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Optimal Shale Gas Flowback Water Desalination under Correlated Data Uncertainty

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Presentation overview

What is we going to present here?





Stochastic multiscenario model

Mathematical model & Scenarios generation



Shale gas wastewater desalination

Conclussions

Conclusions











Introduction



- Shale gas hydraulic fracturing demands large amounts of water, on average 9000-29000 m3 of water to complete each well (Yang el al. 2014). (10% used in drilling and 90% in hydraulic fracturing).
- A fraction of the water used for drilling and hydraulic fracture return to the surface (between 10% and 70%) with typical values around 35%.
- Consequently, high volumes of wastewater from shale gas well pads are generated. As an example, a production forecast for the Marcellus play suggests that Pennsylvania will generate over half billion cubic feet per year by 2025 (*Gay et al. 2012*)
- Most of the water returns to the surface in the first two weeks -flowback water- then it tends to stabilize and continues producing water during the whole life of the well -produced water-.
- The flowback water include part of the additives included in the hydraulic fracturing fluid: Proppant (sand);
 Friction reducers; surfactants, scale inhibitors, Biocide, etc. And other compounds depending on the geological characteristics of the shale.











Union's Horizon 2020 research and innov

Typical range of concentrations for some common constituents of flowback/produced water from natural gas development in the Marcellus shale.

(Data compiled by Elise Barbot, University of Pittsburgh, and Juan Peng, Carnegie Mellon University.)

Constituent	Low (mg/l)	Medium (mg/l)	High (mg/l)	
Total dissolved solids	66000	150000	261000	
Total suspended solids	27	380	3200	
Hardness (as CaCO ₃)	9100	29000	55000	
Alkalinity (as CaCO ₃)	200	200	1100	
Chloride	32000	76000	148000	
Sulfate	Not Detected	7	500	
Sodium	18000	33000	44000	
Calcium, total	3000	9800	31000	
Strontium, total	1400	2100	6800	
Barium, total	2300	3300	4700	
Bromide	720	1200	1600	
Iron, total	25	48	55	
Manganese, total	3	7	7	
Oil and grease	10	18	260	
Total radioactivity	Not Detected	Not Detected	Not Detected	

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Introduction



Salinity of the flowback waters from various shales expressed in terms of Total Dissolved Solids (TDS).

Shale	Average TDS, ppm	Maximum TDS, ppm
Fayetteville	13,000	20,000
Wooford	30,000	40,000
Barnett	80,000	> 150,000
Marcellus	120,000	> 280,000
Haynesville	110,000	> 200,000
Lebien	~ 16,000 - 70,000 *	
Lubocino	~ 17,000*	

* Estimated by correlation with other parameters.









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Introduction





Introduction



- To address these issues, we introduce a two stage stochastic model for the robust design of ZLD desalination systems under uncertainty
- In this new approach, wastewater salinity and flowrate are both treated as uncertain design parameters: The uncertainty is mainly related to the great variability presented in well data from real shale plays
- To the best of our knowledge, this is the first study assessing the impacts of data uncertainty on the optimal design of ZLD evaporation systems, specially developed for high-salinity shale gas wastewater
- Also, important improvements on the **MEE-MVC** process are implemented, including the use of an external energy source to avoid oversized equipment and the consideration of variable compressor efficiency that allows obtaining a more precise and robust operating performance









Problem statement



ZLD desalination under uncertainty

- Given is a high-salinity stream of shale gas wastewater, with known inlet state (described by temperature, and mean values for salt concentration and flowrate) and target condition defined by the ZLD specification
- Furthermore, desalination system and energy services (steam and electricity) are also provided with their corresponding costs
- Salt concentration and flowrate of the inlet water stream are both considered as uncertain design parameters that can be explicitly expressed through a set of correlated feeding scenarios with given probability of occurrence

The new stochastic modelling approach is aimed at obtaining a robust design of MEE-MVC desalination systems by reducing brine discharges and energy consumption, while accounting for different feeding scenarios. The MEE-MVC system should be able to efficiently operate at ZLD condition in a large range of correlated feeding scenarios









Process description



Superstructure



Figure 1. General superstructure proposed for the MEE-MVR desalination plant of wastewater from shale gas production









Two stage stochastic model Mathematical modelling approach



Sizing equations for all equipment 0

- Mass and energy balances 0
- Temperature and pressure feasibilities 0
- Design constraints (ZLD operation) 0
- **Objective function** 0

Index sets

 $I = \{i \mid i = 1, 2, ..., I \text{ is an evaporation effect}\}$ $S = \{s \mid s = 1, 2, ..., S \text{ is a feeding scenario}\}$

Decision variables

- First stage (here and now): sizing-related variables (e.g., volumes, and heat transfer areas)
- Second stage (wait and see): all remaining optimization variables







Figure 2. Decision variables for the optimization of: (*a*) single-stage compressor; and, (b) effect i of the horizontal falling film evaporator coupled to flashing tank i in the MEE-MVR system









Mathematical modelling approach

Design of the multiple-effect evaporator

1. Mass balances

Evaporator effect *i*:

 $\dot{m}_{i+1,s}^{brine} = \dot{m}_{i,s}^{brine} + \dot{m}_{i,s}^{vapor}$ $\forall 1 \leq i \leq I - 1, \ \forall s \in S$ $\dot{m}_{i+1,s}^{brine} \cdot S_{i+1,s}^{brine} = \dot{m}_{i,s}^{brine} \cdot S_{i,s}^{brine} \quad \forall 1 \le i \le I-1, \ \forall s \in S$

First effect:

$$\tilde{m}_{in,s}^{feed} = \dot{m}_{i,s}^{brine} + \dot{m}_{i,s}^{vapor} \qquad \forall i = I, \ \forall s \in S$$

$$\tilde{m}_{in,s}^{feed} \cdot \tilde{S}_{in,s}^{feed} = \dot{m}_{i,s}^{brine} \cdot S_{i,s}^{brine} \quad \forall i = I, \ \forall s \in S$$



are the stochastic parameters that define flowrate and salinity for the feed water in the set of distinct scenarios













Mathematical modelling approach

Design of the multiple-effect evaporator

2. Global energy balances

$$Q_{i,s} + \dot{m}_{i+1,s}^{brine} \cdot H_{i+1,s}^{brine} = \dot{m}_{i,s}^{brine} \cdot H_{i,s}^{brine} + \dot{m}_{i,s}^{vapor} \cdot H_{i,s}^{vapor} \quad \forall i < I, \ \forall s \in S$$

$$Q_{i,s} + \tilde{m}_{in,s}^{feed} \cdot H_{i,s}^{feed} = \dot{m}_{i,s}^{brine} \cdot H_{i,s}^{brine} + \dot{m}_{i,s}^{vapor} \cdot H_{i,s}^{vapor} \quad \forall i = I, \ \forall s \in S$$

specific enthalpies are estimated at the same boiling point temperature

3. Boiling point temperature

$$T_{i,s}^{boiling} = T_{i,s}^{ideal} + BPE_{i,s} \quad \forall i \in I, \ \forall s \in S$$
$$BPE_{i,s} = \begin{bmatrix} 0.1581 + 2.769 \cdot (X_{i,s}^{salt}) - 0.002676 \cdot (T_{i,s}^{ideal}) \\ + 41.78 (X_{i,s}^{salt})^{0.5} + 0.134 \cdot (X_{i,s}^{salt} \cdot T_{i,s}^{ideal}) \end{bmatrix} \quad \forall i \in S$$

 $\in I, \forall s \in S$











Mathematical modelling approach

Design of the multiple-effect evaporator

4. Energy requirements

$$\begin{aligned} Q_{i,s} &= \dot{m}_{s}^{sup} \cdot Cp_{i,s}^{vapor} \cdot \left(T_{s}^{sup} - T_{i,s}^{condensate}\right) + \dot{m}_{s}^{sup} \cdot \left(H_{i,s}^{cv} - H_{i,s}^{condensate}\right) + Q_{s}^{external} \quad \forall i = 1, \ \forall s \in S \\ Q_{i,s} &= \left(\dot{m}_{i-1,s}^{vapor} + \dot{m}_{c_{i-1,s}}^{vapor}\right) \cdot \lambda_{i,s} \quad \forall i > 1, \ \forall s \in S \end{aligned}$$

In which,

$$Q_{s}^{external} = \dot{m}_{s}^{steam} \cdot Cp_{s}^{vapor} \cdot \left(T_{s}^{steam} - T_{i,s}^{condensate}\right) + \dot{m}_{s}^{steam} \cdot \left(H_{i,s}^{cv} - H_{i,s}^{condensate}\right) \qquad \forall i = 1, \ \forall s \in S$$

energy amount from the external source (steam) used to avoid oversized equipment











Mathematical modelling approach

Design of the multiple-effect evaporator

5. Heat transfer area

$$A^{evaporator} = \sum_{i=1}^{I} A_i$$

In which,

Overall heat transfer coefficient:

$$U_{i,s} = 0.001 \cdot \begin{bmatrix} 1939.4 + 1.40562 \cdot (T_{i,s}^{boiling}) \\ -0.00207525 \cdot (T_{i,s}^{boiling})^2 + 0.0023186 \cdot (T_{i,s}^{boiling})^3 \end{bmatrix} \quad \forall i > 1, \ \forall s \in S$$

Log mean temperature difference :

$$\begin{split} A_{i} \geq & \left[\frac{\dot{m}_{s}^{sup} \cdot Cp_{i,s}^{vapor} \cdot \left(T_{s}^{sup} - T_{i,s}^{condensate}\right) / \left(U^{s} \cdot LMTD_{i,s}\right)}{+ \dot{m}_{s}^{sup} \cdot \left(H_{i,s}^{cv} - H_{i,s}^{condensate}\right) / U_{i,s} \cdot \left(T_{i,s}^{condensate} - T_{i,s}^{boiling}\right) \right]} \quad \forall i = 1, \ \forall s \in S \end{split} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ A_{i} \geq Q_{i,s} / \left(U_{i,s} \cdot LMTD_{i,s}\right) & \forall i > 1, \ \forall s \in S \\ A_{i} \geq Q_{i,s} / \left(U_{i,s} \cdot LMTD_{i,s}\right) & \forall i > 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ A_{i} \geq Q_{i,s} / \left(U_{i,s} \cdot LMTD_{i,s}\right) & \forall i > 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ B_{1i,s} = \begin{bmatrix} T_{i,s}^{sup} - T_{i,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ T_{i,s}^{sup} - T_{i,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} A_{i} \geq Q_{i,s} / \left(U_{i,s} \cdot LMTD_{i,s}\right) & \forall i > 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ B_{2i,s} = \begin{bmatrix} T_{i,s}^{condensate} - T_{i+1,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ T_{i,s}^{sup} - T_{i+1,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} A_{i} \geq Q_{i,s} / \left(U_{i,s} \cdot LMTD_{i,s}\right) & \forall i > 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ B_{2i,s} = \begin{bmatrix} T_{i,s}^{condensate} - T_{i+1,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ T_{i,s}^{sup} - T_{i+1,s}^{boiling} & \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{bmatrix} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{bmatrix} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{bmatrix} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{l} \forall i = 1, \ \forall s \in S \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array}$$











Mathematical modelling approach

Design of the multiple-effect evaporator

6. Pressure feasibility

$$P_{i,s}^{vapor} \ge P_{i+1,s}^{vapor} + \Delta P_{\min} \quad \forall i < I, \ \forall s \in S$$

7. Constraints on temperature

$$\begin{split} T_{s}^{sup} \geq T_{i,s}^{condensate} + \Delta T_{\min}^{1} & \forall i = 1, \ \forall s \in S \\ T_{i-1,s}^{boiling} \geq T_{i,s}^{condensate} + \Delta T_{\min}^{1} & \forall i > 1, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i+1,s}^{condensate} + \Delta T_{\min}^{1} & \forall i > 1, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i+1,s}^{boiling} + \Delta T_{\min}^{2} & \forall i < I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i+1,s}^{feed} + \Delta T_{\min}^{2} & \forall i < I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i < I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i = I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i = I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i = I, \ \forall s \in S \\ T_{i,s}^{sat} \geq T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i = I, \ \forall s \in S \\ T_{i,s}^{sat} \geq T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i = I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{feed} + \Delta T_{\min}^{2} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} \geq T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in S \\ T_{i,s}^{boiling} + \Delta T_{i,s}^{boiling} + \Delta T_{\min}^{4} & \forall i \in I, \ \forall s \in$$









Mathematical modelling approach

Design of the mechanical vapor compressor

1. Isentropic temperature

$$T_{s}^{is} = \left(T_{i,s}^{mix} + 273.15\right) \cdot \left(P_{s}^{sup} / P_{i,s}^{vapor}\right)^{\frac{\gamma-1}{\gamma}} - 273.15 \qquad \forall i = I, \ \forall s \in S$$

In which,

$$P_s^{sup} \leq CR_{\max} \cdot P_{i,s}^{vapor} \qquad \forall i = I \ , \ \forall s \in S$$

2. Superheated vapor temperature

$$T_{s}^{sup} = T_{i,s}^{mix} + \frac{1}{\eta_{s}} \cdot \left(T_{s}^{is} - T_{i,s}^{mix}\right) \qquad \forall i = I, \ \forall s \in S$$

isentropic efficiency



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3. Isentropic efficiency

$$\eta_s = \left(0.35/0.8\right) \cdot \left(\frac{W_s}{WC} - 0.2\right) + 0.5 \quad \forall s \in S$$

In which,

 $WC \ge W_s \quad \forall s \in S$

These equations are valid for:

 $0.2 \leq \frac{W_s}{WC} \leq 1$ $0.5 \le \eta_s \le 0.85$



Mathematical modelling approach











Mathematical modelling approach

Design of the mechanical vapor compressor

4. Compression work

$$W_{s} = \dot{m}_{s}^{sup} \cdot \left(H_{s}^{sup} - H_{i,s}^{vapor}\right) \qquad \forall i = I, \ \forall s \in S$$

5. Constraints on temperature and pressure

 $T_{s}^{sup} \geq T_{i,s}^{mix} \qquad \forall i = I, \ \forall s \in S$ $P_{s}^{sup} \geq P_{i,s}^{vapor} \qquad \forall i = I, \ \forall s \in S$









Mathematical modelling approach

Design specification for ZLD operation

ZLD operation is ensured by the following constraint:

 $S_{i,s}^{brine} \ge S^{design} \qquad \forall i = 1, \ \forall s \in S$

In this case,

 $S^{design} = 300 g kg^{-1} TDS$



The inclusion of this constraint in the model restricts the search space to solutions that meet a minimum salinity requirement for the bine (*i.e.*, brine salinity close to salt saturation conditions)

Lower costs are expected for weaker brine salinity restrictions











Two stage stochastic model Mathematical modelling approach

Stochastic objective function

The stochastic objective function for the minimization of the expected total annualized cost is given by:

min
$$TAC^{Exp} = \sum_{s \in S} (prob_s) \cdot TAC_s = \sum_{s \in S} (prob_s) \cdot (CAPEX + OPEX_s)$$

s.t. all equality and inequality constraints

In which, the distributions of capital investment and operational costs are given by:

$$CAPEX = fac \cdot \left(\frac{CEPCI^{2015}}{CEPCI^{2003}}\right) \cdot \left[\begin{pmatrix} C_{PO} \cdot F_{BM} \cdot F_{P} \end{pmatrix}^{evaporator} + \begin{pmatrix} C_{PO} \cdot F_{BM} \cdot F_{P} \end{pmatrix}^{compressor} + \\ \left(\sum_{i=1}^{I} C_{POi} \cdot F_{BM} \cdot F_{P} \right)^{flash} + \left(C_{PO} \cdot F_{BM} \cdot F_{P} \right)^{preheater} \right]$$

$$OPEX_{s} = C^{electricity} \cdot W_{s} + C^{steam} \cdot Q_{s}^{external}$$

Observations:

- The resulting formulation was implemented in GAMS (version 24.8.5) and solved with the interior-point local solver IPOPT (with CPLEX sub-solver)
- The CPU time for stochastic optimizations did not exceed 60 s
- The MEE-MVR system should operate at low temperatures and pressures to avoid rusting













Scenarios generation



Days following hydraulic fracturing









Case study

Shale gas wastewater desalination



Water recycling or safe discharge



Figure 4. Wastewater management alternatives for shale gas industry









Shale gas wastewater desalination



Table 1. Problem data for the case study regarding the optimal design of MEE-MVR desalination systems under well data uncertainty

Feed water	Expected mean value for mass flowrate, (kg s ⁻¹)	8.68	
	Temperature, (ºC)	25	
	Expected mean value for salinity, (g kg ⁻¹ or k ppm)	80	
Mechanical vapor compressor	Isentropic efficiency, (%)	50-85	Standard deviations:
	Heat capacity ratio	1.33	5, 10 and 20 %
	Maximum compression ratio	3	
Process specification and restrictions	Brine salinity for ZLD operation, (g kg ⁻¹ or k ppm)	300	
	Maximum effect temperature, (°C)	100	Matrix correlation: –0.7
	Maximum effect pressure, (kPa)	200	
Cost data	Electricity cost ^a , (US\$ (kW year) ⁻¹)	850.51	
	Steam cost, (US\$ (kW year) ⁻¹)	418.80	
	Fractional interest rate per year	0.1	
	Amortization period	10	
	Working hours per year	8760	

^a Cost data obtained from Eurostat database (European Commission, 2016)











Figure 5. Energy consumption distribution throughout the different feeding scenarios, obtained via stochastic approach with fixed equipment capacities as provided by the deterministic solution













Figure 6. Freshwater cost distribution throughout the different feeding scenarios, obtained via stochastic approach with fixed equipment capacities as provided by the deterministic solution











Figure 7. Distributions of freshwater production cost and produced freshwater obtained by the stochastic model throughout the distinct feeding scenarios























Overview



- A new stochastic multiscenario optimization model is introduced for the robust design of ZLD desalination systems under uncertainty
- Flowback water salinity and flowrate are both considered as uncertain design parameters
- These uncertain parameters are mathematically modelled as a set of correlated scenarios with given probability of occurrence
- The correlated scenarios are generated from a multivariate normal distribution via Monte Carlo sampling technique with a symmetric correlation matrix
- For ensuring the goal of ZLD operation in the uncertain space, we define the discharge brine salinity close to salt saturation condition as a design constraint for all feeding scenarios
- The resulting stochastic multiscenario NLP-based model is implemented in GAMS, and optimized by the minimization of the expected total annualized cost of the desalination process











Conclusions



- Comparative results between deterministic and stochastic (with fixed deterministic solution) approaches indicate that operational expenses can be prohibitive for some correlated scenarios
- This is because the ZLD process is not able to provide all system flexibility required against feeding variability conditions
- These results highlight the importance of the proposed stochastic model to optimize systems subjected to design parameters uncertainty
- Furthermore, cumulative probability curves show that higher standard deviations for uncertain parameters imply riskier decision-making
- This is a consequence of their increased probability of exceeding a target total annualized cost
- The results obtained can be used to support decision-makers towards the implementation of more robust and reliable ZLD desalination systems in the shale gas industry













Thank you for your attention!

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