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Fundamental Study of Corrective Abrasive Machining Technology

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Chen, Xun (2009) Fundamental Study of Corrective Abrasive Machining Technology. In: CIRP UK Meeting , 8th May 2009. (Unpublished)

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CIRP UK Meeting 8th May 2009



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Fundamental Study of Corrective Abrasive Machining Technology

Dr Xun Chen



Advanced Machining Technology Group
Centre for Precision Technologies
School of Computing and Engineering





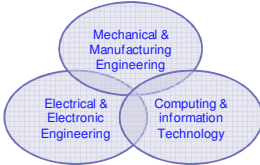

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Precision machining technology

*Unique pioneer challenge in developing
next generation machining technology*

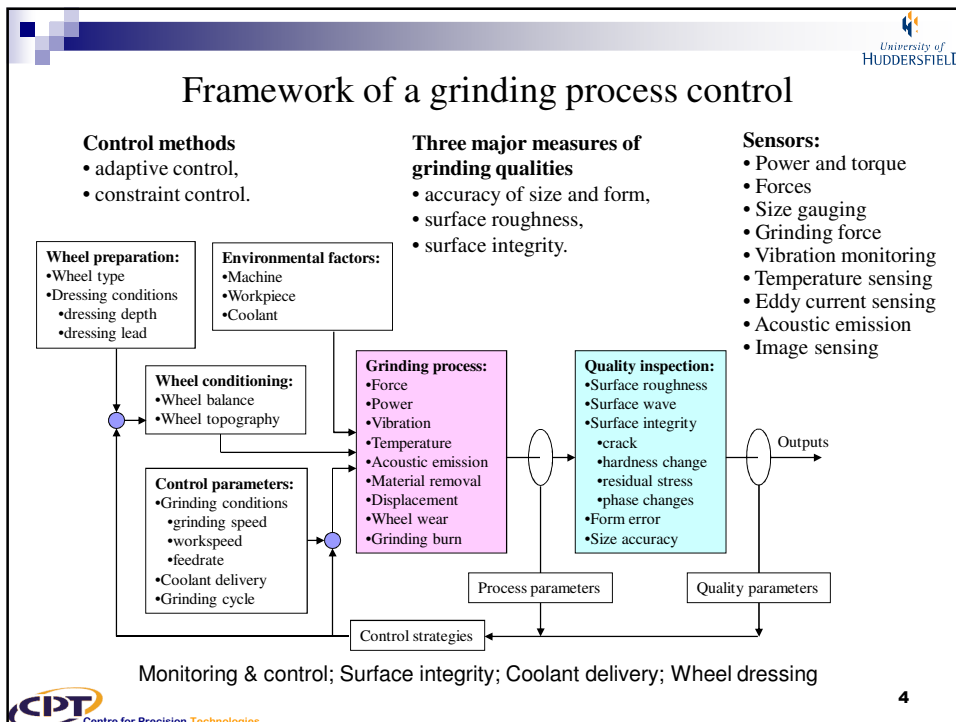
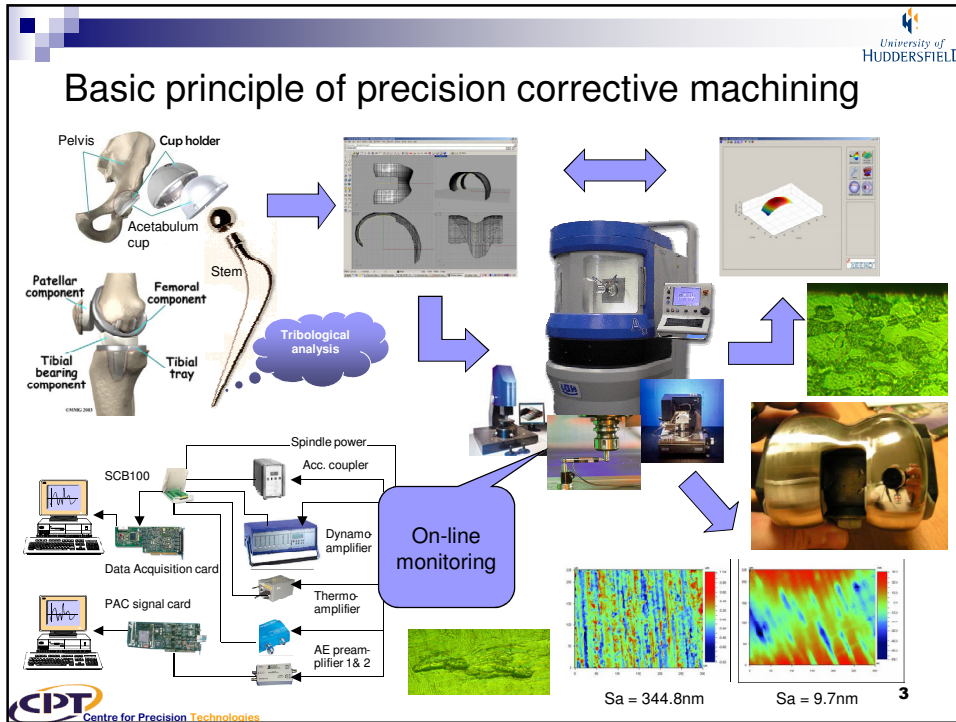
Current Research Themes

- Precision machining
 - Abrasive machining
 - Diamond turning
 - Finite element analysis and molecular dynamics
- Intelligent process monitoring and control
 - Contact detection using acoustic emission
 - Abrasive machining monitoring using AI techniques
- Knowledge support systems
 - Database / Knowledge warehouse

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Educating tomorrow's professionals



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From the macroworld to the nanoworld

(The Hitchhiker's Guide to Nanotechnology, 2006)

Micro-machining is considered to cover the production of minute components and features from a wide range of materials, generally in the size range of 200 microns to a few nanometres and may also be known as micro drilling, micro cutting, micro milling, micro grinding and micro etching.

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Challenge of nanometre scale machining

Sa < 1 nm
Form error < 0.1 μm

Aluminum (Al) Sa = 0.742 nm

- Spindle RPM: 2000
- Finish Feedrate: 7.5 mm/min
- Finish Depth of Cut: 2 μm
- Coolant: Odorless Mineral Spirits

Nickel (Ni) Sa = 0.924 nm

- Spindle RPM: 3000
- Finish Feedrate: 5 mm/min
- Finish Depth of Cut: 4 μm
- Coolant: Odorless Mineral Spirits

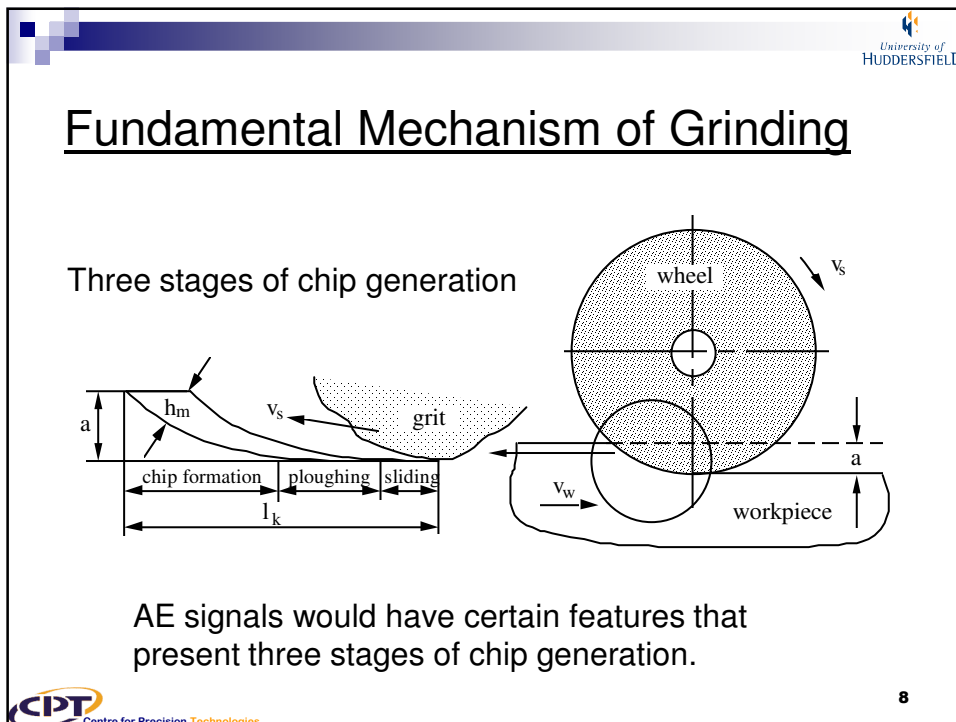
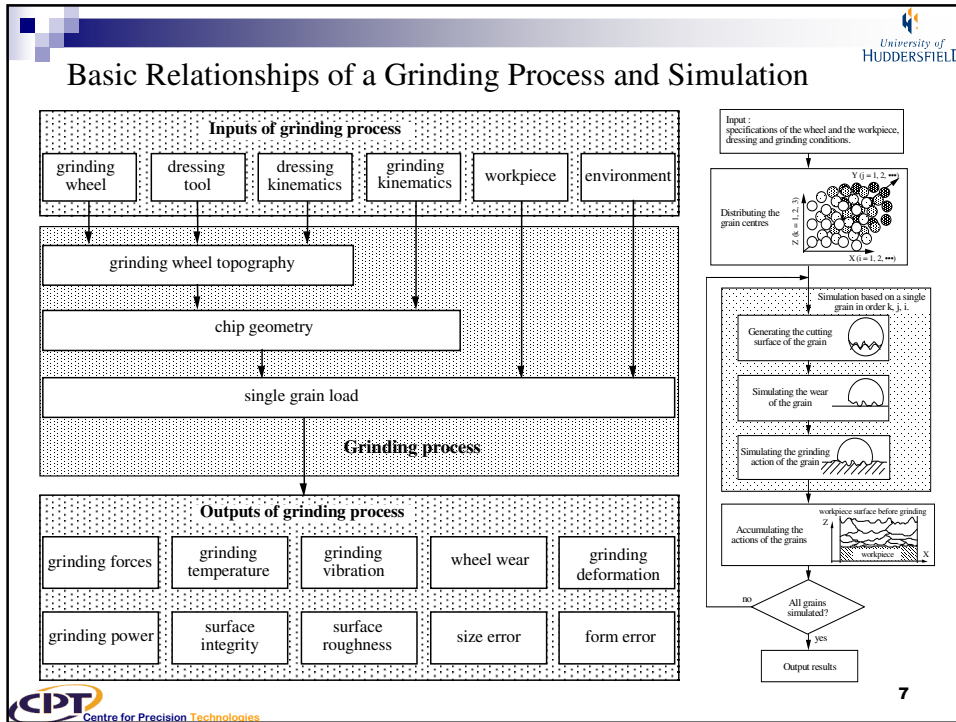
Grain boundary indicates the limitation of the conventional turning operation limitation.

What can be done?

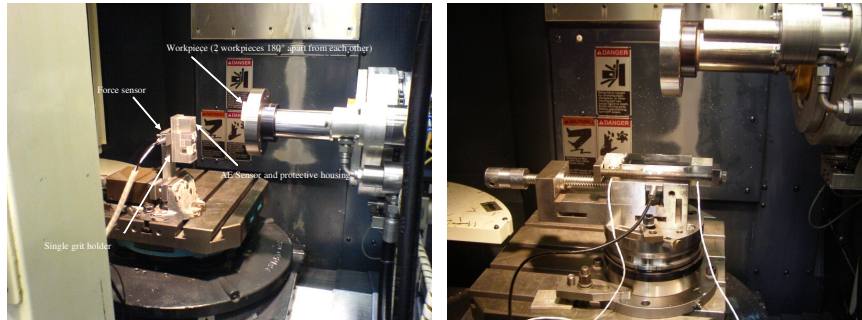
It was claimed that grinding has no minimum depth of cut.

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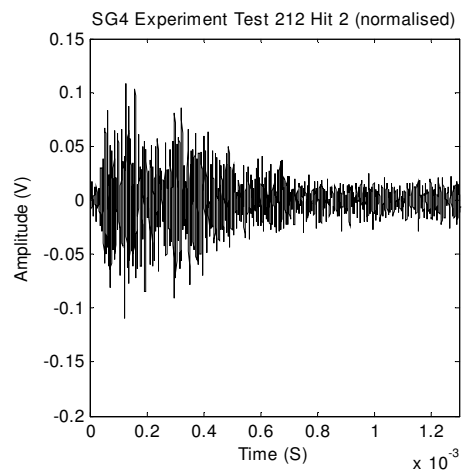
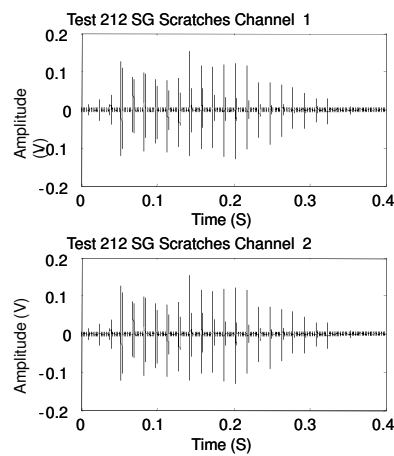
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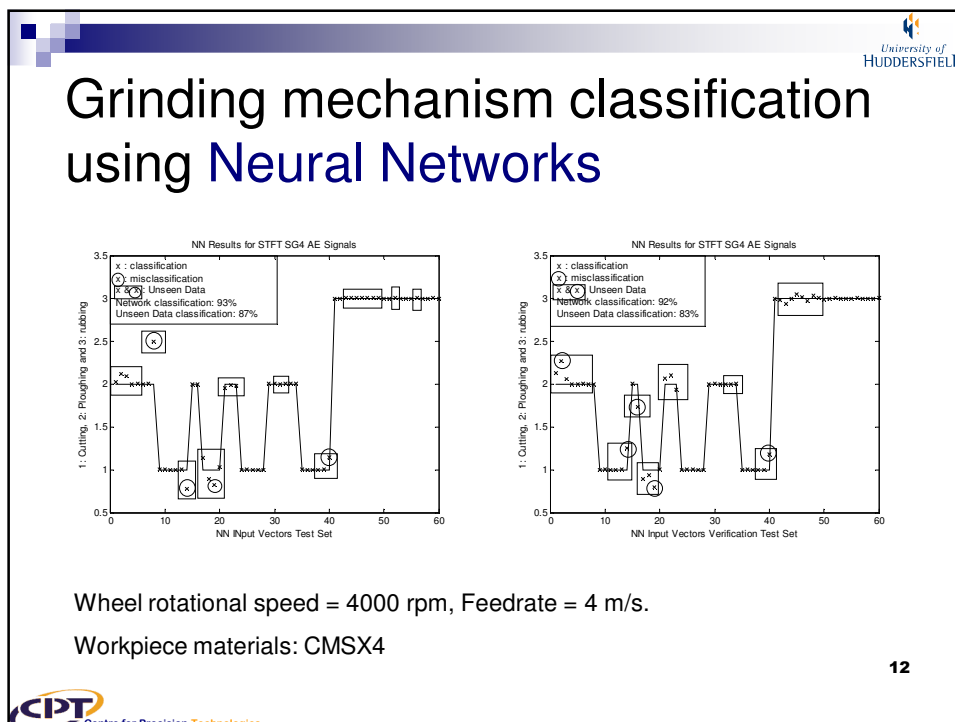
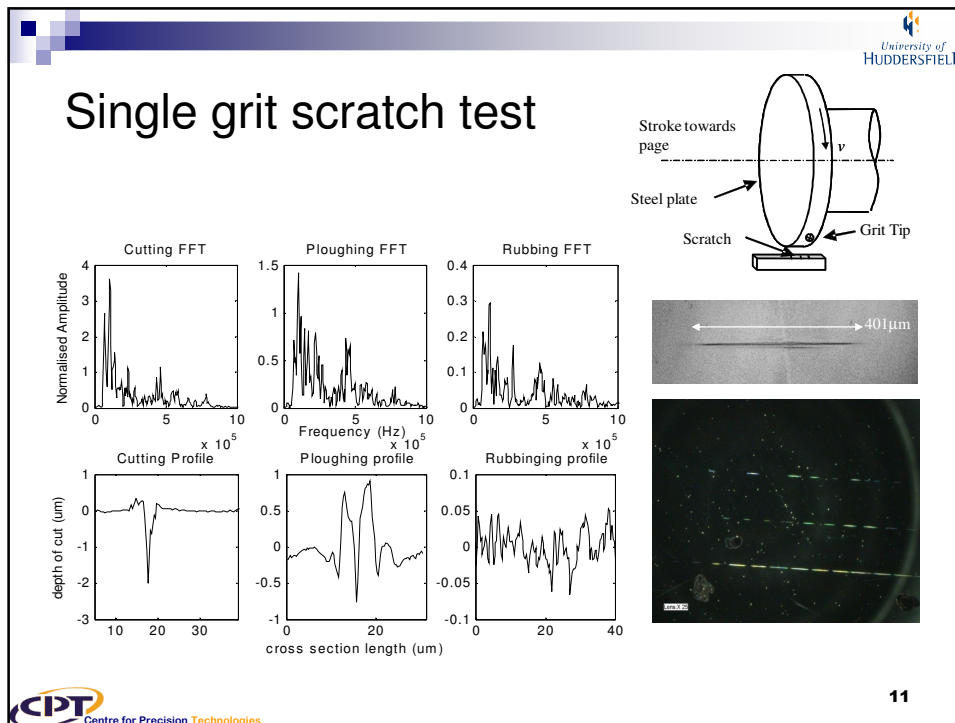



Rigs for single grit grinding tests



AE signals of single grit scratch



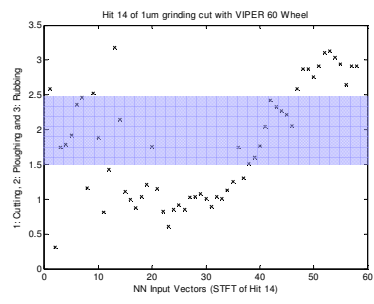


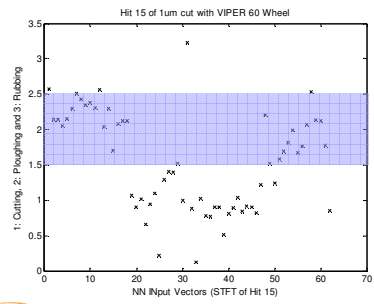


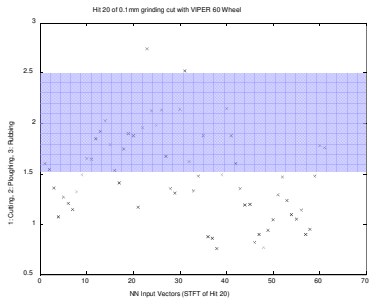
Feature extraction of AE in grinding


Wheel rotational speed = 4000 rpm,
Feedrate = 4 m/s,
Workpiece materials: CMSX4.


	C%	P%	R%
1 μm cut	45	29	26
1 μm cut	45	47	8
0.1 mm cut	57	40	3








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Laser irradiation imitating grinding thermal behaviour

Laser machine Lumonics:JK704 Nd:YAG

Wave length 1.06 μm

Pulse energy 1.36J

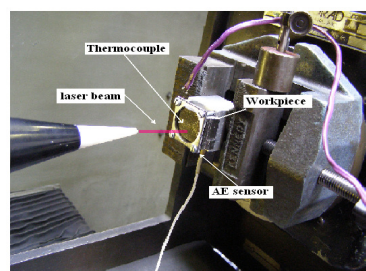
Maximum peak power 2.5kW

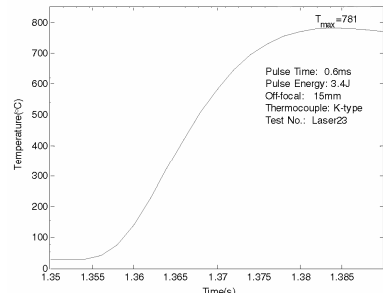
Laser irradiation time 0.06 ms

Focal length 120 mm

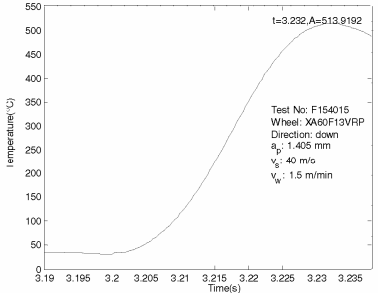
Light beam diameter 12 mm

Off-focal length 34~46 mm




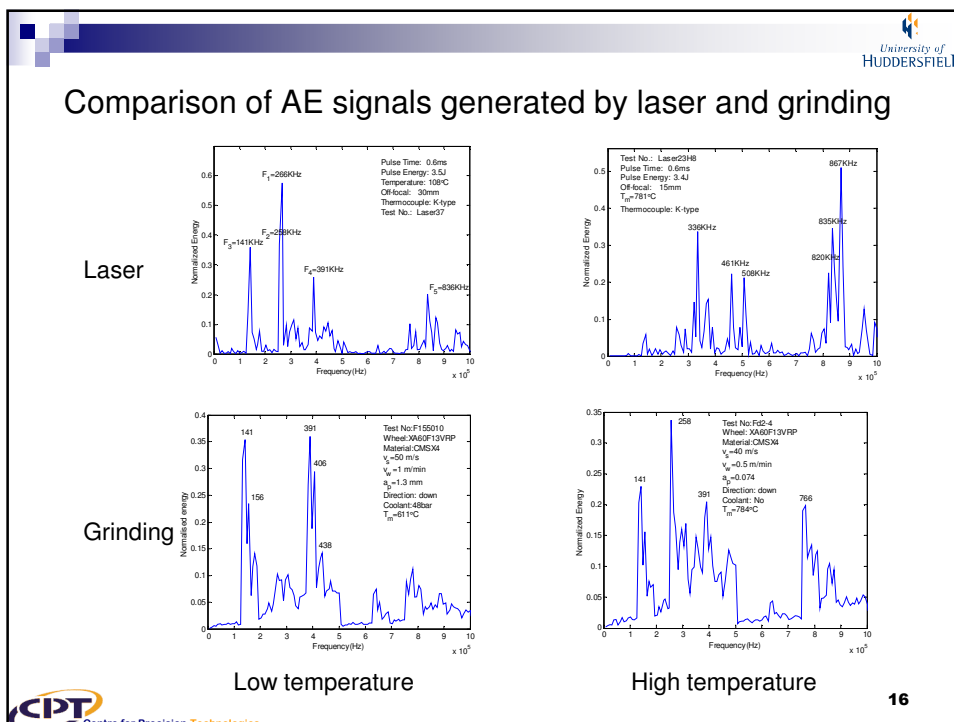
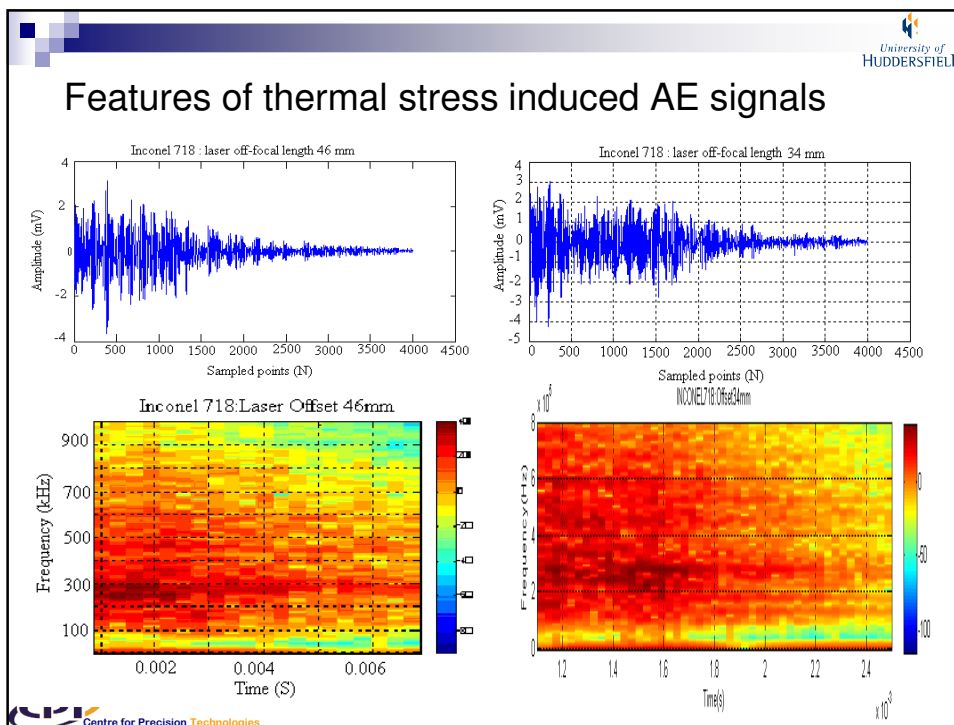


(a)



(b)


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Grinding thermal behaviour monitoring by using thermal AE signatures

The NN created using AE signatures from laser irradiation

Grinding burn identification using the NN from thermal AE signatures

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Pattern recognition for grinding defects

A Real Grinding Process (input)

Signal condition: Sensors (AE signal) → Impedance match & Amplifier → Data digitized & logging

Signal processing: Feature extraction: joint-time-frequency domain (wavelet packet) ← Quantification, Normalization, & Denoise etc

Pattern recognition: Feature optimization → Fuzzy classifier → Non-burn / Burn

Fuzzy c-mean cluster Minimum distance

• Success rate 92.3%

Fuzzy recognition block diagram

Fuzzy recognition procedure

More than 512 features: $X(m \times n) = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & x_{2n} \\ \dots & \dots & \dots & \dots \\ x_{m1} & x_{m2} & \dots & x_{mn} \end{bmatrix}$

Feature equalization, Feature normalization, Feature calibration, Transitive closure calculation → $F = \begin{bmatrix} f_{11} & f_{12} & \dots & f_{1n} \\ f_{21} & f_{22} & \dots & f_{2n} \\ \dots & \dots & \dots & \dots \\ f_{m1} & f_{m2} & \dots & f_{mn} \end{bmatrix}$

Similarity measure & clustering → Selection & Optimisation → Training & Classification → Burn status classification

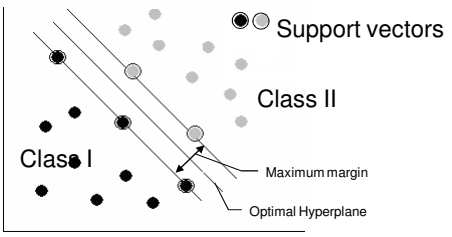
Less than 10 features

Feature extraction by wavelet packet and Joint Time-Frequency Analysis

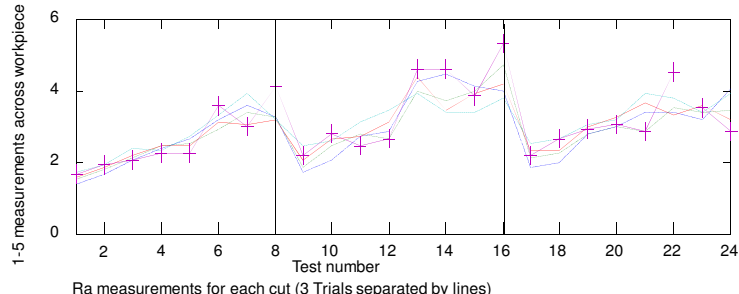
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Support vector machine classification



Support vectors
Class II
Maximum margin
Optimal Hyperplane
Class I



1-5 measurements across workpiece

Test number

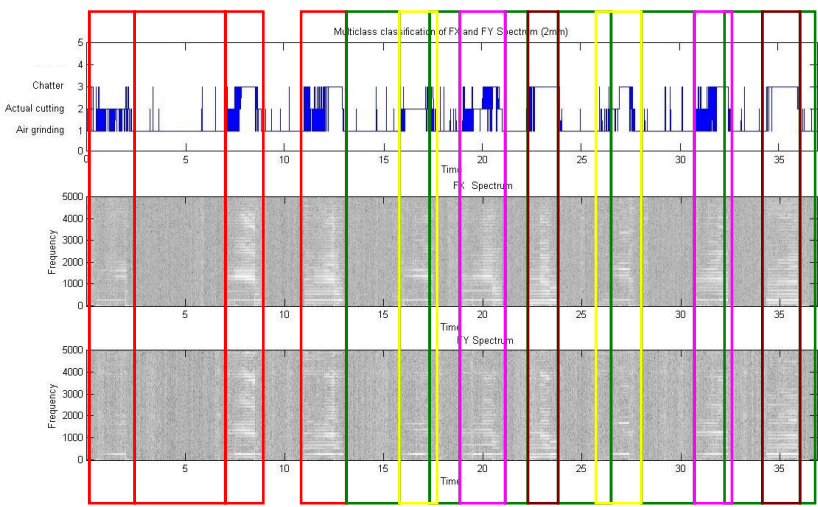
Ra measurements for each cut (3 Trials separated by lines)

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SVM classification



Multiclass classification of FX and FY Spectrum (2mm)

Chatter
Actual cutting
Air grinding

Time

FX Spectrum

Time


FY Spectrum

Benefits of SVM:

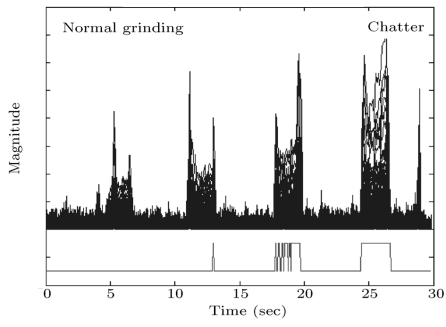
- Small amount of training data required
- Small amount of classifying time

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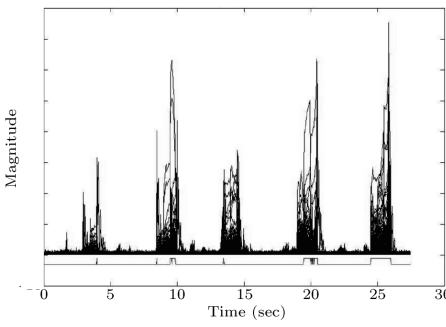
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SVM Classification




Normal grinding




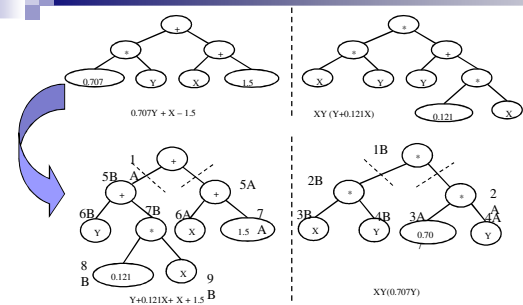
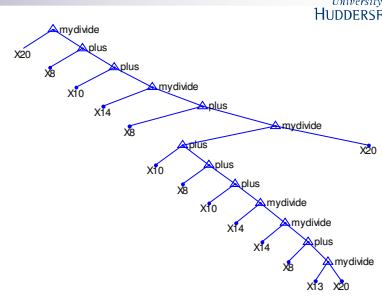
Chatter

Machine: Makino A55 CNC machine centre.
 Workpiece: Inconel 718.
 Wheel: VIPER wheel.
 Depth of cut: 1 mm;
 Grinding speed: 35 m/s;
 Workspeed: 1000 mm/min.

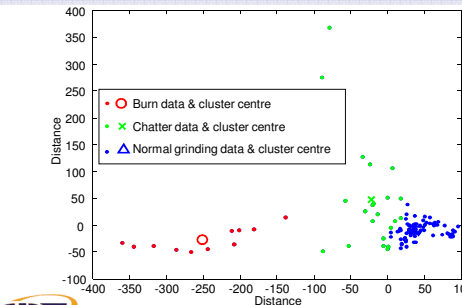
Machine: Makino A55 CNC machine centre.
 Workpiece: Inconel 718.
 Wheel: VIPER wheel.
 Depth of cut: 1 mm;
 Grinding speed: 55 m/s;
 Workspeed: 1000 mm/min.

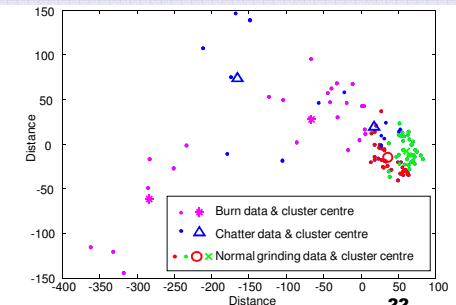

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Multi-classification of normal grinding, grinding chatter and burn using the GP






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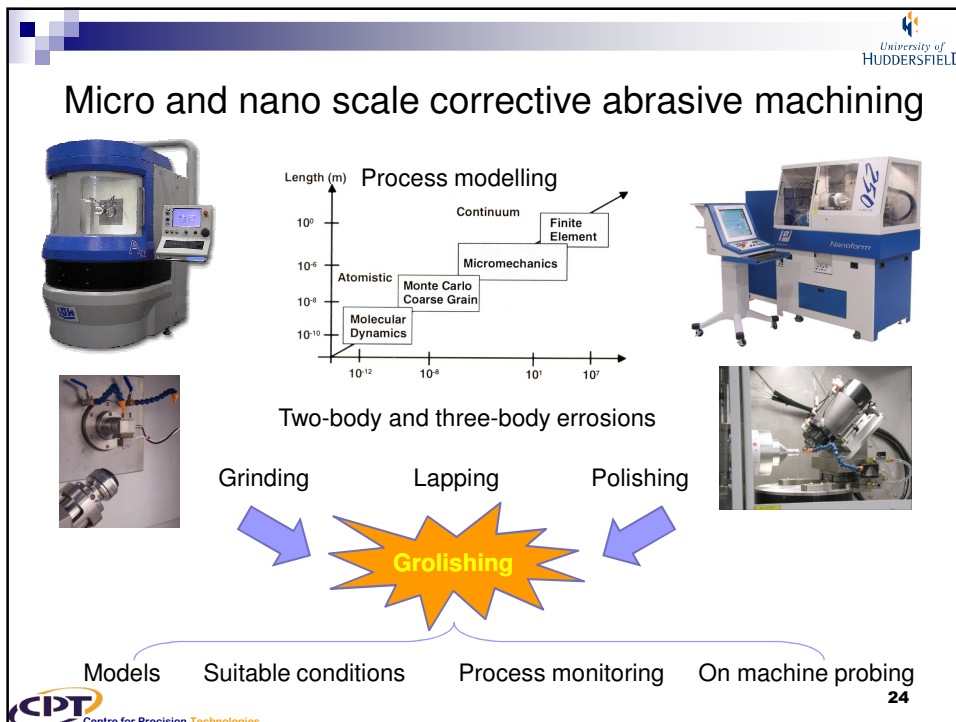
Classification of grinding anomalies using genetic programming

No.	GP fitness function	Data set	Function Nodes	Test Score	Accuracy %
1	sum diff fitness	ICA Chatter and burn	+,', -, '/', *	32/40	80
2	sum diff fitness	*reduction: burn and no burn	+,', -, '/', *	36/40	90
3	sum diff fitness	*reduction: burn and no burn	=<, '=>, if	36/40	90
4	sum diff fitness	*reduction: burn and chatter	+,', -, '/', *	36/40	90
5	sum diff fitness	*reduction: burn and chatter	=<, '=>, if	38/40	95
6	classes overlap	ICA Burn and no burn	+,', -, '/', *	33/40	82.5
7	classes overlap	ICA chatter and no chatter	+,', -, '/', *	32/40	80
8	classes overlap	ICA chatter and no chatter	+,', -, '/', *	40/40	100
9	sum diff fitness	ICA chatter and no chatter	+,', -, '/', *	36/40	90
10	classes overlap	ICA Burn and no burn	+,', -, '/', *	40/40	100
11	classes overlap	*reduction: burn and no burn	+,', -, '/', *	40/40	100
12	classes overlap	*reduction: chatter & no chatter	+,', -, '/', *	40/40	100

*reduction: is based on the statistical window n-dimensional reduction technique

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Grolishing Process Tools

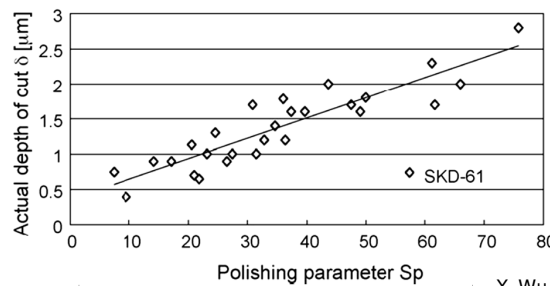
Models of material removal

Preston material removal rate model

$$\frac{dz}{dt} = C_p p v_r$$

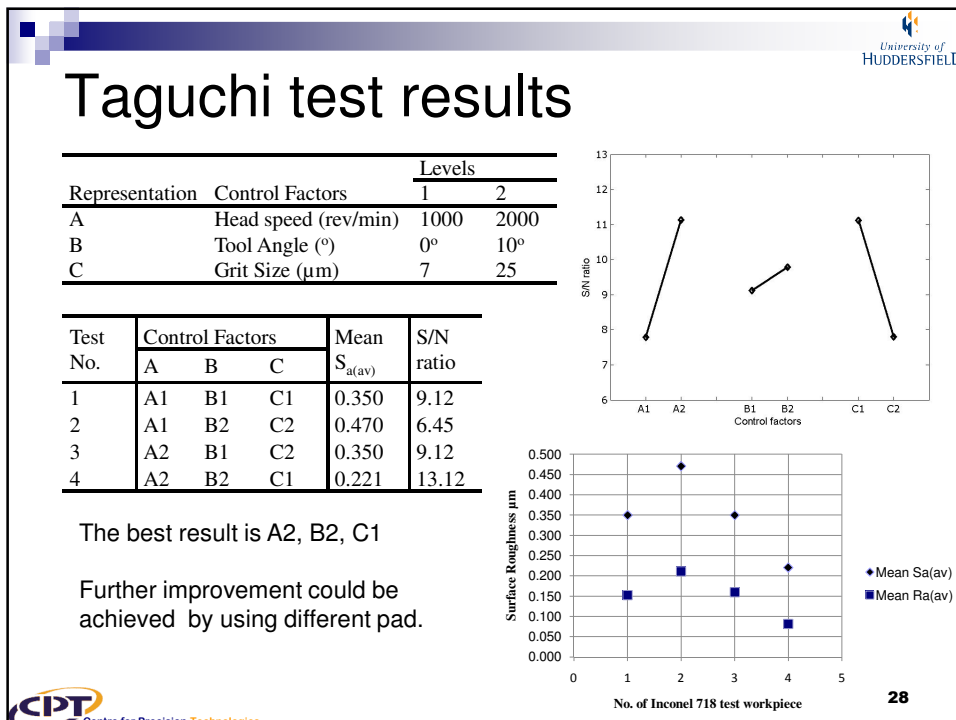
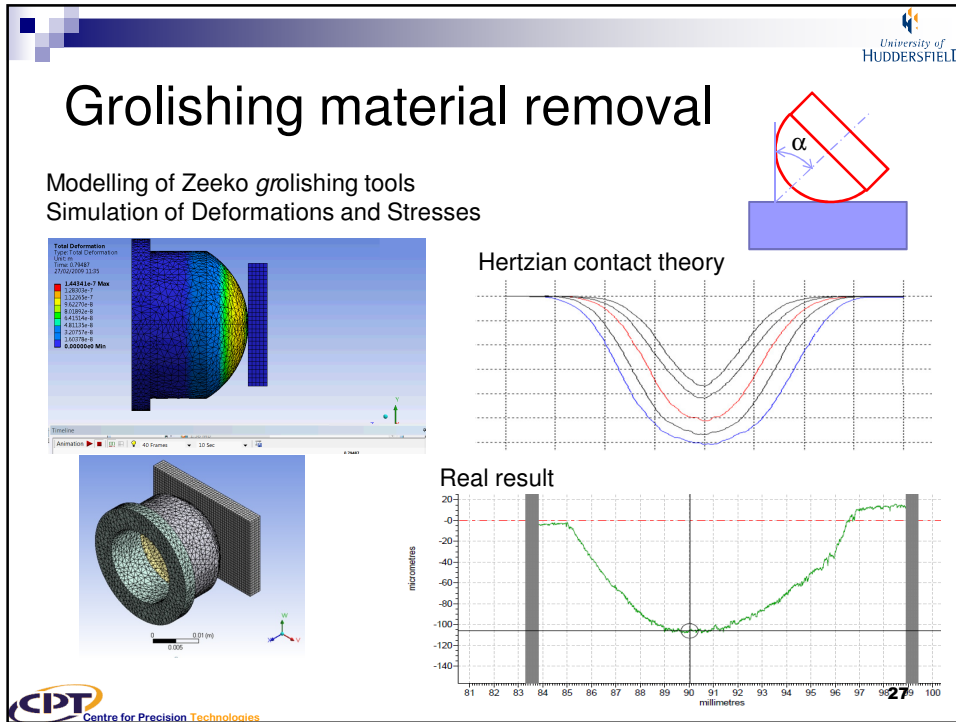
Archard material removal volume model

$$V_w = K \frac{F_n s}{H}$$



$$S_p = \frac{(V + f)p}{f H_v}$$

X. Wu, Y. Kita, K. Ioku (2007) 26



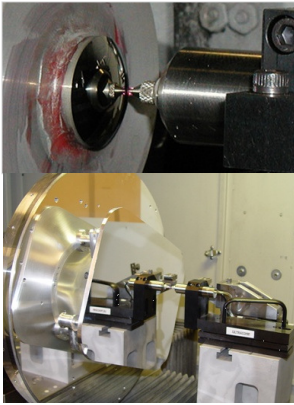
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Error compensation On-Machine Metrology enhanced

2D and 3D Metrology

Utilizing **UltraComp's™** LVDT, 2D and 3D data files of the part profile can be gathered including the machine axes

DIFFSYS® MC3 performs data import, graphically displays and auto-corrects the 3-dimensional part profiles from the LVDT measurement data to the desired part profile.



```

    graph LR
      A[Machine part with DIFFSYS® 3D X,Y,Z program] --> B[Gather data from X,Y,Z by point-to-point analysis or by scanning]
      B --> C[Output data file to 3rd party software]
      B --> D[Output data file to DIFFSYS®]
      C --> E[Quality inspection]
      D --> F[Auto-correct to desired tool path]
      F --> G[Re-machine 3D part to desired profile]
    
```

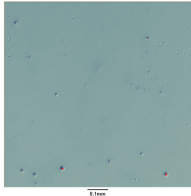
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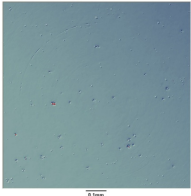
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AE detection of contact

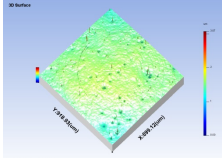
Before contact



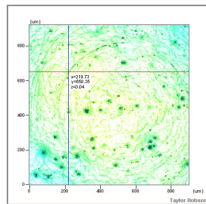
After contact



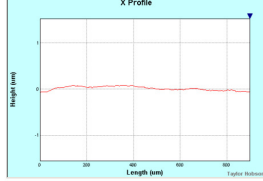
3D Surface



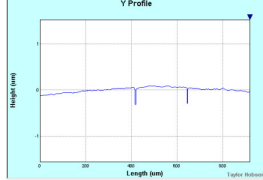
SUPSTAND
2D Profiles Analysis



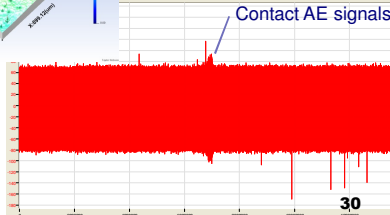
X Profile



Y Profile



Contact AE signals



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