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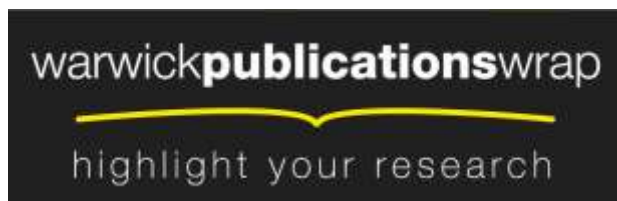
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Testing first-order properties for subclasses of sparse graphs*

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Abstract

We present a linear-time algorithm for deciding first-order (FO) properties in classes of graphs with bounded expansion, a notion recently introduced by Nešetřil and Ossona de Mendez. This generalizes several results from the literature, because many natural classes of graphs have bounded expansion: graphs of bounded tree-width, all proper minor-closed classes of graphs, graphs of bounded degree, graphs with no subgraph isomorphic to a subdivision of a fixed graph, and graphs that can be drawn in a fixed surface in such a way that each edge crosses at most a constant number of other edges. We deduce that there is an almost linear-time algorithm for deciding FO properties in classes of graphs with locally bounded expansion.

More generally, we design a dynamic data structure for graphs belonging to a fixed class of graphs of bounded expansion. After a linear-time initialization the data structure allows us to test an FO property in constant time, and the data structure can be updated in constant time after addition/deletion of an edge, provided the list of possible edges to be added is known in advance and their simultaneous addition results in a graph in the class. All our results also hold for relational structures and are based on the seminal result of Nešetřil and Ossona de Mendez on the existence of low tree-depth colorings.

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1 Introduction

A celebrated theorem of Courcelle [1] states that for every integer $k \geq 1$ and every property Π definable in monadic second-order logic (MSOL) there is a linear-time algorithm to decide whether a graph of tree-width at most k satisfies Π . While the theorem itself is probably not useful in practice because of the large constants involved, it does provide an easily verifiable condition that a certain problem is (in theory) efficiently solvable. Courcelle's result led to the development of a whole new area of algorithmics, known as algorithmic meta-theorems; see the surveys [17, 18]. For specific problems there is very often a more efficient implementation, for instance following the axiomatic approach of [27].

While the class of graphs of tree-width at most k is fairly large, it does not include some important graph classes, such as planar graphs or graphs of bounded degree. Courcelle's theorem cannot be extended to these classes unless $P=NP$, because testing 3-colorability is NP-hard for planar graphs of maximum degree at most four [16] and yet 3-colorability is expressible in monadic second order logic.

Thus in an attempt at enlarging the class of input graphs, we have to restrict the set of properties to be tested. One of the first results in this direction was a linear-time algorithm of Eppstein [10, 11] for testing the existence of a fixed subgraph in planar graphs. He then extended his algorithm to minor-closed classes of graphs with locally bounded tree-width [12]. Since testing containment of a fixed subgraph can be expressed in first order logic by a Σ_1 -sentence, this can be regarded as a precursor to first order (FO) property testing. Prior to our work, the following were the most general results:

- a linear-time algorithm of Seese [28] to test FO properties of graphs of bounded degree,
- a linear-time algorithm of Frick and Grohe [14] for deciding FO properties of planar graphs,
- an almost linear-time algorithm of Frick and Grohe [14] for deciding FO properties for classes of graphs with locally bounded tree-width,
- a fixed parameter algorithm of Dawar, Grohe and Kreutzer [2] for deciding FO properties for classes of graphs locally excluding a minor, and
- a linear-time algorithm of Nešetřil and Ossona de Mendez [21] for deciding Σ_1 -properties for classes of graphs with bounded expansion.

Our main theorem and its corollary generalize these five results. In order to state them we need a couple of definitions. All graphs and digraphs in this paper are finite and have no loops or parallel edges. However, digraphs are permitted to have two edges joining the same pair of vertices in opposite directions. For an integer $r \geq 0$, a graph H is an *r-shallow minor* of a graph G if H can be obtained from a subgraph of G by contracting vertex-disjoint subgraphs of radii

at most r (and removing the resulting loops and parallel edges). A class \mathcal{G} of graphs has *bounded expansion* if there exists a function $f : \mathbb{N} \rightarrow \mathbb{R}^+$ such that for every integer $r \geq 0$ every r -shallow minor G of a member of \mathcal{G} satisfies $|E(G)|/|V(G)| \leq f(r)$. A preliminary version of our main theorem can be stated as follows.

Theorem 1. *Let \mathcal{G} be a class of graphs with bounded expansion, and let Π be a first-order property of graphs. Then there exists a linear-time algorithm that decides whether a graph from \mathcal{G} satisfies Π .*

In fact, we prove a more general theorem (Theorem 3): there exists a linear-time algorithm for L -structures “guarded” by a member of \mathcal{G} , and we design several data structures that allow the L -structure to be modified and support FO property testing in constant time.

Using known techniques we derive the following corollary from Theorem 1. A class \mathcal{G} of graphs has *locally bounded expansion* if there exists a function $g : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{R}^+$ such that for every two integers $d, r \geq 0$, for every graph $G \in \mathcal{G}$ and for every vertex $v \in V(G)$, every r -shallow minor H of the d -neighborhood of v in G satisfies $|E(H)|/|V(H)| \leq g(d, r)$, where the d -neighborhood of v is the subgraph of G induced by vertices at distance at most d from v . We say that there exists an *almost linear-time algorithm* to solve a problem Π if for every $\varepsilon > 0$ there exists an algorithm to solve Π with running time $O(n^{1+\varepsilon})$, where n is the size of the input instance.

Corollary 2. *Let \mathcal{G} be a class of graphs with locally bounded expansion, and let Π be a first-order property of graphs. Then there exists an almost linear-time algorithm that correctly decides whether a graph from \mathcal{G} satisfies Π .*

We announced our results in the survey paper [6]. Dawar and Kreutzer [3] posted an independent proof of Theorem 1 and a proof of Corollary 2 for the more general classes of nowhere-dense graphs (introduced below). However, the proofs in [3] are incorrect. A correct proof of Theorem 1, different from ours, appears in [17].

Thus it remains an interesting open problem whether Corollary 2 can be generalized to the more general classes of nowhere-dense graphs. This is of substantial interest from the point of view of fixed parameter tractability, because nowhere density of classes of graphs gives a natural limitation (subject to a widely believed complexity-theory assumption). Indeed, we prove the following in Theorem 5 below. Let L be a language consisting of one binary relation symbol and let \mathcal{G} be a class of graphs closed under taking subgraphs that is not nowhere dense. We prove that if testing whether an input graph from \mathcal{G} satisfies a given Σ_1 -sentence φ is fixed parameter tractable when parameterized by the size of φ , then $\text{FPT}=\text{W}[1]$.

In the rest of this section we introduce terminology and state all our results.

1.1 Logic theory definitions

Our logic terminology is standard, except for the following. All function symbols have arity one, and hence all functions are functions of one variable. If L is a language, then an L -term is *simple* if it is a variable or it is of the form $f(x)$ where f is a function symbol and x is a variable. An L -formula is *simple* if all terms appearing in it are simple. The rest of our logic terminology is standard, and so readers familiar with it may skip the rest of this subsection.

A language L consists of a disjoint union of a finite set L^r of *relation symbols* and a finite set L^f of *function symbols*. Each relation symbol $R \in L^r$ is associated with an integer $a(R) \geq 0$, called the arity of R . In this paper all function symbols have arity one.

If L is a language, then an L -structure A is a triple $(V, (R^A)_{R \in L^r}, (f^A)_{f \in L^f})$ consisting of a finite set V and for each m -ary relation symbol $R \in L^r$ a set $R^A \subseteq V^m$, the *interpretation* of R in A , and for each function symbol $f \in L^f$ a function $f^A : V \rightarrow V$ of one variable, the *interpretation* of f in A . We define $V(A) := V$. For example, graphs may be regarded as L -structures, where L is the language consisting of a single binary relation. We define the size $|A|$ of A to be $|V(A)| + \sum_{R \in L^r} |R^A| + |L^f| |V(A)|$. If L contains no function symbols, then an L -substructure of an L -structure $A = (V, (R^A)_{R \in L^r})$ is an L -structure $A' = (V', (R^{A'})_{R \in L^r})$ where $V' \subseteq V$ and $R^{A'} \subseteq R^A \cap V'^{a(R)}$. A language L' extends a language L if every function symbol of L is a function symbol of L' and the same holds for relation symbols, which also retain the same arity. If a language L' extends a language L , A is an L -structure and A' is an L' -structure such that $V(A) = V(A')$ and A and A' have the same interpretations of symbols of L , then we say that A' is an *expansion* of A .

Assume that we have an infinite set of variables. An L -term is defined as follows:

1. each variable is an L -term, and
2. if $f \in L^f$ and t is an L -term, then $f(t)$ is an L -term.

Each L -term is obtained by a finite number of applications of these two rules. We say that an L -term is *simple* if it is a variable or is of the form $f(x)$ where $f \in L^f$ and x is a variable. A term t *appears* in a term t' if either $t = t'$ or $t' = f(t'')$ for some $f \in L^f$ and t appears in t'' .

An *atomic L -formula* φ is either the symbol \top (which represents a tautology); or its negation \perp ; or $R(t_1, \dots, t_m)$, where R is an m -ary relation symbol of L and t_1, \dots, t_m are L -terms; or $t_1 = t_2$, where t_1 and t_2 are L -terms. A term t appears in φ if it appears in one of the terms t_1, \dots, t_m . An L -formula is defined recursively as follows: every atomic L -formula is an L -formula, and if φ_1 and φ_2 are L -formulas and x is a variable, then $\neg\varphi_1$, $\varphi_1 \vee \varphi_2$, $\varphi_1 \wedge \varphi_2$, $\exists x \varphi_1$ and $\forall x \varphi_1$ are L -formulas. Every L -formula is obtained by a finite application of these rules. We write $t_1 \neq t_2$ as a shortcut for $\neg(t_1 = t_2)$.

A term t *appears* in an L -formula $\varphi_1 \vee \varphi_2$ if it appears in φ_1 or φ_2 , and we define appearance for the other cases analogously. An L -formula is *simple* if all

terms appearing in it are simple. A variable x *appears freely* in an L -formula φ if either φ is atomic and x appears in φ ; or $\varphi = \varphi_1 \vee \varphi_2$ or $\varphi = \varphi_1 \wedge \varphi_2$ and x appears freely in at least one of the formulas φ_1 and φ_2 ; or $\varphi = \exists y \varphi'$ or $\varphi = \forall y \varphi'$, x is distinct from y and x appears freely in φ' . Occurrences of x in the formula φ not inside the scope of a quantifier bounding x , i.e., those that witness that x appears freely in φ , are called *free* and the variables that appear freely in φ are also referred to as *free variables*. If φ is a formula, then the notation $\varphi(x_1, \dots, x_n)$ indicates that all variables that appear freely in φ are among x_1, \dots, x_n . An L -sentence is an L -formula such that no variable appears freely in it. A Σ_1 - L -sentence is an L -formula of the form $\exists x_1, \dots, x_n \varphi(x_1, \dots, x_n)$ where the L -formula $\varphi(x_1, \dots, x_n)$ is quantifier-free. If $\varphi(x_1, \dots, x_n)$ is an L -formula and A is an L -structure, then for $v_1, \dots, v_n \in V(A)$, we define $A \models \varphi(v_1, \dots, v_n)$ in the usual way. We denote the *length* of a formula φ by $|\varphi|$. Finally, a property Π of L -structures is called a *first order property* if there exists an L -sentence φ such that every L -structure A has property Π if and only if $A \models \varphi$. The property Π is a Σ_1 -*property* if φ can be chosen to be a Σ_1 - L -sentence.

1.2 Classes of sparse graphs

The notion of a class of graphs of bounded expansion was introduced by Nešetřil and Ossona de Mendez in [19] and in the series of journal papers [20, 21, 22]. Examples of classes of graphs with bounded expansion include proper minor-closed classes of graphs, classes of graphs with bounded maximum degree, classes of graphs excluding a subdivision of a fixed graph, classes of graphs that can be embedded on a fixed surface with bounded number of crossings per edge and many others, see [24]. Many structural and algorithmic properties generalize from proper minor-closed classes of graphs to classes of graphs with bounded expansion, see [6, 25].

Nešetřil and Ossona de Mendez [23] defined a class \mathcal{G} of graphs to be *nowhere-dense* if for every $\varepsilon > 0$ and every integer r there exists a real number K such that if G is an r -shallow minor of a member of \mathcal{G} , then $|E(G)| \leq K|V(G)|^{1+\varepsilon}$. (It follows from [23, Corollary 3.3] that this definition is indeed equivalent to the one given in [23].) It can be shown that every class of graphs with (locally) bounded expansion is nowhere-dense [23], but the converse is false: the class \mathcal{G} of graphs G with no cycles of length less than $\Delta(G)$ is nowhere-dense but it fails to have bounded expansion; the class of graphs obtained from graphs G in \mathcal{G} by adding a vertex adjacent to all vertices of G is a class of nowhere-dense graphs that does not have locally bounded expansion. One can also define a “locally nowhere-dense” class of graphs, but it turns out that such classes are nowhere-dense [23].

If L is a language, then the *Gaifman graph* of an L -structure A is the undirected graph G_A with vertex set $V(G_A) = V(A)$ and an edge between two distinct vertices $a, b \in V(A)$ if and only if there exist $R \in L^r$ and a tuple $(a_1, \dots, a_r) \in R^A$ such that $a, b \in \{a_1, \dots, a_r\}$ or there exists a function $f \in L^f$ such that $b = f^A(a)$ or $a = f^A(b)$. We say that the relational structure A is *guarded* by a graph G if $V(G) = V(A)$ and G_A is a subgraph of G . Observe

that if G belongs to a class of graphs with bounded expansion, then every subgraph of G has a vertex of bounded degree, and hence the number of complete subgraphs of G is linear in $|V(G)|$ by a result of [29]. It follows that the size $|A|$ of any L -structure A guarded by a graph belonging to a fixed class of graphs with bounded expansion is $O(|V(A)|)$.

Our model of computation is the standard RAM model with addition and subtraction as arithmetic operations. An L -structure A is represented in the straightforward way by listing all elements of $V(A)$, the images of elements under functions of A , and listing all tuples of all relations of A . However, we will need to be able to decide in constant time whether a given tuple satisfies the interpretation of a relation in an L -structure, and we now explain how to do that for L -structures guarded by d -degenerate graphs. Let d be a fixed integer. A graph G is called *d -degenerate* if every subgraph of G has a vertex of degree d or less. Thus if \mathcal{G} is a class of graphs of bounded expansion, then there exists an integer d such that every member of \mathcal{G} is d -degenerate: indeed, every subgraph G' of G has average degree at most $2f(0)$, where f is the function from the definition of classes of graphs of bounded expansion, and consequently G' has a vertex of degree at most $2f(0)$. Now let A be an L -structure guarded by a d -degenerate graph G . Since G is d -degenerate, its vertices can be numbered v_1, v_2, \dots, v_n in such a way that for each $i = 1, 2, \dots, n$ the vertex v_i has at most d neighbors among v_1, \dots, v_{i-1} . Now each t -tuple $(v_{i_1}, v_{i_2}, \dots, v_{i_t})$, where $i_1 < i_2 < \dots < i_t$, will be associated with the vertex v_{i_t} . Then each vertex is associated with at most $d(d-1) \cdots (d-t+2)$ distinct t -tuples. For each relation we compute the associations at the beginning of the computation, and then we can answer in constant time queries of the form whether a given t -tuple belongs to a given relation.

1.3 Our results

We first state versions of Theorem 1 and Corollary 2 for L -structures. Theorem 1 and Corollary 2 are immediate consequences.

Theorem 3. *Let \mathcal{G} be a class of graphs with bounded expansion, L a language and φ an L -sentence. There exists a linear-time algorithm that decides whether an L -structure guarded by a graph $G \in \mathcal{G}$ satisfies φ .*

Corollary 4. *Let \mathcal{G} be a class of graphs with locally bounded expansion, L a language and φ an L -sentence. There exists an almost linear-time algorithm that decides whether an L -structure guarded by a graph $G \in \mathcal{G}$ satisfies φ .*

Our approach differs from the methods used to prove the results from [2, 14, 28] mentioned above and is based on a seminal result of Nešetřil and Ossona de Mendez [20] on the existence of low tree-depth colorings for graphs with bounded expansion, stated below in a form suitable for our purposes as Theorem 11.

We also consider dynamic setting and design the following data structures, where the last one can be viewed as a dynamic version of Theorem 3.

- For every class \mathcal{G} of graphs with bounded expansion, an integer d_0 and a language L , we design a data structure such that given a graph $G \in \mathcal{G}$ on n vertices and an L -structure guarded by A the data structure is initialized in time $O(n)$ and supports:
 - adding a tuple to a relation of A in time $O(1)$ provided A stays guarded by G ,
 - removing a tuple from a relation of A in time $O(1)$,
 - answering whether $A \models \varphi$ for a Σ_1 - L -sentence φ with at most d_0 variables in time $O(|\varphi|)$ and outputting one of the satisfying assignments, and
- for every class \mathcal{G} of nowhere-dense graphs, every integer d_0 , and every language L we design a data structure such that for every $\varepsilon > 0$, given a graph $G \in \mathcal{G}$ on n vertices and an L -structure guarded by A , the data structure is initialized in time $O(n^{1+\varepsilon})$ and supports:
 - adding a tuple to a relation of A in time $O(n^\varepsilon)$ provided A stays guarded by G ,
 - removing a tuple from a relation of A in time $O(n^\varepsilon)$, and
 - answering whether $A \models \varphi$ for a Σ_1 - L -sentence φ with at most d_0 variables in time $O(|\varphi|)$ and if so, outputting one of the satisfying assignments, and
- for every class \mathcal{G} of graphs with bounded expansion, a language L and an L -sentence φ , we design a data structure such that given a graph $G \in \mathcal{G}$ on n vertices and an L -structure guarded by A the data structure is initialized in time $O(n)$ and supports:
 - adding a tuple to a relation of A in time $O(1)$ provided A stays guarded by G ,
 - removing a tuple from a relation of A in time $O(1)$,
 - answering whether $A \models \varphi$ in time $O(1)$.

The first of these data structures is needed in our linear-time algorithm for 3-coloring triangle-free graphs on surfaces [9], also see [7]. The first two data structures are presented in Theorems 22 and 23 in Section 5, and the third one is presented in Theorem 26 in Section 6.

1.4 A hardness result

Theorem 1 and Corollary 2 fall within the realm of fixed parameter tractability (FPT). We say that a decision problem Π parameterized by a parameter t is *fixed parameter tractable* if there exists an algorithm for Π with running time $O(f(t)n^c)$, where n is the size of the input, f is an arbitrary function and c is a constant independent of t . Analogously to the polynomial hierarchy starting

with the classes P and NP, there exists a hierarchy of classes $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$ of parameterized problems, where FPT is the class of problems that are fixed parameter tractable. See e.g. [5, 13, 26] for more details.

Theorem 5. *Let \mathcal{G} be a class of graphs closed under taking subgraphs. If \mathcal{G} is not nowhere-dense and the problem of deciding Σ_1 -properties in \mathcal{G} is fixed parameter tractable when parametrized by the length of the formula that defines the property, then $\text{FPT}=\text{W}[1]$.*

Proof. An r -subdivision of a graph G is the graph obtained from G by subdividing every edge exactly r times. Since \mathcal{G} is not nowhere-dense and \mathcal{G} is closed under taking subgraphs, there exists an integer r such that \mathcal{G} contains an r -subdivision of every graph [23]. Since the existence of a subgraph isomorphic to an r -subdivision of the complete graph K_m is a Σ_1 -property for every m , we derive from the hypothesis of the theorem that there exists an FPT algorithm \mathcal{A} to decide the existence of an r -subdivision of the complete graph K_m in an input graph from \mathcal{G} , where the problem is parameterized by m . This implies that testing the existence of a complete subgraph of order m is fixed parameter tractable for general graphs G , because it is equivalent to testing whether the r -subdivision of G has a subgraph isomorphic to the r -subdivision of K_m , and the latter can be tested using the algorithm \mathcal{A} . But testing the existence of a K_m subgraph is a well-known $\text{W}[1]$ -complete problem [4], and hence $\text{FPT}=\text{W}[1]$, as desired. \square

Dawar and Kreutzer [3] proved the related result that if \mathcal{G} fails to be nowhere dense in an “effective” way and deciding FO properties in \mathcal{G} is fixed parameter tractable, then $\text{FPT}=\text{AW}[*]$.

The paper is organized as follows. In the next section we review results about classes of graphs with bounded expansion and classes of nowhere-dense graphs that will be needed later. In Section 3 we prove Theorem 3 and in Section 4 we use it to deduce Corollary 4. In Section 5 we present the first two data structures mentioned earlier in this section, and in the final Section 6 we present the third data structure.

A conference version of this article appeared in [8].

2 Classes of graphs with bounded expansion

In this section, we survey results on classes of graphs with bounded expansion and classes of nowhere-dense graphs that we need in the paper. Let G be a graph, and let $r \geq 0$ be an integer. Let us recall that a graph H is an r -shallow minor of G if H can be obtained from a subgraph of G by contracting vertex-disjoint subgraphs of radii at most r and deleting the resulting loops and parallel edges. Following Nešetřil and Ossona de Mendez we denote by $\nabla_r(G)$ the maximum of $|E(G')|/|V(G')|$ over all r -shallow minors G' of G . Thus $\nabla_0(G)$ is the maximum of $|E(G')|/|V(G')|$ taken over all subgraphs G' of G . Since every subgraph of G has a vertex of degree at most $2\nabla_0(G)$, we see that G is

$(2\nabla_0(G) + 1)$ -colorable and that it has an orientation with maximum in-degree at most $2\nabla_0(G)$. Clearly, such an orientation can be found in linear time in a greedy way. Thus we have the following.

Lemma 6. *For every class \mathcal{G} of graphs of bounded expansion there exists an integer K such that every graph $G \in \mathcal{G}$ is K -colorable and has an orientation with maximum in-degree at most $K - 1$. Furthermore, a K -coloring of G and an orientation with maximum in-degree $K - 1$ can be found in linear time.*

Let D be a directed graph, and let D' be a directed graph obtained from D by adding, for every pair of vertices $x, y \in V(D)$,

- the edge xy if D has no edge from x to y and there exists a vertex $z \in V(D)$ such that D has an edge oriented from x to z and an edge oriented from z to y (*transitivity*), and
- either the edge xy or the edge yx if x is not adjacent to y and there exists a vertex z such that D has an edge oriented from x to z and an edge oriented from y to z (*fraternity*).

We call D' an *oriented augmentation* of D and the underlying undirected graph of D' the *augmentation* of D . The following is a result of Nešetřil and Ossona de Mendez [20, Lemma 5.2]. A self-contained proof may be found in [6].

Theorem 7. *There exist polynomials f_0, f_1, f_2, \dots with the following property. Let D be an orientation of an undirected graph G , let D have maximum in-degree at most Δ , and let G' be the augmentation of D . Then $\nabla_r(G') \leq f_r(\nabla_{2r+1}(G), \Delta)$ for all $r \geq 0$.*

Let G be a graph. Consider the following sequence of directed graphs: Let D_0 be an orientation of G with maximum in-degree at most $2\nabla_0(G) + 2$ and assume that we have constructed D_0, D_1, \dots, D_{k-1} . (An alert reader may be wondering why we added the extra factor of $+2$ to the bound on the in-degree. The reason for that will become clear in the proof of Lemma 18.) Let G_k be the augmentation of D_{k-1} , and let D_k be an oriented augmentation of D_{k-1} chosen in such a way that the maximum in-degree of the subgraph formed by the edges added according to the fraternity rule is at most $2\nabla_0(G_k)$. This is possible, because G_k itself has an orientation with maximum in-degree at most $2\nabla_0(G_k)$. We say that G_k is a *k-th augmentation* of G . If D_{k-1} has in-degree at most Δ , then D_k has in-degree at most $\Delta + \Delta^2 + 2\nabla_0(G_k)$, and Theorem 7 implies that $\nabla_r(G_k) \leq f_r(\nabla_{2r+1}(G_{k-1}), \Delta)$ for all $r \geq 0$. Thus we arrive at the following result of Nešetřil and Ossona de Mendez.

Theorem 8. *Let \mathcal{G} be a class of graphs, let $k \geq 0$ be an integer, and let \mathcal{G}_k be the class of all k -th augmentations of members of \mathcal{G} .*

- (i) *If \mathcal{G} has bounded expansion, then \mathcal{G}_k has bounded expansion.*
- (ii) *If \mathcal{G} is nowhere dense, then \mathcal{G}_k is nowhere dense.*

Please note that statement (ii) above needs that the functions f_0, f_1, \dots referenced in Theorem 7 are polynomials. It also follows that if G belongs to a class of graphs of bounded expansion, then D_1, D_2, \dots, D_k and G_k can be found in linear time. We state that as a lemma for future reference.

Lemma 9. *For every class \mathcal{G} of graphs of bounded expansion and for every fixed integer k there exists a linear-time algorithm that computes a k -th augmentation of $G \in \mathcal{G}$ and the directed graphs D_1, D_2, \dots, D_k as in the definition of k -th augmentation.*

For nowhere dense graphs we have the following analogue.

Lemma 10. *For every nowhere dense class \mathcal{G} of graphs and for every fixed integer k there exists an almost linear-time algorithm that computes a k -th augmentation of $G \in \mathcal{G}$ and the directed graphs D_1, D_2, \dots, D_k as in the definition of k -th augmentation.*

An *out-branching* is a rooted directed tree where every edge is directed away from the root. A *rooted forest* F is a directed graph such that every weak component is an out-branching (recall that a weak component of a directed graph is any minimal subgraph with no incoming or outgoing edge). A *subforest* of F is a subgraph F' of F such that if v is a vertex included in F' , then the path between the root of the tree of F containing v and the vertex v is also contained in F' . The *depth of a vertex v* of a rooted forest F is the number of vertices on the path from the root of the tree containing v to the vertex v . The *depth of a rooted forest F* is the maximum depth of a vertex of F . Finally, if F is a rooted forest F , then the *subtree* of a vertex v is the subgraph of F induced by all vertices reachable from v .

The *closure* of a rooted forest F is the undirected graph with vertex-set $V(F)$ and edge-set all pairs of distinct vertices joined by a directed path in F . The *tree-depth* of an (undirected) graph G is the smallest integer s such that G is a subgraph of the closure of a rooted forest of depth s . For an integer $d \geq 1$ a vertex coloring of a graph G is a *low tree-depth coloring of order d* if for every $s = 1, 2, \dots, d$ the union of any s color classes induces a subgraph of G of tree-depth at most s . In particular, every low tree-depth coloring of order d of G is a proper coloring of G . If $s \in \{1, 2, \dots, d\}$ and H is the subgraph of G induced by s color classes, then there exists a rooted forest F of depth at most s such that H is a subgraph of the closure of F . If for all s and all subgraphs H as above the forest F can be chosen in such a way that its closure is a subgraph of some fixed graph G' , then we say that the low tree-depth coloring is *G' -compliant*, and we refer to the corresponding forests F as *depth-certifying forests*.

The following theorem follows from [20, Lemma 6.2]. In the interest of clarity we give a proof.

Theorem 11. *Let G be a graph, let d be an integer, let $k := 3(d+1)^2$, let G' be a k -th augmentation of G , and let c be a proper coloring of G' . Then c is a G' -compliant low tree-depth coloring of G of order d .*

Proof. Let $s \in \{1, 2, \dots, d\}$ and let H' be a subgraph of G induced by the union of s color classes of the coloring c . If H' has tree-depth at least $s + 1$, then let H be a subgraph of H' of tree-depth exactly $s + 1$; otherwise, let $H := H'$. Since H is s -colorable, it does not have a complete subgraph on $s + 1$ vertices. By [6, Lemma 2] applied to every component of H and taking both d and p in that lemma to be $s + 1$ we deduce that H has tree-depth at most s and that it has a depth-certifying forest whose closure is a subgraph of G' . Thus $H = H'$, and the lemma follows. \square

In fact, it follows from the proof that the depth-certifying forests can be found in linear-time, formally as follows.

Theorem 12. *Let $d \geq 1$ be an integer, and let $k := 3(d + 1)^2$. There exists an algorithm with the following specifications:*

Input: *An integer $s \in \{1, 2, \dots, d\}$, a graph G and directed graphs D_0, D_1, \dots, D_k as in the definition of k -th augmentation, a proper coloring c of the underlying undirected graph G' of D_k (so that G' is a k -th augmentation of G), and a subgraph H of G' that is the union of s color classes of c .*

Output: *A rooted forest F of depth at most s such that H is a subgraph of the closure of F and the closure of F is a subgraph of G' .*

Running time: $O(|V(G')| + |E(G')|)$.

3 Deciding FO properties in linear time

In this section, we prove Theorem 3. We start with a lemma which allows us to remove quantifiers from an FO formula (Lemma 17). However, we need more definitions. Let L be a language and let X be a set of L -terms. An X -*template* T is a rooted forest with vertex set $V(T)$ equipped with a mapping $\alpha_T : X \rightarrow V(T)$ such that $\alpha_T^{-1}(w) \neq \emptyset$ for every vertex w of T with no descendants. If φ is a quantifier-free L -formula, then a φ -*template* is an X -template where X is the set of all terms appearing in φ . Two X -templates T and T' are isomorphic if there exists a bijection $f : V(T) \rightarrow V(T')$ such that

- f is an isomorphism of T and T' as rooted forests; in particular, w is a root of T if and only if $f(w)$ is a root of T' , and
- $f(\alpha_T(t)) = \alpha_{T'}(t)$ for every L -term $t \in X$.

The number of non-isomorphic X -templates of a given depth is finite, as stated in the next proposition. The proof is straightforward and is left to the reader.

Proposition 13. *For every finite set of terms X and every integer d , there exists an integer K such that there are at most K non-isomorphic X -templates of depth at most d .*

Let L be a language and let X be a set of L -terms with variables $\{x_1, \dots, x_n\}$. An *embedding* of an X -template T in a rooted forest F is a mapping $\nu : V(T) \rightarrow$

$V(F)$ such that $\nu(r)$ is a root of F for every root r of T and ν is an isomorphism of T and the subforest of F with vertex set $\nu(V(T))$. Let S be an L -structure guarded by the closure of F , and $v_1, \dots, v_n \in V(S)$. We say that the embedding ν is (v_1, \dots, v_n) -admissible for S if for every term $t(x_1, \dots, x_n) \in X$, we have $\nu(\alpha_T(t)) = t(v_1, \dots, v_n)$, where $t(v_1, \dots, v_n)$ denotes the element of $V(S)$ obtained by substituting v_i for x_i in the term t and evaluating the interpretations in S of the function symbols in the term t (in particular, if $x_i \in X$, then $\nu(\alpha_T(x_i)) = v_i$). We say that the elements v_1, v_2, \dots, v_n (in the order listed) are *compatible with T, F and S* if there exists a (v_1, \dots, v_n) -admissible embedding of T in F for S . We will need the following lemma.

Lemma 14. *Let $d \geq 1$ be an integer, let F be a rooted forest of depth at most d , let L be a language, let $\varphi(x_1, \dots, x_n)$ be a quantifier-free L -formula, let S be an L -structure guarded by the closure of F , and let $v_1, \dots, v_n \in V(S)$. Then there exists a φ -template T of depth at most d such that v_1, \dots, v_n are compatible with T, F and S .*

Proof. Let X be the set of all L -terms that appear in φ , and let Y be the set of all evaluations $t(v_1, \dots, v_n)$ of all terms $t(x_1, \dots, x_n)$ from X . Let T be the smallest subforest of F that includes all vertices from Y and the root of every component of F that includes an element of Y . For a term $t(x_1, \dots, x_n)$ in X let $\alpha_T(t) := t(v_1, \dots, v_n)$, and let ν be the identity mapping $V(T) \rightarrow V(F)$. Then T is a φ -template and ν is a (v_1, \dots, v_n) -admissible embedding of T in F for S , as desired. \square

We remark that in the previous lemma T and ν are unique. If F is a rooted forest, then a function $p : V(F) \rightarrow V(F)$ is the F -parent function if $p(v)$ is the parent of v unless v is a root of F ; if v is a root of F , $p(v)$ is set to be equal to v .

We now show that it can be tested by a quantifier-free formula whether there exists an admissible embedding.

Lemma 15 (Testing admissibility). *Let L be a language that includes a function symbol p and let X be a finite set of L -terms with variables x_1, \dots, x_n . If T is an X -template, then there exists a quantifier-free formula $\xi_T(x_1, \dots, x_n)$ such that for every rooted forest F and every L -structure S guarded by the closure of F such that the interpretation p^S of p in S is the F -parent function, and for every n -tuple $v_1, \dots, v_n \in V(S)$, the L -structure S satisfies $\xi_T(v_1, \dots, v_n)$ if and only if v_1, \dots, v_n are compatible with T, F and S .*

Proof. Let $q : V(T) \rightarrow V(T)$ be the T -parent function, and let d be the depth of T . Set $\xi_T(x_1, \dots, x_n)$ to be the conjunction of all formulas

- $p^k(t) = p^{k'}(t')$ if $q^k(\alpha_T(t)) = q^{k'}(\alpha_T(t'))$, and
- $p^k(t) \neq p^{k'}(t')$ if $q^k(\alpha_T(t)) \neq q^{k'}(\alpha_T(t'))$,

for all pairs of not necessarily distinct terms $t, t' \in X$ and all pairs of integers k and k' , $0 \leq k, k' \leq d+1$ (note that including the formulas with $t = t'$ allows for testing the depth of t in F). Here p^k denotes the function p iterated k times.

It is straightforward to show that for $v_1, \dots, v_n \in V(S)$, a (v_1, \dots, v_n) -admissible embedding for S of T in F exists if and only if $S \models \xi_T(v_1, \dots, v_n)$. \square

The following lemma is the core of our algorithmic arguments as it allows replacing an existentially quantified subformula with a quantifier-free formula. Recall that an L -term is simple if it is a variable or a function image of a variable, and an L -formula is simple if all terms appearing in it are simple.

Lemma 16. *Let $d \geq 0$ be an integer, L a language, $\varphi(x_0, \dots, x_n)$ a simple quantifier-free L -formula that is a conjunction of atomic formulas and their negations, and T a φ -template. There exist a language \bar{L} that extends L and a (not necessarily simple) quantifier-free \bar{L} -formula $\bar{\varphi}_T(x_1, \dots, x_n)$ such that the following holds:*

- \bar{L} is obtained from L by adding a function symbol p and finitely many relation symbols U_0, \dots, U_K of arity at most one, and
- for every rooted forest F of depth at most d and every L -structure S guarded by the closure of F , there exists an \bar{L} -structure \bar{S} such that \bar{S} is an expansion of S , $p^{\bar{S}}$ is the F -parent function and the relations $U_0^{\bar{S}}, \dots, U_K^{\bar{S}}$ can be computed (by listing the singletons they contain) in linear time given F and S , and for all $v_1, \dots, v_n \in V(S)$

$\bar{S} \models \bar{\varphi}_T(v_1, \dots, v_n)$ if and only if $S \models \varphi(v_0, v_1, \dots, v_n)$ for some $v_0 \in V(S)$ such that v_0, v_1, \dots, v_n are compatible with T, F and S .

Proof. Let T be a φ -template of depth at most d , let q be the T -parent function, and let X be the set of all terms appearing in φ . Let ξ_T be the formula from Lemma 15 applied to the language obtained from L by adding the function symbol p . We will have to distinguish two cases depending on whether the following condition is satisfied:

- (1) *The tree of T containing the vertex $\alpha_T(x_0)$ also contains an α_T -image of a term in which another variable appears.*

Let K be an integer such that every vertex of T has at most K children and T has at most K weak components, and let \bar{L} be obtained from L by adding a function symbol p and relation symbols U_0, \dots, U_K . If (1) holds, then U_0, \dots, U_K will have arity one; otherwise U_0 will have arity one and U_1, \dots, U_K will have arity zero. The construction of $\bar{\varphi}_T(x_1, \dots, x_n)$ will proceed in several steps.

Let $t = f(x_i)$ be an L -term appearing in φ , for some function symbol $f \in L^f$ and a variable x_i with $0 \leq i \leq n$. (Since φ is simple, every L -term appearing in φ is either a variable or of this form.) If $\alpha_T(t)$ is neither an ancestor nor a

descendant of $\alpha_T(x_i)$, then for every rooted forest F of depth at most d , every L -structure S guarded by the closure of F and every choice of $v_1, \dots, v_n \in V(S)$, there is no (v_0, \dots, v_n) -admissible embedding for S of T into F , because v_i and $f^S(v_i)$ are adjacent in the Gaifman graph of S ; in particular, one is a descendant of the other in F . Hence, if we set $\bar{\varphi}_T$ to \perp , then $\bar{\varphi}_T$ satisfies the conclusion of the lemma. Since φ is simple, we may assume the following:

- (2) *If the variable x_i appears in a term $t \in X$, then $\alpha_T(t)$ is an ancestor or a descendant of $\alpha_T(x_i)$.*

Assume now that $\alpha_T(x_0)$ is an ancestor of a vertex $\alpha_T(t)$, say $q^k(\alpha_T(t)) = \alpha_T(x_0)$ for $k \geq 0$, where $t \in X$ is an L -term such that x_0 does not appear in t . In that case let $\bar{\varphi}_T$ be the formula obtained from $\varphi \wedge \xi_T$ by replacing each x_0 with the term $p^k(t)$. Clearly, for every \bar{L} -structure \bar{S} that is an expansion of S we have $\bar{S} \models \bar{\varphi}_T(v_1, \dots, v_n)$ if and only if there is a choice of v_0 in $V(F)$ such that $S \models \varphi(v_0, \dots, v_n)$ and v_0, \dots, v_n are compatible with T, F and S . Since φ is simple, we may assume the following:

- (3) *Every L -term $t \in X$ such that $\alpha_T(t)$ is contained in the subtree of $\alpha_T(x_0)$ is x_0 or a function image of x_0 .*

We now define an auxiliary formula φ' to be the formula obtained from φ by replacing all atomic formulas of the form:

- $t = t'$, where t and t' are terms such that $\alpha_T(t) \neq \alpha_T(t')$, and
- $R(t_1, \dots, t_m)$ such that $\alpha_T(t_1), \dots, \alpha_T(t_m)$ are not the vertices of a clique in the closure of T ,

by \perp .

- (4) *Let S be an L -structure guarded by the closure of a rooted forest F , and assume that there exists a (v_0, \dots, v_n) -admissible embedding ν of T in F for S . Then $S \models \varphi(v_0, \dots, v_n)$ if and only if $S \models \varphi'(v_0, \dots, v_n)$.*

We notice that, by the existence of ν , the atomic formulas that got replaced by the definition of φ' are not satisfied by S . This proves (4).

We will now complete the proof under the assumption that (1) holds. Let v be the nearest ancestor of $\alpha_T(x_0)$ in T such that there exists a term $t_v \in X$ such that x_0 does not appear in t_v and v is an ancestor of $\alpha_T(t_v)$. Note that $v \neq \alpha_T(x_0)$ by (3). Let d_v be the depth of v in T , d_{x_0} the depth of $\alpha_T(x_0)$ and m the number of children of v in T . Let t_1, \dots, t_{m-1} be terms such that $\alpha_T(t_i)$, $1 \leq i \leq m-1$, are vertices of different subtrees rooted at a child of v and not containing $\alpha_T(x_0)$. Observe that the variable x_0 does not appear in t_1, \dots, t_{m-1} by (2).

Let X_0 be the subset of X consisting of the terms mapped by α_T to a vertex of the unique subtree of T that is rooted at a child of v and includes $\alpha_T(x_0)$. Note that all terms in X_0 contain x_0 by (3) and the choice of v . Let T_0 be the template obtained from T by taking the minimal rooted subtree containing $\alpha_T(X_0)$ and the root of the tree containing $\alpha_T(x_0)$, and restricting the function α_T to the terms containing x_0 . Further, let X'_0 be the subset of X consisting of the terms t such that $\alpha_T(t)$ lies on the path of T from a root to v . Observe that the construction of φ' implies that

- (5) *if a term from X_0 appears in an atomic formula of φ' , then every term that appears in that atomic formula belongs to $X_0 \cup X'_0$.*

Let $\varphi''(x_1, x_2, \dots, x_n)$ be the formula obtained from φ' by removing atomic formulas containing at least one term from X_0 and replacing each term $t \in X'_0$ containing x_0 with $p^k(t_v)$, where k is the integer such that $\alpha_T(t) = q^k(\alpha_T(t_v))$. It follows from (2) that the variable x_0 does not appear in φ'' . Let T' be the template obtained from T by taking the minimal subforest containing all the terms without x_0 and restricting the function α_T to such terms. The formula $\overline{\varphi}_T$ will then be the conjunction of the following formulas:

- (a) the formula $\varphi''(x_1, \dots, x_n)$,
- (b) the formula $\xi_{T'}$ from Lemma 15 applied to the template T' , the language \overline{L} and the set of \overline{L} -terms $X \setminus X_0$, and
- (c) the formulas

$$\neg \left(\bigwedge_{i \in Y} U_0(p^{k_i-1}(t_i)) \right) \vee U_{|Y|+1}(p^k(t_v))$$

for all subsets Y of the set $\{1, \dots, m-1\}$ where k is the integer such that $q^k(\alpha_T(t_v)) = v$ and k_i , $i = 1, \dots, m-1$, are the integers such that $q^{k_i}(\alpha_T(t_i)) = v$ (we note here that a conjunction over an empty set is true by convention).

This completes the definition of $\overline{\varphi}_T$.

Let F be a rooted forest of depth at most d , and let S be an L -structure guarded by the closure of F . We need to define an \overline{L} -structure \overline{S} such that \overline{S} is an expansion of S and $p^{\overline{S}}$ is the F -parent function. To do so we need to define the interpretations $U_0^{\overline{S}}, U_1^{\overline{S}}, \dots, U_K^{\overline{S}}$.

We define the unary relation $U_0^{\overline{S}}(w)$ to be the set of elements w of F at depth $d_v + 1$ such that the subtree of w in F contains an element v_0 at depth d_{x_0} (in F) with the following properties:

- there is a (v_0) -admissible embedding of the template T_0 in F for S , and

- all atomic formulas and their negations from the conjunction φ' that have at least one term from X_0 are true with $x_0 = v_0$ and the terms $t \in X'_0$, say $\alpha_T(t) = q^k(\alpha_T(x_0))$, replaced with $(p^{\bar{S}})^k(v_0)$.

The relation $U_0^{\bar{S}}(w)$ can be computed as follows: for every element $v_0 \in V(S)$ at depth d_{x_0} of F , evaluate all terms in X_0 by substituting v_0 for x_0 and testing whether the tree T_0 and the rooted subtree of F containing the values of the terms are isomorphic as rooted trees (this can be done in time linear in the size of T_0 which is constant). If they are isomorphic, evaluate the atomic formulas in the conjunction φ' with at least one term from X_0 with the terms in X'_0 replaced with $(p^{\bar{S}})^k(v_0)$. If each of them appearing non-negated in φ' is true and each appearing in a negation is false, add the ancestor w of v_0 at depth $d_v + 1$ in F to U_0 (note that w and v_0 coincide if their depths are the same). This produces a valid result by (5). Since the time spent by checking every vertex v_0 at depth d_{x_0} of F is constant, the time needed to compute $U_0^{\bar{S}}$ is linear.

For $i = 1, 2, \dots, K$ we define the unary relation $U_i^{\bar{S}}(w)$ to be the set of elements w of F at depth d_v such that $U_0^{\bar{S}}(w')$ is true for at least i children w' of w . Clearly, the relations $U_i^{\bar{S}}(w)$, $1 \leq i \leq K$, can be computed in linear time when the relation $U_0^{\bar{S}}$ has been determined.

We now verify that the formula $\bar{\varphi}_T$ has the desired properties. Let $v_1, v_2, \dots, v_n \in V(S)$. Suppose first that $\bar{S} \models \bar{\varphi}_T(v_1, \dots, v_n)$. Thus \bar{S} satisfies the formulas listed in (a)–(c) above. Since $\bar{S} \models \xi_{T'}(v_1, v_2, \dots, v_n)$ there exists a (v_1, \dots, v_n) -admissible embedding ν' of T' in F for \bar{S} . Let Y be the set of all integers $i \in \{1, 2, \dots, m-1\}$ such that $U_0^{\bar{S}}(\nu'(\alpha_{T'}(p^{k_i-1}(t_i))))$ holds, where k_i is as in (c) above. Since \bar{S} satisfies the formula in (c) corresponding to the set Y we deduce that the vertex $\nu'(v)$ has a son w such that $U_0^{\bar{S}}(w)$ is true and the subtree of F rooted in w does not contain the value of any term in $X \setminus X_0$. In particular, the subtree rooted in w contains a vertex v_0 such that ν' can be extended to a (v_0, \dots, v_n) -admissible embedding of T in F for S and all atomic formulas in the conjunction φ' containing a term from X_0 are satisfied with $x_0 = v_0$. The atomic formulas of φ' not containing a term from X_0 appear in φ'' and they are satisfied by S since $\bar{S} \models \varphi''(v_1, \dots, v_n)$. Thus $S \models \varphi'(v_0, v_1, \dots, v_n)$, and hence $S \models \varphi(v_0, v_1, \dots, v_n)$ by (4).

On the other hand, assume that there exists $v_0 \in V(S)$ such that $S \models \varphi(v_0, \dots, v_n)$ and there exists a (v_0, \dots, v_n) -admissible embedding ν of T into F for S . From (4) it follows that $S \models \varphi'(v_0, \dots, v_n)$, and hence $\bar{S} \models \varphi''(v_1, \dots, v_n)$. The restriction of ν to T' shows that $\bar{S} \models \xi_{T'}(v_1, \dots, v_n)$. Let w be the son of $\nu(v)$ whose subtree contains v_0 . It follows that $U_0^{\bar{S}}(w)$. The existence of w shows that the formulas listed in item (c) are satisfied by \bar{S} . Thus \bar{S} satisfies all formulas in (a)–(c), and hence it follows that $\bar{S} \models \bar{\varphi}_T(v_1, \dots, v_n)$. This completes the proof under the assumption that (1) holds.

The complementary case when (1) does not hold is handled similarly. In this case, the predicate $U_0^{\bar{S}}$ is defined for the roots of the trees of F , and the nullary predicates $U_1^{\bar{S}}, \dots, U_K^{\bar{S}}$ are such that $U_i^{\bar{S}}$ is true if $U_0^{\bar{S}}(r)$ is satisfied

for at least i roots r of the trees in F . □

We now prove a lemma that forms the core of our first algorithm.

Lemma 17 (Quantifier elimination lemma). *Let $d \geq 0$ be an integer, L a language and $\varphi(x_1, \dots, x_n)$ a simple L -formula of the form $\exists x_0 \varphi'(x_0, \dots, x_n)$ such that $\varphi'(x_0, \dots, x_n)$ is a quantifier-free L -formula with free variables x_0, \dots, x_n . There exist a language \overline{L} and a quantifier-free (not necessarily simple) \overline{L} -formula $\overline{\varphi}$ such that the following holds:*

- \overline{L} is obtained from L by adding a function symbol p and finitely many relation symbols of arity one, and
- for every rooted forest F of depth at most d and every L -structure S guarded by the closure of F , there exists an \overline{L} -structure \overline{S} such that \overline{S} is an expansion of S and for every $v_1, \dots, v_n \in V(S)$,

$$S \models \varphi(v_1, \dots, v_n) \text{ if and only if } \overline{S} \models \overline{\varphi}(v_1, \dots, v_n)$$

where $p^{\overline{S}}$ is the F -parent function and the interpretations in \overline{S} of the new relation symbols can be computed (by listing the singletons they contain) in linear time given F and S .

Proof. Let d , L and φ' be fixed. We assume without loss of generality that the formula φ' is in the disjunctive normal form and all the variables x_0, \dots, x_n appear in φ' . Let F be a rooted forest of depth at most d , and let S be an L -structure.

The proof proceeds by induction on the length of φ' . If φ' is a disjunction of two or more conjunctions, i.e., $\varphi' = \varphi_1 \vee \varphi_2$, we apply induction to the formulas $\exists x_0 \varphi_1$ and $\exists x_0 \varphi_2$. We obtain languages L_1 and L_2 , and for $i = 1, 2$ an L_i -formula $\overline{\varphi}_i$ and an L_i -structure \overline{S}_i . We assume that the new unary relation symbols of L_1 and L_2 are distinct and set $\overline{L}^r = L_1^r \cup L_2^r$, $\overline{L}^f = L_1^f = L_2^f = L^f \cup \{p\}$ and $\overline{\varphi} = \overline{\varphi}_1 \vee \overline{\varphi}_2$. We define the \overline{L} -structure \overline{S} by $V(\overline{S}) = V(S)$ and by taking the interpretations of symbols from \overline{S}_1 and \overline{S}_2 .

Thus in the remainder of the proof we may assume that φ' is a conjunction. Let $v_1, v_2, \dots, v_n \in V(S)$. By Lemma 14 we have $S \models \varphi(v_1, \dots, v_n)$ if and only if there exist $v_0 \in V(S)$ and a φ' -template T of depth at most d such that $S \models \varphi'(v_0, \dots, v_n)$ and there exists an embedding of T into F that is (v_0, \dots, v_n) -admissible for S . By Proposition 13 the number of φ' -templates of depth at most d is bounded by a function of φ and d . By Lemma 16, for every φ' -template T of depth at most d , there exist a language L_T , a quantifier-free L_T -formula φ_T and an L_T -structure S_T that is an expansion of S such that for every $v_1, \dots, v_n \in V(S)$, $S_T \models \varphi_T(v_1, \dots, v_n)$ if and only if there exists v_0 such that there is a (v_0, v_1, \dots, v_n) -admissible embedding of T in F for S and $S \models \varphi'(v_0, v_1, \dots, v_n)$. We may assume that for distinct φ' -templates T and T' , if a function or a relation symbol belongs both L_T and $L_{T'}$, then it belongs to L . Let \overline{L} be the language consisting of all function and relation symbols of all L_T ,

let the formula $\overline{\varphi}$ be obtained as the disjunction of the \overline{L} -formulas $\overline{\varphi}_T$, where the disjunction runs over all choices of φ' -templates T , and let the \overline{L} -structure $\overline{\mathcal{S}}$ be obtained by taking the union of the interpretations of all S_T . Then \overline{L} , $\overline{\varphi}$ and $\overline{\mathcal{S}}$ are as desired. \square

In order to apply Lemma 17, the given formula needs to be simple but the lemma produces a formula that need not be simple. The following lemma copes with this issue.

Lemma 18. *Let \mathcal{G} be a class of graphs of bounded expansion, L a language and $\varphi(x_1, \dots, x_n)$ an L -formula with q quantifiers. There exist a class \mathcal{G}' of graphs of bounded expansion, a language L' that extends L , and a simple L' -formula $\varphi'(x_1, \dots, x_n)$ with q quantifiers with the following properties. For every L -structure A guarded by a graph $G \in \mathcal{G}$, there exists an L' -structure A' guarded by a graph $G' \in \mathcal{G}'$ such that $V(G) = V(G')$, A' is an expansion of A and $A \models \varphi(v_1, \dots, v_n)$ if and only if $A' \models \varphi'(v_1, \dots, v_n)$ for any $v_1, \dots, v_n \in V(A) = V(A')$. Moreover, an L' -structure A' and graph G' satisfying the above specifications can be computed in time $O(|V(G)|)$.*

Proof. We may assume that φ is not simple, for otherwise there is nothing to prove. Let f and g be function symbols of L such that the L -term $g(f(t))$ appears in φ for some L -term t . Let \mathcal{G}_1 be the class of all first augmentations of members of \mathcal{G} ; then \mathcal{G}_1 has bounded expansion by Theorem 8. Let L_1 be the extension of L obtained by adding a new function symbol h , and for an L -structure A we define an L_1 -structure A_1 as the expansion of A , where the interpretation of h is defined by $h^{A_1}(v) = g^A(f^A(v))$ for all $v \in V(A)$. Let φ_1 be obtained from φ by replacing all appearances of $g(f(t))$ by $h(t)$. Then clearly $A \models \varphi(v_1, \dots, v_n)$ if and only if $A_1 \models \varphi_1(v_1, \dots, v_n)$ for all $v_1, \dots, v_n \in V(A) = V(A_1)$. Let D' be an orientation of G of maximum in-degree $2\nabla_0(G)$, and let D be obtained from D' by adding all directed edges with head v and tail $f^A(v)$ and all directed edges with head v and tail $g^A(v)$. Since the orientation D' can be obtained in a greedy way, this step can be performed in time $O(|V(G)| + |E(G)|) = O(|V(G)|)$. Let G_1 be the augmentation of D . Then G_1 is a first augmentation of G (here we make use of the term “+2” in the definition of an augmentation) and A_1 is guarded by G_1 . By repeating this construction at most k times, where k is the maximum number of function compositions appearing in φ , we arrive at a desired formula φ' . Since each step requires linear time, the total running time is linear, as desired. \square

We are now ready to prove Theorem 3; we prove it in a stronger form needed in Section 4.

Theorem 19. *Let \mathcal{G} be a class of graphs with bounded expansion, L a language and $\varphi(x_1, \dots, x_n)$ an L -formula. There exist a language \overline{L} , class $\overline{\mathcal{G}}$ of graphs with bounded expansion, a quantifier-free \overline{L} -formula $\overline{\varphi}(x_1, \dots, x_n)$ and an algorithm \mathcal{A} such that the following holds. Given an L -structure A guarded by a graph $G \in \mathcal{G}$ the algorithm \mathcal{A} finds a graph $\overline{G} \in \overline{\mathcal{G}}$ with $V(G) = V(\overline{G})$ and an*

\bar{L} -structure \bar{A} guarded by \bar{G} such that $V(\bar{A}) = V(A)$ and for all $v_1, \dots, v_n \in V(A) = V(\bar{A})$

$$A \models \varphi(v_1, \dots, v_n) \text{ if and only if } \bar{A} \models \bar{\varphi}(v_1, \dots, v_n).$$

The running time of the algorithm \mathcal{A} is $O(|V(G)|)$. In particular, if $n = 0$, the algorithm decides whether $A \models \varphi$.

Proof. It suffices to show the existence of \bar{L} , \bar{G} , $\bar{\varphi}$ and \mathcal{A} satisfying the specifications of the theorem, except that rather than being quantifier-free, $\bar{\varphi}$ has one fewer quantifier than φ . A proof of the theorem is then obtained by iterating this argument.

If φ is quantifier-free, then there is nothing to prove. Hence, we may and will assume that φ contains at least one quantifier. By Lemma 18 we may assume that φ is simple.

Since $\forall x \psi$ is equivalent to $\neg \exists x \neg \psi$, we can assume that φ contains a subformula $\xi(x_1, x_2, \dots, x_N)$ of the form $\exists x_0 \psi(x_0, x_1, \dots, x_N)$, where ψ is a formula with variables x_0, x_1, \dots, x_N and with no quantifiers. We will define a desired formula by replacing the subformula ξ of φ by a different formula.

Let X be the set of all L -terms that appear in ξ , let $k := 3(|X|^2 + 1)^2$, and let $\bar{\mathcal{G}}$ be the class of all k -th augmentations of members of \mathcal{G} . By Theorem 8 the class $\bar{\mathcal{G}}$ has bounded expansion. By Lemma 6 there exists an integer K such that every member of $\bar{\mathcal{G}}$ is K -colorable. Let L' be the language obtained from L by adding K unary relation symbols C_1, C_2, \dots, C_K , and for each function symbol f of L another K unary relation symbols $C_{f,1}, C_{f,2}, \dots, C_{f,K}$. (Their interpretations in a structure A will be used to encode a given K -coloring of the graph guarding A .) Let Λ be the set of all mappings $X \rightarrow \{1, 2, \dots, K\}$, and let $\alpha \in \Lambda$. For a term $t \in X$ of the form x_i let $E_t := C_{\alpha(t)}(t)$, and for $t \in X$ of the form $f(x_i)$ let $E_t := C_{f, \alpha(t)}(x_i)$. Let φ_α denote the L' -formula $\bigwedge_{t \in X} E_t$, and let $\xi_\alpha(x_1, x_2, \dots, x_N)$ denote the formula $\exists x_0 (\psi(x_0, x_1, \dots, x_N) \wedge \varphi_\alpha(x_0, x_1, \dots, x_N))$. Let \bar{L}_α and $\bar{\xi}_\alpha$ be a language and a formula obtained by applying Lemma 17 to the language L' and the formula ξ_α . Finally, let \bar{L} be the language obtained by taking the union of all function and relation symbols of L and all the languages \bar{L}_α , and let $\bar{\varphi}$ be the \bar{L} -formula obtained from φ by replacing the subformula ξ of φ by the disjunction of $\bar{\xi}_\alpha$ over all $\alpha \in \Lambda$. We will show that $\bar{\varphi}$ is as desired.

To prove this let $G \in \mathcal{G}$, let A be an L -structure guarded by G , let $\bar{G} \in \bar{\mathcal{G}}$ be a k -th augmentation of G , let D_1, D_2, \dots, D_k be as in the definition of k -th augmentation, and let c be a K -coloring of \bar{G} . The coloring c exists by our choice of K , and $\bar{G}, D_1, D_2, \dots, D_k$ and c can be computed in linear time by Lemmas 6 and 9. Let A' be the L' -structure defined by saying that it is an expansion of A , that $C_i^{A'}$ consists of all $v \in V(A')$ such that $c(v) = i$, and that $C_{f,i}^{A'}$ consists of all $v \in V(A')$ such that $c(f^{A'}(v)) = i$.

- (1) For all $v_1, v_2, \dots, v_N \in V(A)$ we have $A \models \xi(v_1, v_2, \dots, v_N)$ if and only if there exists $\alpha \in \Lambda$ such that $A' \models \xi_\alpha(v_1, v_2, \dots, v_N)$.

To prove (1) we note that the “if” part is clear. To prove the “only if” part let $A \models \xi(v_1, v_2, \dots, v_N)$. Thus there exists $v_0 \in V(A)$ such that $A \models \psi(v_0, v_1, \dots, v_N)$. Let $t \in X$. If t is a variable x_i , then let $\alpha(t) := c(v_i)$, and if t is of the form $f(x_i)$ for a function symbol f , then let $\alpha(t) := c(f^A(v_i))$. Then $A' \models \xi_\alpha(v_1, v_2, \dots, v_N)$, as desired. This proves (1).

For $\alpha \in \Lambda$ let A_α be an L' -structure defined as follows. We let $V(A_\alpha)$ be the set of all $v \in V(A)$ such that $c(v) \in \alpha(X)$. For a function symbol f in the language L' let $f^{A_\alpha}(v) := f^A(v)$ if both $c(v)$ and $c(f^A(v))$ belong to $\alpha(X)$, and let $f^{A_\alpha}(v) := v$ otherwise. For a relation symbol R in L' of arity l let R^{A_α} be the subset of R^A consisting of all l -tuples whose every element belongs to $\alpha(X)$.

- (2) *For all $\alpha \in \Lambda$ and all $v_1, v_2, \dots, v_N \in V(A)$ we have $A' \models \xi_\alpha(v_1, v_2, \dots, v_N)$ if and only if $A_\alpha \models \xi_\alpha(v_1, v_2, \dots, v_N)$.*

To prove (2) we first notice that $A' \models \varphi_\alpha(v_0, v_1, \dots, v_N)$ and $A_\alpha \models \varphi_\alpha(v_0, v_1, \dots, v_N)$ are both equivalent to $c(v_i) \in \alpha(x_i)$ for every L -term in X of the form x_i and $c(f^{A'}(v_i)) = \alpha(f(x_i))$ for every L -term in X of the form $f(x_i)$, in which case $c(v_i) \in \alpha(X)$ for every L -term in X of the form x_i and $f^{A'}(v_i) = f^{A_\alpha}(v_i)$ and $c(f^{A'}(v_i)) \in \alpha(X)$ for every L -term in X of the form $f(x_i)$. So, $A' \models \varphi_\alpha(v_0, v_1, \dots, v_N)$ if and only if $A_\alpha \models \varphi_\alpha(v_0, v_1, \dots, v_N)$ (note that if $f^{A'}(v_i) \neq f^{A_\alpha}(v_i)$ for some i , then $E_{f(x_i)}$ fails for both A' and A_α). We deduce that (2) holds.

For $\alpha \in \Lambda$ let H_α be the subgraph of G induced by vertices v such that $c(v) \in \alpha(X)$. By Theorem 11 there exists a rooted forest F_α of depth at most $|X|$ such that H_α is a subgraph of the closure of F_α and the closure of F_α is a subgraph of \overline{G} . Thus A_α is guarded by the closure of F_α . By Theorem 12 the rooted forest F_α can be found in linear time, because $|E(G')| = O(|V(G)|)$ by Theorem 7. Let \overline{A}_α be an \overline{L}_α -structure as in Lemma 17 applied to the L' -structure A_α and rooted forest F_α . Then \overline{A}_α is guarded by the closure of F_α and

- (3) *for all $\alpha \in \Lambda$ and all $v_1, v_2, \dots, v_n \in V(A)$ we have $A_\alpha \models \xi_\alpha(v_1, v_2, \dots, v_n)$ if and only if $\overline{A}_\alpha \models \overline{\xi}_\alpha(v_1, v_2, \dots, v_n)$.*

Let \overline{A} be an \overline{L} -structure defined as follows. Let f be a function symbol from \overline{L} . If f belongs to L , then $f^{\overline{A}}(v) := f^A(v)$, and if f belongs to \overline{L}_α , then $f^{\overline{A}}(v) := f^{\overline{A}_\alpha}(v)$. We define the interpretations of relation symbols analogously. Since \overline{A}_α is guarded by the closure of F_α and the closure of F_α is a subgraph of \overline{G} , we deduce that \overline{A} is guarded by \overline{G} .

- (4) *For all $v_1, v_2, \dots, v_n \in V(A)$ we have $\overline{A} \models \overline{\xi}(v_1, v_2, \dots, v_n)$ if and only if there exists $\alpha \in \Lambda$ such that $\overline{A}_\alpha \models \overline{\xi}_\alpha(v_1, v_2, \dots, v_n)$.*

The proof of (4) is clear.

It follows from claims (1)–(4) that \overline{A} is as desired, and the construction shows that it can be computed from G and A in time $O(|V(G)|)$. \square

4 Deciding FO properties in graphs with locally bounded expansion

The following theorem uses a result of Gaifman [15] that FO properties are local in a certain sense. The theorem is implicit in [14] (see also [17]).

Theorem 20. *Let \mathcal{G} be a class of graphs and for an integer $d \geq 0$ let \mathcal{G}_d be the class of graphs consisting of all induced subgraphs of d -neighborhoods of graphs in \mathcal{G} . Let \mathcal{G}_d have bounded expansion for all integers $d \geq 0$. Furthermore, let L be a language and L' the language obtained from L by adding a new binary relation symbol. Suppose that for every d and every L' -formula $\varphi'(x)$, there exists a linear-time algorithm that lists all elements v of an input L' -structure guarded by a graph from \mathcal{G}_d that satisfy $\varphi'(v)$. Then, for every L -sentence φ there exists an almost linear-time algorithm that decides whether an input L -structure guarded by a graph from \mathcal{G} satisfies φ .*

Proof. We show how to modify the proof of [14, Theorem 1.2] to yield a proof of this theorem. The proof of [14, Theorem 1.2] relies on Lemma 4.4, Corollary 6.3, Corollary 8.2 and Lemma 8.3 from the same paper, and those assume that \mathcal{G} has “bounded local tree-width”. In our context Lemma 4.4 would be needed to justify that for every L -formula $\psi(x)$ and every integer $d \geq 0$ there exists a linear-time algorithm that given an L -structure A guarded by a member of \mathcal{G}_d computes the set of all $v \in V(A)$ such that $A \models \psi(v)$. This follows from the hypothesis of the theorem instead. (Here we do not need the extension L' .)

Corollary 6.3 and Corollary 8.2 apply in our setting without any alterations with the same proofs, using the fact that for every fixed integer d every graph $G \in \mathcal{G}_d$ has at most $O(|V(G)|)$ edges by Lemma 6.

Finally, in Lemma 8.3, we need to be able to compute, in linear time for every fixed r , given an L -structure A and $v \in V(A)$, the set of elements of $V(A)$ at distance at most r in the Gaifman graph of A . This can be derived by applying the hypothesis of the theorem to the L' -structure A' , where A' is the expansion of A defined by saying that the interpretation of the new binary relation is adjacency in the Gaifman graph of A . This relation can be computed in linear time. To carry out the last step of the algorithm of Lemma 8.3 we apply Theorem 3. \square

Proof of Corollary 4. Let \mathcal{G} , L and φ be as in Corollary 4, and let \mathcal{G}_d be as in Theorem 20. In particular, the class \mathcal{G}_d has bounded expansion for every d . By Theorem 19, for every integer d and every L' -formula $\varphi'(x)$, there exist a language L'' and a quantifier-free L'' -formula $\varphi''(x)$ such that every L' -structure A guarded by a graph from \mathcal{G}_d can be transformed in linear time to an L'' -structure A' with $V(A) = V(A')$ such that $A \models \varphi'(v)$ if and only if $A' \models \varphi''(v)$ for every $v \in V(A)$. In particular, it is possible to list in linear time all $v \in V(A)$ such that $A' \models \varphi''(v)$ since evaluating the latter formula requires constant time. So, the assumptions of Theorem 20 are satisfied. \square

5 Dynamic data structures for Σ_1 -queries

In this section, we provide two data structures for answering Σ_1 -queries. The update time is constant but the price we have to pay is that the graph that guards the relational structure must be fixed before the computation starts. Before we start our exposition, we need to introduce more definitions.

Let L be a language with no function symbols. For an integer $k \geq 1$, a k -labelled L -structure is a pair (S, σ) , where S is an L -structure and σ is an injective mapping $\text{dom}(\sigma) \rightarrow V(S)$, where $\text{dom}(\sigma) \subseteq \{1, 2, \dots, k-1\}$.

The *trunk* of a k -labelled L -structure (S, σ) is the k -labelled L -structure (S', σ) , where S' is obtained from S by removing all tuples (v_1, \dots, v_t) with $v_1, \dots, v_t \in \text{dom}(\sigma)$ from each relation of S . A k -labelled L -structure (S, σ) is *hollow* if it is equal to its trunk. Two k -labelled L -structures (S_1, σ_1) and (S_2, σ_2) are *k-isomorphic* if $\text{dom}(\sigma_1) = \text{dom}(\sigma_2)$ and their trunks are isomorphic by way of an isomorphism $f : V(S_1) \rightarrow V(S_2)$ such that $\sigma_2(i) = f(\sigma_1(i))$ for every $i \in \text{dom}(\sigma_1)$. In particular, every k -labelled L -structure is k -isomorphic to its trunk.

Suppose now that an L -structure S is guarded by the closure of a rooted tree T . For a vertex v of T at depth d , let $P_T(v)$ denote the vertex-set of the path from the root of T to v and $T\langle v \rangle$ the vertex-set of the subtree of v (including v itself). Then, $S\langle v \rangle$ denotes the set of all d -labelled L -structures (S', σ) such that S' is an induced substructure of S with elements only in $P_T(v) \cup T\langle v \rangle$ and $\text{dom}(\sigma)$ consists of all integers $i \in \{1, 2, \dots, d-1\}$ such that $V(S')$ includes an element at depth i , in which case $\sigma(i)$ is equal to that element.

We are now ready to prove a lemma that contains the core of our data structure.

Lemma 21. *Let L be a language with no function symbols, d_0 a fixed integer and F a rooted forest of depth at most d_0 . There exists a data structure representing an L -structure S guarded by the closure of F such that*

- *the data structure is initialized in linear time,*
- *the data structure representing an L -structure S can be changed to the one representing an L -structure S' by adding or removing a tuple from one of the relations in constant time provided that S' is guarded by the closure of F , and*
- *the data structure decides in time bounded by $O(|\varphi|)$ whether a given Σ_1 - L -sentence φ with at most d_0 variables is satisfied by S , and if so, it outputs one of the satisfying assignments.*

Proof. For every vertex v of F at depth d , we will store the following two lists:

- for every relation symbol R of L the list of all tuples $\tau \in R^S$ such that τ includes v and all elements of τ belong to $P_T(v)$, where T is the tree of F containing v , and

- the list of all (non- d -isomorphic) d -labelled hollow L -structures with at most d_0 elements that are d -isomorphic to a d -labelled L -structure contained in $S\langle v \rangle$.

Since there are only finitely many non- d -isomorphic d -labelled L -structures with at most d_0 elements for every $d \leq d_0$, the length of each list of the second type is bounded by a constant depending only on d_0 and L . If v is a non-leaf vertex of F , there will be a third list associated with v :

- the list of all (non-isomorphic) $(d+1)$ -labelled hollow L -structures (S', σ) with at most d_0 elements that are isomorphic to a member of the second list of at least one child of v ; for each such (S', σ) , there will be stored the list of all children of v whose second list contains a member isomorphic to (S', σ) .

In addition, there will be a global list of all (non-isomorphic) L -structures with at most d_0 elements that appear as induced L -substructures in S .

Let us describe how all these lists are initialized. The initialization of the first type of list is trivial: just put each tuple contained in one of the relations to the list of its element that is farthest from the root. This can clearly be done in constant time per tuple.

Initialization of other types of lists is more difficult. Fix a tree T of F . We proceed from the leaves towards the root of T . Let v be a vertex of T at depth d . If v is a leaf of T at depth d , then the second list of v contains only those hollow d -labelled L -structures (S', σ) with $V(S') \subseteq P_T(v)$ such that if $v \in V(S')$, then S' contains relations with their tuples from S containing v and elements from $V(S')$, and if $v \notin V(S')$, then all relations of S' are empty. This can be done in linear time as for each tuple in every relation one determines whether its element of the largest depth is a leaf and, if so, it includes the tuple to the structures at that leaf.

Suppose now that v is not a leaf of T . The third list associated with v can be initialized by merging the second type of lists of children of v . (This needs time linear in the number of the children, but the sum of the numbers of children of all vertices is linear in $|T|$. This will require linear time for the whole structure since the number of non- d -isomorphic d -labelled hollow L -structures with at most d_0 elements is bounded, and thus the size of each list of the second type is bounded.) We next describe how it can be decided whether a d -labelled hollow L -structure (S', σ) should be contained in the list of v of the second type. Assume that $S\langle v \rangle$ contains a d -labelled hollow L -structure (S'', σ'') that is d -isomorphic to (S', σ) .

Then $V(S'')$ can be decomposed into disjoint subsets V_0, V_1, \dots, V_m such that $V_0 = V(S'') \cap P_T(v)$, each of the sets V_i , $i = 1, \dots, m$, is fully contained in a subtree of a child v_i of v , and different subsets V_1, \dots, V_m are contained in different subtrees. Observe that each tuple of a relation of S'' has its elements in $V_0 \cup V_i$ for some $i = 1, \dots, m$. Moreover, the only tuples in such relations with all elements from V_0 are those that contain v .

Hence, the existence of (S'', σ'') can be tested by considering all partitions of $V(S')$ into disjoint subsets V_0, V_1, \dots, V_m such that $\sigma(\text{dom}(\sigma)) \subseteq V_0$, $|V_0 \setminus \sigma(\text{dom}(\sigma))| \leq 1$, every tuple in a relation of S' has its elements in $V_0 \cup V_i$ for some $i = 1, \dots, m$, and two additional conditions are satisfied. To state those conditions let $i \in \{1, 2, \dots, m\}$ and let us define (S_i, σ_i) to be the $(d+1)$ -labelled hollow L -structure such that S_i is the substructure of S induced by $V_0 \cup V_i$, $\text{dom}(\sigma_i) = \text{dom}(\sigma) \cup \{d\}$ if $V_0 \setminus \sigma(\text{dom}(\sigma)) \neq \emptyset$ and $\text{dom}(\sigma_i) = \text{dom}(\sigma)$ otherwise, $\sigma_i(j) = \sigma(j)$ for every $j \in \text{dom}(\sigma)$ and $\sigma_i(d)$ is the unique element of $V_0 \setminus \sigma(\text{dom}(\sigma))$ if the latter set is not empty. The two remaining conditions are that there exist distinct children v_1, \dots, v_m of v such that the second list of v_i has a member isomorphic to (S_i, σ_i) and that for each relation symbol R of L the tuples in $R^{S'}$ containing $\sigma(d)$ are precisely the tuples listed in the first list for R and v .

We now describe how to test the existence of children v_1, \dots, v_m . Let W be the set of children of v such that for all $i \in \{1, 2, \dots, m\}$: if v has at most m children with their second list containing a $(d+1)$ -labelled hollow L -structure $(d+1)$ -isomorphic to (S_i, σ_i) , then W contains all such children of v (here, we use the lists of the third type). If v has more than m such children, then W contains arbitrary m of these children. Clearly, $|W| \leq m^2 \leq d_0^2$. In order to test the existence of such children v_1, \dots, v_m of v , we form an auxiliary bipartite subgraph B : one part of B is formed by the numbers $1, \dots, m$ and the other part by children of v contained in W . A child $w \in W$ is joined to a number i if the second list of w contains a $(d+1)$ -labelled hollow L -structure $(d+1)$ -isomorphic to (S_i, σ_i) .

If B has a matching of size m , then this matching determines the choice of children v_1, \dots, v_m . On the other hand, if such children exist, B contains a matching of size m : indeed, if $v_i \in W$, then i is matched with v_i , and if $v_i \notin W$, then v has at least m children whose second list contains a $(d+1)$ -labelled hollow L -structure $(d+1)$ -isomorphic to (S_i, σ_i) , in which case i may be matched with one of those children that is not matched with any $i' < i$.

Since the order of B is at most $m^2 + m$ and the number of disjoint non-empty partitions of $V(S')$ to V_0, \dots, V_m is bounded, testing the existence of a d -labelled hollow L -structure S'' can be performed in constant time for v .

It remains to construct the global list containing L -structures S_0 with at most d_0 elements that are isomorphic to an induced substructure of S . We proceed similarly as when determining the lists of inner elements of the forest F . For every L -structure S' with at most d_0 elements, we compute the list of trees of F that contain S' , i.e., S' is contained in the second list of the root of F . Now, S_0 is an induced substructure of S' if and only if there exist element-disjoint L -structures S'_1, \dots, S'_m such that $V(S_0) = V(S'_1) \cup \dots \cup V(S'_m)$ and S'_1, \dots, S'_m appear in m mutually distinct trees of F . For each such partition of S_0 into S'_1, \dots, S'_m , we can test whether S'_1, \dots, S'_m appear in the list of roots of m distinct trees of F using the auxiliary bipartite graph described earlier. Since all structures involved contain at most d_0 elements, this phase requires time linear in the number of trees of F .

We have shown that the data structure can be initialized in linear time. Let

us now focus on updating the structure and answering queries. Consider a tuple (v_1, \dots, v_k) that is added to a relation R^S or removed from a relation R^S . Let r be the root of the tree T in F that contains all the elements v_1, \dots, v_k and assume that v_1, \dots, v_k appear in this order on a path from r . By the definition, the only lists affected by the change are those associated with vertices on the path $P_T(v_k)$. Recomputing each of these lists requires constant time (we proceed in the same way as in the initialization phase except we do not have to run through the children of the vertices on the path to determine which of them contain particular k -labelled hollow L -substructure S' in their lists). Since the number of vertices on the path $P_T(v_k)$ is at most d_0 , updating the data structure requires constant time only.

It remains to describe how queries are answered. Let φ be a Σ_1 -sentence with $d \leq d_0$ variables. We generate all possible L -structures S_0 with $|V(S_0)| \leq d$ and check whether they satisfy the formula φ . Let \mathcal{S}_0 be the set of those that satisfy φ . The set \mathcal{S}_0 can be generated in time $O(|\varphi|)$ since L and d_0 are fixed.

Observe that S satisfies φ if and only if it has an induced substructure isomorphic to a structure in \mathcal{S}_0 (here, we use that L has no function symbols). This can be tested in constant time by inspecting the global list. Providing the satisfying assignment can be done in constant time if during the computation for each substructure we store a certificate why it was included in the list (which requires constant time overhead only). \square

We are now ready to describe the data structures. We start with the one for graphs with bounded expansion.

Theorem 22. *Let L be a language with no function symbols, d_0 a fixed integer and \mathcal{G} a class of graphs with bounded expansion. There exists a data structure representing an L -structure S guarded by a member of \mathcal{G} such that*

- *given a graph $G \in \mathcal{G}$ and an L -structure S guarded by G , the data structure is initialized in linear time,*
- *if an L -structure S' is obtained from S by adding or removing a tuple from one of the relations, then the data structure representing S can be changed to the one representing S' in constant time provided that both S and S' are guarded by G , and*
- *the data structure allows testing in time bounded by $O(|\varphi|)$ whether a given Σ_1 - L -sentence φ with at most d_0 variables is satisfied by S , and if so, outputting one of the satisfying assignments.*

Proof. Let $k := 3(d_0 + 1)^2$, and let \mathcal{G}' be the class of all k -th augmentations of members of \mathcal{G} . Then \mathcal{G}' has bounded expansion by Theorem 8. Let K be as in Lemma 6 applied to \mathcal{G}' . Thus K depends only on \mathcal{G} and d_0 . Given $G \in \mathcal{G}$ we compute, in linear time using Lemma 9, a k -th augmentation G' of G and directed graphs D_1, D_2, \dots, D_k as in the definition of k -th augmentation. Then we compute a K -coloring c of G' in linear time by Lemma 6. Let \mathcal{X} be the set of all subsets of $\{1, 2, \dots, K\}$ of size d_0 . By Theorem 11 c is a G' -compliant low

tree-depth coloring of G of order d_0 , and by Theorem 12 we can find in linear time, for each $X \in \mathcal{X}$, a rooted forest F_X such that the subgraph H_X of G induced by vertices v with $c(v) \in X$ is a subgraph of the closure of F_X . Now given $X \in \mathcal{X}$ and an L -structure S guarded by G , let S_X denote the induced substructure of S induced by the set $V(H_X) \subseteq V(S)$. Then S_X is guarded by the closure of F_X . Since φ is a Σ_1 - L -sentence, we have

(1) $S \models \varphi$ if and only if $S_X \models \varphi$ for some $X \in \mathcal{X}$.

Thus S will be represented by the collection $\{S_X\}_{X \in \mathcal{X}}$ of induced substructures. Updates will be done using Lemma 21, and testing whether $S \models \varphi$ will be done using (1) and Lemma 21. \square

The following is a variation of the above theorem for nowhere dense graphs.

Theorem 23. *Let L be a language with no function symbols, d_0 a fixed integer, ε a positive real number and \mathcal{G} a class of nowhere-dense graphs. There exists a data structure representing an L -structure S guarded by a member of \mathcal{G} such that*

- *given an n -vertex graph $G \in \mathcal{G}$ and an L -structure S guarded by G , the data structure is initialized in time $O(n^{1+\varepsilon})$,*
- *if an L -structure S' is obtained from S by adding or removing a tuple from one of the relations, then the data structure representing S can be changed to the one representing S' in time $O(n^\varepsilon)$ provided that both S and S' are guarded by G , and*
- *the data structure allows testing in time bounded by $O(|\varphi|)$ whether a given Σ_1 - L -sentence φ with at most d_0 variables is satisfied by S , and if so, outputting one of the satisfying assignments.*

Proof. Let $\varepsilon > 0$. The proof makes use of the data structure from Theorem 22, which we will refer to as the *old data structure*. The parameters of the latter are now slightly different. The class \mathcal{G}' is nowhere dense by Theorem 8. Thus K is no longer a constant; instead, we may select K to satisfy $K = O(n^{\varepsilon/d_0})$, where $n = |V(G)|$. The computation of G' takes time $O(n^{1+\varepsilon})$ by Lemma 10. The computation of c takes time $O(|V(G')| + |E(G')|) = O(n^{1+\varepsilon})$, because \mathcal{G}' is nowhere dense. Since $|\mathcal{X}| = O(n^\varepsilon)$, the old data structure allows updates in time $O(n^\varepsilon)$ and testing $S \models \varphi$ for Σ_1 - L -sentences φ in time $O(|\varphi|n^\varepsilon)$. During initialization and after every update we use the old data structure to compute or recompute the set \mathcal{S} of all isomorphism classes of L -structures A with $|V(A)| \leq d_0$ such that A is isomorphic to an induced substructure of S . This can be done in time $O(n^\varepsilon)$, because the size of \mathcal{S} is bounded. Now $S \models \varphi$ if and only if $A \models \varphi$ for some $A \in \mathcal{S}$. The set \mathcal{S} will form the *new data structure*, which can be used to answer queries of the form $S \models \varphi$ in time $O(|\varphi|)$. \square

6 Dynamic data structure for first order properties

In this section, we present our dynamic data structure for testing FO properties. The main result of this section reads as follows:

Theorem 24. *Let \mathcal{G} be a class of graphs with bounded expansion, L a language and φ an L -sentence. There exists a data structure that, given an n -vertex graph $G \in \mathcal{G}$ and an L -structure A guarded by G , is initialized in time $O(n)$ and supports the following operations:*

- *adding a tuple to a relation of A in constant time provided A stays guarded by G ,*
- *removing a tuple from a relation of A in constant time, and*
- *answering in constant time whether $A \models \varphi$.*

Note that in Theorem 24, we do not allow to change function values of functions from L to simplify our exposition; this does not present a loss of generality as one can model functions as binary relations. We first establish a dynamized version of Lemma 16.

Lemma 25. *Let $d \geq 0$ be an integer, L a language, $\varphi(x_0, \dots, x_n)$ a simple quantifier-free L -formula that is a conjunction of atomic formulas and their negations, and T a φ -template. There exist a language \overline{L} that extends L and a (not necessarily simple) quantifier-free \overline{L} -formula $\overline{\varphi}_T(x_1, \dots, x_n)$ such that the following holds:*

- *\overline{L} is obtained from L by adding a function symbol p and finitely many relation symbols U_0, \dots, U_K of arity at most one,*
- *for every rooted forest F of depth at most d and every L -structure S guarded by the closure of F , there exists an \overline{L} -structure \overline{S} such that \overline{S} is an expansion of S and for every $v_1, \dots, v_n \in V(S)$,*

$$\overline{S} \models \overline{\varphi}_T(v_1, \dots, v_n) \text{ if and only if } S \models \varphi(v_0, v_1, \dots, v_n) \text{ for some } v_0 \in V(S) \text{ such that } v_0, v_1, \dots, v_n \text{ are compatible with } T, F, S,$$

where $p^{\overline{S}}$ is the F -parent function and the relations $U_0^{\overline{S}}, \dots, U_K^{\overline{S}}$ can be computed (by listing the singletons they contain) in linear time given F and S , and

- *adding or removing a tuple to or from a relation of S results in adding and/or removing a constant number of singletons to or from unary relations among $U_0^{\overline{S}}, \dots, U_k^{\overline{S}}$, and the changes to all relations $U_0^{\overline{S}}, \dots, U_k^{\overline{S}}$ can be computed in constant time, provided S stays guarded by the closure of F .*

Proof. We construct $\bar{L}, \bar{\varphi}_T$ and \bar{S} as in the proof of Lemma 16. We need to describe how the relations $U_0^{\bar{S}}, \dots, U_k^{\bar{S}}$ can be updated in constant time after adding/removing a tuple to/from a relation of S . Let us consider in more detail the main case analyzed in the proof of Lemma 16; we leave to the reader the case mentioned at the end of the proof of Lemma 16 as the arguments are completely analogous. Recall (see the proof of Lemma 16 for notation) that $U_0(w)$ is the unary relation containing elements w of F at depth $d_v + 1$ such that the subtree of w in F contains an element v_0 at depth d_{x_0} (in F) with the following properties:

- there is a (v_0) -admissible embedding of the template T_0 in F for S , and
- all atomic formulas appearing in the conjunction φ' with at least one term from X_0 are true with $x_0 = v_0$ and the terms $t \in X'_0$, say $\alpha_T(t) = q^k(\alpha_T(x_0))$, replaced with $(p^{\bar{S}})^k(v_0)$.

Since none of the functions of S changes, the first condition cannot change when adding/removing a tuple to/from a relation of S . The second condition can change only when a tuple containing a term from X_0 is added/removed to/from a relation. But this can result only in a single element (the one at depth $d_v + 1$ on the path in T containing all the elements of the altered tuple) to be added to or removed from U_0 . Based on the tuple we add or remove, we can identify this vertex. The existence of v_0 (which must be at depth determined by the template T_0) is tested using the data structure introduced in the proof of Lemma 21: the values of all terms from X_0 with $x_0 = v_0$ are in the subtree of w and those in X'_0 are on the path from w to the root. The existence of v_0 is equivalent to the existence of an induced subtree comprised of the path from the root to w and a subtree of w witnessing that the atomic formulas listed in the second condition are satisfied. The data structure introduced in the proof of Lemma 21 allows testing the existence of one of these “witnessing” subtrees in constant time (assuming the formula φ is fixed). So, we can update the relation U_0 in constant time.

Once the relation U_0 is updated, the relations U_1, \dots, U_k can be updated in constant time as well: we keep a counter at every vertex at depth d_v determining the number of children of that vertex in U_0 . \square

Next we prove a dynamized version of Theorem 19 (we state the theorem in the variant with no free variables for simplicity).

Theorem 26. *Let \mathcal{G} be a class of graphs with bounded expansion, L a language, φ an L -sentence, and let $\bar{L}, \bar{\mathcal{G}}, \bar{\varphi}$ and \mathcal{A} be as in Theorem 19. Let A and B be L -structures guarded by a graph $G \in \mathcal{G}$, let B be obtained from A by adding or deleting a tuple τ from the relation R^A of A , and let $\bar{A}, \bar{\mathcal{G}}$ and $\bar{B}, \bar{\mathcal{G}}$ be the output of the algorithm \mathcal{A} when given A, \mathcal{G} and B, \mathcal{G} , respectively, as input. Then \bar{B} can be computed from the knowledge of \bar{A} and τ in constant time.*

Proof. The proof follows from the proof of Theorem 19, using Lemma 17 with the proviso that in the proof of Lemma 17 we use Lemma 25 instead of Lemma 16.

An important fact is that A and B have the same interpretations of functions. We observe that every change in S results in a constant number of changes in \overline{S} and these changes can be identified in constant time. Hence, in the inductive proof of Theorem 19, a single change in A results in constantly many changes to the structure obtained in the first inductive step, which result in constantly many changes to the structure obtained in the second inductive step (each change in the structure obtained in the first inductive step yields only constantly many changes), and so on. Since the time to update the final \overline{L} -structure \overline{A} is constant for each of constantly many choices that propagate through the induction from a single change of A , the overall update time is constant. \square

Theorem 24 follows immediately from Theorem 26.

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