Comparative study of mixed product and quaternion product

Md. Shah Alam

Department of Physics, Shahjalal University of Science and Technology, Sylhet, Bangladesh

aymer, anglaue in

E-mail alam@sust.edu

Received 12 September 2002, accepted 29 October 2002

Abstract Mixed number is the sum of a scalar and a vector. The quaternion can also be written as the sum of a scalar and a vector but the product of mixed numbers and the product of quaternions are different. Here, we studied the mixed product which is derived from the product of mixed numbers and the quaternion product which is derived from the product of quaternions. It was observed that mixed product is more consistent with Physics than that of quaternion product.

Keywords ... Mixed number, mixed product, quaternion product

PACS No. 02 90 +p

1. Introduction

1.1. Mixed product :

Mixed number [1] α is the sum of a scalar x and a vector A :

i.e. $\alpha = x + A$.

The product of two mixed numbers is defined as [1]

$$\alpha\beta = (x+A)(y+B) = xy+A, B + xB + yA + iA \times B.$$
 (1)

Taking x = y = 0, we get from eq. (1)

$$A \otimes B = A \cdot B + iA \times B \,. \tag{2}$$

This product is called mixed product [2] and the symbol \otimes is chosen for it.

1.2 Quaternion product :

The quaternion can also be written as the sum of scalar and a vector [3]

i.e. $\underline{A} = a + A$.

The multiplication of any two quaternions A = a + A and $\underline{B} = b + B$ is given by [3-5]

Corresponding Author

 $\boldsymbol{AB} = (\boldsymbol{a} + \boldsymbol{A})(\boldsymbol{b} + \boldsymbol{B}) = \boldsymbol{ab} - \boldsymbol{A} \cdot \boldsymbol{B} + \boldsymbol{aB} + \boldsymbol{bA} + \boldsymbol{A} \times \boldsymbol{B}.$ (3)

Taking a = b = 0, we get from eq. (3)

$$AB = -A \cdot B + A \times B. \tag{4}$$

This product we call quaternion product.

2. Consistency of mixed product and quaternion product with physics

2.1 Consistency with Pauli matrix algebra :

It can be shown that [6]

$$(\boldsymbol{\sigma}.\boldsymbol{A})(\boldsymbol{\sigma}.\boldsymbol{B}) = \boldsymbol{A}.\boldsymbol{B} + i\boldsymbol{\sigma}.(\boldsymbol{A} \times \boldsymbol{B}), \qquad (5)$$

where A and B are two vectors and σ is the Pauli matrix.

From eqs. (2) and (5), we can say that the mixed product is directly consistent with Pauli matrix algebra. From eqs. (4) and (5), we can also say that the quaternion product is not directly consistent with Pauli matrix algebra.

2.2 Consistency with Dirac equation :

Dirac equation $(E - \alpha \cdot P - \beta m)\psi = 0$ can be operated by the Dirac operator $(t - \alpha \cdot V - \beta n)$, then we get

$$(t - \alpha V - \beta n) \left\{ (E - \alpha P - \beta m) \psi \right\} = 0.$$
 (6)

© 2003 IACS

For mass-less particles *i.e.* for m = n = 0, we get [7]

$$(t - \alpha.V)(E - \alpha.P)\psi = \{tE + V.P + i\sigma.(V \times P)\}\psi_1$$
$$+\{-(t\sigma.P + E\sigma.V)\}\psi_2 = 0,$$
(7)

where Ψ is the wave function and ψ_1 and ψ_2 are the components of Ψ .

Putting t = 0 and E = 0 in eq. (7), we get

$$(\alpha.V)(\alpha.P)\psi = \{V.P + i\sigma.(V \times P)\}\psi_1 = 0.$$
(8)

From eqs. (2) and (8), it is clear that Mixed product is consistent with Dirac equation.

From eqs. (4) and (8), it is also clear that quaternion product is not consistent with Dirac equation.

3. Applications of these products in dealing with differential operators

In region of space where there is no charge or current, Maxwell's equation can be written as

(i)
$$\nabla \cdot \boldsymbol{E} = 0$$
, (ii) $\nabla \times \boldsymbol{E} = -(\partial \boldsymbol{B})/(\partial t)$,

(iii)
$$\nabla \cdot \boldsymbol{B} = 0$$
, (iv) $\nabla \times \boldsymbol{B} = \mu_0 \varepsilon_0 (\partial \boldsymbol{E}) / (\partial t)$. (9)

From these equations, it can be written as [8]

$$\nabla^{2} \boldsymbol{E} = \mu_{0} \boldsymbol{\varepsilon}_{0} (\partial^{2} \boldsymbol{E}) / (\partial t^{2}),$$

$$\nabla^{2} \boldsymbol{B} = \mu_{0} \boldsymbol{\varepsilon}_{0} (\partial^{2} \boldsymbol{B}) / (\partial t^{2}).$$
(10)

Using eqs. (2) and (9), we can write

 $\nabla \otimes E = \nabla \cdot E + i \nabla \times E$

 $= 0 + -i(\partial B)/(\partial t),$

or

or
$$\nabla \otimes E = -i(\partial B)/(\partial t)$$
, (11)

 $\nabla \otimes (\nabla \otimes E) = \nabla \otimes \{-i(\partial R) \mid (\partial i)\}$

$$= -i(\partial / \partial t) \{\nabla \otimes B\}$$

$$= -i(\partial / \partial t) \{\nabla . B + i \nabla \times B\}$$

$$= -i(\partial / \partial t) \{0 + i \mu_0 \varepsilon_0 (\partial E) / (\partial t)\},$$
or
$$\nabla \otimes (\nabla \otimes E) = \mu_0 \varepsilon_0 (\partial^2 E) / (\partial t^2).$$
(12)

It can be shown that $\nabla \otimes (\nabla \otimes E) = \nabla^2 E$.

From eqs. (12) and (13), we can write

$$\nabla^2 \boldsymbol{E} = \mu_0 \boldsymbol{\varepsilon}_0 (\partial^2 \boldsymbol{E}) / (\partial t^2)$$

which is exactly same as shown in eq. (10).

Similarly using mixed product, it can also be shown that

$$\nabla^2 \boldsymbol{B} = \mu_0 \boldsymbol{\varepsilon}_0 (\partial^2 \boldsymbol{B}) / (\partial t^2).$$

Therefore, mixed product can be used successfully in dealing with differential operators. Using the definition of quaternion product (eq. 4), it can be shown that quaternion product can not be used in dealing with differential operators.

4. Elementary properties of these products

4.1 Elementary properties of mixed product :

- (i) Mixed product of two perpendicular vectors is equal to the imaginary of the vector product of the vectors
- (ii) Mixed product of two parallel vectors is simply the scalar product of the vectors.
- (iii) It satisfies the distribution law of multiplication.
- (iv) It is associative.

4.2 Elementary properties of quaternion product :

- (i) Quaternion product of two perpendicular vectors is simply the vector product of the vectors.
- Quaternion product of two parallel vectors is negative of the scalar product of the vectors.
- (iii) It satisfies the distribution law of multiplication.
- (iv) It is non-associative.

5. Conclusion

A comparison of Quaternion and mixed products is given in Table 1. From the table we may conclude that mixed product is more consistent with different laws of Physics than that Quaternion product. From the table we may conclude that mixed product is more consistent with different laws of Physics than the Quaternion product.

Acknowledgments

I am grateful to Mushfiq Ahmad, Department of Physics. University of Rajshahi, Rajshahi, Bangladesh and Prof. Habibul Ahsan, Department of Physics, Shahjalal University of Science and Technology, Sylhet, Bangladesh and Prof. Anwarul Haque Sharif, Department of Mathematics, Jahangir Nagar University. Dhaka, Bangladesh for their help and advice.

(13)

	Quaternion product	Mixed product
I. Mathematical expression	$\underline{AB} = A \cdot B - A \times B$	$A \otimes B = A \cdot B + iA \times B$
2. Consistency with Pau matrix algebra	li It is not di re ctly consistent with Pauli matrix algebra	It is directly consistent with Pauli matrix algebra
3. Consistency with Dira equation	c It is not consistent with Dirac equation	It is consistent with Dirac equation
 In dealing with differentia operators 	It can not be used in dealing with differential operators	It can be used successfully in dealing with differential operators
5. Elementary properties	(i) Quaternion product of two perpendicular vectors is simply the vectors product of the vectors.	 (i) Mixed product of two perpendicular vectors is equal to the imaginary of the vector product of the vectors
	(ii) Quaternion product of two parallel vectors is negative of the scalar product of the vectors.	(ii) Mixed product of two parallel vectors is simply the scalar product of the vectors.
	(iii) It satisfies the distribution law of multiplication.	(iii) It satisfies the distribution law of multiplication.
	(iv) It is non-associative.	(iv) It is associative

Table 1. Comparison of quaternion product and mixed product

References

- [1] Md Shah Alam Study of Mixed Number Proc. Pakistan Acad. Sci 37 119 (2000)
- [2] Md Shah Alam Mixed Product of Vectors J. Theoretics Vol 3 (2001)
- [3] A Kyrala Theoretical Physics (Philadelphia & London + W B Saunders Company) (Toppan Company Limited Tokyo, Japan) (1967)
- [4] http://mathworld.wolfram.com/Quaternion.html
- [5] http://www.cs.appstate.edu/~sjg/class/3110/mathfestalg2000/ quaternions1.html
- [6] L I Schift Quantum Mechanics (New York McGraw Hill)
- [7] Md Shah Alam Shabbur Thesis (Department of Physics, University of Rajshahi, Rajshahi, Bangladesh) (1994)
- [8] David J Griffiths Introduction to Electrodynamics second ed (New Delhi – Prentice Hall of India) (1994)