Automating Data Layout Conversion in a Large Cosmological Simulation Code

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Intro: The Gadget cosmological code

- *Large-scale structure* formation (galaxies and clusters)
- Publicly available [1], cosmological TreePM N-body + SPH code
- MPI/OpenMP-parallel; up to O(100k) Xeon cores (SuperMUC@LRZ)
- **Several teams** and **several versions** (>**200 kLoC each**)

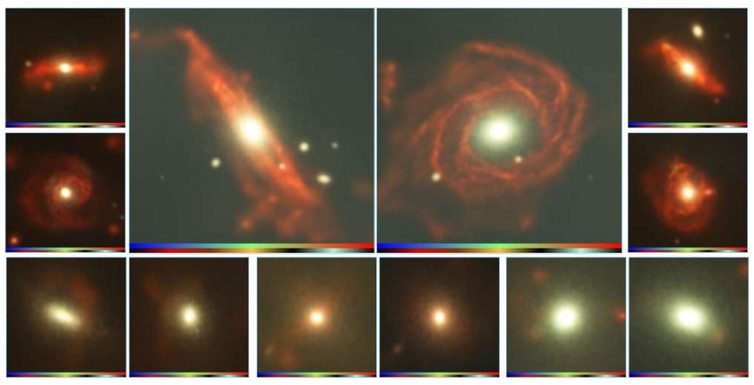

Figure 1: *Galaxies simulated with Gadget – courtesy Magneticum Project [2] / `http://magneticum.org`*

Optimization study of Gkernel

- Gkernel is:
  - isolated representative Gadget code kernel (*"halo finder"*)
  - stand-alone application, avoids simulation overhead
- Node-level optimization study [3] in the frame of the IPCC [4]
- Target computing systems:
  - **Knights Corner (KNC)**, **Ivy Bridge (IVB)**
  - Haswell (HSW), Broadwell (BDW), **Knights Landing (KNL)**
- Main changes:
  - **Data layout optimization**
  - Better threading parallelism

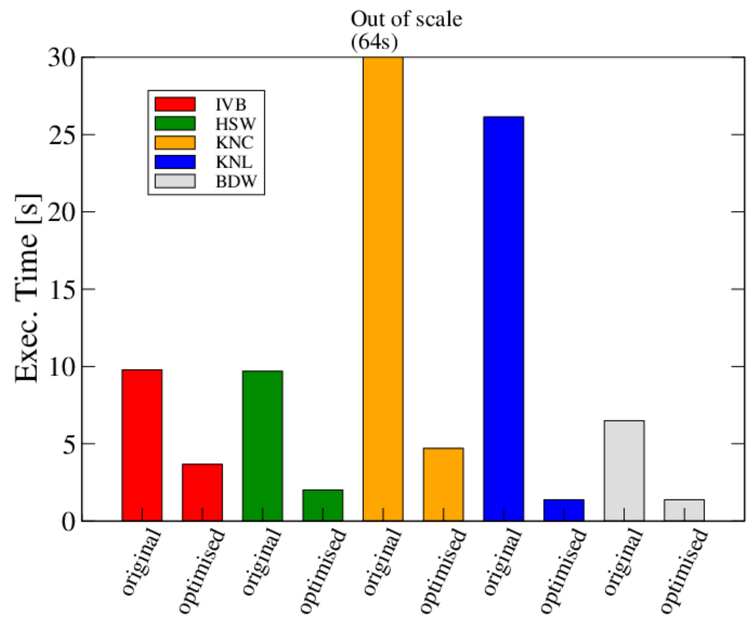

Figure 2: *Tests on one-socket Xeon systems; 240 threads (4 thr./core) for KNC; 128 threads (2 thr./core) for KNL. Performance improvement: up to 19x faster on KNL; 13.6x on KNC, ca. for 2-5x on Xeon.*

Data layout optimization

From *Array of Structures* to *Structure of Arrays* ($AoS \Rightarrow SoA$)

- Sample code changes in Fig. 3 and Fig. 4
- Leads to better memory access
- Eases compiler *auto-vectorization*
- SoA-specific performance benefit (over OpenMP improvement):
  - + 13% on IVB
  - + 48% on KNC

```
1 // Before:
2 // one structure per particle
3 struct particle {
4   double Mass, Hsml, ...;
5   ...
6 };
7
8 ...
9 // Array of Structures
10 struct particle *P;
```

```
1 // After:
2 // One array for each quantity
3 struct particle_soa_t {
4   double *Mass, *Hsml, ...;
5   ...
6 };
7
8 ...
9 // Structure of Arrays
10 struct particle_soa_t P_SoA;
```

Figure 3: *A "Structure of Arrays" `struct` definition introduction example. Only a dozen arrays have been introduced this way in Gkernel. Gadget would need over a hundred.*

```
1 // may not vectorize
2  ...P[i].Mass + P[i]...
```

```
1 // vectorizes better
2  ...P_SoA.Mass[i] + P_SoA...
```

Figure 4: *AoS to SoA transition sample. Impacts a few hundreds statements in Gkernel. Would impact many thousands in full Gadget. Notice that `i` could be any expression.*

Perspective for Gadget

✓ Obtained and validated *performance guidelines* for Gadget

- Limitations of [3] study:
  - single kernel only, no MPI
  - relying on $AoS \Rightarrow SoA \Rightarrow AoS$ at each kernel call
- Left open questions:
  - what to do with members like `Pos[3]` or `DV[3][3]` ?
  - ...and *anonymous unions* ?
  - ...and other kernels/quantities?
- **How** to *backport* ≫200 kLoC to Gadget ?

Discussion: Possible AoS ⇒ SoA breakdown

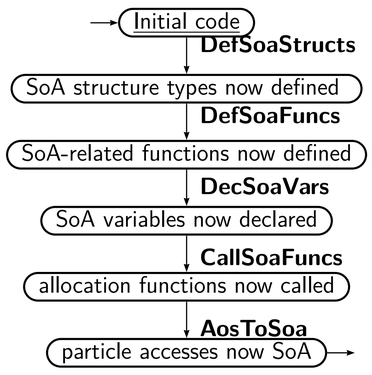

Figure 5: *Transformation steps, ordered so that their introduction does not break code. The Gkernel study has performed this on a subset of Gadget ([3]).*

Solution: Semantic patching

Coccinelle [5]: *"...a program matching and transformation engine ... for specifying desired matches and transformations in C code"*

- specification language inspired from UNIX `patch` (SmPL)
- SmPL can express steps in Fig. 5, enables Fig. 7 work style
- originally for *collateral evolutions* in the Linux kernel
- arbitrary C language transformations possible, model checking

```
1 @@
2 identifier id,I;
3 type T;
4 @@
5 struct id { ...
6 - T  I;
7 + T *I;
8   ...
9 };
```

Figure 8: *Sample semantic patch for step **DefSoaStructs**, cf. Fig. 3. Lines 2-3 specify semantic elements of the C language. Lines 5 and 9 specify matching context, line 6 what to add, line 7 what to remove.*

```
1 @@
2 expression E;
3 identifier AoS;
4 identifier J;
5 fresh identifier SoA=AoS##"_SoA";
6 @@
7 - AoS[E].J
8 + SoA.J[E]
9
```

Figure 9: *Semantic patch example for **AosToSoa**, cf. Fig. 4. This patch requires no context apart from the elements to be replaced. Notice also introduction of a new identifier at line 5, used at line 8.*

- **DefSoaStructs**: define `struct` type with arrays instead of scalars
  - each member might depend on `#ifdef...`
- **DefSoaFuncs**: *glue functions* for SoA
  - like *-allocate, -free, -convert*, etc.
  - repetitive, time consuming

```
1 void aos_alloc(void)
2 {
3     P = (struct particle*) calloc(
        All.MaxPart,struct particle)
        ;
4     // all particle data allocated
5 }
```

```
1 void soa_alloc(void)
2 {
3     P_SoA.Hsml = (double*) calloc(
        All.MaxPart,double);
4     P_SoA.Mass = (double*) calloc(
        All.MaxPart,double);
5     ...
6 }
```

Figure 6: ***DefSoaFuncs**. Transition to SoA in Gadget would require one allocation per quantity. Manual introduction of this and further glue functions (e.g. AoS ⇔ SoA copy functions) is error-prone and repetitive. Manual SoA accesses introduction (Fig. 4) can be worse.*

- **DecSoaVars**: declare SoA structure variables
- **CallSoaFuncs**: call *glue functions*
- **AosToSoa**: replace relevant AoS accesses with SoA accesses
  - thousands of lines impacted (error prone and repetitive)
  - *regular expressions* help, but still error-prone and sloppy

A more desirable approach

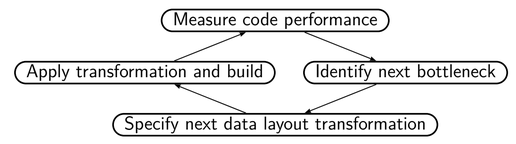

Figure 7: *Tool-assisted automatic data layout transformation would greatly accelerate cycles of development and empirical performance optimization.*

⚒ **Fine-grained AoS ⇒ SoA transition mechanism needed!**

- transitory patch: generating AoS ⇔ SoA converter functions
- exclusion/inclusion of structure members based on
  - * usage / occurrence in files
  - * specific type
  - * identifier whitelist

```
1 @str_flds@
2 identifier id,I;
3 type T;
4 @@
5 struct id{ ...
6  T *I;
7  ...
8 };
9
10 @def_alloc_sig@
11 identifier str_flds.id;
12 @@
13 struct id { ... };
14 +void alloc(struct id*p,int n)
15 +{}
16 @def_alloc_body@
17 type       str_flds.T;
18 identifier str_flds.I, str_flds.
     id;
19 @@
20 void alloc(struct id*p, int n){
21 ++p->I = calloc(n,sizeof(T));
22 }
23
24 @call_alloc@
25 identifier V, str_flds.id;
26 @@
27 struct id V;
28 + alloc(&V, 5);
```

Figure 10: *Semantic patch composed by four rules. This is similar to how **DefSoaFuncs** and **CallSoaFuncs** rules might look like. The first rule (line 1) matches a structure, the second (line 10) introduces an empty function, the third (line 16) populates it, the fourth (line 24) calls it. Notice inheritance of elements across rules, e.g. on line 11.*

Coccinelle advantages

- over other transformation engines (e.g. DMS, Rose Compiler):
  - ✓ straight-forward transformation language SmPL
  - ✓ fully *free software*-licensed (it serves the Linux kernel)
- over certain syntax-preserving C++ techniques (e.g. Intel SDLT)
  - ✓ code clarity (no operators and temporary objects involved)
  - ✓ preserves usability of -O0

Results summary

- ✓ all *scalar* particle variables now SoA
- ☕ enables low effort extension to:
  - ✓ ▶ replay on several communities' Gadget forks
  - ✓ ☯ arbitrary mixes of AoS/SoA
- ✓ patch: $\approx 10K$ `+/- diff` lines (with context: $\approx 20K$)
- ☺ *exploring Coccinelle usage for HPC*

Possible future work

- new performance studies possible
- rules for OpenMP optimizations backport [3]
- MPI-specific glue code

References

[1] V. Springel, "The cosmological simulation code GADGET-2", *MNRAS*, vol. 364, pp. 1105–1134, 2005.

[2] "Magneticum Home page (large-scale project based on Gadget)". `http://www.magneticum.org`.

[3] F. Baruffa, L. Iapichino, N. J. Hammer, and V. Karakasis, "Performance optimisation of smoothed particle hydrodynamics algorithms for multi/many-core architectures", in *2017 International Conference on High Performance Computing Simulation (HPCS)*, pp. 381–388, 2017.

[4] "Intel Parallel Computing Center: LRZ webpage". `https://www.lrz.de/services/compute/labs/astrolab/ipcc`.

[5] J. Lawall and G. Muller, "Coccinelle: 10 years of automated evolution in the Linux kernel", in *2018 USENIX Annual Technical Conference, USENIX ATC*, pp. 601–614, 2018.