


# Giving Neurons to Sensors: An Approach to QoS Management Through Artificial Intelligence

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**Abstract.** For the latest ten years, many authors have focused their investigations in wireless sensor networks. Different researching issues have been extensively developed: power consumption, MAC protocols, self-organizing network algorithms, data-aggregation schemes, routing protocols, QoS management, etc. Due to the constraints on data processing and power consumption, the use of artificial intelligence has been historically discarded. However, in some special scenarios the features of neural networks are appropriate to develop complex tasks such as path discovery. In this paper, we explore the performance of two very well known routing paradigms, *directed diffusion* and *Energy-Aware Routing*, and our routing algorithm, named **SIR**, which has the novelty of being based on the introduction of neural networks in every sensor node. Extensive simulations over our wireless sensor network simulator, OLIMPO, have been carried out to study the efficiency of the introduction of neural networks. A comparison of the results obtained with every routing protocol is analyzed. This paper attempts to encourage the use of artificial intelligence techniques in wireless sensor nodes.

**Keywords:** Wireless sensor networks (WSN); Ad hoc networks, Quality of service (QoS); Artificial neural networks (ANN); Routing; Self-Organizing Map (SOM), ubiquitous computing.

## 1 Introduction

In recent years technological advances have made the manufacturing of small and low-cost sensors economically and technically possible. These sensors can be used to measure ambient conditions in the environment surrounding them. Typically, wireless sensor networks (WSNs) contain hundreds or thousands of those sensors nodes. Due to the sensor features (low-power consumption, low radio range, low memory, low processing capacity, and low cost), self-organizing network is the best suitable network architecture to support applications in such a scenario. Goals like efficient energy management [1], high reliability and availability, communication security, and robustness have become very important

issues to be considered. This is one of the many reasons why we can not neglect the study of the collision effects and the noise influence.

Many research centers worldwide (specially in Europe and USA) have focused their investigations on this kind of networks. Ian Akyldiz et al. [2] and Holger Karl et al. [3] have made great effort to describe the state-of-the-art of this subject.

Our research group, Computer Science for Industrial Applications, from the University of Seville, is working on the development of protocols and system architectures on Wireless Sensor Networks to support Supervisory Control and Data Acquisition (SCADA) applications. We present in this paper a new routing algorithm which introduces artificial intelligence (AI) techniques to measure the QoS supported by the network.

This paper is organized as follows. In section 2, we relate the main routing features we should consider in a network communication system. A description of the defined network topology is given. Section 3 introduces the use of neural networks in sensors for determining the quality of neighborhood links, giving a QoS model for routing protocols. The performance of the use of this technique in existing routing protocols for sensor networks is evaluated by simulation in section 4. Concluding remarks and future works are given on section 5.

## 2 Designing the Network Topology

The WSN architecture as a whole has to take into account different aspects, such as the protocol architecture; Quality-of-Service, dependability, redundancy and imprecision in sensor readings; addressing structures, scalability and energy requirements; geographic and data-centric addressing structures; aggregating data techniques; integration of WSNs into larger networks, bridging different communication protocols; etc.

Due to the desire to cover a large area, a communication strategy is needed. there are many studies that approach the problem of high connectivity in wireless ad hoc networks [4], [5]. In our research we consider a random distribution of sensors.

In general, routing in WSNs can be divided into *flat-based* routing, *hierarchical-base* routing, and *location-based* routing. In this paper we study networks where all nodes are supposed to be assigned equal roles or functionalities. In this sense, flat-based routing is best suited for this kind of networks.

Among all the existing flat routing protocols, we have chosen *directed diffusion* and *Energy-Aware Routing (EAR)* to evaluate the influence of the use of AI techniques.

In directed diffusion [6], sensors measure events and create gradients of information in their respective neighborhoods. The base station request data by broadcasting interests. Each sensor that receives the interest sets up a gradient toward the sensor nodes from which it has received the interest. This process continues until gradients are set up from the sources back to the base station.

EAR [7] is similar to directed diffusion. Nevertheless it differs in the sense that it maintains a set of paths instead of maintaining or enforcing one optimal

path at higher rates. These paths are maintained and chosen by means of a certain probability. The value of this probability depends on how low the energy consumption that each path can achieve is. By having paths chosen at different times, the energy of any single path will not deplete quickly.

### 3 Introducing Neurons in Sensor Nodes

The necessity of connectivity among nodes introduces the routing problem. In a WSN we need a multi-hop scheme to travel from a source to a destiny. The paths the packets have to follow can be established based on a specific criterion. Possible criteria can be minimum number of hops, minimum latency, maximum data rate, minimum error rate, etc. For example, imagine that all the nodes desire to have a path to route data to the *base station*<sup>1</sup>. In this situation, the problem is solved by a technique called *network backbone formation*.

Our approach to enhance this solution is based on the introduction of artificial intelligence techniques in the WSNs: expert systems, artificial neural networks, fuzzy logic and genetic algorithms. Due to the processing constraints we have to consider in a sensor node, the best suited, among all these techniques, is the *self-organizing-map (SOM)*. This is kind of artificial neural network based on the self organization concept.

SOM is an unsupervised neural network. The neurons are organized in an unidirectional two layers architecture. The first one is the input or sensorial layer, formed by  $m$  neurons, one per each input variable. These neurons work as buffers distributing the information sensed in the input space. The input is formed by stochastic samples  $\mathbf{x}(t) \in \mathcal{R}^m$  from the sensorial space. The second layer is usually formed by a rectangular grid with  $n \times n' \times y$  neurons. Each neuron  $(i, j)$  is represented by an  $m$ -dimensional weight or reference vector called *synapsis*,  $\mathbf{w}'_{ij} = [w'_{ij1}, w'_{ij2}, \dots, w'_{ijm}]$ , where  $m$  is the dimension of the input vector  $\mathbf{x}(t)$ . The neurons in the output layer -also known as the competitive Kohonen layer- are fully connected to the neurons in the input layer, meaning that every neuron in the input layer is linked to every neuron in the Kohonen layer. In SOM we can distinguish two phases: the ***learning phase***, in which, neurons from the second layer compete for the privilege of learning among each other, while the correct answer(s) is (are) not known; and the ***execution phase***, in which every neuron  $(i, j)$  calculates the similarity between the input vector  $\mathbf{x}(t)$ ,  $\{x_k \mid 1 \leq k \leq m\}$  and its own synaptic-weight-vector  $\mathbf{w}'_{ij}$ .

#### 3.1 Network Backbone Formation

This problem has been studied in mathematics as a particular discipline called *Graph Theory*, which studies the properties of graphs.

A *directed graph*  $G$  is an ordered pair  $G := (V, A)$  with  $V$ , a set of vertices or nodes,  $v_i$ , and  $A$ , a set of ordered pairs of vertices, called *directed edges*, *arcs*, or *arrows*.

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<sup>1</sup> In WSN, we often consider two kind of nodes, base stations and sensor nodes. There is usually only one base station.

An edge  $v_{xy} = (x, y)$  is considered to be directed from  $x$  to  $y$ ; where  $y$  is called the head and  $x$  is called the tail of the edge.

In 1959, E. Dijkstra proposed an algorithm that solves the single-source shortest path problem for a directed graph with nonnegative edge weights.

We propose a modification on Dijkstra's algorithm to form the network backbone, with the minimum cost paths from the base station or *root*,  $r$ , to every node in the network. We have named this algorithm Sensor Intelligence Routing, **SIR** [8].

### 3.2 Quality of Service in Wireless Sensor Networks

Once the backbone formation algorithm is designed, a way of measuring the edge weight parameter,  $w_{ij}$ , must be defined. On a first approach we can assume that  $w_{ij}$  can be modelled with the number of hops. According to this assumption,  $w_{ij} = 1 \ \forall \ i, j \in \mathcal{R}, i \neq j$ . However, imagine that we have another scenario in which the node  $v_j$  is located in a noisy environment. The collisions over  $v_j$  can introduce link failures increasing power consumption and decreasing reliability in this area. In this case, the optimal path from node  $v_k$  to the root node can be  $p'$ , instead of  $p$ . It is necessary to modify  $w_{ij}$  to solve this problem. The evaluation of the QoS in a specific area can be used to modify this parameter.

The traditional view of QoS in communication networks is concerned with end-to-end delay, packet loss, delay variation and throughput. Numerous authors have proposed architectures and integrated frameworks to achieve guaranteed levels of network performance [9]. However, other performance-related features, such as network reliability, availability, communication security and robustness are often neglected in QoS research. The definition of QoS requires some extensions if we want to use it as a criterion to support the goal of controlling the network. This way, sensors participate equally in the network, conserving energy and maintaining the required application performance.

We use a QoS definition based on three types of QoS parameters: timeliness, precision and accuracy. Due to the distributed feature of sensor networks, our approach measures the QoS level in a spread way, instead of an end-to-end paradigm. Each node tests every neighbor link quality with the transmissions of a specific packet named *ping*. With these transmissions every node obtains mean values of latency, error rate, duty cycle and throughput. These are the four metrics we have defined to measure the related QoS parameters.

Once a node has tested a neighbor link QoS, it calculates the distance to the root using the obtained QoS value. The expression 1 represents the way a node  $v_i$  calculates the distance to the root through node  $v_j$ , where  $gos$  is a variable whose value is obtained as an output of a neural network.

$$d(v_i) = d(v_j) \cdot gos \quad (1)$$

## 4 Performance Evaluation by Simulation

Due to the desire to evaluate the SIR performance, we have created two simulation experiments running on our wireless sensor network simulator OLIMPO

[10]. Every node in OLIMPO implements a neural network (SOM) running the execution phase (online processing).

#### 4.1 Radio Channel Analytical Performance Evaluation

In order to accurately model the sensor networks, the wireless channel is equipped with certain propagation models which allows sensors to determine the strength of the incoming signal. These models are integrated in the channel object of the simulation tool.

For the purpose of this research, the values shown in table 1 have been considered.

**Table 1.** Values of radio communication parameters

Resonating frequency <sup>†</sup> :	869.85 MHz	Communication bandwidth <sup>†</sup> $B$ :	0.5 %
Number of radio channels <sup>†</sup> :	1	Antenna gain <sup>‡</sup> :	$G_r = 1, G_t = 1$
Radio transmitter power:	$P_t = 5mW$	Radio receiver sensibility:	$P_s = -101dB$
System loss	$L = 1$	Path loss exponent:	$n = 2$
Modulation:	FSK	Transmission rate, $R$ :	4800 b/s
Input noise power density $N_{in}$ :	-174 dBm/Hz	Noise Figure $(NF)_{dB}$ :	10 dB

<sup>†</sup>Based on licensed free standard ETSI EN 301 291.

<sup>‡</sup>Antennas are assumed to be omnidirectional.

In this scenario, two sensor nodes attempting to establish a radio communication link can be 218 meters separated<sup>2</sup>. In our simulations we have assumed that the distance between every pair of sensor nodes is set up randomly. We have focused our simulation on a wireless sensor network composed by 250 nodes.

#### 4.2 Noise Influence

Noise influence over a node has been modelled as an Additive Gaussian White Noise, (AWGN), originating at the source resistance feeding the receiver. According to the radio communication parameters detailed in table 1 we can determine the signal-to-noise ratio at the detector input with the equation 2 [11],  $S/N_d = 26.7 dB$ . This signal-to-noise ratio can be expressed as an associated BER (Bit Error Rate)<sup>3</sup>. If  $S/N_d$  is less than 26.7 dB the receiver can't detect any data on air. An increase of the noise can degrade the BER. In another way, due to the relation between  $E_b/N_o$  and the transmission rate ( $R$ ),  $E_b/N_o = (S/R)/N_o$ , an increase of  $R$  can also degrade the BER.

$$(P_s)_{dBm} = (N_{in})_{dB} + (NF)_{dB} + (10 \log B)_{dB} + (S/N)_d \quad (2)$$

To evaluate the effect of noise we have defined a node state declared as *failure*. When the BER goes down below a required value (typically  $10^{-3}$ ) we assume

<sup>2</sup> According to free space propagation model [11].

<sup>3</sup> The minimum probability of bit error  $P_{e,min}$ , in a FSK system with an adaptative filter at the radio receiver, is typically expressed in the literature with the expression:

$$P_{e,min} = \frac{1}{2} \operatorname{erfc} \left( \sqrt{\frac{E_b}{N_o}} \right), \text{ where } \frac{E_b}{N_o} = \frac{(S/R)}{N_o} = \frac{S}{N}.$$

this node has gone to a failure state. We measure this metric as a percentage of the total lifetime of a node. In section 4 we describe two experiments according to different percentages of node failures.

### 4.3 SOM Creation

Our SOM has a first layer formed by four input neurons, corresponding with every metric defined in section 3.2 (latency, throughput, error rate and duty cycle); and a second layer formed by twelve output neurons forming a 3x4 matrix.

Next, we detail our SOM implementation process.

**Learning phase:** In order to organize the neurons in a two dimensional map, we need a set of input samples  $\mathbf{x}(t)=[\text{latency}(t), \text{throughput}(t), \text{error-rate}(t), \text{duty-cycle}(t)]$ . This samples should consider all the QoS environments in which a communication link between a pair of sensor nodes can work. In this sense, we have to simulate special ubiquitous computing environments. These scenarios can be implemented by different noise and data traffic simulations. In our research we create several WSNs over OLIMPO with 250 nodes and different levels of data traffic. The procedure to measure every QoS link between two neighbors is detailed as follows: every pair of nodes (eg.  $v_i$  and  $v_j$ ) is exposed to a level of noise. This noise is introduced increasing the noise power density  $N_o$  in the radio channel in the proximity of a determined node. Hence, the signal-to-noise ratio at the detector input of this selected node decreases and consequently the BER related with its links with every neighbor gets worse.

In order to measure the QoS metrics related with every  $N_o$ , we run a ping application between a selected pair of nodes (eg.  $v_i$  and  $v_j$ ). Node  $v_i$  sends periodically a ping message to node  $v_j$ . Because the ping requires acknowledgment (ACK), the way node  $v_i$  receives this ACK determines a specific QoS environment, expressed on the four metrics elected: latency (seconds), throughput (bits/sec), error rate (%) and duty cycle(%). For example, for a noise power density of  $N_o = -80 \text{ dBm/Hz}$  and a distance of separation<sup>4</sup> between node  $v_i$  and node  $v_j$  of 60 meters the QoS measured in node  $v_i$  and expressed in the metrics defined is [0.58, 1440, 10.95, 2.50]. This process is repeated 100 times with different  $N_o$  and  $d$ . This way, we obtain a set of samples which characterize every QoS scenario.

With this information, we construct a self-organizing map using a high performance neural network tool, such as MATLAB<sup>®</sup>, on a Personal Computer. This process is called *training*, and uses the learning algorithm. Because the training is not implemented by the wireless sensor network, we have called this process *offline processing*.

<sup>4</sup> Considering the free space propagation model, the power transmitted from the source decreases according to the expression  $P_r = P_t \left[ \frac{\lambda}{4\pi d L} \right]^2 G_t G_r$ , where  $P_r$ , is the radio power received at a distance  $d$  from the transmitter;  $P_t$  is the transmitter signal power,  $G_t$  and  $G_r$  are the antenna gains of the transmitter and the receiver respectively;  $L$  ( $L \leq 1$ ) is the *system loss* and  $\lambda$  is the electromagnetic wavelength.

Once we have ordered the neurons on the Kohonen layer, we identify each one of the set of 100 input samples with an output layer neuron. According to this procedure, the set of 100 input samples is distributed over the SOM.

The following phase is considered as the most difficult one. The samples allocated in the SOM form groups, in such a way that all the samples in a group have similar characteristics (latency, throughput, error rate and duty cycle). This way, we obtain a map formed by clusters, where every cluster corresponds with a specific QoS and is assigned a neuron of the output layer. Furthermore, a synaptic-weight matrix  $\mathbf{w}'_{ij} = [w'_{ij1}, w'_{ij2}, \dots, w'_{ij4}]$  is formed, where every synapsis identifies a connection between input and output layer.

In order to quantify the QoS level, we study the features of every cluster and, according to the QoS obtained in the samples allocated in the cluster, we assign a value between 0 and 10. As a consequence, we define an output function  $\Theta(i, j), i \in [1, 3], j \in [1, 4]$  with twelve values corresponding with every neuron  $(i, j), i \in [1, 3], j \in [1, 4]$ . The highest assignment (10) must correspond to that scenario in which the link measured has the worst QoS predicted. On the other hand, the lowest assignment (0) corresponds to that scenario in which the link measured has the best QoS predicted. The assignment is supervised by an engineer during the offline processing.

**Execution phase:** As a consequence of the learning phase, we have declared an output function, that has to be run in every sensor node. This procedure is named the *wining neuron election algorithm*.

In the execution phase, we create a WSN with 250 nodes. Every sensor node measures the QoS periodically running a ping application with every neighbor, which determines an input sample. After a node has collected a set of input samples, it runs the wining neuron election algorithm. For example, if a specific input sample is quite similar than the synaptic-weight-vector of neuron (2,2), this neuron will be activated. After the winning neuron is elected, the node uses the output function  $\Theta$  to assign a QoS estimation, *qos*. Finally, this value is employed to modify the distance to the root (eq. 1). Because the execution phase is implemented by the wireless sensor network, we have called this process *online processing*.

#### 4.4 Evaluating SIR Performance

Our SIR algorithm has been evaluated by the realization of three experiments detailed as follows.

**Experiment #1: No node failure.** The purpose of this experiment is to evaluate the introduction of AI techniques in a scenario where there is no node failure. This means that no node has gone to a failure state because of noise, collision or battery fail influence.

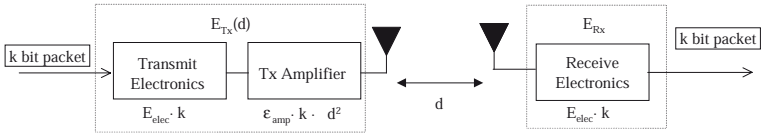
To simulate this scenario, a wireless sensor network with 250 nodes is created on our simulator OLIMPO. Node # 0 is declared as a sink and node # 22 is declared as a source. At a specific time, an event (eg. an alarm) is

provoked in the source. Consequently, the problem now is how to route the event from the specified source to the declared sink.

As detailed in section 2 we solve this problem with three different routing paradigms: SIR, directed diffusion and EAR. We choose two metrics to analyze the performance of SIR and to compare it to others schemes. These metrics are:

- Average dissipated energy. This metric computes the average work done by a node  $a$  in delivering useful tracking information to the sinks. This metric also indicates the overall lifetime of sensor nodes.

According to the first energy consumption order model proposed by Wendi Rabiner Heinzelman in the *LEACH* protocol [12], we can assume the radio dissipates  $E_{elec} = 50 \text{ nJ/bit}$  to run the transmitter or receiver or receiver circuitry, and  $\varepsilon_{amp} = 100 \text{ pJ/bit/m}^2$  for the transmit amplifier to achieve an acceptable  $\frac{E_b}{N_o}$  (figure 1). This way, to transmit a  $k$ -bit



**Fig. 1.** Energy model

message a distance  $d$  using this radio model<sup>5</sup>, the radio expends:

$$E_{Tx}(k, d) = E_{elec} \cdot k + \varepsilon_{amp} \cdot k \cdot d^2 \quad (3)$$

and to receive this message, the radio expends:

$$E_{Rx}(k) = E_{elec} \cdot k \quad (4)$$

We assume that the radio channel is symmetric, and that our simulation is *event-driven*, that is, sensors only transmit data if some event occurs in the environment. Due to transmission distance from a sensor node to the base station is large on a global scale, the transmission energy is much more higher than the received energy. In this network topology, as detailed in section 2, the most energy-efficient protocol is the minimum-transmission-energy.

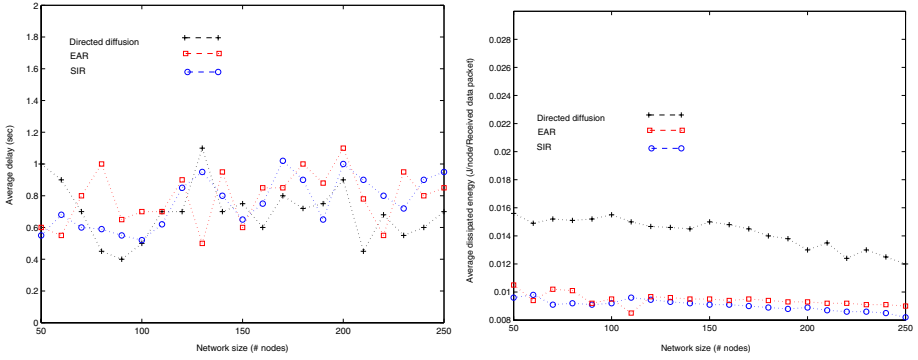
- Average Delay. This metric measures the average one-way latency observed between transmitting an event and receiving it at each sink.

We study these metrics as a function of sensor network size. The results are shown in figure 2.

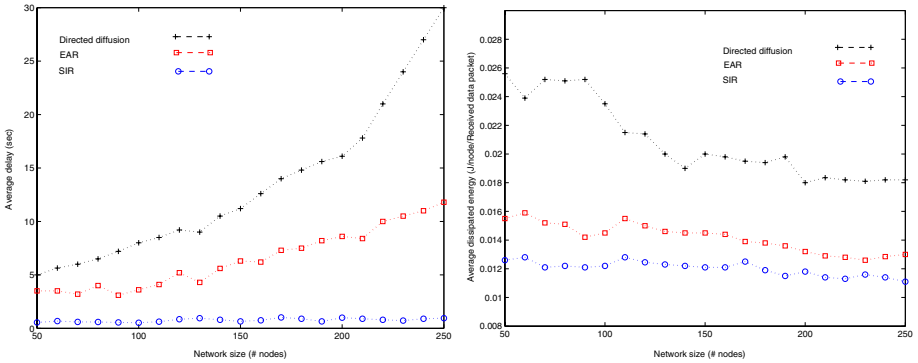
**Experiment #2: 20 % simultaneous node failures.** The purpose of this experiment is to evaluate the introduction of AI techniques in a scenario where there is a 20 % of simultaneous node failures. This means that at any

<sup>5</sup> We assume the radio propagation model.





**Fig. 2.** Average latency and average dissipated energy in a scenario with no simultaneous node failure



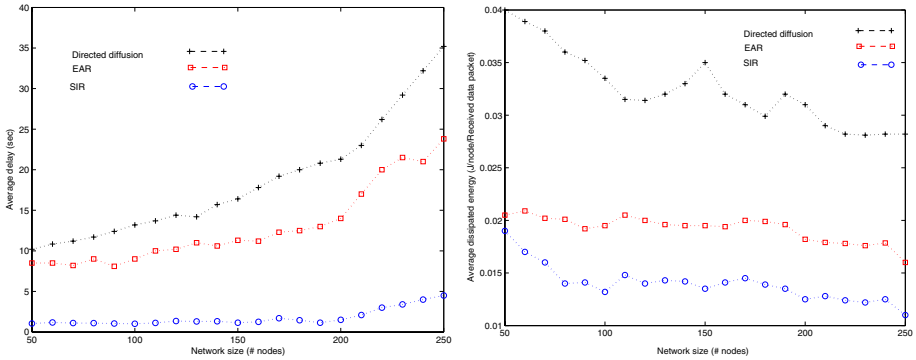
**Fig. 3.** Average latency and average dissipated energy in a scenario with 20 % simultaneous node failures

instant, 20 % of the nodes in the network are unusable because of noise, collision or battery failure influence.

To simulate these situations we create a WSN with 250 nodes. Amongst all of them, we select 20 % of the nodes (50) to introduce one of the following effects:

- $S/N$  ratio degradation. Due to battery energy loss, the radio transmitter power decays. Consequently, the  $S/N$  ratio in its neighbors radio receivers is degraded, causing no detections with a certain probability,  $P$ . In this situation, we can assume that the node affected by the lack of energy is prone to failure with probability  $P$ .
- In many actual occasions, sensor nodes are exposed to high level of noise, caused by inductive motors. Furthermore, the radio frequency band<sup>6</sup> is shared with other applications that can interfere with our WSN.

<sup>6</sup> The use of this band is regulated in Europe by the European Conference of Postal and Telecommunications Administrations (CEPT) and the European Telecommunications Standards Institute (ETSI) by the technical standard *EN 300 220-1*.



**Fig. 4.** Average latency and average dissipated energy in a scenario with 40 % simultaneous node failures

In these scenario we analyze the problem studied described in experiment #1 with the three paradigms related. The results are shown in figure 4.

**Experiment #3: 40 % simultaneous node failures.** This experiment simulates a scenario with a 40 % of simultaneous node failures.

## 5 Conclusion and Future Works

After comparing the results obtained with every routing paradigm, we can conclude that the differences are important when there is a significant percentage of node failures. Thus, while the average delay goes up with the number of sensors in directed diffusion and EAR, it maintains a low level of delay in SIR. The cause of this effect can be found in the fact that while directed diffusion and EAR elect the intermediate nodes using rules based on the propagation of the interest, SIR elects the intermediate nodes running an AI-algorithm. Thus, the path created by SIR avoids the election of intermediate nodes that are prone to failure because of battery draining, interference or noisy environment. Furthermore, the average dissipated energy is less in SIR when the number of nodes in the sensor goes up. We again find the reason in the effect of the election of the intermediate nodes in SIR. The use of AI in every sensor dynamically varies the assignment of this node role, distributing the energy consumption through the network. When the number of nodes is increased, the number of possible paths is increased too. Furthermore, when the percentage of node failures goes up (from 20 % to 40 %) SIR becomes the best suited protocol for these kinds of scenarios.

Although the results obtained with the inclusion of AI techniques in WSN are important and encouraging, we must take in account some relevant remarks:

- What is the price WSNs have to pay for introducing AI techniques? Although the computational payment for implementing the neural network in a sensor is inapreciable, the tradeoff associated with this implementation is the increase of the overhead. However, in typical SCADA applications, WSNs

don't have to attend high level of data traffic. Consequently, the network can support an increase on the overhead.

- Nodes failures can be provoked by the following reasons:
  - Sensor battery draining.
  - Noise originating at industrial environments.
  - Interference in the sensor surroundings.

These phenomena provoke an influence on the average dissipated energy.

SIR has been presented in this paper as an innovative QoS-driven routing algorithm based on artificial intelligence. This routing protocol can be used over wireless sensor networks standard protocols, such as IEEE 802.15.4 and Bluetooth®, and over other well known protocols such as *Arachne*, *SMACS*, *PicoRadio*, etc.

The inclusion of AI techniques (e.g. neural networks) in wireless sensor networks has been proved to be an useful tool to improve network performances.

The great effort made to implement a SOM algorithm inside a sensor node means that the use of artificial intelligence techniques can improve the WSN performance. According to this idea, we are working on the design of new protocols using these kinds of tools.

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