



Citation for published version: Vidal, T, Battarra, M, Subramanian, A & Erdogan, G 2015, 'Hybrid metaheuristics for the clustered vehicle routing problem', Computers and Operations Research, vol. 58, pp. 87-99. https://doi.org/10.1016/j.cor.2014.10.019

10.1016/j.cor.2014.10.019

Publication date: 2015

Document Version Early version, also known as pre-print

Link to publication

University of Bath

Copyright and moral rights for the publications made accessible in the public portal are retained by the authors and/or other copyright owners and it is a condition of accessing publications that users recognise and abide by the legal requirements associated with these rights.

Take down policy
If you believe that this document breaches copyright please contact us providing details, and we will remove access to the work immediately and investigate your claim.

Download date: 13. May. 2019

Hybrid Metaheuristics for the Clustered Vehicle Routing Problem

Thibaut Vidal^a, Maria Battarra^{b,*}, Anand Subramanian^c, Güneş Erdoğan^d

^aMassachusetts Institute of Technology Laboratory for Information and Decision Systems 77 Massachusetts

Avenue, Room 32-D566, Cambridge, MA 02139, U.S

^bUniversity of Southampton, School of Mathematics, Southampton, SO17 1BJ, UK

^cUniversidade Federal da Paraíba - Departamento de Engenharia de Produção, Centro de Tecnologia, Campus I
Bloco G, Cidade Universitária, João Pessoa-PB, 58051-970, Brazil

^dUniversity of Southampton, School of Management, Southampton, SO17 1BJ, UK

Abstract

The Clustered Vehicle Routing Problem (CluVRP) is a variant of the Capacitated Vehicle Routing Problem in which customers are grouped into clusters. Each cluster has to be visited once, and a vehicle entering a cluster cannot leave it until all customers have been visited. This article presents two alternative hybrid metaheuristic algorithms for the CluVRP. The first algorithm is based on an Iterated Local Search algorithm, in which only feasible solutions are explored and problem-specific local search moves are utilized. The second algorithm is a Hybrid Genetic Search, for which the shortest Hamiltonian path between each pair of vertices within each cluster should be precomputed. Using this information, a sequence of clusters can be used as a solution representation and large neighborhoods can be efficiently explored, by means of bi-directional dynamic programming, sequence concatenation, and appropriate data structures. Extensive computational experiments are performed on benchmark instances from the literature, as well as new large scale instances. Recommendations on the choice of algorithm are provided, based on average cluster size.

Keywords: Clustered Vehicle Routing, Iterated Local Search, Hybrid Genetic algorithm, Large Neighborhoods, Shortest Path

1. Introduction

This paper addresses the Clustered Vehicle Routing Problem (CluVRP), which has been introduced by Sevaux and Sörensen (2008). The CluVRP is defined over an undirected graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$, where the vertex 0 is the depot and any other vertex $i \in \mathcal{V} \setminus \{0\}$ is a customer with demand $q_i > 0$. A fleet of m vehicles, each with capacity Q, is stationed at the depot. The

^{*}Corresponding author: Tel. +44 (0)23 8059 3863

Email addresses: vidal@mit.edu (Thibaut Vidal), m.battarra@soton.ac.uk (Maria Battarra),
anand@ct.ufpb.br (Anand Subramanian), g.erdogan@soton.ac.uk (Güneş Erdoğan)

set of customers is partitioned into N disjoint and nonempty subsets called *clusters*, such that $\mathcal{V} = V_1 \cup \cdots \cup V_N$. The customers in each cluster have to be visited consecutively, that is, the vehicle visiting a customer in the cluster cannot leave the cluster until all the other customers in the cluster have been visited. Each edge $(i,j) \in \mathcal{E}$ is associated with a travel cost c_{ij} , and the objective is to minimize the total travel cost. The CluVRP is a generalization of the Capacitated Vehicle Routing Problem (CVRP, c.f. book of Toth and Vigo 2002), obtained when each cluster contains a single vertex, and of the Clustered Traveling Salesman Problem (CluTSP, Chisman, 1975), obtained when m = 1. The CVRP and the CluTSP are both \mathcal{NP} -Hard, and so is the CluVRP.

Sevaux and Sörensen (2008) introduced the CluVRP in the context of a real-world application where containers are employed to carry goods. The customers expecting parcels in the same container form a cluster, because the courier has to deliver the content of a whole container before handling another container. Clusters also arise in applications involving passenger transportation, where passengers prefer to travel with friends or neighbors (as in the transportation of elderly to recreation centres). Gated communities (residential or industrial areas enclosed in walled enclaves for safety and protection reasons) provide another natural example of clusters. The customers within a gated community are likely to be visited by a single vehicle in a sequence, otherwise the vehicles have to spend additional time for the security controls at the gates.

Clusters can thus be imposed by the geography, the nature of the application, as well as by practitioners aiming to achieve *compact* and easy-to-implement routing solutions. Clustered routes allow drivers to be assigned to areas (i.e., certain streets or postcodes) and allow the development of familiarity, which makes their task easier. In addition, clustered routes have significantly less overlaps. In several cases, the additional routing costs due to cluster constraints are compensated by the ease of implementation and the enhanced driver familiarity.

The literature on the CluVRP is quite limited as of the time of this writing. Sörensen et al. (2008) and Sevaux and Sörensen (2008) presented an integer programming formulation capable of finding the best Hamiltonian path between each pair of vertices in each cluster. Barthélemy et al. (2010) suggested to adapt CVRP algorithms to the CluVRP by including a large positive term M to the cost of the edges between clusters and a cluster and the depot. The CluVRP is solved as a CVRP by means of the algorithm of Clarke and Wright (1964) followed by 2-OPT moves and Simulated Annealing (SA). The authors also suggested to dynamically set the penalty M, but observed that the M term interferes with the Boltzmann acceptance criterion of the SA and leads to erratic performance. Computational results were not reported in this initial paper.

Pop et al. (2012) described the directed CluVRP as an extension of the *Generalized Vehicle Routing Problem* (GVRP, Ghiani and Improta, 2000). The authors adapted two polynomial-sized formulations for the GVRP to the directed CluVRP, but again no computational results were reported. Recently, Battarra et al. (2014) proposed exact algorithms for the CluVRP and provided a set of benchmark instances with up to 481 vertices. The best performing algorithm

relies on a preprocessing scheme, in which the best Hamiltonian path is precomputed for each pair of endpoints in each cluster. This allows for selecting a pair of endpoints in each cluster rather than the whole path, relegating some of the problem complexity in the preprocessing scheme. The resulting minimum cost Hamiltonian path problems are reduced to instances of the Traveling Salesman Problem (TSP) and optimally solved with Concorde (Applegate et al., 2001). CluVRP instances of much larger size than the corresponding CVRP instances were optimally solved, thus highlighting the advantage of acknowledging the presence of clusters.

In this paper, we introduce hybrid adaptations of state-of-the-art CVRP metaheuristics for the CluVRP. Rather than rediscovering well-known metaheuristic concepts, we exploit the current knowledge on iterated local search and hybrid genetic algorithms (Subramanian, 2012; Vidal et al., 2014a) and focus our attention on developing efficient problem-tailored neighborhood searches and effectively embedding them into these metaheuristic frameworks. The proposed neighborhood searches aim at 1) better exploiting clustering constraints by means of pruning techniques, 2) exploring larger neighborhoods by means of dynamic programming, 3) reducing the computational time by means of re-optimization, bi-directional search, and data structures. Finally, these experiments lead to further insights on which type of metaheuristic to use for different instance sizes and cluster characteristics.

The remainder of the paper is organized as follows. Section 2 introduces the challenges related to the CluVRP. Sections 3 and 4 describe the proposed metaheuristics and efficient neighborhood-search strategies, whereas Section 5 discusses our computational results. Conclusions are drawn in Section 6, and further avenues of research are discussed.

2. Motivation

Battarra et al. (2014) showed that exact algorithms are capable of solving relatively large CluVRP instances. However, the CPU times remain prohibitively long for large-scale or real time applications. In this paper, we exploit the properties of the CluVRP to develop specialized hybrid metaheuristics that take advantage of cluster constraints. Solution quality is assessed by a comparison with exact solutions whenever possible, and among metaheuristics when it is not.

Two recent and successful metaheuristic frameworks are used in this work. The Iterated Local Search (ILS) algorithm of Subramanian (2012) is simple and flexible, combining the intensification strength of Local Search (LS) operators and effective diversification through perturbation operators. It proved to be remarkably efficient for many variants of the Vehicle Routing Problem (VRP), including the VRP with Simultaneous Pickup and Delivery (Subramanian et al., 2010), the Heterogeneous VRP (Penna et al., 2013), the Minimum Latency Problem (Silva et al., 2012), and the TSP with Mixed Pickup and Delivery (Subramanian and Battarra, 2013). The success of ILS is due to an intelligent design of intensification and diversification neighbourhoods, as well as their random exploration. This latter component allows for extra diversity, and leads to high

quality solutions, even when applied to other problems such as scheduling (Subramanian et al., 2014).

ILS explores only feasible solutions, and allows for testing the M approach suggested by Barthélemy et al. (2010) without possible interferences between M and penalties applied to infeasible solutions. As mentioned in the introduction, the M approach consists of including a large positive term to all those edges that are connecting clusters and connecting the depot to the clusters. Any CVRP algorithm in which the M is chosen to be large enough returns a CluVRP solution in which the number of penalized edges is minimized, therefore a solution in which the cluster constraint is satisfied. Note that the number of edges connecting clusters or connecting the depot to a cluster is m+N and their penalization can be easily deducted from the solution cost.

One drawback of this transformation is that most VRP neighborhoods consider moves of one or two vertices. These neighborhoods can often not relocate complete clusters, and thus many moves appear largely deteriorating due to M penalties, significantly inhibiting the progress towards higher quality solutions. As shown in this paper, ILS can partly overcome this issue by means of perturbation moves. However, as demonstrated by our computational results, a more clever application of the framework specific to the CluVRP considering relocating and exchanges of whole clusters and intra-cluster improvements produces solutions of comparable quality in considerably less CPU time. In the next section, we describe the ILS and these hybrid algorithms in more details.

The Unified Hybrid Genetic Search (UHGS) currently obtains the best known solutions for more than 30 variants of the CVRP and represents the state-of-the-art among hybrid metaheuristics for VRPs. More precisely, the algorithm successfully solves problems with diverse attributes, such as multiple depots and periods (Vidal et al., 2012), time windows and vehicle-site dependencies (Vidal et al., 2013a), hours-of-service-regulations for various countries (Goel and Vidal, 2013), soft, multiple, and general time windows, backhauls, asymmetric, cumulative and load-dependent costs, simultaneous pickup and delivery, fleet mix, time dependency and service site choice (Vidal et al., 2014a), and prize-collecting problems (Vidal et al., 2014c), among others. It has been recently demonstrated that several combinatorial decisions, such as customer selections or depot placement, can be relegated directly at the level of cost and route evaluations, allowing to always rely on the same metaheuristic and local search framework while exploring large neighborhoods in polynomial or pseudo-polynomial time (Vidal et al., 2014b,c).

Our UHGS implementation is based on the assumption that the costs of the optimal Hamiltonian paths among vertices in the same cluster can be efficiently precomputed as in Battarra et al. (2014). Once these paths and their costs are known, an effective route representation as an ordered sequence of clusters can be adopted, and a fast shortest path-based algorithm then transforms this solution representation into the corresponding optimal sequence of customers, which will be explained in detail in Section 4. This approach drastically reduces the size of the search

space of the UHGS method, which optimizes the assignment and sequencing of $\mathcal{O}(N)$ clusters instead of $\mathcal{O}(n)$ customers.

Our computational experiments allow to quantify the trade-off between adopting the preprocessing scheme to compute the Hamiltonian paths, which requires the solution of $\sum_{i=1,...,N} |V_i| \times$ $(|V_i|-1)$ TSP instances and searching in the space of clusters with UHGS, or working in the space of vertices with a well-designed ILS. As long as the average size of the clusters is not high, the computational burden of the preprocessing is not prohibitive, but is observed to become significant when the cluster size increases. On the other hand, UHGS is much faster (ignoring the preprocessing time) and obtains higher quality solutions. Through our computational experiments, we aim at identifying a critical cluster size that makes an approach with cluster-based solution representation more desirable than an approach using vertex-based representation.

3. The ILS metaheuristic

ILS is a well-known metaheuristic framework that iteratively alternate stages of local search (intensification) and perturbation moves (diversification). The interested reader is referred to Lourenço et al. (2003) for a detailed description of the methology, whereas the structure of a typical ILS algorithm is presented in Algorithm 1.

The algorithm starts by generating an initial solution s_0 ; this solution is then improved by means of local search ($LocalSearch(s_0)$) and a local optimal solution s^* is obtained. Perturbation moves are applied to s^* , generating a new solution s', which in turn is improved by means of local search, generating the solution $s^{*'}$. The algorithm updates s^* if an acceptance criterion is met. A typical stopping criterion is to interrupt the execution of the algorithm if no improvement is obtained after n_I consecutive iterations.

Algorithm 1 Iterated Local Search

```
    Procedure ILS:
    s<sub>0</sub> ← GenerateInitialSolution;
    s* ← LocalSearch(s<sub>0</sub>);
    While Stopping criterion is not met
    s' ← Perturb(s*, history);
    s*' ← LocalSearch(s');
    s* ← AcceptanceCriterion(s*, s*', history);
    end ILS;
```

The ILS of Subramanian (2012) is a multi-start heuristic which returns the best solution after n_R restarts (i.e., the Algorithm 1 is executed n_R times). The initial solution is generated using a parallel cheapest insertion heuristic. Classical VRP/TSP neighborhoods are explored during the local search phase and the perturbation operator consists of multiple shift and swaps based

moves selected at random. The neighborhood structures adopted in Subramanian (2012) are interroute moves (Relocate, Relocate, Swap, Swap(2,1), Swap(2,2), 2-opt*), as well as intraroute moves (Relocate, Or-opt2, Or-opt3, 2-opt and Swap). Detailed descriptions of these families of neighborhoods can be found in Subramanian (2012) and Vidal et al. (2013b). Interroute LS neighborhoods are considered one by one in random order and, whenever an improving solution is found, intra-route LS operators are applied, also in random order, to this solution.

As previously mentioned, the algorithm of Subramanian (2012) can be used for solving the CluVRP by applying suitable penalties to edges between clusters and between clusters and the depot. Although simple, this straightforward adaptation has two main drawbacks: (i) most of the local search moves violate the cluster constraint, leading to high penalties, and consuming a large part of the CPU time; and (ii) many promising moves that relocate full clusters are not included in the neighborhoods, thus reducing the intensification capabilities of the LS. ILS was therefore adapted to better take advantage of clusters. In what follows, we denote this adaptation as ILS-Clu.

The ILS-Clu is a hybrid algorithm built upon the structure of ILS. Large neighborhoods proved to be very effective in solving VRP variants, however, to identify promising moves can be a difficult task that is usually left for a large part to randomization (e.g., in Adaptive Large Neighborhood Search, Pisinger and Ropke, 2007). In contrast, the CluVRP structure enables to apply moves to relevant sets of customers. Thus, the LS phase of ILS-Clu explores moves on different levels: among clusters, among edges connecting clusters or clusters with the depot, and within each cluster. This mechanism enables to explore a sufficiently large variety of moves while significantly reducing CPU time. As in ILS, the initial solution is generated using a parallel cheapest insertion heuristic. Iteratively, a randomly selected customer is inserted with minimum cost, either between customers from the same cluster, or between two clusters.

Four types of LS procedures are used in ILS-Clu: "InterRouteSearch $_{C}$ ", "IntraRouteSearch $_{C}$ ", "IntraClusterSearch" and "IntraClusterRestrictedSearch". The former two modify the sequence of clusters in the routes without changing the Hamiltonian paths and their endpoints in each cluster, whereas the latter two optimize the sequence of customers within each cluster. The set of neighborhoods used during "InterRouteSearch $_{C}$ " contains the same inter-route neighborhoods as ILS – previously described – but moves are applied on clusters instead of single deliveries. The intra-route neighborhoods of "IntraRouteSearch $_{C}$ " follow the same rationale.

The LS procedures "IntraClusterSearch" and "IntraClusterRestrictedSearch" rely on the RELOCATE, 2-OPT, and SWAP neighborhoods. "IntraClusterRestrictedSearch" explores only a linear number of LS-moves, more precisely those involving at least one endpoint customer in the cluster, whereas "IntraClusterSearch" explores all moves within a cluster. Algorithm 2 displays the main structure of ILS-Clu, and highlights the differences with ILS.

LEFT TO DO

Both ILS and ILS-Clu apply a perturbation mechanism after each LS stage, which consists

Algorithm 2 Local search of ILS and ILS-Clu Local Search of ILS: Local Search of ILS-Clu: $NL \leftarrow set of InterRouteSearch neighborhoods;$ $NL_C \leftarrow \text{set of InterRouteSearch}_C \text{ neighbor-}$ hoods; While $NL_C \neq \emptyset$ While $NL \neq \emptyset$ Choose randomly Neighborhood \in NL: Choose randomly Neighborhood $\in NL_C$; Find best s' of $s \in \text{Neighborhood}$; Find best s' of $s \in \text{Neighborhood}$; If f(s') < f(s) then If f(s') < f(s) then $s \leftarrow s'$; $s' \leftarrow \text{IntraClusterRestrictedSearch}(s');$ $s \leftarrow \text{IntraRouteSearch}(s);$ $\bar{s} \leftarrow \text{IntraRouteSearch}_C(s');$ Update NL; If $f(\bar{s}) < f(s')$ then $s \leftarrow \text{IntraClusterRestrictedSearch}(\bar{s});$ else $s \leftarrow \bar{s}$; Update NL_C ; else Remove Neighborhood from NL_C ; Remove Neighborhood from NL; $s \leftarrow \text{IntraClusterSearch}(s);$ return s: return s: end. end.

of one or two randomly selected Shift(1,1) or Swap moves. In ILS, Shift(1,1) relocates a random customer from its route r to a random position in another route r', and simultaneously relocates a random customer from r' to a random position in r. The same process is applied in ILS-Clu but considering clusters instead of single customers. Moreover, in ILS, Swap exchanges two customers from different routes, whereas in ILS-Clu the exchange involves two clusters of the same route.LEFT TO DO

4. The UHGS metaheuristic

UHGS is a successful framework capable of producing high quality solutions for many VRP variants. It is a hybrid algorithm, where the diversification strength of a Genetic Algorithm (GA) is combined with the improvement capabilities of local search. One main challenge in the design of a hybrid genetic algorithm is to achieve a good balance between intensification and diversification while controlling the use of computationally intensive local search procedures. This balance is usually achieved by selecting a suitable initial population, crossover operators, mutation, and selection mechanisms. The variety of design choices and the tuning of a multitude of parameters often inhibit the flexibility of the GAs. In fact, most of the previous attempts in the literature focused on the design of problem-specific operators, failing to lead to general algorithms and frequently resulting in a large number of parameters to be tuned. UHGS (Vidal et al., 2014a) managed to overcome most of these drawbacks by adopting the following strategies.

4.1. General UHGS methodology

UHGS evolves a population of individuals representing problem solutions, by means of selection, crossover and education operators. Note that the operator *education* involves a complete local-search procedure aimed at improving the solutions rather than a randomized mutation. The population is managed to contain between μ^{MIN} and $\mu^{\text{MIN}} + \mu^{\text{GEN}}$ individuals, by pruning μ^{GEN} individuals whenever the maximum size is attained. The method is run until It_{max} individuals have been successively created without improvement of the best solution.

UHGS achieves a fine balance between intensification and diversification by means of a bicriteria evaluation of solutions. The first criterion is the contribution of a solution to the population diversity, which is measured as the Hamming distance of the solution to the closest solutions in the population. The second criterion is the objective value. Solutions are ranked with respect to both criteria, and the sum of the ranks provides a "biased fitness" (Vidal et al., 2014a), used for both parents selection and survivors selection when the maximum population size is attained. To deal with tightly constrained problems, linearly penalized route-constraint violations – capacity or distance – are included in the objective. Penalty coefficients are dynamically adjusted to ensure a target ratio of feasible solutions during the search; infeasible solutions are managed in a secondary population.

During crossover, the whole solution is represented as a giant tour visiting all customers once, without intermediate depot trips. As such, a simple ordered crossover that works on permutations can be used. The optimal splitting of the giant tour into separate routes is performed optimally in polynomial time as a shortest path subproblem on an auxiliary graph (Prins, 2004). This process is known to be widely applicable in a unified manner to many vehicle routing variants as long as it is possible to perform separate efficient route evaluations to compute the cost of edges in the auxiliary graph (Vidal, 2013). Finally, UHGS relies on local search to improve every new offspring solution generated during the search. The LS operators used in UHGS are 2-OPT, 2-OPT*, CROSS and I-CROSS (Vidal et al., 2014a). The last two neighborhoods are limited to exchanges, with possible inversions, of up to two customers.

Local search is usually the bottleneck of most advanced metaheuristics for vehicle routing variants, and thus efficient evaluations of routes generated by the neighborhoods are critical for the overall algorithm's performance. When additional attributes (constraints, objectives or decisions) are considered, these route evaluations may be time consuming if implemented in a straightforward manner. To improve this process, UHGS relies on auxiliary data structures that collect partial information on any sub-sequence of consecutive customers in the incumbent solution. This information is then used for efficiently evaluating the cost and feasibility of new routes generated by local search moves since any such move can be seen as a recombination of subsequences of consecutive customers from the incumbent solution.

A simple illustration of this concept is now given. Consider a CVRP solution with two routes: $r_1 = (0, 1, 2, 3, 4, 5, 0)$ and $r_2 = (0, 6, 7, 8, 9, 0)$. To efficiently evaluate the capacity constraints,

the partial load $Q(\pi)$ for any sub-sequence π of the incumbent solution is preprocessed prior to move evaluations. An inter-route 2-OPT* move breaking the edges (3,4) and (7,8) leads to two new routes $r'_1 = (0,1,2,3,8,9,0)$ and $r'_2 = (0,6,7,4,5,0)$ requiring cost and load feasibility evaluations. Loads $Q(\pi_{0\to 3})$, $Q(\pi_{4\to 0})$, $Q(\pi_{0\to 7})$ and $Q(\pi_{8\to 0})$ are known for sequences (0,1,2,3), (4,5,0), (0,6,7) and (8,9,0), respectively. Denoting \oplus as the concatenation operator, we have $Q(r'_1) = Q(\pi_{0\to 3} \oplus \pi_{8\to 0}) = Q(\pi_{0\to 3}) + Q(\pi_{8\to 0})$, and in the same way $Q(r'_2) = Q(\pi_{0\to 7}) + Q(\pi_{4\to 0})$. Load constraints can thus be checked in $\mathcal{O}(1)$ operations, independently of the number of customers in the route. Otherwise, a straightforward approach sweeping through the new route and cumulating the demands would take a number of operations proportional to $\mathcal{O}(n)$. This type of route evaluation is referred to as move evaluation by concatenation in Vidal et al. (2014a), and can be applied to a wide range of resources (load, distance, time), constraints and objectives.

4.2. Application to the CluVRP

Our application of UHGS to the CluVRP relies on two contributions: a route representation based on an ordered sequence of clusters to reduce the search space, and efficient route evaluation procedures using concatenations to evaluate the cost of a route assimilated to a sequence of clusters. Thus, UHGS is applied on sequences of clusters, and the optimal path within the clusters is determined implicitly during move and route evaluations. This leads to an implicit structural problem decomposition, considering only a VRP of a size proportional to the number of clusters N < n, and relegating difficult combinatorial decisions on path selections within clusters at the level of route evaluations. These methodological elements can be easily integrated into the UHGS framework, and it was possible to use the original UHGS implementation with the sole addition of a new route-evaluation operator.

The method relies on the fact that in any cluster V_k , the cost \hat{c}_{ij} of the best Hamiltonian path between customer $i \in V_k$ and customer $j \in V_k$ that services all other customers in $V_k \setminus \{i, j\}$ has been preprocessed (Battarra et al., 2014). Using this information, it is possible to obtain from a route represented as a sequence of clusters the best sequence of visits to customers in polynomial time by finding a shortest path in the auxiliary graph \mathcal{G}' illustrated in Figure 1.

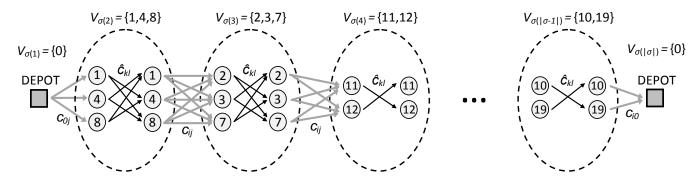


Figure 1: Route representation in UHGS

In Figure 1, black lines correspond to precomputed Hamiltonian paths within clusters. For each cluster in the route, a set containing two copies of each node is generated. Pairs of node copies are connected by an arc (k, l). The cost of this arc is set to the cost of the shortest Hamiltonian path \hat{c}_{kl} in the cluster between k and l. The depot is then connected to the first copy of each node in the first cluster, and the second copies of the nodes are connected to the first node copies of the next cluster, and so on. The cost associated to these arcs (in gray in the figure) is the travel distance between the endpoints. A similar shortest path subproblem was previously used for the GVRP by Pop et al. (2013) and Vidal (2013).

A straightforward application of this technique leads to route evaluations in $\mathcal{O}(NB^2)$ operations, where B is the maximum number of customers in a cluster. These evaluations are computationally expensive. Another contribution of this work is to show that efficient procedures based on preprocessing and concatenations allow for performing each move evaluation in amortized $O(B^2)$ operations, thus only depending on the square of the cluster size. These more efficient evaluation procedures are now described.

For ease of notation, define $\lambda_i = |V_i|$ for any cluster V_i . In addition to the Hamiltonian paths within clusters, which are pre-processed a single time before starting the method, UHGS now pre-processes some information on each subsequence σ of consecutive clusters in each current solution. This information is updated whenever a solution change, e.g. a local search move, is applied. For any sequence $\sigma = (\sigma(1), \ldots, \sigma(|\sigma|))$ of clusters, the method computes for any i^{th} customer of the cluster $\sigma(1)$, and any j^{th} customer of the cluster $\sigma(|\sigma|)$, the shortest path $S(\sigma)[i,j]$ inside the sequence of clusters connecting i and j. These values can be computed as follows.

First, let us assume a subsequence $\bar{\sigma} = (V_k)$ containing a single cluster. If the cluster is restricted to a single customer, i.e., $V_k = \{v_i\}$, then $S(\bar{\sigma})[i,i] = 0$. Otherwise, $S(\bar{\sigma})[i,j]$ is given in Equation (1), in which \hat{c}_{ij} represents the distance of the best Hamiltonian path connecting i and j in the cluster V_k .

$$S(\bar{\sigma})[i,j] = \begin{cases} +\infty & \text{if } i = j \\ \hat{c}_{ij} & \text{if } i \neq j \end{cases} \quad \text{for } i \in \{1,\dots,\lambda_k\} \text{ and } j \in \{1,\dots,\lambda_k\},$$
 (1)

Any longer subsequence can be viewed as a concatenation of shorter subsequences. Equation (2) enables to evaluate $S(\sigma)$ on a new sub-sequence resulting of the concatenation of a pair of subsequences σ_1 and σ_2 , by induction on the concatenation operation \oplus . It is a direct application of the Floyd-Warshall algorithm.

$$S(\sigma_{1} \oplus \sigma_{2})[i,j] = \min_{1 \le x \le \lambda_{\sigma_{1}(|\sigma_{1}|)}, 1 \le y \le \lambda_{\sigma_{2}(1)}} S(\sigma_{1})[i,x] + c_{xy} + S(\sigma_{2})[y,j],$$
for $i \in \{1, \dots, \lambda_{\sigma_{1}(1)}\}$ and $j \in \{1, \dots, \lambda_{\sigma_{2}(|\sigma_{2}|)}\}$ (2)

Equation (2) can be used to perform preprocessing on all subsequences of clusters in the

current solution by iteratively appending a sequence made of a single cluster at the end. The same equation is then applied during neighborhood exploration to compute the cost of routes resulting from local moves. These routes can be viewed as a concatenation of a bounded number of subsequences from the current solution (Vidal, 2013). Figure 2 illustrates this pre-processing and move-evaluations mechanism. We consider the relocation of a subsequence of clusters σ_2 into a route originally made of $\sigma_1 \oplus \sigma_3$. The new route is thus a concatenation of the three sequences $\sigma_1 \oplus \sigma_2 \oplus \sigma_3$. The original shortest path problem is depicted on the top of the figure. Since pre-processing has been done on subsequences from the incumbent solution, the sets of shortest paths $S(\sigma_1)[i,j]$, $S(\sigma_2)[i,j]$ and $S(\sigma_3)[i,j]$ are known. They describe the shortest paths between any origin node i in the first cluster of the sequence, and any destination node j in the last cluster of the sequence. As a consequence, these known paths can be substituted in the graph, leading to an equivalent shortest path problem over a smaller graph, illustrated in the bottom of the figure. The number of nodes and arcs in this new graph does not depend anymore on the number of clusters in the route, but only on the number of concatenations, thus resulting in a reduced computational complexity.

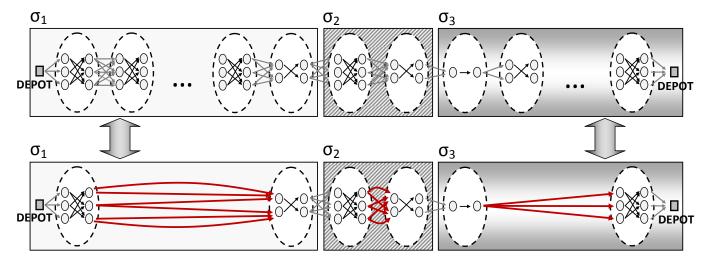


Figure 2: Using preprocessed information on subsequences

Proposition 1. Using the proposed preprocessing, the amortized complexity of move evaluations, for classic VRP neighborhoods such as Relocate, Swap, 2-Opt, 2-Opt*, is $\mathcal{O}(B^2)$.

Proof. First, from the current incumbent solution, the preprocessing phase requires computing the shortest paths between each pair of nodes, for each route. For each route, the graph \mathcal{G}' is directed and acyclic. Equation (2) is applied iteratively, in lexicographic order starting from any cluster σ_i , $i \in \{1, \ldots, |\sigma|\}$ and iteratively applied to σ_j for $j \in \{i+1, \ldots, |\sigma|\}$ to produce all shortest paths. This equation is thus used $\mathcal{O}(N^2)$ times to perform a complete preprocessing on all routes. Each evaluation of this expression requires $\mathcal{O}(B^2)$ time. The total effort for the

preprocessing phase is $\mathcal{O}(N^2B^2)$.

After preprocessing, a local search using classic VRP neighborhoods is performed. Any move based on less than k edge exchanges can be assimilated to a recombination of up to k+1 subsequences of consecutive clusters. This is the case for the mentioned neighborhoods with $k \leq 4$. Thus, each move evaluation is performed with a bounded number of calls to Equation (2), in $\mathcal{O}(B^2)$ elementary operations. The size S of each neighborhood is quadratic in the number of clusters (e.g. swapping any cluster i with cluster j leads to $S = \Theta(N^2)$ possible moves), such that a complete neighborhood exploration takes $\mathcal{O}(B^2N^2)$ time. The amortized complexity per move evaluation, considering both preprocessing and effective evaluation, is thus $\mathcal{O}(\frac{N^2B^2}{S}) = \mathcal{O}(B^2)$. \square

5. Computational results

Computational experiments have been conducted on multiple benchmark instance sets. The first sets have been recently presented in Battarra et al. (2014). The authors considered instances proposed in the GVRP literature by Bektaş et al. (2011) (instance sets GVRP2 and GVRP3) and then generated larger instances by adapting the CVRP instances proposed by Golden et al. (1998) (instance set Golden) using the method reported in Bektaş et al. (2011). Among the instances proposed in Battarra et al. (2014), we have included in our benchmark set all Golden instances (200 up to 484 customers) and the most challenging ones among the GVRP2 and GVRP3 sets (the instances denoted as G and C in the GVRP literature, with 101 up to 262 customers). We have also generated an additional instance set with even larger problems (called hereafter Li), by adapting the method of Bektaş et al. (2011) on the instances originally proposed by Li et al. (2005). The latter set contains instances with up to 1200 customers. We decided to have clusters with average cardinality $\overline{\lambda}=5$, leading to larger instances with 113 up to 241 clusters. A summary of the characteristics of our benchmark set is provided in Table 1. All sets of instances are available upon request and detailed result tables are displayed in the appendix (where the column Exact denotes the best upper bounds found in Battarra et al., 2014).

Table 1: Summary of benchmark set characteristics

Instance Set	Source	# Inst.	n	N
С	Bektaş et al. (2011)	2	101-200	34-100
G	Bektaş et al. (2011)	8	262-262	88-131
Golden	Battarra et al. (2014)	220	201-481	17-97
${ m Li}$	New	12	560-1200	113 -241

An extensive calibration effort was spent in previous studies to find good and robust parameters for UHGS (Vidal et al., 2012) and ILS (Subramanian, 2012). We relied on this knowledge to obtain an initial parameter setting, and then scaled the parameters controlling algorithm termination to generate solutions for large-scale instances in comparable CPU time. As such, the

population-size parameters of UHGS are set to $(\mu^{\text{MIN}}, \mu^{\text{GEN}}) = (8, 8)$ and the termination criterion is $It_{max} = 400$. For ILS, the number of restarts has been set to $n_R = 50$ and the number of perturbations is $n_I = n + 5m$ as in Subramanian (2012). The choice of $n_I = 1000$ was adopted for ILS-Clu. All experiments have been conducted on a Xeon CPU with 3.07 GHz and 16 GB of RAM, running under Oracle Linux Server 6.4. Each algorithm was executed 10 times for each instance using a different random seed.

Table 2 summarizes the results obtained by the proposed hybrid metaheuristics. For each benchmark set, the number of instances "Inst." is given, as well as the number of times "# BKS" the best known solution is found by ILS, ILS-Clu and UHGS, respectively. Columns 6-9 provide the average CPU time per instance in seconds. $UHGS_p$ also includes the CPU time dedicated to computing the cost of all intra-cluster Hamiltonian paths with Concorde. Columns 10-12 report the average percentage deviation from the best known solutions "Avg. % Dev.". Note that the percentage deviation for a solution of value z from the best known solution value z_{BKS} is computed as $\frac{z-z_{BKS}}{z_{BKS}} \times 100$. The last row reports the overall number of best known solutions found by each method, the average CPU time and percentage average deviation.

From the experiments, it appears that UHGS is capable of finding most of the best known solutions (234 out of 242). In most cases, the average percentage gaps among the three methods is still small: ILS-Clu has an average deviation of 0.19% from the best known solutions and ILS has an average deviation of 0.13%. ILS is remarkably slower than the two other algorithms. The average CPU time for the large instances in the Li data set is 9548.6 seconds, versus 535.8, 345.3, 660.0 seconds for ILS-Clu, UHGS, and UHGS_p, respectively. Note that ILS performs about 0.06%better than ILS-Clu, but ILS-Clu is 15 times faster on average.

 $UHGS_p$ is faster on average than ILS, even with the exhaustive search of all intra-cluster Hamiltonian paths using Concorde. This preprocessing phase is fast when the average cluster size is limited, but requires large CPU time when the cluster size increases, as in the case of the Golden instances. A heuristic evaluation of the cost of intra-cluster Hamiltonian paths could be a viable alternative. This is left as a research perspective. Finally, UHGS is faster than ILS-Clu for very large instances. ILS-Clu is on average faster on the G and C data sets, but slower on average on the Li set.

BKS Avg. Time (s) Avg. % Dev. ILS ILS-Clu UHGS ILS ILS-Clu UHGS ILS ILS-Clu Instance Set |Inst.| $UHGS_p$ G 20 2 127.6165.20.64 0.221 53.5150.2 \mathbf{C} 8 6 8 7 26.017.827.10.190.04 35.1

Li

Tot:

Table 2: Summary of results for the G, C, Golden and Li instances

UHGS

0.00

Table 3: Summary of results for the Golden instance set grouped by instance size

		# Opt.			Avg. T	ime (s)			Avg. % De	ev.
n	ILS	ILS-Clu	UHGS	ILS	ILS-Clu	UHGS	UHGS $_p$	ILS	ILS-Clu	UHGS
201	11	11	11	81.18	19.92	14.57	2866.57	0	0	0
241	11	9	11	141.92	23.95	22.4	172.94	0	0.03	0
241	11	11	11	159.43	27.2	20.92	176.87	0	0	0
253	8	5	11	145.67	21.86	23.33	164.69	0.05	0.12	0
256	10	9	10	148.03	21.57	22.09	135.45	0.03	0.06	0.03
281	10	8	11	308.71	47.15	34.14	3848.32	0	0.03	0
301	10	11	11	309.59	37.9	30.75	191.26	0.02	0	0
321	3	2	11	442.25	47.27	47.57	243.39	0.08	0.07	0
321	7	2	11	333.56	34.29	38.12	152.78	0.12	0.25	0
324	6	4	11	336.87	31.55	43.82	175.73	0.19	0.31	0
361	3	1	11	816.36	73.97	66.94	2220.3	0.09	0.13	0
361	10	7	11	523.32	52.43	38.65	276.27	0.01	0.04	0
397	1	0	9	713.35	52.3	65.99	279.15	0.33	0.48	0.03
400	3	0	11	658.46	46.9	59.62	198	0.3	0.56	0
401	5	2	11	1115.99	85.16	82.91	1384.18	0.12	0.14	0
421	7	1	10	886.08	77.59	49.59	351.74	0.11	0.22	0.09
441	4	0	10	1573.62	101.69	97.09	1017.63	0.08	0.16	0
481	1	0	9	2336.64	130.52	137.95	2608.13	0.12	0.13	0.01
481	3	3	11	1344.21	74.34	84.3	246.31	0.15	0.39	0
484	3	1	11	1420.29	72.22	94.05	389.16	0.48	0.73	0
Tot:	127	87	213							

A more detailed comparison of the algorithms is displayed in Table 3 for the Golden instances. The large number of instances in this set allows for an analysis of the algorithms' performances by varying the number of customers and cluster size. The table reports aggregated results, obtained by averaging over instances with the same number of customers.

A correlation between the size of the instance and the performance of ILS can be observed; larger instances lead to larger gaps and higher CPU time. On the other hand, the performance of ILS-Clu is less dependent on instance size. For example, instances of group 12 with 484 customers are the most challenging for ILS-Clu with a 0.73% average deviation, but the deviation for instances of group 4, with size n=481, is only 0.13% in average. A similar observation stands for UHGS, the most challenging instance groups being 4, 9, 14, and 20 with 481, 256, 397 and 421 customers, respectively.

Aggregating the Golden instances by average cluster size λ , as done in Table 4, leads to a further level of understanding of algorithms performance. All algorithms find solutions close to the best known when the average cluster size is large and therefore less clusters are present. The average CPU time of ILS does not depend on the average cluster size, whereas UHGS is consistently faster when large and few clusters are present. ILS-Clu attains its minimum CPU

Table 4: Summary of results for the Golden instances grouped by average cluster size

		# Opt.			Avg. T	time (s)			Avg. De	v.
λ	ILS	ILS-Clu	UHGS	ILS	ILS-Clu	UHGS	UHGS_p	ILS	ILS-Clu	UHGS
5	17	8	20	670.40	55.60	36.29	140.32	0.02	0.11	0.00
6	18	12	20	663.38	53.84	37.22	155.89	0.02	0.08	0.00
7	17	9	20	670.84	52.68	39.55	173.19	0.01	0.11	0.00
8	11	9	20	688.00	50.83	43.15	251.55	0.08	0.12	0.00
9	12	10	20	689.86	48.98	45.71	307.15	0.08	0.18	0.00
10	12	7	20	691.00	49.16	49.64	553.37	0.11	0.18	0.00
11	10	9	20	709.81	48.85	50.82	417.97	0.13	0.18	0.00
12	9	9	20	695.70	50.12	54.77	1025.66	0.13	0.18	0.00
13	8	5	20	725.73	53.12	69.04	916.16	0.18	0.29	0.00
14	7	5	17	699.89	59.99	73.52	2327.81	0.24	0.37	0.06
15	6	4	16	682.94	70.72	91.43	3135.31	0.23	0.31	0.03
Avg:	11.55	7.91	19.36	689.78	53.99	53.74	854.94	0.11	0.19	0.01

time when the average cluster size is approximately 9 customers. This is due to the fact that ILS-Clu performs both intra and inter-cluster LS moves; a balanced instance in terms of number and size of the clusters is a good compromise in terms of CPU time. Finally UHGS was capable of improving the best known solutions for five instances from Battarra et al. (2014). The values of these solutions are listed in Table 7.

6. Conclusions

This paper focused on the CluVRP, a generalization of the CVRP where customers are grouped into clusters. Three metaheuristics have been proposed, two of which are based on iterated local search, while the third is a hybrid genetic algorithm with a cluster-based solution representation. Efficient large neighborhood search procedures based on re-optimization techniques have been developed and integrated with the hybrid genetic search. The resulting three methods produce high quality solutions, and algorithms taking advantage of the cluster structure and large neighborhoods are remarkably faster. The hybrid genetic algorithm and large neighborhood search leads to solutions of higher quality that the two ILS based algorithms, but its pre-processing phase may become time consuming for instances with large clusters. Future work should consider heuristic preprocessing techniques to enhance CPU time, and other large neighborhoods strategies taking advantage of clusters.

Acknowledgements: This work was partially supported by CORMSIS, Centre of Operational Research, Management Sciences and Information Systems, and by CNPq, Conselho Nacional de Desenvolvimento Científico e Tecnológico (grant 471158/2012-7).

References

- Applegate, D., Bixby, R., Chvàtal, V., Cook, W., 2001. Concorde TSP solver. URL http://www.tsp.gatech.edu/concorde/index.html
- Barthélemy, T., Rossi, A., Sevaux, M., Sörensen, K., June 2010. Metaheuristic approach for the clustered VRP. In: EU/ME 2010 10th anniversary of the metaheuristic community. Lorient, France.
- Battarra, M., Erdoğan, G., Vigo, D., 2014. The clustered vehicle routing problem. Operations Research 62, 58–71.
- Bektaş, T., Erdoğan, G., Ropke, S., 2011. Formulations and branch-and-cut algorithms for the generalized vehicle routing problem. Transportation Science 45, 299–316.
- Chisman, J., 1975. The clustered traveling salesman problem. Computers & Operations Research 2, 115–119.
- Clarke, G., Wright, J. W., 1964. Scheduling of vehicles from a central depot to a number of delivery points. Operations Research 12, 568–581.
- Ghiani, G., Improta, G., 2000. An efficient transformation of the generalized vehicle routing problem. European Journal of Operational Research 122, 11–17.
- Goel, A., Vidal, T., 2013. Hours of service regulations in road freight transport: an optimization-based international assessment. Transportation Science, Articles in Advance.

 URL http://papers.srn.com/sol3/papers.cfm?abstract_id=2057556
- Golden, B., Wasil, E., Kelly, J. P., Chao, I.-M., 1998. Metaheuristics in vehicle routing. In: Fleet Management and Logistics. Kluwer, Boston, pp. 33–56.
- Li, F., Golden, G., Wasil, E., 2005. Very large-scale vehicle routing: New test problems, algorithms, and results. Computers & Operations Research 32, 1165–1179.
- Lourenço, H. R., Martin, O. C., Stützle, T., 2003. Iterated local search. In: Glover, F., Kochenberger, G. (Eds.), Handbook of Metaheuristics. Vol. 57 of International Series in Operations Research & Management Science. Springer US, pp. 320–353.
- Penna, P., Subramanian, A., Ochi, L., 2013. An iterated local search heuristic for the heterogeneous fleet vehicle routing problem. Journal of Heuristics 19, 201–232.
- Pisinger, D., Ropke, S., 2007. A general heuristic for vehicle routing problems. Computers & Operations Research 34, 2403–2435.

- Pop, P., Kara, I., Horvat-Marc, A., 2012. New mathematical models of the generalized vehicle routing problem and extensions. Applied Mathematical Modelling 36, 97–107.
- Pop, P., Matei, O., Pop Sitar, C., 2013. An improved hybrid algorithm for solving the generalized vehicle routing problem. Neurocomputing 109, 76–83.
- Prins, C., 2004. A simple and effective evolutionary algorithm for the vehicle routing problem. Computers & Operations Research 31, 1985–2002.
- Sevaux, M., Sörensen, K., October 2008. Hamiltonian paths in large clustered routing problems. In: Proceedings of the EU/MEeting 2008 workshop on Metaheuristics for Logistics and Vehicle Routing. Troyes, France.
- Silva, M., Subramanian, A., Vidal, T., Ochi, L., 2012. A simple and effective metaheuristic for the Minimum Latency Problem. European Journal of Operational Research 221, 513–520.
- Sörensen, K., Van den Bergh, J., Cattrysse, D., Sevaux, M., June 2008. A multiobjective distributionproblem for parcel delivery at TNT. In: Invited Talk at the International Workshop on Vehicle Routing in Practice, VIP'08. Oslo, Norway.
- Subramanian, A., 2012. Heuristic, exact and hybrid approaches for vehicle routing problems. Ph.D. thesis, Universitade Federal Fluminense.
- Subramanian, A., Battarra, M., 2013. An iterated local search algorithm for the traveling salesman problem with pickups and deliveries. Journal of the Operational Research Society 64, 402–409.
- Subramanian, A., Battarra, M., Potts, C., 2014. An iterated local search heuristic for the single machine total weighted tardiness problem with sequence-dependent setup times. International Journal of Production Research 52, 2729–2742.
- Subramanian, A., Drummond, L., Bentes, C., Ochi, L., Farias, R., 2010. A parallel heuristic for the vehicle routing problem with simultaneous pickup and delivery. Computers & Operations Research 37, 1899–1911.
- Toth, P., Vigo, D. (Eds.), 2002. The vehicle routing problem. Society for Industrial and Applied Mathematics, Philadelphia.
- Vidal, T., 2013. Approches générales de résolution pour les problèmes multi-attributs de tournés de véhicules et confection d'horaires. Ph.D. thesis, Université de Montréal & Université de Technologie de Troyes.
- Vidal, T., Crainic, T., Gendreau, M., Lahrichi, N., Rei, W., 2012. A hybrid genetic algorithm for multidepot and periodic vehicle routing problems. Operations Research 60, 611–624.

- Vidal, T., Crainic, T., Gendreau, M., Prins, C., 2013a. A hybrid genetic algorithm with adaptive diversity management for a large class of vehicle routing problems with time-windows. Computers & Operations Research 40, 475–489.
- Vidal, T., Crainic, T., Gendreau, M., Prins, C., 2013b. Heuristics for multi-attribute vehicle routing problems: a survey and synthesis. European Journal of Operational Research 231, 1–21.
- Vidal, T., Crainic, T., Gendreau, M., Prins, C., 2014a. A unified solution framework for multiattribute vehicle routing problems. European Journal of Operational Research 234, 658–673.
- Vidal, T., Crainic, T., Gendreau, M., Prins, C., 2014b. Implicit depot assignments and rotations in vehicle routing heuristics. European Journal of Operational Research 237, 15–28.
- Vidal, T., Maculan, N., Ochi, L., Penna, P., 2014c. Large neighborhoods with implicit customer selection for vehicle routing problems with profits. Tech. rep., CIRRELT, Montréal.

7. Detailed results

Table 5: Detailed results, Golden 1–4.

	Total Time(s)	555.2	168.1	168.5	164.6	168.6	164	135.6	111.6	93.5	86.9	85.7	399	363.6	337.8	296.3	209.6	200.3	216.1	172.6	154.6	169	158.4	9729.2	2754.2	382	431.6	410.6	366.1	166.3	236.6	248.8	244.5	256.1	7547.4	7522.5	1250.1	5533.9	1910.1	1776.9	234.2	1768.3	393.6	326	426.5
	Preproc. (s)	541	151	151	147	151	144	115	06	65	55	46	368	332	305	262	172	152	167	125	66	96	92	9678	2696	326	372	346	290	26	153	124	123	109	7460	7434	1161	5438	1789	1659	113	1635	198	152	133
UHGS	Avg. Time(s)	14.2	17.1	17.5	17.6	17.6	20	20.6	21.6	28.5	31.9	39.7	31	31.6	32.8	34.3	37.6	48.3	49.1	47.6	55.6	73	82.4	51.2	58.2	56	59.6	64.6	76.1	69.3	83.6	124.8	121.5	147.1	87.4	88.5	89.1	95.9	121.1	117.9	121.2	133.3	195.6	174	293.5
	Avg.	4831	4847	4872	4889	4908	4899	4934	5050	5102	5097	2000	7716	7693	7668	7638.2	7617	7641.5	7649.7	7738	7863.8	7920.4	7893.4	10540	10504	10486	10465	10482	10501	10485	10583	10777.9	10801.2	10621.6	13598	13643	13520	13460	13570.5	13758	13760	13791.9	13967.2	13980.2	13792.2
	Best	4831	4847	4872	4889	4908	4899	4934	5050	5102	5097	2000	7716	7693	7668	7638	7617	7640	7643	7738	7861	7920	7892	10540	10504	10486	10465	10482	10501	10485	10583	10776	10797	10614	13598	13643	13520	13460	13568	13758	13760	13791	13966	13977	13783
	Avg. Time(s)	23.9	21.8	22	21.2	22.2	24	22.4	23.6	24.3	27.8	30.5	51.6	51.4	49.3	45.2	38.8	38.8	39.4	43.5	45.3	53.4	63.2	88.3	83.7	78.4	79.1	78.1	79.5	76.4	78.8	84.1	96.4	113.8	130.6	127.2	113.5	113.4	112.8	121.8	123.7	123.5	136.1	149.3	183.8
ILS-Clu	Avg.	4831.9	4848.4	4877.1	4891.2	4912.3	4899.9	4935.3	5050.2	5118	5113.3	5013.8	7722.2	7700.2	7677	7649.4	7644	7658	7660.4	7756.7	7884.7	7931.6	7906.3	10572.5	10520.9	10511.5	10497.6	10515.2	10544.2	10525.1	10639.6	10821.5	10844.8	10682	13628.5	13706.4	13569.3	13492.7	13601.5	13794.8	13816.6	13846.6	14022.8	14031.6	13849
	Best	4831	4847	4872	4889	4908	4899	4934	5050	5108	5107	2000	7718	7693	6992	7638	7629	7646	7653	7742	7871	7926	7900	10547	10509	10500	10483	10482	10523	10495	10583	10797	10821	10662	13602	13678	13535	13468	13591	13767	13779	13800	13979	14010	13808
	Avg. Time(s)	129.6	134.3	137	135.8	147	134.4	143.1	150	152.6	149.1	148.3	461.8	444.5	441.9	460.3	447.4	452.8	439.9	410.5	431.8	427.5	446.4	1077.6	1020.5	1103.9	1093	1096.4	1194.8	1078	1172.1	1157.1	1110.9	1171.6	2397.9	2362.8	2207.7	2116.6	2113.7	2262.5	2368	2294.6	2584.6	2710.1	2284.7
ILS	Avg.	4831.4	4849.6	4877.8	4896.2	4908.7	4905.9	4943	5051.5	5113.3	5108.4	5011.2	7719.5	7.8697	7675	7649.6	7635.3	7660.3	7656.5	7771.5	7888	7937.9	7910.8	10547.6	10513.5	10497.5	10492.7	10504.1	10533	10526.1	10637.3	10810.7	10843.2	10669.7	13614.3	13688.4	13557.9	13494.9	13604.9	13812.8	13829.5	13857.6	14034.8	14031.5	13857.5
	Best	4831	4847	4872	4889	4908	4899	4934	5050	5102	5097	2000	7716	7693	7668	7644	7619	7649	7650	7759	7874	7925	7898	10540	10504	10486	10465	10482	10518	10502	10605	10789	10824	10654	13606	13643	13525	13466	13588	13784	13772	13810	14000	13987	13821
Exact		4831	4847	4872	4889	4908	4899	4934	5050	5102	2002	5000	7716	7693	7668	7638	7617	7640	7643	7738	7861	7920	7892	10540	10504	10486	10465	10482	10501	10485	10583	10776	10797	10614	13598	13643	13520	13460	13568	13758	13760	13791	13966	13975	13775
	m	4	4	4	4	4	4	4	4	4	4	3	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
	Z	17	18	19	21	22	25	27	31	35	41	49	22	23	25	27	30	33	36	41	46	54	65	27	29	31	34	37	41	45	51	28	29	81	33	35	37	41	44	49	54	61	69	81	97
_	u	241	241	241	241	241	241	241	241	241	241	241	321	321	321	321	321	321	321	321	321	321	321	401	401	401	401	401	401	401	401	401	401	401	481	481	481	481	481	481	481	481	481	481	481
	Inst.	Golden 1	Golden 2	Golden 3	Golden 4																																								

Table 6: Detailed results, Golden 5–8.

	Total	Time(s)	7659.3	7580.2	7771.3	6906.3	510.8	221.8	165.6	235.9	235.5	183.4	62.1	19000.1	20364.7	818.9	551	493	291.3	122.6	192.3	193	173.6	130.9	12411.7	3074.4	3153.7	2674.5	1031.8	1067	174.1	263.5	191	177.5	204.1	1071.1	1070.3	1035.9	905.2	873.8	4918.4	222.8	258.6	282.4	294.7
	Preproc.	(s)	7651	7568	7758	6893	498	209	151	221	219	164	40	18971	20337	789	525	465	257	92	160	150	134	92	12354	3017	3092	2626	086	1005	116	201	108	93	95	1004	1003	970	829	792	4836	127	166	155	132
UHGS	Avg.	Time(s)	8.3	12.2	13.3	13.3	12.8	12.8	14.6	14.9	16.5	19.4	22.1	29.1	27.7	29.9	26	28	34.3	30.6	32.3	43	39.6	54.9	57.7	57.4	61.7	48.5	51.8	62	58.1	62.5	83	84.5	109.1	67.1	67.3	62.9	76.2	81.8	82.4	95.8	92.6	127.4	162.7
	Avg.		7622	7424	7491	7434	7576	7596	7643	7560	7410	7429	7241	8624	8628	8646	8853	8910	8936	8891	8969	9028	8923	9028.7	9904	9888	9917	10021	10029	10131	10052	10080	10095	10096	10014.9	10866	10831	10847	10859	10934	10960	11043.3	11196.7	11263.6	11326.8
	Best		7622	7424	7491	7434	7576	7596	7643	7560	7410	7429	7241	8624	8628	8646	8853	8910	8936	8891	8968	9028	8923	9028	9904	9888	9917	10021	10029	10131	10052	10080	10095	10096	10014	10866	10831	10847	10859	10934	10960	11042	11194	11252	11321
	Avg.	Time(s)	22.5	23.9	25.1	21.5	16.9	16	16.9	18	17.1	20.1	21	61.5	59.8	59.6	41	39.2	40.5	39	38.8	40.4	46.3	52.6	90.3	84.4	80	66.1	62.6	65.7	67.1	64.9	65.3	77.4	89.9	102.7	104.2	104	100.2	94.5	88.9	83.6	87.7	100.9	114.4
ILS-Clu	Avg.		7640.8	7427.6	7491	7439.9	7576	7596.3	7643	7560	7410	7430.6	7241	8624	8632.4	8650.1	8.6988	8921.1	8963.7	8899.9	8971.6	9043.2	8923	9052.1	9947.9	9924.4	9949.9	10054.7	10059.8	10148.1	10067.6	10113.1	10130.6	10139.5	10057	10897.3	10866.9	10892	10893.7	10959	10987.8	11083.4	11251.9	11309	11371
	Best		7622	7424	7491	7434	7576	7596	7643	7560	7410	7429	7241	8624	8628	8646	8853	8910	8949	8891	8969	9039	8923	9031	9922	9905	9922	10025	10042	10134	10052	10094	10116	10128	10034	10883	10845	10852	10883	10945	10969	11060	11210	11267	11357
	Avg.	Time(s)	74.5	94.2	94.3	90.6	71.2	76.7	78.7	78.3	75.3	78.6	80.5	353.4	371.1	378.7	281	271.9	302.7	282.7	284.7	284.6	282.8	302.2	1038.6	951.4	946.7	737.3	9.707	723.5	736.5	744.7	804.7	823.9	765.2	1650.7	1700.1	1565.7	1530.1	1660.8	1503.3	1568.9	1678.1	1563.2	1394.3
ILS	Avg.		7622.5	7443.6	7491	7445.8	7576	7596.3	7643	7560	7410	7429	7243	8629.2	8629.7	8648	8868.5	8916.6	8962.8	8905.8	8970.4	8.6806	8924.2	9052.6	9931	9914.5	9944	10048.9	10057.2	10150	10071.3	10100	10117.6	10159.8	10051.9	10885.5	10845.8	10868.8	10885.1	10964.9	10996.5	11089.5	11244.6	11312.3	11372
	Best		7622	7424	7491	7434	7576	7596	7643	7560	7410	7429	7241	8624	8628	8646	8853	8910	8936	8891	8969	9028	8923	9031	6066	2066	9917	10035	10040	10141	10052	10080	10096	10115	10038	10866	10831	10849	10871	10934	10960	11064	11211	11267	11347
Exact			7622	7424	7491	7434	7576	7596	7643	7560	7410	7429	7241	8624	8628	8646	8853	8910	8936	8891	8968	9028	8923	9028	9904	9888	9917	10021	10029	10131	10052	10080	10095	10096	10014	10866	10831	10847	10859	10934	10960	11042	11194	11252	11321
	m		4	3	8	က	4	4	4	4	4	4	4	3	က	က	4	4	4	4	4	4	4	4	3	က	က	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
	Z		14	15	16	17	19	21	23	26	29	34	41	19	21	22	24	26	29	32	36	41	47	22	25	26	28	31	33	37	41	46	22	61	73	30	32	34	37	41	45	49	26	63	74
_	u		201	201	201	201	201	201	201	201	201	201	201	281	281	281	281	281	281	281	281	281	281	281	361	361	361	361	361	361	361	361	361	361	361	441	441	441	441	441	441	441	441	441	441
	Inst.		Golden 5	Golden 6	Golden 7	Golden 8																																							

Table 7: Detailed results, Golden 9–12.

	<u> </u>		Exact	ŗ	ILS		,	ILS-Clu		,	•	OHCS	Ė	Ē
r 	N,	E		pest	AVB.	Avg. Time(s)	Dest	Avg.	Avg. Time(s)	Dest	Avg.	Avg. Time(s)	Freproc.	Time(s)
256	2	4	300	300	300	142.3	300	300	22.7	300	300	15	(8)	179
256	0 1 6	4 4	299	299	299.3	135.3	299	299.4	22.	299	299	L5 16.1	157	173.1
256		4	296	296	296	144.7	296	296.3	21.9	296	296	17.6	133	150.6
256	22	4	290	290	291	141.9	290	291.1	21.3	290	290	18.2	138	156.2
256	• •	4	290	290	290.9	146.8	290	291.6	20.6	290	290	19.3	113	132.3
256	•	4	288	288	288.5	149.7	288	290.2	18.9	288	288	21.5	92	113.5
256	•	4	292	292	293.7	146.4	292	294.8	19.2	292	292	23.6	211	234.6
256	32	4	297	297	298	148.9	297	298.3	20.9	297	297	22.5	4	101.5
256	•••	4	294	294	294.7	149.5	294	294.5	21.1	294	294	25.9	89	93.9
256	43	4	295	295	296.2	156.8	296	296.9	22.8	295	295.8	31.6	59	90.6
256	52	4	296	297	298.6	166	297	298.2	56	297	297	31.6	33	64.6
324	22	4	367	367	368.6	331.3	369	369.9	31.2	367	367	30.3	230	260.3
324	24	4	361	361	362.5	319.4	361	362.2	28.7	361	361	31.6	175	206.6
324	25	4	359	329	360.4	322.4	359	360	29.3	359	359	31.9	173	204.9
324	27	4	361	361	362.1	329.9	361	362.6	29.9	361	361	33.4	168	201.4
324	30	4	367	367	368.8	350	368	369	30.6	367	367.1	40.6	145	185.6
324	33	4	373	375	376.6	352.8	376	377.2	31.1	373	374.2	37.7	125	162.7
324	36	4	385	387	387.7	338.6	387	388.9	29.3	385	385.2	42.1	144	186.1
324	41	4	400	401	402.4	330	400	401.9	29.7	400	400.2	51.8	83	134.8
324	47	4	398	399	400.1	339.3	399	400.1	31.6	398	398.1	52.7	74	126.7
324	54	4	393	395	396.9	336.3	394	395.3	34.9	393	393.6	54.5	72	126.5
324	65	4	387	387	391.7	355.7	390	392	40.9	387	387.9	75.5	62	137.5
400	27	10	457	457	458.1	596.1	458	459	42.4	457	457	38.3	238	313.5
400	29	IJ	455	455	457.8	586.6	456	458.8	42.7	455	455	44.5	222	222
400	31	ນ	455	455	457.1	615.1	457	459.1	42.2	455	455.4	49.8	217	217
400	34	IJ	455	456	457.4	648.9	457	458.7	40.8	455	455.2	49.6	188	188
400	37	IJ	459	460	461.8	693.7	461	462.6	41	459	459	49.9	163	163
400	40	v	461	462	463.8	677.7	463	463.5	41.3	461	461	48.4	142	180.3
400	45	rO	462	464	465.3	636.4	465	465.7	43.5	462	462.1	52.7	270	314.5
400	50	ນ	458	459	461.4	677.3	460	461.2	45.9	458	458.5	57.8	123	172.8
400	58	IJ	456	458	459.9	701.1	460	462	49.6	456	456.4	80.3	105	154.6
400	29	IJ	454	457	459.2	733.8	458	460.5	59.7	454	454.6	85.7	91	140.9
400	80	υ	451	455	457.2	676.3	456	458.6	29	451	451.7	8.86	63	111.4
484	33	IJ	535	535	538.1	1338.3	537	538.4	63	535	535	80.3	270	322.7
484	35	rO	537	537	538.4	1367.3	537	539.7	60.4	537	537	62.6	255	312.8
484	38	v	535	535	540	1327.9	537	540.5	61.9	535	535	70.3	231	311.3
484	41	v	537	539	542.5	1516.8	538	542.7	63.9	537	537	6.07	200	285.7
484	44	IJ	535	537	540.3	1406.3	540	542.2	62.4	535	535.8	87.4	194	292.8
484	49	IJ	533	537	538.3	1443	538	540.9	68.9	533	533.4	104	192	272.3
484	54	ಬ	535	537	540.2	1679.6	539	542.9	69.5	535	535.3	92.1	1656	1718.6
484	_	IJ	538	538	541.3	1453.1	539	544.8	72.7	535	535.2	89.4	152	222.3
484		ಬ	546	538	540	1519.4	540	543.6	80.5	533	533.5	104.4	131	201.9
484		v	546	541	543.4	1296.2	544	547.5	85.4	535	536	133.7	93	180.4
707	1	м	200	548	553	1275.5	548	554.5	105.9	544	544.7	139.6	21	160

Table 8: Detailed results, Golden 13–16.

8	χ	ş	Exact	D ₂₀	ILS	V	D to C	ILS-Clu	νν	Tool T	V	UHGS	Danaga	Lo+0-L
2	A 7	311		Dear	.00	Time(s)	Dear	0 V	Time(s)	Pes	.0 ^.0	Time(s)	(s)	Time(s)
253	3 17	4	552	552	552	144.7	552	553.8	21	552	552	15.8	159	251.1
253	3 19	4	549	549	549.1	138.4	551	551.3	20.7	549	549	16.4	128	217.4
253		4	548	548	548.3	140.9	548	549.5	19.7	548	548	17.9	127	231.4
253		4	548	548	548.4	141.2	549	549.5	20.5	548	548	20.3	110	243.7
253	3 23	4	548	548	548.5	138.5	548	549.1	20.1	548	548	19.6	107	246.6
253		4	542	542	542.1	146.6	542	542.6	20.2	542	542	20.4	94	109.8
253		4	540	540	540.3	147.7	540	540.9	21.3	540	540	21.8	218	234.4
253	32	4	543	543	543.7	145.7	544	544.9	21.3	543	543	23.7	72	89.9
253	3 37	4	545	546	547.9	147.4	546	548.8	21.7	545	545.2	33.7	54	74.3
253	3 43	4	553	554	555.1	146.4	554	555.6	25.3	553	553	29.2	44	63.6
253	5 51	4	260	561	562.1	164.9	561	563	28.6	260	560.4	37.9	29	49.4
321	22	4	692	692	692.8	320.7	693	695	35.4	692	692	25.6	214	235.8
321		4	889	889	688.3	330.6	889	689.7	32.2	688	889	27.3	181	204.7
321		4	678	849	679.1	317.3	629	089	31.2	818	818	29	169	202.7
321		4	676	949	677.6	317.3	676	678.6	31.1	676	676	29.3	147	176.2
321		4	678	089	680.5	319.3	682	682.3	30.5	818	818	32.2	128	165.9
321	. 33	4	682	682	683.6	341.5	684	685.3	31	682	682	32.9	118	143.6
321	36	4	687	687	688.3	349.3	889	689.5	33	687	687	33.7	163	190.3
321		4	069	691	692.4	339.7	691	692.9	33.7	069	690.1	50.2	83	112
321	46	4	694	269	869	352	269	669	34.1	694	695.7	48.5	65	94.3
321	54	4	669	701	703	339	703	704.2	38.2	669	700.1	52.7	53	85.2
321	. 65	4	703	703	706.3	342.7	704	705.9	47	703	703	28	37	6.69
397	7 27	4	842	844	844.2	728.5	844	846.3	54.9	842	842	47.5	244	277.7
397	, 29	4	843	844	846.4	736.6	845	849.2	52.2	843	843.4	52.5	218	268.2
397	, 31	4	837	839	840.9	742.7	841	843.3	48.5	837	837.1	49.3	203	251.5
397	34	4	838	842	844.2	755.2	844	846.6	48.2	838	838.5	72.4	169	221.7
397	, 37	4	845	848	850.1	739.6	848	853.5	48.5	845	845.2	51.6	152	210
397	7 40	4	849	849	851.9	744.5	850	853	50	849	849.2	65.3	141	188.5
397		70	853	856	857.8	655.4	855	858.4	45.5	853	853.1	58.5	1033	1085.5
397		IJ	851	854	855.7	710.7	857	859	48.8	851	821.8	68.1	111	160.3
397	57	Ю	820	854	856.4	700.3	856	858.3	50.6	850	850.4	83.5	94	166.4
397		D	855	857	862.1	685.4	861	862.9	57.2	857	857.3	82.9	73	124.6
397		rO	857	863	864.3	648.1	862	864.2	6.07	858	859.6	94.3	51	116.3
481	. 33	70	1030	1030	1030	1268.8	1030	1031.2	67.7	1030	1030	54.7	296	354.5
481	. 35	D	1028	1028	1029.4	1238	1028	1030.6	65.5	1028	1028	59.5	251	319.1
481	37	D	1028	1028	1029	1288.6	1028	1029.7	63.1	1028	1028	6.09	238	321.5
481	. 41	Ю	1032	1033	1034.3	1329.9	1033	1034.6	64.8	1032	1032	60.1	199	281.9
481	44	D	1028	1029	1031.2	1297	1032	1033.3	64.6	1028	1028	63.8	179	273.3
481	. 49	ъ	1031	1033	1034.6	1264.7	1034	1036	65.4	1031	1031	71.2	161	215.7
481	. 54	ъ	1022	1024	1026	1505.4	1027	1028.8	69.2	1022	1022	83.9	214	273.5
Golden 16 481	. 61	rO	1013	1015	1018.7	1498.7	1022	1023.1	74	1013	1013.8	94.7	143	203.9
481	69	Ŋ	1012	1015	1017.7	1525.2	1020	1020.8	79.4	1012	1012.3	114.5	120	180.1
481		IJ	1018	1019	1023.7	1312	1023	1026.5	93.2	1018	1018	105.3	94	157.8
107	1	ы	1018	1093	10971	1958 1	1007	1000	110 0	1018	1090	0	1	000

Table 9: Detailed results, Golden 17–20.

	Total	Time(s)	292.9	286.7	286.5	267.3	313.8	126.4	98.2	8.06	73	56.1	53.9	351.9	321	316	253.6	191.3	158	134.5	123	101.5	77.3	75.8	9.989	553.1	424.5	331.6	249.4	160.8	136.9	151.1	157.6	128.3	109.1	857.1	573.7	486.9	442.4	327.2	230	7.86	229.2	247.1	231	145.8
	Preproc.	(s)	209	192	172	162	155	111	81	73	53	36	32	329	300	294	229	164	136	112	100	77	51	47	209	519	389	288	201	147	123	116	109	822	71	821	536	444	394	260	209	78	207	203	186	26
UHGS	Avg.	Time(s)	15.4	17.2	17.8	20	20.1	21.9	22.9	21	22	24.6	27.3	22	22.5	23	24.5	26.3	28.8	29.6	34.1	35.5	43.6	48.4	13.8	13.9	35.1	48.6	43.3	38.1	36.1	37.7	42.9	48.4	67.2	21	20.7	22.2	44.1	45	48.8	60.1	55.9	62.4	71.5	93.9
	Avg.		418	419	422	425	424	418	414	421	417	412	414	592	594	592	290	577	578	582	586	594	601	599	925	924	808	811.2	797	799	789	788	800	807	810.1	1220	1232	1208	1059	1052	1052	1053	1058	1058	1059	1049
_	Best		418	419	422	425	424	418	414	421	417	412	414	592	594	592	290	577	873	582	586	594	601	299	925	924	808	811	797	799	789	788	800	807	810	1220	1232	1208	1059	1052	1052	1053	1058	1058	1059	1049
	Avg.	Time(s)	32.3	30.9	31	30.2	31.3	25.9	25	20.9	20.8	23.8	27	41.1	39	41.2	36	35.6	35.3	34.2	35.6	36	39.4	43.8	55.1	52.2	63.3	56.7	51.4	46.3	45.6	44.3	47.5	51.6	62.7	74	73.8	68.3	85.5	78.3	73.7	73.4	75.6	76.1	83.5	91.3
ILS-Clu	Avg.		418.1	419	422	425	424.1	418.4	414	421.3	417.4	412	414.7	593.6	595.6	593.7	590.9	577.4	578.7	582.1	587	594.5	601.9	600.1	926.4	925.2	810.2	813	798.3	800.4	789	788	800.2	802.8	812.1	1226.1	1237.2	1212.9	1064.8	1054.5	1055.6	1056	1061.1	1061.1	1061.1	1051.5
	Best		418	419	422	425	424	418	414	421	417	412	414	592	594	592	290	577	578	582	586	594	601	299	926	924	809	812	797	799	789	788	800	807	811	1221	1235	1212	1060	1052	1053	1055	1060	1060	1059	1050
	Avg.	Time(s)	177.8	176.2	169.4	171.1	179.5	173.3	165.3	132	135.9	134.7	138.5	304.1	318.3	323.4	319.6	317.9	302.2	305.7	301.8	303.5	309.5	299.5	342.5	335.9	658.1	597.7	609.5	539.1	532.6	529.3	536.6	521.5	553.6	529	506.2	490.5	1045.9	1083	1034.2	1038.1	834	1050.4	1049.1	1086.5
ILS	Avg.		418	419	422	425	424	418	414	421.1	417.1	412.1	414.1	592	594	592.1	590	577	578	582.1	587.3	594.8	601.9	599.6	925	924	808.6	812	798.3	6.662	789	788	800	808.6	812.5	1220	1232.1	1208.2	1062	1053.2	1053.8	1055.2	1059.8	1059.7	1060.4	1052
_	Best		418	419	422	425	424	418	414	421	417	412	414	592	594	592	290	577	578	582	587	594	601	299	925	924	808	811	797	799	789	788	800	807	811	1220	1232	1208	1060	1052	1052	1054	1058	1058	1059	1050
Exact			418	419	422	425	424	418	414	421	417	412	414	592	594	262	290	577	842	582	586	594	601	299	925	924	808	811	797	799	789	788	800	807	810	1220	1232	1208	1059	1052	1052	1053	1058	1058	1049	1049
	u		က	33	က	33	က	က	3	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	10	10	4	4	4	ъ	IJ	n	20	ъ	20	11	12	12	ъ	ы	IJ	ro	20	rO	ы	2
	Z		17	18	19	21	22	25	27	31	35	41	49	21	22	24	26	28	31	34	38	43	51	61	25	26	28	31	33	37	41	46	22	61	73	29	31	33	36	39	43	47	53	61	71	85
	u		241	241	241	241	241	241	241	241	241	241	241	301	301	301	301	301	301	301	301	301	301	301	361	361	361	361	361	361	361	361	361	361	361	421	421	421	421	421	421	421	421	421	421	421
	Inst.		Golden 17	Golden 18	Golden 19	Golden 20																																								

Table 10: Detailed results, GVRP2

	Total	Time(s)	239.9	12.2	26.8	31.4	8.76
	Preproc.	(s)	6	က	4	4	œ
UHGS	Avg.	Time(s)	230.9	9.2	22.8	27.4	8.68
	Avg.		3711	642	808.3	817.6	964.2
	Best		8698	642	807	816	096
	Avg.	Time(s)	8.99	8.5	16.3	21.8	35.6
ILS-Clu	Avg.		3718	642	807	816	961.4
	Best		3709	642	807	816	955
	Avg.	Time(s)	127.1	5.1	15.7	22.2	54.3
ILS	Avg.		3749.6	642	809.2	817.5	971.6
	Sest		136	642	807	816	965
	Й		(7)				
Exact	Ď —		- 3		807	816	994
Exact	m B		12 - 3		4 807	6 816	8 994
Exact	_		- -		61 4 807	76 6 816	100 8 994
Exact	_		- -	51 5 642	121 61 4 807	9 92	00

Table 11: Detailed results, GVRP3

	Total	Time(s)	9.06	15.3	26.8	30.4	40.1
	Preproc.	(s)	21	œ	6	12	16
OHGS	Avg.	Time(s)	9.69	7.3	17.8	18.4	24.1
	Avg.		3293.2	607	691	804	806
	Best		3290	607	691	804	806
	Avg.	Time(s)	40.2	7.1	12.6	16.2	24.4
ILS-Clu	Avg.		3291.8	607	691	804	806
	Best		3290	607	691	804	806
	Avg.	Time(s)	128	7.4	14.3	29.5	59.5
ILS	Avg.		3305.9	607	695.4	804	806
	Best		3294	607	694	804	806
Exact			3596	607	691	804	806
_	 u		6	4	က	4	9
	N		88	34	41	51	29
	n N		262 88	101 34	121 41		

Table 12: Detailed results, Li

	Total	Time(s)	283.9	290.8	519.6	642.5	427.2	626.8	524.8	846.7	805.6	994.6	963.9	0 600
	Preproc.	(s)	200	196	265	327	284	263	302	402	290	440	397	411
UHGS	Avg.	Time(s)	83.9	94.8	254.6	315.5	143.2	363.8	222.8	444.7	515.6	554.6	566.9	0 000
	Avg.		27963	29055.6	21330.9	24557.4	35169.6	27307.7	37871.4	30580.2	32717.1	35919.1	38687.8	41400 7
	Best		27962	29051	21243	24486	35166	27238	37859	30483	32656	35885	38669	11181
	Avg.	Time(s)	122.7	123	240.8	330	242.6	457.8	298.3	571.3	742.6	843.5	1187.2	1 260 0
ILS-Clu	Avg.		27997.1	29077.6	21435.3	24664.5	35182.9	27362.8	37871.3	30665.7	32888.3	36044.6	38785.8	416000
	Best		27970	29063	21365	24578	35175	27284	37860	30568	32763	35976	38727	41569
	Avg.	Time(s)	714.6	783.6	2930.2	4444.1	1669.5	7422.5	1881.6	10824.4	14578.7	20634.3	22831.5	0 00000
ILS	Avg.		28079.7	29111.8	21515.2	24834.4	35206.7	27482.7	37895	30766.5	32958	36083	38749	41691 0
	Best		27962	29087	21368	24777	35190	27350	37878	30637	32873	35991	38690	11504
	ш		39	62	10	11	78	11	98	11	11	11	11	Ξ
	Z		113	121	129	145	153	161	169	177	193	209	225	170
_	u		260	009	640	720	092	800	840	880	096	1040	1120	1.900
	Inst.	_	Li	Ę	Ľ	Ľ	Ľ	Ľ	Ľ	Ľ	Ľ	Ľ	Ľ	