

FROM RESEARCH TO INDUSTRY



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Fostering Metamodels and Grammars Within a Dedicated Environment for HPC **The NabLab Environment (tool)**

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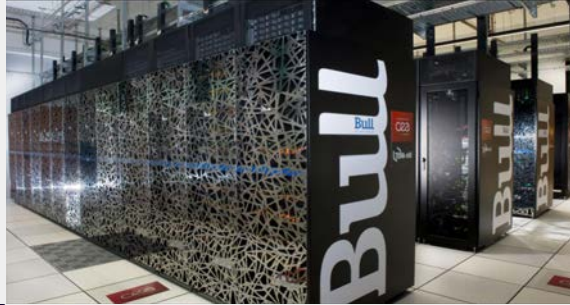
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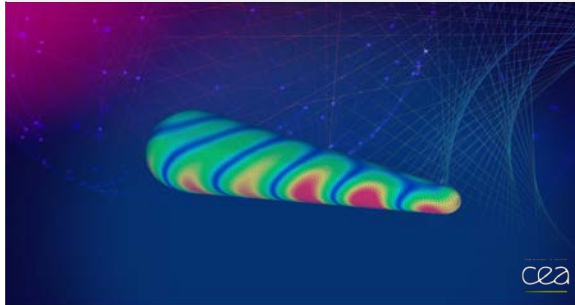


CEA is the French Alternative Energies and Atomic Energy Commission

CEA is a major player in High Performance Computing (HPC) through the **Simulation Programme**. CEA simulates hyperbolic systems and gas dynamics for transport and diffusion equations



Simulation covers **wide physics phenomena**. It takes more than 10 years for a simulator to go into production



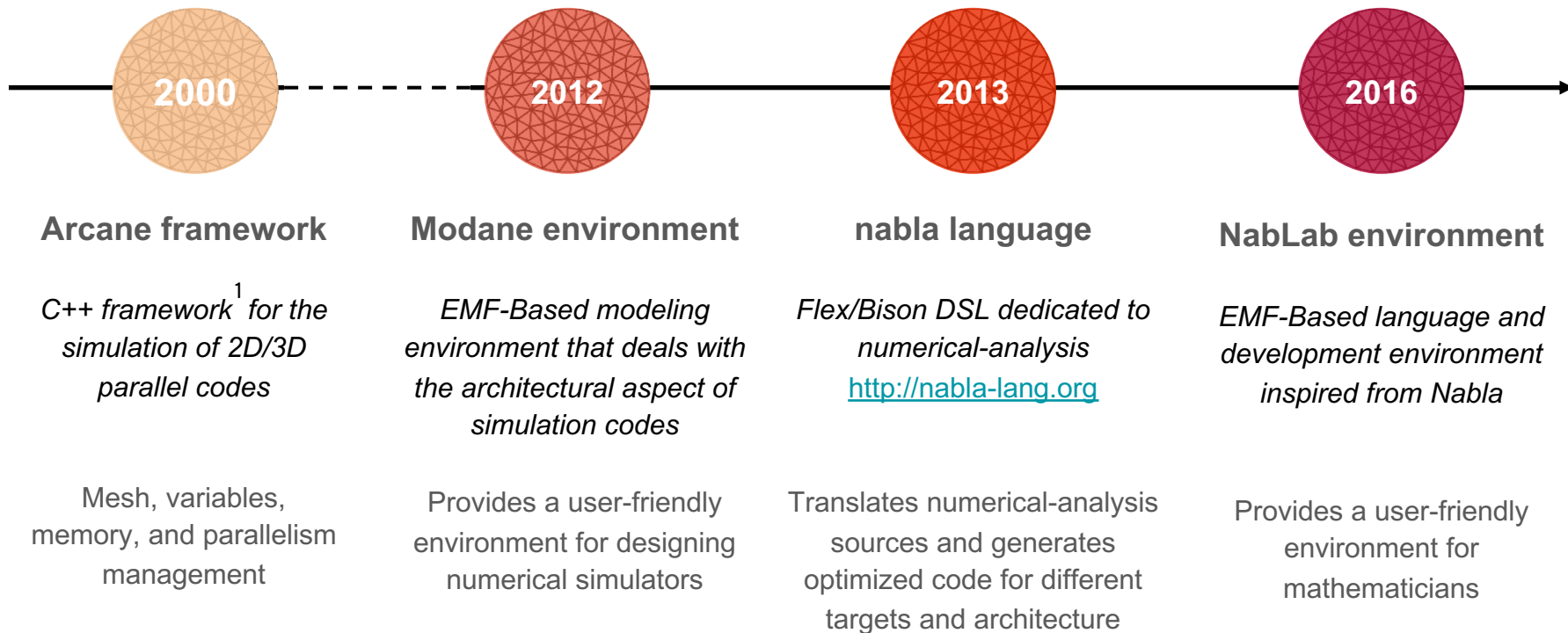
CEA co-designs with Atos future generations of Bull calculators and deploys **new architectures** and models for programming every 5 years



We need to abstract business knowledge from technical knowledge.

It is vital for our applications given the rapid evolution of hardware

Towards Higher Abstraction



¹ Co-developed with IFPEN

Why DSLs are good candidates?



DSL is a good candidate for capturing and perpetuating **domain knowledge**



DSL is a good candidate for improving **software quality and performance**



DSL is a good candidate for supporting **brainstorming**



DSL is a good candidate for **communication and training**

...and all along the lifecycle of simulators thanks to code generation

┌ We have defined a **DSL dedicated to HPC** and built a custom design environment based on this DSL for our end-users └

01

Context

Context - Towards greater abstraction - Why is DSL a good candidate ?

02

Description of developments

What is ∇ ? - What is NabLab ? - NabLab Compilation Chain - Demo

03

Conclusion & Perspectives

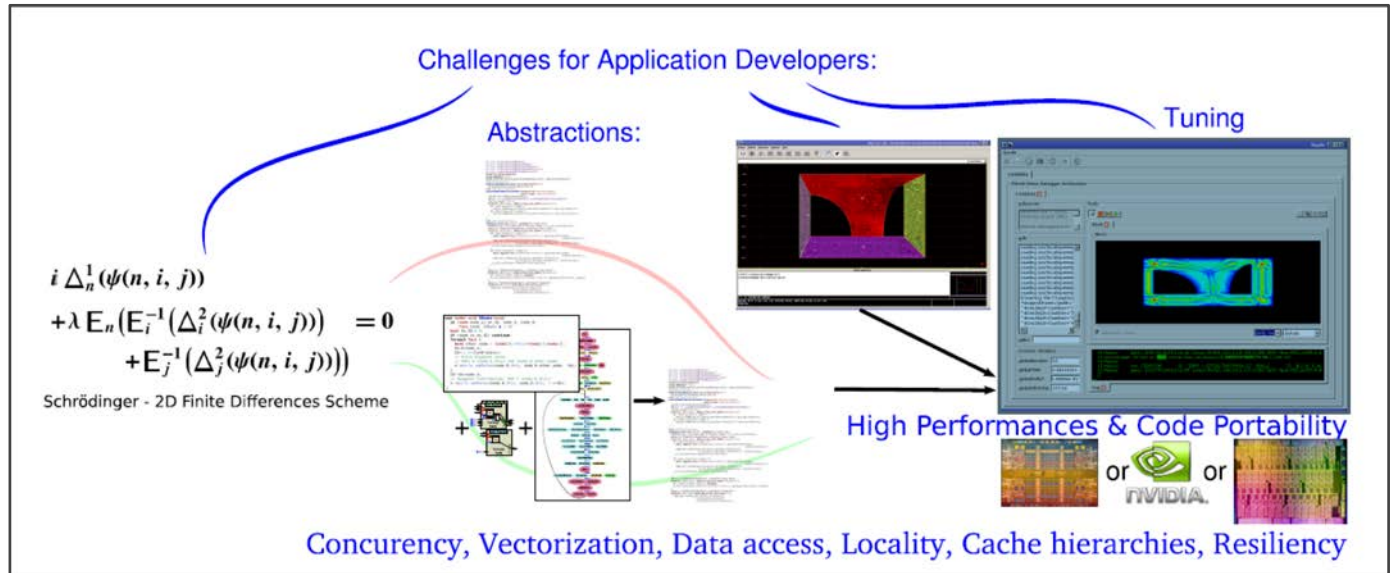
Grammar based DSL vs Metamodel based DSL - Towards a new Generation Strategy
- Perspectives

What is ∇?

Numerical Analysis Specific Language - <http://nabla-lang.org>

nabla is an open source Domain Specific Language (DSL) for numerical analysis algorithms.

The nabla compiler can generate optimized source code for various hardware and software architectures



```

options{
  R option_δt_fixed   = -1e-7;
  R option_δt_initial = 1e-7;
  R option_δt_courant = 1e+20;
  R option_δt_hydro   = 1e+20;
};

nodes{
  R3 ∂x,∂∂x; // Velocity, acceleration
  R3 nForce; // Force
  R nMass; // Mass
};

cells{
  R p,e,q; // pressure, energy, viscosity
  R v,calc_volume,vdov; // volumes
  R delv,volo; // rel. & ref. volumes
  R arealg; // characteristic length
  R3 ε; // terms of deviatoric strain
  R ql,qq; // artificial viscosity terms
  R3 cForce[nodes];
};

global{
  R δt_courant; // Courant time constraint
  R δt_hydro; // Hydro time constraint
};

```

Data-parallelism is implicitly expressed via jobs items

```

V cells hydroConstraintForElems @ 12.2{
  R arg_max_hydro=δt_cell_hydro = +∞;
  R δdv = fabs(vdov[m]);
  R δdvov = option_dvovmax/δdve;
  R δhdr = min(arg_max_hydro,δdvov);
  δt_cell_hydro=(vdov!=0.0)?δhdr;
}

V cells δt_courant <?= δt_cell_courant @ 12.11;
V cells δt_hydro <?= δt_cell_hydro @ 12.22;

```

Jobs parallelism is explicitly declared via Hierarchical Logical Time (HLT)

What is NabLab ?

- 1 **Model Explorer**
to browse the model and semantic concepts
- 2 **Outline**
to give a clear overview of the model
- 3 **Textual Editor**
to enjoy all the benefits of an advanced editor
- 4 **Latex View**
to get scientific notation for your equations
- 5 **Data-flow Graph**
to identify the order of execution of jobs

The screenshot displays the NabLab IDE interface with four numbered callouts:

- 1** Project Explorer: Shows the project structure for 'NablaGlace' and 'Glace2d'.
- 2** Outline: Shows a hierarchical view of the 'IniCenter' model component.
- 3** Textual Editor: Shows the source code for 'Glace2d.nabla' with mathematical expressions in LaTeX-like syntax.
- 4** Latex View: Shows the rendered LaTeX equation for 'Computeδtj'.
- 5** Data-flow Graph: Shows a complex dependency graph for the 'Glace2d' model.

```

*Glace2d.nabla
// *****
// * Init: X_ic(par le mailleur), p_ic, p_ic, V_ic & m
// *****
@IniCenter: ∀j∈cells(), center{j} = (1.0/4.0) *
Σ{r∈nodesOfCell(j)}(coord{r});
@IniIc: ∀j∈cells(), if (center{j}.x < option_x_interface) {
  p_ic{j}=option_p_ini_zg;
  p_ic{j}=option_p_ini_zg;
} else {
  p_ic{j}=option_p_ini_zd;
  p_ic{j}=option_p_ini_zd;
}

@ComputeCjrIc: ∀j∈cells(), ∀r∈nodesOfCell(j),
  C_ic{j,r} = 0.5 * perp(coord{r} - coord{←(r)});
@IniVc: ∀j∈cells(), V_ic{j} = 0.5 *
Σ{r∈nodesOfCell(j)}(dot(C_ic{j,r}, coord{r}));
IniM: ∀j∈cells(), m{j} = ρ_ic{j} * V_ic{j}; // m est constant

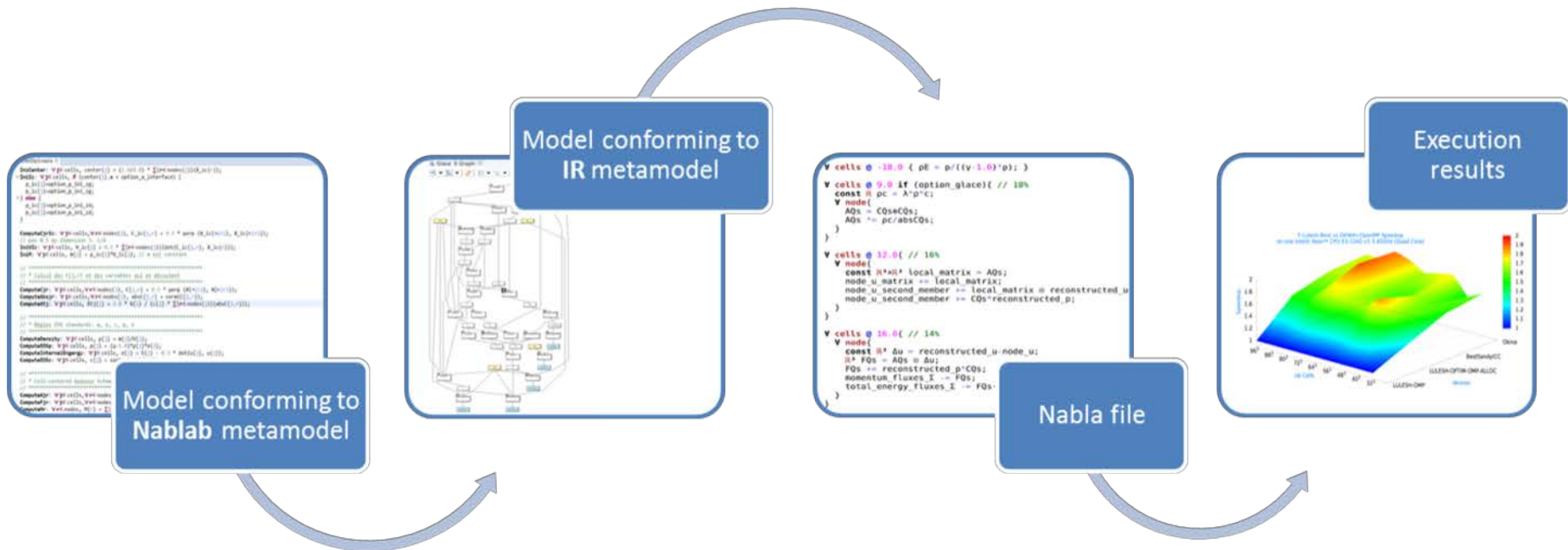
// *****
// * Calcul des C{j,r} et des variables qui en découlent
// *****
@ComputeCjr: ∀j∈cells(), ∀r∈nodesOfCell(j), C{j,r} = 0.5 *
  perp(X{←(r)} - X{r});
@ComputeLjr: ∀j∈cells(), ∀r∈nodesOfCell(j), l{j,r} = norm(C{j,r});
@Computeδtj: ∀j∈cells(), δtj{j} = 2.0 * V{j} /
  (c{j} * Σ{r∈nodesOfCell(j)}(l{j,r}));

// *****
// * Règles EOS standards: m, p, c, p, e
// *****
@ComputeDensity: ∀j∈cells(), ρ{j} = m{j} / V{j};
@ComputeEOSp: ∀j∈cells(), p{j} = (γ-1.0) * ρ{j} * e{j};
@ComputeInternalEnergy: ∀j∈cells(), e{j} = E{j} - 0.5 *
  
```

4

$$\text{Compute}\delta t_j : \forall j \in \text{cells}(), \delta t_j = \frac{2.0 \cdot V_j}{c_j \cdot \sum_{r \in \text{nodesOfCell}(j)} (l_{j,r})}$$

NabLab Compilation Chain



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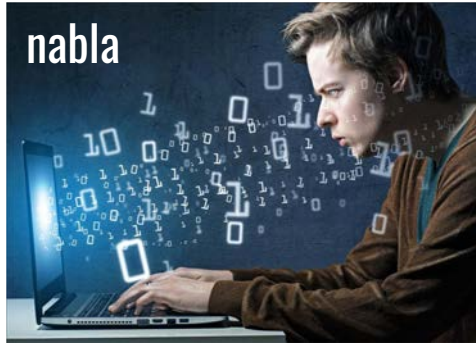
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Conclusion & Perspectives

Grammar based DSL vs Metamodel based DSL - Towards a new Generation Strategy - Perspectives

Grammar based DSL vs. Metamodel based DSL

2013



C++ language & time-honored technologies like Flex/Bison



No facilities for editing code (UTF8, @) or debugging



From mathematics
to optimization

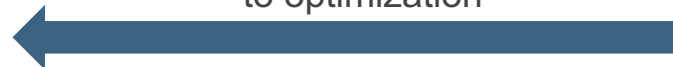
2016



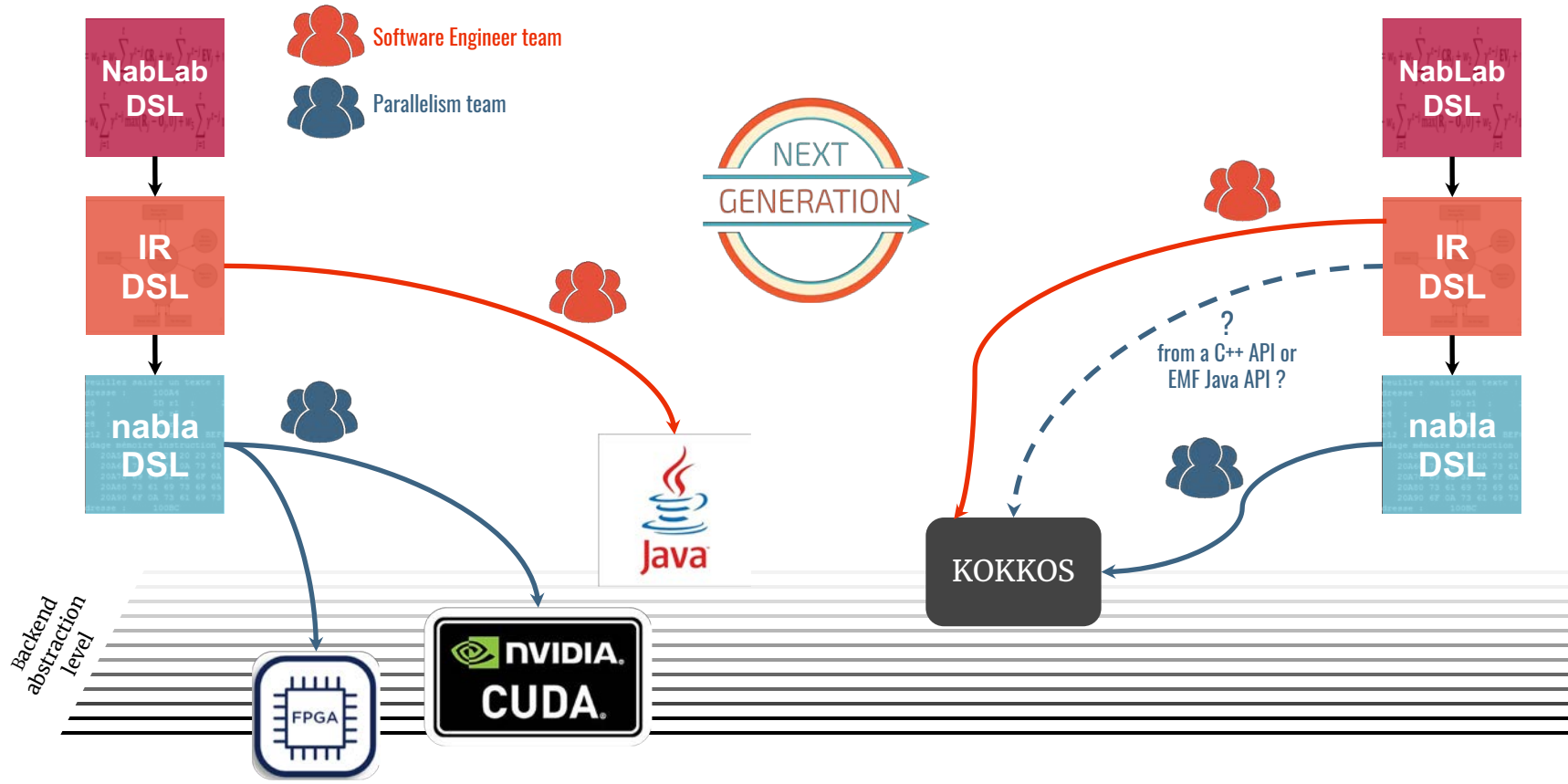
Far from optimization concerns

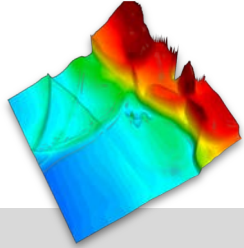


EMF-based language that offers user-friendly environment



Towards a New Strategy





Future work includes **debugging** and **visualization** of results (step-by-step execution, variable inspection, curves, 2D/3D mesh visualization)



We plan to study the use of the **LLVM** Compiler Infrastructure **as an Intermediate Representation**



The ultimate challenge would be to **coordinate NabLab with Modane**, another CEA DSL dedicated to the design, to cover both the architectural and behavioral aspects of the simulation codes




Open to collaboration with the scientific computing community



Take Away Messages

- Abstraction is key
 - For advanced developments
 - For optimized computations
- Complementarity of domain-specific frameworks
 - Domain experts (business domain)
 - Dedicated execution environments (technical domain)
- Fruitful separation of concerns (software eng., optimization eng., and mathematicians and physicists)
- Important tradeoffs regarding the language workbenches, acceptable learning curve in general



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