefore, are limited to the classification of a restricted number of categories, typically left, right, and bi-ventricular hypertrophy; anterior, inferior, and mixed myocardial infarction; normals [15].

Performance

Performance testing of ECG interpretation programs is an intricate subject. Many difficulties and subtleties have to be resolved, which includes the establishment of a gold standard, mapping the output of different programs to a common set of categories, the choice of appropriate test statistics, and the composition of the test database. These topics are discussed in other publications [20,21]. We will only touch upon these problems as far as they are relevant for the comparison of statistical and heuristic classification methods.

There are two important aspects of performance testing of ECG interpretation programs: accuracy and precision. Accuracy is a measure for the correct classification rate. Precision deals with the stability of the classification when the input data are perturbed.

The main motivation for using statistical methods is their promise of having an accuracy surpassing the human interpreter [11,14]. The classifier has to be constructed using a database of ECGs which have been validated by ECG-independent evidence. Heuristic programs, on the other hand, are directly based on knowledge from cardiologists. The highest accuracy attainable will then be that of cardiologists.

Numerous studies have been conducted to evaluate the performance of ECG computer programs. In only a few studies, a comparison was made between heuristic and statistical programs [1,15,18,22]. Generalization of the results of these studies is difficult since only two or three programs were involved. Furthermore, the databases used in the comparison generally were not available to others or difficult to transfer. Therefore, the establishment of a large well-documented database in the CSE project is very much to be welcomed. For the first time, an independent yardstick is available to measure the performance of all interpretation programs currently available. More pertinent results on the accuracy of programs using either classification method may then be expected. Preliminary results of a pilot study on a well-validated database of 250 ECGs suggest that the performance of the statistical programs is similar to those of the best heuristic programs [2]. It should be remarked, however, that statistical programs might have been favored because almost all cases in the database were single-disease ECGs.

The stability of statistical programs has been claimed to exceed those of heuristic programs, the reason being that all features are considered simultaneously [1]. In heuristic programs a small change in a feature value at a critical threshold might result in a different classification. Several studies reported on stability experiments [23-26]. The influence of varying conditions was tested, e.g., interpreting different periods of the same recording, resampling, adding noise, and changing the measurement set. Only a limited number of programs was compared. Although the statistical classifiers proved to be more stable than the heuristic ones, Dudeck [25] and Helppe et al. [26] also noticed large differences in the posterior probabilities of statistical programs due to small input disturbances.

Optimization

Optimization of a classification algorithm assumes the existence of an optimization criterion. In the design of a statistical classifier this criterion is the misclassification rate. On the basis of a learning set of ECGs a classifier is determined which minimizes the probability of error. As the number of ECGs in the learning set is a subset of the universe of ECGs, the resulting classifier is an approximation of the (Bayes) optimal classifier [27]. Optimization in this context consists of the construction of classifiers on the basis of ever-increasing sets of ECGs.

Contrary to the formal way of designing statistical classifiers, the development of heuristic classifiers is often a process of trial and error. Based on the experience of one or more cardiologists, a classifier is constructed which is subsequently tested on a database. This test may suggest improvements which again are tested on the same or another database.

Although conceptually simple, this process of stepwise refinement may face considerable practical difficulties. The most important one stems from the difference between the knowledge as expressed by a cardiologist and the actual implementation of this knowledge in a computer program. In general, cardiologists will not be able to understand computer programs. Even if a high-level computer language is used, a computer expert will be needed to intermediate between the cardiologist and the program [28].

Several tools have been developed to aid the program developer. Hewlett Packard developed a language specifically fit for the representation of cardiological knowledge: ECL (ECG Criteria Language) [29]. Criteria in ECL can be read and written by the cardiologist himself. A compiler translates the ECL statements and incorporates them in the interpretation program. Laks [30] reported good experiences in using this language. Rubel et al. [31] also described a special diagnostic language. They used the system for the interpretation of VCGs. Both approaches tackle the representation problem; the classification part essentially remains a black box. This may not be a problem if the classifier is simple. However, heuristic classifiers may become quite intricate, as described above. To provide insight in the actual classification, Kors et al. developed a decision-tree language (DTL) which may be interpreted, as well as compiled [32]. The interpreter contains comprehensive tracing and debugging facilities, e.g., setting of breakpoints, a step mode, a verbose mode, and on-line modification of measurements and algorithms.

Discussion

ECG computer programs have always been evaluated with respect to their performance. However, performance is only one, albeit important, aspect. Others include comprehensibility, flexibility, and the handling of combined categories. These aspects are of a more qualitative nature, which impedes objective comparison. Doubtlessly, heuristic classifiers are more comprehensible than statistical ones. They encounter less difficulties in dealing with combined categories and are flexible in the sense that new categories may readily be added or that existing ones may be refined stepwise. Statistical classifiers, on the other hand, are more easily adapted to another operating environment by changing the prior probabilities. Once a database has been acquired, involvement of cardiologists in the construction of the classifier is much less.

The accuracy of the statistical and heuristic approaches is difficult to compare. These difficulties are due to the limited number of ECG computer programs which were examined in studies on this subject, the wide range in accuracy of programs that use the same approach [21], and methodological problems [20,21]. More pertinent answers to differences in accuracy are to be expected from the final results of the CSE diagnostic study.

An important performance aspect is the sensitivity of the classifier to small disturbances in its input data. Statistical classifiers have been claimed to be more stable than heuristic ones, but the few experiments in this respect were rather ad hoc and did not allow to draw any general conclusions. Further research in this area is needed.

The claim that statistical classifiers are able to attain a higher accuracy than heuristic ones is, in our opinion, related to a more fundamental issue. The question is this: Should the ECG be classified using as much prior information as possible, or should the ECG be classified on itself, explicitly discarding information other than age and sex, while only afterwards other information will be used to reach a final diagnosis? Taking one of both positions has considerable consequences for the evaluation of ECG computer programs.

If the former position is held, the gold standard for the evaluation of ECG computer programs should be a database of ECGs which are validated by ECG-independent evidence. If the latter position is held, such a database is of value for testing the program's ability to reach a final diagnosis on the basis of the ECG alone. However, one would also be interested to know the capability of the program to reach a valid classification when the ECG is interpreted without reference to other information. In that case the gold standard has to be based on the ECG alone and should be provided by cardiologists.

Figure 1 will be used to comment on both positions. It shows the relations between the entities involved: ECG, ECG-independent evidence, validated databases, and computer interpretation. Taking the second position, ECGs are validated without explicit reference to ECG-independent information. However, criteria used to perform this validation will implicitly

be based on ECG-independent evidence (link b in Figure 1), i.e., the criteria were ultimately derived from clinical studies relating physical disorders to the ECG.

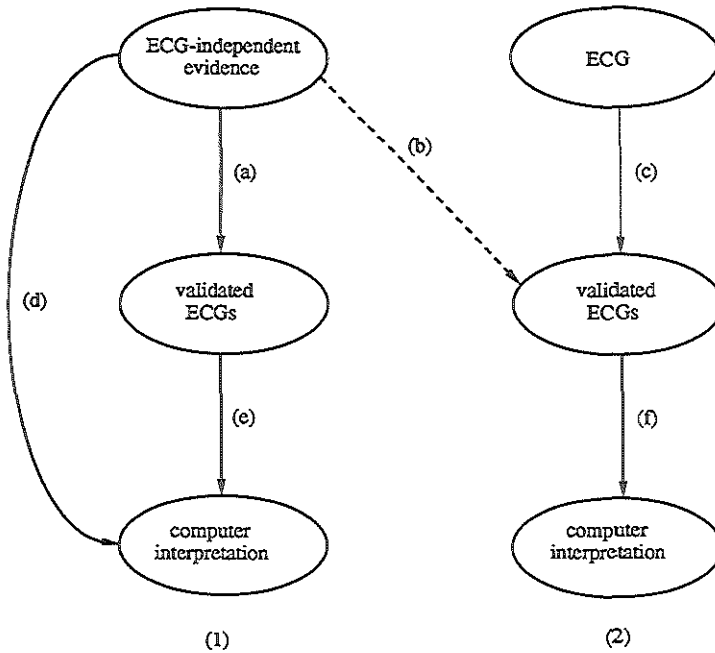


Figure 1. Entities involved in two positions held in computerized ECG interpretation. Position 1: The ECG should be classified using ECG-independent information; position 2: The ECG should be classified without reference to ECG-independent information, apart from age and sex. The links (a)-(f) are described in the text.

Objections against the second position concentrate on the inter- and intraobserver variability of cardiologists (link c). The classical study of Simonson et al. [33] showed these variabilities to be substantial. To reduce the interobserver variability one could follow a Delphi review process [34,35]. This approach was taken in the CSE project to determine a gold standard of fiducial points to test the waveform-recognition algorithms of the programs. Recently, Kors et al. [36] used a Delphi procedure to increase the agreement of five cardiologists on diagnostic classifications. Alternatively, one could combine the classifications of a board of cardiologists [2]. The accuracy of the combined referees has proven to be higher than any of the individual cardiologists or programs.

The problem of inter- and intraobserver variability also applies to tests that are used to establish a gold standard based on ECG-independent evidence (link a in Figure 1). For instance, definitions on infarct location or on what constitutes hypertrophy are by no means standardized.

Statistical classifiers have mainly been developed using a database of ECGs validated by ECG-independent evidence (link e) [12,14,15]. Pipberger [13] advocated the use of additional information in computerized ECG interpretation (link d). He distinguished different sets of prior probabilities for the various diagnostic categories. Depending on the clinical history of a particular patient, the appropriate set of priors is to be chosen for subsequent analysis.

Heuristic classifiers by their very nature are constructed without explicit reference to a database validated by ECG-independent evidence (link f). In fact, it is hard to imagine how ECGs of patients having a disorder that could only be verified by ECG-independent means, may help a cardiologist in the construction of a heuristic classifier.

In our opinion it is worthwhile to evaluate ECG classification methods with a database that is validated both by ECG-independent evidence and the combined opinion of a board of cardiologists. An evaluation that uses the former validation provides insight in the capability of the ECG to serve as a stand-alone test, whereas the latter validation tests the clinical acceptability of an ECG classification method.

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CHAPTER 4

DTL: A Language to Assist Cardiologists in Improving Classification Algorithms

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Computer Methods and Programs in Biomedicine 1991;35:93-110

Abstract

Heuristic classifiers, e.g., for diagnostic classification of the electrocardiogram, can be very complex. The development and refinement of such classifiers is cumbersome and time-consuming. Generally, it requires a computer expert to implement the cardiologist's diagnostic reasoning into computer language. The average cardiologist, however, is not able to verify whether his intentions have been properly realized and perform as he hoped for. But also for the initiated, it often remains obscure how a particular result was reached by a complex classification program.

An environment is presented which solves these problems. The environment consists of a language, DTL (Decision Tree Language), that allows cardiologists to express their classification algorithms in a way that is familiar to them, and an interpreter and translator for that language. The considerations in the design of DTL are described and the structure and capabilities of the interpreter and translator are discussed.

Key words: Programming-language design, ECG classification, interpreter

Introduction

The prevalent approach to computerized interpretation of the electrocardiogram (ECG) is to simulate the cardiologist's reasoning in classifying an ECG by means of decision trees [1]. Generally, these classifiers are complex. This complexity stems from the fact that many disease categories have to be distinguished; the decision nodes may contain comprehensive tests; and procedural knowledge is incorporated in the trees.

The development and refinement of such classifiers is an elusive task. Generally, it requires a computer expert to translate the cardiologist's diagnostic reasoning into computer language. The resulting program, however, is a sealed book to the average cardiologist, who thus cannot verify whether justice has been done to his intentions, or perhaps whether his intentions would need adjustment. But even for the expert, the workings of a complex classification program may be hidden from insight and how a particular diagnostic statement was reached may remain obscure.

In this article we describe DTL (Decision Tree Language), a simple, easy-to-learn language that can be used by domain experts for expressing their classification algorithms. Furthermore, we describe a DTL interpreter and translator. These tools allow the user to develop, test and modify the classification algorithms in an interactive way, and to generate an efficient run-time version.

The outline of the article is as follows. Firstly, we describe the system requirements and motivate the approach that was taken. Secondly, we discuss language-design criteria and their influence on the design of DTL. A description of the syntax and semantics of DTL can be found in the Appendices. Thirdly, the DTL interpreter and translator will be described.

Requirements

Four requirements for the language and its environment were discerned when we started this project:

Readability. The language should provide optimal readability for the intended users, i.e., cardiologists. Language constructs had to be available that allow cardiologists to express their knowledge in a way familiar to them. Decision trees are the main vehicle to represent such knowledge. Of particular importance is the specification of decision criteria. They involve amplitude and time-interval measurements in the so-called ECG leads. ECG leads are signals recorded by means of electrodes on the body surface, the standard ECG consisting of twelve separate leads. Cardiologists often specify criteria that involve the same type of measurement in a set of leads. They may also want to indicate that certain diagnostic categories are inhibited by the presence of others, or that a particular algorithm needs to be executed for a set of leads.

The language constructs that we selected are based on material in user manuals for electrocardiographs [2,3], previous attempts in this field [4,5], and our own experience.

Interaction. It should be possible to follow the diagnostic classification of a particular patient and to modify and test the classification program on-line. This requirement suggests the use of an interpreter with at least the following capabilities: a verbose mode, the setting of breakpoints, a step mode, on-line modification, and logging facilities. The interpreter may be helpful during the implementation of a classification algorithm; its main value, however, is in the help it provides to cure diagnostic errors, inconsistencies, and omissions in a classification program that is functioning properly from a programming point of view, but still can be improved from a diagnostic point of view.

Compilation. It should be possible to generate a compiled version of the program. Classification algorithms are generally evaluated by considering their performance on a large database of ECGs. A fast run-time version of the program is necessary to process such a database in an acceptable amount of time. The program must also be compilable because it had to be implemented on an electrocardiograph.

Open environment. It should be possible to incorporate routines that perform dedicated operations, such as complicated computations or I/O. The intricacies of such operations need not bother a cardiologist. The system should operate in a UNIX environment because other software that we use in this field runs under this operating system.

Several existing languages or expert-system shells provide capabilities that fulfill part of the above requirements. In our opinion, none is able to fulfill all of them. The readability requirement is probably the most strict one. Although the choice of the language constructs that we deemed necessary is admittedly one out of several, we considered the constructs which are available in existing computer languages insufficient to meet our requirement for readability.

We therefore chose to design a new language and to build an interpreter for it. In order to generate an efficient run-time program, we decided that a translator that converts the language into a compiled computer language would suffice.

Language

There exists extensive literature on the design of programming languages (e.g., [6-8]). However, guidelines for language design are hard to formalize and may be overlapping or conflicting; programming-language design still seems to be more of an art than a science. From the above-mentioned literature we distilled three criteria that appeared to be relevant in the design of DTL: readability, reliability, and compilability. We do not intend to give a comprehensive description of DTL at this place; instead we will describe several language

features to illustrate how the above design criteria affected DTL. The full DTL syntax is presented in Appendix A; a semantic description is given in Appendix B.

Readability

Many decisions in the design of DTL were influenced by the readability constraint. Examples will be given of DTL's appearance, data types, expressions, and control constructs.

Appearance. The meaning of language symbols should be easily recognizable. Some characteristics which affect the appearance of DTL are: (i) Identifiers consist of letters, digits, underscores, and primes. They can be of arbitrary length and all characters are significant; (ii) The assignment operator is `<-` (left-pointing arrow). The `=`-operator tests for equality in Boolean expressions; (iii) Comments start with `##` and extend to the end of the line; (iv) White space can be used freely to clarify the structure of the program.

Data types. (i) DTL has only four built-in data types: `integer`, `real`, `boolean`, and `string`. These built-in types can be used to construct arrays and records. No pointers are available; (ii) Symbolic constants, including array constants, can be declared; (iii) Two special record types have been predefined: `lead` and `location`. The 12 standard ECG leads are available as lead variables: `I`, `II`, `III`, `aVR`, `aVL`, `aVF`, `V1`, `V2`, `V3`, `V4`, `V5`, `V6`. The `lead` data type is used for storing lead-dependent measurements that are relevant for a classification, e.g., the duration of a Q wave, the amplitude of an R wave, the presence of a QS pattern, etc. (see Figure 1a). A similar data type `location` is supplied, which is used primarily in the classification of infarctions.

Expressions. (i) DTL supports ternary comparison operators; (ii) Operators distinguish only five precedence levels; (iii) Two special kinds of expression are available: lead conditions and location conditions. The general syntax of a lead condition is:

```
(⟨expression⟩) in [⟨number⟩ of] ⟨lead list⟩
```

The `⟨expression⟩` can be an arbitrary DTL condition in which lead-dependent measurements can occur. The optional `⟨number⟩ of` clause indicates the number of lead variables for which `⟨expression⟩` should at least be true in order for the lead condition to evaluate to true. If this clause is omitted, `⟨expression⟩` must be true in all leads specified in `⟨lead list⟩` (see Figure 1b).

Control constructs. (i) DTL has a powerful set of control structures: 'if-then(-else)', 'for-in-do', 'loop-while', and 'loop-until'. These structures are self-bracketing, i.e., key words terminate each construct. No 'goto'-statement is provided; (ii) A special 'for-in-do' is available which takes lead or location variables as its index variable (see Figure 1c); (iii) Procedures and functions (program units) are supported. Parameters may be passed both 'by value' and 'by reference'. In the latter case, they have to be explicitly marked as such in the call.

```

a. types
  lead: record
    Q_dur: integer;
    R_amp: integer;
    QS_pattern: boolean;
    QR_ratio: real;
    .
  end_record;
end_types;

variables
  I: lead;
  II: lead;
  .
  V6: lead;
end_variables;

b. (R_amp in V3 < R_amp - 50) in 1 of V1, V2

(QRS_pos_amp - QRS_neg_amp > 1000) in I, II, (V1..V6)

(25 <= Q_dur < 35 and 1/4 <= QR_ratio < 1/3) in 2 of V3, V4, V5

c. for lead in I, II, (V1..V6) do
  if (Q_dur in lead > 100) then
    .
  end_if;
  if (lead is II) then
    .
  end_if;
end_for;

```

Figure 1. Examples of the DTL syntax: (a) built-in lead variables, (b) lead conditions, (c) special for-loop.

The example in Figure 2 illustrates some of the above features. A (simple) rule for classifying anterior infarction is presented. The corresponding implementation in FORTRAN, the language in which our ECG classification program was written originally, demonstrates the difference in readability.

Reliability

Several properties of DTL increase its reliability.

No default declaration. All variables must be explicitly declared before being used. The only exception is the index variable of a lead or location for-loop. This variable is declared by DTL

```

procedure anterior_infarction()
## Location variable ANT and lead variables V2-5 are defined globally.
if ( (Q_dur >= 40) in 1 of V3, V4 or
(Q_dur >= 35 and QR_ratio >= 1/3) in 2 of (V2..V5)) then
    INFARCT in ANT <- DEFINITE;
else
    if ((25 < Q_dur < 35 and QR_ratio >= 1/3) in 2 of (V2..V5)) then
        INFARCT in ANT <- PROBABLE;
    end_if;
.
.
end_if;
end_procedure;

```

```

SUBROUTINE ANTINF()
INTEGER I, COUNT1, COUNT2
C Variables QDUR, QRRAT, INF and constants V2-5, ANT, DEF, PROB
C are assumed to be appropriately declared.
COUNT1 = 0
DO I = V3, V4
    IF (QDUR(I) .GE. 40) COUNT1 = COUNT1 + 1
ENDDO
COUNT2 = 0
DO I = V2, V5
    IF (QDUR(I) .GE. 35 .AND. QRRAT(I) .GE. 1.0/3.0)
1    COUNT2 = COUNT2 + 1
ENDDO
IF (COUNT1 .GE. 1 .OR. COUNT2 .GE. 2) THEN
    INF(ANT) = DEF
ELSE
COUNT1 = 0
DO I = V2, V5
    IF (QDUR(I) .GT. 25 .AND. QDUR(I) .LT. 35 .AND.
1    QRRAT(I) .GE. 1.0/3.0) COUNT1 = COUNT1 + 1
ENDDO
IF (COUNT1 .GE. 1) INF(ANT) = PROB
ENDIF
.
.
RETURN
END

```

Figure 2. Example of an algorithm to classify anterior infarction implemented in DTL (upper part) and in FORTRAN (lower part).

upon entering the loop and deleted afterwards. Typing errors in the index variable will still be detected because either an undeclared variable will be referenced or an already declared variable will be redeclared. In both cases an error message will be given.

No default initialization. Variables and fields of arrays or record variables which have been declared but have not been assigned a value, have a special value `undefined`. The function `undefined` is the only function that can accept a variable with the value `undefined`. If so, it returns `true`, otherwise `false`. Using `undefined` variables in numerical or string expressions will cause an error message.

Type checking. DTL has strict rules for the combination of values of different types: Only integer and real types may be combined. This enables the interpreter and the translator to detect illegal combinations of values prior to program execution.

Compilability

DTL contains several language features that ease compilation.

Static types. All variables and constants must be declared. Their types cannot change during program execution. Thus, all information about operand types is available at compile time, which facilitates code generation.

Static arrays. The size of arrays has to be specified by a constant expression and cannot change during program execution. This facilitates run-time memory management and reduces the translator's complexity.

Scope rules. DTL has simple scope rules which facilitate compilation. Variables that are declared in procedures or functions are only accessible from within these units (local variables). All other variables, which must have been declared in the so-called declaration section of the program, can be accessed throughout the program (global variables). If a variable is global and a local variable with the same name is declared inside a certain unit, the name can only be used within that unit to access the local variable.

Interpreter and translator

In this section the DTL interpreter and translator will be described. We will concentrate on the functional aspects of the system; for a more technical description we refer to [9,10].

Interpreter

The interpreter consists of several functional units [11]: the command module, the parser, the pre-run module, and the core interpreter. The command module provides the user interface, processes commands, handles errors, and initializes and deletes data structures. The parser

creates an internal representation of the DTL constructs in the form of parse trees and handles context-dependent errors, e.g., unbalanced parentheses, missing statement terminators, etc. The pre-run module stores DTL objects (constants, variables, procedures, etc.) in symbol tables. It also checks for context-dependent errors, e.g., illegal array ranges or variables that are declared more than once. The core interpreter actually executes the program. The DTL core interpreter is a 'linearizing' interpreter [11,12]. This means that the interpreter takes a parse tree (representing, for instance, a procedure call or a control statement) and breaks it down into simple instructions which are pushed on a control stack. Subsequently, the interpreter executes the instructions on the control stack; values are stored and manipulated on a value stack.

Commands

We chose to have a separate command language and programming language. The other option, to make all commands part of the programming language, would have complicated the core interpreter considerably because of the large number of debugging commands. However, DTL expressions and statements may be entered, prefixed by `p(rint)` and `s(tatement)` commands, respectively. Other commands that can be issued are:

- `b(reak)p(oint) <unit name> <line number>`. This command sets or removes a breakpoint on the specified line of the specified program unit. When the interpreter is executing a program, it checks every statement to see whether a breakpoint is set on one of the lines it occupies. If so, the interpreter does not (yet) execute the statement, but echoes it and enters 'break mode'. At that point the user regains control and can issue other commands.
- `c(ontinue)`. With this command the user can resume a program that has entered break mode.
- `clear_everything`. This command deletes all data structures that were created during the current session. After this command has been issued, the interpreter is in its initial state.
- `describe <object_spec> [<output_file>]`. This command describes the specified DTL object(s). The optional `<output_file>` specifies the name of the file to which the description(s) should be written. Default is standard output.
- `help`. This command prints a short summary of the commands that the interpreter accepts.
- `load <DTL_file>`. This command loads the DTL object that is defined in the specified file, e.g., a program unit, into the interpreter's memory.
- `quit`. This command terminates the current session.
- `reset`. When an error occurs inside a unit or if break mode is entered inside a unit, the interpreter stays in that unit's environment. This means that the local variables of this unit are visible and may hide global variables of the same name. In order to get back to the 'top level' the `reset` command can be used.

- `run <batch_file>`. This command sequentially executes the interpreter commands in the specified batch file.
- `sh <shell_command>`. This command is the shell escape. The rest of the line is passed to the shell.
- `step`. This command toggles the step mode. When the interpreter is in step mode, the program is executed one statement at a time. After every statement, the interpreter enters break mode.
- `verbose`. This command toggles the verbose mode. When the interpreter is in verbose mode, every statement is shown to the user before it is executed. If a conditional statement is executed, the truth value of the condition and its possible constituents are displayed.
- `warn`. This command toggles the warn mode. When the interpreter is in warn mode, loading the definition of an object that was already defined is not possible and will result in a warning. If the warn mode is reset, the interpreter will overwrite the existing object with the newly loaded one.

The user interface has been kept small and simple. It uses the standard C input/output routines and is line-oriented.

Special features

The DTL interpreter has several special features: facilities for debugging the interpreter and for logging, and the inclusion of foreign units.

Debugging the interpreter. There are two interpreter commands to show the contents of the control stack and the value stack: `show_C` and `show_V`, respectively. They can be used to gain insight into the operation of the interpreter and are useful when the DTL language is to be modified or extended.

Logging. To increase insight in the classification process, it may be important to know how often a variable or constant is referenced. Therefore, every variable and constant has a log flag attached to it. The user may toggle these flags by issuing a `log` command. When the log flag of a variable is set, the interpreter counts all reads and writes performed on it. When a constant's log flag is set, all reads are counted. If the log flag is reset, the reference counts are not incremented. The value of the counts can be shown by means of the `describe` command. The `reset_refcnt` command resets the read or write reference count.

Logging is conditional on the value returned by a function `refcnt_permission`. This function has to return `true` for the logging to be performed. In the present implementation, it is a dummy function which always returns `true`. It may be adjusted by the user, however, to provide side effects or additional criteria for logging.

Foreign units. Foreign units are procedures or functions written in a compiled language (C or C++) to be called from DTL programs using the normal calling conventions. The reasons for providing them are that (i) foreign units enable the execution of computer-intensive computations in a much more efficient way than would be possible in interpreted DTL, and (ii) they allow for the incorporation of complicated algorithms, e.g., dedicated I/O routines, without having to provide a large set of DTL statements for implementing these algorithms. Thus, foreign units provide efficiency and extensibility to DTL while retaining its readability and simplicity. Foreign units are linked with the interpreter or translator. They have access to all variables and constants of the DTL program.

```

$ interpreter
Welcome to the DTL command interpreter
>run load_ecg
  The ECG classification programs are loaded; file load_ecg contains DTL load statements for all DTL
  procedures.
>s read_ecg(10)
  The ECG measurements of a patient (no. 10) are read from a file by foreign unit read_ecg.
>s class_ecg()
ECG classification for patient 10
-----
Probable anterior infarction
Definite LVH (Left Ventricular Hypertrophy)
  DTL procedure class_ecg calls the DTL classification procedures. The classification is printed by a foreign
  unit called by class_ecg.
>verbose
verbose is ON
  The user wants to know why the classification "Probable anterior infarction" is made and turns on the verbose
  mode.
>s anterior_infarction()
[ 1]   if ( (Q_dur >= 40) in 1 of V3, V4 or
[ 2]     (Q_dur >= 35 and QR_ratio >= 1/3) in 2 of (V2..V5)) then
false or false = false
***** CONDITION IS false
[ 5]   if ((25 < Q_dur < 35 and QR_ratio >= 1/3) in 2 of (V2..V5)) then
***** CONDITION IS true
[ 6]   INFARCT in AS <- PROBABLE;
  The procedure for anterior infarction is executed (cf. Figure 2). Line numbers are indicated on the left. The
  first condition is false, the second is true. Truth values for subconditions are also indicated.
>sh vi antinf.tree
  The user concludes that the procedure for anterior infarction is flawed and enters the standard text editor to
  modify the file antinf.tree which contains the procedure.
>load antinf.tree
  Upon return, the corrected procedure is loaded and may be tested once again.
.
.
>quit
Do you really want to quit (y/n) ?
y
$

```

Figure 3. Example of the use of the DTL interpreter. System output is bold and explanatory notes are in italics.

Figure 3 illustrates our present use of the DTL interpreter. The ECGs that we use in our research have been processed by the signal analysis part of our ECG computer program [13]. For each ECG the measurements used by the classification program have been stored in a file. These measurements can be retrieved with foreign unit `read_ecg`, obviating a reanalysis of the ECG every time a classification is made. This setup is for research purposes only; eventually a (compiled) version of the classification program is integrated with the signal analysis program.

Translator

The translator converts DTL programs to C or C++ programs which can be subsequently compiled into executables. Its construction was relatively straightforward, since several parts of the DTL interpreter (parser, data structures) could be used for the translator as well. The translator does not provide extensive error checking, as programs are expected to have been debugged with the interpreter.

Interpretation and compilation of DTL programs may differ in two respects. First, the translator expects one main procedure which calls other procedures and functions. In DTL, this procedure starts with the key word `main`. The main procedure is also accepted by the interpreter, of course, but it is not required since any procedure or function may be invoked directly by the user during an interpreter session.

Second, differences may exist between foreign units used by the interpreter and those used by the translator. This is caused by the fact that the interpreter's foreign units use DTL variables which are stored in the interpreter's symbol tables, while the translator's foreign units use their own (C or C++) variables.

Both the interpreter and the translator have been implemented in C++ [14]. We used the Glockenspiel C++ compiler [15], operating on HP-9000 workstations.

Discussion

We developed the DTL environment to enable domain experts to express their classification knowledge in a familiar but algorithmic way and to provide insight into the possibly complex classification process. Our particular interest was to improve the diagnostic classification part of our ECG computer program. In our experience, the cardiologist's way of representing knowledge is closely resembled by the language DTL. We found that diagnostic classification algorithms could be translated into DTL in a natural way and immediately be understood by the cardiologist. The possibility to use dedicated routines written in a compiled computer language within DTL programs proved to be very useful. The interactive character of the system facilitated experimentation. New ideas were quickly implemented and tested, showing their

viability. The cardiologist himself, sitting behind the computer, could follow the program's execution and pinpoint flaws immediately [16].

In the past, other languages have been developed to facilitate the development of heuristic ECG classifiers: DCDL (Diagnostic Criteria Decision Language) [5] and Hewlett Packard's ECL (ECG Criteria Language) [4]. There are, however, many differences between DTL and these languages. For instance, they do not support if-then-else, loop-constructs, and array variables; they permit only a restricted form of program modularization; no foreign units can be used. Furthermore, the programs are compiled instead of interpreted; no particular facilities are provided to acquire insight into the actual classification process.

DTL is a concise language. Its capabilities may be extended, though, by defining new foreign units. Their use has some disadvantages: Foreign units have to be incorporated into the interpreter or translator, and differences exist between foreign units for the interpreter and for the translator. We feel these drawbacks are by far outweighed by the increased flexibility. Besides, foreign units probably will not be changed frequently, and the differences between the translator and interpreter versions are small.

Several useful extensions of the interpreter are possible. A history mechanism which allows the user to recall and edit previously entered commands would increase user-friendliness. Another extension deals with error checking. Presently, most error checking is done at run-time. Errors that exist in infrequently used parts of a program are very hard to detect. More extensive error checking by the pre-run module prior to interpretation may remedy this problem. The fact that DTL is strongly typed facilitates adding static error checking.

DTL contains several constructs dedicated to computerized ECG classification. In our opinion, however, the language is general enough to be used in other application areas. It is easy to learn, probably also for domain experts without programming experience. Especially those areas where insight in complex (heuristic) classifiers and on-line experimentation is important, may benefit from the capabilities of the interpreter.

Availability

Program source codes and executables are available from the authors.

Acknowledgment

We like to thank Dr. D. Grune (Free University, Amsterdam) for helpful discussions concerning the paper.

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Appendix A - DTL-syntax description

A modified version of Backus-Naur Form (BNF) is used. Non-terminal symbols are represented by strings consisting of lower-case letters and underscores, enclosed in `<` and `>`. Terminal symbols represent themselves, but may be enclosed in single quotes (`'`) to prevent ambiguity. The symbol `→` separates the left- and right-hand sides of a production. The vertical bar (`|`) separates alternative right-hand sides of a production. Square brackets (`[]`) enclose items that may appear once or may be omitted (optional items). Braces (`{ }`) enclose items that may be omitted or that may appear one or more times.

```
<compile_unit>    →  <type_block>
                   |  <constant_block>
                   |  <variable_block>
                   |  <procedure_def>
                   |  <function_def>
<type_block>     →  types
                   <type_def>; {<type_def>;}
                   end_types;
<constant_block> →  constants
                   <constant_def>; {<constant_def>;}
                   end_constants;
<variable_block> →  variables
                   <variable_decl>; {<variable_decl>;}
                   end_variables;
<procedure_def>  →  procedure <id> [{<formal_par> {, <formal_par>}]
                   [<variable_block>]
                   <statements>
                   end_procedure;
                   |  main
                   [<variable_block>]
                   <statements>
                   end_main;
<function_def>   →  function <id> [{<formal_par> {, <formal_par>}]
                   returns <built_in_type>
                   [<variable_block>]
                   <statements>
                   end_function;
<type_def>       →  <id>: array '[' <int_range> ']' of <built_in_type>
                   |  <id>: record
                   <record_field_decl>;
                   {<record_field_decl>;}
                   end_record
<constant_def>   →  <id>: <built_in_type> <-> <expression>
                   |  <id>: array <-> '[' <int_const> {, <int_const> } ']'
<variable_decl>  →  <id>: <general_type>
```

```

<formal_par>      → <formal_in_par> | <formal_in_out_par>
<statements>     → [{<statement>}]; {<statement>;}
<built_in_type>  → integer | real | boolean | string
<int_range>      → (<int_const> .. <int_const>)
<record_field_decl> → <id>: <built_in_type>
<expression>     → <relation>
                  | <relation> and <expression>
                  | <relation> or <expression>
<int_const>      → <id> | <int_literal>
<general_type>   → <id> | <built_in_type>
<formal_in_par>  → <id>: <built_in_type>
<formal_in_out_par> → & <id>: <built_in_type>
<statement>      → <simple_statement> | <block_statement>
<relation>       → <simple_expr>
                  | <simple_expr> '<' <simple_expr>
                  | <simple_expr> '<=' <simple_expr>
                  | <simple_expr> '=' <simple_expr>
                  | <simple_expr> '>=' <simple_expr>
                  | <simple_expr> '>' <simple_expr>
                  | <simple_expr> '/=' <simple_expr>
                  | <simple_expr> '<' <simple_expr> '<' <simple_expr>
                  | <simple_expr> '<' <simple_expr> '<=' <simple_expr>
                  | <simple_expr> '<=' <simple_expr> '<' <simple_expr>
                  | <simple_expr> '<=' <simple_expr> '<=' <simple_expr>
                  | <simple_expr> '>' <simple_expr> '>' <simple_expr>
                  | <simple_expr> '>' <simple_expr> '>=' <simple_expr>
                  | <simple_expr> '>=' <simple_expr> '>' <simple_expr>
                  | <simple_expr> '>=' <simple_expr> '>=' <simple_expr>
<simple_statement> → <assignment> | <proc_call> | print <expression>
                  | return <expression> | exit | stop
<block_statement> → <if_block> | <for_block> | <loop_block>
<simple_expr>      → <term>
                  | <term> + <simple_expr>
                  | <term> - <simple_expr>
<assignment>     → <var_expr> <- <expression>
                  | <var_expr> <- undefined
<proc_call>      → <proc_name> [{<actual_par> {, <actual_par>}]}
<if_block>        → if (<expression>) then
                  <statements>
                  [else
                   <statements>]
                  end_if
<for_block>       → for <id> in <for_list>
                  <statements>
                  end_for

```

```

<loop_block>      →   loop
                    <statements>
                    while (<expression>)
                        <statements>
                    end_loop
                    |
                    loop
                        <statements>
                    until (<expression>)
                        <statements>
                    end_loop

<term>            →   <factor> | <factor> * <factor>
                    |
                    <factor> / <factor> | <factor> div <factor>
                    |
                    <factor> mod <factor>

<var_expr>        →   <id> | <array_field_expr> | <record_field_expr>
                    |
                    (<var_expr>)

<proc_name>       →   <id> | main

<actual_par>      →   <actual_in_par> | <actual_in_out_par>

<for_list>        →   <int_list> | <lead_list> | <loc_list>

<factor>          →   <primary> | not <primary> | abs <primary>
                    |
                    <primary> ** <primary> | - <primary>

<array_field_expr> → <id> '[' <expression> '['

<record_field_expr> → <id> in <record_var_name>

<actual_in_par>   →   <expression>

<actual_in_out_par> → & <var_expr>

<int_list>        →   <int_const> | <int_range> | <int_const>, <int_list>
                    |
                    <int_range>, <int_list>

<lead_list>       →   <lead> | <lead_range> | <lead>, <lead_list>
                    |
                    <lead_range>, <lead_list>

<loc_list>        →   <loc> | <loc_range> | <loc>, <loc_list>
                    |
                    <loc_range>, <loc_list>

<primary>         →   <int_literal> | <real_literal>
                    |
                    <boolean_literal> | <string_literal> | <id>
                    |
                    undefined (<expression>) | <array_field_expr>
                    |
                    <record_field_expr> | <function_call>
                    |
                    <lead_condition> | <lead_equality>
                    |
                    <loc_condition> | <loc_equality> | (<expression>)

<record_var_name> → <id> | <lead> | <loc>

<lead_range>      →   (<lead> .. <lead>)

<loc_range>       →   (<loc> .. <loc>)

<function_call>   →   <id> [( <actual_par> {, <actual_par>} )]

<lead_condition> →   (<expression>) in [( <int_const> of] <lead_list>

<lead_equality>   →   <lead> is <id> | <id> is <lead>

<loc_condition>   →   (<expression>) in [( <int_const> of] <loc_list>

<loc_equality>    →   <loc> is <id> | <id> is <loc>

<id>              →   <letter> { <printable> }

```

```

<lead>          → I | II | III | aVR | aVL | aVF
                | V1 | V2 | V3 | V4 | V5 | V6
<loc>           → INF | HL | ANT | AS | AL | POST
<int_literal>   → <digit> {<digit>}
<real_literal>  → [{<int_literal>} . <int_literal> [<exp>]
                | <int_literal> <exp>
<boolean_literal> → true | false
<string_literal> → " {<string_char>} "
<letter>        → a | b | c | d | e | f | g | h | i | j | k | l | m
                | n | o | p | q | r | s | t | u | v | w | x | y | z
                | A | B | C | D | E | F | G | H | I | J | K | L | M
                | N | O | P | Q | R | S | T | U | V | W | X | Y | Z
<printable>     → <letter> | <digit> | _ | '
<digit>         → 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9
<exp>           → e [-] <int_literal> | E [-] <int_literal>
<string_char>  → <printable> | ""

```

Appendix B - DTL-semantics description

1. Basic definitions

1.1. White space

White space is a sequence of spaces, new lines, and tabs. It is never explicitly mentioned in the syntax description of appendix A, but it can be placed before and after any of the non-terminal symbols in the productions.

1.2. Identifiers

An identifier consists of a letter followed by a (possibly empty) string consisting of letters, digits, underscores (`_`) and primes (`'`). Identifiers can be of arbitrary length and all characters of an identifier are significant. The underscores and the case of the letters are also significant.

Identifiers are used to name the entities in a program. Some identifiers have a predefined meaning and may not be reused. These identifiers are called key words or reserved words. The full list of DTL key words is given in appendix C.

1.3. Literals

Literals are constants that specify their own value. Literals can be numbers, truth values or strings.

Integer literals and real literals are numeric literals that denote numbers. Integer literals are expressed in decimal notation and consist of one or more digits. Integers do not contain a decimal point. Real literals are also in decimal notation and consist of one or more digits with an optional decimal point, followed by an optional exponent part that consists of an `e` or `E`, followed by an integer literal that is optionally preceded by a minus sign. A real literal must contain an exponent part or a decimal point, or both, otherwise it cannot be distinguished from an integer literal.

The class of Boolean literals contains only two elements, the reserved words `true` and `false`. These literals denote truth values following the rules of Boole's algebra.

String literals are arbitrary strings of printable characters, enclosed in double quotes. If a string literal is to contain a double quote, this double quote has to be preceded by another one.

1.4. Comment conventions

Comments start with `##` and extend to the end of the line. They can contain arbitrary text and can be placed anywhere except within a lexical element (i.e., identifier, operator or literal).

2. Variables, constants and expressions

2.1. Declaration of variables

All variables have to be explicitly declared by the user. Variables are declared in a 'variables-block'. The declaration has the form:

```
variables
  <var_name>: <type_name>;
  {<var_name>: <type_name>;}
end_variables;
```

The <var_name> can be an arbitrary identifier, as long as it is not a key word and it is not declared more than once in the same variables-block. The <type_name> can be one of the built-in types: `integer`, `real`, `boolean` or `string`, or it can be the name of one of the types defined by the user (see 4.1).

2.2. Assignment

Values can be assigned to variables in two ways: by means of an assignment statement and by means of a procedure or function call with in/out parameters. Procedure and function calls will be discussed in section 5.

An assignment statement consists of two expressions, separated by a `<-` sign. The left-hand side (lhs) of the assignment statement specifies the location where the value of the other expression, the right-hand side (rhs), is to be stored. In DTL one can only assign to simple variables (variables of a built-in type). As a consequence of this, the lhs is a restricted expression that can only be of one of the following three forms: the name of a simple variable, the specification of a field of a record variable, and the specification of a field of an array variable. The rhs is a general expression that is only restricted in the type of values that it can have. This type must be the same as the type of the lhs or coercible to it.

2.3. Undefined variables

When variables are declared but no value has been assigned to them, they are initialized to a special value: 'undefined'. When undefined variables are used as part of an expression, the expression normally also becomes undefined. An exception to this rule is the way in which Boolean expressions (conditions) are handled (see 2.5.2).

Undefined expressions may not be used as rhs of assignment statements. A variable may be assigned an undefined value by using the reserved word `undefined` as the rhs of an assignment statement. It is also illegal to pass undefined variables as in-parameters to a procedure or function. The only exception to this rule is the predefined function `undefined`

which expects a general expression of a built-in type as its parameter and returns `true` if the expression is undefined.

2.4. Symbolic constants

Symbolic constants are declared in a 'constants-block'. The declaration has the form:

```
constants
  <constant_def>;
  {<constant_def>;}
end_constants;
```

Constant definitions have the following syntax:

```
<id>: <built-in_type> <-> <expression>
```

or

```
<id>: array <-> '[' <int_const> {, <int_const>} ']'
```

The identifier (`<id>`) in the production is the name of the symbolic constant. This can be any identifier that is not also a global variable or the name of another symbolic constant.

In the first production, the expression that is used to supply the constant's value is an unrestricted expression that can use all operators and all symbolic constants that are known at the time of definition.

The second production is the syntax of the definition of array constants: symbolic constants that represent one-dimensional arrays of integers. The indices for an array constant range from 1 to the array's number of elements. Array constants are accessed via the same type of expression as array variables (see 4.2).

Symbolic constants can appear in all types of expressions, but not as the lhs of an assignment statement or as in/out parameters (see 5.3).

2.5. Expressions

An expression must always have a value of a built-in type. Expressions consist of literals, symbolic constants, variables, fields of record variables, fields of array variables or constants, function calls and ECG conditions, combined by means of operators and brackets. There are three types of expressions: numerical, Boolean, and string.

2.5.1. Numerical expressions. Numerical expressions are used to supply the program with integer or real values. The simplest numerical expressions are the ones without operators. They can be of the following forms: Integer literal, real literal, identifier (representing a numerical variable or constant), array field (of a numerical array variable or constant), record field (a numerical field of a record variable), function call (of a function with a numerical return type).

The unary operators that are defined on numerical values are: `abs` (absolute value), and `-` (negation). The result of both operators is of the same type as the operand.

The binary operators that are defined on numerical values are: + (addition), - (subtraction), * (multiplication), / (division), ** (exponentiation), div (integer division), and mod (modulus). The result of +, -, and * is an integer if both operands are integers; otherwise it is a real. The result of / and ** is always a real. Both operands and result of div and mod are integers. All numerical operators return the value undefined if one of their operands is undefined.

2.5.2. Boolean expressions. Boolean expressions (conditions) are used in tests that are part of conditional statements or loops. The simplest Boolean expressions are the ones without operators. They can be of the following forms: Boolean literal, identifier (representing a Boolean variable or constant), array field (of a Boolean array variable), record field (a Boolean field of a record variable), function call (of a function with a Boolean return type).

There is one unary Boolean operator: not. This operator expects a Boolean operand and returns its negation. If the operand is undefined, the result is undefined as well.

There are two binary Boolean operators: and and or. These operators also expect Boolean operands and return a Boolean value. If one operand of and is undefined, and the other one is false, the operator returns false. If the other operand is true, the operator returns undefined. If one operand of or is undefined, and the other one is true, the operator returns true. If the other operand is false, the operator returns undefined.

The following binary operators compare values of a built-in type and return Booleans that describe the relation between these values: = (equal), /= (not equal), > (greater than), >= (greater than or equal), <= (smaller than or equal), and < (smaller than). The operands of = and /= can be any of the built-in types provided they are of the same type. The operands of >, >=, <=, and < must be either both numerical or both strings.

DTL also supports ternary comparison operators, which can compare three numerical or string values: > >, >= >, > >=, >= >=, <= <=, < <=, <= <, and < <.

2.5.3. String expressions. String expressions are used to store or print messages. The simplest string expressions are those that are of one of the following forms: String literal, identifier (representing a string variable or constant), array field (of a string array variable), record field (a string field of a record variable).

The only binary operator that is defined on strings is +, which concatenates two strings and returns the result as a new string.

2.5.4. Operator precedence. A precedence level is associated with each operator. If an expression contains two operators of different precedence levels, the one with the highest level is applied first, unless parentheses are used to force another order of evaluation. Operators of the same precedence level are left-associative.

The following precedence levels are distinguished:

- 5: **, not, abs, (unary) -
- 4: div, mod, *, /
- 3: +, -
- 2: >, >=, =, <=, <, /=
- 1: and, or

2.6. Coercion

Most of the numeric operators that are described in 2.5.1 and all of the comparison symbols of 2.5.2 accept combinations of reals and integers as their operands. All integers in the expression are converted to reals and then the whole expression is evaluated, using only the operators (or comparison symbols) for reals.

Another (but similar) use of coercion is when an integer literal is assigned to a real variable. The literal's integer value is first converted to a real and then the assignment statement is executed.

Every other mixing of types is illegal.

3. Control structures

3.1. If-blocks

```
if ((expression)) then
    <statements>
end_if;
or
if ((expression)) then
    <statements>
else
    <statements>
end_if;
```

The first kind of if-block checks whether `<expression>` (a condition) has the value true and if this is the case, executes the statements after then. If the condition has the value false the statements after then will be skipped. In both cases the program resumes execution after `end_if`.

In an if-block of the second kind, the statements after `else` will be ignored if the condition holds; if it does not, they will be executed.

3.2. Loop-blocks

```
loop
  <statements>
until (<expression>)
  <statements>
end_loop;
```

or

```
loop
  <statements>
while (<expression>)
  <statements>
end_loop;
```

The first loop-block executes the statements after `loop`, then checks whether `<expression>` holds. If it does not, the statements after the test are executed and execution resumes at the statement following the `loop` key word. If the condition holds, control is transferred to the statements following `end_loop`.

The second loop-block behaves almost identically to the first. The only difference is that the condition is used as a continuation condition rather than as a termination condition.

3.3. For-blocks

```
for <id> in <int_list> do
  <statements>
end_for;
```

`<int_list>` is a list of integers and/or integer ranges, separated by commas. The integers can be either integer literals, integer variables or integer symbolic constants. Integer ranges are of the form `(<int_val1>..<int_val2>)`, where `<int_val2>` is greater than or equal to `<int_val1>`.

The index variable of an integer for-loop must be declared before it is used in the for-loop. Its type must be `integer`. The value of the index variable should not be changed by the statements in the loop. After termination of the loop, the value of the index variable is the last value in the list.

4. User-defined types

4.1. Type definition

The general format of a type definition is:

```
types
  <type_def>;
  {<type_def>;}
end_types;
```

DTL contains two user-defined types, the array type and the record type. The specification of an array type has the form:

```
<id>: array '[' <int_range> \]' of <built-in_type>;
```

The specification of a record type is as follows:

```
<id>: record
  <id>: <built-in_type>;
  {<id>: <built-in_type>;}
end_record;
```

4.2. Array variables

When a new array type has been defined, variables of this type can be declared in the normal way. Variables of an array type can be accessed one field at the time. An array element can be specified by the name of the array variable followed by an integer expression denoting the index of the desired element. The integer expression must be enclosed in square brackets. Array elements can be used in all situations where normal variables of the same type can be used. This means that array elements can be used in expressions, as parameters to functions and procedures and as lhs of assignment statements. Arrays cannot be returned by functions or passed to procedures or functions. Only one-dimensional arrays are allowed.

4.3. Record variables

Record variables are declared in the same way as all other variables. After a record variable has been declared, its fields are accessible via a record-field specification:

```
<record_field_name> in <record_var_name>
```

The first identifier is the name of one of the fields that are defined for records of this type. The second identifier is the name of the record variable to be accessed. Record fields can be used in all situations where normal variables of the same type can be used. This means that they can be used in expressions, as parameters to functions and procedures and as lhs of assignment statements. Record variables can only be accessed one field at the time. Record variables cannot be returned by functions or passed to procedures or functions.

5. Program units

5.1. Procedures

The definition of a procedure has the following syntax:

```
procedure <id> ([[&]<id>: <built-in_type>
               {, [&]<id>: <built-in_type>}])
  [<variables_block>]
  <statements>
end_procedure;
```

The first <id> is the name of the procedure. It is followed by the list of formal parameters. The parameters can be preceded by an ampersand (&). An ampersand indicates that the parameter is an in/out-parameter, whereas no ampersand means that the parameter is an in-parameter (see 5.3). The parameter list is optionally followed by a variables-block (see 2.1) that specifies the procedure's local variables. This block, in turn, is followed by the statements that perform the procedure's actions.

Procedures can be called by other parts of the program by specifying the name of the procedure and a list of actual parameters that the procedure uses. The in/out-parameters must be preceded by an ampersand.

The DTL compiler demands one main procedure which is the program's starting point. Its syntax is:

```
main
  [<variables_block>]
  <statements>
end_main;
```

A main procedure need not be specified when the interpreter is used.

5.2. Functions

Functions are defined in the following manner:

```
function <id> ([[&] <id>: <built-in_type>
              {, [&] <id>: <built-in_type>}])
  returns <built-in_type>
  [<variables_block>]
  <statements>
end_function;
```

The only non-trivial difference between procedure and function definitions is the clause `returns <built-in_type>`. This clause specifies the return type of the function.

The way a function returns a value is by executing the statement `return <expression>;`

When this statement is encountered, execution of the function is terminated and the value of `<expression>` is returned to the calling unit. The type of `<expression>` must be the same as, or coercible to, the return type of the function. Return statements can be placed anywhere within a function (even in loops) and they can occur more than once in one function specification. If, during execution of a function, the program runs into the `end_function`, a run-time error is raised. Return statements can only occur in functions.

Function calls have the same syntax as procedure calls. Function calls can be used in general expressions, but not as lhs of assignment statements or as in/out parameters for a procedure or other function.

5.3. In- and in/out-parameters

Program units may be provided with two kinds of actual parameters: in- and in/out-parameters. An in-parameter is a parameter that the calling unit uses to supply the called procedure or function with a value. An actual in-parameter can be any kind of expression whose value is of the same type as the corresponding formal parameter or coercible to it. In-parameters behave like local variables of the called unit. Their value can be used in expressions and new values can be assigned to them but these changes do not affect the caller's variables in any way.

Functions return exactly one value. Returning multiple values is done by means of the in/out-parameter mechanism. Both actual and formal in/out-parameters must be preceded by an ampersand. Unlike an actual in-parameter, which specifies a value, an actual in/out-parameter specifies a location in memory that may or may not contain a value. The called unit can use its formal in/out-parameters just like formal in-parameters or local variables. The main difference between in- and in/out-parameters is that changing a formal in/out-parameter causes the corresponding actual parameter to change as well. Another difference is that an actual in/out-parameter needs to be of the same type as its corresponding formal one, whereas for in-parameters it is enough for the actual parameter to be coercible to the formal parameter's type.

5.4. Return from a unit

There are three ways of terminating (part of) a program:

- `stop:` Terminates the whole program, independent of the current position.
- `exit:` Terminates the current procedure. This instruction cannot be used in functions, since it does not specify a return value.
- `return:` Terminates the current function, specifying a return value. This instruction can only be used in functions.

5.5. *Scope and visibility*

Variables that are declared in the declaration section of the program, can be accessed throughout the program. These variables are called 'global'. It is also possible to declare variables in procedures or functions, in which case they are only accessible from within these units.

If a variable is global and a local variable with the same name is declared inside a certain unit, the global variable is 'invisible' within this unit.

5.6. *Notes on memory management*

The current implementation of the DTL interpreter uses a static memory-management scheme. This means that all variables and constants are allocated once and deallocated only when the program is terminated. A consequence of this way of managing memory is that DTL does not support recursion.

The fact that DTL uses static memory management does not mean that the local variables in DTL are static in the FORTRAN sense, however. When a unit is exited, all its local variables are set to undefined and their original values are lost.

6. *ECG-specific features*

DTL contains a number of features that make it especially fit for application in computerized ECG classification.

6.1. *Lead variables*

An ECG classification program uses a number of measurements of the ECG at hand. These measurements are time intervals or amplitudes of waves in the leads of the ECG. DTL supplies a data type, a record type named `lead`, which can be used to store these lead measurements.

The language predefines twelve lead variables of which the names are key words: `I`, `II`, `III`, `aVR`, `aVL`, `aVF`, `V1`, `V2`, `V3`, `V4`, `V5`, `V6`. These variables can be accessed like normal record variables. One can make lists of these lead variables and, like integer lists, these lists can contain ranges. The sequence that is defined on the lead variables is the one shown above.

6.2. *Location variables*

During the classification process, the program needs to record its conclusions and assumptions about the condition of the heart. Much of these data apply to specific locations of the heart. DTL has a predefined record type named `location` for this purpose.

The following predefined variables are of type `location`: `INF`, `HL`, `ANT`, `AS`, `AL`, `POST`. Like lead variables, location variables can be used in both lists and ranges.

6.3. *Special for-loops*

It is often necessary to execute repeatedly the same action for a number of leads or locations. For this purpose, DTL has a special for-loop construct. The syntax of such a for-loop is the same as for the normal for-loop (see 3.3), except for the iteration list which contains leads or locations instead of integers.

The index variable of a special for-loop can be used as a normal lead/location record variable. The index variable is not a record variable, however. It can be printed, in which case it yields a small integer representing the sequence number of the current lead/location. This means that the index variable, unlike a real lead/location variable, can be used as a parameter. All other manipulations that treat the variable as an integer are illegal.

To test whether a particular lead/location in the iteration list has been reached, DTL contains a special comparison operator: `is`. This operator can be used to compare the current value of the index variable with a particular lead/location variable. The declaration of the index variable is done automatically. The variable is declared before the program enters the for-block and deleted when the for-block is exited. Using the variable afterwards results in a run-time error. The name of the index variable cannot hide the name of a local variable; it must be given a name that has not already been given to a local variable.

As in a normal for-loop, it is illegal to assign values to the index variable or use it as an in/out-parameter.

6.4. *Special conditions*

A special type of condition was designed that can test multiple ECG variables at once and that conforms to the notation that is commonly used in cardiology. These conditions can either apply to collections of lead variables or collections of location variables and are therefore called lead conditions or location conditions. The syntax of a lead condition is:

```
((expression)) in [(int_const) of] <lead_list>
```

The `<expression>` can be an arbitrary DTL condition (but not a lead/location condition), in which fields of the lead record type can occur. The (optional) `<int_const>` of clause indicates the number of lead variables for which `<expression>` should (at least) be true in order for the lead condition to evaluate to true. If this clause is omitted, `<expression>` must be true in all of `<lead_list>`'s elements in order for the lead condition to become true. An undefined `<expression>` counts as false. The syntax of location conditions is similar to that of lead conditions.

Appendix C - DTL key words

abs	and	array	boolean
constants	div	do	else
end_constants	end_for	end_function	end_if
end_loop	end_main	end_procedure	end_record
end_types	end_variables	exit	false
for	function	if	in
integer	is	loop	main
mod	not	of	or
print	procedure	real	record
return	returns	stop	string
then	true	types	undefined
until	variables	while	
I	II	III	aVR
aVL	aVF	V1	V2
V3	V4	V5	V6
AL	ANT	AS	INF
POST			

CHAPTER 5

Interactive Optimization of Heuristic ECG Classifiers

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In: *Proceedings of Computers in Cardiology 1991* (in press)

Abstract

Diagnostic classification of the electrocardiogram (ECG) by computer is mostly carried out by means of heuristic classification algorithms, which mimic the cardiologist's way of reasoning. We developed a dedicated language, DTL (Decision Tree Language), that allows cardiologists to express their classification knowledge in a way that is familiar to them. DTL can be processed by an interpreter which enables cardiologists to follow the classifier's operation and to interactively modify and test the algorithms. A translator is also available that can produce a fast run-time version of the program.

We followed a procedure of stepwise refinement to optimize our own ECG computer program. Initial modifications were tested on a large database (N=1220) which was collected in the international project 'Common Standards for Quantitative Electrocardiography' (CSE).

Introduction

In their diagnostic classification most computer programs for the interpretation of the electrocardiogram (ECG) or vectorcardiogram (VCG) mimic the cardiologist's reasoning by means of decision-tree logic [1]. The development and refinement of such classifiers, however, is cumbersome and time consuming because it is difficult to mold human experience and knowledge into computer algorithms. It requires a computer expert to implement these algorithms in a (compiled) computer language. The average cardiologist, however, is not able to verify the implementation and will remain in the dark whether his diagnostic intentions have been properly realized and performed as he wished. But also for the initiated it remains obscure in many cases how a given result was reached by the classification process. The program essentially acts as a black box.

In this article we present an interactive environment which cures these problems. The environment consists of a language, DTL (Decision Tree Language), and an interpreter and translator of that language. DTL allows cardiologists to express their classification knowledge in a way that is familiar to them. With the help of the interpreter every step in the classification process can be elucidated, and algorithms can be modified and tested interactively. The translator produces a fast run-time version of the program. The use of this environment to optimize our ECG computer program will be described and results of the improvement will be given.

Decision Tree Language

The main requirement for DTL was that a cardiologist should find it easy to read and to write. Therefore, DTL should have a notation and structure that would be familiar to him and, in addition, programs written in DTL should provide a clear documentation of the classification procedure. Another requirement was that DTL could be interpreted as well as compiled. An extensive description of DTL and its interpreter and translator is given elsewhere [2]; here we will describe the main features that DTL offers.

- Most of the data that the classification part of the program uses are measurements of which the values are related to ECG leads, e.g., Q duration, R amplitude, etc. DTL supplies a data type `lead` which can be used to store these lead-related measurements. The 12 standard leads have been predefined as lead variables. Thus, the Q amplitude in lead aVF is accessed by the expression: `Q_amp in aVF`. A similar data type `location` is supplied, which is primarily used in the classification of infarctions (anterior, inferior and the like).

- ECG conditions are often expressed by means of set-wise operations on lead-related measurements, e.g., “condition is true if Q amplitude is smaller than $-100 \mu\text{V}$ in at least two of leads II, III, and aVF”. In DTL, this would read:

```
(Q_amp < -100) in 2 of II, III, aVF
```

The general syntax of these lead conditions is:

```
(<expression>) in [<number> of] <lead list>
```

where items between square brackets are optional and items between angle brackets must be specified by the user. The `<expression>` can be an arbitrary DTL condition in which lead-related measurements can occur. The `<number>` of clause indicates the number of lead variables for which `<expression>` should at least be true in order that the lead condition be fulfilled. If this clause is omitted, `<expression>` must be true in all of the leads specified in `<lead list>`. The `<lead list>` may contain ranges. For location variables, location conditions may be defined in a similar syntax.

- DTL has a number of control structures. First, there are two conditional statements: The ‘if-then’ and ‘if-then-else’ constructs. Second, several looping constructs are available. The ‘for-in-do’ construct can be used to execute a group of statements a certain number of times. The values of a list are successively assigned to an index variable and the group of statements is executed at each iteration. The list may contain (ranges of) integer values, lead variables, or location variables. The following example shows a for-loop in combination with if-then statements:

```
for lead in I, II, (V1..V6) do
  if (QRS_dur in lead > 100) then ... end_if;
  if (lead is II) then ... else ... end_if;
end_for;
```

Two other looping-constructs are: ‘loop-while’ and ‘loop-until’. The former is used to execute a group of statements for as long as a certain condition holds, the latter is executed until the condition holds.

- DTL has to its disposition ternary comparison operators. These can compare three numerical or string values. For instance, the following condition tests whether the ratio of the Q amplitude and R amplitude is greater than one fourth and less than or equal to one third in at least one of leads V3 or V4:

```
(1/4 < QR_ratio <= 1/3) in 1 of (V3, V4)
```

- DTL supports procedures and functions that enable modular program development. The difference between these program units (a function or a procedure) is that a function returns a value, whereas a procedure does not. Arguments may be passed from one program unit to another. For instance, a function `compute_score` which calculates a point score for LVH diagnosis might be called in the LVH program unit:

```
point_score <- compute_score(S_amp in V1, R_amp in V5)
```

The function takes two arguments and returns a value which is assigned (<-) to variable `point_score`.

Interpreter and translator

DTL may either be compiled or interpreted. The DTL translator converts DTL program units to routines in a high-level computer language (C or C++) which are subsequently handled by the language (and system) specific compiler and linker.

The DTL interpreter provides a number of facilities for tracing, logging and debugging a DTL program. Some of its features are:

Break mode. While interpreting a program unit, the user may enter break mode, either by hitting the break key or by reaching a program line where he has specified a breakpoint prior to program execution. The user then may inspect and change data or program units, and give other commands. With the 'continue' command execution of the program is resumed.

Verbose mode. When the interpreter is in verbose mode, every statement is shown to the user before it is executed.

Step mode. When the interpreter is in step mode, the program is executed one statement at the time. After every statement, the interpreter enters break mode. This feature is especially useful when combined with the verbose mode.

To enable the incorporation of complex algorithms (e.g., dedicated computer-intensive computations and I/O routines) in an efficient way without compromising the readability and simplicity of DTL, 'foreign units' can be defined. Foreign units are procedures or functions that can be called from DTL using the normal calling conventions, but that are written in language other than DTL. In the current implementation, foreign units are written in C or C++ and are linked with the interpreter.

Material

DTL was applied on the classification parts of our ECG computer program MEANS (Modular ECG Analysis System) [3]. MEANS has subprograms for contour classification of the ECG and the VCG [4], rhythm classification [5] and Minnesota coding [6]. All programs were written in FORTRAN.

Various databases of ECGs were used so that learning and testing could be carried out on independent material. One database served as a test set only and was collected in the project 'Common Standards for Quantitative Electrocardiography' (CSE) [7], an international cooperative study for standardization and evaluation of ECG computer programs. It contains 1220 cases which consist of simultaneously recorded ECGs and VCGs, sampled at 500 Hz for

8 or 10 s. The database has been validated by ECG-independent evidence. This 'gold' standard, however, is only known to the CSE coordinating center. The composition of the database has been made public. We will distinguish three main categories: 'hypertrophy' (N=219), including cases with left, right, and bi-ventricular hypertrophy, 'myocardial infarction' (N=547), including cases with infarction irrespective of location and cases with combined infarction and hypertrophy, and 'normal' (N=382).

Interactive optimization procedure

The procedure that was used for the optimization of the classification algorithms consisted of the following steps:

1. Translate the FORTRAN classification program into DTL. The knowledge accumulated in the existing FORTRAN program had to be the basis for further improvement. Thus, the initial DTL program should behave exactly the same as the FORTRAN program.
2. Test the equivalence of the FORTRAN program and the DTL program. Equivalence was tested by letting both programs process a database of cases and comparing the output statements. Each difference was traced back to its cause and the DTL program modified accordingly. Finally, when the outputs of the programs were completely the same, the FORTRAN program was discarded and the DTL program became the current version of the classification program.
3. Scrutinize the DTL program for errors and inconsistencies. The DTL program was easily readable for a cardiologist (GvH) and could thus be checked without the services of a computer expert.
4. Implement suggestions for improvement. A new version of the DTL program was generated with the possible improvements proposed by the cardiologist, while retaining the previous DTL program.
5. Test modifications. With the new version a database of ECGs was processed. The classifications could be compared with two references for the same database: either the classifications of the previous version of the DTL program, or the cardiologist's interpretations.
6. Evaluate modifications. All discrepancies between the results of the new version of the DTL program and the reference were studied. The more difficult cases were traced with the DTL interpreter. New ideas for improvement could easily be implemented on-line and tested interactively.
7. Repeat steps 4 to 6, with each new version in turn becoming the current version until a 'stable' version is obtained. A version was considered stable if no or only irrelevant changes occurred between the new and current versions.

Results

The first and second step of the optimization procedure, the translation from FORTRAN into DTL and the testing of their equivalence, was time consuming, taking roughly two to three months for each of the three programs: ECG and VCG contour classification and rhythm analysis. This was due to the less than perfect documentation of the FORTRAN programs and to the labor involved in tracking the reasons for differences between the FORTRAN and DTL versions. Although it proved easy, by means of the interpreter, to follow the classification process in DTL, the flow of control in the FORTRAN version could often only be traced after singling out critical points in the program source, inserting print statements, and recompiling and linking. The ability to include foreign program units in DTL was mostly used in the rhythm analysis program where many dedicated C++ programs have been linked with the DTL programs. The flexibility provided by special-purpose I/O routines enabled to efficiently enter data in the DTL program and to mimic the original FORTRAN output completely. A beneficial side effect of meticulously translating the FORTRAN program in DTL, was that several hidden errors in the original programs were found.

After this conversion, the actual ECG classification program was now perspicuous to the cardiologist in our team without help of a computer expert (step 3). Modifications and extensions were then proposed.

In the subsequent stage (steps 4 to 6 in the optimization procedure) the results of the DTL version under consideration were compared to the reference (a previous version, or the cardiologist's classifications). Several main categories were distinguished, such as left ventricular hypertrophy, inferior myocardial infarction, etc. Program changes, while producing intended improvement in some cases, may have the opposite effect in other cases. Therefore, the program was run again on the database and all discordant results were scrutinized with the DTL interpreter. This gave rise to new ideas that were preliminarily implemented and tested. Finally, a set of modifications was agreed upon. Their implementation in DTL typically took less than one hour. Then the compiled version of DTL was run on the entire database. This process generally took a day and was repeated several times (step 7).

To assess the effect of the modifications made, the results of the ECG contour classification program were compared against the 'clinical evidence' for the CSE database. Conform the procedure used in the CSE project, the output statements were mapped to four main categories: 'normal', 'hypertrophy', 'infarction', and 'other'. A case was mapped to the 'other' category when the program stated a major conduction defect (a category not present in the database) as a single statement. In Table 1 the results of the original ('old') ECG classification program, i.e., prior to modification, and the results of the latest ('new') version are given. The specificity increased from 94.6% to 97.1%, while the positive predictive value (ppv) for normal slightly

increased. The sensitivity for hypertrophy dropped 8.9% which was more or less compensated by an increase of 10.5% in the ppv. The sensitivity for infarction increased from 58.1% to 67.2% while its ppv remained similar. The total accuracy increased from 67.5% to 69.8% ($P = 0.02$, equivalence tested with Wilcoxon's signed-rank test [8]). These values give an indication of the improvement attained in a limited time span. It should be stressed, however, that we only scrutinized part of the classification algorithms. We are aware of several omissions and flaws in the remaining programs and further improvements are currently being investigated.

Table 1. Classification matrices of the 'old' and 'new' ECG program results against the 'clinical evidence' for the CSE diagnostic database (N=1220).

clinical evidence	computer program								N
	'old'				'new'				
	nor	hyp	inf	other	nor	hyp	inf	other	
normal	94.6	3.0	2.2	0.1	97.1	0.3	2.6	0.0	382
hypertrophy	35.1	51.6	7.2	6.1	43.0	42.5	9.1	5.4	291
infarction	31.7	5.3	58.1	4.9	26.5	2.5	67.2	3.7	547
positive predictive value	56.8	78.9	91.5		57.9	89.4	91.8		

Discussion

The main objective in developing DTL and its interpreter was to create a tool for optimization of heuristic ECG classifiers. There are no principal reasons why the results that were attained might not have been reached by the more conventional approach, i.e., by modifying the algorithms written in the compiled computer language directly. However, such an approach would have been so time consuming and cumbersome as to make it impracticable.

The greatest asset of the language is its almost colloquial nature. A cardiologist, sitting behind the terminal, can understand the functioning of the program without previous training and can pinpoint flaws and suggest improvements immediately. Errors can be fixed on-line. The interactivity of the system stimulates experimentation: new ideas are quickly implemented and tested as to their viability. Any diagnostic proposition from the cardiologist could so far be readily rendered in DTL, in an easily comprehensible form.

In the past, other languages have been developed to facilitate the development of heuristic ECG classifiers: DCDL (Diagnostic Criteria Decision Language) [9] and Hewlett Packard's ECL (ECG Criteria Language) [10]. These languages differ from DTL in many respects. For instance, they do not provide if-then-else or loop-constructs, and ternary comparison operators; they permit only a restricted form of program modularization; no foreign units can be used. Another important difference is that the programs are compiled instead of interpreted: No particular facilities are provided to acquire insight into the actual classification process, and to modify and test the algorithms interactively. These are features that we found very useful in DTL for developing our classification algorithms.

The method of stepwise refinement appears to be successful. However, if the same database of cases is alternatively used as a learning and test set, there is the potential danger of adjusting to it. An experienced cardiologist, who is well aware of this caveat, knows how to balance between elaboration of diagnostic criteria to include cases from a limited database, and generality of the rules. Improvement of diagnostic discrimination is not brought about by mere adjustment of threshold values, a trade-off between sensitivity and specificity, but by application of new or additional knowledge, hopefully increasing both sensitivity and specificity. Another safeguard is to have a final evaluation performed independently: the CSE diagnostic study [11] provides such a possibility. It should be kept in mind that it is the skill of the expert that determines the success of the classification program. DTL is a tool to ease the job, but the tool cannot be blamed for a disappointing result.

Acknowledgment

We are grateful to the CSE coordinating center (Dr. J.L. Willems, Catholic University Leuven, Belgium) for providing the evaluation results on the CSE diagnostic database.

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CHAPTER 6

The Delphi Method to Validate Diagnostic Knowledge in Computerized ECG Interpretation

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Methods of Information in Medicine 1990;29:44-50

Abstract

We investigated the applicability of the Delphi method for increasing the agreement among multiple cardiologists on, firstly, their classifications of a set of electrocardiograms and, secondly, their reasons for these classifications. Five cardiologists were requested to judge the computer classifications of a set of thirty ECGs. If a cardiologist disagreed with the computer classification, he had to provide a new classification and a reason for this change. The results of this first round were compiled and anonymously fed back to the cardiologists. In a second round the cardiologists were asked once again to judge the ECGs and to rate the reasons provided in the first round. The level of agreement was estimated by means of the kappa statistic. The Delphi procedure substantially increased the agreement on the classifications among the cardiologists. The final agreement was very high and comparable with the intraobserver agreement. There was also a high level of agreement on the reasons provided by the cardiologists. However, their use in improving the program's performance is hampered by the qualitative nature of many of the reasons. Suggestions are given for a more formalized elicitation of knowledge.

Key words: Kappa statistic, interobserver agreement, knowledge validation

Introduction

The central problem of this paper is: How is one to determine and possibly improve the performance of a computer program for the classification of electrocardiograms (ECGs)? Asking ourselves this question we had a particular interest in further improving the classification part of our ECG interpretation program MEANS (Modular ECG Analysis System) [1].

In order to assess the performance of a computer program one must be able to tell whether a computer classification is (partly) right or wrong. One way to resolve this issue is by comparing the classifications of the program with those of a cardiologist for a set of ECGs. Such an approach, however, has an important drawback. The interobserver agreement - i.e., the agreement between two or more cardiologists - on the interpretation of the ECG has been proven to be rather low [2,3]. One would like to compare the computer classifications with the classifications that a group of cardiologists have agreed upon. The problem, then, is how to increase the agreement on ECG classification by multiple cardiologists.

If one knows for what cases the program is wrong, one may start to improve the program's performance. Usually, learning and test sets of ECGs are used to develop and modify, and test classification algorithms. It may be very difficult, however, to acquire databases of sufficient size and one may have to resort to rules or algorithms provided by the cardiologist. Furthermore, a cardiologist may suggest new features to be used in the classification algorithms. Again, one would like to use knowledge that a group of cardiologists has agreed upon. The problem is how to aggregate the knowledge on ECG classification obtained from multiple cardiologists.

Thus, for improving and maintaining ECG interpretation systems we are interested in two types of data: the changes made by the cardiologists in the computer classifications and their motivations for doing so. Providing there exists a high agreement among the cardiologists, the former type would give us a clue to the performance of the program and the latter would show the relevant knowledge of the cardiologists in those cases where the program was in error or did lack the necessary knowledge.

The objective of this study was to assess the feasibility of one particular technique, the Delphi method, to tackle the two problems mentioned above. The Delphi method, which originated at the Rand Corporation [4], is a technique to increase the agreement among experts on some subject matter. Essentially, it is an anonymous feedback technique. It has been used in a wide variety of fields [5,6], including medicine [7-10]. However, to the best of our knowledge it has not yet been applied to the questions we asked ourselves in this study: How to assess and possibly improve the performance of a computer program for the interpretation of medical data.

Material and methods

The material consisted of a set of thirty ECGs. They were taken from a larger data set which had been collected in an international study to establish and compare the performance of programs for computerized ECG interpretation. In the latter study, called the CSE project (Common Standards for Quantitative Electrocardiography) [11,12], the ECGs were validated by means of ECG-independent material. The 'true' classification, however, was kept secret by the coordinating center. We, therefore, asked the CSE project coordinator to suggest a (stratified) random sample of thirty ECGs containing 30% normal ECGs and a mixture of pathological ECGs.

Delphi method

The main features of the Delphi method are: (a) anonymity, and (b) feedback and iteration. Anonymity means that every expert in the group provides his or her opinion on the subject matter without reference to the others. Usually a questionnaire is used. In this way the possibly negative effects of direct group interaction are minimized. Also, there is no need to convene the experts. After the first round a 'moderator' compiles the results which are reported to the group without identifying who provided which opinion. With this additional information the experts are asked to provide their opinions again. This process may be repeated for several rounds. It is then expected that the judgments will converge, ideally reaching some sort of consensus.

Experts

The group of experts consisted of five clinical cardiologists. Three of the cardiologists worked in the cardiological departments of different university hospitals, the other two in general hospitals with specialized cardiological departments. The names of the participating cardiologists were not revealed to each other.

First round

The material which was provided to the cardiologists in the first round of the Delphi study consisted of an ECG plot and a classification form for each of the thirty ECGs. The plots had standard time and amplitude scales: 25 mm/s and 10 mm/mV, respectively. The classification form listed age and sex of the patient as well as a number of categories for classification: 'normal', 'left ventricular hypertrophy' (LVH), 'right ventricular hypertrophy' (RVH), 'anterior myocardial infarction' (AMI), 'inferior myocardial infarction' (IMI), and 'other'. The infarction and 'other' categories were divided in subcategories in order to provide the cardiologists with the categories that they were used to in classifying ECGs. The certainty about the presence of a particular category had to be indicated by one of the qualifiers 'definitely', 'probably',

'possibly', and 'definitely not'. In the first round we indicated the computer classification on the classification form.

The Delphi procedure was as follows: If the cardiologist agreed with the computer classification, no action was required. However, if he disagreed with the computer classification, he had to provide a new classification as well as a motivation for the changes. Thus each cardiologist judged (independently) the set of 30 cases, yielding 150 different interpretations.

Second round

After this first round, for each ECG all categories that had a qualifier other than 'definitely not' given by either the computer program or the cardiologists, were compiled on one page together with the motivations, if present. Given such a category, all four qualifiers were listed, i.e. also the ones which had not been chosen by the computer program or the cardiologists. The number of times that each qualifier had been chosen was indicated. For instance, if the computer classification had been 'definitely' on some category and two of the five cardiologists had agreed, one had chosen 'probably' and two had chosen 'definitely not', the form would indicate that for this category 'definitely' had been chosen three times, 'probably' once, 'possibly' zero times, and 'definitely not' twice. Both 'probably' and 'definitely not' would have motivations attached. The source of the classifications and motivations, however, was not revealed except for the computer classification.

In a second round the cardiologists were again asked to give their classifications based on the information provided and the plots. They now had to make an explicit choice for each of the listed categories since the computer classification was not used as a default. If they chose a category with a qualifier for which one or more motivations had been given in the first round, they had to label each motivation as: 'acceptable', 'not acceptable', or 'unclear'. If no motivation was present, that particular combination of category and qualifier had either been computer-generated or it had not been chosen in the first round. In the former case no further action was required. In the latter case a motivation had to be provided as would have been the case if a completely new category had been chosen.

Although the cardiologists were requested to be as quantitative as possible, no restrictions were imposed on the format of their motivations.

Measure of agreement

We used the kappa statistic as a measure of agreement [13-15]. Kappa is defined by the following expression:

$$\text{kappa} = \frac{p_o - p_e}{1 - p_e},$$

in which p_o is the observed proportion of agreement and p_e is the expected proportion of agreement, i.e., the proportion to be expected if the observers assign the cases randomly. In the following it is assumed that the agreement between only two observers is computed.

The observed proportion of agreement is defined as

$$p_o = \sum_{ij} w_{ij} p_{ij},$$

where p_{ij} is the proportion of cases classified in category i by the first observer and in category j by the second, and w_{ij} is a weighting factor between categories i and j . Generally, $w_{ij} = 1$ if $i = j$ and $w_{ij} = 0$ if $i \neq j$. Then, the observed proportion of agreement p_o is equal to the sum of the diagonal elements p_{ii} . The use of non-zero weights for $i \neq j$ allows one to express that cases classified in category i by the first observer and in category j by the second still contribute to the agreement. For instance, one may consider a case classified as anterolateral infarction by one observer in some agreement with a classification as anteroseptal infarction by the other.

The expected proportion of agreement is defined as

$$p_e = \sum_{ij} w_{ij} m_i m_j,$$

where m_i is the proportion of cases classified in category i by the first observer, and m_j is the proportion of cases classified in category j by the second observer.

Kappa equals one in case of perfect agreement because then $p_o = 1$. Kappa equals zero if $p_o = p_e$, i.e., if the observed agreement is equal to the chance-expected agreement. The interpretation of kappa values between zero and one is somewhat subjective. Landis and Koch [16] distinguish several ranges of values. Kappa values below 0.40 may be taken to represent poor agreement; values above 0.75 excellent agreement and values between 0.40 and 0.75 fair to good agreement.

The kappa statistic has a number of desirable properties. Most notably, it can also be used in case of more than two observers with only minor modifications in the computation of p_o and p_e , it takes into account chance agreement, and its variance can be estimated [14,15] which allows for hypothesis testing.

Results

The agreement on the classifications and motivations given by the five cardiologists, and the change in agreement from round one to round two were studied in several ways. First, the agreement on the classifications will be presented. The kappa statistic is used to quantify this

agreement. The results have been compared with the computer classifications and with the classifications that were obtained from a panel of other cardiologists participating in the CSE project. Secondly, the agreement on the motivations will be evaluated. Quantification here is far more difficult because there are missing values and there are no obvious classes to assign the motivations to; the motivations are hard to compare. The results of simply counting the number of motivations will be given.

Classification

We investigated the agreement on the classifications for different levels of detail. A reduction in detail is achieved if some of the original categories and qualifiers are combined. In effect, this corresponds with a classification based on fewer categories and qualifiers. The way in which the categories and qualifiers are combined will be called a coding scheme and the categories that are used in the coding scheme (and possibly are a combination of the original ones) will be referred to as 'basic' categories.

We computed the level of agreement for three coding schemes. In the first coding scheme the basic categories are the same as the six original ones but only the absence or presence of these categories was scored. The qualifiers 'possibly' and 'definitely not' are taken to imply absence of the category, and the qualifiers 'definitely' and 'probably' are taken to indicate presence. The data resulting from this coding scheme are presented in Table 1.

In the second coding scheme, only four basic categories were discerned: 'normal', 'hypertrophy' (combining LVH and RVH), 'myocardial infarction' (combining AMI and IMI), and 'other'. Again, only the absence or presence of the basic categories was determined as described above. For instance, "possibly LVH" would not be scored and "probably AMI" would be scored as 'myocardial infarction'.

Finally, we computed the agreement for a coding scheme consisting of two basic categories: 'normal' (classified by the cardiologists as 'normal' with qualifier 'definitely' or 'probably'), and 'abnormal' (all other classifications).

In the latter coding scheme, the basic categories are mutually exclusive. The weights w_{ij} between category i chosen by one cardiologist, and category j chosen by another, are 1 if $i = j$, and 0 otherwise. In the two other schemes, however, a particular case could have been classified as belonging to more than one basic category. If so, it was considered to belong to a new category made up of the given ones. The weights w_{ij} are now defined as the number of basic categories that category i and category j have in common ($\#\{i \cap j\}$) divided by the number of different basic categories in i and j ($\#\{i \cup j\}$).

Table 1. Classifications by the computer program and five cardiologists of thirty ECGs using six 'basic' categories.* Classifications in the second round which are different from those in the first, are underlined.

case	computer program	round 1					round 2				
		cardiologist					cardiologist				
		1	2	3	4	5	1	2	3	4	5
1	3	3	3	3	3	3	3	3	3	3	
2	6	6	6	6	6	6	6	6	<u>1</u>	6	
3	2	2	2	7	2	2	2	2	7	2	
4	4	1	1	1	1	1	1	1	1	1	
5	8	8	5	8	8	8	8	5	8	8	
6	6	1	5	8	6	1	<u>6</u>	<u>1</u>	<u>6</u>	<u>1</u>	
7	9	9	5	5	5	5	<u>5</u>	5	5	5	
8	8	8	4	8	8	8	8	4	8	8	
9	8	4	4	4	6	8	4	4	<u>4</u>	<u>4</u>	
10	6	1	1	1	1	1	1	1	1	1	
11	4	4	8	8	8	4	<u>8</u>	8	8	<u>8</u>	
12	10	2	10	10	2	10	2	<u>2</u>	<u>2</u>	<u>2</u>	
13	1	1	1	1	1	1	1	1	1	1	
14	2	2	6	2	2	2	2	<u>2</u>	2	2	
15	1	1	6	5	1	1	1	<u>5</u>	<u>6</u>	<u>6</u>	
16	1	1	1	1	1	1	1	1	1	1	
17	6	2	2	2	6	2	2	2	<u>2</u>	2	
18	1	1	1	1	1	1	1	1	1	1	
19	4	4	6	4	6	4	4	6	4	<u>6</u>	
20	6	6	4	4	11	11	<u>4</u>	4	4	<u>4</u>	
21	2	1	1	1	1	2	1	1	1	<u>1</u>	
22	1	1	1	1	1	1	1	1	1	1	
23	6	1	1	1	1	6	1	1	1	6	
24	1	1	1	1	1	1	1	1	1	1	
25	1	1	1	6	1	1	1	1	<u>1</u>	<u>6</u>	
26	10	4	4	4	4	4	4	4	4	4	
27	1	1	1	1	1	1	1	1	1	1	
28	11	4	4	4	4	4	4	4	4	4	
29	4	4	4	4	4	4	4	4	4	4	
30	5	5	6	6	6	5	<u>6</u>	6	6	5	

*1=normal, 2=left ventricular hypertrophy (LVH), 3=right ventricular hypertrophy (RVH), 4=anterior myocardial infarction (AMI), 5=inferior myocardial infarction (IMI), 6=other (OTH), 7=LVH+IMI, 8=AMI+IMI, 9=IMI+OTH, 10=LVH+AMI, 11=AMI+OTH.

In Table 2 the kappa values are given for the agreement between the five cardiologists in the first and the second round. In the first row of Table 2 the results are given for the classification using six basic categories. The kappa value of 0.68 in round one increases to 0.81 in round 2. Assuming that kappa follows a normal distribution [14,15], this difference is statistically significant ($z = 2.61, P < 0.01$). We also computed the kappa based on the results submitted by six cardiologists participating in the CSE project. These cardiologists were from different countries in the European Community; none of them participated in the present study. The kappa value is in concordance with the kappa of the first round. The difference is not statistically significant ($z = 1.01, P = 0.31$).

In the second row of Table 2 the kappas are given for the coding scheme consisting of four basic categories. The first round kappa is 0.70 and increases to a kappa of 0.81 in the second round, a difference which is statistically significant ($z = 2.32, P = 0.02$). Again, the agreement of the CSE referees (kappa = 0.66) is comparable with the kappa of the first round ($z = 0.59, P > 0.50$).

The last row in Table 2 shows the kappas for the two-class coding scheme. The first and second round kappa and the kappa of the CSE project are almost the same. Applying this coding scheme, the Delphi procedure did not result in an increase of agreement.

Table 2. Kappa values reflecting the degree of agreement in classifying thirty ECGs for three coding schemes.

coding scheme	Delphi round 1	Delphi round 2	CSE study
six basic categories	0.68 (0.06*)	0.81 (0.06)	0.62 (0.05)
four basic categories	0.70 (0.06)	0.81 (0.06)	0.66 (0.06)
two basic categories	0.83 (0.07)	0.83 (0.07)	0.77 (0.07)

*standard error of the kappa statistic.

Table 3 shows kappa values which reflect the intraobserver agreement between the cardiologist's classifications of round one and those of round two for the three coding schemes. Since the results of the second round were obtained after (anonymous) feedback, these agreements are not intraobserver agreements in the strict sense; however, they still give a measure for the instability within one observer. The interobserver agreement of the first round is consistently lower than the intraobserver agreements for the coding schemes that use four or six basic categories. The interobserver agreement of the second round, however, is similar to the intraobserver agreement for all coding schemes.

Table 3. Kappa values reflecting the intraobserver agreement of five cardiologists for three coding schemes.

coding scheme	cardiologist				
	1	2	3	4	5
six basic categories	0.82	0.85	0.85	0.75	0.76
four basic categories	0.83	0.83	0.83	0.74	0.79
two basic categories	0.93	0.93	0.93	0.80	0.78

We also determined the agreement between the computer program on the one hand and the cardiologists on the other hand. The kappa values for the first and second Delphi rounds are given in Table 4. The agreement between the program and the cardiologists is substantially lower than the agreement between the cardiologists alone (cf. Table 2). The kappa values of the second round are lower than those of the first. Apparently, the cardiologists' classifications in the second round, while showing an increasing agreement, are further away from the computer classification as compared to their first-round classifications.

Table 4. Kappa values reflecting the degree of agreement between the computer program and the group of five cardiologists for three coding schemes.

coding scheme	round 1	round 2
six basic categories	0.56	0.50
four basic categories	0.57	0.52
two basic categories	0.66	0.61

Motivations

The cardiologists were asked to motivate any change which they made in the computer classifications they were presented with in the first round. If, in the second round, they classified a case as belonging to a certain category-qualifier combination for which one or more motivations were given in the first round, they had to rate these motivations as one of 'acceptable', 'not acceptable', or 'unclear'. In the first round 167 motivations were given. These were rated 599 times in the second round.

We were especially interested in those cases that showed a discrepancy between the computer classification and the classifications of the cardiologists provided that they had reached some sort of consensus. We assumed consensus on a case to be present if at least four of the five cardiologists agreed on its classification.

Taking the coding scheme for six basic categories, in thirteen cases the computer classification (partially) differed from such a consensus classification (cf. Table 1). In Table 5 the ratings of the motivations after the second round are given for these cases. Three classes are distinguished: 'acceptable', 'not acceptable', and 'unclear'. If a cardiologist did not rate a motivation that he was expected to, it was counted as 'unclear'. Only 23% of the 'unclear' scores were explicitly marked as such. Striking is the low number of 'not acceptable' ratings: 4.3% (9 out of 211 ratings). The number of cardiologists that rated a motivation as 'not acceptable' exceeded the number of cardiologists rating it as 'acceptable' for only three motivations (out of a total of 53). Even if all 'unclear' ratings would be added to the 'not acceptable' rating, for still 75% of the motivations (40 of 53) the number of cardiologists that rated a motivation as 'acceptable' would be greater than those rating it otherwise.

In Table 5 motivations occur that were rated by less than five cardiologists. This phenomenon is due to the fact that only those motivations had to be rated that were attached to the chosen category-qualifier combination. For instance, the computer classification was "definitely not LVH", and three of the five cardiologists chose "probably LVH" and the remaining two "definitely LVH" in round two. Complete agreement was reached but the motivations that had been provided in the first round were rated only two and three times.

Table 5. Acceptability of the motivations that were given by the cardiologists when changing the computer classification. The motivations are rated as one of 'acceptable' (acc), 'not acceptable', or 'unclear'. The motivations pertain to thirteen cases where the computer classification differed from a consensus classification of the cardiologists.

number of cardiologists rating a motivation	number of different motivations	number of ratings		
		acc	not acc	unclear
1	4	2	0	2
2	4	4	0	4
3	9	22	0	5
4	8	19	1	12
5	28	82	8	50
	53	129	9	73

Discussion

We investigated the feasibility of the Delphi technique to solve the two central problems of this study: (a) How to increase the agreement on ECG classification by multiple cardiologists and (b) how to acquire the knowledge that they are using. Our interest in these questions was motivated by the difficulties we encountered in assessing and possibly improving the performance of a program for the interpretation of ECGs.

We will first discuss the results of the Delphi procedure with respect to the classifications and motivations. Thereafter we will address some general issues related to the Delphi method and indicate the lessons learned from this study.

Classification

Although many Delphi studies have been conducted in the medical field, few were directed at increasing the agreement on a classification task. In one study by Nagy et al. on the classification of premalignant urothelial abnormalities [9], the severity of only one category was scored. The scores, which were on an ordinal scale, were assigned numerical values and the mean and standard deviation were taken to represent the group opinion and dispersion of the opinions respectively. In ECG classification such an approach is not feasible since multiple, partially nonexclusive, categories may be scored.

Two other studies to improve the diagnostic accuracy of radiologists were reported [7,10]. In both studies the percentage of correct diagnoses as compared to a gold standard is used to quantify the effect of the Delphi procedure. This approach has two important limitations. Firstly, the percentage of correct diagnoses (which is the observed proportion of agreement p_o in case of two observers and weights w_{ij} that are one if $i = j$ and zero otherwise) does not take into account the chance-expected agreement. Secondly, effectively two 'experts' are compared: one 'expert' is the gold standard, the other 'expert' is the group of referees. If more than two experts need to be compared the agreement will be harder to quantify.

These problems are remedied by the use of the kappa statistic. We advocate its use as a means to quantify the agreement between experts and the changes between various rounds of, e.g., a Delphi procedure.

The agreement on the ECG classification depended on the coding scheme that was used to codify the original data. The results show that the agreement on the classification into 'normal' and 'abnormal' in round one was similar to the agreement in round two. Furthermore, the initial agreement was already very high. However, if the abnormal class is subdivided, the kappa values show that a Delphi procedure increases the agreement substantially. The final agreement is similar to the agreement which was obtained in the two-category classification. It is also comparable to the intraobserver agreement of the individual cardiologists.

After the first round, the agreement between the computer classification and the cardiologists' classifications proved to be considerably lower than the agreement between the classifications of the cardiologists alone. The disagreement was even higher after the second round. Apparently, the computer classification is not yet at an expert level and has to be further improved.

Motivations

The cardiologists were asked to provide a motivation for each change that they made in the computer-generated classification. In the second Delphi round we expected a convergence in the multitude of motivations which had been given in the first. Thus, as we hoped, some of the knowledge which cardiologists use in ECG classification might emerge.

We were especially interested in the motivations given for those cases where the cardiologists' classifications showed a consensus which differed from the computer classification. As it turned out, very few of the motivations were considered 'not acceptable'. The acceptance of the motivations is apparently very high, even if in the first round more than one motivation had been given for a particular category-qualifier combination. Three observations may, at least partially, explain the high agreement. Firstly, we did not attempt to aggregate multiple motivations that were given in the first round. Thus, while the phrasing of the motivations was different, their meaning might have been the same.

Secondly, in several cases multiple motivations tended to stress different criteria. Each criterion then was rated as being an 'acceptable' motivation. This was most prominent for motivations which subsumed others, for instance one motivation that listed a Q in both V5 and V6 and another (on the same category-qualifier combination) that listed a Q in V5 only. Both motivations then were rated as 'acceptable'.

Thirdly, many motivations were of a qualitative nature. Expressions like "large Q", "normal R-wave progression", "low T", "no voltage criteria", were very frequent and will have been accepted more easily than truly quantitative criteria.

Is the Delphi procedure the answer to the central problems of this study? Firstly, the Delphi procedure was successful in increasing the agreement on ECG classification by multiple cardiologists and thus may be used to determine the performance of a computer program.

Secondly, in asking the cardiologists to provide motivations we hoped for the elicitation of knowledge that might be used for the improvement of our current ECG classification program. This goal proved to be too ambitious, at least in the current setup. Although the agreement on the motivations after the second Delphi round was very high, the motivations were too incomplete and too fuzzy to be useful in the adaptation and creation of classification algorithms. In order to be useful, a more formalized approach has to be followed. The cardiologists should no longer provide qualitative motivations but, instead, should comment on features and rules

in a decision model (e.g., a decision tree). Both the computer classification and the relevant part of the decision tree which resulted in that classification should be presented to the cardiologists. In this way the comments of the cardiologists will be directly related to the classification algorithm.

The Delphi method has been criticized for its possible lack of accuracy even if a high agreement has been reached. For example, two cardiologists may agree on the interpretation of an ECG, and yet both be wrong as compared to conclusive evidence acquired by catheterization or autopsy. Indeed, we feel there are no intrinsic reasons why the application of the Delphi procedure would result in an accurate outcome. In our opinion the Delphi method is most valuable in situations where the 'truth' is unknown. This situation also occurs in ECG interpretation. Spodick [17], amongst others, takes the stand that in order to minimize bias, the ECG in first instance should be judged on its own, i.e., without the use of ECG-independent data except for the patient's age and sex. A final diagnosis based on all clinical data might of course deviate from the ECG classification. Yet, this would not invalidate the initial classification.

The present research indicates that still another application of the Delphi method is useful. In the field of computerized ECG interpretation we are in need of validated databases of ECGs that are to be used as learning and test sets for classification algorithms. The Delphi procedure proves to be a means to reach a very high agreement on the classification of ECGs and may thus be used to validate a large database.

Our study is to be considered as having an explorative character. It taught us that the Delphi procedure can be used to reach a very high agreement on the classification of ECGs among multiple experts. Thus, it is possible to detect cases where a computer program is in error or lacks knowledge. This is an indirect way to use the Delphi procedure as a vehicle to acquire the knowledge needed to actually improve and maintain a computer program for the interpretation of medical data. A direct way to improve a program is dependent on the way experts' feedback can be formalized.

Acknowledgments

The authors would like to thank Dr. G. van Herpen (University Hospital, Leiden) who made valuable suggestions concerning the questionnaires, and the cardiologists who participated in the Delphi procedure: Dr. N. van Hemel (St. Antonius Hospital, Nieuwegein), Prof. P.G. Hugenholtz (Thorax Center, Rotterdam), Dr. J.F. May (University Hospital, Groningen), Prof. E.O. Robles de Medina (University Hospital, Utrecht), Dr. F.C. Visser (Free University Hospital, Amsterdam). We are grateful to Prof. J.L. Willems, coordinator of the CSE project, for his permission to use the CSE library for our studies.

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CHAPTER 7

*Reconstruction of the Frank Vectorcardiogram from Standard
Electrocardiographic Leads:
Diagnostic Comparison of Different Methods*

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Abstract

Three methods for reconstructing the Frank VCG from the standard 12-lead ECG were studied. The first was based on multivariate regression, the second on a model of the cardio-electrical activity, and the third method used a quasi-orthogonal set of ECG leads.

The methods were evaluated on a test set of 90 cases by a numerical distance measure and by the agreement in diagnostic classification of the original and reconstructed VCGs. The original and reconstructed VCGs were presented separately and in random order to three referees. Eighteen of the original VCGs were presented three times to estimate the intraobserver agreement. Kappa statistics were used to quantify the agreement between diagnostic classifications. Separately, one referee was simultaneously presented the original VCG and its three reconstructions for all cases. Each reconstructed VCG was classified as either diagnostically 'same' as the original, 'borderline', or 'different'.

The performance of the regression method and the model-based method was comparable. Both methods were preferable to the quasi-orthogonal method. The kappa values for the preferred methods indicated a good to excellent diagnostic agreement between the original and reconstructed VCGs. Only one out of ninety VCGs that were reconstructed with the regression method was classified as 'different' compared to the original VCGs; three VCGs were classified as 'different' with the model-based method. It was also found that estimation of similarity by a distance measure could not replace diagnostic evaluation by skilled observers.

Key words: VCG reconstruction, evaluation of diagnoses, kappa statistic

Introduction

The usefulness of vectorcardiography has repeatedly been recognized [1-3]; its use, however, has declined. From several possible explanations, the two most pertinent probably are that the conventional vectorcardiogram (VCG) registration technique (photography, X-Y plotter) was slower and more cumbersome than that of the electrocardiogram (ECG); and that users tended to dislike the additional electrodes in unusual arrangements and positions that are required by vectorcardiographic lead systems. The latter obstacle might be removed if the VCG could be adequately synthesized from conventional ECG leads. Modern electrocardiographs, equipped with microprocessors and fast printer-plotters, could carry out this task instantaneously and produce a VCG plot in addition to an ECG, thus eliminating the first-mentioned inconvenience as well. The present study deals with three such methods of reconstruction and evaluates their results.

Methods

Materials

Two sets of ECGs were used: One containing 147 cases and serving as a learning set in the statistical approach (described below), the other containing 90 cases and serving as a test set. All cases were taken from data sets used in the study 'Common Standards for Quantitative Electrocardiography' (CSE) carried out by the CSE Working Party [4]. Although the validated diagnosis for each case was not revealed by the CSE coordinating center, the overall composition of the databases was known. The learning set contained about 30% normal cases, 15% cases with hypertrophy, 30% cases with myocardial infarction, and 25% other cases. The test set contained about 30% normals, 25% hypertrophies, 30% myocardial infarctions, and 15% others. Each case consisted of eight independent leads of the standard ECG (leads I, II, V1 to V6) and the Frank VCG (leads X, Y, Z). All leads were recorded simultaneously. The data were sampled at 500 Hz during 10 s. The digitized data were processed off-line by the ECG interpretation program MEANS (Modular ECG Analysis System) [5] which yielded an averaged P-QRS-T complex for each lead. Only such averaged complexes were used in this study.

Reconstruction methods

Reconstruction of a particular VCG lead can be performed by computing a linear combination of the ECG leads, for which the coefficients are arranged in a reconstruction matrix. Three different ways can be envisaged for determination of the reconstruction coefficients:

1. A *single-lead* approach in which a VCG lead is merely represented by that single ECG lead that resembles it best, perhaps using a scaling coefficient. This is the reconstruction matrix in its simplest form: all input leads have coefficients equal to zero, except for the selected three 'quasi-orthogonal' ECG leads. This method will later be denoted by Quasi.

Kors et al. [5] described a set of quasi-orthogonal leads which are used in the signal analysis part of their ECG interpretation program. For each case from a set of simultaneously recorded ECGs and VCGs, they computed the correlations between the ECG and VCG leads. For each VCG lead the ECG lead which showed the highest median correlation was selected. The amplitude adjustment of these ECG leads was chosen as simple as possible without compromising the signal-analysis performance. Thus, leads X, Y and Z were approximated by leads V6, II, and $-0.5 \cdot V2$ respectively. The reconstruction matrix is given in Table 1A. Bjerle and Arvedson [6] reported a reconstruction matrix comparable to the one above. They reconstructed X by $1.06 \cdot V6$, Y by $1.88 \cdot aVF$, and Z by $-0.532 \cdot V2 + 0.043 \cdot V6$.

Table 1. Reconstruction matrices. A: quasi orthogonal; B: inverse Dower; C: regression.

		I	II	V1	V2	V3	V4	V5	V6
A	X	0.00	0.00	0.00	0.00	0.00	0.00	0.00	1.00
	Y	0.00	1.00	0.00	0.00	0.00	0.00	0.00	0.00
	Z	0.00	0.00	0.00	-0.50	0.00	0.00	0.00	0.00
B	X	0.16	-0.01	-0.17	-0.07	0.12	0.23	0.24	0.19
	Y	-0.23	0.89	0.06	-0.02	-0.11	-0.02	0.04	0.05
	Z	0.02	0.10	-0.23	-0.31	-0.25	-0.06	0.05	0.11
C	X	0.38	-0.07	-0.13	0.05	-0.01	0.14	0.06	0.54
	Y	-0.07	0.93	0.06	-0.02	-0.05	0.06	-0.17	0.13
	Z	0.11	-0.23	-0.43	-0.06	-0.14	-0.20	-0.11	0.31

2. A *model-based* approach, as used by Dower et al. [7,8] for reconstruction of the 12-lead ECG from the Frank VCG. Every ECG lead is expressed as a linear combination of the X, Y, and Z components of the VCG with coefficients prescribed by Frank's torso model [9].

Recently, the model approach was also used in reverse mode: Edenbrandt and Pahlm [10,11] computed an ‘inverse’ matrix from the Dower data for reconstruction of the Frank VCG from the 12-lead ECG. In Table 1B the reconstruction coefficients are given for this method, later to be denoted by Invers.

3. A *statistical* approach by which the reconstruction matrix is derived by a regression technique. Based on a learning set of simultaneously recorded ECGs and VCGs, the reconstruction coefficients are found by minimizing the sum of the squared differences between the target lead and its reconstruction. Such transformations were first calculated by Burger et al. [12] between different VCG systems in order to make VCGs from one system resemble those of another. Several investigators used this technique for reconstructing the ECG from the VCG [13-16]. Conversely, Wolf et al. [15] reconstructed the VCG from the ECG in this way but did not publish the reconstruction matrix.

With the BMDP statistical package [17] a multivariate regression was performed on our learning set. Various reconstruction matrices were derived for different segments of the P-QRS-T complex. A visual comparison of the reconstruction results for a subset of the learning population, using different reconstruction matrices, revealed only very small differences. Therefore, we decided to further use the reconstruction matrix which resulted from the regression on the QRS complex only and which was subsequently applied to the whole P-QRS-T complex. The reconstruction coefficients are given in Table 1C. This method will later be denoted by Regres.

Evaluation methods

For the evaluation we reconstructed VCGs from the ECG leads in the test set. Evaluation of the various reconstruction methods is based upon comparisons between the original and reconstructed VCGs. Evaluation was performed by computing a numerical distance measure (morphologic comparison) and by determining the agreement in the diagnostic classification (semantic comparison). For illustration purposes we also present the differences between the original and reconstructed VCGs for one diagnostically important parameter: the occurrence of a Q wave in lead X and lead Y, and an initial R wave in lead Z.

Firstly, we used a numerical distance measure D :

$$D = \frac{1}{K} \sum_{k=1}^K \frac{|V_k - V_k^*|}{|V_k|}$$

where V_k and V_k^* are the original and reconstructed VCG respectively, and k ranges over those sample points in the QRS complex for which the spatial amplitude, $|V_k|$, exceeded a certain

threshold. This threshold value was set because very small values of $|V_k|$ might influence the distance measure disproportionately. K denotes the number of sample points taken into account. The rationale for this measure is that differences occurring at relatively small spatial amplitudes, e.g., in a Q wave, are generally of more diagnostic importance than the same differences at larger amplitudes, e.g., in an R wave, and should be weighted more heavily. If D equals zero, the reconstructed VCG resembles the original perfectly; if D equals one, the difference between the VCGs is on average equal to the spatial amplitude of the original VCG at each time instant.

Secondly, we determined the diagnostic agreement between the original VCGs and their reconstructions. Two situations are distinguished:

- A. All VCGs, both the originals and their reconstructions, were classified separately and in random order. The classifications were made independently by three referees. In order to estimate intraobserver variability, eighteen of the original VCGs were presented two additional times. Thus, each referee classified 396 VCGs $((1+3) \times 90 + 2 \times 18)$. The scalar X, Y, and Z leads as well as their usual planar projections were provided for each original or reconstructed VCG.

The referees used a form which listed six main categories: normal, left ventricular hypertrophy, right ventricular hypertrophy, anterior infarction, inferior infarction, and other. Of course, more than one category could be applicable in a particular case. For each case an overall classification was also required, namely: normal, probably normal, possibly pathological, probably pathological, and pathological.

- B. In a separate evaluation, for each case from the test set the original VCG and its three reconstructions were presented on one page. The scalar X, Y, and Z leads of the original VCG and its usual projections as well as the projections of each of the reconstructed VCGs were provided. The latter were presented in random order without identifying which of the three reconstruction methods was employed.

Taking the original VCG as a reference, a cardiologist had to classify each of the reconstructed VCGs in one of three classes: diagnostically 'same', i.e. both the original and the reconstructed VCG showed the same diagnostic categories, 'different', and 'borderline'.

The kappa statistic was used as a measure of agreement [18-20]. Kappa is defined by the following expression:

$$\text{kappa} = \frac{p_o - p_e}{1 - p_e},$$

in which p_o is the observed proportion of agreement and p_e is the expected proportion of agreement, i.e., the proportion to be expected if the observers assign the cases randomly. In the following short explanation of kappa it is assumed that we have only two observers.

The observed proportion of agreement is defined as:

$$p_o = \sum_{i,j} w_{ij} p_{ij},$$

where p_{ij} is the proportion of cases classified in category i by the first observer and in category j by the second, and w_{ij} is a weighting factor between categories i and j . Generally, $w_{ij} = 1$ for $i = j$ and 0 otherwise. Then the observed proportion of agreement p_o is equal to the sum of the diagonal elements p_{ii} . The use of non-zero weights for $i \neq j$ allows one to express that cases classified in category i by the first observer and in category j by the second still contribute to the agreement. For instance, one may consider a case classified as “probably pathological” by one observer being in some agreement with a classification as “possibly pathological” by the other.

The expected proportion of agreement is defined as:

$$p_e = \sum_{i,j} w_{ij} m_i m_j,$$

where m_i is the proportion of cases classified in category i by the first observer, and m_j is the proportion of cases classified in category j by the second observer.

Kappa equals one in case of perfect agreement because then $p_o = 1$. Kappa equals zero if $p_o = p_e$, i.e. if the observed agreement is equal to the chance-expected agreement. The interpretation of kappa values is discussed by Landis and Koch [21], amongst others, who distinguish three ranges. Values below 0.40 may be taken to represent poor agreement; values above 0.75 excellent agreement and values between 0.40 and 0.75 fair to good agreement.

The kappa statistic has a number of desirable properties. Most notably, it can be used in case of more than two observers, it takes into account chance agreement, and its variance can be estimated [19,20] allowing for hypothesis testing.

Results

In this study, all three methods were used to reconstruct the Frank VCG from the 12-lead ECG. Original and reconstructed VCGs were compared by a numerical measure, by differences in a parameter value, and by the agreement in diagnostic classification.

Firstly, Figure 1 shows the cumulative distribution of the numerical distance measure given for each reconstruction method. The threshold value used in the computation of the distance measure, is 10 μ V. Other thresholds, which we varied between 5 and 25 μ V, yielded almost identical distance values. Applying the sign test, the differences between method Regres and either Invers or Quasi are statistically significant ($P < 0.01$). Figures 2, 3, and 4 show examples of original VCGs and their reconstructions with distance measures at approximately the 10, 50, and 90 percentile values respectively.

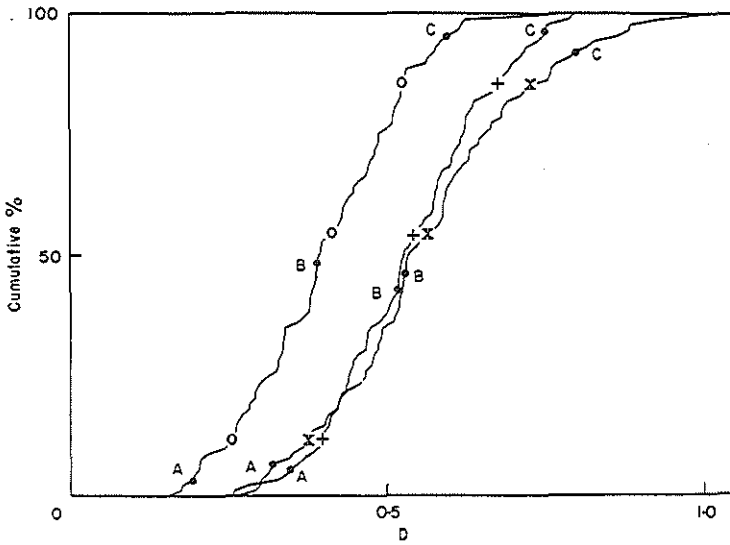


Figure 1. Cumulative distribution of the numerical distance measure D for the reconstruction methods Regres ($-o-$), Invers ($-x-$), and Quasi ($-+-$). A, B, and C indicate three particular cases which are shown in Figures 2, 3, and 4 respectively.

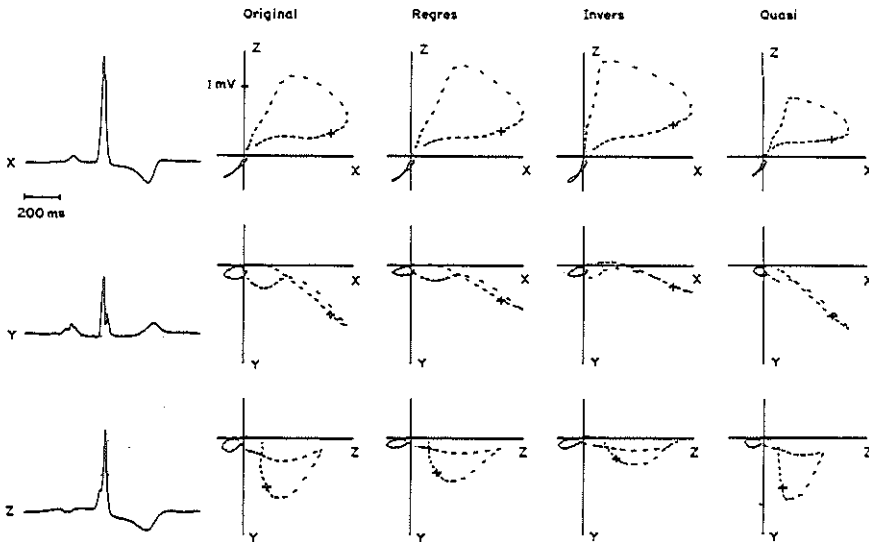


Figure 2. Performance of the three reconstruction methods for a 'better than average' case (A in Figure 1). Shown are the original XYZ leads and the horizontal, frontal, and sagittal projections of the original and reconstructed VCGs. The values of the distance measure are 0.19, 0.32, and 0.35 for method Regres, Invers, and Quasi respectively. The '+'-mark denotes the time instant at 36 ms after QRS onset.

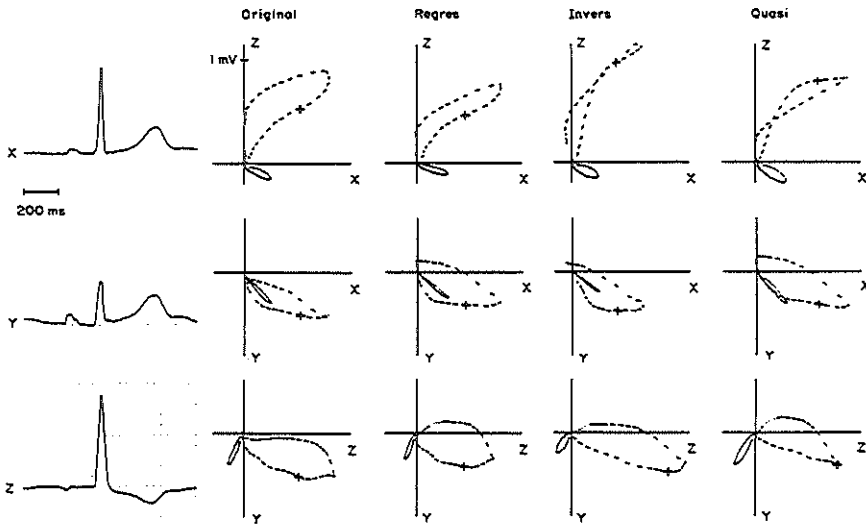


Figure 3. Performance of the three reconstruction methods for an 'average' case (B in Figure 1). Shown are the original XYZ leads and the horizontal, frontal, and sagittal projections of the original and reconstructed VCGs. The values of the distance measure are 0.39, 0.53, and 0.52 for method Regres, Invers, and Quasi respectively. The '+'-mark denotes the time instant at 36 ms after QRS onset.

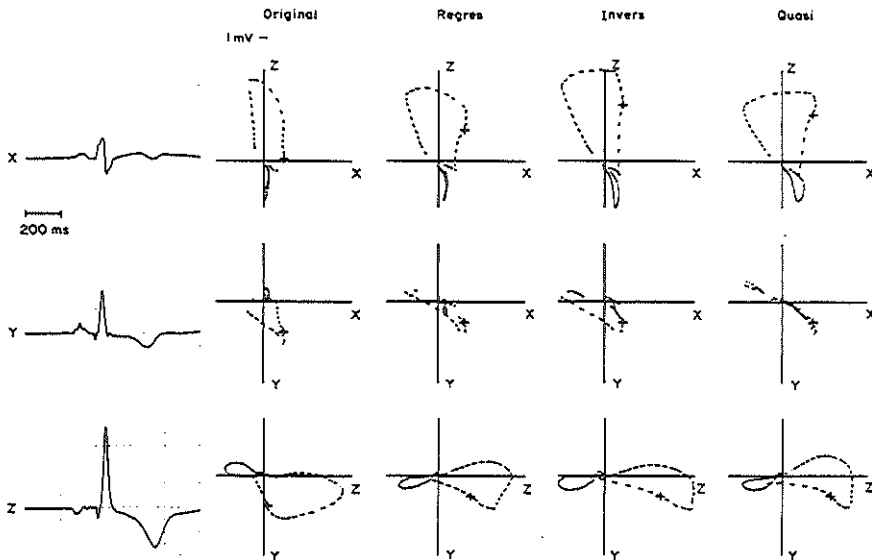


Figure 4. Performance of the three reconstruction methods for a 'worse than average' case (C in Figure 1). Shown are the original XYZ leads and the horizontal, frontal, and sagittal projections of the original and reconstructed VCGs. The values of the distance measure are 0.60, 0.80, and 0.76 for method Regres, Invers, and Quasi respectively. The '+'-mark denotes the time instant at 36 ms after QRS onset.

Secondly, to illustrate the ability of the reconstruction methods to reproduce a diagnostically important parameter, Table 2 gives the results for detection of Q waves in leads X and Y, and for detection of an initial R wave in lead Z, respectively. Wave detection was performed by the MEANS program [5]. There is a remarkably large number of false-negative detections in lead Y. Further inspection, however, revealed that most of these Q waves were small (duration < 20 ms, amplitude < 100 μ V) and diagnostic evaluation proved most of these Q waves to be diagnostically insignificant.

Table 2. Wave detection in the original VCG and its reconstructions by the MEANS program according to presence (+) and absence (-) of waves. X: Q waves in lead X; Y: Q waves in lead Y; Z: initial R waves in lead Z.

			quasi orthogonal		inverse Dower		regression	
			+	-	+	-	+	-
X	o	+	39	5	36	8	40	4
	r	-	12	34	1	45	1	45
	i							
Y	g	+	45	23	52	16	47	21
	i	-	1	21	4	18	2	20
	n							
Z	a	+	8	4	8	4	10	2
	l	-	8	70	6	72	3	75

Thirdly, the agreement in the classification of the original and reconstructed VCGs was measured. The two above-described situations are distinguished: (A) The VCGs are presented separately and randomly, and (B) for each case the original and the reconstructed VCGs are presented together.

A. We discern two situations: one where we used the classification in six main categories, and one where we used the overall classification of the referees. In a particular case a referee may have decided that more than one main category was present; such a combination is handled as an additional category. In computation of the observed agreement p_o and the expected agreement p_e weights are used. The weights w_{ij} are defined as the number of main categories that category i and category j have in common divided by the number of main categories in either category i or j , whichever is largest.

Table 3. Kappa values reflecting the intraobserver agreement (n=18) and the agreement on the classification of the original VCGs and their reconstructions (n=90) for (A) classification in six main categories, (B) overall classification. In the last column kappa values are given for all classifications pooled (n=270).

A				
referee	1	2	3	pooled
intraobserver agreement	0.86	0.84	0.93	
agreement on				
original-quasi orthogonal	0.68	0.73	0.60	0.67
original-inverse Dower	0.76	0.71	0.69	0.72
original-regression	0.77	0.75	0.66	0.72
B				
referee	1	2	3	pooled
intraobserver agreement	0.98	0.91	0.93	
agreement on				
original-quasi orthogonal	0.78	0.65	0.64	0.69
original-inverse Dower	0.84	0.74	0.71	0.77
original-regression	0.85	0.73	0.70	0.76

The kappa values in Table 3A reflect the agreement on the classification in six main categories of the original and reconstructed VCGs. Kappa values are given for the classifications of each referee separately, and for all classifications pooled. The differences between method Invers and Regres are small; method Quasi performs somewhat less for referees 1 and 3. The differences between Quasi and either Invers or Regres for the pooled classifications are significant at the 10% level of significance.

Eighteen of the original VCGs were classified three times by each referee. The agreement on those VCGs, as expressed by the kappa value, is an indication of the intraobserver agreement. These kappa values are very high; the referees appeared to be very consistent in their classifications.

Agreement on the overall classification was also determined using appropriate weighting coefficients. The kappa values are given in Table 3B. The differences between method Quasi and either Invers or Regres for the pooled classifications are statistically significant ($P < 0.05$).

In order to exemplify some of the kappa values, Table 4 provides the data used to compute the agreement on overall classification between the original and reconstructed VCGs. The classifications of the three referees have been pooled.

Table 4. The results of classifying the original VCGs and their reconstructions as normal (--), probably normal (-), possibly pathological (□), probably pathological (+), or pathological (++). The classifications of the three referees have been pooled (n=270).

		quasi orthogonal					inverse Dower					regression				
		--	-	□	+	++	--	-	□	+	++	--	-	□	+	++
o r i g i n a l	--	32	9	2	2	0	30	11	2	2	0	33	7	3	1	1
	-	8	5	3	1	1	9	5	2	0	2	7	7	2	1	1
	□	6	3	1	4	0	4	5	2	2	1	4	4	5	1	0
	+	4	0	3	0	1	1	2	1	1	3	3	0	1	2	2
	++	8	7	10	10	150	0	3	17	9	156	4	4	9	11	157

B. In a separate study, referee 1 (who showed one of the highest intraobserver agreements) classified each of the reconstructed VCGs in one of the classes: diagnostically 'same', 'borderline', and 'different', taking the original VCG as a reference. In Table 5 the results for the three reconstruction methods are given. Clearly, method Quasi is performing least well and method Regres is not significantly better than Invers. For method Regres, only one case was classified as 'different': the reconstructed VCG was considered normal while the corresponding original VCG showed an inferior infarction.

Table 5. The classification of the reconstructed VCGs compared with the original VCG for each of the three reconstruction methods by one referee.

	same	borderline	different
quasi orthogonal	67	13	10
inverse Dower	77	10	3
regression	79	10	1

Finally, we investigated whether the numerical distance measure could replace the laborious diagnostic classification for evaluating reconstruction methods. We compared the distance

measure with the classification in classes 'same', 'borderline', and 'different', pooled over the three reconstruction methods. In Figure 5 the cumulative distribution of the distance measure for each class is given. Although the median distance value is highest for the 'different' class, considerable overlap remains. Especially the 'same' and 'borderline' classes are hard to discriminate on the basis of the distance measure. The difference in median values was statistically not significant (Mann-Whitney test statistic [22], $P = 0.24$); yet about 10% of the cases classified as 'same' have a distance value greater than the median distance value for the 'different' class.

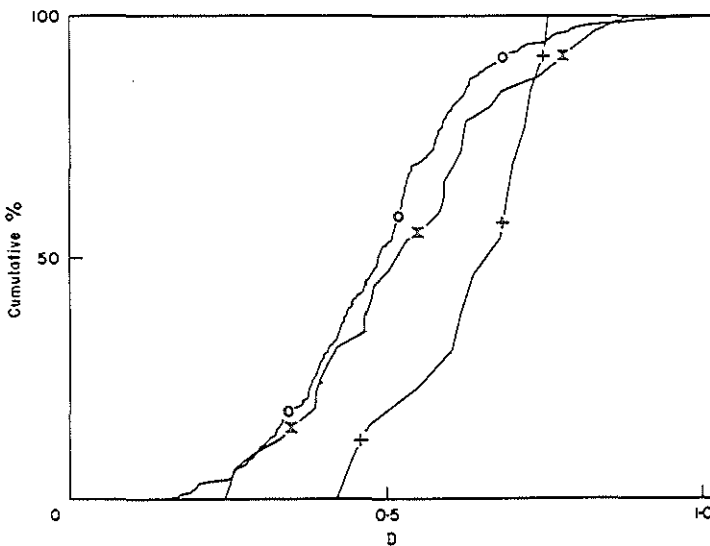


Figure 5. Relation between the numerical distance measure D and the classification of all pairs of the original and reconstructed VCGs. Shown is the cumulative distribution of the distance measure for the three classes: 'same' (o-), 'borderline' (-x-), and 'different' (+).

Discussion

To establish the diagnostic accuracy of a reconstruction method, we decided that evaluation should primarily be based on a comparison of the cardiologists' classification of the original and reconstructed VCGs (semantic comparison). Such an approach contains two major difficulties. First, the classification results for different methods are difficult to compare. This probably

accounts for the use in the literature of other, more objective criteria such as differences in amplitude and interval measurements, or the correlation between the original and reconstructed leads [10,13,15,16]. We used the kappa statistic as a means to quantify the diagnostic agreement. Although the kappa statistic allows for chance-expected agreement, interpretation of the kappa value remains subjective. Secondly, the diagnostic classification is time-consuming for the collaborating cardiologists. An evaluation criterion excluding involvement of cardiologists would be preferable, provided the results agree with those of the diagnostic classification. Therefore, we investigated whether a distance measure could be used instead of the cardiologists' classification. As shown in Figure 5, there is a considerable overlap of the distance values for the three classes 'same', 'borderline', and 'different'. The value of the distance measure is a rather poor predictor for classification of a particular case. Although low distance values (< 0.4) are an indication for classes 'same' or 'borderline', high distance values have a low discriminating power. We therefore conclude that an evaluation based on classifications made by a cardiologist remains necessary or, in other words, a morphologic comparison does not replace a semantic one.

There are several reports on reconstruction of the VCG from the ECG [6,10,11,14,15] but, generally, a single reconstruction method was used in these studies. Solely Edenbrandt and Pahlm [10,11] compared four methods, including Dower's inverse matrix and quasi-orthogonal leads; the inverse matrix gave the best results. Their conclusion was based on a visual comparison of the original and reconstructed VCGs where the cardiologists had to indicate which reconstructed VCG resembled best the original. No regression techniques, however, were used in that study nor a diagnostic evaluation. A proper comparison with the methods described in all other studies is severely hampered by the use of different evaluation methods.

The results for the numerical distance measure in this study indicate that the method based on multivariate regression is superior in a mathematical sense to both other methods. The diagnostic evaluation, however, showed no significant differences between the regression and the inverse Dower methods; both being preferable to the quasi-orthogonal method. Apparently, the distance measure which largely represents information of morphologic nature, does not fully take into account the semantic information used in the diagnostic process.

The diagnostic accuracy of the reconstruction methods was established in two ways. In the first evaluation by three referees, the kappa values indicated a good to excellent agreement on the diagnostic classification of the original and reconstructed VCG. In a second evaluation, one cardiologist was simultaneously presented the original VCG and its reconstructions for all cases. The results for the reconstruction based on regression show that only one case out of ninety was classified diagnostically 'different'; for the reconstruction with the inverse matrix three cases were classified 'different'.

Both evaluations provide strong indications that the semantic (diagnostic) information, present in the original VCG, is also contained in the simultaneously recorded 12-lead ECG. For this reason we pose the central question of this study: Do reconstructed VCGs sufficiently resemble the originals to be used instead? Previous studies on the reconstruction of the VCG from the ECG and vice versa differ in their conclusions. Some concluded that the reconstruction can only be performed accurately when, for each patient, an individual matrix is computed, because the variability between patients is too large to allow for a generally applicable reconstruction matrix [13,14]. Others concluded that the reconstructed leads may reveal valuable diagnostic information in addition to the leads which are used for the reconstruction [6,15]. In one study, it is even concluded that the reconstructed (ECG) leads give more accurate diagnoses than the original leads [8].

One reason for these divergent conclusions is that there is no generally accepted criterion to decide whether a reconstruction method is good enough. Is it accepted only if perfect agreement on the classification of the original and reconstructed VCGs is realized, or is some difference in diagnostic performance acceptable - but then: how much?

In our opinion the reconstructed VCG may be most valuable not as a substitute of the original VCG (or the ECG) but in addition to the 12-lead ECG. Electrocardiographs displaying the reconstructed VCG may provide cardiologists with important additional information, e.g. by showing phase relations between leads more explicitly. Our particular interest is in further improvement of computerized ECG interpretation by supplementing it with the interpretation of the reconstructed VCG.

Acknowledgments

The authors would like to thank Dr. C. Brohet, M.D., Ph.D. (Université Catholique de Louvain, Brussels, Belgium) and Dr. P.W. Macfarlane, Ph.D. (Royal Infirmary, Glasgow, U.K.) for their collaboration in the diagnostic evaluation. We are grateful to the CSE coordinating center (Dr. J.L. Willems, Katholieke Universiteit Leuven, Leuven, Belgium) for providing the recordings in the learning set and test set.

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CHAPTER 8

Improvement of Diagnostic Accuracy by Combination of ECG and VCG Computer Interpretations

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Submitted for publication

Abstract

In the international project 'Common Standards for Quantitative Electrocardiography' (CSE), diagnostic results of different computer programs for the interpretation of the electrocardiogram (ECG) and of the vectorcardiogram (VCG) were combined and it was shown that the 'combined program' performs better than each program separately. As our own program MEANS (Modular ECG Analysis System) comprises two different classification programs - one for the ECG, the other for the VCG - we investigated whether the combination of the two would yield a better diagnostic result than either one separately. This approach requires that a VCG be always recorded in addition to the ECG. To circumvent this complication, the VCG was reconstructed from the simultaneously recorded ECG leads. This reconstructed VCG (rVCG) was then interpreted by the VCG classification program, whereupon the interpretations of the ECG and the rVCG were combined. For the validation, the CSE database of documented ECGs and VCGs (N=1,220) was used.

The combination of the ECG and VCG interpretation programs proves to perform significantly better than each program separately (total accuracy 74.2% (ECG+VCG) versus 69.8% (ECG) and 70.2% (VCG), $P < 0.001$ in both cases). The results of the rVCG (total accuracy 70.5%) are comparable with those of the ECG and the VCG ($P > 0.10$ in both cases). The performance of the combination of ECG and rVCG (total accuracy 73.6%) is approximately the same as that of the combined ECG and VCG ($P > 0.10$). Thus, the performance of an ECG computer program can be improved by incorporating both ECG and VCG classificatory knowledge, using only the ECG itself. The more general question which conditions underlie the improved performance of a combination of classification programs is also discussed.

Key words: ECG interpretation program, reconstructed vectorcardiogram

Introduction

“Two heads are better than one” is a saying that also appears to hold for the interpretation of the electrocardiogram (ECG) - and perhaps the more heads the better. In the international project ‘Common Standards for Quantitative Electrocardiography’ (CSE) [1] it was shown that a ‘synthetic ECG diagnostician’, produced by merging the interpretations of eight ECG readers, performed better than each reader separately [2,3]. The same proved to be the case for computer programs for the interpretation of the ECG or of the vectorcardiogram (VCG). In the present study, we have sought to take advantage of this effect to improve the results of our ECG interpretation program MEANS (Modular ECG Analysis System) [4,5]. This is feasible because MEANS comprises two different classification programs: One for the ECG, the other for the VCG. The combination of the two may then possibly yield a better result than that of either one separately. The obvious objection, that this approach requires that a VCG always be recorded in addition to the routine 12-lead ECG, can be met by a technical artifice: It is possible to synthesize the VCG from the simultaneously recorded ECG leads [6]. The reconstructed VCG (rVCG) is a near-replica of the authentic (Frank) VCG and can be processed in the usual way by the VCG classification program.

We will show that combining the computer interpretations of the ECG and the VCG indeed improves diagnostic accuracy, and that equally good results are obtained when the rVCG replaces the VCG. In view of these results, we will discuss which conditions need to be satisfied in order to have a combination of observers perform better than each observer separately.

Material and methods

Database

For testing purposes, the diagnostic database that was collected in the CSE project [1,7] was used. This database consists of 1,220 ECG and VCG recordings. In each case, all leads of the ECG and VCG were recorded simultaneously at a sampling rate of 500 Hz during 8 or 10 s. All cases have been validated by ECG-independent clinical evidence, such as echocardiography, enzyme levels, etc. [8]. The following eight main categories were distinguished: Normal (N=382), left ventricular hypertrophy (LVH; N=183), right ventricular hypertrophy (RVH; N=55), biventricular hypertrophy (BVH; N=53), anterior infarction (AMI; N=170), inferior infarction (IMI; N=273), combined infarction (N=73), and infarction with manifest hypertrophy (N=31). Major conduction defects, such as complete right and left bundle-branch block, were excluded. Each case in the database was also read independently by nine cardiologists (ECGs read by eight, VCGs read by five of them). For every case, the cardiologists’ interpretations were combined. These ‘combined cardiologist’ results served as another reference set in the

present study. Both the 'clinical evidence' and the 'combined cardiologist' result is classified information that remains under lock and key at the CSE coordinating center. Thus, an independent database for testing ECG computer programs can be maintained.

Computer program

The MEANS program was used for our investigations. In its signal analysis part, one and the same algorithm is employed to process the 12-lead ECG (using three reconstructed orthogonal leads) or the VCG [4]. The classification parts of the ECG and VCG programs use a heuristic approach by means of decision-tree logic.

Reconstruction

Each of the three VCG leads, X, Y and Z, can be reconstructed through a linear combination of ECG leads, i.e., by multiplying each of the eight independent simultaneous ECG leads with an appropriate coefficient and adding the re-scaled leads. The reconstruction coefficients, computed using multivariate regression, are given in Table 1 [6].

Table 1. Reconstruction coefficients for synthesizing the VCG from the ECG.

	I	II	V1	V2	V3	V4	V5	V6
X	0.38	-0.07	-0.13	0.05	-0.01	0.14	0.06	0.54
Y	-0.07	0.93	0.06	-0.02	-0.05	0.06	-0.17	0.13
Z	0.11	-0.23	-0.43	-0.06	-0.14	-0.20	-0.11	0.31

Coding of diagnostic results

The statements produced by the ECG and VCG classification parts of MEANS were rendered into diagnostic codes according to the CSE coding scheme [8]. A code comprises a diagnostic category and a qualifier. The pathological categories are LVH, AMI, etc., corresponding to the diagnostic groups in the clinical database. When the program stated a major conduction defect (a category not present in the database) as a single statement, the case was mapped to a category 'other'. When the program cited none of the major pathological categories but only non-major abnormalities such as ST-T changes, left anterior or posterior fascicular block, etc., the CSE rules prescribe mapping to the 'normal' category. This category thus contains, in addition to true normals, also ECGs that are not normal in an electrocardiographic sense. To avoid misunderstanding, this category has been labelled 'no structural abnormality' (NSA). Further, one of three qualifiers had to be used: definite, probable, or possible.

Combination of diagnostic results

The same method that was used in the CSE project to merge results from different observers or different programs into a combined interpretation, has been applied in the present study to combine results from the ECG and the VCG programs, and the ECG and the rVCG programs. The qualifier in each diagnostic code is assigned points corresponding to the level of certainty: 'definite' 3 points, 'probable' 2 points, and 'possible' 1 point. This is done separately for each reader or each program. The combined result for a particular case is then determined by adding the qualifier points of corresponding categories over the contributing readers or programs, and dividing by their number. The resulting value, between 0 and 3, is then rounded. For instance, when in our study the ECG program would list: "probable (=2) LVH" and the VCG program: "possible (=1) LVH, probable (=2) AMI", the combined program result would be: "probable $((2+1)/2 \rightarrow 2)$ LVH, possible $((0+2)/2 \rightarrow 1)$ AMI".

Classification matrices

In the CSE coordinating center, our program results were compared with the 'clinical evidence' and with the 'combined cardiologist'. The CSE approach has been to score by case rather than by diagnostic category. Thus, each case contributes one single point to a classification matrix. If more than one diagnostic category is associated with a particular case, only the category with the highest degree of certainty is counted. If two or more categories have equal qualifiers at the highest level, the one point to be allotted is evenly divided over the appropriate cells of the classification matrix. Cases with BVH, combined infarction, or a combination of hypertrophy and infarction, are subject to different mapping schemes the details of which have been described previously [8]. Briefly, a case with BVH is counted as partially correct when it was classified as LVH or RVH, i.e., half of the point will be allotted to category BVH and the other half to category 'other'. Likewise, cases with combined infarction or with a combination of hypertrophy and infarction are counted as partially correct when one of the constituent categories was cited.

Results

The results of all interpretations by MEANS, i.e., for the ECG, VCG, rVCG, combined ECG and VCG, and combined ECG and rVCG, were compared with both the 'clinical evidence' and the 'combined cardiologist'. For each comparison, a classification matrix for the main categories was computed. From these 8-by-8 matrices, 3-by-3 matrices were derived for the categories 'no structural abnormality' (NSA), 'hypertrophy' (HYPER, including left, right, and bi-ventricular hypertrophy), and 'infarction' (MI, including anterior, inferior, mixed infarction and infarction

with manifest hypertrophy). As an example, the 3-by-3 classification matrix of the ECG interpretation against the 'clinical evidence' is given in Table 2.

Table 2. Classification matrix of the ECG program result against the 'clinical evidence' (in %).

clinical evidence	computer				N
	NSA	HYPER	MI	OTHER	
NSA	97.1	0.3	2.6	0.0	382
HYPER	43.0	42.5	9.1	5.4	291
MI	26.5	2.5	67.2	3.7	547

NSA=no structural abnormality, HYPER=hypertrophy, MI=myocardial infarction, OTHER=other abnormality; N=number of cases.

The diagonal elements of the 3-by-3 classification matrix of each program against the 'clinical evidence' are given in Table 3. The specificity, i.e., the sensitivity for NSA, of the ECG interpretation (97.1%) is higher than that of any other: The combination of ECG and VCG (ECG+VCG) yields a specificity of 91.6% ($P < 0.001$, equivalence tested with Wilcoxon's signed-rank test [9]), and the combination of ECG and rVCG (ECG+rVCG) a specificity of 94.4% ($P = 0.003$). The positive predictive values for NSA of the ECG program and of the two combinations are 76.0%, 86.4%, and 83.7%, respectively. The sensitivities for HYPER and MI of both the ECG+VCG and ECG+rVCG interpretation are significantly higher than those of the ECG program ($P < 0.001$ in all cases).

Table 3. Agreement (%) between the program results and the 'clinical evidence'.

	ECG	VCG	rVCG	ECG+VCG	ECG+rVCG	N
NSA	97.1	86.6	94.0	91.6	94.4	382
HYPER	42.5	45.8	46.3	49.1	49.7	291
MI	67.2	76.0	70.2	77.9	74.4	547
total accuracy	69.8	70.2	70.5	74.2	73.6	

NSA=no structural abnormality, HYPER=hypertrophy, MI=myocardial infarction; N=number of cases, based on 'clinical evidence'.

The 'combined cardiologist' as the reference appears in Table 4. The comparisons show the same pattern as those with the 'clinical evidence': the specificities of the ECG+VCG and ECG+rVCG interpretations drop slightly with respect to that of the ECG program, while the sensitivities for HYPHER and MI improve.

Table 4. Agreement (%) between the program results and the 'combined cardiologist'.

	ECG	VCG	rVCG	ECG+VCG	ECG+rVCG	N*
NSA	96.8	84.8	91.2	91.0	93.1	503
HYPHER	63.1	66.3	65.8	72.5	72.5	203.5
MI	79.7	89.8	83.7	92.2	88.0	481.5
total accuracy	80.3	78.1	79.0	84.1	83.3	

NSA=no structural abnormality, HYPHER=hypertrophy, MI=myocardial infarction;
N=number of cases, based on the 'combined cardiologist' result.

*32 cases were classified as 'other' by the 'combined cardiologist' and have not been considered here.

Total accuracies were computed from the 8-by-8 classification matrices of all main categories, taking either the 'clinical evidence' or the 'combined cardiologist' as the reference (Tables 3 and 4). In both cases, the total accuracies of the combined interpretations proved to be significantly higher than those of the individual interpretations ($P < 0.001$ in all cases). These total accuracies have been entered in the scatter plot of Figure 1, together with those of the individual cardiologists from whom the 'combined cardiologist' was derived, and of the other interpretation programs which participated in the CSE study [7].

Total accuracy depends on the composition of the database. In the CSE database, about 30% of the cases belongs to category NSA according to 'clinical evidence'. If the composition of the database would be shifted to contain more and more NSA cases, a point would finally be reached where the total accuracy of the ECG interpretation would exceed that of any of the combined interpretations, as the ECG program shows highest specificity. We determined the total accuracies for different percentages of NSA cases; the numbers of cases in the other categories were adjusted in proportion to the initial numbers in the CSE database. If the number of cases in the database belonging to category NSA stays under 62% (71%), the total accuracy of the ECG+VCG (ECG+rVCG) interpretation remains larger than that of the ECG interpretation.

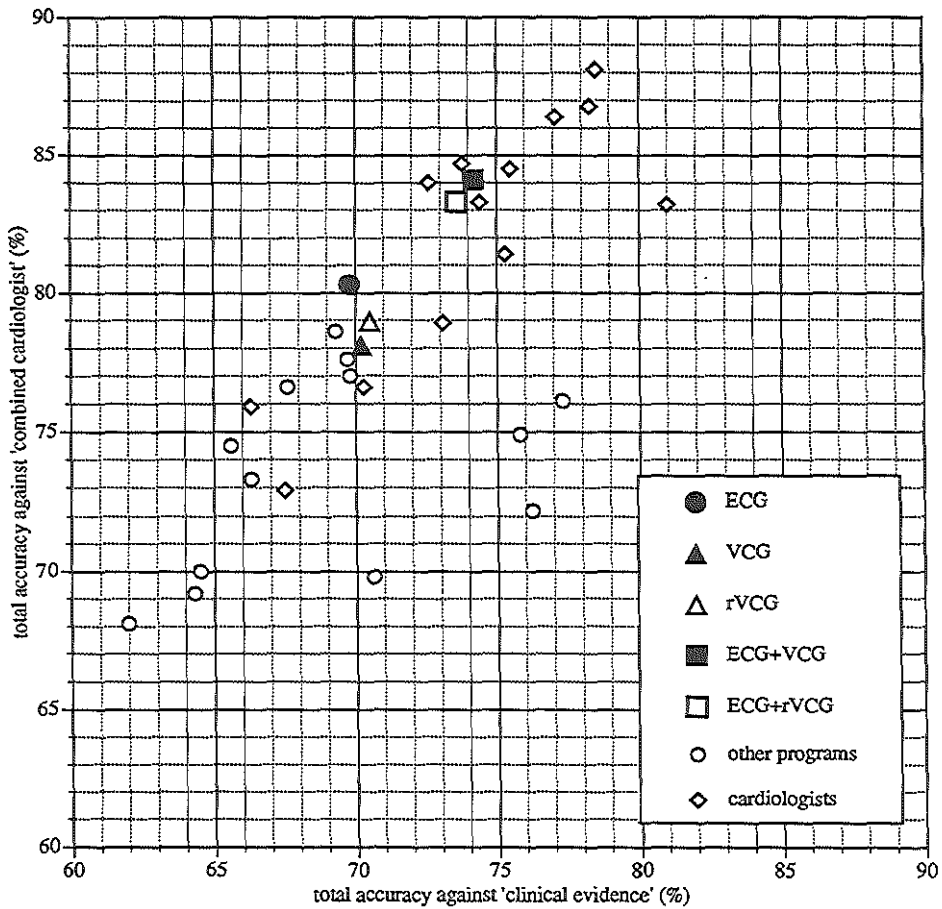


Figure 1. Total accuracies of the individual (indicated by ECG, VCG, and rVCG) and the combined (ECG+VCG and ECG+rVCG) MEANS interpretation programs. Also, the total accuracies of the other programs and of the cardiologists participating in the CSE study have been plotted. From these cardiologists the 'combined cardiologist' was derived. All interpretation results are compared with the 'clinical evidence' (horizontal) and the 'combined cardiologist' (vertical).

Discussion

“Two heads are better than one”, and apparently this saying holds for our ECG and VCG (or rVCG) computer interpretations, for at least the total accuracies (Figure 1). The sensitivities for hypertrophy and infarction are also better, but the specificity is in between (Tables 3 and 4).

Under what conditions, then, do two observers (cardiologists or programs) perform better than each one separately? Suppose that there are only two mutually exclusive categories: X and non-X, i.e., either X is present (‘definite’) or non-X. It can easily be shown (see Appendix) that the sensitivity and specificity of the interpretations of two observers when combined under the CSE rules is the average of their individual sensitivities and specificities. This, however, is not the case when we combine our two computer programs. For instance, the sensitivities for hypertrophy of the interpretation of the ECG, of the VCG, and of the ECG and VCG combined are 42.5%, 45.8%, and 49.1%, respectively (Table 3). The reason is, in the first place, that not one qualifier (‘definite’) but three qualifiers are used (‘definite’, ‘probable’, ‘possible’). Thus, a case may be graded as “definite X” by one observer and as “possible X, probable non-X” by the other. Assuming that X is the correct diagnosis, the first observer classified correctly, and the second incorrectly because the CSE mapping procedure only retains the highest ranking category. The combined result will then be “probable $(=(3+1)/2 \rightarrow 2)$ X, possible $(=(0+2)/2 \rightarrow 1)$ non-X” and one full point will be allocated to X in the classification matrix. In the first, simple (binary) model, the case would have been assigned the same qualifier for X by the first and non-X by the second observer, and the one point would have been split in half between the equal-ranking X and non-X. In the more expanded model, the grading and decision procedures can salvage a full point to the correct diagnosis. This happens when the correct interpretation is stated with confidence and the incorrect one with hesitance.

There is a second reason why the sensitivity or specificity of the combined interpretation may be better than that of each interpretation separately. In reality there are not two but more diagnostic categories, which need not be mutually exclusive. For example, the classification “probable hypertrophy, definite infarction” is perfectly legal. The qualifier that both observers formerly attached to category non-X, may now be assigned to one category, say, Y, by the first observer, and to another, say, Z, by the second: the statement “probable X, possible Y” by the first observer and “possible X, probable Z” by the second would combine to “probable X, possible Y, possible Z”, and a full point would be assigned to X in the classification matrix. Both observers may even be wrong whereas the combination is partly correct, e.g., “possible X, probable Y” by the first and “possible X, probable Z” by the second observer would yield “possible X, possible Y, possible Z” for the combination, thus allotting 1/3 point to X.

When more than two interpretations are combined, as was done in the CSE study, the combinatorics may become quite complex. A discussion of this topic is outside the scope of this article.

In the present study, we integrated two classification programs at the level of their outputs, i.e., their diagnostic statements. This approach is simple, but it is also a rather crude and indirect way of combining diagnostic classification knowledge. A more direct combination procedure would be to integrate into one program the qualities of the ECG and VCG approaches. Such a selective combination of knowledge requires a precise understanding of the strong and weak points in the classification logic and will be an issue for further research.

The results of the reconstructed VCG are in between those of the ECG and the VCG (Tables 3 and 4); the total accuracies of ECG, VCG, and rVCG are very similar. In a previous study [6], cardiological interpretations of a series of original VCGs and of reconstructed VCGs, were proven to be comparable. This suggests that rVCG and VCG are equivalent in information content. Since the rVCG is nothing more than a mathematical conversion of the ECG, this implies that ECG and VCG carry the same diagnostic information. The equivalence of information in the ECG and VCG was also pointed out in another study [10], where statistical classifiers for the ECG and the VCG, determined with the same technique, proved to have similar performance.

As the rVCG contains only the electrical information enclosed in the ECG, it is remarkable that processing the same information, first in the form of the ECG, then, after its mathematical conversion, in the form of the VCG, should yield results that are able to improve on each other when combined. This suggests that representing and processing the signals in VCG form utilizes information that is neglected in ECG interpretation: presumably information on phase relationships between the ECG signals. Conversely, the ECG carries proximity information that is probably lost in the VCG approach. The practical implication of this all is that the performance of an ECG computer program can be improved by applying VCG criteria to the ECG itself.

The conclusions from our study are as follows: (1) A 'combined program', produced by merging the interpretations of our ECG and VCG computer programs, performs better than each program separately (using the CSE database as a test set). (2) Simultaneously recorded ECG leads enable the reconstruction of the VCG. The results of the interpretation of this reconstructed VCG are comparable to those of the authentic VCG. (3) The combination of the interpretations of the ECG and the reconstructed VCG has a performance similar to that of the combination of ECG and authentic VCG.

Acknowledgments

The CSE project was supported by the European Commission within the frame of its Medical and Public Health Research Programmes, and by various funding agencies in member states of the European Community. We are grateful to R. Reniers (Catholic University Leuven, Belgium) for technical and programming help.

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Appendix

Let us assume that two observers (referees or programs) classify a group of subjects into one of two disease categories, D and \bar{D} . $P(D)$ is the a priori probability that a subject has disease D , $P(\bar{D}) = 1 - P(D)$ is the probability that he has not. The observers classify a subject as having the disease (X) or not having the disease (\bar{X}). The sensitivity of the first observer, SE_1 , is the probability that this observer will classify a subject with the disease positively: $SE_1 = P(X_1 | D)$. The sensitivity of the second observer is $SE_2 = P(X_2 | D)$. The sensitivity of a 'combined observer' is $SE_c = (P(X_1 X_2 | D) + (P(X_1 \bar{X}_2 | D) + P(\bar{X}_1 X_2 | D)))/2$, i.e., the sum of the probability that both observers will classify a subject positively and the average probability that one of both observers will do so, given the disease. The latter term is the result of the CSE combination procedure: If two (or more) categories with equal qualifiers at the highest level are given, the one point to be allocated in the classification matrix is evenly divided over the corresponding cells. Since $P(X_1 | D) = P(X_1 X_2 | D) + P(X_1 \bar{X}_2 | D)$ and $P(X_2 | D) = P(X_1 X_2 | D) + P(\bar{X}_1 X_2 | D)$, it follows that $SE_c = (P(X_1 | D) + P(X_2 | D))/2 = (SE_1 + SE_2)/2$. Thus, the sensitivity of the 'combined observer' is the average of the sensitivities of the separate observers. Note that this result holds whether the observers' interpretations are statistically independent or not. Similarly, the specificity of the 'combined observer' is the average of the specificities of both observers.

CHAPTER 9

Intrinsic Variability of ECGs Assessed by Computer Interpretation

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Submitted for publication

Abstract

Variability in the electrocardiogram (ECG) can be due to 'extrinsic' sources, such as powerline interference, baseline wander or electromyographic noise, or can be caused by 'intrinsic' factors, such as changes in the volume conductor or in the heart itself. Computer programs for the interpretation of the ECG base their diagnostic classification on one set of measurements which characterize the ECG. To reduce the influence of noise, the set of measurements can be derived from a representative P-QRS-T complex or it can be computed by taking the median from the measurements for each complex in the recording. However, these methods may fail to do justice to the intrinsic variability that may be present in the ECG. An alternative method is proposed: Derive a set of measurements from each complex in the recording and classify all complexes separately. The classifications of all complexes are then combined in one final classification.

This procedure has been evaluated on a validated database (N=1,220) using our own ECG computer program. The total accuracy against the 'clinical evidence' increased from 69.8% for the interpretations of the averaged complexes to 71.2% for the 'combined' interpretations of the singular complexes ($P < 0.001$). The effect of beat-to-beat variation on the measurements is demonstrated and the influence of extrinsic and intrinsic variability on the classifications is assessed.

Key words: ECG classification, coherent averaging, stability

Introduction

Beat-to-beat variability in the electrocardiogram (ECG) can arise from different sources. The ECG may show noise components from 'extrinsic' sources, such as powerline interference, electromyographic noise, baseline wander, and noise from the signal acquisition device. Variability may also be induced by changes in the volume conductor (the thorax) due to respiration or movement of the heart and, finally, by changes in the heart itself, e.g., in the electrical conduction pattern. The last two types of variability will be termed 'intrinsic' variability.

To reduce the influence of noise, ECG computer programs apply one of two methods. One method is to determine which P-QRS-T complex in the recording shows least distortion, and derive measurements from that complex [1,2]. A generalization of this method is to determine measurement values for every complex in the recording and subsequently take the median value of measurements from complexes which are morphologically of the same type [3-5]. The other method is to compute the coherent average or take the median of similar complexes and to determine the measurement values from this averaged or median complex [6-11]. Both methods result in only one set of measurements which is the basis for diagnostic classification.

However, these methods may fail to do justice to the intrinsic variability in the ECG. When only one complex is considered, any intrinsic variability is neglected by definition. When measurements or complexes are averaged, the intrinsic variability is also averaged. Therefore, we propose an alternative method which allows to take into account the intrinsic variability in the ECG: For each complex in the recording, a set of measurements is derived and a diagnostic classification is made. The classifications of all complexes are then combined into one final classification using a combination rule. As a consequence of this procedure, the complexes from which measurements are derived are likely to contain more ('extrinsic') noise than the representative complex used in the other methods. Therefore, the stability of an ECG computer program, i.e., the influence of noise on measurements and classifications, is also of importance.

Using our own ECG computer program MEANS (Modular ECG Analysis System) [7,12], this alternative procedure has been evaluated. The stability of the program was assessed by comparing the measurements and classifications of the separate complexes in an ECG recording with those of the representative average complex.

Material and methods

Database

The database that was used in our experiments was collected in the project 'Common Standards for Quantitative Electrocardiography' (CSE) [13,15], an international cooperative study for standardization and evaluation of ECG computer programs. It contains 1,220 ECGs and VCGs, of which we used only the ECGs. The ECGs consist of eight simultaneously recorded leads sampled at a rate of 500 Hz during 8 or 10 s. Each case was validated by ECG-independent clinical evidence [14]. The diagnostic classification of individual cases is only known to the CSE coordinating center, but the overall composition of the database has been made public [15]: left ventricular hypertrophy (LVH; N=183), right ventricular hypertrophy (RVH; N=55), biventricular hypertrophy (BVH; N=53), anterior myocardial infarction (AMI; N=170), inferior myocardial infarction (IMI; N=273), combined infarction (MIX; N=73), infarction with manifest hypertrophy (VH+MI; N=31), and normal (NOR; N=382). The NOR group includes 'ambulatory' normals (N=286) and 'catheterized' normals (N=96).

ECG computer program

MEANS was used for the analysis and interpretation of the ECGs. It contains algorithms to detect spikes, to correct for baseline wander, and to suppress mains interference. Beats that do not belong to the dominant rhythm (i.e., extrasystoles) are removed as are drastically different beats such as in intermittent complete right bundle-branch block. Noise reduction is achieved by coherent averaging of the dominant QRS complexes. The resulting averaged P-QRS-T complex is used in subsequent steps of the analysis, i.e., wave boundary recognition and measurement extraction. Finally, a diagnostic classification is generated. The classification part of MEANS is based on heuristic knowledge, structured by means of decision-tree logic.

ECG processing

In this study, each ECG was processed twice. First, MEANS operated under usual conditions, producing measurements and a classification based on the averaged complex. Subsequently, measurements and a classification were determined for every singular complex which had been used in the averaging procedure. All measurements and classifications were stored in a database for further processing.

Measurements

From each averaged and from each singular complex, an extensive series of measurements was taken. We here will consider the amplitudes of the Q, R, and S waves, as well as the durations of the QRS complex, PQ interval, and QT interval. All amplitude measurements are

lead dependent; durations are measured for all leads simultaneously. The noise content in each lead was estimated by the root-mean-square (rms) of amplitude values in an interval of 40 ms, preceding the QRS complex. This procedure has previously been used in the CSE project [16].

Coding of diagnostic results

The statements produced by the ECG classification part of MEANS were mapped onto diagnostic codes following the CSE coding scheme [14]. A code comprises a diagnostic category and a qualifier. Diagnostic categories are NOR, LVH, RVH, BVH, AMI, IMI, MIX, VH+MI, and 'other'. A case is mapped to the 'other' category when the program states a major conduction defect, e.g., complete left bundle-branch block (a condition known not to be present in the database), as a single statement. One of three qualifiers can be used: definite, probable, or possible.

Combination of diagnostic results from singular complexes

The same method that was used in the CSE project to combine diagnostic results from different programs or different observers, was applied in the present study to combine the interpretation results of singular complexes of the same recording. The qualifier of each diagnostic code was assigned points corresponding to the level of certainty: 'definite' 3 points, 'probable' 2 points, and 'possible' 1 point. This was done separately for each singular complex. The combined result for a particular recording was then determined by adding the qualifier points of corresponding categories over the contributing complexes, and dividing by their number. The resulting value, a score between 0 and 3, is then rounded. For instance, when a recording would contain five complexes of which two would have been cited by the program as "possible (=1) LVH, probable (=2) AMI" and three as "definite (=3) LVH", the combined result would be "probable $((2 \times 1 + 3 \times 3) / 5 \rightarrow 2)$ LVH, possible $((2 \times 2 + 3 \times 0) / 5 \rightarrow 1)$ AMI".

Classification matrices

Program results for the averaged complexes and for the singular complexes were compared with each other and with the 'clinical evidence'. Comparisons with the 'clinical evidence' took place in the CSE coordinating center. The mapping procedure that has been applied, is the same as used in the CSE project [15]. Each case contributes one point in the classification matrix. If more than one diagnostic category is associated with a particular case, only the category with the highest degree of certainty is retained. If two or more categories have equal qualifiers at the highest level, the one point to be allotted is evenly divided over the appropriate cells of the classification matrix. Cases with BVH, combined infarction, or a combination of hypertrophy and infarction, are subject to additional testing of which the details have been described previously [14]. Briefly, a case with BVH is counted as partially correct when it was classified

as LVH or RVH. Likewise, cases with combined infarction or with a combination of hypertrophy and infarction are counted partially correct when one of the constituent categories was cited.

Assessment of extrinsic and intrinsic variability

We tried to assess the separate influence of extrinsic variability on the computer's interpretations. For this, we assume that the disagreement in classification between the averaged and the singular complexes is mainly the result of extrinsic noise. An equivalent disagreement is then to be expected when we compare the original averaged complexes with the averaged complexes after contamination with extrinsic noise amounting to that present in the singular complexes. To simulate the extrinsic noise, Gaussian noise with different rms values was added to the averaged complexes. The classifications of the averaged complexes contaminated with additive noise were then compared with those of the original averaged complexes.

Results

The 1,220 ECG recordings in the database contained 9,833 singular complexes which were used in the computation of the averaged complexes. Thus, in total 11,053 (1,220+9,833) complexes were analyzed. In the following, the 1,220 cases for which an averaged complex was computed will be referred to as 'averaged' cases, and the 9,833 as 'singular' cases. In Figure 1, the (smoothed) distributions of the rms noise values are given for singular and averaged complexes. Since the distributions for the various extremity leads were comparable, they have been lumped; the same applies to the precordial leads. The medians of the rms noise values of the averaged and of the singular complexes are 3.6 and 8.4 μV , respectively, for the extremity leads and 2.8 and 5.6 μV , respectively, for the precordial leads.

When wave measurements of averaged and singular complexes are compared, one of the intricacies is that a wave which is detected in the averaged complex may not be detected in a singular complex, or vice versa. This phenomenon will be called detection instability. For instance, a Q wave in the averaged complex may be just large enough to fulfill the minimum wave detection requirements, whereas this Q wave is not detected in some of the singular complexes: the Q wave is 'deleted'. However, detection instability may also affect the labelling of waves, due to the presence or absence of a small initial R wave. If it is detected in a singular case while the averaged case shows a QR pattern, an R wave is 'created' and the waves labelled as Q and R in the averaged complex will pass as S and R' waves, respectively, in the individual complex. Conversely, deletion of an initial R relabels the subsequent S into a Q (or QS).

Figure 2 shows the number of singular complexes per lead in which waves were relabelled when compared with the average complex. Figure 3 gives the number of Q (or QS), R and S waves that were created and deleted without relabelling the other waves.

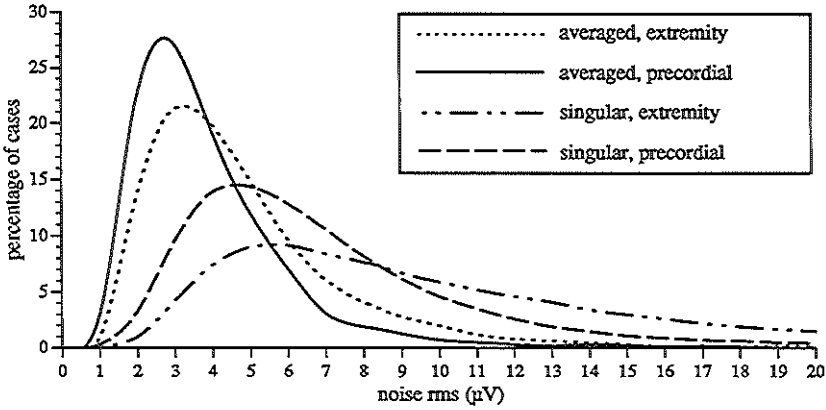


Figure 1. Smoothed distribution of the rms noise values for the averaged complexes and the singular complexes in the extremity leads and in the precordial leads.

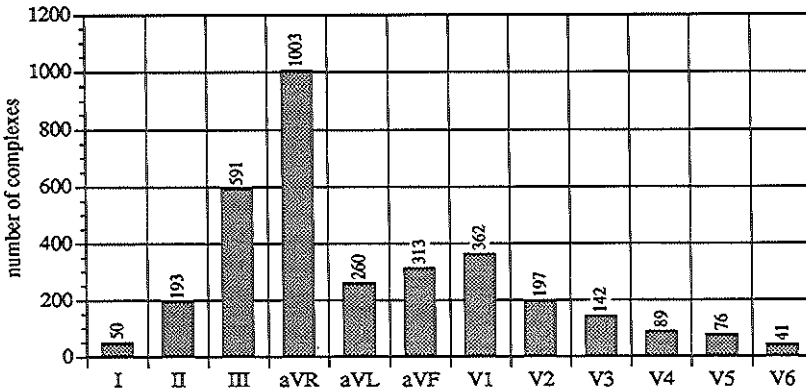


Figure 2. Number of singular complexes (out of 9,833) in which detection instability resulted in wave relabelling, taking the labelling of the averaged complex as the reference.

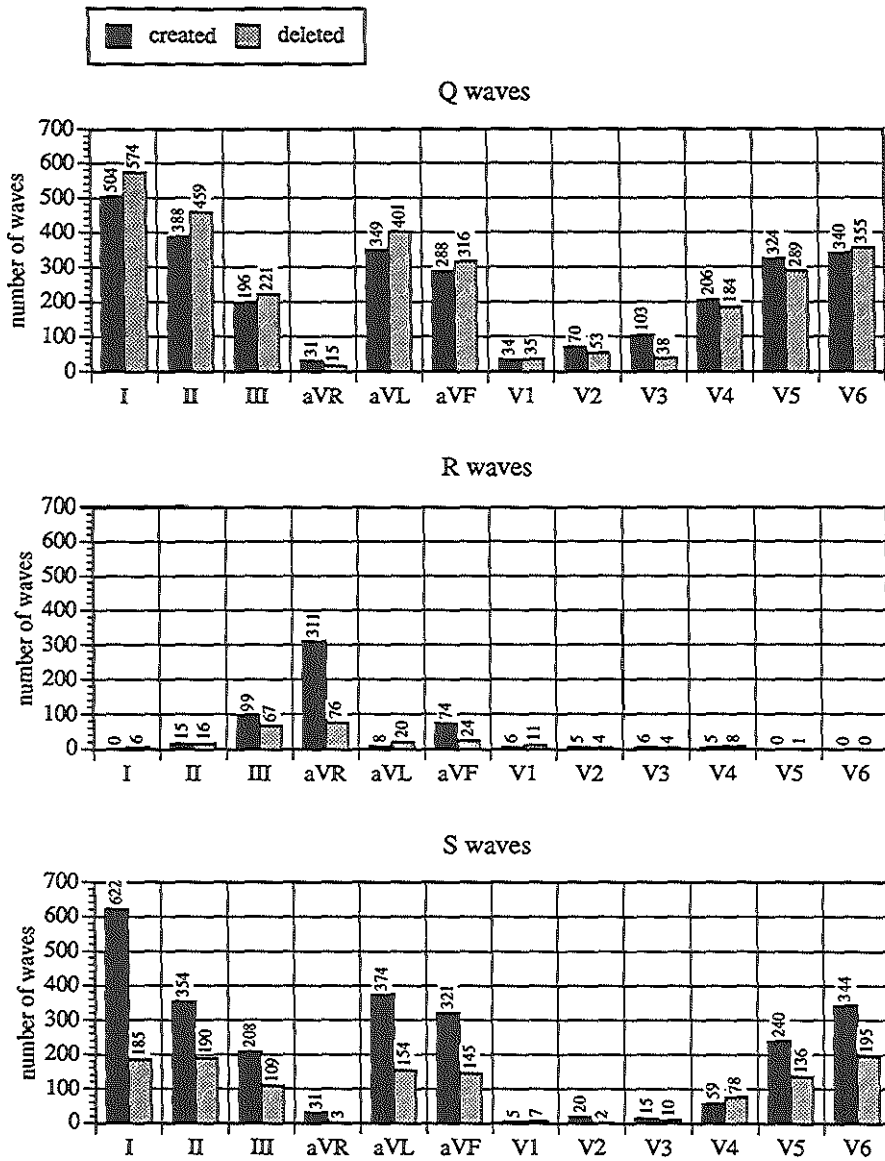


Figure 3. Number of waves created or deleted in the singular complexes, taking the absence or presence of a wave in the averaged complex as the reference. Singular complexes with relabelled waves have not been considered.

Table 1 shows the median and the 10 and 90 percentiles of the differences between each singular and its corresponding averaged complex for the amplitude measurements of the Q, R, and S waves. Differences were computed if a wave had been detected in at least one of the two complexes to be compared. The percentiles were derived from the differences of all leads. For QRS duration the median of the differences between singular and averaged cases was 0 ms (10 percentile -6 ms, 90 percentile 10 ms), for PQ interval 0 ms (-6 ms, 6 ms), and for QT interval 2 ms (-8 ms, 22 ms).

Table 1. Medians of the amplitude differences (in μV) between the singular and the averaged complexes for the Q, R, and S waves of all leads. A difference, i.e., the wave amplitude of a singular complex minus that of the averaged complex, was computed if a wave was present in at least one of the complexes. In parentheses are the 10 and 90 percentiles of the differences.

	no wave relabelling			wave relabelling
	wave in both complexes	wave created	wave deleted	wave in at least one complex
Q	-4 (-31/17)	-44 (-78/-28)	39 (28/63)	47 (-974/876)
R	4 (-38/50)	66 (52/106)	-67 (-113/-52)	-5 (-316/186)
S	-5 (-51/38)	-66 (-109/-52)	64 (52/113)	-53 (-875/953)

Classification matrices of the interpretations of singular complexes versus corresponding averaged complexes are shown in Table 2 for each of three groups: 'normal', 'hypertrophy' (including LVH, RVH, and BVH), and 'infarction' (including AMI, IMI, MIX, and VH+MI). When the program stated two categories belonging to the same group, the highest qualifier was retained. For example, the statement "definite AMI, possible IMP" turns into "definite infarction". Since the computer program does not generate statements that are coded as "possible normal", one row and one column in the classification matrix for 'normal' is empty. The figures in the extreme off-diagonal cells are smallest in the case of hypertrophy, which is therefore the stablest classification, no doubt related to the fact that the R wave is the stablest feature in waveform recognition.

Table 2. Classification matrices (in %) of singular complexes against averaged complexes for each of three categories.

<i>normal</i>	singular complexes				N
	absent	possible	probable	definite	
averaged					
absent	96.1		3.5	0.4	4740
possible					
probable	8.3		86.2	5.5	2605
definite	2.0		14.5	83.5	2488

<i>hypertrophy</i>	singular complexes				N
	absent	possible	probable	definite	
averaged					
absent	98.6	1.1	0.3	0.0	8116
possible	11.9	73.1	13.9	1.1	360
probable	3.1	14.0	66.6	16.4	293
definite	1.6	0.2	3.5	94.7	1064

<i>infarction</i>	singular complexes				N
	absent	possible	probable	definite	
averaged					
absent	95.4	1.8	1.3	1.5	5829
possible	17.8	66.3	11.0	4.9	472
probable	11.0	3.4	67.4	18.2	610
definite	3.1	0.7	3.4	92.8	2922

Table 3 gives the overall classification matrix which was derived using the CSE mapping scheme. The agreement between the classifications of the averaged complexes and those of the singular complexes was 93.3%. This figure was derived from the 8-by-8 classification matrix of all main categories.

Table 3. Overall classification matrix (in %) of singular complexes against averaged complexes.

averaged	singular complexes				N
	NOR	HYP	INF	OTH	
NOR	94.8	1.1	3.1	1.0	5093
HYP	2.5	93.2	3.0	1.3	1218
INF	4.3	0.8	94.1	0.8	3461
OTH	9.8	3.3	29.5	57.4	61

NOR=normal; HYP=hypertrophy; INF=infarction; OTH=other abnormalities.

It is interesting to know how the classifications deviating from that of the averaged complex, are distributed over the ECG recordings. We only consider differences of at least two qualifier points between the classifications of the singular and averaged complex for corresponding categories. For instance, in the statements “probable (=2) LVH, possible (=1) AMI” for one complex and “definite (=3) AMI” for the other, there is a difference of two qualifier points both for LVH and for AMI. For each ECG recording, the number of singular complexes that deviate in the above sense has been counted; in 333 ECGs one or more two-point deviations occurred. Figure 4 shows a histogram of the number of deviating complexes per ECG. It appears that discordant classifications often occur only once in a particular ECG.

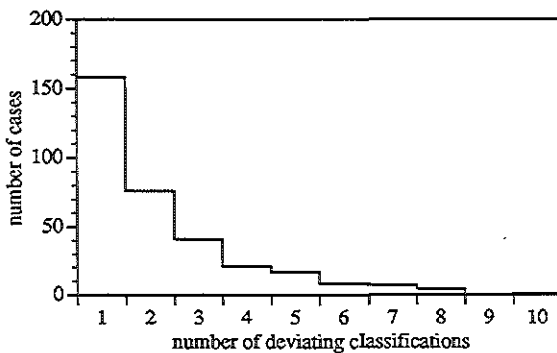


Figure 4. Distribution of the number of deviating classifications per ECG recording, comparing the classifications of singular and averaged complexes. The classification of a singular complex deviates from the classification of the averaged complex if the qualifiers for any of the main categories differ at least two points.

The classifications of the averaged complexes contaminated with additional noise were compared with the classifications of the original averaged complexes. In Figure 5, the percentage agreement is depicted for noise values of 5, 10, 15, 25, and 35 μV rms.

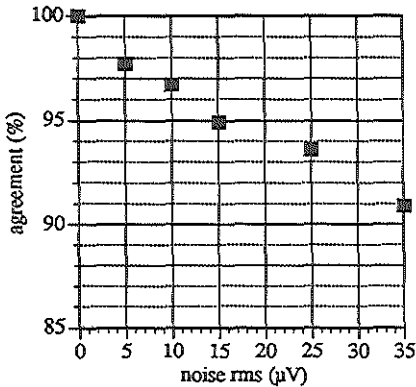


Figure 5. Agreement between the classifications of the averaged complexes contaminated with random noise of different rms values and the classifications of the averaged complexes without contaminating noise ($N=1,220$).

We submitted the classifications based on the averaged complex and the 'combined', i.e., weighted, classifications based on the singular complexes to the CSE coordinating center for comparison with the 'clinical evidence'. Classification matrices for the eight main categories were computed. From these 8-by-8 matrices, 3-by-3 matrices were derived for the categories 'normal', 'hypertrophy', and 'infarction'. The results are shown in Table 4. The specificity and the sensitivities of the combined singular interpretations are slightly higher than for the averaged complex. The total accuracy, derived from the 8-by-8 classification matrices, increased from 69.8% to 71.2% ($P < 0.001$, equivalence tested with Wilcoxon's signed-rank test [17]).

Discussion

Beat-to-beat variation

In several studies [11,18,19], beat-to-beat variation has been demonstrated in the form of variability of measurements in different complexes of the same recording. The recordings that were used in these studies were selected because of their low noise content, so that variation due to extrinsic sources was minimized. The distinction between intrinsic and extrinsic variability is elusive, however, because no reference signal is available. Therefore, in the present study no attempt was made to reduce either one source of variation a priori.

The results of this study demonstrate that large beat-to-beat variation can occur when detection instability results in the relabelling of waves. For instance, Table 1 shows that in

Table 4. Classification matrices of the interpretations of the averaged complexes (upper part) and of the 'combined' interpretations of the singular complexes (lower part) against the 'clinical evidence' for the CSE database (N=1,220).

clinical evidence	averaged complexes				N
	NOR	HYP	INF	OTH	
NOR	97.1	0.3	2.6	0.0	382
HYP	43.0	42.5	9.1	5.4	291
INF	26.5	2.5	67.2	3.7	547

clinical evidence	'combined' singular complexes				N
	NOR	HYP	INF	OTH	
NOR	97.4	0.3	2.4	0.0	382
HYP	42.1	44.8	9.1	4.0	291
INF	24.6	2.7	69.0	3.7	547

NOR=normal; HYP=hypertrophy; INF=infarction; OTH=other abnormalities.

twenty percent of the cases the amplitudes for a created or deleted Q wave exceeds $-974 \mu\text{V}$ or $+876 \mu\text{V}$, respectively, which means that these waves may have a huge impact on diagnosis. Detection instability can also create and delete waves without relabelling the other waves. According to Table 1, the median values and the dispersions of their amplitudes are rather small. When no wave relabelling occurs and both waves are present, the medians of the wave differences are close to zero, while the dispersions are comparable to those of created or deleted waves.

Figure 2 indicates that leads III, aVR, aVF, and V1 are most liable to wave relabelling. The high number of relabellings in aVR corresponds to the number of Q waves created or deleted in the oppositely oriented inferolateral and lateral leads I, II, aVL, V4, V5, and V6 (Figure 3). The latter usually have a main positive deflection: the presence or absence of a small initial negativity does not affect wave labelling. The corresponding manifestation of a small initial R in the mainly negative aVR, however, will relabel a Q or QS into an S, and vice versa. The R

waves in aVR, referred to in Figure 3, are terminal since they occur without relabelling. They correspond to S waves in the inferolateral and lateral leads where terminal negativity often is marginal. Figure 3 shows that the R wave is a very stable feature in waveform recognition, except for aVR which plays a minor or no role in diagnostic classification anyway. In V1, as in aVR, the label of the usually prominently negative deflection depends on an initial R, which however in V1 is more consistent in its manifestation than in aVR. In lead III small variations of the electrical axis, which tends to be perpendicular to this lead, are able to cause the creation or deletion of any wave component, often with relabelling. To a lesser degree this applies also to lead aVF.

Averaging complexes, measurements, or classifications

To reduce noise from extrinsic sources, ECG signals are ‘filtered’, either by averaging complexes or measurements, or by selecting one single (low-noise) complex. The method proposed in this paper refrains from filtering the signal but, instead, ‘filters’ diagnostic statements of singular complexes by weighting the certainty qualifiers of each category. Thus, variability, both extrinsic and intrinsic, will be taken into account in the classification process. (It should be noted that MEANS also performs signal conditioning other than coherent averaging, such as removal of mains interference, baseline correction, etc.) Since noise from extrinsic sources is less reduced, measurement errors are likely to occur more often in singular complexes than in averaged ones, and classification errors may occur more frequently. This is no real drawback, however, because the weighting procedure will remove the erroneous category or reduce the qualifier to ‘possible’. Another way to reduce the effect of measurement errors not pursued here is to apply consistency checks on measurements values. When an outlier is detected, the corresponding complex could be rejected from further processing.

The approach may have two other advantages. First, the dispersion in the diagnostic statements pertaining to the singular complexes, can be communicated to the user of the program, providing information about the stability of the ‘aggregate’ classification, and suggesting alternative classifications. Such information may be expected to be more pertinent than information about measurement variability, as the relationship between measurements and classification will remain obscure to the average user. Second, large discrepancies between classifications of singular complexes may be caused by a high degree of intrinsic variability of the ECG, but may also be the result of flaws in the classification logic. For instance, when adjacent decision regions in the classification space for the same category differ two or three qualifier ‘steps’ (e.g., “definite LVH” and “possible LVH”), small differences in measurements may result in large differences in diagnostic classification. Thus, the approach offers an entry to detect weak parts in the classification algorithms.

Stability testing

The method described in this paper can also be used to test the stability of an ECG computer program. Stability testing procedures expand a test set of ECGs by generating 'new' ECGs; they explore the program's behavior in an enlarged area of the feature space.

In one approach, a set of low-noise recordings was selected [20-23]. Noise of various types (e.g., high-frequency noise, mains interference, baseline sways) and of varying amplitudes is generated and superimposed on the original ECG. Differences are then determined between the ECGs contaminated with noise and the original ECGs. In another approach, a comparison is made between ECGs that are expected to differ in their natural noise content; no noise is added. For this purpose, several ECG recordings of the same patient have been analyzed [24], the same analog recordings have been repeatedly digitized [25], or alternate samples have been processed from ECGs that had been sampled at twice the sampling rate [26,27].

Our study differs from previous approaches in at least one of the following aspects: the size of the database, the assessment of the effect of disturbances, and the type of disturbance.

Size of the database. The original test set contained 1,220 cases, and was expanded to 11,055 cases. This database is (much) larger than used in other studies; whether it is large enough, remains an open question.

Assessment of the influence of noise. The relationship between measurements and classifications is generally obscure. Large differences in diagnosis may be brought about by small differences in measurement values and, conversely, large differences in measurements need not be of diagnostic importance. Therefore, the stability of an ECG computer program should also be evaluated by assessing the influence of disturbances on the program's diagnostic classifications.

Type of disturbances. Our procedure makes use of the disturbances that are naturally present in the original ECGs. The precise nature of the noise, however, is not considered and the influence of a specific type of noise on program performance is difficult to assess. This need not be a problem, provided that the test set is large enough to represent all kinds of disturbances that can be expected in reality. The advantage of the approach is that the program's stability under 'real' operating conditions is tested.

Extrinsic and intrinsic variability

Figure 5 shows that the agreement between the classifications of the averaged complexes contaminated with noise and the original averaged complexes gradually decreases when increasing amounts of noise are added. Noise levels beyond 35 μV rms may be expected to further reduce the agreement rate; eventually so much noise might be added to the averaged complexes that 'random' interpretations would result.

The average difference in noise level between averaged complexes and singular complexes is in the order of 5 μV rms (Figure 1). If an amount of 5-10 μV rms is added to the averaged

complexes, agreement with the original averaged complexes drops to about 97% (Figure 5), whereas the agreement between singular complexes and averaged complexes was 93.3%. The latter level of agreement is apparently only reached after addition of as much as 25 μ V of noise to the averaged complex. This finding lead us to think it unlikely that the observed differences in classification between averaged and singular complexes are fully attributable to the influence of extrinsic noise: intrinsic variability also matters.

Diagnostic accuracy

When tested on a large validated database, the total accuracy of the combined classifications of the singular complexes proved to be higher than that of the classifications of the averaged complexes. One explanation of the good performance of the combined classifications is that any intrinsic variability is not averaged. But there may be other reasons as well. When an averaged complex is being analyzed, errors in the measurement part of the program can have large consequences for the interpretation. The same applies to singular complexes: errors here are even more likely because singular complexes, in general, are noisier than averaged complexes. The final combined interpretation, though, will be less affected because the weighting procedure will 'filter' the erroneous interpretation, provided that most singular complexes are correctly analyzed. A possible second reason for improvement might be that a small amount of jitter occurred in the reference points which are used to align the singular complexes, yielding an averaged complex that is no longer representative.

The main conclusions of our investigations are as follows: (1) Beat-to-beat variation in the measurements of different complexes is largest when detection instability results in wave relabelling; (2) Beat-to-beat variation in the diagnostic interpretations of different complexes is influenced both by extrinsic noise and intrinsic variability; (3) The performance of the 'combined' interpretations of singular complexes is better than that of the interpretation of the averaged complex; furthermore, the interpretation of singular complexes can provide the user with information about the program's stability and may be used to detect flaws in the classification logic.

Acknowledgments

We are grateful to Dr. J.L. Willems and R. Reniers in the CSE coordinating center (Catholic University Leuven, Belgium) for processing the MEANS results. The CSE project was supported by the European Commission within the frame of its Medical and Public Health Research Programmes, and by various funding agencies in the member states of the European Community.

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CHAPTER 10

Discussion

Three problem areas in computerized electrocardiography were distinguished in the introduction of this thesis: formalization of knowledge, observer variability, and evaluation. We will discuss our investigations in relation to these issues, and suggest directions for further research.

Formalization of knowledge

Our main contribution to the problem of knowledge formalization has been the construction of a specialized language, DTL (Decision Tree Language), and the development of an interpreter and a translator for that language. Using these tools, cardiologists can express their classification algorithms in a way that is familiar to them, and can easily verify whether their diagnostic intentions have been realized properly.

Still, the development of a heuristic ECG classifier remains a process of trial and error. First, a cardiologist will generally not be able to foresee all effects of the modifications or extensions that he proposes. These may often only become apparent at a later stage when the modified algorithms have been tested on a large database of ECGs. Second, and more fundamental, flawed parts of the decision trees may not be noticed because of the limited size of the test set. Two extensions of the DTL system can be envisaged to accommodate these problems. First, a closer integration of the DTL interpreter, the DTL translator, and the database could be realized. This should allow, for instance, the alternative execution of interpreted and compiled versions of DTL programs using (part of) the database. Thus, a cardiologist would be able to receive information about the overall effect of modifications almost instantly.

Information about weak parts in the classification logic might be provided by the stability analysis that was described in Chapter 9: the differences between interpretations of singular complexes of the same recording may provide a handle for error detection. Such 'sensitivity analysis' is an area of further research. For example, the effect of controlled disturbances of one or more measurement values may be studied, or the effect of systematically modifying threshold values in the decision nodes. The DTL system should be extended to enable the logging, analysis, and comparison of the classification paths, i.e., the decision nodes that were encountered in classifying particular cases.

Observer variability

Cardiologists may show considerable variability in their diagnostic interpretations. Even greater variability may be expected to exist in the classificatory knowledge which is the basis for their interpretations. We investigated a 'direct' approach and an 'indirect' approach to deal with these variabilities. In the direct approach, a procedure is applied which aims at resolving

the differences between cardiologists. In the indirect approach, no consensus is sought, but instead the cardiologists' outputs are 'aggregated' by some sort of combination rule.

The Delphi procedure, described in Chapter 6, is an example of the direct approach. We investigated whether classification differences between multiple cardiologists could be resolved, and whether a consensus could be reached on their reasons for disagreeing with the computer classifications. The reasons were expected to reflect classificatory knowledge, and would hopefully be useful in improving the computer program. The Delphi procedure was found to increase the consensus on the classifications. However, its use for program improvement appears to be problematic because the reasons provided by the cardiologists were too diffuse to be directly useful.

There is another option, not pursued in this study, to use the Delphi procedure for program improvement. Algorithms exist to generate decision trees automatically from a learning set of cases, where for each case feature values and a classification label have been provided [1,2]. A Delphi procedure could be applied to obtain a consensus on the classification labels for a set of ECGs. The advantage of this approach would be twofold. First, the decision tree would be trained using the consensus opinion of multiple experts and may be expected to reflect this opinion. Second, the reasons for a particular classification could easily be explained, thus obviating an important disadvantage of statistical classifiers. However, as the criteria in the decision nodes are determined automatically, they may appear 'illogical' to cardiologists. Research is needed to determine the 'intelligibility' of the decision trees, and to investigate whether interactive control of the tree generation procedure is worthwhile.

The indirect approach has been used in Chapters 8 and 9. In our investigations, we combined interpretations given by computer programs that incorporate the (formalized) knowledge of cardiologists, rather than interpretations given by cardiologists themselves (which was done in the CSE project). Combination at the level of classificatory knowledge remains an issue for further research.

Evaluation

The project 'Common Standards for Quantitative Electrocardiography' (CSE) [3,4] has been of invaluable help in evaluating the MEANS interpretation programs described in this study: we heavily used the CSE multilead and diagnostic databases, and we adopted many of the evaluation methods developed in the CSE project. The availability of well-validated databases has been, and will remain to be, a sine qua non for the proliferation of ECG interpretation programs. For example, testing agencies like the FDA (Food and Drug Administration) have started to formulate performance requirements for medical software [5]. Such requirements can only be met when large databases are available for testing purposes.

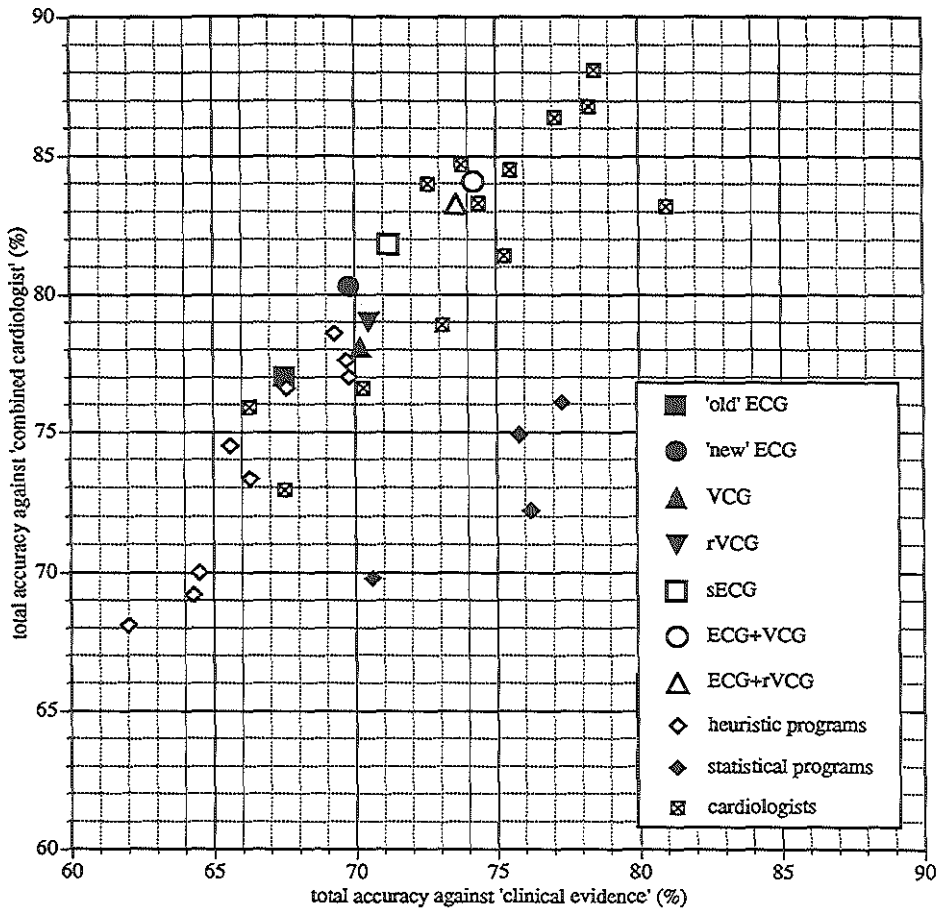


Figure 1. Total accuracies of the MEANS interpretation programs: 'old' ECG, 'new' ECG, VCG, and reconstructed VCG (rVCG) interpretation, 'combined' ECG interpretation of singular complexes (sECG), and 'combined' ECG+VCG and ECG+rVCG interpretations. The total accuracies of the other programs and cardiologists participating in the CSE study have also been entered. From these cardiologists the 'combined cardiologist' was derived.

All interpretation programs that were described in this thesis, have been evaluated using the CSE diagnostic database. Two reference standards have been used: the 'clinical evidence' and the 'combined cardiologist' result. The total accuracies of all MEANS interpretation programs against these two standards are depicted in Figure 1. Total accuracies have also been entered for the other programs participating in the CSE study, and for the cardiologists from which the 'combined cardiologist' was derived [6]. Several remarks can be made:

- The influence of different references used in building heuristic and statistical ECG computer programs is illustrated in Figure 1. The four statistical programs that participated in the CSE study have been trained on databases that were validated by means of 'clinical evidence'. The other, heuristic, programs are based on classification algorithms rendered by cardiologists. Hence, the agreement of the statistical programs with the 'clinical evidence' may be expected to be higher than that of the heuristic programs, while the reverse is true for the agreement with the 'combined cardiologist'.
- Three versions of the ECG interpretation program have been evaluated: the 'old' (i.e., prior to modification with DTL) ECG program, the 'new' ECG program which interprets the averaged complex, and the 'new' ECG program which classifies each individual complex in the recording separately and subsequently combines the multiple classifications into a final result (sECG). Of these three program versions, the sECG program performs best. However, Figure 1 also shows that the ECG program still needs further improvement in order to reach a performance comparable to that of most cardiologists.
- Total accuracies of the 'combined' interpretation programs (ECG+VCG and ECG+rVCG) are significantly higher than those of each interpretation program separately; they are comparable with those of the cardiologists. In the CSE study, the cardiologists always interpreted the ECG or the VCG separately. It would be interesting to investigate whether a cardiologist is able to improve his diagnostic performance by interpreting the ECG and the VCG (or rVCG) simultaneously.

Finally, it should be realized that the total accuracy is dependent on the composition of the database. A patient distribution such as in the CSE diagnostic database may be considered representative for a clinical environment. Therefore, conclusions from the above comparison of program results may not be applicable to other operating environments.

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SUMMARY

This study addresses two main questions: (1) How can the transfer of cardiological knowledge into computer algorithms be facilitated, and (2) Can the diagnostic performance of an ECG computer program be improved by combining different sources of cardiological knowledge? In posing these questions, we had a particular interest in improving our own ECG interpretation program MEANS (Modular ECG Analysis System).

In Chapter 2, we describe the signal analysis algorithms incorporated in the measurement part of MEANS and the procedure that was adopted to process multilead ECGs, i.e., standard 12-lead ECGs with eight independent leads recorded simultaneously. The algorithms were evaluated on a library of 250 simultaneously recorded ECG and VCG leads, which had been collected in the international project 'Common Standards for Quantitative Electrocardiography' (CSE). Results were determined for the multilead ECG, the four lead groups of the 12-lead ECG (which had always been processed in previous versions of MEANS), and the VCG. It proved that the performance of MEANS for the multilead ECG is comparable to that for the VCG, and at least as good as that for each of the four lead groups. The measurement part of MEANS described in Chapter 2 has been used throughout all our investigations.

In Chapter 3, the two prevalent methods for diagnostic ECG classification, statistical and heuristic, are described. In the heuristic approach, the cardiologist provides the knowledge to construct a classifier, usually a decision tree. In the statistical approach, probability densities of diagnostic features are estimated from a learning set of ECGs and multivariate techniques are used to attain diagnostic classification. The relative merits of both approaches are discussed. Heuristic classifiers are more comprehensible than statistical ones, encounter less difficulties in dealing with combined categories, and allow that new categories be readily entered or that existing ones be refined in a stepwise manner. On the other hand, statistical classifiers are easily adapted to another operating environment and require less involvement of cardiologists.

We also argue that two reference standards are of importance in the evaluation of ECG classification methods: ECG-independent clinical evidence and the combined judgment of a board of cardiologists. This point of view is the consequence of our position that the ECG should be classified on itself, discarding information other than age and sex, while only afterwards other information is used to reach a final diagnosis.

The first question - how to ease the transfer of cardiological knowledge into computer algorithms? - is considered in Chapters 4 and 5. Two key issues were discerned: (1) While a computer expert is required to translate the cardiologist's way of reasoning into computer language, most often the average cardiologist is not able to verify whether his intentions were properly realized, and (2) The operations of the program, when classifying a particular case, are often obscure to the program developer and impede program debugging and modification. The first problem ('representation') was solved by designing a dedicated language, DTL (Decision Tree Language), which enables cardiologists to express their classification knowledge in a way

familiar to them. The second problem ('insight') was dealt with by developing an interpreter for DTL which enables cardiologists to interactively trace the operation of the program and to modify the algorithms. A DTL translator was also developed to produce a fast run-time version of DTL programs. A comprehensive description of the considerations in designing these tools together with their functionality is given in Chapter 4.

The DTL environment was used to improve the ECG interpretation part of MEANS. In Chapter 5, a procedure is described to refine an ECG computer program step by step, alternatively using a database as learning set and test set. The almost colloquial nature of the DTL language and the interactivity of the system proved to be of great advantage. Initial modifications were tested on an independent database (N=1,220), which was collected and validated in the CSE project. Total accuracy against the 'clinical evidence' increased from 67.5% to 69.8%.

Transfer of cardiological knowledge into computer algorithms could also have been carried out by the more conventional approach, in which the computer expert acts as an intermediate between the cardiologist and the computer program. In our opinion, such an approach would be so time consuming and cumbersome as to make it impracticable. It should be kept in mind, however, that DTL and its interpreter and translator are tools to ease the transfer of knowledge and identify possible flaws in the (formalized) knowledge; they are not a panacea for the possibly low quality of such knowledge.

The second question - can diagnostic performance be improved by combining knowledge from multiple sources? - is studied in Chapters 6 through 9 from different perspectives.

Multiple cardiologists. In Chapter 6, it was investigated whether the Delphi method could be applied to elucidate knowledge from multiple experts in order to improve computer-supported ECG interpretation. To that end, five cardiologists were asked to judge the computer interpretation of thirty ECGs. The Delphi procedure was aimed at increasing the agreement among the cardiologists for two data items: (1) the changes made by the cardiologists in the computer classifications, and (2) their reasons for doing so.

It was found that the Delphi procedure produced a substantial increase of agreement in the cardiologists' classifications; the final agreement, quantified by kappa statistics, was comparable to the intraobserver agreement of the individual cardiologists. The agreement on the reasons was also very high. However, the reasons proved to be too incomplete and too fuzzy to be directly useful for program improvement.

Multiple programs. We investigated whether a combination of two interpretation programs, one for ECG classification, the other for VCG classification, would yield a better performance than each program separately. As such an approach would require that a VCG be always recorded in addition to the ECG, we also investigated whether the VCG could be adequately

reconstructed from the ECG. Such a reconstructed VCG (rVCG) could then be processed in the usual way by the VCG classification program.

In Chapter 7, three methods for reconstructing the VCG from the ECG were studied: a single-lead method using a quasi-orthogonal set of ECG leads, a method based on a model of the cardiac electrical activity, and a statistical method using multivariate regression. Their evaluation was primarily based on a comparison of the diagnostic classifications of the original and reconstructed VCGs. Using a test set of 90 cases, the original and reconstructed VCGs were presented separately and in random order to three referees. Kappa statistics were used to quantify the agreement between diagnostic classifications. Separately, one referee was simultaneously presented the original VCG and its three reconstructions. Each reconstructed VCG was classified as diagnostically 'same' as the original, 'borderline' or 'different'.

The diagnostic evaluation showed no significant differences between the regression method and the model-based method, both being preferable to the quasi-orthogonal method. Kappa values indicated a good to excellent diagnostic agreement between the original and reconstructed VCGs. Only one out of ninety VCGs that were reconstructed with the regression method was classified as 'different' compared with the original VCGs; three VCGs were classified as 'different' with the model-based method.

In Chapter 8, two 'combined' programs were considered, one produced by merging the ECG and VCG interpretations of MEANS, the other by combining the ECG and rVCG interpretations. The performance of the programs was evaluated with the CSE diagnostic library. It was shown that a 'combined program', produced by merging the classifications of the ECG and VCG interpretation programs, performs better than each program separately. The combination of ECG and rVCG interpretations had a performance similar to that of the combination of ECG and VCG interpretations. This finding implies that the performance of an ECG computer program can be improved by means of VCG criteria without needing the VCG to be recorded.

Multiple classifications. In Chapter 9, we investigated the effect of beat-to-beat variability on the diagnostic classifications of MEANS. Two sources of variability were distinguished: 'extrinsic' sources, e.g., powerline interference, baseline wander or electromyographic noise, and 'intrinsic' sources, e.g., changes in the volume conductor or the heart itself. Conventional approaches of ECG processing base their diagnostic classification on one set of measurements which is derived from a representative 'averaged' complex or by taking the median from the measurements for each complex in the recording. We propose and evaluate an alternative procedure in which each singular complex in the ECG recording is classified separately and the multiple classifications are then combined in one final classification.

Taking the averaged complex as a reference, it was shown that beat-to-beat variation in the measurements of singular complexes from the same recording was considerable. Variation was

largest when instability in the detection of waves resulted in wave relabelling. Leads III, aVR, aVF, and V1 proved to be most liable to wave relabelling.

The agreement between the diagnostic interpretations of singular complexes and corresponding averaged complexes was 93.3%. It was made plausible that both extrinsic noise and intrinsic variability influence the diagnostic interpretations.

The CSE diagnostic database was used to assess the performance of the 'combined' ECG interpretations of singular complexes. Total accuracy was 71.2%, a slight increase over the total accuracy of 69.8% that was obtained with the interpretations of averaged complexes. The interpretation of singular complexes may also provide the user with information about the program's stability and may be used to detect flaws in the classification logic.

In Chapter 10, we discuss our investigations in relation to the difficulties encountered in improving computerized ECG interpretation. It is concluded that the performance of the MEANS ECG interpretation program is not yet at the level of the best cardiologists who participated in the CSE study. The combination of ECG and VCG classificatory knowledge at the level of criteria and 'sensitivity analysis' of the interpretation programs appear to be the most promising research areas to further improve ECG interpretation by computer.

SAMENVATTING

In deze studie staan twee vragen centraal: (1) hoe kan de overdracht van cardiologische kennis naar computeralgoritmes worden vergemakkelijkt, en (2) kan de diagnostische prestatie van een ECG-computerprogramma worden verbeterd door combinatie van verschillende 'bronnen' van cardiologische kennis? Deze vragen werden mede ingegeven door de wens ons ECG-interpretatieprogramma MEANS (Modular ECG Analysis System) te verbeteren.

Hoofdstuk 2 bevat een beschrijving van de signaalanalyse-algoritmes in MEANS en van de procedure voor de verwerking van 'multilead' ECG's (standaard 12-afleidingen ECG's waarvan acht onafhankelijke afleidingen simultaan zijn opgenomen). Een bestand van 250 simultaan opgenomen ECG- en VCG-afleidingen werd gebruikt om de algoritmes te evalueren. Dit bestand werd verzameld in het kader van het internationale project 'Common Standards for Quantitative Electrocardiography' (CSE). Evaluatieresultaten werden bepaald voor het multilead ECG, de vier afleidingsgroepen van het 12-afleidingen ECG (deze groepen werden in voorgaande versies van MEANS gebruikt), en het VCG. De prestaties van MEANS voor het multilead ECG bleken vergelijkbaar met die voor het VCG, en minstens zo goed als die voor elk van de vier afleidingsgroepen. Het in hoofdstuk 2 beschreven signaalanalysedeel van MEANS is gebruikt bij alle experimenten.

In hoofdstuk 3 worden de twee voornaamste methodes voor diagnostische ECG-classificatie beschreven: de heuristische en de statistische. In de heuristische benadering levert een cardioloog de kennis voor het maken van een classifier, meestal in de vorm van een beslissingsboom. In de statistische benadering schat men kansdichtheden van diagnostische kenmerken aan de hand van een leerverzameling van ECG's. Vervolgens wordt met multivariate technieken een diagnostische classificatie bereikt. De voor- en nadelen van beide methodes worden besproken. Heuristische classificatoren zijn inzichtelijker dan statistische, geven minder problemen met gecombineerde categorieën, en laten op eenvoudige wijze het toevoegen van nieuwe categorieën of het stapsgewijs verfijnen van bestaande categorieën toe. Statistische classificatoren daarentegen kunnen makkelijker voor een andere verwerkingsomgeving geschikt gemaakt worden en vereisen minder betrokkenheid van cardiologen.

Ook wordt betoogd dat twee referentiestandaarden van belang zijn bij de evaluatie van ECG-classificatiemethodes: ECG-onafhankelijk klinisch materiaal en de gecombineerde ECG-beoordeling van een groep van cardiologen. Deze positie is het gevolg van ons standpunt dat het ECG op zichzelf geassocieerd dient te worden zonder informatie anders dan leeftijd en geslacht. Na classificatie kan additionele informatie worden gebruikt om de uiteindelijke diagnose te bepalen.

De eerste vraag - hoe kan de overdracht van cardiologische kennis naar computeralgoritmes vergemakkelijkt worden? - komt aan de orde in de hoofdstukken 4 en 5. Twee problemen werden onderscheiden: (1) er is een computerexpert nodig om de manier van redeneren van een cardioloog in computertaal om te zetten, maar de gemiddelde cardioloog is niet in staat te

verifiëren of zijn bedoelingen op de juiste wijze werden gerealiseerd, en (2) de werking van het programma, bij het classificeren van een bepaald geval, is vaak onduidelijk voor de programma-ontwikkelaar en bemoeilijkt het oplossen van fouten en het wijzigen van het programma. Het eerste probleem ('representatie') werd opgelost door een speciale taal te ontwerpen, DTL (Decision Tree Language), die cardiologen in staat stelt hun classificatiekennis op een hun vertrouwde wijze uit te drukken. Het tweede probleem ('inzicht') werd opgelost door een interpretator voor DTL te ontwikkelen. Deze stelt cardiologen in staat op een interactieve manier de werking van het programma te volgen en algoritmes te wijzigen. Daarnaast werd een DTL-vertaler ontwikkeld waarmee een snelle executeerbare versie van de DTL-programma's gegenereerd kan worden. Een uitgebreide beschrijving van de ontwerpcriteria en van de functionaliteit van deze hulpmiddelen is gegeven in hoofdstuk 4.

De DTL-omgeving werd gebruikt om het ECG-interpretatiedeel van MEANS te verbeteren. In hoofdstuk 5 wordt een procedure beschreven om een ECG-computerprogramma stapsgewijs te verfijnen, waarbij een ECG-bestand afwisselend als leer- en testverzameling gebruikt wordt. Het gemak waarmee cardiologische kennis in DTL uitgedrukt kon worden en de interactiviteit van het systeem bleken zeer nuttig. De eerste wijzigingen werden getest op een onafhankelijk bestand (N=1220) dat werd verzameld en gevalideerd in het kader van het CSE-project. Het percentage correcte classificaties, met het 'klinisch materiaal' als referentie, steeg van 67,5% naar 69,8%.

Cardiologische kennis had ook op een meer conventionele manier in computeralgoritmes omgezet kunnen worden. De computerexpert fungeert dan als een schakel tussen cardioloog en computerprogramma. Wij meenden echter dat deze benadering dermate tijdrovend en moeizaam zou zijn, dat zij praktisch onuitvoerbaar was. Overigens, DTL en de interpretator en vertaler zijn hulpmiddelen om de overdracht van kennis te vergemakkelijken en lacunes in de (geformaliseerde) kennis op te sporen; zij vormen geen panacee voor de eventuele geringe kwaliteit van die kennis.

De tweede vraag - kunnen diagnostische prestaties worden verbeterd door kennis uit verschillende bronnen te combineren? - is in de hoofdstukken 6 tot en met 9 vanuit verschillende perspectieven belicht.

Verschillende cardiologen. In hoofdstuk 6 werd onderzocht of de Delphi-methode kon worden toegepast om kennis aan verschillende cardiologen te ontlokken ter verbetering van computerondersteunde ECG-interpretatie. Daartoe werd aan vijf cardiologen gevraagd de computerinterpretatie van dertig ECG's te beoordelen. Het doel van de Delphi-procedure was om de overeenstemming tussen de cardiologen te verhogen wat betreft (1) de door hen gemaakte veranderingen in de computerclassificaties, en (2) hun redenen voor die veranderingen.

De Delphi-procedure leidde tot een aanzienlijke toename in overeenstemming voor wat betreft de cardiologische classificaties; de uiteindelijke overeenstemming, uitgedrukt in kappa-waardes, was vergelijkbaar met de overeenstemming van elke cardioloog met zichzelf. De overeenstemming voor de redenen was ook hoog, maar de redenen bleken niet compleet genoeg en te vaag om direct bruikbaar te zijn voor programmaverbetering.

Verschillende programma's. Onderzocht werd of een combinatie van de programma's voor ECG-classificatie en voor VCG-classificatie een betere prestatie zou leveren dan elk programma afzonderlijk. Omdat deze benadering vereist dat naast het ECG ook het VCG beschikbaar is, werd tevens onderzocht of het VCG uit het ECG gereconstrueerd kon worden. Het gereconstrueerde VCG (rVCG) zou dan op de gebruikelijke manier door het VCG-classificatieprogramma verwerkt kunnen worden.

In hoofdstuk 7 werden drie methodes bestudeerd voor het reconstrueren van het VCG uit het ECG: een methode die drie quasi-orthogonale ECG-afleidingen gebruikt, een methode gebaseerd op een model van de elektrische hartactiviteit, en een statistische methode die gebruik maakt van meervoudige regressie. De evaluatie van de methodes vond plaats door de diagnostische classificaties van de originele en gereconstrueerde VCG's te vergelijken. Voor een testbestand van negentig gevallen werden de originele en gereconstrueerde VCG's afzonderlijk en in willekeurige volgorde gepresenteerd aan drie beoordelaars. Kappa-waardes werden gebruikt om de overeenstemming in diagnostische classificaties te kwantificeren. Daarnaast werden aan één beoordelaar tegelijkertijd een origineel VCG met de bijbehorende drie reconstructies voorgelegd. Elk gereconstrueerd VCG werd geclassificeerd als diagnostisch 'hetzelfde' als het origineel, 'grensgeval' of 'verschillend'.

Uit de diagnostische evaluatie bleken geen significante verschillen tussen de regressiemethode en de modelgebaseerde methode; beide verdienden de voorkeur boven de quasi-orthogonale methode. Kappa-waardes gaven aan dat er een goede tot uitstekende diagnostische overeenstemming tussen de originele en gereconstrueerde VCG's bestond. Slechts één van de negentig VCG's die met de regressiemethode werden gereconstrueerd, werd als 'verschillend' geclassificeerd vergeleken met de originele VCG's; drie VCG's werden als 'verschillend' geclassificeerd met de modelgebaseerde methode.

In hoofdstuk 8 werden twee 'gecombineerde' programma's bestudeerd. Eén programma werd gemaakt door de ECG- en VCG-interpretaties van MEANS te combineren, de ander door de ECG- en rVCG-interpretaties te combineren. Het diagnostische CSE-bestand werd gebruikt om de programma's te evalueren. Er werd aangetoond dat een 'gecombineerd' programma bestaande uit de gecombineerde classificaties van de ECG- en VCG-interpretatieprogramma's, betere resultaten geeft dan elk programma afzonderlijk. De combinatie van ECG- en rVCG-interpretaties gaf vergelijkbare prestaties als de combinatie van ECG- en VCG-interpretaties. Dit

resultaat betekent dat de prestaties van een ECG-computerprogramma verbeterd kunnen worden met behulp van VCG-criteria zonder dat het VCG hoeft te worden opgenomen.

Verskillende classificaties. In hoofdstuk 9 werd de invloed van slag-op-slag variabiliteit op de diagnostische classificaties van MEANS onderzocht. Twee bronnen van variabiliteit werden onderscheiden: 'extrinsieke' bronnen, bv. netstoring, basislijnverstoringen of elektromyografische ruis, en 'intrinsieke' bronnen, bv. veranderingen in de volumegeleider of in het hart zelf. Conventionele benaderingen voor ECG-verwerking baseren hun diagnostische classificatie op één verzameling van metingen die worden bepaald in een representatief 'gemiddeld' complex of door de mediaan te nemen van de metingen voor elk complex in de ECG-opname. Een alternatieve procedure werd voorgesteld en geëvalueerd waarin elk singulier complex in de opname afzonderlijk geïdentificeerd wordt en de verschillende classificaties vervolgens tot één classificatie gecombineerd worden.

Het bleek dat een aanzienlijke slag-op-slag variabiliteit optrad in de metingen van singuliere complexen van dezelfde opname. De grootste variabiliteit trad op, als instabiliteit in de detectie van golven een verandering in de golfbenaming veroorzaakte. Afleidingen III, aVR, aVF en V1 bleken daarvoor het meest gevoelig.

De overeenstemming tussen de diagnostische interpretaties van singuliere complexen en bijbehorende gemiddelde complexen was 93,3%. Er werd plausibel gemaakt dat zowel extrinsieke ruis als intrinsieke variabiliteit van invloed is op diagnostische interpretatie.

Het diagnostisch CSE-bestand werd gebruikt om de prestatie te bepalen van de 'gecombineerde' ECG-interpretaties van singuliere complexen. Het percentage correcte classificaties was 71,2%, een lichte toename in vergelijking met de 69,8% die werd verkregen met de interpretaties van de gemiddelde complexen. De interpretatie van singuliere complexen kan ook informatie over de programmastabiliteit verschaffen en kan gebruikt worden om fouten in de classificatie-logica te ontdekken.

In hoofdstuk 10 worden onze bevindingen gerelateerd aan de moeilijkheden die een rol spelen bij de verbetering van geautomatiseerde ECG-interpretatie. De prestatie van het MEANS ECG-interpretatieprogramma blijkt nog niet op het niveau van de beste cardiologen die aan de CSE-studie deelnamen. Combinatie van ECG- en VCG-classificatiecriteria en 'gevoeligheidsanalyse' van het interpretatieprogramma lijken veelbelovende onderzoeksgebieden voor verdere verbetering van geautomatiseerde ECG-interpretatie.

CURRICULUM VITAE

Jan Alexander Kors was born on October 23rd, 1958 in Delft, The Netherlands. He received his undergraduate education at the Hermann Wesselink College (Gymnasium β) in Amstelveen. In 1976, he graduated and started a study in electrotechnical engineering at the Technical University in Delft. He obtained his degree ('ingenieursexamen') in 1983.

During his civil service of one and a half year, he worked at the Department of Medical Informatics at the Free University in Amsterdam. After this period, he started his Ph.D. research at the same department.

In 1987, he moved to the Department of Medical Informatics at the Erasmus University in Rotterdam where he continued his Ph.D. research.

Jan Kors is presently a scientific staff member at the Department of Medical Informatics at the Erasmus University.

NAWOORD

*Where is the Life we have lost in living?
Where is the wisdom we have lost in knowledge?
Where is the knowledge we have lost in information?*

T.S. Eliot

Velen hebben, direct of indirect, aan de totstandkoming van dit proefschrift bijgedragen. Het plezier waarmee ik eraan gewerkt heb, werd, naast de aard van het onderzoek, in belangrijke mate door deze contacten bepaald. Maar hoe aangenaam of belangrijk het maken van een proefschrift ook mag zijn, het leven bestaat uit (veel) meer dan werk. Het heeft mij steeds de kunst geleken dit goed in het oog te houden, en ook daaraan droegen velen, direct of indirect, bij. Van al die mensen wil ik er een aantal in het bijzonder noemen:

Jan van Bemmel, die mij geregeld op nieuwe sporen zette, die mij met zijn enthousiasme en optimisme stimuleerde verder te gaan, en met wie het ook buiten het werk aangenaam verpozen was;

Gerard van Herpen, met wie ik de afgelopen jaren, zeer tot genoegen, intensief samenwerkte, en die met zijn veelzijdige eruditie altijd graag het gesprek aanging over onderwerpen die de electrocardiografie verre te buiten gingen;

Kine Sittig, die tijdens een deel van het onderzoek mijn directe begeleidster was, en die mij leerde steeds kritisch te vragen bij datgene waar ik mee bezig was;

Jan Talmon, die mij inwijdde in de geautomatiseerde analyse van ECG's, en wiens grote enthousiasme voor verschillende onderwerpen die niets met dit vak te maken hebben, aanstekelijk werkte;

mijn ouders, die in belangrijke mate de wijze waarop ik in het leven sta bepaalden, en waar ik altijd een 'thuis' vond;

Irmgard Ballast, die de juiste woorden vond als ze nodig waren, die zweeg als er niets hoefde te worden gezegd, en die mij steeds weer bepaalt bij het Leven dat geleefd moet worden.