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On the structure of Finsler and areal spaces

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ON THE STRUCTURE OF FINSLER AND AREAL SPACES

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Abstract. We study underlying geometric structures for integral variational functionals, depending on submanifolds of a given manifold. Applications include (first order) variational functionals of Finsler and areal geometries with integrand the Hilbert 1-form, and admit immediate extensions to higher-order functionals.

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1. INTRODUCTION

This paper is a contribution to the theory of integral variational functionals, depending on submanifolds of a given manifold X . The theory is based on geometric notions such as the bundles of (skew-symmetric) multivectors, and Grassmann fibrations. Conceptually, it extends local parametric integrals of Finsler–Kawaguchi and areal geometries (see, e. g., Chern, Chen, Lam [1], Davies [3], Kawaguchi [4], and Tamassy [6]) to global functionals, depending on (global) submanifolds. In Section 2 we summarize integration theory of differential forms along submanifolds. Section 3 is devoted to vector bundles of k -vectors; we show how mappings of Euclidean spaces into manifolds (*parametrisations*) can be lifted to the bundles of k -vectors. In Section 4 we introduce, using the Plücker embedding, underlying spaces for parameter-invariant variational problems, the Grassmann fibrations. In Section 5 we show that any k -form on the Grassmann fibration defines an integral variational functional, depending on k -dimensional submanifolds. An example is the *Hilbert form*, a well-known first-order construction in Finsler geometry and its generalisations (Chern, Chen, Lam [1], Crampin, Saunders [2]).

It should be pointed out that the theory can be further generalised. To this end, one should consider higher-order Grassmann fibrations endowed with Lagrangians satisfying the relevant homogeneity conditions (*Zermelo conditions*, see, e. g., Saunders [5], and Urban and Krupka [8]).

2. INTEGRATION OVER SUBMANIFOLDS

Let X be an n -dimensional manifold, S a subset of X , $x_0 \in S$ a point. A chart $(U, \varphi), \varphi = (x^i)$, at x_0 is a *submanifold chart* for S , if there exists a non-negative integer $k \leq n$ such that $\varphi(U \cap S) = \{x \in U \mid x^{k+1}(x) = c_1, x^{k+2}(x) = c_2, \dots, x^n(x) = c_{n-k}\}$. If such a chart exists, we say that S is a *submanifold* of X at the point x_0 ; k is the *dimension* of S at x_0 . If such a submanifold chart exists at every point of X , we say S is a *submanifold* of X and call k the *dimension* of S .

Denote by (t^1, t^2, \dots, t^n) the canonical coordinates on the Euclidean space \mathbb{R}^n , and $\mathbb{R}_{(-)}^n = \{t_0 \in \mathbb{R}^n \mid t^n(t_0) \leq 0\}$, $\partial\mathbb{R}_{(-)}^n = \{t_0 \in \mathbb{R}_{(-)}^n \mid t^n(t_0) = 0\}$. $\mathbb{R}_{(-)}^n$ is the *halfspace* of \mathbb{R}^n , $\partial\mathbb{R}_{(-)}^n$ is the *boundary* of $\mathbb{R}_{(-)}^n$. Let Ω be a non-void subset of X , and $x_0 \in \Omega$ a point. A chart (U, φ) at x_0 is said to be *adapted* to Ω , if the set $\varphi(U \cap \Omega)$ is an open set in $\mathbb{R}_{(-)}^n$. Ω is a *piece* of X , if it is compact and each point $x \in \Omega$ admits a chart, adapted to Ω .

Let η be a k -form on X . Our aim now will be to introduce an integral of η on a piece of a k -dimensional submanifold S (k -piece of a X). Express η in a submanifold chart $(U, \varphi), \varphi = (x^i)$, as $\eta = \eta_{i_1 i_2 \dots i_k} dx^{i_1} \wedge dx^{i_2} \wedge \dots \wedge dx^{i_k}$. Then, restricting η to S we get from the equations $x^{k+1} = 0, x^{k+2} = 0, \dots, x^n = 0$

$$\eta = f dx^1 \wedge dx^2 \wedge \dots \wedge dx^k,$$

where we write $f = f(x^{i_1}, x^{i_2}, \dots, x^{i_k})$ for the component of η restricted to S . From now on we suppose that S is *orientable*, and is endowed with an orientation $\text{Or}_S X$; only submanifold charts on X belonging to $\text{Or}_S X$ are used. The integral of η on a compact set $\Omega \subset S$ is defined in a standard way. There exist a finite family $\{(U_1, \varphi_1), (U_2, \varphi_2), \dots, (U_N, \varphi_N)\}$ of submanifold charts on X , such that the family $\{U_1 \cap S, U_2 \cap S, \dots, U_N \cap S\}$ covers Ω . Let $\{\chi_1, \chi_2, \dots, \chi_N\}$ be a partition of unity, subordinate to this covering. Then,

$$\int_{\Omega} \eta = \sum_{j=1}^N \int_{\text{supp } \chi_j \cap \Omega} \chi_j \eta.$$

The following basic properties of the integral are needed in the calculus of variations.

Lemma 1 (transformation of integration domain). *Let X and Y be two smooth n -dimensional oriented manifolds, $\alpha : X \rightarrow Y$ an orientation-preserving diffeomorphism. Then*

$$\int_{\Omega} \eta = \int_{\alpha^{-1}(\Omega)} \alpha * \eta$$

for any compact set $\Omega \subset S$ and any continuous differential n -form on Y .

Lemma 2 (Leibniz rule). *Let X be an oriented n -dimensional manifold, η_t a family of n -forms on X , differentiable on a real parameter t , $\Omega \subset S$ a compact set.*

Then, the function $I \ni t \mapsto \int_{\Omega} \eta_t \in \mathbb{R}$ is differentiable, and

$$\frac{d}{dt} \int_{\Omega} \eta_t = \int_{\Omega} \frac{d\eta_t}{dt}.$$

Lemma 3 (Stokes formula). *Let X be an n -dimensional manifold, S a k -dimensional oriented submanifold of X , η a $(k - 1)$ -form on X . Let Ω be a piece of S with boundary $\partial\Omega$, endowed with induced orientation. Then*

$$\int_{\partial\Omega} \eta = \int_{\Omega} d\eta.$$

3. BUNDLES OF k -VECTORS

Let X be an n -dimensional manifold, $\Lambda^k T_x X$ the k -exterior product of the tangent space $T_x X$, $x \in X$ a point. We put

$$\Lambda^k TX = \bigcup_{x \in X} \Lambda^k T_x X.$$

This set has a natural vector bundle structure over X , with type fibre $\Lambda^k \mathbb{R}^n$. We denote by τ^k the vector bundle projection of $\Lambda^k TX$.

Let X (resp. Y) be a smooth manifold of dimension n (resp. m), and let $f : X \rightarrow Y$ be a differentiable mapping. Choose a point $x \in X$ and a k -vector $\mathcal{E} \in \Lambda^k T_x X$. Then, choose a chart (U, φ) , $\varphi = (x^i)$, at x and a chart (V, ψ) , $\psi = (y^\sigma)$, at $f(x) \in Y$ such that $f(U) \subset V$. Expressing \mathcal{E} in components and setting

$$\begin{aligned} \Lambda^k T_x f \cdot \mathcal{E} &= \frac{1}{(k!)^2} \left(\frac{\partial y^{\sigma_1} f \varphi^{-1}}{\partial x^{i_1}} \right)_{\varphi(x)} \left(\frac{\partial y^{\sigma_2} f \varphi^{-1}}{\partial x^{i_2}} \right)_{\varphi(x)} \cdots \left(\frac{\partial y^{\sigma_k} f \varphi^{-1}}{\partial x^{i_k}} \right)_{\varphi(x)} \\ &\cdot \mathcal{E}^{i_1 i_2 \dots i_k} \left(\frac{\partial}{\partial y^{\sigma_1}} \right)_{f(x)} \wedge \left(\frac{\partial}{\partial y^{\sigma_2}} \right)_{f(x)} \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\sigma_k}} \right)_{f(x)}, \end{aligned}$$

we get a k -vector $\Lambda^k T_x f \cdot \mathcal{E} \in \Lambda^k T_{f(x)} Y$, and a vector bundle homomorphism $\Lambda^k T f : \Lambda^k TX \rightarrow \Lambda^k TY$ over f (the lift of f).

It is easily seen that differentiable mappings of a Euclidean space into a manifold can be canonically lifted to the bundles of k -vectors. For this purpose we use the canonical k -vector field on \mathbb{R}^n

$$\mathbb{R}^n \ni t \rightarrow \theta(t) = \frac{1}{k!} \varepsilon^{i_1 i_2 \dots i_k} \left(\frac{\partial}{\partial t^{i_1}} \right)_t \wedge \left(\frac{\partial}{\partial t^{i_2}} \right)_t \wedge \dots \wedge \left(\frac{\partial}{\partial t^{i_k}} \right)_t \in \Lambda^k T \mathbb{R}^n.$$

Identifying $\Lambda^k T \mathbb{R}^n$ with $\mathbb{R}^n \times \Lambda^k \mathbb{R}^n$, the canonical section becomes the mapping $t \rightarrow (t, \varepsilon^{i_1 i_2 \dots i_k})$.

Consider a differentiable mapping $f : U \rightarrow Y$, where U is an open subset of \mathbb{R}^n . For any point $t \in U$, $\Lambda^k T_t f \cdot \theta(t)$ is an element of the vector space $\Lambda^k T_{f(t)} Y$. We

get the *canonical lift* $\Lambda^k f$ of f to $\Lambda^k TY$, defined by

$$\Lambda^k f = \Lambda^k Tf \cdot \theta.$$

The canonical lift of the *parametrisation* $U \ni t \rightarrow (\psi^{-1} \circ \iota_{k,m})(t) \in V \cap S$ is expressed in a chart (V, ψ) , $\psi = (y^\sigma)$, as

$$\begin{aligned} & \Lambda^k(\psi^{-1} \circ \iota_{k,m})(t) \\ &= \left(\frac{\partial}{\partial y^1} \right)_{\psi^{-1} \circ \iota_{k,m}(t)} \wedge \left(\frac{\partial}{\partial y^2} \right)_{\psi^{-1} \circ \iota_{k,m}(t)} \wedge \dots \wedge \left(\frac{\partial}{\partial y^k} \right)_{\psi^{-1} \circ \iota_{k,m}(t)}. \end{aligned} \quad (3.1)$$

Formula (3.1) also defines the mapping $V \ni y \rightarrow (\Lambda^k \psi)(y) \in (\tau^k)^{-1}(V)$ by

$$\Lambda^k \psi = \Lambda^k(\psi^{-1} \circ \iota_{k,m}) \circ \text{pr}_{m,k} \psi, \quad (3.2)$$

the *canonical section along* S , associated with (V, ψ) . $\Lambda^k \psi$ is expressed by

$$\begin{aligned} & (y^1, y^2, \dots, y^k, y^{k+1}, y^{k+2}, \dots, y^m) \rightarrow \Lambda^k(\psi^{-1} \circ \iota_{k,m})(y^1, y^2, \dots, y^k) \\ &= ((y^1, y^2, \dots, y^k, 0, 0, \dots, 0), (1, 0, 0, \dots, 0)). \end{aligned}$$

Writing in the multi-index notation $((\tau^r)^{-1}(V), \Phi)$, $\Phi = (\dot{y}^I)$, and setting $I_0 = (1, 2, \dots, k)$, we get the image of this mapping as a subset of $(\tau^r)^{-1}(V)$, defined by the equations $y^{k+1} = 0, y^{k+2} = 0, \dots, y^m = 0, \dot{y}^{I_0} = 1, \dot{y}^I = 0, I \neq I_0$.

Lemma 4. *Let (V, ψ) , $\psi = (y^\sigma)$, and $(\bar{V}, \bar{\psi})$, $\bar{\psi} = (\bar{y}^\sigma)$, be two charts on Y , adapted to S , such that $V \cap \bar{V} \neq \emptyset$.*

(1) *The canonical sections along S satisfy*

$$\Lambda^k \bar{\psi} = \det \left(\frac{\partial y^i}{\partial \bar{y}^j} \right)_{\bar{\psi}(y)} \Lambda^k \psi.$$

(2) *The differential forms dy^σ and $d\dot{y}^I$ satisfy $(\Lambda^k \psi)^* d\dot{y}^i = dy^i$, $1 \leq i \leq k$, $(\Lambda^k \psi)^* dy^\nu = 0$, $k+1 \leq \nu \leq m$, $(\Lambda^k \psi)^* d\dot{y}^I = 0$. In particular, on the set $V \cap \bar{V}$,*

$$\begin{aligned} & (\Lambda^k \bar{\psi})^* d\bar{y}^1 \wedge d\bar{y}^2 \wedge \dots \wedge d\bar{y}^k \\ &= \det \left(\frac{\partial \bar{y}^i}{\partial y^j} \right)_{\psi(y)} (\Lambda^k \psi)^* dy^1 \wedge dy^2 \wedge \dots \wedge dy^k. \end{aligned} \quad (3.3)$$

4. GRASSMANN FIBRATIONS

Consider the vector bundle $\Lambda^k TY$ and the subset $\Lambda_0^k TY \subset \Lambda^k TY$, consisted of *non-zero k -vectors*. We have an equivalence relation on $\Lambda_0^k TY$ “ \mathcal{E}_1 is equivalent with \mathcal{E}_2 , if there exists a real number $\lambda > 0$ such that $\mathcal{E}_1 = \lambda \mathcal{E}_2$ ”. The quotient set has the structure of a fibration over Y , called the *Grassmann fibration* of degree k , and is denoted by $G^k Y$.

To describe the structure of the set $G^k Y$, we proceed similarly as in the case of classical projective spaces. If in a chart (V, ψ) , $\psi = (y^\sigma)$,

$$\mathcal{E}_i = \frac{1}{k!} \mathcal{E}_i^{\sigma_1 \sigma_2 \dots \sigma_k} \left(\frac{\partial}{\partial y^{\sigma_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\sigma_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\sigma_k}} \right)_y, \quad i = 1, 2,$$

are two nonzero k -vectors, then \mathcal{E}_1 is equivalent with \mathcal{E}_2 if and only if in this chart, $\mathcal{E}_1^{\sigma_1 \sigma_2 \dots \sigma_k} = \lambda \mathcal{E}_2^{\sigma_1 \sigma_2 \dots \sigma_k}$ for some $\lambda > 0$ and all $\sigma_1, \sigma_2, \dots, \sigma_k$. We denote $V^{\nu_1 \nu_2 \dots \nu_k} = \{\mathcal{E} \in (\tau^k)^{-1}(V) \mid \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} > 0\}$. Then, a k -vector belonging to the set $V^{\nu_1 \nu_2 \dots \nu_k} \subset \Lambda_0^k TY$ can be expressed by

$$\begin{aligned} \mathcal{E} &= \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} \left(\frac{\partial}{\partial y^{\nu_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\nu_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\nu_k}} \right)_y \\ &+ \frac{1}{k!} \sum_{(\tau_1 \tau_2 \dots \tau_k) \neq (\nu_1 \nu_2 \dots \nu_k)} \mathcal{E}^{\tau_1 \tau_2 \dots \tau_k} \left(\frac{\partial}{\partial y^{\tau_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\tau_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\tau_k}} \right)_y \end{aligned}$$

(no summation through $\nu_1, \nu_2, \dots, \nu_k$). Denoting by $\text{sgn } \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}$ the sign of the component $\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}$, we can write $\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} = \text{sgn } \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} \cdot |\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}|$ and

$$\begin{aligned} \mathcal{E} &= \text{sgn } \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} \cdot |\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}| \left(\frac{\partial}{\partial y^{\nu_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\nu_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\nu_k}} \right)_y \\ &+ \frac{|\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}|}{k!} \sum \frac{\mathcal{E}^{\tau_1 \tau_2 \dots \tau_k}}{|\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}|} \left(\frac{\partial}{\partial y^{\tau_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\tau_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\tau_k}} \right)_y, \end{aligned}$$

with the summation through $(\tau_1 \tau_2 \dots \tau_k) \neq (\nu_1 \nu_2 \dots \nu_k)$. But $\text{sgn } \mathcal{E}^{\nu_1 \nu_2 \dots \nu_k} = 1$, so we see the class of \mathcal{E} can be represented as

$$\begin{aligned} [\mathcal{E}] &= \left(\frac{\partial}{\partial y^{\nu_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\nu_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\nu_k}} \right)_y \\ &+ \frac{1}{k!} \sum \frac{\mathcal{E}^{\tau_1 \tau_2 \dots \tau_k}}{\mathcal{E}^{\nu_1 \nu_2 \dots \nu_k}} \left(\frac{\partial}{\partial y^{\tau_1}} \right)_y \wedge \left(\frac{\partial}{\partial y^{\tau_2}} \right)_y \wedge \dots \wedge \left(\frac{\partial}{\partial y^{\tau_k}} \right)_y. \end{aligned}$$

We set for any $\mathcal{E} \in V^{\nu_1 \nu_2 \dots \nu_k}$

$$\begin{aligned} w^\sigma(\mathcal{E}) &= y^\sigma(\mathcal{E}), \quad w^{\nu_1 \nu_2 \dots \nu_k}(\mathcal{E}) = \dot{y}^{\nu_1 \nu_2 \dots \nu_k}(\mathcal{E}), \\ w^{\sigma_1 \sigma_2 \dots \sigma_k}(\mathcal{E}) &= \frac{\dot{y}^{\sigma_1 \sigma_2 \dots \sigma_k}(\mathcal{E})}{\dot{y}^{\nu_1 \nu_2 \dots \nu_k}(\mathcal{E})}, \quad (\sigma_1 \sigma_2 \dots \sigma_k) \neq (\nu_1 \nu_2 \dots \nu_k). \end{aligned} \quad (4.1)$$

The pair $(V^{\nu_1 \nu_2 \dots \nu_k}, \Psi^{\nu_1 \nu_2 \dots \nu_k})$, $\Psi^{\nu_1 \nu_2 \dots \nu_k} = (w^\sigma, w^{\nu_1 \nu_2 \dots \nu_k}, w^{\sigma_1 \sigma_2 \dots \sigma_k})$, where the indices satisfy $(\sigma_1 \sigma_2 \dots \sigma_k) \neq (\nu_1 \nu_2 \dots \nu_k)$, is a chart on $\Lambda_0^k TY$; we call this chart $(\nu_1 \nu_2 \dots \nu_k)$ -associated with (V, ψ) . The pair $(V^{\nu_1 \nu_2 \dots \nu_k}, W^{\nu_1 \nu_2 \dots \nu_k})$, $W^{\nu_1 \nu_2 \dots \nu_k} = (w^\sigma, w^{\sigma_1 \sigma_2 \dots \sigma_k})$, $(\sigma_1 \sigma_2 \dots \sigma_k) \neq (\nu_1 \nu_2 \dots \nu_k)$, is a fibred chart on

$G^k Y$. Writing formulas (4.1) in a different way, we have the transformation equations

$$w^\sigma = y^\sigma, \quad w^{v_1 v_2 \dots v_k} = \dot{y}^{v_1 v_2 \dots v_k}, \quad w^{\sigma_1 \sigma_2 \dots \sigma_k} = \frac{\dot{y}^{\sigma_1 \sigma_2 \dots \sigma_k}}{\dot{y}^{v_1 v_2 \dots v_k}}.$$

The projection $\kappa^k : \Lambda^k T Y \rightarrow G^k Y$ of $\Lambda^k T Y$ onto $G^k Y$ is the Cartesian projection $(w^\sigma, w^{v_1 v_2 \dots v_k}, w^{\sigma_1 \sigma_2 \dots \sigma_k}) \rightarrow (w^\sigma, w^{\sigma_1 \sigma_2 \dots \sigma_k})$. Combining $\Lambda^k(\psi^{-1} \iota_{k,m})$ and κ^k we get the canonical lift of $\psi^{-1} \iota_{k,m}$ to the Grassmann fibration,

$$G^k(\psi^{-1} \iota_{k,m}) = \kappa^k \circ \Lambda^k(\psi^{-1} \iota_{k,m}). \quad (4.2)$$

Lemma 5. *Let (V, ψ) , $\psi = (y^\sigma)$, and $(\bar{V}, \bar{\psi})$, $\bar{\psi} = (\bar{y}^\sigma)$, be two rectangle charts, adapted to S at a point $y \in Y$. Suppose that (V, ψ) and $(\bar{V}, \bar{\psi})$ are consistently oriented. Then*

$$G_k(\bar{\psi}^{-1} \iota_{k,m}) = G^k(\psi^{-1} \iota_{k,m}). \quad (4.3)$$

We set

$$G^k S = \{[\mathcal{E}] \in G^k Y \mid [\mathcal{E}] = G^k(\psi^{-1} \iota_{k,m})(\text{pr}_{m,k} \psi(y)), y \in S\}. \quad (4.4)$$

To a given chart (V, ψ) , $\psi = (y^\sigma)$, we associate the induced chart $((\tau^k)^{-1}(V), \Phi)$, $\Phi = (y^\sigma, \dot{y}^{\sigma_1 \sigma_2 \dots \sigma_k})$, on $\Lambda^k T Y$; the associated charts on the Grassmann fibration $G^k Y$ are $(V_0^{v_1 v_2 \dots v_k}, W^{v_1 v_2 \dots v_k})$,

$$W^{v_1 v_2 \dots v_k} = (w^\sigma, w^{\sigma_1 \sigma_2 \dots \sigma_k}),$$

with $(\sigma_1 \sigma_2 \dots \sigma_k) \neq (v_1 v_2 \dots v_k)$. Then, it is easily seen that each of the charts $(V_0^{v_1 v_2 \dots v_k}, W^{v_1 v_2 \dots v_k})$ is adapted to the submanifold $G^k S$.

Theorem 1. *Suppose S is oriented. Then, the subset $G^k S$ of the Grassmann fibration $G^k Y$ is a k -dimensional oriented submanifold, diffeomorphic with S .*

Theorem 1 allows us to integrate over k -dimensional submanifolds of Y directly on the Grassmann fibration $G^k Y$.

5. VARIATIONAL FUNCTIONALS DEPENDING ON SUBMANIFOLDS

As before, we write $G^k S$ (resp., $G^k \Omega$) for the canonical lift of a k -dimensional submanifold $S \subset Y$ (resp., k -piece $\Omega \subset Y$) to the Grassmann fibration $G^k Y$. Denote by $\Gamma^k Y$ the set of all k -pieces Ω of the manifold Y .

Let η be a k -form on the Grassmann fibration $G^k Y$. The form η defines the *variational functional*

$$\Gamma^k Y \ni \Omega \rightarrow \eta_\Omega(S) = \int_{G^k \Omega} \eta \in \mathbb{R}. \quad (5.1)$$

We roughly describe in this paper this construction for $k = 1$, representing variational functionals of *Finsler geometry* in terms of differential forms (cf. Urban and

Krupka [7]). Consider the tangent bundle $\Lambda^1 TY = TY$, a chart (V, ψ) , $\psi = (y^\sigma)$, on Y , and the associated chart $(\tau^1)^{-1}(V)$, $\Psi = (y^\sigma, \dot{y}^\sigma)$, on TY . A function $F : TY \rightarrow \mathbb{R}$ satisfies the *homogeneity condition*, if it satisfies

$$F(\lambda\xi) = \lambda F(\xi)$$

for all tangent vectors ξ and every positive $\lambda \in \mathbb{R}$. The same can be stated in coordinates, requiring that

$$F(y^\nu, \lambda\dot{y}^\nu) = \lambda F(y^\nu, \dot{y}^\nu).$$

Theorem 2.

(1) For any function $F : TY \rightarrow \mathbb{R}$, the chart expressions

$$\eta = \frac{\partial F}{\partial \dot{y}^\nu} dy^\nu \tag{5.2}$$

define a global 1-form on TY .

(2) If F satisfies the homogeneity condition, then η is projectable on the Grassmann fibration $G^1 TY$.

(3) If F satisfies the homogeneity condition, then, for any curve $\zeta : I \rightarrow Y$

$$(\Lambda^1 \zeta) * \eta = (F \circ \Lambda^1 \zeta) dt. \tag{5.3}$$

The form η (5.2) is known as the *Hilbert form* (Chern, Chen and Lam [1], Crampin and Saunders [2]). Theorem 2 (2) characterizes its basic property when F is positive homogeneous: namely, in this case the Hilbert form is defined on the *Grassmann fibration* $G^1 TY$. One can also easily verify that η is a special case of the *Lepage-Cartan form*. This fact completely determines the behaviour of the variational functional (5.1) under variations of submanifolds, extremal submanifolds, and their invariance properties.

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