## Calculation of Acoustic Shielding at Full-Scale Aircraft Configurations

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Wissen für Morgen

Shielding of engine noise as scattering problem



- Shielding of engine noise as scattering problem
  - Asymptotic high-frequency method: Ray-Tracing Method (RTM)



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- Summary and Outlook



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- Complex sound sources are difficult to handle

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Amplitude A by solution of transport equation 
Jacobian
Initial Conditions

$$\frac{A^2D}{\varrho c^2 |\boldsymbol{g}|^2} = \text{const. along a ray}, \quad D = \frac{d\boldsymbol{x}}{ds} \cdot \left(\frac{\partial \boldsymbol{x}}{\partial \alpha} \times \frac{\partial \boldsymbol{x}}{\partial \beta}\right)$$

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- Diffraction is frequency dependent

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#### Helmholtz Equation – Boundary Element Method

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$$p_I(x)$$
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• Kirchhoff integral: p(x) by integral over surface pressure p(y)

$$c \ p(\boldsymbol{x}) - \frac{1}{4\pi} \int_{\Omega} p(\boldsymbol{y}) \frac{\partial G(\boldsymbol{x}, \boldsymbol{y})}{\partial n_y} d\Omega_y + \frac{1}{4\pi} \int_{\Omega} \frac{\partial p(\boldsymbol{y})}{\partial n_y} G(\boldsymbol{x}, \boldsymbol{y}) d\Omega_y = p_I(\boldsymbol{x})$$

Green's Function  $G(\pmb{x},\pmb{y})=\frac{e^{ik|\pmb{x}-\pmb{y}|}}{|\pmb{x}-\pmb{y}|}$ 

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- Full storage of matrix limits BEM to low frequencies
- ► Complex sources (CRORs, Fans, etc.) are possible



Acceleration of BEM



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- Iterative solver applied to BEM equations



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Burton-Miller approach to guarantee uniqueness of solution



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  - Model has been extended to CRORs with different rotational speed

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Shielding Examples

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Sphere – 2.7M – 6 PPW





Sphere – 2.7M – 9 PPW





# Comparison RTM - FMM

Shielding Examples

Monopole above unit sphere



# Comparison RTM - FMM

- Monopole above unit sphere
- Monopole shielding by Low-Noise-Aircraft (LNA)



# Comparison RTM - FMM

Shielding Examples

- Monopole above unit sphere
- Monopole shielding by Low-Noise-Aircraft (LNA)
- 'Shielding' of rear mounted CROR at a conventional Z08 aircraft configuration

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#### Sphere RTM – FMM – 6 PPW

- Monopole at R = 1.5 above unit sphere
- ▶ Attenuation factor  $\left|\frac{p_{Shielded}}{p_{Incident}}\right|$  in plane centered at R = 6 below sphere
- ▶ Wavelength  $\lambda = 0.013, 2.7 \times 10^6$  triangles 6 elements per wavelength



#### Sphere RTM – FMM – 9 PPW

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### Sphere RTM – FMM

- Attenuation factor  $\left| \frac{p_{Shielded}}{p_{Incident}} \right|$  in plane centered at R = 6 below sphere
- Wavelength  $\lambda = 0.013, 0.020$
- Arago spot visible



► DLR Low-Noise-Aircraft (LNA) – fuselage length ca. 50 m



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- $4 \times 10^6$  triangles frequency 2841 Hz



# LNA - FMM/RTM

- Attenuation in dB
- Monopole above right wing trailing edge
- a/c shown not scaled!





# LNA - FMM/RTM

Modulus of pressure 120 m below flight path (y = 0 m) and along y = ±200 m (y-axes scaled differently!)





Pusher CRORs are 'faked': inflow undisturbed by pylon • Cror model



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- Different diffraction pattern for left/right installed CROR by interaction of near field with geometry
- Can not be obtained by Ray-Tracing!

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### Summary and Outlook

 Shielding calculations as scattering problem feasible for full scale aircraft configurations up to some kHz



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    - Formulated for point sources so far
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Thank you for your attention!



Determination initial conditions of rays to a target point



 Rays are straight lines between reflections if sound speed and mean flow are constant





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- Multiple reflections at the geometry are possible





- Rays are straight lines between reflections if sound speed and mean flow are constant
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Determination initial conditions of rays to a target point



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- General geometries: Perform line integral along the shadow boundaries on the body 

   Shadow Boundary
- Return

#### **Shadow Boundaries**



Shadow Region – 2.7M – 6 PPW


Illuminated Region – 2.7M – 6 PPW



Shadow Region – 2.7M – 9 PPW





Illuminated Region – 2.7M – 9 PPW





DLR-CROR where unsteady CFD-data are easily available



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🕨 🔍 🖣 Return

# **Taylor Transformation**

- Low Mach number potential mean flow field
- Convected wave equation for acoustic velocity potential
- Calculation of velocity potential from CFD data necessary



### **Taylor Transformation**

Taylor (1978), Agarwal & Dowling (2007)

• Convected wave equation (Mean flow potential  $u = \nabla \overline{\Phi}$ )

$$\left(\frac{\partial}{\partial t} + \nabla \overline{\Phi} \cdot \nabla\right)^2 \phi_g - c^2 \nabla^2 \phi_g = -\delta(\boldsymbol{x} - \boldsymbol{x}_0) e^{-i\omega t}$$

• Acoustic velocity potential  $\phi_g(x, t)$ 

$$\begin{split} \phi_g(\boldsymbol{x},t) &= \hat{\Phi}_h(\boldsymbol{x},\omega) e^{ik \frac{\overline{\Phi}(\boldsymbol{x}_0) - \overline{\Phi}(\boldsymbol{x})}{c}} e^{-i\omega t} \\ (\omega^2 + c^2 \nabla^2) \hat{\Phi}_h &= -\delta(\boldsymbol{x} - \boldsymbol{x}_0), \quad \boldsymbol{n} \cdot \nabla \hat{\Phi}_h = 0 \end{split}$$

Acoustic pressure

$$p(\boldsymbol{x},t) = c\overline{\varrho}\left(ik\hat{\Phi}_h - \frac{\nabla\overline{\Phi}}{c}\cdot\nabla\hat{\Phi}_h\right)e^{ik\frac{\overline{\Phi}(\boldsymbol{x}_0)-\overline{\Phi}(\boldsymbol{x})}{c}}e^{-i\omega t}$$



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