

First Annual Partners' Meeting Presentation

Integrated Framework to Identify, Track and Communicate Sea-Ice Hazards

Arctic Domain Awareness Center (ADAC)
A DHS Center of Excellence



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June 29 & 30, 2015¹



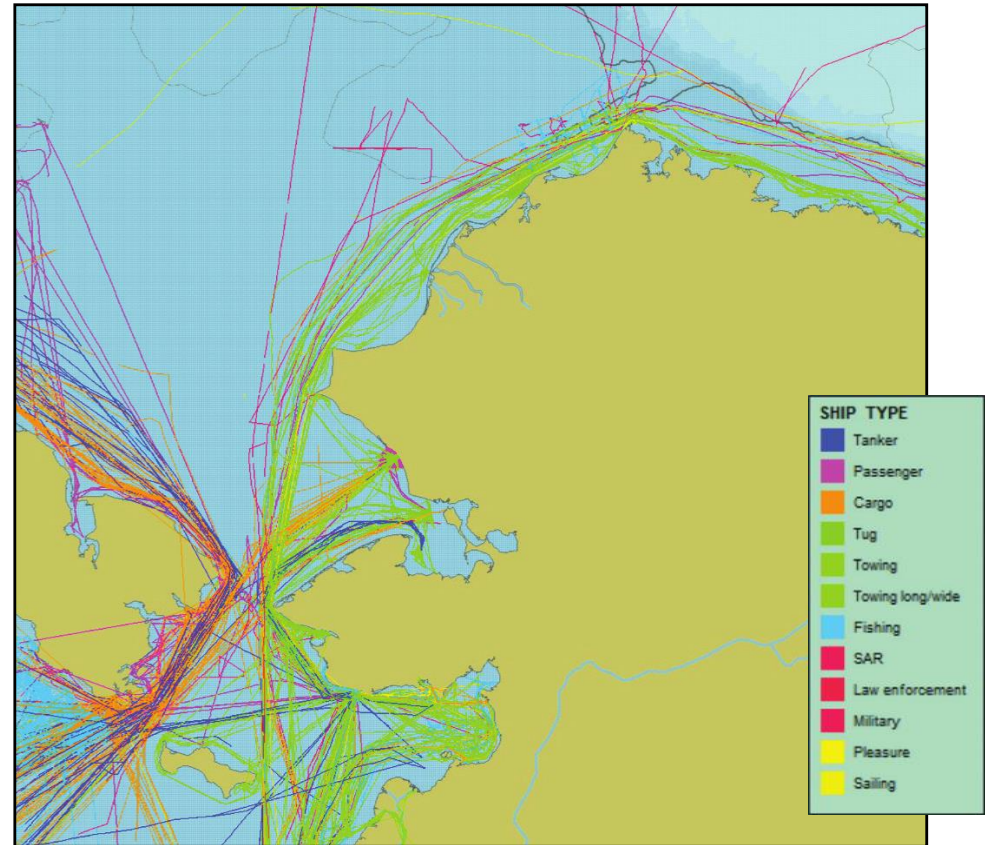
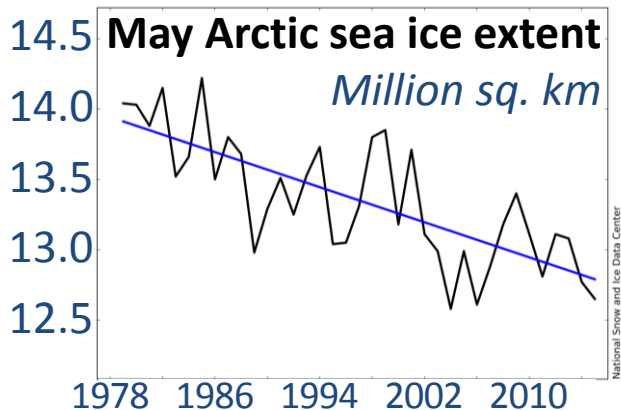
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Overview

- Increasing Arctic maritime activity
- Driven in part by decreasing sea ice extent



AIS traffic, Jun 1 – Nov 30, 2013. [from Brigham, 2014]



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Risk posed by sea-ice hazards growing despite declining sea ice

Urgent need for enhanced
sea-ice hazard awareness

- *Improved hazard detection*
- *Real time tracking*
- *Improved communication and data dissemination*



Barge NTCL II

Photo Stephan Hill Era Helicopters

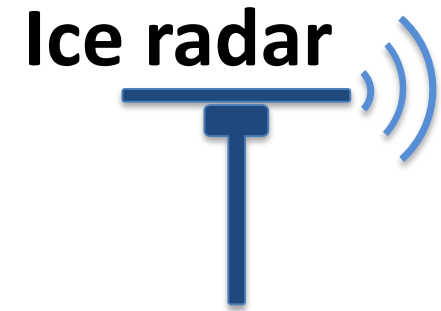


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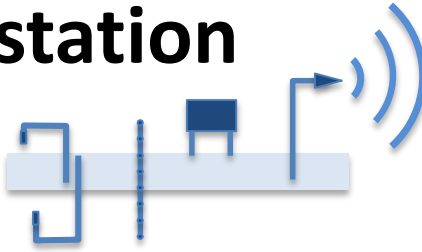
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Approach



Ice radar

**Mass balance
station**



GPS buoys



Real-time data

- *Ice detection*
- *Ice velocity*
- *Ice stability*

- *Ice thickness*
- *Ice temperature*
- *Sea level*

- *Ice motion*
- *Ice deformation*
- *Ice uplift*

**Satellite
data**



**Sea ice hazards
Information products**

- *Ice speed*
- *Ice pressure*
- *Ridge / crack
formation*
- *Ice breakout*

Stakeholders

Barrow test bed



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Stakeholders & Partners

USCG District 17

Cdr. Shawn Decker, Rob Hynes
James Robinson

USCG R & D Center

Rich Hansen, Bert Macesker
Jason Story, Scott Trip

NOAA Office of Response and Restoration

*Chief, Spatial Data
Branch/Assessment and
Restoration Div.*

Amy Merten

*Chair, Arctic Council Emergency
Preparedness & Prevention
Working Group*

Nat. Weather Service Anchorage Ice Desk

James Nelson *NOAA-NWS Regional Scientist*
Rebecca Legatt Heim *Ice Forecaster*

Alaska Dept. Environmental Conservation
John Engles

Eskimo Walrus Commission

Vera Kingeekuk Metcalf *Executive Director*
Eugene Brower *President*

Alaska Clean Seas

Tony Parkin *Chair, Research & Development*

Barrow Search and Rescue

No formal contact at this time

Milestones

- 1. Completion of vector product for ice velocity field in format and delivery mode that conforms with USCG and NOAA ERMA needs (March 2015).** Multi-parameter suite of products as vector and raster data available in May 2016. Baseline TRL-4, target TRL-6.
- 2. Capabilities to produce mean velocity and divergence/convergence fields compatible with CMR model architecture and coastal HF radar data. (February 2015).** Full time series from Barrow site processed by January 2016. Baseline TRL-4, target TRL-6.
3. White paper outlining North Slope/Barrow ADAC testbed, discussing relevant observing system resources, logistics support options, ADAC testbed elements and activities (December 2015). Baseline TRL-1, target TRL-2.
4. Identify and review suitable DGPS hardware for use in harsh Arctic sea-ice environment and compatibility with observing system infrastructure to detect small-scale deformation as threat precursor (April 2016). Baseline TRL-2, target TRL-5.



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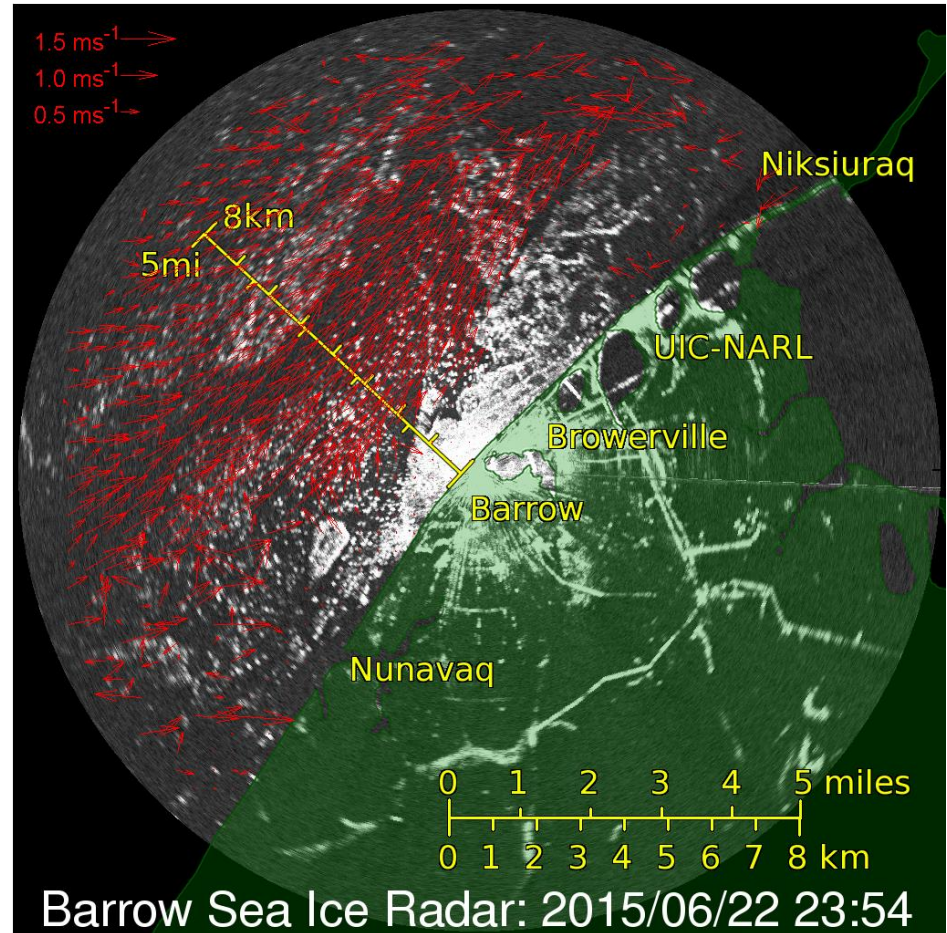
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Radar-derived ice velocities

Milestone #1: Completion of vector product for ice velocity field in format and delivery mode that conforms with USCG and NOAA ERMA needs (March 2015)

- *Gridded ice velocities now being calculated operationally from real time radar data*
- *Data available in KMZ format for integration into Arctic ERMA and GoogleEarth*
- *Awaiting feedback from USCG D17; Integrated feedback from Barrow Rescue Base*



Near-real data time at:

http://seice.alaska.edu/gi/observatories/barrow_radar/sea-ice-velocity



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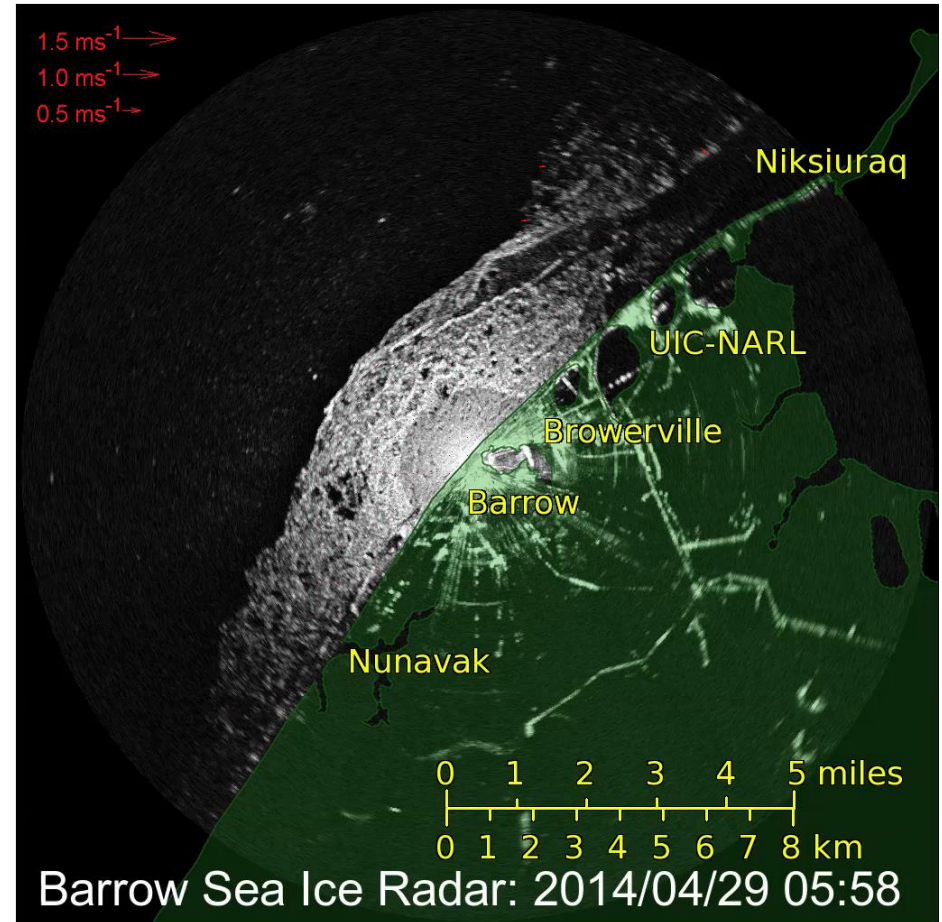
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Real world application

UAF ice radar data used by Barrow Search & Rescue

April 29, 2014:

- *Mid-season breakout of landfast ice casts several hunters adrift*
- *Weather conditions prevent launch of SAR helicopter*
- *Radar data used to help coordinate rescue effort using small boats*
- *All people and gear safely recovered!*





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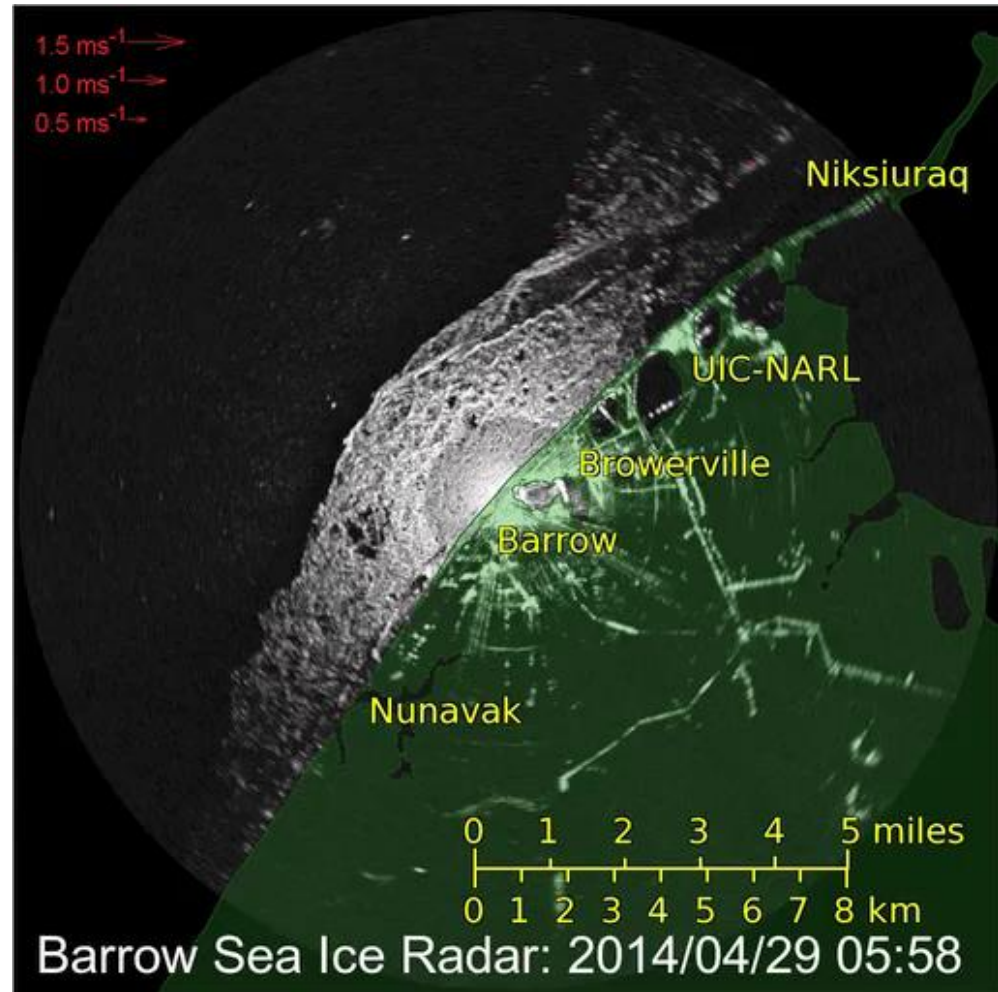
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Ice divergence/convergence

Milestone #2: Capabilities to produce mean velocity and divergence/convergence fields compatible with CMR model architecture and coastal HF radar data. (February 2015)

- *Algorithms developed to generate ice convergence / divergence fields*
- *Red indicates closing/ridging ice*
- *Blue indicates opening ice*
- *Once operational, data can be formatted to meet stakeholder needs*





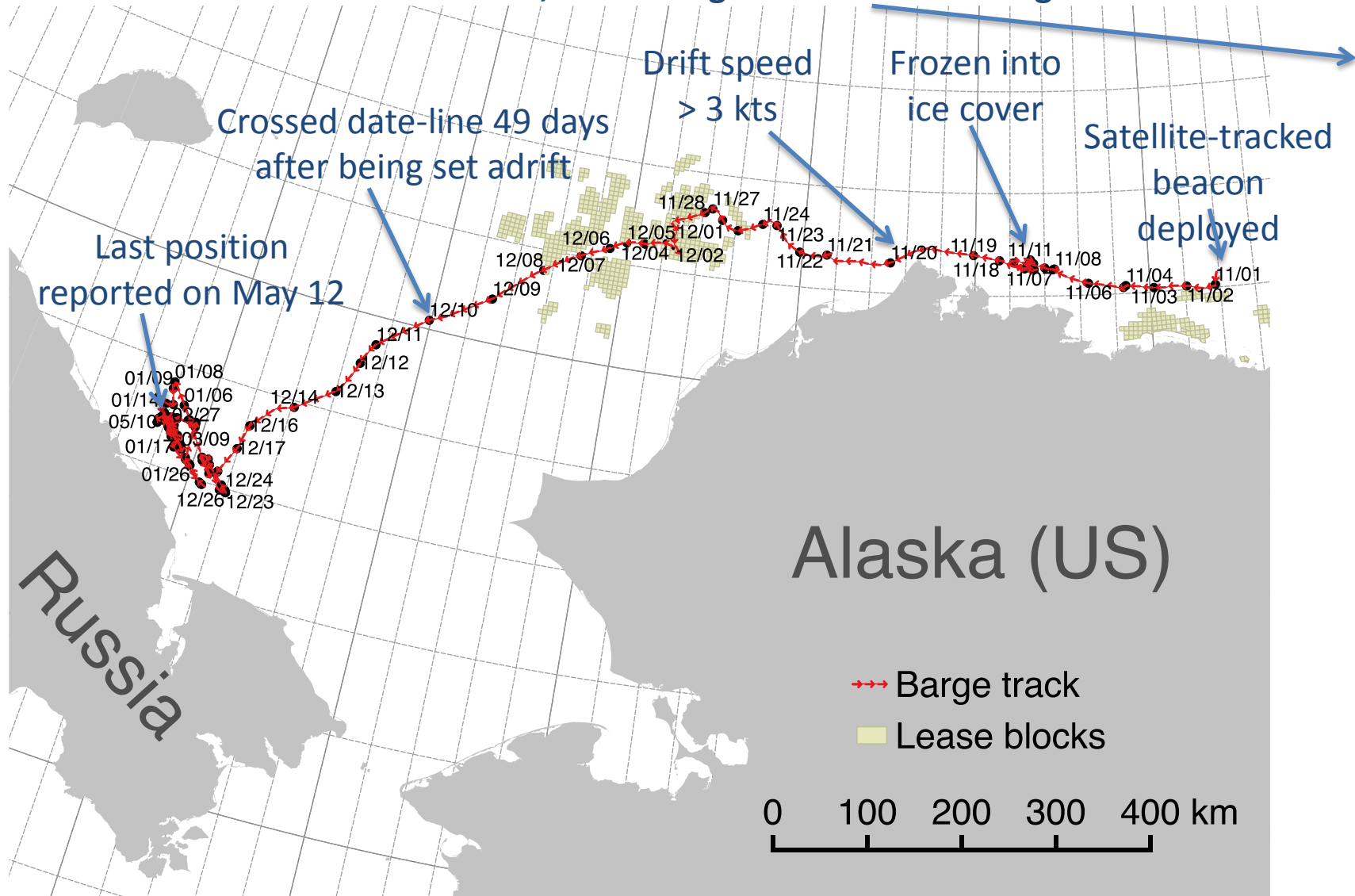
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Barge NTCL II

October 22, 2014: Barge breaks loose of tug in Canadian Arctic





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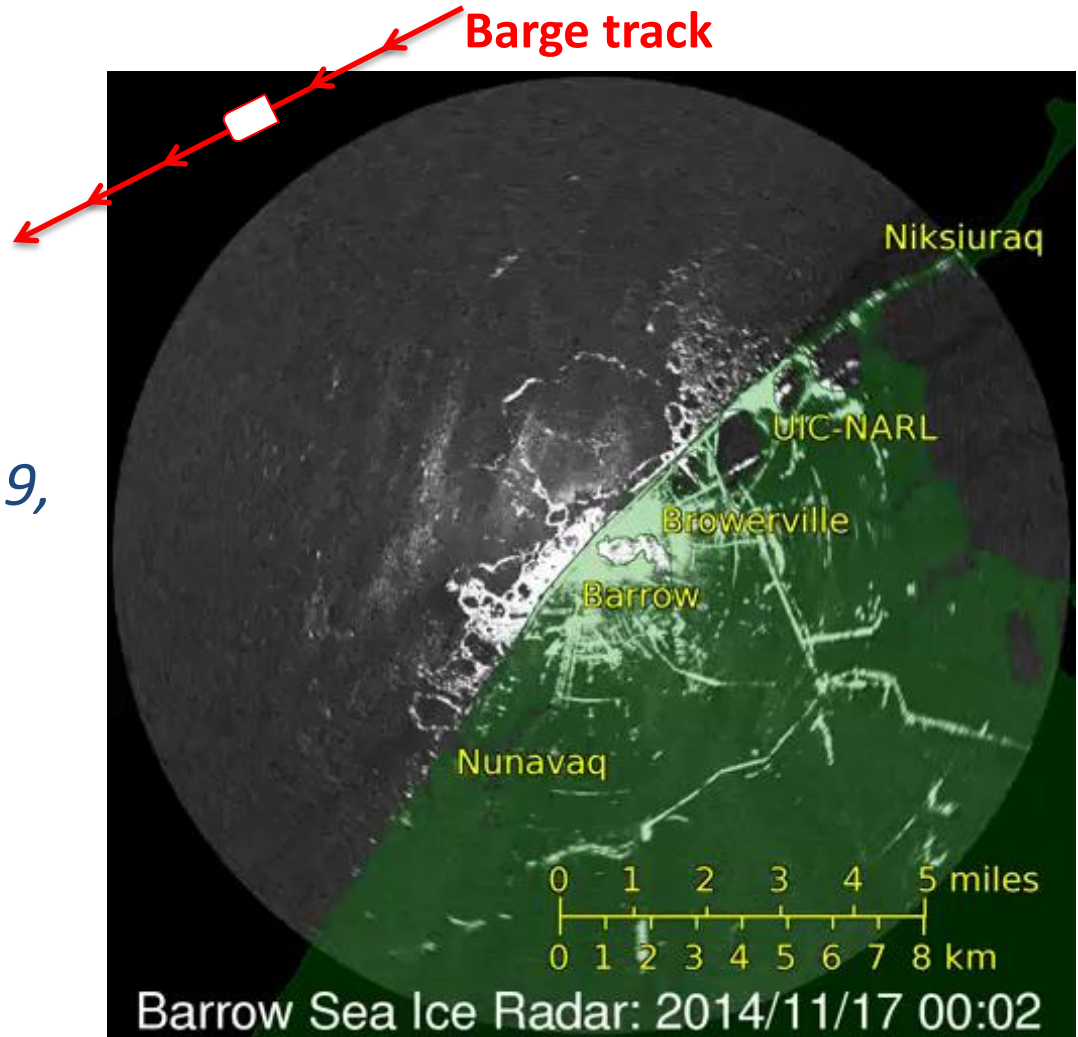
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Passing Pt. Barrow



- *Barge passed Point Barrow just before midnight on October 19, 2014*
- *Closest approach: 11.3 km offshore*
- *Ice motion highly complex*
- *No landfast ice*



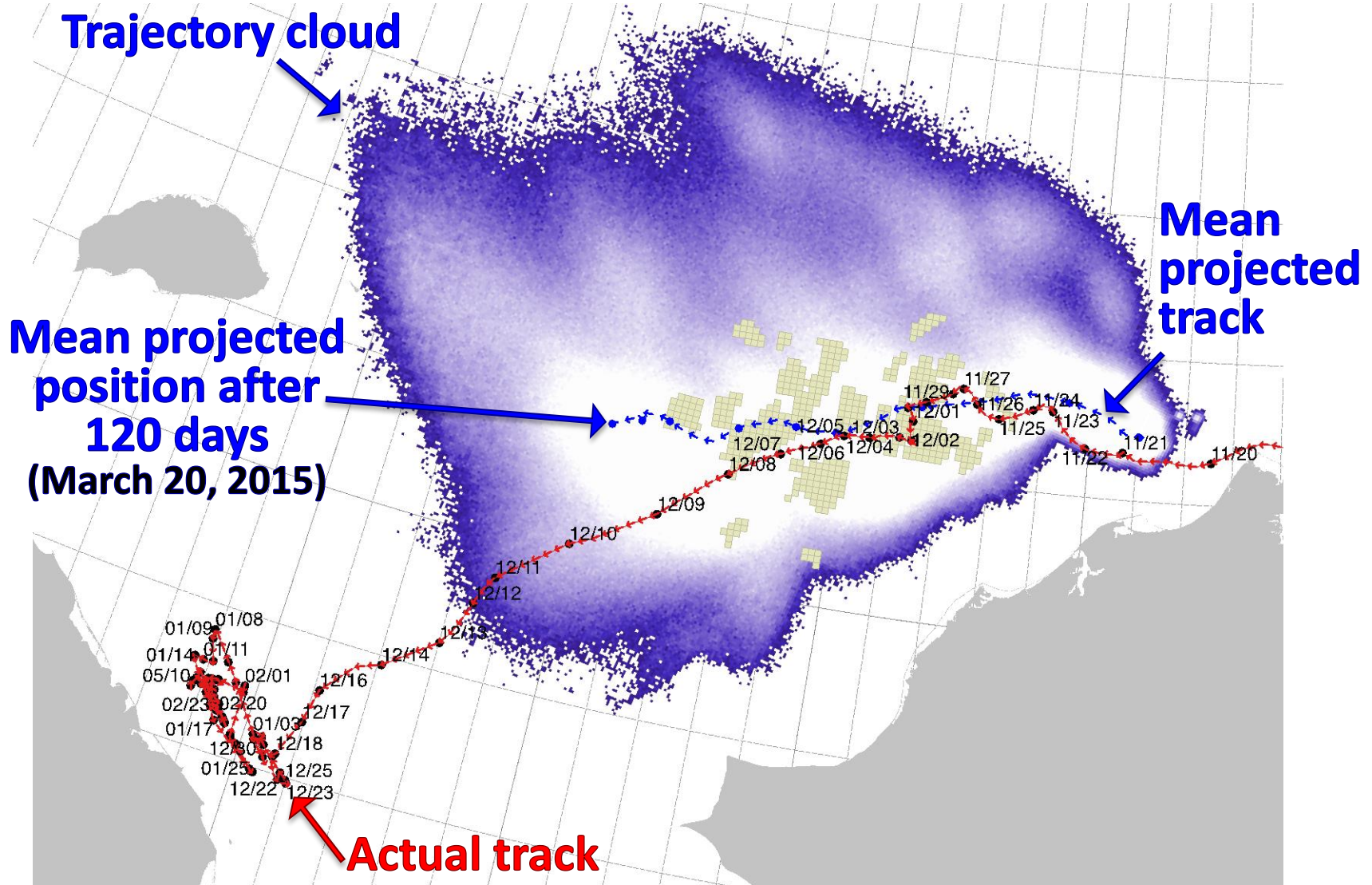


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Projected barge drift (on Nov 21, 2014)





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Gaps and Lessons Learned

Search and rescue operations in ice-infested waters can benefit from radar data

- Particularly during periods of poor visibility
- Ice velocity data most useful
- Simple, low-bandwidth products most suitable for local first responders

Calculating differential ice motion high precision data

- Spurious data needs to be removed with additional signal processing
- Unclear how this would apply on moving vessel

There are significant gaps in our ability to forecast long-term drift patterns

- With ongoing rapid change, historical data must be used with caution
- Ice drift near coast particularly difficult with current satellite data



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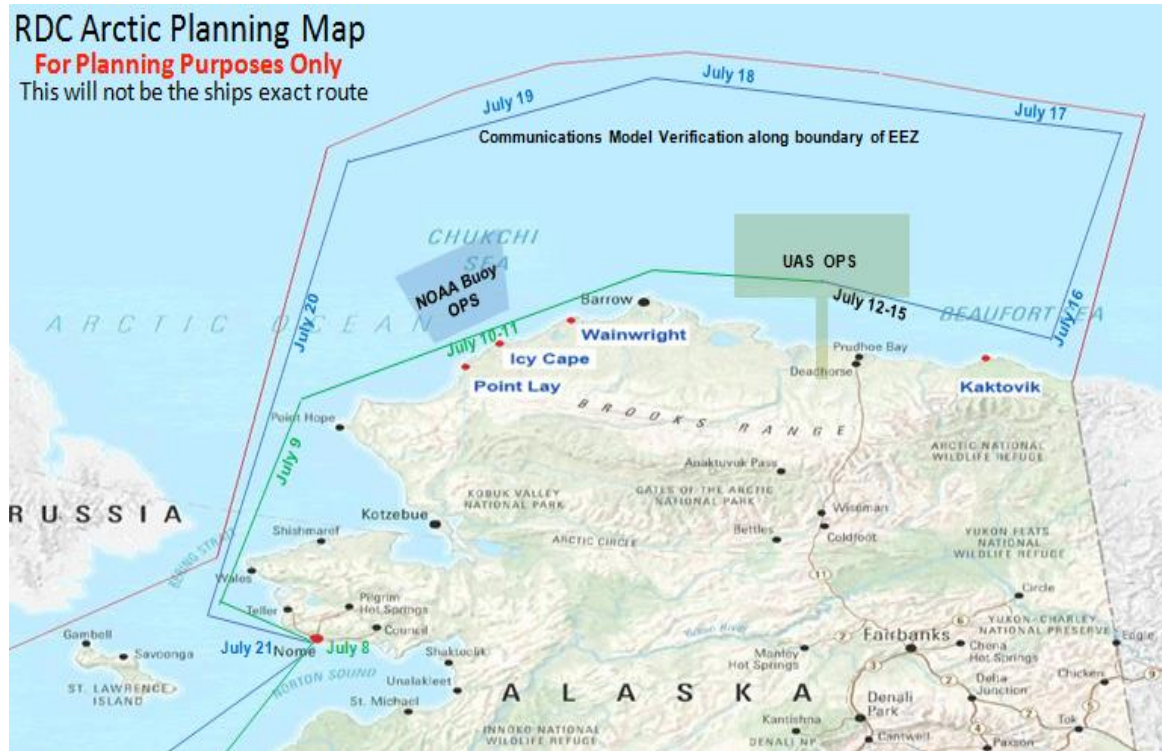
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Next steps

July 8-22: Arctic Shield 2015 Technology Evaluation

- Test ice radar performance while under way
- Deploy autonomous buoy to monitor ice hazards



Next steps

Barrow test bed (2015/16)

- *Deployment of high-precision DGPS beacons to monitor cracking, ridging and break-outs*
- *Development of integrated of ice motion / mass balance data product for storm/ocean model validation*
- *Engagement with stakeholders to assess value of data products for application in past and future scenarios*
- *Framework for collaborative sensor, model & response assessments*

