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1 **Title: Non-invasive vibrometry-based diagnostic detection of acetabular cup**
2 **loosening in Total Hip Replacement (THR)**

3

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23 **Abstract**

24 Total hip replacement is aimed at relieving pain and restoring function. Currently, imaging
25 techniques are primarily used as a clinical diagnosis and follow-up method. However, these
26 are unreliable for detecting early loosening, and this has led to the proposal of novel
27 techniques such as vibrometry. The present study had two aims, namely, the validation of the
28 outcomes of a previous work related to loosening detection, and the provision of a more
29 realistic anatomical representation of the clinical scenario. The acetabular cup loosening
30 conditions (secure, and 1 and 2 mm spherical loosening) considered were simulated using
31 Sawbones composite bones. The excitation signal was introduced in the femoral lateral
32 condyle region using a frequency range of 100–1500 Hz. Both the 1 and 2 mm spherical
33 loosening conditions were successfully distinguished from the secure condition, with a
34 favourable frequency range of 500–1500 Hz. The results of this study represent a key
35 advance on previous research into vibrometric detection of acetabular loosening using
36 geometrically realistic model, and demonstrate the clinical potential of this technique.

37 **Keywords:**

38 Acetabular cup loosening, Non-invasive diagnosis, Vibration analysis, Loosening diagnosis.

39 **1. Introduction**

40 Total hip replacement (THR) is aimed at relieving pain and restoring function. The procedure
41 has come a long way since it was introduced by Charnley in the early 1960s, and was
42 nominated as the operation of the century [1]. The high success rate of THR has contributed
43 to the rapid increase in its use, with well over one million operations performed annually
44 worldwide [2]. However, approximately about 4%–10% of all the involved implants are
45 expected to fail in their first decade [3, 4], mostly due to aseptic loosening, which has been
46 identified as the primary THR failure factor since 1979 [5]. Currently, imaging techniques are
47 the primary diagnostic and follow-up method used clinically. These have, however, been
48 shown to be unreliable for early loosening detection [6-8], especially of the acetabular cup
49 [9]. The situation has led to the proposal of novel techniques such as vibrometry.

50

51 Vibration analysis is a mechanical non-destructive testing technique that is widely used in the
52 inspection of composite materials and assessment of structural integrity, and has been
53 successfully extended to the field of biomechanics [9, 10]. Vibrometry predominantly
54 involves the measurement of the response to low-frequency excitation, as reflected from the
55 target surface or structure [11]. Long bone property assessment, fracture healing monitoring,
56 osseointegration, and stability monitoring are some of the applications of vibration analysis in
57 biomechanics [9]. However, the most widespread use was initially in the field of dentistry,
58 following the pioneering works of Meredith *et al.* [12, 13]. Since then, many research groups
59 have used vibration analysis to detect prosthetic loosening through different measurement
60 and excitation techniques [14].

61

62 Despite acetabular cups having a higher revision rate compared to femoral components,
63 according to various national registries [15-19], the majority of published work on the use of

64 vibrometry for the diagnosis of loosening [7, 20-26] are femoral stem-related. Others have
65 explored the detection of acetabular cup loosening [6, 9, 23] and were able to distinguish it
66 from the stable condition, but did not define the detected level of loosening. Moreover, while
67 the findings of a preliminary study [27] using Sawbones blocks substantiated the validity of
68 the vibrometry approach, the complex geometry of the hemi-pelvis was not taken into
69 consideration. The present study thus had two aims: i) to validate the outcomes of a previous
70 study [27] related to the detection of loosening, and ii) to provide a more realistic anatomical
71 representation of the clinical scenario through the development of an acetabular cup
72 loosening model using a composite Sawbones femur and hemi-pelvis bones.

73

74 **2. Materials and Methods**

75 The loosening conditions of the acetabular cup were simulated using a composite femoral and
76 hemi-pelvis bones (Femur 3406, Hemi-pelvis 3405, Sawbones Europe AB, Malmö, Sweden),
77 a 44-mm stem (Exeter™ V40™, 28 mm standard head, Stryker Orthopaedics, USA), and a
78 56-mm cup (Trident® Hemispherical Cup, Stryker Orthopaedics, USA). The composite
79 femur articulated with the hemi-pelvis that accommodated the loosened acetabular cup. The
80 simulated conditions were 1 mm press-fit (secure condition), 1 mm spherical loosening, and 2
81 mm spherical loosening (Figure 1).

82

83 The 1 mm press-fit condition included a computer numerical control machined cup cavity of
84 diameter 55 mm and depth 28.5 mm. A Stryker cup of diameter 56 mm was inserted through
85 repeated impacting by a soft mallet until it was fully seated, in accordance with the existing
86 literature [28-30]. The two spherical loosening conditions with gaps of 1 and 2 mm were
87 simulated using machined hemispherical cavities of diameters 58 and 60 mm respectively,
88 including a 5 mm wide channel of depth 3 mm in the lower cavity surface, used to control the

89 silicone thickness. The loosening gaps were filled with a silicone layer (EVO-STIK, Bostik
90 Limited, England) in accordance with previous practise [10, 21, 31] to replicate the soft
91 fibrous interface between the surfaces of the cup and bone. The silicone thickness was
92 controlled using two 56-mm Nylon 66 domes (RS Ltd. Northants, UK) with different
93 extended stem lengths of 4 and 5 mm, respectively. The domes were fixed inside the cup
94 cavity channel (length 3 mm) for 24 h to cure the silicone (Figure 2).

95
96 The Exeter stem was cemented into the fourth-generation femur composite bone, in
97 accordance with the manufacture's recommended surgical protocol. The femur was
98 subsequently attached to the pelvis with springs to replicate the attachment muscles, as
99 previously adopted by Rieger *et al.* [9]. Two springs with a spring constant of 2.26 N/mm,
100 were respectively used to simulate the adductor magnus and adductor longus, while the
101 gluteus medius muscle was simulated by two springs with a spring constant of 4.17 N/mm.

102
103 Two test mediums were used in this study. One set of tests was conducted in water to
104 simulate the soft tissue surrounding the femur and pelvis, while the second set was conducted
105 in air using a foam supports (Figure 3). The water medium was used in replication of the
106 work of Rowlands *et al.* [32] to investigate its effect on the ultrasound readings. In the case of
107 the air medium, two accelerometers were used together with the ultrasound probe to
108 determine the optimal response measurement location.

109

110 **2.1 Excitation Signal**

111 The excitation signal was introduced at the femoral lateral condyle with a frequency range of
112 100–1500 Hz in increments of 25 Hz and a constant amplitude of 4 Volts (peak-to-peak)
113 using a mini-shaker (V201, Ling Dynamic Systems Ltd, UK). That was driven through a

114 function generator (TG230, Thurlby Thandar Ltd, UK) via a power amplifier (PA25E, LDS
115 Ltd, UK). The excitation method, input signal characteristics, and frequency range were
116 adopted from previous works [20-23, 32], which highlighted the suitability of detecting
117 implant loosening using a frequency sweep range below 1500 Hz.

118

119 **2.2 Measurement and Analysis**

120 The measurement instruments used for the two test mediums were different. In the case of the
121 water medium, only the ultrasound probe was used, and it was positioned facing the anterior
122 superior iliac spine (Figure 3b). In the case of the air medium (foam support) test, two
123 accelerometers (Model 353B18, PCB Piezotronics Inc, Depew, NY, US) and an ultrasound
124 probe (Mini Dopplex 500 4 MHz, Huntleigh Technology PLC, Cardiff, UK) were used
125 (Figure 3a). The ultrasound probe and one accelerometer were coupled at the iliac crest,
126 whereas the second accelerometer was located at the greater trochanter of the femur. Two
127 accelerometers were attached to the surface of the Sawbones by screws using threaded steel
128 inserts (PEM® Inserts, UK) for additional stability. The ultrasound probe was positioned on
129 the Sawbones and supported using a laboratory stand, and an ultrasound gel (Aquasonic 100,
130 Doppler size 60g, Huntleigh Technology PLC, UK) was employed between the probe and
131 Sawbones surfaces for the air medium only.

132

133 Three composite hemi-pelvises and one femoral Sawbones were used to obtain ten sample
134 readings for each simulated condition (1 mm press fit, 1 mm spherical loosening, and 2 mm
135 spherical loosening). The hemi-pelvis was Velcro-coupled (VELCRO® Brand Heavy Duty,
136 Polyamide) with the foam support material (Neoprene Foam, durometer value 15A–20A).
137 The Sawbones femur medial epicondyle was also foam-supported rather than clamped [21,

138 22] or counterbalanced by weights [32]. After each reading, the system was disassembled and
139 reassembled based on the marks on the composite bone and the holding table.

140

141 The characteristics used to diagnose THR loosening by vibrometry are mainly dependent on
142 the frequency analysis of the targeted system based on the magnitudes of the primary
143 frequency and related harmonics. This was completed with the aid of the spectrum analysis
144 tool in the LabVIEW sound and vibration package (Signal Express, Suite version 11,
145 National Instruments). The harmonic ratio was used to better illustrate the relationship
146 between the harmonics and the fundamental frequency over the entire driving frequency
147 range. At each response to the driving signal frequency, the magnitude of the resultant
148 harmonic was divided by the main fundamental frequency of the response. The obtained
149 harmonic ratios were numbered based on the number of harmonics used.

150

151 **2.3 Statistics**

152 The data normality was tested using the Shapiro-Wilk test. Based on the results of these tests,
153 a non-parametric analysis was adopted for comparisons at each excitation frequency. A
154 Kruskal-Wallis test was performed among the three simulation conditions (1 mm press-fit, 1
155 and 2 mm spherical loosening); in cases of significance, this was followed by Mann-Whitney
156 U-tests. All statistical analyses were conducted using SPSS (IBM SPSS Statistics 20.0, IBM
157 Corporation, Armonk, NY, USA), with the significance level defined as $p < 0.05$.

158

159 **3. Results**

160 **3.1 Harmonic Ratio**

161 The harmonic ratios of the Sawbones femur hemi-pelvis system was calculated up to the third
162 harmonic. The effect of the accelerometer location on the measurements and that of the water
163 medium on the ultrasound ratio are examined in the following subsections.

164

165 **3.2.1 Accelerometer**

166 The accelerometer harmonic ratio was quantified for the first three harmonics with respect to
167 the magnitude of the primary fundamental frequency.

168 The first harmonic ratio was obtained by dividing the magnitude of the first harmonic (F1) by
169 the fundamental frequency for the simulated conditions. Comparison of the secure condition
170 with the 1 mm loosening condition revealed that the first harmonic ratio of the latter was
171 significantly higher at 18 driving frequencies (100–250, 400, 550–800, and 1100–1400 Hz)
172 ($p < 0.05$) based on the femur accelerometer reading, and for 17 frequencies (100, 300, 400–
173 450, 600–700, 950–1000, 1100–1400, and 1500 Hz) ($p < 0.01$) based on the pelvis
174 accelerometer reading. The 2 mm loosening condition had a significantly higher harmonic
175 ratio compared to the secure condition at 16 driving frequencies ($p < 0.01$) based on the
176 readings of both accelerometers—100, 400, 600–700, and 900–1400 Hz for the pelvis
177 accelerometer, and 150–250, 550–800, 1100, and 1200–1450 Hz for the femur accelerometer.
178 Further, comparison of the two loosening conditions revealed that the first harmonic ratio of
179 the 2 mm condition was higher than that of the 1 mm condition at 12 driving frequencies
180 (200, 650–950, 1050, 1200–1250, and 1450 Hz) ($p < 0.01$) based on the pelvis accelerometer
181 reading, and at seven driving frequencies (800, 1050, and 1250–1450 Hz) ($p < 0.05$) based on
182 the femur accelerometer reading (Figure 4).

183

184 The second harmonic ratios were also examined to see whether they exhibited the same
185 pattern as the first harmonic ratios with regard to loosening. This was observed to be the case,
186 although the corresponding driving frequencies for the second harmonic ratios were lower.
187 Comparison of the secure and 1 mm spherical loosening conditions revealed that the
188 loosening condition initially had significantly higher second harmonic ratios at 16 driving
189 frequencies (100–250, 500–550, 650–750, 1050–1100, and 1200–1400 Hz) ($p < 0.05$) based
190 on the femur accelerometer reading, and at 11 driving frequencies (650, 900–1000, 1150–
191 1400, and 1500 Hz) ($p < 0.01$) based on the pelvis accelerometer reading. This was also true
192 for the 2 mm loosening condition, which had significantly higher second harmonic ratios ($p <$
193 0.05) compared to the secure condition at 14 driving frequencies (100–150, 650–750, 900–
194 950, 1050, and 1200–1450 Hz) based on the femur accelerometer reading, and at 13 driving
195 frequencies (450, 650–700, 900–1000, and 1100–1400 Hz) based on the pelvis accelerometer
196 reading. However, the harmonic ratios of the 2 mm loosening condition were significantly
197 higher than those of the 1 mm loosening condition for 12 and 15 driving frequencies based on
198 the femur and pelvis accelerometer readings, respectively ($p < 0.05$).

199

200 The third harmonic ratios exhibited the same pattern as the first and second harmonic ratios.
201 This was evident from a comparison of the 1 mm loosening condition with the 1 mm secure
202 condition, wherein the third harmonic ratios of the loosening condition were found to be
203 significantly higher for 16 driving frequencies (100–200, 400, 500–800, 1100, and 1250–
204 1400 Hz) ($p < 0.05$) based on the femur accelerometer reading, and 14 driving frequencies
205 (200, 550, 650–700, 950–1000, 1100–1400, and 1500 Hz) ($p < 0.01$) based on the pelvis
206 accelerometer reading. The 2 mm loosening condition had higher third harmonic ratios at 17
207 driving frequencies (300, 450, 550–700, 850–1000, and 1100–1400 Hz) ($p < 0.05$) based on
208 the pelvis accelerometer reading, and 10 frequencies (100, 200, 600–700, and 1250–1450 Hz)

209 ($p < 0.01$) based on the femur accelerometer reading. Further, the 2 mm loosening condition
210 had higher third harmonic ratios compared to the 1 mm loosening condition at six driving
211 frequencies (1000–1050, 1250–1300, and 1400–1450 Hz) ($p < 0.01$) based on the femur
212 accelerometer reading. Based on the pelvis accelerometer reading, the third harmonic ratios
213 of the 2 mm loosening condition were significantly higher than that of the 1 mm loosening
214 condition at 13 frequencies (250–300, 600–750, 850–950, 1050, 1200–1250, and 1450 Hz) (p
215 < 0.05).

216

217 To summarize, the harmonic ratios determined by the readings of the two accelerometers
218 (located at the femur and pelvis, respectively) for the three simulated conditions show that
219 loosening can be simulated detected in specimens that replicate the complex geometry of the *in*
220 *vivo* scenario.

221

222 **3.2.2 Ultrasound**

223 The ultrasound harmonic ratio was quantified for the two tested mediums, namely, water and
224 air. The majority of the significant findings were within the frequency range of 500–1500 Hz;
225 with less consistent differences occurring within 200–450 Hz range.

226

227 The pattern of the first harmonic ratios for the ultrasound measurements were the same as
228 that for the loosening conditions; with increased loosening from 1 to 2 mm, the harmonic
229 ratio also increased. Initially, in comparing the secure and 1 mm loosening conditions, it was
230 found that the latter had significantly higher first harmonic ratios ($p < 0.01$) for eight driving
231 frequencies (200, 400–550, 1000, and 1250–1300 Hz) in the air medium, and 16 driving
232 frequencies (200, 300, 400–450, 550–600, 1000–1300, and 1400–1500 Hz) ($p < 0.05$) in the
233 water medium. The 2 mm loosening condition had higher first harmonic ratios for 16 driving

234 frequencies (200–250, 600–700, and 900–1400 Hz) ($p < 0.01$) in the air medium, and 20
235 driving frequencies (550–15000 Hz) ($p < 0.05$) in the water medium. Further, the 2 mm
236 spherical loosening condition had higher harmonic ratios than its 1 mm counterpart at 19
237 driving frequencies (200–250, 650–700, and 800–1500 Hz) ($p < 0.05$) in the air medium, and
238 12 driving frequencies (550 and 650–1150 Hz) ($p < 0.01$) in the water medium (Figure 5).

239

240 The second harmonic ratios also enabled distinction among the different conditions at
241 frequencies that were closely related to those of the first harmonic ratios. Comparison of the
242 secure and 1 mm loosening conditions revealed that the latter had higher second harmonic
243 ratios ($p < 0.05$) for seven driving frequencies (200, 400–500, 1000, and 1300–1350 Hz) in
244 the air medium, and 12 driving frequencies (300–350, 450, 700, 1000, 1100–1300, and 1400–
245 1450 Hz) ($p < 0.05$) in the water medium. The 2 mm loosening condition also had higher
246 second harmonic ratios ($p < 0.05$) compared to the secure condition for 19 driving
247 frequencies in both mediums. Between the 1 and 2 mm loosening conditions, the latter had
248 higher second harmonic ratios at 20 driving frequencies (250 and 600–1500 Hz) ($p < 0.01$) in
249 the air medium, and 13 in the water medium (550–1150 Hz) ($p < 0.01$).

250

251 The third harmonic ratios likewise distinguished the three simulated conditions in both the air
252 and water mediums. Higher ratios were observed for the 1 mm spherical loosening condition
253 compared to the secure condition at seven driving frequencies (200, 400–500, 1000, 1250–
254 1300, and 1400 Hz) ($p < 0.05$) in the air medium, and 11 frequencies in the water medium
255 (300, 1000–1300, and 1400–1500 Hz) ($p < 0.05$). The 2 mm loosening condition also had
256 higher third harmonic ratios compared to the secure condition at 19 frequencies (200–250,
257 400–450, 600–700, and 900–1450 Hz) ($p < 0.01$) in the air medium, and 21 frequencies (350,
258 500–1300, and 1400–1500 Hz) ($p < 0.01$) in the water medium. Further, the third harmonic

259 ratios of the 2 mm loosening condition were higher than those of the 1 mm loosening
260 condition for 20 driving frequencies (250 and 600–1500 Hz) ($p < 0.01$) in the air medium,
261 and 16 frequencies (200, 350, and 500–1150 Hz) ($p < 0.05$) in the water medium.

262

263 To summarize, the ultrasound harmonic ratio analysis enabled distinction between secure and
264 loosening conditions in both the test air and water mediums, as well as between loosening
265 conditions of differing severities. The findings of the investigations indicate that 500–1500
266 Hz is a favourable frequency range for both mediums.

267

268 **4. Discussion**

269 Despite the fact that acetabular cups have a higher revision rate compared to femoral
270 components [15–19], the majority of previous works on vibrometry loosening diagnosis [7,
271 20–26] are stem-related. Although the detection of acetabular cup loosening has been
272 previously explored [6, 9, 23] and was able to distinguish it from the stable condition, the
273 degree of the detected loosening was not defined. The two aims of the present study were to
274 validate the outcomes of a previous work [27] related to loosening detection, and investigate
275 vibrometry diagnosis using a more realistic anatomical representation of the clinical
276 condition.

277

278 The simulation of acetabular cup loosening using a Sawbones femur and composite hemi-
279 pelvis bone was an attempt to achieve a more realistic anatomical setup. The femoral bone
280 was fixed in position with springs that simulated the muscle attachment of the hemi-pelvis, as
281 adopted by Rieger *et al.* [9]. This enabled the positioning of the excitation source on the
282 lateral femoral condyle in the manner primarily suggested by Rosenstein *et al.* [20]. Two

283 mediums, namely, water and air (with foam support) were considered for the ultrasound
284 probe measurements in an acrylic tank.

285

286 In the case of the air medium, two accelerometers and an ultrasound probe were used to
287 measure the output vibrations. Two accelerometers were used in order to determine the
288 optimal location for measuring the frequency response. One was located at the greater
289 trochanter of the femur, and the other at the iliac crest of the pelvis. The initially spectral
290 analysis based on the readings of the two accelerometers for a frequency range of 100–1500
291 Hz suggested that 1 and 2 mm spherical cup loosening could be distinguished from a secure
292 cup. Specifically, there was a decrease in the fundamental frequency and increases in the
293 related harmonics with increasing loosening gap. The patterns of the harmonic ratios with
294 respect to loosening also supported the results of previous case studies; an increase in the
295 loosening gap induced an increase in the harmonic ratio, with most of the significant readings
296 occurring within the frequency range of 500–1500 Hz. Comparison of the two loosening
297 conditions with the secure condition revealed that there were slightly more significant
298 differences between the harmonic ratios based on the femur accelerometer readings compared
299 to the pelvis accelerometer readings. In comparing the two loosening conditions of 1 and 2
300 mm, the pelvis accelerometer indicated more significant differences between the harmonic
301 ratios.

302

303 The ultrasound measurement was used to compare the water and air mediums. The ultrasound
304 spectral analysis of the three simulated conditions revealed that cup loosening could be
305 detected even when using a more complex Sawbones femur-pelvis setup compared to a
306 previous study [27]. The determined ultrasound harmonic ratios indicated a favourable
307 frequency range of 500–1500 Hz in both tested mediums. In the water medium, there were

308 generally more significant differences between the two loosening conditions and the secure
309 condition.

310

311 The findings of this study substantiate those of a previous work [27] related to the diagnosis
312 of acetabular cup loosening by vibrometry. When the cup-loosening gap was increased from
313 1 to 2 mm, the fundamental frequency decreased, while the harmonics increased within a
314 certain frequency range. Further, the harmonic ratio consistently increased with increasing
315 loosening. These observations agree with those of previous works [9, 23], which found that
316 acetabular cup loosening could be detected by vibrometry. However, the present study differs
317 from previous ones by defining the minimum degree of loosening that was reliably detected,
318 namely, 1 mm spherical loosening, as well as the favourable detection frequency range, namely,
319 500–1500 Hz.

320

321 However, the present study has certain limitations that should be taken into consideration in
322 interpreting the results. Firstly, the considered spherical loosening is actually a simplification
323 of acetabular cup loosening. In addition, the tests focused on the use of vibrometry to
324 diagnose cup loosening using a cementless acetabular component. There is the need for
325 further study using different acetabular cup designs, including cemented cups, to better
326 establish the reliability of vibrometry diagnosis for future clinical application. Furthermore,
327 the present study did not investigate the distinction between cup loosening and stem
328 component loosening or the influence of the liner wear. However, the present study was an
329 initial step in assessing the feasibility of vibrometry for detecting acetabular cup loosening.
330 Simplification was thus expedient in obtaining credible preliminary evidence of the merit of
331 the technique for further study to consider a wider range of scenarios and address the

332 abovementioned limitations. Such further work is expected to provide more conclusive data
333 that can be used to lay the foundation for a clinical study.

334

335 **5. Conclusion**

336 The findings of this study support those of previous works on the use of vibrometry to detect
337 acetabular cup loosening, namely, a decrease in the fundamental frequency and an increase in
338 the related harmonics with increasing loosening gap in an anatomically realistic model. This
339 was also indicated by the harmonic ratios, which were observed to consistently increase with
340 increasing loosening. This study differed from previous work by defining the loosening level
341 detected, namely, 1 mm spherical loosening, and the favourable detection frequency range,
342 namely, 500–1500 Hz. Further research is required to determine the lower detection limit for
343 this vibrometry approach.

344

345 **Ethical approval**

346 Not required.

347

348 **Conflict of interest statement**

349 There are no conflicts of interest to declare.

350

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441 Figure captions

442 Figure 1: Simulation setup of loosened acetabular cup using a femur and hemi-pelvis
443 composite bone system.

444 Figure 2: Procedure for mimicking 1 and 2 mm spherical loosening: a) Silicone was injected
445 between the surfaces of the cup and Sawbones cavity, b) The silicon thickness was controlled
446 using two Nylon domes, c) After 24 h, the acetabular cup was inserted into the Sawbones
447 cavity.

448 Figure 3: Test setups for a) air medium, and b) water medium.

449 Figure 4: First harmonic ratios for the 1 mm press-fit, 1 mm and 2 mm loosening conditions
450 based on the readings of the accelerometer located at the pelvis (a, c, and e) and femur (b, d,
451 and f). All the conditions are compared in a and b, while the 1 mm press-fit and 1 mm
452 loosening conditions are compared in c and d, and the 1 mm press-fit and 2 mm loosening
453 conditions in e and f. * Mann-Whitney test, $p < 0.05$, $n = 10$.

454 Figure 5: First harmonic ratios for secure (1 mm press-fit), 1 mm and 2 mm loosening
455 conditions measured by the ultrasound probe in air (a, c, and e) and water (b, d, and f). All the
456 test conditions are shown in a and b, while c and d statistically compares the secure and 1 mm
457 loosening conditions, and e and f compares the secure and 2 mm loosening conditions. *
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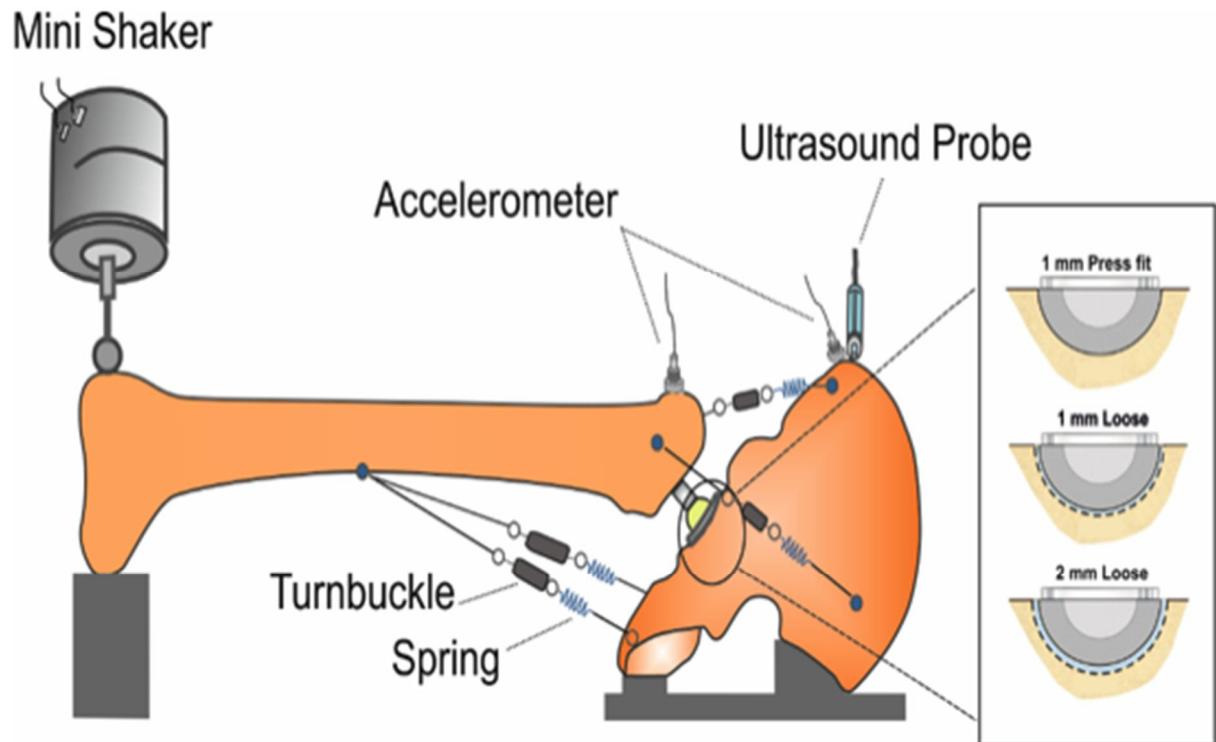
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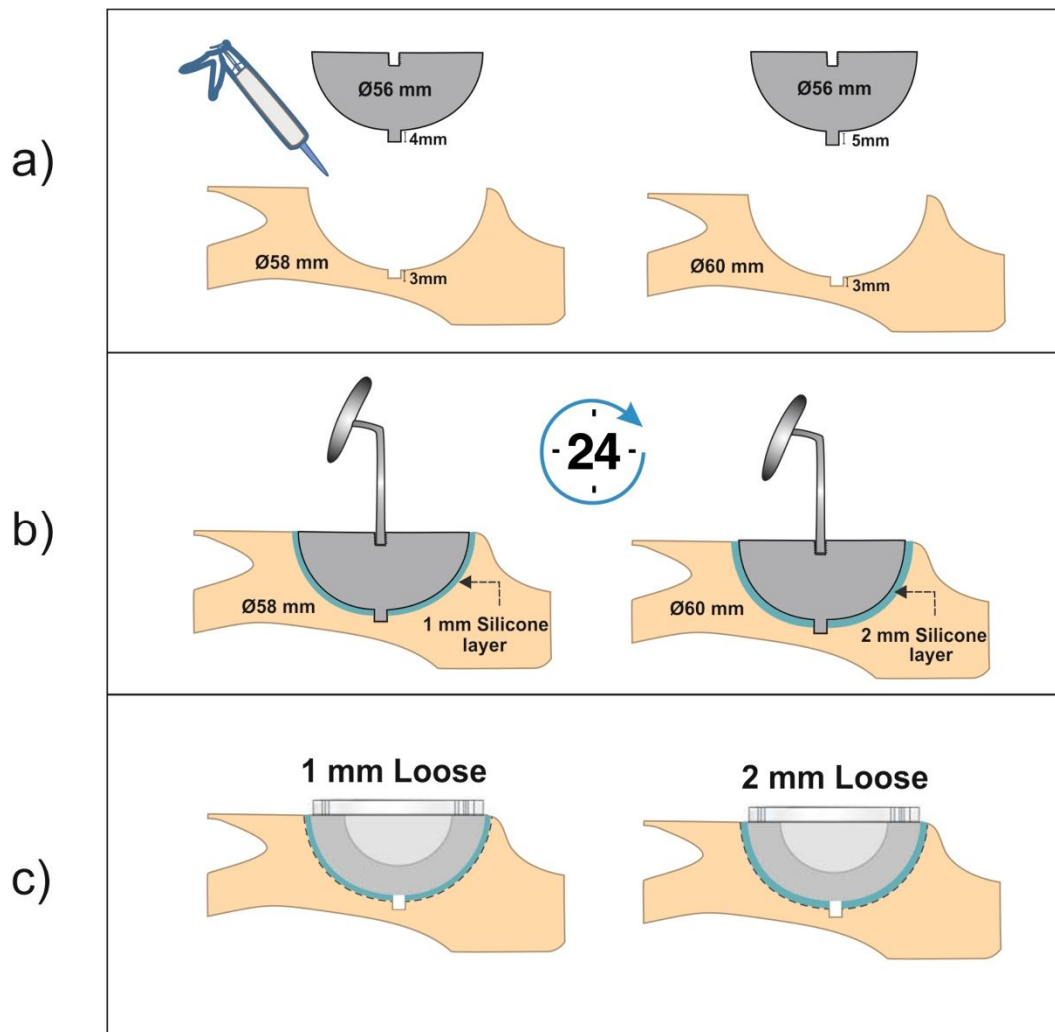
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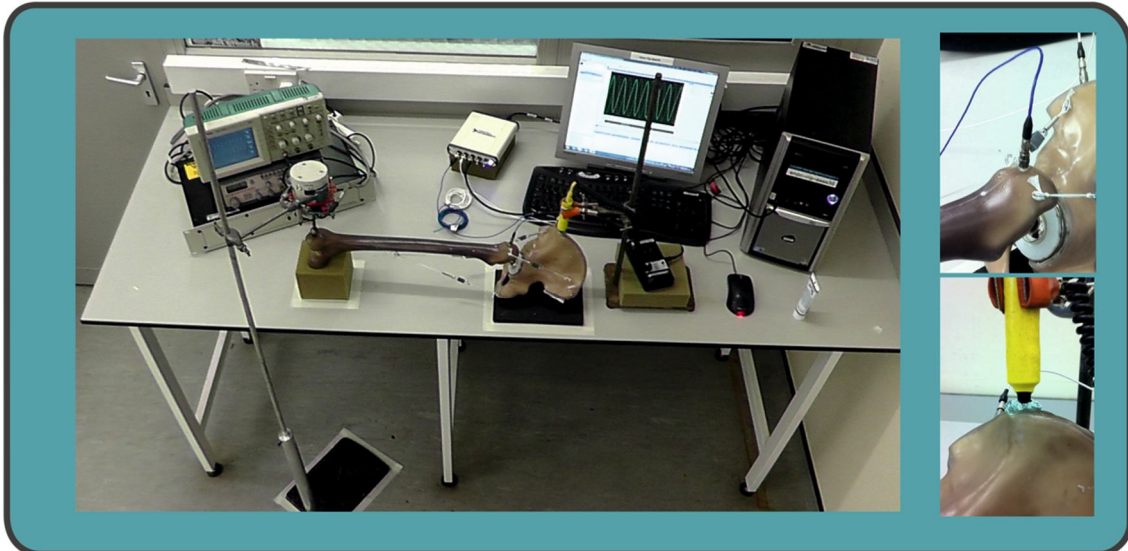
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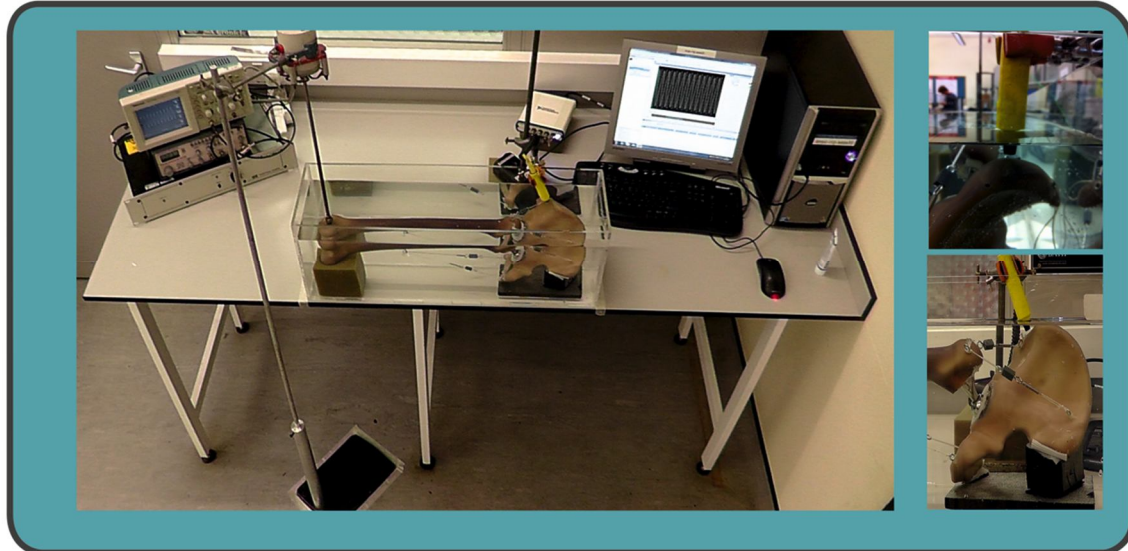
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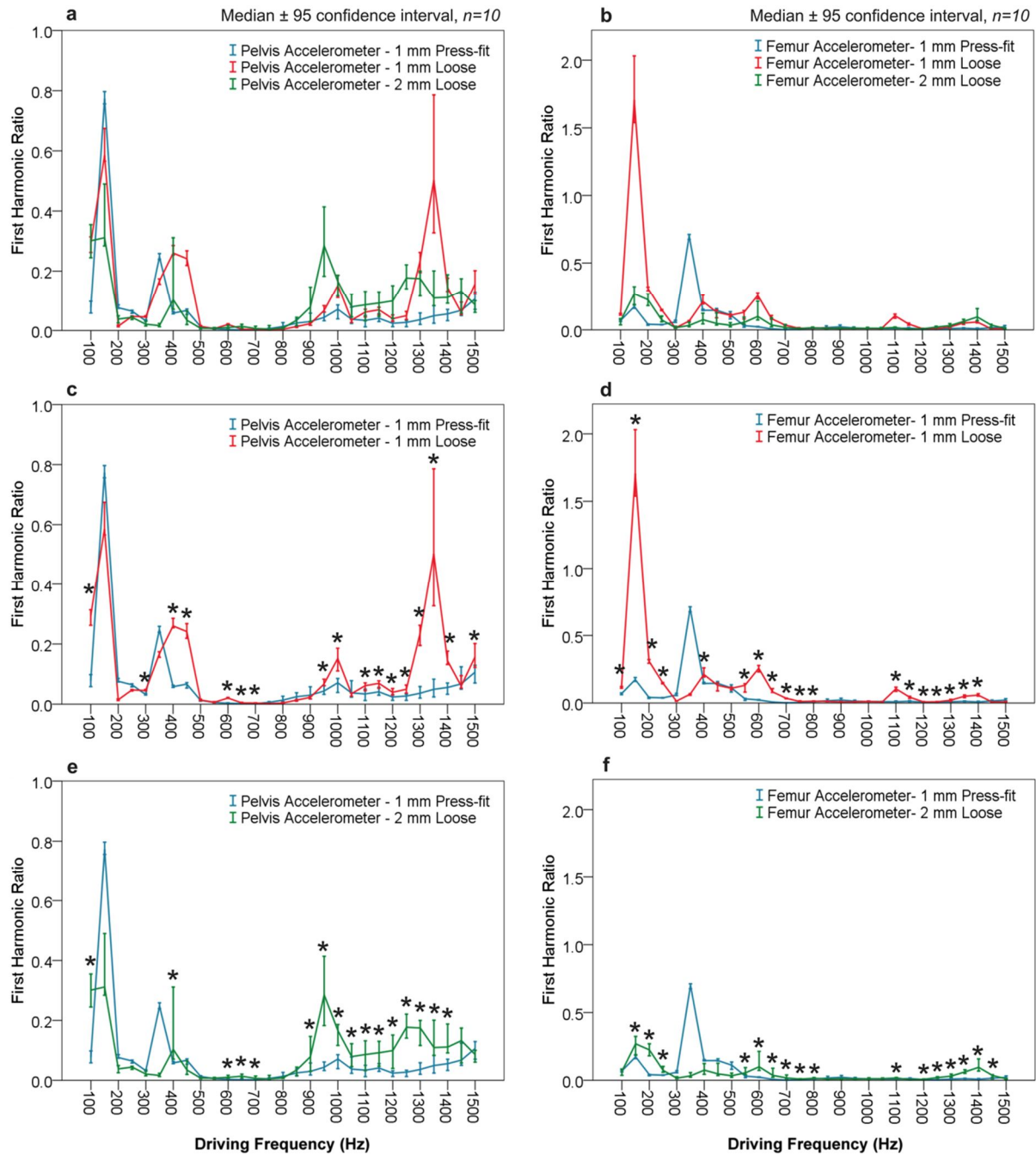


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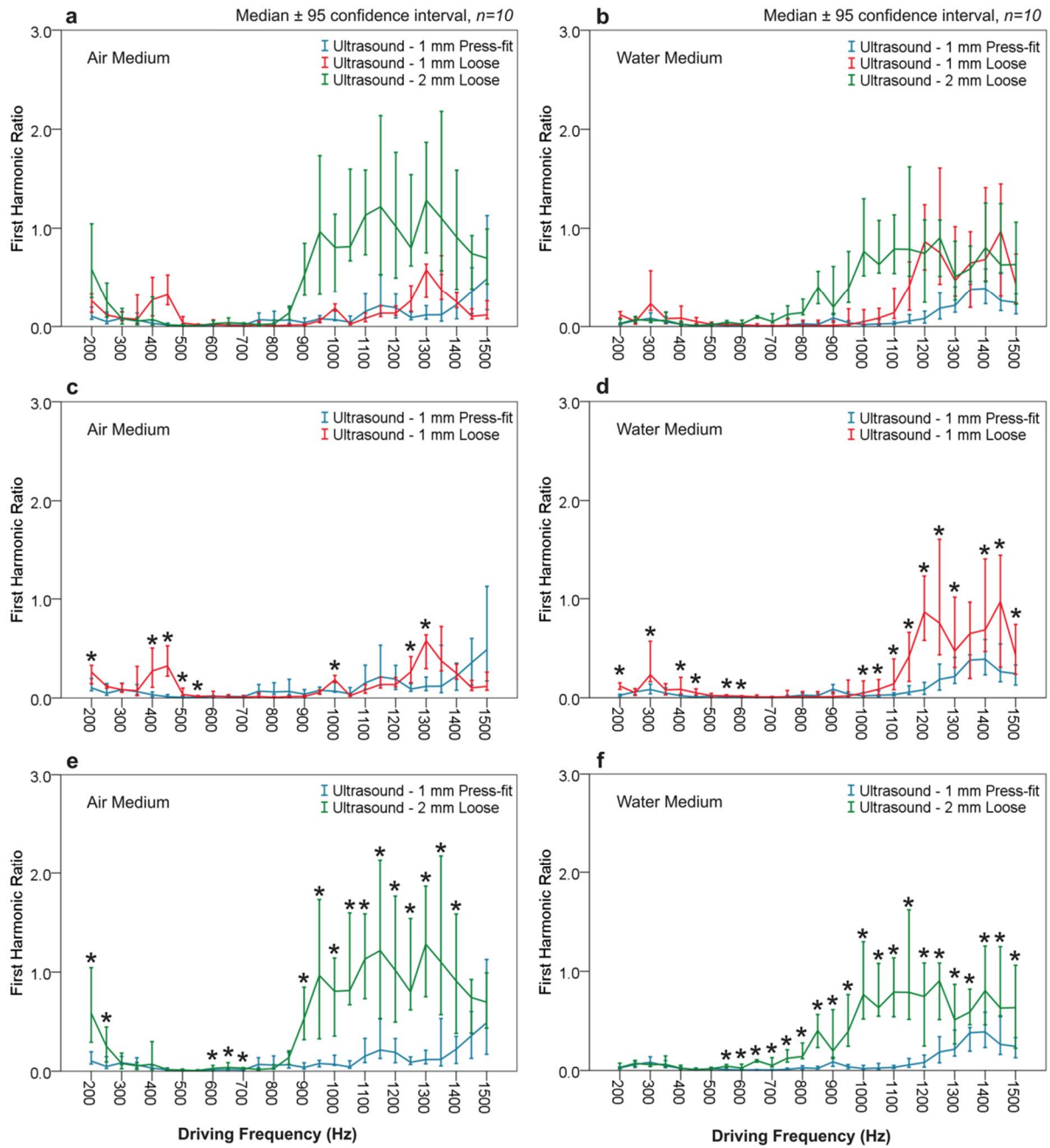
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