



Miskolc Mathematical Notes
Vol. 14 (2013), No 1, pp. 19-30

HU e-ISSN 1787-2413
DOI: 10.18514/MMN.2013.399

On common fixed point theorems for (ψ, ϕ) -generalized f -weakly contractive mappings

H. Aydi



ON COMMON FIXED POINT THEOREMS FOR (ψ, φ) -GENERALIZED f -WEAKLY CONTRACTIVE MAPPINGS

H. AYDI

Received September 15, 2011

Abstract. In this paper, we present some common fixed point theorems for (ψ, φ) -generalized f -weakly contractive mappings in metric and ordered metric spaces. Our results extend, generalize and improve some well-known results in the literature. Also, we give an example to illustrate our results.

2000 *Mathematics Subject Classification:* 54H25; 47H10; 54E50

Keywords: common fixed point, commuting maps, f -weakly contractive maps, generalized f -weakly contractive maps, ordered metric space

1. INTRODUCTION AND PRELIMINARIES

The first important result on fixed points for contractive type mapping was the much celebrated Banach's contraction principle by Banach [2] in 1922. After this, Kannan [9, 10] proved the following result:

Theorem 1. *Let (X, d) be a complete metric space. If $T : X \rightarrow X$ satisfies*

$$d(Tx, Ty) \leq k[d(x, Tx) + d(y, Ty)],$$

where $0 < k < \frac{1}{2}$ and $x, y \in X$, then T has a unique fixed point.

A similar type of contractive condition has been studied by Chatterjee [5] and he proved the following result:

Theorem 2. *Let (X, d) be a complete metric space. If $T : X \rightarrow X$ satisfies a C -contraction given as follows:*

$$d(Tx, Ty) \leq k[d(x, Ty) + d(y, Tx)],$$

where $0 < k < \frac{1}{2}$ and $x, y \in X$, then T has a unique fixed point.

Alber and Guerre-Delabriere [1] introduced the definition of weak Φ -contraction.

Definition 1. A self mapping T on a metric space X is called weak Φ -contraction if there exists a function $\Phi : [0, +\infty) \rightarrow [0, +\infty)$ such that for each $x, y \in X$,

$$d(Tx, Ty) \leq d(x, y) - \Phi(d(x, y)).$$

The notion of Φ -contraction and weak Φ -contraction has been studied by many authors, see [3, 12, 15, 17, 19]. In recent years, many results related to fixed point theorems in partially ordered metric spaces are given, for more details see [8, 12–16].

Choudhury in [6] introduced a generalization of C -contraction given by the following definition.

Definition 2 ([6]). Let (X, d) be a metric space. A mapping $T : X \rightarrow X$ is said to be weakly C -contractive (or a weak C -contraction) if for all $x, y \in X$,

$$d(Tx, Ty) \leq \frac{1}{2}(d(x, Ty) + d(y, Tx)) - \varphi(d(x, Ty), d(y, Tx)),$$

where $\varphi : [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function such that $\varphi(x, y) = 0$ if and only if $x = y = 0$.

In [6] the author proves that if X is complete then every weak C -contraction has a unique fixed point. Recently, Harjani et al, [8] presented this last result in the context of ordered metric spaces.

Chandok [4] introduced the following definition : A map $T : X \rightarrow X$ is generalized f -weakly contractive if for each $x, y \in X$,

$$d(Tx, Ty) \leq \frac{1}{2}(d(fx, Ty) + d(fy, Tx)) - \varphi(d(fx, Ty), d(fy, Tx)),$$

where $\varphi : [0, +\infty) \rightarrow [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function such that $\varphi(x, y) = 0$ if and only if $x = y = 0$.

If $f = I_X$, the identity mapping, then generalized f -weakly contractive mapping is weakly C -contractive.

Khan et al. [11] introduced the concept of altering distance function as follows:

Definition 3 (altering distance function, [11]). The function $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is called an altering distance function if the following properties are satisfied:

- (1) ψ is continuous and non-decreasing.
- (2) $\psi(t) = 0$ if and only if $t = 0$.

Following the above definitions, we introduce the following:

Definition 4. A map $T : X \rightarrow X$ is called (ψ, φ) -generalized f -weakly contractive if for each $x, y \in X$,

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)),$$

where

- (1) $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function.
- (2) $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(t, s) = 0$ if and only if $t = s = 0$.

If $\psi(t) = t$, then (ψ, φ) -generalized f -weakly contractive mapping is generalized f -weakly contractive.

The aim of this paper is to study some common fixed point theorems for (ψ, φ) -generalized f -weakly contractive in metric and ordered metric spaces.

2. MAIN RESULTS

First, we state the following known definition:

Definition 5. Let X a non-empty set. A point $x \in X$ is a coincidence point (common fixed point) of $f : X \rightarrow X$ and $T : X \rightarrow X$ if $fx = Tx$ ($x = fx = Tx$). The pair $\{f, T\}$ is called commuting if $Tfx = fTx$ for all $x \in X$.

We start with a common fixed point theorem for (ψ, φ) -generalized f -weakly contractive mappings in complete metric spaces.

Theorem 3. Let (X, d) be a metric space. Let $f, T : X \rightarrow X$ satisfy $T(X) \subset f(X)$, $(f(X), d)$ is complete and

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.1)$$

for all $x, y \in X$, where

- (1) $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function,
- (2) $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(t, s) = 0$ if and only if $t = s = 0$, then T and f have a coincidence point in X . Further, if T and f commute at their coincidence points, then T and f have a common fixed point.

Proof. Let $x_0 \in X$. Since $T(X) \subset f(X)$, we can choose $x_1 \in X$, so that $fx_1 = Tx_0$. Since $Tx_1 \in f(X)$, there exists $x_2 \in X$ such that $fx_2 = Tx_1$. By induction, we construct a sequence $\{x_n\}$ in X such that $fx_{n+1} = Tx_n$, for every $n \in \mathbb{N}$. By inequality (2.1), we have

$$\begin{aligned} \psi(d(Tx_{n+1}, Tx_n)) &\leq \psi\left(\frac{1}{2}[d(fx_{n+1}, Tx_n) + d(fx_n, Tx_{n+1})]\right) \\ &\quad - \varphi(d(fx_{n+1}, Tx_n), d(fx_n, Tx_{n+1})) \\ &= \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) - \varphi(0, d(Tx_{n-1}, Tx_{n+1})) \\ &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) \\ &\leq \psi\left(\frac{1}{2}[d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n+1})]\right). \end{aligned} \quad (2.2)$$

Since ψ is a non-decreasing function, we get that

$$d(Tx_n, Tx_{n+1}) \leq d(Tx_{n-1}, Tx_n) \quad \text{for any } n \in \mathbb{N}^*. \quad (2.3)$$

Thus, $\{d(Tx_n, Tx_{n+1})\}$ is a monotone non-increasing sequence of non-negative real numbers and hence is convergent. Hence there is $r \geq 0$ such that

$$\lim_{n \rightarrow +\infty} d(Tx_n, Tx_{n+1}) = r.$$

Using a triangular inequality, we have

$$d(Tx_{n+1}, Tx_n) \leq \frac{1}{2}d(Tx_{n-1}, Tx_{n+1}) \leq \frac{1}{2}[d(Tx_{n-1}, Tx_n) + d(Tx_n, Tx_{n+1})].$$

Letting $n \rightarrow +\infty$, we get

$$r \leq \frac{1}{2} \lim_{n \rightarrow +\infty} d(Tx_{n-1}, Tx_{n+1}) \leq \frac{1}{2}r + \frac{1}{2}r,$$

that is $\lim_{n \rightarrow +\infty} d(Tx_{n-1}, Tx_{n+1}) = 2r$. Using the continuity of ψ and φ , and inequality (2.2), we have, letting $n \rightarrow +\infty$

$$\psi(r) \leq \psi(r) - \varphi(0, 2r),$$

and consequently, $\varphi(0, 2r) \leq 0$. Thus, by a property of φ , $r = 0$, so

$$\lim_{n \rightarrow +\infty} d(Tx_{n+1}, Tx_n) = 0. \quad (2.4)$$

Now, we show that $\{Tx_n\}$ is a Cauchy sequence. If otherwise, then there exists $\varepsilon > 0$ for which we can find subsequences $\{Tx_{m(k)}\}$ and $\{Tx_{n(k)}\}$ of $\{Tx_n\}$ with $n(k) > m(k) > k$ such that for every k ,

$$d(Tx_{m(k)}, Tx_{n(k)}) \geq \varepsilon, \quad d(Tx_{m(k)}, Tx_{n(k)-1}) < \varepsilon. \quad (2.5)$$

By triangular inequality, we have from (2.5)

$$\begin{aligned} \varepsilon &\leq d(Tx_{m(k)}, Tx_{n(k)}) \\ &\leq d(Tx_{m(k)}, Tx_{n(k)-1}) + d(Tx_{n(k)-1}, Tx_{n(k)}) \\ &< \varepsilon + d(Tx_{n(k)-1}, Tx_{n(k)}). \end{aligned}$$

Using (2.4), we get

$$\lim_{k \rightarrow +\infty} d(Tx_{m(k)}, Tx_{n(k)}) = \lim_{k \rightarrow +\infty} d(Tx_{m(k)}, Tx_{n(k)-1}) = \varepsilon. \quad (2.6)$$

On the other hand,

$$\begin{aligned} d(Tx_{m(k)}, Tx_{n(k)-1}) &\leq d(Tx_{m(k)}, Tx_{m(k)-1}) + d(Tx_{m(k)-1}, Tx_{n(k)}) \\ &\quad + d(Tx_{n(k)}, Tx_{n(k)-1}), \end{aligned}$$

and

$$d(Tx_{m(k)-1}, Tx_{n(k)}) \leq d(Tx_{m(k)-1}, Tx_{m(k)}) + d(Tx_{m(k)}, Tx_{n(k)}).$$

Letting $k \rightarrow +\infty$ in the two above inequalities, we have thanks to (2.4) and (2.6),

$$\lim_{k \rightarrow +\infty} d(Tx_{m(k)-1}, Tx_{n(k)}) = \varepsilon. \quad (2.7)$$

From (2.1), we have

$$\begin{aligned}
\psi(\varepsilon) &\leq \psi(d(Tx_{m(k)}, Tx_{n(k)})) \\
&\leq \psi\left(\frac{1}{2}[d(fx_{m(k)}, Tx_{n(k)}) + d(fx_{n(k)}, Tx_{m(k)})]\right) \\
&\quad - \varphi(d(fx_{m(k)}, Tx_{n(k)}), d(fx_{n(k)}, Tx_{m(k)})) \\
&= \psi\left(\frac{1}{2}[d(Tx_{m(k)-1}, Tx_{n(k)}) + d(Tx_{n(k)-1}, Tx_{m(k)})]\right) \\
&\quad - \varphi(d(Tx_{m(k)-1}, Tx_{n(k)}), d(Tx_{n(k)-1}, Tx_{m(k)})).
\end{aligned}$$

Taking $k \rightarrow +\infty$, using the continuity of ψ and φ , we obtain from (2.6), (2.7)

$$\psi(\varepsilon) \leq \psi(\varepsilon) - \varphi(\varepsilon, \varepsilon),$$

hence $\varphi(\varepsilon, \varepsilon) = 0$, so $\varepsilon = 0$, it is a contradiction. Thus $\{Tx_n\}$ is a Cauchy sequence. Since $fx_n = Tx_{n-1}$, hence $\{fx_n\}$ is a Cauchy sequence in $(f(X), d)$, which is complete. Thus there is $z \in X$ such that

$$\lim_{n \rightarrow +\infty} fx_n = fz. \quad (2.8)$$

Moreover, (2.4) reads

$$\lim_{n \rightarrow +\infty} d(fx_n, fx_{n+1}) = 0. \quad (2.9)$$

By (2.1), we have

$$\begin{aligned}
\psi(d(Tz, fx_{n+1})) &= \psi(d(Tz, Tx_n)) \\
&\leq \psi\left(\frac{1}{2}[d(fz, Tx_n) + d(fx_n, Tz)]\right) - \varphi(d(fz, Tx_n), d(fx_n, Tz)) \\
&= \psi\left(\frac{1}{2}[d(fz, fx_{n+1}) + d(fx_n, Tz)]\right) - \varphi(d(fz, fx_{n+1}), d(fx_n, Tz)),
\end{aligned}$$

and letting $n \rightarrow +\infty$, using the continuity of ψ and φ and by (2.8), (2.9), we find

$$\psi(d(Tz, fz)) \leq \psi\left(\frac{1}{2}d(Tz, fz)\right) - \varphi(0, d(fz, Tz)) \leq \psi\left(\frac{1}{2}d(Tz, fz)\right).$$

Consequently, $d(Tz, fz) \leq \frac{1}{2}d(Tz, fz)$, that is, $d(Tz, fz) = 0$, i.e. $Tz = fz$, hence z is a coincidence point of T and f . Now suppose that T and f commute at z . Let $w = Tz = fz$. Then $Tw = T(fz) = f(Tz) = fw$. By inequality (2.1)

$$\begin{aligned}
\psi(d(Tz, Tw)) &\leq \psi\left(\frac{1}{2}[d(fz, Tw) + d(fw, Tz)]\right) - \varphi(d(fz, Tw), d(fw, Tz)) \\
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi(d(Tz, Tw)) - \varphi(d(Tz, Tw), d(Tw, Tz)).
\end{aligned}$$

This implies that $d(Tz, Tw) = 0$, by the property of φ . Therefore, $Tw = fw = w$. This completes the proof of Theorem 3. \square

Example 1. Let $X = [0, +\infty)$. Let d be defined by $d(x, y) = |x - y|$ for all $x, y \in X$. We set $fx = \frac{x}{2}$ and $Tx = \frac{x}{4}$ for all $x \in X$. It is clear that $T(X) \subset f(X)$ and $(f(X), d)$ is a complete metric space. Define $\psi : [0, +\infty) \rightarrow [0, +\infty)$ and $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ by

$$\psi(t) = \frac{t}{2} \quad \text{and} \quad \varphi(t, s) = \frac{1}{16}(t + s).$$

It is obvious that ψ and φ satisfy the hypotheses of Theorem 3. We need to show that the inequality (2.1) holds for any $x, y \in X$. First, the left-hand side of (2.1) is

$$\psi(d(Tx, Ty)) = \frac{1}{8}|x - y|. \quad (2.10)$$

While, the right-hand side of (2.1) is

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{1}{4}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] - \frac{1}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right]. \end{aligned} \quad (2.11)$$

By symmetry of (2.10) and (2.11), and without loss of generality, we suppose that $x \geq y$. In particular, (2.10) reads

$$\psi(d(Tx, Ty)) = \frac{1}{8}(x - y).$$

We distinguish two cases:

- If $2y \geq x$. Here, we have from (2.11)

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] = \frac{3}{16}\left[\left(\frac{x}{2} - \frac{y}{4}\right) + \left(\frac{y}{2} - \frac{x}{4}\right)\right] \\ &= \frac{3}{64}(x + y) \geq \frac{1}{8}(x - y) = \psi(d(Tx, Ty)). \end{aligned} \quad (2.12)$$

- If $2y < x$. Here, we have from (2.11)

$$\begin{aligned} & \psi\left(\frac{1}{2}(d(fx, Ty) + d(fy, Tx))\right) - \varphi(d(fx, Ty), d(fy, Tx)) \\ &= \frac{3}{16}\left[\left|\frac{x}{2} - \frac{y}{4}\right| + \left|\frac{y}{2} - \frac{x}{4}\right|\right] = \frac{3}{16}\left[\left(\frac{x}{2} - \frac{y}{4}\right) + \left(-\frac{y}{2} + \frac{x}{4}\right)\right] \\ &= \frac{9}{64}(x - y) \geq \frac{1}{8}(x - y) = \psi(d(Tx, Ty)). \end{aligned} \quad (2.13)$$

By (2.12) and (2.13), the inequality (2.1) is satisfied. Then by Theorem 3, T and f have a common fixed point, which is $z = 0$.

Corollary 1. *Let (X, d) be a complete metric space. If $T : X \rightarrow X$ satisfies*

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(x, Ty) + d(y, Tx)]\right) - \varphi(d(x, Ty), d(y, Tx)), \quad (2.14)$$

for all $x, y \in X$, where

- (1) $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function,
- (2) $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(t, s) = 0$ if and only if $t = s = 0$, then T has a unique fixed point.

Proof. It follows by taking $f = I_X$ in Theorem 3. The uniqueness of the fixed point follows by the following: suppose u and v are fixed points of T . By (2.14), we have

$$\begin{aligned} \psi(d(u, v)) &= \psi(d(Tu, Tv)) \\ &\leq \psi\left(\frac{1}{2}[d(u, Tv) + d(v, Tu)]\right) - \varphi(d(u, Tv), d(v, Tu)) \\ &= \psi\left(\frac{1}{2}[d(u, v) + d(v, u)]\right) - \varphi(d(u, v), d(v, u)) \\ &= \psi(d(u, v)) - \varphi(d(u, v), d(v, u)), \end{aligned}$$

which implies that $\varphi(d(u, v), d(v, u)) = 0$, and by a property of φ , we get $u = v$. \square

Corollary 2. *Let (X, d) be a metric space. If $T, f : X \rightarrow X$ are such that $T(X) \subset f(X)$, $(f(X), d)$ is complete and*

$$d(Tx, Ty) \leq \frac{1}{2}[d(fx, Ty) + d(fy, Tx)] - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.15)$$

for all $x, y \in X$, where $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(t, s) = 0$ if and only if $t = s = 0$, then T and f have a coincidence point in X . Further, if T and f commute at their coincidence points, then T and f have a common fixed point.

Proof. The proof follows by taking $\psi(t) = t$ in Theorem 3. \square

Corollary 3. *Let (X, d) be a complete metric space. If $T : X \rightarrow X$ satisfies for all $x, y \in X$*

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \varphi(d(x, Ty), d(y, Tx)), \quad (2.16)$$

where $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(t, s) = 0$ if and only if $t = s = 0$, then T has a unique fixed point.

Proof. It follows by taking $f = Id_X$ in Corollary 2. The uniqueness of the fixed point follows from Corollary 1. \square

- Remark 1.*
- Corollary 1 corresponds to Corollary 2.1 of Shatanawi [18].
 - Corollary 2 corresponds to Theorem 1 of Chandok [4].
 - Corollary 3 corresponds to Theorem 2.1 of Choudhury [6].

Now, we extend Theorem 3 and we prove a common fixed point theorem for f -non-decreasing generalized nonlinear contraction mappings in the context of ordered metric spaces.

Definition 6 ([7]). Suppose (X, \leq) is a partially ordered set and $T, f : X \rightarrow X$. T is said to be monotone f -nondecreasing if for all $x, y \in X$,

$$fx \leq fy \quad \text{implies} \quad Tx \leq Ty. \quad (2.17)$$

If $f = I_X$ in Definition 6, then T is monotone non-decreasing.

Theorem 4. Let (X, \leq) be a partially ordered set and suppose that there exists a metric d on X such that (X, d) is a complete metric space. Let f and T are self-mappings of X such that $T(X) \subset f(X)$, $f(X)$ is closed and T is f -non-decreasing mapping. Suppose that f and T satisfy for all $x, y \in X$, for which $f(x) \leq f(y)$

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(fx, Ty) + d(fy, Tx)]\right) - \varphi(d(fx, Ty), d(fy, Tx)) \quad (2.18)$$

where

- (1) $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function,
- (2) $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(x, y) = 0$ if and only if $x = y = 0$.

Also, suppose that if $\{f(x_n)\} \subset X$ is a non-decreasing sequence with $f(x_n) \rightarrow f(z)$ in $f(X)$, then $f(x_n) \leq f(z)$ and $f(z) \leq f(f(z))$ for every n .

If there exists $x_0 \in X$ with $fx_0 \leq Tx_0$, then T and f have a coincidence point. Further, if T and f commute at their coincidence points, then T and f have a common fixed point.

Proof. Let $x_0 \in X$ such that $fx_0 \leq Tx_0$. Since $T(X) \subset f(X)$, we can choose $x_1 \in X$, so that $fx_1 = Tx_0$. Since $Tx_1 \in f(X)$, there exists $x_2 \in X$ such that $fx_2 = Tx_1$. By induction, we construct a sequence $\{x_n\}$ in X such that

$$fx_{n+1} = Tx_n.$$

Since $fx_0 \leq Tx_0$, $Tx_0 = fx_1$, so $fx_0 \leq fx_1$. T is f -non-decreasing mapping, we get $Tx_0 \leq Tx_1$. Similarly $fx_1 \leq fx_2$, $Tx_1 \leq Tx_2$, hence $fx_2 \leq fx_3$. Continuing, we obtain

$$fx_0 \leq fx_1 \leq fx_2 \leq \dots \leq fx_n \leq fx_{n+1} \leq \dots$$

If for some n , $Tx_{n+1} = Tx_n$, then $Tx_{n+1} = fx_{n+1}$, i.e. T and f have a coincidence point x_{n+1} , and so we have the result. For the rest, assume that $d(Tx_n, Tx_{n+1}) > 0$

for all $n \in \mathbb{N}$. By (2.18), we have

$$\begin{aligned} \psi(d(Tx_n, Tx_{n+1})) &\leq \psi\left(\frac{1}{2}[d(fx_{n+1}, Tx_n) + d(fx_n, Tx_{n+1})]\right) \\ &\quad - \varphi(d(fx_{n+1}, Tx_n), d(fx_n, Tx_{n+1})) \\ &= \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) - \varphi(0, d(Tx_{n-1}, Tx_{n+1})) \\ &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_{n+1})\right) \\ &\leq \psi\left(\frac{1}{2}d(Tx_{n-1}, Tx_n) + \frac{1}{2}d(Tx_n, Tx_{n+1})\right). \end{aligned}$$

It follows that, for any $n \in \mathbb{N}^*$

$$d(Tx_n, Tx_{n+1}) \leq d(Tx_{n-1}, Tx_n).$$

Thus $\{d(Tx_n, Tx_{n+1})\}$ is a monotone non-increasing sequence, hence it is convergent. Now, proceeding as in Theorem 3, we can prove that

$$\lim_{n \rightarrow +\infty} d(Tx_n, Tx_{n+1}) = 0. \quad (2.19)$$

Moreover, $\{Tx_n\}$ is a Cauchy sequence. Since $Tx_n = fx_{n+1}$ and $f(X)$ is closed, so there exists $z \in X$ such that

$$\lim_{n \rightarrow +\infty} fx_n = fz. \quad (2.20)$$

Having in mind $\{fx_n\}$ is a non-decreasing sequence, so by (2.20) we have for every $n \in \mathbb{N}$

$$fx_n \leq fz, \quad f(z) \leq f(fz). \quad (2.21)$$

Having $fx_n \leq fz$, so from inequality (2.18), we have

$$\begin{aligned} \psi(d(fx_{n+1}, Tz)) &= \psi(d(Tx_n, Tz)) \\ &\leq \psi\left(\frac{1}{2}[d(fz, Tx_n) + d(fx_n, Tz)]\right) - \varphi(d(fz, Tx_n), d(fx_n, Tz)) \\ &= \psi\left(\frac{1}{2}[d(fz, fx_{n+1}) + d(fx_n, Tz)]\right) - \varphi(d(fz, fx_{n+1}), d(fx_n, Tz)). \end{aligned}$$

Taking $n \rightarrow +\infty$, using the continuity of ψ and φ , we get from (2.19), (2.20)

$$\psi(d(Tz, fz)) \leq \psi\left(\frac{1}{2}d(fz, fz)\right) - \varphi(0, d(fz, Tz)),$$

that is, $d(Tz, fz) = 0$, hence $Tz = fz$, so z is a coincidence point of T and f .

Now suppose that T and f commute at z . Let $w = Tz = fz$. Then $Tw = T(fz) = f(Tz) = fw$. From (2.21), we have $fz \leq f(fz) = fw$, so the inequality (2.18) gives us

$$\psi(d(Tz, Tw)) \leq \psi\left(\frac{1}{2}[d(fz, Tw) + d(fw, Tz)]\right) - \varphi(d(fz, Tw), d(fw, Tz))$$

$$\begin{aligned}
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi\left(\frac{1}{2}[d(Tz, Tw) + d(Tw, Tz)]\right) - \varphi(d(Tz, Tw), d(Tw, Tz)) \\
&= \psi(d(Tz, Tw)) - \varphi(d(Tz, Tw), d(Tw, Tz)).
\end{aligned}$$

This implies that $d(Tz, Tw) = 0$, by the property of φ . Therefore, $Tw = fz = w$. This completes the proof of Theorem 4. \square

Corollary 4. *Let (X, \leq) be a partially ordered set and suppose that there exists a metric d on X such that (X, d) is a complete metric space. Let f and T are self-mappings of X such that $T(X) \subset f(X)$, $f(X)$ is closed and T is f -non-decreasing mapping. Assume that f and T satisfy for all $x, y \in X$, for which $f(x) \leq f(y)$*

$$d(Tx, Ty) \leq \frac{1}{2}[d(fx, Ty) + d(fy, Tx)] - \varphi(d(fx, Ty), d(fy, Tx)), \quad (2.22)$$

where $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(x, y) = 0$ if and only if $x = y = 0$.

Also, suppose that if $\{f(x_n)\} \subset X$ is a non-decreasing sequence with $f(x_n) \rightarrow f(z)$ in $f(X)$, then $f(x_n) \leq f(z)$ and $f(z) \leq f(f(z))$ for every n .

If there exists $x_0 \in X$ with $fx_0 \leq Tx_0$, then T and f have a coincidence point. Further, if T and f commute at their coincidence points, then T and f have a common fixed point.

Proof. It follows by taking $\psi(t) = t$ in Theorem 4. \square

Corollary 5. *Let (X, \leq) be a partially ordered set and suppose that there exists a metric d on X such that (X, d) is a complete metric space. Let $T : X \rightarrow X$ be a monotone non-decreasing mapping. Suppose that T satisfies for all $x, y \in X$, for which $x \leq y$,*

$$\psi(d(Tx, Ty)) \leq \psi\left(\frac{1}{2}[d(x, Ty) + d(y, Tx)]\right) - \varphi(d(x, Ty), d(y, Tx)), \quad (2.23)$$

where

- (1) $\psi : [0, +\infty) \rightarrow [0, +\infty)$ is an altering distance function,
- (2) $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(x, y) = 0$ if and only if $x = y = 0$.

Also suppose either

- (i) $\{x_n\} \subset X$ is a non-decreasing sequence with $x_n \rightarrow z$, then $x_n \leq z$ for every n , or
- (ii) T is continuous.

If there exists $x_0 \in X$ with $x_0 \leq Tx_0$, then T has a fixed point.

Proof. If (i) holds, then taking $f = I_X$ in Theorem 4, we get the result. If (ii) holds, then proceeding as in Theorem 4 with $f = I_X$, we can prove that $\{Tx_n\}$ is a Cauchy sequence and

$$z = \lim_{n \rightarrow +\infty} x_{n+1} = \lim Tx_n = T(\lim_{n \rightarrow +\infty} x_n) = Tz.$$

Hence the proof is completed. \square

Corollary 6. *Let (X, \leq) be a partially ordered set and suppose that there exists a metric d on X such that (X, d) is a complete metric space. Let $T : X \rightarrow X$ be a monotone non-decreasing mapping. Suppose that T satisfies for all $x, y \in X$, for which $x \leq y$,*

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \varphi(d(x, Ty), d(y, Tx)), \quad (2.24)$$

where $\varphi : [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function with $\varphi(x, y) = 0$ if and only if $x = y = 0$.

Also, suppose either

- (i) If $\{x_n\} \subset X$ is a non-decreasing sequence with $x_n \rightarrow z$, then $x_n \leq z$ for every n , or
- (ii) T is continuous.

If there exists $x_0 \in X$ with $x_0 \leq Tx_0$, then T has a fixed point.

Proof. It follows by taking $\psi(t) = t$ in Corollary 5. \square

Remark 2. Corollary 6 corresponds to Theorem 2.1 and Theorem 2.2 of Harjani et al. [8].

Corollary 7. *Let (X, \leq) be a partially ordered set and suppose that there exists a metric d on X such that (X, d) is a complete metric space. Let $T : X \rightarrow X$ be a monotone non-decreasing mapping. Suppose that T satisfies for all $x, y \in X$, for which $x \leq y$,*

$$d(Tx, Ty) \leq k[d(x, Ty) + d(y, Tx)], \quad (2.25)$$

where $0 < k < \frac{1}{2}$.

Also, suppose either

- (i) If $\{x_n\} \subset X$ is a non-decreasing sequence with $x_n \rightarrow z$, then $x_n \leq z$ for every n , or
- (ii) T is continuous.

If there exists $x_0 \in X$ with $x_0 \leq Tx_0$, then T has a fixed point.

Proof. It follows by taking $\varphi(t) = (\frac{1}{2} - k)t$ in Corollary 6. \square

REFERENCES

- [1] Y. I. Alber and S. Guerre-Delabriere, "Principle of weakly contractive maps in Hilbert spaces," in *New results in operator theory and its applications: the Israel M. Glazman memorial volume*, ser. Oper. Theory, Adv. Appl., I. Gohberg, Ed. Basel: Birkhäuser, 1997, vol. 98, pp. 7–22.
- [2] S. Banach, "Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales," *Fundamenta math.*, vol. 3, pp. 133–181, 1922.
- [3] D. W. Boyd and J. S. W. Wong, "On nonlinear contractions," *Proc. Am. Math. Soc.*, vol. 20, pp. 458–464, 1969.
- [4] S. Chandok, "Some common fixed point theorems for generalized f -weakly contractive mappings," *J. Appl. Math. Inform.*, vol. 29, no. 1-2, pp. 257–265, 2011.
- [5] S. K. Chatterjee, "Fixed point theorem," *C. R. Acad. Bulgare Sci.*, vol. 25, pp. 727–730, 1972.
- [6] B. S. Choudhury, "Unique fixed point theorem for weakly C -contractive mappings," *Kathmandu University J. Sci. Engg. Tech.*, vol. 5, pp. 6–13, 2009.
- [7] L. Ćirić, N. Ćakić, M. Rajović, and J. S. Ume, "Monotone generalized nonlinear contractions in partially ordered metric spaces," *Fixed Point Theory Appl.*, vol. 2008, p. 11, 2008.
- [8] J. Harjani, B. López, and K. Sadarangani, "Fixed point theorems for weakly c -contractive mappings in ordered metric spaces," *Comput. Math. Appl.*, vol. 61, no. 4, pp. 790–796, 2011.
- [9] R. Kannan, "Some results on fixed points. ii," *Am. Math. Mon.*, vol. 76, pp. 405–408, 1969.
- [10] R. Kannan, "Some results on fixed points," *Bull. Calcutta Math. Soc.*, vol. 60, pp. 71–76, 1986.
- [11] M. S. Khan, M. Swaleh, and S. Sessa, "Fixed point theorems by altering distances between the points," *Bull. Aust. Math. Soc.*, vol. 30, pp. 1–9, 1984.
- [12] H. K. Nashine and B. Samet, "Fixed point results for mappings satisfying (ψ, φ) -weakly contractive condition in partially ordered metric spaces," *Nonlinear Anal., Theory Methods Appl., Ser. A, Theory Methods*, vol. 74, no. 6, pp. 2201–2209, 2011.
- [13] J. J. Nieto, R. L. Pouso, and R. Rodríguez-López, "Fixed point theorems in ordered abstract spaces," *Proc. Am. Math. Soc.*, vol. 135, no. 8, pp. 2505–2517, 2007.
- [14] J. J. Nieto and R. Rodríguez-López, "Contractive mapping theorems in partially ordered sets and applications to ordinary differential equations," *Order*, vol. 22, no. 3, pp. 223–239, 2005.
- [15] O. Popescu, "Fixed points for (ψ, φ) -weak contractions," *Appl. Math. Lett.*, vol. 24, no. 1, pp. 1–4, 2011.
- [16] A. C. M. Ran and M. C. B. Reurings, "A fixed point theorem in partially ordered sets and some applications to matrix equations," *Proc. Am. Math. Soc.*, vol. 132, no. 5, pp. 1435–1443, 2004.
- [17] B. E. Rhoades, "Some theorems on weakly contractive maps," *Nonlinear Anal., Theory Methods Appl.*, vol. 47, no. 4, pp. 2683–2693, 2001.
- [18] W. Shatanawi, "Fixed point theorems for nonlinear weakly-contractive mappings in metric spaces," *Math. Comput. Modelling*, vol. 54, no. 11-12, pp. 2816–2826, 2011.
- [19] Q. Zhang and Y. Song, "Fixed point theory for generalized φ -weak contractions," *Appl. Math. Lett.*, vol. 22, no. 1, pp. 75–78, 2009.

Author's address

H. Aydi

Université de Sousse, Institut Supérieur d'Informatique et des Technologies de Communication de Hammam Sousse, Route GPI-4011, H. Sousse, Tunisia

E-mail address: hassen.aydi@isima.rnu.tn