

Model and parameter identification through Bayesian inference in solid mechanics

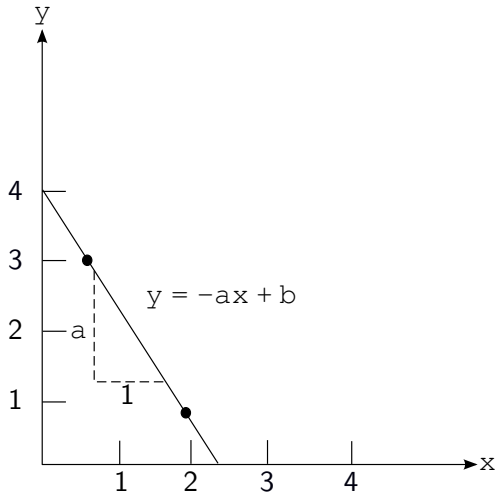
Hussein Rappel

h.rappel@gmail.com

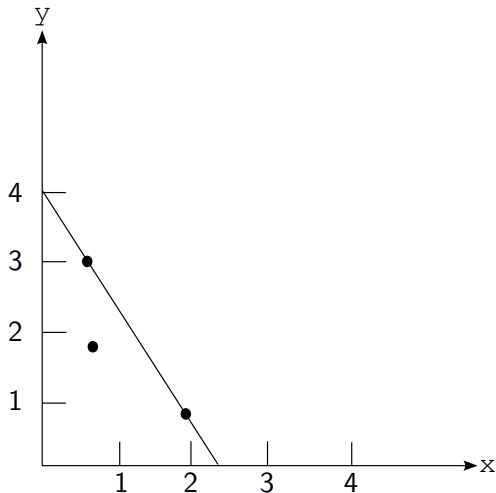
September 07, 2018



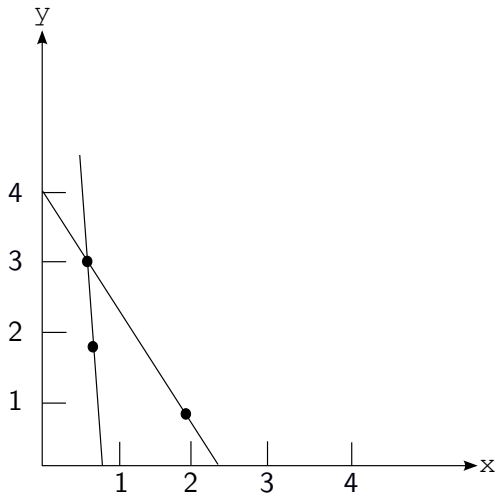
Introduction: Probabilistic modelling



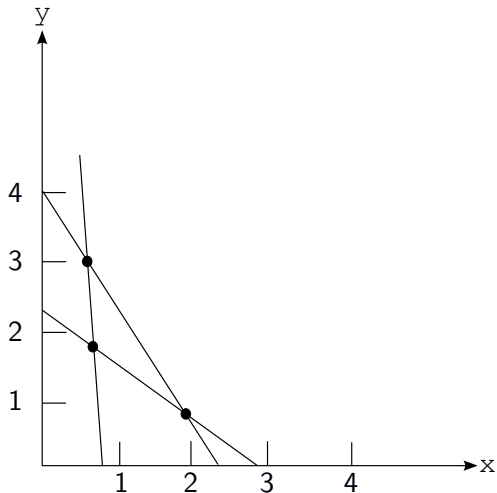
Introduction: Probabilistic modelling



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Introduction: Probabilistic modelling



Introduction: Probabilistic modelling

Each point can be written as the **model**+ a **corruption**:

$$y_1 = ax + c + \omega_1$$

$$y_2 = ax + c + \omega_2$$

$$y_3 = ax + c + \omega_3$$

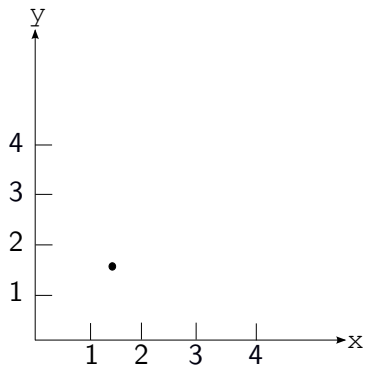
Introduction: Probabilistic modelling



Pierre-Simon
Laplace
1749–1827
([source wikipedia](#))

The corruption term can be
presented with a probability
distribution

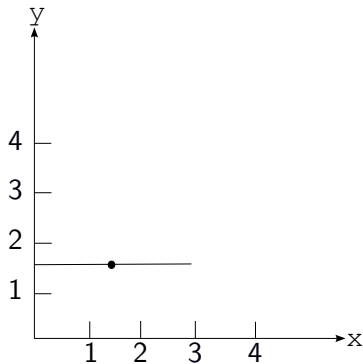
Introduction: Probabilistic modelling



How can we fit the $y = ax + b$ line, having only one point?

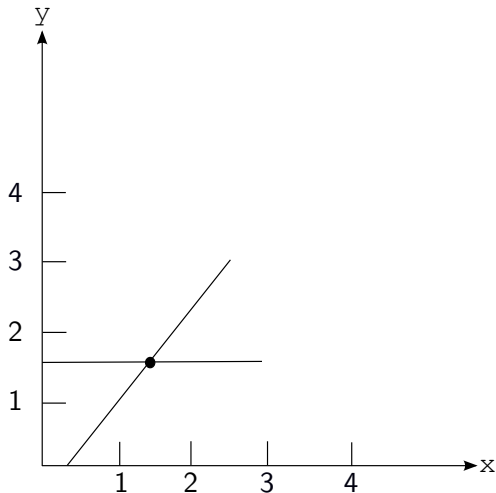
[Introduction to Gaussian Processes, Neil Lawrence](#)

Introduction: Probabilistic modelling

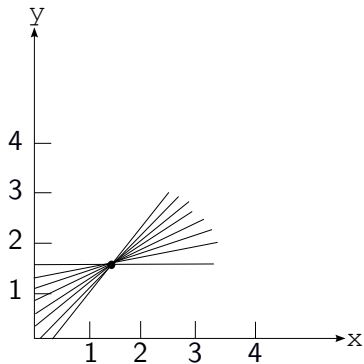


If b is fixed
 $\implies a = \frac{y-b}{x}$

Introduction: Probabilistic modelling



Introduction: Probabilistic modelling

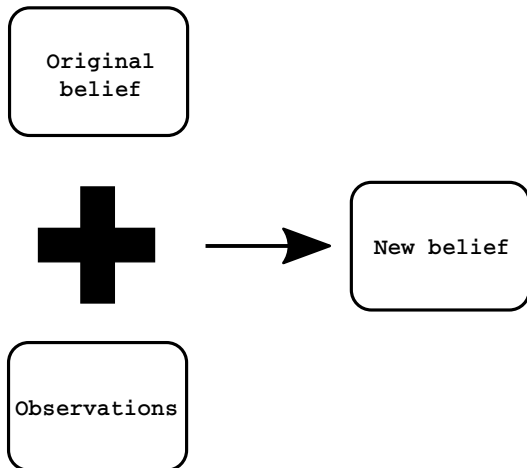


$$b \sim \pi_1 \implies a \sim \pi_2$$

Introduction: Probabilistic modelling

- This is called Bayesian treatment.
- The model parameters are treated as **random variables**.

Introduction: Bayesian perspective



Introduction: Bayesian formula (inverse probability)

$$\underbrace{\pi(x|y)}_{\text{posterior}} = \frac{\underbrace{\pi(x)}_{\text{prior}} \times \underbrace{\pi(y|x)}_{\text{likelihood}}}{\underbrace{\pi(y)}_{\text{evidence}}}$$

y := observation

x := parameter

$\pi(x)$:= original belief

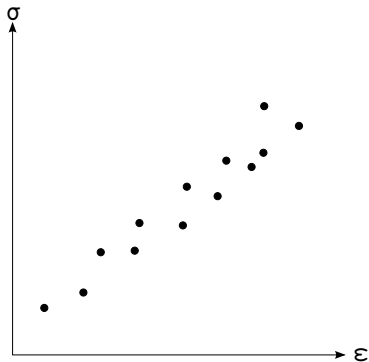
$\pi(y|x)$:= given by the mathematical model that relates y to x

$\pi(y)$:= is a constant number

Introduction: Bayesian formula (inverse probability)

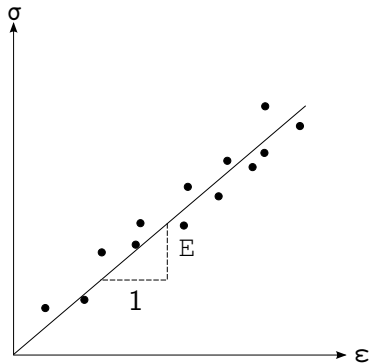
$$\pi(\mathbf{x}|\mathbf{y}) \propto \pi(\mathbf{x}) \times \pi(\mathbf{y}|\mathbf{x})$$

BI in computational mechanics



Linear elasticity

$$\sigma = E\varepsilon$$

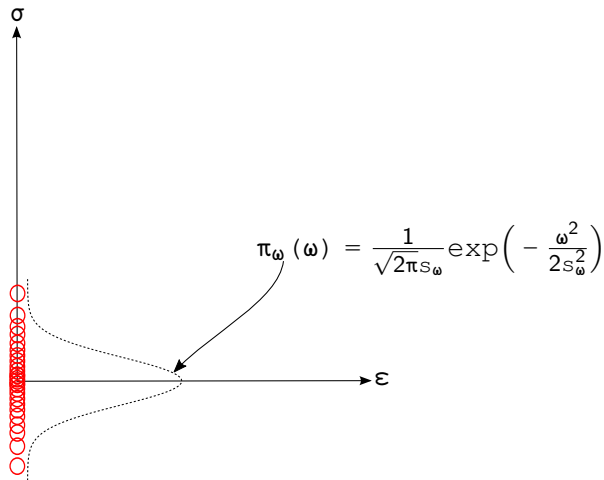


Linear elasticity

$$y = E\varepsilon + \omega$$
$$\Omega \sim \pi_{\omega}(\omega)$$

Capital letters denote a random variable

Linear elasticity



Noise PDF is modelled through calibration test.

Linear elasticity

Bayes' formula:

$$\pi(E | y) = \frac{\pi(E) \pi(y | E)}{\pi(y)} = \frac{\pi(E) \pi(y | E)}{k}$$

$$\pi(E | y) \propto \pi(E) \pi(y | E)$$

Linear elasticity

$$y = E\varepsilon + \omega$$
$$\Omega \sim N(0, s_{\omega}^2)$$

Linear elasticity

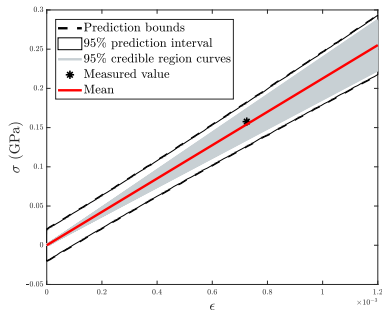
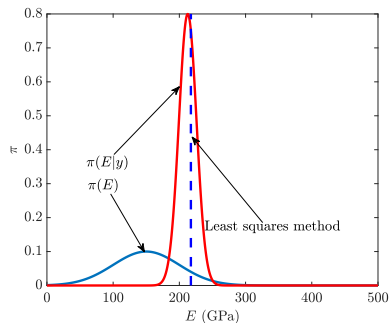
$$\pi(y|E) = \frac{1}{\sqrt{2\pi s_\omega}} \exp\left(-\frac{(y - E\varepsilon)^2}{2s_\omega^2}\right)$$

Linear elasticity

Posterior:

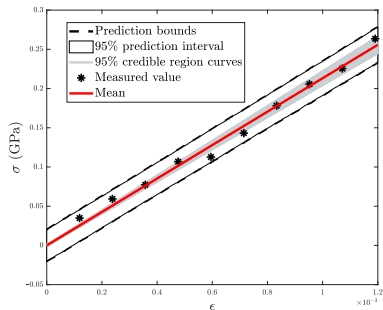
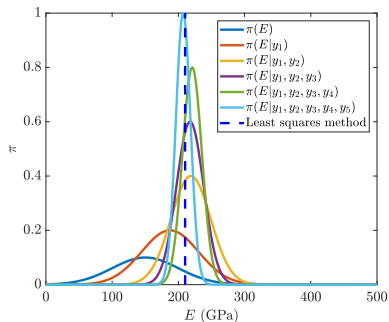
$$\pi(E | y) \propto \exp\left(-\frac{(E - \bar{E})^2}{2s_E^2}\right) \exp\left(-\frac{(y - E\epsilon)^2}{2s_\omega^2}\right)$$

Linear elasticity

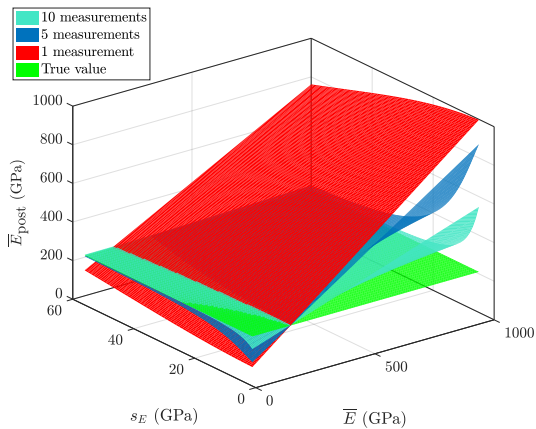


- **Prediction interval:** An estimate of an interval in which an observation will fall, with a certain probability.
- **Credible region:** A region of a distribution in which it is believed that a random variable lie with a certain probability.

Linear elasticity



Prior effect



Model uncertainty and input error

$$y = f(\mathbf{x}, \varepsilon) + \omega$$
$$\Omega \sim \pi_{\omega}(\omega)$$

ε is the input variable and \mathbf{x} is the parameter vector

*All models are wrong
but some are useful*



George E.P. Box

Model uncertainty and input error

Kennedy-O'Hagan (KOH) framework:

$$y = \underbrace{f(\mathbf{x}, \varepsilon) + d(\mathbf{x}_d, \varepsilon)}_{Y_{\text{true}}} + \omega$$

ε is the input variable and \mathbf{x} is the parameter vector

Model uncertainty and input error

- Constant number d_0
- Deterministic function $\sum_{i=0}^l a_i \epsilon^i$
- Random variable from normal distribution
 $d \sim N(m, s_d^2)$
- Random variable from a normal distribution
with input dependent mean and variance
 $d \sim N(m(\epsilon), s_d^2(\epsilon))$
- Gaussian process (GP)
- ...

Model uncertainty and input error

Bayes' formula:

$$\pi(\mathbf{x}, \mathbf{x}_d | y) \propto \pi(\mathbf{x}) \pi(\mathbf{x}_d) \pi(y | \mathbf{x}, \mathbf{x}_d)$$

- Both material and model error parameters must be inferred.

If $d(\mathbf{x}_d, \varepsilon)$ is deterministic (for simplicity):

$$\pi(\mathbf{x}, \mathbf{x}_d | y) \propto \pi(\mathbf{x}) \pi(\mathbf{x}_d) \pi_\omega(y - f(\mathbf{x}, \varepsilon) - d(\mathbf{x}_d, \varepsilon))$$

Model uncertainty and input error

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Model uncertainty and input error

But what about the input error?

Model uncertainty and input error

$$y = f(\mathbf{x}, \boldsymbol{\varepsilon}) + d(\mathbf{x}_d, \boldsymbol{\varepsilon}) + \omega$$
$$\boldsymbol{\varepsilon}^* = \boldsymbol{\varepsilon} + \omega_{\boldsymbol{\varepsilon}}$$

$$\Omega \sim \pi(\omega)$$
$$\Omega_{\boldsymbol{\varepsilon}} \sim \pi(\omega_{\boldsymbol{\varepsilon}})$$

Model uncertainty and input error

Bayes' formula:

$$\pi(\mathbf{x}, \mathbf{x}_d, \varepsilon | y, \varepsilon^*) \propto \pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) \pi(\varepsilon | \varepsilon^*) \pi(\mathbf{x}) \pi(\mathbf{x}_d)$$

$$\pi(\mathbf{x}, \mathbf{x}_d | y, \varepsilon^*) \propto \int_0^b \pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) \pi(\varepsilon | \varepsilon^*) d\varepsilon \pi(\mathbf{x}) \pi(\mathbf{x}_d)$$

$$\begin{aligned} \pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) &= \pi_{\omega} (y - f(\mathbf{x}, \varepsilon) - d(\mathbf{x}_d, \varepsilon)) \\ \pi(\varepsilon | \varepsilon^*) &= \pi_{\omega_{\varepsilon}} (\varepsilon^* - \varepsilon) \end{aligned}$$

Model uncertainty and input error

Bayes' formula:

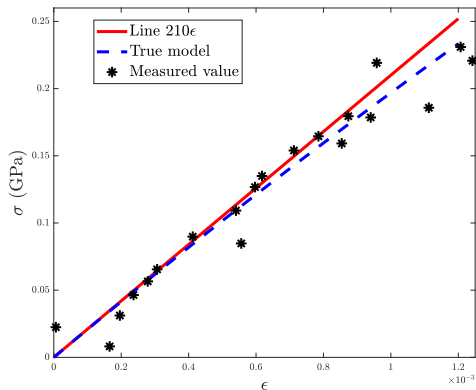
$$\pi(\mathbf{x}, \mathbf{x}_d, \varepsilon | y, \varepsilon^*) \propto \pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) \pi(\varepsilon | \varepsilon^*) \pi(\mathbf{x}) \pi(\mathbf{x}_d)$$

$$\pi(\mathbf{x}, \mathbf{x}_d | y, \varepsilon^*) \propto \int_0^b \pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) \pi(\varepsilon | \varepsilon^*) d\varepsilon \pi(\mathbf{x}) \pi(\mathbf{x}_d)$$

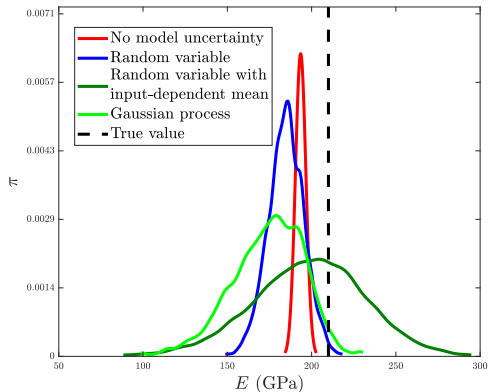
$$\pi(y | \mathbf{x}, \mathbf{x}_d, \varepsilon) = \pi_{\omega} (y - f(\mathbf{x}, \varepsilon) - d(\mathbf{x}_d, \varepsilon))$$

$$\pi(\varepsilon | \varepsilon^*) = \pi_{\omega_{\varepsilon}} (\varepsilon^* - \varepsilon)$$

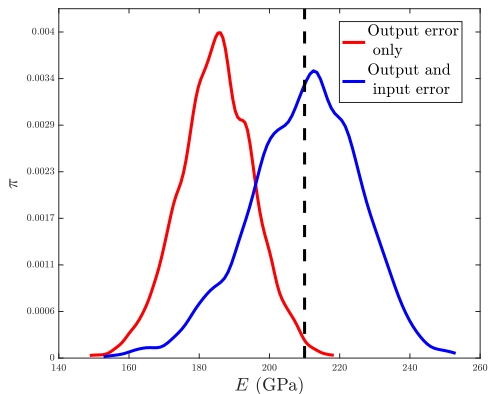
Model uncertainty and input error: Linear elasticity



Model uncertainty and input error: Effect of model uncertainty

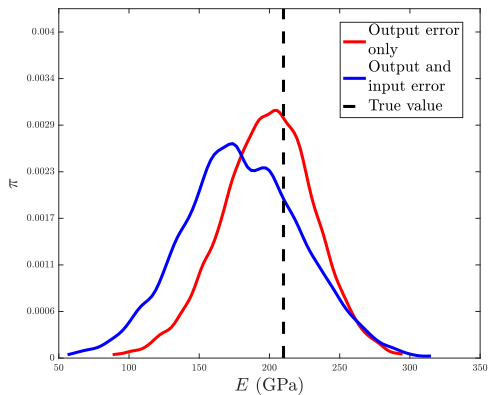


Model uncertainty and input error: Effect of model uncertainty as well as input error



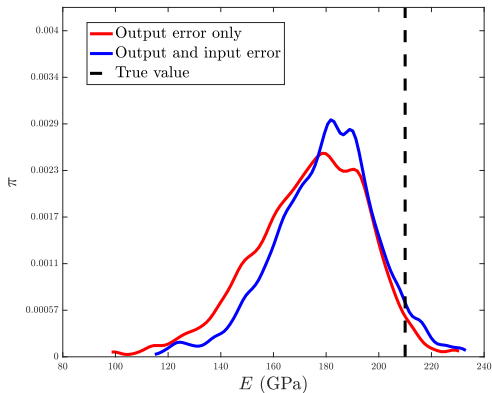
Normal distribution with constant parameters

Model uncertainty and input error: Effect of model uncertainty as well as input error



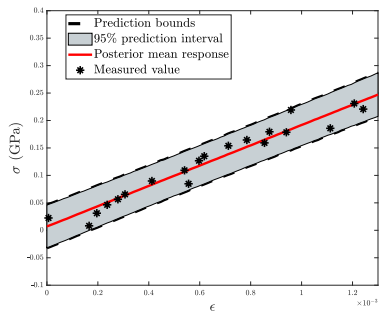
Normal distribution with an input-dependent mean

Model uncertainty and input error: Effect of model uncertainty as well as input error

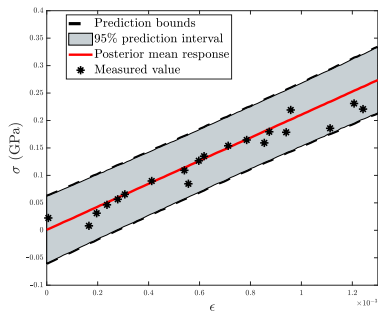


Gaussian process

Model uncertainty and input error: Effect of model uncertainty as well as input error



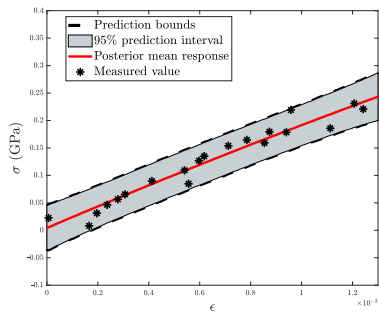
without input error



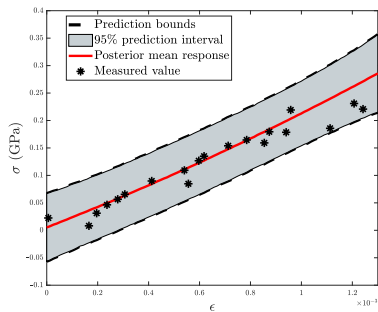
with input error

Normal distribution with constant parameters

Model uncertainty and input error: Effect of model uncertainty as well as input error



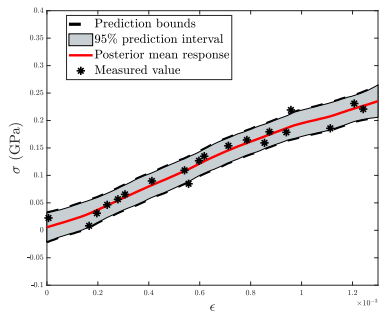
without input error



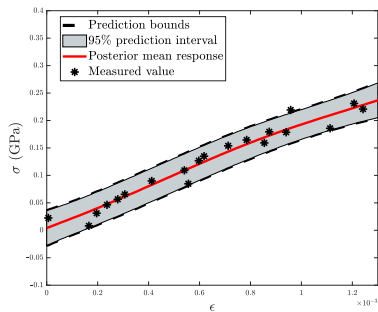
with input error

Normal distribution with an input-dependent mean

Model uncertainty and input error: Effect of model uncertainty as well as input error



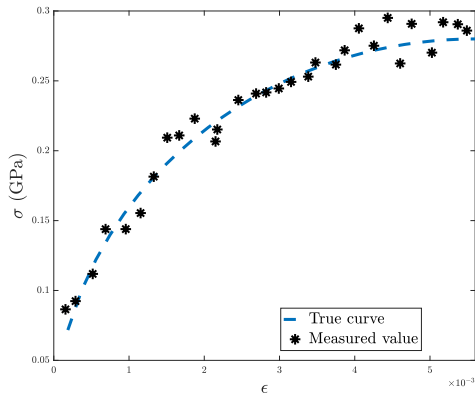
without input error



with input error

Gaussian process

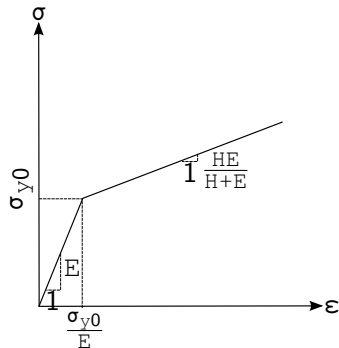
Model uncertainty and input error: Linear elastic-linear hardening



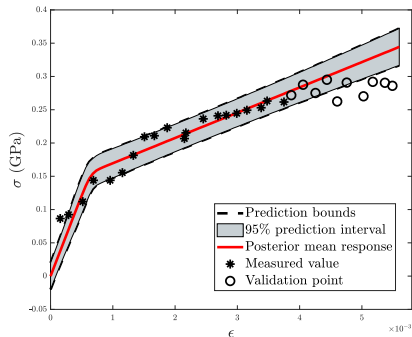
Model uncertainty and input error: Linear elastic-linear hardening

$$\sigma(\epsilon, \mathbf{x}) = \begin{cases} E\epsilon & \text{if } \epsilon \leq \frac{\sigma_{y0}}{E} \\ \sigma_{y0} + \frac{HE}{H+E} \left(\epsilon - \frac{\sigma_{y0}}{E} \right) & \text{if } \epsilon > \frac{\sigma_{y0}}{E} \end{cases}$$

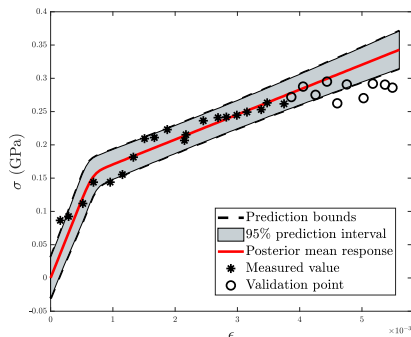
$$\mathbf{x} = [E, \sigma_{y0}, H]$$



Model uncertainty and input error: Linear elastic-linear hardening, extrapolation

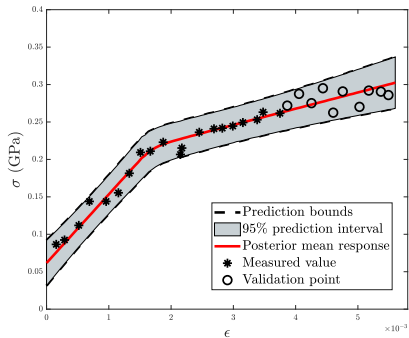


Error in the stress measurements only

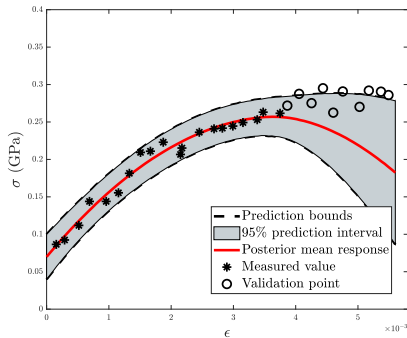


Error in both the stress and the strain measurements

Model uncertainty and input error: Linear elastic-linear hardening, extrapolation



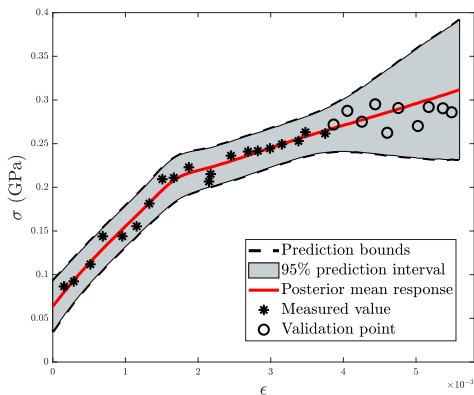
Normal distribution with constant parameters



Normal distribution with an input-dependent mean

Input error is considered for both cases.

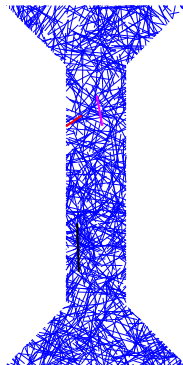
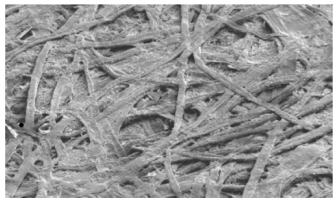
Model uncertainty and input error: Linear elastic-linear hardening, extrapolation



Gaussian process

Input error is also considered.

Material parameter distribution

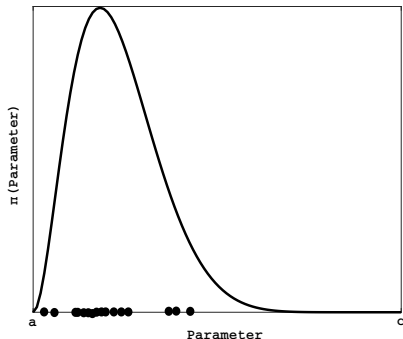


- Geometrical randomness
- Material parameter randomness

Material parameter distribution

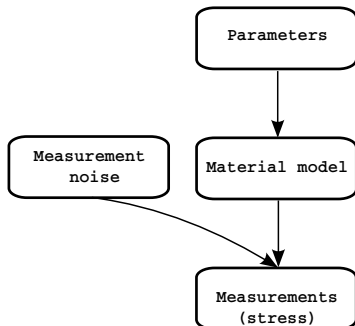
Objective

Find the distribution from which the parameters of the specimens are coming with **limited** number of specimens, $N=20$.



Identification scheme

$$\pi(x|y) \propto \pi(x) \pi(y|x)$$



Identification scheme

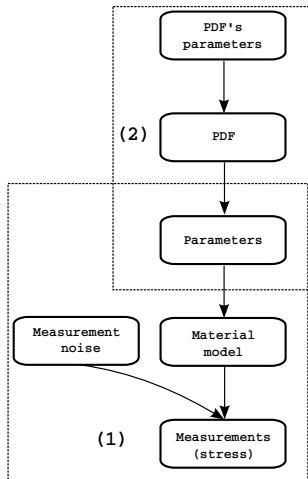
$$y \sim \pi(y | x_m) \rightarrow (1)$$

$$x_m \sim \pi(x_m | x_{PDF}) \rightarrow (2)$$

$$x_{PDF} \sim \pi(x_{PDF}) \rightarrow \text{prior}$$

$$\pi(x_m, x_{PDF} | y) \propto$$

$$\pi(y | x_m) \pi(x_m | x_{PDF}) \pi(x_{PDF})$$



Hard to incorporate when the parameter distribution or model is not standard!

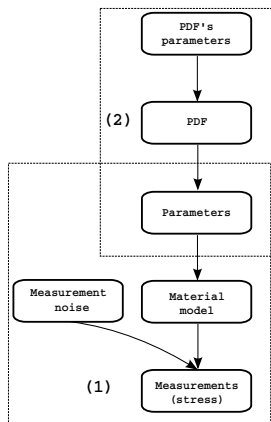
Identification scheme: Bayesian updating-Least squares

(1) \rightarrow Least squares

(2) \rightarrow
Bayesian updating

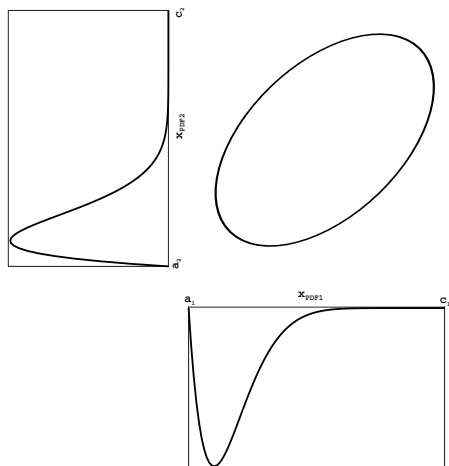
$$\pi(x_{\text{PDF}} | \bar{x}_m) \propto$$

$$\pi(x_{\text{PDF}} | \bar{x}_m) \pi(x_{\text{PDF}})$$

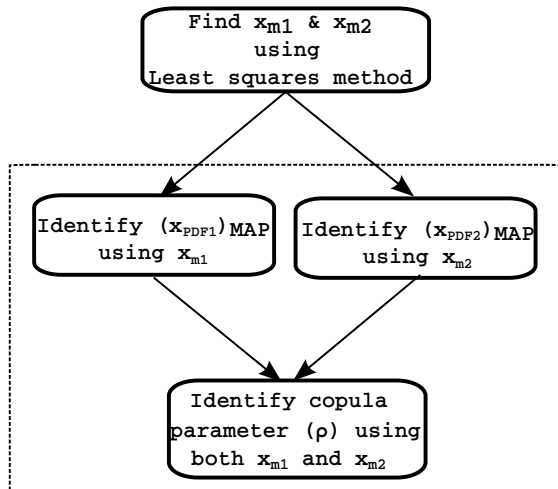


Copula

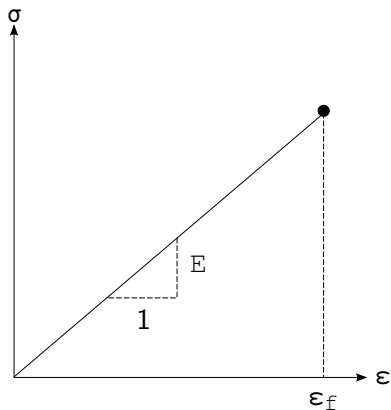
Copulas are tools enable us to model dependence of several random variables in terms of their marginal distribution.



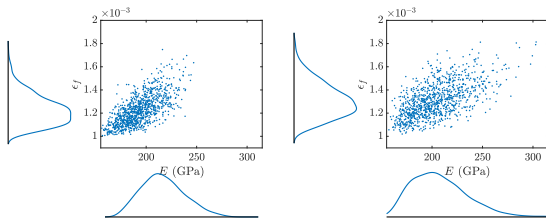
Proposed framework



Identification results: Brittle damage

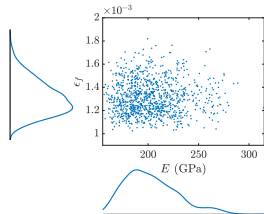


Identification results: Brittle damage



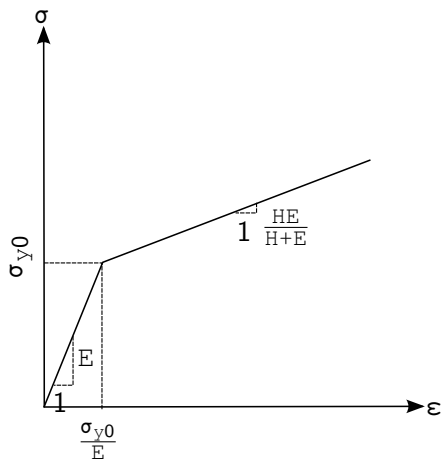
True

Identified

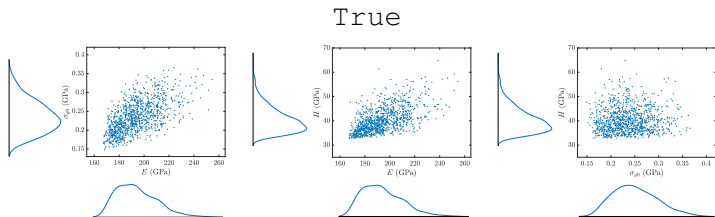
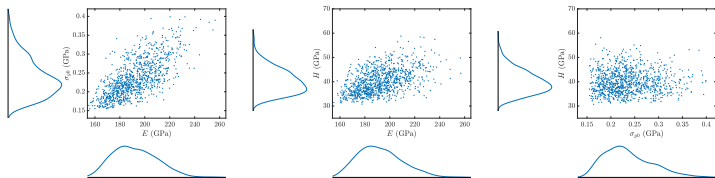


Identified without correlation

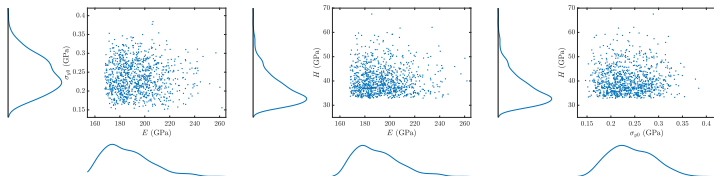
Identification results: Linear elastic-linear hardening



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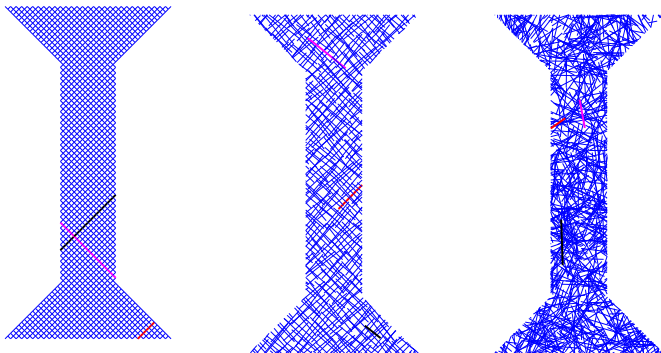


Identification results: Linear elastic-linear hardening



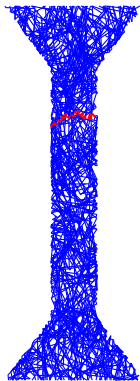
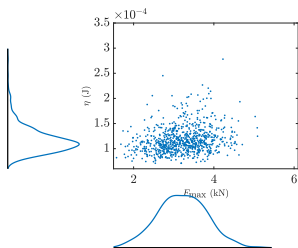
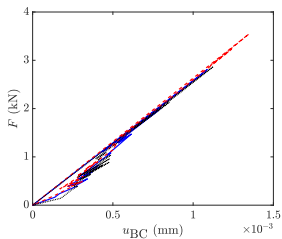
Identified without correlation

Influence of geometrical randomness

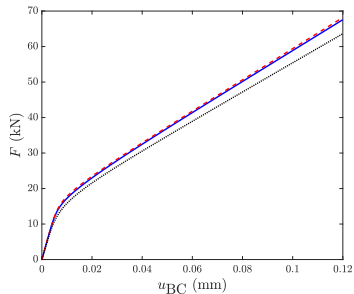


A: Regular B: Partially random C: Random

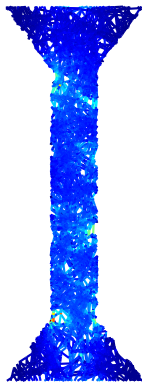
Influence of geometrical randomness: Brittle damage



Influence of geometrical randomness: Linear elastic-linear hardening



Equivalent parameters
scatter plots are
given.



Influence of geometrical randomness

- Including correlation has no significant influence in damage case.
- The effect of correlation becomes significant for the elastoplastic case.
- Increasing geometry randomness decreases the influence of correlation.
- Correlation is more important for long fibres and large fibre densities.

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Summary and conclusion

- Probability is the natural way of modelling lack of our knowledge (what Laplace calls it our ignorance).
- From Bayesian perspective (inverse probability) the parameters are treated as *random variables*.
- In addition to number of measurements the influence of the prior is dependent to the model (e.g. for viscoelastcity the prior has more significant effect than elastoplasticity).
- Incorporating model uncertainty as well as input error improves both identification results and probabilistic predictions.

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- Incorporating model uncertainty as well as input error improves both identification results and probabilistic predictions.

Summary and conclusion

- Probability is the natural way of modelling lack of our knowledge (what Laplace calls it our ignorance).
- From Bayesian perspective (inverse probability) the parameters are treated as **random variables**.
- In addition to number of measurements the influence of the prior is dependent to the model (e.g. for viscoelastcity the prior has more significant effect than elastoplasticity).
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Summary and conclusion

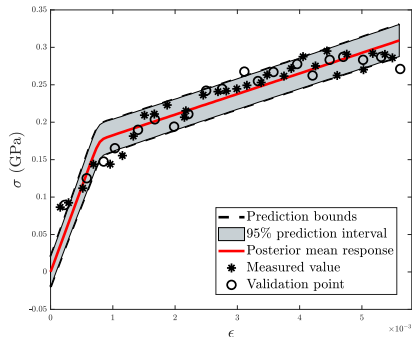
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- We tried to answer the question of “how accurate the material parameter PDF needs to be identified?” in presence of geometrical randomness.
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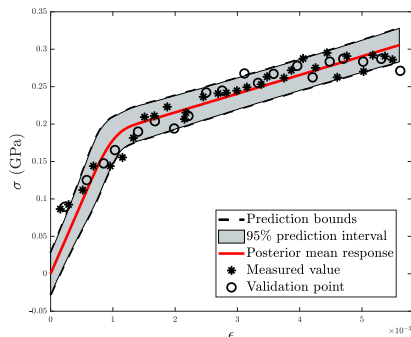
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The End

Model uncertainty and input error: Linear elastic-linear hardening, interpolation

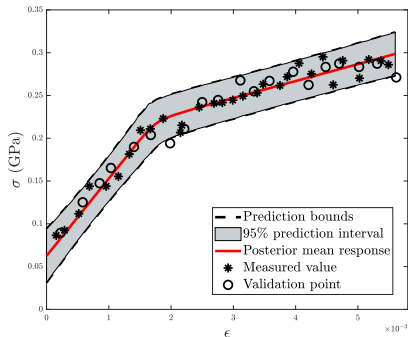


Error in the stress measurements only

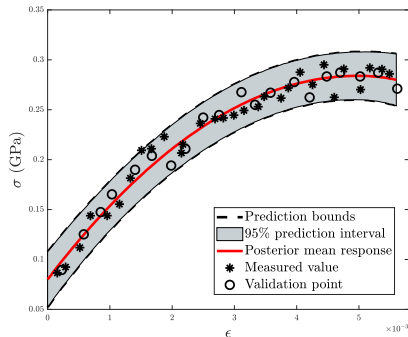


Error in both the stress and the strain measurements

Model uncertainty and input error: Linear elastic-linear hardening, interpolation

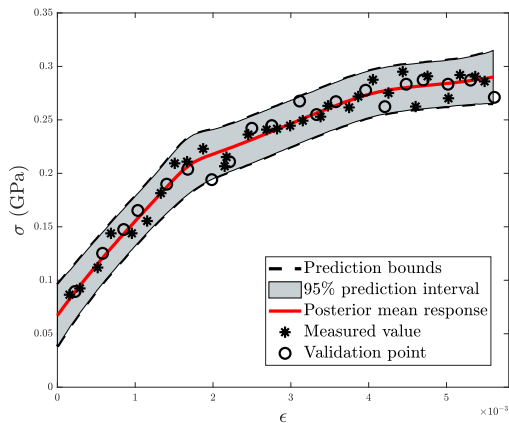


Normal distribution with constant parameters



Normal distribution with an input-dependent mean

Model uncertainty and input error: Linear elastic-linear hardening, interpolation



Gaussian process