

Manuscript Number: CEJ-D-18-07067R1

Title: From semi-batch to continuous tubular reactors: a kinetics-free approach

Article Type: Research Paper

Keywords: semi-batch to continuous; process intensification; kinetics-free; tubular reactor

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Abstract: A methodology, which does not require any kinetic information, for the rigorous transformation of an isothermal, homogeneous semi-batch process into an equivalent continuous side-fed tubular reactor was developed. Once the semi-batch process parameters are known, the proposed methodology allows for easily defining all the process parameters of a side-fed tubular reactor that guarantees the same performances as the original semi-batch process, in terms of conversion and product characteristics. Two different case studies were selected to investigate the potential of the proposed approach: a copolymer synthesis and the production of a fine chemical, clearly showing the need of a rigorous transformation of the semi-batch process into the continuous one since productivity and product quality are strongly affected by the feeding policy.

Response to Reviewers: Detailed reply to the Reviewers' comments to the manuscript: From semi-batch to continuous tubular reactors: a kinetics-free approach by F. Florit, V. Busini, G. Storti, and R. Rota
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For the Reader's convenience, the original Reviewers' comments are reported followed by our detailed replies.

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I recommend authors to formulate an explicit conclusion on the optimal side feed policy. Generally, does this optimal policy exist?

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In section 3, the authors managed to apply their methodology for the transformation of operating conditions for a SBR to a continuous tubular reactor with discrete lateral injections. Figure 6 shows the effect of increasing the number of discrete side-injection points (N_d) on the relative difference of between outlet flowrates for chemical species. It compares the relative error when $N_d=3$ and $N_d=5$. It would be rather useful to see a bigger variation in N_d . Furthermore, it would be important to show how the relative error corresponding to the case of discrete lateral injections approaches to the one calculated with continuous injections, when N_d tends to infinity. A critical value for N_d at which the discrete and continuous injection mode behave similarly could be found.

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Milano, 06 August 2018

DIPARTIMENTO DI
CHIMICA, MATERIALI E
INGEGNERIA CHIMICA
"GIULIO NATTA"

Renato Rota

Dear Editor

Please find enclosed a revised version of the manuscript *From semi-batch to continuous tubular reactors: a kinetics-free approach* by Florit et al. (Manuscript ID: CEJ-D-18-07067), which we submit for publication in Chemical Engineering Journal.

I believe that we have satisfactorily accounted for all the comments of the Reviewers, as detailed in the attached list.

Best regards

Renato Rota
Professor

***List of Suggested Reviewers**

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Highlights

- A methodology for transforming a SBR process into a tubular reactor one is proposed
- The tubular reactor involves a properly defined continuous side feed
- The proposed methodology does not require any kinetic information
- The syntheses of a copolymer and a fine chemical are investigated as a case study

From semi-batch to continuous tubular reactors: a kinetics-free approach

Federico Florit^a, Valentina Busini^a, Giuseppe Storti^b, Renato Rota^{a,*}

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^b*ETH Zürich, Department of Chemistry and Applied Biosciences, Vladimir-Prelog-Weg 1-5/10, HCI F 125, 8093 Zürich, Switzerland*

Abstract

A methodology, which does not require any kinetic information, for the rigorous transformation of an isothermal, homogeneous semi-batch process into an equivalent continuous side-fed tubular reactor was developed. Once the semi-batch process parameters are known, the proposed methodology allows for easily defining all the process parameters of a side-fed tubular reactor that guarantees the same performances as the original semi-batch process, in terms of conversion and product characteristics.

Two different case studies were selected to investigate the potential of the proposed approach: a copolymer synthesis and the production of a fine chemical, clearly showing the need of a rigorous transformation of the semi-batch process into the continuous one since productivity and product quality are strongly affected by the feeding policy.

Keywords: semi-batch to continuous, process intensification, kinetics-free, tubular reactor

1. Introduction

Fine chemicals and specialties are generally produced via discontinuous or semi-continuous processes. This is mainly due either to discontinuous market needs (seasonal campaigns), which require a high degree of flexibility in the synthesis, or to complex and dangerous reaction processes, which are carried out in semi-batch reactors, SBRs, for safety reason [1, 2].

An effective way to reduce costs and enhance reproducibility of such processes is to transform discontinuous ones into their continuous counterpart. This way reactor volumes are usually reduced, the intrinsic process safety is increased thanks to the lower hold-up, and investment costs are also decreased [3]. Moreover, overall process times can be reduced and more constant quality is achieved, with a general decrease in

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operative costs [4]. This is the framework of the so called process intensification. Transition from discontinuous to continuous processes is also motivated by the increasing demand of specialty products. Higher production volumes would require more complex and expensive discontinuous equipment, making engineers more prone to consider continuous systems.

Straightforward choices for continuous reactors are mixed vessels (approximating the behaviour of Continuous Stirred Tank Reactors, CSTRs) [5] or tubular reactors (aiming at Plug Flow Reactors, PFRs) [3]. This last configuration also benefits better heat exchange due to higher heat transfer area/volume ratios [6]; as a consequence, it is possible to run reactions in more severe conditions leading to an increase in product quantity/quality, while keeping the process safe. Mixed vessels for continuous synthesis are well investigated and find several industrial applications. On the contrary, only few works analyse the same problem in tubular reactors. Roughly speaking, four main research areas for continuous syntheses can be identified: classical PFR-like reactors [6, 7], modular systems [8–11], microreactors [12] and other reactors [13].

Ferrouillant *et al.* [6] have studied the improved heat removal in a multifunctional heat exchanger running an exothermic reaction. Rossow *et al.* [7] have designed a continuous copolymerisation PFR-like reactor from a process carried out in a SBR. Kohlmann *et al.* [8], Goerke *et al.* [9] and Hashemi *et al.* [11] have developed a continuous modular tubular reactor with intermediate injections for a copolymerisation reaction, analysing its feasibility with respect to the original SBR process and proposing also an optimised control system. Meimaroglou *et al.* [10] used a series of tubular reactors in a modular system to run a solution copolymerisation varying process conditions. Haber *et al.* [12] have analysed the behaviour of a microstructured tubular reactor running a quasi-instantaneous exothermic reaction. Anxionnaz *et al.* [13] reviewed different configurations and geometries for process intensification in heat exchanger reactors. All previous works succeeded in finding a specific condition for carrying out the desired process in a given reactor, but seem to lack a sense of generality, being the reported approach limited to the particular process under examination.

This work focuses on continuous side-fed tubular reactors. In particular a PFR with continuous side injections, similar to the one proposed by Zwietering [14], was considered. Given a reaction process effectively carried out in a semi-batch reactor with an optimised recipe, the primary aim was to define the feeding policy for the side injections into the Zwietering-like tubular reactor which allows to reproduce exactly the SBR behaviour without knowing the reaction kinetics. This way, the operating conditions of a tubular reactor having the same efficiency as the original SBR in terms of conversion and selectivity are identified. On the

other hand, the process productivity remains as degree of freedom and, therefore, can be increased.

2. Model formulation

2.1. Dimensional equations

Let us consider a generic industrial reaction process through which a chemical species is produced using an optimised recipe in SBR. Figure 1 shows the scheme of such SBR, which is initially charged with a known quantity of each species, $m_{i,0}$, and fed with a mass flowrate of each component, $F_i(t)$, ($i = 1, \dots, NC$). The reactor is assumed to be well mixed and to operate at isothermal conditions.

Our aim is to transform this discontinuous process into a continuous, steady-state one, using a tubular reactor with side feed injections (Figure 2) and constant temperature (equal to that of the SBR). The key question to be answered is how to distribute the side feed injections to obtain the same performances (in terms of conversion and selectivity) as the original industrial process carried out in SBR.

2.1.1. SBR governing equations

The original SBR can be modelled using the conventional conservation equations, considering a process duration equal to t_{proc} . The mass balance equations in terms of mass fractions are:

$$\frac{d\omega_i^*}{dt} = \frac{F_i(t)}{m} - \omega_i^* \frac{F(t)}{m} + \frac{\dot{\Omega}_i(\omega^*)}{\rho^*(t)} \quad (1)$$

where ω_i^* is the mass fraction of species i in the SBR, t is the time, m is the total mass, $\dot{\Omega}_i$ is species i massive reaction rate, and ρ^* is the density of the reactive mixture.

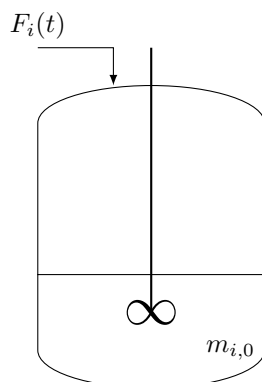


Figure 1: Semi-batch reactor. $m_{i,0}[\text{kg}]$ is the initially charged amount of species i , $F_i(t)[\text{kg s}^{-1}]$ is the feed rate of species i .

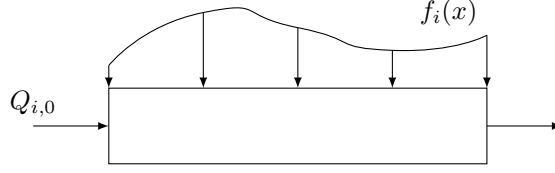


Figure 2: Tubular reactor with distributed side feed. $Q_{i,0}[\text{kg s}^{-1}]$ is the inlet flow rate of species i , $f_i(x)[\text{kg m}^{-1} \text{s}^{-1}]$ is the specific side feed rate of species i .

An additional equation (the overall mass balance) is required to track the total mass increase in time:

$$\frac{dm}{dt} = F(t) \quad (2)$$

where

$$F(t) \stackrel{\text{def}}{=} \sum_{i=1}^{NC} F_i(t) \quad (3)$$

This system of ODEs is completed by the corresponding initial conditions, ICs:

$$\omega_i^*(0) = \frac{m_{i,0}}{m_0} \quad (4)$$

$$m(0) = m_0 \quad (5)$$

where $m_0 = \sum_{i=1}^{NC} m_{i,0}$ is the total initial mass.

Note that the system density, ρ^* , can be computed through a proper equation of state as a function of composition (and therefore time):

$$\rho^*(t) = \rho(\underline{\omega}^*(t)) \quad (6)$$

The simplest equation of state that can be used is obviously $\rho^*(t) = \text{const.}$

The equations above are used to compute the time evolution of mass fractions, ω_i^* , total mass, m , and overall density, ρ^* , given the reaction kinetics, $\dot{\Omega}_i(\underline{\omega}^*)$, and the feed rates, $F_i(t)$. However, it is worth noting that also measurements of the time evolutions of the same quantities (composition, overall mass, and density) in the existing industrial SBR are enough to use the proposed approach.

2.1.2. Tubular reactor governing equations

Similar mass balance equations can be written for the tubular reactor with side injections at steady state:

$$\frac{d\omega_i}{dx} = \frac{1}{Q} \left(f_i(x) - \omega_i f(x) + \dot{\Omega}_i(\underline{\omega}) \mathcal{A}(x) \right) \quad (7)$$

where ω_i is species i mass fraction in the tubular reactor, x is the axial coordinate, Q is the total mass flowrate, \mathcal{A} is the cross sectional area and

$$f(x) \stackrel{\text{def}}{=} \sum_{i=1}^{NC} f_i(x) \quad (8)$$

The total flowrate changes along the axial coordinate according to the overall mass balance:

$$\frac{dQ}{dx} = f(x) \quad (9)$$

Again, the previous equations ask for boundary conditions, BCs:

$$\omega_i(0) = \omega_{i,0} \quad (10)$$

$$Q(0) = Q_0 \quad (11)$$

where Q_0 and $\omega_{i,0}$ are the inlet mass flowrate and inlet species i mass fraction, respectively.

Again, an equation of state (the same used to simulate the SBR) is required to evaluate the density profile, $\rho(x)$, as a function of composition:

$$\rho(x) = \rho(\underline{\omega}(x)) \quad (12)$$

Finally, it is convenient to introduce the elapsed time, $\theta(x)$, defined as the time spent by a generic fluid element to reach the position x after entering the reactor:

$$\frac{d\theta}{dx} = \frac{\rho(x)\mathcal{A}(x)}{Q(x)} \quad (13)$$

This equation follows from the definition of the fluid parcel instantaneous velocity from an inertial observer point of view. It also provides the connection between time and space inside the tubular reactor and it will be helpful to build the relationship between the SBR and the Zwietering-like reactor.

The final system involves $(NC + 4)$ equations (namely, Equations (7), (8), (9), (12) and (13)) and $(3NC + 7)$ unknowns: $\underline{\omega}(x)$, $\underline{\omega}_0$, $Q(x)$, Q_0 , $\underline{f}(x)$, $f(x)$, $\theta(x)$, $\rho(x)$, \mathcal{A} , and the reactor length L . Therefore, $(2NC + 3)$ degrees of freedom need to be specified to make the problem defined.

2.1.3. Proposed semi-batch to continuous transformation procedure

A connection between the SBR and a Zwietering-like reactor can be established forcing the same species mass fraction to be present at a given SBR time (t) and at the corresponding tubular reactor position (x), that is, at the coordinate reached by a fluid element after time $t = \theta(x)$:

$$\omega_i(x) = \omega_i^*(\theta(x)) \quad \forall x \in [0, L] \quad (14)$$

Note that, as a consequence, the same relation holds true for the density, i.e., $\rho(x) = \rho^*(\theta(x))$.

Moreover, to ensure the same overall process time in both reactors, the following equation applies:

$$\theta(L) = t_{proc} \quad (15)$$

Equations (14) and (15) enforce $2NC + 1$ additional constraints, being the former valid not only along the reactor, but also at the inlet where the BCs (10) apply (i.e., $\omega_i(0) = \omega_i^*(0) = \frac{m_{i,0}}{m_0}$). Therefore, 2 degrees of freedom remain, which can be saturated by setting arbitrary values of Q_0 and $\mathcal{A}(x)$. Note that different values of these quantities lead to different values of productivity and length of the tubular reactor.

Equations (7) and (14) together with (13) lead to (note that in the following the dependencies on x are dropped for brevity):

$$\omega_i^*(\theta)f + Q \left. \frac{d\omega_i^*}{d\theta} \right|_{\theta=t} \frac{d\theta}{dx} = \omega_i^*(\theta)f + \left. \frac{d\omega_i^*}{dt} \right|_{t=\theta} \rho \mathcal{A} = f_i + \dot{\Omega}_i(\underline{\omega}^*(\theta)) \mathcal{A} \quad (16)$$

which, combined with Equation (1), becomes:

$$\omega_i^*(\theta) \left(f - \rho \mathcal{A} \frac{F(\theta)}{m(\theta)} \right) = \omega_i^*(\theta) \sum_{j=1}^{NC} \left(f_j - \rho \mathcal{A} \frac{F_j(\theta)}{m(\theta)} \right) = f_i - \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} \quad (17)$$

where, $m(\theta)$ can be obtained from Equation (2) as:

$$m(\theta) = m_0 + \int_0^\theta F(t) dt \quad (18)$$

Equation (17) leads to a linear system $\underline{A}\underline{y} = \underline{0}$, where

$$\underline{A} = \begin{bmatrix} \omega_1^* & \omega_1^* & \dots & \omega_1^* \\ \omega_2^* & \omega_2^* & \dots & \omega_2^* \\ \vdots & \vdots & \ddots & \vdots \\ \omega_{NC}^* & \omega_{NC}^* & \dots & \omega_{NC}^* \end{bmatrix} \Big|_{t=\theta} - \underline{I} \quad (19)$$

$$\underline{y} = \begin{bmatrix} f_1 - \rho \mathcal{A} \frac{F_1(\theta)}{m(\theta)} \\ f_2 - \rho \mathcal{A} \frac{F_2(\theta)}{m(\theta)} \\ \vdots \\ f_{NC} - \rho \mathcal{A} \frac{F_{NC}(\theta)}{m(\theta)} \end{bmatrix}$$

and \underline{I} is the identity matrix. Nevertheless, these equations are not linearly independent. In fact, an identity is obtained if all equations are summed up since the stoichiometric condition $\sum_{i=1}^{NC} \omega_i^* = 1$ holds true. It should be noted that at least one unknown is zero: this is the case when a species is neither fed to the SBR nor to the tubular reactor side (for instance, this is true when the species is a product). In this case the solution of the system is the trivial one, $\underline{y} = \underline{0}$, that is:

$$f_i - \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} = 0 \quad (20)$$

The same solution could be obtained even if all species were fed to the SBR since one function $f_k(x)$ can be arbitrarily chosen to fulfil the constraint $y_k = 0$. Therefore, in any case it follows that the solution of the previous linear system of equations reduces to:

$$f_i(x) = \rho \mathcal{A} \frac{F_i(\theta(x))}{m(\theta(x))} \quad (21)$$

This last equation can be recast as:

$$\frac{f_i(x)}{\mathcal{A}(x)} = \frac{F_i(\theta(x))}{V(\theta(x))} \quad (22)$$

where $V(\theta(x)) = \frac{m(\theta(x))}{\rho^*(\theta(x))}$ is the reaction volume in the SBR at time $t = \theta(x)$. This means that the volume specific mass flowrate must be the same in both the SBR and the Zwietering-like reactor at the same time. Note that the ratio $f_i(x)$ to $\mathcal{A}(x)$ has units of flowrate per volume and it represents the feed profile which allows reproducing a process carried out in a SBR by a continuous tubular reactor while keeping the same performances in terms of both conversion and selectivity.

2.1.4. Model constitutive equations

The proposed model for the rigorous transformation of a SBR process into a Zwietering-like tubular reactor process is based on Equations (9), (13), (15) and (21) together with the required boundary conditions, that is:

$$\begin{cases} \frac{dQ}{dx} = \sum_{i=1}^{NC} f_i(x) \\ \frac{d\theta}{dx} = \frac{\rho \mathcal{A}}{Q(x)} \\ \theta(L) = t_{proc} \\ f_i(x) = \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} \end{cases} \quad \begin{cases} \theta(0) = 0 \\ Q(0) = Q_0 \end{cases} \quad (23)$$

This is a set of 2 ODEs with Dirichlet BCs and $NC + 1$ algebraic relationships. Note that the algebraic equations are uncoupled from the ODEs solution, therefore this system is not DAE. From a numerical point of view, the ODE system must be integrated until the exit condition, $\theta(L) = t_{proc}$, is met, thus providing the tubular reactor length. Moreover, since the ODEs solution provides the $\theta(x)$ relation, the required side feed rates $f_i(x)$ can be easily computed.

2.2. Dimensionless equations

Dimensionless equations can be obtained from the aforementioned ones by defining the following dimensionless variables:

$$\begin{aligned} \hat{x} &\stackrel{\text{def}}{=} \frac{x}{L} &\rightarrow & dx = L d\hat{x} \\ \hat{t} &\stackrel{\text{def}}{=} \frac{t}{t_{proc}} &\rightarrow & dt = t_{proc} d\hat{t} \\ \hat{Q}(\hat{x}) &\stackrel{\text{def}}{=} \frac{Q(L\hat{x})}{Q_0} &\rightarrow & dQ = Q_0 d\hat{Q} \\ \hat{f}_i(\hat{x}) &\stackrel{\text{def}}{=} \frac{L}{Q_0} f_i(L\hat{x}) \\ \hat{\rho}(\hat{x}) &\stackrel{\text{def}}{=} \frac{\rho(L\hat{x})}{\rho_0} \\ \hat{\rho}^*(\hat{t}) &\stackrel{\text{def}}{=} \frac{\rho^*(t_{proc}\hat{t})}{\rho_0} \\ \hat{\mathcal{A}}(\hat{x}) &\stackrel{\text{def}}{=} \frac{\mathcal{A}(L\hat{x})}{\mathcal{A}_0} \end{aligned} \quad (24)$$

It should be noted that $\hat{\rho}^*(\hat{\theta}) = \hat{\rho}(\hat{x})$ since density depends on the composition only, as a consequence of Equation (14). Using these definitions, Equations (9), (13) and (21) **become**:

$$\frac{d\hat{Q}}{d\hat{x}} = \hat{f} \quad (25)$$

$$\frac{d\hat{\theta}}{d\hat{x}} = \frac{\frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0}\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})}{\hat{Q}} = \frac{K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})}{\hat{Q}} \quad (26)$$

$$\hat{f}_i = \frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0}\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})\frac{F_i(\theta)t_{proc}}{m(\theta)} = K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})\frac{F_i(\theta)t_{proc}}{m(\theta)} \quad (27)$$

where $\hat{Q}(0) = 1$, $\hat{\theta}(0) = 0$ and

$$K \stackrel{\text{def}}{=} \frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0} = \frac{\frac{L}{v_0}}{t_{proc}} = \frac{\tau_0}{t_{proc}} = \frac{L}{L_0} \quad (28)$$

is a dimensionless number expressing the ratio of the initial residence time with respect to the overall process time, which can also be considered as a dimensionless tubular reactor length. Here $v_0 = \frac{Q_0}{\rho_0\mathcal{A}_0}$ is the initial velocity, $\tau_0 = \frac{L}{v_0}$ is a formal initial residence time (that is, the one computed without accounting for the side feed) and $L_0 = \frac{v_0}{t_{proc}}$ is the reactor length computed without considering the side injections.

By further defining

$$\hat{F}_i(\hat{\theta}) \stackrel{\text{def}}{=} F_i(t_{proc}\hat{\theta})\frac{t_{proc}}{m_0} \quad (29)$$

one gets

$$\begin{aligned} \frac{F_i(\theta)}{m(\theta)} &= \frac{F_i(\theta)}{m_0 + \int_0^\theta F(t)dt} = \\ &= \frac{1}{t_{proc}} \frac{\hat{F}_i(\hat{\theta})}{1 + \int_0^{\hat{\theta}} \hat{F}(\hat{t})d\hat{t}} \stackrel{\text{def}}{=} \frac{\hat{\gamma}_i(\hat{\theta})}{t_{proc}} \end{aligned} \quad (30)$$

and Equation (25) becomes:

$$\frac{d\hat{Q}}{d\hat{x}} = \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \quad (31)$$

By applying the chain rule and using Equation (26) it is possible to obtain:

$$\frac{d\hat{Q}}{d\hat{\theta}} = K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x}) \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \left(\frac{d\hat{\theta}}{d\hat{x}} \right)^{-1} = \hat{Q} \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \quad (32)$$

This equation can be integrated, leading to

$$\begin{aligned}\hat{Q}(\hat{\theta}) &= \exp\left(\int_0^{\hat{\theta}} \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{t}) d\hat{t}\right) = \\ &= 1 + \int_0^{\hat{\theta}} \hat{F}(\hat{t}) d\hat{t}\end{aligned}\tag{33}$$

where

$$\hat{F}(\hat{t}) = \sum_{i=1}^{NC} \hat{F}_i(\hat{t})\tag{34}$$

which allows solving Equation (26) as:

$$\int_0^{\hat{\theta}} \frac{\hat{Q}(\hat{t})}{\hat{\rho}^*(\hat{t})} d\hat{t} = K \int_0^{\hat{x}} \hat{\mathcal{A}}(\hat{\xi}) d\hat{\xi}\tag{35}$$

to obtain the function $\hat{\theta}(\hat{x})$.

K value can be found by using the dimensionless Equation (15)

$$\hat{\theta}(1) = 1\tag{36}$$

together with Equation (35)

$$K = \frac{\int_0^1 \frac{\hat{Q}(\hat{\theta})}{\hat{\rho}^*(\hat{\theta})} d\hat{\theta}}{\int_0^1 \hat{\mathcal{A}}(\hat{x}) d\hat{x}}\tag{37}$$

Consequently, Equation (27) becomes:

$$\hat{f}_i(\hat{x}) = K \hat{\rho}^*(\hat{\theta}) \hat{\mathcal{A}}(\hat{x}) \frac{\hat{F}_i(\hat{\theta})}{\hat{Q}(\hat{\theta})}\tag{38}$$

The solution of this problem is guaranteed to exist and to be unique by the Cauchy-Lipschitz theorem. In fact the problem consists in the solution of a Cauchy problem: the integrand function $\hat{\theta}(\hat{x})$ is Lipschitz continuous on $[0, 1]$ as it has bounded first derivative, therefore satisfying the theorem conditions.

Note that the trivial case with constant density and cross sectional area leads to the simpler equation:

$$K = \int_0^1 \hat{Q}(\hat{\theta}) d\hat{\theta}\tag{39}$$

The general algorithm used to solve this problem is the following:

1. assign a value to $\mathcal{A}(\hat{x})$ and Q_0 ;
2. from the SBR recipe, compute $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$, and $\hat{F}(\hat{t})$ through Equations (24), (29) and (34);
3. compute $\hat{Q}(\hat{\theta})$ through Equation (33);
4. compute K through Equation (37);
5. solve ODE (26) to compute $\hat{\theta}(\hat{x})$;
6. compute $\hat{f}_i(\hat{x})$ using Equation (38);
7. find the tubular reactor length using Equation (28).

From these dimensionless values, dimensional values can be easily computed through their definitions (24).

An important feature of the proposed procedure is now evident: no kinetic information is required once an effective recipe is available. In other words, some measurements on the industrial SBR (namely: $\rho^*(t)$, $F(t)$, and m_0) suffice to identify all the parameters of a side fed tubular reactor which is able to achieve the same product quality (at least in terms of conversion and selectivity) of an existing SBR industrial plant.

3. Parametric analysis

The proposed procedure guarantees a rigorous transformation of a SBR based process to a continuous one carried out in a Zwietering-like tubular reactor. However, also more trivial procedures, based on rules-of-thumb arising from engineering intuition, could be guessed. To highlight the different results (in terms of conversion and selectivity) obtained using the proposed methodology or a more intuitive side feed injection policy, a simple case study was investigated. Density and cross sectional area are assumed constant for the sake of simplicity and a second-order process reaction is considered:



along with an undesired first-order side reaction consuming the desired product, C :



According to the SBR recipe, a given amount of the main reactant B , m_0 , has to be initially loaded in the reactor, while the coreactant A is fed at constant flowrate, F_{A0} . For this simple case study, an analytical solution can be found by applying the aforementioned procedure:

1. arbitrary values can be chosen for both \mathcal{A}_0 and Q_0 ; however, being the cross sectional area constant, it follows that:

$$\hat{\mathcal{A}} = 1 \quad (42)$$

2. $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$ and $\hat{F}(\hat{t})$ are computed using Equations (24), (29) and (34), resulting in the following constant values:

$$\hat{\rho}^* = 1 \quad (43)$$

$$\hat{F} = \hat{F}_A = \frac{t_{proc}}{m_0} F_{A0} \quad \hat{F}_B = \hat{F}_C = \hat{F}_D = 0 \quad (44)$$

3. $\hat{Q}(\hat{\theta})$ is computed through Equation (33), leading to:

$$\hat{Q}(\hat{\theta}) = 1 + \hat{F}\hat{\theta} \quad (45)$$

4. K is then computed using Equation (37):

$$K = 1 + \frac{\hat{F}}{2} \quad (46)$$

5. the ODE (26) can be integrated analytically to give the functional dependence $\hat{\theta}(\hat{x})$:

$$\hat{\theta}(\hat{x}) = \frac{1}{\hat{F}} \left(\sqrt{1 + 2K\hat{F}\hat{x}} - 1 \right) \quad (47)$$

6. $\hat{f}_A(\hat{x})$ is computed using Equation (38) (note that only the coreactant A is fed to the SBR and therefore injected laterally in the tubular reactor):

$$\hat{f}_A(\hat{x}) = \frac{K\hat{F}}{\sqrt{1 + 2K\hat{F}\hat{x}}} \quad (48)$$

7. finally, $\hat{f}_A(\hat{x})$ is made dimensional using Equation (38) and the tubular reactor length is found using Equation (28)

$$f_A(x) = \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 \sqrt{1 + 2 \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 Q_0} x}} \quad (49)$$

$$L = \left(1 + \frac{F_{A0} t_{proc}}{2m_0} \right) \frac{Q_0 t_{proc}}{\rho_0 \mathcal{A}_0} \quad (50)$$

As previously stated, it is important noting that no chemical kinetics information was used to evaluate $f_A(x)$

and L .

This solution can be compared with an approximate solution derived from a more intuitive transformation involving constant side feedrate, f_{A0} , all along the entire tubular reactor. For instance, this constant side feedrate can be computed using the following similarity relationship between tubular reactor flowrates and SBR masses:

$$\frac{f_{A0}L}{Q_0} = \frac{F_{A0}t_{proc}}{m_0} \quad (51)$$

Moreover, the mean residence time in the tubular reactor can be set equal to the SBR process time as follows:

$$\frac{\rho_0 \mathcal{A} L}{Q_0 + \frac{f_{A0}L}{2}} = t_{proc} \quad (52)$$

Also the use of these rules-of-thumb leads to analytical relations for both f_{A0} and L :

$$f_{A0} = \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 \left(1 + \frac{F_{A0}t_{proc}}{2m_0}\right)} \quad (53)$$

$$L = \left(1 + \frac{F_{A0}t_{proc}}{2m_0}\right) \frac{Q_0 t_{proc}}{\rho_0 \mathcal{A}_0} \quad (54)$$

The two different lateral feed policies are compared in Figure 3 for different values of the parameter \hat{F} , which represents the amount of coreactant fed to the SBR with respect to the initially loaded amount of reactants. At increasing values of \hat{F} , the variation of the required lateral feed with the axial coordinate increases and, therefore, the differences between the two feed laws increase as well.

In particular, it is worthwhile noting that the constant feed policy of the SBR results in a non-constant lateral feed flowrate along the axial coordinate of the tubular reactor. This behaviour arises from the constraint (22): being \mathcal{A} and F_A constant in this case study, the time variation of the SBR reaction volume results in a f_A change along the axial coordinate of the tubular reactor. Note that, in spite of the linear variation of the volume in time, the axial variation of f_A is not linear due to the non-linear dependence of θ on x .

The practical impact of the different feed policies can be estimated by integrating the mass balances (Equations (7) and (9)) for both constant and variable lateral feed policies. Then, the outlet flowrates of the desired product C computed using the process parameters summarised in Tables 1 and 2 are compared through their percentage relative difference, defined as:

$$\Delta Q_C = \left| \frac{Q_C - Q_C^{const}}{Q_C} \right|_{x=L} \cdot 100 \quad (55)$$

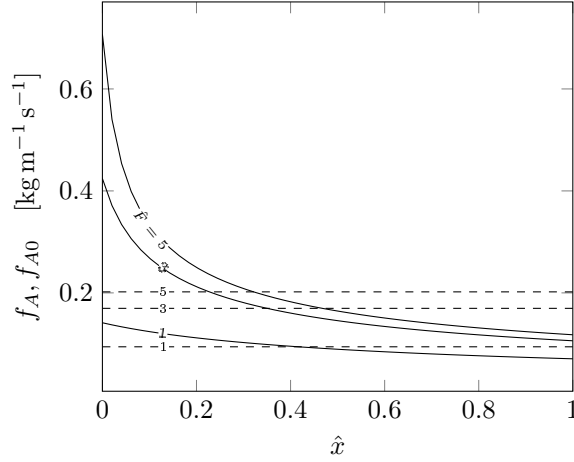


Figure 3: Side feed flowrate along the dimensionless axial coordinate for the rigorous (solid line) and for the constant lateral feed (dashed line) transformations. Curves are parametrised according to the dimensionless SBR feedrate, \hat{F} .

Table 1: Process data for parametric analysis simulations.

$MW_A = MW_B$	20 kg kmol ⁻¹
$MW_C = MW_D$	40 kg kmol ⁻¹
m_0	1000 kg
t_{proc}	500 s
ρ	1000 kg m ⁻³
Q_0	1 kg s ⁻¹
\mathcal{A}	0.07 m ²

in Figure 4 as a function of the dimensionless SBR feed rate, \hat{F} , parametrised according to the kinetic constant values of the two reactions, k_1 and k_2 . Q_C is the flowrate computed using the rigorous transformation policy, while Q_C^{const} is that computed using constant lateral feed flowrate. We can see that large differences arise, clearly indicating that the proposed approach is more effective than simpler rules-of-thumb in the general case.

Another comparison was performed between the continuous lateral feed injection and a discrete one, to investigate the possibility of implementing the proposed procedure with a series of finite additions. This was done by dividing the computed reactor length in N_d equal parts, each having a lateral feed injection at

Table 2: Reaction rate constants for the selected cases.

	$k_1 \cdot 10^6$ $\left[\frac{\text{m}^3}{\text{kmol s}}\right]$	$k_2 \cdot 10^4$ $[\text{s}^{-1}]$
a	1	1
b	1	100
c	100	1
d	100	100

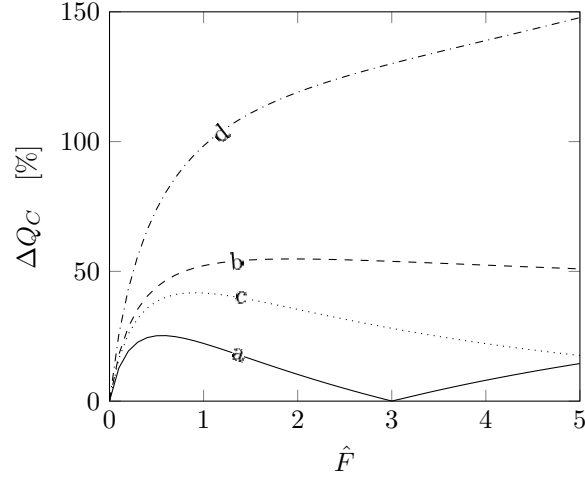


Figure 4: Percentage relative difference between outlet flowrates of species C (Equation (55)) computed using the constant side feed policy and the rigorous one. Curves are parametrised according to **the kinetic constants, as from Table 2.**

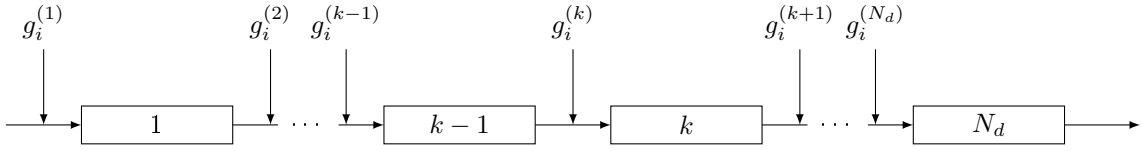


Figure 5: Approximation of the continuous lateral feed injection, $f_i(x)$, with N_d discrete side injections, $g_i^{(k)}$.

its beginning, with a mass flowrate equal to

$$g_i^{(k)} = \int_{\frac{L}{N_d}(k-1)}^{\frac{L}{N_d}k} f_i(x) dx \quad k = 1, \dots, N_d \quad (56)$$

as shown in Figure 5; obviously, L and $f_i(x)$ values are computed using the rigorous approach.

Modelling such reactor configuration requires the solution of $N_d \cdot NC$ PFR mass balance equations:

$$\frac{dQ_i^{(k)}}{dx} = \dot{\Omega}_i(\omega^{(k)}) \quad (57)$$

where Q_i^k is the mass flowrate of species i along the axial coordinate of the k -th section, and

$$\omega_i^{(k)} = \frac{Q_i^{(k)}}{\sum_{j=1}^{NC} Q_j^{(k)}} \quad (58)$$

These equations are solved with BCs:

$$Q_i^{(k)}(0) = Q_{i,out}^{(k-1)} + g_i^{(k)} \quad (59)$$

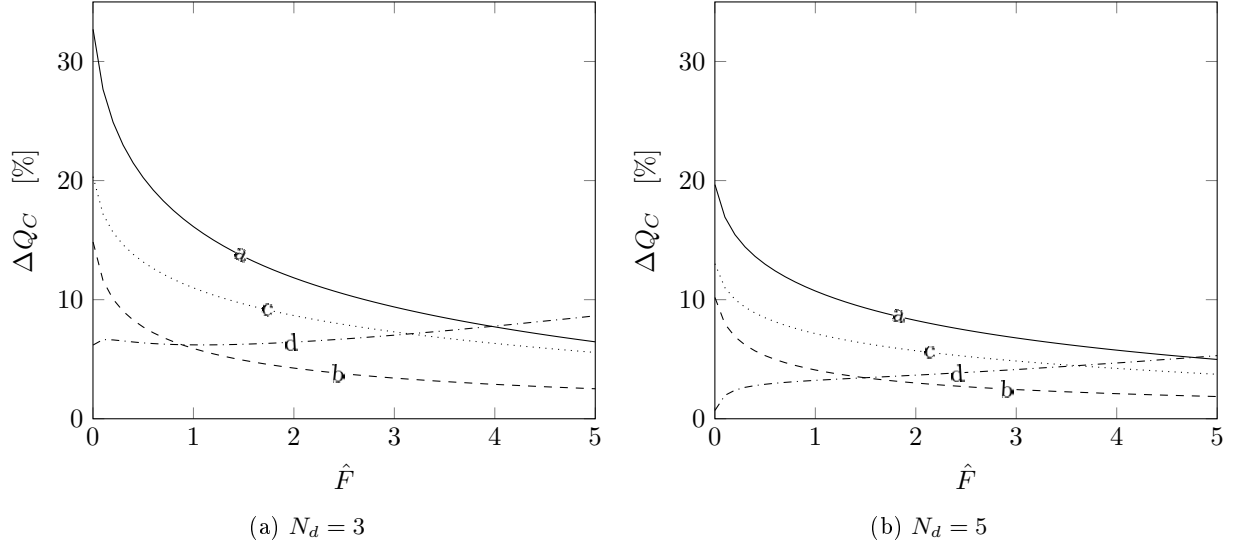


Figure 6: Percentage relative difference between outlet flowrates for species C (Equation (55)) using the discrete side feed policy with respect to the rigorous one. Curves are parametrised according to [the kinetic constants, as from Table 2](#).

where $Q_{i,out}^{(k-1)}$ is the flowrate of species i at the outlet of the previous $(k-1)$ section, defined as:

$$Q_{i,out}^{(k-1)} = \begin{cases} Q_0 \omega_{i,0} & k = 1 \\ Q_i^{(k-1)} \Big|_{x=\frac{l}{N_d}} & k > 1 \end{cases} \quad (60)$$

Figure 6 compares the continuous and discrete feed policies for different values of the kinetic constants in terms of ΔQ_C as defined by Equation (55). Even though the differences are not negligible, they are definitely lower than those found using a constant side feed rate policy and obviously decrease by increasing the number of subdivisions, [as can be seen from Figures 7 and 8](#). [The former shows how the maximum difference in productivity changes according to the number of discrete feeds, for any analysed dimensionless feedrate and couple of kinetic constants](#). [The latter depicts \$C\$ mass fractions according to the number of feed locations for an example case](#). Differences decrease super-linearly between the ideal continuous feed policy and the discrete one at increasing number of feed points. [If a maximum deviation of 5% can be accepted, a critical value \(above which deviations are smaller\) of \$N_d = 20\$ is obtained](#).

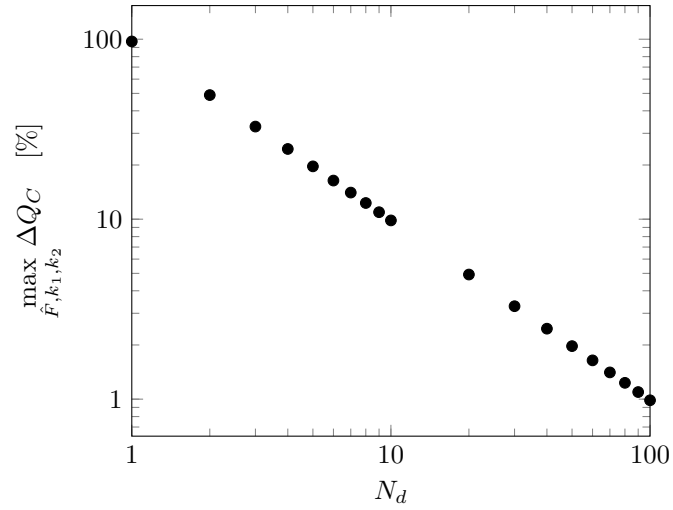


Figure 7: Maximum relative difference between outlet flowrates for species C using the discrete side feed policy with respect to the rigorous one as function of the number of discrete feeds.

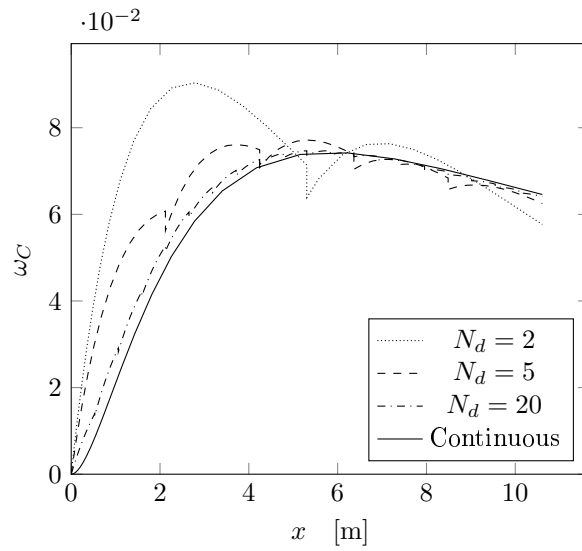


Figure 8: C mass fraction along the axial coordinate where $\hat{F} = 1$, $k_1 = 1 \times 10^{-4} \text{ m}^3 \text{ kmol}^{-1} \text{ s}^{-1}$ and $k_2 = 1 \times 10^{-2} \text{ m}^3 \text{ kmol}^{-1} \text{ s}^{-1}$. Curves are parametrised according to the number of discrete feeds.

4. Case studies

The potentials of the proposed approach were investigated through two case studies, representative of two relevant classes of industrial processes: production of copolymers and production of fine chemicals.

4.1. Copolymerisation

4.1.1. SBR feed policy design

The feedrate of a copolymerisation SBR can be designed to obtain a given product composition by means of the well known power feed policy [15, 16]. According to this feed policy, the rate between the residual amounts of the two monomers (A , the most reactive, and B , the least reactive) is kept constant during the entire process, thus enabling the production of a copolymer at constant composition, i.e. with the desired monomer i mass fraction, ϕ_i^w . A typical reaction scheme for a radical copolymerisation process involves initiation, propagation and termination reactions, as summarised in Table 3. According to the power feed policy, A is the coreactant to be fed to the SBR, while the stoichiometric amount of B is charged to the reactor at the beginning of the process. Therefore, molar balances for the two monomers in the SBR are:

$$\begin{cases} \frac{dn_A}{dt} = \dot{N}_A(t) + R_A V \\ \frac{dn_B}{dt} = R_B V \end{cases} \quad (61)$$

where $n_i(t)$ is the molar quantity of species i , \dot{N}_A is the feedrate of A to the SBR, $R_i = -k_{pi}^* c_{R\bullet} c_i$ is species i molar production rate, c_i is species i molar concentration and $c_{R\bullet}$ is the overall concentration of active chains, given by the quasi-steady-state formula $\sqrt{\frac{R_i}{k_t^*}}$. Assuming long chains approximation (LCA) [17] and the pseudo-kinetic approach [18], the expressions of effective rate coefficients (indicated by the superscript $*$) can be readily evaluated as a function of the actual monomer mixture composition as summarised in Table 4.

The analytical solution of these equations is:

$$n_B(t) = \frac{n_{B,0}}{n_{A,0}} n_A(t) = n_{B,0} e^{-\bar{k}_d t} \quad (62)$$

$$\dot{N}_A(t) = \dot{N}_{A,0} e^{-\bar{k}_d t} \quad (63)$$

where $n_{A,0}$ and $n_{B,0}$ can be obtained from the so called Mayo-Lewis plot [19], which reports monomer A molar fraction of the instantaneously produced copolymer, ϕ_A , as a function of the same monomer molar

Table 3: Radicalic copolymerisation reaction scheme. All reactions are bimolecular second order, except initiation, which is unimolecular with rate R_I . $A_{l,m}^\bullet$ stands for a chain of l units of A and m units of B , where the radical is located on the terminating A unit.

	Reaction	Rate constant
<i>Initiation</i>	$I_2 + M \rightarrow 2R^\bullet$	
<i>Propagation</i>	$A_{l,m}^\bullet + A \rightarrow A_{l+1,m}^\bullet$	k_{pAA}
	$A_{l,m}^\bullet + B \rightarrow B_{l,m+1}^\bullet$	k_{pAB}
	$B_{l,m}^\bullet + A \rightarrow A_{l+1,m}^\bullet$	k_{pBA}
	$B_{l,m}^\bullet + B \rightarrow B_{l,m+1}^\bullet$	k_{pBB}
<i>Termination</i>	$A_{l,m}^\bullet + A_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tAA}
	$A_{l,m}^\bullet + B_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tAB}
	$B_{l,m}^\bullet + B_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tBB}

Table 4: Variable definitions for the copolymerisation case study.

Variable	Definition
R_I	$2\eta k_d c_{I_2}$
k_{pA}^*	$k_{pAAP_A} + k_{pBAP_B}$
k_{pB}^*	$k_{pBBP_B} + k_{pABP_A}$
p_A	$\frac{k_{pBACA}}{k_{pABCB} + k_{pBACA}}$
p_B	$\frac{k_{pABCB}}{k_{pABCB} + k_{pBACA}}$
k_t^*	$k_{tAA}p_A^2 + 2k_{tAB}p_Ap_B + k_{tBB}p_B^2$
\tilde{k}_d	$\left(k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{pBB}k_{pAB} \right) \sqrt{\frac{R_I}{k_{tAA}k_{pBA}^2 \left(\frac{n_{A,0}}{n_{B,0}} \right)^2 + 2k_{tAB}k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{tBB}k_{pAB}^2}}$
$\dot{N}_{A,0}$	$n_{A0} \left(k_{pAA}k_{pBA} \frac{n_{A0}}{n_{B0}} + k_{pAB}k_{pBA} \left(1 - \frac{n_{A0}}{n_{B0}} \right) - k_{pBB}k_{pAB} \right) \cdot \sqrt{\frac{R_I}{k_{tAA}k_{pBA}^2 \left(\frac{n_{A,0}}{n_{B,0}} \right)^2 + 2k_{tAB}k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{tBB}k_{pAB}^2}}$

fraction in the monomeric mixture, X_A :

$$\phi_A = \frac{(r_A - 1)X_A^2 + X_A}{(r_A - 2)X_A^2 + 2X_A + r_B(1 - X_A)^2} \quad (64)$$

$$X_A = \frac{n_A}{n_A + n_B}$$

under the long-chain approximation. In these equations $r_i = \frac{k_{p_{ii}}}{k_{p_{ij}}}$ is the reactivity ratio of species i . From the ϕ_A value, using the known values of the monomer molecular weights, one can easily compute the moles of A and B required to produce a given mass of copolymer, n_A^{tot} and n_B^{tot} . Since all the amount of B is initially loaded into the SBR, from the X_A value also the moles of A to be initially loaded, $n_{A,0}$, can be easily computed. The moles of A to be fed to the SBR, $n_A^{tot} - n_{A,0}$, can be related to the feed flowrate as

Table 5: Process data for copolymerisation reaction.

	<i>A</i>	<i>B</i>
MW_i [kg kmol ⁻¹]	50	80
ρ [kg m ⁻³]		900
F_i^w	0.4	0.6
k_{pii} [m ³ kmol ⁻¹ s ⁻¹]	3×10^3	1×10^3
r_i	3	0.83
k_t [m ³ kmol ⁻¹ s ⁻¹]		1×10^6
ηk_d [s ⁻¹]		1×10^{-4}

follows:

$$n_A^{tot} - n_{A,0} = \int_0^{t_{proc}} \dot{N}_A(t) dt = \int_0^{t_{proc}} \dot{N}_{A,0} e^{-\tilde{k}_d t} dt \quad (65)$$

This equation allows computing the overall process time:

$$t_{proc} = -\frac{1}{\tilde{k}_d} \ln \left(1 - (n_A^{tot} - n_{A,0}) \frac{\tilde{k}_d}{\dot{N}_{A0}} \right) \quad (66)$$

This case study was worked out using the process data reported in Table 5 for a SBR aimed at producing 1 t of copolymer. The initiator has initial concentration of 0.5 mol%.

Since the required value of ϕ_A is equal to 0.516, the molar fraction of monomer *A* in the reacting mixture, X_A , has to be equal to 0.357 from which the initial monomer amounts are readily evaluated: $n_{A0} = 4.167$ kmol, $n_{B0} = 7.500$ kmol, and $m_0 = 808.33$ kg. Therefore, using the parameter values in Table 4, $\tilde{k}_d = 3.604 \times 10^{-3}$ s⁻¹ and $\dot{N}_{A0} = 13.82$ mols⁻¹ are evaluated, leading to $t_{proc} = 5200$ s. This process time is quite large because it reflects the continuously decreasing polymerisation rate when very high conversion is required. On the other hand, the required addition rate becomes negligible much before and the process can be interrupted much earlier without affecting product amount and quality. About 99% of the overall amount of monomer *A* has been already injected into the reactor after slightly more than 1000 s. This specific value has been set as the process duration, i.e. $t_{proc} = 1074$ s.

4.1.2. Transformation to continuous process

For the sake of example, the tubular reactor is assumed to have an inlet total flowrate equal to 1 kg s⁻¹ and a diameter of 0.3 m. Assuming again constant density and cross sectional area, the transformation to a side-fed tubular reactor carried out using the previously discussed procedure leads to an analytical solution, summarised in the following:

1. assuming constant cross sectional area, $\mathcal{A} = 1$ follows;

2. $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$ and $\hat{F}(\hat{t})$ are computed using Equations (24), (29) and (34), leading to:

$$\hat{\rho} = 1 \quad (67)$$

$$\hat{F}(\hat{t}) = \hat{F}_A(\hat{t}) = ae^{-b\hat{t}} \quad \hat{F}_B = \hat{F}_C = \hat{F}_D = 0 \quad (68)$$

where $a \stackrel{\text{def}}{=} \frac{\dot{N}_{A,0}MW_{A,t_{proc}}}{m_0} = 0.918$ and $b \stackrel{\text{def}}{=} \tilde{k}_d t_{proc} = 3.869$.

3. $\hat{Q}(\hat{\theta})$ is found from Equation (33):

$$\hat{Q}(\hat{\theta}) = 1 + \frac{a}{b} (1 - e^{-b\hat{\theta}}) \quad (69)$$

4. K is computed from Equation (37):

$$K = 1 + \frac{a}{b} + \frac{a}{b^2} (e^{-b} - 1) = 1.177 \quad (70)$$

5. the ODE (26) is solved to give a relationship between $\hat{\theta}$ and \hat{x} :

$$K\hat{x} = \left(1 + \frac{a}{b}\right)\hat{\theta} + \frac{a}{b^2} (e^{-b\hat{\theta}} - 1) \quad (71)$$

6. $\hat{f}_A(\hat{\theta})$ is computed using Equation (38):

$$\hat{f}_A(\hat{\theta}) = \frac{Kabe^{-b\hat{\theta}}}{b + a(1 - e^{-b\hat{\theta}})} \quad (72)$$

7. the tubular reactor length is computed using Equation (28):

$$L = \frac{Kt_{proc}Q_0}{\rho_0\mathcal{A}_0} = 19.9 \text{ m} \quad (73)$$

8. $f_A(x)$ is computed using Equation (38) leading to the side feed profile shown in Figure 9.

From the numerical simulation of the side-fed tubular reactor using Equations (7) and (9), it can be easily verified that a constant value of $X_A = 0.357$ is maintained throughout the entire reactor length: this means that the produced polymer will have the desired constant value of monomer ratio as in the SBR process.

Finally, it is worth mentioning again that kinetic information (i.e., \dot{N}_{A0} and \tilde{k}_d) is used only to derive the

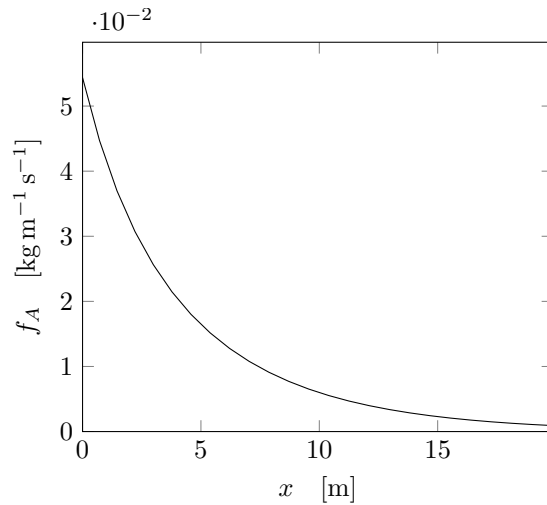
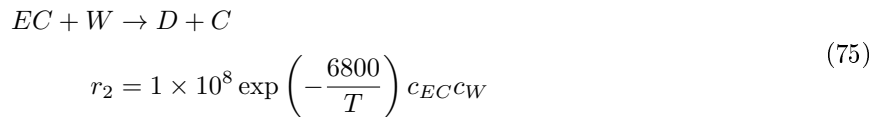
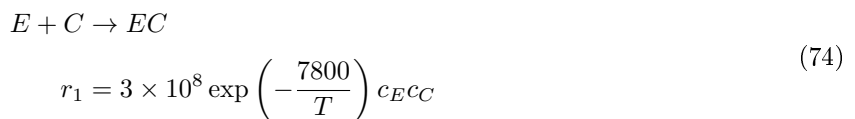


Figure 9: Side feed policy as a function of the axial coordinate for the copolymerisation reaction.

SBR feed policy. However, given the SBR feed policy (that is, given the value of $F_i(t)$), the transformation of the industrial SBR process into a tubular reactor with side injections can be carried out without any kinetic information.

4.2. Fine chemicals

This case study is inspired to the production of a diol, D , via catalytic reduction (catalyst, C) and hydrolysis (water, W) of the corresponding internal ester, E , as in the last step of the regioselective reaction discussed by Bringmann *et al.* [20]:



with r [$\text{kmol m}^{-3} \text{s}^{-1}$], T [K] and c_i [kmol m^{-3}]. EC is an intermediate complex and the reaction is carried out in a solvent, S .

The recipe developed at laboratory scale for the production of D in a SBR is summarised in Table 6. The reactor is initially charged with 10 g S . Temperature is kept constant at 30 °C throughout the entire process.

Table 6: Laboratory scale recipe for the asymmetric synthesis.

Time [s]	Description
0 – 3600	Constant simultaneous feeding of 19.8 g 9 wt% solution of E in S and 18.36 g 2 wt% solution of C in S .
3600 – 3660	Idle.
3660 – 3720	Constant feeding of 0.60 g W .
3720 – 4020	Idle.

Table 7: Process data for the diol synthesis.

MW_E	260 kg kmol ⁻¹
MW_C	80 kg kmol ⁻¹
MW_W	18 kg kmol ⁻¹
ρ	911 kg m ⁻³
Q_0	0.3 kg s ⁻¹
\mathcal{A}	0.0314 m ²

Using the process data summarised in Table 7, the transformation of this SBR recipe to the one suitable for a single side-fed tubular reactor was performed through the previously discussed procedure, which in this case does not allow an analytical solution. The reactor length results equal to about 130m with the feed policy summarised in Figure 10 for each species to be fed. Once more, to highlight the relevance of the use of variable feed flowrates, mass balance equations (7) and (9) were solved for both the rigorous solution and a simplified case, which assumes constant side feed flowrates. The latter were obtained through the intuitive relationships previously discussed in section 3. Since the SBR process involves four steps, the constant flowrates are computed for each tubular reactor region separately using the following relations:

$$\frac{f^{(k)} L^{(k)}}{Q_0^{(k)}} = \frac{F^{(k)} t^{(k)}}{m_0^{(k)}} \quad (76)$$

$$\frac{\rho \mathcal{A} L^{(k)}}{Q_0^{(k)} + \frac{f^{(k)} L^{(k)}}{2}} = t^{(k)} \quad (77)$$

where $k = 1, \dots, 4$ specifies the considered SBR step or reactor portion. In this case, the total reactor length is the sum of the lengths of the four regions, which is equal to about 125 m, and the side feed flowrate values for each chemical species are easily computed from the relations:

$$\frac{f_i^{(k)}}{f^{(k)}} = \frac{F_i^{(k)}}{F^{(k)}} \quad (78)$$

The results of this transformation are summarised in Figure 10 as dashed lines. In spite of the similarity

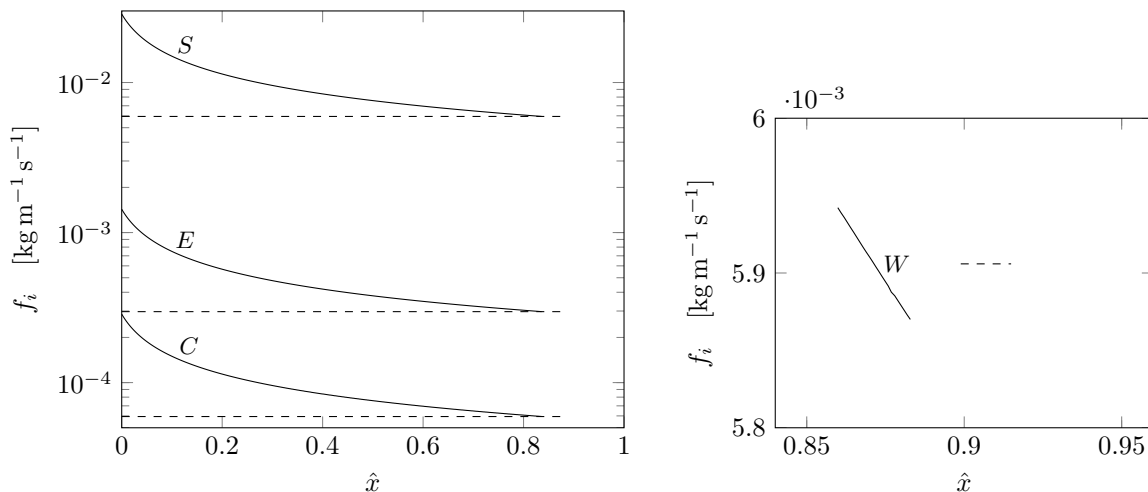


Figure 10: Side feed flowrate along the dimensionless axial coordinate according to the rigorous (solid line) and the constant feed (dashed line) method for the diol synthesis. Species S , E and C on the left, W on the right (enlargement).

between these two side feed policies, they lead to quite different results in terms of tubular reactor performances: at constant side feed flowrates, about 40 % less productivity is established than implementing the rigorous side feed flowrates. Furthermore, the final conversion is also reduced, by about 5%. This means that the product quality from the constant feed tubular reactor is no more guaranteed to be the same as in the SBR plant. These results agree with the conclusions of the parametric analysis: since the rigorous solution is the only one that guarantees overlapping SBR and tubular reactor species profiles, the two reactor configurations show the same performances only in this case.

5. Conclusions

An approach for the transformation of isothermal homogeneous semi-batch processes into continuous ones was proposed and verified in the case of tubular reactors with distributed side injections. The key advantage of the proposed approach is that it does not require any kinetic information once the SBR recipe and some density measurements on an existing industrial plant are available. **This procedure is optimal since it allows the exact reproduction of the original SBR performances. Of course, when available, kinetic information allow optimizing the reaction recipe whatever is the reactor type. However, since our primary focus is the transfer of a previously assessed recipe from SBR to the continuous tubular reactor, giving up the kinetic information becomes a major benefit.**

Two case studies were analysed, a copolymer synthesis and the production of a fine chemical. In both cases, the tubular reactor ensures the same product composition and final conversion of the semi-batch

process. Moreover, the reaction performances when applying these side feed policies have been compared with those achieved when using simpler and more intuitive feed policies, showing relevant differences.

Finally, it is worth mentioning that this tubular reactor enables scaling of productivity either changing the inlet flowrate or the cross sectional area. Being these two variables related to each other by well known design constraints, they act as a degree of freedom for the process design.

Acknowledgements

Financial support of Innovhub for one of us (FF) is gratefully acknowledged.

Nomenclature

\mathcal{A}	PFR cross sectional area [m ²]
a	Auxiliary variable [-]
b	Auxiliary variable [-]
c_i	i -th species molar concentration [kmol m ⁻³]
F	SBR total feedrate [kg s ⁻¹]
F_i	SBR i -th species feedrate [kg s ⁻¹]
f	PFR total distributed feedrate [kg s ⁻¹ m ⁻¹]
f_i	PFR i -th species distributed feedrate [kg s ⁻¹ m ⁻¹]
g_i	PFR i -th species discretised feedrate [kg s ⁻¹]
K	PFR dimensionless length [-]
k	Reaction rate constant
k_d	Dissociation rate constant [s ⁻¹]
\tilde{k}_d	Decay rate [s ⁻¹]
k_p	Propagation rate constant [m ³ kmol ⁻¹ s ⁻¹]
k_t	Termination rate constant [m ³ kmol ⁻¹ s ⁻¹]
L	PFR length [m]
m	SBR total mass [kg]
m_i	SBR i -th species mass [kg]
\dot{N}_i	SBR i -th species molar feedrate [kmol s ⁻¹]

n_i	SBR i -th species molar quantity [kmol]
MW_i	i -th species molecular weight [kg kmol ⁻¹]
NC	Number of components (species) [-]
Q	PFR total flowrate [kg s ⁻¹]
Q_i	PFR i -th species flowrate [kg s ⁻¹]
R_i	i -th species molar production rate [kmol m ⁻³ s ⁻¹]
r	Molar reaction rate [kmol m ⁻³ s ⁻¹]
r_i	i -th species reactivity ratio [-]
T	Temperature [K]
t	Time [s]
t_{proc}	Overall process time [s]
V	SBR volume [m ³]
v	Velocity [m s ⁻¹]
W_i	i -th species overall mass [kg]
X_i	i -th species monomeric molar fraction [-]
x	PFR axial coordinate [m]

Greek symbols

δ	Monomer fraction to be fed [-]
$\hat{\gamma}_i$	Auxiliary variable [-]
ϕ_i	i -th species desired molar fraction in copolymer [-]
ϕ_i^w	i -th species desired mass fraction in copolymer [-]
$\dot{\Omega}_i$	i -th species massive production rate [kg m ⁻³ s ⁻¹]
ω_i	PFR i -th species mass fraction [-]
ω_i^*	SBR i -th species mass fraction [-]
ρ	Density in the PFR [kg m ⁻³]
ρ^*	Density in th SBR [kg m ⁻³]
τ	Residence time [s]

θ Elapsed time [s]

Other symbols

0 Initial value (subscript)

(k) Diol synthesis reactor section (superscript)

$\hat{\cdot}$ Dimensionless quantity

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From semi-batch to continuous tubular reactors: a kinetics-free approach

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Abstract

A methodology, which does not require any kinetic information, for the rigorous transformation of an isothermal, homogeneous semi-batch process into an equivalent continuous side-fed tubular reactor was developed. Once the semi-batch process parameters are known, the proposed methodology allows for easily defining all the process parameters of a side-fed tubular reactor that guarantees the same performances as the original semi-batch process, in terms of conversion and product characteristics.

Two different case studies were selected to investigate the potential of the proposed approach: a copolymer synthesis and the production of a fine chemical, clearly showing the need of a rigorous transformation of the semi-batch process into the continuous one since productivity and product quality are strongly affected by the feeding policy.

Keywords: semi-batch to continuous, process intensification, kinetics-free, tubular reactor

1. Introduction

Fine chemicals and specialties are generally produced via discontinuous or semi-continuous processes. This is mainly due either to discontinuous market needs (seasonal campaigns), which require a high degree of flexibility in the synthesis, or to complex and dangerous reaction processes, which are carried out in semi-batch reactors, SBRs, for safety reason [1, 2].

An effective way to reduce costs and enhance reproducibility of such processes is to transform discontinuous ones into their continuous counterpart. This way reactor volumes are usually reduced, the intrinsic process safety is increased thanks to the lower hold-up, and investment costs are also decreased [3]. Moreover, overall process times can be reduced and more constant quality is achieved, with a general decrease in

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operative costs [4]. This is the framework of the so called process intensification. Transition from discontinuous to continuous processes is also motivated by the increasing demand of specialty products. Higher production volumes would require more complex and expensive discontinuous equipment, making engineers more prone to consider continuous systems.

Straightforward choices for continuous reactors are mixed vessels (approximating the behaviour of Continuous Stirred Tank Reactors, CSTRs) [5] or tubular reactors (aiming at Plug Flow Reactors, PFRs) [3]. This last configuration also benefits better heat exchange due to higher heat transfer area/volume ratios [6]; as a consequence, it is possible to run reactions in more severe conditions leading to an increase in product quantity/quality, while keeping the process safe. Mixed vessels for continuous synthesis are well investigated and find several industrial applications. On the contrary, only few works analyse the same problem in tubular reactors. Roughly speaking, four main research areas for continuous syntheses can be identified: classical PFR-like reactors [6, 7], modular systems [8–11], microreactors [12] and other reactors [13].

Ferrouillant *et al.* [6] have studied the improved heat removal in a multifunctional heat exchanger running an exothermic reaction. Rossow *et al.* [7] have designed a continuous copolymerisation PFR-like reactor from a process carried out in a SBR. Kohlmann *et al.* [8], Goerke *et al.* [9] and Hashemi *et al.* [11] have developed a continuous modular tubular reactor with intermediate injections for a copolymerisation reaction, analysing its feasibility with respect to the original SBR process and proposing also an optimised control system. Meimaroglou *et al.* [10] used a series of tubular reactors in a modular system to run a solution copolymerisation varying process conditions. Haber *et al.* [12] have analysed the behaviour of a microstructured tubular reactor running a quasi-instantaneous exothermic reaction. Anxionnaz *et al.* [13] reviewed different configurations and geometries for process intensification in heat exchanger reactors. All previous works succeeded in finding a specific condition for carrying out the desired process in a given reactor, but seem to lack a sense of generality, being the reported approach limited to the particular process under examination.

This work focuses on continuous side-fed tubular reactors. In particular a PFR with continuous side injections, similar to the one proposed by Zwietering [14], was considered. Given a reaction process effectively carried out in a semi-batch reactor with an optimised recipe, the primary aim was to define the feeding policy for the side injections into the Zwietering-like tubular reactor which allows to reproduce exactly the SBR behaviour without knowing the reaction kinetics. This way, the operating conditions of a tubular reactor having the same efficiency as the original SBR in terms of conversion and selectivity are identified. On the

other hand, the process productivity remains as degree of freedom and, therefore, can be increased.

2. Model formulation

2.1. Dimensional equations

Let us consider a generic industrial reaction process through which a chemical species is produced using an optimised recipe in SBR. Figure 1 shows the scheme of such SBR, which is initially charged with a known quantity of each species, $m_{i,0}$, and fed with a mass flowrate of each component, $F_i(t)$, ($i = 1, \dots, NC$). The reactor is assumed to be well mixed and to operate at isothermal conditions.

Our aim is to transform this discontinuous process into a continuous, steady-state one, using a tubular reactor with side feed injections (Figure 2) and constant temperature (equal to that of the SBR). The key question to be answered is how to distribute the side feed injections to obtain the same performances (in terms of conversion and selectivity) as the original industrial process carried out in SBR.

2.1.1. SBR governing equations

The original SBR can be modelled using the conventional conservation equations, considering a process duration equal to t_{proc} . The mass balance equations in terms of mass fractions are:

$$\frac{d\omega_i^*}{dt} = \frac{F_i(t)}{m} - \omega_i^* \frac{F(t)}{m} + \frac{\dot{\Omega}_i(\omega^*)}{\rho^*(t)} \quad (1)$$

where ω_i^* is the mass fraction of species i in the SBR, t is the time, m is the total mass, $\dot{\Omega}_i$ is species i massive reaction rate, and ρ^* is the density of the reactive mixture.

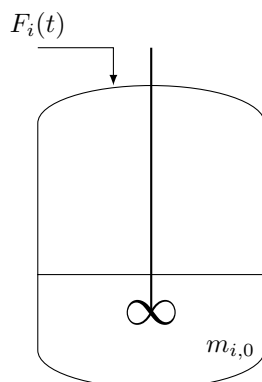


Figure 1: Semi-batch reactor. $m_{i,0}[\text{kg}]$ is the initially charged amount of species i , $F_i(t)[\text{kg s}^{-1}]$ is the feed rate of species i .

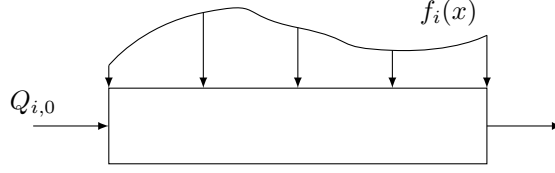


Figure 2: Tubular reactor with distributed side feed. $Q_{i,0}[\text{kg s}^{-1}]$ is the inlet flow rate of species i , $f_i(x)[\text{kg m}^{-1} \text{s}^{-1}]$ is the specific side feed rate of species i .

An additional equation (the overall mass balance) is required to track the total mass increase in time:

$$\frac{dm}{dt} = F(t) \quad (2)$$

where

$$F(t) \stackrel{\text{def}}{=} \sum_{i=1}^{NC} F_i(t) \quad (3)$$

This system of ODEs is completed by the corresponding initial conditions, ICs:

$$\omega_i^*(0) = \frac{m_{i,0}}{m_0} \quad (4)$$

$$m(0) = m_0 \quad (5)$$

where $m_0 = \sum_{i=1}^{NC} m_{i,0}$ is the total initial mass.

Note that the system density, ρ^* , can be computed through a proper equation of state as a function of composition (and therefore time):

$$\rho^*(t) = \rho(\underline{\omega}^*(t)) \quad (6)$$

The simplest equation of state that can be used is obviously $\rho^*(t) = \text{const.}$

The equations above are used to compute the time evolution of mass fractions, ω_i^* , total mass, m , and overall density, ρ^* , given the reaction kinetics, $\dot{\Omega}_i(\underline{\omega}^*)$, and the feed rates, $F_i(t)$. However, it is worth noting that also measurements of the time evolutions of the same quantities (composition, overall mass, and density) in the existing industrial SBR are enough to use the proposed approach.

2.1.2. Tubular reactor governing equations

Similar mass balance equations can be written for the tubular reactor with side injections at steady state:

$$\frac{d\omega_i}{dx} = \frac{1}{Q} \left(f_i(x) - \omega_i f(x) + \dot{\Omega}_i(\underline{\omega}) \mathcal{A}(x) \right) \quad (7)$$

where ω_i is species i mass fraction in the tubular reactor, x is the axial coordinate, Q is the total mass flowrate, \mathcal{A} is the cross sectional area and

$$f(x) \stackrel{\text{def}}{=} \sum_{i=1}^{NC} f_i(x) \quad (8)$$

The total flowrate changes along the axial coordinate according to the overall mass balance:

$$\frac{dQ}{dx} = f(x) \quad (9)$$

Again, the previous equations ask for boundary conditions, BCs:

$$\omega_i(0) = \omega_{i,0} \quad (10)$$

$$Q(0) = Q_0 \quad (11)$$

where Q_0 and $\omega_{i,0}$ are the inlet mass flowrate and inlet species i mass fraction, respectively.

Again, an equation of state (the same used to simulate the SBR) is required to evaluate the density profile, $\rho(x)$, as a function of composition:

$$\rho(x) = \rho(\underline{\omega}(x)) \quad (12)$$

Finally, it is convenient to introduce the elapsed time, $\theta(x)$, defined as the time spent by a generic fluid element to reach the position x after entering the reactor:

$$\frac{d\theta}{dx} = \frac{\rho(x)\mathcal{A}(x)}{Q(x)} \quad (13)$$

This equation follows from the definition of the fluid parcel instantaneous velocity from an inertial observer point of view. It also provides the connection between time and space inside the tubular reactor and it will be helpful to build the relationship between the SBR and the Zwietering-like reactor.

The final system involves $(NC + 4)$ equations (namely, Equations (7), (8), (9), (12) and (13)) and $(3NC + 7)$ unknowns: $\underline{\omega}(x)$, $\underline{\omega}_0$, $Q(x)$, Q_0 , $\underline{f}(x)$, $f(x)$, $\theta(x)$, $\rho(x)$, \mathcal{A} , and the reactor length L . Therefore, $(2NC + 3)$ degrees of freedom need to be specified to make the problem defined.

2.1.3. Proposed semi-batch to continuous transformation procedure

A connection between the SBR and a Zwietering-like reactor can be established forcing the same species mass fraction to be present at a given SBR time (t) and at the corresponding tubular reactor position (x), that is, at the coordinate reached by a fluid element after time $t = \theta(x)$:

$$\omega_i(x) = \omega_i^*(\theta(x)) \quad \forall x \in [0, L] \quad (14)$$

Note that, as a consequence, the same relation holds true for the density, i.e., $\rho(x) = \rho^*(\theta(x))$.

Moreover, to ensure the same overall process time in both reactors, the following equation applies:

$$\theta(L) = t_{proc} \quad (15)$$

Equations (14) and (15) enforce $2NC + 1$ additional constraints, being the former valid not only along the reactor, but also at the inlet where the BCs (10) apply (i.e., $\omega_i(0) = \omega_i^*(0) = \frac{m_{i,0}}{m_0}$). Therefore, 2 degrees of freedom remain, which can be saturated by setting arbitrary values of Q_0 and $\mathcal{A}(x)$. Note that different values of these quantities lead to different values of productivity and length of the tubular reactor.

Equations (7) and (14) together with (13) lead to (note that in the following the dependencies on x are dropped for brevity):

$$\omega_i^*(\theta)f + Q \left. \frac{d\omega_i^*}{d\theta} \right|_{\theta=t} \frac{d\theta}{dx} = \omega_i^*(\theta)f + \left. \frac{d\omega_i^*}{dt} \right|_{t=\theta} \rho \mathcal{A} = f_i + \dot{\Omega}_i(\underline{\omega}^*(\theta)) \mathcal{A} \quad (16)$$

which, combined with Equation (1), becomes:

$$\omega_i^*(\theta) \left(f - \rho \mathcal{A} \frac{F(\theta)}{m(\theta)} \right) = \omega_i^*(\theta) \sum_{j=1}^{NC} \left(f_j - \rho \mathcal{A} \frac{F_j(\theta)}{m(\theta)} \right) = f_i - \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} \quad (17)$$

where, $m(\theta)$ can be obtained from Equation (2) as:

$$m(\theta) = m_0 + \int_0^\theta F(t) dt \quad (18)$$

Equation (17) leads to a linear system $\underline{A}\underline{y} = \underline{0}$, where

$$\underline{A} = \begin{bmatrix} \omega_1^* & \omega_1^* & \dots & \omega_1^* \\ \omega_2^* & \omega_2^* & \dots & \omega_2^* \\ \vdots & \vdots & \ddots & \vdots \\ \omega_{NC}^* & \omega_{NC}^* & \dots & \omega_{NC}^* \end{bmatrix} \Big|_{t=\theta} - \underline{I} \quad (19)$$

$$\underline{y} = \begin{bmatrix} f_1 - \rho \mathcal{A} \frac{F_1(\theta)}{m(\theta)} \\ f_2 - \rho \mathcal{A} \frac{F_2(\theta)}{m(\theta)} \\ \vdots \\ f_{NC} - \rho \mathcal{A} \frac{F_{NC}(\theta)}{m(\theta)} \end{bmatrix}$$

and \underline{I} is the identity matrix. Nevertheless, these equations are not linearly independent. In fact, an identity is obtained if all equations are summed up since the stoichiometric condition $\sum_{i=1}^{NC} \omega_i^* = 1$ holds true. It should be noted that at least one unknown is zero: this is the case when a species is neither fed to the SBR nor to the tubular reactor side (for instance, this is true when the species is a product). In this case the solution of the system is the trivial one, $\underline{y} = \underline{0}$, that is:

$$f_i - \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} = 0 \quad (20)$$

The same solution could be obtained even if all species were fed to the SBR since one function $f_k(x)$ can be arbitrarily chosen to fulfil the constraint $y_k = 0$. Therefore, in any case it follows that the solution of the previous linear system of equations reduces to:

$$f_i(x) = \rho \mathcal{A} \frac{F_i(\theta(x))}{m(\theta(x))} \quad (21)$$

This last equation can be recast as:

$$\frac{f_i(x)}{\mathcal{A}(x)} = \frac{F_i(\theta(x))}{V(\theta(x))} \quad (22)$$

where $V(\theta(x)) = \frac{m(\theta(x))}{\rho^*(\theta(x))}$ is the reaction volume in the SBR at time $t = \theta(x)$. This means that the volume specific mass flowrate must be the same in both the SBR and the Zwietering-like reactor at the same time. Note that the ratio $f_i(x)$ to $\mathcal{A}(x)$ has units of flowrate per volume and it represents the feed profile which allows reproducing a process carried out in a SBR by a continuous tubular reactor while keeping the same performances in terms of both conversion and selectivity.

2.1.4. Model constitutive equations

The proposed model for the rigorous transformation of a SBR process into a Zwietering-like tubular reactor process is based on Equations (9), (13), (15) and (21) together with the required boundary conditions, that is:

$$\begin{cases} \frac{dQ}{dx} = \sum_{i=1}^{NC} f_i(x) \\ \frac{d\theta}{dx} = \frac{\rho \mathcal{A}}{Q(x)} \\ \theta(L) = t_{proc} \\ f_i(x) = \rho \mathcal{A} \frac{F_i(\theta)}{m(\theta)} \end{cases} \quad \begin{cases} \theta(0) = 0 \\ Q(0) = Q_0 \end{cases} \quad (23)$$

This is a set of 2 ODEs with Dirichlet BCs and $NC + 1$ algebraic relationships. Note that the algebraic equations are uncoupled from the ODEs solution, therefore this system is not DAE. From a numerical point of view, the ODE system must be integrated until the exit condition, $\theta(L) = t_{proc}$, is met, thus providing the tubular reactor length. Moreover, since the ODEs solution provides the $\theta(x)$ relation, the required side feed rates $f_i(x)$ can be easily computed.

2.2. Dimensionless equations

Dimensionless equations can be obtained from the aforementioned ones by defining the following dimensionless variables:

$$\begin{aligned} \hat{x} &\stackrel{\text{def}}{=} \frac{x}{L} &\rightarrow & dx = L d\hat{x} \\ \hat{t} &\stackrel{\text{def}}{=} \frac{t}{t_{proc}} &\rightarrow & dt = t_{proc} d\hat{t} \\ \hat{Q}(\hat{x}) &\stackrel{\text{def}}{=} \frac{Q(L\hat{x})}{Q_0} &\rightarrow & dQ = Q_0 d\hat{Q} \\ \hat{f}_i(\hat{x}) &\stackrel{\text{def}}{=} \frac{L}{Q_0} f_i(L\hat{x}) \\ \hat{\rho}(\hat{x}) &\stackrel{\text{def}}{=} \frac{\rho(L\hat{x})}{\rho_0} \\ \hat{\rho}^*(\hat{t}) &\stackrel{\text{def}}{=} \frac{\rho^*(t_{proc}\hat{t})}{\rho_0} \\ \hat{\mathcal{A}}(\hat{x}) &\stackrel{\text{def}}{=} \frac{\mathcal{A}(L\hat{x})}{\mathcal{A}_0} \end{aligned} \quad (24)$$

It should be noted that $\hat{\rho}^*(\hat{\theta}) = \hat{\rho}(\hat{x})$ since density depends on the composition only, as a consequence of Equation (14). Using these definitions, Equations (9), (13) and (21) become:

$$\frac{d\hat{Q}}{d\hat{x}} = \hat{f} \quad (25)$$

$$\frac{d\hat{\theta}}{d\hat{x}} = \frac{\frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0}\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})}{\hat{Q}} = \frac{K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})}{\hat{Q}} \quad (26)$$

$$\hat{f}_i = \frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0}\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})\frac{F_i(\theta)t_{proc}}{m(\theta)} = K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x})\frac{F_i(\theta)t_{proc}}{m(\theta)} \quad (27)$$

where $\hat{Q}(0) = 1$, $\hat{\theta}(0) = 0$ and

$$K \stackrel{\text{def}}{=} \frac{L\rho_0\mathcal{A}_0}{t_{proc}Q_0} = \frac{\frac{L}{v_0}}{t_{proc}} = \frac{\tau_0}{t_{proc}} = \frac{L}{L_0} \quad (28)$$

is a dimensionless number expressing the ratio of the initial residence time with respect to the overall process time, which can also be considered as a dimensionless tubular reactor length. Here $v_0 = \frac{Q_0}{\rho_0\mathcal{A}_0}$ is the initial velocity, $\tau_0 = \frac{L}{v_0}$ is a formal initial residence time (that is, the one computed without accounting for the side feed) and $L_0 = \frac{v_0}{t_{proc}}$ is the reactor length computed without considering the side injections.

By further defining

$$\hat{F}_i(\hat{\theta}) \stackrel{\text{def}}{=} F_i(t_{proc}\hat{\theta})\frac{t_{proc}}{m_0} \quad (29)$$

one gets

$$\begin{aligned} \frac{F_i(\theta)}{m(\theta)} &= \frac{F_i(\theta)}{m_0 + \int_0^\theta F(t)dt} = \\ &= \frac{1}{t_{proc}} \frac{\hat{F}_i(\hat{\theta})}{1 + \int_0^{\hat{\theta}} \hat{F}(\hat{t})d\hat{t}} \stackrel{\text{def}}{=} \frac{\hat{\gamma}_i(\hat{\theta})}{t_{proc}} \end{aligned} \quad (30)$$

and Equation (25) becomes:

$$\frac{d\hat{Q}}{d\hat{x}} = \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \quad (31)$$

By applying the chain rule and using Equation (26) it is possible to obtain:

$$\frac{d\hat{Q}}{d\hat{\theta}} = K\hat{\rho}^*(\hat{\theta})\hat{\mathcal{A}}(\hat{x}) \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \left(\frac{d\hat{\theta}}{d\hat{x}} \right)^{-1} = \hat{Q} \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{\theta}) \quad (32)$$

This equation can be integrated, leading to

$$\begin{aligned}\hat{Q}(\hat{\theta}) &= \exp\left(\int_0^{\hat{\theta}} \sum_{i=1}^{NC} \hat{\gamma}_i(\hat{t}) d\hat{t}\right) = \\ &= 1 + \int_0^{\hat{\theta}} \hat{F}(\hat{t}) d\hat{t}\end{aligned}\tag{33}$$

where

$$\hat{F}(\hat{t}) = \sum_{i=1}^{NC} \hat{F}_i(\hat{t})\tag{34}$$

which allows solving Equation (26) as:

$$\int_0^{\hat{\theta}} \frac{\hat{Q}(\hat{t})}{\hat{\rho}^*(\hat{t})} d\hat{t} = K \int_0^{\hat{x}} \hat{\mathcal{A}}(\hat{\xi}) d\hat{\xi}\tag{35}$$

to obtain the function $\hat{\theta}(\hat{x})$.

K value can be found by using the dimensionless Equation (15)

$$\hat{\theta}(1) = 1\tag{36}$$

together with Equation (35)

$$K = \frac{\int_0^1 \frac{\hat{Q}(\hat{\theta})}{\hat{\rho}^*(\hat{\theta})} d\hat{\theta}}{\int_0^1 \hat{\mathcal{A}}(\hat{x}) d\hat{x}}\tag{37}$$

Consequently, Equation (27) becomes:

$$\hat{f}_i(\hat{x}) = K \hat{\rho}^*(\hat{\theta}) \hat{\mathcal{A}}(\hat{x}) \frac{\hat{F}_i(\hat{\theta})}{\hat{Q}(\hat{\theta})}\tag{38}$$

The solution of this problem is guaranteed to exist and to be unique by the Cauchy-Lipschitz theorem. In fact the problem consists in the solution of a Cauchy problem: the integrand function $\hat{\theta}(\hat{x})$ is Lipschitz continuous on $[0, 1]$ as it has bounded first derivative, therefore satisfying the theorem conditions.

Note that the trivial case with constant density and cross sectional area leads to the simpler equation:

$$K = \int_0^1 \hat{Q}(\hat{\theta}) d\hat{\theta}\tag{39}$$

The general algorithm used to solve this problem is the following:

1. assign a value to $\mathcal{A}(\hat{x})$ and Q_0 ;
2. from the SBR recipe, compute $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$, and $\hat{F}(\hat{t})$ through Equations (24), (29) and (34);
3. compute $\hat{Q}(\hat{\theta})$ through Equation (33);
4. compute K through Equation (37);
5. solve ODE (26) to compute $\hat{\theta}(\hat{x})$;
6. compute $\hat{f}_i(\hat{x})$ using Equation (38);
7. find the tubular reactor length using Equation (28).

From these dimensionless values, dimensional values can be easily computed through their definitions (24).

An important feature of the proposed procedure is now evident: no kinetic information is required once an effective recipe is available. In other words, some measurements on the industrial SBR (namely: $\rho^*(t)$, $F(t)$, and m_0) suffice to identify all the parameters of a side fed tubular reactor which is able to achieve the same product quality (at least in terms of conversion and selectivity) of an existing SBR industrial plant.

3. Parametric analysis

The proposed procedure guarantees a rigorous transformation of a SBR based process to a continuous one carried out in a Zwietering-like tubular reactor. However, also more trivial procedures, based on rules-of-thumb arising from engineering intuition, could be guessed. To highlight the different results (in terms of conversion and selectivity) obtained using the proposed methodology or a more intuitive side feed injection policy, a simple case study was investigated. Density and cross sectional area are assumed constant for the sake of simplicity and a second-order process reaction is considered:



along with an undesired first-order side reaction consuming the desired product, C :



According to the SBR recipe, a given amount of the main reactant B , m_0 , has to be initially loaded in the reactor, while the coreactant A is fed at constant flowrate, F_{A0} . For this simple case study, an analytical solution can be found by applying the aforementioned procedure:

1. arbitrary values can be chosen for both \mathcal{A}_0 and Q_0 ; however, being the cross sectional area constant, it follows that:

$$\hat{\mathcal{A}} = 1 \quad (42)$$

2. $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$ and $\hat{F}(\hat{t})$ are computed using Equations (24), (29) and (34), resulting in the following constant values:

$$\hat{\rho}^* = 1 \quad (43)$$

$$\hat{F} = \hat{F}_A = \frac{t_{proc}}{m_0} F_{A0} \quad \hat{F}_B = \hat{F}_C = \hat{F}_D = 0 \quad (44)$$

3. $\hat{Q}(\hat{\theta})$ is computed through Equation (33), leading to:

$$\hat{Q}(\hat{\theta}) = 1 + \hat{F}\hat{\theta} \quad (45)$$

4. K is then computed using Equation (37):

$$K = 1 + \frac{\hat{F}}{2} \quad (46)$$

5. the ODE (26) can be integrated analytically to give the functional dependence $\hat{\theta}(\hat{x})$:

$$\hat{\theta}(\hat{x}) = \frac{1}{\hat{F}} \left(\sqrt{1 + 2K\hat{F}\hat{x}} - 1 \right) \quad (47)$$

6. $\hat{f}_A(\hat{x})$ is computed using Equation (38) (note that only the coreactant A is fed to the SBR and therefore injected laterally in the tubular reactor):

$$\hat{f}_A(\hat{x}) = \frac{K\hat{F}}{\sqrt{1 + 2K\hat{F}\hat{x}}} \quad (48)$$

7. finally, $\hat{f}_A(\hat{x})$ is made dimensional using Equation (38) and the tubular reactor length is found using Equation (28)

$$f_A(x) = \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 \sqrt{1 + 2 \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 Q_0} x}} \quad (49)$$

$$L = \left(1 + \frac{F_{A0} t_{proc}}{2m_0} \right) \frac{Q_0 t_{proc}}{\rho_0 \mathcal{A}_0} \quad (50)$$

As previously stated, it is important noting that no chemical kinetics information was used to evaluate $f_A(x)$

and L .

This solution can be compared with an approximate solution derived from a more intuitive transformation involving constant side feedrate, f_{A0} , all along the entire tubular reactor. For instance, this constant side feedrate can be computed using the following similarity relationship between tubular reactor flowrates and SBR masses:

$$\frac{f_{A0}L}{Q_0} = \frac{F_{A0}t_{proc}}{m_0} \quad (51)$$

Moreover, the mean residence time in the tubular reactor can be set equal to the SBR process time as follows:

$$\frac{\rho_0 \mathcal{A} L}{Q_0 + \frac{f_{A0}L}{2}} = t_{proc} \quad (52)$$

Also the use of these rules-of-thumb leads to analytical relations for both f_{A0} and L :

$$f_{A0} = \frac{\rho_0 \mathcal{A}_0 F_{A0}}{m_0 \left(1 + \frac{F_{A0}t_{proc}}{2m_0}\right)} \quad (53)$$

$$L = \left(1 + \frac{F_{A0}t_{proc}}{2m_0}\right) \frac{Q_0 t_{proc}}{\rho_0 \mathcal{A}_0} \quad (54)$$

The two different lateral feed policies are compared in Figure 3 for different values of the parameter \hat{F} , which represents the amount of coreactant fed to the SBR with respect to the initially loaded amount of reactants. At increasing values of \hat{F} , the variation of the required lateral feed with the axial coordinate increases and, therefore, the differences between the two feed laws increase as well.

In particular, it is worthwhile noting that the constant feed policy of the SBR results in a non-constant lateral feed flowrate along the axial coordinate of the tubular reactor. This behaviour arises from the constraint (22): being \mathcal{A} and F_A constant in this case study, the time variation of the SBR reaction volume results in a f_A change along the axial coordinate of the tubular reactor. Note that, in spite of the linear variation of the volume in time, the axial variation of f_A is not linear due to the non-linear dependence of θ on x .

The practical impact of the different feed policies can be estimated by integrating the mass balances (Equations (7) and (9)) for both constant and variable lateral feed policies. Then, the outlet flowrates of the desired product C computed using the process parameters summarised in Tables 1 and 2 are compared through their percentage relative difference, defined as:

$$\Delta Q_C = \left| \frac{Q_C - Q_C^{const}}{Q_C} \right|_{x=L} \cdot 100 \quad (55)$$

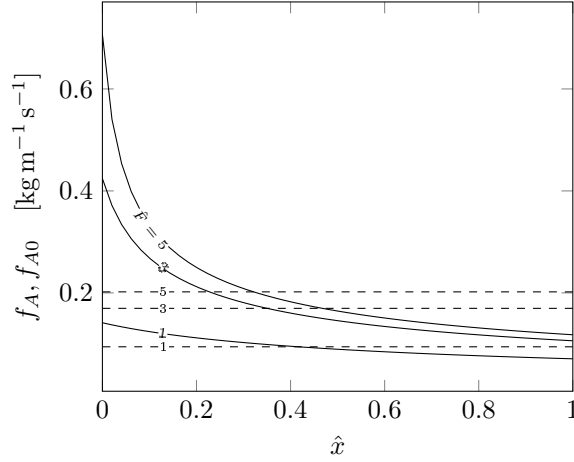


Figure 3: Side feed flowrate along the dimensionless axial coordinate for the rigorous (solid line) and for the constant lateral feed (dashed line) transformations. Curves are parametrised according to the dimensionless SBR feedrate, \hat{F} .

Table 1: Process data for parametric analysis simulations.

$MW_A = MW_B$	20 kg kmol ⁻¹
$MW_C = MW_D$	40 kg kmol ⁻¹
m_0	1000 kg
t_{proc}	500 s
ρ	1000 kg m ⁻³
Q_0	1 kg s ⁻¹
\mathcal{A}	0.07 m ²

in Figure 4 as a function of the dimensionless SBR feed rate, \hat{F} , parametrised according to the kinetic constant values of the two reactions, k_1 and k_2 . Q_C is the flowrate computed using the rigorous transformation policy, while Q_C^{const} is that computed using constant lateral feed flowrate. We can see that large differences arise, clearly indicating that the proposed approach is more effective than simpler rules-of-thumb in the general case.

Another comparison was performed between the continuous lateral feed injection and a discrete one, to investigate the possibility of implementing the proposed procedure with a series of finite additions. This was done by dividing the computed reactor length in N_d equal parts, each having a lateral feed injection at

Table 2: Reaction rate constants for the selected cases.

	$k_1 \cdot 10^6$ [$\frac{\text{m}^3}{\text{kmol s}}$]	$k_2 \cdot 10^4$ [s ⁻¹]
a	1	1
b	1	100
c	100	1
d	100	100

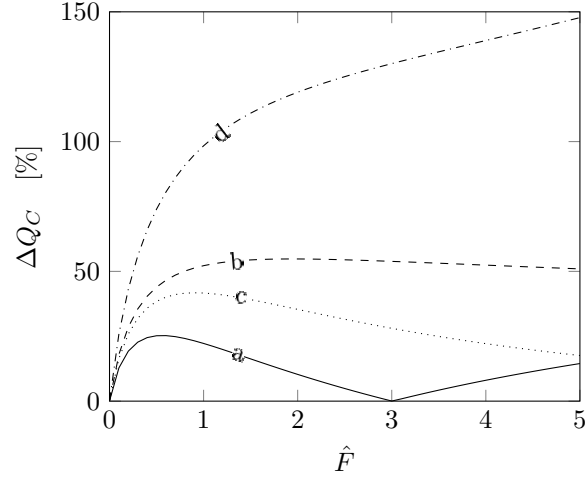


Figure 4: Percentage relative difference between outlet flowrates of species C (Equation (55)) computed using the constant side feed policy and the rigorous one. Curves are parametrised according to the kinetic constants, as from Table 2.

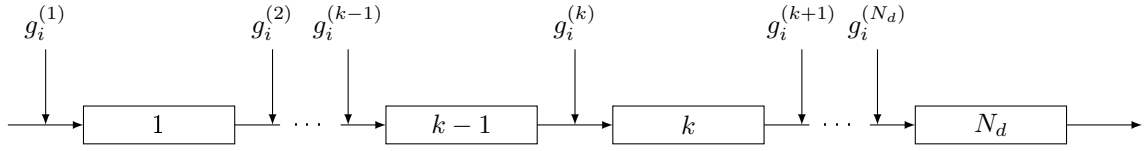


Figure 5: Approximation of the continuous lateral feed injection, $f_i(x)$, with N_d discrete side injections, $g_i^{(k)}$.

its beginning, with a mass flowrate equal to

$$g_i^{(k)} = \int_{\frac{L}{N_d}(k-1)}^{\frac{L}{N_d}k} f_i(x) dx \quad k = 1, \dots, N_d \quad (56)$$

as shown in Figure 5; obviously, L and $f_i(x)$ values are computed using the rigorous approach.

Modelling such reactor configuration requires the solution of $N_d \cdot NC$ PFR mass balance equations:

$$\frac{dQ_i^{(k)}}{dx} = \dot{\Omega}_i(\omega^{(k)}) \quad (57)$$

where Q_i^k is the mass flowrate of species i along the axial coordinate of the k -th section, and

$$\omega_i^{(k)} = \frac{Q_i^{(k)}}{\sum_{j=1}^{NC} Q_j^{(k)}} \quad (58)$$

These equations are solved with BCs:

$$Q_i^{(k)}(0) = Q_{i,out}^{(k-1)} + g_i^{(k)} \quad (59)$$

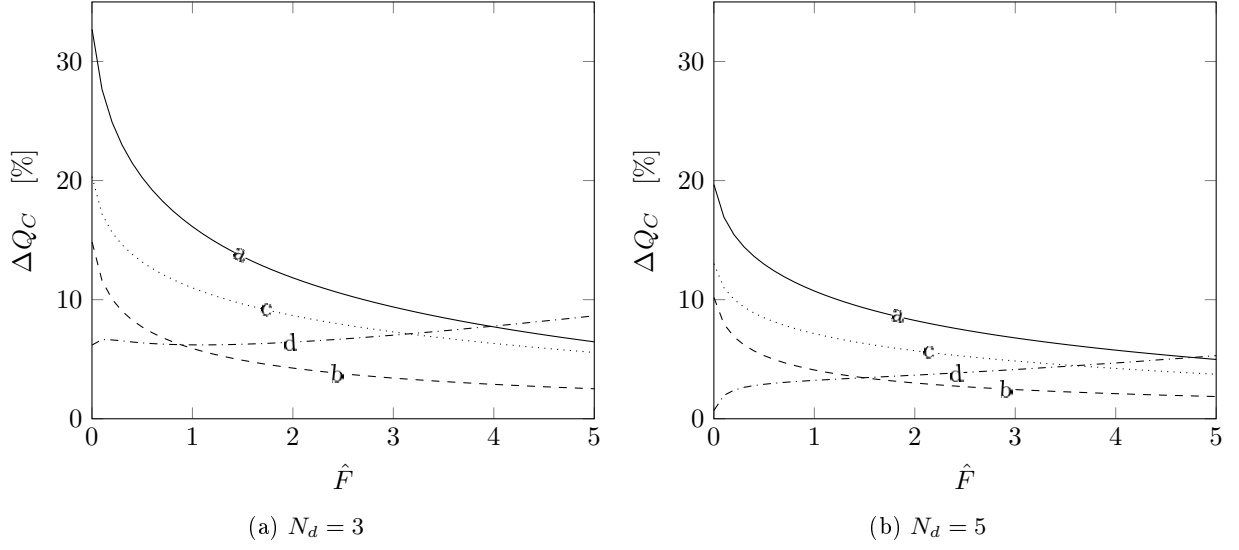


Figure 6: Percentage relative difference between outlet flowrates for species C (Equation (55)) using the discrete side feed policy with respect to the rigorous one. Curves are parametrised according to the kinetic constants, as from Table 2.

where $Q_{i,out}^{(k-1)}$ is the flowrate of species i at the outlet of the previous $(k-1)$ section, defined as:

$$Q_{i,out}^{(k-1)} = \begin{cases} Q_0 \omega_{i,0} & k = 1 \\ Q_i^{(k-1)} \Big|_{x=\frac{L}{N_d}} & k > 1 \end{cases} \quad (60)$$

Figure 6 compares the continuous and discrete feed policies for different values of the kinetic constants in terms of ΔQ_C as defined by Equation (55). Even though the differences are not negligible, they are definitely lower than those found using a constant side feed rate policy and obviously decrease by increasing the number of subdivisions, as can be seen from Figures 7 and 8. The former shows how the maximum difference in productivity changes according to the number of discrete feeds, for any analysed dimensionless feedrate and couple of kinetic constants. The latter depicts C mass fractions according to the number of feed locations for an example case. Differences decrease super-linearly between the ideal continuous feed policy and the discrete one at increasing number of feed points. If a maximum deviation of 5% can be accepted, a critical value (above which deviations are smaller) of $N_d = 20$ is obtained.

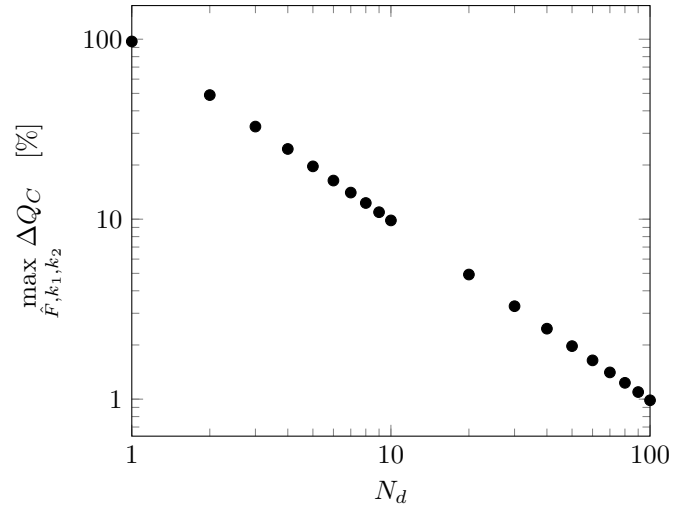


Figure 7: Maximum relative difference between outlet flowrates for species C using the discrete side feed policy with respect to the rigorous one as function of the number of discrete feeds.

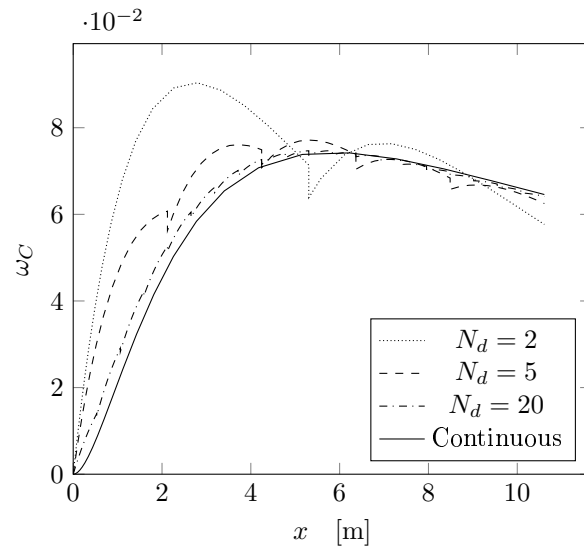


Figure 8: C mass fraction along the axial coordinate where $\hat{F} = 1$, $k_1 = 1 \times 10^{-4} \text{ m}^3 \text{ kmol}^{-1} \text{ s}^{-1}$ and $k_2 = 1 \times 10^{-2} \text{ m}^3 \text{ kmol}^{-1} \text{ s}^{-1}$. Curves are parametrised according to the number of discrete feeds.

4. Case studies

The potentials of the proposed approach were investigated through two case studies, representative of two relevant classes of industrial processes: production of copolymers and production of fine chemicals.

4.1. Copolymerisation

4.1.1. SBR feed policy design

The feedrate of a copolymerisation SBR can be designed to obtain a given product composition by means of the well known power feed policy [15, 16]. According to this feed policy, the rate between the residual amounts of the two monomers (A , the most reactive, and B , the least reactive) is kept constant during the entire process, thus enabling the production of a copolymer at constant composition, i.e. with the desired monomer i mass fraction, ϕ_i^w . A typical reaction scheme for a radical copolymerisation process involves initiation, propagation and termination reactions, as summarised in Table 3. According to the power feed policy, A is the coreactant to be fed to the SBR, while the stoichiometric amount of B is charged to the reactor at the beginning of the process. Therefore, molar balances for the two monomers in the SBR are:

$$\begin{cases} \frac{dn_A}{dt} = \dot{N}_A(t) + R_A V \\ \frac{dn_B}{dt} = R_B V \end{cases} \quad (61)$$

where $n_i(t)$ is the molar quantity of species i , \dot{N}_A is the feedrate of A to the SBR, $R_i = -k_{pi}^* c_{R\bullet} c_i$ is species i molar production rate, c_i is species i molar concentration and $c_{R\bullet}$ is the overall concentration of active chains, given by the quasi-steady-state formula $\sqrt{\frac{R_i}{k_t^*}}$. Assuming long chains approximation (LCA) [17] and the pseudo-kinetic approach [18], the expressions of effective rate coefficients (indicated by the superscript $*$) can be readily evaluated as a function of the actual monomer mixture composition as summarised in Table 4.

The analytical solution of these equations is:

$$n_B(t) = \frac{n_{B,0}}{n_{A,0}} n_A(t) = n_{B,0} e^{-\bar{k}_d t} \quad (62)$$

$$\dot{N}_A(t) = \dot{N}_{A,0} e^{-\bar{k}_d t} \quad (63)$$

where $n_{A,0}$ and $n_{B,0}$ can be obtained from the so called Mayo-Lewis plot [19], which reports monomer A molar fraction of the instantaneously produced copolymer, ϕ_A , as a function of the same monomer molar

Table 3: Radicalic copolymerisation reaction scheme. All reactions are bimolecular second order, except initiation, which is unimolecular with rate R_I . $A_{l,m}^\bullet$ stands for a chain of l units of A and m units of B , where the radical is located on the terminating A unit.

	Reaction	Rate constant
<i>Initiation</i>	$I_2 + M \rightarrow 2R^\bullet$	
<i>Propagation</i>	$A_{l,m}^\bullet + A \rightarrow A_{l+1,m}^\bullet$	k_{pAA}
	$A_{l,m}^\bullet + B \rightarrow B_{l,m+1}^\bullet$	k_{pAB}
	$B_{l,m}^\bullet + A \rightarrow A_{l+1,m}^\bullet$	k_{pBA}
	$B_{l,m}^\bullet + B \rightarrow B_{l,m+1}^\bullet$	k_{pBB}
<i>Termination</i>	$A_{l,m}^\bullet + A_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tAA}
	$A_{l,m}^\bullet + B_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tAB}
	$B_{l,m}^\bullet + B_{q,r}^\bullet \rightarrow P_{l+q,m+r}$ or $P_{l,m} + P_{q,r}$	k_{tBB}

Table 4: Variable definitions for the copolymerisation case study.

Variable	Definition
R_I	$2\eta k_d c_{I_2}$
k_{pA}^*	$k_{pAAP_A} + k_{pBAP_B}$
k_{pB}^*	$k_{pBBP_B} + k_{pABP_A}$
p_A	$\frac{k_{pBACA}}{k_{pABCB} + k_{pBACA}}$
p_B	$\frac{k_{pABCB}}{k_{pABCB} + k_{pBACA}}$
k_t^*	$k_{tAA}p_A^2 + 2k_{tAB}p_Ap_B + k_{tBB}p_B^2$
\tilde{k}_d	$\left(k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{pBB}k_{pAB} \right) \sqrt{\frac{R_I}{k_{tAA}k_{pBA}^2 \left(\frac{n_{A,0}}{n_{B,0}} \right)^2 + 2k_{tAB}k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{tBB}k_{pAB}^2}}$
$\dot{N}_{A,0}$	$n_{A0} \left(k_{pAA}k_{pBA} \frac{n_{A0}}{n_{B0}} + k_{pAB}k_{pBA} \left(1 - \frac{n_{A0}}{n_{B0}} \right) - k_{pBB}k_{pAB} \right) \cdot \sqrt{\frac{R_I}{k_{tAA}k_{pBA}^2 \left(\frac{n_{A,0}}{n_{B,0}} \right)^2 + 2k_{tAB}k_{pAB}k_{pBA} \frac{n_{A,0}}{n_{B,0}} + k_{tBB}k_{pAB}^2}}$

fraction in the monomeric mixture, X_A :

$$\phi_A = \frac{(r_A - 1)X_A^2 + X_A}{(r_A - 2)X_A^2 + 2X_A + r_B(1 - X_A)^2} \quad (64)$$

$$X_A = \frac{n_A}{n_A + n_B}$$

under the long-chain approximation. In these equations $r_i = \frac{k_{p_{ii}}}{k_{p_{ij}}}$ is the reactivity ratio of species i . From the ϕ_A value, using the known values of the monomer molecular weights, one can easily compute the moles of A and B required to produce a given mass of copolymer, n_A^{tot} and n_B^{tot} . Since all the amount of B is initially loaded into the SBR, from the X_A value also the moles of A to be initially loaded, $n_{A,0}$, can be easily computed. The moles of A to be fed to the SBR, $n_A^{tot} - n_{A,0}$, can be related to the feed flowrate as

Table 5: Process data for copolymerisation reaction.

	<i>A</i>	<i>B</i>
MW_i [kg kmol ⁻¹]	50	80
ρ [kg m ⁻³]		900
F_i^w	0.4	0.6
k_{pii} [m ³ kmol ⁻¹ s ⁻¹]	3×10^3	1×10^3
r_i	3	0.83
k_t [m ³ kmol ⁻¹ s ⁻¹]		1×10^6
ηk_d [s ⁻¹]		1×10^{-4}

follows:

$$n_A^{tot} - n_{A,0} = \int_0^{t_{proc}} \dot{N}_A(t) dt = \int_0^{t_{proc}} \dot{N}_{A,0} e^{-\tilde{k}_d t} dt \quad (65)$$

This equation allows computing the overall process time:

$$t_{proc} = -\frac{1}{\tilde{k}_d} \ln \left(1 - (n_A^{tot} - n_{A,0}) \frac{\tilde{k}_d}{\dot{N}_{A0}} \right) \quad (66)$$

This case study was worked out using the process data reported in Table 5 for a SBR aimed at producing 1 t of copolymer. The initiator has initial concentration of 0.5 mol%.

Since the required value of ϕ_A is equal to 0.516, the molar fraction of monomer *A* in the reacting mixture, X_A , has to be equal to 0.357 from which the initial monomer amounts are readily evaluated: $n_{A0} = 4.167$ kmol, $n_{B0} = 7.500$ kmol, and $m_0 = 808.33$ kg. Therefore, using the parameter values in Table 4, $\tilde{k}_d = 3.604 \times 10^{-3}$ s⁻¹ and $\dot{N}_{A0} = 13.82$ mols⁻¹ are evaluated, leading to $t_{proc} = 5200$ s. This process time is quite large because it reflects the continuously decreasing polymerisation rate when very high conversion is required. On the other hand, the required addition rate becomes negligible much before and the process can be interrupted much earlier without affecting product amount and quality. About 99% of the overall amount of monomer *A* has been already injected into the reactor after slightly more than 1000 s. This specific value has been set as the process duration, i.e. $t_{proc} = 1074$ s.

4.1.2. Transformation to continuous process

For the sake of example, the tubular reactor is assumed to have an inlet total flowrate equal to 1 kg s⁻¹ and a diameter of 0.3 m. Assuming again constant density and cross sectional area, the transformation to a side-fed tubular reactor carried out using the previously discussed procedure leads to an analytical solution, summarised in the following:

1. assuming constant cross sectional area, $\mathcal{A} = 1$ follows;

2. $\hat{\rho}^*(\hat{t})$, $\hat{F}_i(\hat{t})$ and $\hat{F}(\hat{t})$ are computed using Equations (24), (29) and (34), leading to:

$$\hat{\rho} = 1 \quad (67)$$

$$\hat{F}(\hat{t}) = \hat{F}_A(\hat{t}) = ae^{-b\hat{t}} \quad \hat{F}_B = \hat{F}_C = \hat{F}_D = 0 \quad (68)$$

where $a \stackrel{\text{def}}{=} \frac{\dot{N}_{A,0}MW_A t_{proc}}{m_0} = 0.918$ and $b \stackrel{\text{def}}{=} \tilde{k}_d t_{proc} = 3.869$.

3. $\hat{Q}(\hat{\theta})$ is found from Equation (33):

$$\hat{Q}(\hat{\theta}) = 1 + \frac{a}{b} (1 - e^{-b\hat{\theta}}) \quad (69)$$

4. K is computed from Equation (37):

$$K = 1 + \frac{a}{b} + \frac{a}{b^2} (e^{-b} - 1) = 1.177 \quad (70)$$

5. the ODE (26) is solved to give a relationship between $\hat{\theta}$ and \hat{x} :

$$K\hat{x} = \left(1 + \frac{a}{b}\right)\hat{\theta} + \frac{a}{b^2} (e^{-b\hat{\theta}} - 1) \quad (71)$$

6. $\hat{f}_A(\hat{\theta})$ is computed using Equation (38):

$$\hat{f}_A(\hat{\theta}) = \frac{Kabe^{-b\hat{\theta}}}{b + a(1 - e^{-b\hat{\theta}})} \quad (72)$$

7. the tubular reactor length is computed using Equation (28):

$$L = \frac{Kt_{proc}Q_0}{\rho_0\mathcal{A}_0} = 19.9 \text{ m} \quad (73)$$

8. $f_A(x)$ is computed using Equation (38) leading to the side feed profile shown in Figure 9.

From the numerical simulation of the side-fed tubular reactor using Equations (7) and (9), it can be easily verified that a constant value of $X_A = 0.357$ is maintained throughout the entire reactor length: this means that the produced polymer will have the desired constant value of monomer ratio as in the SBR process.

Finally, it is worth mentioning again that kinetic information (i.e., \dot{N}_{A0} and \tilde{k}_d) is used only to derive the

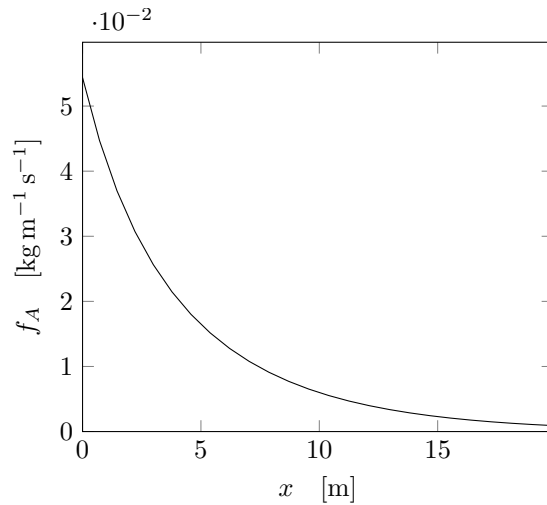
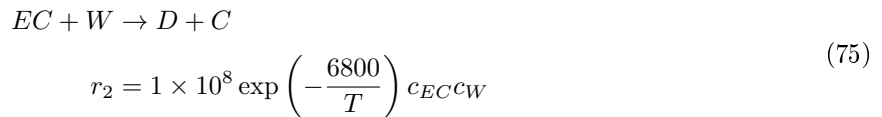
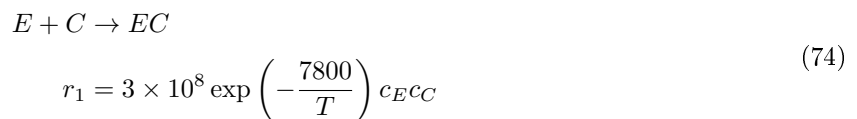


Figure 9: Side feed policy as a function of the axial coordinate for the copolymerisation reaction.

SBR feed policy. However, given the SBR feed policy (that is, given the value of $F_i(t)$), the transformation of the industrial SBR process into a tubular reactor with side injections can be carried out without any kinetic information.

4.2. Fine chemicals

This case study is inspired to the production of a diol, D , via catalytic reduction (catalyst, C) and hydrolysis (water, W) of the corresponding internal ester, E , as in the last step of the regioselective reaction discussed by Bringmann *et al.* [20]:



with r [$\text{kmol m}^{-3} \text{s}^{-1}$], T [K] and c_i [kmol m^{-3}]. EC is an intermediate complex and the reaction is carried out in a solvent, S .

The recipe developed at laboratory scale for the production of D in a SBR is summarised in Table 6. The reactor is initially charged with 10 g S . Temperature is kept constant at 30 °C throughout the entire process.

Table 6: Laboratory scale recipe for the asymmetric synthesis.

Time [s]	Description
0 – 3600	Constant simultaneous feeding of 19.8 g 9 wt% solution of E in S and 18.36 g 2 wt% solution of C in S .
3600 – 3660	Idle.
3660 – 3720	Constant feeding of 0.60 g W .
3720 – 4020	Idle.

Table 7: Process data for the diol synthesis.

MW_E	260 kg kmol ⁻¹
MW_C	80 kg kmol ⁻¹
MW_W	18 kg kmol ⁻¹
ρ	911 kg m ⁻³
Q_0	0.3 kg s ⁻¹
\mathcal{A}	0.0314 m ²

Using the process data summarised in Table 7, the transformation of this SBR recipe to the one suitable for a single side-fed tubular reactor was performed through the previously discussed procedure, which in this case does not allow an analytical solution. The reactor length results equal to about 130m with the feed policy summarised in Figure 10 for each species to be fed. Once more, to highlight the relevance of the use of variable feed flowrates, mass balance equations (7) and (9) were solved for both the rigorous solution and a simplified case, which assumes constant side feed flowrates. The latter were obtained through the intuitive relationships previously discussed in section 3. Since the SBR process involves four steps, the constant flowrates are computed for each tubular reactor region separately using the following relations:

$$\frac{f^{(k)} L^{(k)}}{Q_0^{(k)}} = \frac{F^{(k)} t^{(k)}}{m_0^{(k)}} \quad (76)$$

$$\frac{\rho \mathcal{A} L^{(k)}}{Q_0^{(k)} + \frac{f^{(k)} L^{(k)}}{2}} = t^{(k)} \quad (77)$$

where $k = 1, \dots, 4$ specifies the considered SBR step or reactor portion. In this case, the total reactor length is the sum of the lengths of the four regions, which is equal to about 125 m, and the side feed flowrate values for each chemical species are easily computed from the relations:

$$\frac{f_i^{(k)}}{f^{(k)}} = \frac{F_i^{(k)}}{F^{(k)}} \quad (78)$$

The results of this transformation are summarised in Figure 10 as dashed lines. In spite of the similarity

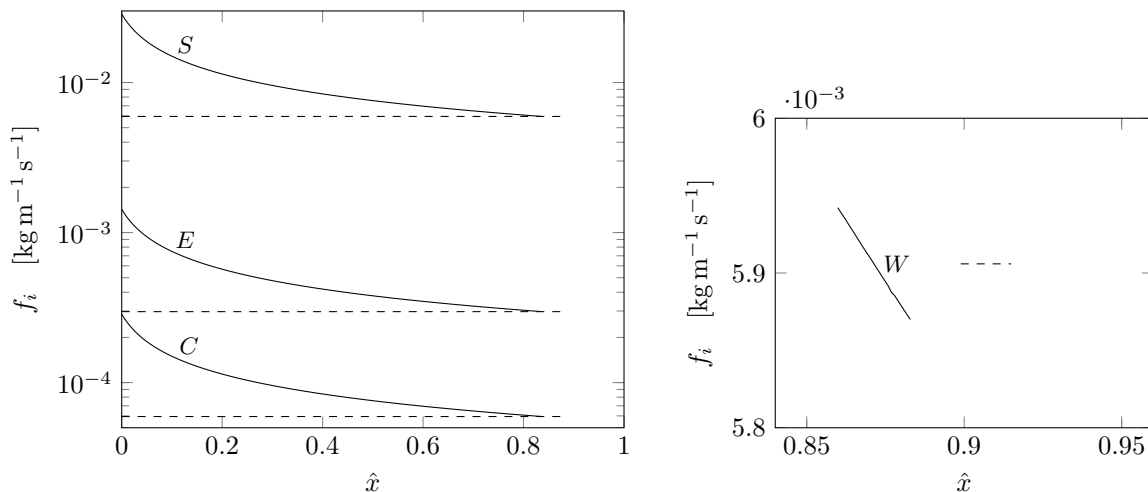


Figure 10: Side feed flowrate along the dimensionless axial coordinate according to the rigorous (solid line) and the constant feed (dashed line) method for the diol synthesis. Species S , E and C on the left, W on the right (enlargement).

between these two side feed policies, they lead to quite different results in terms of tubular reactor performances: at constant side feed flowrates, about 40 % less productivity is established than implementing the rigorous side feed flowrates. Furthermore, the final conversion is also reduced, by about 5%. This means that the product quality from the constant feed tubular reactor is no more guaranteed to be the same as in the SBR plant. These results agree with the conclusions of the parametric analysis: since the rigorous solution is the only one that guarantees overlapping SBR and tubular reactor species profiles, the two reactor configurations show the same performances only in this case.

5. Conclusions

An approach for the transformation of isothermal homogeneous semi-batch processes into continuous ones was proposed and verified in the case of tubular reactors with distributed side injections. The key advantage of the proposed approach is that it does not require any kinetic information once the SBR recipe and some density measurements on an existing industrial plant are available. This procedure is optimal since it allows the exact reproduction of the original SBR performances. Of course, when available, kinetic information allow optimizing the reaction recipe whatever is the reactor type. However, since our primary focus is the transfer of a previously assessed recipe from SBR to the continuous tubular reactor, giving up the kinetic information becomes a major benefit.

Two case studies were analysed, a copolymer synthesis and the production of a fine chemical. In both cases, the tubular reactor ensures the same product composition and final conversion of the semi-batch

process. Moreover, the reaction performances when applying these side feed policies have been compared with those achieved when using simpler and more intuitive feed policies, showing relevant differences.

Finally, it is worth mentioning that this tubular reactor enables scaling of productivity either changing the inlet flowrate or the cross sectional area. Being these two variables related to each other by well known design constraints, they act as a degree of freedom for the process design.

Acknowledgements

Financial support of Innovhub for one of us (FF) is gratefully acknowledged.

Nomenclature

\mathcal{A}	PFR cross sectional area [m ²]
a	Auxiliary variable [-]
b	Auxiliary variable [-]
c_i	i -th species molar concentration [kmol m ⁻³]
F	SBR total feedrate [kg s ⁻¹]
F_i	SBR i -th species feedrate [kg s ⁻¹]
f	PFR total distributed feedrate [kg s ⁻¹ m ⁻¹]
f_i	PFR i -th species distributed feedrate [kg s ⁻¹ m ⁻¹]
g_i	PFR i -th species discretised feedrate [kg s ⁻¹]
K	PFR dimensionless length [-]
k	Reaction rate constant
k_d	Dissociation rate constant [s ⁻¹]
\tilde{k}_d	Decay rate [s ⁻¹]
k_p	Propagation rate constant [m ³ kmol ⁻¹ s ⁻¹]
k_t	Termination rate constant [m ³ kmol ⁻¹ s ⁻¹]
L	PFR length [m]
m	SBR total mass [kg]
m_i	SBR i -th species mass [kg]
\dot{N}_i	SBR i -th species molar feedrate [kmol s ⁻¹]

n_i	SBR i -th species molar quantity [kmol]
MW_i	i -th species molecular weight [kg kmol ⁻¹]
NC	Number of components (species) [-]
Q	PFR total flowrate [kg s ⁻¹]
Q_i	PFR i -th species flowrate [kg s ⁻¹]
R_i	i -th species molar production rate [kmol m ⁻³ s ⁻¹]
r	Molar reaction rate [kmol m ⁻³ s ⁻¹]
r_i	i -th species reactivity ratio [-]
T	Temperature [K]
t	Time [s]
t_{proc}	Overall process time [s]
V	SBR volume [m ³]
v	Velocity [m s ⁻¹]
W_i	i -th species overall mass [kg]
X_i	i -th species monomeric molar fraction [-]
x	PFR axial coordinate [m]

Greek symbols

δ	Monomer fraction to be fed [-]
$\hat{\gamma}_i$	Auxiliary variable [-]
ϕ_i	i -th species desired molar fraction in copolymer [-]
ϕ_i^w	i -th species desired mass fraction in copolymer [-]
$\dot{\Omega}_i$	i -th species massive production rate [kg m ⁻³ s ⁻¹]
ω_i	PFR i -th species mass fraction [-]
ω_i^*	SBR i -th species mass fraction [-]
ρ	Density in the PFR [kg m ⁻³]
ρ^*	Density in th SBR [kg m ⁻³]
τ	Residence time [s]

θ Elapsed time [s]

Other symbols

0 Initial value (subscript)

(k) Diol synthesis reactor section (superscript)

$\hat{\cdot}$ Dimensionless quantity

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