Robotic Protein Crystal Streak Seeding Using Silicon Microtools

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Introduction

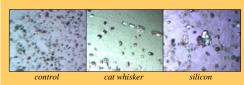
Automated streak seeding of 96-well plates

Problems:

- Tools for seeding
- Crystal detection in image
- Droplet location in image
- Robotic streak seeding system

Streak Seeding With Silicon

- A cat whisker is normally used for manual seeding by crystallographers
- Cat whiskers are not rigid
- Difficult to:
- Track in image
- Locate tip
- Detect contact
- Silicon microtools produce good seeding results



Design and Fabrication

Created CAD designs of over 30 different shapes and sizes of *microshovels*



- Used MEMS technology (photolithography, DRIE) to manufacture over 100 tooltips out of silicon wafers
- Microshovels used for both streak seeding and crystal mounting





Seeding Steps

1. Wash tool in bucket



Crystal Detection

Detect edges in

Fill in holes and

Clean up using

morphological

The original image

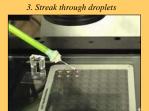
with the boundary

of detected crystals overlaid

operators

threshold

image



Droplet Location

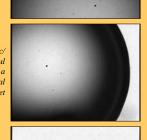
3a/ Successful detection of a small offset







Successful detection of a large diagonal offset





Prototype Microrobotic Streak Seeding System







Sample Seeding Run



1. Initial image



2. Detected crystals



crystal 1



5. Droplet center located



4. Probe poking crystal 2



droplet

Conclusions

- Progress toward automated crystal seeding
- Designed and manufactured new tools to address limitations of traditional cat whiskers
- New tools can be used for both manual and automatic
- Built a functional prototype of a microrobotic seeding

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