

# Matrices $A$ such that $A^{s+1}R = RA^*$ with $R^k = I$

Minerva Catral\* Leila Lebtahi† Jeffrey Stuart‡ Néstor Thome§

March 17, 2018

## Abstract

We study matrices  $A \in \mathbb{C}^{n \times n}$  such that  $A^{s+1}R = RA^*$  where  $R^k = I_n$ , and  $s, k$  are nonnegative integers with  $k \geq 2$ ; such matrices are called  $\{R, s+1, k, *\}$ -potent matrices. The  $s = 0$  case corresponds to matrices such that  $A = RA^*R^{-1}$  with  $R^k = I_n$ , and is studied using spectral properties of the matrix  $R$ . For  $s \geq 1$ , various characterizations of the class of  $\{R, s+1, k, *\}$ -potent matrices and relationships between these matrices and other classes of matrices are presented.

**Keywords:**  $\{R, s+1, k, *\}$ -potent matrix;  $k$ -involutory.

**AMS subject classification:** Primary: 15A21; Secondary: 15A09.

## 1 Introduction

The set of  $n \times n$  complex matrices is denoted by  $\mathbb{C}^{n \times n}$ . The symbols  $A^*$  and  $A^\dagger$  denote the conjugate transpose and the Moore-Penrose inverse, respectively, of  $A \in \mathbb{C}^{n \times n}$ . The set of distinct eigenvalues of  $A$  (the spectrum of  $A$ ) is denoted by  $\sigma(A)$ . The symbol  $I_n$  denotes the identity matrix of  $\mathbb{C}^{n \times n}$ .

Throughout this paper we will use matrices  $R \in \mathbb{C}^{n \times n}$  such that  $R^k = I_n$  where  $k \in \{2, 3, 4, \dots\}$ . These matrices  $R$  are called *k-involutory* [29, 30, 32], and are a generalization of the well-studied *involutory matrices* (the  $k = 2$  case). We say that  $k$  is *minimal* with respect to  $R^k = I_n$  if  $k$  is the smallest integer over all  $h \in \{2, 3, 4, \dots\}$  such that  $R^h = I_n$ . Note that the definition given in [29, 30] differs from that in [32]; in this paper we adopt the definition given in [32], namely that  $R$  is  $k$ -involutory does not require that  $k$  be minimal with respect to  $R^k = I_n$ .

---

\*Department of Mathematics, Xavier University, Cincinnati, OH 45207, USA. E-mail: [catralm@xavier.edu](mailto:catralm@xavier.edu).

†Departamento de Matemáticas, Universitat de València. E-46100 Valencia, Spain. E-mail: [leila.lebtahi@uv.es](mailto:leila.lebtahi@uv.es).

‡Department of Mathematics, Pacific Lutheran University, Tacoma, WA 98447, USA. E-mail: [jeffrey.stuart@plu.edu](mailto:jeffrey.stuart@plu.edu).

§Instituto Universitario de Matemática Multidisciplinar. Universitat Politècnica de València. E-46022 Valencia, Spain. E-mail: [njthome@mat.upv.es](mailto:njthome@mat.upv.es).

For a  $k$ -involutory matrix  $R \in \mathbb{C}^{n \times n}$  and  $s \in \{0, 1, 2, 3, \dots\}$ , a matrix  $A \in \mathbb{C}^{n \times n}$  is called  $\{R, s+1, k\}$ -potent if it satisfies

$$A^{s+1}R = RA \quad (1)$$

[17, 8]. These matrices generalize the *centrosymmetric matrices* (matrices  $A \in \mathbb{C}^{n \times n}$  such that  $A = JAJ$  where  $J$  is the  $n \times n$  antidiagonal matrix [31]), the matrices  $A \in \mathbb{C}^{n \times n}$  such that  $AP = PA$  where  $P$  is an  $n \times n$  permutation matrix [25], and  $\{K, s+1\}$ -potent matrices (matrices  $A \in \mathbb{C}^{n \times n}$  for which  $KAK = A^{s+1}$  where  $K^2 = I_n$  [18, 19, 20]).

Characterizations of  $\{R, s+1, k\}$ -potent matrices were presented in [17], and properties of a matrix group constructed from an  $\{R, s+1, k\}$ -potent matrix were studied in [8]. Motivated by the results found in these papers and their connections to important known classes of matrices, we investigate matrices  $A \in \mathbb{C}^{n \times n}$  where  $A$  in the right-hand side of (1) is replaced by  $f(A)$  for some function  $f$ . In (1),  $f(A) = A$  and in this paper  $f(A) = A^*$ . We introduce and study this further class of matrices related to the  $\{R, s+1, k\}$ -potent matrices.

**Definition 1.** Let  $A \in \mathbb{C}^{n \times n}$ ,  $R \in \mathbb{C}^{n \times n}$  be  $k$ -involutory (that is,  $R^k = I_n$  for some integer  $k \geq 2$ ), and  $s \in \{0, 1, 2, 3, \dots\}$ . The matrix  $A$  is called  $\{R, s+1, k, *\}$ -potent if it satisfies

$$A^{s+1}R = RA^*. \quad (2)$$

The set of all  $\{R, s+1, k, *\}$ -potent matrices will be denoted by  $\mathcal{P}_{R,s,k,*}$ .

If  $A \in \mathcal{P}_{R,s,k,*}$  and  $A = A^*$ , then  $A$  is an  $\{R, s+1, k\}$ -potent matrix. Hence, we are interested in non-Hermitian  $\{R, s+1, k, *\}$ -potent matrices. In this case,  $A^{s+1}$  and  $A$  have the same spectrum up to conjugation.

The  $s = 0$  case corresponds to matrices such that  $A = RA^*R^{-1}$ . This class has been investigated when  $R$  is either a permutation matrix or an involution, and will be further addressed in Section 2. Matrices in  $\mathcal{P}_{R,s,k,*}$  generalize the *perhermitian matrices* (matrices  $A \in \mathbb{C}^{n \times n}$  such that  $A = JA^*J$  where  $J$  is the  $n \times n$  antidiagonal matrix [24]) and the  $\kappa$ -*Hermitian matrices* (matrices  $A \in \mathbb{C}^{n \times n}$  such that  $A = KA^*K$  where  $K$  is any  $n \times n$  involutory permutation matrix [13]).

A Toeplitz matrix  $T = [t_{ij}] \in \mathbb{C}^{n \times n}$  satisfies  $t_{ij} = t_{j-i}$  for some given sequence  $t_{-n}, \dots, t_n$ , while a Hankel matrix  $H = [h_{ij}] \in \mathbb{C}^{n \times n}$  satisfies  $h_{ij} = h_{i+j-2}$  for some given sequence  $h_0, \dots, h_{2n}$ ; note that if  $J$  is the  $n \times n$  antidiagonal matrix, then  $JT$  is Hankel and  $HJ$  is Toeplitz [14]. Every real Toeplitz matrix  $T$  can be written as  $T^t = J^{-1}TJ$ , similarly  $H^t = J^{-1}HJ$  for any Hankel matrix  $H$  with real entries (here  $B^t$  denotes the transpose of  $B$ ); these matrices provide interesting examples of  $\{R, s+1, k, *\}$ -potent matrices ( $R = J$ ,  $s = 0$ , and  $k = 2$ ).

The well-known Sylvester equations  $BX + X^*C = E$ , for arbitrary matrices  $B$ ,  $C$  and  $E$  of conformable sizes, are widely studied in the literature, and the homogeneous case ( $E = 0$ ) has recently attracted the attention of several researchers due to its relationship with palindromic eigenvalue problems [27].

$\{R, s+1, k, *\}$ -potent matrices can be seen as solutions to a subclass of the homogeneous Sylvester equations ( $B = R^{-1}$ ,  $C = -R^{-1}$  where  $R$  is  $k$ -involutory, and  $s = 0$ ) since the resulting equations relate a matrix with its conjugate transpose by a  $k$ -involutory similarity.

It is known that any  $n \times n$  matrix over any field is congruent to its transpose by an involutory congruence, i.e, for any  $n \times n$  matrix  $A$ , there is an  $X$  with  $X^2 = I_n$  such that  $XAX^t = A^t$  [15, 10]. In [9], it was shown that any projector (idempotent matrix) is unitarily similar to its conjugate transpose.

The concepts of generalized and hypergeneralized projectors were introduced by Groß and Trenkler [12]: For  $A \in \mathbb{C}^{n \times n}$ ,  $A$  is called a *generalized projector* if  $A^2 = A^*$ , and  $A$  is called a *hypergeneralized projector* if  $A^2 = A^\dagger$ . Benítez and Thome [6] have extended the definition of generalized projectors to *k-generalized projectors* and in this paper we define *k-hypergeneralized projectors*, for any integer  $k$  greater than or equal to 2. Results concerning generalized and hypergeneralized projectors and their extensions can be found in [2, 3, 4, 6, 12, 26, 28]. Matrices  $A \in \mathbb{C}^{n \times n}$  satisfying  $(A - pI_n)(A - qI_n) = O$  for some  $p, q \in \mathbb{C}$  are called *quadratic matrices* [1]; such matrices were generalized and studied in [11]. We extend the definition in [1] to what we will call  $\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ -potent matrices.

Except in Section 2, we will assume  $s \in \mathbb{N}$ . The  $s = 0$  case is discussed in Section 2. In Section 3, we derive properties of  $\{R, s+1, k, *\}$ -potent matrices and give various characterizations. In [8] it was proved that an  $\{R, s+1, k\}$ -potent matrix is always diagonalizable but this is not always true for matrices in  $\mathcal{P}_{R,s,k,*}$ . We impose conditions on  $R$  or on the matrix  $A$  to recover some of the properties obtained for the former class of matrices. In Section 4, we study the relationship between  $\{R, s+1, k, *\}$ -potent matrices and other classes of matrices such as the  $\{s+1\}$ -generalized projectors, the  $\{s+1\}$ -hypergeneralized projectors, and the  $\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ -potent matrices. We summarize these relationships in a diagram provided in Figure 1.

## 2 $AR = RA^*$ when $R^k = I_n$

In this section, we analyze the case  $s = 0$ . The techniques used for this case are different from those for the case  $s \geq 1$ , which will be discussed separately in the next section. We begin with the following lemma regarding  $k$ -involutory matrices. The expression  $\gcd(a_1, \dots, a_n)$  is the greatest common divisor of integers  $a_1, \dots, a_n$ .

**Lemma 2.** *Let  $R \in \mathbb{C}^{n \times n}$  with  $R^k = I_n$  for some positive integer  $k \geq 2$ . Then  $\sigma(R) \subseteq \{\omega, \omega^2, \omega^3, \dots, \omega^k = 1\}$  where  $\omega = \exp\left(\frac{2\pi i}{k}\right)$ . Further, there exists an invertible  $S \in \mathbb{C}^{n \times n}$  such that  $R = SDS^{-1}$  with*

$$D = \omega^{\alpha_1} I_{n_1} \oplus \omega^{\alpha_2} I_{n_2} \oplus \dots \oplus \omega^{\alpha_p} I_{n_p}$$

where  $p$  is the number of distinct eigenvalues in  $\sigma(R)$ , where the  $\alpha_j$  are positive integers with  $1 \leq \alpha_1 < \alpha_2 < \dots < \alpha_p \leq k$ , and where the dimension of the

eigenspace of  $R$  for  $\omega^{\alpha_j}$  is  $n_j$  for each  $j$ . The minimality of  $k$  with respect to  $R^k = I_n$  is equivalent to  $\gcd(\alpha_1, \alpha_2, \dots, \alpha_p, k) = 1$ .

*Proof.* Since  $R^k - I_n = O$ , the minimum polynomial of  $R$  must divide  $x^k - 1$ , which has no repeated roots, and hence, all eigenvalues of  $R$  are  $k^{\text{th}}$  roots of unity, and all Jordan blocks for  $R$  are  $1 \times 1$ . Let  $g = \gcd(\alpha_1, \alpha_2, \dots, \alpha_p, k)$ . Then there are positive integers  $\beta_1, \beta_2, \dots, \beta_p$  so that  $\alpha_j = g\beta_j$  for each  $j$ , and a positive integer  $h$  so that  $k = gh$ . Then, for each  $j$ ,

$$\omega^{\alpha_j} = \exp\left(\frac{2\pi i}{k}\alpha_j\right) = \exp\left(\frac{2\pi i}{k}g\beta_j\right) = \exp\left(\frac{2\pi i}{h}\beta_j\right)$$

so that  $\omega^{\alpha_j}$  is actually an  $h^{\text{th}}$  root of unity where  $h = k/g$ . Then

$$D^h = \bigoplus_{j=1}^p (\omega^{\alpha_j})^h I_{n_j} = I_n.$$

Since  $R^h = I_n$  if and only if  $D^h = I_n$ , the minimality of  $k$  is equivalent to  $g = 1$ .  $\square$

One would hope that  $AR = RA^*$  would imply that  $D = S^{-1}RS$  and  $B = S^{-1}AS$  would satisfy  $BD = DB^*$ . However, this requires that

$$BD = (S^{-1}AS)(S^{-1}RS) = S^{-1}(AR)S = S^{-1}(RA^*)S$$

and

$$DB^* = (S^{-1}RS)(S^{-1}AS)^* = S^{-1}R(SS^*)A^*(S^{-1})^*$$

are the same, which need not be true. What is needed is that  $S^{-1} = S^*$ , which is to say, what is needed is that  $R$  is unitarily diagonalizable. While requiring that  $R = R^*$  suffices, so does the weaker condition,  $RR^* = R^*R$ . (The matrix  $R$  is called a normal matrix when the weaker condition holds, and this condition is equivalent to unitary diagonalizability.)

Consequently, we assume that  $R$  is a normal matrix. We examine what the condition  $BD = DB^*$  implies about the matrix  $B$ . Begin by imposing the block partitioning of  $D$  on  $B$ . Observe that under Hermitian transpose, the block  $(B^*)_{ij}$  is the block  $(B_{ji})^*$  for  $1 \leq i, j \leq p$ . Then  $BD = DB^*$  is equivalent to the conditions

$$B_{ij}\omega^{\alpha_j}I_{n_j} = \omega^{\alpha_i}I_{n_i}(B^*)_{ij} \quad \text{for } 1 \leq i, j \leq p.$$

Equivalently,

$$B_{ij} = \omega^{\alpha_i - \alpha_j}(B^*)_{ij} \quad \text{for } 1 \leq i, j \leq p. \quad (3)$$

Observe that when  $i = j$ , it follows that  $B_{ii} = (B^*)_{ii} = (B_{ii})^*$ . Hence, each diagonal block of  $B$  must be Hermitian.

Now suppose that  $i \neq j$ . Note that (3) gives

$$B_{ij} = \omega^{\alpha_i - \alpha_j}(B^*)_{ij} = \omega^{\alpha_i - \alpha_j}(B_{ji})^*;$$

and it also gives  $B_{ji} = \omega^{\alpha_j - \alpha_i} (B_{ij})^*$ . The latter implies  $(B_{ji})^* = \omega^{\alpha_i - \alpha_j} B_{ij}$ . Combining these results, we see that when  $i \neq j$ ,

$$B_{ij} = \omega^{\alpha_i - \alpha_j} (B_{ji})^* = \omega^{\alpha_i - \alpha_j} \omega^{\alpha_i - \alpha_j} B_{ij} = \omega^{2(\alpha_i - \alpha_j)} B_{ij}.$$

When  $2(\alpha_i - \alpha_j) \not\equiv 0 \pmod k$ ,  $B_{ij} = 0_{n_i \times n_j}$ . Note that  $2(\alpha_i - \alpha_j) \not\equiv 0 \pmod k$  can be restated as  $2\alpha_i \not\equiv 2\alpha_j \pmod k$ . Also, when  $2\alpha_i \equiv 2\alpha_j \pmod k$ , no restrictions are imposed on  $B_{ij}$ .

When is  $2\alpha_i \equiv 2\alpha_j \pmod k$ , and how does this depend on  $k$ ?

When  $k$  is odd, 2 is invertible mod  $k$ , and consequently,  $2\alpha_i \equiv 2\alpha_j \pmod k$  if and only if  $\alpha_i \equiv \alpha_j \pmod k$ . Since  $\alpha_i$  and  $\alpha_j$  are distinct integers in  $\{1, 2, \dots, k\}$ ,  $2(\alpha_i - \alpha_j) \not\equiv 0 \pmod k$ . Thus, when  $k$  is odd,  $B$  must be a direct sum of Hermitian matrices.

What about when  $k = 2m$  for some positive integer  $m$ ? Note that  $\omega^m = \exp\left(\frac{2\pi i}{k}m\right) = \exp(\pi i) = -1$ . Since  $\alpha_i$  and  $\alpha_j$  are distinct integers in  $\{1, 2, \dots, k\}$ ,  $0 < |\alpha_i - \alpha_j| < k$ , and consequently,  $2(\alpha_i - \alpha_j) \equiv 0 \pmod k$  if and only if  $2|\alpha_i - \alpha_j| = k$ , or equivalently, if and only if  $|\alpha_i - \alpha_j| = m$ . That is, when  $\alpha_i < \alpha_j$ , this means  $\alpha_j = \alpha_i + m$ , and when  $\alpha_i > \alpha_j$ , this means  $\alpha_i = \alpha_j + m$ . Thus, if  $k = 2m$ , and if whenever  $\omega^{\alpha_i}$  is in  $\sigma(R)$ ,  $\omega^{\alpha_i + m} = -\omega^{\alpha_i} \notin \sigma(R)$ , then  $B$  must be a direct sum of Hermitian matrices.

The interesting case is when  $k = 2m$  and for at least one  $i$ ,  $\{\omega^{\alpha_i}, -\omega^{\alpha_i}\} \subseteq \sigma(R)$ . In this case, the diagonal blocks of  $B$  are all Hermitian, and for  $B_{ij}$  where  $\alpha_j \equiv \alpha_i + m \pmod k$ ,  $B_{ji} = \omega^{\alpha_j - \alpha_i} (B_{ij})^* = \omega^m (B_{ij})^* = -(B_{ij})^*$ . Apparently, in this case, there will be some nontrivial off-diagonal blocks, which are connected by a skew-Hermitian relationship to other off-diagonal blocks.

The preceding arguments lead to the main result of this section.

**Theorem 3.** *Suppose  $n, k$  are positive integers, and  $A, R \in \mathbb{C}^{n \times n}$  where  $R$  is normal and  $k$ -involutory, with  $k$  minimal with respect to  $R^k = I_n$ . Let  $S, D \in \mathbb{C}^{n \times n}$  be the unitary and diagonal matrices, respectively, given in Lemma 2 such that  $R = SDS^*$ . Then,  $AR = RA^*$  holds if and only if  $BD = DB^*$  where  $B = S^*AS$ . Further,*

1. When  $k$  is odd,  $BD = DB^*$  if and only if  $B = \bigoplus_{j=1}^p B_{jj}$  where each  $B_{jj}$  is an arbitrary  $n_j \times n_j$  Hermitian matrix.
2. When  $k = 2m$  for some positive integer  $m$ , partition  $B$  into blocks using the natural partition of  $D$ . The following are equivalent:
  - (a)  $BD = DB^*$
  - (b) For  $1 \leq j \leq p$ ,  $B_{jj}$  is an arbitrary  $n_j \times n_j$  Hermitian matrix.  $B_{ij} = 0_{n_i \times n_j}$  whenever  $|\alpha_i - \alpha_j| \neq m$ . If  $\alpha_j = \alpha_i \pm m$  (equivalently,  $\omega^{\alpha_j} = -\omega^{\alpha_i}$ ) for some  $\alpha_i$  with  $1 \leq \alpha_i \leq m$  and some  $\alpha_j$ , then  $B_{ij}$  is an arbitrary  $n_i \times n_j$  complex matrix such that  $B_{ji} = -(B_{ij})^*$ .

**Corollary 4.** *Suppose  $A, R \in \mathbb{C}^{n \times n}$ ,  $R = R^*$ , and  $R^k = I_n$  for some minimal positive integer  $k$ . Then  $k \in \{1, 2\}$ . If  $R = \pm I_n$ , then  $AR = RA^*$  if and only if  $A = A^*$ . If  $R \neq \pm I_n$ , then  $\sigma(R) = \{-1, 1\}$ ,  $k = 2$ , and there exists a unitary  $S \in \mathbb{C}^{n \times n}$  such that  $R = S(I_{n_1} \oplus (-1)I_{n_2})S^*$  where  $n_1 > 0$  is the multiplicity of 1 in  $\sigma(R)$  and  $n_2 > 0$  is the multiplicity of  $-1$  in  $\sigma(R)$ . Let  $B = S^*AS$ . Then  $AR = RA^*$  if and only if*

$$B = \begin{bmatrix} B_{11} & B_{12} \\ -(B_{12})^* & B_{22} \end{bmatrix}$$

where  $B_{11} \in \mathbb{C}^{n_1 \times n_1}$  and  $B_{22} \in \mathbb{C}^{n_2 \times n_2}$  are Hermitian, and  $B_{12} \in \mathbb{C}^{n_1 \times n_2}$  is arbitrary.

*Proof.* If  $R = R^*$ , then  $\sigma(R)$  must be real, so  $\sigma(R) \subseteq \{-1, 1\}$ , and hence,  $k \in \{1, 2\}$  by the minimality condition. If  $\sigma(R) = \{1\}$ , then  $k = 1$  and  $R = I_n$ . If  $\sigma(R) = \{-1\}$ , then  $k = 2$  and  $R = -I_n$ . If  $\sigma(R) = \{-1, 1\}$ , then use the preceding theorem with  $k = 2$  and  $p = 2$ .  $\square$

The next corollary follows by using a similar argument.

**Corollary 5.** *Suppose  $A, R \in \mathbb{C}^{n \times n}$ ,  $R^* = -R$ , and  $R^k = I_n$  for some minimal positive integer  $k$ . Then  $k = 4$ . If  $R = \pm iI_n$ , then  $AR = RA^*$  if and only if  $A = A^*$ . If  $R \neq \pm iI_n$ , then  $\sigma(R) = \{-i, i\}$  and there exists a unitary  $S \in \mathbb{C}^{n \times n}$  such that  $R = S(iI_{n_1} \oplus (-i)I_{n_2})S^*$  where  $n_1 > 0$  is the multiplicity of  $i$  in  $\sigma(R)$  and  $n_2 > 0$  is the multiplicity of  $-i$  in  $\sigma(R)$ . Let  $B = S^*AS$ . Then  $AR = RA^*$  if and only if*

$$B = \begin{bmatrix} B_{11} & O \\ O & B_{22} \end{bmatrix}$$

where  $B_{11} \in \mathbb{C}^{n_1 \times n_1}$  and  $B_{22} \in \mathbb{C}^{n_2 \times n_2}$  are Hermitian.

The following example illustrates the second case in Theorem 3.

**Example 6.** *Suppose that  $k = 4$  and  $\sigma(R) = \{i, -1, -i\}$ . Here  $\omega = i$ ,  $\alpha_1 = 1$ ,  $\alpha_2 = 2$ ,  $\alpha_3 = 3$ ,  $n_1 = 4$  and  $n_2 = n_3 = 1$ . Then  $k = 2m$  where  $m = 2$ ;  $\omega^{\alpha_1}$  and  $\omega^{\alpha_3} = -\omega^{\alpha_1}$  are in  $\sigma(R)$ ; and  $\omega^{\alpha_2}$  is in  $\sigma(R)$  but  $\omega^{\alpha_2+m} = -\omega^{\alpha_2}$  is not. Suppose that  $S = I_6$  so  $R = D$ . If  $A \in \mathbb{C}^{6 \times 6}$  satisfies  $AR = RA^*$ , then  $A_{11}$ ,  $A_{22}$  and  $A_{33}$  must be arbitrary Hermitian matrices;  $A_{12}$ ,  $A_{21}$ ,  $A_{23}$  and  $A_{32}$  must be zero matrices;  $A_{13}$  must be arbitrary, and  $A_{31} = -(A_{13})^*$ . That is,  $AR = RA^*$  holds if and only if  $A$  satisfies*

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & 0 & a_{16} \\ a_{12}^* & a_{22} & a_{23} & a_{24} & 0 & a_{26} \\ a_{13}^* & a_{23}^* & a_{33} & a_{34} & 0 & a_{36} \\ a_{14}^* & a_{24}^* & a_{34}^* & a_{44} & 0 & a_{46} \\ 0 & 0 & 0 & 0 & a_{55} & 0 \\ -a_{16}^* & -a_{26}^* & -a_{36}^* & -a_{46}^* & 0 & a_{66} \end{bmatrix}$$

where each diagonal entry of  $A$  is real.

### 3 Characterizations of $\{R, s + 1, k, *\}$ -potent matrices

For a matrix  $A \in \mathbb{C}^{n \times n}$ , the *group inverse*, if it exists, is the unique matrix  $A^\#$  satisfying the matrix equations  $AA^\#A = A$ ,  $A^\#AA^\# = A^\#$ , and  $AA^\# = A^\#A$ ; it is well known that  $A^\#$  exists if and only if  $\text{rank } A^2 = \text{rank } A$  [5].

Throughout this section, we assume that  $s, k$  are integers with  $s \geq 1$  and  $k \geq 2$ . First, we list some properties of  $\{R, s + 1, k, *\}$ -potent matrices.

**Lemma 7.** *Suppose that  $A \in \mathcal{P}_{R, s, k, *}$ . Then the following statements hold.*

- a.  $A^\#$  exists.
- b.  $A^\# \in \mathcal{P}_{R, s, k, *}$ .
- c.  $AA^\# \in \mathcal{P}_{R, s, k, *}$ .
- d.  $\sigma(A) \subseteq \{0\} \cup \left\{ \exp\left(\frac{2\pi t}{s+2}i\right), t \in \{0, 1, \dots, s+1\} \right\}$ .

*Proof.* (a) Since  $s \geq 1$ ,  $\text{rank}(A) = \text{rank}(A^*) = \text{rank}(R^{-1}A^{s+1}R) = \text{rank}(A^{s+1}) \leq \text{rank}(A^2) \leq \text{rank}(A)$ . Thus,  $\text{rank}(A^2) = \text{rank}(A)$ .

(b) Using the relation  $(A^*)^\# = (A^\#)^*$ , we obtain  $(A^*)^\# = (R^{-1}A^{s+1}R)^\# = R^{-1}(A^{s+1})^\#R = R^{-1}(A^\#)^{s+1}R = (A^\#)^*$ .

(c) Since  $A, A^\# \in \mathcal{P}_{R, s, k, *}$ ,  $(AA^\#)^{s+1} = A^{s+1}(A^\#)^{s+1} = RA^*R^{-1}R(A^\#)^*R^{-1} = RA^*(A^\#)^*R^{-1} = R(A^\#A)^*R^{-1} = R(AA^\#)^*R^{-1}$ .

(d) From  $RA^*R^{-1} = A^{s+1}$ , we have  $[\sigma(A)]^{s+1} = \sigma(A^{s+1}) = \sigma(RA^*R^{-1}) = \sigma(A^*) = \overline{\sigma(A)}$ , where  $\overline{\sigma(A)}$  means the set of the conjugate of the eigenvalues of  $A$ . Thus,  $\lambda \in \sigma(A)$  if and only if  $\lambda^{s+1} = \bar{\lambda}$ , which becomes  $r^{s+1} \exp((s+1)i\theta) = r \exp(-i\theta)$  where we assume that  $\lambda = r \exp(i\theta)$ . Now, taking modulus the two possibilities are  $r = 0$  which implies  $\lambda = 0$ , or  $\lambda = \exp\left(\frac{2\pi t}{s+2}i\right)$ ,  $t \in \{0, 1, \dots, s+1\}$ .  $\square$

Some results related to Lemma 7 were given in [16].

The next result presents a characterization of matrices in  $\mathcal{P}_{R, s, k, *}$ .

**Theorem 8.** *Let  $A, R \in \mathbb{C}^{n \times n}$  be such that  $R^k = I_n$  and  $r = \text{rank}(A)$ . Then  $A$  is an  $\{R, s + 1, k, *\}$ -potent matrix if and only if there exist nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$  such that*

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^*, \quad (4)$$

for  $X \in \mathbb{C}^{r \times r}$  satisfying  $XC^* = C^{s+1}X$  with  $X$  nonsingular and for any nonsingular  $T \in \mathbb{C}^{(n-r) \times (n-r)}$ .

*Proof.* By Lemma 7,  $A$  has index at most 1. So, the core-nilpotent representation gives

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1}$$

for some nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$ . Substituting in  $A^{s+1} = RA^*R^{-1}$  we get

$$P^{-1}R(P^{-1})^* \begin{bmatrix} C^* & O \\ O & O \end{bmatrix} P^*R^{-1}P = \begin{bmatrix} C^{s+1} & O \\ O & O \end{bmatrix}.$$

Denoting  $Z = P^{-1}R(P^{-1})^*$  and partitioning  $Z$  as

$$Z = \begin{bmatrix} X & Y \\ V & T \end{bmatrix}$$

of adequate sizes, we arrive at

$$\begin{bmatrix} X & Y \\ V & T \end{bmatrix} \begin{bmatrix} C^* & O \\ O & O \end{bmatrix} = \begin{bmatrix} C^{s+1} & O \\ O & O \end{bmatrix} \begin{bmatrix} X & Y \\ V & T \end{bmatrix},$$

from where we obtain  $XC^* = C^{s+1}X$ ,  $Y = O$ , and  $V = O$ . Since  $R$  is nonsingular,  $X$  and  $T$  are nonsingular as well. Substituting in the expression  $R = PZP^*$ , we get the representation (4).  $\square$

From Theorem 8, it follows that if  $A$  is an  $\{R, s+1, k, *\}$ -potent matrix with  $A$  as in (4) then

$$A^\# = P \begin{bmatrix} C^{-1} & O \\ O & O \end{bmatrix} P^{-1}.$$

Observe that in Theorem 8 we obtain the condition  $XC^* = C^{s+1}X$  but, in general, we cannot conclude that  $C$  is an  $\{X, s+1, k, *\}$ -potent matrix. Moreover, while  $A$  is similar to a block diagonal matrix via the matrix  $P$ , the corresponding relation for  $R$  using the same  $P$  is a congruence to a block diagonal matrix. The concept of  $EP$  matrices allows us to improve the form in (4) by giving (unitary) similarity in  $R$  as well.

Recall that a matrix  $A \in \mathbb{C}^{n \times n}$  is called  $EP$  if  $AA^\dagger = A^\dagger A$  [7], or equivalently, if there exists a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a nonsingular matrix  $C \in \mathbb{C}^{r \times r}$  such that

$$A = U \begin{bmatrix} C & O \\ O & O \end{bmatrix} U^*.$$

**Theorem 9.** *Let  $A, R \in \mathbb{C}^{n \times n}$  be such that  $R^k = I_n$  and  $r = \text{rank}(A)$ . Consider the following three conditions:*

- a.  *$A$  is an  $EP$  matrix.*
- b.  *$A$  is an  $\{R, s+1, k, *\}$ -potent matrix.*
- c. *There exist a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a nonsingular matrix  $C \in \mathbb{C}^{r \times r}$  such that*

$$A = U \begin{bmatrix} C & O \\ O & O \end{bmatrix} U^* \quad \text{and} \quad R = U \begin{bmatrix} X & O \\ O & T \end{bmatrix} U^*$$

where  $C$  is a  $\{X, s+1, k, *\}$ -potent matrix for  $X \in \mathbb{C}^{r \times r}$  and any  $T \in \mathbb{C}^{(n-r) \times (n-r)}$  satisfying  $T^k = I_{n-r}$ .



Then any two of these conditions (a)-(c) imply the third one.

*Proof.* (a) + (b)  $\implies$  (c): Assume that

$$A = U \begin{bmatrix} C & O \\ O & O \end{bmatrix} U^*$$

for some unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a nonsingular matrix  $C \in \mathbb{C}^{r \times r}$ . Now, a similar proof as that of Theorem 8 gives (c). (a) + (c)  $\implies$  (b): This can be directly derived from Theorem 8. (b) + (c)  $\implies$  (a): This direction is trivial.  $\square$

The findings in the next result relate to some facts about the diagonalization of a matrix in  $\mathcal{P}_{R,s,k,*}$ .

**Theorem 10.** *Let  $A, R \in \mathbb{C}^{n \times n}$  be such that  $R^k = I_n$  and  $A$  is an  $\{R, s + 1, k, *\}$ -potent matrix. Then*

- a.  $A^{(s+1)^{2j}} = (R(R^{-1})^*)^j A (R^* R^{-1})^j$ ,  $j = 1, \dots, k$ .
- b. If  $R$  is normal, then  $A^{(s+1)^{2k}} = A$ . In this case,  $A^\# = A^{(s+1)^{2k}-2}$ .
- c. If  $R$  is Hermitian, then  $A^{(s+1)^2} = A$ . In this case,  $A^\# = A^{(s+1)^2-2}$ .
- d. If  $R$  is normal, then  $A$  is diagonalizable.

*Proof.* (a) The definition  $A^{s+1} = RA^*R^{-1}$  implies  $A^{(s+1)^2} = (A^{s+1})^{s+1} = R(A^{s+1})^*R^{-1} = R(R^{-1})^*AR^*R^{-1}$ . Similarly,

$$A^{(s+1)^3} = (A^{(s+1)^2})^{s+1} = R(R^{-1})^*RA^*R^{-1}R^*R^{-1}$$

and  $A^{(s+1)^4} = (R(R^{-1})^*)^2 A^* (R^{-1}R^*)^2$ . The result follows by induction. (b) If  $R$  is normal, then  $(R^*)^{-1}R = R(R^*)^{-1}$  and inductively,

$$(R(R^{-1})^*)^k = R^k((R^{-1})^*)^k = R^k((R^k)^*)^{-1} = I_n$$

and

$$(R^*R^{-1})^k = (R^*)^k(R^{-1})^k = (R^k)^*(R^k)^{-1} = I_n,$$

since  $R^k = I_n$ . Now, the result follows from (a). (c) If  $R^* = R$  and  $R^k = I_n$ , then  $R^2 = I_n$  because  $R$  is (unitarily) diagonalizable and

$$\sigma(R) \subseteq \mathbb{R} \cap \left\{ \exp\left(\frac{2\pi q}{k}i\right), q \in \{0, 1, \dots, k-1\} \right\} \subseteq \{-1, 1\}.$$

Hence,  $R^{-1} = R = R^*$ . Now, again the result follows from (a). (d) This follows from (b) and by taking into account that all the roots of the polynomial  $p(z) = z^{(s+1)^{2k}} - z$  are simple. In order to compute the group inverses of  $A$  in parts (b) and (c) the following general fact is used:  $A^\# = A^\ell$  if and only if  $A^{\ell+2} = A$  for some given integer  $\ell \geq 1$ .  $\square$

While in [8] it was proved that an  $\{R, s+1, k\}$ -potent matrix is always diagonalizable, this property is not always true for matrices in  $\mathcal{P}_{R,s,k,*}$ . The next example illustrates this fact.

**Example 11.** Let  $\omega$  be a primitive root of unity of order  $2m$ ,

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad \text{and} \quad R_\omega = \begin{bmatrix} 0 & \sqrt{s+1} & 0 \\ \frac{1}{\sqrt{s+1}} & 0 & 0 \\ 0 & 0 & \omega \end{bmatrix}.$$

Then  $R_\omega^{2m} = I_3$  and the matrix

$$X = \begin{bmatrix} 0 & \sqrt{s+1} \\ \frac{1}{\sqrt{s+1}} & 0 \end{bmatrix}$$

satisfies  $XC^* = C^{s+1}X$  and  $X^2 = I_2$  where  $C = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ . Hence,  $A$  is a  $\{R_\omega, s+1, 2m, *\}$ -potent matrix. It is clear that  $A$  is not diagonalizable.

Recall that for a pair of matrices  $A, B \in \mathbb{C}^{n \times n}$ , the commutator  $[A, B]$  is defined as  $[A, B] = AB - BA$ .

**Lemma 12.** Let  $R \in \mathbb{C}^{n \times n}$  be such that  $R^k = I_n$ . The set

$$G = \{A \in \mathcal{P}_{R,s,k,*} : [A, B] = O, \forall B \in \mathcal{P}_{R,s,k,*}\}$$

is a semigroup under matrix multiplication.

*Proof.* Let  $A_1, A_2 \in G$ . Then,  $A_1, A_2 \in \mathcal{P}_{R,s,k,*}$ , and for  $i = 1, 2$  we have  $A_i B = BA_i$  for all  $B \in \mathcal{P}_{R,s,k,*}$ . In particular,  $A_1 A_2 = A_2 A_1$ . Since  $RA_i^* R^{-1} = A_i^{s+1}$  for  $i = 1, 2$ , we get

$$(A_1 A_2)^{s+1} = A_1^{s+1} A_2^{s+1} = RA_1^* A_2^* R^{-1} = R(A_2 A_1)^* R^{-1} = R(A_1 A_2)^* R^{-1},$$

that is  $A_1 A_2 \in \mathcal{P}_{R,s,k,*}$ . Moreover,  $(A_1 A_2)B = A_1 B A_2 = B(A_1 A_2)$  for all  $B \in \mathcal{P}_{R,s,k,*}$ . Hence,  $A_1 A_2 \in G$ .  $\square$

**Remark 13.** If  $A, B \in \mathcal{P}_{R,s,k,*}$  satisfy  $AB = BA$ , then  $AB \in \mathcal{P}_{R,s,k,*}$ .

## 4 Relationship between $\mathcal{P}_{R,s,k,*}$ and other classes of matrices

First, we present a general result whose proof will be useful in this section.

**Lemma 14.** Let  $A \in \mathbb{C}^{n \times n}$  be a matrix of index 1 and  $\text{rank}(A) = r > 0$ . Then  $A$  is a normal matrix if and only if there exist nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$  be such that

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad P^* P = \begin{bmatrix} M & O \\ O & N \end{bmatrix}$$

where  $M \in \mathbb{C}^{r \times r}$  and  $N \in \mathbb{C}^{(n-r) \times (n-r)}$  are both positive definite matrices and  $C^*$  commutes with  $MCM^{-1}$ .

*Proof.* It is well known that any matrix of index 1 has the form

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1}$$

for some nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$ . Substituting in  $AA^* = A^*A$  and reordering factors yield

$$P^*P \begin{bmatrix} C & O \\ O & O \end{bmatrix} (P^*P)^{-1} \begin{bmatrix} C^* & O \\ O & O \end{bmatrix} P^*P = \begin{bmatrix} C^* & O \\ O & O \end{bmatrix} P^*P \begin{bmatrix} C & O \\ O & O \end{bmatrix}. \quad (5)$$

Partitioning  $P^*P$  with adequate sizes to the partition considered for  $A$  we obtain

$$P^*P = \begin{bmatrix} M & Q \\ Q^* & N \end{bmatrix},$$

with  $M$  and  $N$  Hermitian. Since  $P$  is nonsingular, by using the positive definiteness of  $P^*P$  it is easy to see that  $M$  and  $N$  are positive definite. The inversion formula of Banachiewicz-Schur ensures the nonsingularity of the Schur complement  $W = (P^*P)/M = N - Q^*M^{-1}Q$  and gives

$$(P^*P)^{-1} = \begin{bmatrix} M^{-1} + M^{-1}QW^{-1}Q^*M^{-1} & -M^{-1}QW^{-1} \\ -W^{-1}Q^*M^{-1} & W^{-1} \end{bmatrix}.$$

Substituting in (5) and making the block products we get

$$\begin{bmatrix} MLM & MLQ \\ Q^*LM & Q^*LQ \end{bmatrix} = \begin{bmatrix} C^*MC & O \\ O & O \end{bmatrix}$$

where  $L = C(M^{-1} + M^{-1}QW^{-1}Q^*M^{-1})C^*$ . Thus,  $MLM = C^*MC$ ,  $MLQ = O$ ,  $Q^*LM = O$ , and  $Q^*LQ = O$ . By the nonsingularity of  $M$  and  $N$  we get  $LQ = O$  and  $Q^*L = O$ , that is

$$O = C(M^{-1} + M^{-1}QW^{-1}Q^*M^{-1})C^*Q = CM^{-1}(I_r + QW^{-1}Q^*M^{-1})C^*Q.$$

This last expression gives  $(I_r + QW^{-1}Q^*M^{-1})C^*Q = O$ . Similarly, from  $O = Q^*L = Q^*C(I_r + M^{-1}QW^{-1}Q^*)M^{-1}C^*$  we get  $Q^*(I_r + M^{-1}QW^{-1}Q^*) = O$ . Now, substituting the expression of  $L$  in  $MLM = C^*MC$  we arrive at  $MCM^{-1}(I_r + QW^{-1}Q^*M^{-1})C^*M = C^*MC$  which implies

$$O = MCM^{-1}(I_r + QW^{-1}Q^*M^{-1})C^*Q = C^*MCM^{-1}Q,$$

from where  $Q = O$  due to the nonsingularity of  $C$  and  $M$ . Hence,

$$P^*P = \begin{bmatrix} M & O \\ O & N \end{bmatrix},$$

with  $MCM^{-1}C^* = C^*MCM^{-1}$  since  $L = CM^{-1}C^*$ . The converse is evident.  $\square$

In Lemma 7 we proved that the projector  $AA^\# \in \mathcal{P}_{R,s,k,*}$  provided that  $A \in \mathcal{P}_{R,s,k,*}$ . The next result characterizes all projectors that belong to  $\mathcal{P}_{R,s,k,*}$ .

**Theorem 15.** *Let  $A \in \mathbb{C}^{n \times n}$  be a projector, i.e.,  $A^2 = A$ . Then the following conditions are equivalent:*

- a.  $A$  is  $\{R, s+1, k, *\}$ -potent.
- b.  $AR = RA^*$ .
- c. There exists a nonsingular matrix  $P \in \mathbb{C}^{n \times n}$  such that

$$A = P \begin{bmatrix} I_r & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^*$$

where  $X \in \mathbb{C}^{r \times r}$  and  $T \in \mathbb{C}^{(n-r) \times (n-r)}$  are nonsingular matrices.

*Proof.* Since  $A^2 = A$ , we get  $A^{s+1} = A$  for all  $s$  and

$$A = P \begin{bmatrix} I_r & O \\ O & O \end{bmatrix} P^{-1}. \quad (6)$$

(a)  $\iff$  (b) This follows directly from the definitions. (b)  $\iff$  (c) The form of  $R$  can be found by substituting (6) into  $AR = RA^*$  and partitioning

$$P^{-1}R(P^{-1})^* = \begin{bmatrix} X & Y \\ Z & T \end{bmatrix}.$$

□

**Remark 16.** *Note that in the above theorem the value used for  $s$  was not relevant.*

In Theorem 9 we have characterized all  $\{R, s+1, k, *\}$ -potent matrices that are  $EP$ . Next, we characterize  $\{R, s+1, k, *\}$ -potent matrices that are normal.

**Theorem 17.** *Let  $A \in \mathbb{C}^{n \times n}$  be a nonzero  $\{R, s+1, k, *\}$ -potent matrix. Then  $A$  is normal if and only if there exist nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$  such that*

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} XM & O \\ O & TN \end{bmatrix} P^{-1}$$

where  $M \in \mathbb{C}^{r \times r}$  and  $N \in \mathbb{C}^{(n-r) \times (n-r)}$  are both positive definite matrices and  $X \in \mathbb{C}^{r \times r}$  and  $T \in \mathbb{C}^{(n-r) \times (n-r)}$  are nonsingular matrices such that  $XC^* = C^{s+1}X$ .

*Proof.* By Theorem 8 there exist nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$  such that

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^*,$$

for  $X \in \mathbb{C}^{r \times r}$  satisfying  $XC^* = C^{s+1}X$  with  $X$  nonsingular and for any nonsingular  $T \in \mathbb{C}^{(n-r) \times (n-r)}$ . Assume that  $A$  is normal. Then, a similar proof to that of Lemma 14 yields

$$P^* = \begin{bmatrix} M & O \\ O & N \end{bmatrix} P^{-1}$$

where  $M \in \mathbb{C}^{r \times r}$  and  $N \in \mathbb{C}^{(n-r) \times (n-r)}$  are both positive definite matrices. Thus, we can deduce that

$$R = P \begin{bmatrix} XM & O \\ O & TN \end{bmatrix} P^{-1}.$$

The converse is evident.  $\square$

In [12], Groß and Trenkler defined *generalized projectors* as matrices  $A \in \mathbb{C}^{n \times n}$  that satisfy  $A^2 = A^*$  and denoted this class of matrices by GP. In [6], Benítez and Thome introduced  $\{s+1\}$ -generalized projectors (for  $s \geq 1$ ) and for ease we call these matrices  $\{s+1\}$ -GP matrices [19]. A matrix  $A \in \mathbb{C}^{n \times n}$  is called an  $\{s+1\}$ -GP matrix if  $A^* = A^{s+1}$ ; we denote the set of all  $n \times n$   $\{s+1\}$ -GP matrices by  $GP_{s+1}$ . The matrices in  $GP_{s+1}$  are characterized as follows [6]:

$$A \in GP_{s+1} \iff A \text{ is normal and } \sigma(A) \subseteq \{0\} \cap \Omega_{s+2} \iff A \text{ is normal and } A^{s+3} = A$$

where  $\Omega_{s+2}$  denotes the roots of unity of order  $s+2$ . We next give another characterization.

**Lemma 18.** *Let  $A \in \mathbb{C}^{n \times n}$ . Then  $A$  is a  $\{s+1\}$ -GP matrix if and only if there exist a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a diagonal matrix  $D = [d_{ij}] \in \mathbb{C}^{r \times r}$  such that*

$$A = U \begin{bmatrix} D & O \\ O & O \end{bmatrix} U^*,$$

with  $d_{jj} \in \Omega_{s+2}$ .

*Proof.* This is a straightforward extension of [6, Corollary 2.2].  $\square$

Now, we characterize  $\{R, s+1, k, *\}$ -potent matrices that are in  $GP_{s+1}$ .

**Theorem 19.** *Let  $A \in \mathbb{C}^{n \times n}$  be an  $\{R, s+1, k, *\}$ -potent matrix. Then, the following statements are equivalent:*

- a.  $A$  is a  $\{s+1\}$ -GP.
- b.  $A^*R = RA^*$ .
- c. There exists a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a diagonal matrix  $D = [d_{ij}] \in \mathbb{C}^{r \times r}$  such that

$$A = U \begin{bmatrix} D & O \\ O & O \end{bmatrix} U^* \quad \text{and} \quad R = U \begin{bmatrix} R_1 & O \\ O & R_2 \end{bmatrix} U^*$$

where  $d_{jj} \in \Omega_{s+2}$  with  $R_1 \in \mathbb{C}^{r \times r}$  satisfying  $R_1^*D = DR_1$  and  $R_2 \in \mathbb{C}^{(n-r) \times (n-r)}$ .

*Proof.* From the definition  $A^{s+1} = RA^*R^{-1}$ , it is easy to see that  $A^{s+1} = A^*$  and  $A^*R = RA^*$  are equivalent; thus (a)  $\iff$  (b). Now, suppose that  $A$  is a  $\{s+1\}$ -GP matrix. By Lemma 18

$$A = U \begin{bmatrix} D & O \\ O & O \end{bmatrix} U^*,$$

under the conditions indicated there. Consider the partition

$$U^*RU = \begin{bmatrix} R_1 & R_3 \\ R_4 & R_2 \end{bmatrix},$$

according to the sizes of the partition of  $U^*AU$ . Equating blocks, we obtain that the expression  $A^*R = RA^*$  is equivalent to  $D^*R_1 = R_1D^*$ ,  $R_3 = O$ , and  $R_4 = O$ , since  $D$  is nonsingular; thus (a)  $\iff$  (c).  $\square$

Now, we relate the class of  $\{R, s+1, k, *\}$ -potent matrices to the class of  $\{s+1\}$ -HGP matrices. In [12], Groß and Trenkler defined *hypergeneralized projectors* as matrices  $A \in \mathbb{C}^{n \times n}$  that satisfy  $A^2 = A^\dagger$  and denoted this class of matrices by HGP. We call a matrix  $A \in \mathbb{C}^{n \times n}$  an  $\{s+1\}$ -*hypergeneralized potent* (or  $\{s+1\}$ -HGP) *matrix* if  $A^{s+1} = A^\dagger$  and we denote the set of all  $n \times n$   $\{s+1\}$ -HGP matrices by  $HGP_{s+1}$ . The matrices in  $HGP_{s+1}$  are characterized as follows:

$$A \in HGP_{s+1} \iff A \text{ is EP and } A^{s+3} = A.$$

**Theorem 20.** *Let  $A \in \mathbb{C}^{n \times n}$  be an  $\{R, s+1, k, *\}$ -potent matrix. Then, the following statements are equivalent:*

- a.  $A$  is an  $\{s+1\}$ -HGP matrix.
- b.  $A^\dagger R = RA^*$ .
- c. There exists a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a nonsingular matrix  $C \in \mathbb{C}^{r \times r}$  such that

$$A = U \begin{bmatrix} C & O \\ O & O \end{bmatrix} U^* \quad \text{and} \quad R = U \begin{bmatrix} R_1 & O \\ O & R_2 \end{bmatrix} U^*$$

where  $C^{-1}R_1 = R_1C^*$  with  $R_1 \in \mathbb{C}^{r \times r}$  and  $R_2 \in \mathbb{C}^{(n-r) \times (n-r)}$  satisfying  $R_1^k = I_r$  and  $R_2^k = I_{n-r}$ .

*Proof.* The equivalence (a)  $\iff$  (b) follows directly from the definitions. Suppose that  $A$  is a  $\{s+1\}$ -HGP. Then  $A$  is EP, so there exists a unitary matrix  $U \in \mathbb{C}^{n \times n}$  and a nonsingular matrix  $C \in \mathbb{C}^{r \times r}$  such that

$$A = U \begin{bmatrix} C & O \\ O & O \end{bmatrix} U^*.$$

It is clear that

$$A^\dagger = U \begin{bmatrix} C^{-1} & O \\ O & O \end{bmatrix} U^*.$$

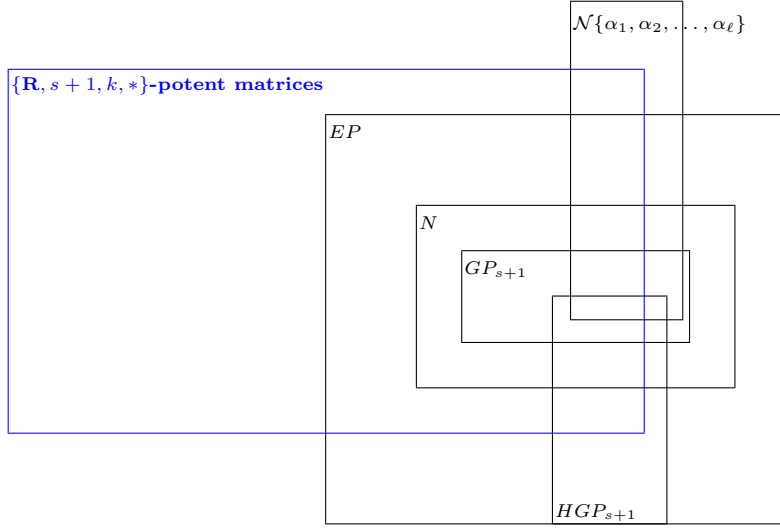


Figure 1: Relation between  $\{R, s + 1, k + *\}$ -potent matrices and other classes

Now we consider the partition

$$U^*RU = \begin{bmatrix} R_1 & R_3 \\ R_4 & R_2 \end{bmatrix},$$

according to the sizes of the partition of  $U^*AU$ . Substituting in  $RA^* = A^\dagger R$  and equating blocks we obtain  $R_1C^* = C^{-1}R_1$ ,  $R_3 = O$ , and  $R_4 = O$ . Thus, the conditions on  $R$  have been obtained. Observe that  $R^k = I_n$  implies  $R_1^k = I_r$  and  $R_2^k = I_{n-r}$ . Hence (a)  $\implies$  (c). Finally, (c)  $\implies$  (b) is straightforward.  $\square$

We summarize all the information studied in this section in Figure 1.

A matrix  $A \in \mathbb{C}^{m \times n}$  is a *partial isometry* if  $A^\dagger = A^*$ , or equivalently,  $AA^*A = A$  [22]. The relation between  $\mathcal{P}_{R,s,k,*}$  and partial isometries is presented in the next result.

**Theorem 21.** *Let  $A \in \mathbb{C}^{n \times n}$  be a matrix in  $\mathcal{P}_{R,s,k,*}$ . As in Theorem 8, let*

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^*,$$

and partition  $P^*P$  as

$$P^*P = \begin{bmatrix} M & L \\ L^* & N \end{bmatrix}.$$

Then  $A$  is a partial isometry if and only if  $I_r + L(N - L^*M^{-1}L)^{-1}L^*M^{-1} = MC^{-1}M^{-1}(C^{-1})^*$ .

*Proof.* The result is obtained by substituting in  $AA^*A = A$  the expression of  $A$  given in the statement and by using the Banachiewicz-Schur formula for the inverse of  $P^*P$ .  $\square$

Finally, we present the relationship between  $\mathcal{P}_{R,s,k,*}$  and  $\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ -potent matrices. The latter is an extension of the  $\{\alpha_1, \alpha_2\}$ -quadratic matrices [23].

**Definition 22.** A matrix  $A \in \mathbb{C}^{n \times n}$  is called an  $\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ -potent matrix if

$$(A - \alpha_1 I_n)(A - \alpha_2 I_n) \dots (A - \alpha_\ell I_n) = 0$$

where  $\alpha_1, \alpha_2, \dots, \alpha_\ell \in \mathbb{C}$  are pairwise distinct.

The set of all  $\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ -potent matrices will be denoted by  $\mathcal{N}\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ .

If  $\ell = 2$ , matrices in  $\mathcal{N}\{\alpha_1, \alpha_2\}$  are called  $\{\alpha_1, \alpha_2\}$ -quadratic [1, 11]. Allowing equalities between  $\alpha_1, \alpha_2, \dots, \alpha_\ell$ , the choice  $\alpha_1 = \alpha_2 = \dots = \alpha_\ell = 0$  leads to nilpotent matrices.

**Lemma 23.** A nonzero  $\{R, s+1, k, *\}$ -potent matrix is not nilpotent.

*Proof.* Suppose that  $A \in \mathbb{C}^{n \times n}$  is an  $\{R, s+1, k, *\}$ -potent matrix that is not the zero matrix. By Theorem 8,

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1}$$

for some nonsingular matrices  $P \in \mathbb{C}^{n \times n}$  and  $C \in \mathbb{C}^{r \times r}$ . If we assume that  $A^m = O$  for some positive integer  $m$  then  $C^m = O$ , which is impossible.  $\square$

**Theorem 24.** Let  $A \in \mathcal{P}_{R,s,k,*}$ , and let  $\alpha_1, \alpha_2, \dots, \alpha_\ell \in \mathbb{C}$  be pairwise distinct. Then  $A \in \mathcal{N}\{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$  if and only if  $\alpha_1 = 0$ ,

$$A = L \begin{bmatrix} D & O \\ O & O \end{bmatrix} L^{-1} \quad \text{and} \quad R = L \begin{bmatrix} Y & O \\ O & T \end{bmatrix} L^*$$

for some nonsingular matrix  $L \in \mathbb{C}^{n \times n}$  and a diagonal matrix  $D = [d_{ij}] \in \mathbb{C}^{r \times r}$  where  $d_{jj} \in \{\alpha_2, \dots, \alpha_\ell\} \cap \left\{ \exp\left(\frac{2\pi t}{s+2}i\right), t \in \{0, 1, \dots, s+1\} \right\}$  for  $j = 1, 2, \dots, r$  and some nonsingular matrices  $Y \in \mathbb{C}^{r \times r}$ ,  $T \in \mathbb{C}^{(n-r) \times (n-r)}$  such that  $YD^* = D^{s+1}Y$ .

*Proof.* Since  $A \in \mathcal{P}_{R,s,k,*}$ , by Theorem 8 we have

$$A = P \begin{bmatrix} C & O \\ O & O \end{bmatrix} P^{-1} \quad \text{and} \quad R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^*$$

for some nonsingular matrices  $P \in \mathbb{C}^{n \times n}$ ,  $X \in \mathbb{C}^{r \times r}$ , and  $T \in \mathbb{C}^{(n-r) \times (n-r)}$  such that  $XC^* = C^{s+1}X$ . Suppose that  $(A - \alpha_1 I_n)(A - \alpha_2 I_n) \dots (A - \alpha_\ell I_n) = 0$  where  $\alpha_1, \alpha_2, \dots, \alpha_\ell \in \mathbb{C}$  are pairwise distinct. Then

$$P \begin{bmatrix} \prod_{j=1}^{\ell} (C - \alpha_j I_r) & O \\ O & (-1)^\ell \prod_{j=1}^{\ell} \alpha_j I_{n-r} \end{bmatrix} P^{-1} = O.$$



So,  $\prod_{j=1}^{\ell}(C - \alpha_j I_r) = O$  and  $\prod_{j=1}^{\ell} \alpha_j = 0$ . It is clear that there is at least one  $j \in \{1, 2, \dots, \ell\}$  such that  $\alpha_j = 0$  (since  $\alpha_i \neq \alpha_q$  if  $i \neq q$ ). Without loss of generality, we can assume that  $\alpha_1 = 0$  (consequently,  $\alpha_j \neq 0$  for all  $j \in \{2, \dots, \ell\}$ ). Now,  $\prod_{j=2}^{\ell}(C - \alpha_j I_r) = O$  because  $C$  is nonsingular, and  $p(x) = (x - \alpha_2)(x - \alpha_3) \dots (x - \alpha_{\ell})$  is a (monic) annihilator polynomial of  $C$  with all its factors linear. Since all  $\alpha_j \in \mathbb{C}$  and  $\mathbb{C}$  is algebraically closed,  $C$  must be diagonalizable. Let  $C = QDQ^{-1}$  with  $D$  diagonal. Then

$$A = P \begin{bmatrix} QDQ^{-1} & O \\ O & O \end{bmatrix} P^{-1} = L \begin{bmatrix} D & O \\ O & O \end{bmatrix} L^{-1}$$

where  $L = P \begin{bmatrix} Q & O \\ O & I_{n-r} \end{bmatrix}$ . Hence,  $A$  is diagonalizable. Substituting now,  $C = QDQ^{-1}$  in  $\prod_{j=2}^{\ell}(C - \alpha_j I_r) = O$  we get  $\prod_{j=2}^{\ell}(D - \alpha_j I_r) = O$ , that is for every  $i = 1, 2, \dots, \ell$ ,  $\prod_{j=2}^{\ell}(d_{jj} - \alpha_j) = 0$ , thus,  $d_{jj} \in \{\alpha_2, \dots, \alpha_{\ell}\}$  for all  $j = 1, 2, \dots, r$ . From Lemma 7,  $d_{jj} \in \left\{ \exp\left(\frac{2\pi t}{s+2}i\right), t \in \{0, 1, \dots, s+1\} \right\}$  for all  $j \in \{1, 2, \dots, r\}$ . By using  $XC^* = C^{s+1}X$  and  $C = QDQ^{-1}$ , we can denote  $Y = Q^{-1}X(Q^*)^{-1}$  to arrive at

$$R = P \begin{bmatrix} X & O \\ O & T \end{bmatrix} P^* = L \begin{bmatrix} Y & O \\ O & T \end{bmatrix} L^*,$$

with  $YD^* = D^{s+1}Y$  and  $Y$  nonsingular.  $\square$

**Remark 25.** Notice that, if either  $\alpha_j \neq 0$  for all  $j \in \{1, 2, \dots, \ell\}$  or if  $\alpha_j \notin \left\{ \exp\left(\frac{2\pi t}{s+2}i\right), t \in \{0, 1, \dots, s+1\} \right\}$  for some  $j \in \{2, \dots, \ell\}$  then  $\mathcal{N}\{\alpha_1, \alpha_2, \dots, \alpha_{\ell}\} \cap \mathcal{P}_{R,s,k,*} = \emptyset$ .

## Acknowledgements

The second and fourth authors have been partially supported by Ministerio de Economía y Competitividad of Spain (Grant MTM2013-43678-P).

## References

- [1] M. Aleksiejczyk, A. Smoktunowicz. On properties of quadratic matrices, *Mathematica Pannonica*, 11, 239–248, 2000.
- [2] O.M. Baksalary, Revisitation of generalized and hypergeneralized projectors, in: B. Schipp, W. Krämer(eds), *Statistical Inference, Econometric Analysis and Matrix Algebra—Festschrift in Honour of Götz Trenkler*, Springer, Heidelberg, 317-324, 2008.
- [3] J.K. Baksalary, O.M. Baksalary, J. Groß. On some linear combinations of hypergeneralized projectors, *Linear Algebra and its Applications*, 413, 264–273, 2006.

- [4] J.K. Baksalary, O.M. Baksalary, X. Liu, G. Trenkler. Further results on generalized and hypergeneralized projectors, *Linear Algebra and its Applications*, 429, 1038–1050, 2008.
- [5] A. Ben-Israel, T. Greville. Generalized Inverses: Theory and Applications, John Wiley & Sons, 2nd Edition, 2003.
- [6] J. Benítez, N. Thome. Characterizations and linear combinations of  $k$ -generalized projectors, *Linear Algebra and its Applications*, 410, 150–159, 2005.
- [7] S.L. Campbell, C.D. Meyer Jr. Generalized Inverse of Linear Transformations. Dover, New York, Second Edition, 1991.
- [8] M. Catral, L. Lebtahi, J. Stuart, N. Thome. On a matrix group constructed from an  $\{R, s + 1, k\}$ -potent matrix, *Linear Algebra and its Applications*, 461, 200–201, 2014.
- [9] D. Doković. Unitary similarity of projectors, *Aequationes Mathematicae*, 42, 220–224, 1991.
- [10] D. Doković, F. Szechtman, K. Zhao. An algorithm that carries a square matrix into its transpose by an involutory congruence transformation, *Electronic Journal of Linear Algebra*, 10, 320–340, 2003.
- [11] R.W. Farebrother, G. Trenkler. On generalized quadratic matrices, *Linear Algebra and its Applications*, 410, 244–253, 2005.
- [12] J. Groß, G. Trenkler. Generalized and hypergeneralized projectors, *Linear Algebra and its Applications*, 264, 463–474, 1997.
- [13] R.D. Hill, S.R. Waters. On  $\kappa$ -Real and  $\kappa$ -Hermitian Matrices, *Linear Algebra and its Applications*, 169, 17–29, 1992.
- [14] R. Horn, C. Johnson. Matrix Analysis, Cambridge U. P., New York, Second Edition, 2013.
- [15] R.A. Horn, V.V. Sergeichuk. Congruences of a square matrix and its transpose, *Linear Algebra and its Applications*, 389, 347–353, 2004.
- [16] L. Lebtahi, P. Patrício, N. Thome. Special elements in a ring related to Drazin inverses, *Linear and Multilinear Algebra*, 61, 1017–1027, 2013.
- [17] L. Lebtahi, J. Stuart, N. Thome, J.R. Weaver. Matrices  $A$  such that  $RA = A^{s+1}R$  when  $R^k = I$ , *Linear Algebra and its Applications*, 439, 1017–1023, 2013.
- [18] L. Lebtahi, O. Romero, N. Thome. Characterizations of  $\{K, s + 1\}$ -potent matrices and applications, *Linear Algebra and its Applications*, 436, 293–306, 2012.

- [19] L. Lebtahi, O. Romero, N. Thome. Relations between  $\{K, s + 1\}$ -potent matrices and different classes of complex matrices, *Linear Algebra and its Applications*, 438, 1517–1531, 2013.
- [20] L. Lebtahi, O. Romero, N. Thome. Algorithms for  $\{K, s + 1\}$ -potent matrix constructions, *Journal of Computational and Applied Mathematics*, 249, 157–162, 2013.
- [21] D. Mošić, D. Djordjević. Moore-Penrose-invertible normal and Hermitian elements in rings, *Linear Algebra and its Applications*, 431, 732–745, 2009.
- [22] D. Mošić, D. Djordjević. Partial isometries and EP elements in rings with involution, *Electronic Journal of Linear Algebra*, 18, 761–772, 2009.
- [23] T. Petik, M. Uç, H. Özdemir. Generalized quadraticity of linear combination of two generalized quadratic matrices, *Linear and Multilinear Algebra*, 63, 12, 2430–2439, 2015.
- [24] I. S. Pressman. Matrices with multiple symmetry properties: applications of centrohermitian and perhermitian matrices, *Linear Algebra and its Applications*, 284, 239–258, 1998.
- [25] J. Stuart, J. Weaver. Matrices that commute with a permutation matrix, *Linear Algebra and its Applications*, 150, 255–265, 1991.
- [26] G.W. Stewart. A note on generalized and hypergeneralized projectors, *Linear Algebra and its Applications*, 412, 408–411, 2006.
- [27] F. De Terán, F. M. Dopico, N. Guillery, D. Montealegre, N. Reyes. The solution of the equation  $AX + X^*B = 0$ , *Linear Algebra and its Applications*, 438, 2817–2860, 2013.
- [28] M. Tošić, D. S. Cvetković-Ilić. The invertibility of the difference and the sum of commuting generalized and hypergeneralized projectors, *Linear and Multilinear Algebra*, 61, 4, 482–493, 2013.
- [29] W.F. Trench. Characterization and properties of matrices with  $k$ -involutionary symmetries, *Linear Algebra and its Applications*, 429, 2278–2290, 2008.
- [30] W.F. Trench. Characterization and properties of matrices with  $k$ -involutionary symmetries II, *Linear Algebra and its Applications*, 432, 2782–2797, 2010.
- [31] J. Weaver. Centrosymmetric (cross-symmetric) matrices, their basic properties, eigenvalues and eigenvectors, *American Mathematical Monthly*, 2, 10, 711–717, 1985.
- [32] M. Yasuda. Some properties of commuting and anti-commuting  $m$ -involutions. *Acta Mathematica Scientia*, 32B(2), 631–644, 2012.