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Conservative-dissipative approximation schemes for a generalized Kramers equation

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We propose three new discrete variational schemes that capture the conservative-dissipative structure of a generalized Kramers equation. The first two schemes are single-step minimization schemes while the third one combines a streaming and a minimization step. The cost functionals in the schemes are inspired by the rate functional in the Freidlin-Wentzell theory of large deviations for the underlying stochastic system. We prove that all three schemes converge to the solution of the generalized Kramers equation. Copyright © 2009 John Wiley & Sons, Ltd.

Keywords: Kramers equation, Gradient flows, Hamiltonian flows, variational principle, optimal transport.

1. Introduction

1.1. The Kramers equation

In this paper we discuss the variational structure of a generalized *Kramers equation*,

$$\partial_t \rho = -\operatorname{div}_q \rho \frac{p}{m} + \operatorname{div}_p \rho \nabla_q V + \gamma \operatorname{div}_p \rho \nabla_p F + \gamma k T \Delta_p \rho, \quad \text{in } \mathbf{R}^{2d} \times \mathbf{R}^+, \quad (1)$$

which is the Fokker-Planck or Forward Kolmogorov equation of the stochastic differential equation

$$dQ(t) = \frac{P(t)}{m} dt, \quad (2a)$$

$$dP(t) = -\nabla V(Q(t)) dt - \gamma \nabla F(P(t)) dt + \sqrt{2\gamma k T} dW(t). \quad (2b)$$

The system (2) describes the movement of a particle at position Q and with momentum P under the influence of three forces. One force is the derivative $-\nabla V$ of a background potential $V = V(Q)$, the second is a friction force $-\gamma \nabla F(P)$, and the third is a stochastic perturbation generated by a Wiener process W . The parameter $m > 0$ is the mass of the particle (so that the velocity is P/m), γ is a friction parameter, k is the Boltzmann constant, and T is the temperature of the noise. A common choice for F is $F(P) = P^2/2m$, which results in a linear friction force.

For a stochastic particle given by (2), $\rho = \rho(t, q, p)$ characterizes the probability of finding the particle at time t at position q and with momentum p . Equation (1) characterizes the evolution of this probability density over time. The three deterministic drift terms in (2) lead to convection terms in (1), and the noise results in the final term in (1). We use the notation div_q and similar to indicate that the differential operator acts only on one variable.

Both equations describe the behaviour of a *Brownian particle with inertia* [5], such as which is large enough to be distinguished from the molecules in the surrounding solvent, but small enough to show random behaviour arising from collisions with those same molecules. Both the friction force and the noise term arise from collisions with the solvent, and the parameter γ

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characterizes the intensity of these collisions. The parameter kT measures the mean kinetic energy of the solvent molecules, and therefore characterizes the magnitude of the collision noise. A major application of this system is as a simplified model for chemical reactions, and it is in this context that Kramers originally introduced it [21].

The aim of this paper is to discuss variational formulations for equation (1). The theory of such variational structures took off with the introduction of Wasserstein gradient flows by [19, 20] and of the energetic approach to rate-independent processes [23, 22]. Both have changed the theory of evolution equations in many ways. If a given evolution equation has such a variational structure, then this property gives strong restrictions on the type of behaviour of such a system, provides general methods for proving well-posedness [3] and characterizing large-time behaviour (e.g., [6]), gives rise to natural numerical discretizations (e.g., [15]), and creates handles for the analysis of singular limits (e.g., [26, 27, 4]). Because of this wide range of tools, the study of variational structure has important consequences for the analysis of an evolution equation.

Remark 1.1 *A brief word about dimensions. We make the unusual choice of preserving the dimensional form of the equations, because the explicit constants help in identifying the modelling origin and roles of the different terms and effects, and these aspects are central to this paper. Therefore Q and q are expressed in m, P and p in kg m/s, m in kg, V , F , and kT in J, and γ in kg/s. The density ρ has dimensions such that $\int \rho$ is dimensionless. This setup implies that the Wiener process has dimension \sqrt{s} , in accordance with the formal property $dW^2 = dt$.*

1.2. Variational evolution

To avoid confusion between the Boltzmann constant and the integer k , from now on we define $\beta^{-1} := kT$. The authors of [20] studied an equation that can be seen as a simpler, spatially homogeneous case of (1), where $\rho = \rho(t, p)$:

$$\partial_t \rho = \gamma \beta^{-1} \Delta_p \rho + \gamma \operatorname{div}_p \rho \nabla_p F. \quad (3)$$

They showed that this equation is a gradient flow of the free energy

$$\mathcal{A}_p(\rho) := \int_{\mathbb{R}^d} [\rho F + \beta^{-1} \rho \log \rho] dp$$

with respect to the Wasserstein metric. This statement can be made precise in a variety of different ways (see [3] for a thorough treatment of this subject); for the purpose of this paper the most useful one is that the solution $t \mapsto \rho(t, p)$ can be approximated by the time-discrete sequence ρ_k defined recursively by

$$\rho_k \in \operatorname{argmin}_\rho K_h(\rho, \rho_{k-1}), \quad K_h(\rho, \rho_{k-1}) := \frac{1}{2h} \frac{1}{\gamma} d(\rho, \rho_{k-1})^2 + \mathcal{A}_p(\rho). \quad (4)$$

Here d is the Wasserstein distance between two probability measures $\rho_0(x)dx$ and $\rho(y)dy$ with finite second moment,

$$d(\rho_0, \rho)^2 := \inf_{P \in \Gamma(\rho_0, \rho)} \int_{\mathbb{R}^d \times \mathbb{R}^d} |x - y|^2 P(dx dy),$$

where $\Gamma(\rho_0, \rho)$ is the set of all probability measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals ρ_0 and ρ ,

$$\Gamma(\rho_0, \rho) = \{P \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d) : P(A \times \mathbb{R}^d) = \rho_0(A), P(\mathbb{R}^d \times A) = \rho(A) \text{ for all Borel subsets } A \subset \mathbb{R}^d\}. \quad (5)$$

A consequence of this gradient-flow structure is that \mathcal{A}_p decreases along solutions of (3).

Unfortunately, a convincing generalization of this gradient-flow concept and corresponding theory to equations such as the Kramers equation is still lacking. This is related to the mixture of both dissipative and conservative effects in these equations, which we now explain.

1.3. A combination of conservative and dissipative effects

The full Kramers equation (1) is a mixture of the dissipative behaviour described by (3) and a Hamiltonian, conservative behaviour. The conservative behaviour can be recognized by setting $\gamma = 0$, thus discarding the last two terms in (2); what remains in (2) is a deterministic Hamiltonian system with Hamiltonian energy $H(q, p) = p^2/2m + V(q)$. The evolution of this system is reversible and conserves H . Correspondingly, the evolution of (1) with $\gamma = 0$ also is reversible and conserves the expectation of H ,

$$\mathcal{H}(\rho) := \int_{\mathbb{R}^{2d}} \rho(q, p) H(q, p) dq dp.$$

On the other hand, as suggested by the discussion in the previous section, the γ -dependent terms represent dissipative effects. In the variational schemes that we define below, a central role is played by the (q, p) -dependent analogue of \mathcal{A}_p ,

$$\mathcal{A}(\rho) := \int_{\mathbb{R}^{2d}} [\rho(q, p) F(p) + \beta^{-1} \rho(q, p) \log \rho(q, p)] dq dp.$$

Because of the special structure of (1), the functional \mathcal{A} does not decrease along solutions, but in the particular case $F(\rho) := \rho^2/2m$, a ‘total free energy’ functional does: setting

$$\mathcal{E}(\rho) := \mathcal{A}(\rho) + \int \rho V dqd\rho = \int [H + \beta^{-1} \log \rho] \rho dqd\rho,$$

we calculate that

$$\partial_t \mathcal{E}(\rho(t)) = -\gamma \int_{\mathbf{R}^{2d}} \frac{1}{\rho(t, q, p)} \left| \rho(t, q, p) \frac{p}{m} + \beta^{-1} \nabla_p \rho(t, q, p) \right|^2 dqd\rho \leq 0. \tag{6}$$

The choice $F(\rho) = \rho^2/2m$ is related to the fluctuation-dissipation theorem, and we comment on this in Section 1.7.

Because of the conservative, Hamiltonian terms, equation (1) is not a gradient flow, and an approach such as [20] is not possible. In 2000 Huang [17] proposed a variational scheme that is inspired by [20], but modified to account for the conservative effects, and in this paper we describe three more variational schemes for the same equation.

1.4. Huang’s discrete schemes for the Kramers equation

The time-discrete variational schemes of Huang’s and of this paper are best understood through the connection between *gradient flows* on one hand and *large deviations* on the other. We have recently shown this connection for a number of systems [1, 25, 12, 13, 14], including (3).

The philosophy can be formulated in a number of ways, and here we choose a perspective based on the behaviour of a single particle. We start with the simpler case of equation (3) and the discrete approximation (4). Let $\{X_\epsilon\}_{\epsilon>0}$ be a rescaled d -dimensional Wiener process,

$$dX_\epsilon(t) = \sqrt{2\sigma\epsilon} dW(t), \tag{7}$$

where σ is a mobility coefficient. If we fix $h > 0$, then by Schilder’s theorem (e.g. [11, Th. 5.2.3]), the process $\{X_\epsilon(t) : t \in [0, h]\}$ satisfies a large-deviation principle

$$\text{Prob}(X_\epsilon(\cdot) \approx \xi(\cdot)) \sim \exp\left[-\frac{1}{\epsilon} I(\xi)\right], \quad \text{as } \epsilon \rightarrow 0,$$

where the *rate functional* $I : C([0, h]; \mathbf{R}^d) \rightarrow \mathbf{R} \cup \{+\infty\}$ is given by

$$I(\xi) = \frac{1}{4\sigma} \int_0^h |\dot{\xi}(t)|^2 dt.$$

The Wasserstein cost function $|x - y|^2$ can be written in terms of I as

$$|x - y|^2 = 4h\sigma \inf \left\{ I(\xi) : \xi \in C^1([0, h], \mathbf{R}^d) \text{ such that } \xi(0) = x, \xi(h) = y \right\}. \tag{8}$$

Hence the cost $|x - y|^2$ can be interpreted as the the probability that a Brownian particle goes from x to y in time h , in the sense of large deviations, and rescaled as to be independent of the magnitude of the noise σ .

The results of [1, 25, 13] concern a similar large-deviation analysis, but now for the empirical measure of a large number n of particles. For this system the limit $n \rightarrow \infty$ plays a role similar to $\epsilon \rightarrow 0$ in the example above. In [1, 25, 13], it is shown that this rate functional is very similar to the right-hand side of (4) in the limit $h \rightarrow 0$. This result explains the strong connection between large deviations on one hand and the gradient-flow structure on the other.

However, the core of the argument of [1, 25, 13] is contained in the Schilder example (7) and its connection (8) to the Wasserstein cost. Hence we use this simpler point of view to generalize the approximation scheme (4) to the Kramers equation. There are two different ways of doing this.

Approach 1 [17]. Instead of the inertia-less Brownian particle given by (7), we consider a particle with inertia satisfying

$$dQ_\epsilon(t) = \frac{P_\epsilon(t)}{m} dt, \tag{9a}$$

$$dP_\epsilon(t) = \sqrt{2\epsilon\gamma\beta^{-1}} dW(t), \tag{9b}$$

which can formally also be written as

$$m \frac{d^2}{dt^2} Q_\epsilon(t) = \sqrt{2\gamma\beta^{-1}\epsilon} \frac{dW}{dt}(t).$$

By the Freidlin-Wentzell theorem (e.g. [11, Th. 5.6.3]), the process $Q_\epsilon(t)$ satisfies a similar large-deviation principle with rate functional $\bar{I} : C([0, h], \mathbf{R}^d) \rightarrow \mathbf{R} \cup \{+\infty\}$ given by

$$\bar{I}(\xi) = \frac{1}{4\gamma\beta^{-1}} \int_0^h |m\ddot{\xi}(t)|^2 dt.$$

The comparison with (8) suggests to define a cost functional $\bar{C}_h(q, p; q', p')$ in a similar way, i.e.,

$$\begin{aligned} \bar{C}_h(q, p; q', p') &:= h \inf \left\{ \int_0^h |m\dot{\xi}(t)|^2 dt : \xi \in C^1([0, h], \mathbf{R}^d) \text{ such that} \right. \\ &\quad \left. (\xi, m\dot{\xi})(0) = (q, p), (\xi, m\dot{\xi})(h) = (q', p') \right\} \\ &= |p' - p|^2 + 12 \left| \frac{m}{h}(q' - q) - \frac{p' + p}{2} \right|^2. \end{aligned} \tag{10}$$

The second formula follows from an explicit calculation of the minimizer. As above, the interpretation is that of the probabilistic ‘cost’, that is, the large-deviations characterization of the probability of a path of (9) connecting (q, p) to (q', p') over time h . Note that \bar{C}_h is not a metric, since it is not symmetric, and also $\bar{C}_h(q, p; q, p) = 12|p|^2$ generally does not vanish. Therefore the Wasserstein ‘distance’ \bar{W}_h defined with \bar{C}_h as cost is not a metric, but only an optimal-transport cost (see [28] for an exposition on the theory of optimal transportation).

Huang then defines the approximation scheme as

Scheme 1 [17]. Given a previous state ρ_{k-1}^h , define ρ_k^h as the solution of the minimization problem

$$\min_{\rho} \frac{1}{2h} \bar{W}_h(\rho_{k-1}^h, \rho) + \mathcal{A}(\rho) + \frac{2m}{\gamma h} \int_{\mathbf{R}^{2d}} \rho(q, p) V(q) dq dp, \tag{11}$$

where \bar{W}_h is the optimal-transport cost on \mathbf{R}^{2d} with cost function \bar{C}_h .

Huang proves [17, 18] that the approximations generated by this scheme indeed converge to the solution of (1) as $h \rightarrow 0$.

1.5. Criticism

Although Scheme 1 is approximately of similar form to (4), there are in fact important issues with this scheme:

1. In (1), the dissipative effects are represented by the terms prefixed by γ , and the conservative effects by the the Hamiltonian terms $\text{div}_q \rho p / m$ and $\text{div}_p \rho \nabla V$. It would be natural to see these effects play separate roles in the variational formulation. However, in Scheme 1 the effects are mixed, since the final term in (11) mixes conservative effects (represented by V and m) with dissipative effects (the prefactor γ , and the role as driving force in a gradient-flow-type minimization).
2. The dependence on h of the final term in (11) adds to the confusion; since this parameter is an approximation parameter chosen independently from the actual system, the combination $\mathcal{A} + 2m/\gamma h \int \rho V$ can not be considered a single driving potential.
3. In fact, in the standard case $F(p) = p^2/2m$ the sum of \mathcal{A} and $\int \rho V$ is a natural object, since it represents total free energy and decreases along solutions (see Section 1.3). Note how the coefficient in this sum is 1 instead of $2m/\gamma h$.

The way in which V appears in Scheme 1 can be traced back to the fact that of the two conservative terms in (1) and (2), only P/m is represented in the definition of the cost \bar{C}_h , in the right-hand side of (9a); the term ∇V is missing in (9). Therefore the scheme has to compensate for the other term ∇V in a different manner.

These arguments lead us to pose the following question, which is the central topic of this paper:

Can we construct an approximation scheme that respects the conservative-dissipative split?

The answer is ‘yes’, and in the rest of this paper we explain how; in fact we detail three different schemes, corresponding to different ways of answering this question.

1.6. The schemes of this paper

We take a different approach than Huang did.

Approach 2. To set up a new cost functional, we first return to the single-particle point of view, as in (7) and (9). We now take a particle whose behaviour is a combination of the two Hamiltonian terms in (2) and a noise term:

$$dQ_\epsilon(t) = \frac{P_\epsilon(t)}{m} dt, \tag{12a}$$

$$dP_\epsilon(t) = -\nabla V(Q_\epsilon) dt + \sqrt{2\gamma\beta^{-1}\epsilon} dW(t), \tag{12b}$$

which again can formally be written as

$$m \frac{d^2}{dt^2} Q_\epsilon(t) + \nabla V(Q_\epsilon(t)) = \sqrt{2\gamma\beta^{-1}\epsilon} \frac{dW}{dt}(t).$$

Note how this system differs from (9) by the term involving ∇V in (12b).

A very similar application of the Freidlin-Wentzell theorem states that Q_ϵ satisfies a large-deviation principle as $\epsilon \rightarrow 0$ with rate function

$$\tilde{I}(\xi) = \frac{1}{4\gamma\beta^{-1}} \int_0^h |m\dot{\xi}(t) + \nabla V(\xi(t))|^2 dt.$$

This leads to the following scheme.

Scheme 2a. We define the cost to be

$$\begin{aligned} \tilde{C}_h(q, p; q', p') := h \inf \left\{ \int_0^h |m\dot{\xi}(t) + \nabla V(\xi(t))|^2 dt : \xi \in C^1([0, h], \mathbf{R}^d) \text{ such that} \right. \\ \left. (\xi, m\dot{\xi})(0) = (q, p), (\xi, m\dot{\xi})(h) = (q', p') \right\}. \end{aligned} \quad (13)$$

Given a previous state ρ_{k-1}^h , define ρ_k^h as the solution of the minimization problem

$$\min_{\rho} \frac{1}{2h} \frac{1}{\gamma} \tilde{W}_h(\rho_{k-1}^h, \rho) + \mathcal{A}(\rho), \quad (14)$$

where \tilde{W}_h is the optimal-transport cost on \mathbf{R}^{2d} with cost function \tilde{C}_h .

Note how now the term involving V has disappeared from the minimization problem (14). In Sections 4–6 we show that this approximation scheme converges to the solution of (1) as $h \rightarrow 0$.

For practical purposes it is inconvenient that the cost \tilde{C}_h in (13) has no explicit expression. It turns out that we may approximate \tilde{C}_h with an explicit expression and obtain the same limiting behaviour.

Scheme 2b. Define

$$\begin{aligned} \hat{C}_h(q, p; q', p') := h \inf \left\{ \int_0^h |m\dot{\xi}(t) + \nabla V(q)|^2 dt : (\xi, m\dot{\xi})(0) = (q, p), (\xi, m\dot{\xi})(h) = (q', p') \right\} \\ \stackrel{(10)}{=} |p' - p|^2 + 12 \left| \frac{m}{h}(q' - q) - \frac{p' + p}{2} \right|^2 + 2h(p' - p) \cdot \nabla V(q) + h^2 |\nabla V(q)|^2 \\ = |p' - p + h\nabla V(q)|^2 + 12 \left| \frac{m}{h}(q' - q) - \frac{p' + p}{2} \right|^2. \end{aligned} \quad (15)$$

Given a previous state ρ_{k-1}^h , define ρ_k^h as the solution of the minimization problem

$$\min_{\rho} \frac{1}{2h} \frac{1}{\gamma} \hat{W}_h(\rho_{k-1}^h, \rho) + \mathcal{A}(\rho), \quad (16)$$

where \hat{W}_h is the optimal-transport cost on \mathbf{R}^{2d} with cost function \hat{C}_h .

Note how \hat{C}_h differs from (13) in that $\xi(t)$ is replaced by q in ∇V . This approximation is exact when V is linear. We prove the convergence of solutions of Scheme 2b in Sections 4–6.

Neither of the costs \tilde{C}_h and \hat{C}_h gives rise to a metric, since they are asymmetric and do not vanish when $(q', p') = (q, p)$. It is possible to construct a two-step scheme with a symmetric cost and corresponding metric W_h .

Scheme 2c. Define

$$C_h(q, p; q', p') := |p' - p|^2 + 12 \left| \frac{m}{h}(q' - q) - \frac{p' - p}{2} \right|^2 + 2m(q' - q) \cdot (\nabla V(q') - \nabla V(q)). \quad (17)$$

Assume ρ_{k-1}^h is given, define the single-step, backwards approximate streaming operator

$$\sigma_h(q, p) := \left(q - h \frac{p}{m}, p + h \nabla V(q) \right). \quad (18)$$

Given a previous state ρ_{k-1}^h , define ρ_k^h in two steps.

Hamiltonian step: First determine $\mu_k^h(q, p)$ such that

$$\mu_k^h(q, p) := \sigma_h^{-1}(q, p) \# \rho_{k-1}^h(q, p), \quad (19)$$

where $\#$ denotes the push forward operator.

Gradient flow step: Then determine ρ_k^h that minimizes

$$\min_{\rho} \frac{1}{2h} \frac{1}{\gamma} W_h(\mu_k^h, \rho) + \mathcal{A}(\rho), \quad (20)$$

where W_h is the metric on \mathbf{R}^{2d} generated by the cost function C_h .

1.7. The main result and the relation to GENERIC

The main theorem of this paper, Theorem 2.4 below, states that the three new Schemes 2a-c are indeed approximation schemes for the Kramers equation (1): the discrete-time approximate solutions constructed using each of these three schemes converge, as $h \rightarrow 0$, to the unique solution of (1).

This statement itself is a relatively uninteresting assertion: it states that the schemes are what we claim them to be, approximation schemes. The interest of this paper lies in the fact that these three schemes suggest a way towards a generalization of the theory of metric-space gradient flows, as developed in [3], to equations like (1) that combine dissipative with conservative effects.

Indeed, the full class of equations and systems that combines dissipative and conservative effects is extremely large. It contains the Navier-Stokes-Fourier equations (which include heat generation and transport), systems modelling visco-elasto-plastic materials, relativistic hydrodynamics, many Boltzmann-type equations, and many other equations describing continuum-mechanical systems. In fact, the full class of systems covered by the GENERIC formalism [24] is of this conservative-dissipative type, and indeed the Kramers equation is one of them.

The GENERIC class (General Equation for the Non-Equilibrium Reversible Irreversible Coupling) consists of equations for an unknown x in a state space \mathcal{X} that can be written as

$$\dot{x}(t) = J(x)E'(x) + K(x)S'(x).$$

Here $E, S : \mathcal{X} \rightarrow \mathbf{R}$ are functionals, and J, K are operators. A GENERIC system is fully characterized by \mathcal{X}, E, S, J , and K . In addition, there are certain requirements on these elements, which include the *symmetry conditions*

$$J \text{ is antisymmetric} \quad \text{and} \quad K \text{ is symmetric and nonnegative,}$$

and the *degeneracy or non-interaction conditions*

$$J(x)S'(x) = 0, \quad K(x)E'(x) = 0, \quad \text{for all } x \in \mathcal{X}.$$

Because of these properties, along a solution E is constant and S increases. In many systems the functionals E and S correspond to *energy* and *entropy*.

When $F(p) = |p|^2/2m$, the Kramers equation (1) can be cast in this form.[†] Because of this, the results of this paper strongly suggest that similar schemes can be constructed for arbitrary GENERIC systems. We study this approach in a separate paper [14].

[†]In order to do this, the variable ρ needs to be supplemented with an additional energy variable, that compensates for the gain and loss in the energy \mathcal{H} as a result of the dissipative effects.

1.8. Conclusion and further discussion

We now make some further comments about the schemes of this paper.

Value of the three schemes. Scheme 2a is in our opinion interesting because ‘it is the right thing to do’—it stays as close as possible to the underlying physics. However, its non-explicit nature makes it difficult to work with, as the calculations in the proof of Lemma 3.1 illustrate. Scheme 2b is therefore useful as an approximation of Scheme 2a. Scheme 2c has the advantage of being formulated in terms of a metric W_h , which suggests applicability of metric-space theory.

Whichever scheme is chosen, the split between conservative and dissipative effects may lead to operator-splitting numerical methods that reflect the same division between conservative and dissipative effects [31]. Since conservative effects are often best treated by explicit or symplectic integration, while dissipative effects are better discretized using implicit schemes, this split allows for better tailoring of the method to the two steps.

Connections with large deviations. We motivated the choice of the cost \tilde{C}_h by drawing from the large-deviation behaviour of the single-particle SDE (12), in the limit of small noise. This is only a formal connection, and the question therefore remains whether a similar connection exists at the level of empirical measures $\rho_n = n^{-1} \sum_{i=1}^n \delta_{(Q_i, P_i)}$ of many i.i.d. copies of (2) on one hand and the schemes of this paper on the other. As we described in Section 1.4, for reversible systems we now know such connections to be deeply connected with gradient-flow structures.

The answer is affirmative. In more recent work [14] we have proved a large-deviations principle for this empirical measure, and indeed the rate functional for this system is closely connected with the cost of Scheme 2a, \tilde{C}_h , in the following way: the rate functional measures fluctuations in a norm that is the differential analogue of the pseudo-distance function \tilde{W}_h , which is based on \tilde{C}_h . In fact, one can view the approximations that we make in Schemes 2b and 2c as well-chosen reductions that are easier to calculate but generate the same differential structure as \tilde{W}_h .

The potential force ∇V . Throughout this paper, V appears only through its gradient in the Hamiltonian part of the equation. In Lemma 5.1 we use a property of the Hamiltonian system (68), that its solution $s_h(q, p)$ at time h is bijective and volume-preserving. The results of the paper still hold true if ∇V is replaced by a generic field $B: \mathbf{R}^d \rightarrow \mathbf{R}^d$ with appropriate regularity properties—for instance, if B satisfies the same conditions as ∇V and is such that s_h is bijective and its Jacobian is bounded from above by $1 + o(h)(|\gamma q|^2 + |p|^2)$. However, in this case the Hamiltonian part of the structure is lost, as is the GENERIC structure (see the previous section). Since our focus is on building schemes that mimic this structure, we do not pursue this avenue here.

The linear-friction case $F(p) = |p|^2/2m$. The coefficient γkT in (1) and the coefficient $\sigma := \sqrt{2\gamma kT}$ in (2b) are obviously related by $\sigma^2 = 2\gamma kT$. When $F(p) = |p|^2/2m$, the coefficient γ is also the coefficient of linear friction, and this relationship between σ , γ , and temperature is the one given by the fluctuation-dissipation theorem. This guarantees that the Boltzmann distribution

$$\rho_\infty(q, p) = Z^{-1} \exp\left(-\frac{1}{kT} H(q, p)\right), \tag{21}$$

is the unique stationary solution of (1). Moreover, the total free energy \mathcal{E} is the relative entropy with respect to ρ_∞ , and it is a Lyapunov functional for the system, as is shown in (6).

When F does not have this specific form, but does have appropriate growth at infinity, then there still exists a unique stationary solution ρ_∞ , which however does not have the convenient characterization (21). The relative entropy with respect to ρ_∞ is then again a Lyapunov functional.

Connection to ultra-parabolic equations. If V is linear, $V(q) = c \cdot q$, where $c \in \mathbf{R}^d$ is a constant vector, then \hat{C}_h coincides with \tilde{C}_h . In this case, $\tilde{C}_h = \hat{C}_h$ is closely related to the fundamental solution of the equation

$$\partial_t \rho(t, q, p) = -\frac{p}{m} \cdot \nabla_q \rho(t, q, p) + c \cdot \nabla_p \rho(t, q, p) + \frac{\sigma^2}{2} \Delta_p \rho(t, q, p). \tag{22}$$

Indeed, the fundamental solution $\Gamma_t(q, p; q', p')$ of (22) is given by

$$\Gamma_t(q, p; q', p') = \frac{\alpha_1}{t^{2d}} \exp\left(-\frac{\gamma}{\sigma^2 t} \hat{C}_t(q, p; q', p')\right), \tag{23}$$

where α_1 is a normalization constant depending only on d . This fact is true for a much more general linear system and is related to the *controllable* property of the system [10]. The appearance of the rate functional from the Freidlin-Wentzell theory in (23) consolidates the connection to the large deviation principle of our approach.

Connection to the isentropic Euler equations. The cost function \tilde{C}_h has been used in [16, 30] to study the system of isentropic Euler equations,

$$\begin{aligned} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) &= 0, \\ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} &= -\nabla U'(\rho), \end{aligned}$$

where $U: [0, \infty) \rightarrow \mathbf{R}$ is an internal energy density. We now formally show the relationship between two equations. Suppose that $\rho(t, q, p)$ is a solution of the Kramers equation (1) with $F(p) = |p|^2/2m$. We define the macroscopic spatial density and

the bulk velocity as

$$\tilde{\rho}(t, q) = \int_{\mathbf{R}^d} \rho(t, q, p) dp, \tag{24}$$

$$\mathbf{u}(t, q) = \frac{1}{\tilde{\rho}(t, q)} \int_{\mathbf{R}^d} \frac{p}{m} \rho(t, q, p) dp. \tag{25}$$

Using the so-called moment method, we find that $(\tilde{\rho}, \mathbf{u})$ satisfies the following damped Euler equations [9, 7, 8],

$$\partial_t \tilde{\rho} + \nabla \cdot (\tilde{\rho} \mathbf{u}) = 0 \tag{26}$$

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{\beta^{-1}}{m} \frac{\nabla \tilde{\rho}}{\tilde{\rho}} - \frac{1}{m} \nabla V - \frac{\gamma}{m} \mathbf{u}. \tag{27}$$

If $\gamma = 0$ and $V \equiv 0$, these are the isentropic Euler equations with internal energy $U(\rho) = \beta^{-1} \rho \log \rho$. In [16, 30], the authors showed that the isentropic Euler equations may be interpreted as a second-order differential equation in the space of probability measures. They introduced a discrete approximation scheme, which is similar to Schemes 2a-b, using the cost functional \bar{C}_h . One future topic of research is to analyse whether one can approximate other second-order differential equations in the space of probability measures (e.g., the Schrödinger equation [29]), using the cost function \bar{C}_h .

Connection to Ambrosio-Gangbo [2]. The Hamiltonian step in Scheme 2c is a generalization of the implicit Euler method for a finite-dimensional Hamiltonian system to an infinite-dimensional case. It is also compatible with the concept of Hamiltonian flows in the Wasserstein space of probability measures defined by Ambrosio and Gangbo in [2]. Let $\mathcal{H}: \mathcal{P}_2(\mathbf{R}^{2d}) \rightarrow (-\infty, +\infty]$ and $\bar{\mu} \in \mathcal{P}_2(\mathbf{R}^{2d})$ be given. Then $\mu_t: [0, \infty) \rightarrow \mathcal{P}_2(\mathbf{R}^{2d})$ is called a Hamiltonian flow of \mathcal{H} with the initial measure $\bar{\mu}$ if the following equation holds

$$\frac{d}{dt} \mu_t = \operatorname{div}_{qp}(\mu_t J \nabla \mathcal{H}(\mu_t)), \quad \mu_0 = \bar{\mu}, \quad t \in (0, T),$$

where J is a skew-symmetric matrix and $\nabla \mathcal{H}(\mu_t)$ is the gradient of the Hamiltonian \mathcal{H} at μ_t (Definition 3.2 in [2]). In particular, when $\mathcal{H}(\rho) = \int_{\mathbf{R}^{2d}} \left(\frac{p^2}{2m} + V(q) \right) \rho(q, p) dq dp$ then $\nabla \mathcal{H} = (\nabla_q V(q), \frac{p}{m})^T$. According to Lemma 6.2 in [2] when $\bar{\mu}$ is regular, a Hamiltonian flow in a small interval $(0, h)$ is constructed by pushing forward the initial measure $\bar{\mu}$ under the map $\Phi(t, \cdot) = (q(t), p(t))$ which is the solution of the system (2) (with $\gamma = 0$). In the Hamiltonian step we approximate this system by the implicit Euler method and define μ_k^h to be the end point $\mu(h)$.

1.9. Overview of the paper

The paper is organized as follows. In Section 2, we describe our assumptions and state the main result. Section 3 establishes some properties of the three cost functions. The proof of the main theorem is given in Sections 4 to 6. In Section 4, we establish the Euler-Lagrange equations for the minimizers in three schemes. In Section 5, we prove the boundedness of the second moments and the entropy functional. Finally, the convergence result is given in Section 6.

2. Assumptions and main result

Throughout the paper we make the following assumptions.

$$V \in C^3(\mathbf{R}^d) \text{ and } F \in C^2(\mathbf{R}^d), \quad F(x) \geq 0 \text{ for all } x \in \mathbf{R}^d. \tag{28}$$

There exists a constant $C > 0$ such that for all $z_1, z_2 \in \mathbf{R}^d$

$$\frac{1}{C} |z_1 - z_2|^2 \leq (z_1 - z_2) \cdot (\nabla V(z_1) - \nabla V(z_2)), \tag{29a}$$

$$|\nabla V(z_1) - \nabla V(z_2)| \leq C |z_1 - z_2|, \tag{29b}$$

$$|\nabla F(z_1) - \nabla F(z_2)| \leq C |z_1 - z_2|, \tag{29c}$$

$$|\nabla^2 V(z_1)|, |\nabla^3 V(z_1)| \leq C. \tag{29d}$$

Note that (29a) implies that V increases quadratically at infinity, and therefore V achieves its minimum. Without loss of generality we assume that this minimum is at the origin, which implies the estimate

$$|\nabla V(z)| \leq C|z|. \tag{30}$$

Remark 2.1 *There is plenty of scope to relax these conditions. We do not do that here, since in this paper we focus on structure rather than generality; relaxing the conditions would hide the ideas behind technical issues.*

As we remarked in the Introduction, we work in the dimensional setting, and keep all the physical constants in place, in order to make the physical background of the expressions clear. We make an important exception, however, for inequalities of the type above; here the constants C can have any dimension, and we will group terms on the right-hand side of such estimates without taking their dimensions into account. This can be done without loss of generality, since we do not specify the generic constant C , and this constant will be allowed to vary from one expression to the next.

We only consider probability measures on \mathbf{R}^{2d} which have a Lebesgue density, and we often tacitly identify a probability measure with its density. We denote by $\mathcal{P}_2(\mathbf{R}^{2d})$ the set of all probability measures on $\mathbf{R}^d \times \mathbf{R}^d$ with finite second moment,

$$\mathcal{P}_2(\mathbf{R}^{2d}) := \left\{ \rho: \mathbf{R}^d \times \mathbf{R}^d \rightarrow [0, \infty) \text{ measurable, } \int_{\mathbf{R}^{2d}} \rho(q, p) dq dp = 1, M_2(\rho) < \infty \right\},$$

where

$$M_2(\rho) = \int_{\mathbf{R}^{2d}} (\gamma^2 |q|^2 + |p|^2) \rho(q, p) dq dp. \tag{31}$$

With these assumptions, the functionals \mathcal{A} and \mathcal{E} introduced in the introduction are well-defined in $\mathcal{P}_2(\mathbf{R}^{2d})$. Moreover, the following two lemmas are now classical (see, e.g., [28, Theorem 1.3], [20, Proposition 4.1], and [17, Lemma 4.2]). Let C_h^* be one of \widehat{C}_h , \widetilde{C}_h , or C_h , defined in (13), (15), and (17), with corresponding optimal-transport cost functional W_h^* .

Lemma 2.2 *Let $\rho_0, \rho \in \mathcal{P}_2(\mathbf{R}^{2d})$ be given. There exists a unique optimal plan $P_{\text{opt}}^* \in \Gamma(\rho_0, \rho)$ such that*

$$W_h^*(\rho_0, \rho) = \int_{\mathbf{R}^{4d}} C_h^*(q, p; q', p') P_{\text{opt}}^*(dq dp dq' dp'). \tag{32}$$

Lemma 2.3 *Let $\rho_0 \in \mathcal{P}_2(\mathbf{R}^{2d})$ be given. If h is small enough, then the minimization problem*

$$\min_{\rho \in \mathcal{P}_2(\mathbf{R}^{2d})} \frac{1}{2h} \frac{1}{\gamma} W_h^*(\rho_0, \rho) + \mathcal{A}(\rho), \tag{33}$$

has a unique solution.

These lemmas imply that Schemes 2a–c are well-defined.

Next, we make the definition of a weak solution precise. A function $\rho \in L^1(\mathbf{R}^+ \times \mathbf{R}^{2d})$ is called a weak solution of equation (1) with initial datum $\rho_0 \in \mathcal{P}_2(\mathbf{R}^{2d})$ if it satisfies the following weak formulation of (1):

$$\begin{aligned} \int_0^\infty \int_{\mathbf{R}^{2d}} \left[\partial_t \varphi + \frac{p}{m} \cdot \nabla_q \varphi - (\nabla_q V(q) + \gamma \nabla_p F(p)) \cdot \nabla_p \varphi + \gamma \beta^{-1} \Delta_p \varphi \right] \rho dq dp dt \\ = - \int_{\mathbf{R}^{2d}} \varphi(0, q, p) \rho_0(q, p) dq dp, \quad \text{for all } \varphi \in C_c^\infty(\mathbf{R} \times \mathbf{R}^{2d}). \end{aligned} \tag{34}$$

The main result of the paper is the following.

Theorem 2.4 *Let $\rho_0 \in \mathcal{P}_2(\mathbf{R}^{2d})$ satisfy $\mathcal{A}(\rho_0) < \infty$. For any $h > 0$ sufficiently small, let ρ_k^h be the sequence of the solutions of any of the three Schemes 2a–c. For any $t \geq 0$, define the piecewise-constant time interpolation*

$$\rho^h(t, q, p) = \rho_k^h(q, p) \quad \text{for } (k-1)h < t \leq kh. \tag{35}$$

Then for any $T > 0$,

$$\rho^h \rightharpoonup \rho \text{ weakly in } L^1((0, T) \times \mathbf{R}^{2d}) \text{ as } h \rightarrow 0, \tag{36}$$

where ρ is the unique weak solution of the Kramers equation with initial value ρ_0 . Moreover

$$\rho^h(t) \rightarrow \rho(t) \text{ weakly in } L^1(\mathbf{R}^{2d}) \text{ as } h \rightarrow 0 \text{ for any } t > 0, \tag{37}$$

and as $t \rightarrow 0$,

$$\rho(t) \rightarrow \rho_0 \text{ in } L^1(\mathbf{R}^{2d}). \tag{38}$$

Proof:[Outline of the proof] The proof follows the procedure of [20] (see also [17, 18]) and is divided into three main steps, which are carried out in Sections 4, 5, and 6: establish the Euler-Lagrange equation for the minimizers, then estimate the second moments and entropy functionals, and finally pass to the limit $h \rightarrow 0$. We start in Section 3 with some properties of the cost functions. \square

3. Properties of the three cost functions

Here we derive and summarize a number of properties of the three cost functions. Define the quadratic form

$$N(q, p) := |\gamma q|^2 + |p|^2,$$

so that $M_2(\rho) = \int_{\mathbb{R}^{2d}} N(q, p) \rho(q, p) dq dp$.

Lemma 3.1 1. Let C_h^* be either \tilde{C}_h or \hat{C}_h . There exists $C > 0$ such that

$$|q - q'|^2 + |p - p'|^2 \leq C C_h(q, p; q', p'), \quad (39a)$$

$$|q - q'|^2 \leq C h^2 [C_h^*(q, p; q', p') + N(q, p) + N(q', p')], \quad (39b)$$

$$|p - p'|^2 \leq C [C_h^*(q, p; q', p') + h^2 N(q, p) + h^2 N(q', p')]. \quad (39c)$$

2. For the cost function \tilde{C}_h of Scheme 2a we have

$$\nabla_{q'} \tilde{C}_h(q, p; q', p') = \frac{24m}{h} \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right) - 2h \nabla^2 V(q') \cdot p' + \sigma_h(q, p; q', p'), \quad (40a)$$

$$\nabla_{p'} \tilde{C}_h(q, p; q', p') = 2(p' - p) - 12 \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right) + 2h \nabla V(q') + \tau_h(q, p; q', p'), \quad (40b)$$

where there exists $C > 0$ such that

$$|\sigma_h(q, p; q', p')|, \frac{1}{h} |\tau_h(q, p; q', p')| \leq C h \left\{ \tilde{C}_h(q, p; q', p') + N(q, p) + N(q', p') + 1 \right\}. \quad (41)$$

3. For the cost function \hat{C}_h of Scheme 2b we have

$$\nabla_{q'} \hat{C}_h(q, p; q', p') = \frac{24m}{h} \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right), \quad (42a)$$

$$\nabla_{p'} \hat{C}_h(q, p; q', p') = 2(p' - p) - 12 \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right) + 2h \nabla V(q). \quad (42b)$$

4. For the cost function C_h of Scheme 2c we have

$$\nabla_{q'} C_h(q, p; q', p') = \frac{24m}{h} \left(\frac{m}{h}(q' - q) - \frac{p' - p}{2} \right) + 4m(\nabla V(q') - \nabla V(q)) + r(q, q'), \quad (43a)$$

$$\nabla_{p'} C_h(q, p; q', p') = 2(p' - p) - 12 \left(\frac{m}{h}(q' - q) - \frac{p' - p}{2} \right), \quad (43b)$$

where

$$|r(q, q')| \leq C h^2 [C_h(q, p; q', p') + N(q, p) + N(q', p')]. \quad (44)$$

Proof: For the length of this proof we fix q, p, q', p' , and h , and we abbreviate

$$\bar{C}_h := \bar{C}_h(q, p; q', p'), \quad \tilde{C}_h := \tilde{C}_h(q, p; q', p'), \quad \text{and} \quad N := N(q, p) + N(q', p') = |\gamma q|^2 + |p|^2 + |\gamma q'|^2 + |p'|^2.$$

Let $\bar{\xi}(t)$ and $\tilde{\xi}(t)$, respectively, be the optimal curves in the definition of \bar{C}_h in (10) and of \tilde{C}_h in (15). We will need a number of properties of these two curves. All the statements below are of the following type: there exists $C > 0$ and $0 < h_0 < 1$ such that the property holds for all $h < h_0$. Here C is always independent of q, p, q', p' , and h . The norm $\|\cdot\|_p$ is the L^p -norm on the interval $(0, h)$.

The curve $\bar{\xi}$ satisfies $\bar{\xi}''' = 0$, and hence it is a cubic polynomial

$$\bar{\xi}(t) = q_0 + at + bt^2 + ct^3, \quad (45)$$

where the coefficients can be calculated from the boundary conditions:

$$a = \frac{p}{m}, \quad b = \frac{3}{h^2} \left(q' - q - \frac{ph}{m} \right) - \frac{p' - p}{mh}, \quad c = \frac{p' + p}{mh^2} - \frac{2}{h^3} (q' - q).$$

Explicit calculations give

$$\|\bar{\xi}\|_2^2 \leq h\|\bar{\xi}\|_\infty^2 \leq ChN, \quad (46)$$

$$\|\ddot{\xi}\|_2^2 \leq h\|\ddot{\xi}\|_\infty^2 \leq C\{h^{-3}|q - q'|^2 + h^{-1}|p - p'|^2\}, \quad (47)$$

$$\|\ddot{\xi}\|_1 \leq h\|\ddot{\xi}\|_\infty \leq C\{h^{-1}|q - q'| + |p - p'|\}. \quad (48)$$

The curve $\tilde{\xi}(t)$ satisfies the equation

$$\begin{aligned} \mathcal{N}(\tilde{\xi})(t) &:= m^2 \ddot{\tilde{\xi}}(t) + 2m\nabla^2 V(\tilde{\xi}) \cdot \ddot{\tilde{\xi}}(t) + m\nabla^3 V(\tilde{\xi}) \cdot \dot{\tilde{\xi}} \cdot \dot{\tilde{\xi}}(t) + \nabla^2 V(\tilde{\xi}) \cdot \nabla V(\tilde{\xi})(t) = 0, \\ (\tilde{\xi}, m\dot{\tilde{\xi}})(0) &= (q, p), \quad (\tilde{\xi}, m\dot{\tilde{\xi}})(h) = (q', p'), \end{aligned} \quad (49)$$

where $\nabla^3 V$ is the third-order tensor of third derivatives of V . This is a relatively benign equation, but non-trivially nonlinear.

We will need the following four intermediate estimates:

$$\|\tilde{\xi}\|_2^2 \leq ChN, \quad (50)$$

$$\bar{C}_h + h\|\ddot{\tilde{\xi}}\|_2^2 \leq C\{\bar{C}_h + h^2 N\}, \quad (51)$$

$$\|\ddot{\tilde{\xi}}\|_2^2 \leq Ch\{\bar{C}_h + N\}, \quad (52)$$

$$\|\ddot{u}\|_1 \leq C\{\bar{C}_h + N + 1\}. \quad (53)$$

We first prove (50). Since $\tilde{\xi}$ is optimal in \tilde{C}_h ,

$$\begin{aligned} m\|\ddot{\tilde{\xi}}\|_2 &\leq \|m\ddot{\tilde{\xi}} + \nabla V(\tilde{\xi})\|_2 + \|\nabla V(\tilde{\xi})\|_2 \\ &\stackrel{(13)}{\leq} \|m\ddot{\tilde{\xi}} + \nabla V(\bar{\xi})\|_2 + \|\nabla V(\tilde{\xi})\|_2 \\ &\leq m\|\ddot{\tilde{\xi}}\|_2 + \|\nabla V(\bar{\xi})\|_2 + \|\nabla V(\tilde{\xi})\|_2 \\ &\stackrel{(30)}{\leq} m\|\ddot{\tilde{\xi}}\|_2 + C(\|\bar{\xi}\|_2 + \|\tilde{\xi}\|_2) \\ &\leq m\|\ddot{\tilde{\xi}}\|_2 + C(\|\bar{\xi}\|_2 + h^{1/2}\|\tilde{\xi}\|_\infty). \end{aligned} \quad (54)$$

Therefore

$$\begin{aligned} \|\tilde{\xi}\|_\infty &\leq |\tilde{\xi}(0)| + h|\dot{\tilde{\xi}}(0)| + h^{3/2}\|\ddot{\tilde{\xi}}\|_2 \\ &\leq |q| + \frac{h}{m}|p| + Ch^{3/2}\{ \|\ddot{\tilde{\xi}}\|_2 + \|\bar{\xi}\|_2 + h^{1/2}\|\tilde{\xi}\|_\infty \}. \end{aligned}$$

If h_0 is small enough, then $Ch^2 < 1/2$, so that

$$\|\tilde{\xi}\|_\infty \stackrel{(46),(47)}{\leq} 2|q| + \frac{2h}{m}|p| + C\{|q - q'| + h|p - p'| + h^2\sqrt{N}\}.$$

Therefore

$$\|\tilde{\xi}\|_2^2 \leq h\|\tilde{\xi}\|_\infty^2 \leq ChN,$$

which is (50).

Similar to (54) it also follows, since $\tilde{\xi}$ is admissible for \bar{C}_h , that

$$\begin{aligned} \bar{C}_h &= m^2 h\|\ddot{\tilde{\xi}}\|_2^2 \leq m^2 h\|\ddot{\tilde{\xi}}\|_2^2 \leq 2h\|m\ddot{\tilde{\xi}} + \nabla V(\tilde{\xi})\|_2^2 + 2h\|\nabla V(\tilde{\xi})\|_2^2 \\ &\stackrel{(13),(30)}{\leq} 2\bar{C}_h + Ch\|\ddot{\tilde{\xi}}\|_2^2 \stackrel{(50)}{\leq} 2\bar{C}_h + Ch^2 N, \end{aligned}$$

which implies (51).

We now can prove part 1 of the Lemma. (39a) is a direct consequence of (17) and (29a). The estimate for p follows from (15) and (30) for \hat{C}_h , and from (10) and (51) for \tilde{C}_h :

$$\begin{aligned} |p' - p|^2 &\leq C\left[|p' - p + h\nabla V(q)|^2 + h^2|\nabla V(q)|^2\right] \leq C\left[\hat{C}_h(q, p; q', p') + h^2 N\right], \\ |p' - p|^2 &\leq \bar{C}_h \leq C(\tilde{C}_h + h^2 N). \end{aligned}$$

Similarly,

$$\begin{aligned} |q' - q|^2 &= \frac{h^2}{m^2} \left| \frac{m}{h}(q' - q) - \frac{p + p'}{2} + \frac{p' + p}{2} \right|^2 \\ &\leq \frac{3h^2}{m^2} \left(\left| \frac{m}{h}(q' - q) - \frac{p + p'}{2} \right|^2 + \frac{|p|^2}{4} + \frac{|p'|^2}{4} \right) \\ &\leq Ch^2(\bar{C}_h + N) \leq Ch^2(\tilde{C}_h + N), \end{aligned} \tag{55}$$

and also

$$|q' - q|^2 \leq Ch^2(\hat{C}_h + N).$$

Using the Poincaré inequality $\|v - f v\|_2 \leq Ch\|v'\|_2$, the estimate (52) then follows by

$$\|\ddot{\xi}\|_2^2 \leq 2\|f \ddot{\xi}\|_2^2 + Ch^2\|\ddot{\xi}\|_2^2 \stackrel{(51)}{\leq} \frac{2}{h}|q - q'|^2 + Ch\{\tilde{C}_h + h^2N\} \stackrel{(39b)}{\leq} Ch\{\tilde{C}_h + N\}.$$

To prove the final of the four intermediate estimates, (53), we define $u = \tilde{\xi} - \bar{\xi}$; remark that

$$m^2 \ddot{u} = -2m\nabla^2 V(\tilde{\xi}) \cdot \ddot{\xi} - m\nabla^3 V(\tilde{\xi}) \cdot \dot{\xi} \cdot \dot{\xi} - \nabla^2 V(\tilde{\xi}) \cdot \nabla V(\tilde{\xi}). \tag{56}$$

Note that $u = \dot{u} = 0$ at $t = 0, h$, so that we have $\|u\|_1 \leq Ch^4\|\ddot{u}\|_1$ and $\|\dot{u}\|_1 \leq Ch^2\|\ddot{u}\|_1$. We then calculate

$$\begin{aligned} \|\ddot{u}\|_1 &\stackrel{(56),(29)}{\leq} C\{\|\ddot{\xi}\|_1 + \|\dot{\xi}\|_2^2 + \|\tilde{\xi}\|_1\} \\ &\leq C\{\|\ddot{\xi}\|_1 + \|\dot{\xi}\|_2^2 + \|\bar{\xi}\|_1 + \|\dot{u}\|_1 + \|u\|_1\} \\ &\leq C\{\|\ddot{\xi}\|_1 + \|\dot{\xi}\|_2^2 + \|\bar{\xi}\|_1 + h^2\|\ddot{u}\|_1 + h^4\|\ddot{u}\|_1\}. \end{aligned}$$

Again, taking h_0 sufficiently small, we have $C(h^2 + h^4) < 1/2$, and therefore

$$\begin{aligned} \|\ddot{u}\|_1 &\leq C\{\|\ddot{\xi}\|_1 + \|\dot{\xi}\|_2^2 + \|\bar{\xi}\|_1\} \\ &\stackrel{(46),(48),(52)}{\leq} C\left\{\frac{|q - q'|}{h} + |p - p'| + h\tilde{C}_h + hN + h\sqrt{N}\right\} \\ &\stackrel{(39b)}{\leq} C\left\{\sqrt{\tilde{C}_h + N} + h\tilde{C}_h + N + 1\right\} \\ &\leq C\{\tilde{C}_h + N + 1\}. \end{aligned}$$

We now continue with parts 2, 3, and 4. The derivatives of \hat{C}_h can be calculated directly using the explicit expression (15). The derivatives of \tilde{C}_h can be calculated as follows. Let $\eta \in C^2([0, h]; \mathbf{R}^{2d})$ satisfy $\eta(0) = \dot{\eta}(0) = 0$. Then

$$\begin{aligned} 4\gamma\beta^{-1}h \frac{d}{d\varepsilon} \tilde{I}(\tilde{\xi} + \varepsilon\eta)|_{\varepsilon=0} &= 2h \int_0^h (m\ddot{\xi} + \nabla V(\tilde{\xi})) \cdot (m\dot{\eta} + \nabla^2 V(\tilde{\xi}) \cdot \eta)(t) dt \\ &= 2h \int_0^h \mathcal{N}(\tilde{\xi}) \cdot \eta(t) dt + 2h \left[m\dot{\eta}(m\ddot{\xi} + \nabla V(\tilde{\xi})) - m\eta(m\ddot{\xi} + \nabla^2 V(\tilde{\xi}) \cdot \dot{\xi}) \right](h). \end{aligned}$$

Note that $\mathcal{N}(\tilde{\xi}) \equiv 0$ by the stationarity (49) of $\tilde{\xi}$. This expression is equal to

$$\nabla_{q'} \tilde{C}_h(q, p; q', p') \cdot \eta(h) + \nabla_{p'} \tilde{C}_h(q, p; q', p') \cdot m\dot{\eta}(h),$$

which allows us to identify the two derivatives in terms of $\tilde{\xi}$. Setting $u = \tilde{\xi} - \bar{\xi}$, we rewrite these in terms of u :

$$\begin{aligned} \nabla_{q'} \tilde{C}_h(q, p; q', p') &= -2hm^2 \ddot{\xi}(h) - 2hm\nabla^2 V(\tilde{\xi}(h)) \cdot \dot{\xi}(h) \\ &= -2hm^2 \ddot{\xi}(h) - 2hm\nabla^2 V(\tilde{\xi}(h)) \cdot \dot{\xi}(h) - 2hm^2 (\ddot{\xi}(h) - \ddot{\bar{\xi}}(h)) \\ &\stackrel{(45)}{=} \frac{24m}{h} \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right) - 2h\nabla^2 V(q') \cdot p' - 2hm^2 \ddot{u}(h), \\ \nabla_{p'} \tilde{C}_h(q, p; q', p') &= 2hm\ddot{\xi}(h) + 2h\nabla V(\tilde{\xi}(h)) \\ &= 2hm\ddot{\xi}(h) + 2h\nabla V(\tilde{\xi}(h)) + 2hm(\ddot{\xi}(h) - \ddot{\bar{\xi}}(h)) \\ &\stackrel{(45)}{=} 2(p' - p) - 12 \left(\frac{m}{h}(q' - q) - \frac{p' + p}{2} \right) + 2h\nabla V(q') + 2hm\ddot{u}(h). \end{aligned}$$

Therefore (40) holds with

$$\sigma_h = -2hm^2\ddot{u}(h) \quad \text{and} \quad \tau_h = 2hm\dot{u}(h).$$

The estimates (41) then follow from (53) and the inequalities

$$\|\ddot{u}\|_\infty \leq h\|\dot{u}\|_\infty \leq Ch\|\dot{u}\|_1,$$

which hold since $u = \dot{u} = 0$ at $t = 0, h$.

The derivatives of C_h are given by (43), where

$$r(q, q') := 2m\left[\nabla^2 V(q') \cdot (q' - q) - \nabla V(q') + \nabla V(q)\right].$$

The estimate (44) on r follows from (29d), (55), and the fact that by (29a), $\bar{C}_h \leq C_h$. □

4. The Euler-Lagrange equation for the minimization problem

Let C_h^* be one of \tilde{C}_h , \widehat{C}_h , or C_h , defined in (13), (15), and (17), with corresponding optimal-transport cost functional W_h^* . Let $\bar{\rho} \in \mathcal{P}_2(\mathbf{R}^{2d})$ be given and let ρ be the unique solution of the minimization problem

$$\min_{\mu \in \mathcal{P}_2(\mathbf{R}^{2d})} \frac{1}{2\gamma h} W_h^*(\bar{\rho}, \mu) + \mathcal{A}(\mu).$$

We now establish the Euler-Lagrange equation for ρ . Following the now well-established route (see e.g. [20, 17]), we first define a perturbation of ρ by a push-forward under an appropriate flow. Let $\xi, \eta \in C_0^\infty(\mathbf{R}^{2d}, \mathbf{R}^d)$. We define the flows $\Phi, \Psi: [0, \infty) \times \mathbf{R}^{2d} \rightarrow \mathbf{R}^{2d}$ such that

$$\begin{aligned} \frac{\partial \Psi_s}{\partial s} &= \phi(\Psi_s, \Phi_s), \quad \frac{\partial \Phi_s}{\partial s} = \eta(\Psi_s, \Phi_s), \\ \Psi_0(q, p) &= q, \quad \Phi_0(q, p) = p. \end{aligned}$$

Let $\rho_s(q, p)$ be the push forward of $\rho(q, p)$ under the flow (Ψ_s, Φ_s) , i.e., for any $\varphi \in C_0^\infty(\mathbf{R}^{2d}, \mathbf{R})$ we have

$$\int_{\mathbf{R}^{2d}} \varphi(q, p) \rho_s(q, p) dq dp = \int_{\mathbf{R}^{2d}} \varphi(\Psi_s(q, p), \Phi_s(q, p)) \rho(q, p) dq dp. \quad (57)$$

Obviously $\rho_0(q, p) = \rho(q, p)$, and an explicit calculation gives

$$\partial_s \rho_s \Big|_{s=0} = -\operatorname{div}_q \rho \phi - \operatorname{div}_p \rho \eta \quad \text{in the sense of distributions.} \quad (58)$$

By following the calculations in e.g. [17] we then compute the stationarity condition on ρ ,

$$\begin{aligned} 0 &= \frac{1}{2\gamma h} \int_{\mathbf{R}^{4d}} [\nabla_{q'} C_h^*(q, p; q', p') \cdot \phi(q', p') + \nabla_{p'} C_h^*(q, p; q', p') \cdot \eta(q', p')] P_{\text{opt}}^*(dq dp dq' dp') \\ &\quad + \int_{\mathbf{R}^{2d}} \rho(q, p) \nabla_p F(p) \cdot \eta(q, p) dq dp - \beta^{-1} \int_{\mathbf{R}^{2d}} \rho(q, p) [\operatorname{div}_q \phi(q, p) + \operatorname{div}_p \eta(q, p)] dq dp, \end{aligned} \quad (59)$$

where P_{opt}^* is optimal in $W_h^*(\bar{\rho}, \rho)$. For any $\varphi \in C_0^\infty(\mathbf{R}^{2d}, \mathbf{R})$, we choose

$$\begin{aligned} \phi(q', p') &= -\frac{\gamma h^2}{6m^2} \nabla_{q'} \varphi(q', p') + \frac{\gamma h}{2m} \nabla_{p'} \varphi(q', p'), \\ \eta(q', p') &= -\frac{\gamma h}{2m} \nabla_{q'} \varphi(q', p') + \gamma \nabla_{p'} \varphi(q', p'). \end{aligned}$$

i.e.,

$$\begin{pmatrix} \phi \\ \eta \end{pmatrix} = \begin{pmatrix} -\frac{\gamma h^2}{6m^2} I & \frac{\gamma h}{2m} I \\ -\frac{\gamma h}{2m} I & \gamma I \end{pmatrix} \nabla \varphi(q', p'). \quad (60)$$

Now the specific form of the cost functional $C_h^*(q, p; q', p')$ comes into play. We calculate the gradient expression in (59) for each scheme in the next subsections.

Remark 4.1 The structure of the choice (60) can be understood in terms of the conservative-dissipative nature of the Kramers equation. The matrix in front of $\nabla\varphi(q', p')$ in (60) is of the form

$$\begin{pmatrix} -\frac{\gamma h^2}{6m^2}I & \frac{\gamma h}{2m}I \\ -\frac{\gamma h}{2m}I & \gamma I \end{pmatrix} = \underbrace{\begin{pmatrix} -\frac{\gamma h^2}{6m^2}I & 0 \\ 0 & \gamma I \end{pmatrix}}_A - \underbrace{\frac{\gamma h}{2m} \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}}_B.$$

Note that A is symmetric and B is antisymmetric: this mirrors the conservative-dissipative structure of the Kramers equation.

The top-left block in A , which would correspond to diffusion in the spatial variable q , is of order $O(h^2)$, and therefore vanishes when $h \rightarrow 0$. The other block, which corresponds to diffusion in the momentum variable p , is of order $O(1)$ and remains. This explains how in the limit $h \rightarrow 0$ only diffusion in the momentum variable remains.

4.1. Schemes 2a and 2b

Lemma 4.2 Let $h > 0$ and let $\{\rho_k^h\}$ be the sequence of the minimizers either for problem (14) in Scheme 2a or for problem (16) in Scheme 2b. Let W_h^* be \widehat{W}_h for Scheme 2a and \widetilde{W}_h for Scheme 2b, and let P_k^{h*} be optimal in $W_h^*(\rho_{k-1}^h, \rho_k^h)$. Then, for all $\varphi \in C_c^\infty(\mathbf{R}^{2d})$, there holds

$$\begin{aligned} 0 &= \frac{1}{h} \int_{\mathbf{R}^{4d}} [(q' - q) \cdot \nabla_{q'}\varphi(q', p') + (p' - p) \cdot \nabla_{p'}\varphi(q', p')] P_k^{h*}(dqdpdq'dp') \\ &\quad - \frac{1}{m} \int_{\mathbf{R}^{2d}} p' \cdot \nabla_{q'}\varphi(q', p') \rho_k^h(q', p') dq'dp' + \int_{\mathbf{R}^{2d}} \nabla V(q') \cdot \nabla_{p'}\varphi(q', p') \rho_k^h(q', p') dq'dp' \\ &\quad + \gamma \int_{\mathbf{R}^{2d}} [\nabla F(p') \cdot \nabla_{p'}\varphi(q', p') - \beta^{-1} \Delta_{p'}\varphi(q', p')] \rho_k^h(q', p') dq'dp' + \omega_k^h, \end{aligned} \tag{61}$$

where

$$|\omega_k^h| \leq Ch [W_h^*(\rho_{k-1}^h, \rho_k^h) + M_2(\rho_{k-1}^h) + M_2(\rho_k^h) + 1].$$

The second moment M_2 is defined in (31).

Proof: For Scheme 2b we combine (60) with (42) to yield

$$\begin{aligned} &\nabla_{q'} \widehat{C}_h(q, p; q', p') \cdot \phi(q', p') + \nabla_{p'} \widehat{C}_h(q, p; q', p') \cdot \eta(q', p') \\ &= 2\gamma \left[(q' - q) \cdot \nabla_{q'}\varphi(q', p') + (p' - p) \cdot \nabla_{p'}\varphi(q', p') - \frac{h}{m} p' \cdot \nabla_{q'}\varphi(q', p') \right] \\ &\quad + 2\gamma \nabla V(q) \cdot \left[-\frac{h^2}{2m} \nabla_{q'}\varphi(q', p') + h \nabla_{p'}\varphi(q', p') \right]. \end{aligned} \tag{62}$$

Substituting (60) and (62) into the Euler-Lagrange equation (59), we obtain

$$\begin{aligned} 0 &= \frac{1}{h} \int_{\mathbf{R}^{4d}} [(q' - q) \cdot \nabla_{q'}\varphi(q', p') + (p' - p) \cdot \nabla_{p'}\varphi(q', p')] \widehat{P}_k^h(dqdpdq'dp') \\ &\quad - \frac{1}{m} \int_{\mathbf{R}^{2d}} p' \cdot \nabla_{q'}\varphi(q', p') \rho_k^h(q', p') dq'dp' + \int_{\mathbf{R}^{4d}} \nabla V(q) \cdot \nabla_{p'}\varphi(q', p') \widehat{P}_k^h(dqdpdq'dp') \\ &\quad + \gamma \int_{\mathbf{R}^{2d}} \left[\nabla F(p') \cdot \nabla_{p'}\varphi(q', p') + \beta^{-1} \frac{h^2}{6m^2} \Delta_{q'}\varphi(q', p') - \beta^{-1} \Delta_{p'}\varphi(q', p') \right] \rho_k^h(q', p') dq'dp' \\ &\quad - \frac{h}{2m} \int_{\mathbf{R}^{4d}} [\nabla V(q) + \gamma \nabla F(p')] \cdot \nabla_{q'}\varphi(q', p') \widehat{P}_k^h(dqdpdq'dp'). \end{aligned} \tag{63}$$

Therefore (61) holds with

$$\begin{aligned} |\omega_k^h| &= \left| \int_{\mathbf{R}^{4d}} (\nabla V(q) - \nabla V(q')) \cdot \nabla_{p'}\varphi(q', p') \widehat{P}_k^h(dqdpdq'dp') dq'dp' \right. \\ &\quad \left. + \beta^{-1} \frac{h^2}{6m^2} \int_{\mathbf{R}^{2d}} \Delta_{q'}\varphi(q', p') \rho_k^h(q', p') dq'dp' \right. \\ &\quad \left. - \frac{h}{2m} \int_{\mathbf{R}^{4d}} [\nabla V(q) + \gamma \nabla F(p')] \cdot \nabla_{q'}\varphi(q', p') \widehat{P}_k^h(dqdpdq'dp') \right| \\ &\stackrel{(29b),(29c)}{\leq} C \int_{\mathbf{R}^{4d}} [|q - q'| + h(|q| + |p'| + 1)] \widehat{P}_k^h(dqdpdq'dp') \\ &\leq C \int_{\mathbf{R}^{4d}} \left[\frac{1}{h} |q - q'|^2 + h(|q|^2 + |p'|^2 + 1) \right] \widehat{P}_k^h(dqdpdq'dp') \\ &\stackrel{(39)}{\leq} Ch [\widehat{W}_h(\rho_{k-1}^h, \rho_k^h) + M_2(\rho_{k-1}^h) + M_2(\rho_k^h) + 1]. \end{aligned}$$

This proves Lemma 4.2 for Scheme 2b.

For Scheme 2a we obtain an identity similar to (62),

$$\begin{aligned} & \nabla_{q'} \tilde{C}_h(q, p; q', p') \cdot \phi(q', p') + \nabla_{p'} \tilde{C}_h(q, p; q', p') \cdot \eta(q', p') \\ &= 2\gamma \left[(q' - q) \cdot \nabla_{q'} \varphi(q', p') + (p' - p) \cdot \nabla_{p'} \varphi(q', p') - \frac{h}{m} p' \cdot \nabla_{q'} \varphi(q', p') \right] \\ & \quad + 2\gamma \left\{ h \nabla V(q') + \frac{1}{2} \tau_h(q, p; q', p') \right\} \cdot \left[-\frac{h}{2m} \nabla_{q'} \varphi(q', p') + \nabla_{p'} \varphi(q', p') \right] \\ & \quad + 2\gamma \left\{ -h \nabla^2 V(q') \cdot p' + \frac{1}{2} \sigma_h(q, p; q', p') \right\} \cdot \left[-\frac{h^2}{6m^2} \nabla_{q'} \varphi(q', p') + \frac{h}{2m} \nabla_{p'} \varphi(q', p') \right]. \end{aligned}$$

This leads to the same equation as (61), but now with error term

$$\begin{aligned} \omega_k^h &= -\frac{h}{2m} \int_{\mathbb{R}^{4d}} \nabla V(q') \cdot \nabla_{q'} \varphi(q', p') \tilde{P}_k^h(dqdpdq'dp') \\ & \quad + \int_{\mathbb{R}^{4d}} \left\{ \nabla^2 V(q') \cdot p' - \frac{1}{2h} \sigma_h(q, p; q', p') \right\} \cdot \left[\frac{h^2}{6m^2} \nabla_{q'} \varphi(q', p') - \frac{h}{2m} \nabla_{p'} \varphi(q', p') \right] \tilde{P}_k^h(dqdpdq'dp') \\ & \quad + \frac{1}{2h} \int_{\mathbb{R}^{4d}} \tau_h(q, p; q', p') \left[-\frac{h}{2m} \nabla_{q'} \varphi(q', p') + \nabla_{p'} \varphi(q', p') \right] \tilde{P}_k^h(dqdpdq'dp') \\ & \quad - \frac{\gamma h}{2m} \int_{\mathbb{R}^{4d}} \nabla F(p') \cdot \nabla_{q'} \varphi(q', p') \rho_k^h(q', p') dq'dp' \\ & \quad + \beta^{-1} \frac{h^2}{6m^2} \int_{\mathbb{R}^{2d}} \Delta_{q'} \varphi(q', p') \rho_k^h(q', p') dq'dp'. \end{aligned}$$

We estimate this error as follows, using the notation of the proof of Lemma 1:

$$\begin{aligned} |\omega_k^h| &\leq C \int_{\mathbb{R}^{4d}} \left\{ h(1 + |q'|) + h|p'| + |\sigma_h| + \frac{1}{h} |\tau_h| + h(1 + |p'|) + h^2 \right\} \tilde{P}_k^h \\ &\leq C \int_{\mathbb{R}^{4d}} \left\{ h(1 + |q'|^2 + |p'|^2) + h[\tilde{C}_h + N + 1] \right\} \tilde{P}_k^h \\ &\leq Ch \int_{\mathbb{R}^{4d}} [\tilde{C}_h + N + 1] \tilde{P}_k^h \\ &\leq Ch [\tilde{W}_h(\rho_{k-1}^h, \rho_k^h) + M_2(\rho_{k-1}^h) + M_2(\rho_k^h) + 1]. \end{aligned}$$

This concludes the proof of Lemma 4.2. □

4.2. Scheme 2c

Lemma 4.3 Let $h > 0$ and let $\{\mu_k^h\}$ and $\{\rho_k^h\}$ be the sequences constructed in Scheme 2c. Let $P_k^h(dqdpdq'dp')$ be the optimal plan in the definition of $W_h(\mu_k^h, \rho_k^h)$. Then, for all $\varphi \in C_c^\infty(\mathbb{R}^{2d})$, there holds

$$\begin{aligned} 0 &= \frac{1}{h} \int_{\mathbb{R}^{4d}} \left[(q' - q + \frac{p}{m} h) \cdot \nabla_{q'} \varphi(q', p') + (p' - p - h \nabla_q V(q)) \cdot \nabla_{p'} \varphi(q', p') \right] P_k^h(dqdpdq'dp') \\ & \quad - \frac{1}{m} \int_{\mathbb{R}^{2d}} p \cdot \nabla_q \varphi(q, p) \rho_k^h(dqdp) + \int_{\mathbb{R}^{2d}} \nabla V(q) \cdot \nabla_p \varphi(q, p) \rho_k^h(q, p) dqdp \\ & \quad + \gamma \int_{\mathbb{R}^{2d}} [\nabla F(p) \cdot \nabla_p \varphi(q, p) - \beta^{-1} \Delta_p \varphi(q, p)] \rho_k^h(q, p) dqdp + \zeta_k^h, \end{aligned} \tag{64}$$

where

$$|\zeta_k^h| \leq Ch [hW_h(\mu_k^h, \rho_k^h) + M_2(\mu_k^h) + M_2(\rho_k^h) + 1].$$

Proof: From (60) and (43) we obtain

$$\begin{aligned} & \nabla_{q'} C_h(q, p; q', p') \cdot \phi(q', p') + \nabla_{p'} C_h(q, p; q', p') \cdot \eta(q', p') \\ &= 2\gamma \left[(q' - q) \cdot \nabla_{q'} \varphi(q', p') + (p' - p) \cdot \nabla_{p'} \varphi(q', p') - \frac{h}{m} (p' - p) \cdot \nabla_{q'} \varphi(q', p') \right] \\ & \quad + \gamma \left[4m(\nabla V(q') - \nabla V(q)) + r(q, q') \right] \cdot \left\{ -\frac{h^2}{6m^2} \nabla_{q'} \varphi(q', p') + \frac{h}{2m} \nabla_{p'} \varphi(q', p') \right\}. \end{aligned} \tag{65}$$

Substituting (60) and (65) into the Euler-Lagrange equation (59), we obtain

$$\begin{aligned}
 0 &= \frac{1}{h} \int_{\mathbb{R}^{4d}} [(q' - q) \cdot \nabla_{q'} \varphi(q', p') + (p' - p) \cdot \nabla_{p'} \varphi(q', p')] P_k^h(dqdpdq'dp') \\
 &\quad - \frac{1}{m} \int_{\mathbb{R}^{4d}} (p' - p) \cdot \nabla_{q'} \varphi(q', p') P_k^h(dqdpdq'dp') + \int_{\mathbb{R}^{4d}} (\nabla V(q') - \nabla V(q)) \cdot \nabla_{p'} \varphi(q', p') P_k^h(dqdpdq'dp') \\
 &\quad + \gamma \int_{\mathbb{R}^{2d}} [\nabla F(p) \cdot \nabla_p \varphi(q, p) - \beta^{-1} \Delta_p \varphi(q, p)] \rho_k^h(q, p) dqdp + \zeta_k^h,
 \end{aligned} \tag{66}$$

where we estimate the remainder, again using the notation of the proof of Lemma 3.1,

$$\begin{aligned}
 |\zeta_k^h| &= \left| -\frac{h}{3m} \int_{\mathbb{R}^{4d}} (\nabla V(q') - \nabla V(q)) \cdot \nabla_{q'} \varphi(q', p') P_k^h(dqdpdq'dp') \right. \\
 &\quad \left. + \frac{1}{2} \int_{\mathbb{R}^{4d}} r(q, q') \cdot \left[-\frac{h}{6m^2} \nabla_{q'} \varphi(q', p') + \frac{1}{2m} \nabla_{p'} \varphi(q', p') \right] P_k^h(dqdpdq'dp') \right. \\
 &\quad \left. - \frac{\gamma h}{2m} \int_{\mathbb{R}^{2d}} \rho_k^h(q, p) \nabla F(p) \cdot \nabla_q \varphi(q, p) dqdp + \beta^{-1} \frac{\gamma h^2}{6m^2} \int_{\mathbb{R}^{2d}} \rho_k^h(q, p) \Delta_q \varphi(q, p) dqdp \right| \\
 &\stackrel{(29),(44)}{\leq} C \int_{\mathbb{R}^{4d}} [h|q' - q| + h^2(C_h + N) + h(1 + |p'|) + h^2] P_k^h(dqdpdq'dp') \\
 &\leq C \int_{\mathbb{R}^{4d}} [h(|q|^2 + |q'|^2) + h^2(C_h + N) + h(1 + |p'|^2)] P_k^h(dqdpdq'dp') \\
 &\leq Ch[hW_h(\mu_k^h, \rho_k^h) + M_2(\mu_k^h) + M_2(\rho_k^h) + 1].
 \end{aligned}$$

This concludes the proof of Lemma 4.3. □

5. A priori estimate: Boundedness of the second moment and entropy

This section includes some technical lemmas that are needed in order to prove the convergence result of Section 6.

Lemma 5.1 *Let $\{\rho_k^h\}_{k \geq 1}$ be the sequence of the minimizers of Scheme 2a or Scheme 2b for fixed $h > 0$. Then for any positive integer n and sufficiently small h , we have*

$$\sum_{k=1}^n W_h^*(\rho_{k-1}^h, \rho_k^h) \leq 2\gamma h(\mathcal{A}(\rho_0) - \mathcal{A}(\rho_n^h)) + Ch^2 \sum_{k=0}^n M_2(\rho_k^h) + Cnh^2, \tag{67}$$

for some constant $C > 0$ independent of n , where W_h^* is either \widetilde{W}_h or \widehat{W}_h . Similarly, if $\{\mu_k^h\}$ and $\{\rho_k^h\}$ are the sequences constructed in Scheme 2c, then

$$\sum_{k=1}^n W_h(\mu_k^h, \rho_k^h) \leq 2\gamma h(\mathcal{A}(\rho_0) - \mathcal{A}(\rho_n^h)) + Ch^2 \sum_{k=0}^n M_2(\rho_k^h) + Cnh^2.$$

Proof: We give the details for Scheme 2a and then comment on the differences for the other schemes. We first define the operator $\mathbf{s}_h : \mathbf{R}^{2d} \rightarrow \mathbf{R}^{2d}$ as the solution operator over time h for the Hamiltonian system

$$Q' = \frac{P}{m}, \quad P' = -\nabla V(Q), \tag{68}$$

that is, $\mathbf{s}_h(q, p)$ is the solution at time h given the initial datum (q, p) at time zero. The operator \mathbf{s}_h is bijective and volume-preserving.

For any fixed $k \geq 1$, ρ_k^h minimizes the functional $(2h\gamma)^{-1} \widetilde{W}_h(\rho_{k-1}^h, \rho) + \mathcal{A}(\rho)$ over $\rho \in \mathcal{P}_2(\mathbf{R}^{2d})$, i.e.,

$$\widetilde{W}_h(\rho_{k-1}^h, \rho_k^h) + 2h\gamma \mathcal{A}(\rho_k^h) \leq \widetilde{W}_h(\rho_{k-1}^h, \rho) + 2h\gamma \mathcal{A}(\rho), \tag{69}$$

for every $\rho \in \mathcal{P}_2(\mathbf{R}^{2d})$. In particular by taking $\rho = (\mathbf{s}_h^{-1})\# \rho_{k-1}^h =: \rho_*^h$, for which $\widetilde{W}_h(\rho_{k-1}^h, \rho_*^h) = 0$, it follows that

$$\widetilde{W}_h(\rho_{k-1}^h, \rho_k^h) \leq 2\gamma h[\mathcal{A}(\rho_*^h) - \mathcal{A}(\rho_k^h)] = 2\gamma h[\mathcal{F}(\rho_*^h) - \mathcal{F}(\rho_k^h)] + 2\gamma h[S(\rho_*^h) - S(\rho_k^h)]. \tag{70}$$

We now estimate each term on the right hand side. Write $(\bar{q}, \bar{p}) = \mathbf{s}_h(q, p)$. Using equation (68), we readily estimate that the solution $(Q(t), P(t))$ starting at (q, p) and ending at (\bar{q}, \bar{p}) satisfies $\|Q\|_\infty \leq C(|\bar{q}| + h|\bar{p}|)$, and therefore

$$\left| \int_0^h \nabla V(Q(t)) dt \right| \leq h \sup_{t \in [0, h]} |\nabla V(Q(t))| \leq h \|Q\|_\infty \leq Ch(|\bar{q}| + h|\bar{p}|),$$

so that

$$\begin{aligned} F(p) &= F\left(\bar{p} + \int_0^h \nabla V(Q(t)) dt\right) \\ &\stackrel{(28), (29c)}{\leq} F(\bar{p}) + C(|\bar{p}| + 1) \left| \int_0^h \nabla V(Q(t)) dt \right| + C \left(\int_0^h \nabla V(Q(t)) dt \right)^2 \\ &\leq F(\bar{p}) + Ch(|\bar{p}| + 1)(|\bar{q}| + h|\bar{p}|) + Ch^2(|\bar{q}| + h|\bar{p}|)^2 \\ &\leq F(\bar{p}) + Ch[N(\bar{q}, \bar{p}) + 1]. \end{aligned}$$

Therefore

$$\begin{aligned} \mathcal{F}(\rho_*^h) &= \int_{\mathbb{R}^{2d}} F(p) \rho_*^h(q, p) dq dp = \int_{\mathbb{R}^{2d}} F(p) \rho_{k-1}^h(\bar{q}, \bar{p}) d\bar{q} d\bar{p} \\ &\leq \int_{\mathbb{R}^{2d}} (F(\bar{p}) + ChN(\bar{q}, \bar{p}) + Ch) \rho_{k-1}^h(\bar{q}, \bar{p}) d\bar{q} d\bar{p} \leq \mathcal{F}(\rho_{k-1}^h) + ChM_2(\rho_{k-1}^h) + Ch. \end{aligned} \quad (71)$$

For the entropy term, we have, since \mathbf{s}_h is volume-preserving and bijective,

$$S(\rho_*^h) = \beta^{-1} \int_{\mathbb{R}^{2d}} \rho_*^h(q, p) \log \rho_*^h(q, p) dq dp = \beta^{-1} \int_{\mathbb{R}^{2d}} \rho_{k-1}^h(\mathbf{s}_h(q, p)) \log \rho_{k-1}^h(\mathbf{s}_h(q, p)) dq dp = S(\rho_{k-1}^h). \quad (72)$$

From (70), (71), and (72), we obtain

$$\widetilde{W}_h(\rho_{k-1}^h, \rho_k^h) \leq 2\gamma h(\mathcal{A}(\rho_{k-1}^h) - \mathcal{A}(\rho_k^h)) + Ch^2 M_2(\rho_{k-1}^h) + Ch^2.$$

Summing over $k = 1$ to n we obtain (67).

For Scheme 2b, the equation (68) only modifies slightly, in that the acceleration becomes constant:

$$Q' = \frac{P}{m}, \quad P' = -\nabla V(q).$$

Similar estimates lead to the same result.

For Scheme 2c, the proof is again similar, by taking $\rho_*^h := \mu_k^h$ and estimating the difference $\mathcal{A}(\mu_k^h) - \mathcal{A}(\rho_{k-1}^h)$ as is done above. \square

Lemma 5.2 *There exist positive constants T_0 , h_0 , and C , independent of the initial data, such that for any $0 < h \leq h_0$, the solutions $\{\rho_k^h\}_{k \geq 1}$ for Scheme 2a, Scheme 2b, or Scheme 2c, satisfy*

$$M_2(\rho_k^h) \leq C[M_2(\rho_0) + 1] \quad \text{and} \quad |S(\rho_k^h)| \leq C[S(\rho_0) + M_2(\rho_0) + 1] \quad \text{for any } k \leq K_0, \quad (73)$$

where $K_0 = \lceil T_0/h \rceil$.

Proof: We detail the proof for Scheme 2a; the modifications for Schemes 2b and 2c are very minor.

For a fixed i , let $\tilde{P}_i \in \Gamma(\rho_{i-1}^h, \rho_i^h)$ be the optimal plan in the definition of $\widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)$. We have

$$\begin{aligned} \left(\int_{\mathbb{R}^{2d}} |\rho|^2 \rho_i^h(q, p) dq dp \right)^{\frac{1}{2}} &= \left(\int_{\mathbb{R}^{4d}} |\rho'|^2 \tilde{P}_i^h(dq dp dq' dp') \right)^{\frac{1}{2}} \\ &\leq \left(\int_{\mathbb{R}^{4d}} |\rho' - \rho|^2 \tilde{P}_i^h(dq dp dq' dp') \right)^{\frac{1}{2}} + \left(\int_{\mathbb{R}^{4d}} |\rho|^2 \tilde{P}_i^h(dq dp dq' dp') \right)^{\frac{1}{2}} \end{aligned}$$

By (39c), we estimate

$$\left(\int_{\mathbb{R}^{4d}} |\rho' - \rho|^2 \tilde{P}_i^h(dq dp dq' dp') \right)^{\frac{1}{2}} \leq C \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch[M_2(\rho_i^h)^{\frac{1}{2}} + M_2(\rho_{i-1}^h)^{\frac{1}{2}}],$$

and hence,

$$\left(\int_{\mathbb{R}^{2d}} |p|^2 \rho_i^h(q, p) dq dp\right)^{\frac{1}{2}} \leq \left(\int_{\mathbb{R}^{2d}} |p|^2 \rho_{i-1}^h(q, p) dq dp\right)^{\frac{1}{2}} + C\widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch[M_2(\rho_i^h)^{\frac{1}{2}} + M_2(\rho_{i-1}^h)^{\frac{1}{2}}].$$

Summing over i from 1 to k we obtain

$$\begin{aligned} \left(\int_{\mathbb{R}^{2d}} |p|^2 \rho_k^h(q, p) dq dp\right)^{\frac{1}{2}} &\leq C \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch \sum_{i=1}^k M_2(\rho_{i-1}^h)^{\frac{1}{2}} + \left(\int_{\mathbb{R}^{2d}} |p|^2 \rho_0(q, p) dq dp\right)^{\frac{1}{2}} \\ &\leq C \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch \sum_{i=1}^k M_2(\rho_i^h)^{\frac{1}{2}} + CM_2(\rho_0)^{\frac{1}{2}}. \end{aligned}$$

Therefore

$$\begin{aligned} \int_{\mathbb{R}^{2d}} |p|^2 \rho_k^h(q, p) dq dp &\leq C \left(\sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}}\right)^2 + Ch^2 \left(\sum_{i=1}^k M_2(\rho_i^h)^{\frac{1}{2}}\right)^2 + CM_2(\rho_0) \\ &\leq Ck \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h) + Ckh^2 \sum_{i=1}^k M_2(\rho_i^h) + CM_2(\rho_0). \end{aligned} \tag{74}$$

Similarly, we use (55) and the fact that

$$q' = \frac{h}{2m\sqrt{3}} 2\sqrt{3} \left(\frac{m}{h}(q' - q) - \frac{p+p'}{2}\right) + \frac{h}{2m}(p' + p) + q$$

to derive that

$$\begin{aligned} \left(\int_{\mathbb{R}^{2d}} |q|^2 \rho_i^h(q, p) dq dp\right)^{\frac{1}{2}} &= \left(\int_{\mathbb{R}^{4d}} |q'|^2 \widetilde{P}_i^h(dq dp dq' dp')\right)^{\frac{1}{2}} \\ &\leq \frac{h}{2m\sqrt{3}} \left(\int_{\mathbb{R}^{4d}} 12 \left|\frac{m}{h}(q' - q) - \frac{p' + p}{2}\right|^2 \widetilde{P}_i^h(dq dp dq' dp')\right)^{\frac{1}{2}} + \frac{h}{2m} \left(\int_{\mathbb{R}^{4d}} |p'|^2 \widetilde{P}_i^h(dq dp dq' dp')\right)^{\frac{1}{2}} \\ &\quad + \frac{h}{2m} \left(\int_{\mathbb{R}^{4d}} |p|^2 \widetilde{P}_i^h(dq dp dq' dp')\right)^{\frac{1}{2}} + \left(\int_{\mathbb{R}^{2d}} |q|^2 \rho_{i-1}^h(q, p) dq dp\right)^{\frac{1}{2}} \\ &\leq Ch\widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch[M_2(\rho_{i-1}^h)^{\frac{1}{2}} + M_2(\rho_i^h)^{\frac{1}{2}}] + \left(\int_{\mathbb{R}^{2d}} |q|^2 \rho_{i-1}^h(q, p) dq dp\right)^{\frac{1}{2}}. \end{aligned}$$

Summing over i from 1 to k , we obtain

$$\left(\int_{\mathbb{R}^{2d}} |q|^2 \rho_k^h(q, p) dq dp\right)^{\frac{1}{2}} \leq Ch \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h)^{\frac{1}{2}} + Ch \sum_{i=1}^k M_2(\rho_i^h)^{\frac{1}{2}} + CM_2(\rho_0)^{\frac{1}{2}}$$

and therefore,

$$\int_{\mathbb{R}^{2d}} \gamma^2 |q|^2 \rho_k^h(q, p) dq dp \leq Ckh^2 \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h) + Ckh^2 \sum_{i=1}^k M_2(\rho_i^h) + CM_2(\rho_0). \tag{75}$$

From (74) and (75) it holds that

$$M_2(\rho_k^h) = \int_{\mathbb{R}^{2d}} (|\gamma q|^2 + |p|^2) \rho_k^h(q, p) dq dp \leq Ck \sum_{i=1}^k \widetilde{W}_h(\rho_{i-1}^h, \rho_i^h) + Ckh^2 \sum_{i=1}^k M_2(\rho_i^h) + CM_2(\rho_0).$$

Applying Lemma 5.1 with $n = k$, it follows that

$$\begin{aligned} M_2(\rho_k^h) &\leq Ck \left[h(\mathcal{A}(\rho_0) - \mathcal{A}(\rho_k^h)) + Ch^2 \sum_{i=0}^k M_2(\rho_i^h) + Ckh^2 \right] + Ckh^2 \sum_{i=1}^k M_2(\rho_i^h) + CM_2(\rho_0) \\ &\leq -CkhS(\rho_k^h) + Ckh^2 \sum_{i=1}^k M_2(\rho_i^h) + CM_2(\rho_0) + Ckh\mathcal{A}(\rho_0) + Ck^2h^2. \end{aligned} \tag{76}$$

By inequality (29) in [20], $S(\rho_k^h)$ is bounded from below by $M_2(\rho_k^h)$,

$$S(\rho_k^h) \geq -C - CM_2(\rho_k^h). \quad (77)$$

Substituting (77) into (76) we have

$$M_2(\rho_k^h) \leq C_1^2 kh^2 \sum_{i=1}^k M_2(\rho_i^k) + C_1 kh M_2(\rho_k^h) + C_1(k^2 h^2 + 1) + C_1 M_2(\rho_0), \quad (78)$$

where we fix the constant C_1 , and use it to set the time horizon T_0 :

$$T_0 = \frac{1}{4C_1}, \quad K_0 = \left\lceil \frac{T_0}{h} \right\rceil. \quad (79)$$

We emphasize that C_1 , and hence T_0 , is independent of the initial data. We now choose $h_0 \leq T_0$ so small that for all $h \leq h_0$ we have $K_0 h \leq 2T_0$ and $C_1 K_0 h \leq \frac{1}{2}$. Then it follows from (78) that, for any $h \leq h_0$, $k \leq K_0$,

$$\frac{3}{4} M_2(\rho_k^h) \leq C_1^2 kh^2 \sum_{i=1}^k M_2(\rho_i^h) + C_1(4T_0^2 + 1) + C_1 M_2(\rho_0). \quad (80)$$

Hence

$$\begin{aligned} \frac{3}{4} \sum_{i=1}^{K_0} M_2(\rho_i^h) &\leq C_1^2 K_0^2 h^2 \sum_{i=1}^{K_0} M_2(\rho_i^h) + K_0(T_0 + C_1) + C_1 M_2(\rho_0) \\ &\leq 4C_1^2 T_0^2 \sum_{i=1}^{K_0} M_2(\rho_i^h) + K_0(T_0 + C_1) + C_1 M_2(\rho_0) \\ &\leq \frac{1}{4} \sum_{i=1}^{K_0} M_2(\rho_i^h) + K_0(T_0 + C_1) + C_1 M_2(\rho_0). \end{aligned} \quad (81)$$

Consequently,

$$\sum_{i=1}^{K_0} M_2(\rho_i^h) \leq 2K_0(T_0 + C_1) + 2C_1 M_2(\rho_0). \quad (82)$$

Substituting (82) into (80), we obtain

$$M_2(\rho_k^h) \leq \frac{2}{3} (2 + K_0) (T_0 + C_1) + C_1 M_2(\rho_0). \quad (83)$$

This finishes the proof of the boundedness of $M_2(\rho_k^h)$.

We now show that the entropy $S(\rho_k^h)$ is also bounded. From (77) and (83), it follows that $S(\rho_k^h)$ is bounded from below. It remains to find an upper bound. Applying Lemma 5.1 for $n = k$, and noting that $F(\rho_k^h) \geq 0$, $\bar{W}_h(\rho_{i-1}^h, \rho_i^h) \geq 0$ for all i , we have

$$S(\rho_k^h) \leq \mathcal{A}(\rho_0) + Ch \sum_{i=0}^k M_2(\rho_i^h) + Ckh \leq Ch \sum_{i=1}^k M_2(\rho_i^h) + C[S(\rho_0) + M_2(\rho_0)] + 2CT_0. \quad (84)$$

By combining with (82) we obtain the upper bound for the entropy. This completes the proof of the lemma. \square

The following lemma extends Lemma 5.2 to any $T > 0$. The proof is the same as Lemma 5.3 in [17], and we omit it.

Lemma 5.3 *Let $\{\rho_k^h\}_{k \geq 1}$ be the sequence of the minimizers of Scheme 2a or Scheme 2b for fixed $h > 0$. For any $T > 0$, there exists a constant $C > 0$ depending on T and on the initial data such that*

$$M_2(\rho_k^h) \leq C, \quad (85)$$

$$\sum_{i=1}^k W_h^*(\rho_{i-1}^h, \rho_i^h) \leq Ch, \quad (86)$$

$$\int_{\mathbb{R}^{2d}} \max\{\rho_k^h \log \rho_k^h, 0\} dqdp \leq C, \quad (87)$$

for any $h \leq h_0$ and $k \leq K_h$, where

$$K_h = \left\lceil \frac{T}{h} \right\rceil.$$

For Scheme 2c the same inequalities hold, with (86) replaced by

$$\sum_{i=1}^k W_h(\mu_i^h, \rho_i^h) \leq Ch.$$

6. Proof of Theorem 2.4

In this section we bring all the parts together to prove Theorem 2.4. The structure of this proof is the same as that of e.g. [20, 17], and we refer to those references for the parts that are very similar. The main difference lies in the convergence of the discrete Euler-Lagrange equations for each of the cases to the weak formulation of the Kramers equation as $h \rightarrow 0$.

Throughout we fix $T > 0$ and for each $h > 0$ we set

$$K_h := \lceil T/h \rceil.$$

The proof of the space-time weak compactness (36) is the same for the three schemes. Let $(\rho_k^h)_k$ be the sequence of minimizers constructed by any of the three schemes, and let $t \mapsto \rho^h(t)$ be the piecewise-constant interpolation (35). By Lemma 5.3 we have

$$M_2(\rho^h(t)) + \int_{\mathbb{R}^{2d}} \max\{\rho^h(t) \log \rho^h(t), 0\} dq dp \leq C, \quad \text{for all } 0 \leq t \leq T. \quad (88)$$

Since the function $z \mapsto \max\{z \log z, 0\}$ has super-linear growth, (88) guarantees that there exists a subsequence, denoted again by ρ^h , and a function $\rho \in L^1((0, T) \times \mathbb{R}^{2d})$ such that

$$\rho^h \rightarrow \rho \text{ weakly in } L^1((0, T) \times \mathbb{R}^{2d}). \quad (89)$$

This proves (36).

The proof of the stronger convergence (37) and of the continuity (38) at $t = 0$ follows the same lines as in [20, 17]. The main estimate is the ‘equi-near-continuity’ estimate

$$d(\rho^h(t_1), \rho^h(t_2))^2 \leq C(|t_2 - t_1| + h),$$

where $d(\rho_0, \rho_1)$ is the metric generated by the quadratic cost $|q - q'|^2 + |p - p'|^2$. This estimate follows from the inequality (see (39))

$$|q - q'|^2 + |p - p'|^2 \leq C[C_h^*(q, p; q', p') + h^2 N(q, p) + h^2 N(q', p')],$$

and the estimates (88) and (86); see [17, Theorem 5.2].

The only remaining statement of Theorem 2.4 is the characterization of the limit in terms of the solution of the Kramers equation, and we now describe this.

Let ρ^h be generated by one of the three schemes. We now prove that the limit ρ satisfies the weak version of the Kramers equation (34). Fix $T > 0$ and $\varphi \in C_c^\infty((-\infty, T) \times \mathbb{R}^{2d})$; all constants C below depend on the parameters of the problem, on the initial datum ρ_0 , and on φ , but are independent of k and of h . We first discuss Schemes 2a and 2b.

Let $P_k^{h*} \in \Gamma(\rho_{k-1}^h, \rho_k^h)$ be the optimal plan for $W_h^*(\rho_{k-1}^h, \rho_k^h)$, where the star indicates the quantities associated with either Scheme 2a or Scheme 2b. For any $0 < t < T$, we have

$$\begin{aligned} & \int_{\mathbb{R}^{2d}} [\rho_k^h(q, p) - \rho_{k-1}^h(q, p)] \varphi(t, q, p) dq dp \\ &= \int_{\mathbb{R}^{2d}} \rho_k^h(q', p') \varphi(t, q', p') dq' dp' - \int_{\mathbb{R}^{2d}} \rho_{k-1}^h(q, p) \varphi(t, q, p) dq dp \\ &= \int_{\mathbb{R}^{4d}} [\varphi(t, q', p') - \varphi(t, q, p)] P_k^{h*}(dq dp dq' dp') \\ &= \int_{\mathbb{R}^{4d}} [(q' - q) \cdot \nabla_{q'} \varphi(t, q', p') + (p' - p) \cdot \nabla_{p'} \varphi(t, q', p')] P_k^{h*}(dq dp dq' dp') + \varepsilon_k, \end{aligned} \quad (90)$$

where

$$\begin{aligned} |\varepsilon_k| &\leq C \int_{\mathbb{R}^{4d}} [|q' - q|^2 + |p' - p|^2] P_k^{h*}(dq dp dq' dp') \\ &\stackrel{(39)}{\leq} C W_h^*(\rho_{k-1}^h, \rho_k^h) + C h^2 [M_2(\rho_{k-1}^h) + M_2(\rho_k^h)] \\ &\stackrel{(88)}{\leq} C W_h^*(\rho_{k-1}^h, \rho_k^h) + C h^2. \end{aligned} \quad (91)$$

By combining (90) with (61) we find

$$\begin{aligned} & \int_{\mathbb{R}^{2d}} \left(\frac{\rho_k^h(t, q, p) - \rho_{k-1}^h(t, q, p)}{h} \right) \varphi(t, q, p) dq dp \\ &= \int_{\mathbb{R}^{2d}} \left[\frac{p}{m} \cdot \nabla_q \varphi(t, q, p) - (\nabla V(q) + \gamma \nabla F(p)) \cdot \nabla_p \varphi(t, q, p) + \gamma \beta^{-1} \Delta_p \varphi(t, q, p) \right] \rho_k^h(q, p) dq dp \\ & \quad + \theta_k(t), \end{aligned} \quad (92)$$

where

$$\begin{aligned} |\theta_k(t)| &\leq \frac{|\varepsilon_k|}{h} + Ch[W_h^*(\rho_{k-1}^h, \rho_k^h) + M_2(\rho_{k-1}^h) + M_2(\rho_k^h) + 1] \\ &\stackrel{(88),(91)}{\leq} \frac{C}{h}W_h^*(\rho_{k-1}^h, \rho_k^h) + Ch. \end{aligned} \quad (93)$$

Note that θ_k depends on t through the t -dependence of φ . Next, from (92), for $k \geq 1$ we have

$$\begin{aligned} &\int_{(k-1)h}^{kh} \int_{\mathbb{R}^{2d}} \left(\frac{\rho_k^h(q, p) - \rho_{k-1}^h(q, p)}{h} \right) \varphi(t, q, p) dq dp dt \\ &= \int_{(k-1)h}^{kh} \int_{\mathbb{R}^{2d}} \left[\frac{p}{m} \cdot \nabla_q \varphi(t, q, p) - (\nabla V(q) + \gamma \nabla F(p)) \cdot \nabla_p \varphi(t, q, p) + \gamma \beta^{-1} \Delta_p \varphi(t, q, p) \right] \rho_k^h(q, p) dq dp dt \\ &\quad + \int_{(k-1)h}^{kh} \theta_k(t) dt \\ &= \int_{(k-1)h}^{kh} \int_{\mathbb{R}^{2d}} \left[\frac{p}{m} \cdot \nabla_q \varphi(t, q, p) - (\nabla V(q) + \gamma \nabla F(p)) \cdot \nabla_p \varphi(t, q, p) + \gamma \beta^{-1} \Delta_p \varphi(t, q, p) \right] \rho^h(t, q, p) dq dp dt \\ &\quad + \int_{(k-1)h}^{kh} \theta_k(t) dt. \end{aligned}$$

Summing from $k = 1$ to K_h we obtain

$$\begin{aligned} &\sum_{k=1}^{K_h} \int_{(k-1)h}^{kh} \int_{\mathbb{R}^{2d}} \left(\frac{\rho_k^h(q, p) - \rho_{k-1}^h(q, p)}{h} \right) \varphi(t, q, p) dq dp dt \\ &= \int_0^T \int_{\mathbb{R}^{2d}} \left[\frac{p}{m} \cdot \nabla_q \varphi(t, q, p) - (\nabla V(q) + \gamma \nabla F(p)) \cdot \nabla_p \varphi(t, q, p) + \gamma \beta^{-1} \Delta_p \varphi(t, q, p) \right] \rho^h(t, q, p) dq dp dt \\ &\quad + R_h, \end{aligned} \quad (94)$$

where

$$R_h = \sum_{k=1}^{K_h} \int_{(k-1)h}^{kh} \theta_k(t) dt. \quad (95)$$

By a discrete integration by parts, we can rewrite the left hand side of (94) as

$$- \int_0^h \int_{\mathbb{R}^{2d}} \rho_0(q, p) \frac{\varphi(t, q, p)}{h} dq dp dt + \int_0^T \int_{\mathbb{R}^{2d}} \rho^h(t, q, p) \left(\frac{\varphi(t, q, p) - \varphi(t+h, q, p)}{h} \right) dq dp dt. \quad (96)$$

From (94) and (96) we obtain

$$\begin{aligned} &\int_0^T \int_{\mathbb{R}^{2d}} \rho^h(t, q, p) \left(\frac{\varphi(t, q, p) - \varphi(t+h, q, p)}{h} \right) dq dp dt \\ &= \int_0^T \int_{\mathbb{R}^{2d}} \left[\frac{p}{m} \cdot \nabla_q \varphi(t, q, p) - (\nabla V(q) + \gamma \nabla F(p)) \cdot \nabla_p \varphi(t, q, p) + \gamma \beta^{-1} \Delta_p \varphi(t, q, p) \right] \rho^h(t, q, p) dq dp dt \\ &\quad + \int_0^h \int_{\mathbb{R}^{2d}} \rho_0(q, p) \frac{\varphi(t, q, p)}{h} dq dp dt + R_h. \end{aligned} \quad (97)$$

Now $R_h \rightarrow 0$ as $h \rightarrow 0$, since

$$\begin{aligned} |R_h| &\stackrel{(95)}{\leq} \sum_{k=1}^{K_h} \int_{(k-1)h}^{kh} |\theta_k(t)| dt \stackrel{(93)}{\leq} C \sum_{k=1}^{K_h} \int_{(k-1)h}^{kh} \left(\frac{1}{h} W_h^*(\rho_{k-1}^h, \rho_k^h) + h \right) dt \\ &= C \sum_{k=1}^{K_h} [W_h^*(\rho_{k-1}^h, \rho_k^h) + Ch^2] \stackrel{(86)}{\leq} Ch. \end{aligned}$$

Taking the limit $h \rightarrow 0$ in (97) yields equation (34).

For Scheme 2c, only (90) is different:

$$\begin{aligned} & \int_{\mathbb{R}^{2d}} [\rho_k^h(q, p) - \rho_{k-1}^h(q, p)] \varphi(t, q, p) dq dp \\ &= \int_{\mathbb{R}^{2d}} \rho_k^h(q', p') \varphi(t, q', p') dq' dp' - \int_{\mathbb{R}^{2d}} \rho_{k-1}^h(q, p) \varphi(t, q, p) dq dp \\ &= \int_{\mathbb{R}^{2d}} \rho_k^h(q', p') \varphi(t, q', p') dq' dp' - \int_{\mathbb{R}^{2d}} \mu_k^h(q, p) \varphi(t, \sigma_h(q, p)) dq dp \\ &= \int_{\mathbb{R}^{4d}} \left[\varphi(t, q', p') - \varphi\left(t, q - \frac{p}{m}h, p + \nabla V(q)h\right) \right] P_k^h(dq dp dq' dp') \\ &= \int_{\mathbb{R}^{4d}} \left[(q' - q + \frac{p}{m}h) \cdot \nabla_{q'} \varphi(t, q', p') + (p' - p - \nabla V(q)h) \cdot \nabla_{p'} \varphi(t, q', p') \right] P_k^h(dq dp dq' dp') + \varepsilon_k, \end{aligned}$$

where

$$|\varepsilon_k| \leq C \int_{\mathbb{R}^{4d}} \left(\gamma^2 \left| q' - q + \frac{p}{m}h \right|^2 + |p' - p - \nabla V(q)h|^2 \right) P_k^h(dq dp dq' dp')$$

with the constant C depending only on φ . Since $|p' - p|^2, |q' - q|^2 \leq CC_h(q, p; q', p')$ and $|\nabla V(q)|^2 \leq C|q|^2$,

$$\begin{aligned} \gamma^2 \left| q' - q + \frac{p}{m}h \right|^2 + |p' - p - \nabla V(q)h|^2 &\leq 2 \left(\gamma^2 |q - q'|^2 + \frac{\gamma^2 h^2}{m^2} |p|^2 + |p - p'|^2 + h^2 |\nabla V(q)|^2 \right) \\ &\leq CC_h(q, p; q', p') + Ch^2 N(q, p). \end{aligned}$$

Therefore

$$\begin{aligned} |\varepsilon_k| &\leq C \int_{\mathbb{R}^{4d}} [C_h(q, p; q', p') + h^2 N(q, p) + h^2] P_k^h(dq dp dq' dp') \\ &= CW_h(\mu_k^h, \rho_k^h) + CM_2(\mu_k^h)h^2 + Ch^2 \\ &\leq CW_h(\mu_k^h, \rho_k^h) + Ch^2. \end{aligned}$$

The rest of the proof is the same.

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