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Hydrodynamics of elastic micro-filaments : model comparison and applications

Clément Moreau, Laetitia Giraldi, and Hermes Gadêlha

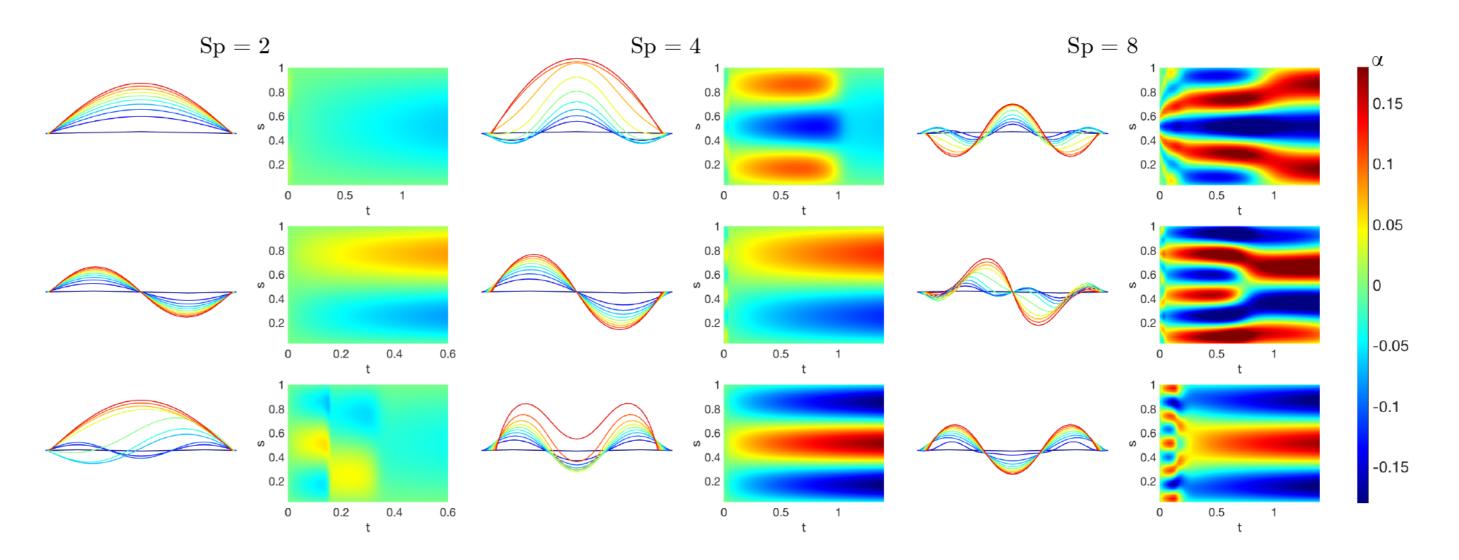


Motivations

- Efficiently model and simulate the dynamics of inextensible micro-filaments in 2D
- Deal with the coupling between elastic and hydrodynamic interactions
- Propose a model that is
 - simple to implement
 - Description of the numerically robust
 - adaptable for a range of applications

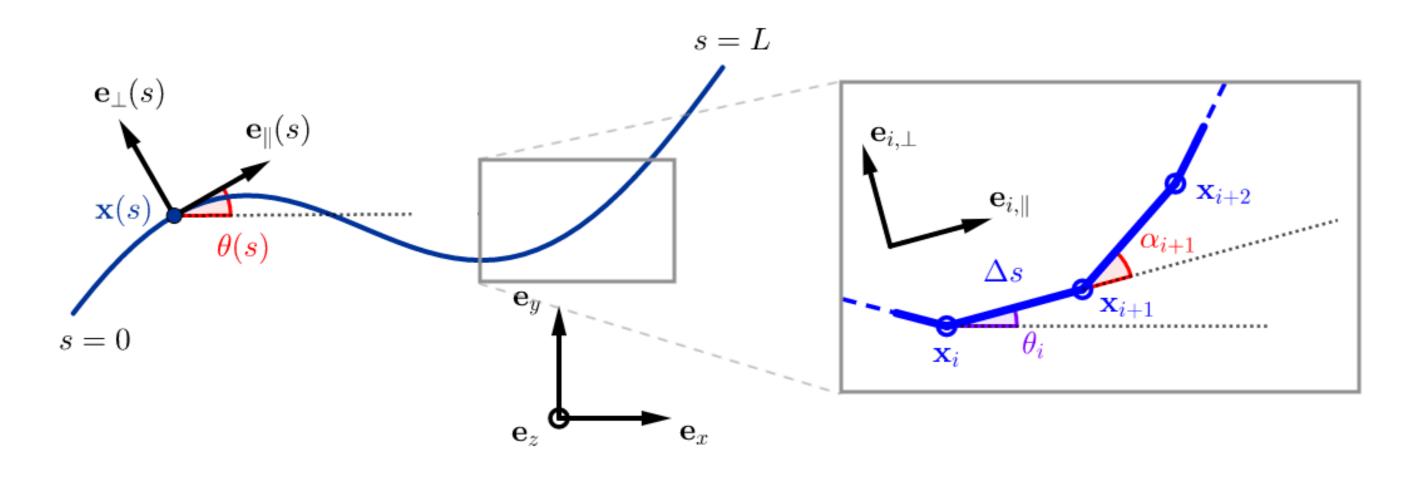
Applications : Buckling

- Filament submitted to compression
- Triggering different modes by changing initial condition



Modeling

> We consider an **inextensible flexible filament** immersed in a fluid at **low Reynolds number** \rightarrow inertia is negligible, viscous effects dominate: **Stokes regime**



Parametrisation for the continuous and coarse-grained models

Hydrodynamics: segment force density (Resistive Force Theory [2]) $\mathbf{f}_{\mathsf{i}}(\mathsf{s}) = \eta_{\parallel}(\mathbf{v}_{\mathsf{i}}(\mathsf{s}) \cdot \mathbf{e}_{\mathsf{i},\parallel})\mathbf{e}_{\mathsf{i},\parallel} + \eta_{\perp}(\mathbf{v}_{\mathsf{i}}(\mathsf{s}) \cdot \mathbf{e}_{\mathsf{i},\perp})\mathbf{e}_{\mathsf{i},\perp}.$

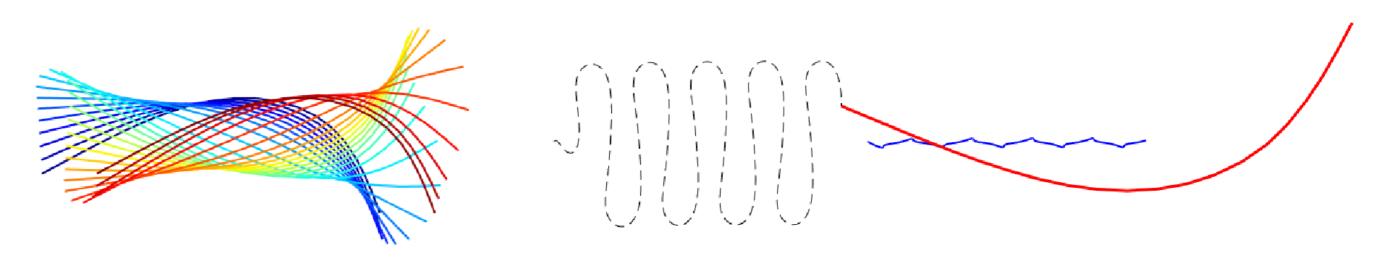
Visualization of the buckling phenomenon for three different rigidities and three different initial conditions.

Study made easier by the discrete approach, under investigation

Applications : Magnetic Swimmers

 \blacktriangleright Magnetised filament – magnetisations μ_i External magnetic field **H** creating a torque

 $\mathbf{T}_{i}^{m} = \mu_{i} (\mathbf{e}_{i,\parallel} \times \mathbf{H})$



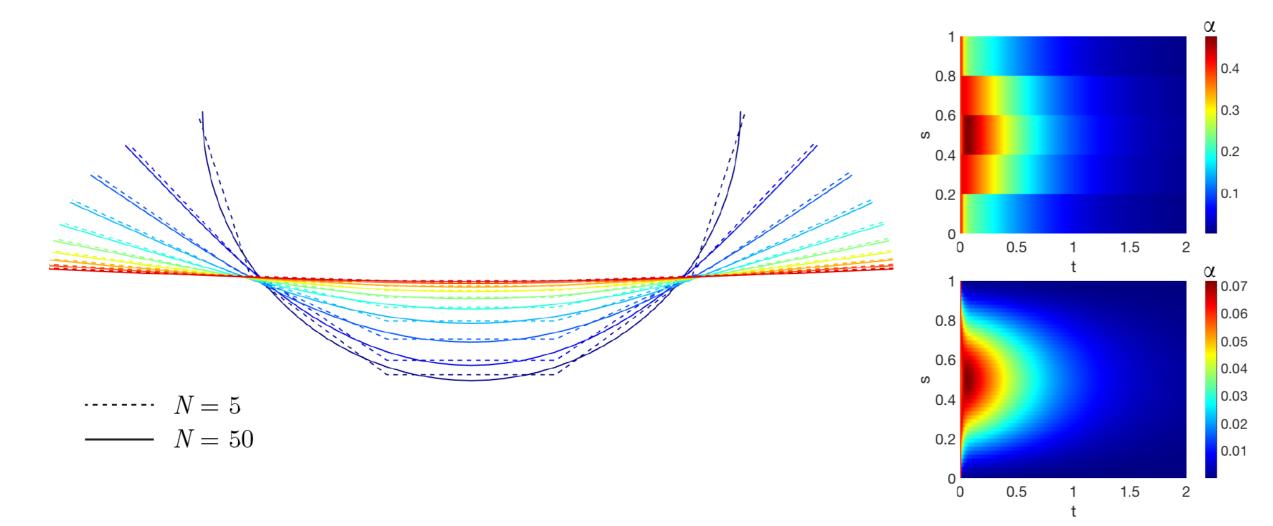
Elasticity: linear model

$\mathbf{M}_{i}^{el} = \kappa (\theta_{i+1} - \theta_{i}) \mathbf{e}_{z}$

- > 2nd Newton law gives the balance of forces and torques :
 - ▷ Continuous model → **PDE system**
 - \triangleright Discrete model \rightarrow integration on the segments \rightarrow **ODE system**

Numerical Comparison

Similar behavior on the "relaxation test"

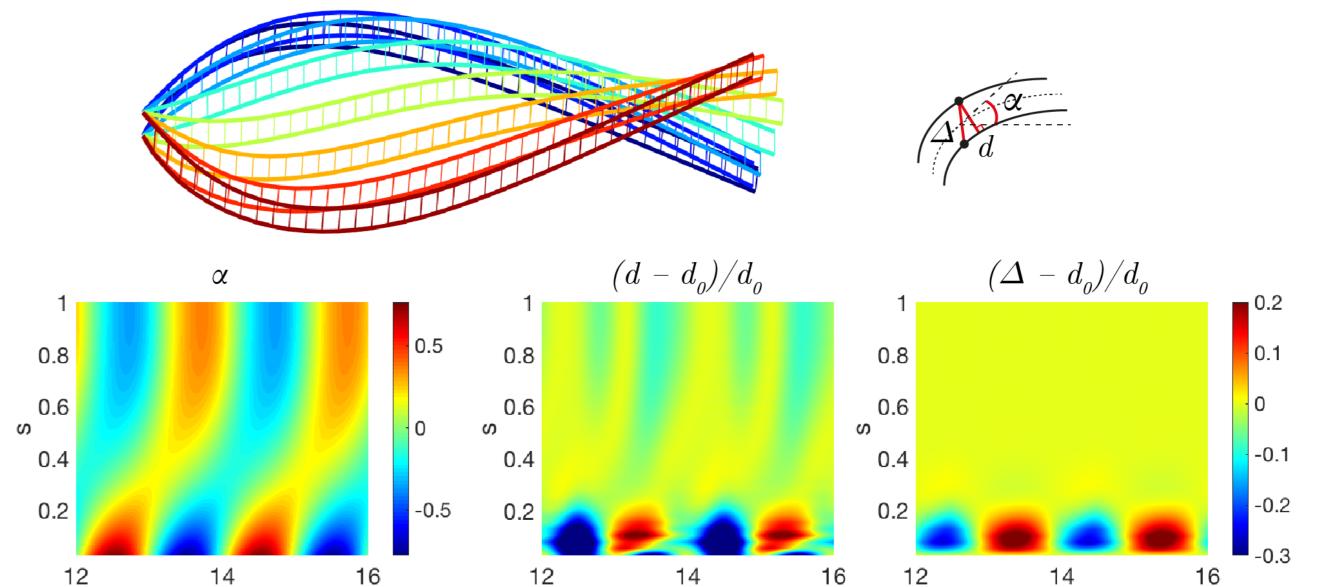


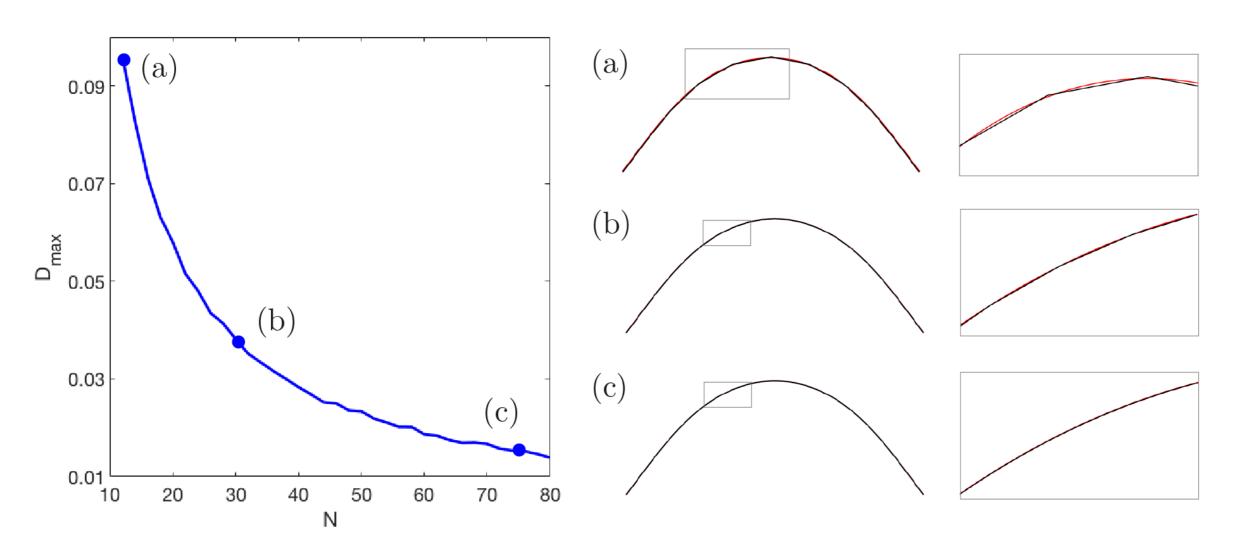
Fast convergence of the discrete model (error criterion $D_{max} = max |x_c - x_{cg}|$) s,t

- Artificial self-propulsion at micro-scale [3]
- Controllability and optimal control

Applications : Filament Bundle

Model a biological flagellum through two filaments linked together Highlight non-trivial coupling phenomena





Comparison between the classical and coarse-grained systems for increasing number of segments.

Discrete approach up to 100 times faster than PDE approach More robust for rigid filaments and sharp curvatures

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Coupling between two filaments obtained with the coarse-grained approach.

Applications include sperm cell motility studies

References and Contact Information

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