A Note on Bivariate

Box Splines on a k-direction Mesh

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This research was initiated while working at IBM Research Laboratories, Yorktown Heights, New York, Summer 1983 and was supported in part by the National Science Foundation under Grant DCR-82-14322. Abstract.

We determine the dimension of the polynomial subspace of the linear space spanned by the translates over lattice points of a bivariate box spline on a k-direction mesh.

Keywords: Box spline, k-direction mesh.

1. Introduction.

Box splines were introduced by de Boor and De Vore, [1], and systematically studied by de Boor and Hollig in [2,3] and by Dahmen and Micchelli in [4,5,7].

For box splines on a k-direction mesh in an s-dimensional space, one is interested in the dimension of the polynomial subspace of the linear space spanned by the translates of a box spline over lattice points in 2^{S} , since this dimension is closely related to the rate of approximation using box splines. This problem has been solved for the case s = 2 and k = 4. For the proof see [4]. For the general case, the result has been announced in a recent paper [6]. The authors suggest to prove it by employing an induction. In this paper, we provide a proof of this result for the case of bivariate box splines (i.e., s = 2) and arbitrary k. Our proof does not use induction.

A k-direction mesh is a set of vectors

(1.1)
$$X = \{\underbrace{v^1, \ldots, v^1}_{m_1}, \ldots, \underbrace{v^k, \ldots, v^k}_{m_k}\},$$

where $v^{i} = (\alpha_{i}, \beta_{i}) \in \mathbf{g}^{2}$, \mathbf{z} is the set of integers, and $\beta_{i} \ge 0$, $\alpha_{i}\beta_{j} \ne \alpha_{j}\beta_{i}$ for $i \ne j$, $m_{i} \ge 1$, i, j = 1, ..., k, $k \ge 2$. Let (1.2)

(1.2)
$$n = \sum_{i=1}^{n} m_{i}$$
 and $d = \min\{n - m_{i}\} - 1$.

Then there exists a unique function $B(\cdot | X)$ in R^2 , called a box spline on a k-direction mesh, such that

(1.3)
$$\int_{R^{2}} f(x, y) B((x, y) | x) dx dy = \int_{0}^{1} \dots \int_{0}^{1} f(t_{1} v^{1} + \dots + t_{n} v^{k}) x dt_{1} \dots dt_{n}$$

for all $f \in C(\mathbb{R}^2)$. The box spline $B(\cdot | X)$ is a piecewise polynomial in $C^{d-1}(\mathbb{R}^2)$ where d is given in (1.2), and has compact support [2,3].

Let S(X) be the linear span of translates of the box spline over lattice points in 2^2 , i.e.,

(1.4)
$$S(X) = \operatorname{span}(\{B(\cdot - (\alpha, \beta) | X) : (\alpha, \beta) \in \mathbb{Z}^2\}).$$

We are particularly interested in the subspace $S_{\pi}(X)$ of polynomials in S(X). Let

$$Q_{\ell}(\mathbf{x},\mathbf{y}) = \prod_{i \neq \ell} (\alpha_{i}\mathbf{x} + \beta_{i}\mathbf{y})^{m_{i}},$$

and let

(1.5)
$$Q_{\ell}(D) = \prod_{i \neq \ell} (\alpha_i \frac{\partial}{\partial x} + \beta_i \frac{\partial}{\partial y})^{m_i}.$$

It was proved [3,6,7] that $S_{\pi}(X)$ is of finite dimension and that

(1.6) $S_{\pi}(X) = \mathfrak{D}(X)$,

where

(1.7) $\mathfrak{Y}(X) = \{f: Q_{\ell}(D) \ f=0, \ \ell=1, \ldots, k\}.$

It was proved [3]

<u>Theorem 1.1</u>: If $det(v^i, v^j) = 1$ for each pair of vectors in X which spans R^2 , then

(1.8) $\dim S_{\pi}(X) = \dim \mathfrak{D}(X) = A(X),$

where A(X) is the area of the support of $B(\cdot|X)$.

A simple example is the case of a 3-direction mesh, where $X = \{\underbrace{e^1, \ldots, e^1}_{m_1}, \underbrace{e^{1} + e^2, \ldots, e^{1} + e^2}_{m_2}, \underbrace{e^2, \ldots, e^2}_{m_3}\}, e^1 = (1.0),$

 $e^2 = (0, 1)$. We have

$$\dim_{\pi} S(X) = \dim \mathfrak{D}(X) = A(X) = \Sigma_{1 \le i \le j \le 3} \underset{i \le j \le 3}{\operatorname{m}_{i}} m_{j}.$$

In general, the condition in Theorem 1.1 does not hold, as in the case of a 4-direction mesh, where

$$x = \{\underbrace{e^{1}, \ldots, e^{1}}_{m_{1}}, \underbrace{e^{1} + e^{2}, \ldots, e^{1} + e^{2}}_{m_{2}}, \underbrace{e^{2}, \ldots, e^{2}}_{m_{3}}, \underbrace{e^{2} - e^{1}, \ldots, e^{2} - e^{1}}_{m_{4}}\},$$

since $det(e^{1}+e^{2},e^{2}-e^{1}) = 2$. We address this problem in section 2.

2. Box splines on a k-direction mesh.

For a k-direction mesh as given in (1.1), we give the dimension of $S_{\pi}(X)$ in Theorem 2.1.

Lemma 2.1: Let $(\alpha_i, \beta_i) \in \mathbb{Z}^2$ with $\alpha_i \beta_j \neq \alpha_j \beta_i$, i, j = 1, ..., k, and let $G_j(\lambda) = \prod_{i \neq j} (\alpha_i + \beta_i \lambda)^{n_i}$, where $m_i \ge 1$. Then for all distinct $\lambda_0, \ldots, \lambda_{n-1}$, the following matrix is nondegenerate:

$$(2.1) \qquad M_{n} = \begin{pmatrix} G_{1}(\lambda_{0}) & \cdots & \cdots & G_{1}(\lambda_{n-1}) \\ \lambda_{0}G_{1}(\lambda_{0}) & \cdots & \ddots & \lambda_{n-1}G_{1}(\lambda_{n-1}) \\ \vdots & \vdots & \vdots \\ m_{1}^{-1} & m_{1}^{-1} & m_{1}^{-1} \\ \lambda_{0} & G_{1}(\lambda_{0}) & \cdots & \lambda_{n-1}G_{1}(\lambda_{n-1}) \\ \vdots & \vdots & \vdots \\ G_{k}(\lambda_{0}) & \cdots & \cdots & G_{k}(\lambda_{n-1}) \\ \lambda_{0}G_{k}(\lambda_{0}) & \cdots & \cdots & \lambda_{n-1}G_{k}(\lambda_{n-1}) \\ \vdots & \vdots & \vdots \\ m_{k}^{-1} & m_{k}^{-1} & m_{k}^{-1} \\ \lambda_{0} & G_{k}(\lambda_{0}) & \cdots & \cdots & \lambda_{n-1}G_{k}(\lambda_{n-1}) \end{pmatrix}$$

where $n = \sum_{i=1}^{k} m_i$.

Proof: The matrix M_n is nondegenerate for any choice of distinct λ_j , j=0,...,n-1, if and only if for any vector a, $M_n a = 0$ implies a = 0. Let

$$a^{T} = (a_{1,0}, a_{1,1}, \dots, a_{1,m_{1}}, \dots, a_{k,0}, a_{k,0}, \dots, a_{k,m_{k}}, \dots, a_{k,m_{k$$

and let $P_{\ell}(x) = a_{\ell,0} + a_{\ell,1}x + \cdots + a_{\ell,m_{\ell}-1}x^{m_{\ell}-1}x^{\ell}$, $\ell=1,\ldots,k$. Then $\sum_{\ell=1}^{k} P_{\ell}(x) G_{\ell}(x)$ vanishes at all the n distinct λ_{j} , since $M_{n}a = 0$. On the other hand, $\sum_{\ell=1}^{k} P_{\ell}(x) G_{\ell}(x)$ is a polynomial of degree less than n, hence must be identically zero. But then since all summands except for the ℓ -th one have the factor $(\alpha_{\ell}+\beta_{\ell}x)^{m_{\ell}}$, the ℓ -th summand must also have it and, since G_{ℓ} does not have it, P_{ℓ} must have it, and that is possible only when $P_{\ell} = 0$. This shows that a = 0, as required. \square

<u>Remark 2.1</u>: We choose distinct $\lambda_0, \dots, \lambda_{n-1}$ with $\lambda_i \neq 1, 0, 1$, $\alpha_j + \beta_j \lambda_i \neq 0, j = 1, \dots, k, i = 0, \dots, n-1$, such that M_n in (2.1) is non-degenerate, and we denote this matrix with fixed $\lambda_i \approx M_n^*$.

We are ready to prove

Theorem 2.1: Let X be a k-direction mesh. Then

(2.2) $\dim S_{\pi}(X) = \sum_{1 \leq i < j \leq k} m_{i}m_{j}.$

<u>Proof:</u> In the proof we denote the differential operator $Q_{l}(D)$ by Q_{l} , l=1,...,k. Since $S_{\pi}(X) = \mathfrak{J}(X)$, we need only to derive the

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dimension of the space $\mathfrak{P}(X)$. Let Π_j be the linear space of all homogeneous polynomials of degree j. Observe that $\Pi_i \cap \Pi_j = \{0\}$ for $i \neq j$ and that $\{(x+\lambda_{0j}y)^j, (x+\lambda_{1j}y)^j, \ldots, (x+\lambda_{jj}y)^j\}$ is a basis of Π_j for arbitrary distinct λ_{ij} , $i=0,\ldots,j$, with $\lambda_{ij}\neq-1,0,1$. Since $\mathfrak{P}(X)$ is a finite dimensional linear space of polynomials, $\mathfrak{P}(X)$ is a subspace of $\Pi_0 \oplus \cdots \oplus \Pi_N$ for sufficiently large N. Let $S_j = \mathfrak{P}(X) \cap \Pi_j$. Then $S_i \cap S_j = \{0\}$ for $i\neq j$, and

therefore $S_0 \oplus \cdots \oplus S_N$ is well defined. We prove that

(2.3)
$$\mathfrak{Y}(X) = S_0 \oplus \cdots \oplus S_N.$$

Indeed, $S_0 \oplus \cdots \oplus S_N \subseteq \mathfrak{I}(X)$ by the definition of S_j . To show that $\mathfrak{I}(X) \subseteq S_0 \oplus \cdots \oplus S_N$, take arbitrary $f \in \mathfrak{I}(X)$, and $f = \sum_{j=0}^{N} f_j$, where $f_j \in \pi_j$. Due to (1.7), $Q_{\ell}f = \sum_{j=0}^{N} Q_{\ell}f_j = 0$, $\ell = 1, \ldots, k$. By (1.5), we know that for i < j and $Q_{\ell}f_j \neq 0$, $\deg(Q_{\ell}f_i) < \deg(Q_{\ell}f_j)$. Thus $Q_{\ell}f_j = 0$, $\ell = 1, \ldots, k$, $j = 0, \ldots, N$, i.e., $f_j \in S_j$, $j = 0, \ldots, N$. This means that $\mathfrak{I}(X) \leq S_0 \oplus \cdots \oplus S_N$, which completes the proof of (2.3).

To derive dim \mathfrak{I} we compute dim S_j , j = 0, ..., N, since

dim
$$\mathfrak{D}(X) = \Sigma$$
 dim S_j, due to (2.3). Let $f \in S_j$. Then
 $j=0$

(2.4)
$$f(x,y) = \sum_{i=0}^{j} a_{ij}(x+\lambda_{ij}y)^{j},$$

and

(2.5)
$$Q_{\varrho}f = 0, \ \ell = 1, \dots, k.$$

Let
$$q_{\ell} = \deg Q_{\ell} = n - m_{\ell}$$
, where $n = \sum_{\ell=1}^{k} m_{\ell}$. Since

$$(2.6) \qquad (\alpha \frac{\partial}{\partial x} + \beta \frac{\partial}{\partial y})^{m} (x + \lambda y)^{j}$$

$$= \begin{cases} 0, & \text{if } m > j, \\ j(j-1)\cdots(j-m+1)(\alpha+\beta\lambda)^{m}(x+\lambda y)^{j-m}, & \text{if } m \leq j, \end{cases}$$

from (2.4) we have

Since $S_{\pi}(X)$ is the polynomial subspace of the linear space spanned by the translates of a box spline for which there are only n directions, polynomials in $S_{\pi}(X)$ have degree less than n. Thus we only need to derive dim S_{j} , for $j=0,1,\ldots,n-1$.

From (2.7) we have

(2.8)
$$\begin{cases} Q_{\ell}f = 0, & \text{if } q_{\ell} \ge j+1, \\ \\ Q_{\ell}f = \sum_{i=0}^{j} a_{ij} j(j-1) \cdots (j-q_{\ell}+1)Q_{\ell}(1,\lambda_{ij}) (x+\lambda_{ij}y) \\ \\ \end{bmatrix}^{j-q_{\ell}}, \end{cases}$$

From (2.5) and (2.8), we have a system of equation in a_{ij} :

(2.9)
$$\int_{z}^{J} a_{ij} Q_{\ell}(1,\lambda_{ij}) \lambda_{ij}^{r} = 0, r=0,\ldots,j-q_{\ell}; q_{\ell} \leq j,$$
$$i=0$$

and the coefficient matrix M_j of (2.9) consists of blocks $B_{l,j}$:

$$B_{\ell,j} = \begin{pmatrix} Q_{\ell}(1,\lambda_{0j}) & \cdots & \cdots & Q_{\ell}(1,\lambda_{jj}) \\ \lambda_{0j}Q_{\ell}(1,\lambda_{0j}) & \cdots & \ddots & \lambda_{jj}Q_{\ell}(1,\lambda_{jj}) \\ \vdots & & \vdots \\ \lambda_{0j}Q_{\ell}(1,\lambda_{0j}) & \cdots & \lambda_{jj}Q_{\ell}(1,\lambda_{jj}) \end{pmatrix}$$

Since $j \leq n-1$, $j-q_{\ell} = j - (n-m_{\ell}) = m_{\ell} - (n-j) \leq m_{\ell} - 1$, M_{j} is a submatrix of M_{n}^{\star} in Remark 2.1, and is contained in $\sum_{\ell=1}^{k} (j+1-q_{\ell})_{+}$ rows. Notice that $j+1 \geq \sum_{\ell=1}^{k} (j+1-q_{\ell})_{+}$, for $j \leq n-1$, since we get equality when j + 1 = n. Since M_{n}^{\star} is non-degenerate, we can find j+1 columns, such that the $\sum_{\ell=1}^{k} (j+1-q_{\ell})_{+}$ by (j+1) submatrix of M_{n}^{\star} , corresponding to M_{j} , is of rank $\sum_{\ell=1}^{k} (j+1-q_{\ell})_{+}$. Use the $j+1 \quad \lambda_{i}$'s in M_{n}^{\star} , corresponding to the j+1 chosen columns as $\lambda_{0,j}, \dots, \lambda_{j,j}$ in (2.4) and (2.9), and M_j is obviously of rank $k \atop_{l=1}^{k} (j+1-q_l)_+$. Since the number of a_{ij} 's, j+1, is no less than $k \atop_{l=1}^{l} (j+1-q_l)_+$, the number of equations in (2.9), and the coefficient matrix of (2.9), M_j , is non-degenerate, the solution space of (2.9) is of dimension (i+1) = k (i+1-q_l) = which is the dimension of S_{l} .

(j+1) - $\sum_{l=1}^{k} (j+1-q_l)_+$, which is the dimension of S_j. So

$$\sum_{j=0}^{n-1} \dim S_{j} = \sum_{j=0}^{n-1} [(j+1) - \sum_{\ell=1}^{k} (j+1-q_{\ell})_{+}]$$

$$= \sum_{j=1}^{n} j - \sum_{\ell=1}^{k} \sum_{j=1}^{m_{\ell}} j = \sum_{\substack{1 \le i \le j \le k}} m_{i}m_{j},$$

since

 $\sum_{j=0}^{n-1} (j+1-q_{\ell})_{+} = 1 + \cdots + n-q_{\ell} \text{ and } n-q_{\ell} = m_{\ell}.$

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