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A new location-scale model for conditional heavy-tailed distributions

Aboubacrène Ag Ahmad¹, Aliou Diop¹, El Hadji Deme² & Stéphane Girard³

¹ UGB - Université Gaston Berger de Saint-Louis, Sénégal.

² LERSTAD - Laboratoire d'Etudes et de Recherches en Statistiques et Développement, UGB Saint-Louis, Sénégal.

³ Université Grenoble Alpes, Inria, CNRS, Grenoble INP, LJK, 38000 Grenoble, France.

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1. Abstract

We are interested in a location-scale model for heavy-tailed distributions where the covariate is deterministic. We first address the nonparametric estimation of the location and scale functions and derive an estimator of the conditional extreme-value index. Second, new estimators of the extreme conditional quantiles are introduced. The asymptotic properties of the estimators are established under mild assumptions.

2. Model

$$\mathbf{Y} = \mathbf{a}(\mathbf{x}) + \mathbf{b}(\mathbf{x})\mathbf{Z},$$

where $\mathbf{x} \in \mathbb{R}$ is a nonrandom covariate, $Y \in \mathbb{R}$ a random variable that depends on \mathbf{x} and Z an independent random variable of \mathbf{x} . The location function $a(\cdot)$ and the scale function $b(\cdot) > 0$ are unknown. We assume that the survival function of Z denoted by \bar{F}_Z belongs to the class of regular varying functions at infinity

$$\bar{F}_Z(z) = z^{-1/\gamma} \ell(z), \quad \gamma > 0,$$

where ℓ is a slowly-varying function at infinity and γ is the conditional extreme-value index.

4. Asymptotic results

Assume n large enough so that $h = h_n < 1/2$, the following results are obtained under some regularity conditions on the probability density function of Z (f_Z) and \bar{F}_Z and a Lipschitzian condition on the kernel K .

Proposition 1 : Estimation of classical conditional quantiles

Let $(t_n)_n$ be a sequence in $[h_n, 1 - h_n]$ and $(\alpha_j)_{j=1, \dots, J}$ a strictly decreasing sequence in $(0, 1)$. If $nh_n \rightarrow +\infty$ and $nh_n^3 \rightarrow 0$ as $n \rightarrow +\infty$, then

$$\left\{ \frac{\sqrt{nh_n}}{\mathbf{b}(t_n)} \left[\hat{\mathbf{q}}_{n,Y}(\alpha_j | t_n) - \mathbf{q}_Y(\alpha_j | t_n) \right] \right\}_{j=1, \dots, J} \xrightarrow{d} \mathcal{N}(\mathbf{0}_{\mathbb{R}^J}, \int_{-1}^1 \mathbf{K}^2(\mathbf{u}) \mathbf{d}\mathbf{u} \mathbf{A}),$$

where $A_{k,l} = \frac{\alpha_{k \vee l} (1 - \alpha_{k \wedge l})}{f_Z(q_Z(\alpha_k)) f_Z(q_Z(\alpha_l))}$, for all $(k, l) \in \{1, \dots, J\}^2$ and \vee (resp. \wedge) denotes the maximum (resp. the minimum).

Proposition 2 : Estimation of location and scale functions

If $nh_n \rightarrow +\infty$ and $nh_n^3 \rightarrow 0$ as $n \rightarrow +\infty$, then for all sequence $(t_n)_n$ in $[h_n, 1 - h_n]$,

$$\frac{\sqrt{nh_n}}{\mathbf{b}(t_n)} \begin{pmatrix} \hat{a}_n(t_n) - a(t_n) \\ \hat{b}_n(t_n) - b(t_n) \end{pmatrix} \xrightarrow{d} \mathcal{N}(\mathbf{0}_{\mathbb{R}^2}, \int_{-1}^1 \mathbf{K}^2(\mathbf{u}) \mathbf{d}\mathbf{u} \mathbf{B}),$$

where B is a given symmetric matrix.

Proposition 3 : Estimation of extreme conditional quantiles

Let $(t_n)_n$ be a sequence in $[h_n, 1 - h_n]$, $(\tau_j)_{j=1, \dots, J}$ a positive and strictly decreasing sequence, $(\alpha_n)_n$ a sequence such that $\alpha_n \rightarrow 0$, $nh_n \alpha_n \rightarrow +\infty$ and $nh_n^3 \alpha_n \rightarrow 0$ as $n \rightarrow +\infty$. Then,

$$\left\{ \frac{\sqrt{nh_n \alpha_n}}{\mathbf{b}(t_n) \mathbf{q}_Z(\alpha_n)} \left[\hat{\mathbf{q}}_{n,Y}(\alpha_n \tau_j | t_n) - \mathbf{q}_Y(\alpha_n \tau_j | t_n) \right] \right\}_{j=1, \dots, J} \xrightarrow{d} \mathcal{N}(\mathbf{0}_{\mathbb{R}^J}, \int_{-1}^1 \mathbf{K}^2(\mathbf{u}) \mathbf{d}\mathbf{u} \mathbf{C}),$$

where $C_{k,l} = \frac{1}{(\tau_{k \wedge l})^{1+\gamma} (\tau_{k \vee l})^\gamma}$, for all $(k, l) \in \{1, \dots, J\}^2$.

6. References

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3. Estimators

Let $\{(x_1, Y_1), \dots, (x_n, Y_n)\}$ be a n -sample of observations such that $Y_i = a(x_i) + b(x_i)Z_i$, $i = 1, \dots, n$, where Z_i are independent and identically distributed. For simplicity, the design points are of the form $x_i = i/n$, $i = 1, \dots, n$ and $x_0 = 0$ by convention.

Notations :

- $\bar{F}_Y(y | x)$: the conditional survival function of Y given x . For α fixed in $(0, 1)$,
- $q_Z(\alpha)$: the α -th quantile of Z ;
- $q_Y(\alpha | x)$: the conditional α -th quantile of Y given x ,

$$q_Y(\alpha | x) = \inf\{y / \bar{F}_Y(y | x) \leq \alpha\}.$$

Kernel estimator of $\bar{F}_Y(y | x)$:

$$\hat{\bar{F}}_{n,Y}(y | x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{Y_i > y\}} \int_{x_{i-1}}^{x_i} K_h(x - t) dt, \quad (x, y) \in [0, 1] \times \mathbb{R},$$

where the bandwidth $h = h_n$ is a nonrandom sequence such that $h \rightarrow 0$ as $n \rightarrow \infty$, $\mathbb{1}(\cdot)$ is the indicator function and $K_h(\cdot) = K(\cdot/h)/h$, where K (kernel) is a probability density function on \mathbb{R} .

Kernel estimator of $q_Y(\alpha | x)$:

$$\hat{q}_{n,Y}(\alpha | x) \stackrel{\text{def}}{=} \hat{F}_{n,Y}^{\leftarrow}(\alpha | x) = \inf\{y / \hat{\bar{F}}_{n,Y}(y | x) \leq \alpha\}, \quad \alpha \in (0, 1),$$

where $\hat{F}_{n,Y}^{\leftarrow}(\cdot | x)$ is the generalized inverse of $\hat{\bar{F}}_{n,Y}(\cdot | x)$.

Estimators of $a(\cdot)$ and $b(\cdot)$:

Under this assumption : $\exists \rho_1, \rho_2, \rho_3 \in (0, 1)$, $\rho_1 > \rho_2 > \rho_3$ such that $q_Z(\rho_2) = 0$ and $q_Z(\rho_3) - q_Z(\rho_1) = 1$, we propose as :

- An estimator of $a(\cdot)$:

$$\hat{\mathbf{a}}_n(\mathbf{x}) = \hat{\mathbf{q}}_{n,Y}(\rho_2 | \mathbf{x}),$$

- An estimator of $b(\cdot)$:

$$\hat{\mathbf{b}}_n(\mathbf{x}) = \hat{\mathbf{q}}_{n,Y}(\rho_3 | \mathbf{x}) - \hat{\mathbf{q}}_{n,Y}(\rho_1 | \mathbf{x}).$$

Estimator of γ :

- Pseudo-observations \hat{Z}_i , associated with Z_i , $[nh] \leq i \leq n - [nh]$ defined by :

$$\hat{Z}_i = \frac{Y_i - \hat{a}_n(x_i)}{\hat{b}_n(x_i)}$$

- Number of pseudo-observations :

$$m = \#\{i / [nh] \leq i \leq n - [nh]\}$$

- Associated order-statistics : $\hat{Z}_{i,m}$, $i = 1, \dots, m$

- Hill-type estimator of γ :

$$\hat{\gamma}_n = \frac{1}{k} \sum_{i=1}^k \log \hat{Z}_{m-i+1,m} - \log \hat{Z}_{m-k,m},$$

where $k \in \{1, \dots, m\}$ is an intermediate sequence, i.e $k \rightarrow +\infty$, $\frac{k}{m} \rightarrow 0$.

5. Conclusion

The study of the problem in fixed design, which we have made, reveals interesting theoretical results. As a perspective, we are considering the conditional extreme-value index estimation and a validation of our results on simulations. We also plan to extend these results to the random framework.

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