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**Cities as Complex Systems:
Scaling, Interactions,
Networks, Dynamics
and Urban Morphologies**

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Cities as Complex Systems[†]

Scaling, Interactions, Networks, Dynamics and Urban Morphologies

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Abstract

Cities have been treated as systems for fifty years but only in the last two decades has the focus changed from aggregate equilibrium systems to more evolving systems whose structure emerges from the bottom up. We first outline the rudiments of the traditional approach focusing on equilibrium and then discuss how the paradigm has changed to one which treats cities as emergent phenomena generated through a combination of hierarchical levels of decision, driven in a decentralized fashion. This is consistent with the complexity sciences which dominate the simulation of urban form and function. We begin however with a review of equilibrium models, particularly those based on spatial interaction, and we then explore how simple dynamic frameworks can be fashioned to generate more realistic models. In exploring dynamics, nonlinear systems which admit chaos and bifurcation have relevance but recently more pragmatic schemes of structuring urban models based on cellular automata and agent-based modeling principles have come to the fore. Most urban models deal with the city in terms of the location of its economic and demographic activities but there is also a move to link such models to urban morphologies which are clearly fractal in structure. Throughout this chapter, we show how key concepts in complexity such as scaling, self-similarity and far-from-equilibrium structures dominate our current treatment of cities, how we might simulate their functioning and how we might predict their futures. We conclude with the key problems that dominate the field and suggest how these might be tackled in future research.

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Glossary

- Agent-Based Models:** systems composed of individuals who act purposely in making locational/spatial decisions
- Bifurcation:** a process whereby divergent paths are generated in a trajectory of change in an urban system
- City Size Distribution:** a set of cities by size, usually population, often in rank order
- Emergent Patterns:** land uses or economic activities which follow some spatial order
- Entropy Maximizing:** the process of generating a spatial model by maximizing a measure of system complexity subject to constraints
- Equilibrium:** a state of the urban system which is balanced and unchanging
- Exponential Growth:** the process whereby an activity changes through positive feedback on itself
- Fast Dynamics:** a process of frequent movement between locations, often daily
- Feedback:** the process whereby a system variable influences another variable, either positively or negatively
- Fractal Structure:** a pattern or arrangement of system elements that are self-similar at different spatial scales
- Land Use Transport Model:** a model linking urban activities to transport interactions
- Life Cycle Effects:** changes in spatial location which are motivated by aging of urban activities and populations
- Local Neighborhood:** the space immediately around a zone or cell
- Logistic Growth:** exponential growth capacitated so that some density limit is not exceeded
- Lognormal Distribution:** a distribution which has fat and long tails which is normal when examined on a logarithmic scale
- Microsimulation:** the process of generating synthetic populations from data which is collated from several sources
- Model Validation:** the process of calibrating and testing a model against data so that its goodness of fit is optimized
- Multipliers:** relationships which embody nth order effects of one variable on another.
- Network Scaling:** the in-degrees and out-degrees of a graph whose nodal link volumes follow a power law
- Population Density Profile:** a distribution of populations which typically follows an exponential profile when arrayed against distance from some nodal point
- Power Laws:** scaling laws that order a set of objects according to their size raised to some power
- Rank Size Rule:** a power law that rank orders a set of objects
- Reaction-Diffusion:** the process of generating changes as a consequence of a reaction to an existing state and interactions between states

Scale-free Networks: networks whose nodal volumes follow a power law

Segregation Model: a model which generates extreme global segregation from weak assumptions about local segregation

Simulation: the process of generating locational distributions according to a series of sub-model equations or rules

Slow Dynamics: changes in the urban system that take place over years or decades

Social Physics: the application of classical physical principles involving distance, force and mass to social situations, particularly to cities and their transport

Spatial Interaction: the movement of activities between different locations ranging from traffic distributions to migration patterns

Trip Distribution: the pattern of movement relating to trips made by the population, usually from home to work but also to other activities such as shopping

Urban Hierarchy: a set of entities physically or spatially scaled in terms of their size and areal extent

Urban Morphology: patterns of urban structure based on the way activities are ordered with respect to their locations

Urban System: a city represented as a set of interacting subsystems or their elements

Introduction: Cities as Systems

Cities were first treated formally as systems when General System Theory and Cybernetics came to be applied to the softer social sciences in the 1950s. Ludwig von Bertalanffy (1969) in biology and Norbert Wiener (1948) in engineering gave enormous impetus to this emerging interdisciplinary field that thrust upon us the idea that phenomena of interest in many disciplines could be articulated in generic terms as 'systems'. Moreover the prospect that the systems approach could yield generic policy, control and management procedures applicable to many different areas, appeared enticing. The idea of a general systems theory was gradually fashioned from reflections on the way distinct entities which were clearly collections of lower order elements, organized into a coherent whole, displaying pattern and order which in the jargon of the mid-twentieth century was encapsulated in the phrase that "the whole is greater than the sum of the parts". The movement began in biology in the 1920s, gradually eclipsing parts of engineering in the 1950s and spreading to the management and social sciences, particularly sociology and political science in the 1960s. It was part of a wave of change in the social sciences which began in the late 19th century as these fields began to emulate the physical sciences, espousing positivist methods which had appeared so successful in building applicable and robust theory.

The focus then was on ways in which the elements comprising the system interacted with one another through structures that embodied feedbacks keeping the system sustainable within bounded limits. The notion that such systems have controllers to 'steer' them to meet certain goals or targets is central to this early paradigm and the science of "...control and communication in the animal and the machine" was the definition taken up by Norbert Wiener (1948) in his exposition of the science of cybernetics. General system theory provided the generic logic for both the structure and behavior of such systems through various forms of feedback and hierarchical organization while cybernetics represents the 'science of steersmanship' which would enable such systems to move towards explicit goals or targets. Cities fit this characterization admirably and in the 1950s and 1960s, the traditional approach that articulated cities as structures that required physical and aesthetic organization,

quickly gave way to deeper notions that cities needed to be understood as general systems. Their control and planning thus required much more subtle interventions than anything that had occurred hitherto in the name of urban planning.

Developments in several disciplines supported these early developments. Spatial analysis, as it is now called, began to develop within quantitative geography, linked to the emerging field of regional science which represented a synthesis of urban and regional economics in which location theory was central. In this sense, the economic structure of cities and regions was consistent with classical macro and micro economics and the various techniques and models that were developed within these domains had immediate applicability. Applications of physical analogies to social and city systems, particularly ideas about gravitation and potential, had been explored since the mid 19th century under the banner of 'social physics' and as transportation planning formally began in the 1950s, these ideas were quickly adopted as a basis for transport modeling. Softer approaches in sociology and political science also provided support for the idea of cities as organizational systems while the notion of cybernetics as the basis for management, policy and control of cities was adopted as an important analogy in their planning (Chadwick, 1971; McLoughlin, 1969).

The key ideas defined cities as sets of elements or components tied together through sets of interactions. The archetypal structure was fashioned around land use activities with economic and functional linkages between them represented initially in terms of physical movement, traffic. The key idea of feedback, which is the dynamic that holds a general system together, was largely represented in terms of the volume and pattern of these interactions, at a single point in time. Longer term evolution of urban structure was not central to these early conceptions for the focus was largely on how cities functioned as equilibrium structures. The prime imperative was improving how interactions between component land uses might be made more efficient while also meeting goals involving social and spatial equity. Transportation and housing were of central importance in adopting the argument that cities should be treated as examples of general systems and steered according to the principles of cybernetics.

Typical examples of such systemic principles in action involve transportation in large cities and these early ideas about systems theory hold as much sway in helping make

sense of current patterns as they did when they were first mooted fifty or more years ago. Different types of land use with different economic foci interact spatially with respect to how employees are linked to their housing locations, how goods are shipped between different locations to service the production and consumption that define these activities, how consumers purchase these economic activities which are channeled through retail and commercial centers, how information flows tie all these economies together, and so on: the list of linkages is endless. These activities are capacitated by upper limits on density and capacity. In Greater London for example, the traffic has reached saturation limits in the central city and with few new roads being constructed over the last 40 years, the focus has shifted to improving public transport and to road pricing.

The essence of using a systems model of spatial interaction to test the impact of such changes on city structure is twofold: first such a model can show how people might shift mode of transport from road to rail and bus, even to walking and cycling, if differential pricing is applied to the road system. The congestion charge in central London imposed in 2003 led to a 30 percent reduction in the use of vehicles and this charge is set to increase massively for certain categories of polluting vehicles in the near future. Second the slightly longer term effects of reducing traffic are to increase densities of living, thus decreasing the length and cost of local work journeys, also enabling land use to respond by changing their locations to lower cost areas. All these effects ripple through the system with the city system models presented here designed to track and predict such n'th order effects which are rarely obvious. Our focus in this chapter is to sketch the state-of-the-art in these complex systems models showing how new developments in the methods of the complexity sciences are building on a basis that was established half century ago.

Since early applications of general systems theory, the paradigm has changed fundamentally from a world where systems were viewed as being centrally organized, from the top down, and notions about hierarchy were predominant, to one where we now consider systems to be structured from the bottom up. The idea that one or the other – the centralized or the decentralized view – are mutually exclusive of each other is not entirely tenable of course but the balance has certainly changed. Theories have moved from structures and behaviors being organized according to some central

control to theories about how systems retain their own integrity from the bottom up, endorsing what Adam Smith over 300 years ago, called “the hidden hand”. This shift has brought onto the agenda the notion of equilibrium and dynamics which is now much more central to systems theory than it ever was hitherto. Systems such as cities are no longer considered to be equilibrium structures, notwithstanding that many systems models built around equilibrium are still eminently useful. The notion that city systems are more likely to be in disequilibrium, all the time, or even classed as far-from-equilibrium continually reinforcing the move away from equilibrium, are comparatively new but consistent with the speed of change and volatility in cities observed during the last fifty years.

The notion too that change is nowhere smooth but discontinuous, often chaotic, has become significant. Equilibrium structures are renewed from within as unanticipated innovations, many technological but some social, change the way people make decisions about how they locate and move within cities. Historical change is important in that historical accidents often force the system onto a less than optimal path with such path dependence being crucial to an understanding of any current equilibria and the dynamic that is evolving. Part of this newly emerging paradigm is the idea that new structures and behaviors that emerge are often unanticipated and surprising. As we will show in this chapter, when we look at urban morphologies, they are messy but ordered, self-similar across many scales, but growing organically from the bottom up. Planned cities are always the exception rather than the rule and when directly planned, they only remain so for very short periods of time.

The new complexity sciences are rewriting the theory of general systems but they are still founded on the rudiments of structures composed of elements, now often called actors or agents, linked through interactions which determine the processes of behavior which keep the system in equilibrium and/or move it to new states. Feedback is still central but recently has been more strongly focused on how system elements react to one another through time. The notion of an unchanging equilibrium supported by such feedbacks is no longer central; feedback is now largely seen as the way in which these structures are evolved to new states. In short, system theory has shifted to consider such feedbacks in positive rather than negative terms although both are essential. Relationships between the system elements in terms of their interactions are

being enriched using new ideas from networks and their dynamics (Newman, Barabasi, and Watts, 2006). Key notions of how the elements of systems scale relative to one another and relative to their system hierarchies have become useful in showing how local actions and interactions lead to global patterns which can only be predicted from the bottom up (Miller and Page, 2007). This new view is about how emergent patterns can be generated using models that grow the city from the bottom up (Epstein and Axtell, 1996), and we will discuss all these ideas in the catalogue of models that we present below.

We begin by looking at models of cities in equilibrium where we illustrate how interactions between key system elements located in space follow certain scaling laws reflecting agglomeration economies and spatial competition. The network paradigm is closely linked to these ideas in structural terms. None of these models, still important for operational simulation modeling in a policy context, have an internal dynamic and thus we turn to examine dynamics in the next section. We then start with simple exponential growth, showing how it can be capacitated as logistic growth from which nonlinear behaviors can result as chaos and bifurcation. We show how these models might be linked to a faster dynamics built around equilibrium spatial interaction models but to progress these developments, we present much more disaggregate models based on agent simulation and cellular automata principles. These dynamics are then generalized as reaction-diffusion models.

Our third section deals with how we assemble more integrated models built from these various equilibrium and dynamic components or sub-models. We look at large-scale land use transport models which are equilibrium in focus. We then move to cellular automata models of land development, concluding our discussion with reference to the current development of fine scale agent-based models where each individual and trip maker in the city system is simulated. We sprinkle our presentation with various empirical applications, many based on data for Greater London showing how employment and population densities scale, how movement patterns are consistent with the underling infrastructure networks that support them, and how the city has grown through time. We show how the city can be modeled in terms of its structure and the way changes to it can be visualized. We then link these more abstract notions about how cities are structured in spatial-locational terms to their

physical or fractal morphology which is a direct expression of their scaling and complexity. We conclude with future directions, focusing on how such models can be validated and used in practical policy-making.

Cities in Equilibrium

Arrangements of Urban Activities

Cities can usually be represented as a series of n locations, each identified by i , and ordered from $i = 1, 2, \dots, n$. These locations might be points or areas where urban activity takes place, pertaining either to the inter-urban scale where locations are places not necessarily adjacent to one another or at the intra-urban scale where a city is exhaustively partitioned into a set of areas. We will use both representations here but begin with a generic formulation which does not depend on these differences *per se*.

It is useful to consider the distribution of locations as places where differing amounts of urban activity can take place, using a framework which shows how different arrangements of activity can be consistently derived. Different arrangements of course imply different physical forms of city. Assume there is N amount of activity to be distributed in n locations as N_1, N_2, \dots . Beginning with N_1 , there are $N!/[N_1!(N - N_1)!]$ allocations of N_1 , $(N - N_1)!/[N_2!(N - N_1 - N_2)!]$ allocations of N_2 , $(N - N_1 - N_2)!/[N_3!(N - N_1 - N_2 - N_3)!]$ of N_3 and so on. To find the total number of arrangements W , we multiply each of these quantities together where the product is

$$W = \frac{N!}{\prod_i N_i!} \quad . \quad (1)$$

This might be considered a measure of complexity of the system in that it clearly varies systematically for different allocations. If all N activity were to be allocated to

the first location, then $W = 1$ while if an equal amount of activity were to be allocated to each location, then W would vary according to the size of N and the number of locations n . It can be argued that the most likely arrangement of activities would be the one which would give the greatest possibility of distinct individual activities being allocated to locations and such an arrangement could be found by maximizing W (or the logarithm of W which leads to the same). Such maximizations however might be subject to different constraints on the arrangements which imply different conservation laws that the system must meet. This would enable different types of urban form to be examined under different conditions related to density, compactness, sprawl and so on, all of which might be formalized in this way.

To show how this is possible, consider the case where we now maximize the logarithm of W subject to meaningful constraints. The logarithm of equation (1) is

$$\ln W = \ln (N!) - \sum_i \ln(N_i!) \quad (2)$$

which using Stirling's formula, simplifies to

$$\ln W \approx N + \ln (N!) - \sum_i N_i \ln N_i \quad (3)$$

N_i which is the number of units of urban activity allocated to location i , is a frequency that can be normalized into a probability as $p_i = N_i/N$. Substituting for $N_i = N p_i$ in equation (3) and dropping the constant terms leads to

$$\ln W \propto -\sum_i p_i \ln p_i = H \quad (4)$$

where it is now clear that the formula for the number of arrangements is proportional to Shannon's entropy H . Thus the process of maximizing $\ln W$ is the well-known process of maximizing entropy subject to relevant constraints and this leads to many standard probability distributions (Tribus, 1969). Analogies between city and other social systems with statistical thermodynamics and information theory were

developed in the 1960s and represented one of the first formal approaches to the derivation of models for simulating the interaction between locations and the amount of activity attracted to different locations in city, regional and transport systems. As such, it has become a basis on which to build many different varieties of urban model (Wilson, 1970)

Although information or entropy has been long regarded as a measure of system complexity, we will not take this any further here except to show how it is useful in deriving different probability distributions of urban activity. Readers are however referred to the mainstream literature for both philosophic and technical expositions of the relationship between entropy and complexity (for example see Gell-Man, 1994) The measure H in equation (4) is at a maximum when the activity is distributed evenly across locations, that is when $p_i = 1/n$ and $H = \ln n$ while it is at a minimum when $p_i = 1$ and $p_j = 0, j = 1, 2, \dots, n, i \neq j$, and $H = 0$. It is clear too that H varies with n ; that is as the number of locations increases, the complexity or entropy of the system also increases. However what is of more import here is the kind of distribution that maximizing entropy generates when H is maximized subject to appropriate constraints. We demonstrate this as follows for a simple but relevant case where the key constraint is to ensure that the system reproduces the mean value of an attribute of interest. Let p_i be the probability of finding a place i which has P_i population residing there. Then we maximize the entropy

$$H = -\sum_i p_i \ln p_i \quad , \quad (5)$$

subject to a normalization constraint on the probabilities

$$\sum_i p_i = 1 \quad , \quad (6)$$

and a constraint on the mean population of places \bar{P} in the system, that is

$$\sum_i p_i P_i = \bar{P} \quad . \quad (7)$$

The standard method of maximizing equation (5) subject to constraint equations (6) and (7) is to form a Langrangian L – a composite of the entropy and the constraints

$$L = -\sum_i p_i \ln p_i - \beta \left(\sum_i p_i - 1 \right) - \mathcal{G} \left(\sum_i p_i P_i - \bar{P} \right) \quad (8)$$

where β and \mathcal{G} are multipliers designed to ensure that the constraints are met. Maximizing (8) with respect to p_i gives

$$\frac{\partial L}{\partial p_i} = \ln p_i - 1 - \beta - \mathcal{G} P_i = 0 \quad (9)$$

leading directly to a form for p_i which is

$$p_i = \exp(-\beta - 1) \exp(-\mathcal{G} P_i) = K \exp(-\mathcal{G} P_i) \quad . \quad (10)$$

K is the composite constant of proportionality which ensures that the probabilities sum to 1. Note also that the sign of the parameters is determined from data through the constraints. If we substitute the probability in equation (10) into the Shannon entropy, the measure of complexity of this system which is at a maximum for the given set of constraints, simplifies to $H = \beta + 1 + \mathcal{G} \bar{P}$. There are various interpretations of this entropy with respect to dispersion of activities in the system although these represent a trade-off between the form of the distribution, in this case, the negative exponential, and the number of events or objects n which characterize the system.

Distributions and Densities of Population

The model we have derived can be regarded as an approximation to the distribution of population densities over a set of n spatial zones as long as each zone is the same size (area), that is, $A_i = A, \forall_i$ where nA is the total size (area) of the system. A more

general form of entropy takes this area into account by maximizing the expected value of the logarithm of the density, not distribution, where the ‘spatial’ entropy is defined as

$$S = -\sum_i p_i \ln \frac{p_i}{A_i} \quad , \quad (11)$$

with the probability density as p_i / A_i . Using this formula, the procedure simply generalizes the maximization to densities rather than distributions (Batty, 1974) and the model we have derived simply determines these densities with respect to an average population size \bar{P} . If we order populations over the zones of a city or even take their averages over many cities in a region or nation, then they are likely to be distributed in this fashion; that is, we would expect there to be many fewer zones or cities of high density than zones or cities of low density, due to competition through growth.

However the way this method of entropy-maximizing has been used to generate population densities in cities is to define rather more specific constraints that relate to space. Since the rise of the industrial city in the 19th century, we have known that population densities tend to decline monotonically with distance from the centre of the city. More than 50 years ago, Clark (1951) demonstrated quite clearly that population densities declined exponentially with distance from the centre of large cities and in the 1960s with the application of micro-economic theory to urban location theory following von Thunen’s (1826) model, a range of urban attributes such as rents, land values, trip densities, and population densities were shown to be consistent with such negative exponential distributions (Alonso, 1964). Many of these models can also be generated using utility maximizing which under certain rather weak constraints can be seen as equivalent to entropy-maximizing (Anas, 1983). However it is random utility theory that has been much more widely applied to generate spatial interaction models with a similar form to the models that we generate below using entropy-maximizing (Ben Akiva and Lerman, 1985; Helbing and Nagel, 2004).

We will show how these typical micro-economic urban density distributions can be derived using entropy-maximizing in the following way. Maximizing S in equation (11) or H in equation (5) where we henceforth assume that the probability p_i is now the population density, we invoke the usual normalization constraint in equation (6) and a constraint on the average travel cost \bar{C} incurred by the population given as $\sum_i p_i c_i = \bar{C}$ where c_i is the generalized travel cost/distance from the central business district (CBD) to a zone i . This maximization leads to

$$p_i = K \exp(-\mu c_i) \quad (12)$$

where μ is the parameter controlling the rate of decay of the exponential function, sometimes called the ‘friction’ of distance or travel cost.

Gravitational Models of Spatial Interaction

It is a simple matter to generalize this framework to generate arrangements of urban activities that deal with interaction patterns, that is movements or linkages between pairs of zones. This involves extending entropy to deal with two rather than one dimensional systems where the focus of interest is on the interaction between an origin zone called $i, i = 1, 2, \dots, I$ and a destination zone $j, j = 1, 2, \dots, J$ where there are now a total of IJ interactions in the system. These kinds of model can be used to simulate routine trips from home to work, for example, or to shop, longer term migrations in search of jobs, moves between residential locations in the housing market, as well as trade flows between countries and regions. The particular application depends on context as the generic framework is independent of scale.

Let us now define a two-dimensional entropy as

$$H = -\sum_i \sum_j p_{ij} \ln p_{ij} \quad (13)$$

p_{ij} is the probability of interaction between origin i and destination j where the same distinctions between distribution and density noted above apply. Without loss of generality, we will assume in the sequel that these variables p_{ij} covary with density in that the origin and destination zones all have the same area. The most constrained system is where we assume that all the interactions originating from any zone i must sum to the probability p_i of originating in that zone, and all interactions destined for zone j must sum to the probability p_j of being attracted to that destination zone. There is an implicit constraint that these origin and destination probabilities sum to 1, that is

$$\sum_i \sum_j p_{ij} = \sum_i p_i = \sum_j p_j = 1 \quad , \quad (14)$$

but equation (14) is redundant with respect to the origin and destination normalization constraints which are stated explicitly as

$$\left. \begin{array}{l} \sum_j p_{ij} = p_i \\ \sum_i p_{ij} = p_j \end{array} \right\} \quad . \quad (15)$$

There is also a constraint on the average distance or cost traveled given as

$$\sum_i \sum_j p_{ij} c_{ij} = \bar{C} \quad . \quad (16)$$

The model that is derived from the maximization of equation (13) subject to equations (15) and (16) is

$$p_{ij} = K_i K_j p_i p_j \exp(-\gamma c_{ij}) \quad (17)$$

where K_i and K_j are normalization constants associated with equations (15), and γ is the parameter on the travel cost c_{ij} between zones i and j associated with

equation (16). It is easy to compute K_i and K_j by substituting for p_{ij} from equation (17) in equations (15) respectively and simplifying. This yields

$$\left. \begin{aligned} K_i &= \frac{1}{\sum_j K_j p_j \exp(-\gamma c_{ij})} \\ K_j &= \frac{1}{\sum_i K_i p_i \exp(-\gamma c_{ij})} \end{aligned} \right\} , \quad (18)$$

equations that need to be solved iteratively.

These models can be scaled to deal with real trips or population simply by multiplying these probabilities by the total volumes involved, T for total trips in a transport system, P for total population in a city system, Y for total income in a trading system and so on. This system however forms the basis for a family of interaction models which can be generated by relaxing the normalization constraints; for example by omitting the destination constraint, $K_j = 1, \forall_j$, or by omitting the origin constraint, $K_i = 1, \forall_i$ or by omitting both where we need an explicit normalization constraint of the form $\sum_{ij} p_{ij} = 1$ in equation (14) to provide an overall constant K . Wilson (1970) refers to this set of four models as: doubly-constrained – the model in equations (17) and (18), the next two as singly-constrained, first when $K_i = 1, \forall_i$, the model is origin constrained, and second when $K_j = 1, \forall_j$, the model is destination constrained; and when we have no constraints on origins or destinations, we need to invoke the global constant K and the model is called unconstrained. It is worth noting that these models can also be generated in nearly equivalent form using random utility theory where they are articulated at the level of the individual rather than the aggregate trip-maker and are known as discrete choice models (Ben Akiva and Lerman, 1985).

Let us examine one of these models, a singly-constrained model where there are origin constraints. This might be a model where we are predicting interactions from

work to home given we know the distribution of work at the origin zones. Then noting that $K_j = 1, \forall j$, the model is

$$p_{ij} = K_i p_i p_j \exp(-\gamma c_{ij}) = p_i \frac{p_j \exp(-\gamma c_{ij})}{\sum_j p_j \exp(-\gamma c_{ij})} . \quad (19)$$

The key issue with this sort of model is that not only are we predicting the interaction between zones i and j but we can predict the probability of locating in the destination zone p'_j , that is

$$p'_j = \sum_i p_{ij} = \sum_i p_i \frac{p_j \exp(-\gamma c_{ij})}{\sum_j p_j \exp(-\gamma c_{ij})} . \quad (20)$$

If we were to drop both origin and destination constraints, the model becomes one which is analogous to the traditional gravity model from which it was originally derived prior to the development of these optimization frameworks. However to generate the usual standard gravitational form of model in which the ‘mass’ of each origin and destination zone appears, given by P_i and P_j respectively, then we need to modify the entropy formula, thus maximizing

$$H = -\sum_i \sum_j p_{ij} \ln \frac{p_{ij}}{P_i P_j} , \quad (21)$$

subject to the normalization

$$\sum_i \sum_j p_{ij} = 1 , \quad (22)$$

and this time a constraint on the average ‘logarithmic’ travel cost $\overline{\ln C}$

$$\sum_i \sum_j p_{ij} \ln c_{ij} = \overline{\ln C} \quad . \quad (23)$$

The model that is generated from this system can be written as

$$p_{ij} = K \frac{P_i P_j}{c_{ij}^\eta} \quad (24)$$

where the effect of travel cost/distance is now in power law form with η the scaling parameter. Besides illustrating the fact that inverse power forms as well as negative exponential distributions can be generated in this way according to the form of the constraints, one is also able to predict both the probabilities of locating at the origins and the destinations from the traditional gravity model in equation (24).

Scaling, City Size, and Network Structure: Power Laws

Distance is a key organizing concept in city systems as we have already seen in the way various urban distributions have been generated. Distance is an attribute of nearness or proximity to the most accessible places and locations. Where there are the lowest distance or travel costs to other places, the more attractive or accessible are those locations. In this sense, distance or travel cost acts as an inferior good in that we wish to minimize the cost occurred in overcoming it. Spatial competition also suggests that the number of places that have the greatest accessibilities are few compared to the majority of places. If you consider that the most accessible place in a circular city is the centre, then assuming each place is of similar size, as the number of places by accessibility increases, the lower the accessibility is. In short, there are many places with the same accessibility around the edge of the city compared to only one place in the centre. The population density model in equation (12) implies such an ordering when we examine the frequency distribution of places according to their densities.

If we now forget distance for a moment, then it is likely that the distribution of places at whatever scale follows a distribution which declines in frequency with attributes

based on size due to competition. If we look at all cities in a nation or even globally, there are far fewer big cities than small ones. Thus the entropy-maximizing framework that we have introduced to predict the probability (or frequency) of objects of a certain size occurring, is quite applicable in generating such distributions. We derived a negative exponential distribution in equation (10) but to generate a power law, all we need to do is to replace the constraint in equation (7) with its logarithmic equivalent, that is

$$\sum_i p_i \ln P_i = \overline{\ln P} \quad , \quad (25)$$

and then maximize equation (5) subject to (6) and (25) to give

$$p_i = KP_i^{-\varphi} = \exp(-\beta - 1) \exp(-\varphi \ln P_i) \quad , \quad (26)$$

where φ is the scaling parameter. Equation (26) gives the probability or frequency – the number of cities – for a zone (or city) with P_i population which is distributed according to an inverse power law. It is important to provide an interpretation of the constraint which generates this power law. Equation (25) implies that the system conserves the average of the logarithm of size which gives greater weight to smaller values of population than to larger, and as such, is recognition that the average size of the system is unbounded as a power function implies. With such distributions, it is unlikely that normality will prevail due to the way competition constrains the distribution in the long tail. Nevertheless in the last analysis, it is an empirical matter to determine the shape of such distributions from data, although early research on the empirical distributions of city sizes following Zipf's Law (Zipf, 1949) by Curry (1964) and Berry (1964) introduced the entropy-maximizing framework to generate such size distributions.

The power law implied for the probability p_i of a certain size P_i of city or zone can be easily generalized to a two-dimensional equivalent which implies a network of interactions. We will maximize the two-dimensional entropy H in equation (13)

subject to constraints on the mean logarithm of population sizes at origins and destinations which we now state as

$$\left. \begin{aligned} \sum_i \sum_j p_{ij} \ln P_i &= \sum_i p_i \ln P_i = \bar{P}_{origins} \\ \sum_i \sum_j p_{ij} \ln P_j &= \sum_j p_j \ln P_j = \bar{P}_{destinations} \end{aligned} \right\} , \quad (27)$$

where $p_i = \sum_j p_{ij}$ and $p_j = \sum_i p_{ij}$. Note however that there are no constraints on these origins and destination probabilities p_i and p_j *per se* but the global constraints in equation (14) must hold. This maximization leads to the model

$$p_{ij} = K P_i^{-\lambda_i} P_j^{-\lambda_j} = \frac{P_i^{-\lambda_i}}{\sum_i P_i^{-\lambda_i}} \frac{P_j^{-\lambda_j}}{\sum_j P_j^{-\lambda_j}} , \quad (28)$$

where it is clear that the total flows from any origin node or location i vary as

$$p'_i \propto P_i^{-\lambda_i} , \quad (29)$$

and the flows into any destination zone vary as

$$p'_j \propto P_j^{-\lambda_j} , \quad (30)$$

with the parameters λ_i and λ_j relating to the mean of the observed logarithmic populations associated with the constraint equations (27). Note that the probabilities for each origin and destination node or zone are independent from one another as there is no constraint tying them together as in the classic spatial interaction model where distance or travel cost is intrinsic to the specification.

These power laws can be related to recent explorations in network science which suggest that the number of in-degrees – the volume of links entering a destination in

our terms – and the number of out-degrees – the volume emanating from an origin, both follow power laws (Albert, Jeong, and Barabasi, 1999). These results have been widely observed in topological rather than planar networks where the focus is on the numbers of physical links associated with nodes rather than the volume of traffic on each link. Clearly the number of physical links in planar graphs is limited and the general finding from network science that the number of links scales as a power law cannot apply to systems that exist in two-dimensional Euclidean space (Cardillo, Scellato, Latora, and Porta, 2006). However a popular way of transforming a planar graph into one which is non-planar is to invoke a rule that privileges some edges over others merging these into long links and then generating a topology which is based on the merged edges as constituting nodes and the links between the new edges as arcs. This is the method that is called space syntax (Hillier, 1996) and it is clear that by introducing order into the network in this way, the in-degrees and out-degrees of the resulting topological graph can be scaling. Jiang (2007) illustrates this quite clearly although there is some reticence to make such transformations and where planar graphs have been examined using new developments in network science based on small worlds and scale-free graph theory, the focus has been much more on deriving new network properties than on appealing to any scale-free structure (Crucitti, Latora, and Porta, 2006).

However to consider the scale-free network properties of spatial interaction systems, each trip might be considered a physical link in and of itself, albeit that it represents an interaction on a physical network as a person making such an interaction is distinct in space and time. Thus the connections to network science are close. In fact the study of networks and their scaling properties has not followed the static formulations which dominate our study of cities in equilibrium for the main way in which such power laws are derived for topological networks is through a process of preferential attachment which grows networks from a small number of seed nodes (Barabasi and Albert, 1999). Nevertheless, such dynamics appear quite consistent with the evolution of spatial interaction systems.

We will introduce these models a little later when we deal with urban dynamics. For the moment, let us note that there are various simple dynamics which can account not only for the distribution of network links following power laws, but also for the

distribution of city sizes, incomes, and a variety of other social (and physical) phenomena from models that grow the number of objects according to simple proportionate growth consistent with the generation of lognormal distributions. Suffice it to say that although we have focused on urban densities as following either power laws or negative exponential functions in this section, it is entirely possible to use the entropy-maximizing framework to generate distributions which are lognormal, another alternative with a strong spatial logic. Most distributions which characterize urban structure and activities however are not likely to be normal and to conclude this section, we will review albeit very briefly, some empirical results that indicate the form and pattern of urban activities in western cities.

Empirical Applications: Rank-Size Representations of Urban Distributions

The model in equation (26) gives the probability of location in a zone i as an inverse power function of the population or size of that place which is also proportional to the frequency

$$f(p_i) \propto p_i = KP_i^{-\varphi} \quad . \quad (31)$$

It is possible to estimate the scaling parameter φ in many different ways but a first test of whether or not a power law is likely to exist can be made by plotting the logarithms of the frequencies and population sizes and noting whether or not they fall onto a straight line. In fact a much more preferable plot which enables each individual observation to be represented is the cumulative function which is formed from the integral of equation (31) up to a given size; that is $F_i \propto P_i^{-\varphi+1}$. The counter-cumulative $F - F_i$ where F is the sum of all frequencies in the system – that is the number of events or cities – also varies as $P_i^{-\varphi+1}$ and is in fact the rank of the city in question. Assuming each population size is different, then the order of $\{i\}$ is the reverse of the rank, and we can now write the rank r of i as $r = F - F_i$. The equation for this rank-size distribution (which is the one that is usually used to fit the data) is thus

$$r = GP_r^{-\varphi+1} \quad (32)$$

where G is a scaling constant which in logarithmic form is $\ln r = G - (\varphi - 1)\ln P_r$. This is the equation that is implicit in the rank-size plots presented below which reveal evidence of scaling.

First let us examine the scaling which is implicit in urban size distributions for the largest world city populations over 1 million in 2005, for cities over 100000 in the USA in 2000, and for the 200 tallest buildings in the world in 2007. We could repeat such examples *ad nauseum* but these provide a good selection which we graph in rank-size logarithmic form in Figure 1(a), noting that we have normalized all the data by their means, that is by $\langle P_r \rangle$ and $\langle r \rangle$, as $P_r / \langle P_r \rangle$ and $r / \langle r \rangle$. We are only examining a very small number at the very top of the distribution and this is clearly not definitive evidence of scaling in the rest of the distribution but these plots do show the typical distributions of city size activities that have been observed in this field for over 50 years. As we will imply later, these signatures are evidence of self-organization and fractal structure which emerge through competition from the bottom up (Batty, 2008).

To illustrate densities in cities, we take employment and working population in small zones in Greater London, a city which has some 4.4 million workers. We rank-order the distribution in the same way we have done for world cities, and plot these, suitably normalized by their means, logarithmically in Figure 1(b). These distributions are in fact plotted as densities so that we remove aerial size effects. Employment densities $e_i = E_i / A_i$ can be interpreted as the number of work trips originating in employment zones $e_i = \sum_j T_{ij}$ – the volume of the out-degrees of each employment zone considered as nodes in the graph of all linkages between all places in the system, and population densities $h_j = P_j / A_j$ as the destination distributions $h_j = \sum_i T_{ij}$ – the in-degrees which measure all the trips destined for each residential zone from all employment zones. In short if there is linearity in the plots, this is evidence that the underlying interactions on the physical networks that link these zones are scaling. Figure 1(b) provides some evidence of scaling but the distributions are more similar

to lognormal distributions than to power laws. This probably implies that the mechanisms for generating these distributions are considerably more complex than growth through preferential attachment which we will examine in more detail below (Batty, 2008).

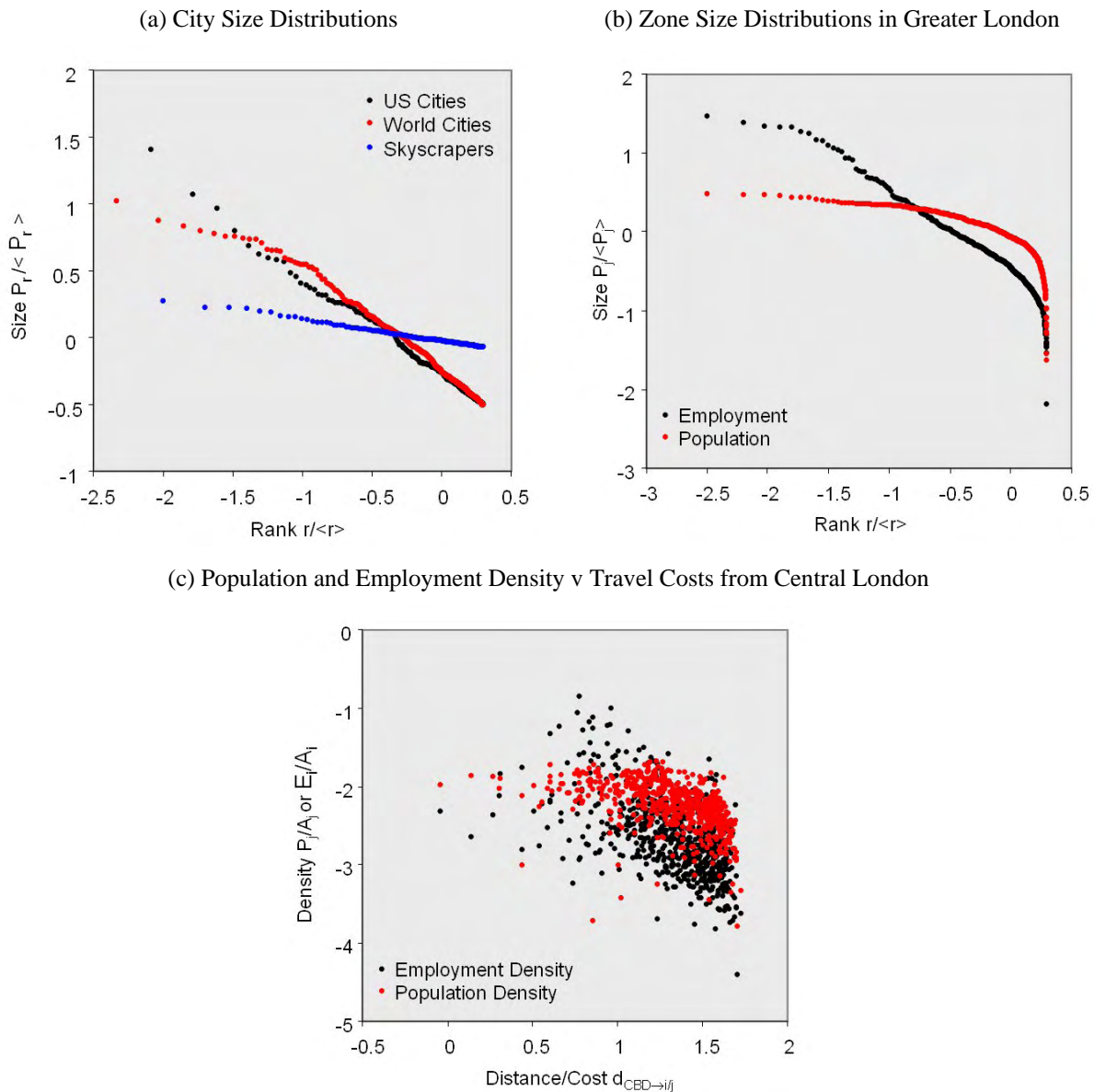


Figure 1: Scaling Distributions in World Cities and in Greater London

Lastly, we can demonstrate that scaling in city systems also exists with respect to how trips, employment and population activities vary with respect to distance. In Figure 1(c), we have again plotted the employment densities $e_i = E_i / A_i$ at origin locations and population densities $h_j = P_j / A_j$ at destination locations but this time against

distances $d_{CBD \rightarrow i}$ and $d_{CBD \rightarrow j}$ from the centre of London's CBD in logarithmic terms. It is clear that there is significant correlation but also a very wide spread of values around the log-linear regression lines due to the fact that the city is multi-centric. Nevertheless the relationships appears to be scaling with these estimated as $e_i = 0.042 d_{CBD \rightarrow i}^{-0.98}$, ($r^2 = -0.30$), and $h_j = 0.029 d_{CBD \rightarrow j}^{-0.53}$, ($r^2 = -0.23$). However more structured spatial relationships can be measured by accessibilities which provide indices of overall proximity to origins or destinations, thus taking account of the fact that there are several competing centers. Accessibility can be measured in many different ways but here we use a traditional definition of potential based on employment accessibility A_i to populations at destinations, and population accessibility A_j to employment at origins defined as

$$\left. \begin{aligned} A_i &\propto \sum_j \frac{h_j}{c_{ij}} \\ A_j &\propto \sum_i \frac{e_i}{c_{ij}} \end{aligned} \right\} , \quad (33)$$

where c_{ij} is, as before, the generalized cost of travel from employment origin i to population destination j . In Figures 2(a) and (b), we compare the distribution of employment densities e_i with accessibility origins A_i and in 2(c) and 2(d), population densities h_j with accessibility destinations A_j . Each set of maps is clearly correlated with higher associations than in Figure 1(c) which took account of only the single CBD. Regressing $\{\ln e_i\}$ on $\{\ln A_i\}$ and $\{\ln p_j\}$ on $\{\ln A_j\}$ gives an approximate scaling with 31% of the variance accounted for in terms of origin accessibility and 41% for destination accessibility. These relations appear linear but there is still considerable noise in the data which undoubtedly reflects the relative simplicity of the models and the fact that accessibility is being measured using current transport costs without any reference to the historical evolution of the city's structure. It is, however, building blocks such as these that constitute the basis for operational land use transport models that have developed for comparative static and quasi-dynamic forecasting that we will discuss below.

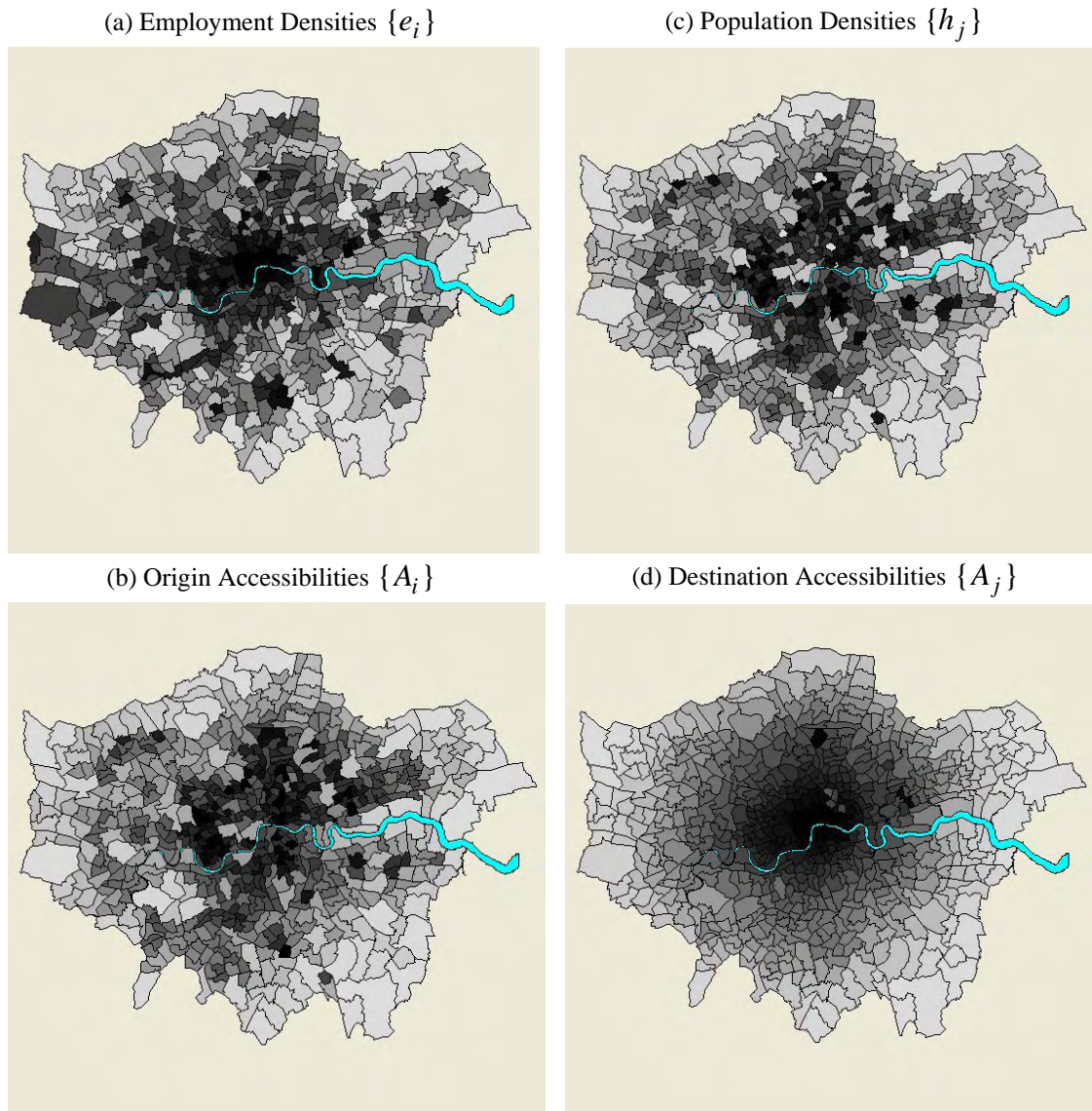


Figure 2: Employment, Population and Accessibilities in Greater London
 (greatest extent is 55kms east to west; 45kms north to south)

Urban Dynamics

Aggregate Development

Models of city systems have largely been treated as static for at first sight, urban structure in terms of its form and to some extent its function appears stable and long-lasting. During the industrial era, cities appeared to have a well-defined structure where land uses were arranged in concentric rings according to their productivity and wealth around a central focus, usually the central business district (CBD), the point

where most cities were originally located and exchange took place. Moreover data on how cities had evolved were largely absent and this reinforced the focus on statics and equilibria. Where the need to examine urban change was urgent, models were largely fashioned in terms of the simplest growth dynamics possible and we will begin with these here.

The growth of human populations in their aggregate appears to follow an exponential law where the rate of change σ is proportional to the size of the population itself $P(t)$, that is

$$\frac{dP(t)}{dt} = \sigma P(t) \quad . \quad (34)$$

It is easy to show that starting from an initial population $P(0)$, the growth is exponential, that is

$$P(t) = P(0)\exp(\sigma t) \quad . \quad (35)$$

which is the continuous form of model. When formulated discretely, at time steps $t = 1, 2, \dots, T$, equation (34) can be written as $P(t) - P(t-1) = \beta P(t-1)$ which leads to

$$P(t) = (1 + \beta) P(t-1) \quad . \quad (36)$$

Through time from the initial condition $P(0)$, the trajectory is

$$P(t) = (1 + \beta)^t P(0) \quad . \quad (37)$$

$1 + \beta$ is the growth rate. If $\beta > 0$, equation (37) shows exponential growth, if $\beta < 0$, exponential decline, and if $\beta = 0$, the population is in the steady state and simply reproduces itself.

This simple growth model leads to smooth change, and any discontinuities or breaks in the trajectories of growth or decline must come about through an external change in the rate from the outside environment. If we assume the growth rate fluctuates around a mean of one with β varying randomly, above -1 , then it is not possible to predict the trajectory of the growth path. However if we have a large number of objects which we will assume to be cities whose growth rates are chosen randomly, then we can write the growth equation for each city as

$$P_i(t) = [1 + \beta_i(t)] P_i(t-1) \quad (38)$$

which from an initial condition $P_i(0)$ gives

$$P_i(t) = \prod_{\tau=1}^t [1 + \beta_i(\tau)] P_i(0) \quad . \quad (39)$$

This is growth by proportionate effect; that is, each city grows in proportion to its current size but the growth rate in each time period is random. In a large system of cities, the ultimate distribution of these population sizes will be lognormal. This is easy to demonstrate for the logarithm of equation (39) can be approximated by

$$\ln P_i(t) = \ln P_i(0) + \sum_{\tau=1}^t \beta_i(\tau) \quad (40)$$

where the sum of the random components is an approximation to the log of the product term in equation (39) using Taylor's expansion. This converges to the lognormal from the law of large numbers. It was first demonstrated by Gibrat (1931) for social systems but is of considerable interest here in that the fat tail of the lognormal can be approximated by an inverse power law. This has become the default dynamic model which underpins an explanation of the rank-size rule for city populations first popularized by Zipf (1949) and more recently confirmed by Gabaix (1999) and Blank and Solomon (2000) amongst others. We demonstrated this in Figure 1(a) for the world city populations greater than 1 million and for US city

populations greater than 100,000. As such, it is the null hypothesis for the distribution of urban populations in individual cities as well as population locations within cities.

Although Gibrat's model does not take account of interactions between the cities, it does introduce diversity into the picture, simulating a system that in the aggregate is non-smooth but nevertheless displays regularity. These links to aggregate dynamics focus on introducing slightly more realistic constraints and one that is of wide relevance is the introduction of capacity constraints or limits on the level to which a population might grow. Such capacitated growth is usually referred to as logistic growth. Retaining the exponential growth model, we can limit this by moderating the growth rate σ according to an upper limit on population P_{\max} which changes the model in equation (34) and the growth rate σ to

$$\frac{dP(t)}{dt} = \left[\sigma \left(1 - \frac{P(t)}{P_{\max}} \right) \right] P(t) \quad . \quad (41)$$

It is clear that when $P(t) = P_{\max}$, the overall rate of change is zero and no further change occurs. The continuous version of this logistic is

$$P(t) = \frac{P_{\max}}{1 + \left(\frac{P_{\max}}{P(0)} - 1 \right) \exp(-\sigma t)} \quad (42)$$

where it is easy to see that as $t \rightarrow \infty$, $P(t) \rightarrow P_{\max}$.

The discrete equivalent of this model in equation (41) follows directly from $P(t) - P(t-1) = \beta [1 - (P(t-1)/P_{\max})] P(t-1)$ as

$$P(t) = \left[1 + \beta \left(1 - \frac{P(t-1)}{P_{\max}} \right) \right] P(t-1) \quad , \quad (43)$$

where the long term dynamics is too intricate to write out as a series. Equation (43) however shows that the growth component β is successively influenced by the growth of the population so far, thus preserving the capacity limit through the simple expedient of adjusting the growth rate downwards. As in all exponential models, it is based on proportionate growth. As we noted above, we can make each city subject to a random growth component $\beta_i(t)$ while still keeping the proportionate effect.

$$P(t) = \left[1 + \beta_i(t) \left(1 - \frac{P(t-1)}{P_{\max}} \right) \right] P(t-1) \quad . \quad (44)$$

This model has not been tested in any detail but if $\beta_i(t)$ is selected randomly, the model is a likely to generate a lognormal-like distribution of cities but with upper limits being invoked for some of these. In fact, this stochastic equivalent also requires a lower integer bound on the size of cities so that cities do not become too small (Batty, 2007). Within these limits as long as the upper limits are not too tight, the sorts of distributions of cities that we observe in the real world are predictable.

In the case of the logistic model, remarkable and unusual discontinuous nonlinear behavior can result from its simple dynamics. When the β component of the growth rate is $\beta < 2$, the predicted growth trajectory is the typical logistic which increases at an increasing rate until an inflection point after which the growth begins to slow, eventually converging to the upper capacity limit of P_{\max} . However when $\beta \cong 2$, the population oscillates around this limit, bifurcating between two values. As the value of the growth rate increases towards 2.57, these oscillations get greater, the bifurcations doubling in a regular but rapidly increasing manner. At the point where $\beta \cong 2.57$, the oscillations and bifurcations become infinite, apparently random, and this regime persists until $\beta \cong 3$ during which the predictions look entirely chaotic. In fact, this is the regime of ‘chaos’ but chaos in a controlled manner from a deterministic model which is not governed by externally induced or observed randomness or noise.

These findings were found independently by May (1976), Feigenbaum (1980), Mandelbot (1983) amongst others. They relate strongly to bifurcation and chaos theory and to fractal geometry but they still tend to be of theoretical importance only. Growth rates of this magnitude are rare in human systems although there is some suggestion that they might occur in more complex coupled biological systems of predator-prey relations. In fact one of the key issues in simulating urban systems using this kind of dynamics is that although these models are important theoretical constructs in defining the scope of the dynamics that define city systems, much of these dynamic behaviors are simplistic. In so far as they do characterize urban systems, it is at the highly aggregate scale as we demonstrate a little later. The use of these ideas in fact is much more applicable to extending the static equilibrium models of the last section and to demonstrate these, we will now illustrate how these models might be enriched by putting together logistic behaviors with spatial movement and interaction.

One way of articulating urban dynamics at the intra-urban level is to identify different speeds of change. In particular we can define a fast dynamics that relates to how people might move around the city on daily basis, for example, in terms of the journey to work, and a slower dynamics that relates to more gradual change that relates to the size of different locations affected by residential migrations. We can model the fast dynamics using a singly-constrained spatial interaction which distributes workers to residential locations which we define using previous notation where all variables are now time scripted by (t) : $T_{ij}(t)$ trips between zones i and j , employment $E_i(t)$ at origin zone i , population $P_j(t)$ at destination zone j , the friction of distance parameter $\gamma(t)$, and the travel cost $c_{ij}(t)$ between zones i and j . The model is defined as

$$T_{ij}(t) = E_i(t) \frac{P_j(t) \exp[-\gamma(t)c_{ij}(t)]}{\sum_j P_j(t) \exp[-\gamma(t)c_{ij}(t)]} , \quad (45)$$

from which we can predict residential population $P'_j(t)$ as

$$P'_j(t) = \sum_i T_{ij}(t) = \sum_i E_i(t) \frac{P_j(t) \exp[-\gamma(t)c_{ij}(t)]}{\sum_j P_j(t) \exp[-\gamma(t)c_{ij}(t)]} . \quad (46)$$

This is the fast dynamics but each zone is capacitated by an unchanging upper limit on population where the zonal population changes slowly in proportion to its existing size through internal migration and in response to the upper limit $P_{j\max}$. The change in terms of this slower dynamic from t to $t+1$ is modeled as

$$\Delta P_j(t+1) = \beta [P_{j\max} - P'_j(t)] P'_j(t) \quad (47)$$

with the long term trajectory thus given as

$$P_j(t+1) = (1 + \beta [P_{j\max} - P'_j(t)]) P'_j(t) . \quad (48)$$

Clearly $P_j(t)$ will converge to $P_{j\max}$ as long as $P'_j(t)$ is increasing while the fast dynamics is also updated in each successive time period from

$$P'_j(t+1) = \sum_i T_{ij}(t+1) = \sum_i E_i(t+1) \frac{P_j(t+1) \exp[-\gamma(t+1)c_{ij}(t+1)]}{\sum_j P_j(t+1) \exp[-\gamma(t+1)c_{ij}(t+1)]} . \quad (49)$$

We may have an even slower dynamics relating to technological or other social change which changes $P_{j\max}$ while various other models may be used to predict employment for example, which itself may be a function of another fast dynamics relating to industrial and commercial interactions. The time subscripted variables travel $c_{ij}(t+1)$ and the friction of distance parameter $\gamma(t+1)$ might be changes that reflect other time scales. We might even have lagged variables independently introduced reflecting stocks or flows at previous time periods $t-1$, $t-2$ etc. Wilson (1981, 2007) has explored links between these spatial interaction entropy-maximizing models and logistic growth and has shown that in a system of cities or zones within a city, unusual bifurcating behavior in terms of the emergence of different zonal centers

can occur when parameter values, particularly the travel cost parameter $\gamma(t+1)$, crosses certain thresholds

There have been many proposals involving dynamic models of city systems which build on the style of nonlinear dynamics introduced here and these all have the potential to generate discontinuous behavior. Although Wilson (1981) pioneered embedding dynamic logistic change into spatial interaction models, there have been important extensions to urban predator-prey models by Dendrinos and Mullaly (1985) and to bifurcating urban systems by Allen (1982, 1998), all set within a wider dynamics linking macro to micro through master equation approaches (Haag, 1989). A good summary is given by Nijkamp and Reggiani (1992) but most of these have not really led to extensive empirical applications for it has been difficult to find the necessary rich dynamics in the sparse temporal data sets available for cities and city systems; at the macro-level, a lot of this dynamics tends to be smoothed away in any case. In fact, more practical approaches to urban dynamics have emerged at finer scale levels where the agents and activities are more disaggregated and where there is a stronger relationship to spatial behavior. We will turn to these now.

Dynamic Disaggregation: Agents and Cells

Static models of the spatial interaction variety have been assembled into linked sets of sub-models, disaggregated into detailed types of activity, and structured so that they simulate changes in activities through time. However, the dynamics that is implied in such models is simplistic in that the focus has still been very much on location in space with time added as an afterthought. Temporal processes are rarely to the forefront in such models and it is not surprising that a more flexible dynamics is emerging from entirely different considerations. In fact, the models of this section come from dealing with objects and individuals at much lower/finer spatial scales and simulating processes which engage them in decisions affecting their spatial behavior. The fact that such decisions take place through time (and space) makes them temporal and dynamic rather than through the imposition of any predetermined dynamic structures such as those used in the aggregate dynamic models above. The models here deal with individuals as agents, rooted in cells which define the space they occupy and in this

sense, are highly disaggregate as well as dynamic. These models generate development in cities from the bottom up and have the capability of producing patterns which are emergent. Unlike the dynamic models of the last section, their long term spatial behavior can be surprising and often hard to anticipate.

It is possible however to use the established notation for equilibrium models in developing this framework based on the generic dynamic $P_i(t) = P_i(t-1) + \Delta P_i(t)$ where the change in population $\Delta P_i(t)$ can be divided into two components. The first is the usual proportionate effect, the positive feedback induced by population on itself which is defined as the reactive element of change $\omega P_i(t-1)$. The second is the interactive element, change that is generated from some action-at-a-distance which is often regarded as a diffusion of population from other locations in the system. We can model this in the simplest way using the traditional gravity model in equation (24) but noting that we must sum the effects of the diffusion over the destinations from where it is generated as a kind of accessibility or potential. The second component of change is $\phi P_i(t-1) K \sum_j P_j(t-1) / c_{ij}^\eta$ from which the total change between t and $t-1$ is

$$\Delta P_i(t) = \omega P_i(t-1) + \phi P_i(t-1) K \sum_j \frac{P_j(t-1)}{c_{ij}^\eta} + \varepsilon_i(t-1) \quad . \quad (50)$$

We have also added a random component $\varepsilon_i(t-1)$ in the spirit of our previous discussion concerning growth rates. We can now write the basic reaction-diffusion equation, as it is sometimes called, as

$$\begin{aligned} P_i(t) &= P_i(t-1) + \Delta P_i(t) \\ &= P_i(t-1) \left(1 + \omega + \phi K \sum_j \frac{P_j(t-1)}{c_{ij}^\eta} + \varepsilon_i(t-1) \right) \quad . \quad (51) \end{aligned}$$

This equation looks as though it applies to a zonal system but we can consider each index i or j simply a marker of location, and each population activity can take on any value; for single individuals it can be 0 or 1 while it might represent proportions of an

aggregate population or total numbers for the framework is entirely generic. As such, it is more likely to mirror a slow dynamics of development rather than a fast dynamics of movement although movement is implicit through the diffusive accessibility term.

We will therefore assume that the cells are small enough, space-wise, to contain single activities – a single household or land use which is the cell state – with the cellular tessellation usually forming a grid associated with the pixel map used to visualize data input and model output. In terms of our notation, population in any cell i must be $P_i(t) = 1$ or 0 , representing a cell which is occupied or empty with the change being $\Delta P_i(t) = -1$ or 0 if $P_i(t-1) = 1$ and $\Delta P_i(t) = 1$ or 0 if $P_i(t-1) = 0$. These switches of state are not computed by equation (51) for the way these cellular variants are operationalized is through a series of rules, constraints and thresholds. Although consistent with the generic model equations, these are applied in more *ad hoc* terms. Thus these models are often referred to as automata and in this case, as cellular automata (CA).

The next simplification which determines whether or not a CA follows a strict formalism, relates to the space over which the diffusion takes place. In the fast dynamic equilibrium models of the last section and the slower ones of this, interaction is usually possible across the entire space but in strict CA, diffusion is over a local neighborhood of cells around i , Ω_i , where the cells are adjacent. For symmetric neighborhoods, the simplest is composed of cells which are north, south, east and west of the cell in question, that is $\Omega_i = n, s, e, w$ – the so-called von Neumann neighborhood, while if the diagonal nearest neighbors are included, then the number of adjacent cells rises to 8 forming the so-called Moore neighborhood. These highly localized neighborhoods are essential to processes that grow from the bottom up but generate global patterns that show emergence. Rules for diffusion are based on switching a cell's state on or off, dependent upon what is happening in the neighborhood, with such rules being based on counts of cells, cell attributes, constraints on what can happen in a cell, and so on.

The simplest way of showing how diffusion in localized neighborhoods takes place can be demonstrated by simplifying the diffusion term in equation (50) as follows.

Then $\phi K \sum_j P_j(t-1) = \phi K \sum_j P_j(t-1) c_{ij}^{-\eta}$ as $c_{ij} = 1$ when $\Omega_i = n, s, e, w$. The cost is set as a constant value as each cell is assumed to be small enough to incur the same (or no) cost of transport between adjacent cells. Thus the diffusion is a count of cells in the neighborhood i . The overall growth rate is scaled by the size of the activity in i but this activity is always either $P_i(t-1) = 1$ or 0 , presence or absence. In fact this scaling is inappropriate in models that work by switching cells on and off for it is only relevant when one is dealing with aggregates. This arises from the way the generic equation in (51) has been derived and in CA models, it is assumed to be neutral. Thus the change equation (50) becomes

$$\Delta P_i(t) = \omega + \phi K \sum_j P_j(t-1) + \varepsilon_i(t) \quad , \quad (52)$$

where this can now be used to determine a threshold Z_{\max} over which the cell state is switched. A typical rule might be

$$P_i(t) = \begin{cases} 1 & \text{if } [\omega + \phi K \sum_j P_j(t-1) + \varepsilon_i(t)] > Z_{\max} \\ 0, & \text{otherwise} \end{cases} \quad . \quad (53)$$

It is entirely possible to separate the reaction from the diffusion and consider different combinations of these effects sparking off a state change. As we have implied, different combinations of attributes in cells and constraints within neighborhoods can be used to effect a switch, much depending on the precise specification of the model.

In many growth models based on CA, the strict limits posed by a local neighborhood are relaxed. In short, the diffusion field is no longer local but is an information or potential field consistent with its use in social physics where action-at-distance is assumed to be all important. In the case of strict CA, it is assumed that there is no action-at-a-distance in that diffusion only takes place to physically adjacent cells. Over time, activity can reach all parts of the system but it cannot hop over the basic cell unit. In cities, this is clearly quite unrealistic as the feasibility of deciding what and where to locate does not depend on physical adjacency. In terms of applications,

there are few if any urban growth models based on strict CA although this does rather beg the question as to why CA is being used in the first place. In fact it is more appropriate to call such models cell-space or CS models as Couclelis (1985) has suggested. In another sense, this framework can be considered as one for agent-based modeling where the cells are not agents and where there is no assumption of a regular underlying grid of cells (Batty, 2005a, 2005b). There may be such a grid but the framework simply supposes that the indices i and j refer to locations that may form a regular tessellation but alternatively may be mobile and changing. In such cases, it is often necessary to extend the notation to deal with specific relations between the underlying space and the location of each agent.

Empirical Dynamics: Population Change and City Size

We will now briefly illustrate examples of the models introduced in this section before we then examine the construction of more comprehensive models of city systems. Simple exponential growth models apply to rapidly growing populations which are nowhere near capacity limits such as entire countries or the world. In Figure 3, we show the growth of world population from 2000 BCE to date where it is clear that the rate of growth may be faster than the exponential model implies, although probably not as fast as double exponential. In fact world population is likely to slow rapidly over the next century probably mirroring global resource limits to an extent which are clearly illustrated in the growth of the largest western cities. In Figures 4(a) and 4(b), we show the growth in population of New York City (the five boroughs) and Greater London from 1750 to date and it is clear that in both cases, as the cities developed, population grew exponentially only to slow as the upper density limits of each city were reached.

Subsequent population loss and then a recent return of population to the inner and central city now dominate these two urban cores, which is reminiscent of the sorts of urban dynamic simulated by Forrester (1969) where various leads and lags in the flow of populations mean that the capacity limit is often overshoot, setting up a series of oscillations which damp in the limit. Forrester's model was the one of the first to grapple with the many interconnections between stocks and flows in the urban

economy although these relationships were predicated hypothetically in simple proportionate feedback terms. Together they generated a rich dynamics but dominated by growth which was capacitated, thus producing logistic-like profiles with the leads and lags giving damped oscillations which we illustrate from his work in Figure 5 (Batty, 1976). We will see that the same phenomena can be generated from the bottom up as indeed Forrester’s model implies, using cellular automata within a bounded spatial system.

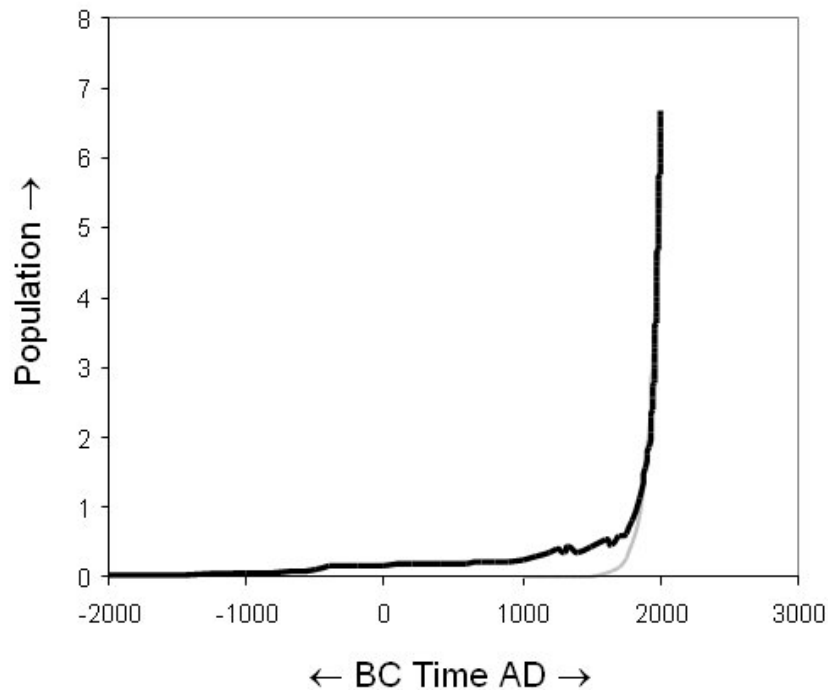


Figure 3: Exponential World Population Growth

The fitted exponential curve is shown in grey where for the most part it is coincident with the observed growth, except for the very long period before the Industrial Revolution (before 1750)

Dynamics which arise from bottom-up urban processes can be illustrated for a typical CA/CS model, DUEM (Dynamic Urban Evolutionary Model) originally developed by Xie (1994). In the version of the model here, there are five distinct land uses – housing, manufacturing/primary industry, commerce and services, transport in the form of the street/road network, and vacant land. In principle, at each time period, each land use can generate quantities and locations of any other land use although in practice only industry, commerce and housing can generate one other as well as generating streets. Streets do not generate land uses other than streets themselves. Vacant land is regarded as a residual available for development which can result from a state change (decline) in land use. The way the generation of land uses takes place is

through a rule-based implementation of the generic equation (51) which enables a land use k , $P_i^k(t)$, to be generated from any other land use ℓ , $P_j^\ell(t-1)$. Land uses are also organized across a life cycle from initiating through mature to declining. Only initiating land uses which reflect their relative newness can spawn new land use. Mature remain passive in these terms but still influence new location while declining land uses disappear, thus reflecting completion of the life cycle of built form.

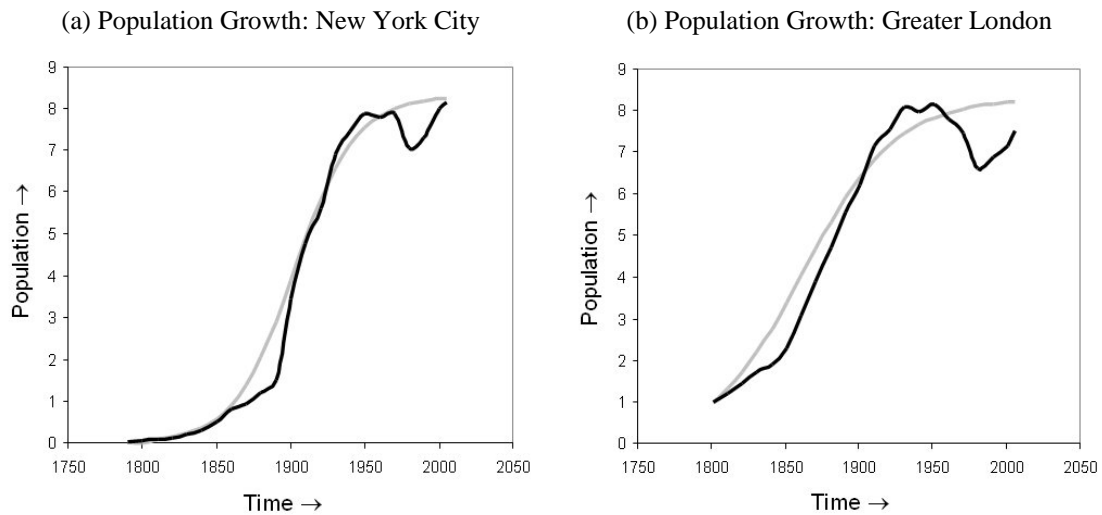


Figure 4: Logistic Population Growth

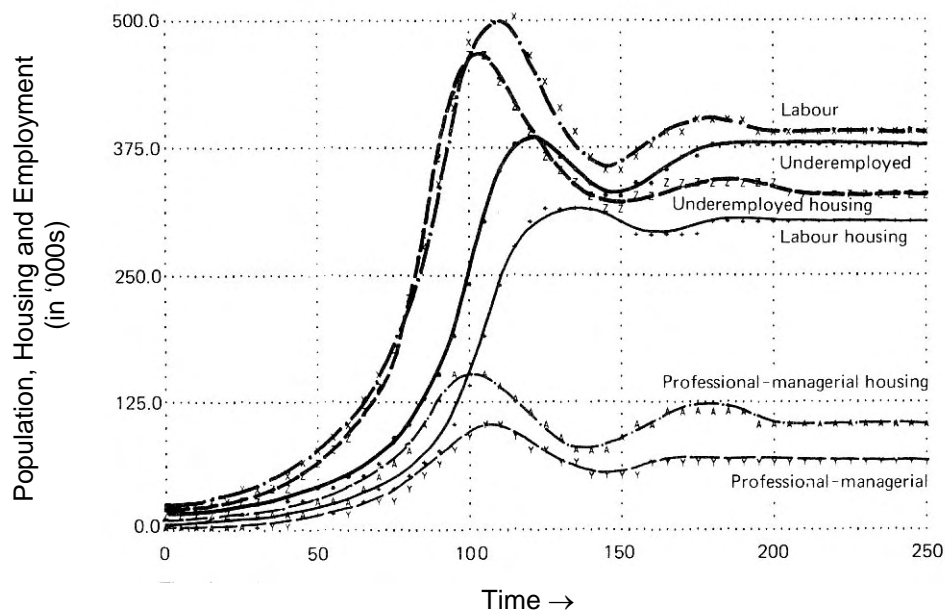


Figure 5: Oscillating Capacitated Growth in a Version of the Forrester Urban Dynamics Model (from Batty, 1976)

We are not able to present the fine details of the model here (see Batty, Xie and Sun, 1999, and Xie and Batty, 2005) but we can provide a broad sketch. The way initiating land uses spawn new ones is structured according to rule-based equations akin to the thresholding implied in equation (53). In fact, there are three spatial scales at which these thresholds are applied ranging from the most local neighborhood through the district to the region itself. The neighborhood exercises a trigger for new growth or decline based on the existence or otherwise of the street network, the district uses the densities of related land uses and distance of the new land use from the initiating use to effect a change, while the region is used to implement hard and fast constraints on what cells are available or not for development. Typically an initiating land use will spawn a new land use in a district only if the cells in question are vacant and if they are not affected by some regional constraint on development with these rules being implemented first. The probability of this land use occurring in a cell in this district is then fixed according to its distance from the initiating location. This probability is then modified according to the density of different land uses that exist around each of these potential locations – using compatibility constraints – and then in the local neighborhood, the density of the street network is examined. If this density is not sufficient to support a new use, the probability is set equal to zero and the cell in question does not survive this process of allocation. At this point, the cell state is switched from ‘empty’ or ‘vacant’ to ‘developed’ if the random number drawn is consistent with the development probability determined through this process.

Declines in land use which are simply switches from developed to vacant in terms of cell state are produced through the life cycling of activities. When a mature land use in a cell reaches a certain age, it moves into a one period declining state and then disappears at the end of this time period, the cell becoming vacant. Cells remain vacant for one time period before entering the pool of eligible locations for new development. In the model as currently constituted, there is no internal migration of activities or indeed any mutation of uses but these processes are intrinsic to the model structure and have simply not been invoked. The software for this model has been written from scratch in *Visual C++* with the loosest coupling possible to GIS through the import of raster files in different proprietary formats. The interface we have developed, shown below, enables the user to plant various land use seeds into a virgin landscape or an already developed system which is arranged on a suitably registered

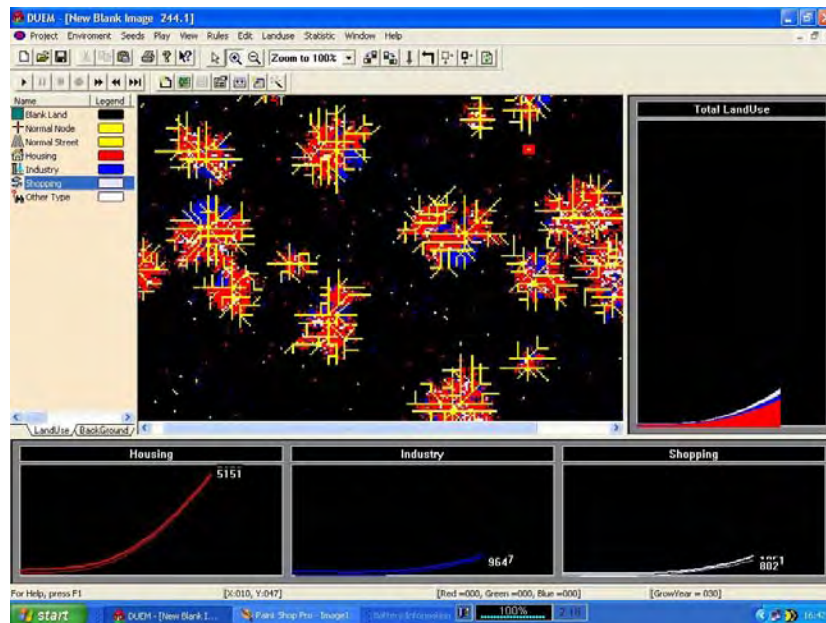
pixel grid which can be up to 3K x 3K or 9 million pixels in size. A map of this region forms the main window but there are also three related windows which show the various trajectories of how different land uses change through time with the map and trajectories successively updated in each run.

A feature which is largely due to the fact that the model can be run quickly through many time periods, is that the system soon grows to its upper limits with exponential growth at first which then becomes logistic or capacitated. In Figure 6, we show how this occurs from planting a random selection of land use seeds in the region and then letting these evolve until the system fills. Because there are lags in the redevelopment of land uses in the model due to the life cycle effects, as the system fills, land is vacated. This increases the space available for new development leading to oscillations of the kind reflected in Forrester's model shown in Figure 5 and more controversially in the real systems shown for New York City and Greater London in Figure 4. In this sense, a CA model has a dynamics which is equivalent to that of the more top-down dynamics where growth is modeled by exponential or logistic functions. CA models however generate this as an emergent phenomena from the bottom up.

Our last demonstration of CA really does generate emergent phenomena. This is a model of residential movement that leads to extreme segregation of a population classified into two distinct groups which we will call red R and green G. Let us array the population on a square grid of dimension 51 x 51 where we place an R person next to a G person in alternate fashion, arranging them in checker board style as in Figure 7(a). The rule for being satisfied with one's locational position viz a viz one's relationship to other individuals is as follows: persons of a different group will live quite happily, side by side with each other, as long as there are as many persons of the same persuasion in their local neighborhood. The neighborhood in this instance is the eight cells that surround a person on the checkerboard in the *n*, *s*, *e*, *w*, and *nw*, *se*, *sw*, and *ne* positions. If however a person finds that the persons of the opposing group outnumber those of their own group, and this would occur if there were more than 4 persons of the opposite persuasion, then the person in question would change their allegiance. In other words, they would switch their support to restore their own equilibrium which ensures that they are surrounded by at least the same number of

their own group. There is a version of this model that is a little more realistic in which a person would seek another location – move – if this condition were not satisfied rather than change their support, but this is clearly not possible in the completely filled system that we have assumed; we will return to this slightly more realistic model below.

(a) Land Use Seeds as Developing Cities



(b) Capacitated Growth with Cycling

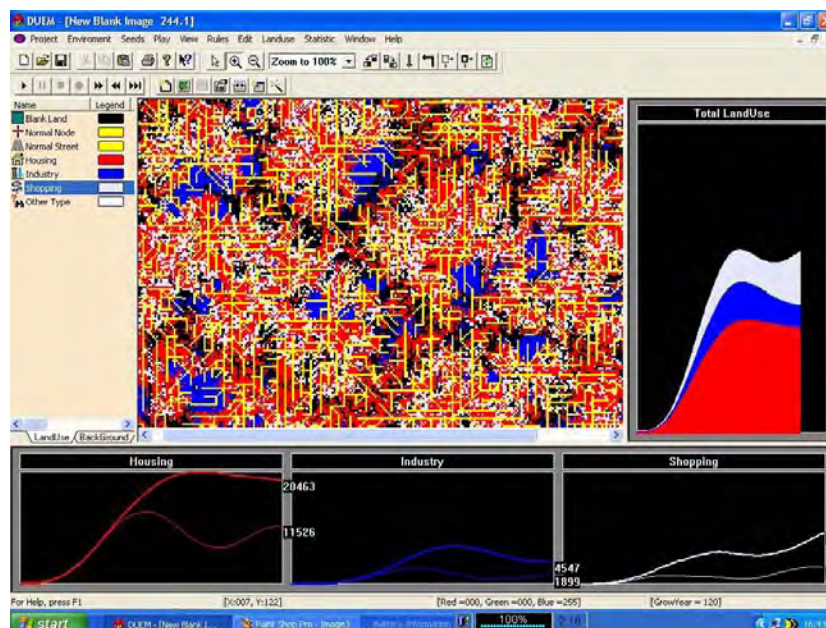


Figure 6: Cellular Growth using the *DUEM* Model

In Figure 7(a), the alternative positioning shown in the checker board pattern meets this rule and the locational pattern is in 'equilibrium': that is, no one wants to change their support to another group. However let us suppose that just six persons out of a total of 2601 (51 x 51 agents sitting on the checker board) who compose about 0.01 percent of the two populations, change their allegiance. These six changes are easy to see in Figure 7(a) where we assume that four R persons of the red group, change in their allegiance to support the green group, and two Gs change the opposite way. What then happens is the equilibrium is upset in these locations but instead of being quickly restored by local changes, this sets off a mighty unraveling which quickly changes the locational complexion of the system to one where the Rs are completely and utterly segregated from the Gs. We show this in Figure 7(b). From a situation where everyone was satisfied and mixed completely, we get dramatic segregation which is a most unusual consequence. At first sight, one would never imagine that with so mild a balance of preferences, such segregation would take place. The ultimate pattern implies that Rs will live nowhere near Gs unless they really have to and there is nowhere else to live and vice versa. If an R or a G could not tolerate more than one person of a different kind living near them, then such segregation would be understandable but this is not the case: Rs are quite content to live in harmony with Gs as long as the harmony is equality.

This model was first proposed more than 30 years by Schelling (1969, 1978). In fact we can make this a little more realistic if we provide some free space within the system. In this case, we assume that 1/3 of the lattice is empty of persons of any kind, 1/3 composed of Rs, and 1/3 of Gs, and we mix these randomly as we show in Figure 7(c). Now the rule is slightly different in that if there are more opposition persons around a person of one persuasion, then that person will try to move his or her location to a more preferential position. This sets up a process of shuffling around the checker board but as we show in Figure 7(d), quite dramatic shifts take place in location which leads to the segregation shown. This is the kind of effect that takes place in residential areas in large cities where people wish to surround themselves with neighbors of their own kind. What is surprising about the phenomena which makes it 'emergent' is that for very mild preferential bias, dramatic segregation can take place. Of course if the preferences for like neighbors are very strong anyway, then segregation will take place. But in reality, such preferences are usually mild

rather than strong, yet extreme segregation takes place anyway. The conclusion is that cities often look more segregated around racial and social lines than the attitudes of their residents might suggest.

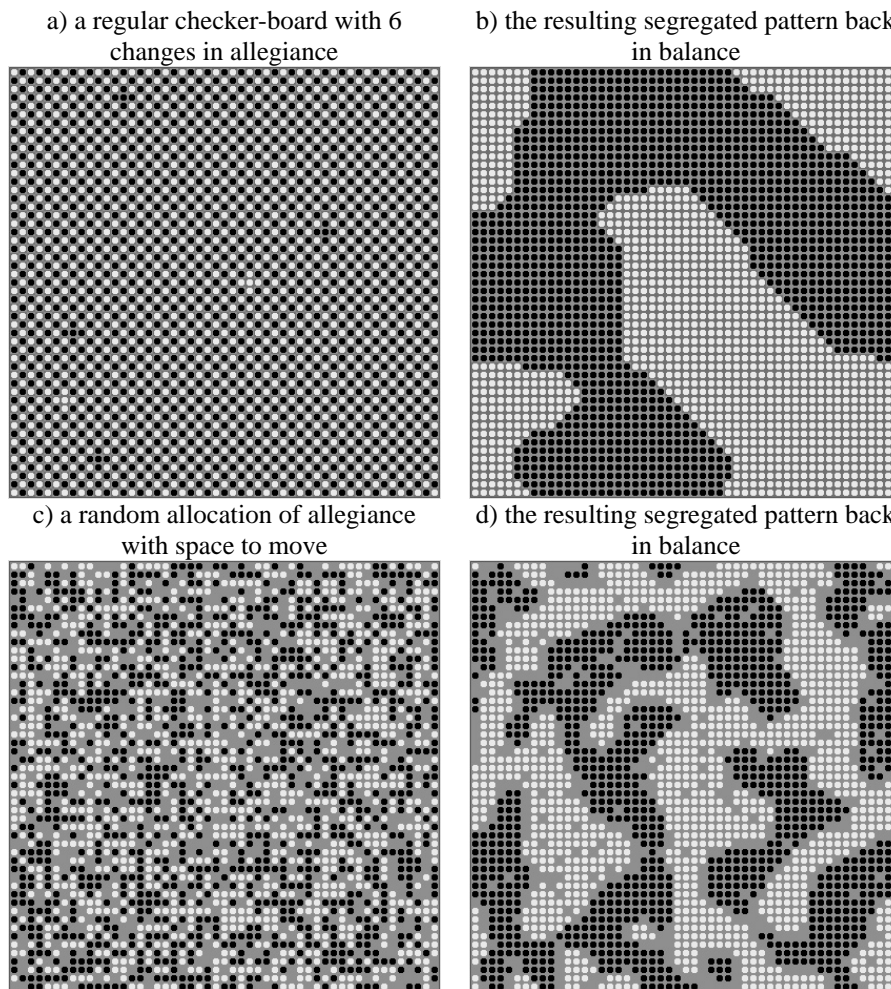


Figure 7: Emergent Segregation: A Fragile Equality (a) gives way to Segregation (b); A Random Mix with Available Space (c) gives way to Segregation (d)

Comprehensive System Models of Urban Structure

Integrated Land Use Transport Models

The various components used to model cities in equilibrium were quickly assembled into structures that attempted to simulate urban structure and growth from the 1960s onwards. These models were referred to as land use transport models in that their aim was to simulate the locations of different land uses and their consequent patterns of

traffic generation, usually according to spatial interaction principles based on gravitational assumptions. But they usually represented cities as demographic and economic activities – population, households, employment and so on – rather than as residential, commercial or industrial land use. In short the city system was seen to operate at the level of the location of activities which then consumed space through land use from which traffic was generated, and once urban activities and their interactions were predicted, appropriate translations were made into land use. As we shall see, this is not as unproblematic as was originally thought.

The integration of urban activities and their interactions – land use and transport – can be accomplished using a variety of economic frameworks built around economic relationships between activities. Traditionally these have been represented as input-output models where one activity is linked to another and it is possible to predict the chain of linkages between all the activities using multipliers. We will illustrate this for two activities: we assume that employment E is divided into an unpredictable component, sometimes considered as employment that is basic B and export orientated in the economy, and employment that is non-basic S where $E = B + S$. Non-basic employment services the population P from which it is derived as $S = bP$. If we then consider that population can be generated by applying an activity rate a to employment as $P = aE$, we have the rudiments of a generative sequence that forms a structure for predicting activities and their locations which are highly interdependent. Simple manipulation of these relationships shows that $E = B(1 - ba)^{-1}$ where $(1 - ba)^{-1}$ is the multiplier central to traditional macro-economic theory.

If we now consider that employment and population are related spatially through their interactions, we model the relationship between employment as population using a singly-constrained sub-model

$$P_j = a \sum_i T_{ij} = a \sum_i E_i \frac{F_j c_{ij}^{-\psi}}{\sum_k F_k c_{ik}^{-\psi}}, \quad (54)$$

where T_{ij} are work trips between i and j , F_j is some measure of attraction at residential location j , and ψ is the friction of distance/travel cost parameter. Employment is modeled in reverse direction as

$$E_i = b \sum_j S_{ji} = b \sum_j P_j \frac{F_i c_{ji}^{-\varpi}}{\sum_k F_k c_{ki}^{-\varpi}}, \quad (55)$$

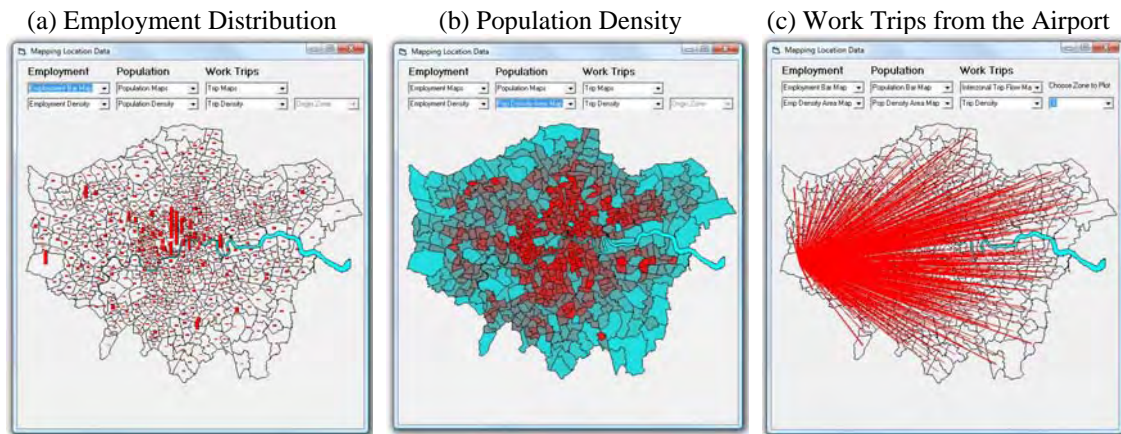
where S_{ji} are employment demands in j from i , F_i is some measure of attraction at residential location i , and ϖ is the friction of distance/travel cost parameter. These two equations for the two sectors are not usually solved simultaneously but the chain is broken in that we start with basic employment B in equation (54), predicting basic population, then using this basic population in equation (55) to produce an increment of non-basic employment which in turn is used to predict the next increment of non-basic population in equation (54). This iteration converges to the multiplier relationships $E = B(1 - ba)^{-1}$ and $P = bB(1 - ba)^{-1}$.

This kind of sequence can be disaggregated indefinitely with respect to population and employment types and linked demands to other sectors. Education, leisure and so on can be added to the framework making the model ever more comprehensive. This was the model first developed by Lowry (1964). It is still the most widely applied of all operational urban models and has been elaborated in various ways, some of them dealing with partial dynamics (Batty, 1976). Their theoretical pedigree is rooted largely in regional economics, location theory and the new urban economics which represent the spatial equivalents of classical macro and micro economics. The most coherent recent statement in this vein is based on applications of trade theory to the urban economy as reflected in the work of Fujita, Krugman and Venables (1999) but there is a long heritage of empirical models in the Lowry (1964) tradition which continue to be built (Wegener, 2005).

These models now incorporate the four-stage transportation modeling process of trip generation, distribution, modal split and assignment explicitly and they are consistent with discrete choice methods based on utility maximizing in their simulation of trip-

making (Ben Akiva and Lerman, 1985). They have been slowly adapted to simulate dynamic change although they still tend to generate the entire activity pattern of the city in one go, and they remain parsimonious in that the assumption is that all the outcomes from the model can be tested in terms of their goodness of fit. They have also become more disaggregate and there are now links to physical land use although they still remain at the level of activity allocation despite their nomenclature as land use transport models. In short, this class of models is the most operational in that newer styles tend to be less comprehensive in their treatment of urban activities and transportation. Probably the most highly developed of these models currently is the UrbanSim model (Waddell, 2002) although the MEPLAN, TRANUS and IRPUD models, whose most recent versions were developed in the EU Propolis (2004) project, also represent the state-of-the-art.

To conclude this section, it is worth showing a visualization from one of these land use transport models which we have recently built for the London region as part of an integrated assessment of climate change in the metropolis. The component we show is a residential location model which predicts the flow of workers from employment locations to residential areas using four different modes of transport and disaggregated into five employment and five household types. In Figure 8(a), we show some outputs from the model – the observed employment distribution, the pattern of population density, and total work trips from the airport (Heathrow) zone in the base year simulation 2005. This kind of model assumes that employment and the travel cost network are exogenously determined and thus ‘what-if’ style questions can be thrown at the model to be evaluated in terms of the impact of changes in the transport network and employment volumes on the location of population. We illustrate such a scenario builder for changes in the transport routes and costs in Figure 8(b) which provides some sense of how such complexity can be visualized. These are key issues in planning policy for the future growth of London, particularly with respect to flooding in the Thames Estuary which is likely to be affected by climate change. These kinds of models are hardly routine but they are being developed now in many places.



(a) (d) Building a Transport Scenario: Changing the Travel Costs from a Fast Rail Line

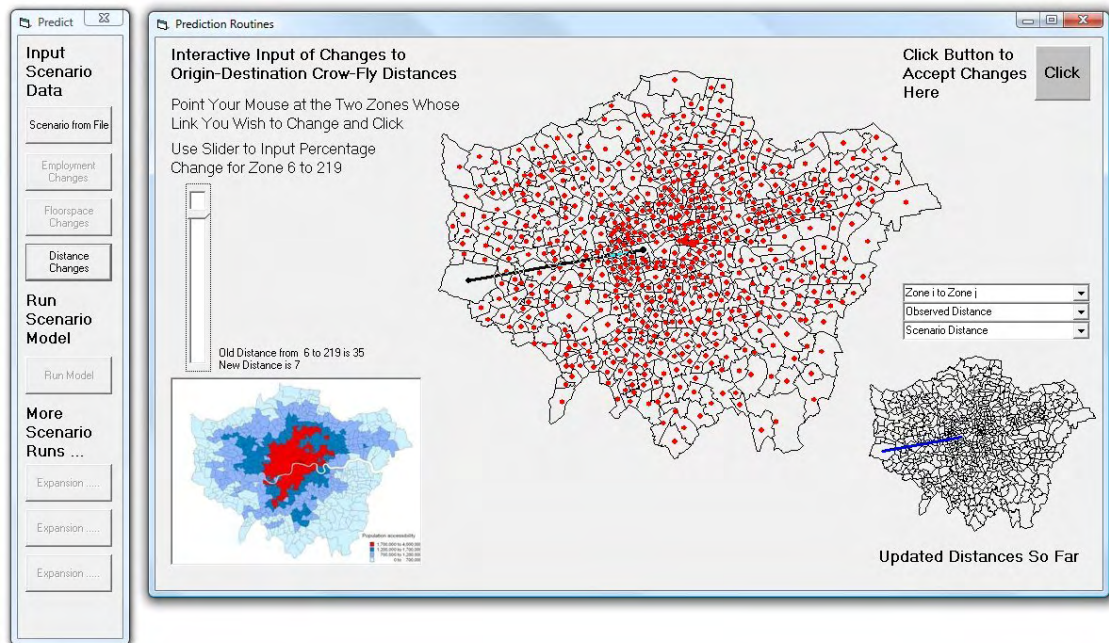


Figure 8: Visualization of Outputs from a Greater London Land Use Transport Model

Agent-Based and Cellular Automata Models of Land Development

The first bottom-up CA models applicable to urban structure and growth can be traced back to the 1960s. Chapin and Weiss (1968) used cell-space (CS) simulation whose locational attractions were based on linear regression, in their models of urban growth in Greensboro, North Carolina. Lathrop and Hamburg (1965) used gravitational models to effect the same in simulating growth in the Buffalo-Niagara region while from a rather different perspective, Tobler (1970) used CA-like simulation to generate a movie of growth in the Detroit region. All these applications were on the edge of the

mainstream which 30 years ago was based not on formal dynamics but on cross-sectional equilibrium models of the variety presented above. In the intervening years, CA insofar as it was considered a simulation tool, was regarded as important mainly for its pedagogic and analytical value (Couclelis, 1985). It was not until the early 1990s that models began to emerge which were considered to be close enough to actual urban growth patterns to form the basis for simulation and prediction. In fact, there still exists a recurrent debate about whether or not CA models are more important for their pedagogic value rather than for their abilities to simulate real systems. These require gross simplifications of model processes and spatial units, sometimes rendering them further from reality than the static cross-sectional models that came before.

The three earliest attempts at such modeling were geared to simulating rapid urban growth for metropolitan regions, medium-sized towns, and suburban areas. Batty and Xie (1994) developed simulations of suburban residential sprawl in Amherst, New York, where a detailed space-time series of development was used to tune the model. Clarke and Gaydos (1998) embarked on a series of simulations of large-scale metropolitan urban growth in the Bay Area and went on to model a series of cities in the US in the Gigaopolis project. White and Engelen (1993) developed a CA model for Cincinnati from rather crude temporal land use data and in all these cases, the focus was on land development, suburbanization, and sprawl. Since then, several other groups have developed similar models focusing on suburbanization in Australian cities (Ward, Murray, and Phinn, 2000), 'desakota' – rapid urban growth in rural areas in China – specifically in the Pearl River Delta (Yeh and Li, 2000), diffused urban growth in Northern Italy (Besussi, Cecchini, and Rinaldi, 1998), and rapid urbanization in Latin American cities (Almeida et al., 2003). Other attempts at modeling and predicting sprawl have been made by Papini et al. (1998) for Rome and Cheng (2003) for Wuhan, while Engelen's group at RIKS in the Netherlands has been responsible for many applications of their model system to various European cities (Barredo, Kasanko, McCormick, and Lavalle, 2003).

There are at least four applications which do not focus on urban growth *per se*. Wu and Webster (1998) have been intent on adding spatial economic processes and market clearing to such models, while Portugali and Benenson (1996) in Tel-Aviv

have focused their efforts on intra-urban change, particularly segregation and ghettoization. Sembloni (2000) has worked on adding more classical mechanisms to his CA models reflecting scale and hierarchy as well as extending his simulations to the third dimension, while there have been several attempts by physicists to evolve a more general CA framework for urban development which links to new ideas in complexity such as self-organized criticality and power law scaling (Andersson, Rasmussen, and White, 2002; Schweitzer and Steinbrink, 1997).

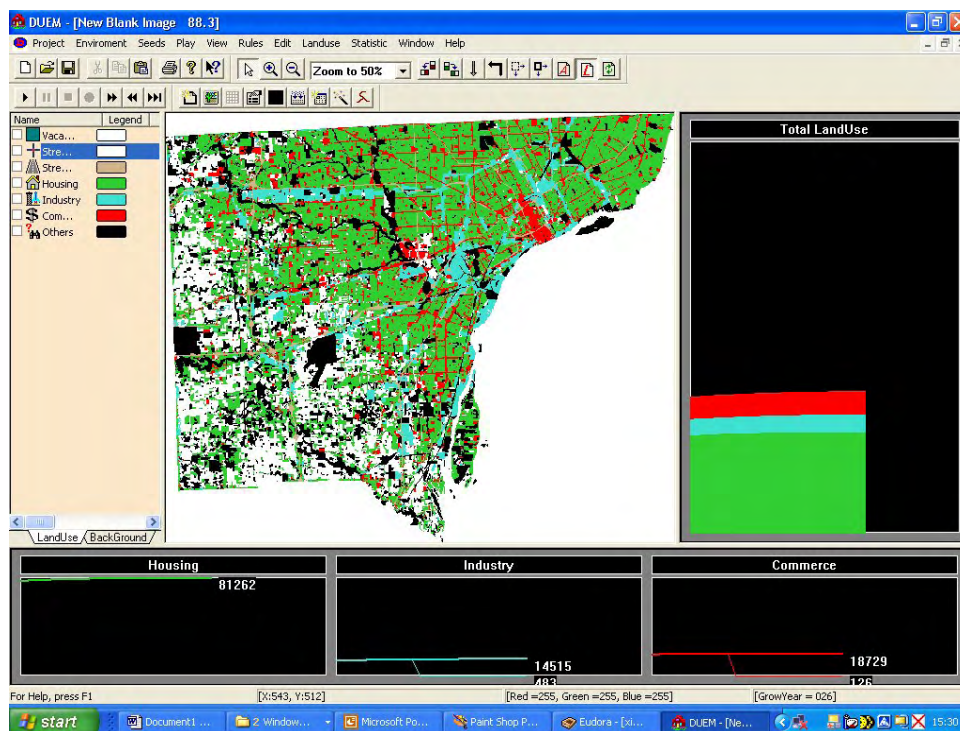


Figure 9: Simulating Very Slow Growth and Rapid Decline in the Detroit Region Using the CA DUEM Model

It is worth showing some graphics from such CA models as they are being applied to real cities. In Figure 9, we show how the DUEM model can be used to simulate the pattern of development change in the Detroit region of South East Michigan. In a sense because we live in world dominated by a somewhat unhealthy interest in growth, it might be assumed that all the models we have presented here are only geared to simulating new development. In fact, each of these models can simulate decline or reproduce the steady state because CA models can solely deal with transitions and change in the existing fabric as we illustrated earlier in the Schelling segregation model. This is the case in Detroit where the population has rapidly adjusted and

segregated its locations in the last 50 years but in a context where the overall growth has been extremely modest with many areas growing very fast in the suburbs but the central areas declining at similar rates. The profile in Figure 9 is akin to a steady state rather than the overall exponential growth or decline shown in previous examples.

There are some agent-based models at the land use or activities level which enable predictions of future urban patterns but the main focus is at the very micro-level where local movements in terms of traffic are being simulated (Castle and Crooks, 2006). Several models that approach the agent-based ideal originate from other areas. TRANSIMS is a hybrid in that its roots are in agent-based simulation of vehicles but it has been scaled to embrace urban activities (Nagel, Beckman, and Barrett, 1999) and even UrbanSim can be interpreted through the agent paradigm. A parallel but significant approach to individualistic modeling is based on micro-simulation which essentially samples individual behavior from more aggregate distributions and constructs synthetic agent-based models linked to spatial location (Clarke, 1996). This is a rapidly changing field at the present time with no agreement about terminology. The term agent is being used to describe many different types of models with some focusing on unique objects ranging from cells or points in space where activities or individuals exist to models of institutions and groups with only implicit spatial positioning (Gilbert, 2007).

Models of Urban Morphology

The models introduced above do not capture many of the physical features of cities and regions in terms of their morphology. Cities are highly organized with respect to their form, displaying as we have already seen in terms of city size, clusters of activity on all scales, in short, fractal (Batty and Longley, 1994). Insofar as static equilibrium models are able to reproduce this form and to an extent they are able to do so, this is largely because some of the structure of the city is input into these models through existing employment and population distributions which have already captured elements of the morphology. There are competitive effects in these models too that are intrinsic to these simulations with the dynamic models based on cellular automata closest to reflecting these processes in urban form. This is because the process of development is generated from the bottom up and agglomeration is a key feature of

the processes of development that are simulated as in some of the models discussed in the last section. Here we will simply illustrate some of the evolving forms that various combinations of the models already discussed are able to simulate. This shows how various processes of land development and travel behavior can come together to generate structures that are close to what we observe in the real world.

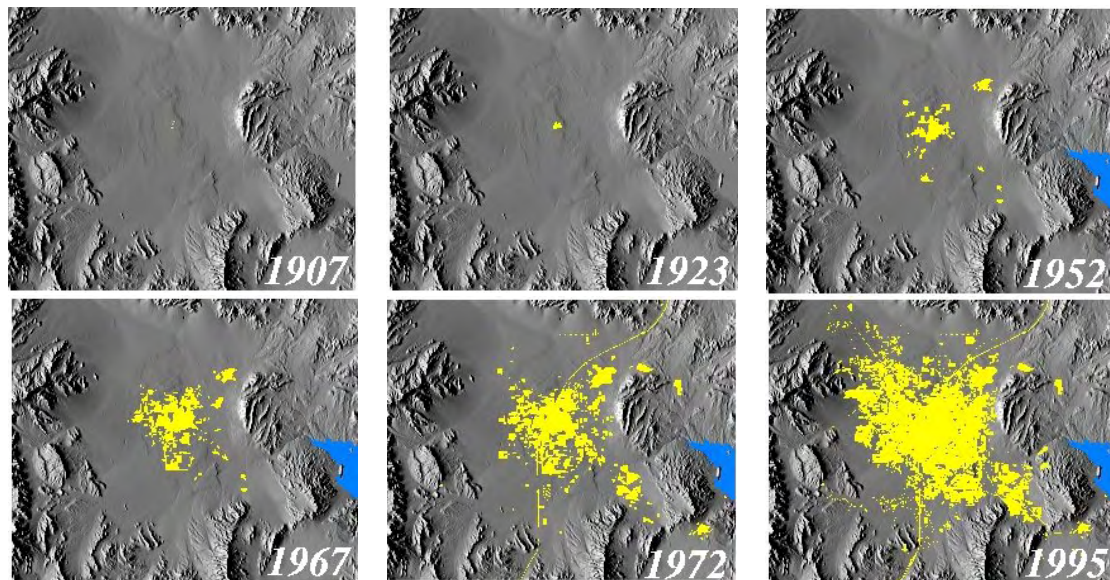


Figure 10: The Growth of Las Vegas from 1907 to 1995
(from Acevedo et al., 1997)

A good example of the urban growth which has been rapid over the last 50 years is Las Vegas, the fastest growing metropolitan area in the United States which is illustrated in Figure 10 (Acevedo et al., 1997). The sprawl does not look very different from time period to time period although it is clear that growth is clustered and these clusters tend to merge as the city grows. In this sense, the pattern always looks like more of the same from time period to time period but inside the city, things have changed rather more dramatically as the place has moved from desert oasis and staging post prior to 1950 to the entertainment and gambling capital of the US. Exponential growth of population, employment and tourism is implied by this volume of urban development mirroring the simplest ‘un-capacitated’ growth model in equations (36) and (37). The fact that the city has grown in some directions rather than others is largely due to a combination of physical and accidental historical factors and does not imply any differences in the way growth has occurred from one time period to the next.

Cellular automata models can generate such growth where entirely local development rules are operated uniformly across the space to grow a city from a single seed. This can lead to fractal patterns, patterns that are self-similar in form with respect to scale, of the kind observed in real cities. In Figure 11(a), we show how the operation of deterministic rules where a cell is developed if there is one and only one cell already developed in its immediate neighborhood, leads to a growing structure. This is a typical example of a modular principle that preserves a certain level of density and space when development occurs but when operated routinely and exhaustively leads to cellular growth that is regular and self-similar across scales, hence fractal. In Figure 11(b), the shape of the structure generated is now circular in that development eventually occurs everywhere. The city fills up completely but the order in which this takes place is a result of development taking place at each time period with random probability. This is the effect of introducing ‘noise’ or ‘diversity’ into the model used to generate the sequence in Figure 11(a).

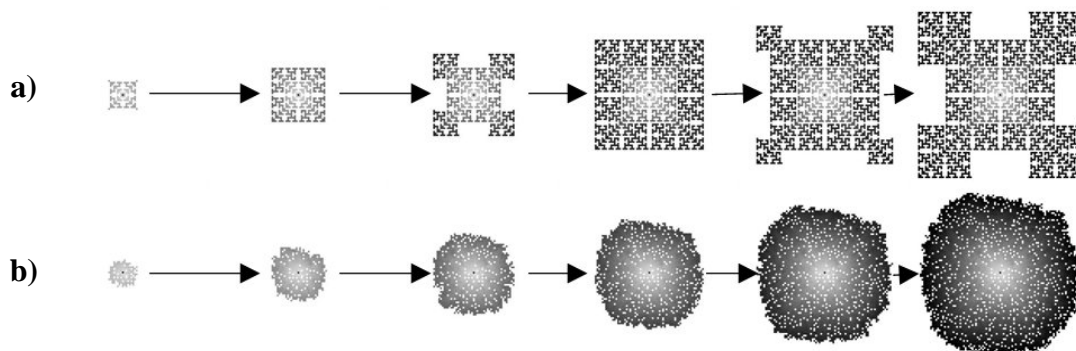


Figure 11: Growth from the Bottom Up

- a) deterministic growth based on developing cells if one and only one cell is already developed in their 8 cell adjacent neighborhood, and b) stochastic growth based on developing cell if any cell is developed in the adjacent neighborhood according to a random probability

If urban growth is modular and scales in the simplistic way that is portrayed in these models of fractal growth, then it is not surprising that there is a tendency to explain such patterns generically, without regard to growth *per se*; to study these as if they represent systems with an equilibrium pattern that simply scales through time. But this is a trap that must be avoided. Dig below the surface, and examine the processes of growth and the activities that occupy these forms, disaggregate the scale and change the time interval, and this image of an implied stability changes quite radically.

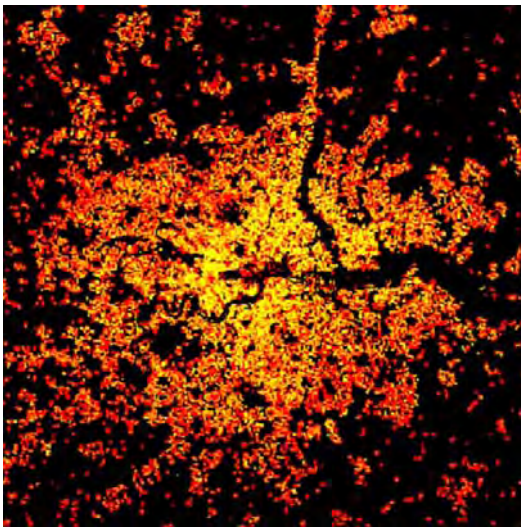
During the era pictured in Figure 10, technology has changed dramatically. Las Vegas did not acquire its gambling functions until the 1950s but by then it was already growing fast and the subsequent injection of cash into its local economy, the largest per capita in the western world for those who reside there, did little to change the pattern of explosive growth that followed. The manner in which people moved in the early Las Vegas was by horse and wagon but the city could only grow with the car, the plane and air-conditioning, not to say the incredible information technologies that now dictate how one gambles, wins, and loses.

Our six frame 'movie' of the growth of Las Vegas does reveal that the established pattern of adding to the periphery is not entirely the complete story for small blobs of development seem to attach themselves and then are absorbed back into the growing mass as growth catches them up. In this case, this is simply housing being constructed a little beyond the edge due to the mechanics of the development process. In older, more established settlement patterns such as those in Western Europe for example, this might be the absorption of older villages and freestanding towns into the growing sprawl. Consider the picture of population density in London recorded in 1991 and illustrated in Figure 12(a). Here there are many towns and villages that existed long before London grew to embrace them. If we define the metropolis as the connected network of settlement that fills an entire space where everyone can connect to everybody else either directly or indirectly, the picture is similar as we show in Figure 12(b).

One could envisage London being connected in this way with a much sparser network of links while at the other extreme the entire space could be filled. In fact, it would seem that the level of connectivity which has evolved with respect to the density of the space filled is just enough for the city to function as a whole. It is this morphology and degree of connectivity that marks the fact that the city has reached a level of self-organization which is regarded as critical. If connectivity were greater, more space would be filled and many more connections put in place but the structure would contain a certain degree of redundancy making it inefficient. Below this, the system would not be connected at all and it would not function as a metropolis. In fact there are strong relationships to this characterization of urban settlement as a porous media in which a phase transition might take place as the system fills up which in network

terms, is like a percolation threshold (Batty, 2005b). The models that we have sketched above all provide ways of generating these kinds of morphology, albeit through somewhat different mechanisms than the obvious way in which growth in physical systems takes place. The forms generated constitute an essential check on the adequacy or otherwise of these system models.

(a) population density on a 200m grid from the 1991 Census of Population



(b) The evolution of the road network over the last 500 years from the centre outwards



Figure 12: Greater London: Self-Similar Clusters and the Connectivity Network within the Sprawl

Future Directions

The biggest problems facing the development of complex systems models in general and those applied to cities in particular involve validation. The move from articulating systems as organized entities structured from the top down based on some sort of centralized control mechanisms to systems that grow in an uncoordinated way from the bottom up have also shifted our perspective from developing systems model in a parsimonious way to developing much richer models requiring more detailed data. In short, complexity theory has changed the basis for theory and model selection from an insistence that all models must be testable against data to an acceptance that if there is a strong reason why some non-testable propositions should be included in a model (as models with very rich behaviors and processes imply), then these should be included

even if they cannot be tested. This is consistent with the shift from aggregate to disaggregate modeling, from the focus on equilibrium to dynamics, and on processes and behaviors rather than simply outcomes.

This changes the entire basis of validation and combined with the difficulties of articulating processes which are clearly relevant but often unobservable, the way in which models might be useful in policy making in complex systems is changing too. Modeling is now much more contingent on context and circumstance than at any time in the past. The use of multiple models, counter modeling and the synthesis of different and often contradictory model structures is now taken for granted in systems where we consider there may be no optimal solutions and where there will always be dissent from what is regarded as acceptable. Many newer models such as those based on cellular and agent-based structures and those which postulate a dynamics that involves bifurcations that are often of only theoretical interest until one such dynamic is observed, are unlikely to meet the canons of parsimony in which unambiguous tests can be made against data. These limits to validation begin to suggest that complex system models need to be classified on a continuum of ways in which they can be tested and used in practice which will depend on the type of model, the context, and the users involved (Batty and Torrens, 2005).

In terms of more substantive developments, the question of dynamics is still of burning importance in developing better models of cities. There is an intrinsic problem of articulating urban processes of change from sparsely populated data bases which often contain only the aggregate outcomes of multiple processes. The way in which our commonsense observations of decision making in cities can be linked to more considered outcomes represented in data has barely been broached in developing good models of urban spatial behavior. In agent-based modeling, the role of cognition is important while the question of defining agents at appropriate levels is a major research focus, particularly when it comes to aggregates which are of a more abstract nature, such as groups and institutions. However what is of clear importance is the fact that as our focus becomes finer and as we disaggregate to ever more detailed levels, we then begin to represent policy processes into which these models might be nested in more detailed ways, implying that policy making and planning itself might be simply one other feature of these system models.

In short in our quest for more detail and for embracing a wider environment, city models have come to encapsulate the control mechanisms themselves as intrinsic to their functioning. It is at this point that we need much better ways of showing how such models can be used in practice. To an extent, this implies that we need to link these system models to their wider context of use and application, showing how other conceptions, other systems models, might be related to them in less formal ways than in terms of the science we have presented here. This has always been a challenge for the application of complexity theory to human and social systems, and it will remain the cutting edge of this field whose rationale is the prediction and design of more efficient, equitable, and sustainable cities.

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