

## The development of a space climatology: 1. solar-wind magnetosphere coupling as a function of timescale and the effect of data gaps

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#### The development of a space climatology: 1. Solar-wind magnetosphere coupling as a

- 2 function of timescale and the effect of data gaps
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- 8 Key Points:
- Gaps in interplanetary data from minutes to years generate significant errors in
   empirically-derived solar wind coupling functions
- All coupling functions derived using data from before 1995 need to be critically reevaluated and checked for over-fitting
- The optimum coupling function quantifying power input to the magnetosphere has no detectable variation with averaging timescale

#### **Abstract**

15

Different terrestrial space weather indicators (such as geomagnetic indices, transpolar voltage, 16 and ring current particle content) depend on different "coupling functions" (combinations of 17 near-Earth solar wind parameters) and previous studies also reported a dependence on the 18 19 averaging timescale,  $\tau$ . We study the relationships of the am and SME geomagnetic indices to the power input into the magnetosphere  $P_{\alpha}$ , estimated using the optimum coupling exponent  $\alpha$ , 20 for a range of  $\tau$  between 1 min and 1 year. The effect of missing data is investigated by 21 introducing synthetic gaps into near-continuous data and the best method for dealing with them 22 when deriving the coupling function, is formally defined. Using  $P_{\alpha}$ , we show that gaps in data 23 recorded before 1995 have introduced considerable errors into coupling functions. From the 24 near-continuous solar wind data for 1996-2016, we find  $\alpha = 0.44 \pm 0.02$  and no significant 25 evidence that  $\alpha$  depends on  $\tau$ , yielding  $P_{\alpha} \propto B^{0.88} V_{\rm sw}^{1.90} (m_{\rm sw} N_{\rm sw})^{0.23} \sin^4(\theta/2)$ , where B is the 26 Interplanetary Magnetic Field (IMF),  $N_{sw}$  the solar wind number density,  $m_{sw}$  its mean ion mass, 27  $V_{\rm sw}$  its velocity and  $\theta$  the IMF clock angle in the Geocentric Solar Magnetospheric reference 28 frame. Values of  $P_{\alpha}$  that are accurate to within ±5% for 1996-2016 have an availability of 83.8% 29 and the correlation between  $P_a$  and am for these data is shown to be 0.990 (between 0.972 and 30 0.997 at the  $2\sigma$  uncertainty level),  $0.897\pm0.004$ , and  $0.790\pm0.03$ , for  $\tau$  of 1 year, 1 day and 3 31 hours, respectively, and that between  $P_a$  and SME at  $\tau$  of 1 min. is 0.7046 $\pm$ 0.0004. 32

#### 1. Introduction

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#### 1.1 Coupling functions

- On short timescales, the coupled magnetosphere-ionosphere-thermosphere system responds to the magnitude of the southward component of the Interplanetary Magnetic Field (IMF, in a suitable frame oriented with respect to the geomagnetic field axis, such as Geocentric Solar Magnetospheric, GSM). There are two time constants of response, the "directly-driven" system responds on a timescale of order a few minutes [Nishida, 1968; Lockwood et al., 1986; Etemadi
- 40 et al., 1988, Todd et al., 1988]. The directly-driven flows store magnetic energy in the

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magnetospheric tail and subsequently that energy is released and deposited in the inner
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     magnetosphere and nightside auroral ionosphere and thermosphere via the substorm current
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     wedge. This is the "storage-unloading" system, which generates a response after a delay of
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     typically between about 30 and 60 min. [Schatten and Wilcox, 1967; Arnoldy, 1971; Baker et al.,
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      1981, 1983; Lockwood et al., 1990]. Finch et al. [2007] used data from the global network of
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     geomagnetic observatories to show how stations responded differently to the directly-driven and
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     storage/unloading systems depending on their position (in geomagnetic latitude and magnetic
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     local time (MLT) coordinates). Similar conclusions was reached by Dods et al. [2015; 2017],
     using network analysis.
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     A great many combinations of near-Earth interplanetary parameters (so-called "coupling
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     functions") have been proposed over many years to describe the transfer of energy, and/or mass,
     and/or momentum, and/or electric field from the solar wind into the Earth's magnetosphere-
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     ionosphere-thermosphere system [e.g., Burton et al., 1975; Crooker et al., 1977; Feynman and
     Crooker, 1978; Perreault and Akasofu, 1978; Kan and Lee, 1979; Reiff et al., 1981; Murayama,
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     1982; Wygant et al., 1983; Bargatze et al., 1985; 1986; Vasyliunas et al., 1982; Scurry and
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     Russell, 1991; Wing and Sibeck, 1997; Wu and Lundstedt, 1997; Papitashvili et al. 2000;
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     Temerin and Li, 2002; 2006; Newell et al., 2007; Borovsky, 2008; Balikhin et al., 2010; Spencer
     et al., 2011; Tenfjord and Ostgaard, 2013, McPherron et al., 2015]. These are derived and
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     tested by comparison with terrestrial space weather disturbance indices (sometimes in
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     combination) which respond to the energy, mass, electric field and/or momentum input to the
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     magnetosphere from the solar wind (in a combination thereof that depends on which terrestrial
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     index is used). Gonzalez [1990] examined the empirical coupling functions in use at the time
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     and concluded that almost all could be derived either from electric field or power transfer
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     associated with the reconnection process. Although they are related in a general sense [e.g. Saba
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     et al., 1997], different terrestrial indices respond differently to different combinations of energy,
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     mass, momentum and/or electric field transfer into the magnetosphere (and on different
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     timescales): hence it is not surprising that there are a wide variety of derived coupling functions.
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     For example, Svalgaard and Cliver [2005] noted that different geomagnetic indices responded
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     differently to different coupling functions. This is also unsurprising as each is influenced by
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     different combinations of the currents in the terrestrial system: the ionospheric DP1 (auroral
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electrojet and substorm current wedge); the ionospheric DP2 (growth phase convection) currents;
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      the magnetospheric ring current; the magnetopause (Chapman-Ferraro) currents; the cross-tail
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      current sheet; and (unless ionospheric conductivities are spatially uniform) the field-aligned
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      (Birkeland) currents. Svalgaard and Cliver [2005] also noted that this is a very useful feature
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      because it allows reconstruction of multiple solar wind parameters from combinations of indices
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      for times before interplanetary spacecraft were available, as exploited by Lockwood et al. [1999],
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      Lockwood [2003], Rouillard et al. [2009] and Lockwood et al. [2014a]. A comparison of the
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      optimum exponents of interplanetary parameters for various commonly-used geomagnetic
      indices has been presented for annual timescales by Lockwood [2013].
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      On long timescales (e.g., \tau = 1 year) the substorm cycles and geomagnetic storm responses are
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      averaged out and also the IMF orientation factor converges to almost a constant factor. On such
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      timescales, the coupling functions that depend only on the IMF magnitude, B, work well
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      [Stamper et al., 1999; Lockwood, 2003; 2013; Lockwood et al., 2017]. A coupling function
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      derived for small averaging timescale \tau should, if all the physical mechanisms have been
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      properly accounted for, integrate over time and so also work at large \tau. On the other hand, a
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      coupling function that works well at high \tau may not apply on shorter timescales (the IMF B, as
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      discussed above, being a good example of this). Naturally, cancellation of noise and other factors
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      (i.e., the central limit theorem) means that correlations are higher for larger \tau.
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      Many studies of coupling functions have concentrated on the exponents needed for each of the
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      solar wind parameters that have been shown statistically to play a role in controlling the variation
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      of the terrestrial response, and have used multivariate analysis to adjust the exact functional form
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      of the combination of parameters used in the coupling function. This raises a problem. Including
      all of the factors with their own weighting factors and/or exponents could result in extremely
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      good fits that are, nevertheless, statistically meaningless as each additional fit parameter reduces
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      the statistical significance of the correlation. Such fits can have limited, and in extreme cases, no
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      predictive capability. This pitfall is called "over-fitting" and it is a serious, but often under-
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      appreciated, problem in multiple regression analysis of geophysical time series that have internal
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      "geophysical" noise. Overfitting refers to the situation when a fit has too many degrees of
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      freedom and starts to approximate the noise in the training subset, which is not robust throughout
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      the whole dataset. This is a recognized pitfall in areas where quasi-chaotic behaviors give large
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internal noise such as climate science and population growth (see, for example, *Knutti et al.* [2006] and Knape and de Valpine [2011]) but is not recognized as widely in space physics, possibly because systems may have been viewed as being somewhat more deterministic and with lower internal variability. To help guard against over-fitting, we favor the physics-based approach to coupling function derivation by Vasyliunas et al. [1982] which is described in the next section. This approach yields a single fit parameter, the coupling exponent  $\alpha$ , which arises from an unknown dependence on the solar wind Alfvén Mach number but which influences the dependence of the coupling function on solar wind speed,  $V_{\rm SW}$ , number density  $N_{\rm SW}$ , mean ion mass,  $m_{SW}$  and the interplanetary field B – all in a consistent way. Despite having just the one free fit parameter, extremely high correlations with geomagnetic indices (often exceeding 0.99 for annual timescales) can be derived for some geomagnetic indices. We here concentrate on the optimum coupling function to predict the am geomagnetic index [Mayaud, 1980]. This is a "range" index, being based on the range of variation of the more variable horizontal component of the field in 3-hour windows. This range is used to give a Kvalue, as introduced by Bartels et al. [1939]. The stations used to compile the am index are situated at sub-auroral latitudes close to corrected geomagnetic latitude  $\Lambda_{CG} = 50^{\circ}$ . They are grouped into longitude sectors, with 5 such groups in the Northern hemisphere, and 4 in the Southern. The K indices for stations in a longitude sector are averaged together and the result is converted into a sector  $a_K$  value using the standard "K2aK" scale. Weighted averages of these sector  $a_K$  values are then generated in each hemisphere giving an and as, the weighting factors accounting for the differences in the longitude extents of the sectors. The index am is the average of the hemispheric indices an and as. The study presented here as also been repeated using the ap index, generated from K values from a network of 11–13 stations at  $|\Lambda_{CG}|$  between 44° and 60°. To generate this index, the station K indices are first converted into standardized  $K_S$  values, using conversion tables for each observatory that were defined by Bartels [1949, 1957]. The Kp index is the arithmetic mean of the 3-hourly  $K_S$  values for the observatories employed. The  $K_P$  values are converted into apvalues using the standard K2aK scale that is constructed such that ap may be regarded as the range of the most-disturbed of the two horizontal field components, expressed in the unit of 2nT,

at a station at dipole latitude of 50°. More details of the compilation of the ap and am indices are 130 provided by Mayaud [1980], Menvielle and Berthelier [1991] and Dieminger et al. [1996]. 131 We here use the am index in preference to ap because am is constructed using only measured K-132 values from a relatively uniform global network of stations, whereas ap employs a less uniform 133 distribution of stations and relies on an empirical model (via Bartels' K to Ks conversion tables) 134 to become global in nature. Our research (reported elsewhere) has shown that although this gives 135 more accurate annual means for ap, it also generates some spurious time-of-year and time-of-day 136 variations in the response of ap (of amplitude about 20%) whereas the time-of-year/time-of-day 137 response of am is constant to within 2.5%. All the results presented here are also found for ap, 138 but uncertainties are slightly lower for am except on annual timescales. Any differences between 139 results for ap and am will be noted and the results for ap are given in the supplementary 140 materials. 141 142 The am index and its daily means, Am, responds strongly to substorm currents [Saba et al., 1997], such that the linear correlation coefficient between all available coincident 56 annual 143 means of the auroral electrojet AE(12) index (from 1959-2017, inclusive) and Am is 0.92±0.04 144 (significant at >99.99% level), and the correlation between the 20301 coincident daily means of 145 AE(12) and Am is  $0.855\pm0.004$  (significant to at least the same level). One reason for the lower 146 correlation for daily means is evident from the scatter plot which is linear at low disturbance 147 levels but shows a marked non-linearity in large disturbances, with large Am values consistently 148 exceeding the corresponding linearly-regressed values from AE(12) (see, for example, Figure 4 149 150 of Adebesin [2016] and the scatter plots presented in the supplementary material for the present paper). This is consistent with the effect on AE(12) of an extremely expanded auroral oval 151 migrating increasingly equatorward of the fixed latitude of the ring of 12 stations that it is 152 compiled from. 153 154 The mid-latitude planetary range indices such as am are particularly sensitive to the ionospheric currents that flow in the substorm current wedge. These currents are strong during substorm 155 expansion phases, in which the energy that was extracted from the solar wind and stored as 156 magnetic energy in the geomagnetic tail is released and deposited in the upper atmosphere. (See 157 description of energy flow as a function of substorm cycle phase using Poynting's theorem by 158

Lockwood [2004]). Hence am is an index that we expect to depend on the energy input to the 159 magnetosphere and so correlate well with  $P_{\alpha}$ . 160 The substorm current wedge (that am responds to) forms when the near-Earth edge of the cross-161 tail current is disrupted at, or soon after, substorm expansion phase onset and, due to the shape of 162 the magnetosphere, the solar wind dynamic pressure constrains the cross-sectional area of the 163 geomagnetic tail lobe at such locations. This means that solar wind dynamic pressure plays a 164 role in the growth-phase rise in magnetic field intensity at and around the distances down the tail 165 (the X-coordinate in the GSM frame) of the inner edge of the cross tail current. Hence the 166 dynamic pressure (as well as the open magnetospheric flux in tail) controls the magnetic sheer 167 and hence the cross-tail current at these locations [Lockwood, 2013]. (Note that this is not the 168 case in the far tail (greater -X) where the tail lobe area expands as the open flux increases and 169 the cross-tail current is constant, being set by the static pressure of the solar wind). This role of 170 solar wind dynamic pressure in setting the cross-tail current (the current that becomes deflected 171 into the substorm current wedge at substorm onset) means that the am index should show a 172 strong variation on  $V_{SW}^n$ , where the exponent n is close to 2 [Lockwood, 2013]. The Kp (and 173 hence ap) and am indices are also known to be good indicators of the strength of convection in 174 the magnetosphere-ionosphere system [Thomsen, 2004]. That am is good indicator of both 175 176 substorm currents and convection is also expected from the Expanding-Contracting Polar Cap model in which convection is understood as the net effect of the opening of field lines by 177 magnetopause reconnection (associated with the directly-driven current system, and the storage 178 (growth) phase of the substorm cycle) and their re-closing by reconnection in the cross-tail 179 180 current sheet in expansion and recovery phases (associated with the unloading phase of the substorm cycle) [Lockwood et al., 1990; Lockwood and Cowley, 1992; Cowley and Lockwood, 181 1992; Milan et al., 2003; 2008]. 182

#### 1.2. Power Input into the magnetosphere

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- 184 Vasyluinas et al. [1982] estimated the power input from the solar wind into the magnetosphere,
- 185  $P_{\alpha}$ . As discussed below, a key point about the coupling function that this theory yields is that it
- has just one free fit parameter, the various solar wind parameters being linked by the theory used.
- To demonstrate this, the formula used by *Vasyluinas et al.* [1982] is:

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$$P_{\rm gr} = (\pi L_{\rm o}^2) \times (m_{\rm sw} N_{\rm sw} V_{\rm sw}^3/2) \times (t_{\rm r})$$
 (1)

- where  $L_0$  is the mean cross-sectional radius of the magnetosphere, such that the geomagnetic
- field presents an area  $\pi L_0^2$  to the solar wind flow and  $(m_{\rm sw} N_{\rm sw} V_{\rm sw}^3/2)$  is the kinetic energy flux
- of the particles, which is the dominant energy flux in the solar wind (where  $m_{\rm sw}$  is the mean ion
- mass,  $N_{\rm sw}$  the number density and  $V_{\rm sw}$  the speed). The term  $t_{\rm r}$  is a dimensionless transfer
- function, the fraction of the incident energy flux that is transferred to inside the magnetosphere.
- Assuming a hemispheric shape to the dayside magnetosphere, pressure balance at the nose of the
- magnetosphere gives [e.g. Farrugia et al., 1989]:

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$$L_0 = k_1 \left( M_E^2 / P_{\text{sw}} \, \mu_0 \right)^{1/6}$$
 (2)

- where  $k_1$  is a geometric factor for a blunt-nosed object,  $M_E$  is Earth's magnetic dipole moment,  $\mu_0$
- is the magnetic constant, and  $P_{\rm sw}$  is the solar wind dynamic pressure, given by

$$199 P_{\rm sw} = m_{\rm sw} N_{\rm sw} V_{\rm sw}^2 (3)$$

200 Vasyluinas et al. [1982] adopted the dimensionless transfer function:

$$201 t_{\rm r} = k_2 M_{\rm A}^{-2\alpha} \sin^4(\theta/2) (4)$$

- where  $\alpha$  is the "coupling exponent" (the one free fit parameter used),  $\theta$  is the clock angle that the
- IMF makes with the north in the GSM frame of reference (so  $\theta = \tan^{-1}(B_{\rm VM}/B_{\rm zM})$ , where  $B_{\rm VM}$  and
- $B_{zM}$  are the Y and Z components of the IMF in the GSM frame)  $k_2$  is a constant (which below is
- combined with other constant factors) and  $M_A$  is the Alfvén Mach number of the solar wind flow
- 206 given by

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$$M_{\rm A} = V_{\rm SW} \left( \mu_{\rm o} \ m_{\rm sw} \ N_{\rm sw} \right)^{1/2} / B$$
 (5)

208 Substituting equations (2) - (5) into (1) yields

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$$P_{\alpha} = (k_1 k_2. \pi/2 \mu_0^{(1/3-\alpha)}) M_E^{2/3} m_{sw}^{(2/3-\alpha)} \times B^{2\alpha} N_{sw}^{(2/3-\alpha)} V_{sw}^{(7/3-\alpha)} \sin^4(\theta/2)$$
 (6)

- The predictions from equation compare well with the global MHD simulations of the energy
- transfer into the magnetosphere by Wang et al. [2014]: their results agreed best with  $P_{\alpha}$  for a
- value of  $\alpha$  of 0.34.

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- The interplanetary parameters B,  $N_{\rm sw}$  and  $V_{\rm sw}$  have been routinely measured by near-Earth,
- interplanetary craft. We here use 1-minute samples of these parameters from the Omni-2 dataset
- [Couzens and King, 1986; Hapgood et al., 1991; King and Papitashvili, 1994; 2005]. The error
- introduced into  $P_{\alpha}/P_{\alpha}$  (where  $P_{\alpha}$  is the mean of  $P_{\alpha}$  over a long reference period) by using a
- constant value of the mean ion mass,  $m_{\rm sw}$ , is less than 5% [Lockwood et al., 2017a]. However,
- we here reduce that uncertainty by employing all the available information and compute the
- mean ion mass. The full mass spectrum of the solar wind is not routinely available and we here
- use the ratio of the number densities, of the two dominant components, protons and Helium ions
- 221 (He<sup>+</sup> and He<sup>++</sup>), and neglect the trace higher-mass ions [Kaspar et al., 2007]. Using the typical
- heavier ion abundances given by *Bochsler* [1987], the effect of neglecting ions heavier than
- Helium on  $m_{\rm sw}$  introduces an uncertainty into the correction of 1.8%. However, we here reduce
- this uncertainty further by using  $P_{\alpha}$  as a ratio of the mean for the whole period (1996-2016,
- inclusive),  $P_{o}$ .
- The helium abundance ratio,  $N_{\text{He}}/N_{\text{p}}$ , is relatively constant near 0.04 in high-speed streams, but
- varies in phase with the sunspot number in slow wind, between about 0.01 and 0.04 [Wang,
- 228 2016]. Hourly means of  $N_{\text{He}}/N_{\text{p}}$  are available in the Omni2 dataset from 1972 and are here
- interpolated to the center times of the 1-minute samples of B,  $N_{\rm sw}$  and  $V_{\rm sw}$  using Piecewise Cubic
- Hermite Interpolating Polynomial (PCHIP) interpolation [Fritsch and Carlson, 1980]. As a
- check, linear interpolation was also used and the deviation of the results from the two methods
- 232 quantified to check that it remained small (<10%) and hence that the interpolations were
- reasonable. The mean ion mass is then given by

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$$m_{\text{sw}} = m_{\text{p}} \left\{ 1 + (4N_{\text{He}}/N_{\text{p}}) \right\} / \left\{ 1 + (N_{\text{He}}/N_{\text{p}}) \right\}$$
 (7)

- where  $m_p$  is the mass of the proton.
- There is a clear but weak solar cycle variation in this  $m_{sw}$  estimate, with the largest annual mean
- being 1.139 a.m.u. (a deviation from the mean of +3.4%) in the year 2000 (sunspot maximum)
- and the lowest value being 1.050 a.m.u. (a deviation of -4.7%) in the low sunspot minimum year
- of 2009. This is allowed for by our procedure but the effects of any corresponding variation in
- the heavier ion fraction (a.m.u. > 4) is not: from the range in the relative abundances given by
- 241 Bochsler [1987] we estimate this introduces an uncertainty into  $P_{\alpha}/P_{\alpha}$  of  $\leq 0.4\%$ .

By taking the results for  $P_{\alpha}$  as a ratio of the mean for the whole period,  $P_{\alpha}$ , we also remove the 242 dependence on the constant  $k_3$  with the assumption that it remains constant. Earth's magnetic 243 dipole moment  $M_{\rm E}$  varies on long timescales and we use the dipole moment variation provided 244 by the IGRF-11 model [Thébault et al., 2015] to account for any drift. 245 The coupling exponent  $\alpha$  influences almost all the factors in equation (6) but is unknown and has 246 to be derived empirically. Wang et al. [2014] present a review of previously derived values 247 which, as noted by Finch and Lockwood [2007], appear to also depend on averaging timescale τ 248 (they found an optimum  $\alpha$  of 0.4 at  $\tau = 3$ hrs, falling to  $\alpha = 0.3$  at  $\tau = 1$  yr). The results also 249 appear to depend on which indictor of solar wind energy deposition is used: Finch and 250 Lockwood were using the am geomagnetic index. Murayama [1982] also found  $\alpha = 0.4$  for the 251 am and the AL indices and  $\tau$  near 1 day whereas Stamper et al. [1999] found  $\alpha = 0.38$  using the 252 aa index and  $\tau = 1$  yr. On the other hand, Bargatze et al. [1986] found  $\alpha = 0.5$  for the AL index 253 and τ < 1 hr. Tenfjord and Ostgaard [2013] employed combinations of SuperMAG 254 255 magnetometer data designed to quantify energy sinks in the terrestrial system: using 5-minute data their results were close to  $\alpha = 0.5$ . 256 1.3. The effect of data gaps on studies of coupling functions 257 Since 1995, we have available a much more continuous data series on the near-Earth 258 interplanetary medium from the WIND, ACE and DSCOVR satellites. However, before this date 259 the data series contained many data gaps with a broad (and bimodal) spectrum of durations 260 [Finch and Lockwood, 2007]. An analysis of interplanetary data availability is presented in 261 262 section 2 of this paper. Data gaps can influence correlation studies [George et al., 2015]. For many applications such as 263 spectral analysis, it is desirable or necessary to fill the data gaps and a number of methods for 264 doing this are available, but one has to remain aware of the implications of the method used for 265 application in question [Sturges, 1983; Wynn and Wickwar, 2007; Henn et al., 2013, Munteanu 266 et al., 2016]. Such gap filling techniques have been applied to solar wind data by, for example, 267 Kondrashov et al. [2010; 2014] but many require a proxy dataset for either interpolation or 268 testing purposes. This usually involves using a terrestrial space weather disturbance index as the 269

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proxy, which means the coupling function is assumed and used to help fill the data gap and so such techniques must not be used in the context of deriving a coupling function. Correlation studies, such as between a solar wind coupling function and a terrestrial space weather response, are not influenced by data gaps at basic time resolution, other than through the loss of correlation significance through the reduced number data point pairs available. The question then arises as to how best to deal with data gaps when the basic time resolution data are averaged into longer intervals  $\tau$ . Some of the more recent studies of solar wind-magnetosphere coupling have been able to reduce the problem of data gaps by employing only data from after 1995 when data became much more continuous [e.g., Luo et al., 2013; Temerin and Li, 2006], despite the drawback that this reduces the number of years covered by the study. Some studies have placed tight restrictions on data gap occurrence [e.g., Teodorescu et al., 2015] but these tend to be severe and also greatly reduce the available data such that only some spectral studies are possible and coupling functions are studied through of a series of events [e.g. Bargatze et al., 1985; 1986]. This limits the potential for noise reduction by averaging (which makes correlation coefficients increase with averaging timescale  $\tau$ ) and reduction of the influence of others factors such as ionospheric conductivity [e.g., Nagatsuma, 2006; Luo et al., 2013]. Many studies continue to use the pre-1995 data, despite its severe problem of many and long data gaps (as shown in Figures 2 and 3 and discussed in section 2). In a great many of these studies, the averages of all available data have been taken on the (usually tacit) assumption that the effect of data gaps will average out. This philosophy is often introduced by the use of the Omni or Omni2 interplanetary datasets, which supply averages for a requested  $\tau$  without a limit on the data availability (so in extreme cases a mean is given even if only one data sample is available in the interval). Lockwood and Finch [2007] made allowance for data gaps by introducing the solar wind data gaps into the geomagnetic data sequence that they correlated with and showed that the assumption that data gaps can be neglected is often invalid: hence they argued for piecewise removal of the geomagnetic data at times corresponding to the interplanetary data gaps (i.e. allowing for an appropriate lag) before the averaging of both into the intervals of duration  $\tau$ . For  $P_{\rm g}$  values this means that if any of  $N_{\rm SW}$ ,  $V_{\rm SW}$ ,  $m_{\rm SW}$ , B or  $\theta$  were missing, the corresponding geomagnetic data were piecewise masked out. This ensures that the averages contain only the corresponding data in the two data sets. Although they argued that this was the best approach,

[Finch and Lockwood, 2007] also cautioned that data gaps could still have an influence on the 300 optimum correlations. 301 On the other hand, Svalgaard and Cliver [2005] deployed a linear interpolation scheme on solar 302 303 rotation timescales to fill the data gaps in the interplanetary data. Because it can give a small number of data points a greatly inflated weighting, Lockwood et al. [2006] argued this procedure 304 was unsound. 305 Other interpolation procedures have been employed to fill data gaps, such as in *Temerin and Li* 306 [2002] in their analysis of a coupling function to predict the Dst index. However, the same 307 authors soon after moved to using only data from after 1995 and assuming that the effects of 308 gaps averaged out, with considerable improvement of the correlation between their coupling 309 function and the Dst geomagnetic index [Temerin and Li, 2006]. Others have used interpolation 310 with restrictions, for example Wu and Lundstedt [1997] deployed autocorrelation-based 311 interpolation for data gaps of up to 5 hours, and intervals with longer data gaps excluded from 312 the study. 313 314 Note that there is also a related issue in that there are two separate ways in which mean coupling function values over an interval  $\tau$  can be generated. Because, in general, there are non-linear 315 dependencies on interplanetary parameters, the most representative of the two is to evaluate 316 values at high time resolution and then average them (the "combine-then-average" approach). 317 318 This is the most desirable approach, but this is not possible in some circumstances and the coupling function instead is computed from averages of the required parameters (the "average-319 then-combine" approach). For example, Lockwood et al. [2017a] have shown that, although 320 compiling annual  $P_{\alpha}$  values from annual means of  $N_{SW}$ ,  $V_{SW}$ , B and  $\sin^4(\theta/2)$  is a less satisfactory 321 approach and does slightly alter the optimum coupling exponent,  $\alpha$ , it does not lower the 322 correlation with ap or am on annual timescales. An example of when the "average-then-323 combine" method is necessary is when working with the reconstructed parameters which can 324 only be generated as annual means [Lockwood, 2013; Lockwood et al., 2017a]: reconstructed 325 annual means of  $N_{SW}$ ,  $V_{SW}$  and B generated by Owens et al. [2017] (with constant mean  $\sin^4(\theta/2)$ 326 and  $m_{SW}$  which only introduce small uncertainties) were employed by Lockwood et al. [2017a] to 327 328 reconstruct the variation of  $P_{\alpha}$  over the last 400 years.

From the above discussions, the variation of  $\alpha$  with  $\tau$  found by Finch and Lockwood [2007] is a 329 concern because, if the physics of the relevant solar wind-magnetosphere coupling is properly 330 described by  $P_{\alpha}$ , it should simply integrate over longer  $\tau$  and  $\alpha$  should not vary. Finch and 331 Lockwood did consider it a somewhat unsatisfactory result and cautioned that it may have arisen 332 from the presence of large data gaps in the interplanetary data. In the current paper we 333 investigate the origins of the drift in  $\alpha$  with  $\tau$ . In particular, we study the effects of data gaps by 334 restricting our attention to the interval 1996-2016 during which the interplanetary data come 335 from the WIND, ACE and DISCVR satellites: data gaps are present but relatively few and short 336 in duration compared to in the interval 1974-2003 that was used by Finch and Lockwood [2007]. 337 We introduce synthetic data gaps to enable us to study the effects on the derived coupling 338 functions (and on the optimum coupling exponent  $\alpha_D$ ) of methods for dealing with gaps in the 339 interplanetary data. 340 2. Datasets 341 Finch and Lockwood [2007] used Omni2 hourly interplanetary data for 1974-2005 (inclusive), 342 for which the average availability of  $P_a$  was just 30%. Since data became available from ACE, 343 Wind and DSCOVR (from 1995 onwards) this data availability has risen to 92% for 1995-2016. 344 We here use a basis dataset of 1-minute resolution from 1996-2016 taken from the Omni2 345 dataset maintained by the Space Physics Data Facility, NASA/Goddard Space Flight Centre 346 [Couzens and King, 1986; King and Papitashvili, 1994; 2005]. (We keep 1995 aside to generate 347 independent data gap masks, as described in section 4.2). 348 A great many coupling function studies have employed the Omni2 hourly means, which are 349 generated for the Omni database even if only one sample is available within the hour (but note 350 the number of samples used can always also be downloaded). In evaluating the full effect of data 351 gaps, the question arises as to how much data within each hour is required to generate a valid 352 hourly mean (i.e., one which is close to the value that would be obtained with continuous 353 sampling). The answer to this depends strongly on the autocorrelation function of the parameter 354 in question. Figure 1a shows the autocorrelation functions (a.c.f.s) of B,  $N_{\rm sw}$ ,  $V_{\rm sw}$ ,  $\sin^4(\theta/2)$  and 355  $P_{\alpha}$  (computed here for the optimum  $\alpha$  found in section 3,  $\alpha_p = 0.5$ ) for lags up to 3 hours. The 356

vertical gray line is at 1 hour. It can be seen that over 1 hour, the a.c.f. of  $\sin^4(\theta/2)$  has fallen 357 considerably whereas that of  $V_{sw}$  has hardly fallen at all. It follows that the number of samples 358 required to make a valid mean to a given uncertainty is much greater for  $\sin^4(\theta/2)$  than it is for 359  $V_{\rm sw}$ . 360 To study the effect of data gaps on 1-hour averages, we here took 1-minute Omni2 data for 1996-361 2016 (11046240 samples, falling in 184104 hourly intervals). We note that for some of the solar 362 wind measurements, the basic time resolution is greater than 1-minute: for example the ACE 363 satellite spins with 64 s. period setting the time resolution of the solar wind data. In such cases, 364 the long autocorrelation time constant of the solar wind parameters allows interpolation into 1-365 minute values. However, the same is not true for the IMF data. For each parameter we searched 366 for hourly intervals in which all 60 minutes in the hour gave a 1-minute sample made up from at 367 least one observation such that it was not classed as "missing data" in the Omni dataset. For B, 368 and  $\sin^4(\theta/2)$  and such hours numbered 112855; for  $N_{\rm sw}$  and  $V_{\rm sw}$  the number was 121685 and for 369  $P_{\rm g}$  it was 1083797. For these hours we removed  $N_{\rm g}$  1-minute sub-samples at random (this was 370 done 10 times for each of the hours) where  $N_{\rm g}$  was increased from 1 up to 59 and the percentage 371 error in the mean of the reduced data for that parameter and hour was evaluated by comparing it 372 to the mean for the full data (i.e., the effect of the synthesized data gaps was determined). The 373 distributions of these fractional errors were Gaussian and in Figure 1b the standard deviations 374 (i.e., the one sigma error in the hourly means),  $\varepsilon_{hr}$ , are shown for each parameter as a function of 375 data availability within the hour,  $f_{hr} = 1 - (N_g/60)$ . As expected, the high a.c.f. of  $V_{sw}$  results in the 376 average error introduced into hourly means,  $\varepsilon_{hr}$ , being very small and it is only 0.2% even if just 377 one sample is available in the hour. For  $N_{\rm sw}$  and B, this figure is larger but is still, respectively, 378 only just above and just below 2%. Much larger errors arise from the IMF orientation factor 379  $\sin^4(\theta/2)$ , as expected for its greater variability at sub-hour timescales, shown by rapid decline in 380 its a.c.f. with time in Figure 1a. Figure 1b shows that it is the variability in  $\sin^4(\theta/2)$  that 381 generates matching behavior for  $P_{\alpha}$ , and hence sets a requirement for a sub-hour  $\sin^4(\theta/2)$ 382 availability threshold for coupling studies. From this plot we can find the fraction of samples  $f_{hr}$ 383 384 that is needed in the hour to give a specified 1- $\sigma$  uncertainty in the hourly means for that parameter,  $\varepsilon_{hr}$ . We here study the 2% and 5% uncertainty levels. Figure 1b shows that  $\varepsilon_{hr} < 2\%$  is 385

achieved for  $P_{cr}$  if  $f_{hr} \ge 0.96$  for  $\sin^4(\theta/2)$  observations and  $f_{hr} \ge 0.15$  for  $N_{sw}$  data. On the other 386 hand,  $\varepsilon_{hr} < 5\%$  achieved for  $P_{cr}$  if  $f_{hr} \ge 0.82$  for  $\sin^4(\theta/2)$  observations and for all other parameters 387 just one sample is adequate. 388 Figures 2 and 3 present an analysis of the data gaps in the interplanetary data. To avoid being 389 classed as a data gap requires that all the parameters required to compute  $P_{\alpha}$  are available, 390 meaning we require a valid mean of B,  $B_{\rm vM}$ ,  $B_{\rm zM}$ ,  $n_{\rm He}/n_{\rm p}$ ,  $N_{\rm sw}$ . The definitions used of "valid" are 391 discussed below. For Figure 2 we make an exception to this because data on the helium ion 392 fraction  $n_{\rm He}/n_{\rm p}$  are not routinely available before 1972 and many coupling functions do not make 393 use of this parameter, and even in many implementations of  $P_{\alpha}$  it is assumed to be constant 394 because such an assumption introduces only a small uncertainty (one that is comparable with 395 other observational uncertainties [Lockwood et al., 2017a]). Hence for the purpose of Figures 2 396 and 3, missing data on  $n_{\text{He}}/n_{\text{p}}$  does not generate a data gap before 1972. 397 398 In both Figures 2 and 3, and all subsequent places in the text, we employ hourly means that we have made from the downloaded 1-minute Omni data. In Figure 3 we require enough 1-minute 399 samples in the hour to reduce the statistical uncertainty (as shown by Figure 1) to a given level 400 whereas in Figure 2 we use the criterion of requiring just a single 1-minute sample in the hour to 401 402 generate an hourly mean in order to investigate the effects of that criterion. To distinguish the two later in this paper, the latter cases are always identified using the phrase "using the Omni 403 404 criterion" (because the Omni data give an hourly mean value even if only one sample in the hour is available). All other hourly means refer to the former definition. From the analysis presented 405 406 in Figure 1, the Omni criterion is certainly adequate for  $V_{\rm sw}$  and generates acceptable average uncertainties of  $\varepsilon_{th} \approx \pm 2\%$  for B and  $N_{sw}$ . However, for the IMF orientation, and hence coupling 407 function, the errors in using a single sample are  $\epsilon_{th} \approx \pm 15\%$ . Comparison of Figures 2 and 3 408 investigates the effect of criteria on the occurrence of data gaps because, whereas Figure 2 is for 409 the Omni criterion, Figure 3 uses the criterion that  $\varepsilon_{th} \leq 5\%$  (requiring  $f_{hr} \geq 0.82$  for the IMF 410 orientation data) and  $\epsilon_{th} \le 2\%$  (requiring  $f_{hr} \ge 0.96$  for the IMF orientation data and  $f_{hr} \ge 0.15$  for 411 the solar wind data). 412 The availability of hourly samples in calendar years, f, is shown for the Omni criterion in Figure 413 2a. The large rise in f caused by the advent of data from ACE and WIND in 1995 is marked by 414

the vertical green line. Figure 2b shows the spectrum of data-gap durations by giving the 415 probability p(L) of being in a data gap of duration L, as a function of  $\log_{10}(L)$ , evaluated in bins 1 416 hour wide. Note that at large L before 1995 (in blue) the spectrum become discrete as there were 417 often just single occurrences of a data gap at that L, but p(L) increases linearly with L for such 418 cases. Figure 2b shows that data gaps at almost all L (but particularly at large L) were 419 considerably rarer after 1995 than before. Figure 2c shows the information as the cumulative 420 probability distribution, which shows clearly the durations of gaps that contribute most to the 421 422 loss of data. Using the Omni criterion, the total probability for being in a data gap for 1966-1994 is 68% (so the average availability is < f > = 32%) and for 1995-2016 it is 8% (< f > = 92%). 423 Remember from Figure 1b, this gives average errors in the hourly energy input estimates,  $P_{\alpha}$ , of 424  $\varepsilon_{th} \approx \pm 15\%$ . 425 Figure 3 is the same as Figure 2, but for two tighter criteria on what constitutes a valid mean, 426 namely  $\varepsilon_{hr}$  < 5% and  $\varepsilon_{hr}$  < 2%. The red and blue lines require IMF data to have an availability of 427 82% within in each hour (giving  $\epsilon_{th} \leq 5\%$ ) and this raises the total probability for being in a data 428 gap for 1966-1994 to 76.1% (so the average availability is < f > = 23.9%) and for 1995-2016 it is 429 16.2% (< f > = 83.8%). Comparison of the red and blue lines in Figures 2a and 3a shows that the 430 additional requirement reduces the availability in most years before 1995 and makes some years 431 around 1980 unusable. After 1995, it amplifies somewhat the trend for loss of data towards the 432 end of the period when the main source of data was the ACE satellite. Comparing parts (b) and 433 (c) of the two figures show that data gaps of all durations are increased by the extra criterion 434 before 1995 but that after then the main effect is the loss of individual hours with data gaps of 435 duration L < 1day. The pink and cyan lines in Figure 3 are for  $\varepsilon_{th} \le 2\%$ . The cyan line in Figure 436 3a shows that this relatively small (3%) gain in the accuracy has a relatively small effect on the 437 availability of valid data before 1995 ( $\langle f \rangle = 18.5\%$ ) but after then it has a somewhat greater 438 effect, lowering the average availability to < f > = 70.0%. Figure 3b and 3c show that the 439 dominant effect of the lower error threshold is to introduce many short-duration data gaps. 440 Hence a compromise needs to be struck between the error in hourly  $P_{\alpha}$  means,  $\varepsilon_{th}$ , and the 441 average availability of those hourly means < f >. We here adopt and uncertainty limit of  $\varepsilon_{th} \le 5\%$ 442

which gives the annual availability and data gap spectra after 1 January 1995 shown by the red 443 lines in Figure 3. 444 The am data are continuous and are generated by L'École et Observatoire des Sciences de la 445 Terre (EOST), a joint unit of the University of Strasbourg and the French National Center for 446 Scientific Research (CNRS) institute, on behalf of the International Service of Geomagnetic 447 Indices (ISGI). The data available from http://isgi.unistra.fr/data download.php. 448 3. Optimum coupling function as a function of timescale 449 The hourly interplanetary data formed from hours with more than 82% of 1-minute IMF 450 orientation samples (giving  $\varepsilon_{th} \le 5\%$ ) were averaged into independent intervals of duration  $\tau$ . The 451 process was repeated 2922 times as  $\tau$  was varied between 3hrs and 1average year (365.25 days = 452 8766hrs) in steps of 3hrs (in other words, the values of  $\tau$  used were 3hrs, 6hrs, 9hrs ... up to 453 8766hrs). Before the am data were similarly averaged, values co-incident in time to data gaps in 454 the interplanetary data were masked out using the procedure of Finch and Lockwood [2007] and 455 not included in the means. Note that the data in the Omni2 dataset are lagged by the predicted 456 propagation time between the observing satellite and the nose of the magnetosphere (see 457 description of the procedure by King and Papitashvili available at 458 https://omniweb.gsfc.nasa.gov/html/omni\_min\_data.html). 459 The averages of the input power for a given  $\tau$ ,  $\langle P_{\alpha} \rangle_{\tau}$  were computed using equation (6) for 460 values of the coupling exponent  $\alpha$  between 0 and 1.5 in steps of 0.01. The linear correlation 461 coefficient between  $\langle P_{\alpha} \rangle_{\tau}$  and  $\langle am \rangle_{\tau}$  (with data gaps introduced into am to that match those in 462 the  $P_{\alpha}$  data) at each  $\alpha$ ,  $r(\alpha)$ , was then determined. Figure 4 presents an example of the results for 463 annual means (i.e. for  $\tau = 1$  yr). Figure 4(a) shows the correlogram of  $r(\alpha)$  as a function of  $\alpha$ . 464 The peak  $r(\alpha)$ ,  $r_p = 0.990$ , is at  $\alpha = \alpha_p = 0.44$  (marked by the vertical green line). Figure 4(b) 465 shows the significance  $S(\alpha)$  of the difference between  $r(\alpha)$  and its peak value,  $r_D$ , evaluated using 466 the Meng-Z test of the significance of the difference between two correlations [Meng et al., 467 1992]. Sometimes also called Steiger's Z test, this is a variant of the Fisher-Z test [e.g. Asuero et

al., 2006] that makes allowance for inter-correlation between the comparison time series. We

use a one-sided version of the test against the null hypothesis that  $r(\alpha)$  is not lower than  $r(\alpha_D)$ .

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By definition, S(\alpha) = 0 at \alpha = \alpha_p and increases at \alpha away from the peak as r(\alpha) falls. The vertical
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       red and blue lines are where S(\alpha) rises to 0.68 and so mark the 1-\sigma uncertainties in the \alpha_p value
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       (giving the optimum \alpha to be \alpha_p = 0.42, with 1-\sigma uncertainties of +0.11 and -0.08 in this case for
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       \tau = 1 \text{ yr}). Figure 4e shows the time series of \langle am \rangle_{\tau = 1 \text{ yr}} (in black) and the best-fit linear
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       regression of \langle P_{\alpha} \rangle_{\tau=1\text{yr}} to \langle am \rangle_{\tau=1\text{yr}} (in mauve) for \alpha = \alpha_p, the best fit being s \langle P_{\alpha} / P_{\rho} \rangle_{\tau=1\text{yr}} + c,
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       for linear coefficients of s = 13.07 \pm 0.32 and c = -2.59 \pm 0.33, where P_0 is the mean of P_{\alpha} over
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       the whole 1996-2016 dataset and is a convenient normalizing factor. The corresponding scatter
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       plot is shown by the points in Figure 4f and the best-fit linear regression in mauve.
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       Figures 4(c) and 4(d) show an alternative procedure for determining \alpha_p and its uncertainty. The
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       r.m.s. deviation of am from the best-fit linear regression of \langle P_{\alpha}/P_{o}\rangle_{\tau=1\text{yr}} (illustrated in Figures
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       4e and 4f for \alpha = \alpha_p), \Delta Am_{rms}, is plotted as a function of \alpha in Part (c). This r.m.s. fit residual is
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       a different metric of the same thing as the correlation coefficient (i.e., the level of agreement
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       between Am and \langle P_{\alpha}/P_{o}\rangle_{\tau=1\text{yr}}), but can be used with different statistical tests. As expected, the
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       two procedures give the same \alpha_p to within \pm 0.05 (the resolution of the tests deployed as \alpha was
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       incremented in steps of 0.1). Figure 4d looks at the significance S of the difference between
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       \Delta Am_{rms} at \alpha = \alpha_p and the values at all other \alpha. This is evaluated using a 2-sample F test of the
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       variances of the distributions of the fit residuals [Snedecor and Cochran, 1989]: this allows us to
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       estimate the \alpha values at which \Delta Am_{rms} is larger than the minimum by an amount that is
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       significant at a specified level. We use the one-tailed version of the test against the null
       hypothesis that \Delta Am_{rms} at general \alpha is not greater than that \alpha = \alpha_p. The F-test is a parametric
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       test (i.e., it assumes Gaussian distributions) and is particularly sensitive to the effect of
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       distortions from that form. Furthermore, a non-normal distribution of fit residuals indicates that
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       the linear regression may also be invalid as it is a violation of one of the assumptions of the
       regression. Hence, although this is a more direct test of the fit, it is particularly sensitive to the
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       normality of the distributions and it is important to test if the fit residuals are normally
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       distributed. This is done in the quantile-quantile (q-q) plot against a normal distribution in Figure
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       4g. For a normal distribution, the points would lie along the diagonal line and Figure 4g shows
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       the residuals' distribution is quite close to Gaussian in this case. (However, there is a slight "S-
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shape" which is discussed below in relation to Figure 5 in which it is more pronounced). The pink and cyan vertical lines in Figure 4c and 4d are at S = 0.68 (the 1-sigma level) for this test and comparison with Figures 4a and 4b shows that the F-test gives slightly larger uncertainties in the best value of  $\alpha$  than does the Meng-Z test. Note that the Meng-Z test is also parametric, but is not as sensitive to the assumption of Gaussian distributions and gives valid results even if the distributions tested are only approximately normal. It is important to stress that we are testing the significance of the difference between the agreement between the optimum fit of  $\langle P_{\alpha}/P_{o}\rangle_{\tau=1\text{yr}}$  to Am and the fits for other, less optimum,  $\langle P_{\alpha}/P_{\alpha}\rangle_{\tau=1\text{yr}}$  data series. This is different to testing the significance of the less-good fits. Because the optimum fits are so good (correlation coefficient very close to unity and r.m.s. fit residual close to zero), the agreements for less-good fits are still highly significant in themselves - even when the difference to the optimum fit is found to be significant. Notice also that we here use the 1-sigma level to quantify the uncertainty in  $\alpha$  and the estimate would naturally be larger for the 2-sigma or 3-sigma level. This is because 1-sigma is a conservative (pessimistic) estimate for our application of the uncertainties because they are here used to gauge if  $\alpha$  is constant with  $\tau$  and using the smaller uncertainties is a stricter test of the constancy of  $\alpha$ . Figure 5 shows the corresponding plots for  $\tau = 1$ day. As expected, the peak correlation is lower and the scatter is greater. The optimum  $\alpha$  is again  $\alpha_p = 0.42$  and the best-fit linear regression coefficients are  $s = 12.46 \pm 0.69$  and  $c = -2.06 \pm 0.40$ . Thus not only is the optimum  $\alpha$  the same for the two timescales illustrated by Figures 4 and 5, but the regression coefficients s and c agree closely, and are the same to within the statistical fit uncertainties. In this case, the uncertainties in α are much smaller. However, the q-q plot in Figure 5g reveals a significant and systematic departure from a normal distribution of residuals, the "S-shape" pattern shape revealing a tailheavy distribution with lower kurtosis than a Gaussian. Hence the F-test uncertainties are probably less reliable in this case. Note, however, that the minimum r.m.s. fit deviation again gives the same best-fit  $\alpha$  and similar uncertainties as the peak correlation method and, as the sensitivity to non-normal distributions is different for the two tests, we can infer the effect of this uncertainty on the uncertainties is small.

Figure 6a studies the full evolution of the  $r(\alpha)$  correlograms with averaging timescale  $\tau$  between 527 3 hours and 1 year, (i.e. averaging intervals of duration  $\tau = 3, 6, 9, \dots$  8766 hours, a total of 528 2922 different durations). The correlation coefficient is color-coded as a function of  $\tau$  along the 529 horizontal axis and  $\alpha$  along the vertical axis. The middle white line gives the  $\alpha_p$  value which 530 yields the peak correlation  $r_p$  (given by the vertical green lines in the examples presented in 531 Figures 4 and 5) and the two black lines give the  $\pm 1\sigma$  uncertainty points from the Meng-Z test 532 (given by the vertical red and blue lines in Figures 4 and 5). Figure 6b compares the uncertainty 533 bands from the two methods or computing the uncertainty, as a function of averaging timescale, 534 τ, and using the same line colors as Figures 4 and 5. It can be seen that they give very similar 535 results, except at lower  $\tau$  when there are concerns about the normality of the distributions, 536 537 particularly for the F test. We here use the results from the Meng-Z test and the general similarity of the F test results gives us confidence in these uncertainty estimates. Figure 6c plots the 538 corresponding variation with  $\tau$  of the peak correlation  $r_p$ . 539 Range indices, such as am, cannot easily be generated for  $\tau < 3$ hrs. In addition, at such 540 541 timescales the correlations become complicated by lag times with the directly-driven system responding within about 5 min. of changes in  $P_{\alpha}$  arriving at the dayside magnetopause and the 542 storage-release system responding, typically, after between 30 min. and an hour (see section 1). 543 Hence the analysis becomes more complex and depends critically on the combination of current 544 systems to which a given index responds. Nevertheless the near-constant  $\alpha$  found for  $\tau$  between 545 3 hours and 1 year in figure 6 is found to apply at  $\tau$  < 3hrs for indices that respond primarily to 546 the auroral electrojet and the substorm current wedge. Figure 8 shows an example of the analysis 547 548 used to test this at  $\tau = 1$  min. We use the 1-min. resolution SME index generated by the SuperMAG project [Newell and Gierloev, 2011]. This index is equivalent to the AE index and 549 responds strongly to the nightside auroral electrojet, but is compiled from the large SuperMAG 550 magnetometer network and so does not suffer the nonlinear effect due to the limited latitudinal 551 coverage of the AE(12) stations (see supplementary materials). Figure 8 shows the correlation 552 between  $P_{\alpha}$  and SME for  $\tau = 1$  min. as a function of coupling exponent,  $\alpha$  (horizontal axis) and 553 time lag,  $\Delta t$  (vertical axis). Positive  $\Delta t$  is when  $P_{\alpha}$  is lagged, i.e. the SME variation follows  $P_{\alpha}$ . 554 The peak correlation is  $r_p = 0.705$  at  $\alpha = 0.46$  and  $\Delta t = 37$  min. The plot suggests that  $\alpha$  for this 555

τ is slightly higher than 0.44 (marked by the vertical white dashed line) but inside the white 556 contour the difference between r and  $r_p$  is not significant at even the 1- $\sigma$  level. Hence we cannot 557 regard the difference between  $r_p$  for  $\tau = 1$ min. and 0.44 as significant. However, it is quite 558 possible that  $\alpha$  is indeed slightly greater than 0.44 in this case because SME is influenced by 559 both the directly-driven and the storage/release systems and analysis of indices such as AU that 560 respond primarily to the directly-driven system find a dependence on  $V_{sw}^{n}$  with a smaller 561 exponent n than for the storage-release system. We do know that the dominant response of SME 562 is due to the storage-release system because the optimum lag is  $\Delta t = 37\pm3$  min., which we 563 equate to the average duration of substorm growth phases for strong solar wind forcing [Li et al., 564 565 2013]. Note that the correlation is large (>0.65) for a wide range of lags  $\Delta t$  (between about 15 min and 1 hour) and this great variability in the length of the substorm growth phase will have 566 reduced the peak correlation at  $\Delta t = 37$ min whereas it would have had no effect on 3-hourly 567 means. This, and equivalent tests at other  $\tau$ , show that  $\alpha = 0.44$  is consistent with the best 568 correlation at all  $\tau$  between 1 min and 1 year. 569 Figure 6 shows that, at all  $\tau$ , the optimum  $\alpha$  is consistent with a constant value of 0.44. This 570 contrast somewhat with the results of Finch and Lockwood [2007], who found an optimum \alpha of 571  $\alpha_p = 0.4$  at  $\tau = 3$  for the *am* index hours which fell to  $\alpha_p = 0.3$  at  $\tau = 1$  year. The major 572 573 difference between the present study and that by Finch and Lockwood is that, as shown by Figure 2, much of the interplanetary data used by Finch and Lockwood contained many data gaps 574 of a wide range of durations whereas we here employ data from 20 years that has a relatively 575 small number of relatively short data gaps.  $P_{\alpha}$  is designed to be an estimate of the power input 576 that drives the substorm cycle and the geomagnetic am index has been shown to be an excellent 577 indicator of the geomagnetic response to that energy input on timescales longer than the 578 579 substorm cycle of energy storage and release (typically 1-2 hours) [Finch et al., 2007; Finch, 2008]. Hence, there is no physical reason why the optimum  $\alpha$  should vary with averaging 580 timescale and so Finch and Lockwood considered the variation of  $\alpha$  with  $\tau$  a somewhat 581 unsatisfactory result that may have arisen from the presence of large data gaps in interplanetary 582 data. In the next section we introduce synthetic data gaps into the near-continuous data since the 583 start of 1996 to investigate their effects and see if this was indeed the case. 584

# 4. The effect of data gaps on the peak correlation and the derived optimum coupling exponent

#### 4.1. Simulation of the effects of the interplanetary data gaps before 1995

- To test for the effect of data gaps we here use the interplanetary data for 1996-2016, inclusive (for which over 80% of the data meets our availability criterion of  $\varepsilon_{hr} \le 5\%$ ) but introduce synthetic data gaps using 500 masks. To keep the same distributions of gap durations and frequency as were observed in the earlier (pre-1995) interplanetary data series (see Figure 2), we here take the sequence data gaps in the Omni hourly dataset (30-*D*) years earlier where *D* is varied between 0 and 10 years in steps of 0.02 years (175 hours). Because of the large number of data masks considered and because of the need to repeat for the full range of  $\alpha$  values, the tests are here restricted to annual means (i.e.  $\tau = 1$  year). For each of the 500 cases, the synthetic data gaps were then dealt with in 4 different ways:
  - A. The interplanetary data were averaged into a mean over interval of length  $\tau = 3$  hours only if there are 3 valid hourly means available (by our criterion of sufficient one-minute samples in the hour to give an error below 5%). The simultaneous *am* data during gaps in these 3-hourly  $P_{\alpha}$  data series were piecewise removed using the procedure of *Finch and Lockwood* [2017] before both *am* and  $P_{\alpha}$  were averaged into annual means. Similar piecewise removal of Dst data during solar wind data gaps was used by *Temerin and Li* [2006].
    - B. The full *am* data series (with no piecewise data removal) and all the available hourly  $P_{\alpha}$  data were used (i.e. the presence of data gaps in  $P_{\alpha}$  was ignored).
    - C. The full am data series were used and the available 1-hour  $P_{\alpha}$  data were linearly interpolated to fill the data gaps before both am and  $P_{\alpha}$  were averaged. This method was used (at 10-minute resolution) in the coupling function study by *Temerin and Li* [2002].
    - D. The full *am* data series were used and the  $P_{\alpha}$  data interpolated to fill data gaps using the scheme adopted by *Svalgaard and Cliver* [2005]. Specifically, the hourly means were calculated and combined into daily means (in Universal Time), even if only one hourly mean was available; the 27-day Bartels rotation mean was calculated from available daily

means (again even if only one was available); if there were no data for a rotation, its 613 mean was linearly interpolated from surrounding rotations. The average for a year was 614 then calculated from the Bartels rotations with center dates in the year in question. 615 In all cases both the "combine-then-average" and the "average-then-combine" procedures were 616 studied. This is an additional complication that applies to all 4 methods. We here term annual 617 values of  $P_{\alpha}$  generated by the former  $\langle P_{\alpha} \rangle_{\text{lyr}}$  and by the latter as  $\langle P_{\alpha} \rangle_{\text{ann}}$ . Figure 9a shows the 618 time series of  $\langle P_{\alpha} \rangle_{1yr}$  (in red) and  $\langle P_{\alpha} \rangle_{ann}$  (in blue) (both normalized to ratio of Po, their 619 average value over the whole period) and Figure 9b the scatter plot of  $\langle P_{\alpha} \rangle_{ann} / P_{\alpha}$  as a function 620 of  $\langle P_{\alpha} \rangle_{1yr} / P_{\alpha}$ . The agreement is very close indeed for after 1995 (the linear correlation 621 622 coefficient is 0.99, with a 2-\sigma uncertainty range of 0.97-0.995) but the increased scatter of the green points shows it is not so close for the data before 1996 (linear correlation coefficient 0.93, 623 with a 2-σ uncertainty range of 0.86-0.97). Hence it appears that data gaps also play a role in 624 creating a difference between these two ways of generating annual estimates of this coupling 625 function. 626 Figure 10 shows the results of using Method B to deal with data gaps. In this method the 627 628 (synthetic) data gaps are effectively ignored and the annual mean  $P_{\alpha}$  data series constructed from the available data (after removal of the synthetic data gaps), whereas  $\langle am \rangle_{1yr}$  is 629 constructed using all of the (continuous) am data. This method assumes that the effects of data 630 gaps average out, and this is the most common way of dealing with the missing data. In Figure 631 10a, the red and blue lines are the correlograms (correlation coefficient r as a function of 632 633 assumed coupling exponent,  $\alpha$ ) for all the 1996-2016 data (i.e. no synthetic data gaps are 634 introduced) showing, in red,  $r(\alpha)$  for am and  $\langle P_{\alpha} \rangle_{1\text{vr}}$  (the combine-then-average annual estimates) and, in blue,  $r(\alpha)$  for am and  $P_{\alpha}$  and the average-then-combine annual estimates). 635 As found by Lockwood et al. [2017a] the peak,  $r_p$ , is at slightly higher  $\alpha$  for  $\langle P_{\alpha} \rangle_{ann}$  than for 636  $< P_{\alpha} >_{1 \text{yr}} (\alpha_p = 0.44 \text{ and } \alpha_p = 0.48, \text{ marked by the vertical green and orange lines, respectively)}.$ 637 Note that this is despite the fact that, as shown by figure 9,  $\langle P_{\alpha} \rangle_{ann}$  and  $\langle P_{\alpha} \rangle_{lyr}$  are very 638 highly correlated (r = 0.99) for this interval. The solid points are the means of the values of  $r(\alpha)$ 639 for am and  $\langle P_{\alpha} \rangle_{1yr}$  from the runs for the  $N_S = 500$  different data masks, and the error bars are 640

 $\pm 1$  standard deviation. It can be seen that correlations at a given  $\alpha$  are generally reduced 641 compared to that for the full available data series. The mean correlation at the peak (at  $\alpha = \alpha_p =$ 642 0.44, marked by the vertical green line) is reduced from 0.99 to  $r_{avp} = 0.94$  with a standard 643 deviation for the  $N_S$  simulations of  $\sigma_{avp} = 0.04$  and the optimum  $\alpha$  is increased to 0.48, compared 644 to the 0.44 obtained without data gaps. The gray histogram in Figure 10(b) shows the distribution 645 of the derived  $\alpha_p$  values (giving the peak  $r = r_p$  between  $\langle P_{\alpha} \rangle_{1yr}$  and  $\langle am \rangle_{1yr}$ ) for the  $N_S = 500$ 646 different data gap masks. It can be seen that the mode value of this distribution is  $\alpha_m = 0.48$  and 647 the median  $\alpha_{0.5} = 0.43$ . It must be remembered that we have introduced 500 sets of data gaps but 648 only one would have existed in the actual pre-1996 data and so it is really the range of possible 649 individual values in Figure 10b that we need to consider, rather than the mean, median or mode 650 of the distribution. The standard deviation of the distribution of the 500  $\alpha_p$  values is  $\sigma = 0.116$ , 651 the minimum to maximum range is 0.14 - 1.00 and the lower and upper 2- $\sigma$  points are  $\alpha_{0.05}$  = 652 0.24 and  $\alpha_{0.95} = 0.67$ . It must be remembered that the only difference between the 500 653 654 simulations is when the data gaps happen, by chance, to fall and neglecting the effect of data gaps (the most commonly used procedure) could generate any one of the  $\alpha$  values in this 655 distribution. 656 657 Figure 10c shows the corresponding distribution of  $\alpha_p$  values giving the peak r between  $\langle P_{\alpha} \rangle_{ann}$ and <am><sub>1yr</sub> for the 500 different data gap masks. The effects of data gaps are very similar to 658 those for  $\langle P_{\alpha} \rangle_{1\text{vr}}$ , namely a very wide range of  $\alpha_p$  values are possible, depending on when the 659 data gaps happen to fall, and the most likely value is larger than the "true" value (by "true" in 660 this context we mean the value obtained without the introduction of synthetic data gaps). We 661 stress here that we have used the sequence of data gaps that actually existed in the pre-1995 662 interplanetary data series and so these large uncertainties apply to all studies that used such data 663 but made no allowance or data gaps. 664 Table 1 summarizes the results shown by Figure 10 for Method B and compares them to the 665 results or the other methods. The plots corresponding to Figure 10 for the other methods are 666 included in the supplementary materials to this paper. In this section we highlight the major 667 differences between the results. 668

The results or the piecewise removal of am data using the procedure of Finch and Lockwood 669 [2007] (Method A) are surprisingly similar to those shown in Figure 10 for Method B. On 670 average, the correlations are very slightly increased ( $r_{avp}$  is 0.95 instead of 0.94) but the 671 distributions  $\alpha_p$  are actually slightly broader for Method A for both  $\langle P_{\alpha} \rangle_{1yr}$  and  $\langle P_{\alpha} \rangle_{2nn}$ . 672 However the distribution medians are closer to the "true" values (data gap free, i.e. 0.44 and 673 0.48) in both cases. Hence we can say that the procedure of Finch and Lockwood [2007] is an 674 improvement over neglecting data gaps and averaging over all available data; however, it is only 675 a very small improvement in the context of improving the peak correlation and is slightly more 676 likely to give the correct estimate of the optimum  $\alpha$ . 677 The most unsatisfactory method for dealing with the (synthetic) gaps in 1-hour  $P_{\alpha}$  data is to fill 678 them using interpolation (method C). This is here implemented using linear interpolation but 679 results are even worse if cubic splines or PCIP are used. The peak correlations are lower, the 680 distributions of  $\alpha_p$  are very wide and the median and mode values of those distributions shifted 681 away from the "true" (i.e., data gap free) value. We note this method was used (on pre-1995 682 data) by Temerin and Li [2002]; however, we also note that the same authors soon after moved to 683 684 using a variant of method A and only data from after 1995 with considerable improvement of the correlation between their coupling function and the Dst geomagnetic index [Temerin and Li, 685 2006]. There are many variants of interpolation procedures. Others have used interpolation with 686 restrictions, for example Wu and Lundstedt [1997] deployed autocorrelation-based interpolation 687 for data gaps of up to 5 hours, and intervals with longer data gaps excluded from the study (a 688 variant of method A). 689 Method D was used by Svalgaard and Cliver [2005]. This method performs better than Method 690 C but significantly less well than Methods A and B. Hence it is better to simply ignore the effect 691 of data gaps than use Method D. The reason is that Method D enables some datapoints to take on 692 far too great statistical weight. For example, if there were a single 1-minute sample in a whole 693 Bartels rotation, it would be used in method D to give the Bartels rotation mean value, thereby 694 giving that data point a huge weighting. This extreme possibility illustrates why the Method D 695 introduces extra noise by giving some datapoints too much weight. 696

#### 4.2. For the availability of interplanetary data after 1995 697 The previous section shows that Method A is the best method for dealing with data gaps; 698 however, it is only a very marginal improvement on making no allowance for data gaps (Method 699 700 B). These two methods perform significantly better than the others tested, but Table 1 shows both give a considerable spread of $\alpha_p$ values (standard deviations $\sigma > 0.1$ and deviations of 2- $\sigma$ 701 points > 0.2). Hence data gaps in the pre-1995 will have been a large factor in producing the 702 range of optimum $\alpha$ values in the literature. 703 704 In this section, we assess the effects of data gaps when the data availability rises to over 80%, as has been the case since 1995 (with $\varepsilon_{th} \le 5\%$ ). To do this we use the same procedure as was used 705 in the last section, but we have fewer data available (for 1995 and after) from which to make the 706 masks to introduce synthetic data gaps. Hence we test the 1996-2016 dataset using 500 masks 707 that are the occurrence of data gaps 1-D years earlier where D is varied between 0 and 1 yr in 708 709 steps of 17.5 hours. Figure 11 shows the results in the same format as Figure 10. It can be seen that the correlations 710 for any of the 500 masks are only slightly reduced compared to the values for no additional data 711 gaps. The optimum $\alpha$ is unchanged and the 500 masks give a standard deviation $\sigma$ of only 712 0.014. It is instructive to compare this to the uncertainty in the $\alpha$ of peak correlation ( $\alpha_p$ ) 713 between am and $\langle P_{\alpha} \rangle_{1yr}$ for this $\tau$ (1 year) with the +0.11 to -0.08 1- $\sigma$ error from the Meng-Z 714 test, as shown in figure 4. Hence data gaps are contributing to the uncertainty in $\alpha_D$ when data 715 availability is 83% (post 1995) but are far from the dominant factor and so uncertainties 716 introduced by the data gaps are smaller than that inherent in the correlations due to instrumental 717 and geophysical noise in both $P_{\alpha}$ and am. In contrast, the test of Method A with data gap masks 718

#### 5. Discussion and Conclusions

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drawn from before 1995 (when average data availability is 30%) shows that these uncertainties

rise to  $\pm 0.13$  and so errors due to data gaps would be dominant.

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Figure 1 and comparison of the columns in Table 1 gives a number of important insights into the effect of data gaps on the tuning of coupling functions to reproduce and predict terrestrial space weather responses. The first is that the low auto-correlation time constant of the IMF orientation factor means that hourly samples that do not have 82% data availability within the hour cause errors greater than 5% (at the 1- $\sigma$  level) in hourly values of coupling functions, such as  $P_{\alpha}$ , and should be treated as bad data and removed. Note that this error could be reduced by requiring a higher availability, but this would generate a great many and longer data gaps. The second insight is that piecewise removal of the terrestrial response index during interplanetary data gaps is the best option for dealing with data gaps although, on annual scales at least, the improvement over simply neglecting them is very small. We recommend Method A on principle and tests at lower  $\tau$  (not presented here) show it sometimes performs significantly better than Method B. All the interpolation methods to fill in data gaps that we tested introduced errors and performed less well than ignoring data gaps and we recommend that interpolation should always be avoided in this context. If interpolation is to be used we recommend a "reanalysis" approach, using a physical model such as ENLIL (and not a statistical empirical model) and even then it should only be applied over appropriate timescales. Using the dataset with the requirement that IMF availability in each hour is 82% (which limits the uncertainty in hourly  $P_{\alpha}$  values to  $\pm 5\%$  at the 1- $\sigma$  level) we find that the optimum coupling exponent of  $\alpha = \alpha_p = 0.44 \pm 0.02$  at all averaging timescales  $\tau$  between 1 minute and 1 year. We find no significant variation of this value with τ. From equation (6), this yields dependencies on  $B^{0.88}$ ,  $V_{\rm sw}^{1.90}$ , and  $(m_{\rm sw}N_{\rm sw})^{0.23}$ . A dependence on B has been found in a great many proposed coupling functions [e.g., Kan and Lee, 1979; Wygant et al., 1983; Scurry and Russell, 1991; Temerin and Li, 2006]. The 1- $\sigma$  uncertainty on the optimum  $\alpha$  found here is  $\pm 0.02$  which allows a variation of anywhere between  $B^{0.84}$  and  $B^{0.92}$ ; however, this is not enough to explain the discrepancy with a dependence on B, nor with the result of Newell et al. [2007] who find a  $B^{0.67}$ dependence (probably because these authors were attempting to match a wide range of terrestrial response measures). The dependence found here is close to  $BV_{sw}^2$  and similar to that found in a

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great many other studies. Lockwood [2013] studied the optimum values of n for functions of the
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       form BV_{sw}^n and found that n = 2 for AL, n = 1.9 for aa, n = 1.8 for am, and n = 1.6 for ap. The
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       optimum value deduced here for am is n = 1.90 and allowing for the uncertainty in the peak \alpha
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       (\pm 0.02) the, n derived here is between 1.75 and 1.91. However, bearing in mind that Lockwood
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       [2013] used annual means of data from 1966 onwards with the Finch and Lockwood [2007]
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       method (A) to deal with data gaps, Table 1 shows a 1-\sigma uncertainty in \alpha of \pm 0.12 would apply to
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       the Lockwood [2013] values which means that n could be between about 1.86 and 2.24 for AL
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       and between 1.55 and 2.04 for am. Hence results of Lockwood [2013] for the mid-latitude
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       station range indices am, ap and aa and the auroral electrojet index AL are not inconsistent with
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       the result found here for am when we allow for the potential effect of data gaps.
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       The IMF orientation factor \sin^4(\theta/2) is here assumed rather than fitted, but we note overall
       correlations are extremely high at all \tau, rising to 0.990 for \tau = 1 year for am (and 0.997 or ap).
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       However at \tau = 1 year this factor averages out to an almost constant number [Lockwood, 2013;
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       Lockwood et al., 2017a] and so the exponent used has no effect. Although \sin^4(\theta/2) is the most
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       used formulation, Kan and Lee [1979] used \sin^2(\theta/2), Temerin and Li [2006] used \sin^6(\theta/2), and
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       Newell et al. [2007] derived \sin^{8/3}(\theta/2). We have repeated our correlation study for \sin^{1/3}(\theta/2)
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       with i of [6:1:18]. Although there were very slight differences (<1%) in peak correlation, r_D, and
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       optimum \alpha, \alpha_p at low \tau, they were not statistically significant for any of the i tested. Hence the
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       correlogram with i is exceptionally flat and we find no evidence that the widely-used \sin^4(\theta/2)
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       dependence is not optimum.
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       The derived dependence on (m_{sw}N_{sw})^{0.23} is interesting. The exponent of this term would be zero
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       if \alpha = 2/3, removing any dependence on the solar wind mass or number flux. This is because for
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       \alpha = 2/3 the effect of an increase in mass flux (m_{\rm sw}N_{\rm sw}) on the particle kinetic energy flux in the
       solar wind (m_{sw}N_{sw}V_{sw}^3) would be cancelled by the compressional effect of the solar wind
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       dynamic pressure (m_{sw}N_{sw}V_{sw}^2) and the reduction of the target area presented to the solar wind
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       flow by the geomagnetic field. The lower \alpha of 0.44 means that the first effect is the slightly
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       larger of the two and there is a (weak) dependence on solar wind mass flux (m_{\text{sw}}N_{\text{sw}}), variations
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       in which are dominated by the number flux (N_{sw}). Several studies have found that increased N_{sw}
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increases terrestrial space weather response to IMF changes [e.g., Lopez et al. 2004; Weigel, 778 2010] but many coupling functions do not include a term in either  $(m_{sw}N_{sw})$  or  $N_{sw}$ . Newell et al. 779 [2007] also found a  $(m_{sw}N_{sw})^{1/6}$  dependence, but chose to omit it from their coupling function in 780 the interests of making it match a wide range of terrestrial responses. 781 Plots corresponding to those presented in this paper, but using the geomagnetic ap index rather 782 783 than am, are given in the supplementary materials. These plots are very similar indeed to those for am in all cases. Table 2 shows how ap correlates slightly better with  $P\alpha$  on annual averaging 784 timescales, but am performs slightly better at 27 days, 1 day and 3 hours. This is consistent with 785 an analysis of the two indices that have carried out showing that the empirical, tabular K-to-K<sub>S</sub> 786 conversions used to make Kp (and hence ap) introduce spurious diurnal and annual variations, 787 but these are averaged out on annual timescales, on which ap gains an advantage in noise 788 suppression by averaging data from a more concentrated cluster of stations in Europe. The best 789 fit α values are higher for ap than for am by between 0.02 and 0.06. Figure 7 investigates the 790 implications of the precise value of  $\alpha$ . Parts (c) and (d) of Figure 7 demonstrate that the 791 difference in  $\alpha_p$  for the two indices makes almost no difference to the distribution of the 792 normalized power input to the magnetosphere,  $P_{cl}/P_{o}$ , but part (b) shows it does influence the 793 794 average value over the whole interval 1996-2016, Po, and hence the absolute magnitude of the power input which is estimated. Because am has a more uniform time-of-day-time-of-year 795 response pattern, we prefer the value obtained for am, which is  $P_0 = (0.38 \pm 0.06) \times 10^{19}$  W (at the 796 2σ uncertainty level). However, the sensitivity of this value to the index used illustrates how 797 difficult it is to get an absolute power input value accurately even though the variation in  $P_0/P_0$  is 798 well defined. 799 Lockwood et al. [2017] have estimated the annual mean power input into the magnetosphere for 800 all years back to 1612 from the reconstructed solar wind and interplanetary field parameters 801 derived by Owens et al. [2017], and from this Lockwood et al. [2018a] have derived the annual 802 803 means of Ap and AE back to this date. In the two subsequent papers in the present series [Lockwood et al., 2018b; c] we begin to construct a space weather climatology by studying the 804 distributions of space weather parameters about these averages and, in particular, how these 805 distributions evolve with timescale. The present paper is an important first step in this because

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it shows that the formula for the optimum coupling function does not significantly evolve with timescale. Previous studies that suggested there was such a variation had been influenced by data gaps which have different effects on different timescales. Removing this potential complication (by showing that the optimum coupling exponent  $\alpha$  is, in fact, independent of timescale) is a valuable first step in the construction of a useful space weather climatology.

#### **Acknowledgments and Data**

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**Table 1.** Comparison of the performance of methods to handle data gaps or annual data. The rows, from top to bottom, give: (1) the ranking order of the accuracy the method; (2) the interval used to give data gap masks; (3) the number of masked data simulations,  $N_s$ ; (4) the peak value of the average correlation coefficient,  $r_{avp}$ , from the  $N_s$  simulations, plus and minus (when  $N_s > 1$ ) the standard deviation at that peak,  $\sigma_{avp}$  (shown in Figure 10a for the case of Method C by the black dot and error bar aligned with the vertical green line); (5) and (10) the value of  $\alpha$  giving that peak,  $\alpha_{avp}$  (marked by the vertical green line); (6) and (11) the mode value  $\alpha_m$  of the distribution (given in Figure 10b or 10c for Method C) of the  $N_s$  individual  $\alpha$  values giving peak correlation; (7) and (12) the standard deviation of that distribution,  $\sigma$ ; (8) and (13) the median value of that distribution,  $\alpha_{0.5}$ ; (9) and (14) the range between the upper and lower 2- $\sigma$  points of that distribution,  $(\alpha_{0.05}-\alpha_{0.95})$ . Rows (4) to (9) apply to the combine-then-average annual means,  $< P_{\alpha} >_{1 \text{vr}}$  (the distribution shown in Figure 10b for Method C) and rows (10) to (14) apply to the combine-then-average annual means,  $\langle P_{\alpha} \rangle_{ann}$  (the distribution shown in Figure 10c for Method C). Row (15) gives the relevant figure. The columns are for: the single analysis with no simulated data gaps (the ideal case that the methods are trying to reproduce) and Methods A-D. Method A is applied with data masks drawn from both 1995-2015 and from 1966-1994. The other methods are only used with masks from 1966-1994.

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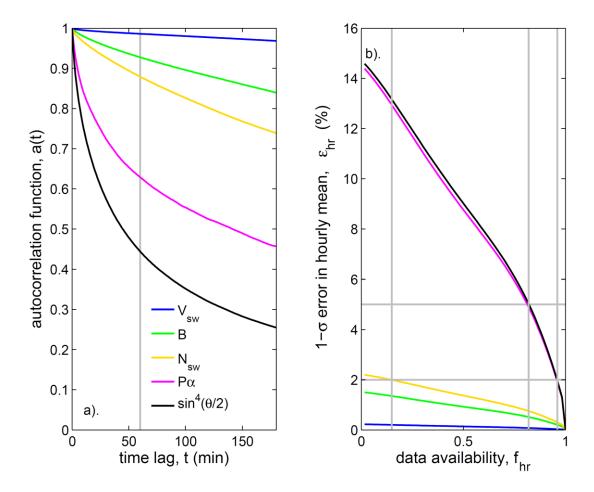
Averaging used			No added data gaps	Method A	Method A	Method B	Method D	Method C
	1	Rank	-	-	1	2	3	4
	2	Dates giving gap masks	-	1995-2015	1966-1994	1966-1994	1966-1994	1966-1994
	3	Number of gap simulations, $N_s$	1	500	500	500	500	500
Combine then average, $< P_{\alpha}>_{1 \text{yr}}$	4	peak average correlation $r_{\text{avp}} \pm \sigma_{\text{avp}}$	0.990	0.989±0.002	0.96±0.04	0.94±0.04	0.92±0.06	0.86±0.09
	5	$\alpha$ giving peak $r_{av}$ , $\alpha_{avp}$	0.44	0.44	0.47	0.48	0.5	0.52
	6	Mode of $\alpha$ distribution, $\alpha_m$	0.44	0.44	0.40	0.48	0.52	0.56
	7	Standard deviation, σ	0	0.014	0.132	0.116	0.150	0.239
	8	Median, $\alpha_{0.5}$	0.44	0.435	0.44	0.43	0.46	0.49
	9	5 percentile range ( $\alpha_{0.05}$ - $\alpha_{0.95}$ )	0.44-0.44	0.404-0.445	0.24-0.67	0.27-0.65	0.20-0.71	0.16-0.96
Average then combine,	10	$\alpha$ giving peak $r_{av}$ , $\alpha_{avp}$	0.48	0.51	0.50	0.54	0.54	0.46
	11	Mode of $\alpha$ distribution, $\alpha_m$	0.48	0.48	0.50	0.49	0.56	0.56
	12	Standard deviation, σ	0	0.014	0.152	0.105	0.130	0.217
	13	Median, α <sub>0.5</sub>	0.48	0.476	0.49	0.50	0.51	0.58
	14	5 percentile range ( $\alpha_{0.05}$ - $\alpha_{0.95}$ )	0.48-0.48	0.451-0.498	0.31-0.76	0.35-0.68	0.32-0.74	0.29-1.05
		Figure(s)	3	11 and S9	S5	10 and S6	S7	S8

## **Table 2.** Correlations between P $\alpha$ and the ap and am indices

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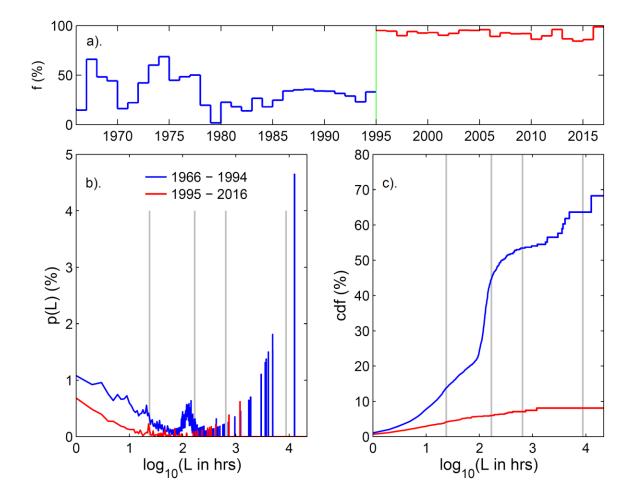
averaging timescale, τ	correlation coefficient, r		2-σ range in <i>r</i>		optimum coupling exponent, $\alpha_p$	
Index	ар	am	ар	am	Ap	am
1 year	0.997	0.990	0.993- 0.999	0.971 - 0.995	0.46	0.44
27 days	0.959	0.968	0.949 - 0.968	0.960 - 0.975	0.50	0.44
1 day	0.897	0.927	0.893 - 0.901	0.923 - 0.930	0.48	0.43
3 hours	0.790	0.855	0.787 - 0.793	0.853 - 0.858	0.48	0.45

#### **Figures**

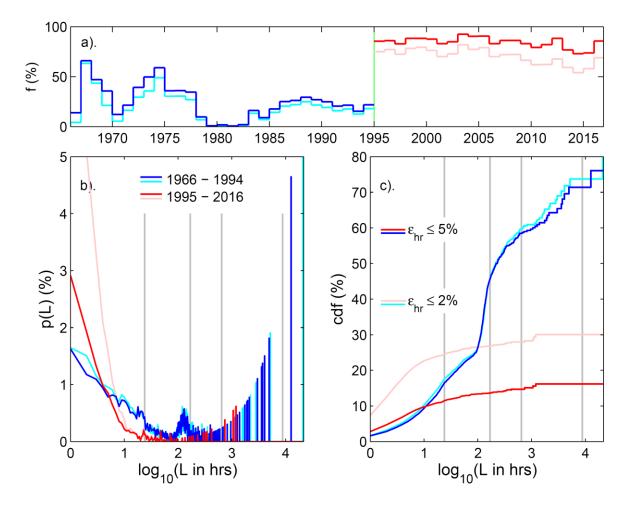


**Figure 1.** (a) Autocorrelation functions, a(t) as a function of lag time, t, for 1-minute samples of: (blue) solar wind speed,  $V_{\rm sw}$ ; (orange) solar wind number density,  $N_{\rm sw}$ ; (green) interplanetary magnetic field (IMF), B; (mauve) power input to the magnetosphere (for  $\alpha = 0.5$ ),  $P_{\alpha}$ ; and (black) IMF orientation factor,  $\sin^4(\theta/2)$ . The vertical gray line marks t = 1 hour. (b) 1-σ percentage errors in hourly means,  $\varepsilon_{\rm hr}$ , as a function of data availability within the hour,  $f_{\rm hr}$ , for the same parameters (modulated by introducing synthetic data gaps, see text), shown using the same color scheme. The horizontal gray lines in (b) are uncertainties  $\varepsilon_{\rm hr}$  of 5% and 2% which set threshold requirements for IMF orientation data availability of  $f_{\rm hr} \ge 0.82$  and  $f_{\rm hr} \ge 0.96$ , respectively. The  $\varepsilon_{\rm hr} \le 2\%$  condition sets an additional availability requirement on  $N_{\rm sw}$  data of  $f_{\rm hr}$ 

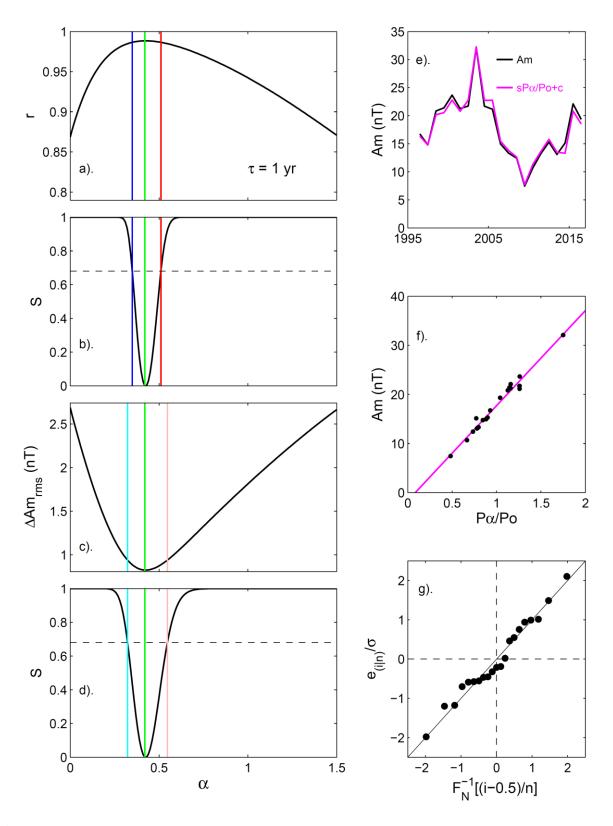
1164  $\geq$  0.15. These  $f_{hr}$  thresholds are shown by the vertical gray lines. Plots are constructed using 1-1165 minute Omni samples for 1996-2016.



**Figure 2.** Analysis of data gap occurrence in the  $P_{\alpha}$  interplanetary data. Data in blue are for 1966-1994 (inclusive) and in red are for 1995-2016 (inclusive). Data gaps are here defined by the absence of any sample in one-hour intervals, as used in compiling Omni2 data hourly samples. (a) the availability f of 1-hour means in calendar years. (b) The probability of being in a data gap of duration L, p(L), shown as a function  $\log_{10}(L)$  for L between 1 hour and 1 year, for before and after 1 January 1995 (blue and red lines, respectively). (c) The cumulative probability distribution as a function of  $\log_{10}(L)$ . The total probability for being within a data gap for 1966-1994 is 67% (so the average data availability is < f > = 33%) and for 1995-2016 it is 8% (< f > = 92%). Gray vertical lines in (b) and (c) are at 1 day, 7 days, 27 days and 1 year.

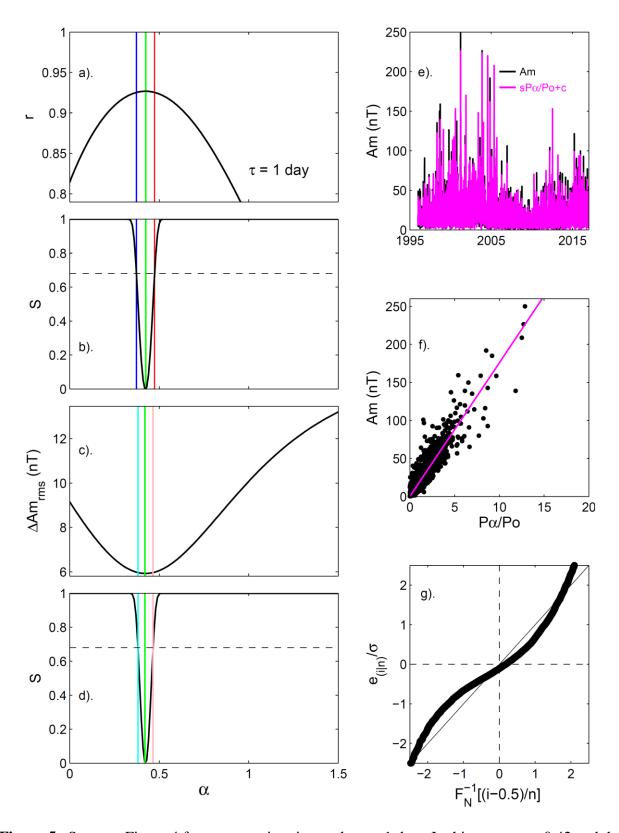


**Figure 3.** Same as Figure 2 for more stringent criteria as to what constitutes a valid hourly sample. Specifically, for the red and blue lines we require that solar wind data availability gives an average uncertainty in the hourly coupling function  $P_{\alpha}$  values of ε<sub>hr</sub> ≤ 5% and for the pink and cyan lines we require ε<sub>hr</sub> ≤ 2%. Blue and cyan lines are for before 1995: ε<sub>hr</sub> ≤ 5% gives the blue lines and 23.9% availability of hourly sample; lowering the uncertainty limit to ε<sub>hr</sub> ≤ 2% lowers this availability to 18.9% (cyan lines). Red and pink lines are for 1995 and after: ε<sub>hr</sub> ≤ 5% gives the red lines with 83.8% availability of hourly samples; lowering the uncertainty limit to ε<sub>hr</sub> ≤ 2% lowers this availability to 70.0% (pink lines).



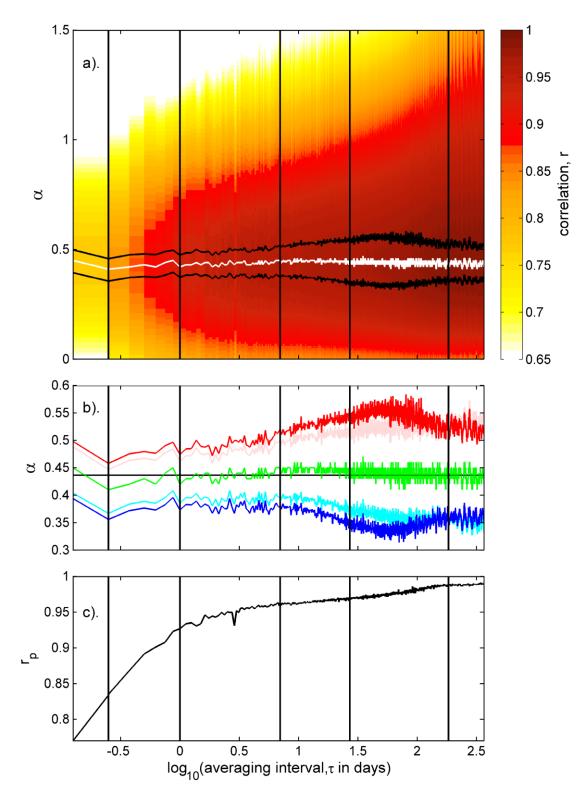
**Figure 4.** Analysis of correlation between power input to the magnetosphere,  $P_{\alpha}$ , and the am

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geomagnetic index for averaging timescale \tau = 1 yr over the interval 1996-2016 (inclusive).
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          Panels (a)-(d) show, as a function of the coupling exponent \alpha, (a) the correlation coefficient r
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          between \langle Am \rangle_{1\text{yr}} and \langle P_{\alpha} \rangle_{1\text{yr}}; (b) the significance, S, of the difference between the peak value
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          of r, r_p (marked by the vertical green line at \alpha = \alpha_p = 0.42) and the r at any other \alpha, r(\alpha),
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          computed using the Meng-Z text (see text for details): the vertical red and blue lines are where S
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1192
          = 0.68 and so mark where r is significantly lower than r_p at the 1-\sigma level; (c) the r.m.s.
          difference, \Delta Am_{rms} between \langle Am \rangle_{1yr} and the best fit (for \alpha = \alpha_p) of \langle P_{\alpha}/P_o \rangle_{1yr}, Am_{fit} =
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          s.\langle P_{\alpha}/P_{o}\rangle_{1\text{yr}} + c, where P_{o} is the average of P_{\alpha} for all the data and the linear best-fit regression
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          coefficients s = 19.37 \pm 0.42 and c = -1.64 \pm 0.31. (d) shows the significance S of the difference
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          between \Delta Am_{rms} for \alpha = \alpha_p and that at other \alpha, computed using a 2-sample variance F test (see
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          text for details): pink and cyan vertical lines are at S = 0.68. (e) shows the time series of
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          <\!\!Am\!\!>_{1\text{yr}} (in black) and the best-fit Am_{\text{fit}} (in mauve);. (f) Scatter plot of <\!\!Am\!\!>_{1\text{yr}} against <\!\!P_{\alpha}/P_{\alpha}
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          >_{1\text{yr}} for \alpha = \alpha_p with the best-fit linear regression line shown in mauve. (g) is a quantile-quantile
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          (q-q) plot of the best-fit fit residuals of Am_{\text{fit}} and \langle Am \rangle used to test for the normality of their
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          distribution: e_{(i|n)}/\sigma are the ordered standardized residuals and F_N^{-1}[(i-0.5)/n] are the quantiles of
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          the standard normal distribution.
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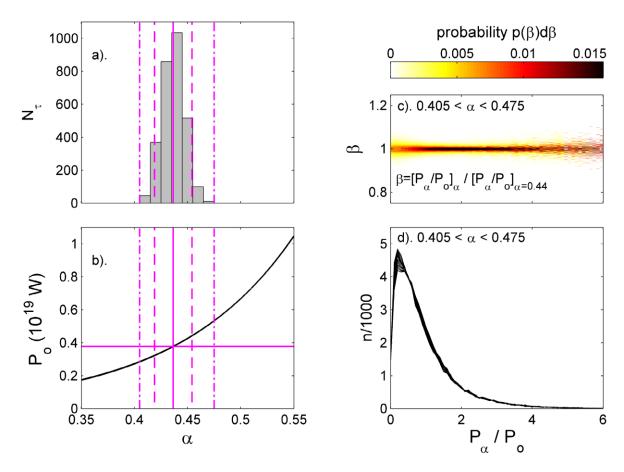
**Figure 5.** Same as Figure 4 for an averaging timescale  $\tau = 1$  day. In this case,  $\alpha_p = 0.42$  and the

best-fit linear regression coefficients are  $s = 17.58 \pm 0.89$  and  $c = 0.02 \pm 0.40$ .

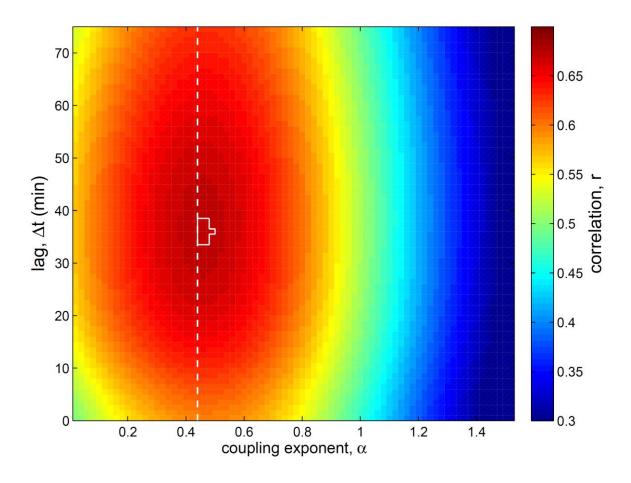


**Figure 6.** (a). Correlation coefficients between  $\langle am \rangle_{\tau}$  and  $\langle P_{\alpha} \rangle_{\tau}$  for the interval 1996-2016 (inclusive), r, color-coded as a function the logarithm of averaging timescale,  $\log_{10}(\tau)$ , and the

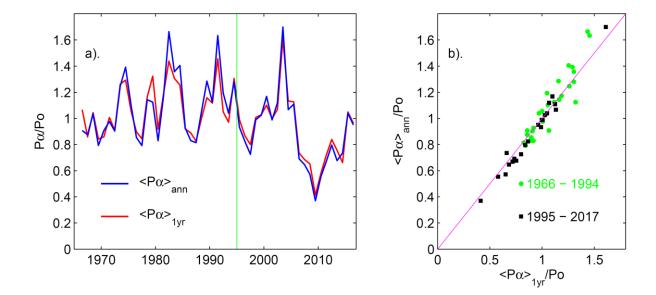
coupling exponent,  $\alpha$ . The middle white line gives the peak of each vertical slice, i.e. the optimum  $\alpha$ ,  $\alpha_p$  (for which r has a maximum value  $r_p$ ) (as shown by the vertical green lines in Figures 4a and 5a for  $\tau = 1$  yr and  $\tau = 1$  day, respectively). The upper and lower black lines give the  $\pm 1\sigma$  uncertainty of  $\alpha_p$  from the Meng-Z test (as shown by the vertical red and blue lines in Figure 4a for  $\tau$  of 1 year and in Figure 5a for  $\tau$  of 1 day, respectively). The left-hand edge of the plot is at  $\tau = 3$  hrs, the right hand edge at  $\tau = 1$  yr, and the vertical lines show  $\tau$  of 6 hours, 1 day, 7 days, 27 days and 0.5 year. (b) Variation of best  $\alpha$  estimates ( $\alpha_p$ ) and uncertainties. Line colors are as are used in Figures 4 and 5. The green line give the results for  $\alpha_p$  from both the peak correlation ( $r = r_p$ ) and the minimum r.m.s. fit deviation ( $\Delta Am_{rms}$ ), which are always exactly the same. The blue and red lines are the  $\pm 1$ - $\sigma$  uncertainties in  $\alpha_p$  computed from the  $r(\alpha)$  variation at each  $\tau$  using the Meng-Z test. The cyan and pink are the 1-sigma uncertainties in  $\alpha_p$  computed from the fit residuals  $\Delta Am_{rms}(\alpha)$  variation using a two-sample variance F test. (c) The peak correlation  $r_p$  as a function of  $\log_{10}(\tau)$ .



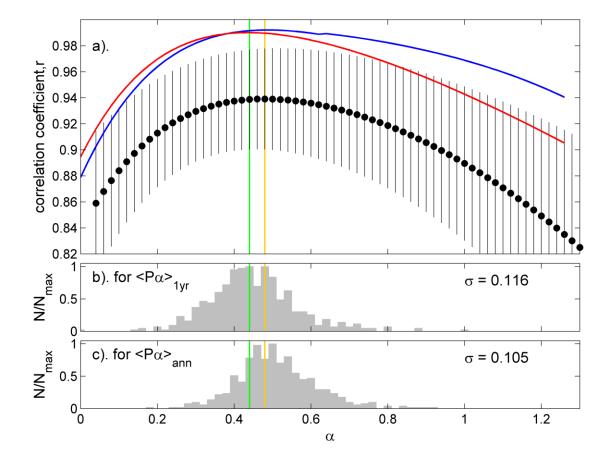
**Figure 7.** Analysis of the effects of the uncertainty in the best-fit  $\alpha$ . (a). The distribution of best fit  $\alpha$  values from the analysis of 2922 τ-values surveyed in figure 6. The vertical mauve dashed lines are the 2-σ points of the distribution and the dot-dash lines mark the extreme values. (b) The variation of the mean value of power input into the magnetosphere over the interval 1996-2017,  $P_0$ , as a function of  $\alpha$ : the average  $\alpha$  is 0.44 which gives  $P_0 = 0.38 \times 10^{19}$  W and the uncertainty range of  $\alpha$  of 0.42- 0.45 at the 2-σ level (between the dashed lines) gives  $P_0$  between 0.32×10<sup>19</sup> W and 0.44×10<sup>19</sup> W. The extreme limits of  $\alpha$  of 0.41 and 0.47 yield  $P_0$  of 0.29×10<sup>19</sup> W and 0.53×10<sup>19</sup> W, respectively. (c) Analysis of the effect of  $\alpha$  on 3-hourly  $P_0/P_0$  values: the probability density is color-coded of values of  $\beta = [P_0/P_0]_0/[P_0/P_0]_{\alpha=0.44}$  for the full range of  $\alpha$  of 0.41-0.47 (computed in steps of 0.01). (d) The distributions of  $P_0/P_0$  values for this full range of  $\alpha$ .



**Figure 8.** The correlation r of 1-minute  $P_{\alpha}$  values with 1-minute values of the SuperMAG auroral electrojet index, SME, color-coded as a function of coupling exponent,  $\alpha$  (horizontal axis) and time lag,  $\Delta t$  (vertical axis). Positive  $\Delta t$  is when  $P_{\alpha}$  is lagged, i.e. the SME variation follows  $P_{\alpha}$ . Inside the white contour the correlation is not significantly different from the peak value at the 1- $\sigma$  level. The vertical white dashed line is at  $\alpha = 0.44$ .

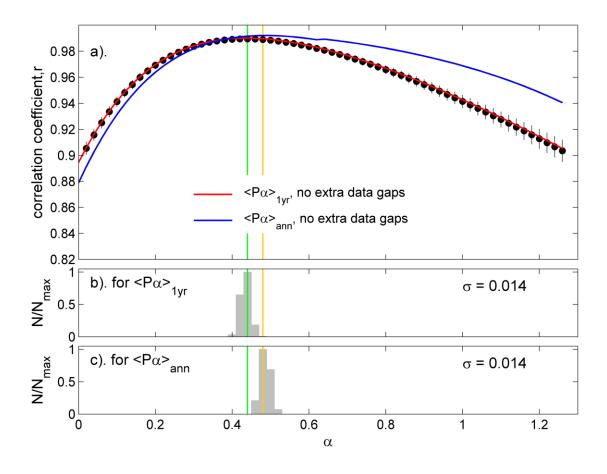


**Figure 9.** Comparison of "combine-then-average" and "average-then-combine" annual values of  $P_{\alpha}$  (respectively,  $\langle P_{\alpha} \rangle_{\rm lyr}$  and  $\langle P_{\alpha} \rangle_{\rm ann}$ ). Note that the optimum coupling exponent is used which is  $\alpha_{\rm p} = 0.44$  for  $\langle P_{\alpha} \rangle_{\rm lyr}$  and  $\alpha_{\rm p} = 0.48$  for  $\langle P_{\alpha} \rangle_{\rm ann}$ . (a) The time series of values (normalized to  $P_{\rm o}$ , their mean value over the whole 1966-2016 data set:  $P_{\rm o} = 5.679 \times 10^{18}$  W for  $\langle P_{\rm o} \rangle_{\rm lyr}$  and  $P_{\rm o}' = 5.719 \times 10^{18}$  W for  $\langle P_{\rm o} \rangle_{\rm ann}$ ). The vertical green line is the start of almost continuous interplanetary data from ACE, WIND and DSCOVR. (b) Scatter plot of  $\langle P_{\alpha} \rangle_{\rm lyr} / P_{\rm o}$  against  $\langle P_{\alpha} \rangle_{\rm ann} / P_{\rm o}'$ . Points for 1995 and after are shown as black squares and points for before then are as green circles. The correlation coefficient for the 1995-2016 data is 0.994 and for the 1966-1994 data is 0.929. The mauve line is the line of perfect agreement.



**Figure 10.** Analysis of the effect of adding the series of data gaps that exist in the  $P_{\alpha}$  data series during 1966-1996 on the  $P_{\alpha}$ -am correlogram (as a function of the coupling exponent, α,used) derived for annual means (i.e.,  $\tau = 1 \text{yr}$ ) from 1996-2016. In this case the effects of these gaps has been neglected (i.e., Method B, the most commonly employed). (a) The red and blue lines are the correlograms for all the 1996-2016 data for, respectively,  $\langle P_{\alpha} \rangle_{1 \text{yr}}$  (the combine-then-average estimate) and  $\langle P_{\alpha} \rangle_{\text{ann}}$  (the average-then-combine estimate). The black points with error bars are the mean and standard deviations of the distribution of correlation coefficients, r, for  $\langle P_{\alpha} \rangle_{1 \text{yr}}$  at a given α, obtained from  $N_s = 500$  different masks applied to the 1996-2016 data to introduce extra, synthetic data gaps. These masks produce the time series of gaps as was observed (30–D) years earlier where D is varied between 0 and 10 years in steps of 175 hours. (So, for example, for D = 0, the mask produces data gaps in the same positions of the data series as for the 1966-

1986 data and for D=10 years they are in the same positions as for 1976-1996). For the period from which the data gap masks are drawn (1966-1996) data availability is 23.9%. (b) The distribution of the optimum  $\alpha$  values (which give the peak r between  $<\!P_{\alpha}\!>_{\mathrm{lyr}}$  and  $<\!am\!>_{\mathrm{lyr}}$  for the  $N_{\mathrm{S}}=500$  different data gap masks applied to both series. (c) The corresponding distribution of  $\alpha$  values giving the peak r between  $<\!P_{\alpha}\!>_{\mathrm{ann}}$  and  $<\!am\!>_{\mathrm{lyr}}$  for the 500 different data gap masks applied to both series. The green line in all three panels is the optimum  $\alpha$  of 0.44 derived for  $<\!P_{\alpha}\!>_{\mathrm{lyr}}$  and the orange line is the optimum  $\alpha$  of 0.48 derived for  $<\!P_{\alpha}\!>_{\mathrm{lann}}$ .



**Figure 11.** The same as Figure 10, but allowance for data gaps is made using the piecewise removal procedure of *Finch and Lockwood* [2007] (Method B) applied to the *am* data at times of the synthesized data gaps in  $P_{\alpha}$ . In addition, in this case, the 500 synthetic data gap masks that have been applied to the  $P_{\alpha}$  data are drawn from sequences of actual data gaps during 1995-2016, when data availability is 83.8%. Specifically, the 500 masks constructed for the data-gap series observed (1-*D*) years earlier (when the data are almost continuous) for *D* varied between 0 and 1 year in steps of 17.5 hours. (So for example, for D = 0, the mask produces extra, synthetic data gaps in the same positions of the data series as for the 1995-2015 data and for D = 1 year the mask reproduces the actual data gaps 1996-2016).