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# Designing objective quality metrics for panoramic videos based on human perception

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## Abstract

The creation of high quality panoramic videos for immersive VR content is commonly done using a rig with multiple cameras covering the required scene. Unfortunately, this setup introduces both spatial and temporal artifacts due to the difference in optical centers as well as imperfect synchronization of cameras. Traditional image quality metrics are inadequate for describing geometric distortions in panoramic videos. In this paper, we propose an objective quality assessment approach for calculating these distortions based on optical flow coupled with an existing salience detection model. Our approach is validated with a human-centered study using error annotations and eye-tracking. Preliminary results indicate a good correlation between errors detected by the algorithm and human perception of errors.

**Keywords:** Panoramic Videos, Quality Assessment, Human Perception, Parallax Errors.

## 1 Introduction

The richness of panoramic videos within immersive environments makes it possible to capture outstanding scenes where the user can experience presence. However, realism of such videos is highly affected by visual artifacts such as parallax errors that appear in the form of deformations or ghosting. Unfortunately, this is unavoidable in panoramic video capture due to the use of multiple overlapping cameras. Several attempts have striven to minimize these errors [Perazzi et al., 2015, Lee et al., 2016], but neither could completely remove them. Quantifying those errors is important to video producers for quality monitoring and to researchers for algorithms optimization. Traditional image/video quality metrics are not well suited for capturing the geometric nature of panoramic video defects.

In this paper, we propose a quality assessment method based on a relative comparison of optical flow between the set of input videos overlapping at a pixel location and its corresponding pixel in the output panorama. We enhance our results with the calculation of a salience map proposed by [Conze et al., 2012]. Finally, we assess our method using a human-centered empirical experiment by means of an error annotation interface along with eye-tracking Tobii glasses. Results show a good correlation between the way human perceive errors and the proposed objective metric as well as put the light on the importance of salience calculation.

## 2 Optical flow-based quality metrics

Several techniques for panoramic video quality assessment focus on user experiments within a virtual environment where salience data is recorded and analyzed [Xu et al., 2017, Zhang et al., 2017]. Although interesting, subjective experiments are expensive and unpractical. As an alternative, we have investigated optical flow-based methods for this problem. A quality metric for stitched images was proposed by [Cheung et al., 2017] which calculates optical flow in the overlapping regions between views along with a salience map that guides the calculation. Unlike our approach, this method only works for images and is not applicable on videos. Another limitation is the constraint they put on camera setup where the central image in a 3-view scene can be

considered the reference. Similar to our method, [K. and Channappayya, 2016] calculate a temporal feature from optical flow then use feature statistics to compare the reference and distorted videos on a frame-by-frame basis. Their approach is intended, however, to single-view videos hence does not have to deal with multiple inputs. The success of these methods in identifying geometrical defects has motivated us to work on an optical flow-based method for panoramic videos.

### 3 Proposed objective quality metric

In a panoramic video, a final output video frame is a composite novel view from a number of input views that go through a series of geometric transformations. Panoramic video stitching methods usually add further transformations for parallax compensation [Perazzi et al., 2015, Lee et al., 2016]. Our method suggests using the original videos as a reference to the single output panorama by comparing the difference in motion between two given frames in the original videos and motion in the final panorama. However, this is not directly applicable since a given pixel  $x_{pano}$  in the final panorama can have one to  $N$  sources corresponding to  $N$  input videos with overlapping regions. To overcome this, we have explored the calculation of the deviation of displacements of all source pixels  $x_i, i \in N$  from the displacement of the panorama  $x_{pano}$  between times  $t$  and  $t + 1$ . In this way, we calculate the optical flow between two frames at times  $t$  and  $t + 1$  of each input video and the final panorama. We calculate the standard deviation of the end points of the vector field at each pixel  $x$  of the panoramic image to produce our distortion map  $M_d$  as follows:

$$M_d(x_t) = \sqrt{\frac{(x_{pano,t+1} - \sum_i^n x_{i,t+1})^2}{n}} \quad (1)$$

where  $n \in [1, N]$  is the number of overlapping images at pixel  $x$  and  $x_{t+1} = x_t + \mu(x_t)$  and  $\mu$  is the motion field of a pixel between times  $t$  and  $t + 1$ .

For more accurate results, we determine visual salience using visibility maps as suggested by [Conze et al., 2012]. Visibility maps model three features that have been shown to mask errors, which are contrast, texture and variation of gradient orientations. Equations for these maps are detailed in [Conze et al., 2012]. We define our salience map  $M_s$  for a panoramic frame  $I_{pano}$  as:

$$M_s = W_c(I_{pano}) * W_t(I_{pano}) * W_o(I_{pano}) \quad (2)$$

where  $W_c$ ,  $W_t$  and  $W_o$  correspond to contrast, texture and orientation weighting maps respectively.

Building on the assumption that a human would gaze a region if it is distorted or if it salient, we propose to produce a distortion-salience map  $M_{ds}$  from  $M_d$  and  $M_s$  using a weighted sum. The parameter  $\omega$  can be changed depending on the video content, i.e.: a highly salient content implies a lower weight for  $M_s$ .

$$M_{ds} = \omega M_d + (1 - \omega) M_s \quad (3)$$

### 4 Human gaze and annotations: an empirical assessment

Our objective visual quality assessment is meant to model human perception’s sensitivity to distortions and salience. Thus, it was important to validate it with a human-centered study where we collected gaze data using eye tracking and user decision using annotation. In our experiment, we define an error as a region with high number of fixations and an annotation by at least one participant. The protocol for measuring such errors involved the observation of 20 participants wearing Tobii eye-tracking glasses while watching 4 short panoramic videos. Our experiment was designed to answer the following question: Do humans recognize errors that are not identified by an algorithm and vice-versa? The videos were displayed on a large screen for immersion and were played in a random order within an annotation interface that allows the observer to pause the video and mark a region they perceived as deformed. This setup allowed the collection of two types of data, participants’

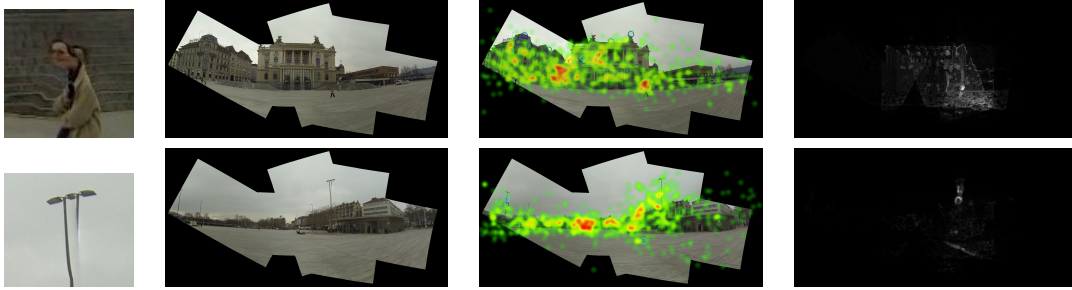


Figure 1: Results on *Opera* with corresponding heatmaps for gaze data and distortion map calculated by Eq. 1

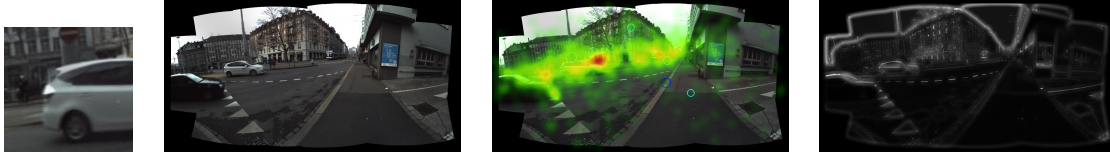


Figure 2: Results on *Street* with corresponding heatmaps for gaze data and salience map calculated by Eq. 2

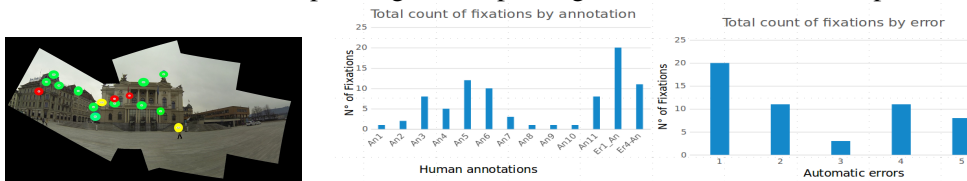


Figure 3: An example of a keyframe of *Opera* with corresponding AOIs. Charts to the right show that highest gazed error was also the most annotated by humans and it corresponds to the deformed person.

gaze and frames annotations. Our analysis was conducted on both types of data jointly. For each video, we chose one or more keyframes representing the central view within a sequence of frames. Depending on the scene being taken from a fixed view-point or a moving camera, we chose one keyframe or more.

To compare this with our objective metric, we calculated the temporal distortion on a sequence of frames whose center was a given keyframe. Temporal pooling of a given sequence was done by a simple OR then we overlaid our final composite map on the keyframe. Afterwards, data analysis was done using *Tobii Pro Lab* software. For each keyframe, we defined annotations collected by the 20 participants using Tobii Areas of Interest (AOI) corresponding to at least one human annotation. On the same keyframe, we defined the error regions identified by our distortion map as seen in figure 3. Qualitative results were obtained by generating heat-maps from gaze data recordings using an I-VT Tobii attention filter as suggested by [Salvucci and Goldberg, 2000]. Classical metrics such as total fixation count and total fixation duration [Holmqvist et al., 2011] were used to obtain descriptive statistics on the AOIs described earlier.

## 5 Preliminary results

In this paper, we present preliminary results that were obtained mainly on two videos *Opera* and *Street* taken in Zurich by Disney researchers [Perazzi et al., 2015]. We subdivided *Opera* into 5 keyframes since the camera is constantly moving, and only one for *Street* which was taken using a fixed rig hence content was nearly stable. Distortion and salience maps are calculated on those keyframes and we used [Farneback, 2003] for optical flow calculation. Heatmaps were generated for the 20 observers and combined on a single keyframe. We assume that an area with high fixations on a heatmap correspond to perceiving a distortion and/or a salience.

In response to our experimental question, preliminary results shown in 1 indicate that a person's face deformation and a lamp ghosting were the most annotated errors by participants in *Opera* which correspond to error locations identified by the distortion maps (see figure ). Results on *street* (see figure 2) show a correlation

between human gaze and the calculated salience map. Statistics on AOIs confirm our findings as in figure 3.

## 6 Conclusion

We presented a method for designing quality metrics for panoramic videos that was evaluated using a human-centered study. Our early results show that humans are more likely to see errors present in the foreground or moving objects, rather than those in the background. We were able to verify that the calculated distortion map was able to identify most error locations. However, the salience map is yet to be improved to reflect the new findings and be able to penalize distortions occurring in particular regions. Finally, we aim to complete our data analysis and provide a pooling method to obtain an index that can allow the comparison to other methods.

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