

Lack of separation of scales

A view from reduced order modelling and homogenisation

Joint work with Pierre Kerfriden
Ahmad Akbari, Olivier Goury, Hussein Rappel
Paul Hauseux, Jack Hale





+

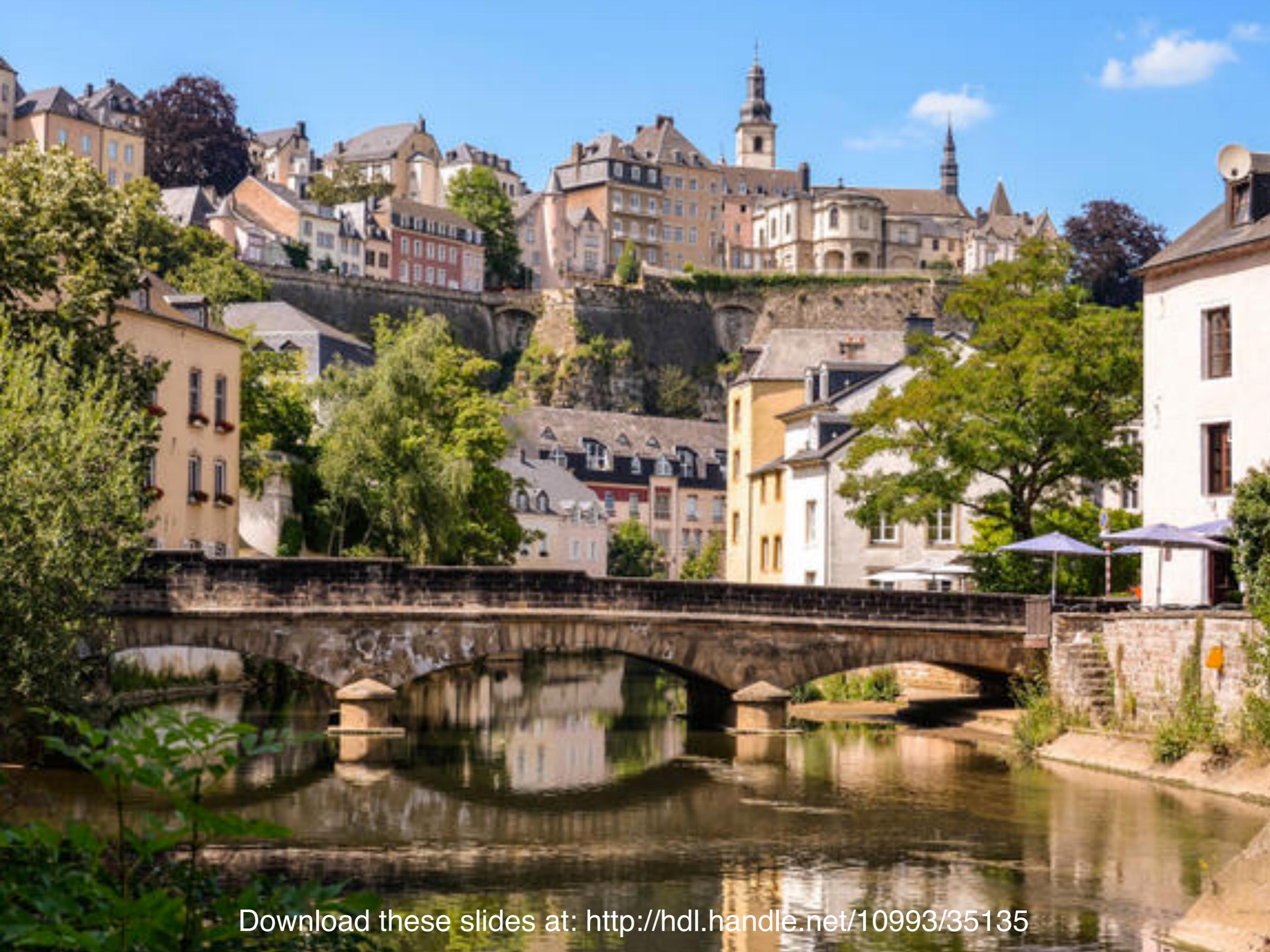


Computed in Luxembourg

Computational Sciences Luxembourg



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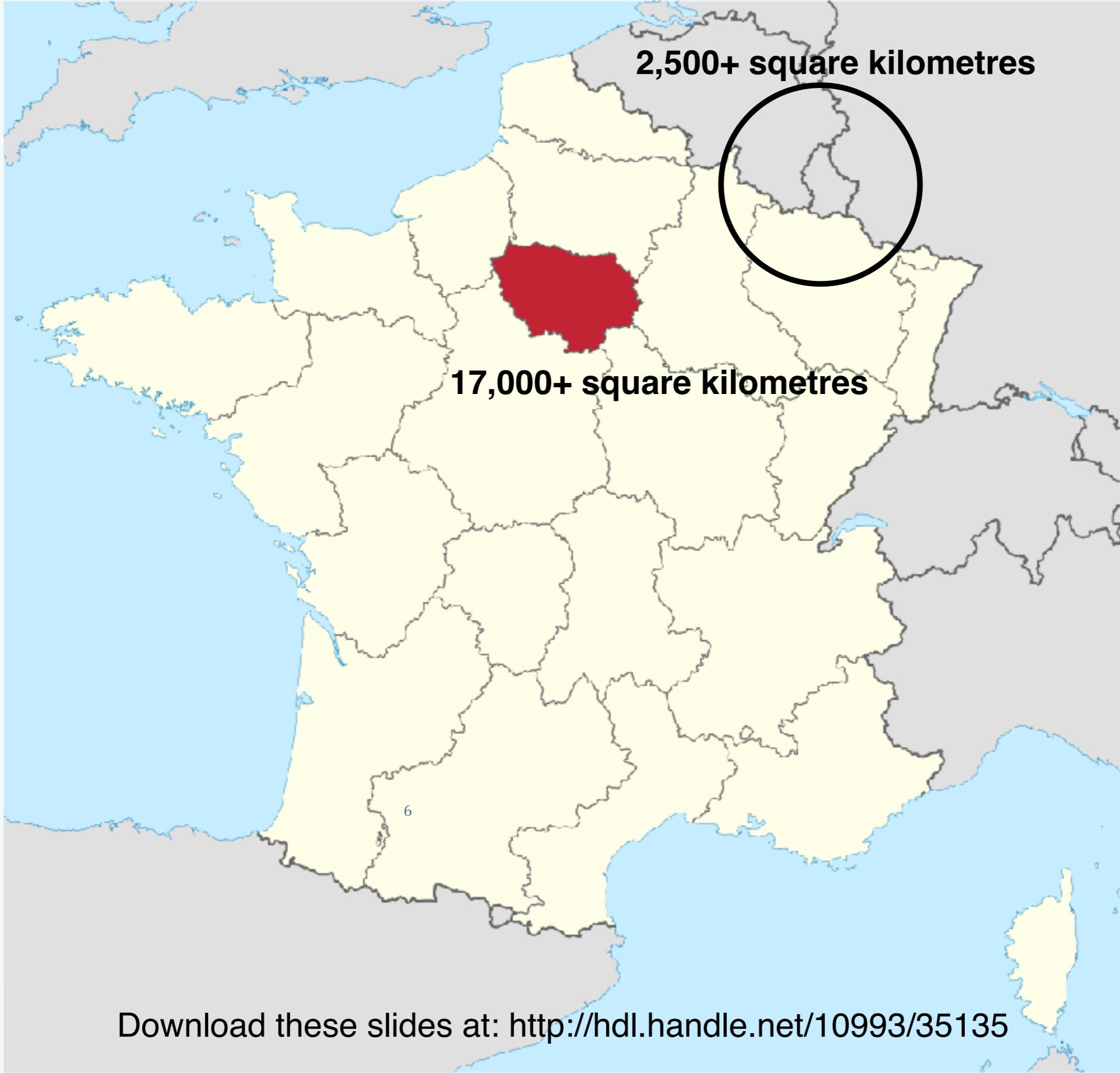
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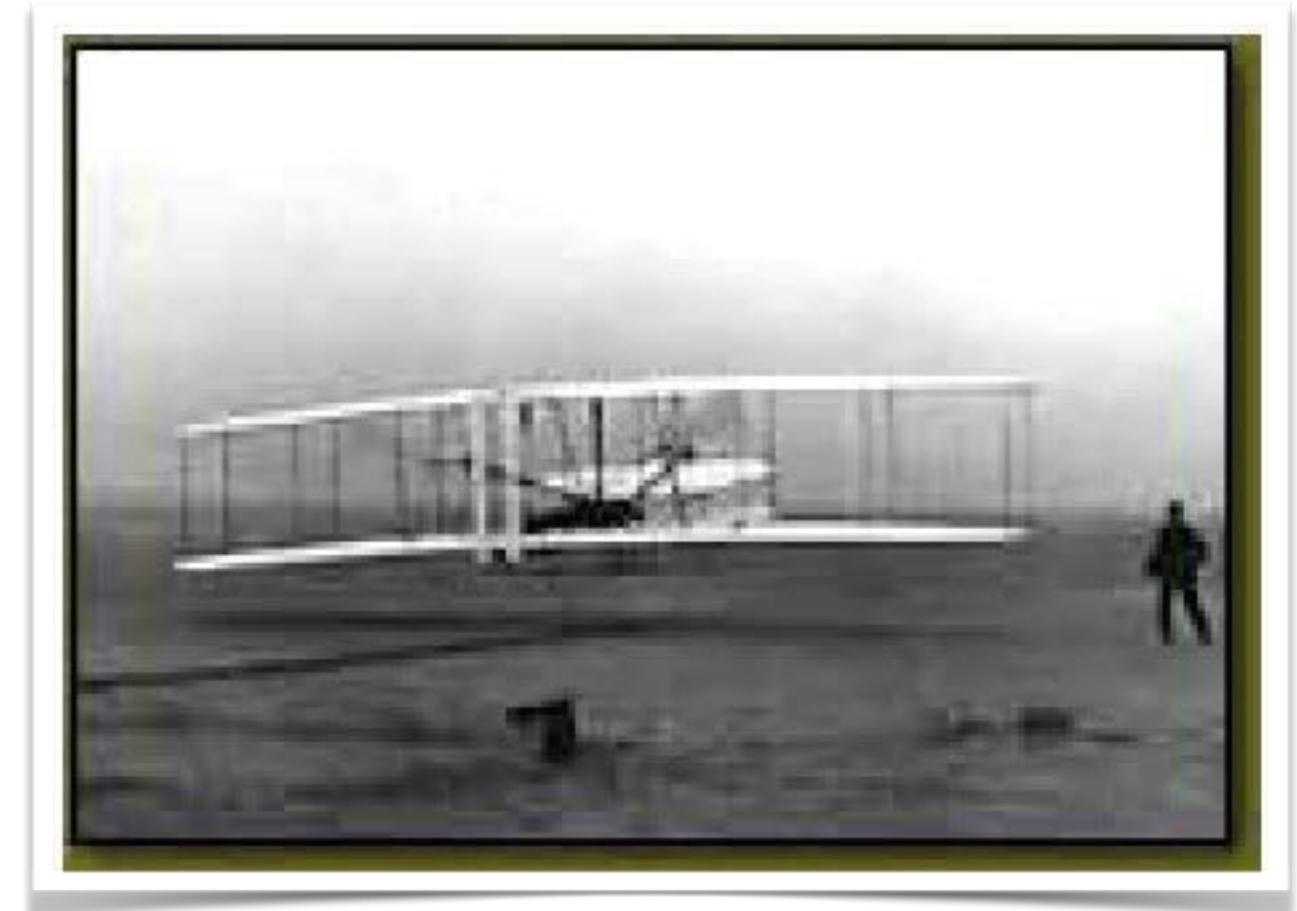


Download these slides at: <http://hdl.handle.net/10993/35135>

Wilbur and Orville Wright

Wright Flyer

10:35am Dec 17, 1903

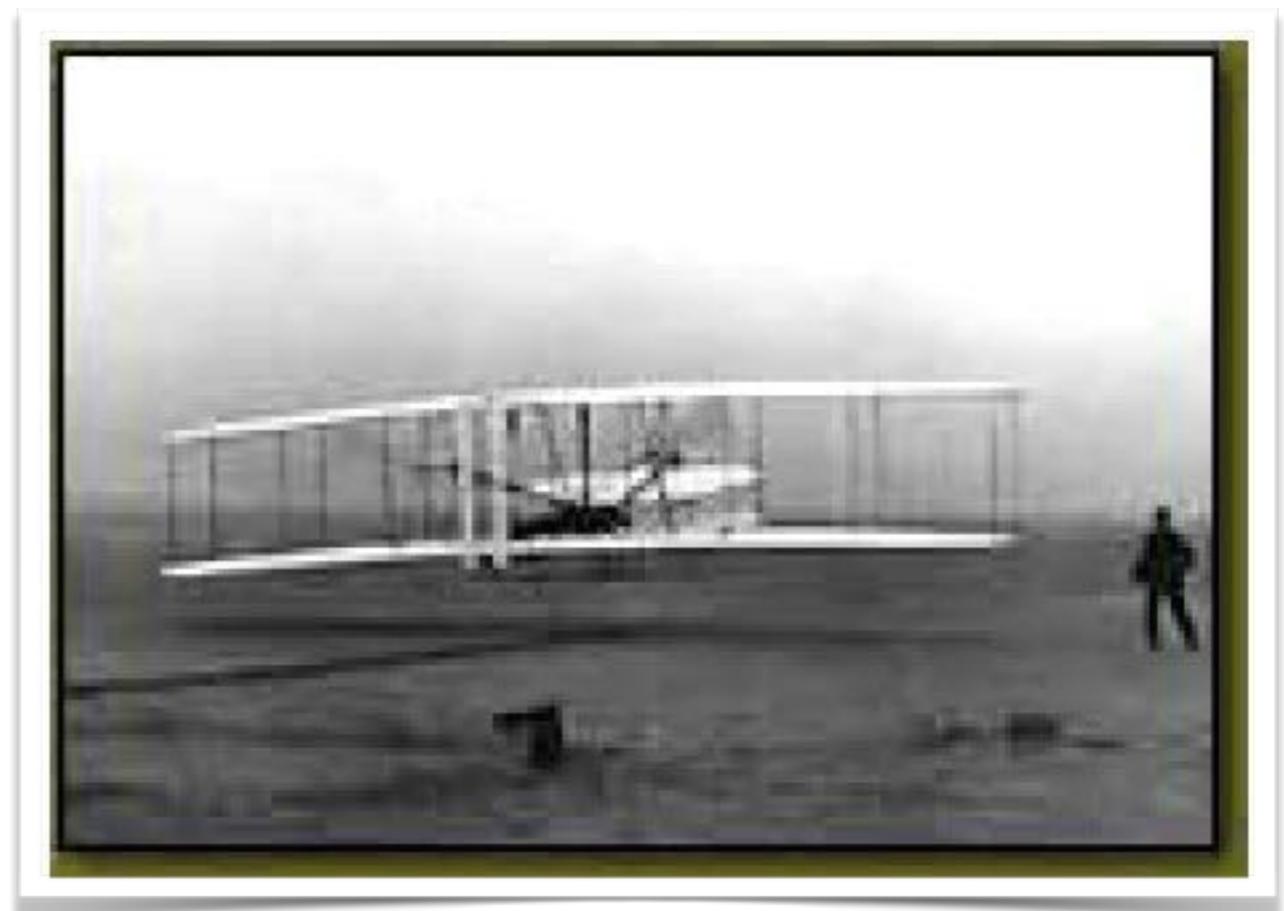


Wilbur and Orville Wright

On Dec 14 Wilbur won
the coin toss, made the
first attempt and stalled

Orville made the first
flight on Dec. 17

12 seconds & 120 ft



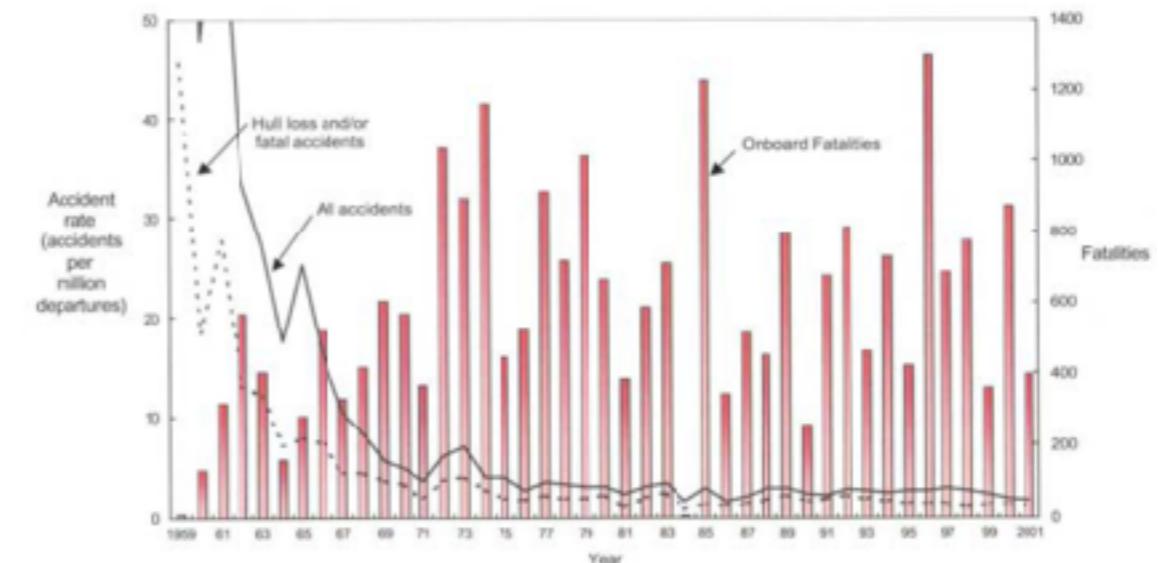
Aircraft safety

20,000 years



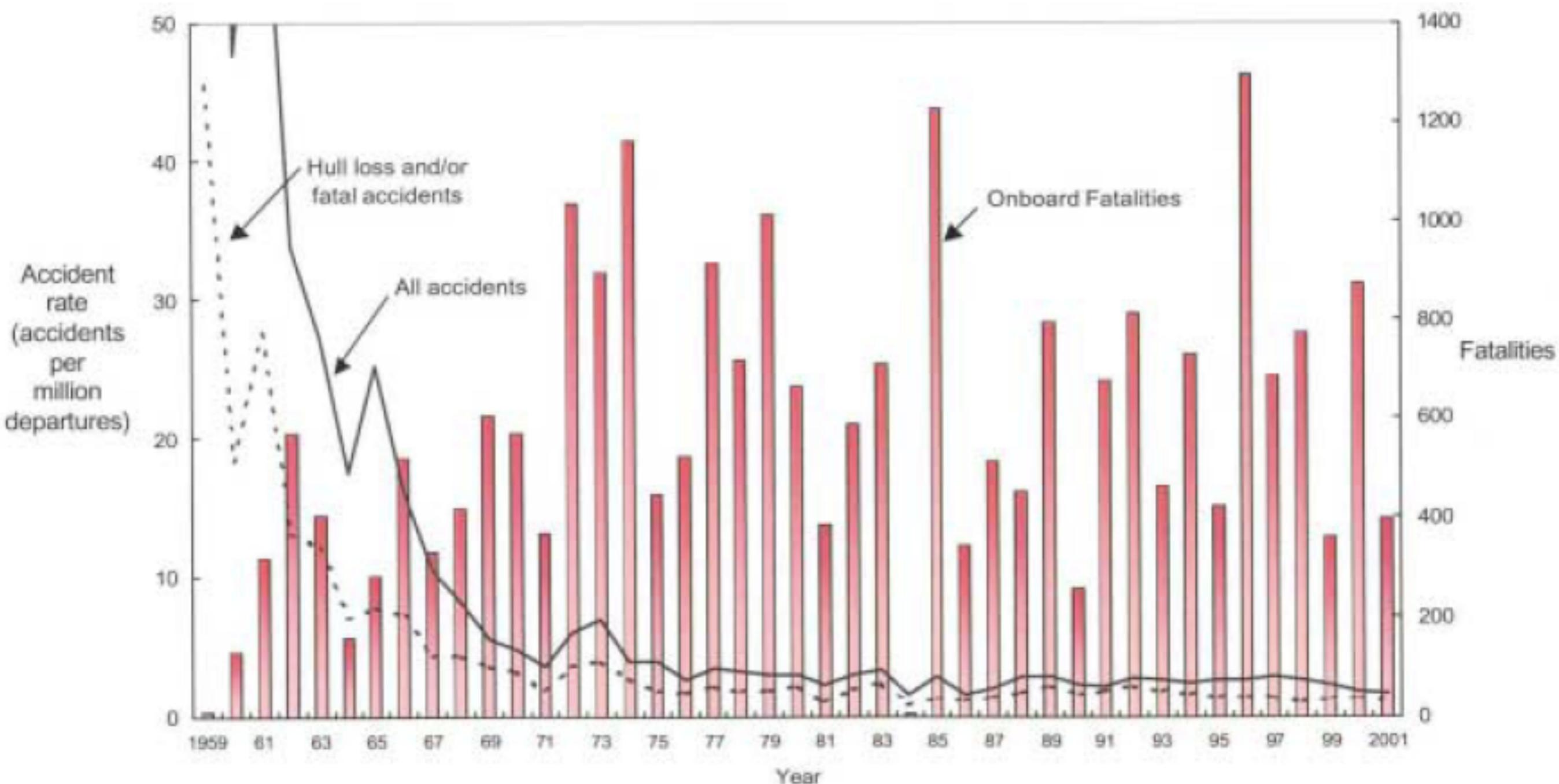
Worldwide statistics

[1959-2001] 1,307
commercial jet aircraft
losses

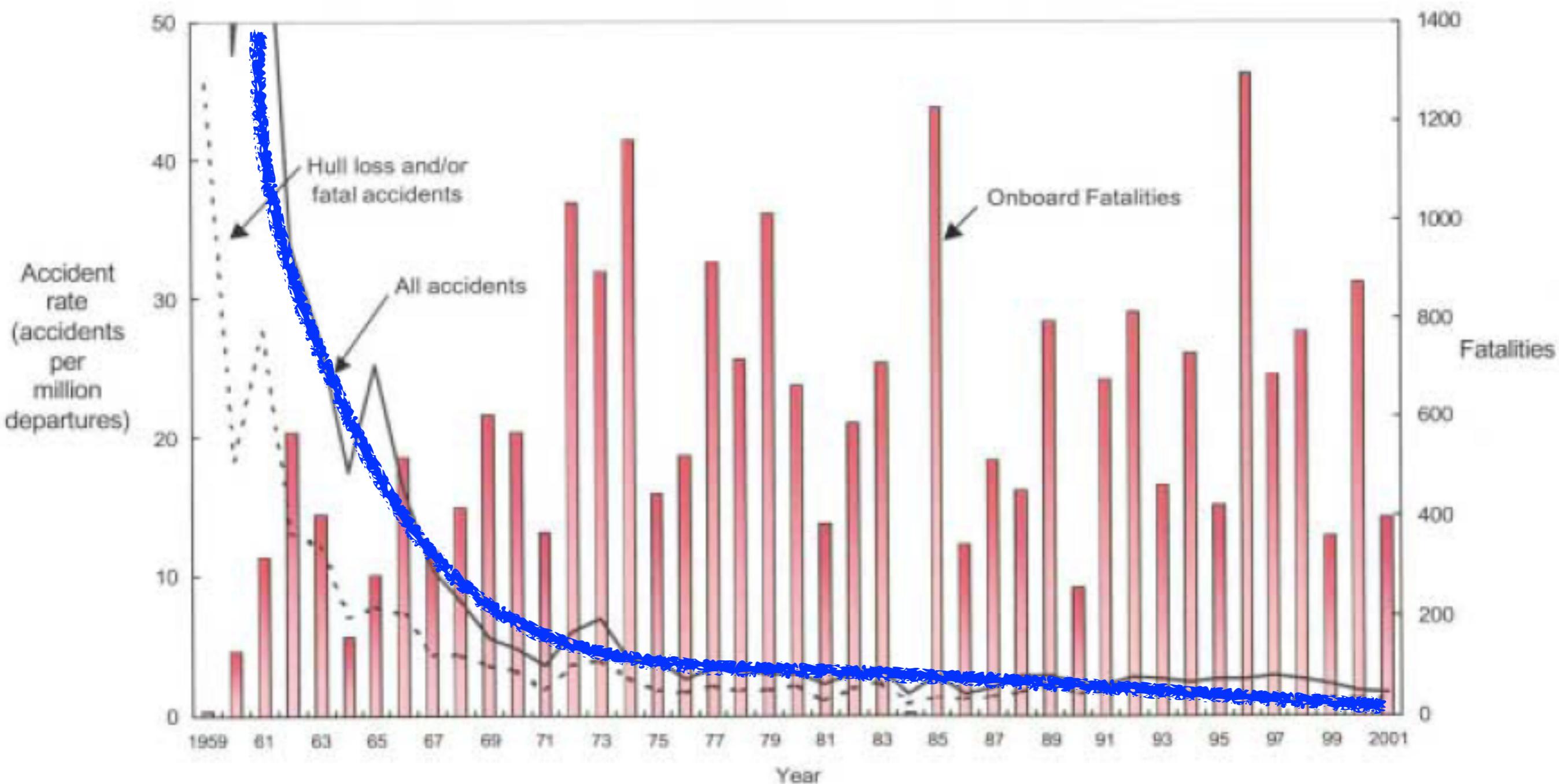


Today:
1 accident per
1,000,000
departures

Accident rates and fatalities/year

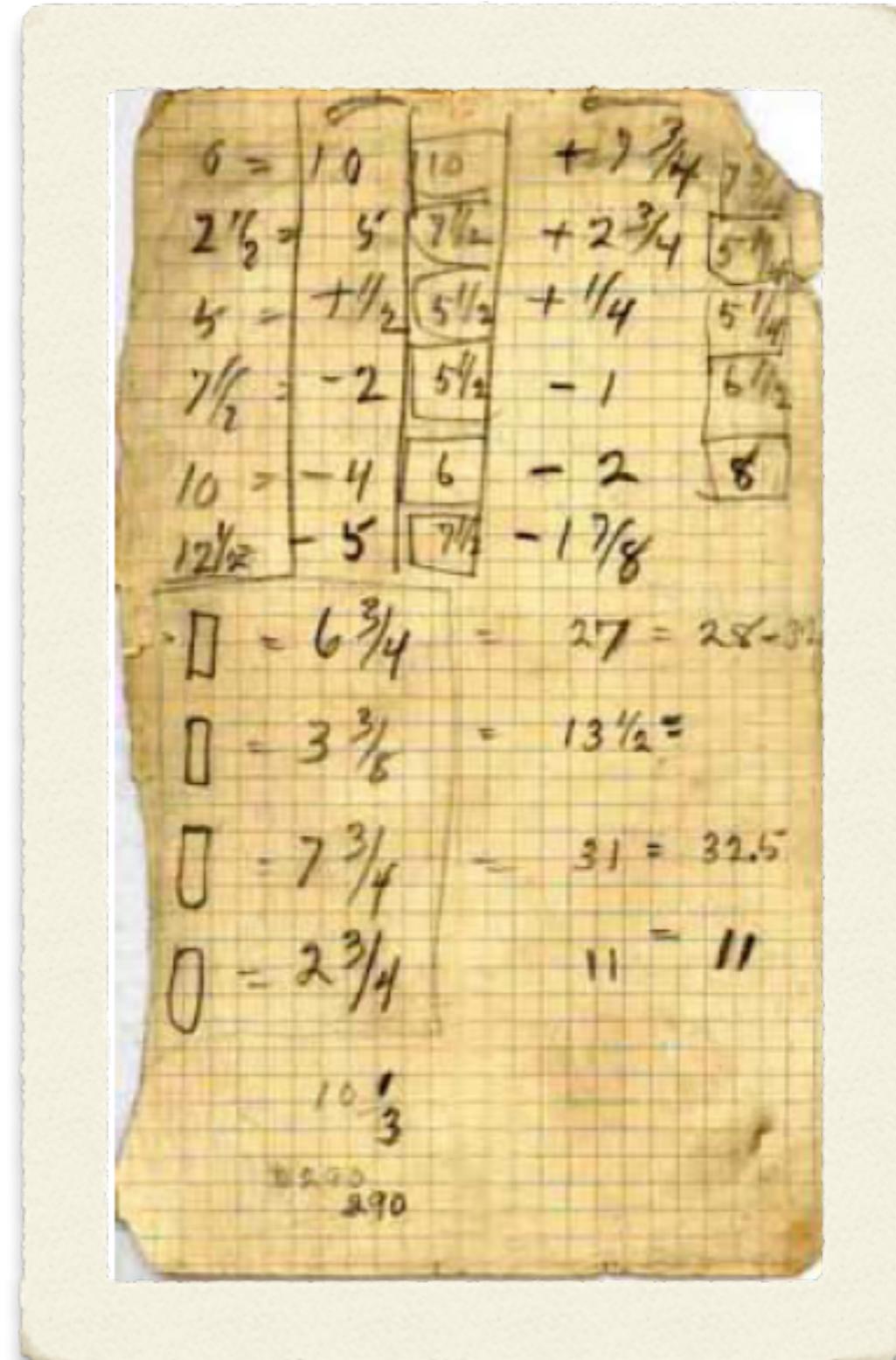
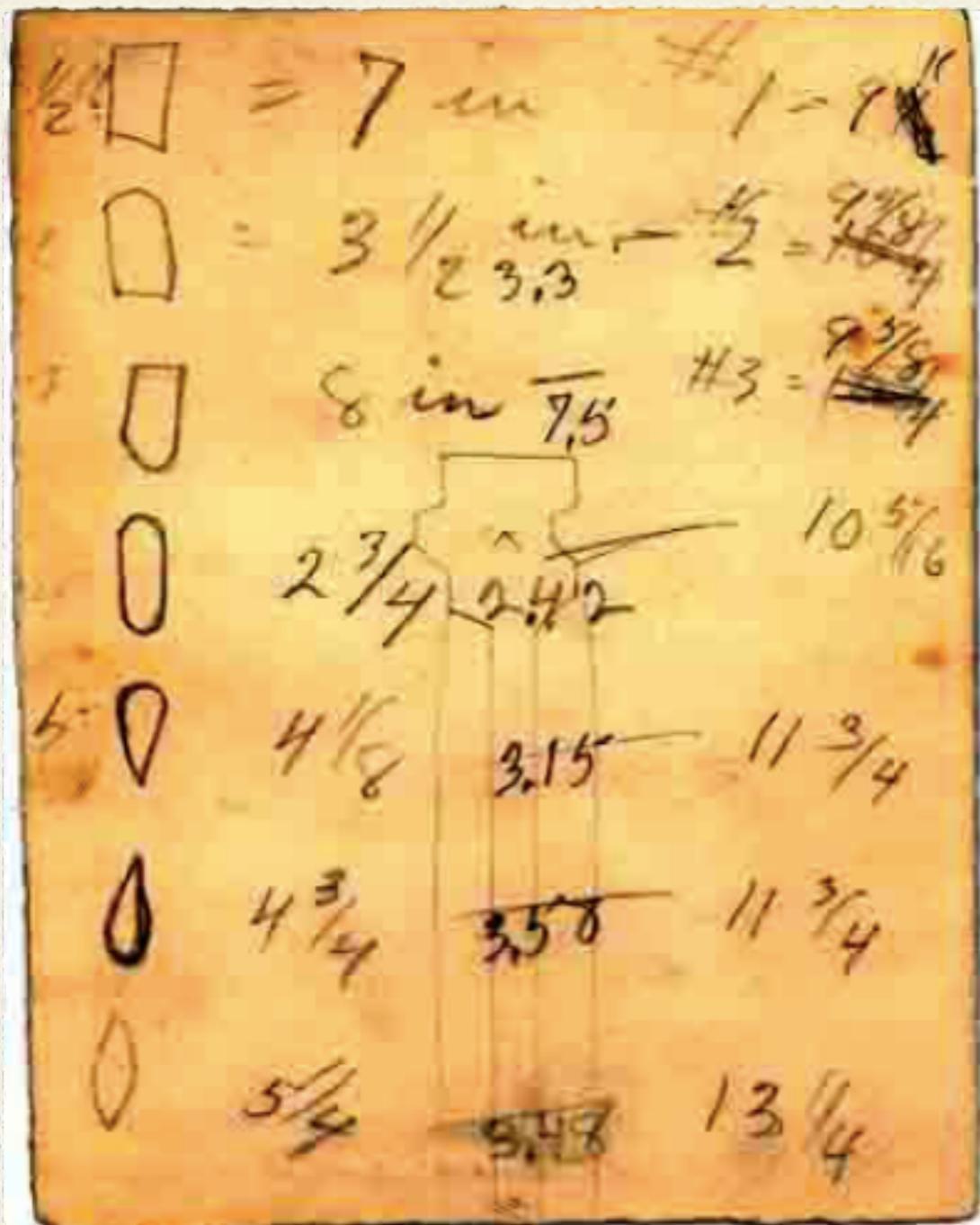


Accident rates and fatalities/year



Source: Flight Safety Foundation/Boeing Commercial Airplane Group

Learning from intuition & theory



Franklin Institute Science Museum. Wilbur Wright's handwriting

Learning from experience

Increased practical understanding of mechanics — in particular fracture and fatigue



Aloha airlines accident - fatigue cracks at corners

Novel convertible aircraft

Learning from experience

The Liberty Ships

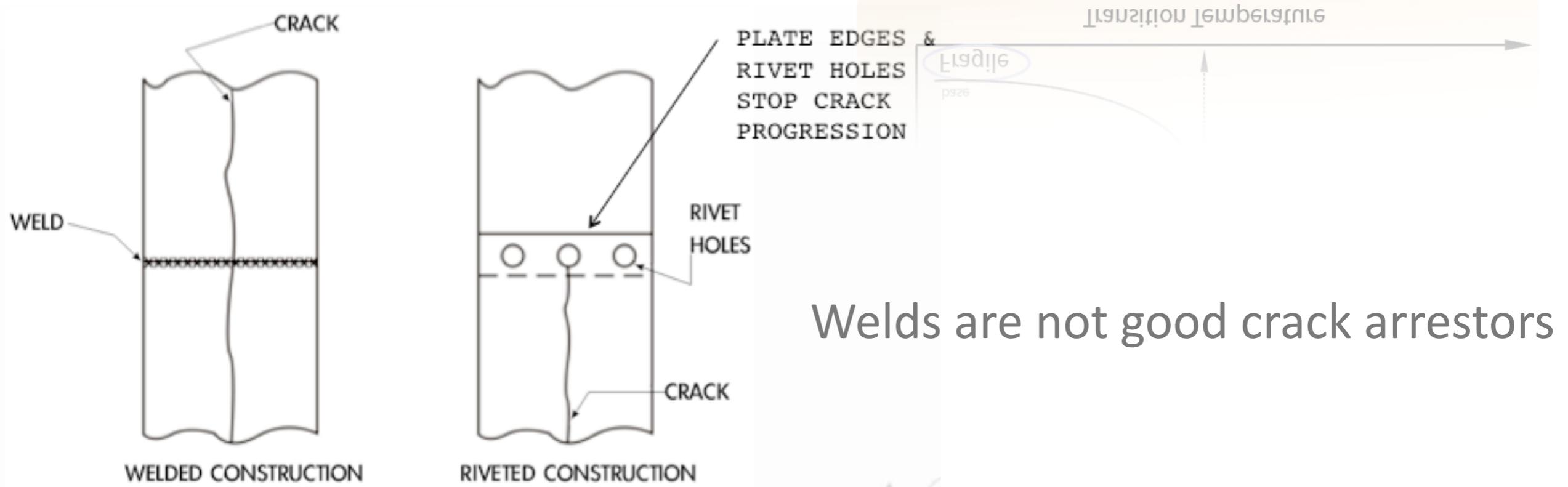
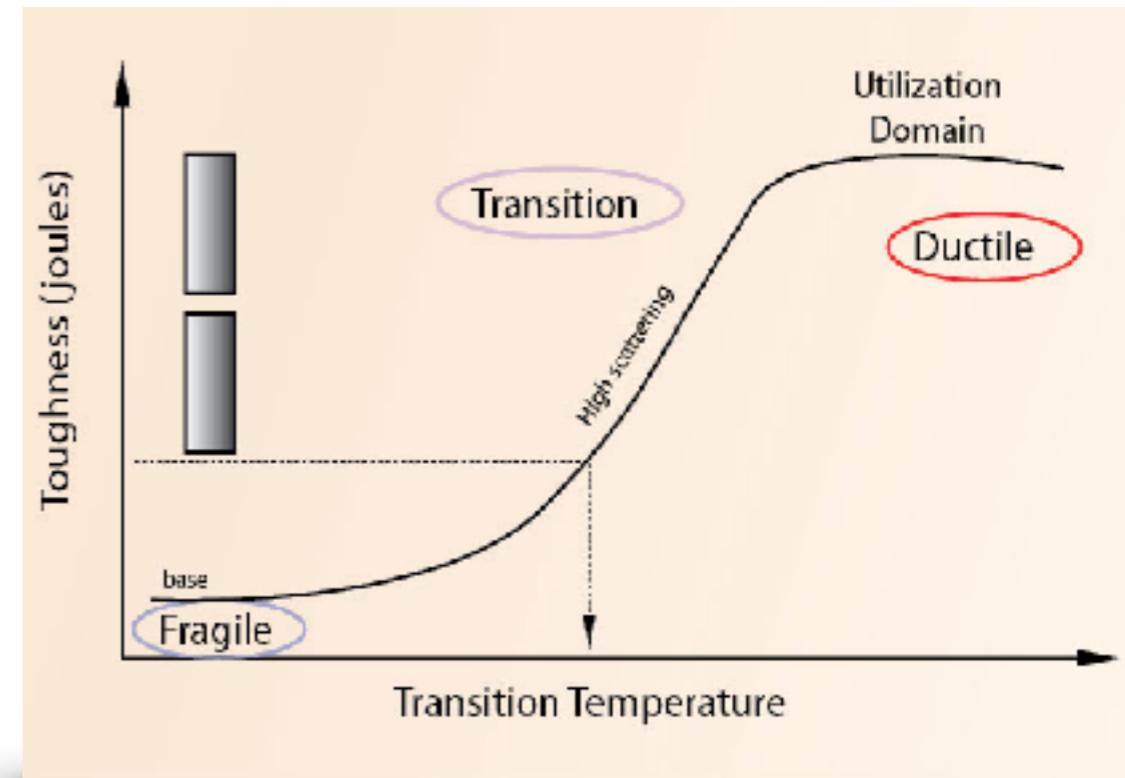


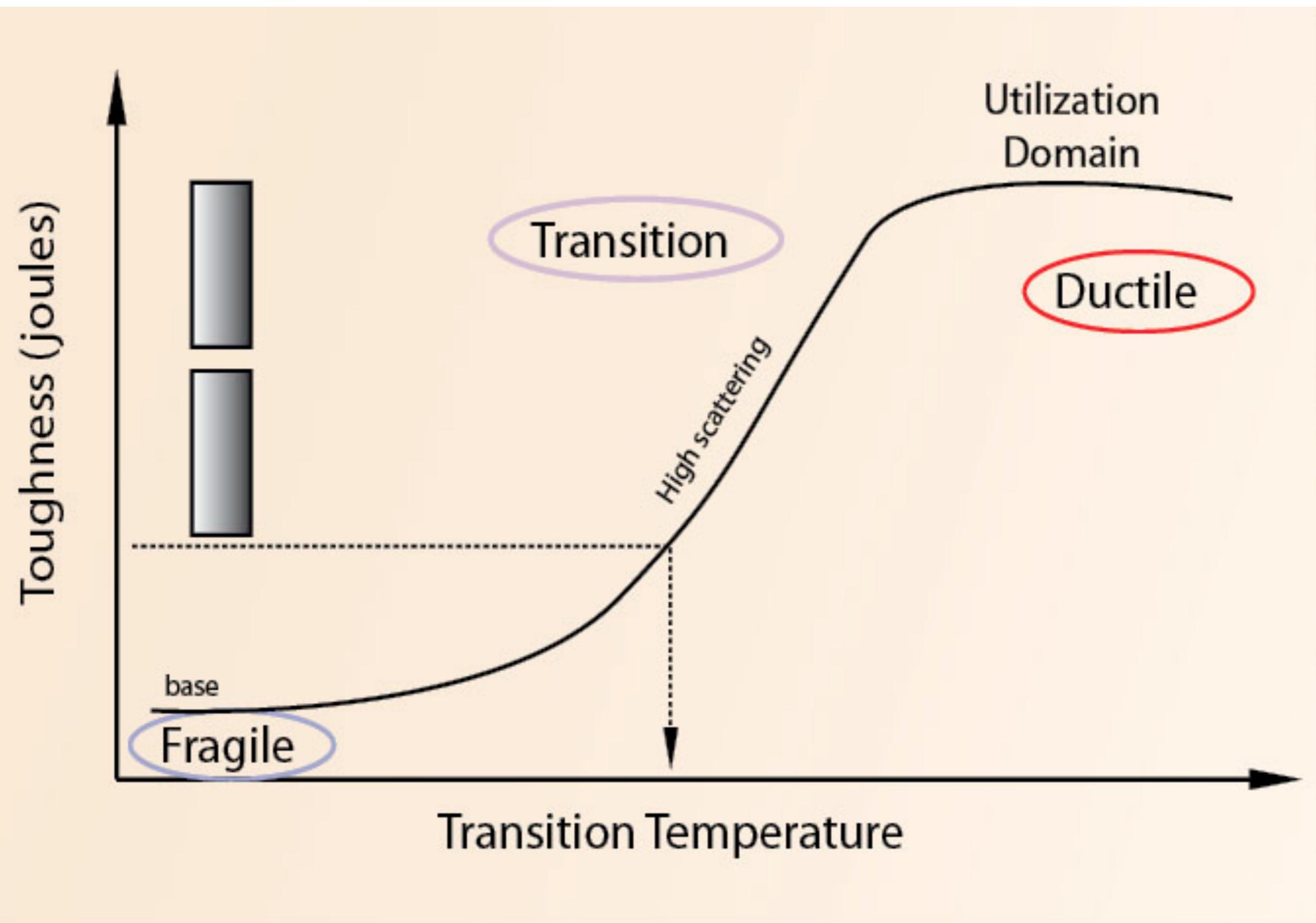
Source: www.libertyshipsamerica.org

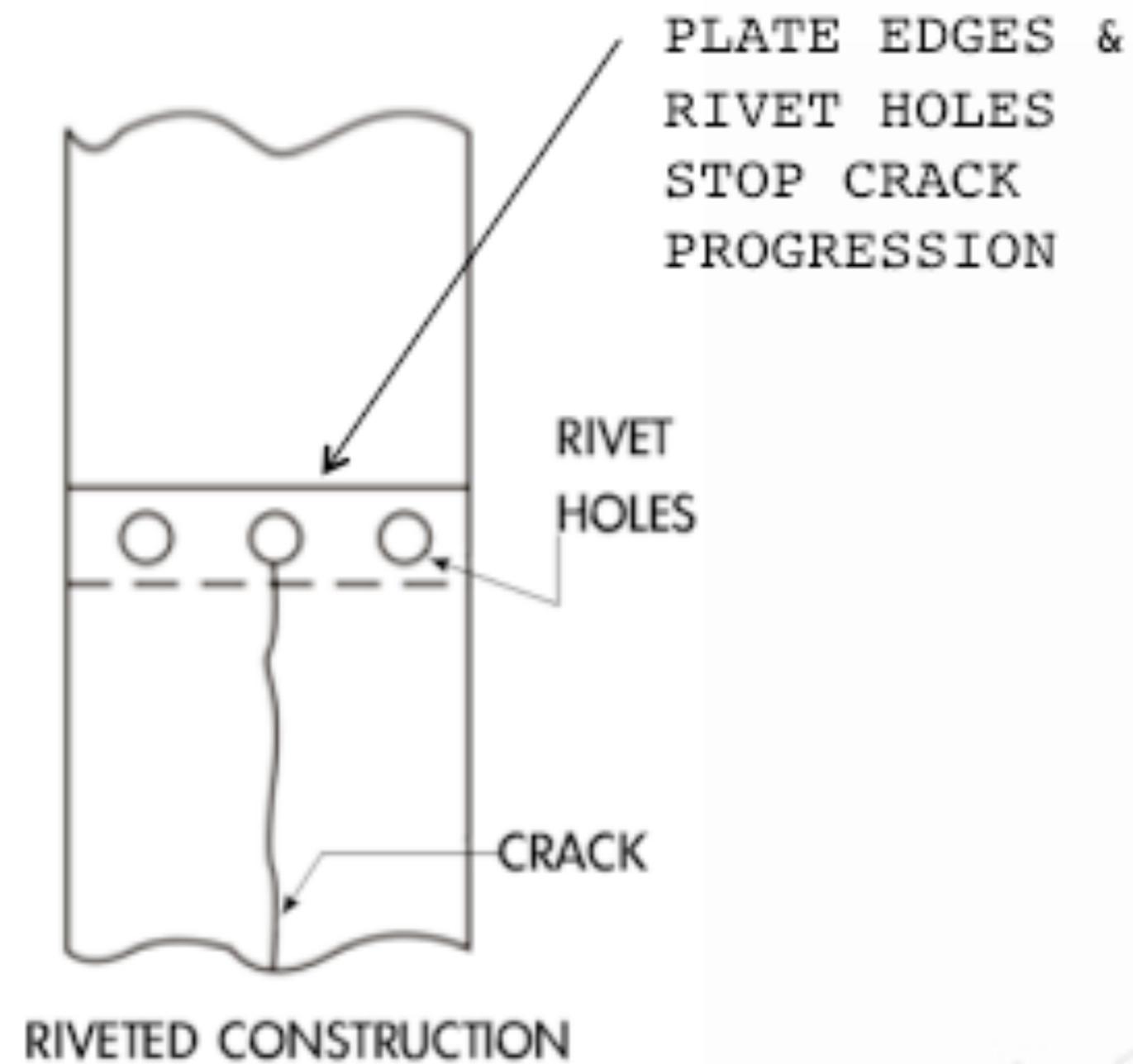
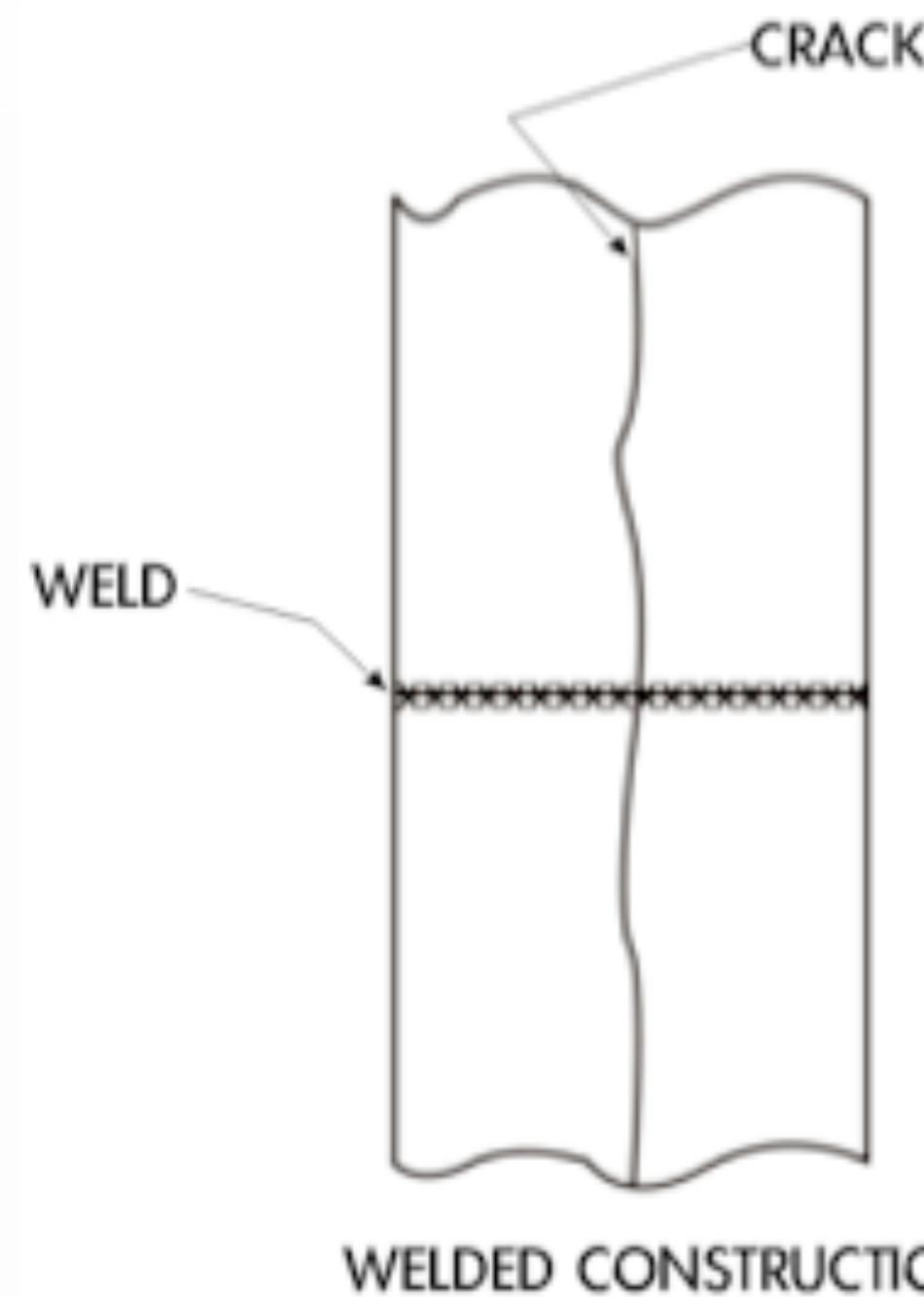


Learning from experience

At low temperatures,
steel becomes more
brittle

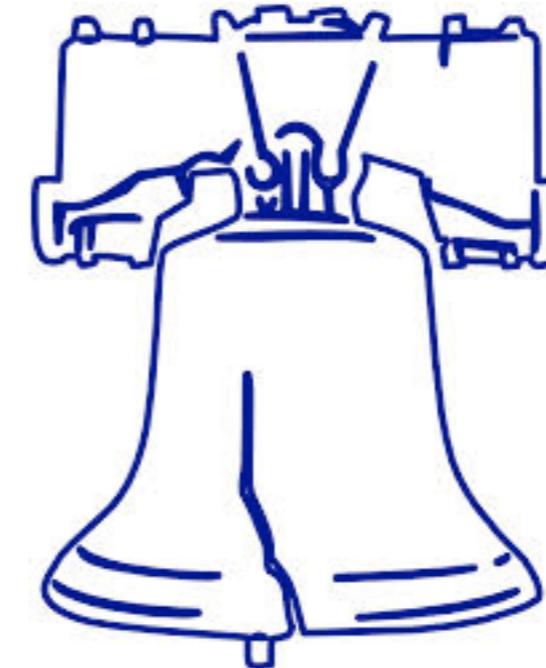








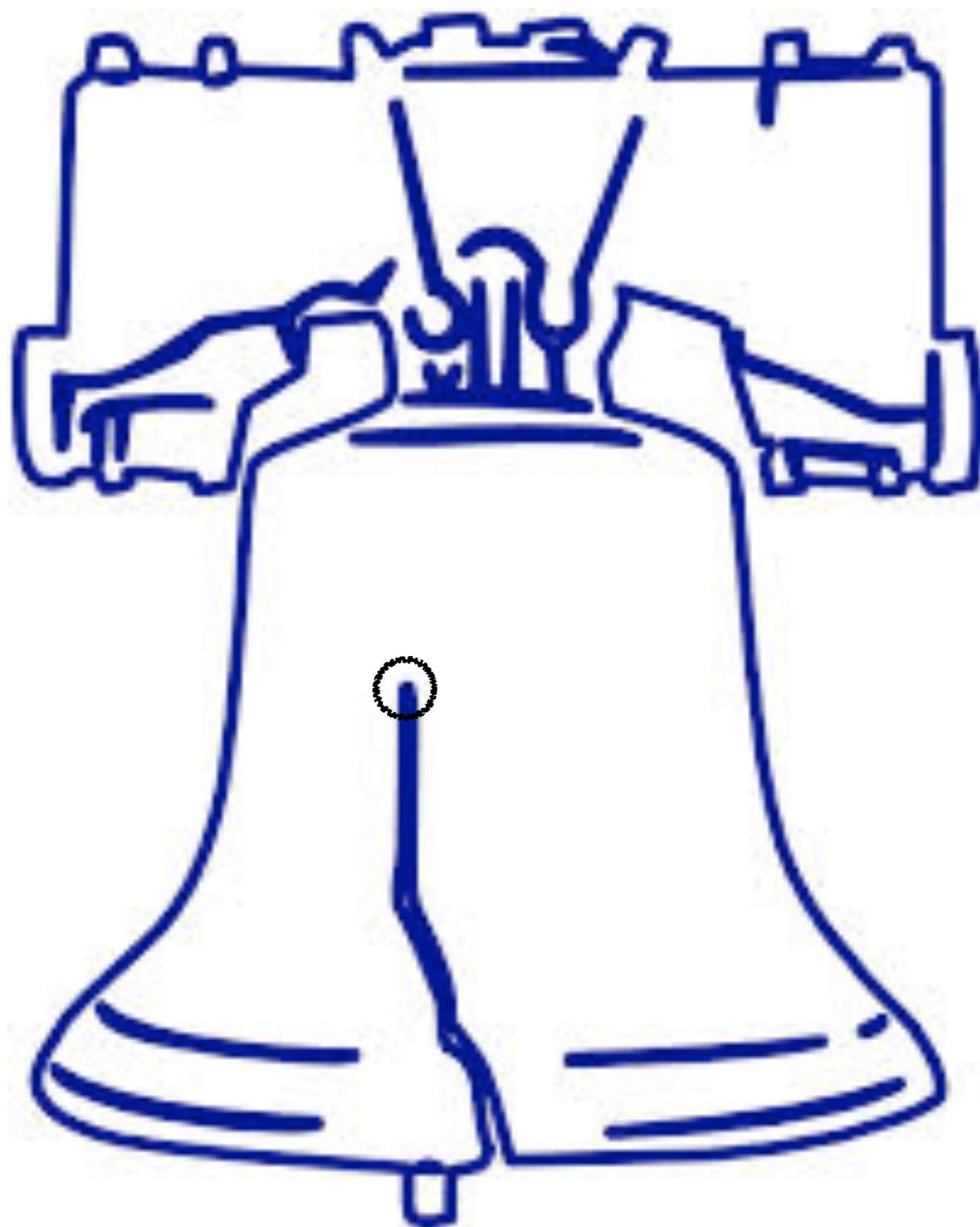
Learning from experience



The liberty bell
(Philadelphia)



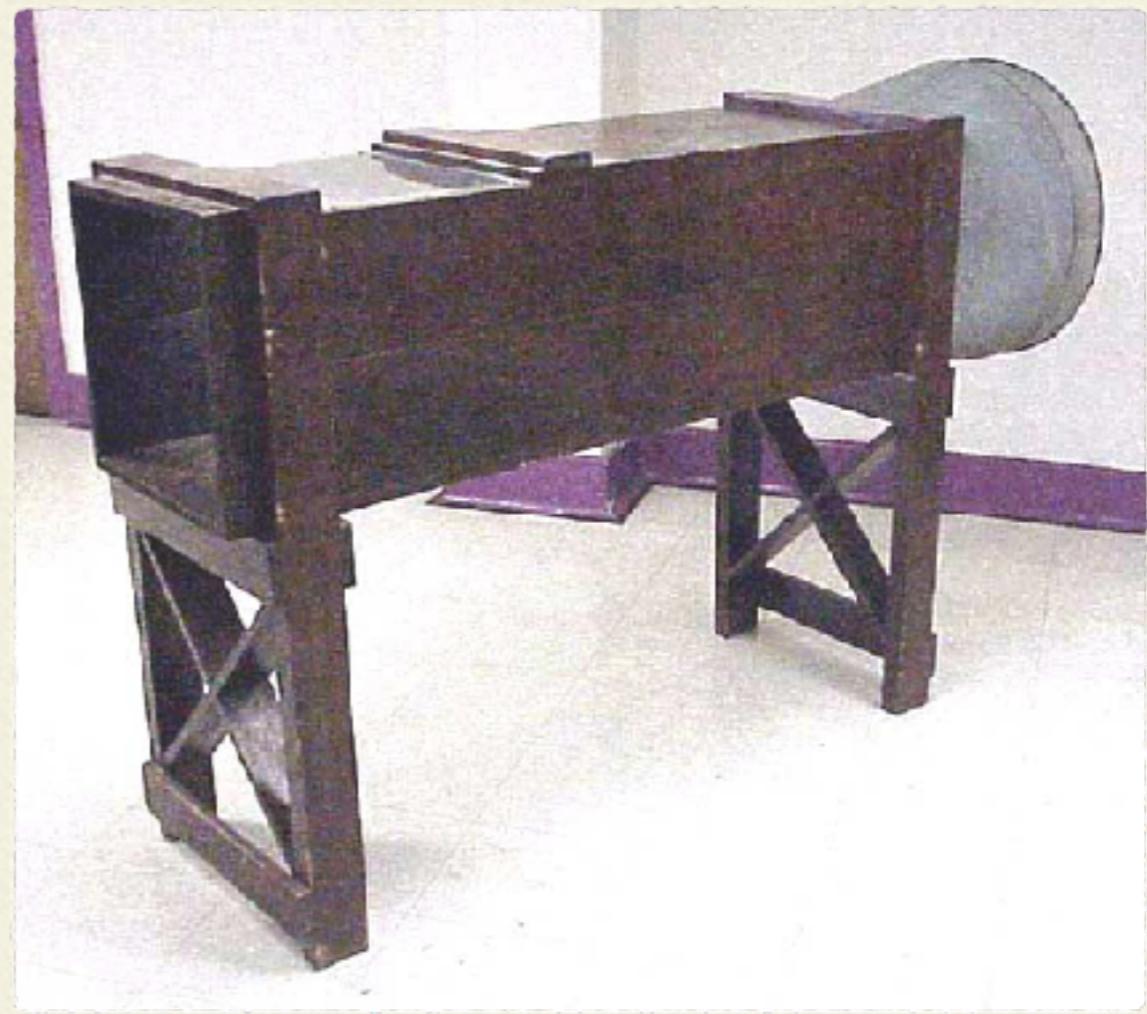
Learning from experience



The liberty bell
(Philadelphia)

Learning from experiments

World's largest wind tunnel (2014)



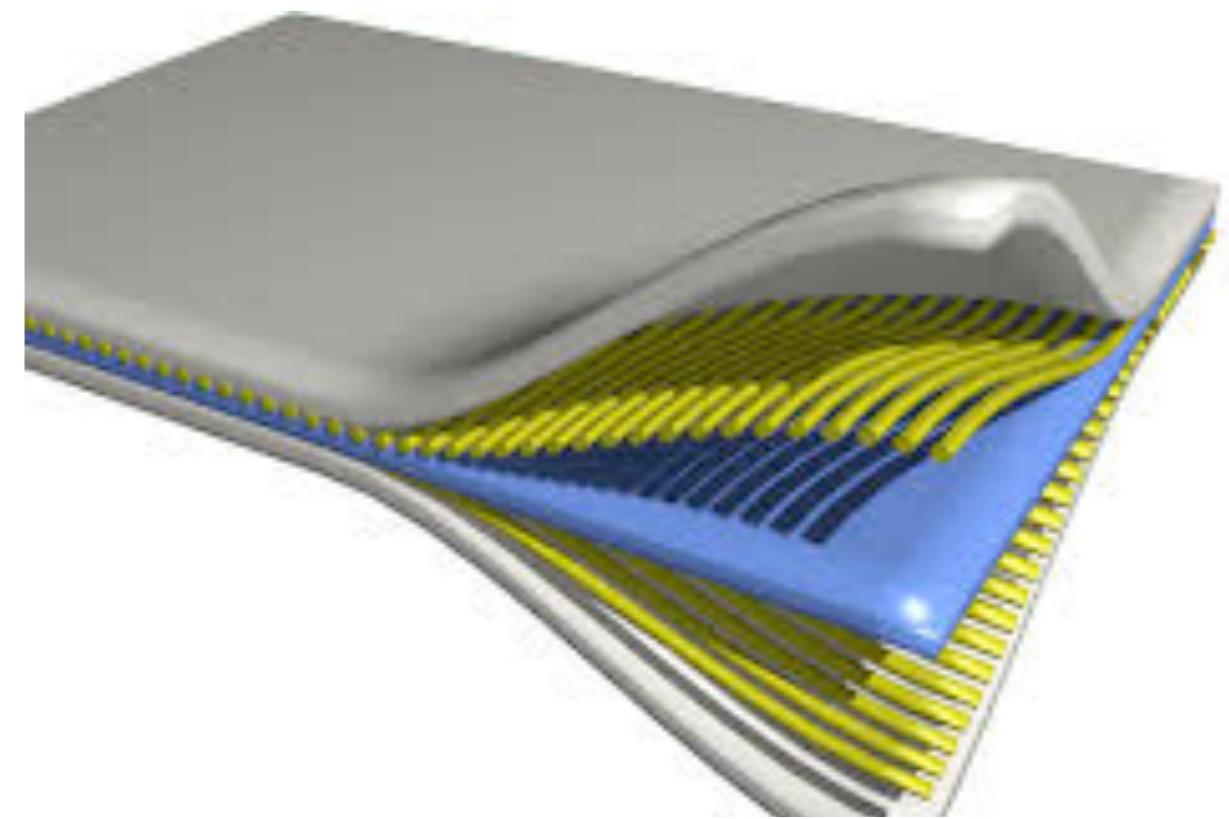
Replica of the 1901 Wright Wind Tunnel
(constructed with assistance from Orville Wright)

teaching...

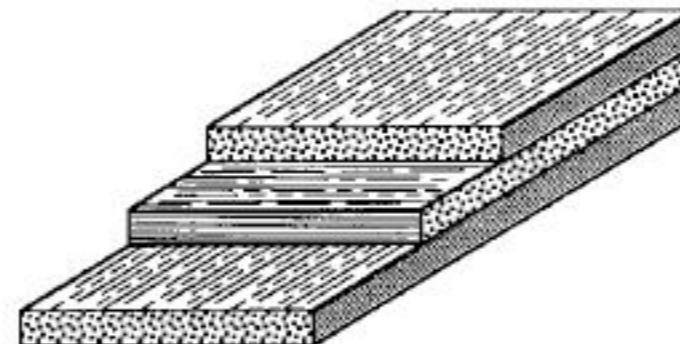


New materials for more payload

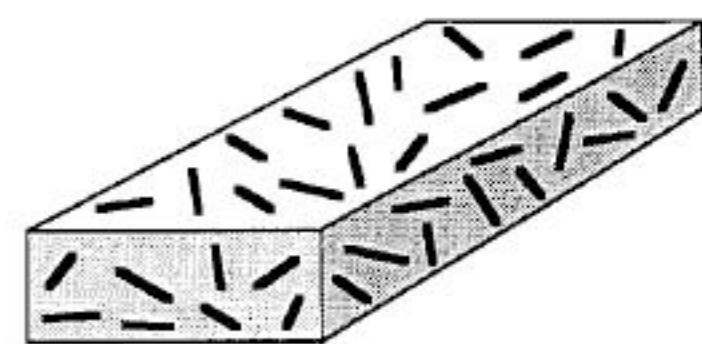
Introduction of composite materials have reduced the weight of structures by 20%



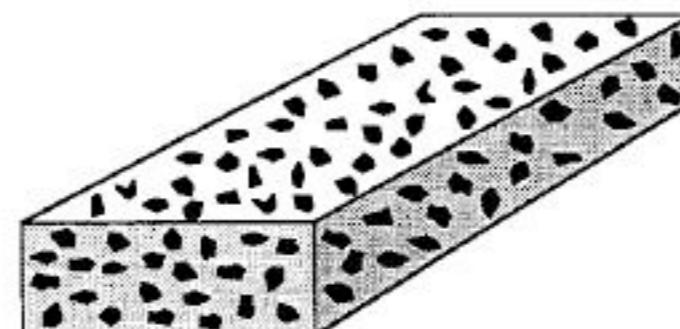
Continuous Fibers



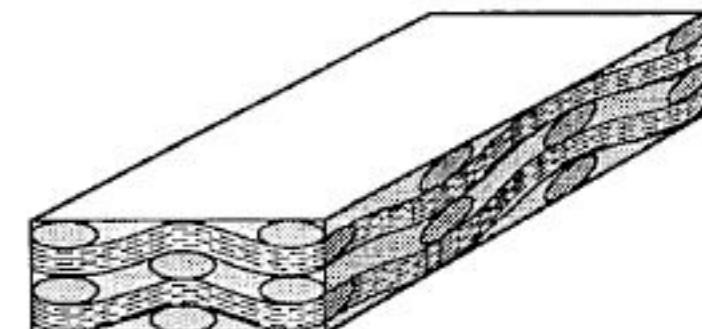
Discontinuous Fibers, Whiskers



Particles

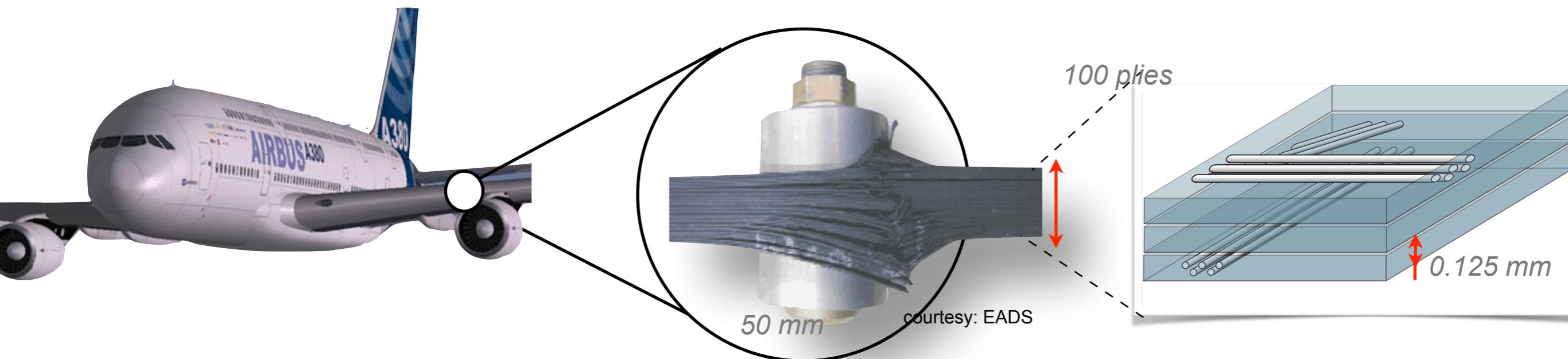


Fabric, Braid, Etc.

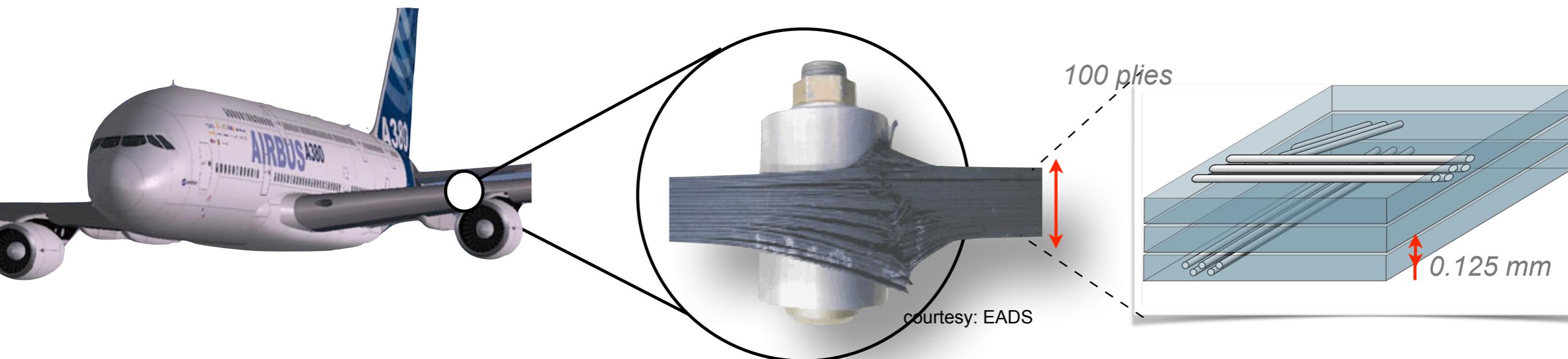


Over 1,000km saving
of 8,660kg of fuel
[A340-300]

Material complexity

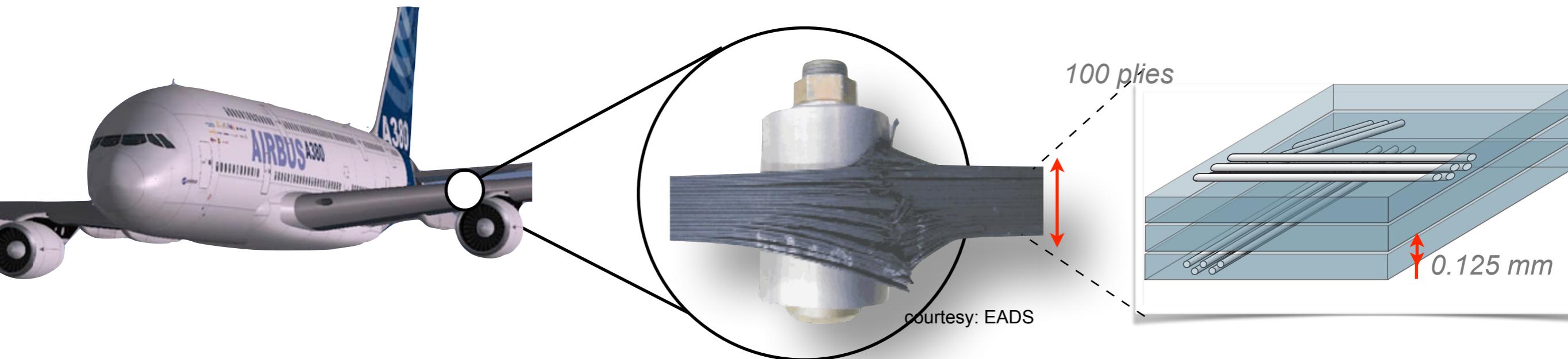


Material complexity



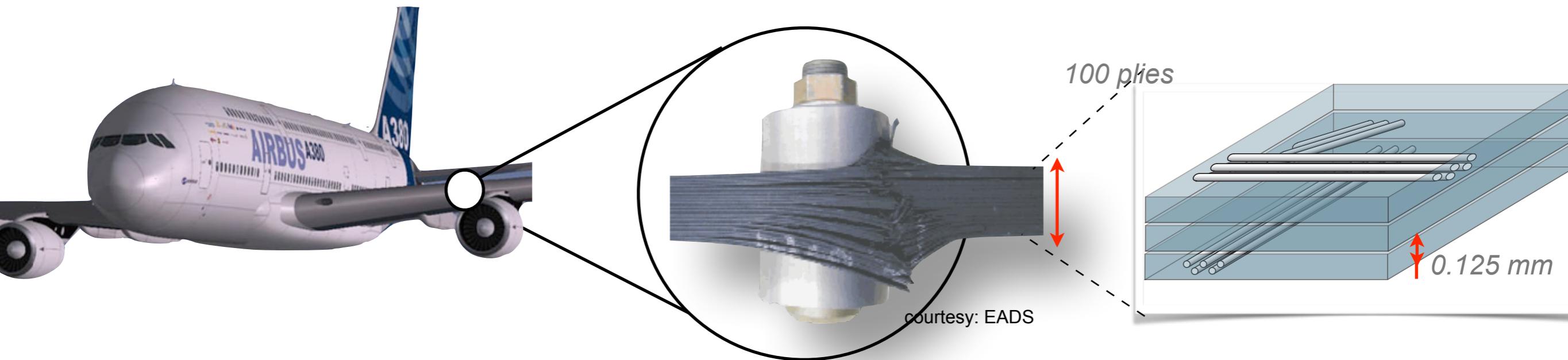
- Heterogeneous & multi-functional
- Experiments required to attain sufficient confidence in their behavior are increasingly costly

Material complexity



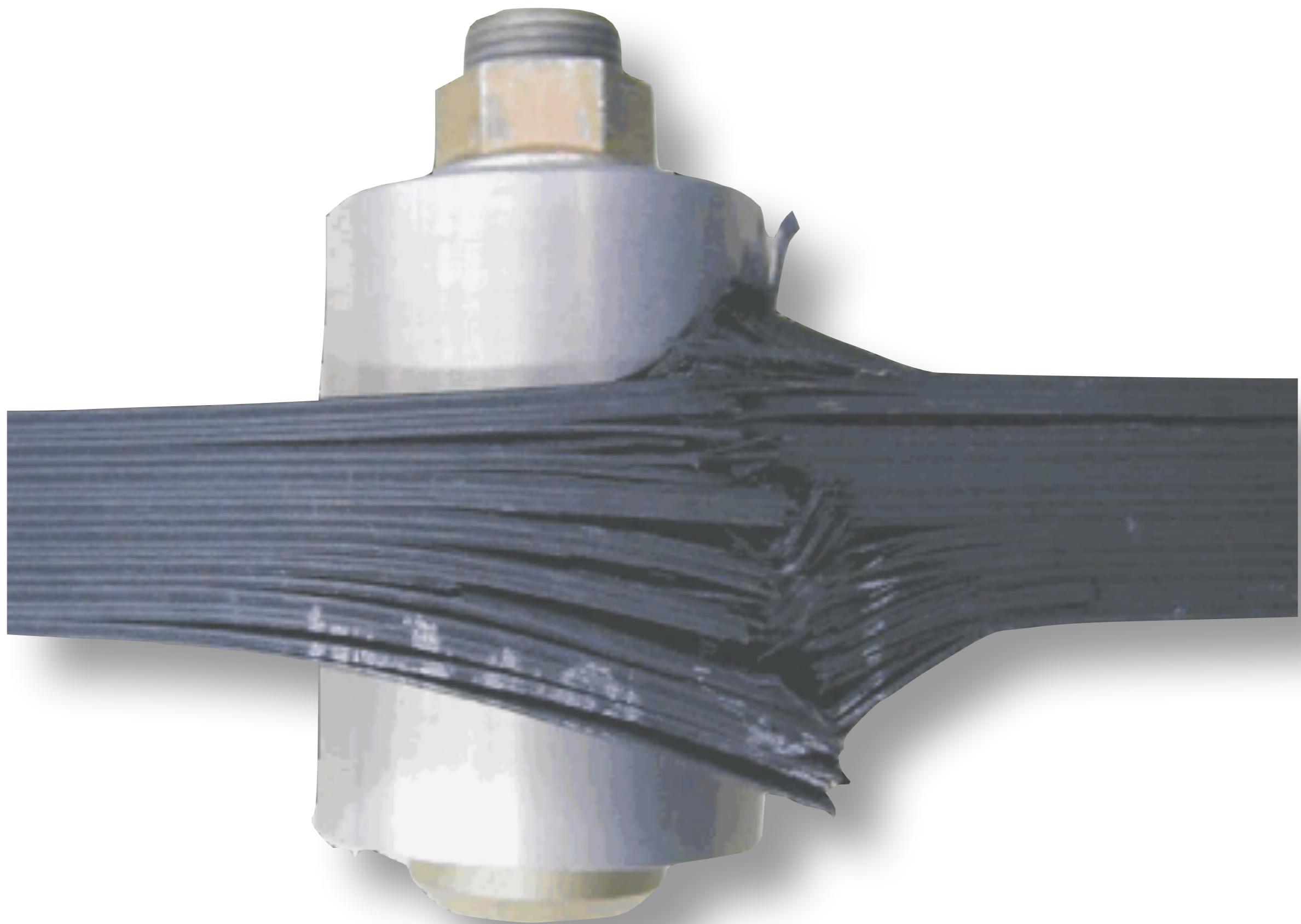
- Heterogeneous & multi-functional
- Experiments required to attain sufficient confidence in their behavior are increasingly costly
- Factor-of-Safety or probabilistic based methods cannot handle unknown unknowns
- Lack of similitude between testing (experimental) and operating conditions — also encountered in geophysics...

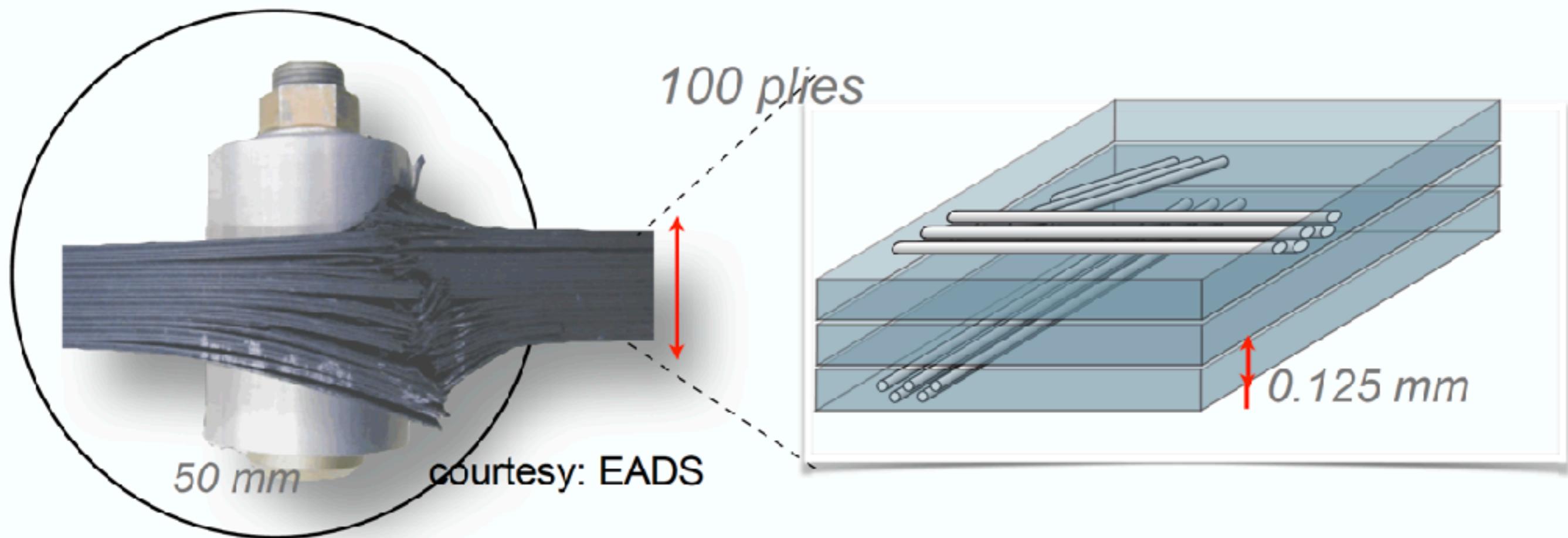
Material complexity

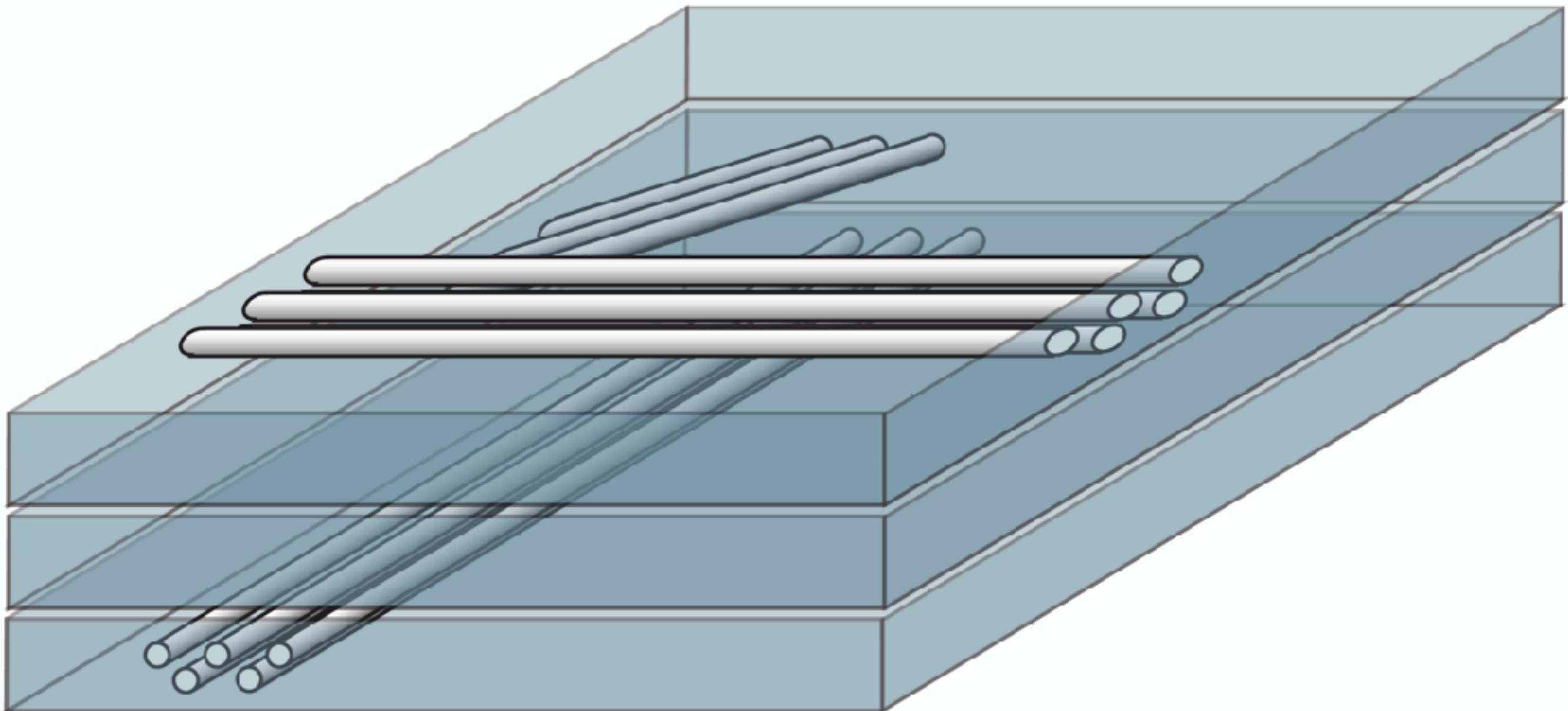


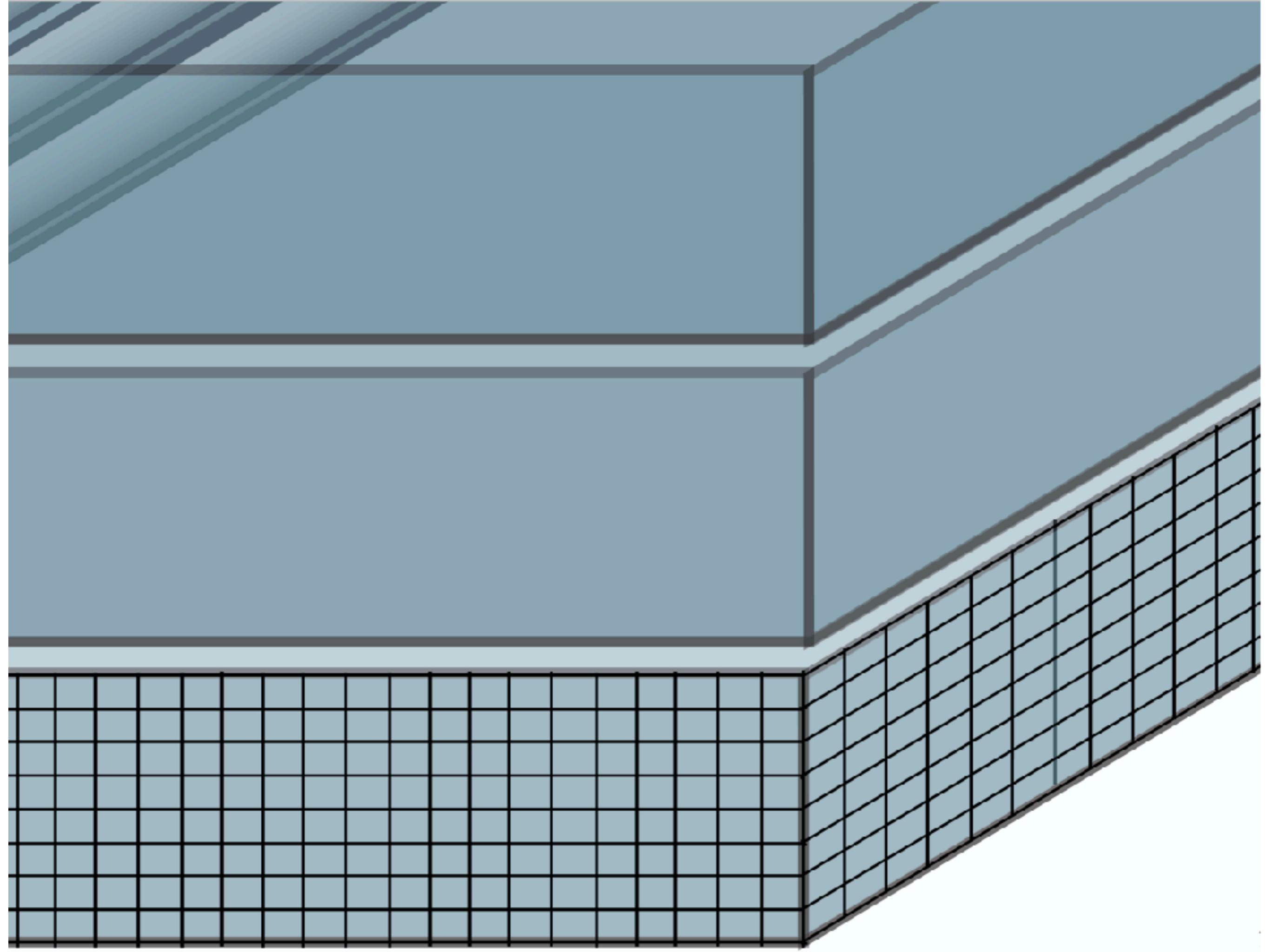
- Heterogeneous & multi-functional
- Experiments required to attain sufficient confidence in their behavior are increasingly costly
- Factor-of-Safety or probabilistic based methods cannot handle unknown unknowns - lack of similitude
- Move away from heuristics and experience-based engineering
- Develop fundamental understanding of physical processes (degradation, ...)
- Reduce weight

A bolted joint

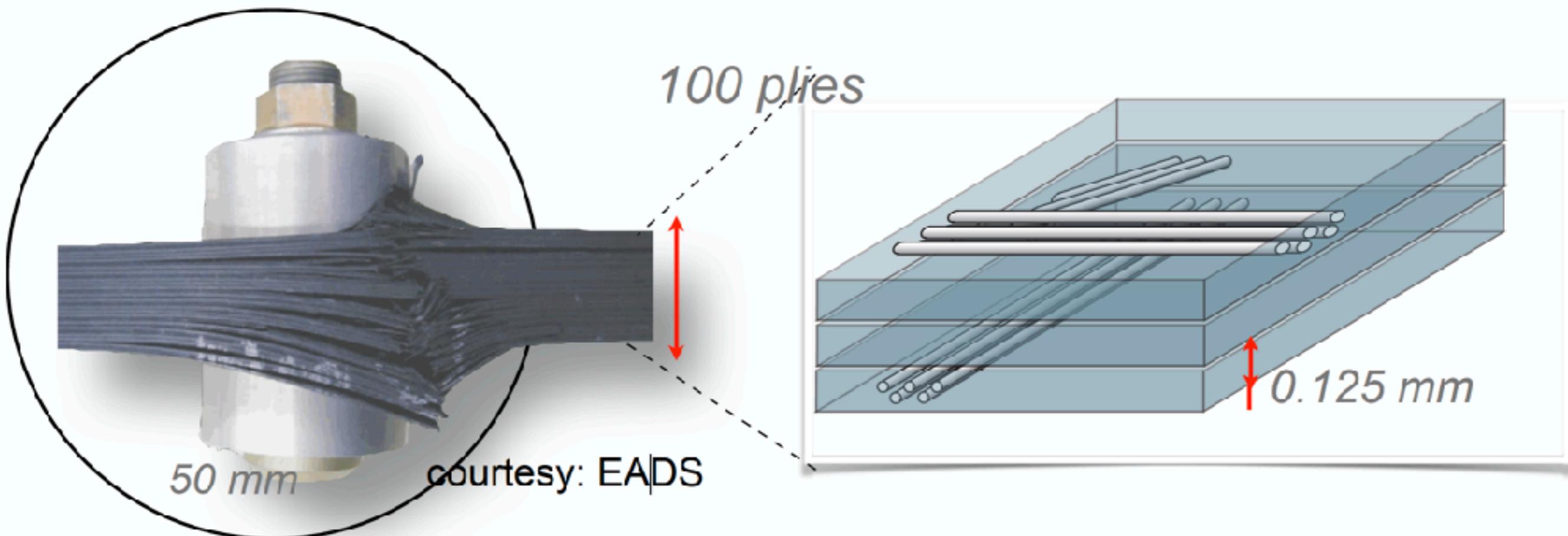




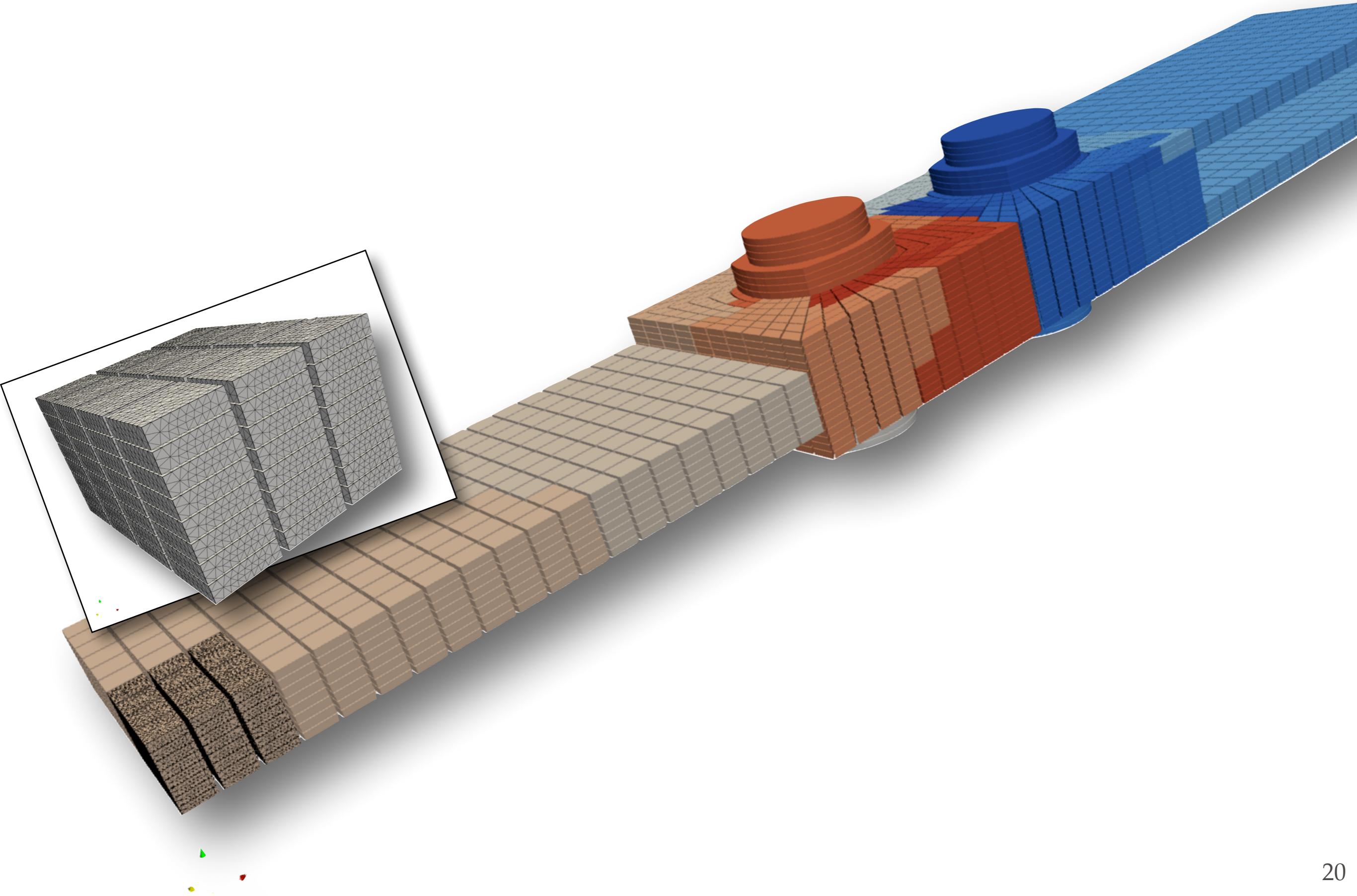


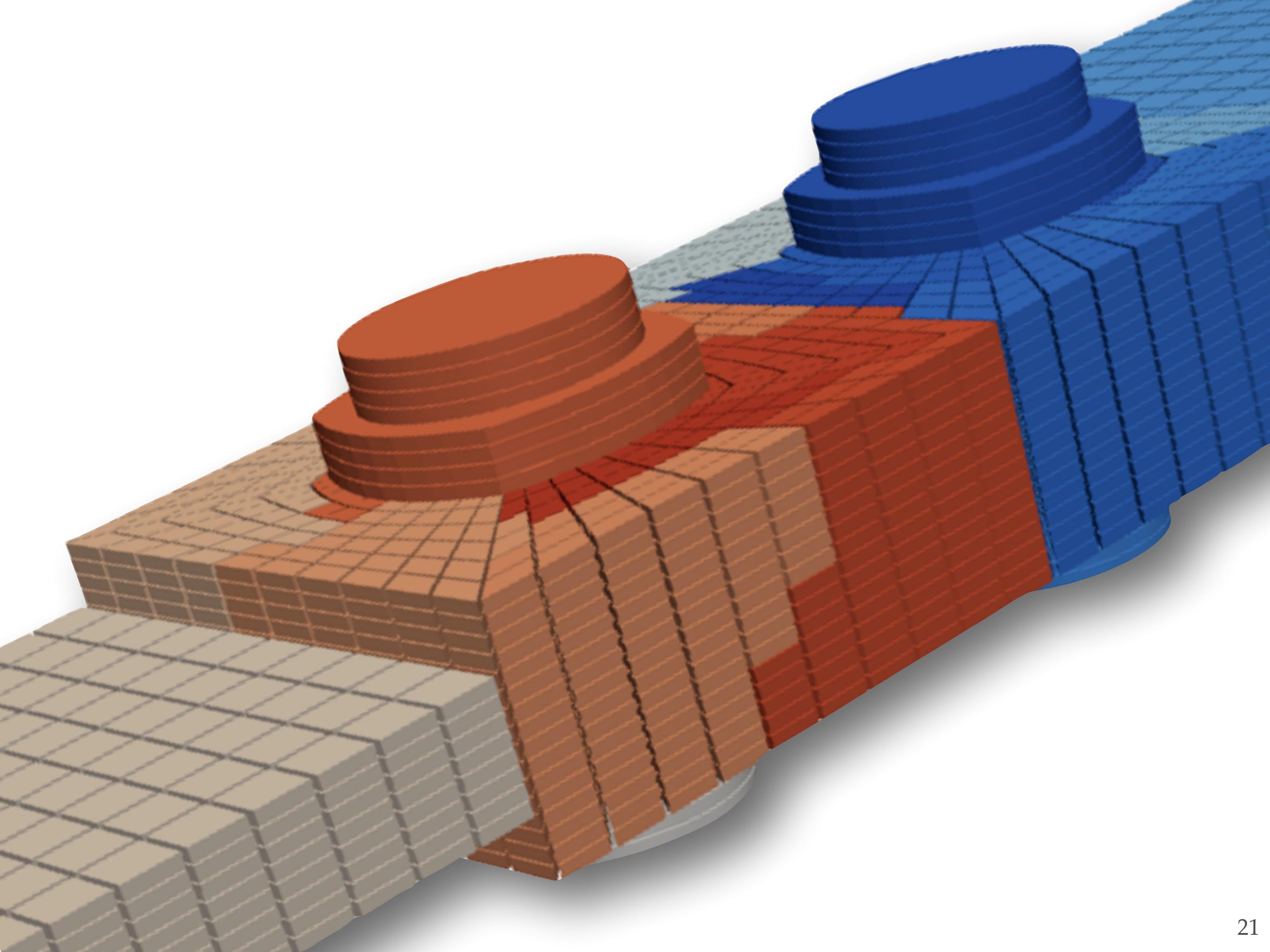


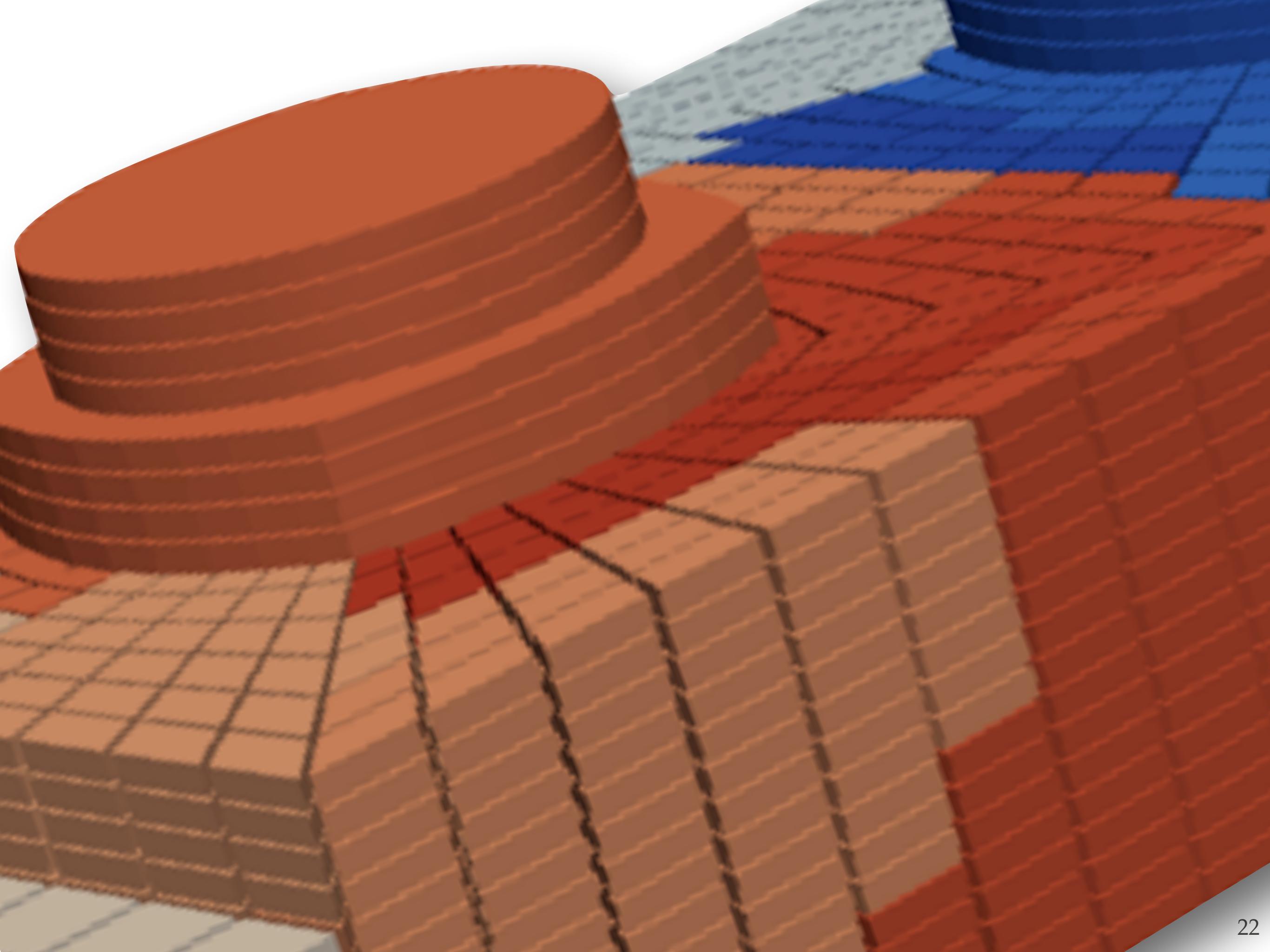
One single bolted joint



- 5 elements through the thickness of a ply => 0.025mm/element
 - 50mm bolted joint area => 2,000 elements
 - 50mm x 50mm x 100 plies => $2,000 \times 2,000 \times (100 \times 5)$
- => **2 billion elements**



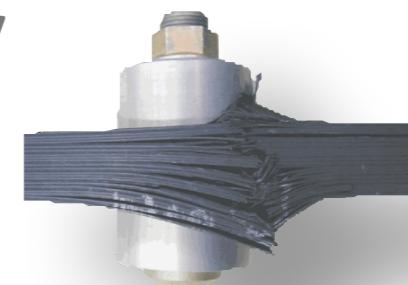




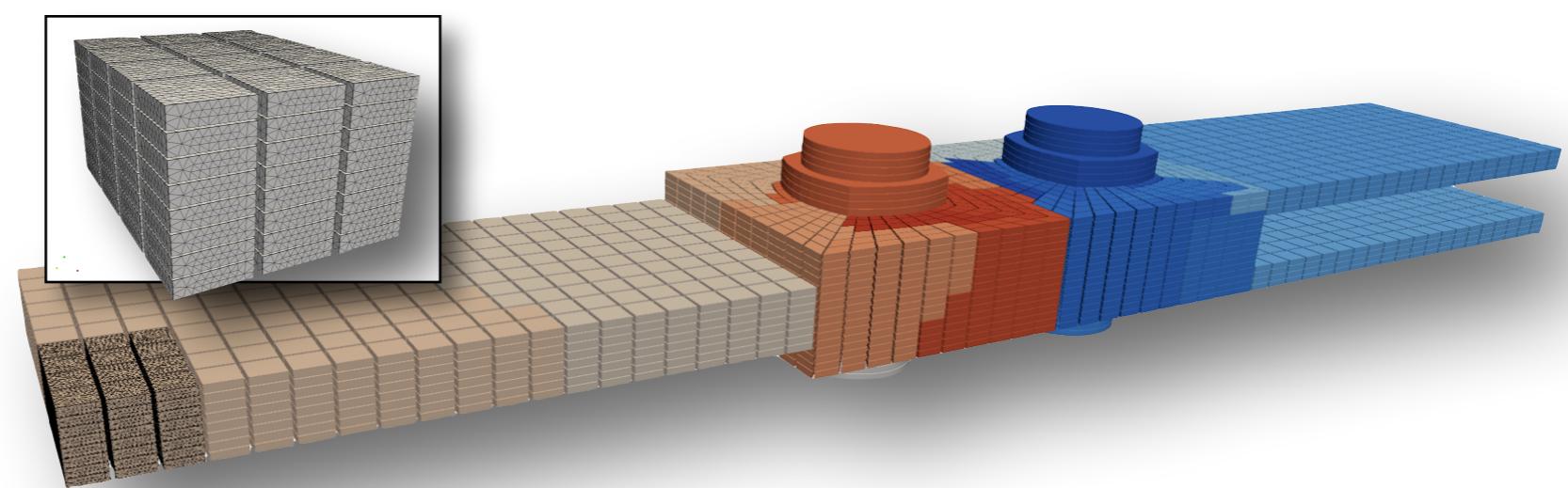
Large structures



whose behaviour is governed by
small-scale effects



=> intractable problem size



How can the problem size
be reduced but the
accuracy controlled?

Challenge

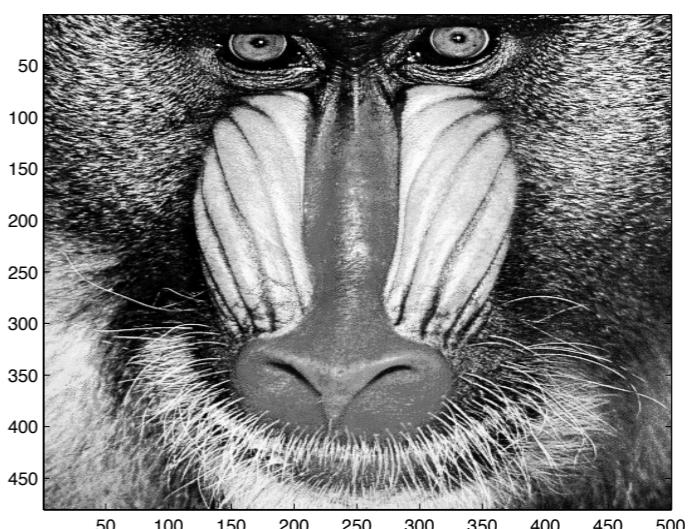
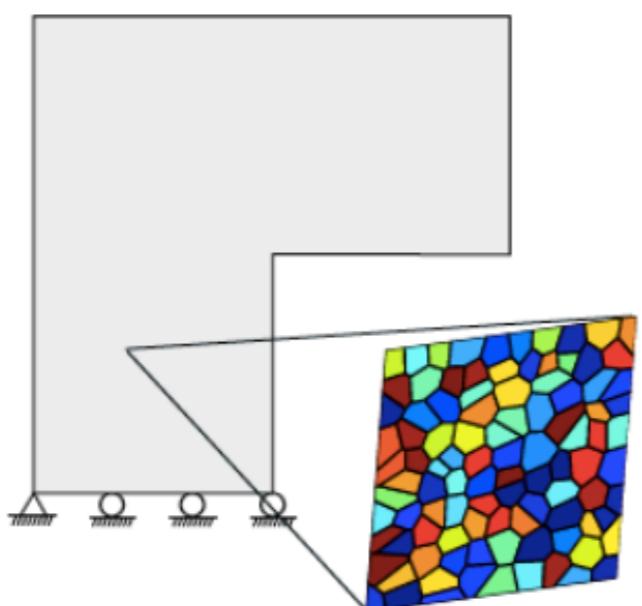
- Reduce the problem size
- Preserve essential features

Reduce computational
expense

Control the error

Physics based model
reduction a.k.a. Multiscale
Methods

Algebraic based model
reduction a.k.a. Machine
Learning



Challenge

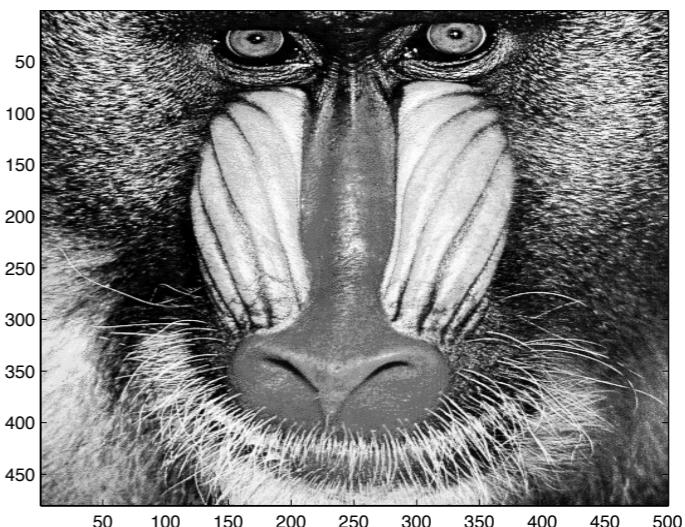
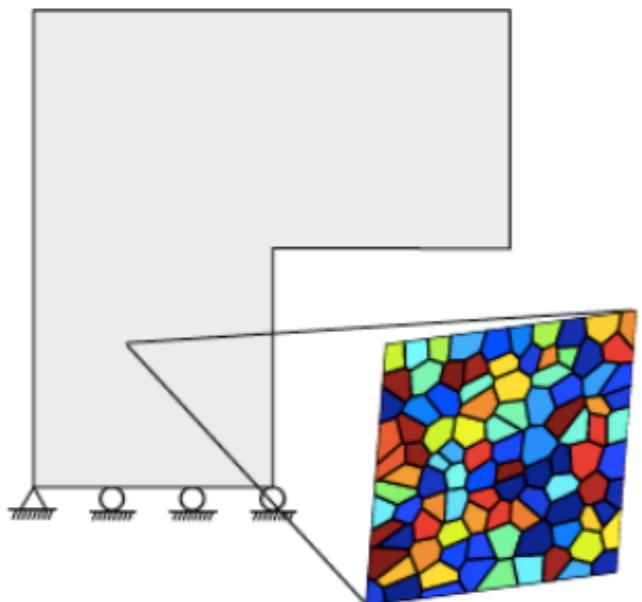
- Reduce the problem size
- Preserve essential features

Reduce computational
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Control the error

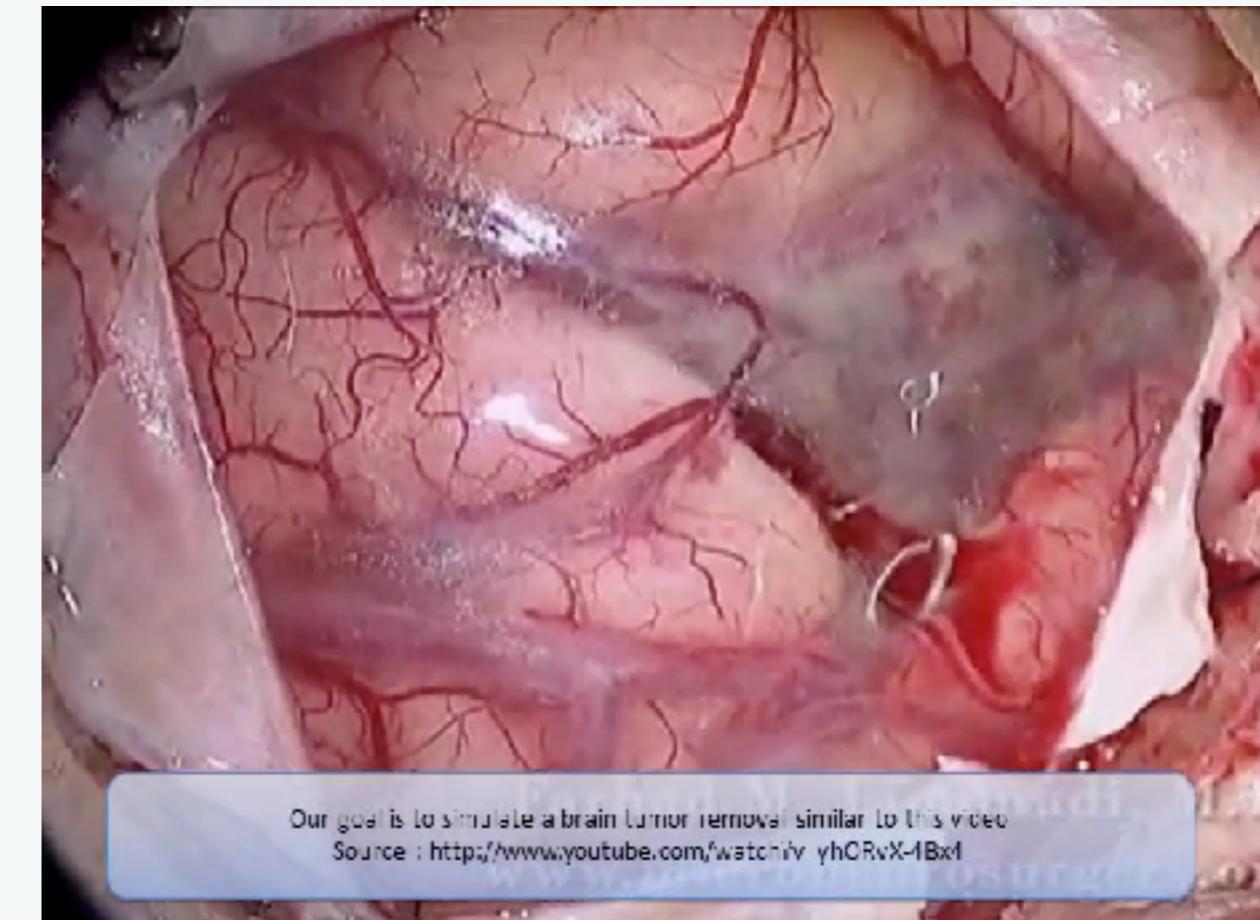
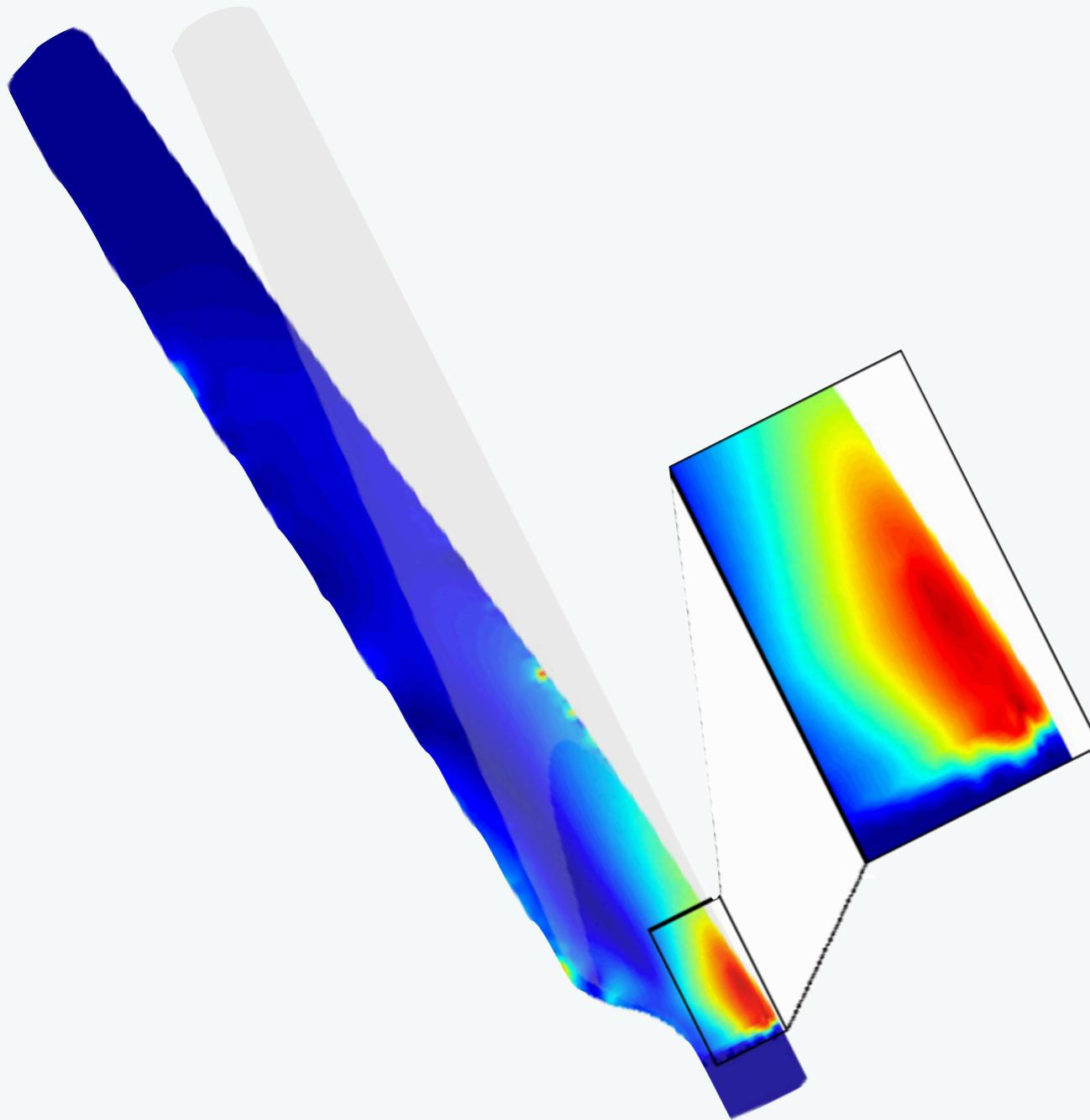
Physics based model
reduction a.k.a. Multiscale
Methods

Algebraic based model
reduction a.k.a. Machine
Learning



Lack of scale separation

A view from reduced order modelling and homogenisation



Mathematical Modelling

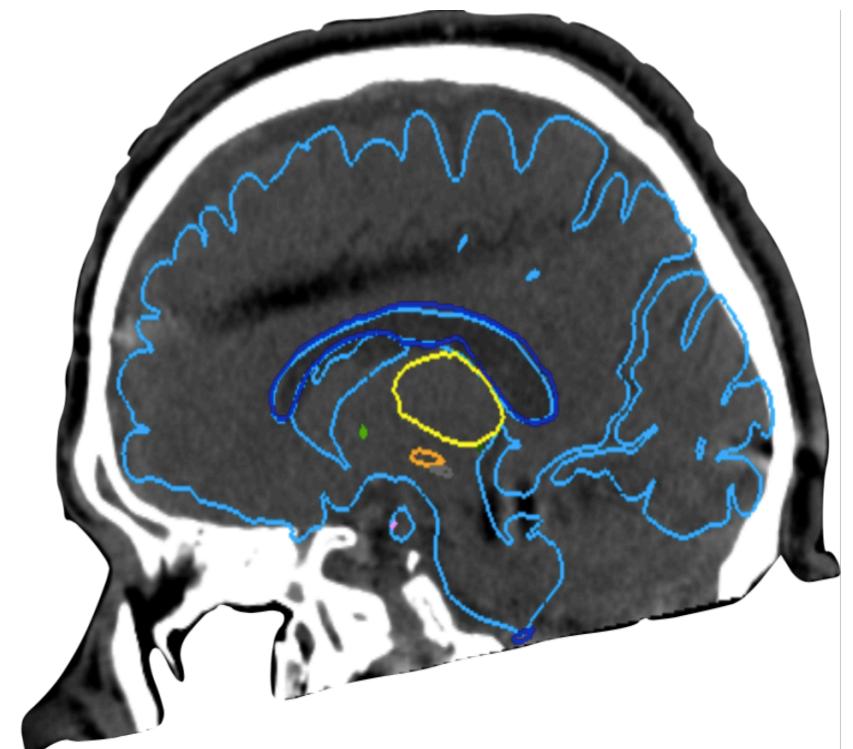
Continuous
Problem

Mathematical Modelling

Continuous
Problem



Bijar, Rohan, Perrier &
Payan 2015



Mathematical Modelling

Continuous
Problem



Mathematical
Model

Mathematical Modelling

Continuous
Problem



Mathematical
Model

with

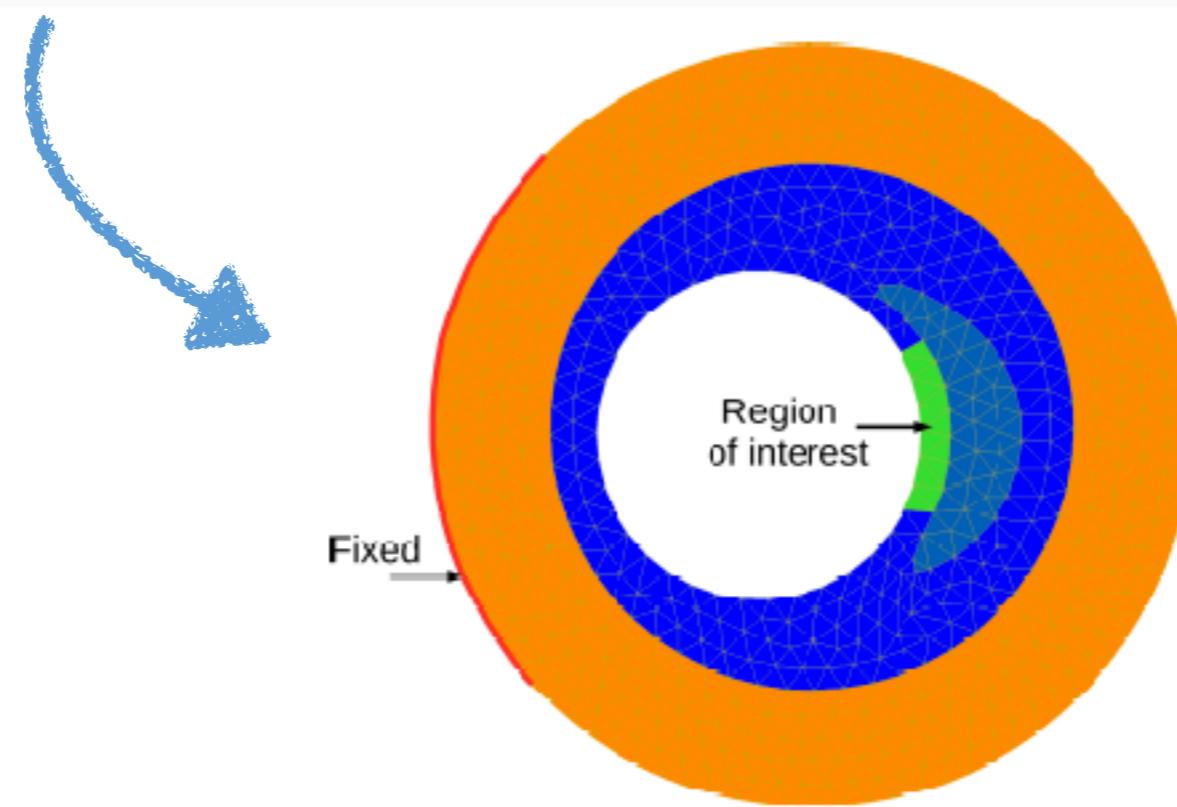
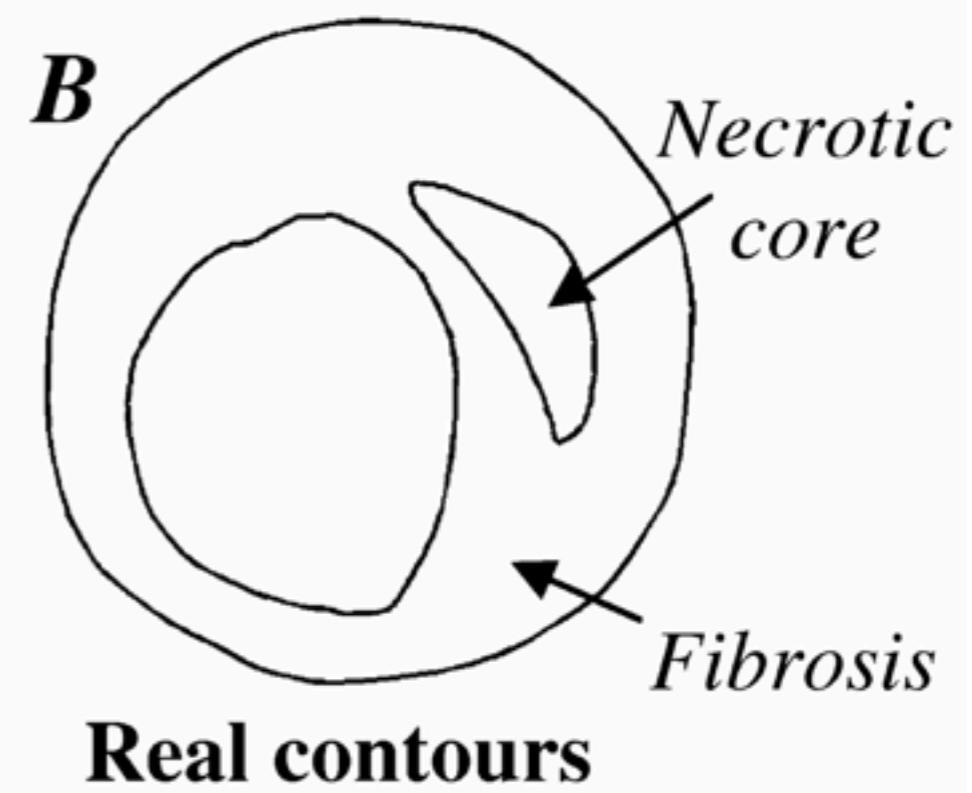
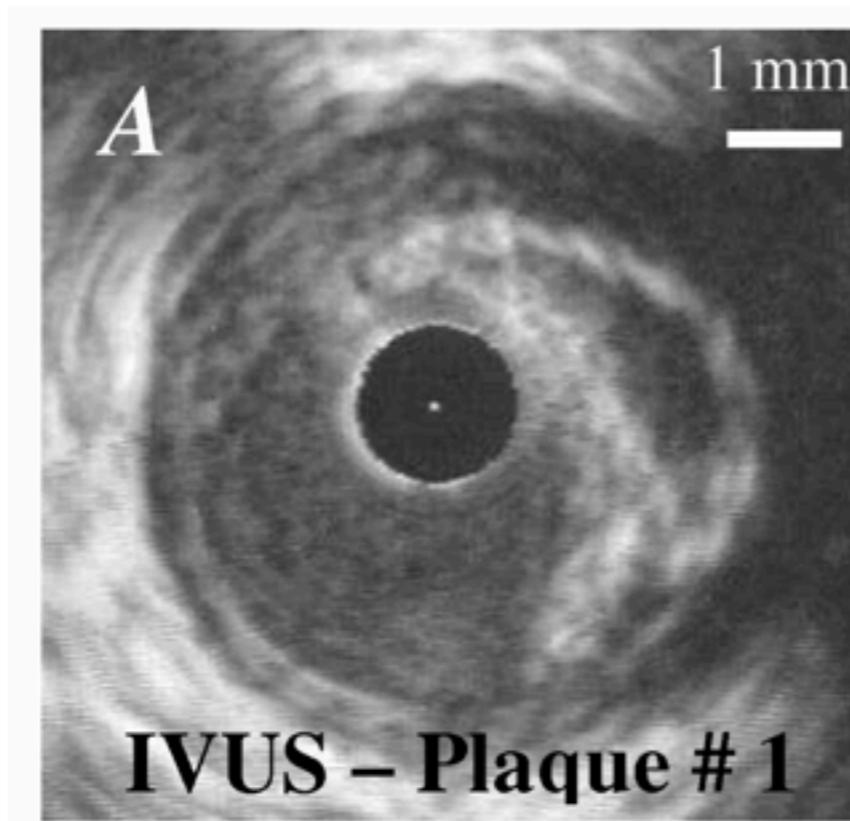
$$\min_{\mathbf{u} \in V} \frac{1}{2} \int_{\Omega} \boldsymbol{\sigma}(\mathbf{u}, \beta) : \boldsymbol{\varepsilon}(\mathbf{u}) d\mathbf{x} - \int_{\Omega} \mathbf{g} \cdot \mathbf{u} d\mathbf{x}$$
$$\boldsymbol{\sigma}(\mathbf{u}, \beta) = \underbrace{\boldsymbol{\sigma}_P(\mathbf{u})}_{\text{passive material}} + \underbrace{\boldsymbol{\sigma}_A(\beta)}_{\text{muscular activation}} \quad \left\{ \begin{array}{l} \boldsymbol{\sigma}_A(\beta) = \beta T e_A \otimes e_A \\ e_A : \text{fiber direction} \\ T : \text{tension} \\ \beta : \text{activation} \end{array} \right.$$

Mathematical Modelling

Continuous
Problem



Mathematical
Model



Mathematical Modelling

Continuous
Problem



Mathematical
Model



Discrete Problem

Mathematical Modelling

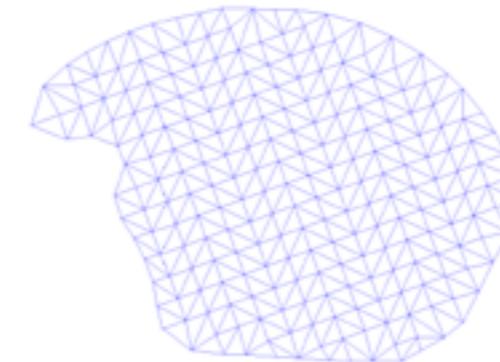
Continuous
Problem



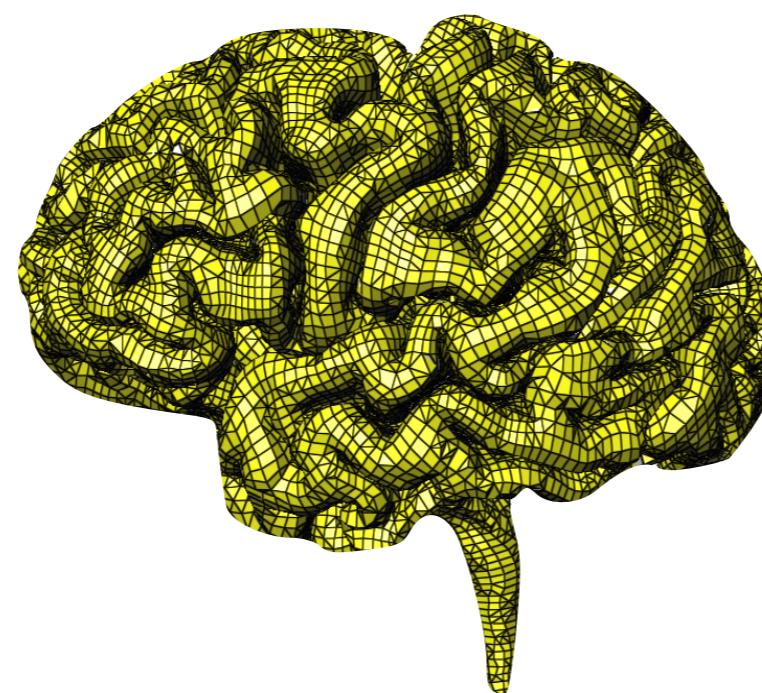
Mathematical
Model



Discrete Problem



Finite element mesh
of a tongue with F. Chouly et al.



Hexahedral mesh of a brain
with Bruno Lévy, Inria



Meshless brain discretization
with Bruno Lévy, Inria

Mathematical Modelling

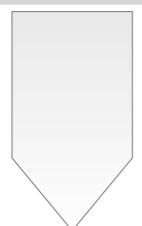
Continuous
Problem



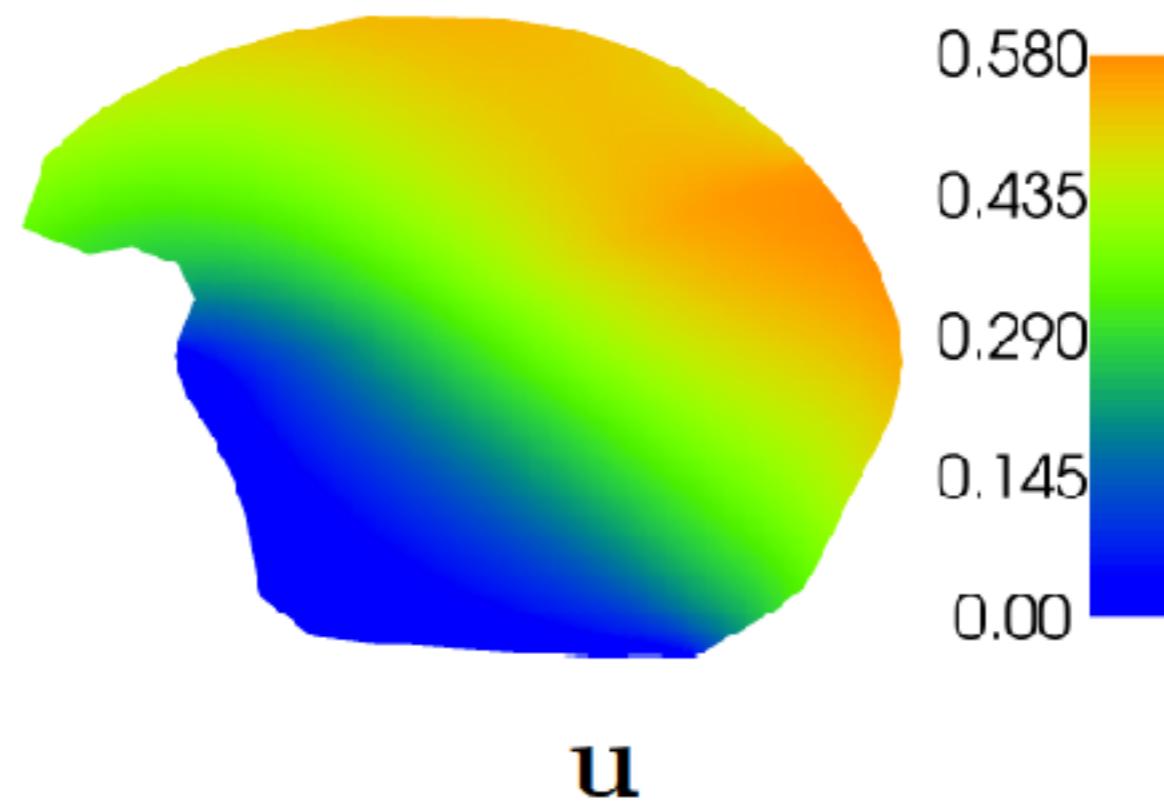
Mathematical
Model



Discrete Problem



Numerical
Solution



Mathematical Modelling

Continuous
Problem



Mathematical
Model



Discrete Problem



Numerical
Solution

Mathematical Modelling

Continuous
Problem



Mathematical
Model



Discrete Problem



Numerical
Solution



Bijar, Rohan, Perrier &
Payan 2015

\neq

$$\min_{\mathbf{u} \in \mathbf{V}} \frac{1}{2} \int_{\Omega} \boldsymbol{\sigma}(\mathbf{u}, \beta) : \boldsymbol{\varepsilon}(\mathbf{u}) \, d\mathbf{x} - \int_{\Omega} \mathbf{g} \cdot \mathbf{u} \, d\mathbf{x}$$

Mathematical Modelling

Continuous
Problem



Model Error

Mathematical
Model



Discrete Problem



Numerical
Solution



Bijar, Rohan, Perrier &
Payan 2015

\neq

$$\min_{\mathbf{u} \in \mathbf{V}} \frac{1}{2} \int_{\Omega} \boldsymbol{\sigma}(\mathbf{u}, \beta) : \boldsymbol{\varepsilon}(\mathbf{u}) \, d\mathbf{x} - \int_{\Omega} \mathbf{g} \cdot \mathbf{u} \, d\mathbf{x}$$

Physical Problem
Constitutive Model
Material Parameters

Mathematical Modelling

Continuous
Problem



Model Error

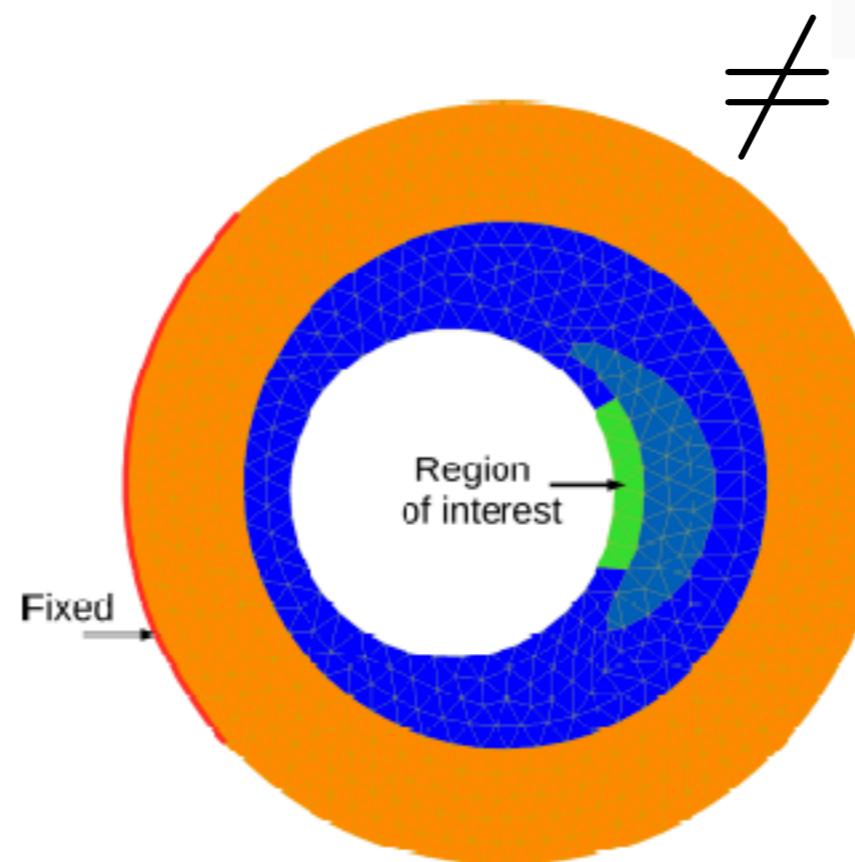
Mathematical
Model



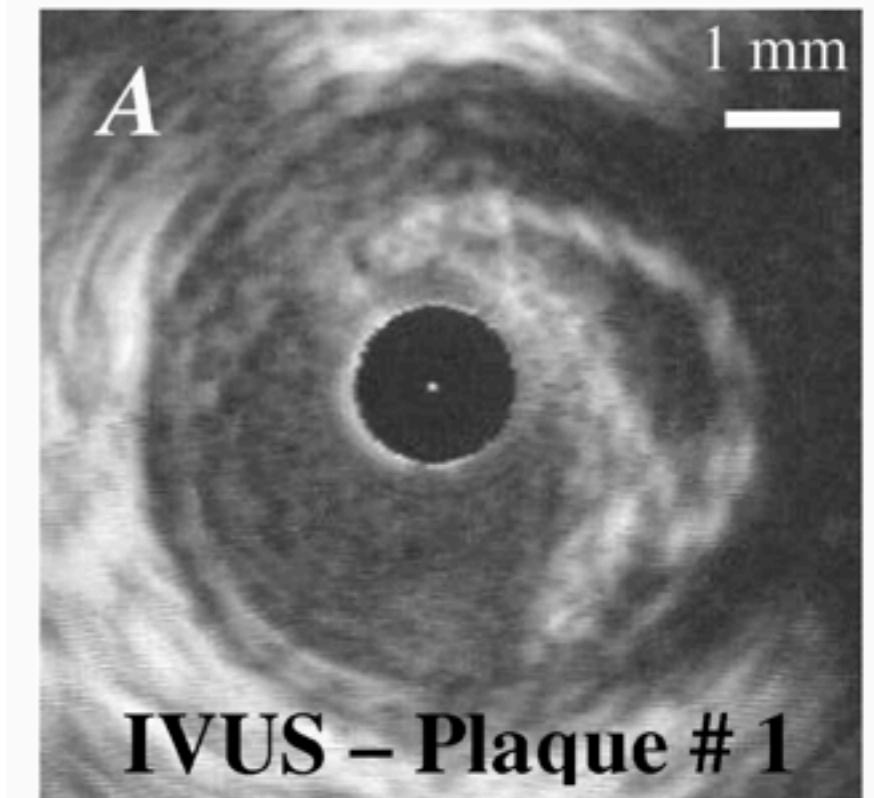
Discrete Problem



Numerical
Solution



Geometry
Boundary conditions



Mathematical Modelling

Continuous
Problem

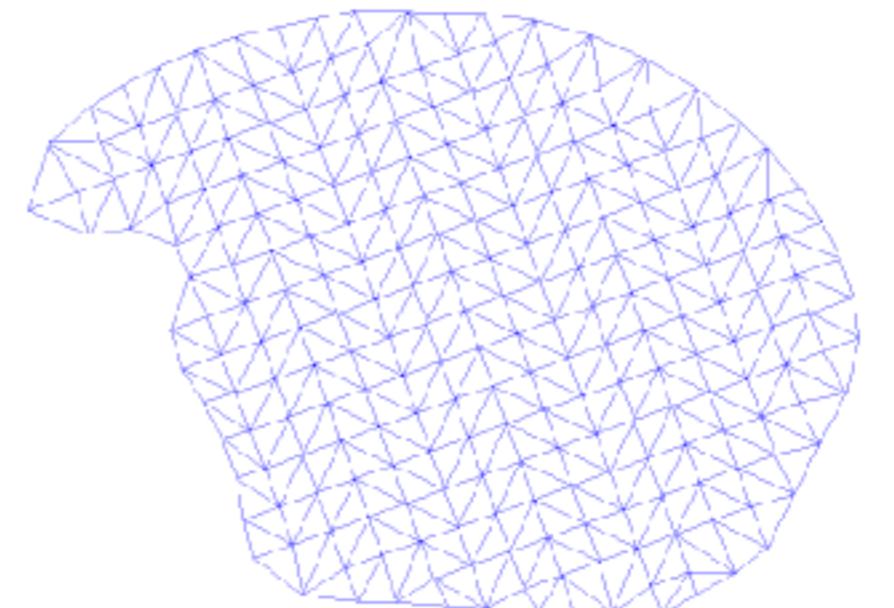
Model Error

Mathematical
Model

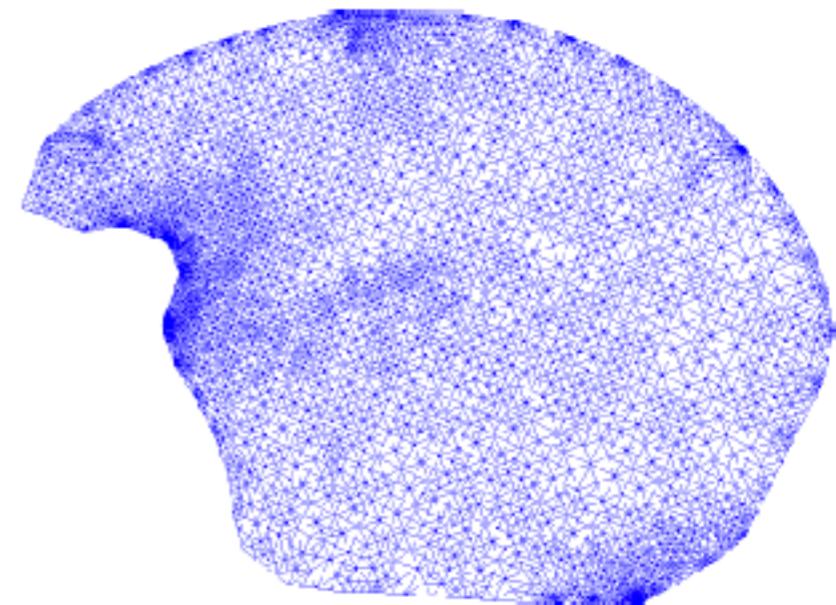
Discretization Error

Discrete Problem

Numerical
Solution



vs.



Mathematical Modelling

Continuous
Problem



Mathematical
Model



Discrete Problem



Numerical
Solution

Model Error

Discretization Error



Mathematical Modelling

Continuous
Problem



Mathematical
Model



Discrete Problem

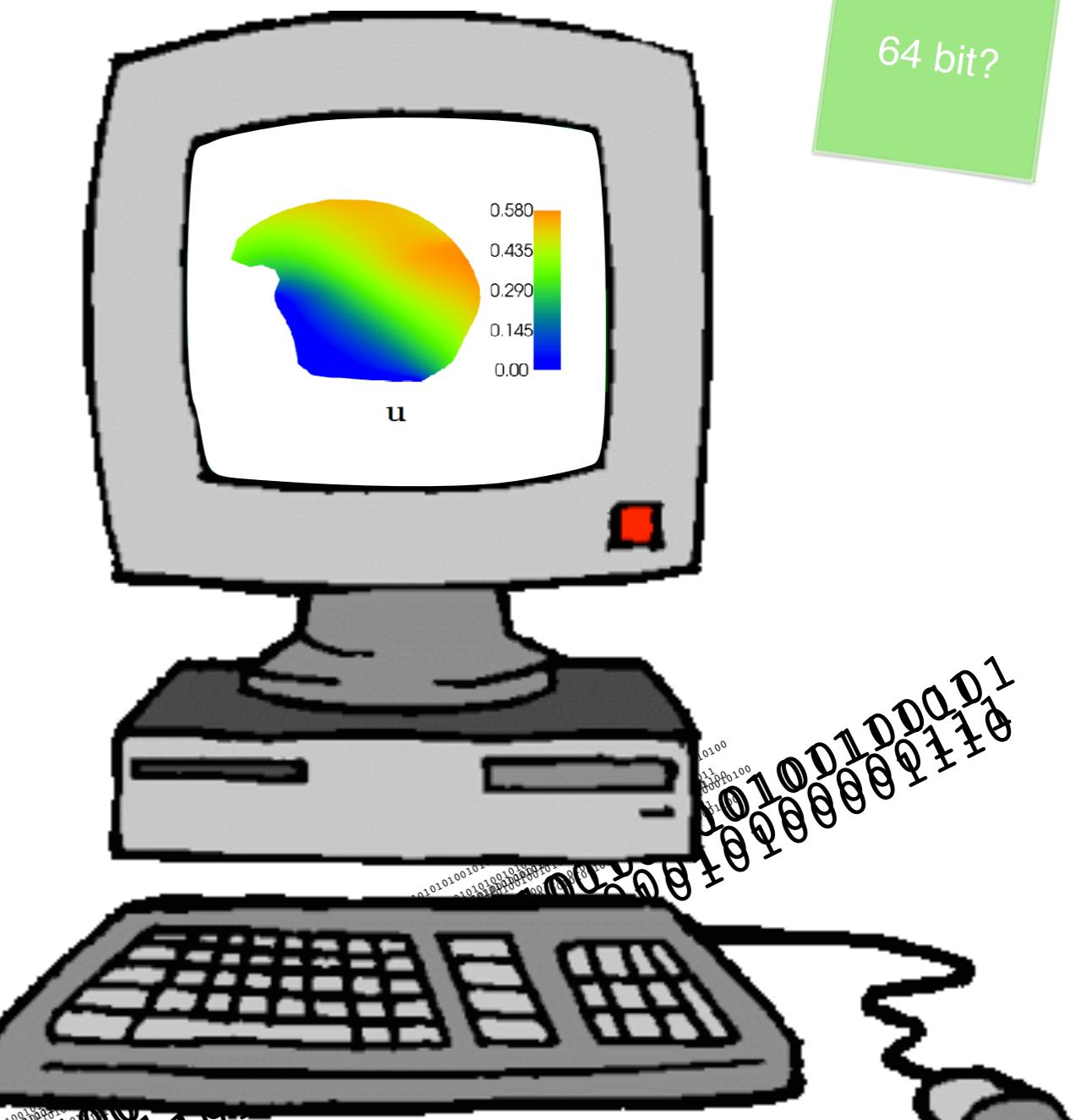


Numerical
Solution

Model Error

Discretization Error

Numerical Error



Mathematical Modelling

Continuous
Problem



Model Error

Mathematical
Model



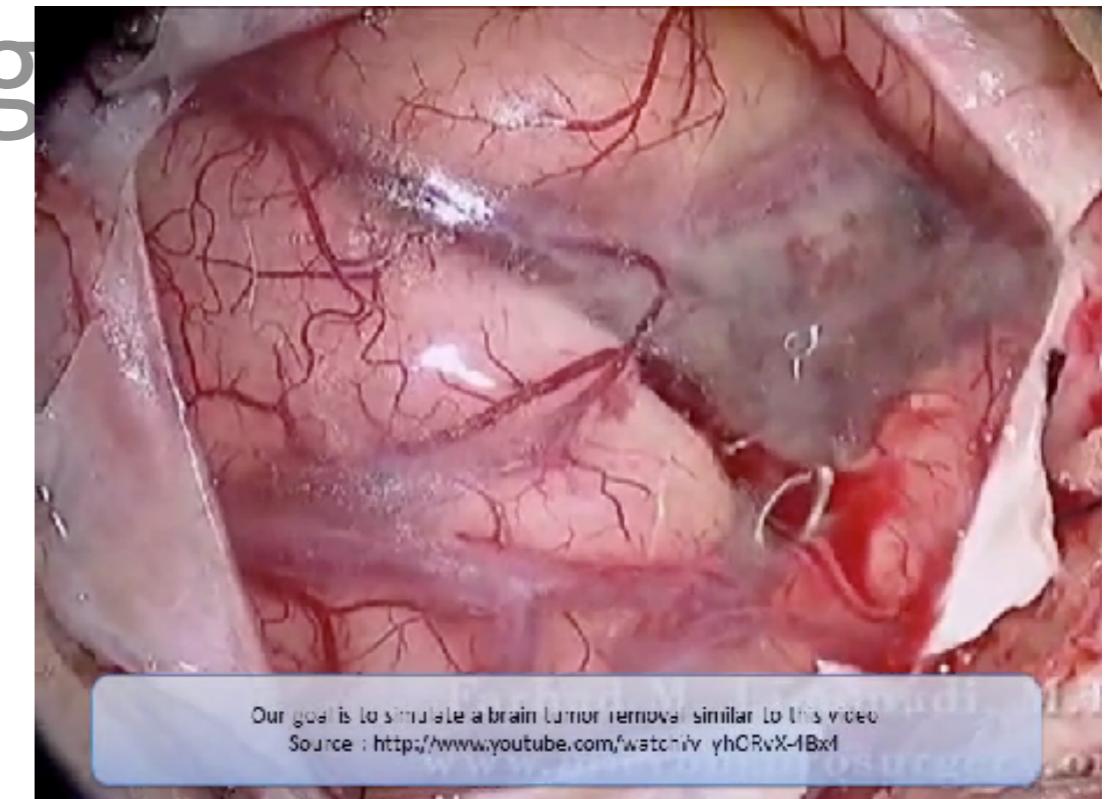
Discrete Problem



Numerical
Solution

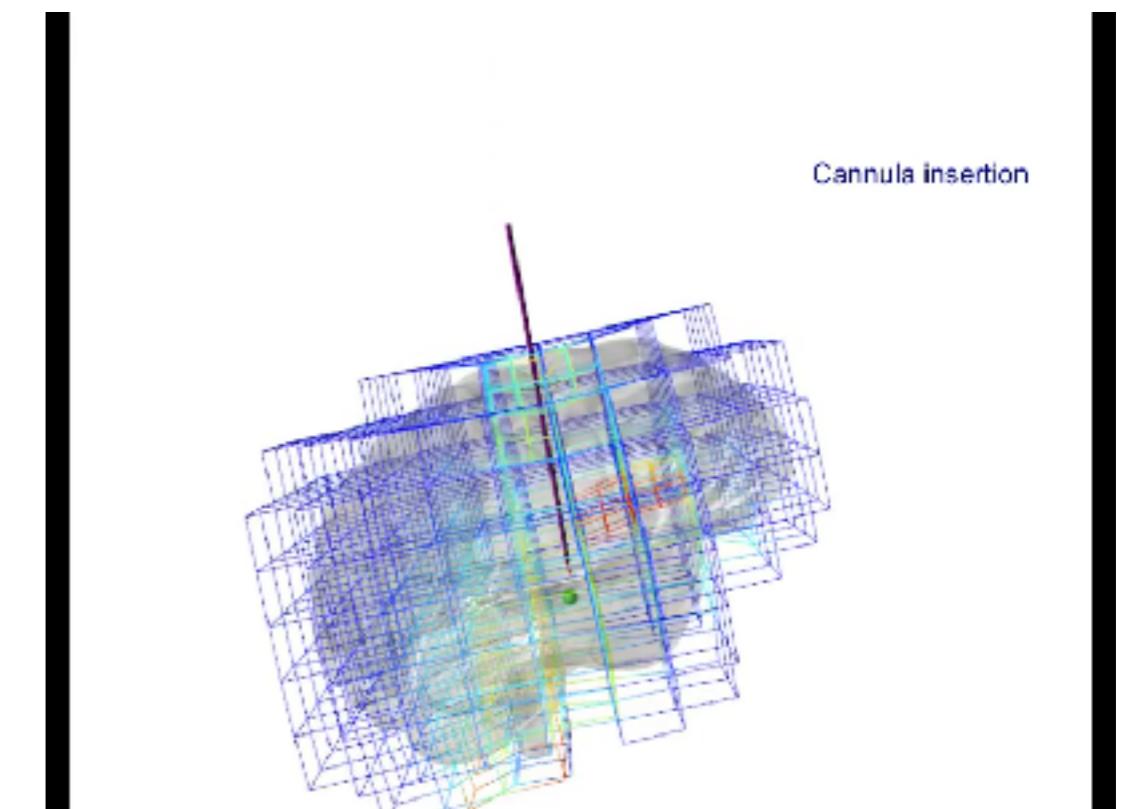
Discretization Error

Numerical Error



Total Error

Reality
vs.
Simulation



Mathematical Modelling

Continuous
Problem

Model Error

Are we solving the right
problem?

Mathematical
Model

Total Error

Discretization Error

Discrete Problem

Numerical Error

Numerical
Solution

Mathematical Modelling

Continuous
Problem

Model Error

Are we solving the right
problem?

Mathematical
Model

Total Error

Discretization Error

Discrete Problem

Numerical Error

Numerical
Solution

Mathematical Modelling

Continuous
Problem

Model Error

*Are we solving the right
problem?*

Mathematical
Model

Total Error

Discretization Error

*Are we solving the
problem right?*

Discrete Problem

Numerical Error

Numerical
Solution

Mathematical Modelling

Continuous
Problem

Model Error

Mathematical
Model

Discrete Problem

Numerical
Solution

Are we solving the right
VALIDATION problem?

Total Error

Are we solving the
problem fast enough?

Discretization Error

Are we solving the
VERIFICATION problem right?

Numerical Error



Mathematical Modelling

Continuous
Problem

Model Error

Mathematical
Model

Discrete Problem

Numerical
Solution

Total Error

Discretization Error

Numerical Error

Are we solving the right
VALIDATION problem?

Are we solving the
problem fast enough?

Are we solving the
VERIFICATION problem right?

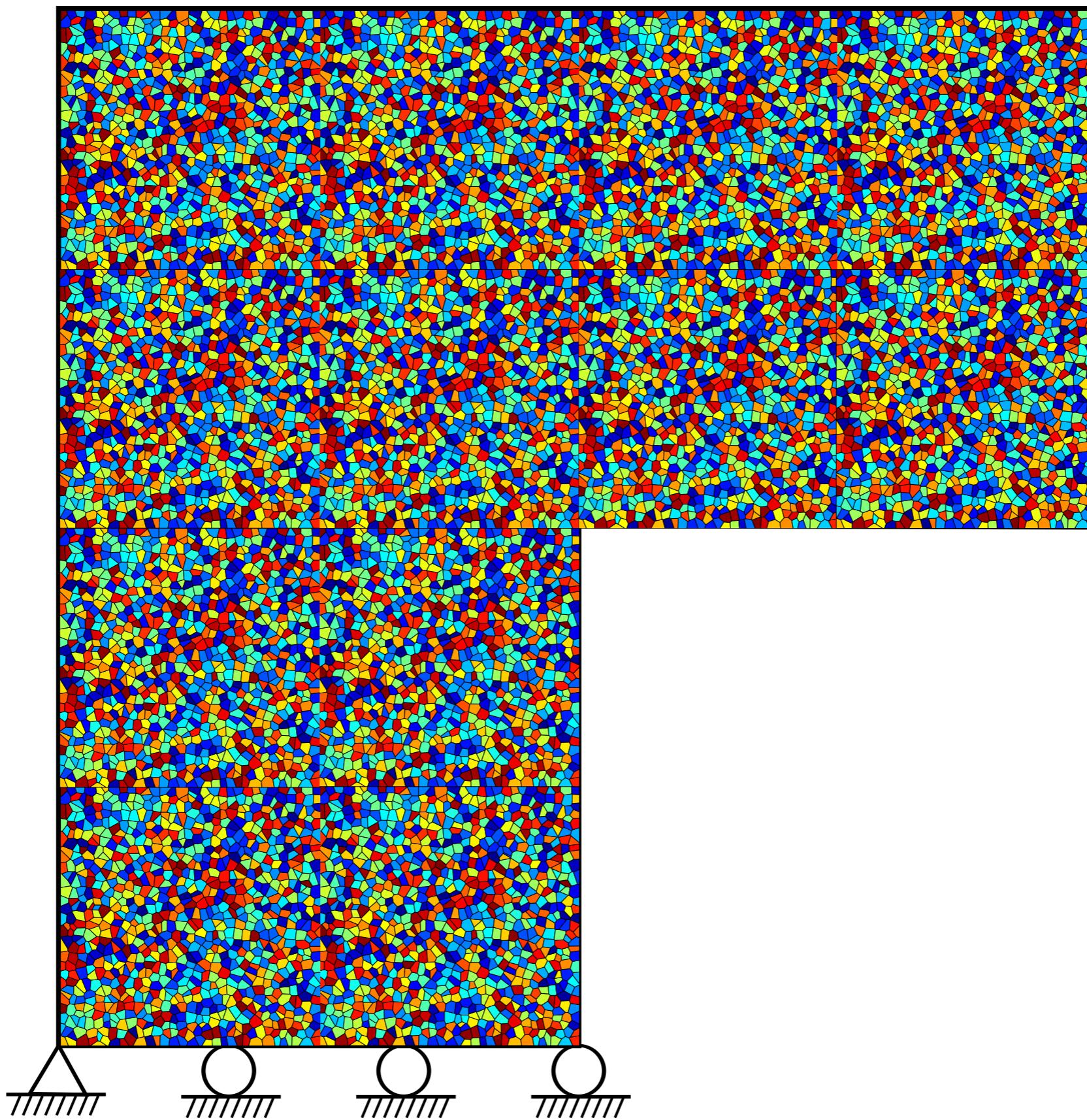
Exact solution is
not known

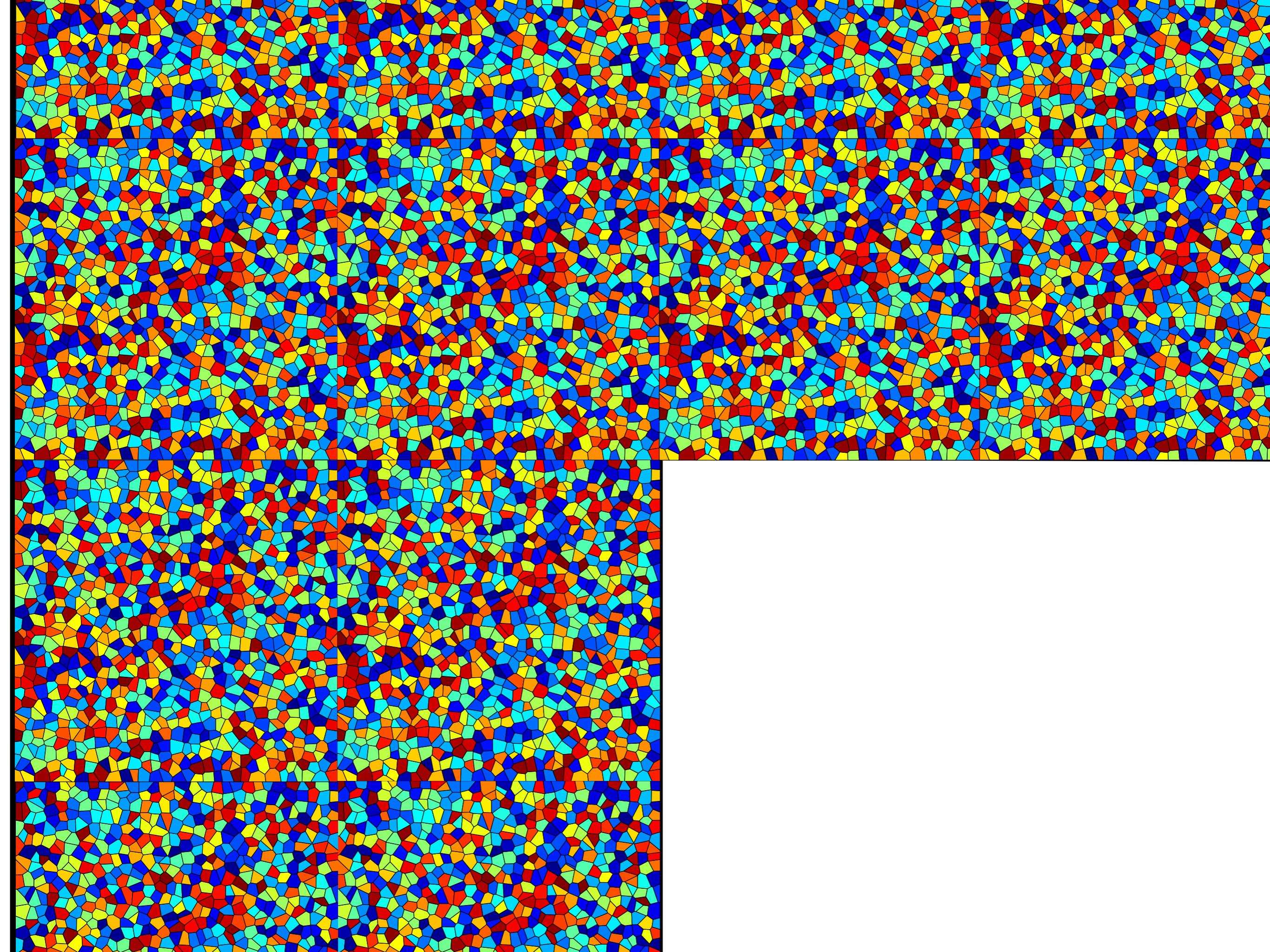


Physics-based model reduction methods

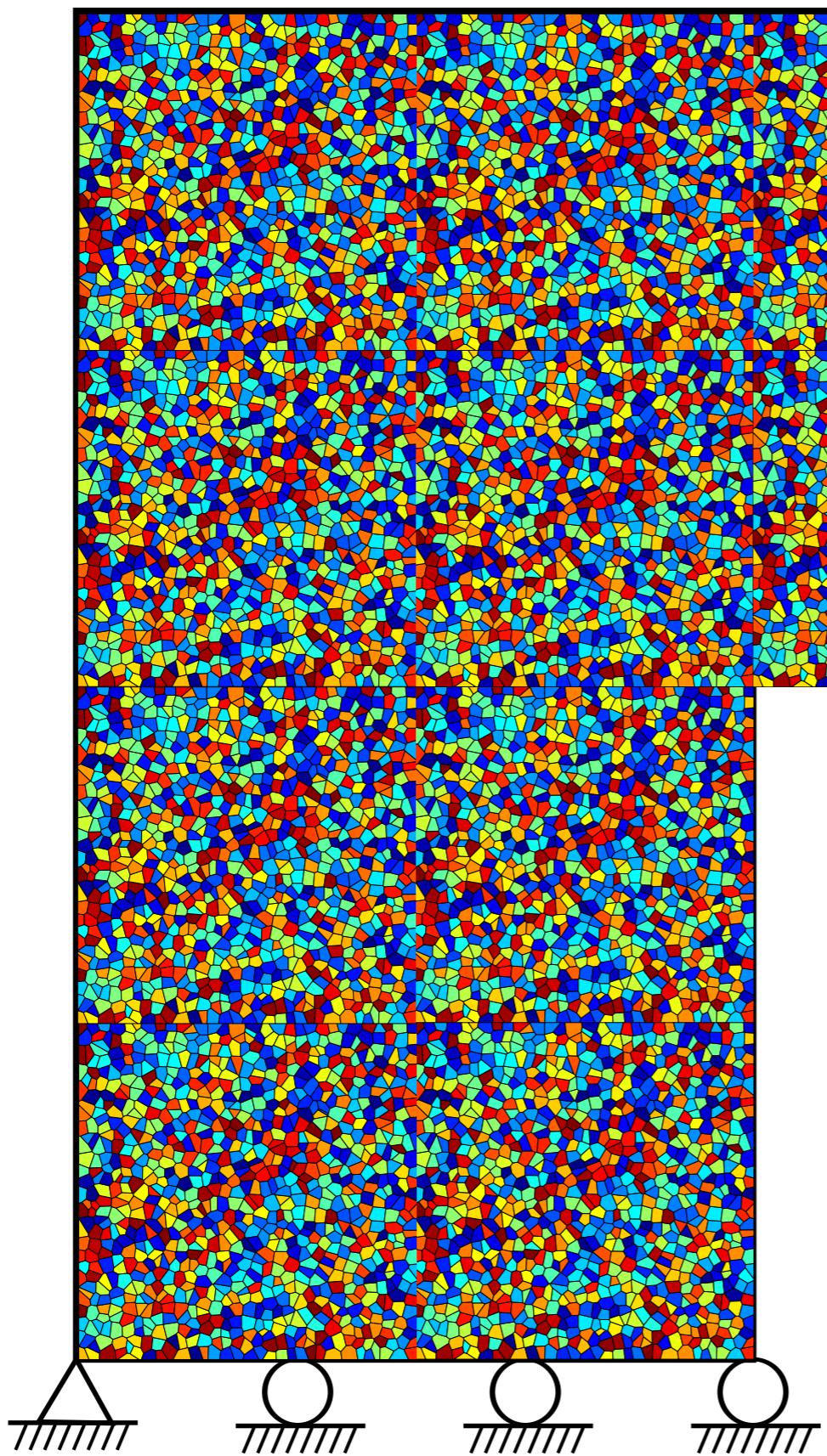
multi-scale methods

Full-scale



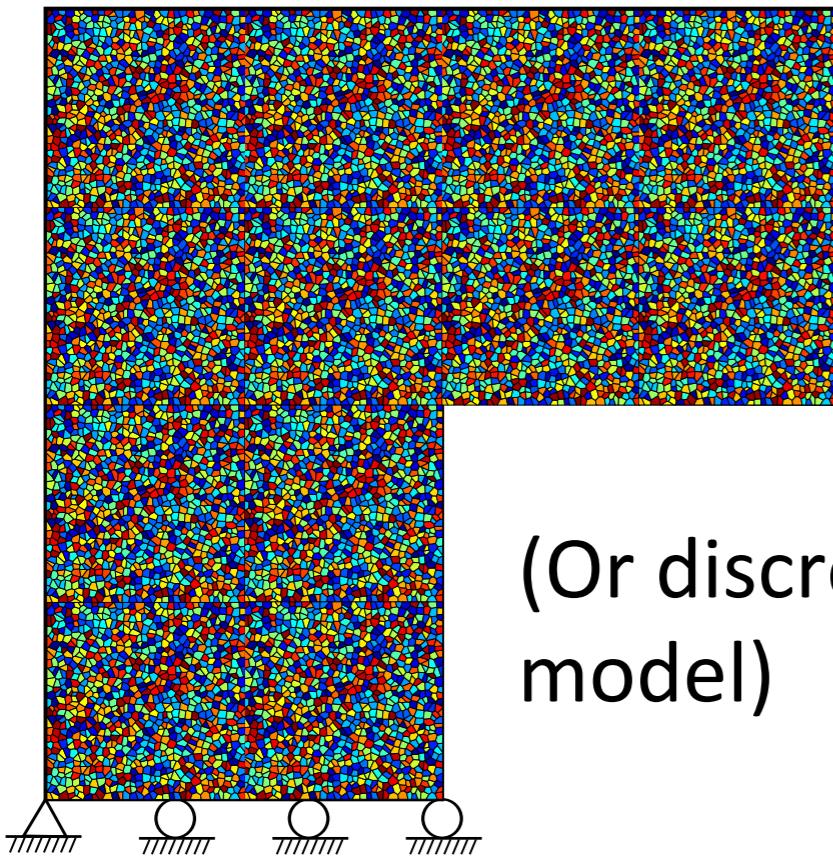


Full-scale

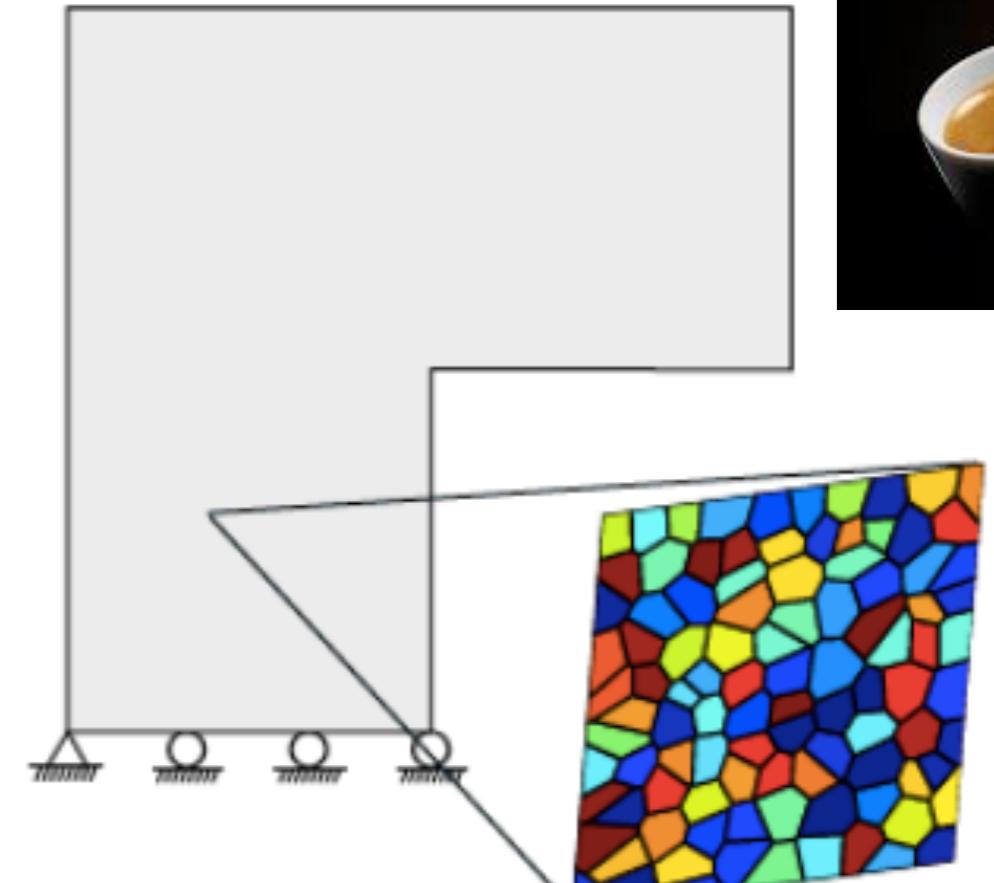
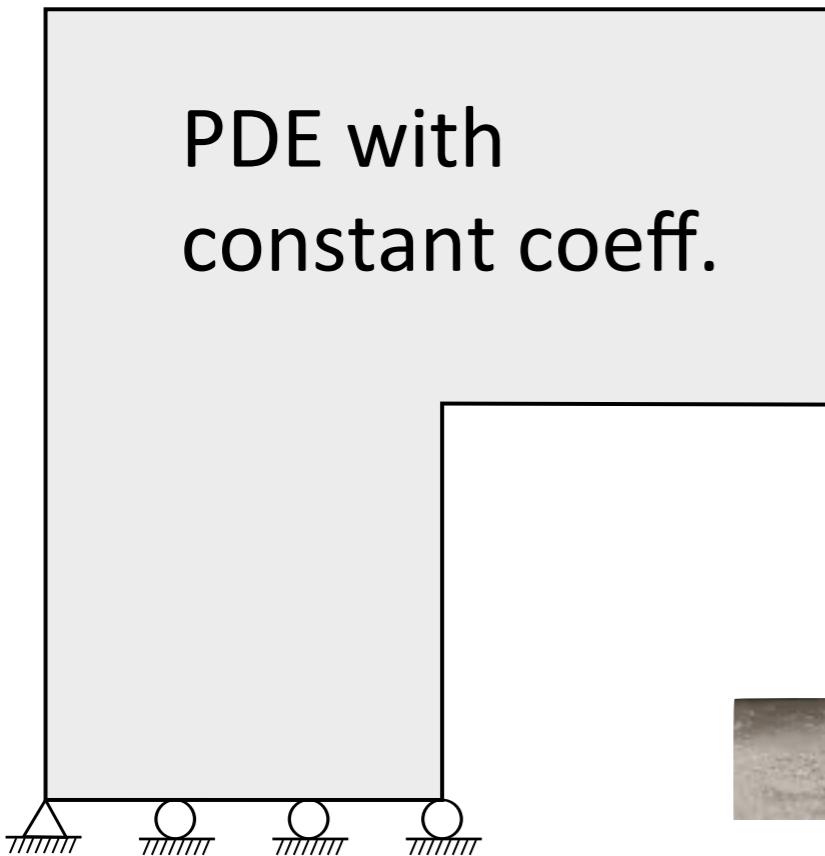


Multi-scale methods

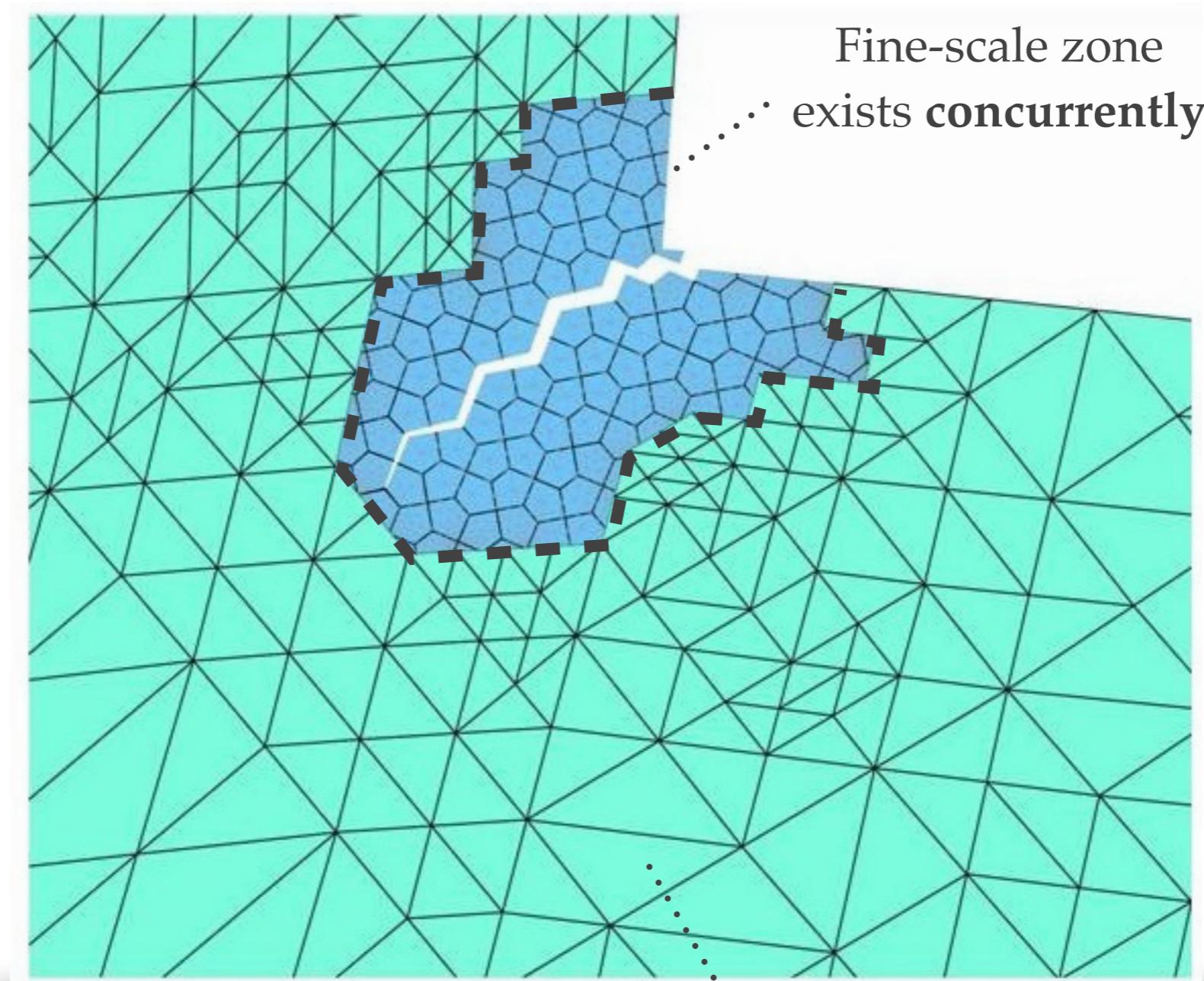
Replace the heterogeneous fine-scale model by an equivalent smoother model at the scale where the predictions are required



↓ Homogenisation

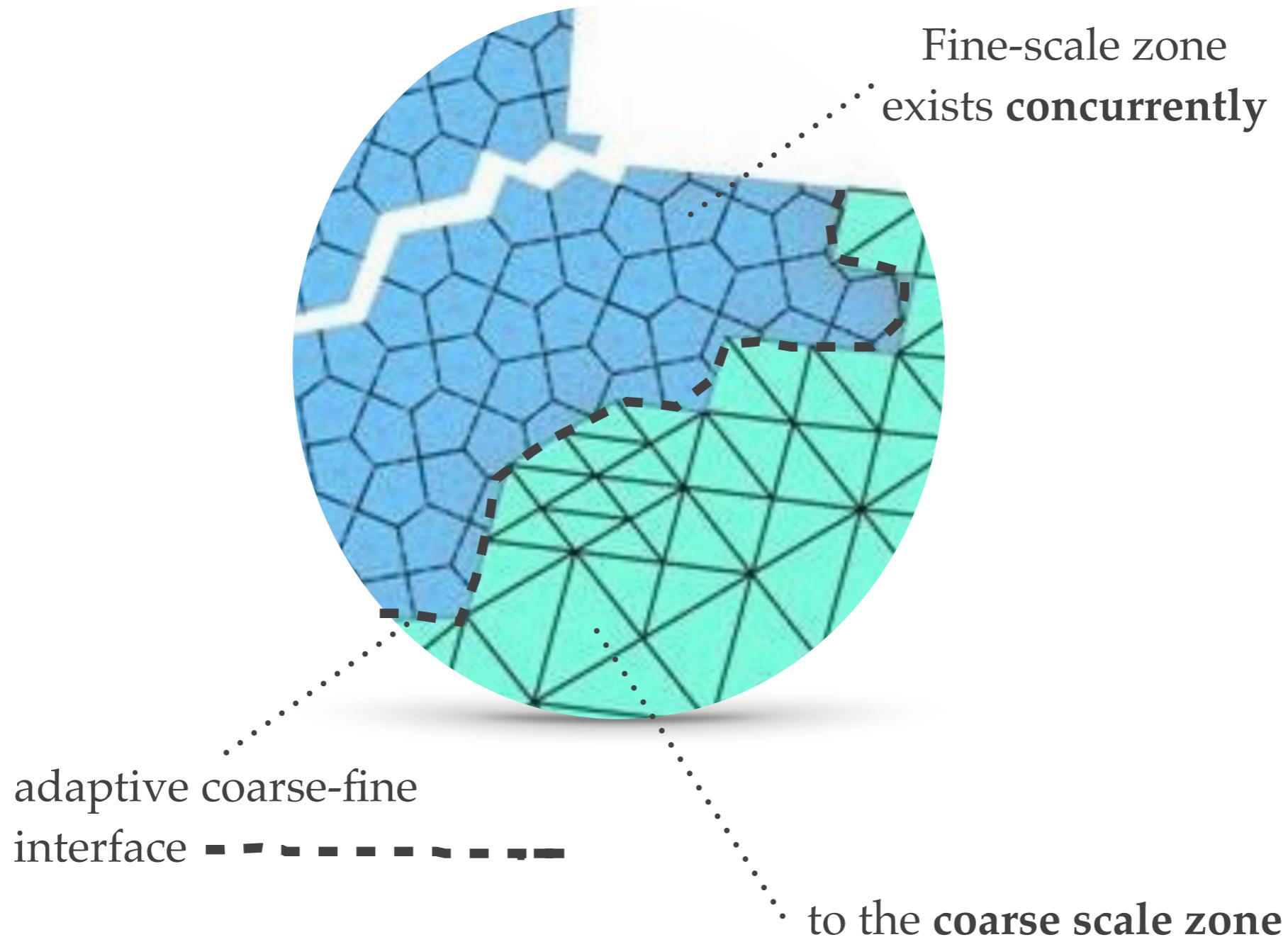


Concurrent methods

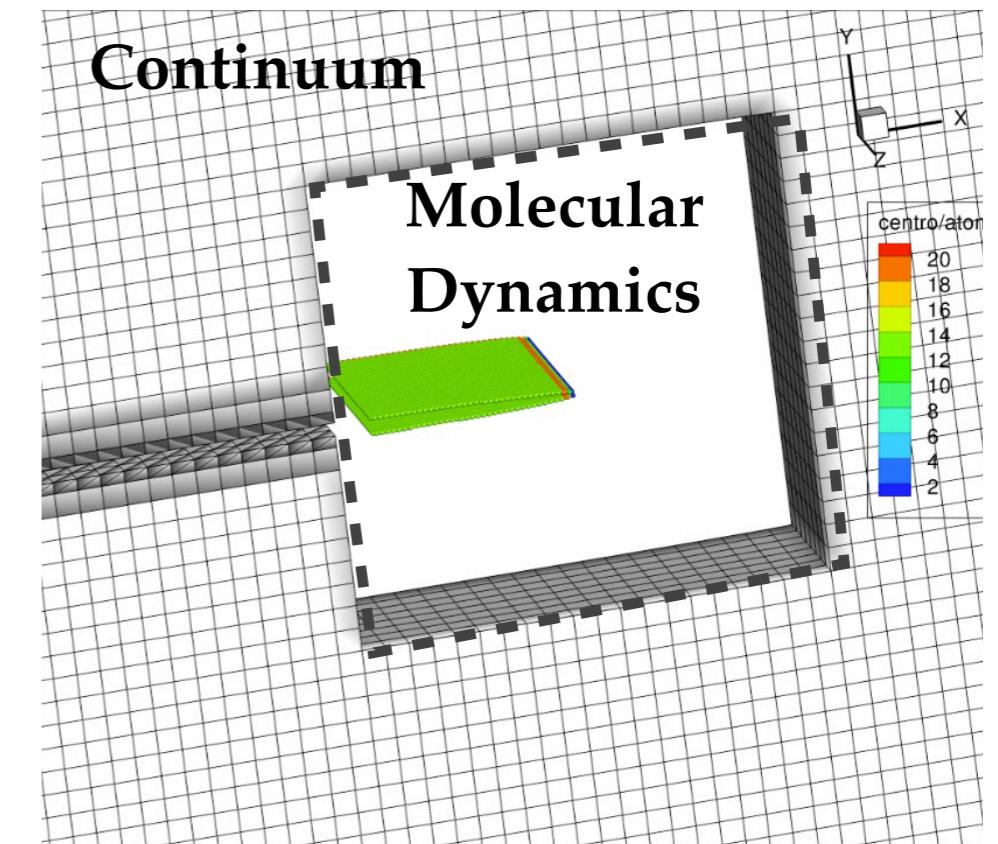
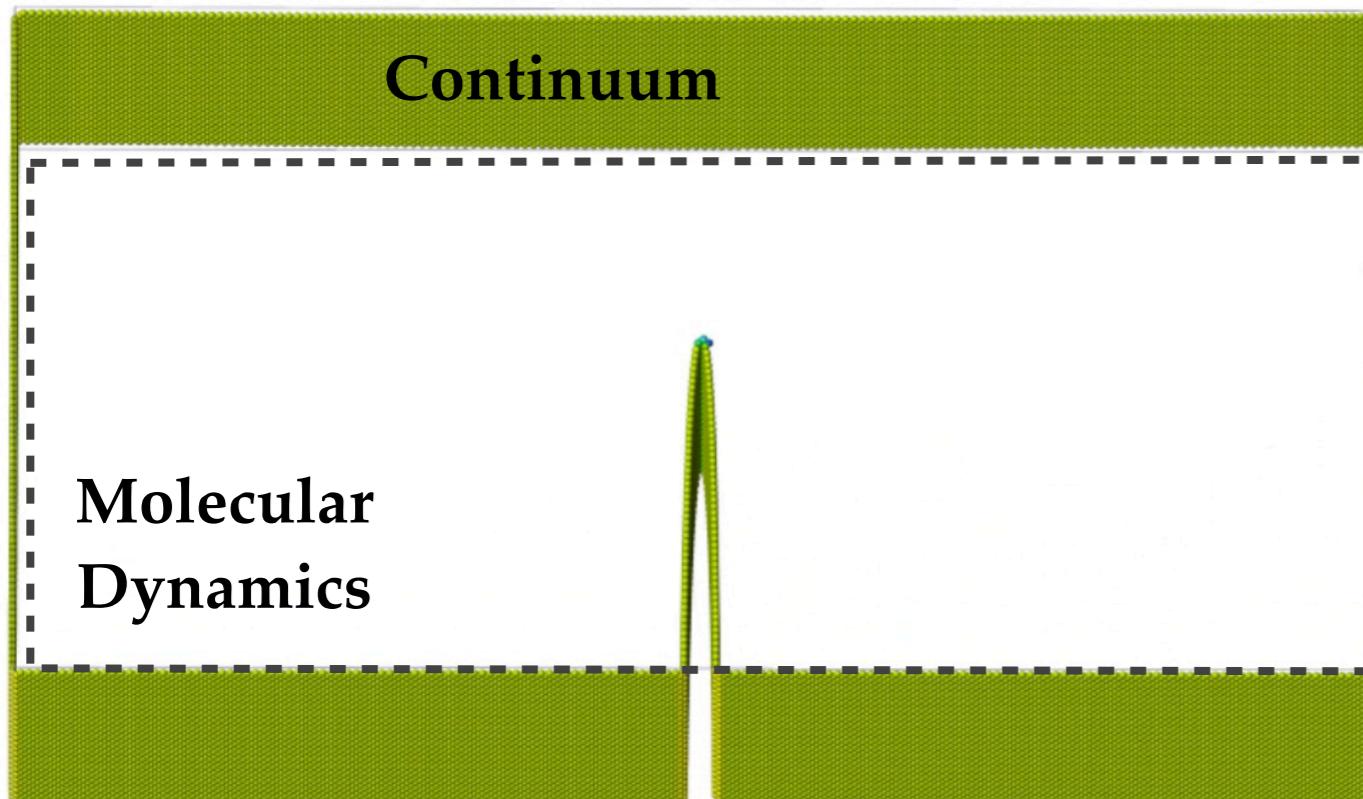
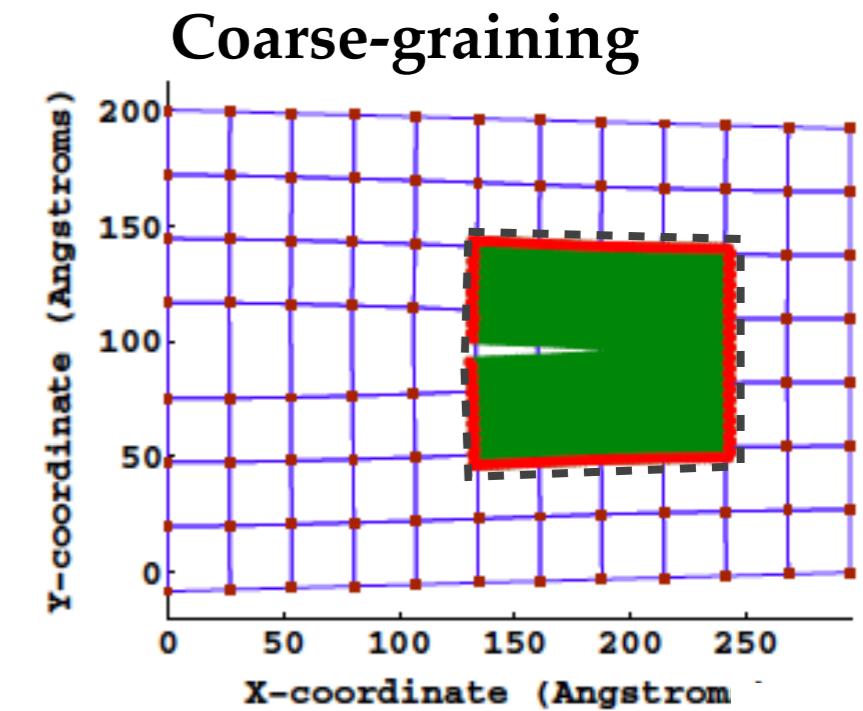
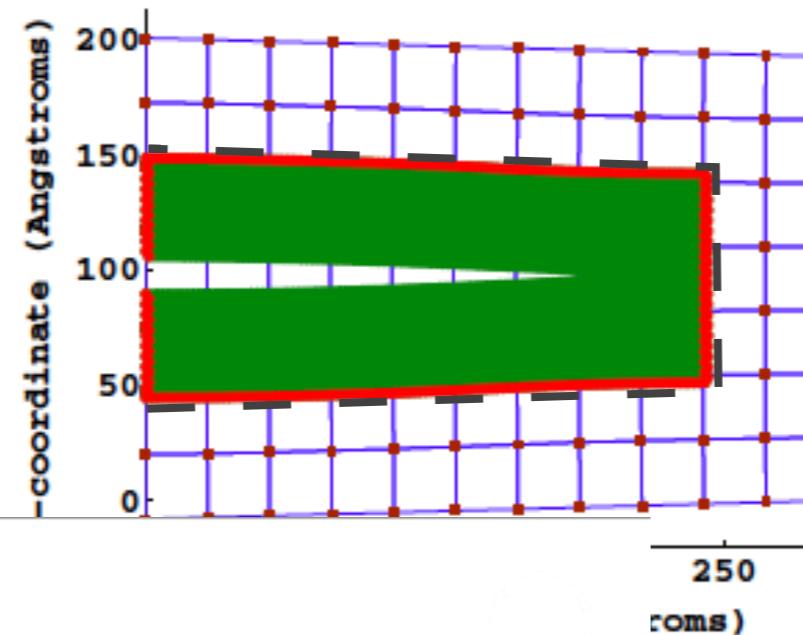
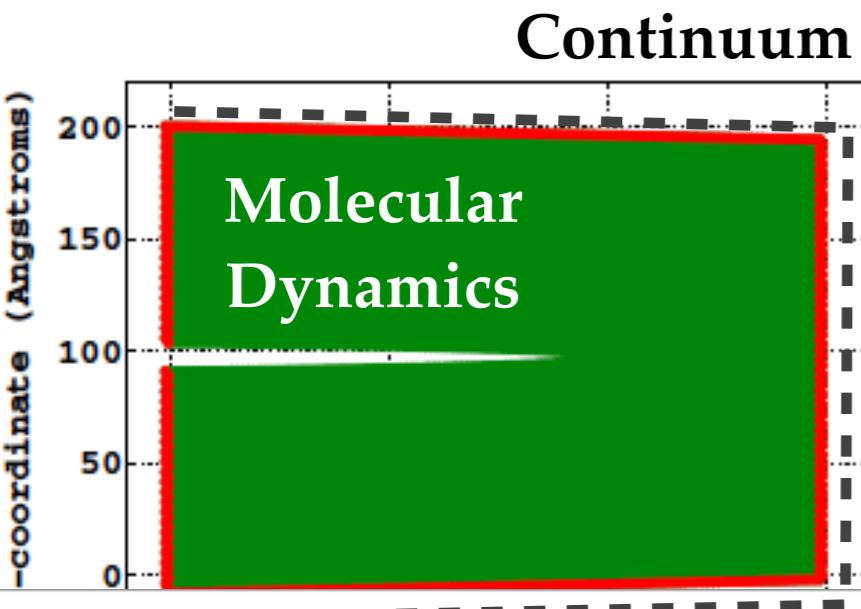


Akbari, Kerfriden, Bordas, 2014

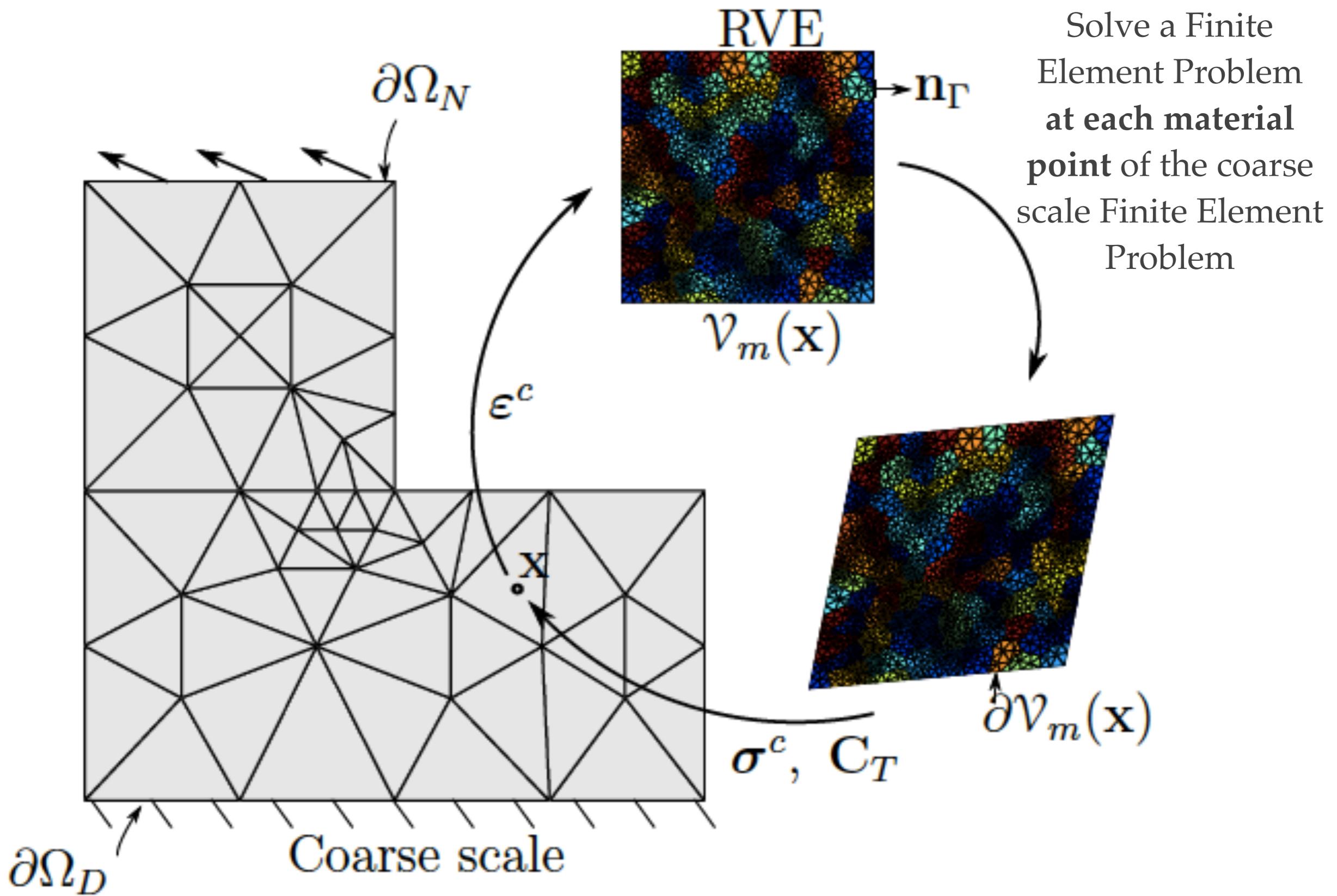
Concurrent methods



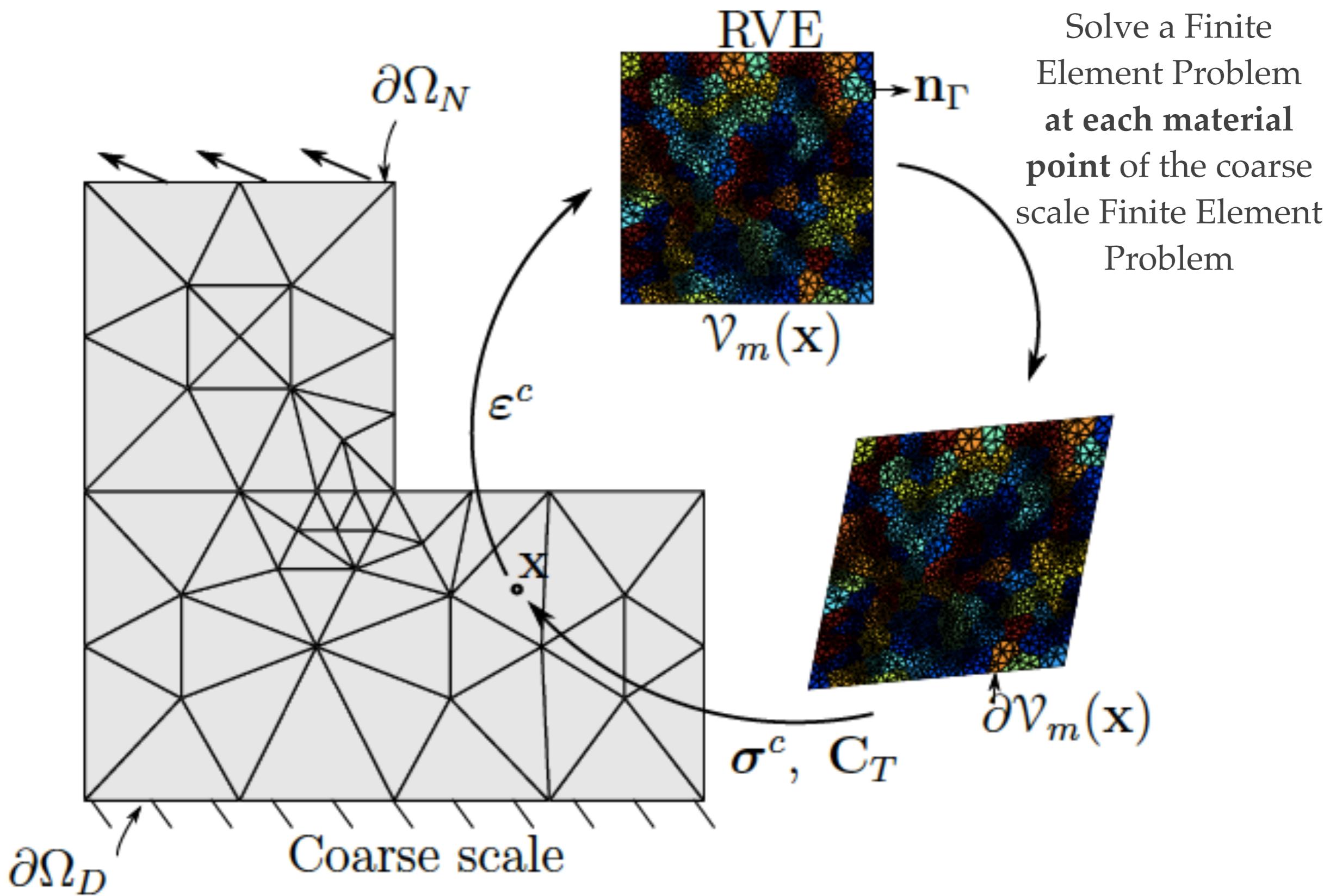
Concurrent methods



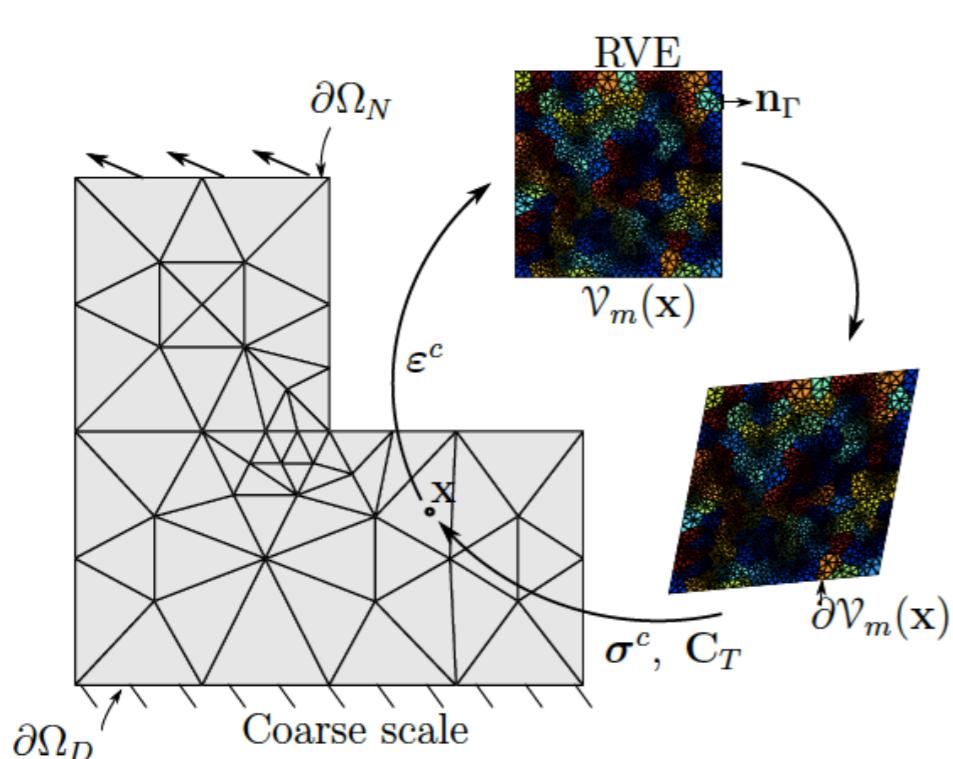
Hierarchical methods FEA²



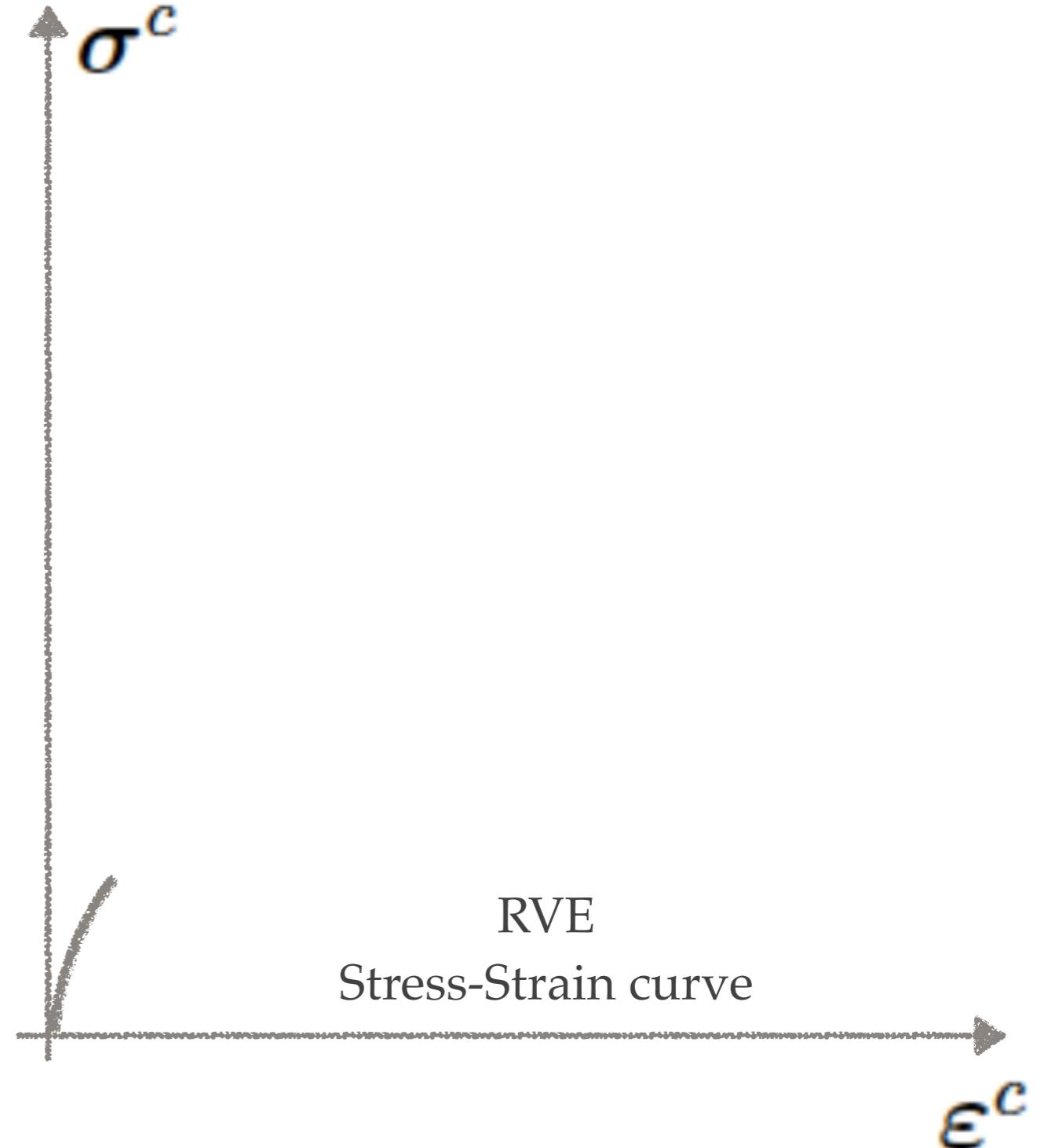
Hierarchical methods FEA²



Hierarchical methods FEA²

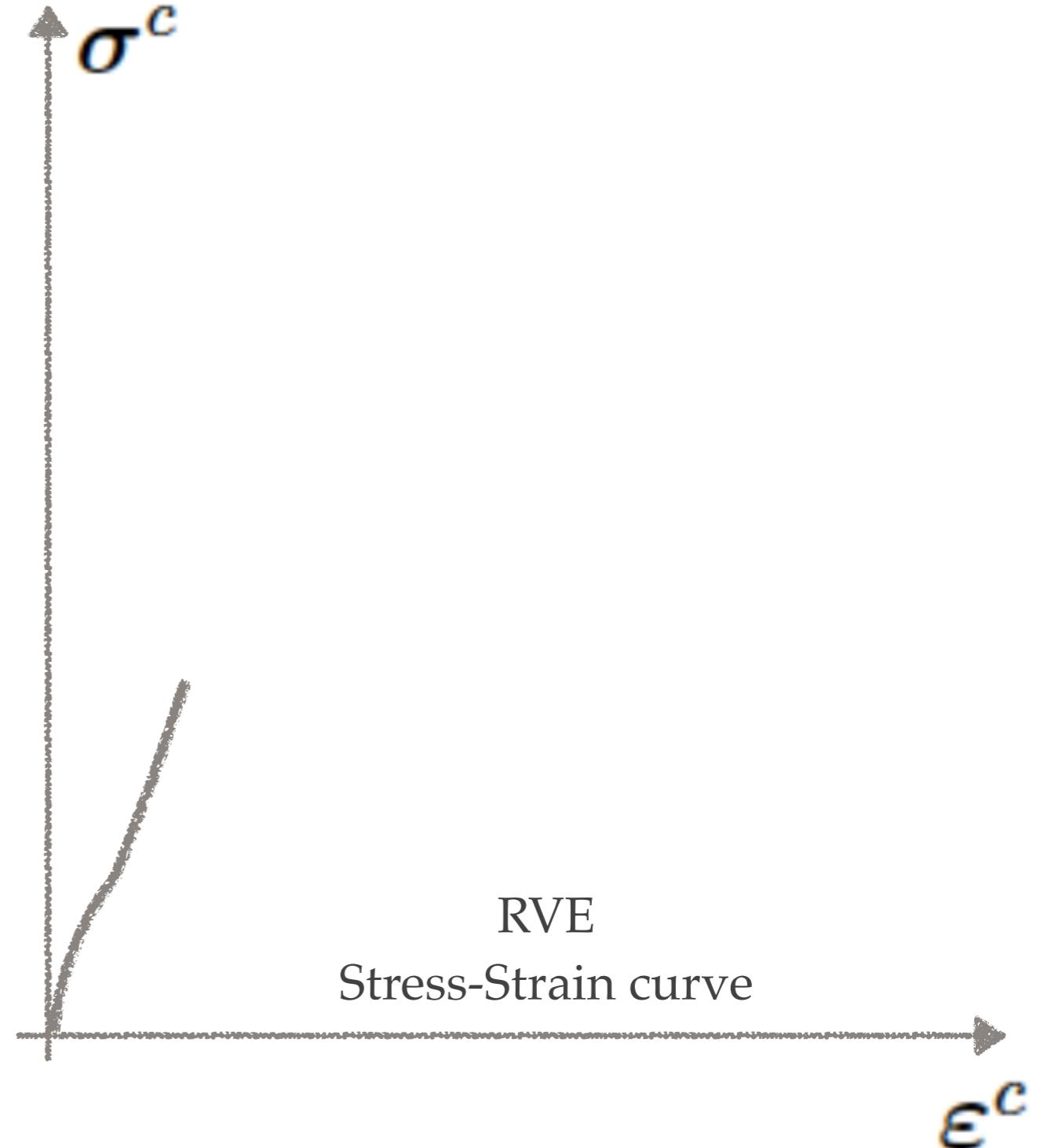
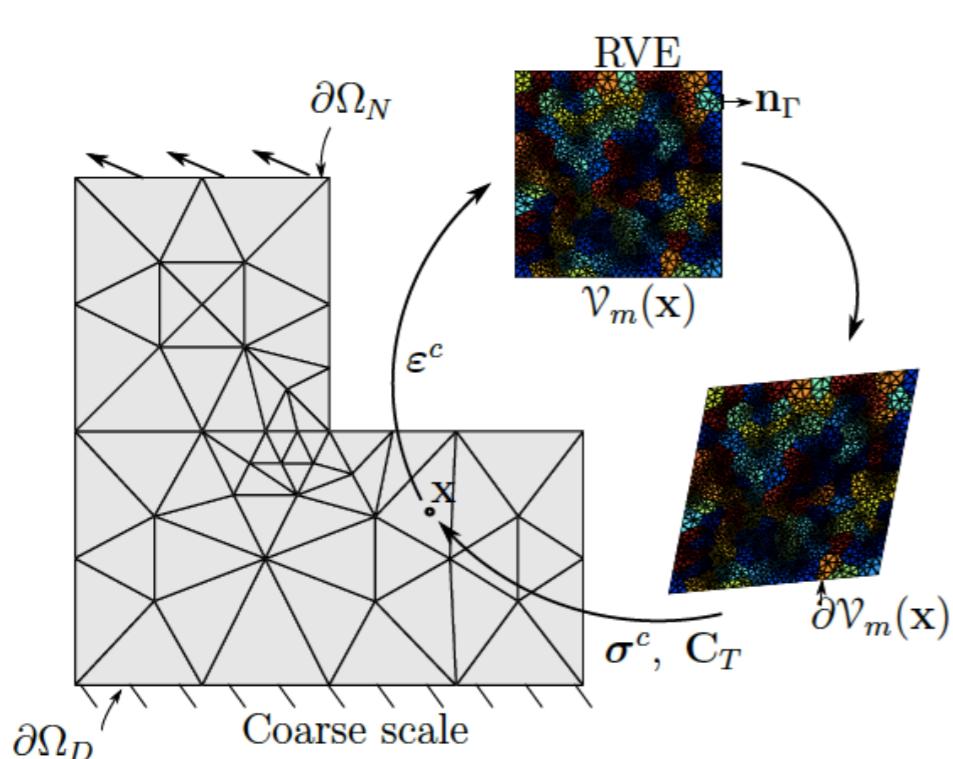


Loading



Feyel, Chaboche, 2000 - Akbari, Kerfriden, Bordas, 2014

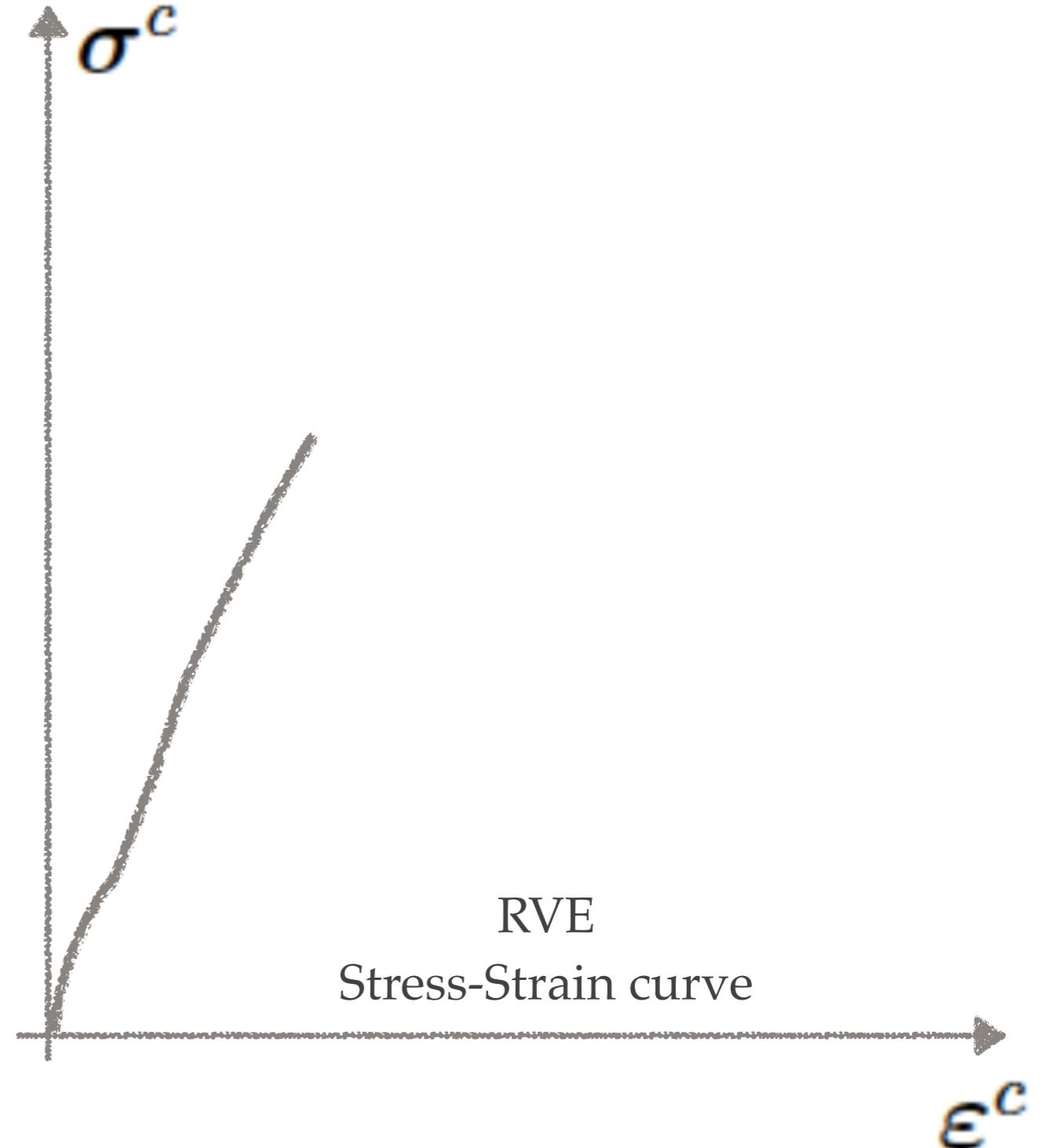
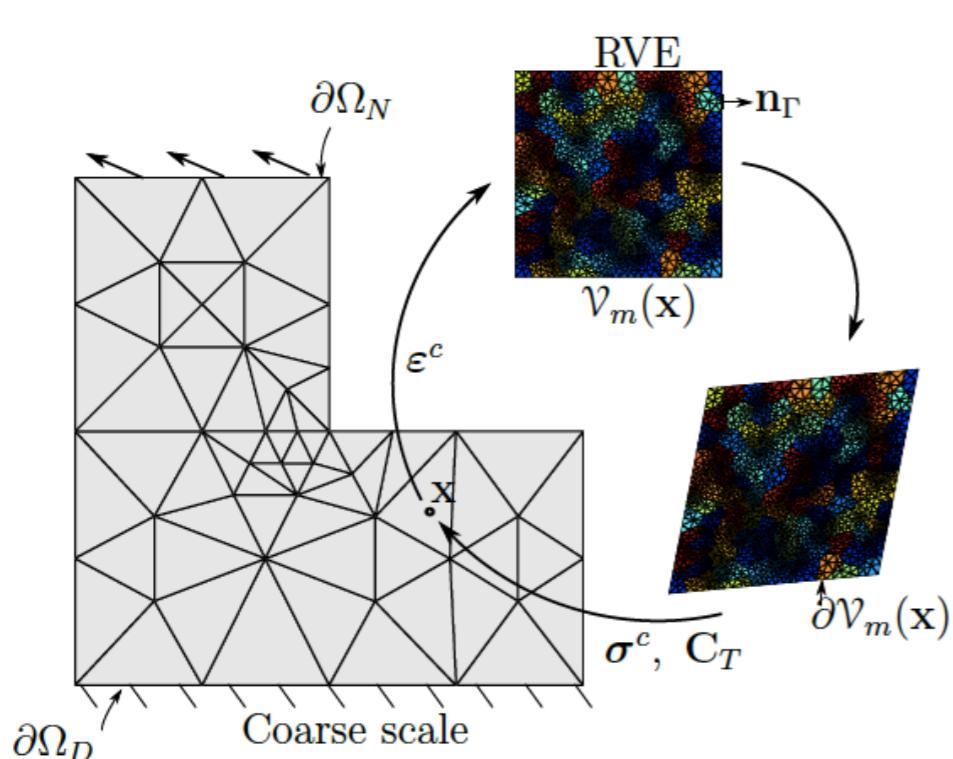
Hierarchical methods FEA²



Loading

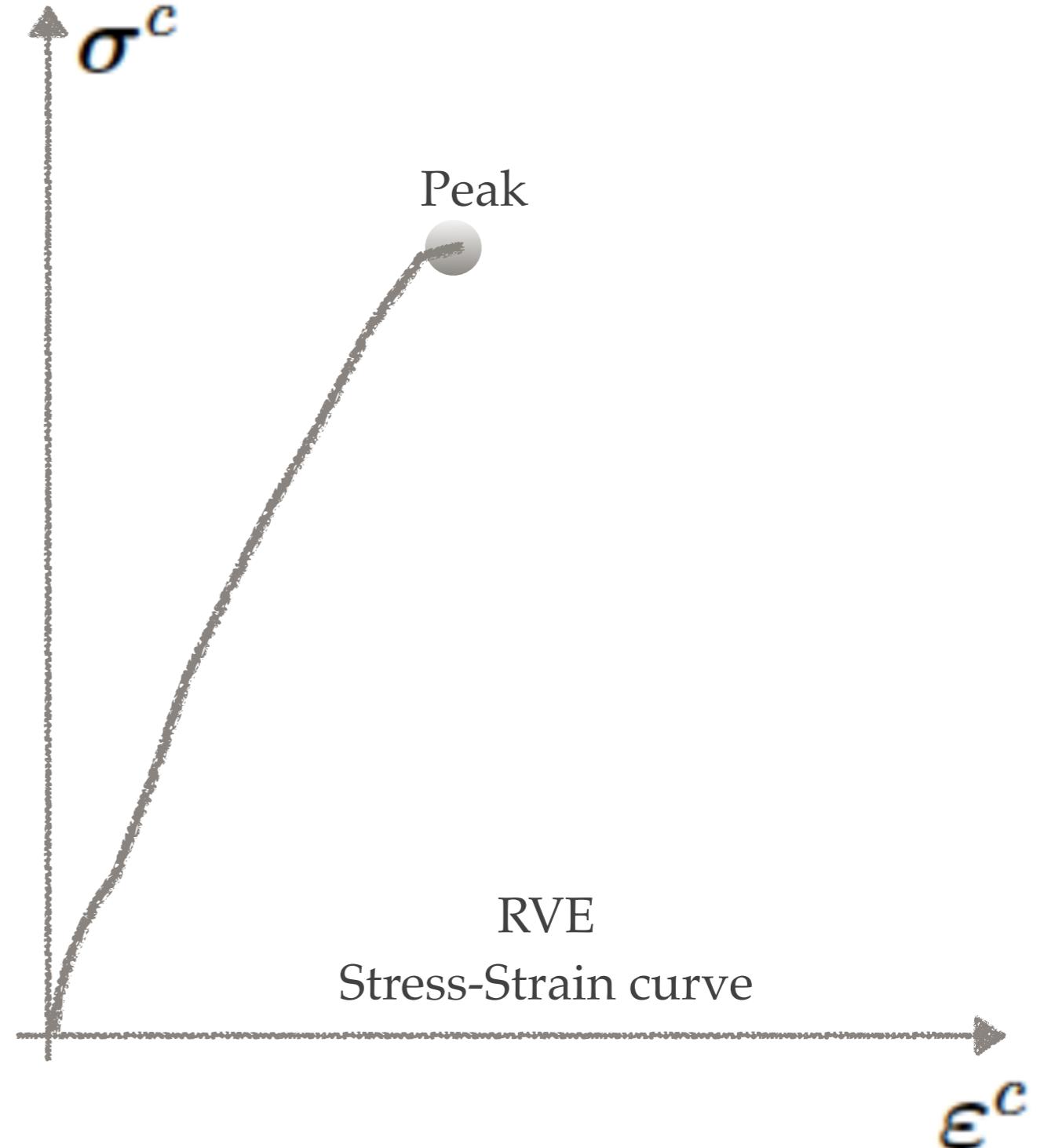
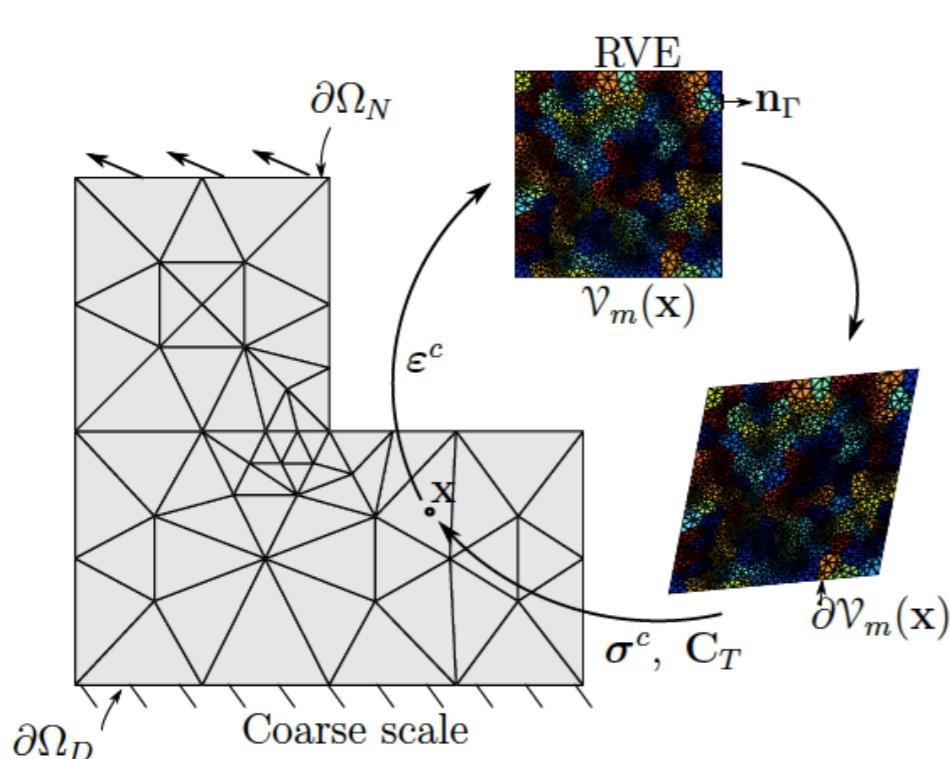
Feyel, Chaboche, 2000 - Akbari, Kerfriden, Bordas, 2014

Hierarchical methods FEA²



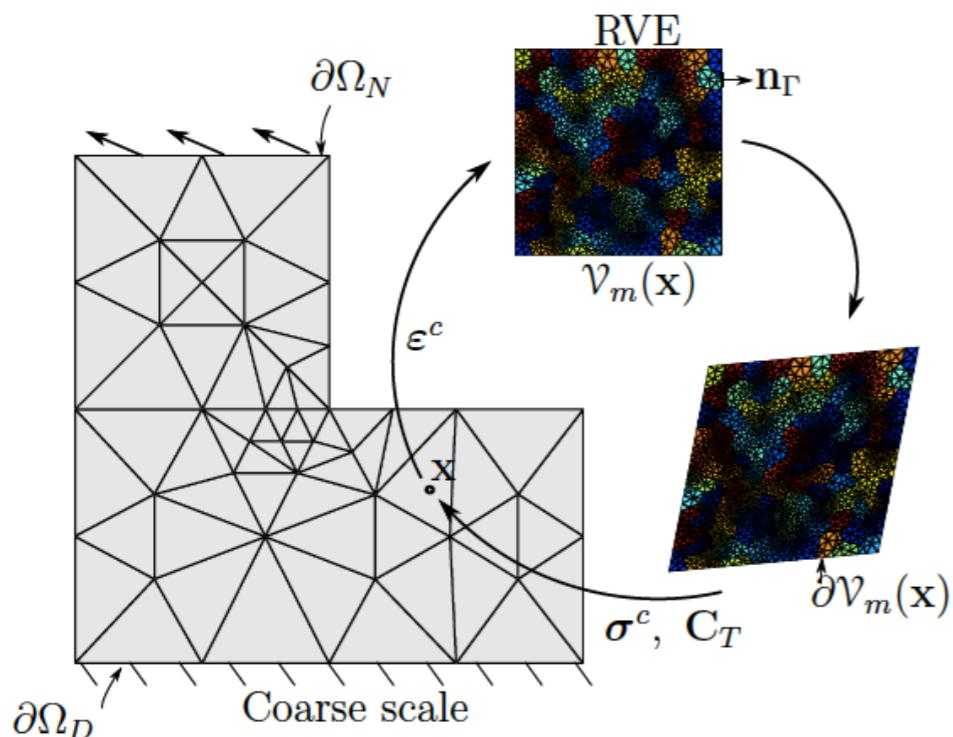
Feyel, Chaboche, 2000 - Akbari, Kerfriden, Bordas, 2014

Hierarchical methods FEA²

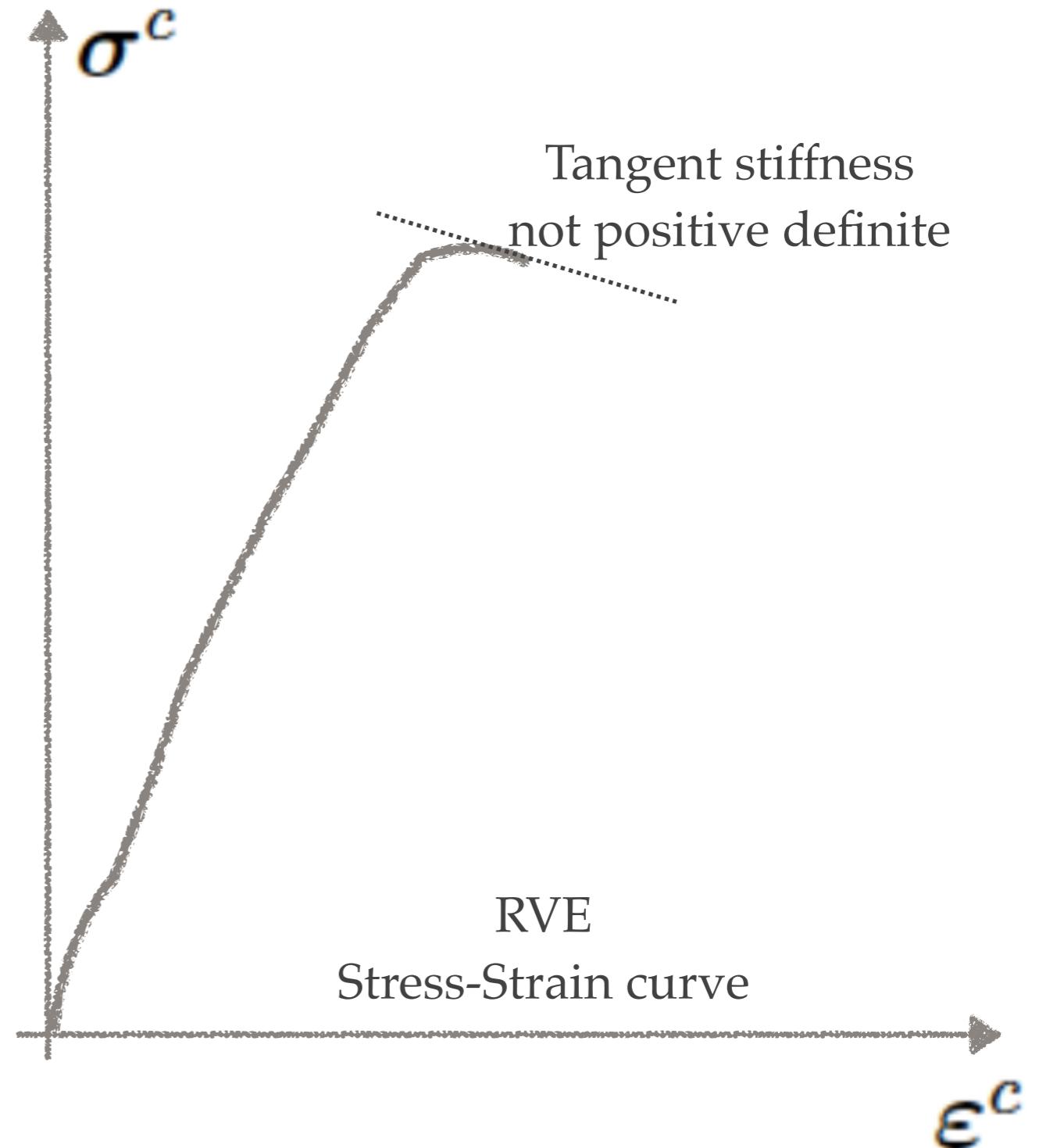


Feyel, Chaboche, 2000 - Akbari, Kerfriden, Bordas, 2014

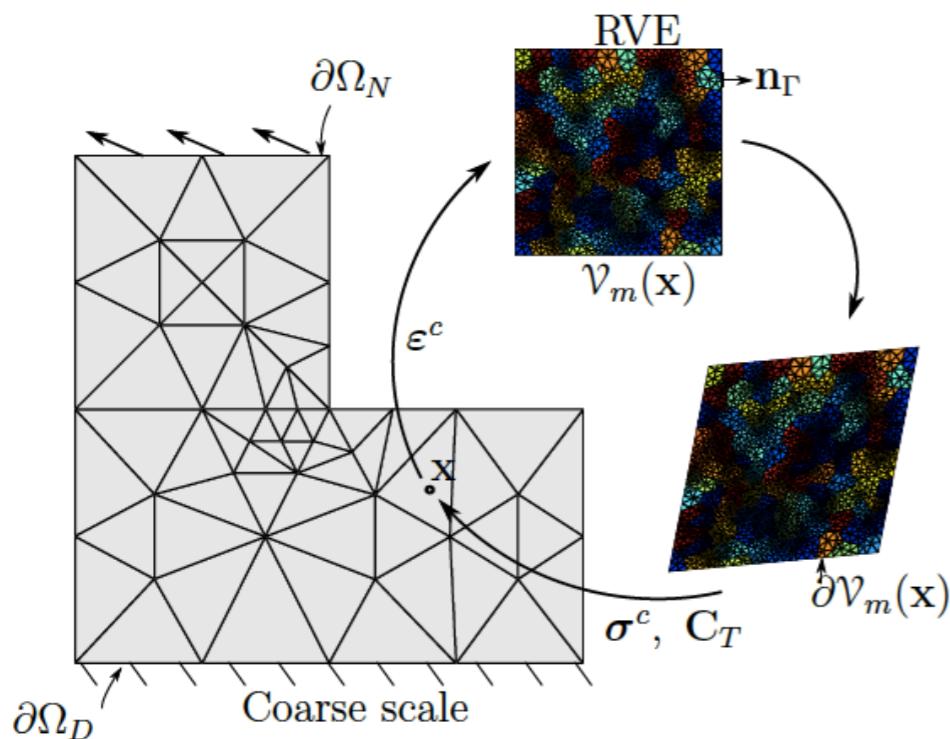
Hierarchical methods FEA²



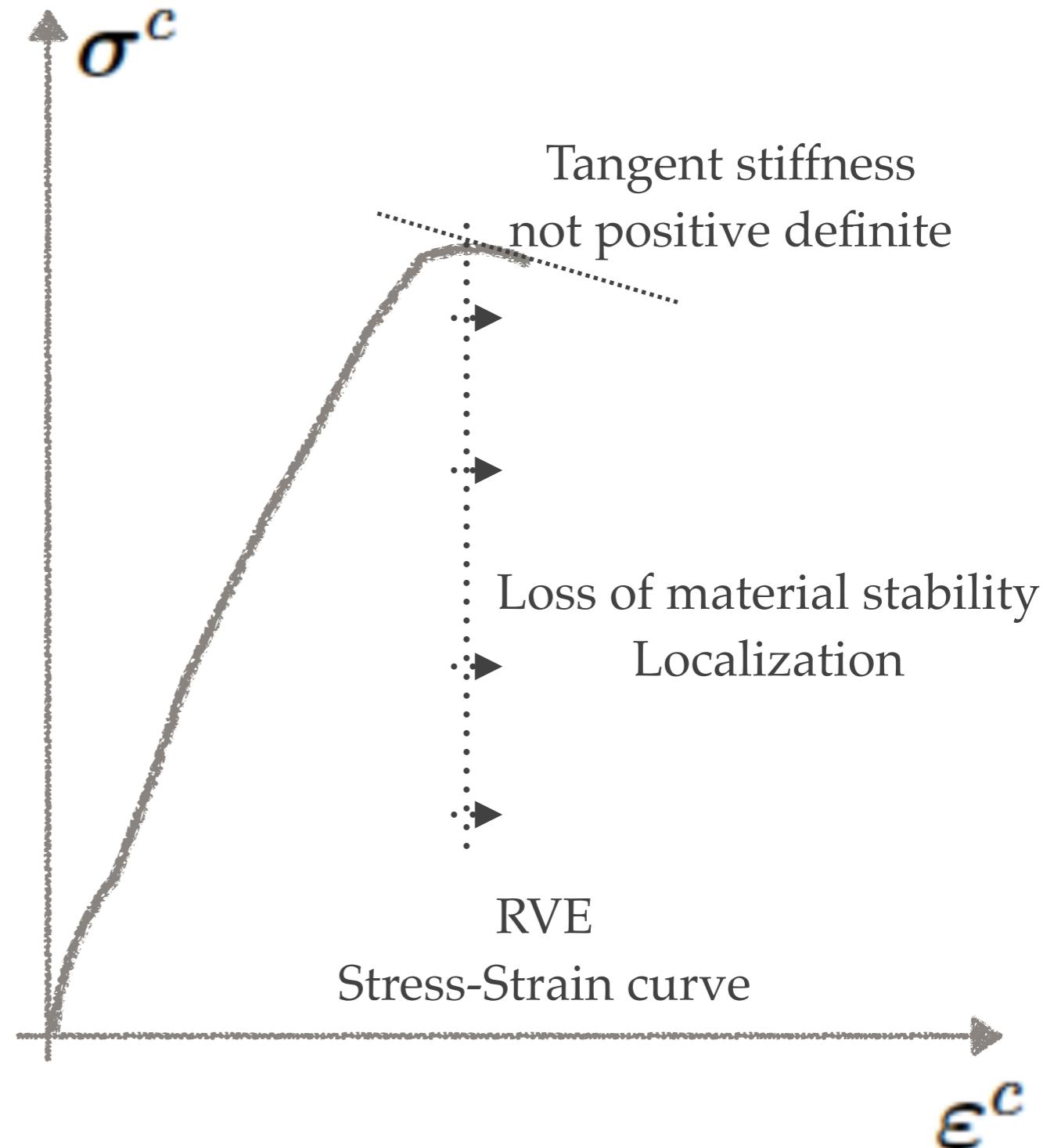
Unloading



Hierarchical methods FEA²

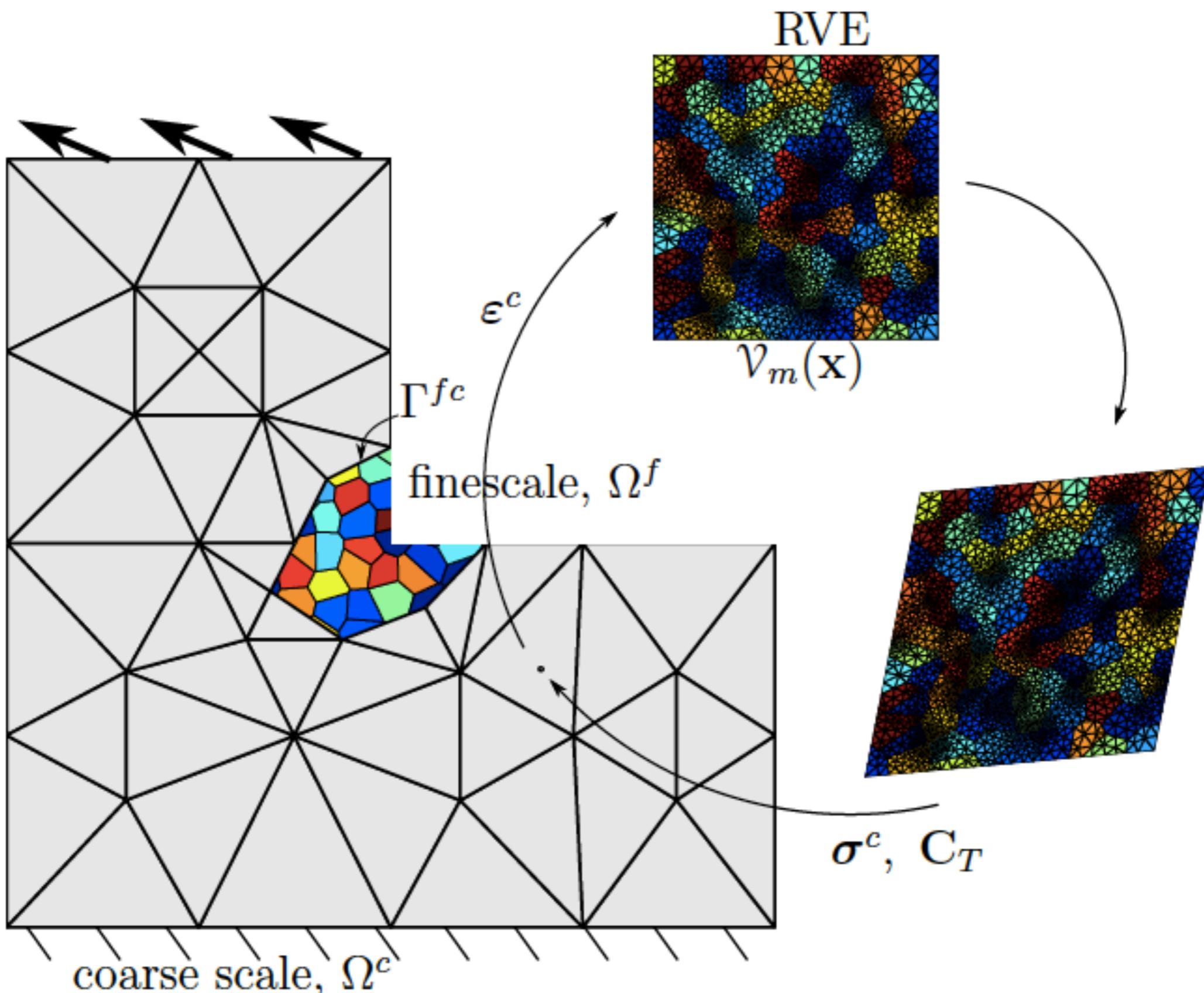


Unloading
RVE does not exist



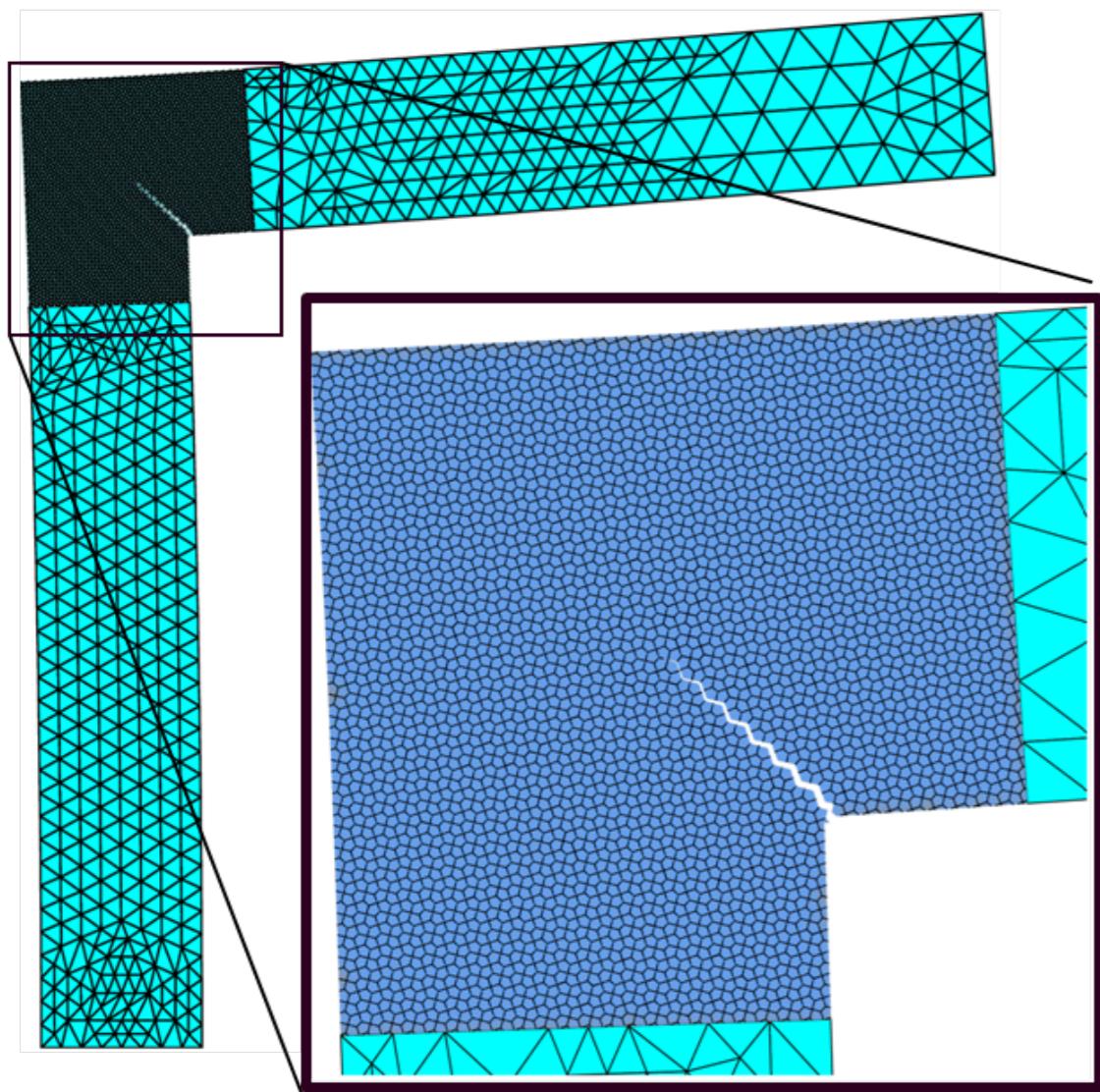
Feyel, Chaboche, 2000 - Akbari, Kerfriden, Bordas, 2014

Hybrid methods

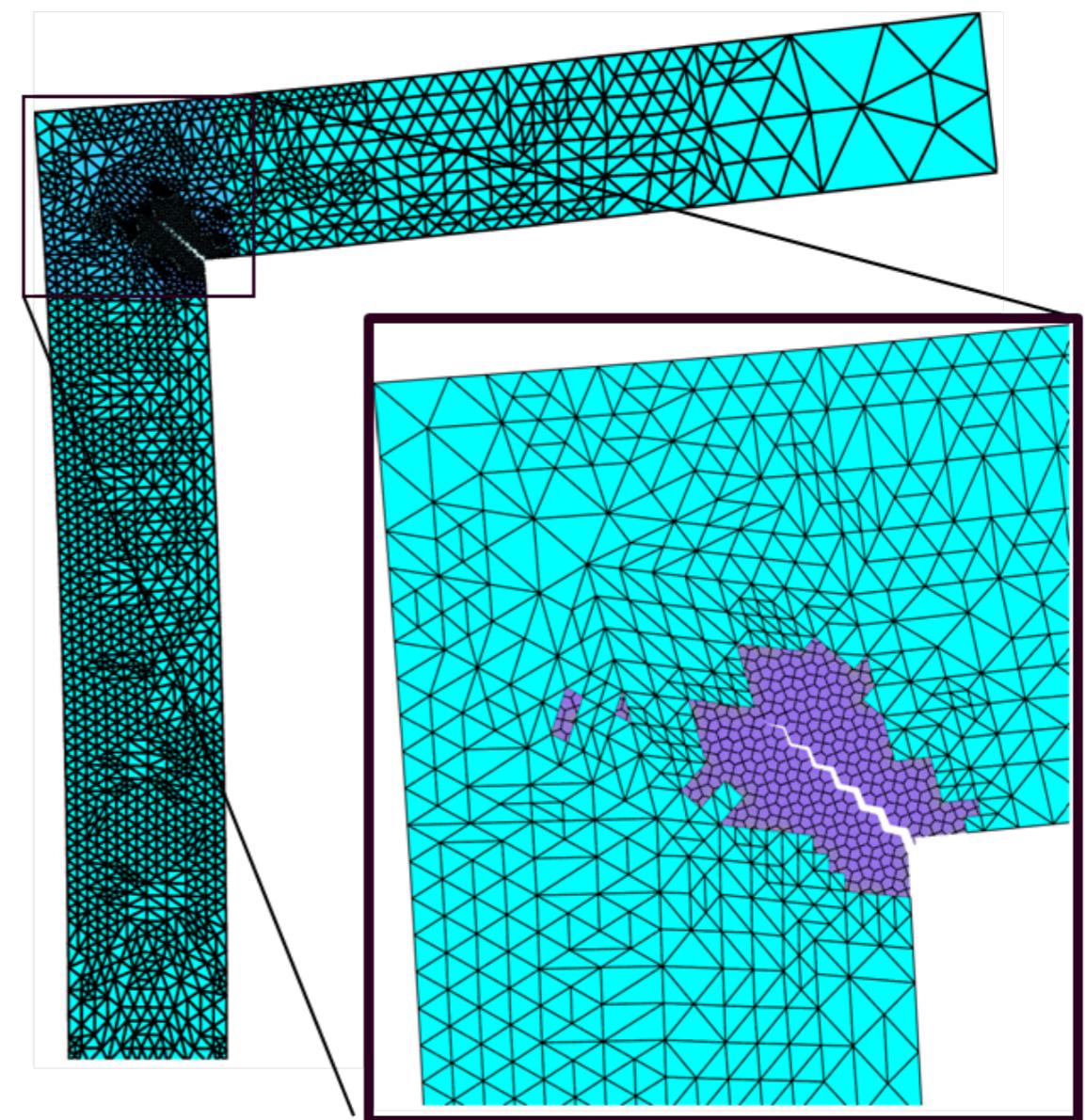


Example

Direct Numerical Solution



Adaptive Multiscale method

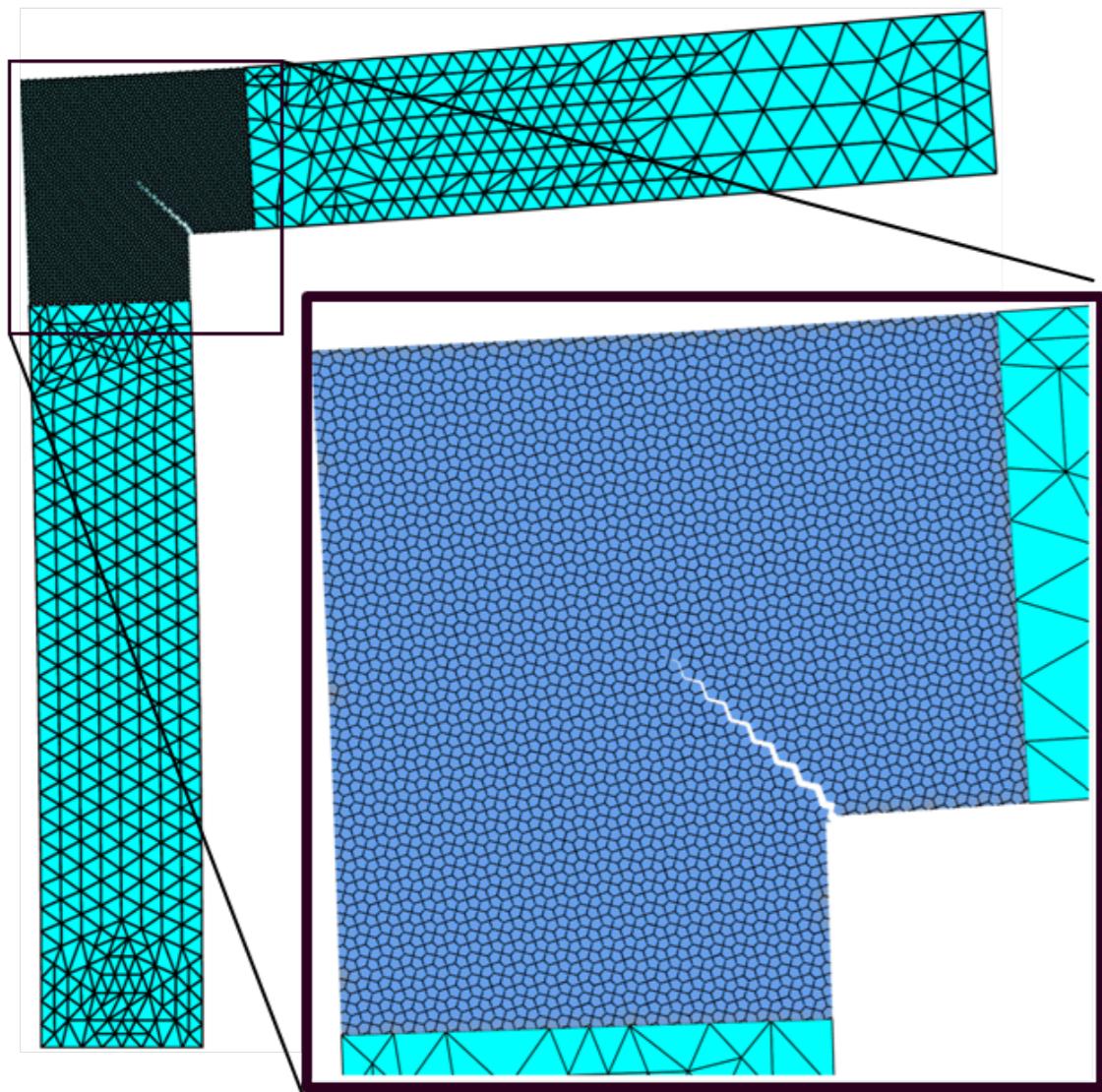


Example

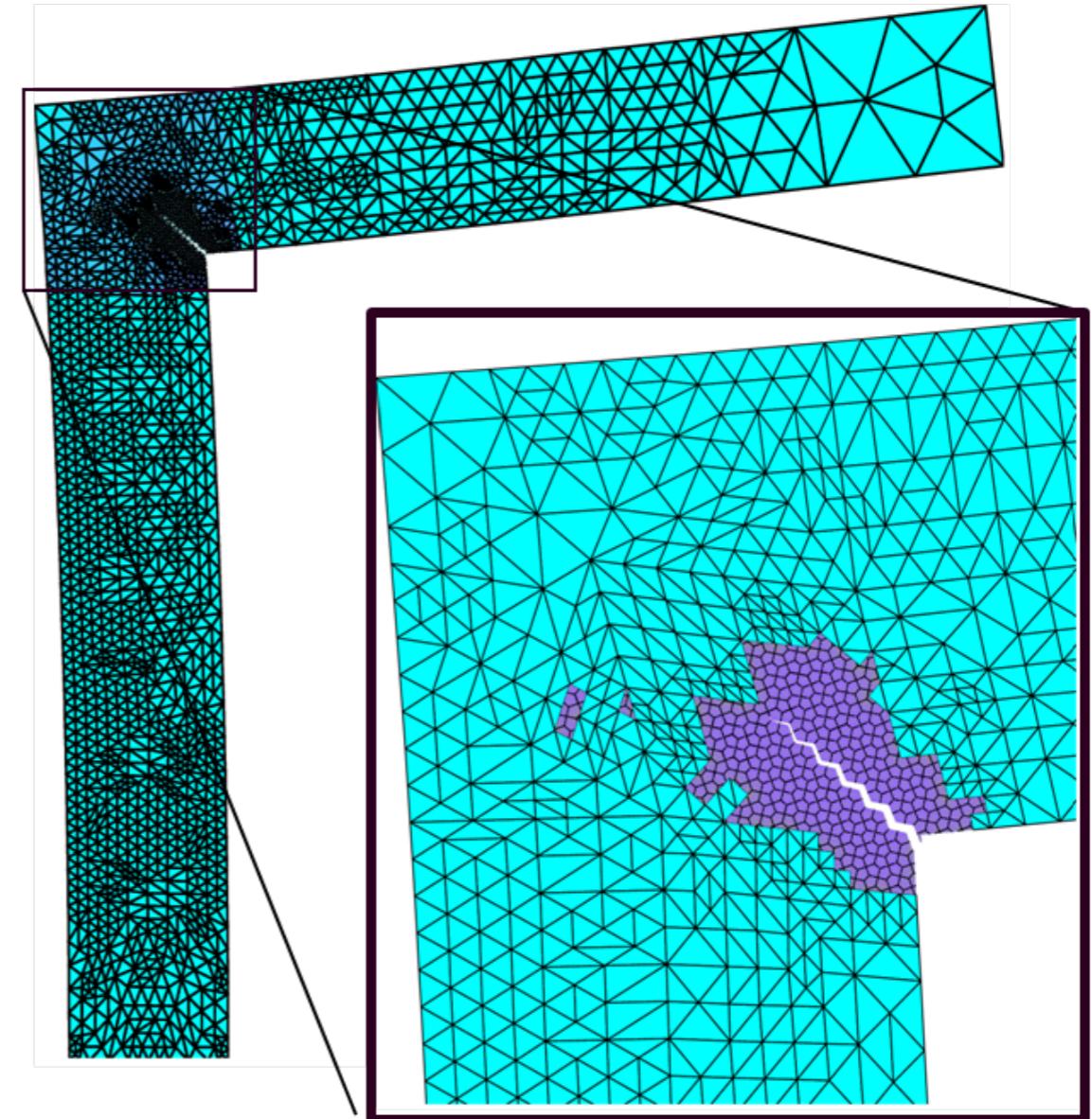


20-100 times fewer unknowns in 2D ~ 1000 times fewer in 3D

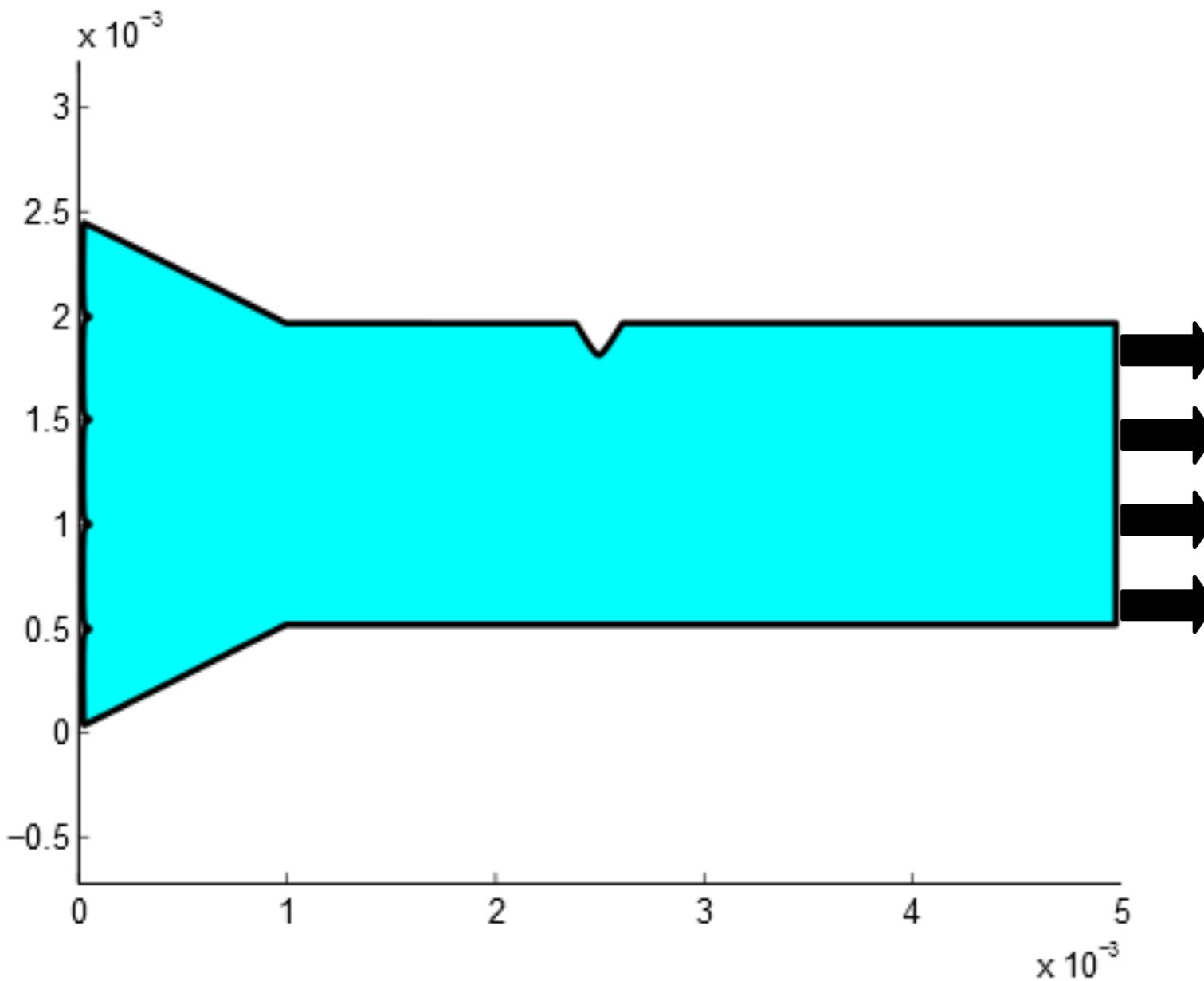
Direct Numerical Solution



Adaptive Multiscale method

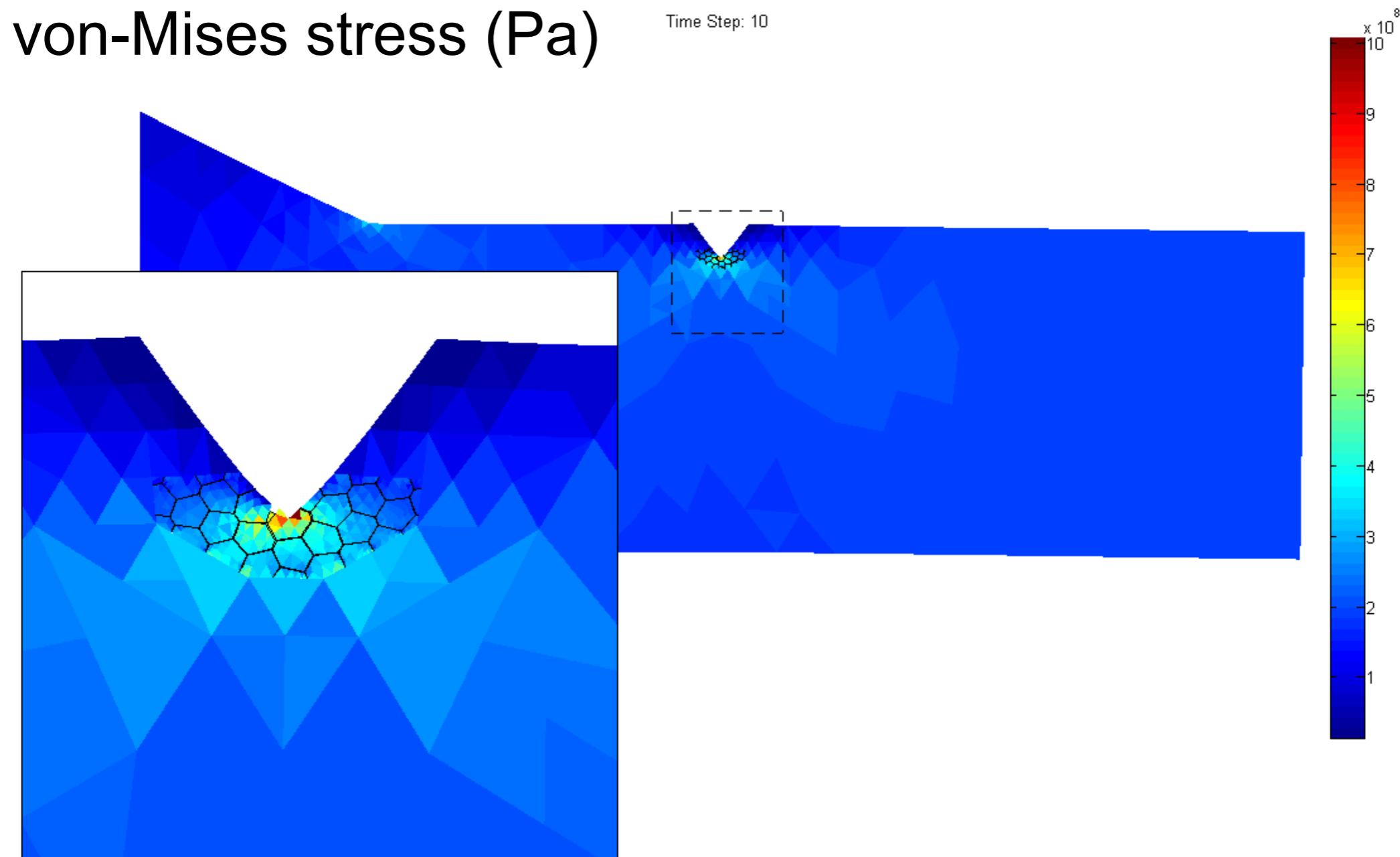


Results: uni-axial tension



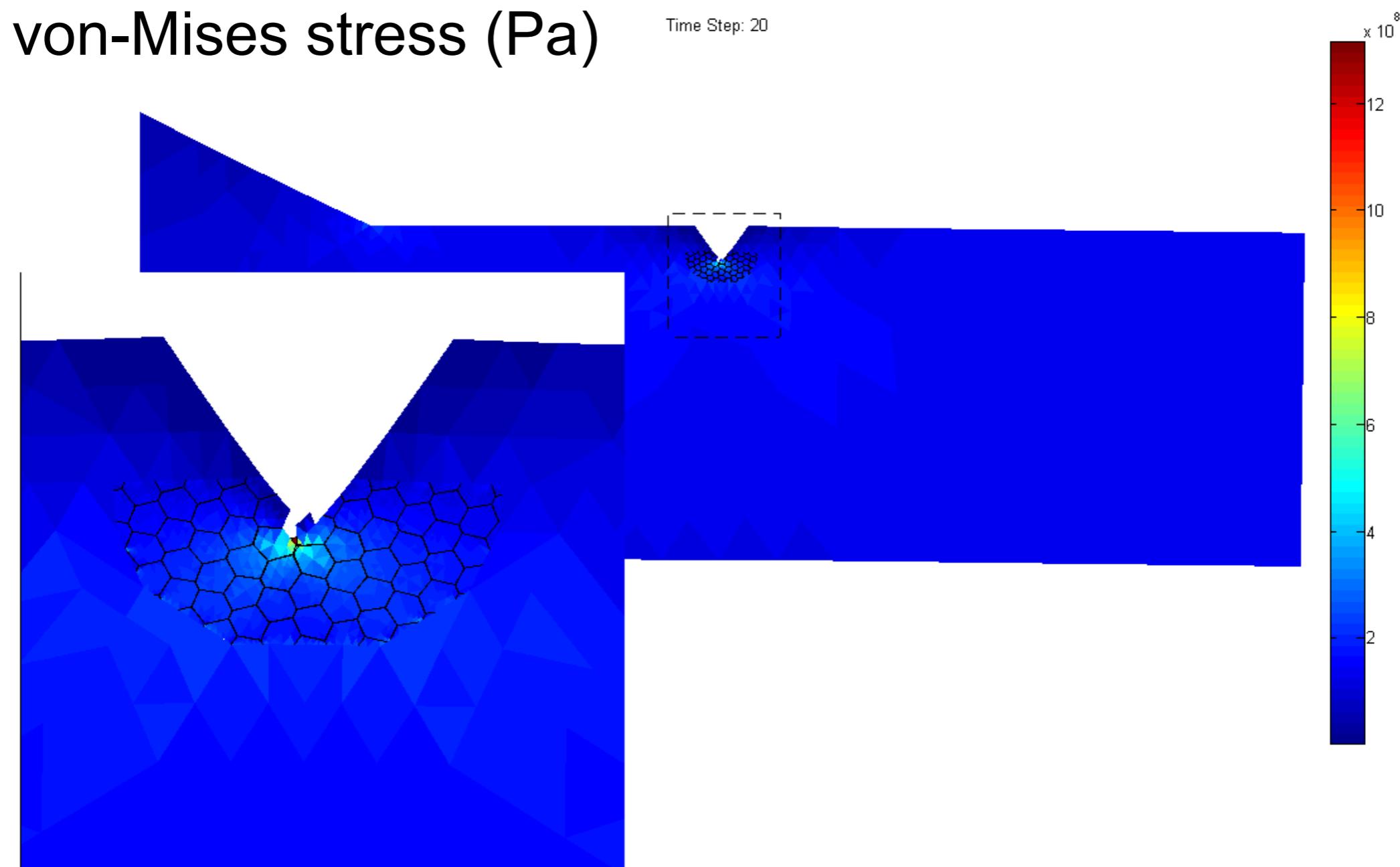
- ❖ Sizes are in mm

Results: uni-axial tension



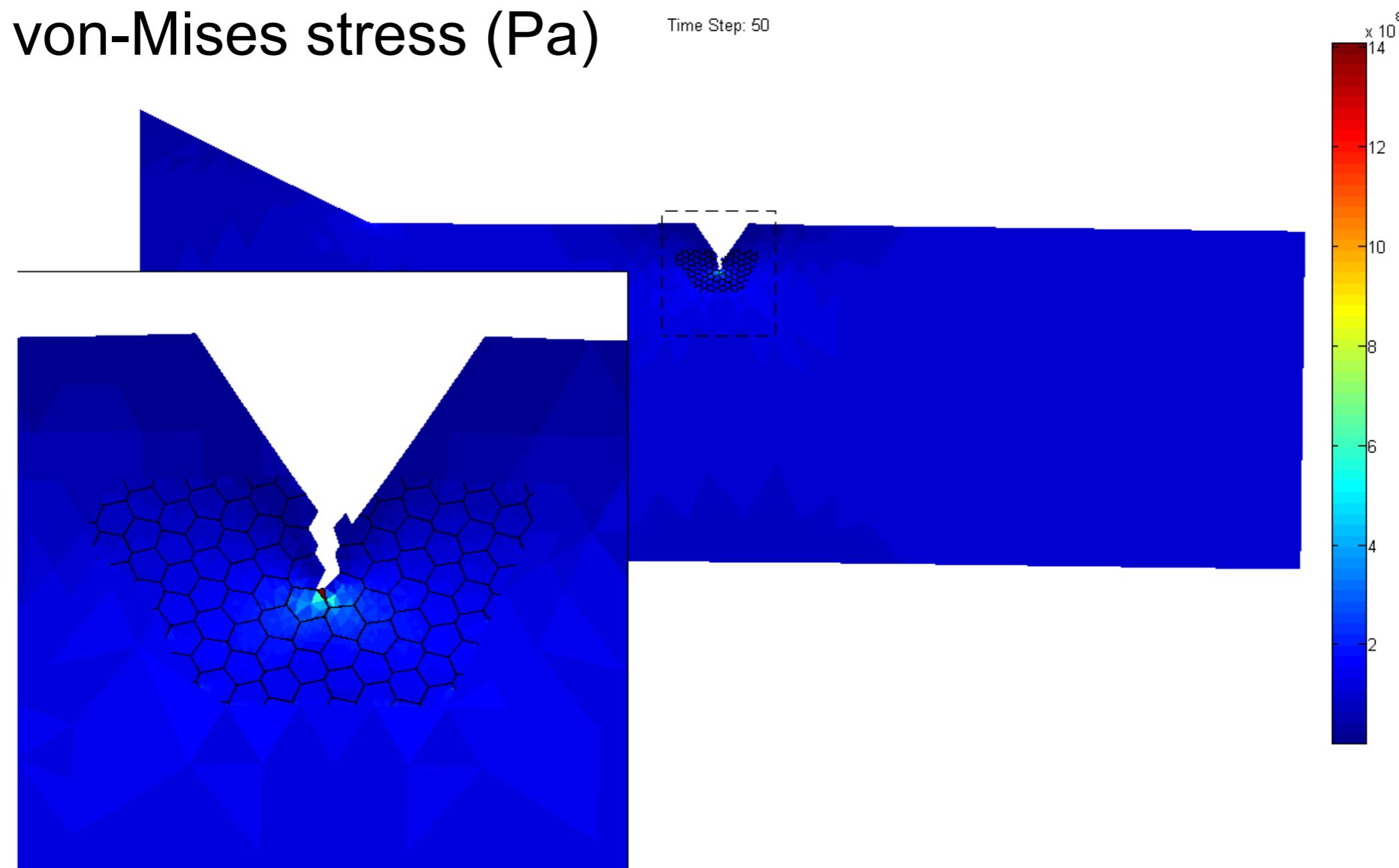
- ❖ 100X (magnification of displacement)

Results: uni-axial tension



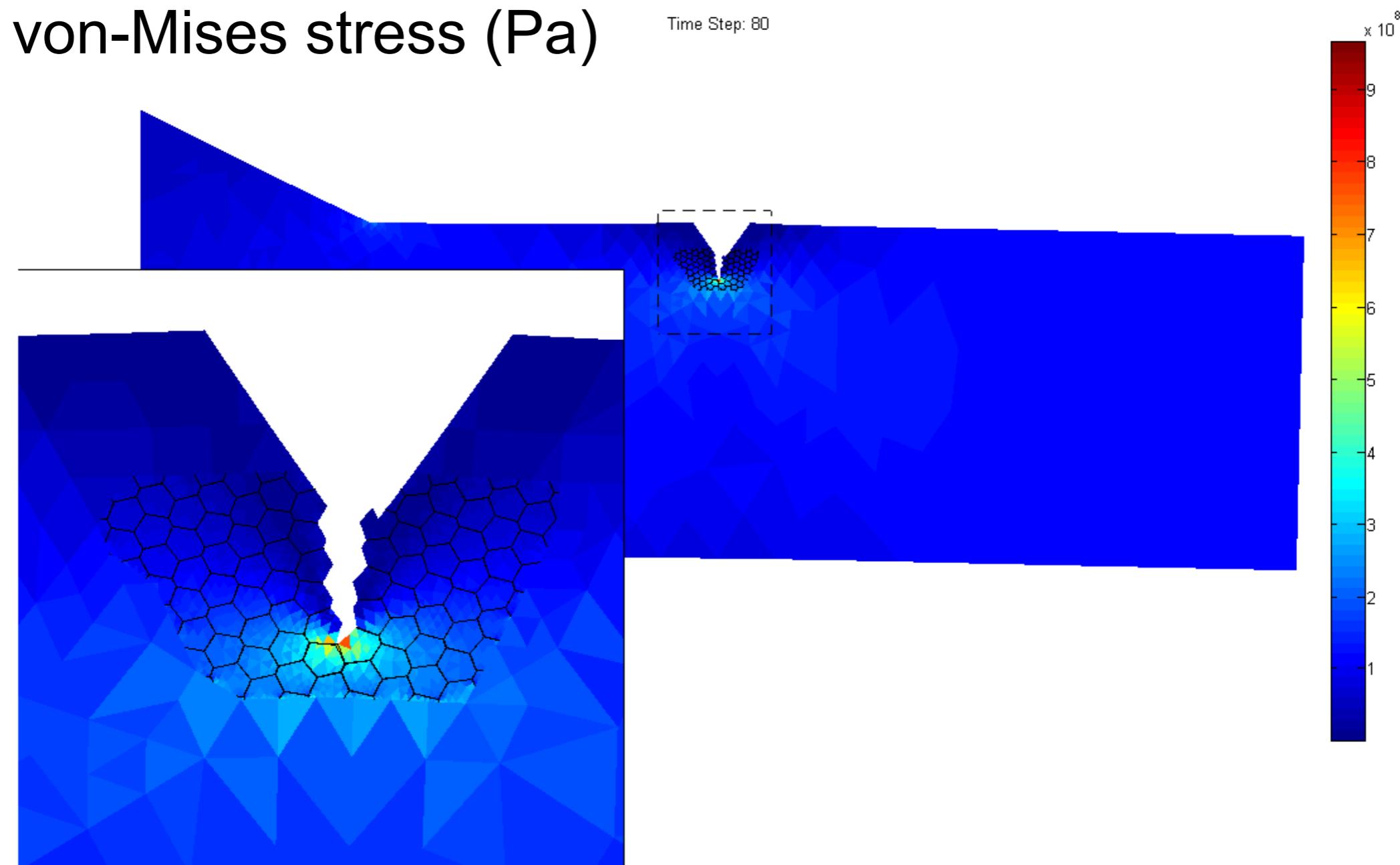
- ❖ 100X (magnification of displacement)

Results: uni-axial tension



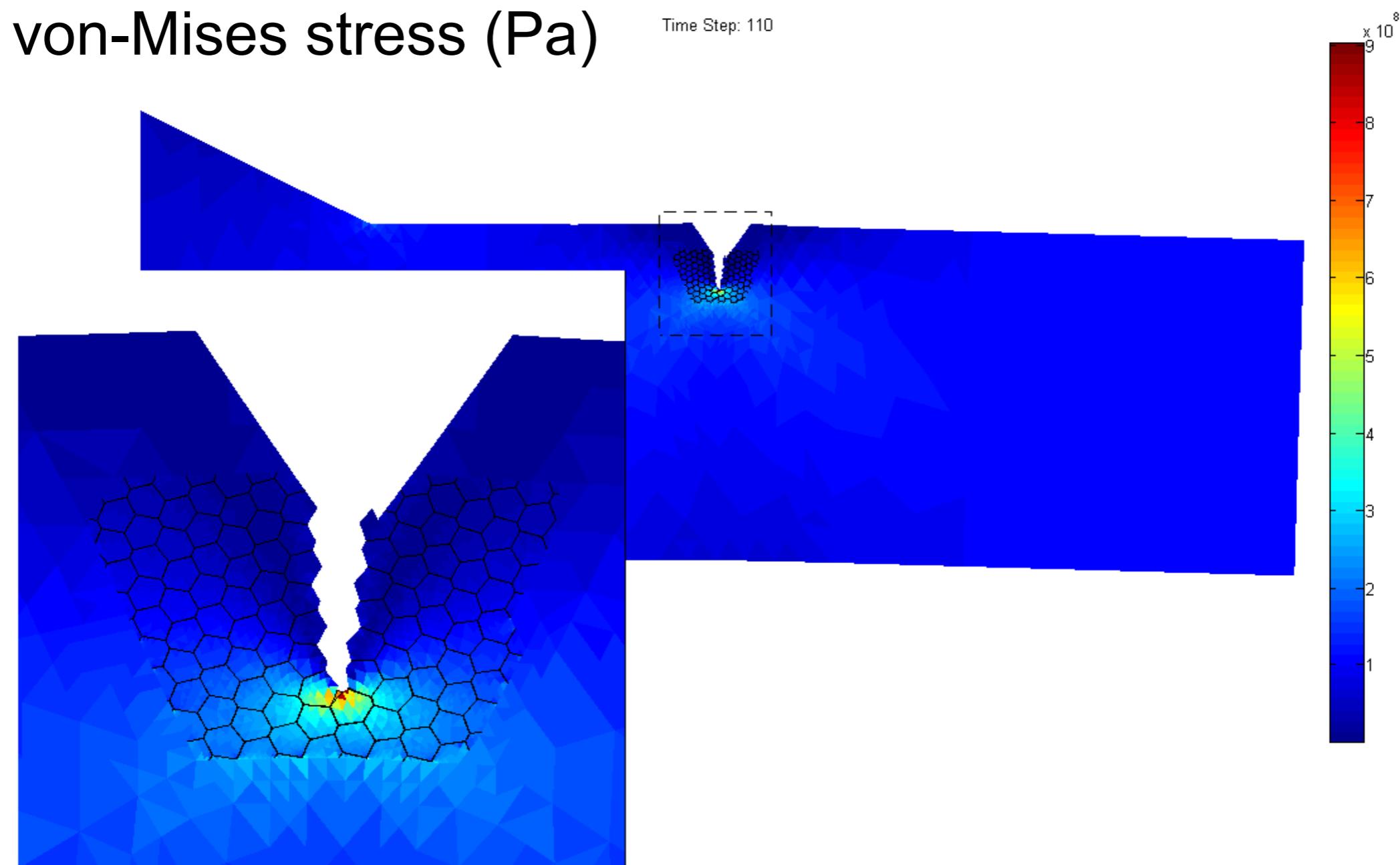
- ❖ 100X (magnification of displacement)

Results: uni-axial tension



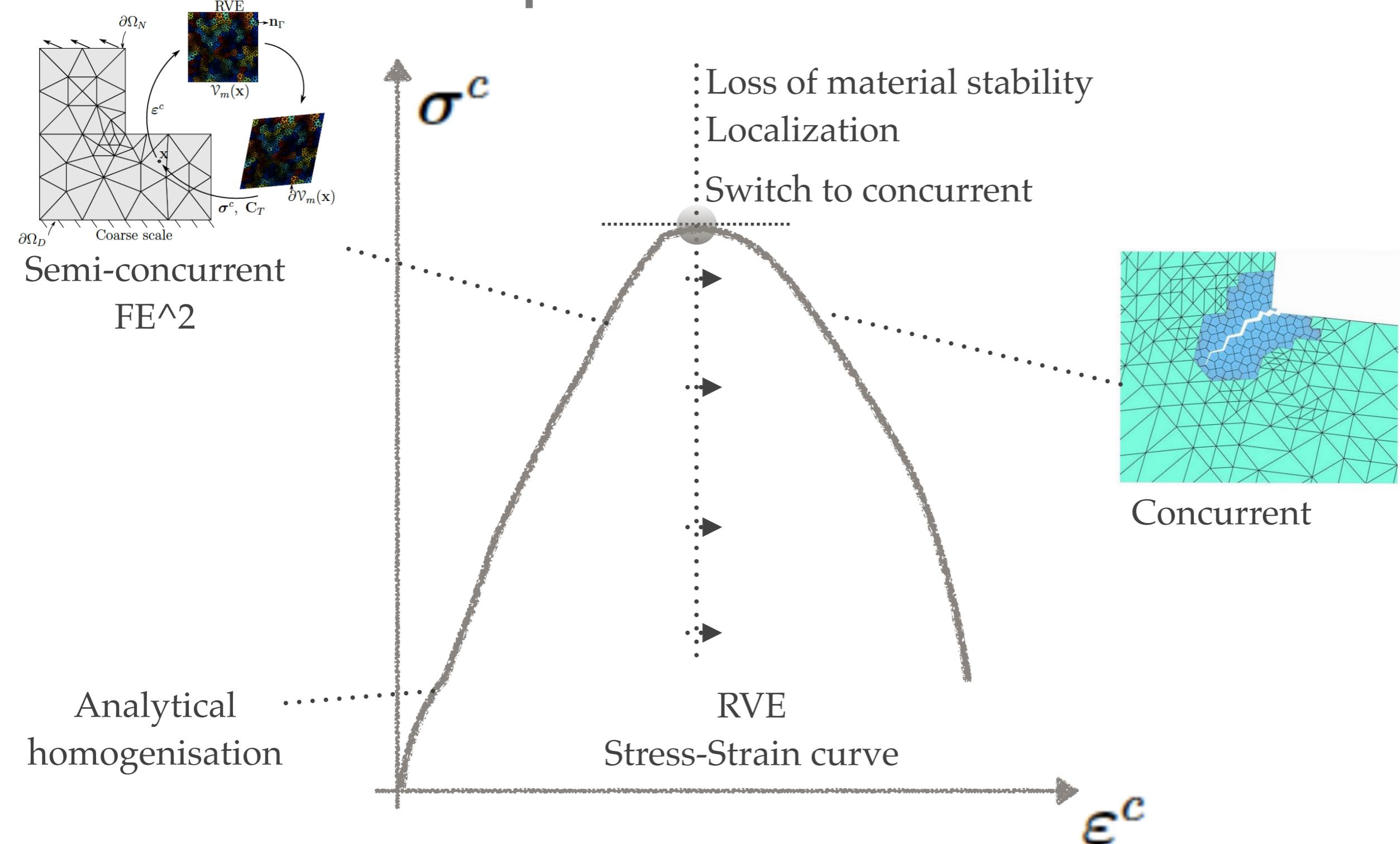
- ❖ 100X (magnification of displacement)

Results: uni-axial tension



- ❖ 100X (magnification of displacement)

Adaptive multi-scale



Open problem

- model selection and error control

Possible approach

- machine learning and statistical inference, e.g.

Bayesian statistics

Open problem

- statistical variability at the fine scale (geometry, material parameter)

Possible approach

- identification through small-scale experiments (costly, difficult to characterize interfaces)
- Monte Carlo

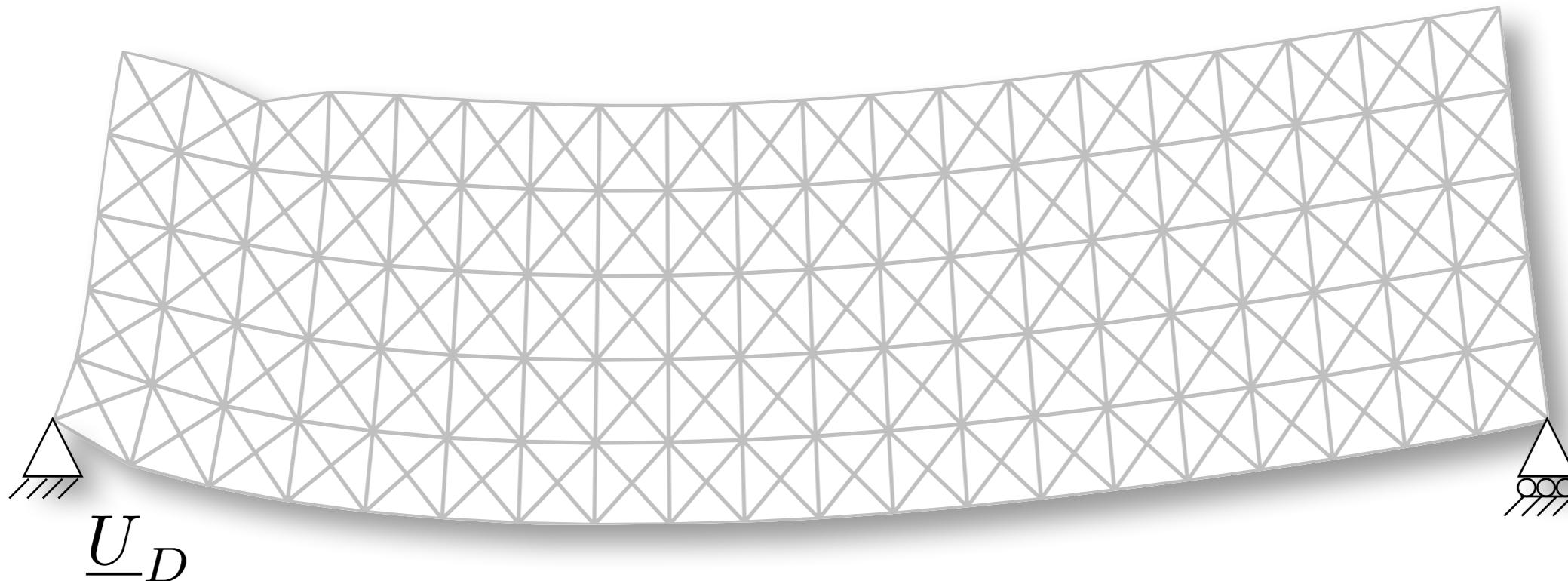
Algebraic model reduction methods

Use precomputed solutions to accelerate online simulations

Example - parametric problems

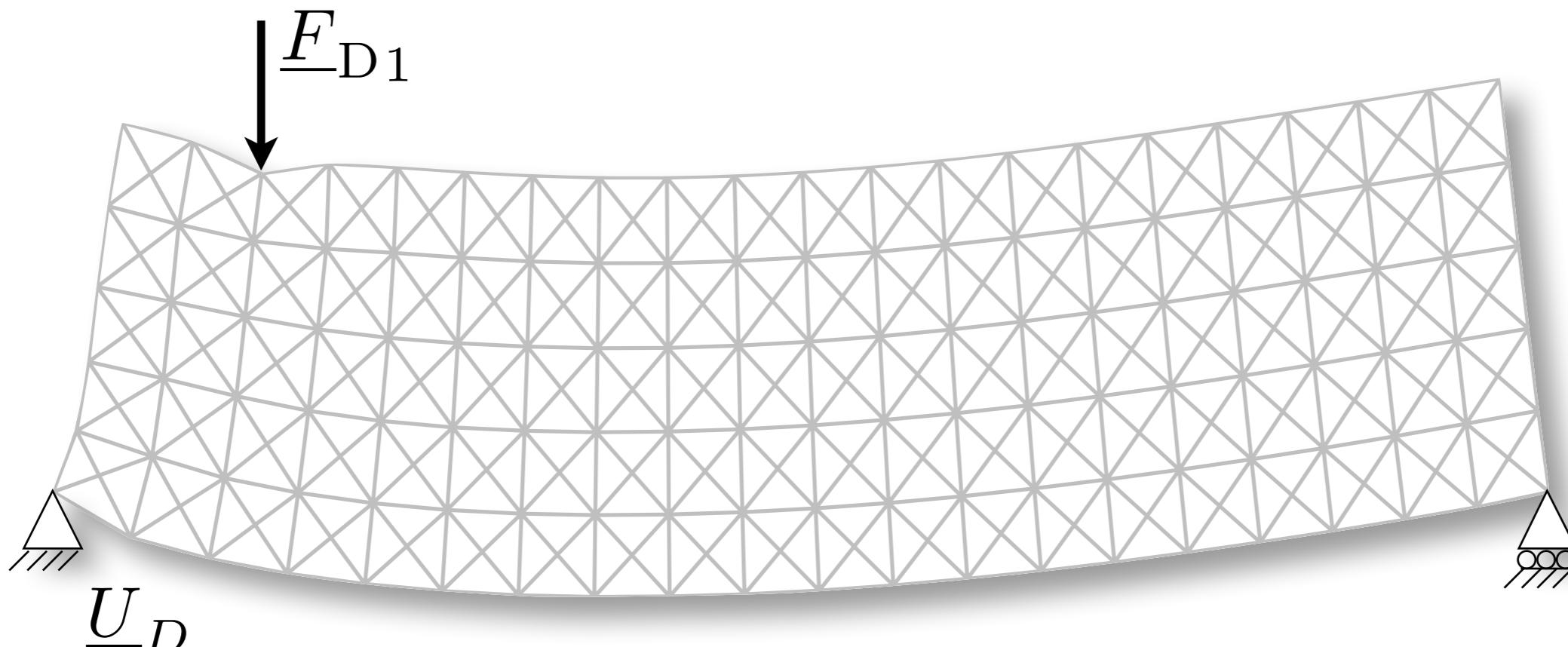
Method of separated representation

Lattice beam problem



Aim: accelerate the simulation using
pre-computations

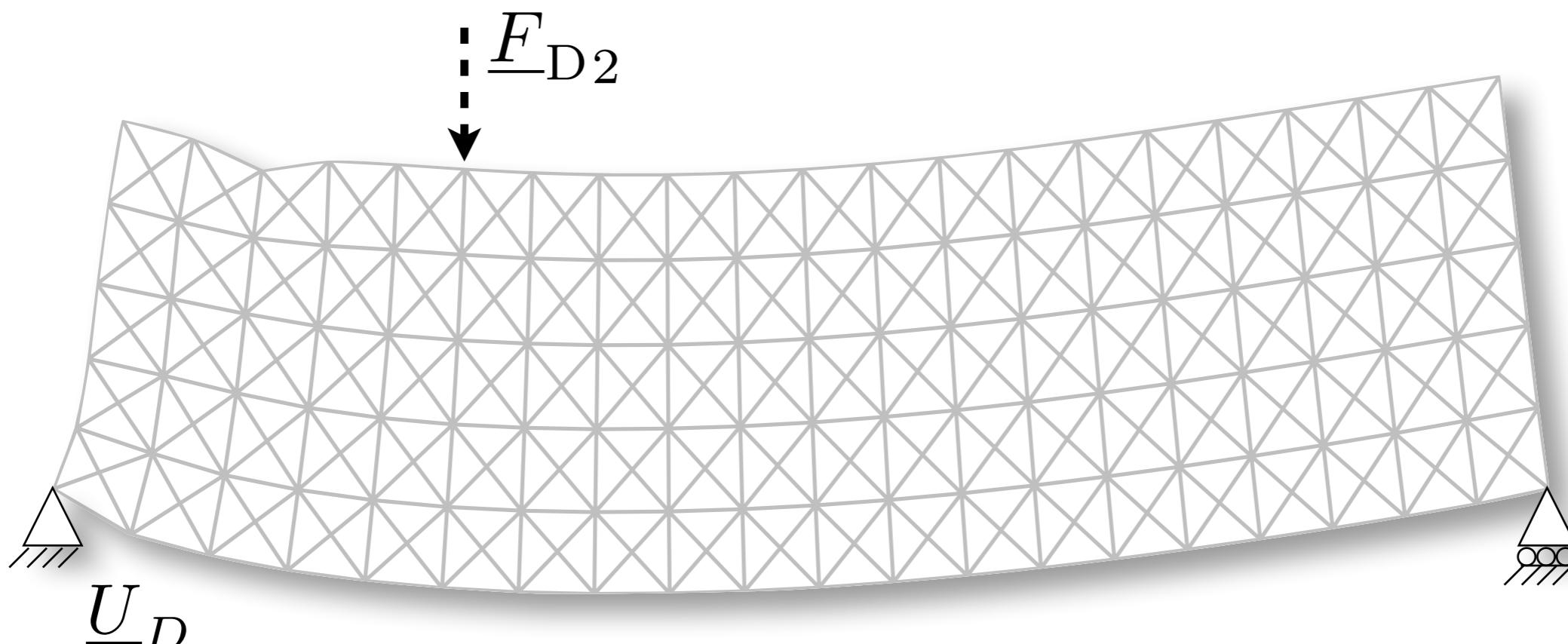
Lattice beam problem



$$\underline{\underline{S}} = \left(\begin{array}{c} \underline{S}^1 \\ \vdots \\ \underline{S}^n \end{array} \right)$$

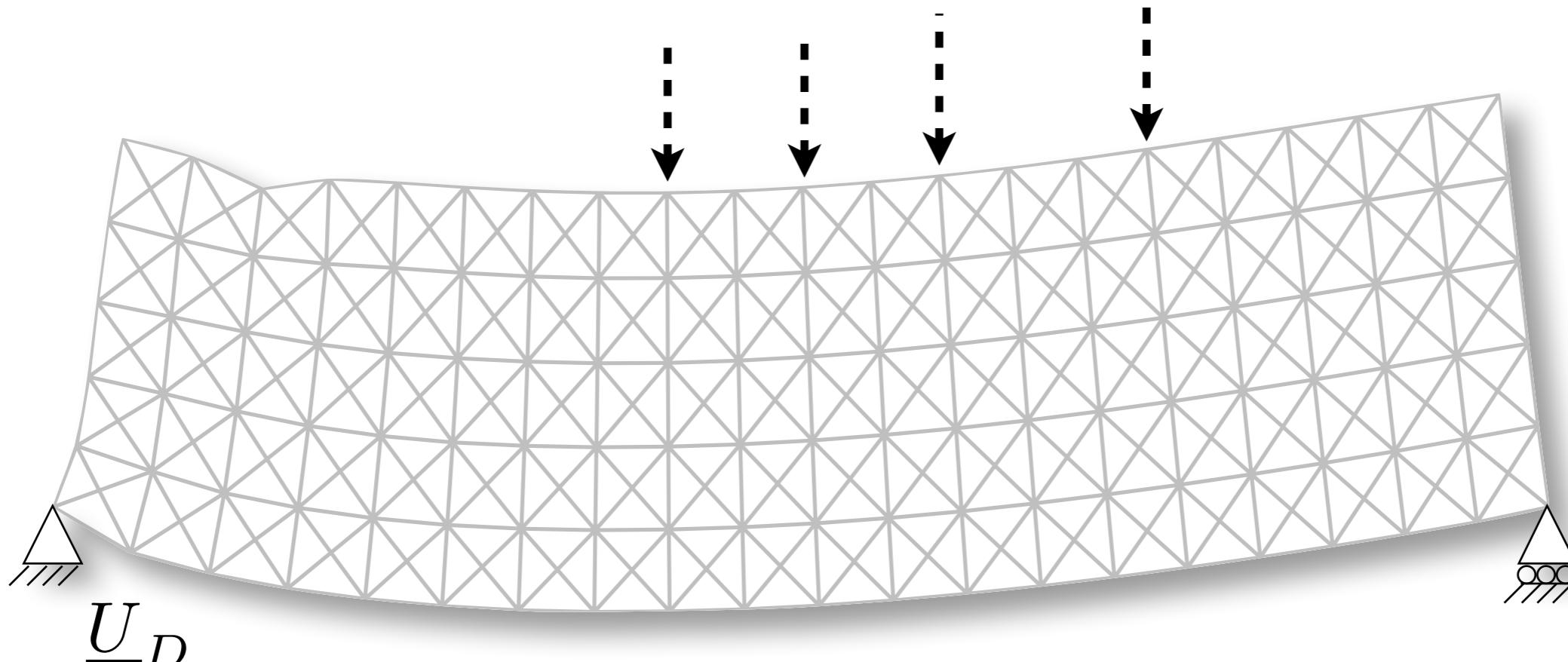
Compute solutions for several loading conditions

Lattice beam problem



$$\underline{\underline{S}} = \begin{pmatrix} \underline{S}^1 & \underline{S}^2 \end{pmatrix}$$

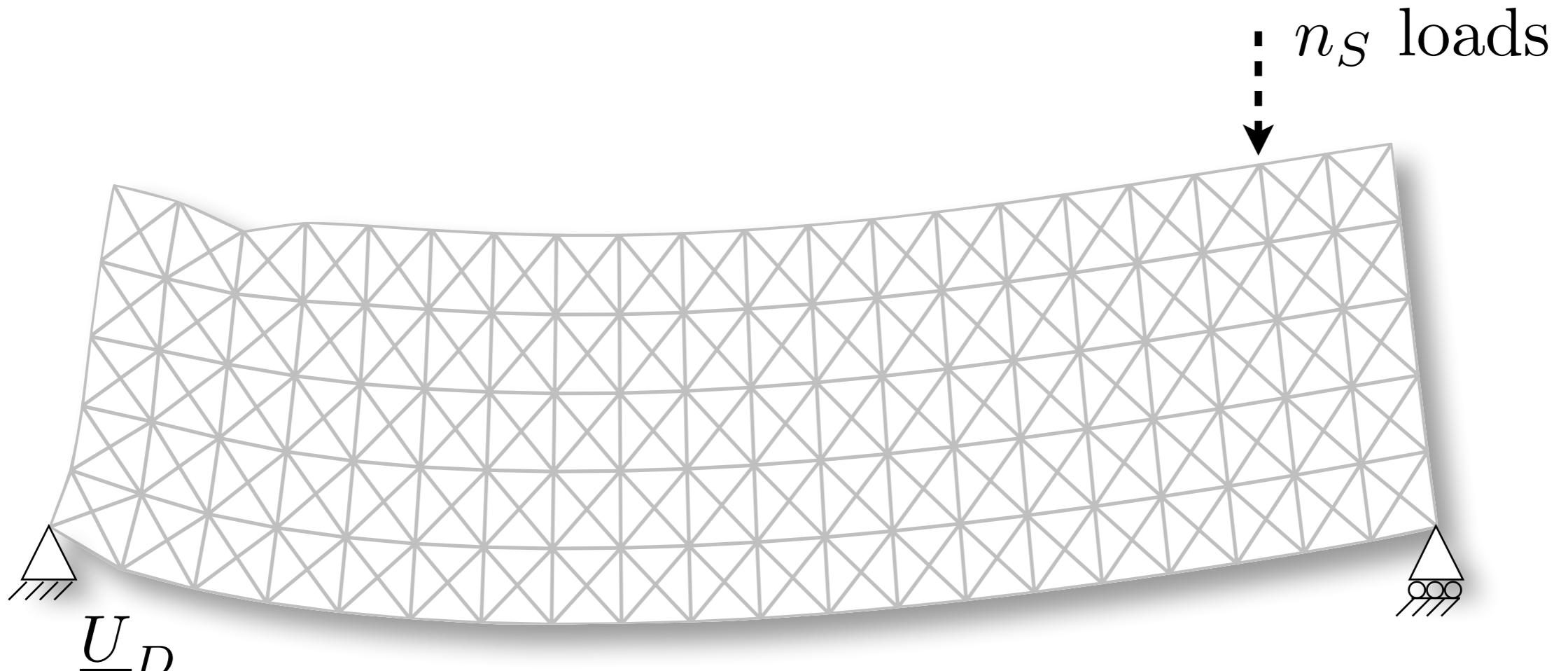
Lattice beam problem



\underline{U}_D

$$\underline{\underline{S}} = \begin{pmatrix} \underline{S}^1 & \underline{S}^2 & \dots \end{pmatrix}$$

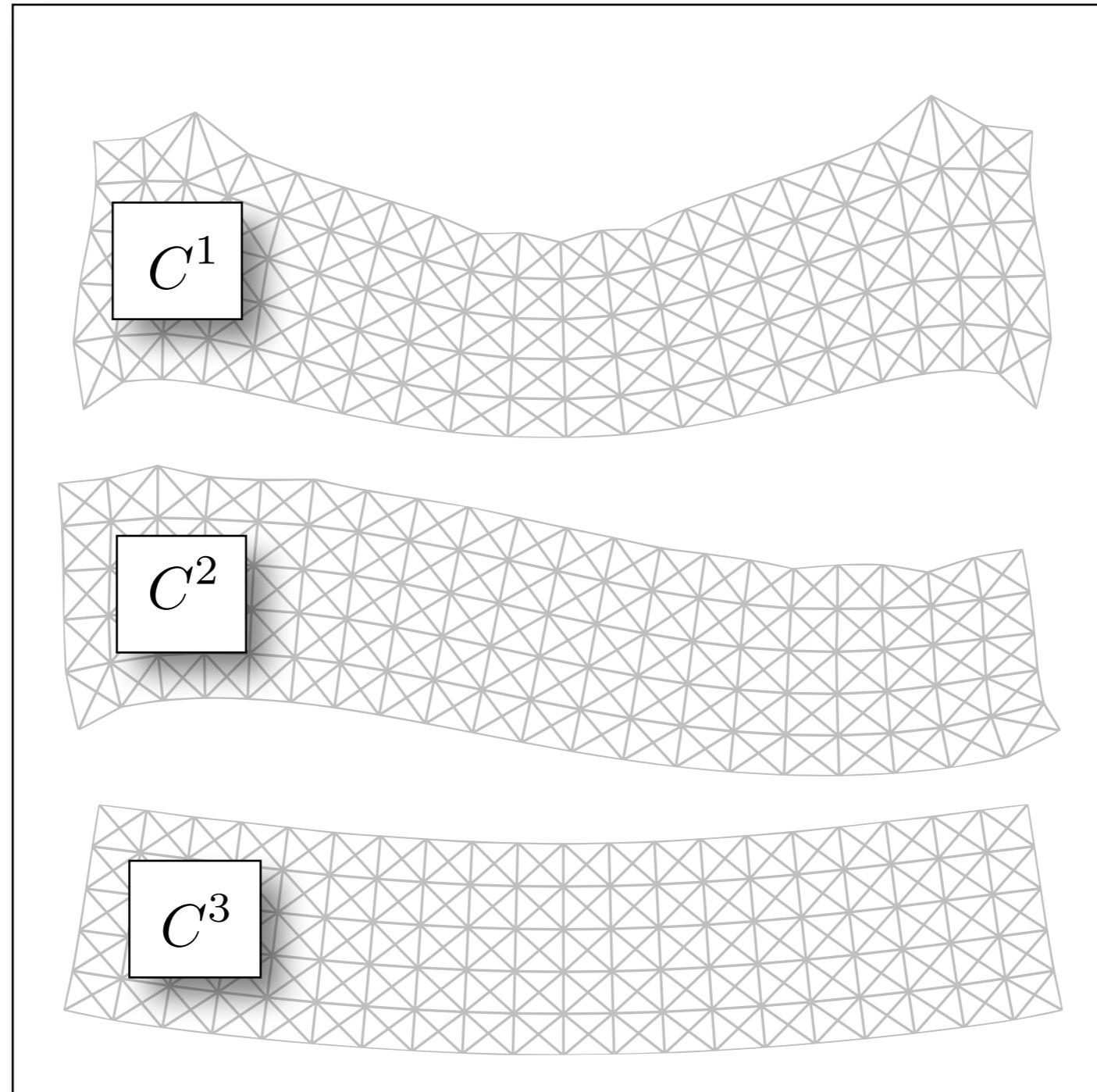
Lattice beam problem



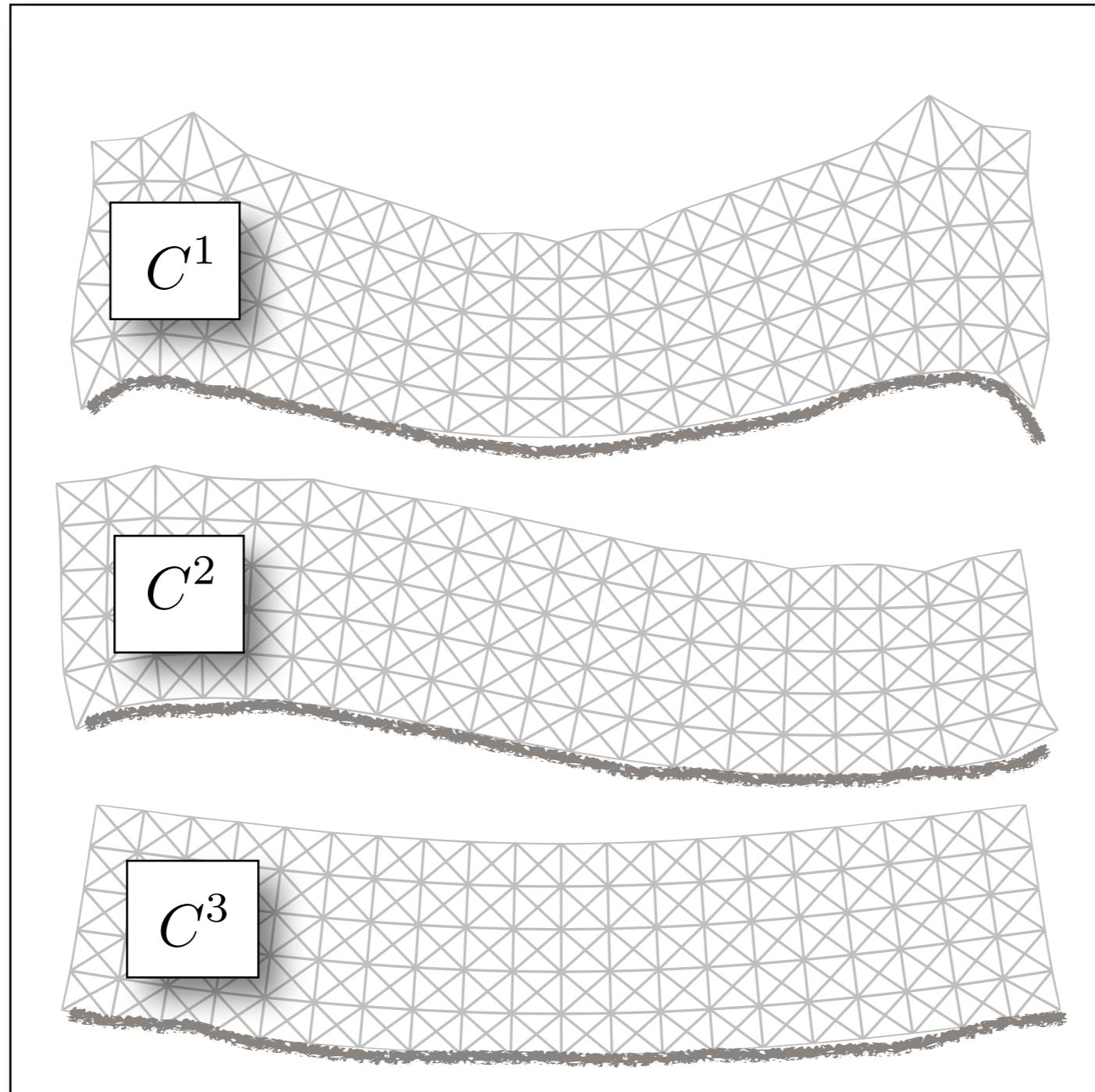
$$\underline{\underline{S}} = \left(\underline{S}^1 \quad \underline{S}^2 \quad \dots \quad \underline{S}^{n_S} \right)$$

Perform singular value decomposition - POD
to obtain “most energetic modes”

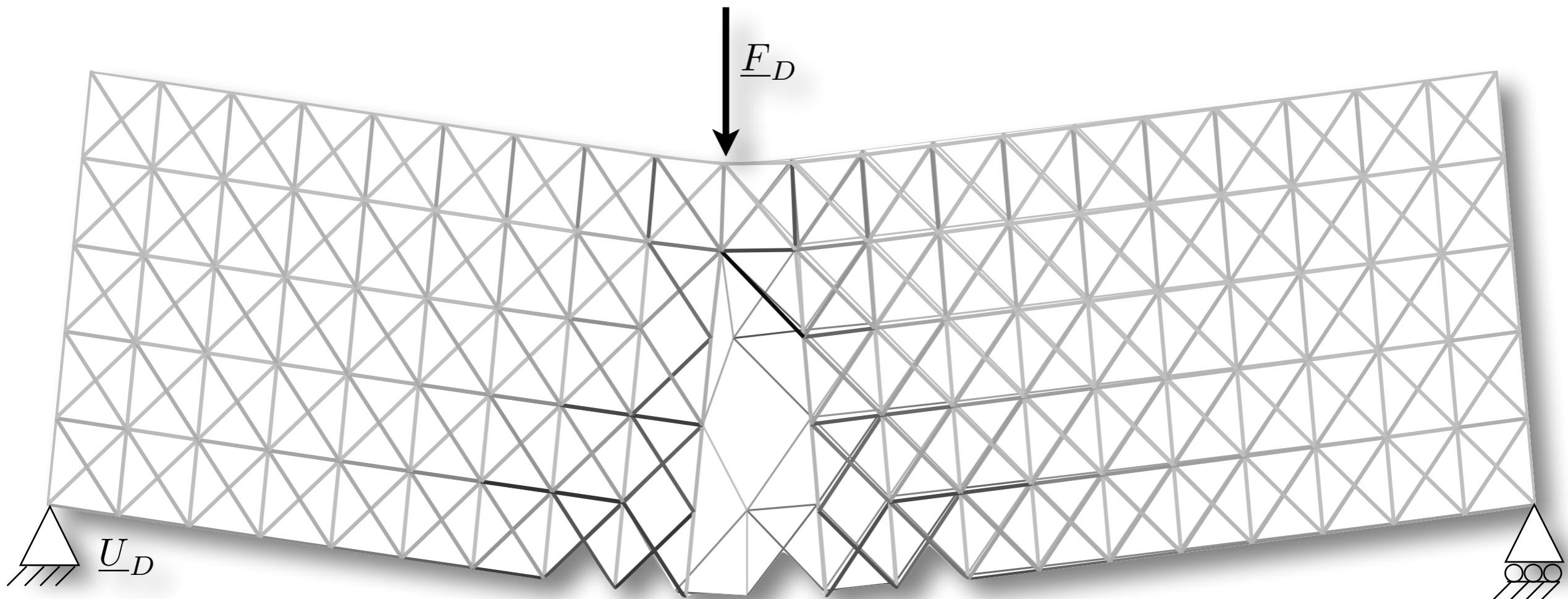
Reduced basis



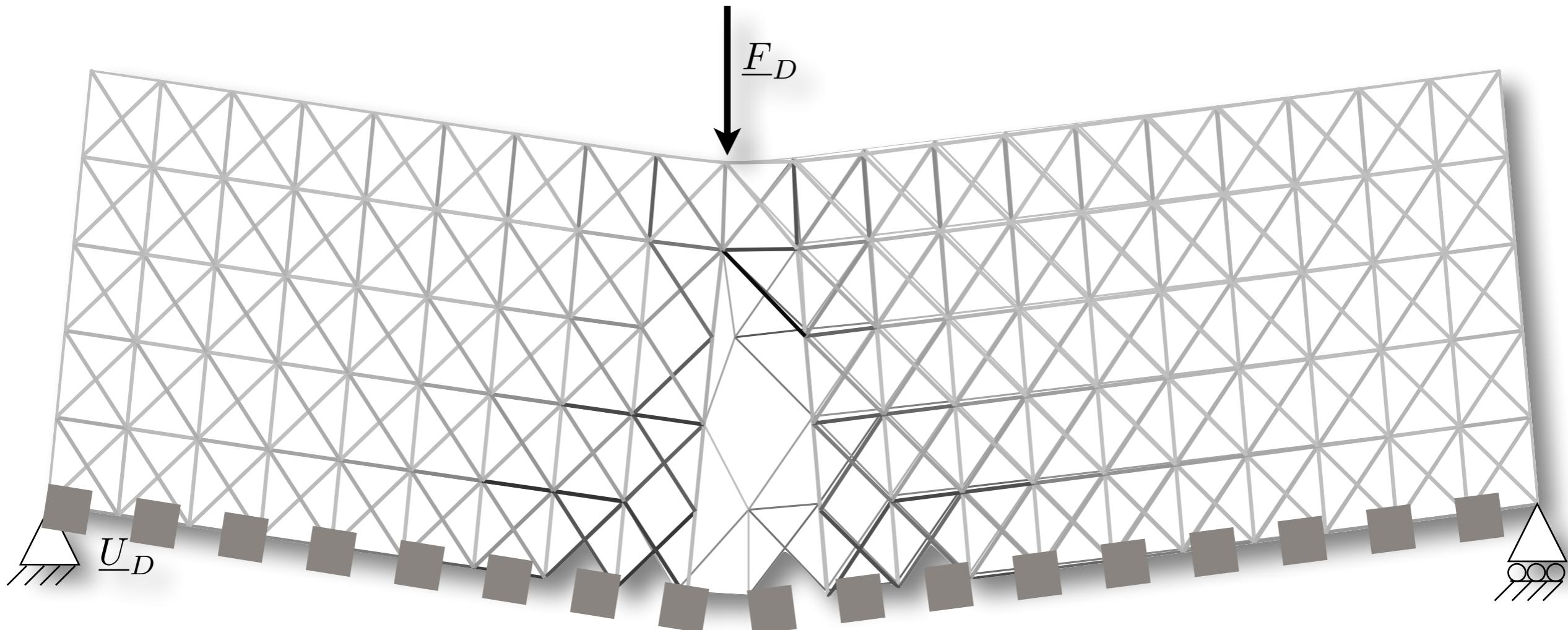
Reduced basis

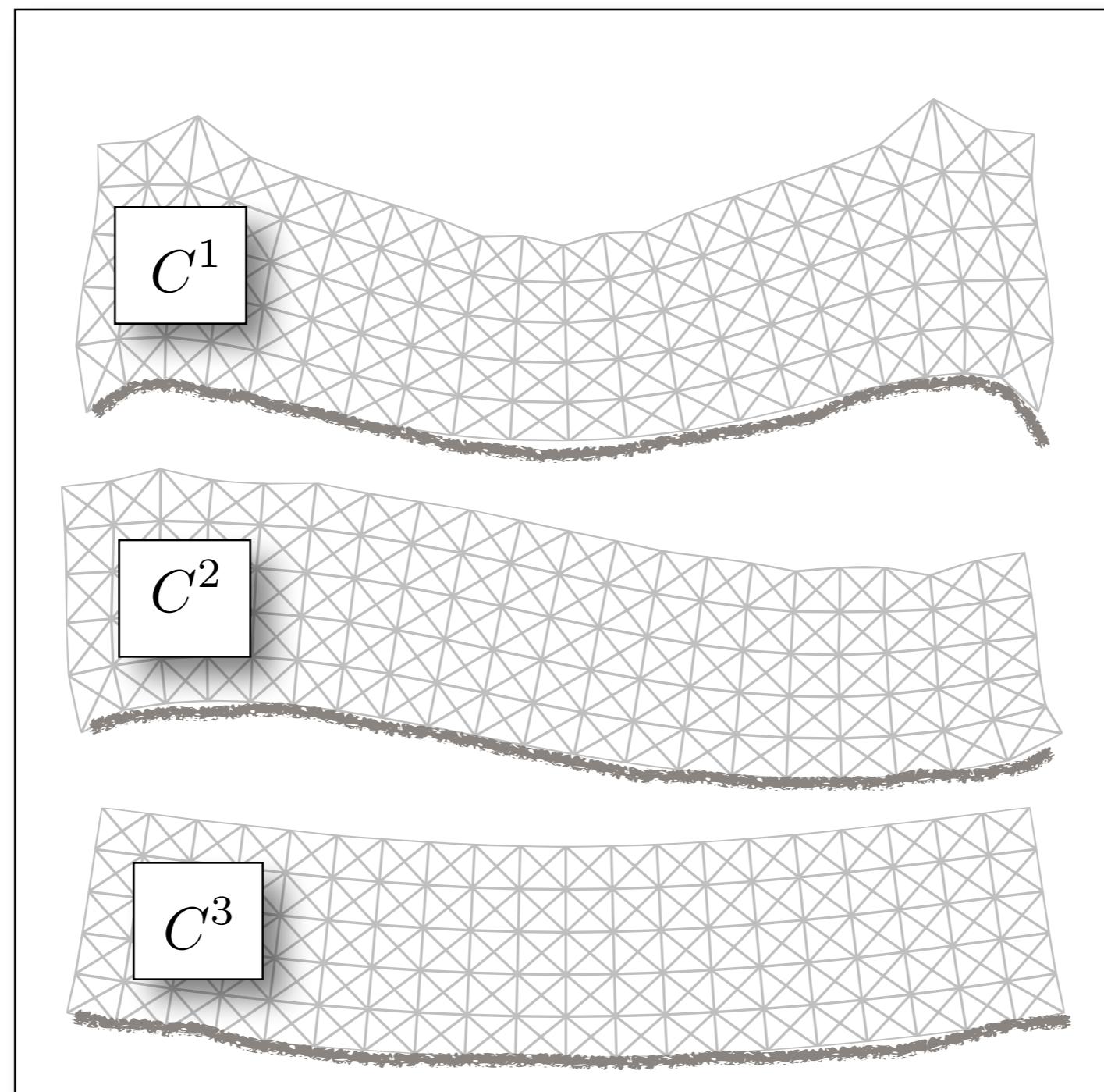


Beyond the elastic limit



Beyond the elastic limit

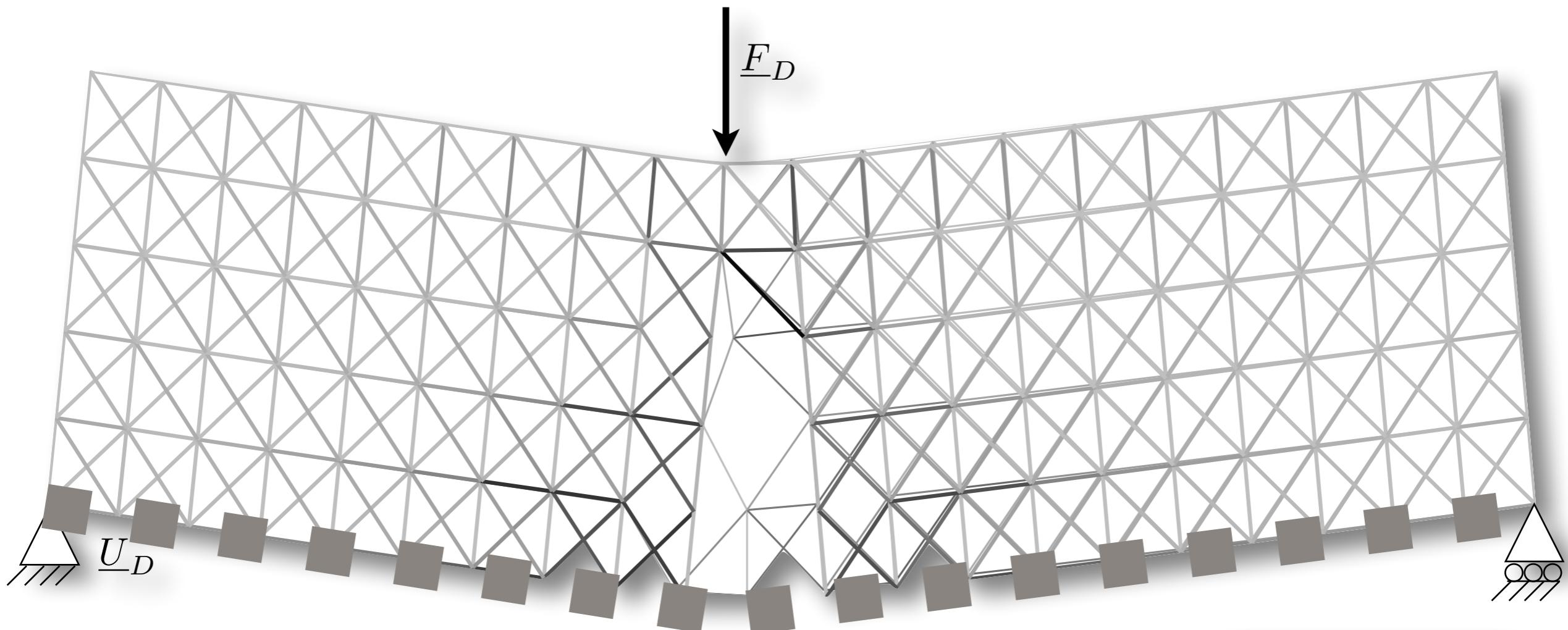




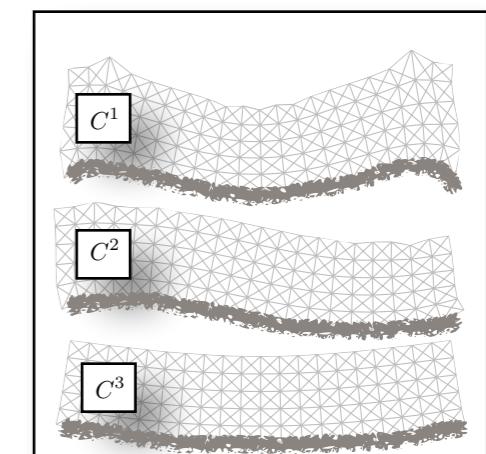
Smooth



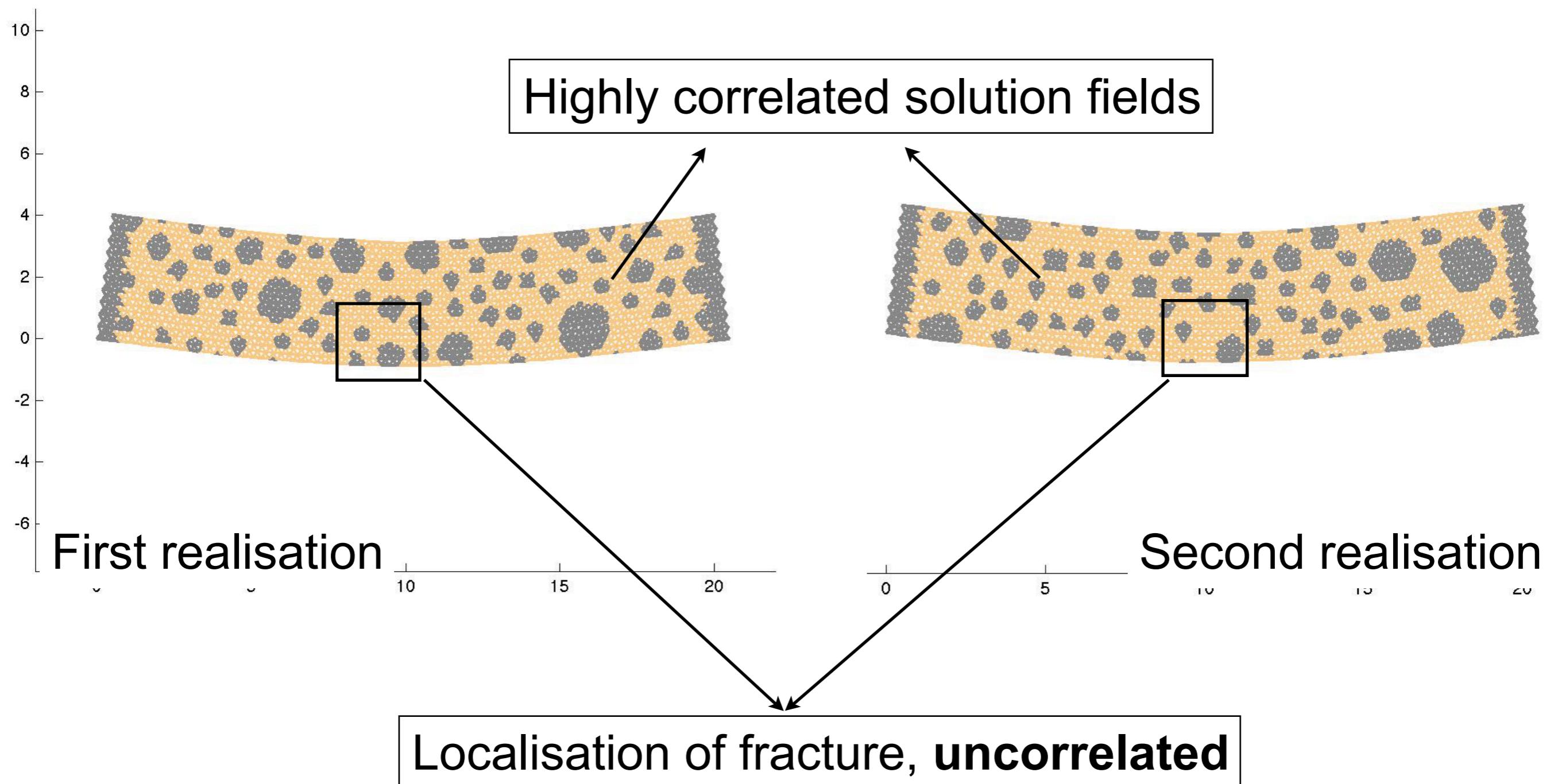
Kink



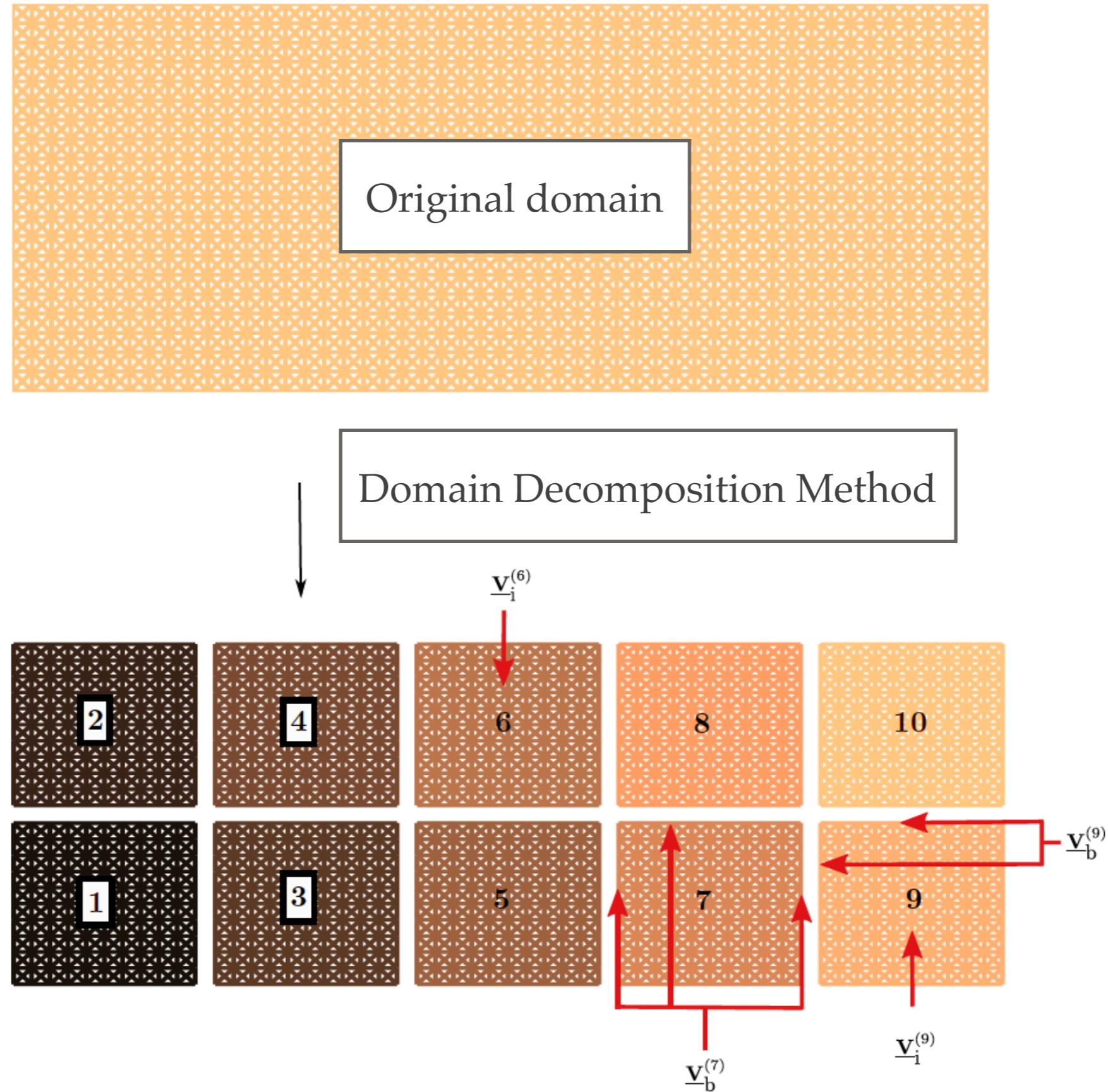
This solution is not in the snapshot !



Parametric / stochastic multiscale fracture mechanics



Partitioned POD/DDM

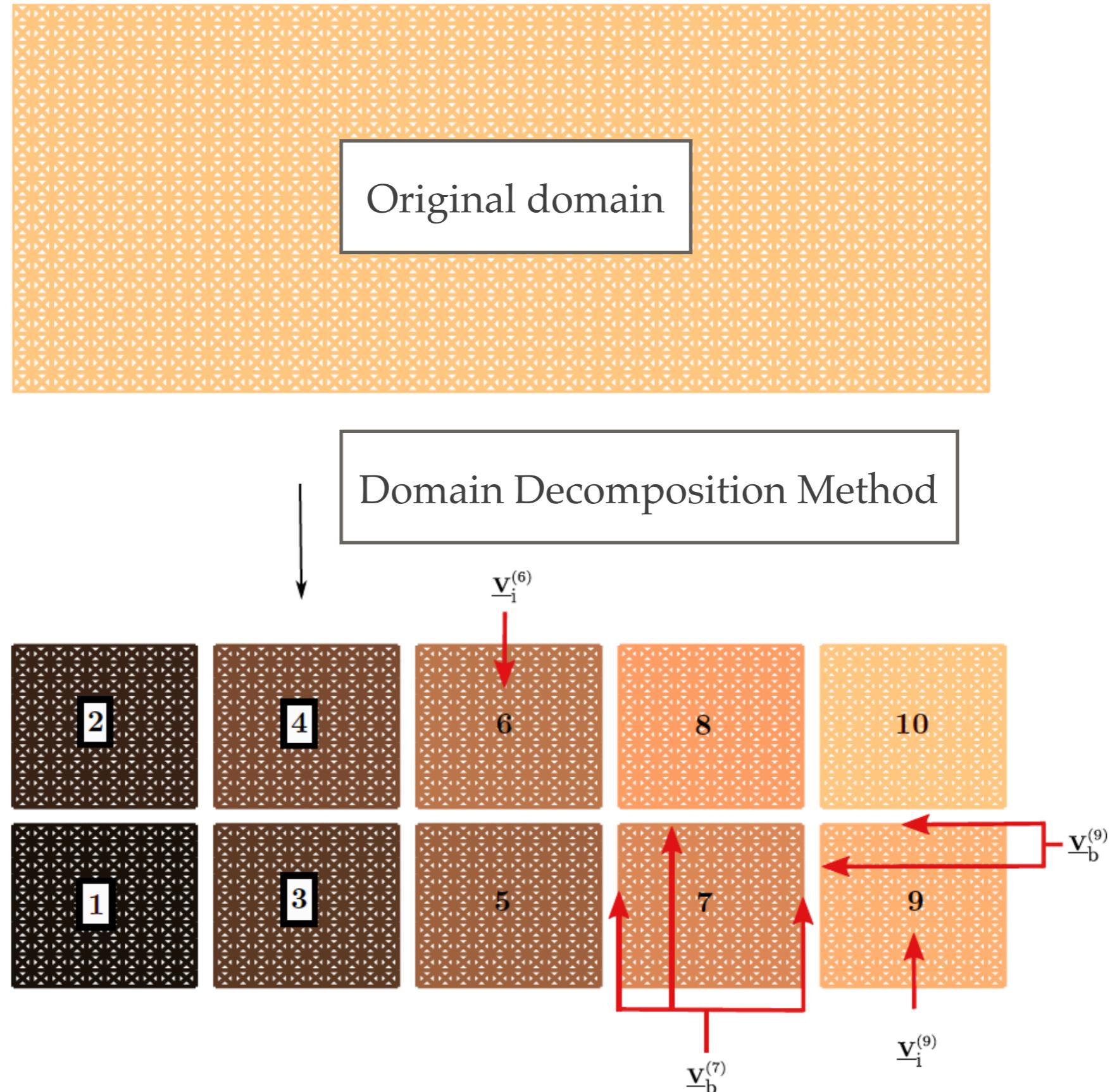


Partitioned POD/DDM



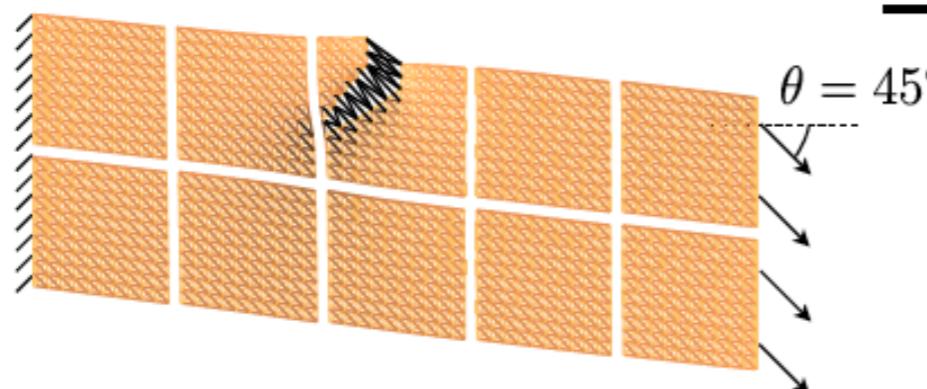
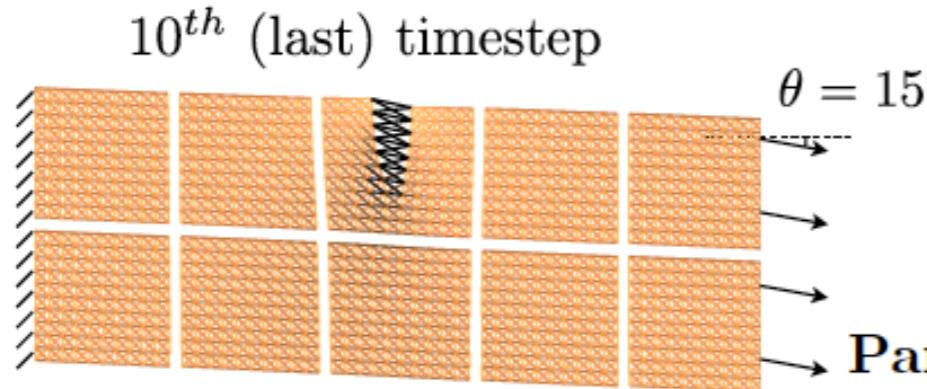
Domain Decomposition Method

Partitioned POD/DDM



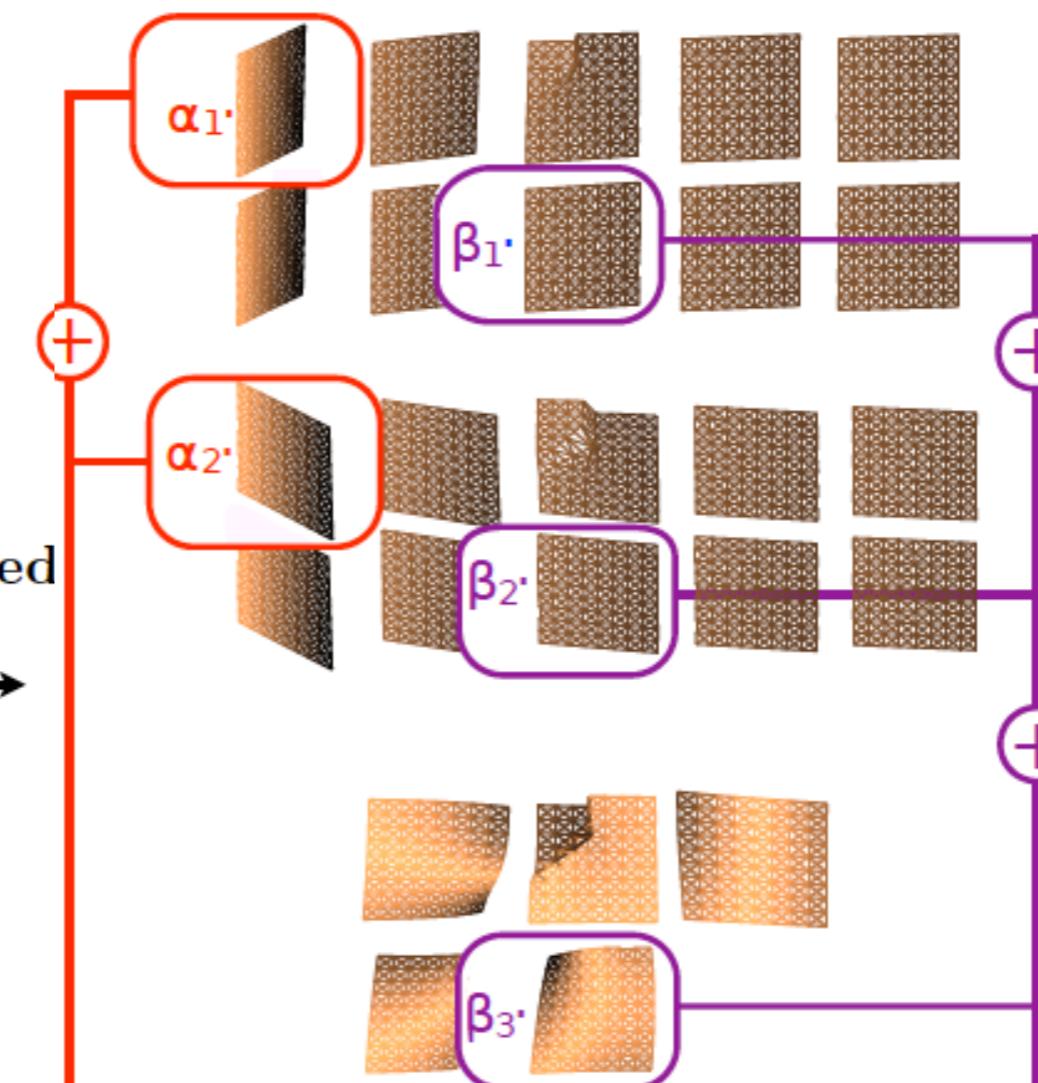
Compute particular realisations

(cost intensive) using domain decomposition (snapshots)



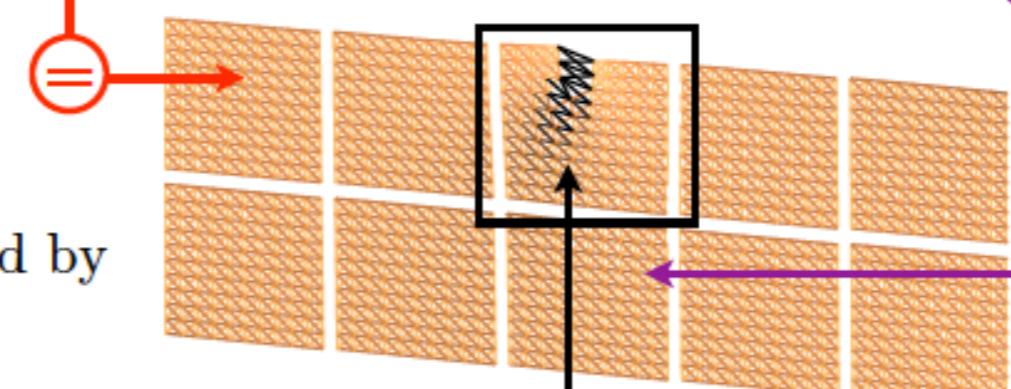
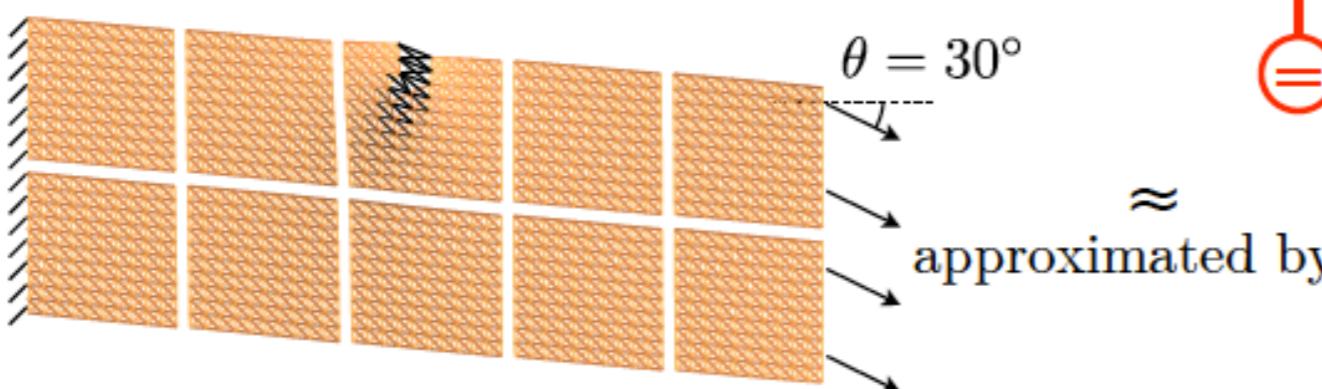
Partitioned
POD

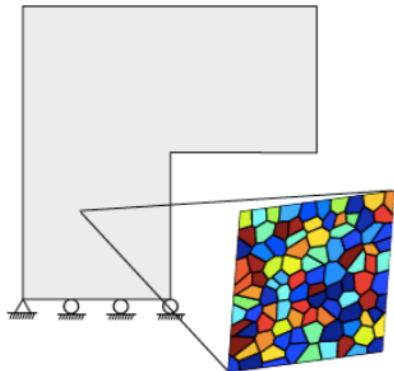
Partitioned reduced basis



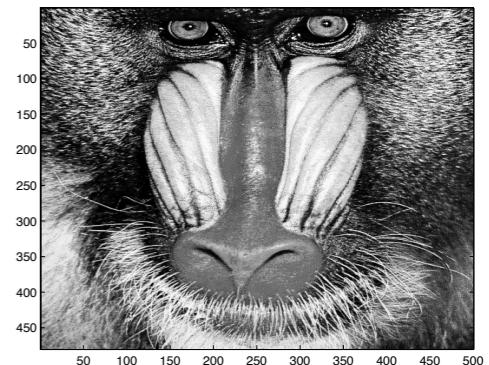
- ▶ Decompose the structure into subdomains
- ▶ Perform a reduction in the highly correlated region
- ▶ Couple the reduced to the non-reduced region by a primal Schur complement

Solution for arbitrary parameter using reduced model





Challenges
Reduce the problem size
Preserve essential features



Reduce computational expense - Control the error

Physics based model reduction
a.k.a. Multiscale Methods

Algebraic based model reduction a.k.a. Machine Learning

Representative volume elements do not exist after the onset of fracture

The problem is not reducible in the fracture process zone

Adaptive Multi-scale Methods: hierarchical - semi-concurrent - concurrent

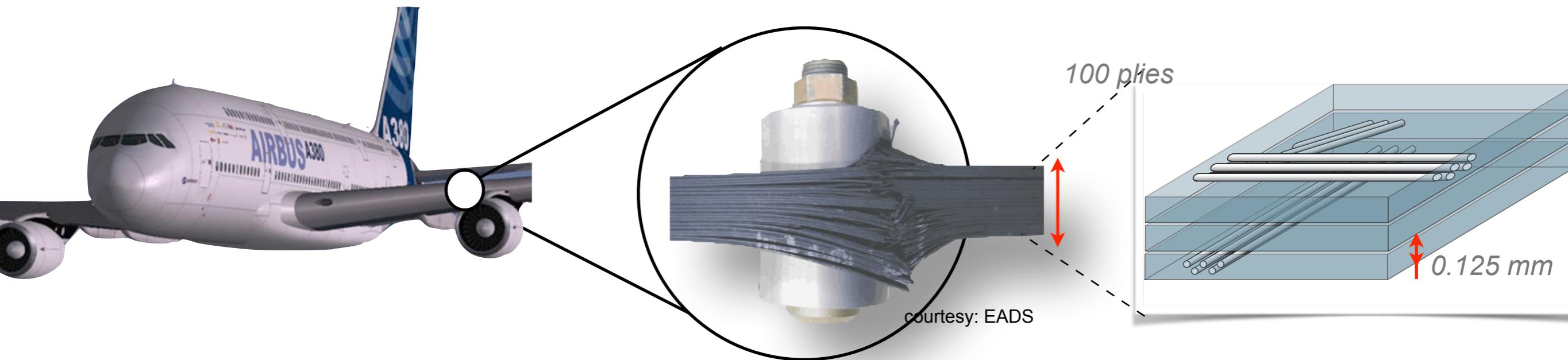
Adaptive Domain Decomposition Proper Orthogonal Decomposition

Open problems

- how to define the reduced area?
- precomputation time (offline)

Future?

Material complexity

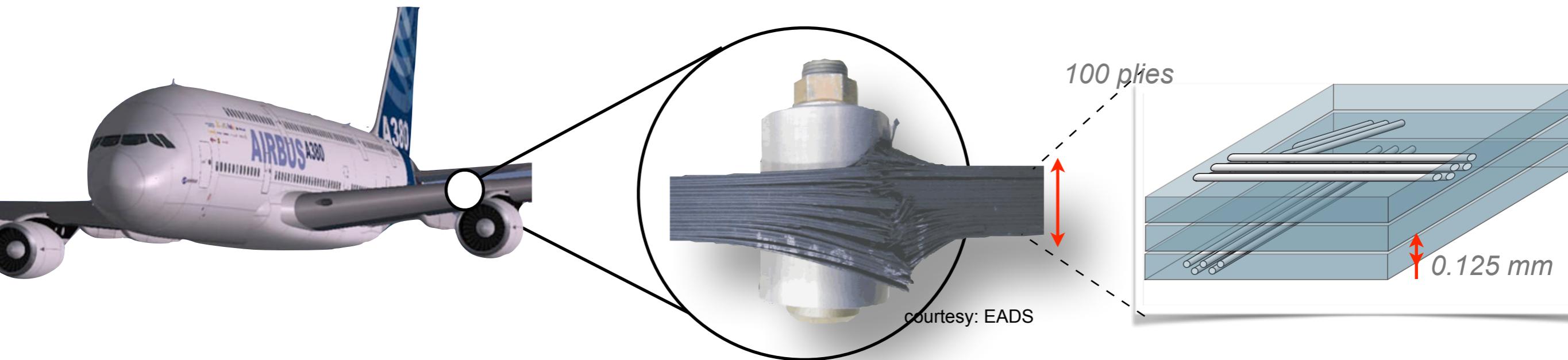


Heterogeneous & multi-functional materials

Can we optimise the material microstructure given macroscopic objective functions

Experiments required to attain sufficient confidence in their behavior are increasingly costly

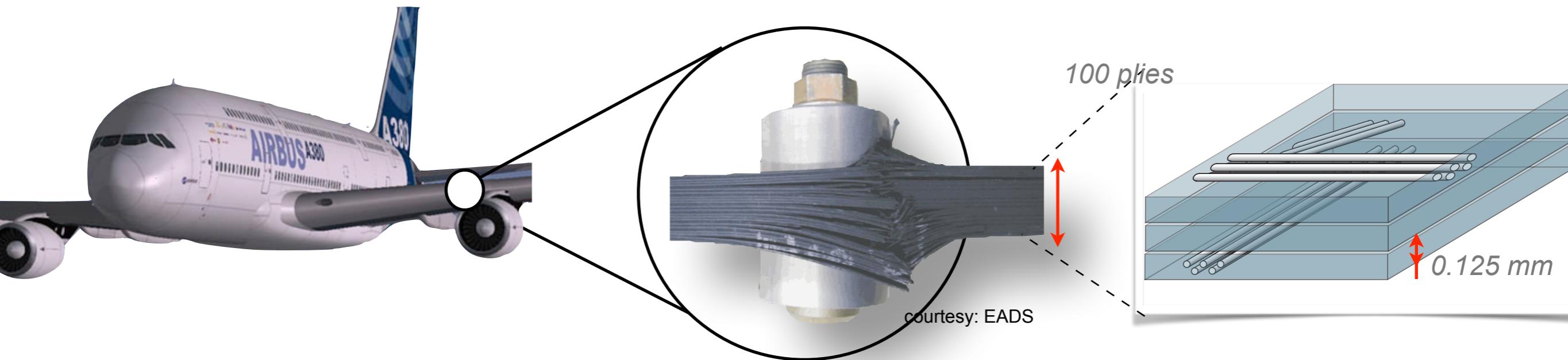
Material complexity



Factor-of-Safety or probabilistic based methods cannot handle unknown unknowns

Lack of similitude between testing (experimental) and operating conditions — also encountered in geophysics, medicine...

Challenges



- Move away from heuristics and experience-based engineering
- Develop fundamental understanding of physical processes (degradation, ...)

Digital twin concept

Actual aircraft

Life prediction and extension

High fidelity modeling and simulation

Digital aircraft model

Situation awareness

Certification and design methods

Requires real-time data assimilation, and model update...

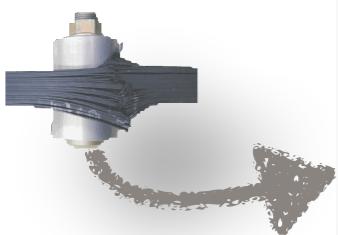
Parallel with medicine

Mechanics

Macro (wing) - Micro
(carbon fibres)

Environmental effects
(Temperature,
irradiation...)

Experimental condition
dissimilarities



Medicine

Macro (Body,
Physiology) to micro
(microbes, needle/
scalpel...)

Patient's environment,
living conditions,
habits...

Organ properties
depend strongly on age,
gender, ...

Medicine

The average drug developed by a major pharmaceutical company costs at least \$4 billion, and it can be as much as \$11 billion.

Mechanics

The development cost of the A380

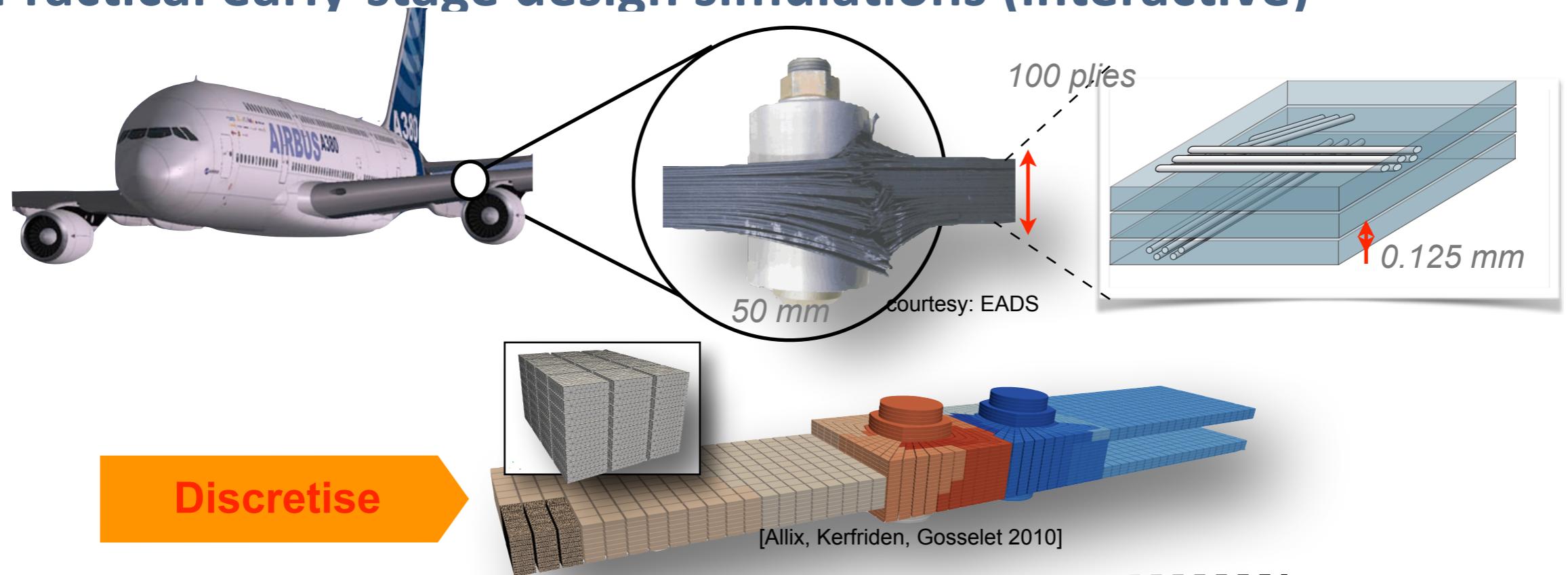
11 billion euros...

of the dreamliner...

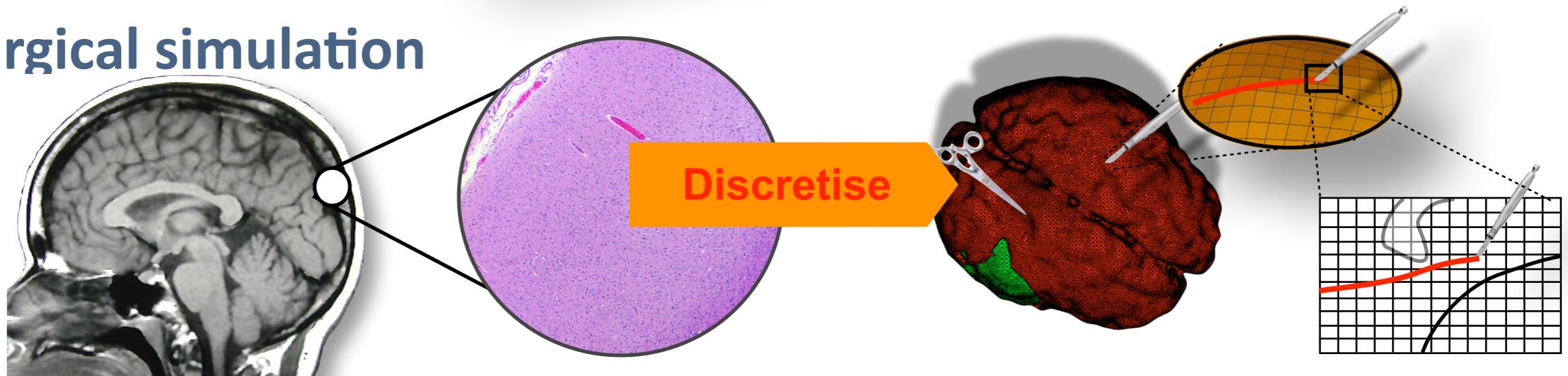
\$32 billion

Patient/plane-specific simulation

Practical early-stage design simulations (interactive)



Surgical simulation



- ▶ Reduce the problem size while controlling the error (in QoI) when solving very large (multiscale) mechanics problems

thanks for your attention

Partners and Funding



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Pioneering research
and skills

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Bauhaus-
Universität
Weimar



UNIVERSIDAD DE CHILE



UNIVERSIDAD
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Vietnamese-German University
VGU



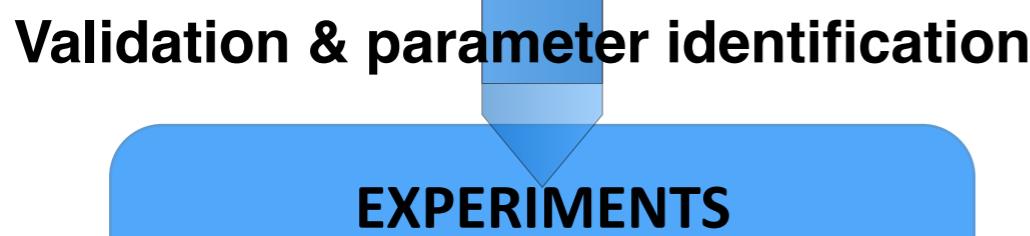
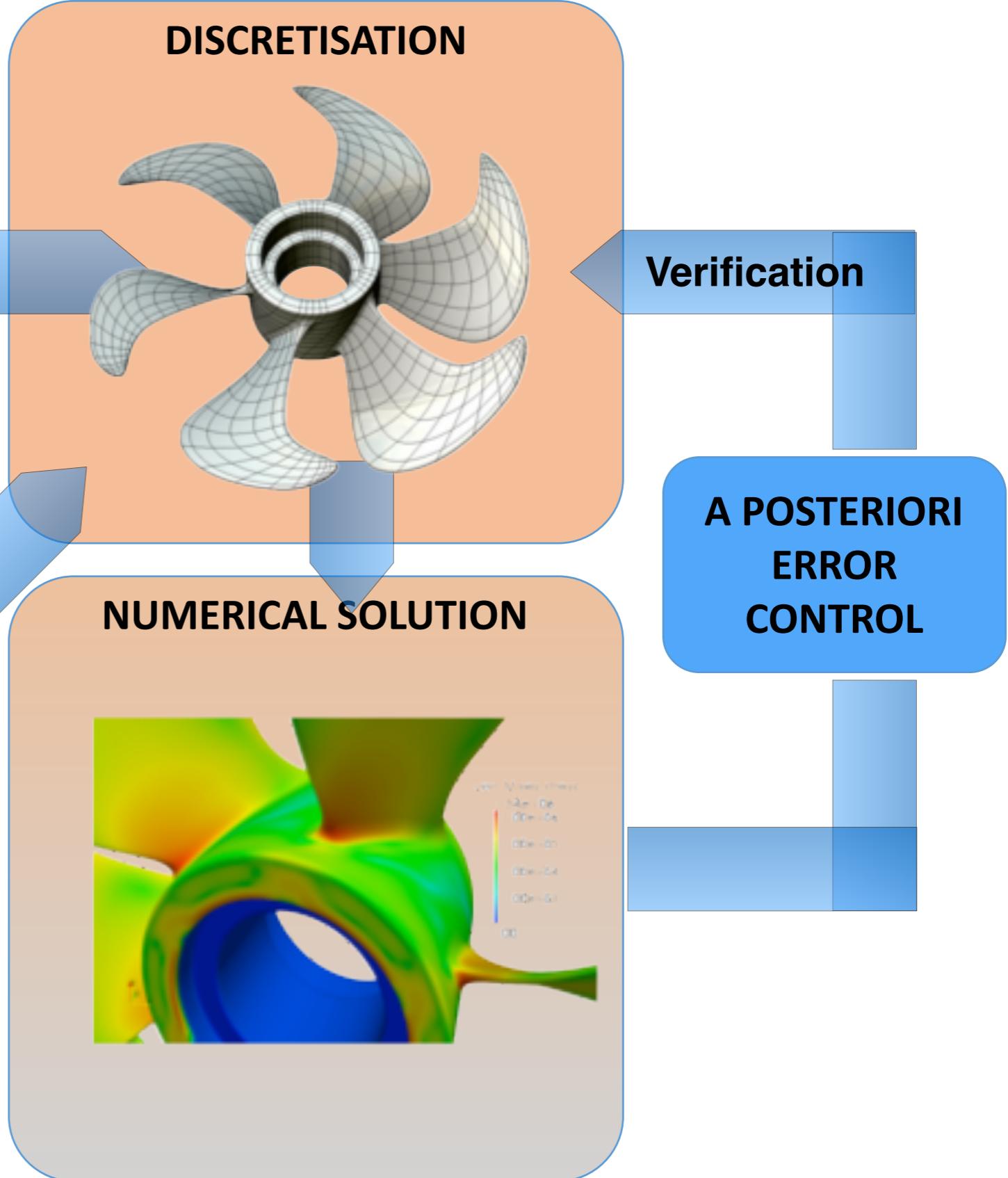
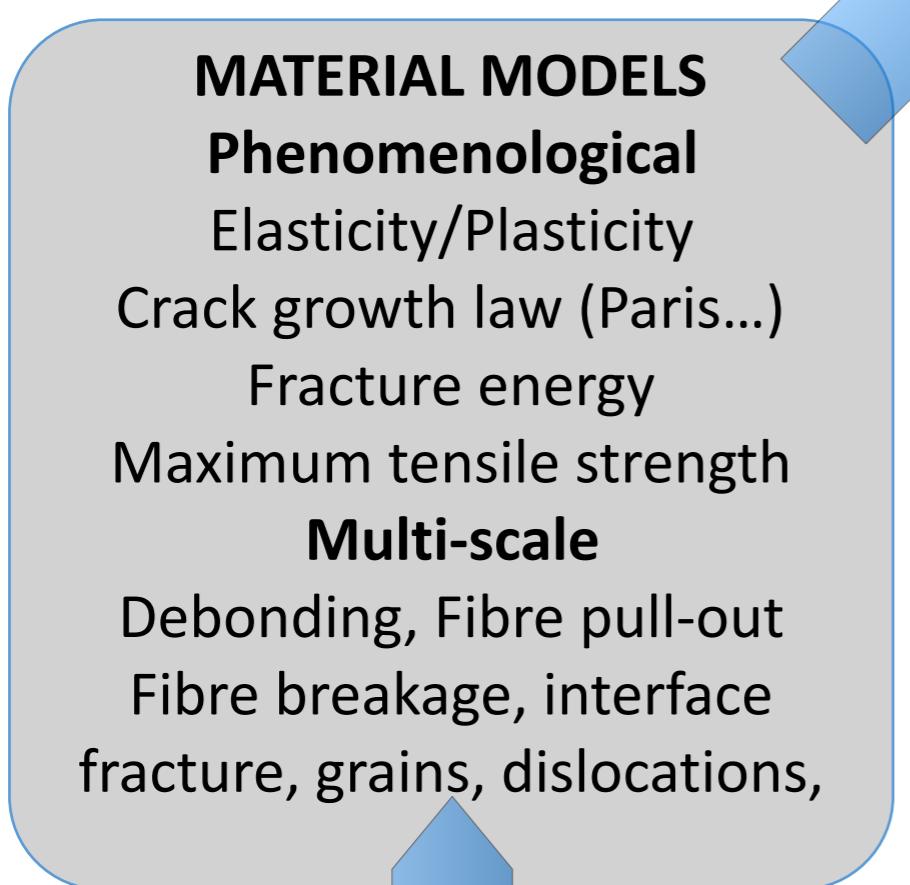
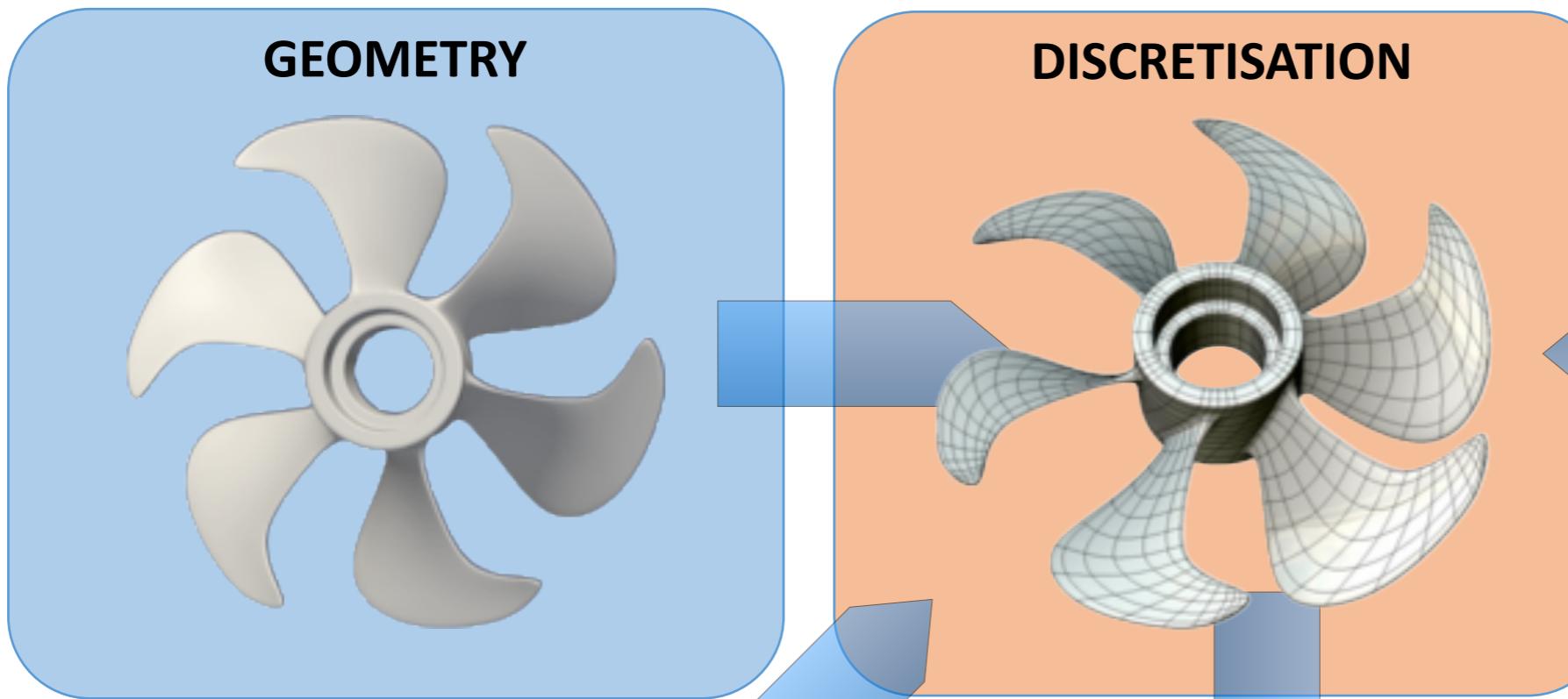
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Technik fürs Leben



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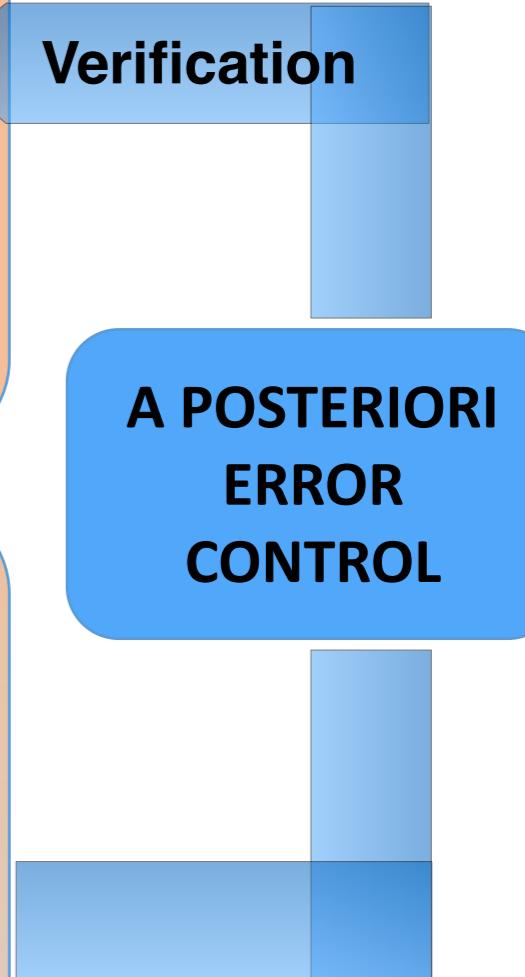
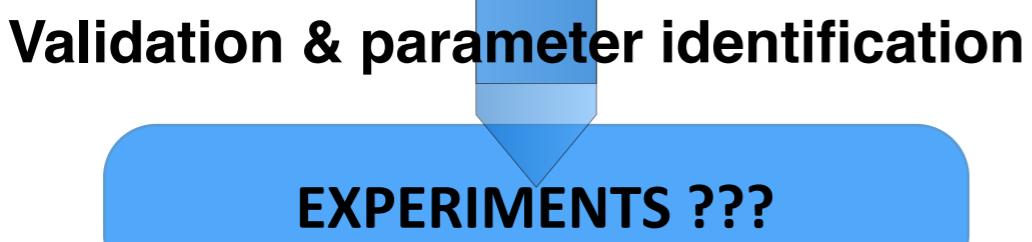
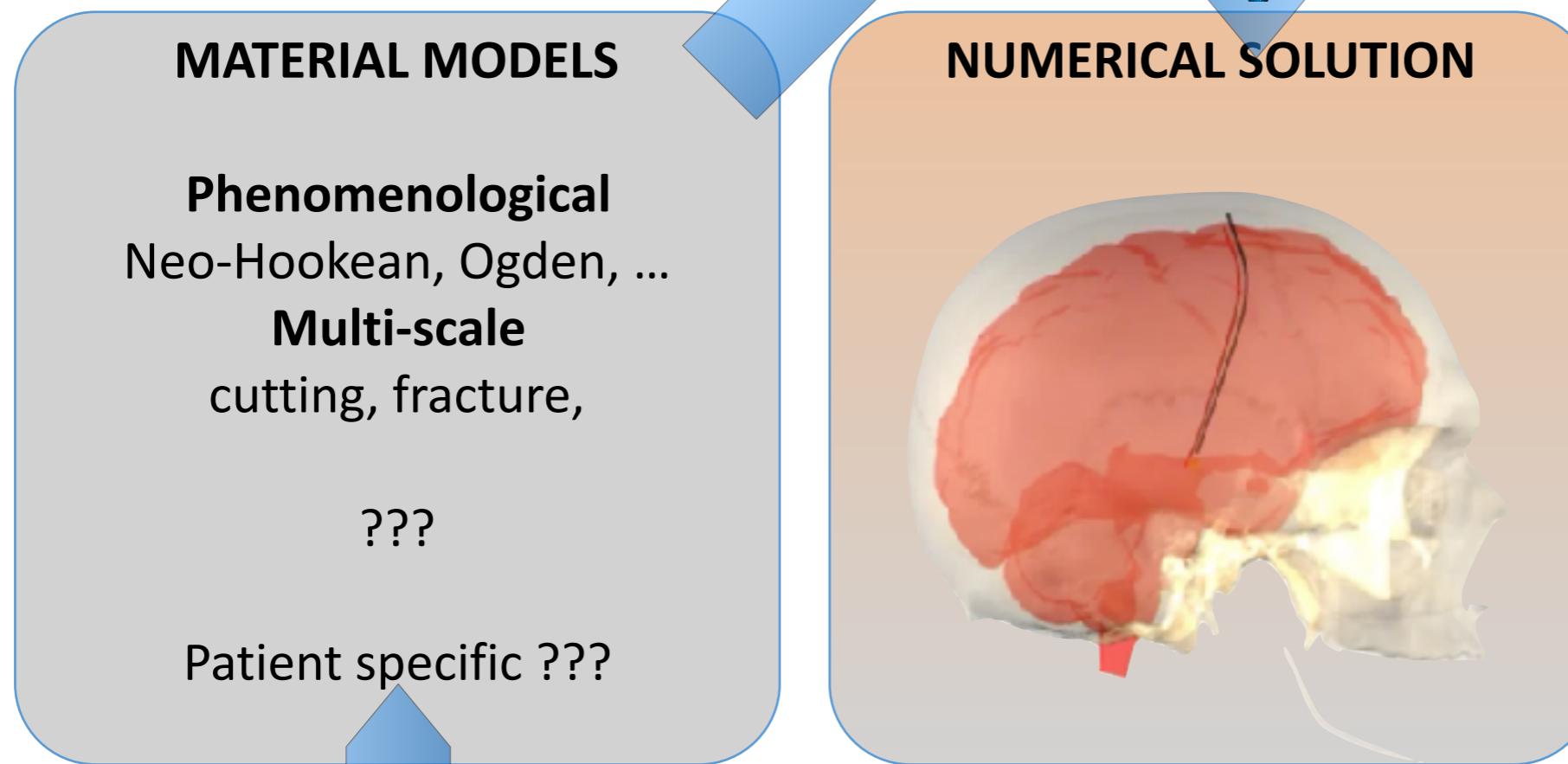
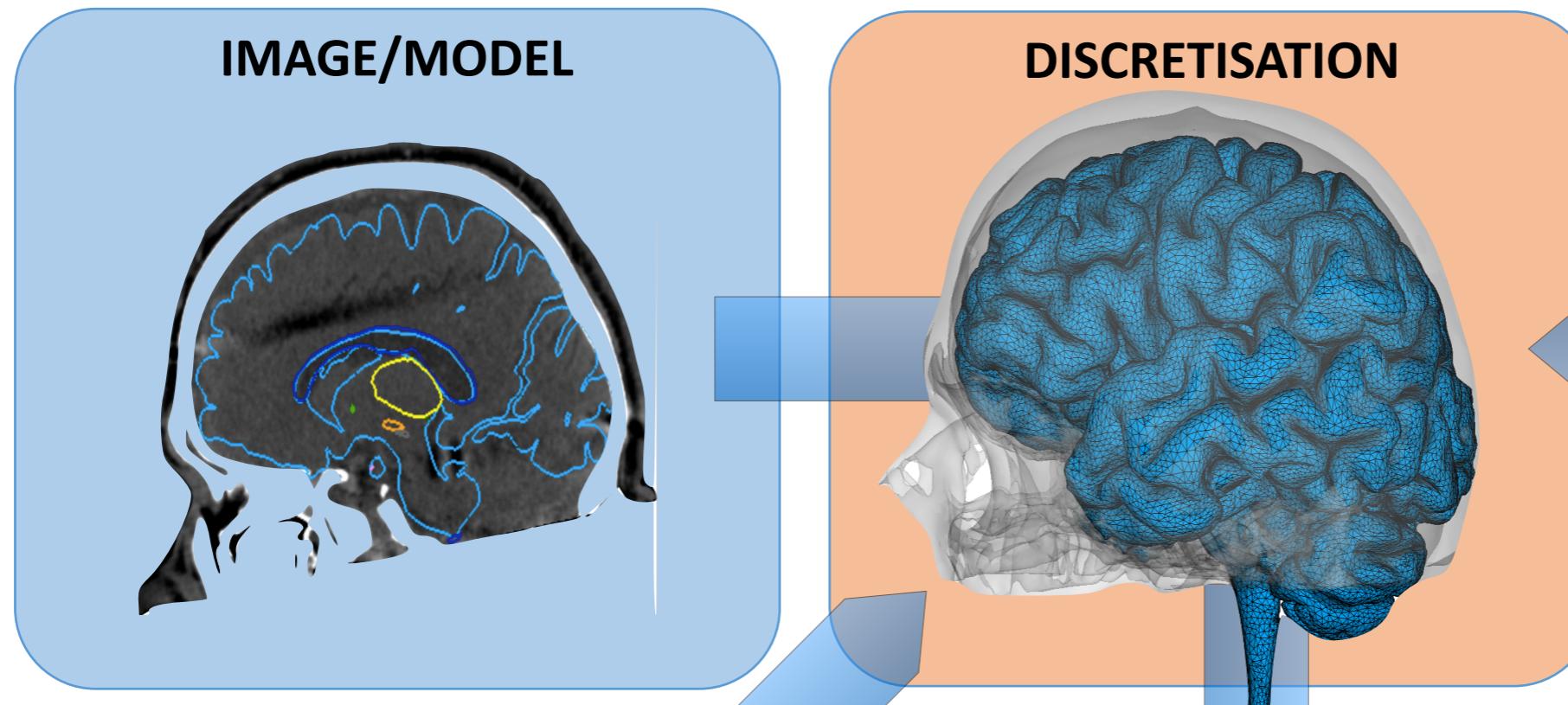
inuTech



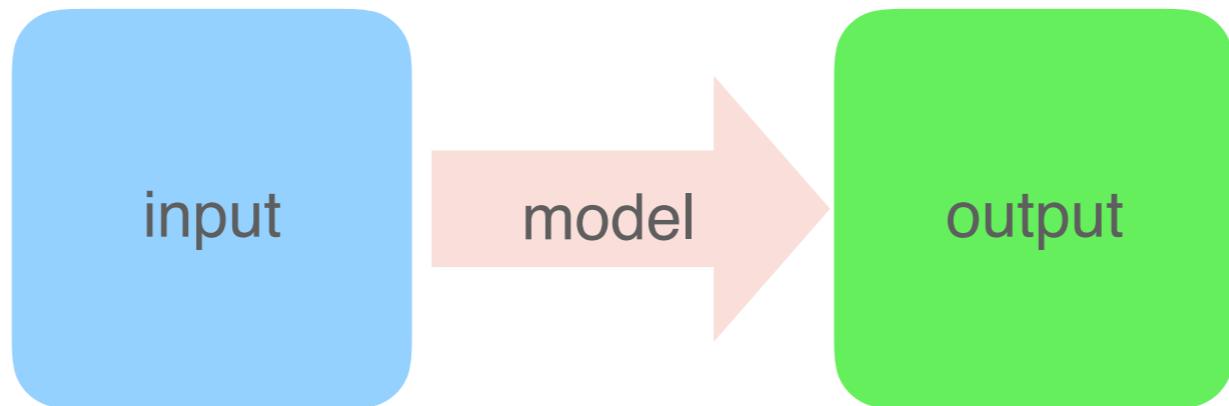


CONVENTIONAL APPROACH





Data-driven Modelling



$$f : \mathbf{x} \rightarrow \mathbf{y}$$

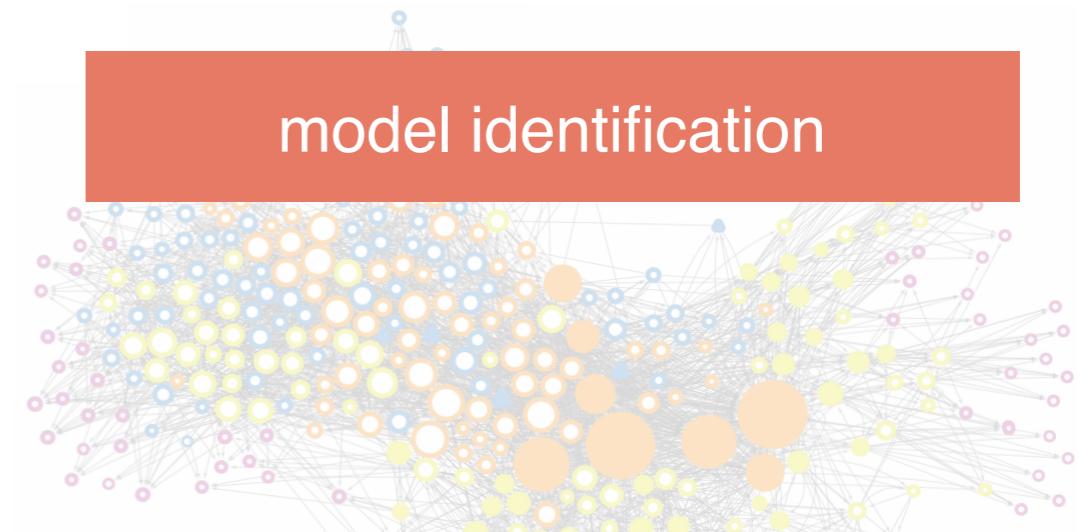
The structure of f is known but its parameters are not.

model calibration



There is no a priori knowledge about the function f available.

model identification

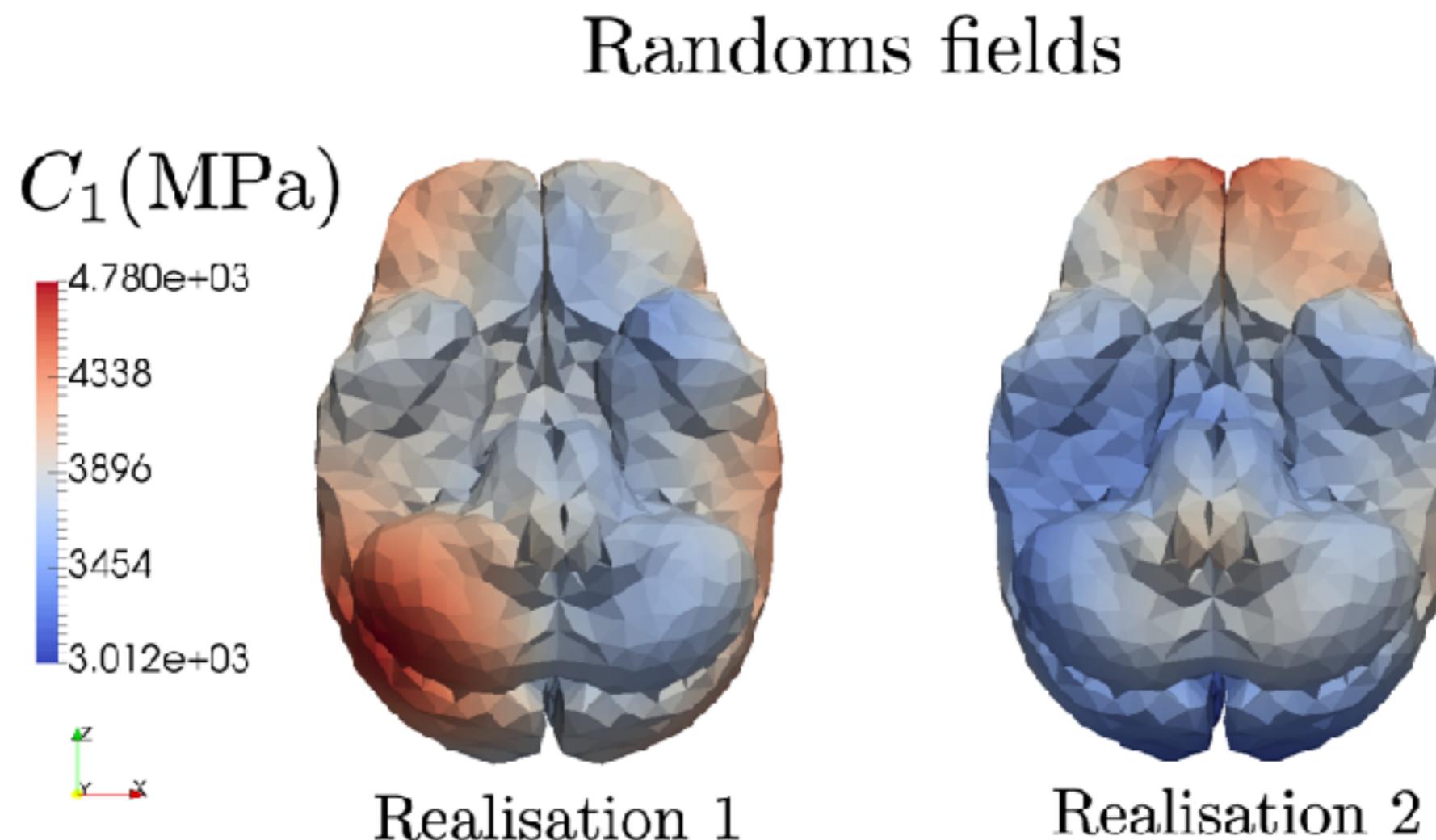


Embrace the conceptual shift from "*model through data abstraction*" to "*data is the model*".



Assuming the material model is representative, what is the influence of each parameter in the model?

- ▶ Different methods: Karhunen–Loève expansion [Adler 2007], Fast Fourier transform [Nowak 2004].



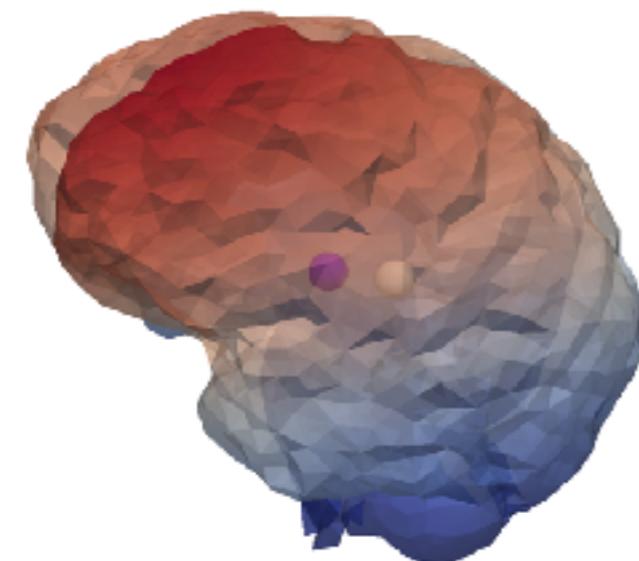
Two realisations of RF, with a log-normal distribution, for the parameter C_1 (in MPa).



Confidence level in predicting the target location

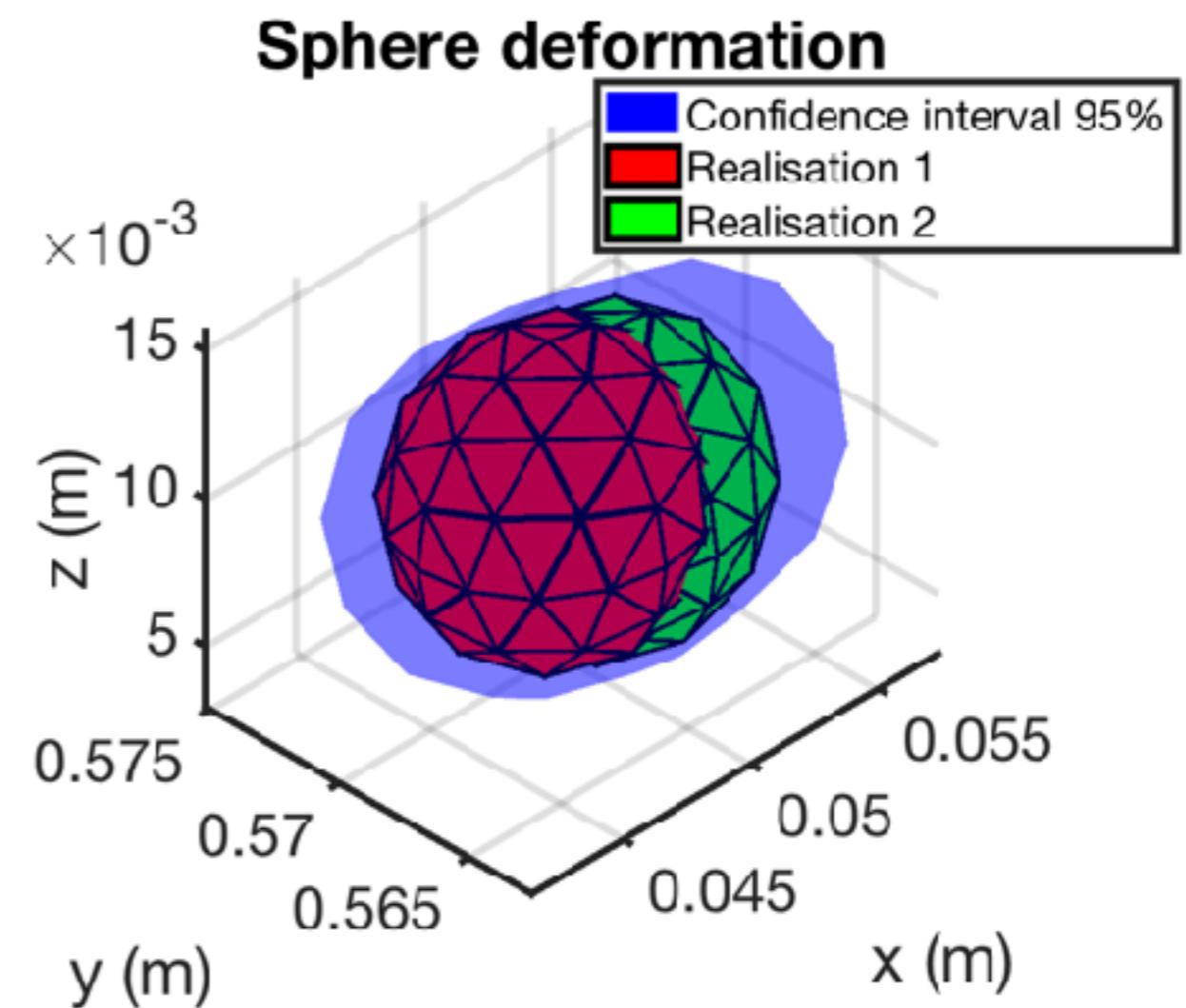
Displacement magnitude (m)

0.008 0.016 0.024

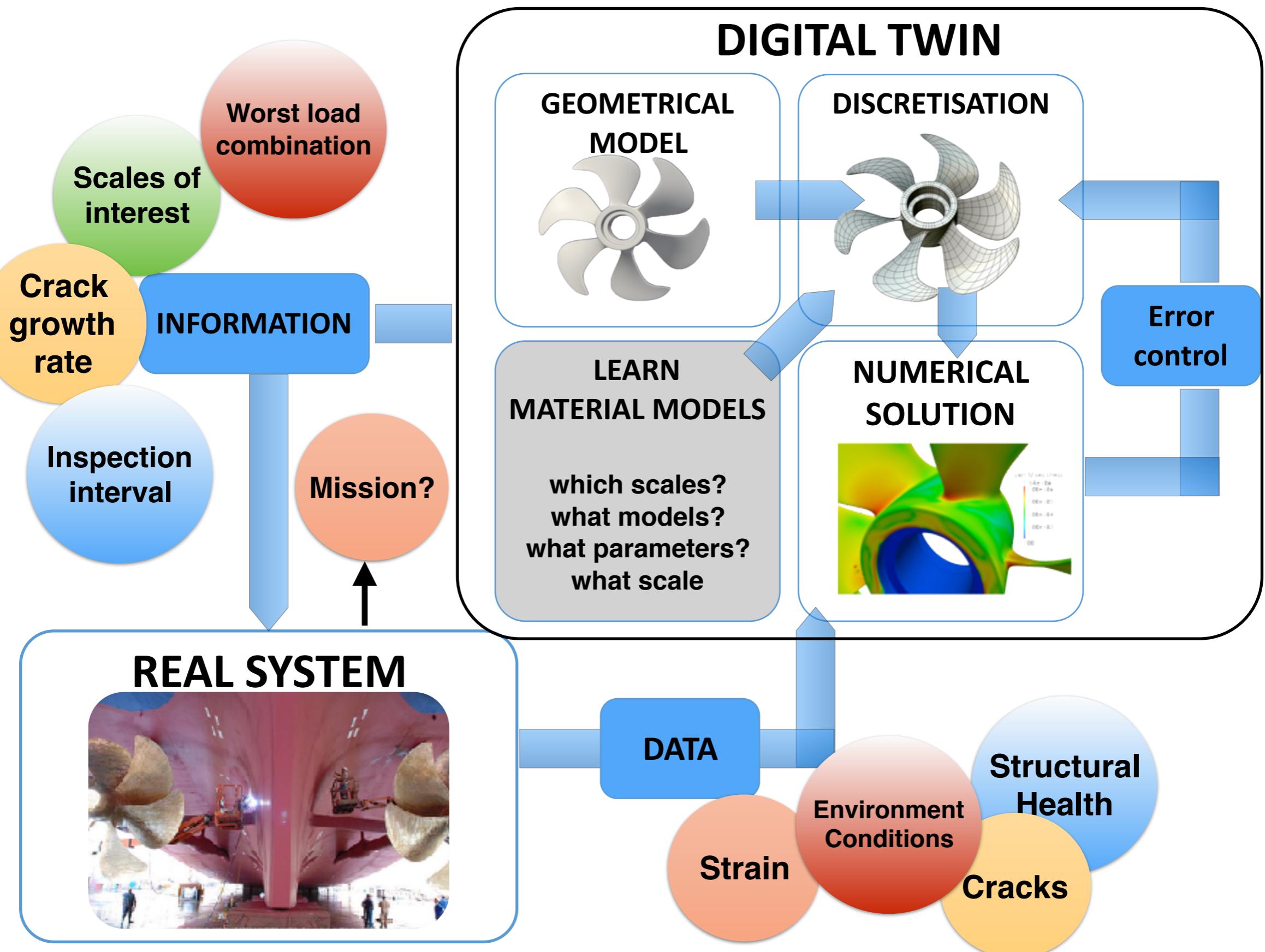


- Initial
- Deform

What is the influence of material parameters on computed quantities of interest?



Possible approach



DIGITAL TWIN OF THE PATIENT

