BASIC PRINCIPLES OF HYDROSTATIC LEVELLING

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Abstract

The paper aims to introduce the distribution, history and the basic physical principles hydrostatic leveling. The principle of this method is based on known law of connected vessels filled with fluid. Well known equipment is surface water level, the height of the surface is deducted on millimetre scale. There are currently used devices that allow deducting with accuracy of 0,01 mm.

Keywords: levelling, height, hydrostatic pressure

1 INTRODUCTION

Hydrostatic levelling is one of many methods used for definition of elevation. This term is usually used for all systems using for the elevation definition fluids in connected vessels. Devides these methods into:

- hydrostatic,
- hydrodynamic,
- hydromechanic.

All stated methods are based on the same principles of hydrostatics and hydrodynamics. The methods varies in the way of realization of a measuring process.

Hydrostatic levelling observes surface of still fluid. These systems measures elevation in a scope of circa 10 cm, they have high accuracy from 0,05 mm to 0,01 mm. Nowadays the height of surface is mostly defined automatically by various types of sensors, contact, capacity, ultrasound or floating.

Hydrodynamic levelling uses for the definition of elevation flowing fluid based on Bernoulli quotation. Measuring systems may be similar to systems for hydrostatic levelling. Equipments for hydrodynamic levelling reach accuracy 0,01 mm to 2,5 mm. This category may cover also levelling defining elevation based on sea surface elevation among land and the closest islands. This way may be used for transferring the heights for tens of kilometers distance. The method was used e.g. at height connection of British continent over English Channel.

The method of hydromechanical levelling defines elevation based on hydrostatic pressure in fluid column in connected vessels. Deriving the hydrostatic pressure quotation, described into more details in the following chapter, it can be stated the hydrostatic pressure is independent on the value of the fluid in a vessel but on a height of a water column. The accuracy of these systems states with a determinative deviation 1 cm in which states accuracy of 2,2 cm. (Lechner, J 1990, Vasjutinskij, I 1984)

The usage of hydrometric levelling states e.g. when measuring roads, piping, power line, geodetical control of a volume of ground works, measuring of relieve of densly constructed and forested areas. Hydromechanical levelling is of a relative vast extend of measured elevation (to several meters), and in labour productivity significantly overcome majority of other levelling methods.

Hydrostatic and hydrodynamic systems recorded the largest development in the last decades of the last century when there started to be used electrical systems for surface deduction and automatical report of processed results by computers.

2 HISTORY

Historically is the hydrostatic height levelling dated back to the time of ancient Egypt when constructing vast irrigational sewers. As states it was so called first water levelling device used 2 500 years ago while constructing Pharao's sewers connecting the Nile and the Red Sea. The first devices using still water levels was Chorobates. This device leveled itself into water level according to water filled up in the groove on the upper side of the device. As another example of device used in ancient times may be mentioned Heron levelling device, see Figure 1. This device used water level in two mutually connected pipes. The level served as model for evening peepholes and with a rod with circular target helped to define elevation.



Fig. 1. Heron's levelling device (Kotsanas, K)

Other known device, see Figure 2, working based on water level was constructed during the reign of Rudolf II, it was constructed by emperor's mechanic Erasmus Habermel. Its function describes e.g.. The groove as long as 552 mm was poured by water and the device evened by the toothed segment in the down part. The water level position is observed on both front small plates. The device was made of gilden copper. (Staňková et al. 2010).



Fig. 2. Habermel levelling device

"Hydrostatic levelling", or rather still fluid surface, further started to use pipe and spirit level vials. It can be said libels are currently most frequently used measuring equipment using the principle of still fluid surface.

The easiest device based on similar principle as the above described devices is currently laser water level. This device substituted groove with water for pipe water level, and uses laser diode.



Fig. 3. Laser water level (Robert Bosch GmbH)

The development of devices for hydrostatic levelling continued with the use of hose devices. Most often used equipments of this type are hose waterlevel used in constructing. (Jadviščok et al. 2012)



Fig. 4. Hose water level

More accurate equipments are hose altimeters. As a first hose altimeter was used Takahasi altimeter during the construction of a railway tunel Tana in Japan in 1930. As another example may serve Meisser set of 1952 which was widely used also in our region. This set used for a water surface height definition needle and micrometer. Later Meisser construction incorporates an electrical circuit to detect the touch of needle and water. Both the Meisser's sets are currently made in Freiberger Präzisionsmechanik company.



Fig. 5. Meisser set (Sladková 2002)

Further development of hydrostatic levelling is in rising accuracy of deduction of location and water surface. The surface deduction is possible to make optically, micrometrically, and lately the most frequently used electronical deduction. The accuracy of these devices is stated as circa 0,01 mm. (Jadviščok et al. 2012)

Altitudial connection of islands and constructions of long bridges abroad used systems suitable for measuring elevation for distances of tens of kilometers. The accuracy of the height tracing between the German island Fehmarn and Danish island Loland of the distance of circa 19 km states as 0,11 mm. These measurings were made for at that time intended bridge construction connecting the island. Some countries used also hydrodynamic systems, with fluid in a constant motion. Worth mentioning is also a way of height connection of Sri Lanka and India that was realized by longitudinal observation of sea level.

The problem of hydrostatic levelling and its practical usage studied in the Czech Republic doc. Ing. Jiří Pažourek, CSc. He used this method for observing deformations of constructions. His most important work was monitoring of turbogenerators in nuclear plant in Dukovany. This set consists of two vessels connected by a hose. Deduction was done with a use of metal prong with micrometer-equipped move. (Pažourek 1982)

Hydrostatic levelling was used in Ostrava region for observing inclination of gasometer in Ostrava – Marianske Hory. This aktivity was realised by the Institute of Geodesy and Mine Surveying employees using Meisser hose water level.

Worth mentioning is also device Nivelovat designed in Institute of Measurement Science Slovak Academy of Sciences in Bratislava, that was used for measuring inclination of reactor in Jaslovske Bohunice. (Michalčák et al. 1993) There are many systems based on the principle of hydrostatic levelling and the summary of currently most used ones can be found in the next chapter No. 3.

3 PHYSICAL PRINCIPLE OF HYDROSTATIC LEVELLING

This part of work focuses rather on physics than geodetics. But it is physics together with mathematics that build the base for all other technical branches, including geodetics.

The principle of hydrostatic levelling is relatively simple; it is based on a principle of communicating vessels filled with fluid. The principle of communicating vessels is applied in many scientific branches, such as engineering, building, geodetics, geotechnics, and many others.

3.1 Fluids

All substances are divided into solid, liquid, and gaseous state. Solid substances are in fact crystalline. Rising temperature causes their transition from solid to liquid state, with relatively easy change of molecules positioning. The molecules of liquids are mutually attracted that is why they keep together and seem cohesive. Rising temperature leads to rising speed of molecules that may afterwards overcome the force of their mutual attraction and draw apart from the fluid, the fluid then vaporizes. This is the origin of another state – the gaseous state.

3.2 Mechanics of fluids

The state of fluids allow significant move of the smallest particles causing so easy change of their shape. Fluids due to the Earth's gravity adjust their shape to the shape of their containers and fill their bottom parts. Fluids would keep themselves in ball-shape shapes without gravity, that is only due to their mutual cohesiveness of molecules and their surface tension.

The move of the particles in fluids causes that the surface of the fluid is always orthogonal to the resultant forces affecting it. Motionlessness fluid (static) affects only gravity and its surface is curved according to the geiod. This curvature can be seen only on larger water surfaces. Smaller surfaces level flat.

The volume of fluids is especially influenced by temperature and pressure. Distil water has according to higher density at average pressure and temperature of 3,98°C. Reliance of density on temperature shows Figure 6.



Fig. 6. Reliance of distil water density on temperature

The volume of the fluid varies only a little on a constant temperature and different pressure. The fluids can be defined to have almost constant volume in constant temperature and changeable shape. If the volume of the liquid changes due to the pressure, its volume change would equal zero after the pressure returns to its initial position. Fluids are so perfectly elastic. The term pressure is understood as a ratio of force and surface that is being affected. Pressure is then defined as:

$$p = \frac{dF}{dS} \tag{1}$$

where: p-pressure,

F - force change,

S – surface area that is affected by force.

3.3 Fluid compressibility

One of the basic qualities of all real fluids is compressibility. Compressibility is different for different fluids, decreases in rising pressure, and on the other hand it usually increases with rising temperature. The term compressibility of fluids γ is defined as a relative reduction of fluid volume at 1 Pa pressure decrease. This can be expressed by formula

$$\gamma = -\frac{1}{V} \cdot \frac{dV}{dp}$$
⁽²⁾

where: γ – fluid compressibility,

V - volume of fluid before compression,

dV - change of original fluid volume,

dp - change of pressure.

3.4 Pascal's law

Pascal's law describes spread of pressure in fluids and it says according "A change in pressure at any point in an enclosed fluid at rest is transmitted undiminished to all points in the fluid." That means when affected by the external pressure the hydrostatic pressure in fluid decreases equally, and the difference of hydrostatic pressures in different height of a water column remain unchanged.

3.5 Hydrostatic pressure

Hydrostatic pressure is understood any pressure in fluid, it is caused by the weight of fluid and external force. In case of free surface of fluid, the only external force acting on the fluid is barometric pressure. In other horizontal level every fluid particle is acting by force caused by surrounding particles in all directions. The pressure is so submitted and affects the sides of the vessel by perpendicular forces (perpendicular pressures), or the surface of dived object.

The relation for hydrostatic pressure can be derived from the Newton laws of motion. When the second law can be defined as:

$$F = m \cdot \frac{dv}{dt} \tag{3}$$

where: F - force acting on object,

m - weight of object,

dv - decrease object speed,

dt - duration of force acting on object.

This formula may be applied if the weight m of the object is constant. Adding the formula the acceleration element the object gains through the acting of force F:

$$a = \frac{dv}{dt} \tag{4}$$

Then we get a relation:

$$F = m \cdot a \tag{5}$$

Considering the hydrostatic pressure being caused by the weight of fluid and external force, then the weight of the fluid may be defined.

$$G = m \cdot g \tag{6}$$

where: g - gravitational acceleration.

The weight of the fluid object in depth h can be defined as

$$m = V \cdot \rho = h \cdot S \cdot \rho \tag{7}$$

where: m-weight of fluid object,

V-volume of fluid object,

 ρ – fluid density,

- h depth of base under the surface (height object),
- S area of fluid object base.

The previous relations then define a relation for figure of hydrostatic pressure p in depth h:

$$p = \frac{G}{S} = \frac{h \cdot \rho \cdot S \cdot g}{S} = h \cdot \rho \cdot g \tag{8}$$

where: p – hydrostatic pressure.

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Fig. 7. Reliance of hydrostatic pressure on depth

Hydrostatic pressure caused by weight depends only on depth h under the surface, that is why it is even in the whole horizontal level, see Figure 7. In connected vessels of a big enough diameter (not to show the surface tension) the surface calms and the pressure evens in all levels. In case both the surfaces are affected by the same external pressure, they are in the same horizontal level.

Some sources state as base of hydrostatic levelling the Bernoulli's equation in fluid dynamics. Using the Bernoulli formula for quoting the figure of pressure at zero flow speed, the pressure equals hydrostatic pressure.

3.6 Surface tension

Fluids act as their surface was covered with very thin and elastic layer trying to tighten the surface of the fluid to the smallest possible area. In case the fluid was not affected by any external forces it would be of a ball-shaped shape, because it is the ball that has the smallest shape out of all solids of the same volume. The reason of the surface tension is a capillary phenomena.

This phenomenon can be demonstrated on soap water in a wire loop (bubble blower), the fluid creates thin film and tightens so it has the smallest surface. Surface tension σ and capillary phenomena are explained by mutual effect of attractive forces of molecules, so called cohesive forces. The result of effect of cohesive forces is cohesive pressure. Cohesive pressure cannot be measured directly it can be estimated based on theoretical data.

3.7 Outside angle

Let's mark fluid, sides of vessel, and air, then a rising can be observed in the area of contact of fluid, vessel sides and air, or possibly lowering the adges of the fluid (Figure 8).



Fig. 8. Fluid in contact with the vessel side

We assume this place is affected by three cohesive forces F proportional to surface tension σ , which relies on separate substances. The equal state must define:

$$\boldsymbol{F}_{13} = \boldsymbol{F}_{12} + \boldsymbol{F}_{23} \cdot \cos \boldsymbol{\sigma} \tag{9}$$

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$$\cos \upsilon = \frac{F_{12} - F_{23}}{F_{13}} = \frac{\sigma_{12} - \sigma_{23}}{\sigma_{13}}$$
(10)

where: F - cohesive force,

 σ – surface tension between substances,

v – fluid edge angle.

v angle is called edge (side) angle. If it is a case of a contact of the same three settings, the edge angle is the same. The value of the edge angle in contact with water, glass, and air is very small, approximately 8°.

3.8 Capillary phenomena

The surface of fluid in a tight pipe (capillary) is not always flat, the above stated shows that the surface bends. As an example there can be used small glass plate dipped in the water, Figure 9. Its dipping causes the same elevation like in the case of the vessel sides. When moving the small plate close enough to the vessel side, there occurs so called capillary elevation and the water surface rises higher than the surrounding surface.



Fig. 9. Capillary phenomena

The opposite example is capillary depression. The values of elevation or depression of the surface in capillary can be calculated out of equal cohesive forces and gravitational force of fluid in capillary. The surface height in a capillary then equals:

$$h = \frac{2.\sigma}{r.\rho.g} \tag{11}$$

where: h - difference of surfaces,

 σ – surface tension,

r – capillary radius,

 ρ – fluid density,

g – gravitation acceleration.

The formula (11) shows the surface difference is inversely proportionated to the capillary radius.

3.9 Summary of physical principles

The principle of hydrostatic levelling and the construction of measuring devices is based on all stated physical laws. It is important to realize that hydrostatic levelling observes free surface of connected vessels with zero hydrostatic pressure. The surfaces of the vessels must be affected by even external (atmospheric) pressure and even weight acceleration. The effect of same external pressure and weight acceleration is possible to assume when observing small-sized objects.

The other important condition is a homogenous fluid temperature having effect on its density and its volume afterwards. Different fluid temperature and effect on its density can be mathematically defined and the results may be corrected. The fluid temperature should be in ideal case measured continuously along with the

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whole height of the pipe between devices for their difference. The praxis measures the fluid temperature only at certain points of the pipe bringing so a certain inaccuracy into calculations.

The accuracy of measuring may even be affected by the construction of deductive devices. The deductive devices should be same and their measures should be chosen the way the results would not be influenced by the capillary phenomena.

The hydrostatic levelling devices used for further distances (several kilometers) are necessary to consider elasticity of fluid and pipe, changes of atmospheric pressure and tides (Volk, J. T. 2012)

4 CURRENT HYDROSTATIC SYSTEMS

This chapter shortly describes ways of surface height registration. The next part briefly describes most frequently used systems in the Czech Republic and the whole world. Overview of the system is brief because currently exists of more than one hundred of hydrostatic systems

Most frequently are currently used hydrostatic systems enabling very accurate definition of moves and deformation of observed objects. They are stationary and fully automatical systems.

HYNI is the best known system in the Czech Republic, see Figure 10, designed by Research Institute of Geodesy, Topography and Cartography, Department of Metrology and Engineering Surveying. The system is based on a principle of hydrostatic levelling and consists of mutually connected measuring sensors and a computer with special software. The monitoring is automatical in non-stop regime. The sensor is power supplied by direct current of 24 voltage. The measuring range of a sensor is ± 10 cm and the accuracy of measuring may be characterised by determinative deviation < 0,01 mm. This system is used for measuring and observance of vertical deformations of construction in a real time. It is installed in nuclear power station Temelin for observance turboaggregate (Volk, J. T. 2012)



Fig. 10. HYNI system (VÚGTK 2015)

It is also necessary to state systems used in geotechnics for measuring decrease of bedrock under construction or extended ground bodies. As an example may be mentioned HPG device made by Glötzl reaching the standard deviation 5 mm. Other hydrostatic systems have rather historical value. (Volk, J. T. 2012)

Foreight literature to are frequently mentioned systems labeled with abbreviation HLS (Hydrostatic Levelling System). These are systems of hydrostatic levelling using for indication mainly capacitive, optical and ultrasound sensors. The accuracy of systems using the most accurate sensors is stated to circa units of micrometers. (Jakobs et al. 2012).

Among the most significant sensors producers may be ranked Russian Budker Institute of Nuclear Physics in Novosibirsk, see Picture No. 11, and American Fermilab with a seat in Batavia, Illinois, see Picture No. 12.



Fig. 11. Budker Institute of Nuclear Physics (Volk, J. T. 2012)



Fig. 12. Fermilab designed Tevatron style (Volk, J. T. 2012)

These systems are used for observing vertical moves of very important buildings, such as:

- Accelerator of particles Budker Institute of Nuclear Physics,
- Swiss light accelerator SLS (Swiss Light Source) in Villingenu,
- Accelerator of particles in Cern,
- Detector of proton collisions Atlas,
- accelerator SLAC National Accelerator Laboratory in California.

Since the water surface shivers with a birth of vibrations, these systems are used for detection of seismic quakes detection in deep mines in North Aurora Illinois, LaFarge company (Volk, J. T. 2012)

The last system called Druckschlauchwaage Hydrostatic levelling system which will be described in this chapter is a system made by German company GeTec Ingenieurgesellschaft für Informations - und Planungstechnologie mbH. The schema of the device shows Picture No. 13.

The system is based on a principle of hydrodynamic levelling. It uses capacity pressure sensors for moves definition, it has the following parameters:

- measuring extend: 200 mm,
- resolution: 0,02 mm,
- linearity: 0,2 mm,
- stability: 0,2 mm / year,
- working temperature: -20 °C to 80 °C.

Determinative deviation of measured values is within the scope of 0,02 mm to 0,05 mm. Temperature influence may be controled by integrated mathematical model and the system then reaches accuracy better than 0,3 mm. The system was used for measuring vertical moves of a railway bridge Ponte Vecchio in Bologna effected by tunnelling. (Jakobs et al. 2012)

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Fig. 13. Druckschlauchwaage Hydrostatic levelling system (Jakobs et al. 2012)

SUMMARY

Finally, it should be mentioned that the current use of hydrostatic leveling systems is very limited in the Czech Republic. From a geodetic aspect it is only a HYNI system. Wider use of these systems is found in geotechnics where they have become a commonly used geotechnical monitoring method. This fact may be due to a certain lack of knowledge about this issue because hydrostatic leveling is mentioned very briefly in most textbooks and usually only the principle of connected vessels is mentioned. In the best case, the Bernoulli equation is given and briefly mentions the use and accuracy of the method. In most expert textbooks and scripts we do not know anything about the principles of hydrodynamic and hydromechanical leveling even though this height measurement method is one of the oldest and today has relatively large potential in terms of accuracy and speed of the measurement.

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