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# Optimization Based Improved Softened Membrane Model for Rectangular Reinforced Concrete Members under Combined Shear and Torsion --Manuscript Draft--

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Abstract:	Reinforced concrete (RC) elements are often subjected to combined actions including torsion under seismic events. Understanding the behavior of RC members under combined actions including torsion is essential for safe design. Behavioral predictions of RC columns under combined loading can be improved by including the bi-directional stress effects. The objective of this work is to propose improved combined actions softened membrane model (CA-SMM) for predicting the behavior of RC elements under combined torsion (T) and shear loading (V). In this approach, the rectangular cross-section is modeled as an assembly of four cracked shear panels. The applied external loads are distributed among these four shear panels. This assumption helps in reducing the complex stress state from combined loading to four different simple stress states on these panels. Additional equilibrium and compatibility conditions are imposed, and the system of non-linear equations are solved by using an optimization technique called gradient descent method. The developed improved model (CA-SMM) is validated with the experimental data available in the literature. After that, an interaction between the shear and torsion is developed to understand the behavior under various combinations of torsion and shear. A parametric study is carried out for understanding the effect of various sectional parameters such as longitudinal reinforcement ratio, transverse reinforcement ratio, and concrete strength. The predictions of the improved model had a close correlation with the test results.					
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	Has extensively worked on devleopment of improved models for combined loading including torsion			
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	Has extensively worked on behavior of RC members and on development of improved models			
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## Optimization-Based Improved Softened Membrane Model for Rectangular Reinforced Concrete Members under Combined Shear and Torsion

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#### Abstract

17 Reinforced concrete (RC) elements are often subjected to combined actions including torsion under seismic events. Understanding the behavior of RC members under combined actions including torsion is essential 18 19 for safe design. Behavioral predictions of RC columns under combined loading can be improved by 20 including the bi-directional stress effects. The objective of this work is to propose improved combined 21 actions softened membrane model (CA-SMM) for predicting the behavior of RC elements under combined torsion (T) and shear loading (V). In this approach, the rectangular cross-section is modeled as an assembly 22 23 of four cracked shear panels. The applied external loads are distributed among these four shear panels. This 24 assumption helps in reducing the complex stress state from combined loading to four different simple stress states on these panels. Additional equilibrium and compatibility conditions are imposed, and the system of 25 26 non-linear equations are solved by using an optimization technique called gradient descent method. The 27 developed improved model (CA-SMM) is validated with the experimental data available in the literature. After that, an interaction between the shear and torsion is developed to understand the behavior under 28 29 various combinations of torsion and shear. A parametric study is carried out for understanding the effect of 30 various sectional parameters such as longitudinal reinforcement ratio, transverse reinforcement ratio, and 31 concrete strength. The predictions of the improved model had a close correlation with the test results.

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33 Keywords: Combined loading; RC Member; Shear; Softened Membrane Model (SMM); Torsion

34

#### 35 INTRODUCTION

Reinforced concrete (RC) bridge columns are subjected to combined loading including torsion under 36 seismic events. In general, numerous structural elements namely arch ribs, L-shaped bridge columns, and 37 spiral staircases are subjected to combinations of loading. General system of forces and moments acting in 38 39 RC member subjected to combined loading are shown in Fig. 1. Accurate predictions of the behavior of RC members subjected to combined loading is essential for optimal design solutions. In typical design practices 40 of RC members, the effect of the torsional moment is ignored or indirectly considered in the design. 41 However, previous studies indicate that the presence of torsion during seismic events could significantly 42 43 affect the performance of the RC members (Tirasit and Kawashima 2007, Prakash et al. 2010, Prakash et al. 2012). Previous researchers have extensively studied predicting the behavior of RC columns subjected 44 to torsional loading analytically through various approaches (Onsongo 1978, Chalioris 2007, Prakash and 45 Belarbi 2010, Belarbi et al. 2010, Deifalla 2015, Mondal et al. 2017). The cyclic torsional behavior of the 46 47 square and circular RC columns has also been investigated (Li 2012, Chalioris and Karayannis 2013, Li and Belarbi 2013). In the past, only few studies (Klus 1968, Lampert and Thurlimann 1969, McMullen and 48 Warwaruk 1970, Onsongo 1978, Ewida and McMullen 1982, Greene and Belarbi 2009) have 49 experimentally investigated the effect of combined bending moment, shear and torsional loads on the 50 51 behavior of RC members.

52

Noncircular RC members warp under torsional loading (Collins and Mitchell 1997, Hsu 1993, Jeng 2014, 53 Zhang and Hsu 1998; Mullapudi and Ayoub 2013) and pose challenges in developing a rational model 54 55 under combined loading including torsion. Different analytical models such as softened truss model (STM) from University of Houston (Hsu and Belarbi; Hsu and Zhu 2002; Greene and Belarbi 2009; Mondal and 56 Prakash 2015) and modified compression field theory (MCFT) from University of Toronto (Onsongo 1978; 57 58 Rahal 1993, Rahal and Collins 1995) were developed. These rational models were based on the principles 59 of mechanics and evolved over the years with increasing sophistication. The present study comes in the purview of studies that include modeling the behavior of cracked concrete using STM developed at the 60 University of Houston. Mondal and Prakash (2015a, 2015b) showed that inclusion of tension stiffening 61

62 could significantly improve the torque twist prediction using STM. The effect of Poisson's ratio is observed by the researchers and is found to be significant in the prediction of the behavior of RC members. Due to 63 the Poisson effect, the stresses get induced in the direction perpendicular to the direction in which loads are 64 applied. This stress state is known as bi-directional stress state and occurs due to Poisson effect. Zhu and 65 66 Hsu (2002) proposed a softened membrane model (SMM) including the effect of bi-directional stress states. Jeng and Hsu (2009) proposed a softened membrane model for torsion (SMMT) for rectangular cross 67 sections by considering the effect of strain gradient. The consideration of bi-directional stresses using 68 69 Poisson's ratio helps in predicting the post-peak behavior accurately (Hsu and Zhu 2002). The fundamental 70 differences between CA-STM and CA-SMM are summarised in Table 1. SMMT was extended to other geometries, and configuration like box girders (Greene and Belarbi 2009), hollow RC members (Jeng and 71 Hsu 2009), and rectangular sections strengthened with fiber reinforced polymer (FRP) composites 72 73 (Ganganagoudar et al. 2016) under pure torsion. Ganganagoudar et al. (2016) have also extended the SMM 74 based model for torsion (SMMT) for circular members and validated with the experimental test results.

75

Previous researchers have developed rational models for analysis of RC members under bending, shear, 76 axial load and their combinations (Rahal and Collins 1995; Mullapudi and Ayoub 2010, 2013). However, 77 78 combined loading with torsion can result in brittle failure of RC members and calls for deeper understanding and development of improved models. Using MCFT, Rahal and Collins (1995) proposed a theoretical 79 model for predicting the behavior of RC rectangular columns subjected to combined torsion and shear 80 81 loading. They have modeled the rectangular section as an assembly of four cracked shear panels. The 82 applied loads are distributed among the shear panels in such a way that equilibrium and compatibility conditions are satisfied. The stress states in each shear panels will be different due to different loads acting 83 on it. Greene and Belarbi (2009a, 2009b) developed a softened truss model (STM) based approach for 84 85 predicting the response of rectangular girder subjected to combined loading. Greene's model is developed 86 based on STM and can predict the behavior until peak load. Also, both the previous MCFT and STM approaches were iterative and ignored the bi-directional stress effects. Recently, Silva et al. (2017) adopted 87 an optimization technique for solving the system of equations for analyzing the behavior of concrete 88

89 members. Adopting such optimization technique significantly reduces the computation time in the case of 90 multiple variables in the system. Developing a more sophisticated SMM theory for combined loading 91 analysis and solving the system by adopting an optimization technique is the focus of this study.

92

#### 93 RESEARCH SIGNIFICANCE AND OBJECTIVES

Only limited analytical models are available for predicting the response of rectangular RC members 94 95 subjected to combined loading including torsion. This study presents an improved and robust combined action softened membrane model (CA-SMM) for the analysis of rectangular RC members. To include the 96 97 effects of combined actions, the cross-section of the concrete member is modeled as an assembly of four shear panels. The equations satisfying the equilibrium and compatibility conditions between the panels are 98 developed. Solving the nonlinear set of equations using trial and error is tedious especially in the case of 99 100 combined loading. In this study, an optimization technique namely gradient descent method is adopted to 101 solve the CA-SMM system of non-linear equations rather than conventional trial and error approach. In particular, the following advancements are made in the CA-SMM model developed in this study: 102

- Sophisticated softened membrane based model is adopted for analyzing the behavior of RC
   members subjected to combined shear and torsion loading.
- The effect of bi-directional stress (Poisson's effect) is considered in the formulations of CA-SMM
   for improved post-peak predictions.
- 107 3. An improved tension stiffening effect model is used to account for the strain gradient effect.
- 4. A robust optimization based solution algorithm is proposed for significantly reducing the
   computational time involved in the analysis of RC members under combined actions including
   torsion.
- 111

#### 112 COMBINED ACTION-SOFTENED MEMBRANE MODEL (CA-SMM)

**113** Assumptions of the model

114	The improved CA-SMM model makes the following assumptions for satisfying the equilibrium and
115	compatibility conditions. The assumptions made are related to the modeling of geometry, strain profile, and
116	various material aspects as given below:

- i. The rectangular cross-section is divided into four RC shear panels. The overall distribution of stresses
   across the section are consolidated into four stress states, and each panel corresponds to a particular
   stress state.
- ii. The concrete member is assumed to act as a truss after cracking, i.e., concrete in diagonal struts is
   assumed to resist the compression stresses, steel in longitudinal and transverse directions resist the
   tensile stresses.
- 123 iii. The externally applied loads on the member are distributed to each of the panels as uniform normal124 and shear stresses.
- iv. The model neglects the dowel action of the reinforcement and assumes a perfect bond betweenconcrete and reinforcement.
- v. Bredt's thin tube theory is considered for satisfying the torsion equilibrium at the sectional level. In
   case of solid sections, the core of the member does not contribute to the torsional resistance and
   therefore, neglected as per this theory.

The assumption of a concrete member acting as a truss is valid for a cracked RC member. The behavior of the concrete member is known to be linear until cracking. The stress and strain at cracking can be calculated from the expressions given by Collins and Mitchel (1991). The behavior is linear until cracking, and the post-cracking behavior is predicted using the proposed CA-SMM theory.

#### 134 The idealization of RC cross-section:

A rectangular RC section can be idealized as a thin-tube, assuming the shear stress due to torsion to be constant over the thickness of the thin-tube. The centreline of the shear flow zone in a rectangular crosssection has dimensions of by  $b_0$ , and a constant thickness of  $t_{d,i}$  along each side as shown in Fig. 2. The modeled thickness of each panel is the depth of the shear flow zone  $t_d$  in that panel. The width of panels 1 and 3 is  $h_0$ , and  $b_0$  for panels 2 and 4. The cross-sectional area of a panel ( $A_o$ ) is equal to a product of 140 its modeled width and thickness. The idealised  $b_o$ ,  $h_o$ ,  $A_o$  and  $p_o$  are calculated using Eq. 1, formulated by 141 Greene and Belarbi (2009). The panel dimensions used to analyse the cross-section and the cross-sectional 142 area of panel one is shown in Fig. 2.

143 
$$b_o = b - \left(\frac{t_{d,1} + t_{d,3}}{2}\right)$$
 (1a)

144 
$$h_o = h - \left(\frac{t_{d,2} + t_{d,4}}{2}\right)$$
 (1b)

$$A_o = b_o h_o \tag{1c}$$

146  $p_o = 2(b_o + h_o)$  (1d)

The longitudinal and transverse reinforcement in the section also has to be distributed among the shear 147 148 panels. If the sections have symmetrical reinforcement, then longitudinal steel and transverse steel are distributed equally among all the shear panels. The transverse reinforcement is distributed equally among 149 150 all the shear panels as it is symmetric for all the specimens adopted in the current study. The longitudinal 151 steel area is assigned to that shear panel in which the longitudinal bar is located. In the cases of overlap of 152 steel area between two shear panels, it is distributed as a function of the width of the shear panels that are overlapping. A detailed account of the distribution of longitudinal reinforcement can be obtained from 153 154 Greene and Belarbi (2009).

155

#### 156 Equilibrium equations

157 The applied external loads are distributed as normal, and shear stresses on the membrane element. Fig. 3 158 depicts the stress state at the element level. The normal stresses are distributed among the concrete and steel components of membrane element. The principle of transformation is used for determining the stresses in 159 160 principal directions 1 and 2, making an angle  $\alpha_i$  with *l*-direction. It is worth mentioning that SMM is based 161 on fixed angle theory. More details on fixed angle theory can be found elsewhere (Hsu and Zhu 2002, 162 Ganganagoudar et al. 2016). The cracks are assumed to occur in the principal directions of RC composite element. The crack angle in the concrete element will be different as it is subjected to shear stresses. The 163 164 equilibrium equations (Eqs. 2-4) of membrane element can be derived using the principle of transformation.

165 The planes of primary interest in the membrane element are the principal planes (1-2 planes) and the planes166 in which loads are applied (L-T planes), as shown in the Fig. 3.

168 
$$\sigma_{l,i} = \sigma_{2c,i} cos^2 \alpha_i + \sigma_{1c,i} sin^2 \alpha_i + 2\tau_{12c,i} sin\alpha_i cos\alpha_i + \rho_l f_l$$
(2)

169 
$$\sigma_{t,i} = \sigma_{2c,i} \sin^2 \alpha_i + \sigma_{1c,i} \cos^2 \alpha_i - 2\tau_{12c,i} \sin \alpha_i \cos \alpha_i - \rho_t f_t$$
(3)

170 
$$\tau_{lt,i} = \left( \left( -\sigma_{2c,i} + \sigma_{1c,i} \right) \sin \alpha_i \cos \alpha_i + \tau_{12c,i} \left( \cos^2 \alpha_i - \sin^2 \alpha_i \right) \right) \cdot sign(q_i)$$
(4)

171

The shear flow due to torsional loading is constant along the cross-section. The applied shear loads are distributed in accordance with the direction of load application as shown below in the Fig. 4. The shear load is added to loads on one of the panels and is subtracted from the other panel due to combined shear and torsion loading (Fig. 4). Eq. 5 (Rahal and Collins 1995, Greene and Belarbi 2009) gives the net shear flow (q<sub>i</sub>) in each panel.

177 
$$q_1 = \frac{T_x}{2A_0} + \frac{V_y}{2h_0}$$
(5a)

178 
$$q_2 = \frac{T_x}{2A_0} + \frac{V_z}{2b_0}$$
(5b)

179 
$$q_3 = \frac{T_x}{2A_0} - \frac{V_y}{2h_0}$$
(5c)

180 
$$q_4 = \frac{T_x}{2A_0} - \frac{V_z}{2b_0}$$
(5d)

181

#### **182 Bredt's thin tube theory**:

When torsion acts on an RC member, it induces shear stress within the member. Bredt's thin tube theory assumes that the applied torsion is resisted by the shear stresses developed across a tube of thickness known as shear flow depth. The elastic shear stress distribution varies linearly across the section with maximum stress at the surface and reaches zero at the center. However, Bredt's thin tube theory assumes the stress distribution to be constant across the depth of thin tube as shown in Fig. 5. The relation between the external torque and shear flow is given by Bredt's thin tube theory, as in Eq 6.

189 
$$T_x = q \left[ 2(\frac{b_0}{2}h_0 + \frac{h_0}{2}b_0) \right]$$
(6*a*)

190 From the Fig. 6 (Hsu 1993), the integration around the cross section gives twice the area inscribed by shear191 flow region:

192 
$$\left[2(\frac{b_0}{2}h_0 + \frac{h_0}{2}b_0)\right] = 2A_0$$

$$T_x = 2A_0 q \tag{6b}$$

#### **194 Compatibility equations:**

The equations of compatibility (Eqs. 7-10) are derived using the principle of transformation (Hsu and Zhu2002). In-plane strain compatibility should be satisfied for all the membrane elements.

197 
$$\varepsilon_{l,i} = \varepsilon_{2,i} \cos^2 \alpha_i + \varepsilon_{1,i} \sin^2 \alpha_i + \gamma_{12,i} \sin \alpha_i \cos \alpha_i \tag{7}$$

198 
$$\varepsilon_{t,i} = \varepsilon_{2,i} \sin^2 \alpha_i + \varepsilon_{1,i} \cos^2 \alpha_i - \gamma_{12,i} \sin \alpha_i \cos \alpha_i \tag{8}$$

199 
$$\gamma_{LT,i} = (2(-\varepsilon_{2,i} + \varepsilon_{1,i})sin\alpha_i cos\alpha_i + \gamma_{12,i}(cos^2\alpha_i - sin^2\alpha_i)).sign(q_i)$$
(9)

$$\varepsilon_{t,i} = \varepsilon_{2,i} + \varepsilon_{1,i} - \varepsilon_{l,i} \tag{10}$$

201

The equations of compatibility are derived at the section level by imposing the strain compatibility requirement at the center of the cross-section. It is assumed that shear stress due to combined shear flows from an applied torsion and shear acts as a uniformly distributed shear stress,  $\tau_{LT}$ , over the thickness of the shear flow zone. Eq. 11 gives the curvature of the concrete strut of each panel.

206

207 
$$\Psi_i = \frac{-\overline{\varepsilon_{2s,i}}}{t_{d,i}}$$
(11)

The thickness of shear flow zone  $(t_{d,i})$  is calculated using a simplified expression given by Ganganagoudar et al. (2016), as given below

210 
$$t_{d,i} = \frac{-\overline{\varepsilon_{2S,i}}}{\psi_i} \quad \left(\leq \frac{b_0}{2}\right)$$
(12a)

211 
$$\Psi_i = \theta \sin(2\alpha_i) \tag{12b}$$

212 
$$H_i = \frac{4\overline{\varepsilon_{2,i}}}{\gamma_{LT,i}\sin(2\alpha_i)}$$
(12c)

213 
$$t_{d,i} = \frac{1}{2(H+4)} \left[ P_c \left( 1 + \frac{H}{2} \right) - \sqrt{\left( 1 + \frac{H}{2} \right)^2 - 4H(H+4)A_c} \right]$$
(12d)

214 where 
$$\theta = [(\gamma_{LT,1} + \gamma_{LT,3})h_0 + (\gamma_{LT,2} + \gamma_{LT,4})b_0]\frac{1}{2A_0}$$
 (13)

The calculated shear flow depth  $t_{d,i}$  should be limited to the thickness of the wall in the case of hollow specimen and should be limited to half of the depth of the idealized cross-section  $\left(\frac{b_o}{2}\right)$  in the case of solid cross-sections.

218

#### 219 **Constitutive laws**:

The constitutive laws shown in Fig. [7, 8] are adopted in this study. The constitutive laws used in this study are developed based on flat panels which are a 2D element (Vecchio and Collins 1986, Hsu 1993) and includes the effects of softening and tension stiffening. Torsion is a 3-dimension problem. However, these constitutive laws are the current state of the art. The evaluation of constitutive laws for a 3-dimension panel is recently investigated by Labib et al. (2017). These constitutive laws for compression and tension based on a warped 3-dimension panel, Poisson effect on these 3-D panels and their application for torsion are not fully understood yet and is scope for further work.

227

#### 228 Concrete in compression:

The presence of tensile cracks in principle compression plane causes softening of concrete struts. The softening coefficient ( $\zeta$ ) of concrete is a function of principle tensile strain (Vecchio and Collins 1986), compressive strength (Zhang and Hsu 1998) and deviation angle ( $\beta$ ). The softening co-efficient used by Jeng and Hsu (2009), that accounts for all the above effects has been used in the present study. The concrete compression law has been given in Eq. 14.

234 
$$\beta_i = \frac{1}{2} \left[ tan^{-1} \left( \frac{\gamma_{12c,i}}{\varepsilon_{2c,i} - \varepsilon_{1c,i}} \right) \right]$$
(14a)

235 
$$\zeta_{i} = \frac{5.8}{\sqrt{fc'}} \frac{0.9}{\sqrt{1+400\overline{\epsilon_{2c,i}}}} \left(\frac{1-\beta_{i}}{24^{0}}\right)$$
(14b)

$$\sigma_{2c,i} = K_{2c,i} \zeta f_c' \tag{14c}$$

237 
$$K_{2c,i} = \left[\frac{\overline{\varepsilon_{2s,i}}}{\zeta_i \varepsilon_0} - \frac{\varepsilon_{2s,i}^2}{3(\zeta_i \varepsilon_0)^2}\right] \text{ for } \frac{\overline{\varepsilon_{2s,i}}}{\zeta_i \varepsilon_0} \le 1$$
(14d)

238 
$$K_{2c,i} = 1 - \frac{\zeta_i \varepsilon_0}{3\overline{\varepsilon_{2s,i}}} - \frac{1}{3\overline{\varepsilon_{2s,i}}} \left[ \frac{(\overline{\varepsilon_{2s,i}} - \zeta_i \varepsilon_0)^3}{(4\varepsilon_0 - \zeta_i \varepsilon_0)^2} \right] \quad \text{for } \frac{\overline{\varepsilon_{2s,i}}}{\zeta_i \varepsilon_0} \ge 1 \tag{14e}$$

#### 239 Concrete in tension:

The current study employs the tension stiffening relation used by Jeng and Hsu (2009) for modeling thetension behavior of concrete. Fig. 9 shows the tension constitutive law of the concrete.

242 
$$f_{cr} = 0.652\sqrt{f_{ck}}$$
 (15a)

243 
$$E_c = 5620\sqrt{f_{ck}}$$
 (15b)

244 
$$\sigma_{1c,i} = E_c \overline{\varepsilon_{1,i}} \qquad \text{for } \frac{\varepsilon_{1s}}{\varepsilon_{cr}} \le 1 \qquad (15c)$$

245 
$$\sigma_{1c,i} = f_{cr} \left(\frac{\varepsilon_{cr}}{\varepsilon_{1,i}}\right)^{0.4} \quad \text{for } \frac{\overline{\varepsilon_{1s}}}{\varepsilon_{cr}} \ge 1 \tag{15d}$$

246

#### 247 Stress-strain relationship of steel:

The smeared stress-strain behavior of steel embedded in concrete as adopted by Jeng (2009) and Ganganagoudar et al. (2016) in the previous SMMT formulations is used in the present study (Fig. 9). In the below equations,  $f_{s,i}$  represents both longitudinal and transverse steel.

251 
$$f_{s,i} = E_s \overline{\varepsilon_{l,i}}$$
 for  $\overline{\varepsilon_{l,i}} \le \overline{\varepsilon_{ln,i}}$  (16a)

252 
$$f_{s.i} = \left[ (0.91 - 2B_i) + (0.02 + 0.25B_i) \frac{\overline{\varepsilon_{l.i}}}{\varepsilon_{ly}} \right] \quad \text{for } \overline{\varepsilon_{l.i}} \le \overline{\varepsilon_{ln.i}} \quad (16b)$$

253 
$$B_{i} = \left[\frac{\left(\frac{f_{cr}}{f_{ly}}\right)^{1.5}}{\rho_{i}}\right]$$
(16c)

254 
$$\overline{\varepsilon_{ln.\iota}} = \varepsilon_{ly} \left( 0.93 - B_i \right) \tag{16d}$$

#### 256 The constitutive relation for concrete in shear

The shear modulus is expressed as a function of normal stresses and strains in concrete element. Therelation is given in Eq. 17.

259 
$$\tau_{12c,i} = \frac{(-\sigma_{2c,i} + \sigma_{1c,i})}{2(\varepsilon_{1,i} - \varepsilon_{2,i})} \gamma_{12c,i}$$
(17)

260

#### 261 **Poisson's effect in SMMT:**

Stresses in one direction can result in the development of stresses in its perpendicular direction due to Poisson's effect. This Poisson's ratio is considered in the formulation of CA-SMM. The strain in one direction is not only a function of stress in its direction but will also depend on the stress in its perpendicular direction. Zhu and Hsu (2002) investigated the Poisson's ratio of shear panels experimentally and proposed a parameter called Hsu/Zhu ratio, which quantifies the bi-directional stress effect. Hsu/Zhu ratio relates the strains and bi-directional stresses as given in equation 17.

268

269 
$$\varepsilon_1 = \frac{\sigma_{1c}}{E_{1c}} - v_{12} \frac{\sigma_{2c}}{E_{2c}}$$
 (17a)

270 
$$\varepsilon_2 = \frac{\sigma_{2c}}{E_{2c}} - v_{21} \frac{\sigma_{1c}}{E_{1c}}$$
(17b)

 $v_{12} = 1.52$ 

271 where

272 
$$v_{12} = (0.16 + 680\varepsilon_{sf})$$
 for  $\varepsilon_{sf} \le \varepsilon_y$  (18a)

274 
$$v_{21} = 0$$
 (18b)

for  $\varepsilon_{sf} \geq \varepsilon_y$ 

275

273

Here,  $v_{12}$  is the strain increment in direction 1 for an applied unit strain in direction 2. Now, defining uniaxial strains as  $\overline{\varepsilon_1} = \frac{\sigma_{1c}}{E_{1c}}$  and  $\overline{\varepsilon_2} = \frac{\sigma_{2c}}{E_{2c}}$  and re-writing the equation (17), the relation between uniaxial strains and biaxial strains can be arrived.

$$\varepsilon_1 = \overline{\varepsilon_1} - v_{12}\overline{\varepsilon_1} \tag{19a}$$

$$\varepsilon_2 = \overline{\varepsilon_2} - v_{21}\overline{\varepsilon_2} \tag{19b}$$

281 After re-arranging the equations (19), one can get

282 
$$\overline{\varepsilon_1} = \frac{\varepsilon_1}{(1 - v_{12}v_{21})} + \frac{v_{12}\varepsilon_2}{(1 - v_{12}v_{21})}$$
(20a)

283 
$$\overline{\varepsilon_2} = \frac{v_{21}\varepsilon_2}{(1-v_{12}v_{21})} + \frac{\varepsilon_1}{(1-v_{12}v_{21})}$$
(20b)

284 The constitutive law of material relates stresses and uniaxial strains as given by equation (18).

285

#### 286 OPTIMIZATION BASED GRADIENT DESCENT METHOD

An alternative and efficient procedure to the conventional trial and error method is used for solving the system of equilibrium and compatibility equations in CA-SMM. Gradient descent method is a first-order iterative optimization algorithm for finding the minimum of a multi-variable function. To solve for the local minimum of a function, the subsequent iterations take steps in a direction negative to the gradient of the function at the current point. The solution algorithm is described in detail in the following sections.

292

#### 293 Primary Variables

The primary variables are the variables that are varied numerically until the objective functions are set to zero. In the proposed algorithm, the primary variables are  $T_x$ ,  $\varepsilon_{2s,j}$ ,  $\varepsilon_{1,i}$ , and  $\gamma_{12,i}$  (j = 2,3,4 and i = 1,2,3,4).  $\varepsilon_{2s,1}$  of panel 1 is fixed for each step and is incremented until a concrete failure strain of -0.0035. The primary variable  $\varepsilon_{2s,j}$  is varied until the shear stresses  $F_{CASMM}(j)$  (j=2,3,4) of Eq. 21 are in agreement. The equilibrium Eq. 2- 3 are summed and subtracted to get the set of objective functions  $F_{CASMM}(i + 8)$  and  $F_{CASMM}(i + 12)$ , whose primary variables are chosen as  $\varepsilon_{1,i}$  and  $\gamma_{12,i}$ , respectively.

300

#### **301** Residual Equations and Objective function

The set of equations of the model that has to be solved are developed from the equilibrium and compatibility conditions as explained in earlier sections. This set of equations that has to be solved are called residual equations as given in Eq. 21.

$$305 \quad \begin{bmatrix} F_{CASMM}(1) \\ F_{CASMM}(j) \\ F_{CASMM}(i+8) \\ F_{CASMM}(i+12) \end{bmatrix} = \begin{bmatrix} \tau_{lt,1-q_1/t_{d,1}} \\ \tau_{lt,j-q_j/t_{d,j}} \\ (\rho_l f_l + \rho_t f_t)_i - ((\sigma_{l,i} + \sigma_{t,i}) - (\sigma_{2c,i} + \sigma_{1c,i})) \\ (\rho_l f_l - \rho_t f_t)_i - ((\sigma_{l,i} - \sigma_{t,i}) - (\sigma_{2c,i} - \sigma_{1c,i})\cos 2\alpha_i + 2\tau_{12c,i}\sin 2\alpha_i) \end{bmatrix}$$
(21)

306 The above set of equations are compactly represented as f(x) = 0.

where x is a vector of primary variables taken as  $x = \{T_x, \varepsilon_{2s,j}, \varepsilon_{1,i}, \gamma_{12,i}\}$ . (where j = 2,3,4 and i = 1,2,3,4). In conventional way of solving, the function f(x) is solved by trial and error way of varying primary variables. It is very tedious and time consuming. In the present study, the set of equations of the model are solved by adopting an optimisation technique (Gradient descent method). Instead by directly solving for f(x) = 0, we will minimise the objective function "*J*". The objective function "*J*" is the norm of the function f(x), as defined in Eq. 22.

313 
$$J = \frac{1}{2} (f^{T}(x) \cdot f(x))$$
(22)

The scalar output given by the objective function at every step is called a residue. The residue is zero only when each of the residual functions  $f_1(x)$ ,  $f_2(x) \dots f_{12}(x)$  is zero. The value of primary variables gets updated for each step as per gradient descent method as given in Eq. 23.

317 
$$x^{+} = x^{-} - \gamma \frac{\partial J}{\partial x}$$
(23)

318 where  $\gamma$  is chosen as a small incremental decimal value such that  $J(x^+) < J(x^-)$ .

The characteristic of residue (*J*) at a fixed value of  $\overline{\varepsilon_{2s,1}}$  for specimen tested by Klus (1968) is shown in Fig. 10, till the objective function reaches a tolerable value. The tolerance for Klus specimen has been set a value of  $1e^{-3}$  after 5700 steps (Fig. 10). By moving towards the minimum of the objective function (*J*) at each step, the residue (*J*) decreases. The optimal minimum solution within the tolerant limits is obtainedby minimising the objective function.

324

#### 325 Solution procedure

The proposed solution algorithm is explained in Fig. 11. The solution algorithm is executed using a program 326 327 developed and executed in the software MATLAB. The geometry of the member cross-section, the equivalent longitudinal and transverse reinforcement in each panel, the mechanical properties for the 328 concrete and steel, the ratios of the internal acting forces to the torsional moment  $(N_X/T_X, V_Y/T_X, V_Z/T_X)$ 329 and the initial strain  $\varepsilon_{2s,1}$ , are known or assumed to start with. The unknown variables  $T_x$ ,  $\varepsilon_{2s,i}$ ,  $\varepsilon_{1,i}$ , and 330 331  $\gamma_{12,i}$  (j = 2,3,4 and i = 1,2,3,4) are determined by solving the nonlinear system of twelve equations f(x) =0. For these system of equations, the residue of the objective function (I) should be within an acceptable 332 tolerance. This is formulated as a nonlinear least-squares problem, where F<sub>CA-SMM</sub>, Eq. (21) are the residual 333 334 equations.

335

#### 336 EXPERIMENTAL VALIDATION

337 The proposed solution algorithm is validated using experimental data obtained from the literature. Prakash et al. (2010, 2012) conducted experiments on RC columns subjected to torsion. Li (2013) tested square 338 columns with torsion and axial loads. Columns tested by Prakash and Belarbi (2010) and Li et al. (2013) 339 340 are denoted as Missouri columns. Rahal and Collins (1993) and Klus (1968) tested RC beams under combined torsion and shear loading. The data of following RC members are used in validation of the CA-341 SMM model proposed in this study: Missouri-1 (Pure Torsion); Missouri 2 (Torsion + Axial); one RC 342 square girder of Greene (Pure Torsion); two beams tested by Rahal and Collins (Torsion + Shear + Axial) 343 344 and three beams tested by Klus (one in Pure Torsion and two in Torsion + Shear). The details of all these specimens are given in Table 2. Cross sections of specimens are shown in Fig. 12. 345

346

#### 347 Torque – Twist Behavior:

348 The torque-twist behavior of the specimens under different load combinations is shown in Fig. 13. The behavior is linear until cracking. The stiffness reduces considerably after the peak torque. The peak torque 349 350 and the corresponding twist are captured reasonably well by the CA-SMM. The proposed model predicted 351 the peak torque and twist more accurately for the specimen of Missouri, Rahal, and Collins while the results 352 of CA-STM are close to experimental peak values of Greene's and Klus specimen. However, it can be 353 observed from the Table 3 that the predictions in the peak torque and peak twist predictions of CASTM and 354 CASMM are very close. The observed behavior until cracking is similar to the torsional response of plain 355 concrete elements as observed by Karayannis and Chalioris (2013). Comparison of predictions is provided 356 in Table 3 and Table 4. Table 3 presents the comparison of values of peak torque and twist values. Table 4 presents the comparison of values of ultimate torque and corresponding ultimate twist values. It is evident 357 that the response predicted by the CA-SMM is better in the post-cracking regime and close to the 358 359 experimental peak values. It is observed that due to consideration of bi-axial stress effects, CA-SMM predicts the ultimate torque values with fair accuracy. The ultimate twist values predicted by the CA-SMM 360 are close to experimental values. Specimens considered for analysis had the following failure progression: 361 362 shear cracking followed by vielding of transverse reinforcement and the longitudinal reinforcement respectively. All the specimens finally failed by crushing of the concrete under diagonal compression. The 363 364 same failure progression was observed in the predictions of CA-SMM. The strain distribution in the steel for the specimens is shown in Figs. [14-15]. The parametric study also depicts that the effect of transverse 365 steel on torsional behavior is very significant when compared to any other sectional parameters. 366

367

#### 368 Distribution of Strains in Reinforcement:

Predictions of behavior at the local level, i.e. the distribution of strains in reinforcement are analyzed using CA-SMM. Variation of strain in longitudinal and of transverse steel reinforcement with change in applied torque are presented in Figs. 14 &15. It is worth mentioning that the strains predicted by the model are smeared strains. The strains are calculated as an average of all the strains smeared across the number of cracks. Before the onset of cracking in the concrete, the contribution from reinforcement is negligible. After cracking, steel reinforcement gets engaged and starts contributing to the load resistance. Moreover, the 375 transverse reinforcement is known to be a prime contributor in resisting shear, and torsional loads and the same is reflected in the predictions (Figs. 14,15). It can be observed that at any given loading level, the 376 strains in the transverse steel reinforcement is higher than that of strains in the longitudinal steel. Due to 377 unavailability of experimental data pertaining to the longitudinal and transverse strains, only the analytical 378 379 predictions are presented in the Fig. [14-15]. When the section is subjected to the combined loading of 380 torsion and shear as shown in the direction as represented in Fig. 4, the shear flow due to torsion and shear 381 gets added up in panel 3 and gets subtracted in panel 1. The shear flow in the panels 2 and 4 are only due to torsion and are not affected by the applied shear in Y-direction. It is due to this difference in the shear 382 383 flow that the strains are different in each of the panels for the specimen that are loaded with torsion and shear (Fig. 15). The strains predicted by the model are observed to be increasing smoothly with an increase 384 in the level of torsional loading. Steel in the transverse direction is the key component of resisting shear 385 386 and torsion. It is expected typically that the strains in the transverse direction increase till the loading 387 reaches peak value and decreases after that (Ganganagoudar et al. 2016, Prakash et al. 2012). The model is capable of capturing the same trend of strain variations in accordance with the expectation, that in Fig. 388 389 15 the transverse strains were increasing smoothly till the peal load is reached and decreased after that.

390

#### **391** The interaction between torsion and shear loads

The torsion and shear loads are distributed as shear stresses at the element level. Therefore, the presence of any external shear loads directly influences the shear flow  $(q_i)$  of the cross-section. The presence of shear load either increases or decreases the shear flow in the panels depending on its direction of application. The effect of shear load and torsion on shear flow has been quantified through Eq. (5). The developed algorithm has been used for developing these interaction diagrams of torsion and shear. Fig. 16 depicts the validation of predicted interaction with that of the experimental data of specimens tested by Rahal and Collins and Klus. The results predicted by the algorithm are in good agreement with the experimental results.

399

#### 400 Parametric studies using CA-SMM

401 The effect of transverse reinforcement ratio ( $\rho_t$ ), longitudinal reinforcement ratio ( $\rho_t$ ) and concrete strength 402  $(f_{ck})$  on the behavior of specimens are investigated by carrying out a detailed parametric study and shown 403 in Fig. 16. The torsion shear interaction curves are plotted for the Rahal and Collins series 2 specimen by 404 varying the parameters ( $\rho_l$ ,  $\rho_t$  and  $f_{ck}$ ). Torsion (T) and shear (V) interaction curves are presented in Fig. 16. Transverse reinforcement is a key element in resisting the shear loads. Therefore, the increase in 405 406 transverse reinforcement ratio directly increases the torsional capacity of the specimen. The parametric 407 study of varying concrete compressive strength and longitudinal reinforcement ratio for predicting the torsion shear interaction is also presented in Fig. 16. The variation in torsional capacity with respect to the 408 409 variation of longitudinal reinforcement is observed to be marginal and insignificant.

410

#### 411 SUMMARY AND CONCLUSIONS

412 A robust algorithm is used in this study for predicting the behavior of RC members subjected to different combinations of torsion, shear and axial loads. The set of equations of CA-SMM are employed by modeling 413 414 the geometry of section as an assembly of four shear panels. The accuracy in predictions can be improved by increasing the number of panels and by establishing compatibility conditions among the panels, but this 415 occurs at the cost of a significant increase in computation time. Also, the inclusion of bending effects 416 417 (Ewida and McMullen 1981, Rahal 2007) and prestress effects (Karayannis et al. 2000) would also be 418 interesting. The bending effects can be included by altering the longitudinal strain variable in the solution algorithm and is scope for future work. It is also to be noticed that the constitutive laws adopted in the 419 420 model are derived based on 2-dimensional flat panels. Since torsion is a 3-dimensional problem, it causes the walls of the member to warp. However, the constitutive laws for warped 3-dimensional elements are 421 422 not established yet. Currently researchers (Labib et al., 2017) are focusing in the direction to establish the 423 constitutive laws of concrete based on 3-dimensional panels. It is referred to future work that the results can be refined accurately by adopting constitutive laws that are developed based on a 3-dimensional panel. 424 Based on the results presented in this study, the following major conclusions can be drawn: 425

An improved analytical model is proposed for predicting the response of the RC rectangular members
 using softened membrane model at the element level analysis. The predictions from the analytical
 model were in agreement with the experimental results.

429 2. For combined shear and torsional loading, the inclusion of Poisson's effect and strain gradient effect430 resulted in improved torque twist predictions and strain variations in the reinforcement.

3. Transverse reinforcement plays a key role in improving the overall torque – twist performance of RC
members under combined torsion and shear loading. It is observed that the reinforcements in panel 3
(torsion and shear as additive) experienced higher strain levels than the other individual panels.

4. A detailed parametric investigation considering the effect of concrete strength and various steel
reinforcement ratio under combined shear and torsion loading was carried out. Results indicate that the
transverse reinforcement plays a major role in the load resistance when compared to longitudinal
reinforcement ratio and concrete strength under all combinations of torsion and shear loading.

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442

#### 443 Notations:

- 444 *The notations used in the paper are:* 
  - *A<sub>1</sub>* The total cross-section area of longitudinal steel bars
  - $A_t$  The cross-section area of transverse steel bar
  - $A_o$  The core area of the idealized cross-section
  - B Variable as defined in the constitutive relation of steel bar
  - *b* Breadth of the actual cross-section
  - $b_0$  Breadth of the idealised cross-section
  - $E_c$  Modulus of elasticity of concrete
  - $E_s$  Modulus of elasticity of steel

$f_{l,i}, f_{t,i}$	Stress in Longitudinal steel and transverse steel		
$f_{\mathcal{Y}}$	Yield strength of steel bar		
$f_c'$	Cylinder compressive strength of concrete		
$f_{cr}$	Cracking stress of concrete		
$H_i$	A variable to calculate shear flow depth		
h	Depth of the actual cross-section		
$h_o$	Depth of the idealized cross-section		
$K_{2c,i}$	Ratio of average compressive stress to peak compressive stress in concrete struts		
$P_o$	Perimeter of the idealized cross-section		
$q_i$	Shear flow force in $i^{th}$ panel		
$r_0$	Radius or perpendicular distance from centre to centre of shear flow region		
S	Spacing of transverse steel bars		
$T_{x}$	Applied Torsion with respect to X-direction		
$t_{d,i}$	Shear flow depth of $i^{th}$ panel		
$V_y, V_z$	Applied Shear force in Y and Z directions		
$lpha_i$	Cracking angle of $i^{th}$ panel of RC element		
$eta_i$	Deviation angle of $i^{th}$ panel		
$\varepsilon_{l,i},\varepsilon_{t,i}$	Strain along longitudinal and transverse directions		
$\overline{\mathcal{E}_{l,l}}, \overline{\mathcal{E}_{t,l}}$	Smeared uniaxial strain in L and T directions respectively		
$\mathcal{E}_{1,i},\mathcal{E}_{2,i}$	Principle tensile strain and Principle compressive strains		
$\overline{\varepsilon_{2,l}}, \overline{\varepsilon_{1,l}}$	Smeared uniaxial strain in 1 and 2 directions respectively at centre of shear flow zone.		
$\overline{\varepsilon_{2s,l}}, \overline{\varepsilon_{1s,l}}$	Smeared uniaxial strain in 1 and 2 directions respectively at top surface of strut.		
$\gamma_{12,i}$	Shear strain in 1 and 2 coordinate system		
$ ho_l, ho_t$	Ratio of Longitudinal steel and transverse steel		
$\Psi_i$	Curvature of strut		
θ	Twist per unit length of the member		
$\zeta_i$	Softening co-efficient of concrete in compression		
$v_{12}, v_{21}$	Hsu/Zhu ratios		
$\sigma_{l,i}$	Longitudinal Normal stress in $i^{th}$ panel in RC element		

$\sigma_{t,i}$	Transverse Nor	mal stress in	i <sup>th</sup> panel in	RC element
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 $\sigma_{2c,i}, \sigma_{1c,i}$ Smeared Normal stresses on concrete element in directions 1 and 2 $\tau_{lt,i}$ Shear stress in  $i^{th}$  panel in RC element $\tau_{12c,i}$ Smeared Shear stress on concrete element in 1 and 2 coordinate system

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 Structural Journal, 99(5), 631–640.

Details	CA-STM	CA-SMM	
Theory	Rotating angle theory	Fixed angle theory	
Crack Direction	Cracking is assumed along principal coordinate of the concrete element	Cracking is assumed along Principal Coordinates of RC Element	
Poisson's Effect	Not considered	Included in the formulation	
Strain Gradient effect	Considered only for principal compression	Considered for both principal compression and principal tension.	
Post Peak Behavior	Cannot predict accurately	Predictions are better than CA-STM	
Post-Cracking Stiffness	Cannot predict accurately	Predictions are better than CA-STM	
The contribution of Concrete in Shear	Shear stress contribution from the concrete element is not considered.	Shear stress contribution from the concrete element is considered.	
Solution procedure	Iterative trial and error	Optimisation of functional residue (Gradient descent method)	
Computation time	Very large	Significantly less(few seconds)	

#### Table 1: Comparison between CA-STM and CA-SMM

	Rahal-	Rahal-	Greene –	ĸ	Tus		
Specimen ID	Collins	Collins	Box Girder	specimen		Missouri Columns	
	Selles-1	561165-2		Ι	II	Ι	II
Cross-section type	Rectangle	Rectangle	Square	Rectangle	Rectangle	Square	Square
Section dimension (m x m)	0.30 X 0.60	0.34 X 0.64	0.76 X 0.76	0.2 X 0.3	0.2 X 0.3	0.56 X 0.56	0.56 X 0.56
Hollow core area (m x m)	-	-	0.50 X 0.50	-	-	-	-
Effective Column height (m)	1.66	1.66	3.66	1	1	3.35	3.35
Cylinder strength (MPa)	28.4	28.4	45	27	27	34.6	34.5
Long. Reinf. Ratio (%)	1.27	1.27	0.63	1.48	1.48	2.1	2.1
Trans. Reinf. Ratio (%)	0.75	0.75	0.95	0.08	0.08	1.32	1.32
Longitudinal bar yield strength (MPa)	354	354	446	439	439	512	512
Transverse bar Yield strength (MPa)	328	328	446	270	270	454	454
Axial Force (kN)	160	160	0	0	0	0	668
Elastic modulus of steel (MPa)	200000	200000	226000	200000	200000	200000	200000
T/V ratios	1500 mm	1500 mm	0	0	656 mm & 281 mm*	0	0

## Table 1: Specimen Details

\*The presented T/V ratios were that of those used in validation, out of various Klus specimen of Klus 1968.

Parameter/ Specimen ID		n)	Peak twist (degrees)									
	Exp. $(T_{exp})$	CA- STM	CA- SMM (T <sub>calc</sub> )	$T_{exp}/T_{calc}$	Exp. $(\theta_{exp})$	CA- STM	$CA-SMM$ $(\theta_{calc})$	$\left. \theta_{exp} \right _{\theta_{calc}}$				
Missouri specimen												
Series I	330.1	322.6	353.4	0.94	6.3	4.1	7.4	0.85				
Series II	324.9	323.4	357	0.91	6.3	4.1	7.3	0.86				
Rahal and Collins specimen												
Series 1	141.0	114.0	117.5	1.20	4.2	2.4	3.5	1.20				
Series 2	134	145.7	144.8	0.92	2.4	2.2	3.5	0.68				
Greene specimen												
Greene	428.0	402.0	444.0	0.96	1.0	1.0	1.4	0.71				
Klus specimen*												
Series I (Pure Torsion)	14.5	14.0	15.0	0.96	2.0	2.3	2.0	1.00				
Series II (T/V = 656 mm)	12.8	13.5	14.0	0.91	1.8	2	1.9	0.94				
Series II (T/V = 281 mm)	11.8	11.8	11.2	1.05	1.5	1.7	1.2	1.25				

 Table 1: Comparison of Predictions with Experimental Data ( at Peak)

\*The presented T/V ratios were that of those used in validation, out of various Klus specimen of Klus 1968.

Parameter/ Specimen ID		e Torque (K	N-m)	Ultimate twist (degrees)							
	Exp. $(T_{u,exp})$	CA- STM	$\begin{array}{c} \text{CA-SMM} \\ (T_{u,calc}) \end{array}$	$T_{u,exp}/T_{u,calc}$	Exp. $(\theta_{u,exp})$	CA- STM	$CA-SMM$ $(\theta_{u,calc})$	$\theta_{exp} / \theta_{calc}$			
Missouri specimen											
Series I	300.2	294.7	353.0	0.85	9.7	5.4	7.4	1.31			
Series II	295.0	303.0	357.0	0.82	9.7	5.3	7.2	1.34			
Rahal and Collins specimen											
Series 1	131.0	113.0	116.0	1.13	4.9	2.4	4.1	1.19			
Series 2	123.0	145.0	144.0	0.85	4.4	2.5	3.9	1.13			
Greene specimen											
Greene	354.0	394.0	440.0	0.80	1.4	1.5	1.9	0.76			

## Table 1: Comparison of Predictions with Experimental Data (at ultimate)



ho



Figure2



































































































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Dear Editor,

Thank you for reviewing and providing us with the opportunity to revise our manuscript (MS STENG-6964). We appreciate the careful review, complimentary comments, and constructive suggestions to improve our work. We believe that the manuscript is significantly improved by incorporating the suggestions.

Following this letter are the point-by-point response to reviewers' comments, including how and where the text has been modified. The revision has been developed, and each author has approved the final form of this revision. We hope that you find our responses satisfactory and that the manuscript is now acceptable for publication.

Thank you for your consideration.

Sincerely,

S. Suriya Prakash, Ph.D. Associate Professor Department of Civil Engineering Indian Institute of Technology, Hyderabad Sangareddy, Telangana, India Email: <u>suriyap@iith.ac.in</u>

# **Response to Reviewer's Comments**

# Optimization Based Improved Softened Membrane Model for Rectangular Reinforced Concrete Members under Combined Shear and Torsion

# (Manuscript Number: MS STENG-6964)

We are very much thankful to the reviewers for their deep and thorough review. We have revised the manuscript in the light of their useful suggestions and comments. We hope our revision has improved the manuscript to a level of their satisfaction. Number wise answers to their specific comments/suggestions/queries are as follows.

# **Response to Reviewer #1 Comments**

General Comment: The paper entitled "Optimization-Based Improved Softened Membrane Model for Rectangular Reinforced Concrete Members under Combined Shear and Torsion" contains original contribution to the analytical study of Reinforced Concrete (RC) members under predominant torsion. A Combined Actions Softened Membrane Model (CA-SMM) to evaluate the entire behaviour of RC structural members under torsion, shear and axial load is developed and evaluated. The proposed model adopts an interesting optimization technique (namely gradient descent method) to solve the well-known non-linear equations of the SMM. Although there are several versions of the SMM available in the literature that face successfully the problem of torsion certain utility. Validation of the CA-SMM is achieved using comparisons between analytical and experimental torsional moment versus angle of twist curves. Further, an effort to investigate the interaction between shear and torsion using the developed method as a numerical tool for parametric analysis is attempted. The manuscript is well-structured, and the developed model is adequately presented.

**Response:** The authors thank the reviewer for the positive feedback on the submitted work. Reviewers suggestions have been included as explained below:

1. The linear, pre-cracking behavior of the analytical torsional moment versus angle of twist curves illustrated in the diagrams of Fig. 13 presents increased stiffness that is very close to the

experimentally observed one. However, this is not justified since based on the assumptions of the model (see also line 118) "the concrete member is assumed to act as a truss after cracking." Further, it is claimed that (see also lines 330-332) "...the response predicted by the CA-SMM is better in the post-cracking regime and close to the experimental peak values." Additional comments on these issues and proper clarification are required.

**Response:** The authors agree with the reviewer's comment that the apparent truss model should lead to less stiff prediction. However, the assumption that the RC member acts as a truss is valid only after cracking. The pre-cracking behavior is known to be linear. The point corresponding to which cracking occurs is calculated from the expressions given by Collins and Mitchel (1991). The information explaining the same has been added in lines 128-131 (Page 3). As the current work focuses more on the truss model based SMM theory, the equations about cracking are not mentioned explicitly in the draft. Those equations are referred to the below references, and the same discussion has been included in the revised manuscript.

### References added:

- Collins, M.P., and Mitchell, D. (1991)," Prestressed Concrete Structures," Response Publications, Canada.
- Mondal, TG, and Prakash, SS. (2015) "Effect of tension stiffening on the behavior of square RC columns under torsion." Struct. Eng. Mech. J 54.3 (2015): 501-520.

As suggested by the reviewer, more clarifications on the predictions of model and comparisons with the experimental results are provided.

2. The results and the concluding remarks derived from the torsional moment versus longitudinal and transverse strain diagrams presented in Fig. 15 are not adequately discussed. The statement reported in line 352 that "... the model is capable of capturing the trend of strain variations in the section accurately" needs further justification and explanation.

**Response:** The experimental results pertaining to the variation of longitudinal and transverse strains are not available for all the specimens to compare with the analytical predictions. However, the authors wanted to highlight the variation of the strain distribution in the longitudinal and transverse steel to illustrate the capability of the model in calculating the strains at the local level. Depending upon the loading that the panel is subjected to (Pure torsion/ torsion + shear/ torsion – shear), there are four different strains on four different panels, as depicted in Fig. 15. Transverse

steel reinforcement primarily resists loads of torsion and shear. Hence, as expected, the strains will increase smoothly until peak load and decreases after that. As the experimental data is not available, the authors want to depict with the graphs that the model is predicting the strains as expected from physical behavior. The section on "distribution of strains in reinforcement" has been elaborated in the revised manuscript.

**3.** The interaction between torsion and shear and the use of the developed CA-SMM as a numerical tool for parametric analysis is very briefly presented. It is strongly recommended to enrich these sections. The influence of the axial load on the torsional response is also a parameter that could be further examined to provide useful interaction curves. The articles "Torsion-shear-flexure interaction in reinforced concrete members", "Strength of prestressed concrete beams in torsion" and "Combined torsion and bending in reinforced and prestressed concrete beams using simplified method for combined stress-resultants" could help in this direction since they present and discuss the flexure-torsion and shear-torsion interaction curves with and without axial force of RC members.

**Response:** The authors thank the reviewer for the valuable suggestion. All the suggested references are included in the revised manuscript. Major findings from these references are also presented in the revised manuscript.

The key interaction between torsion and shear is due to the change in shear flow (Eq. 5), which depends on the direction of application of the torsion and shear loads. Torsion-shear interaction diagram is shown in Fig. 4 and quantified in equation 5. The current work focuses on the interaction of torsion and shear, and the same has been validated with the available experimental data.

Authors would like to clarify that the developed algorithm considers the effect of the axial load as well. Axial stress is included in the CA-SMM formulation. The interaction between axial stress and the shear stresses occurs at the membrane element level. The presence of axial compression stress increases the capacity of the shear element, and it is reciprocal for axial tensile stress. The same effect will be reflected at member level when the applied loads are torsion or shear. However, including the curvature and flexural effects in the proposed model is scope for further work. Therefore, only the axial load has been included in the algorithm but not the flexure.

4. The concrete confinement in RC members with a short spacing of stirrups has been proved as a parameter of significant influence on the torsional response. Special stress-strain relationships of softened and confined concrete have been proposed for RC members, such columns with high ratio of transverse reinforcement. The Authors are invited to comment this issue.

**Response:** The authors agree with the reviewer that the short spacing of stirrups will have a significant influence on the torsional response due to a possible reduction in softening of the concrete. The confinement of concrete due to the short spacing of stirrups will enhance the torsional performance of RC member. In the current work, the authors have used the close spacing of stirrups only in parametric studies. The transverse reinforcement ratio is increased theoretically, and the predictions are calculated. By keeping the behavior of concrete as a constant help in observing the changes predicted by the model, with the change in the intended parameter, i.e. transverse reinforcement ratio. The authors only want to depict the applicability of the model for parametric study. The confinement effect due to the close spacing of stirrups and its possible effect on the reduction in softening of concrete will be very interesting. More work is needed to understanding the interaction between the confinement and softening effect and is scope for further work.

# Response to Reviewer #2 Comments

*General Comment:* The authors have presented a very detailed, well-written paper on the topic of the Optimization Based Improved Softened Membrane Model for Rectangular Reinforced Concrete Members under Combined Shear and Torsion.

**Response:** The authors would like to thank the reviewer for his appreciation.

1. The reviewer observes the analytical model results deviation from the experimental results in the non-elastic region of the load curve. Please explain the possible reasons more elaborately.

**Response:** The authors agree with the reviewer that the predictions of the model deviate somewhat from the experimental results in the post-peak region. There are various assumptions involved in the model as follows:

- 1. "Section is modeled as an assembly of four cracked shear panels". This assumption is essential to distribute the external loads among the shear panels. Though the actual stress state is very complex and the stress is distributed across the cross-section, the above assumption reduces the overall stress state into four different stress states (one stress state on each panel). The predictions can be refined more accurately by modeling the cross section using more number of panels and by establishing the compatibility conditions among the panels. However, this incurs a significant increase of computational time, and development of sophistical computational tools would be interesting and is scope for future work.
- 2. Torsion is modeled using Bredt's thin tube theory. According to which, the externally applied torsion is resisted by the shear flow stresses developed in the region of shear flow depth 't<sub>d</sub>' and also the stress is assumed to be uniform across the depth. The actual stress state due to torsion is very complicated for rectangular cross-sections. The results can be refined more accurately by including the exact stress state that occurs due to torsion which is very complicated and has not been established precisely for RC members. The authors here, have used the Bredt's thin tube theory which is the current state of the art concerning the truss models for modeling torsional effects in RC section.

The predictions of the proposed model are reasonably accurate considering the various assumptions and interactions among the parameters (i.e., sectional details, loading levels, spalling). Future work should focus on more refined predictions. The above discussion is included in the revised draft under the sections "Bredt's thin tube theory" and "Summary and conclusions."

## **Response to Reviewer #3 Comments**

The authors thank the reviewer for his detailed review and suggestions. His comments were all included as discussed below:

1. Page 2, Line 4: Omitted work by Onsongo for RC columns, although his paper is listed in the references (note column in the title).

**Response:** The additional reference is included as suggested by the reviewer.

2. Page 2, Line 50: Omitted work by Greene and Belarbi, although their specimen is used in the analysis included in the paper.

**Response:** The additional reference is included as suggested by the reviewer.

3. Page 3, Line 67-70: The paper incorrectly states that the SMMT which has a 2016 reference was the basis ("also extended") for models that were developed before 2016 and published in 2009. This is not possible.

**Response:** It is a typo. The authors only mean that the SMMT has been extended for various crosssectional shapes and applications that include box girders, circular sections and FRP strengthened specimen. The phrases that created confusion in the timeline has been rephrased in the same section as mentioned below:

"SMM based torsional model was extended to other geometries, and strengthening configuration like box girders (Greene and Belarbi 2009), hollow RC members (Jeng and Hsu 2009), and rectangular sections strengthened with fiber reinforced polymer (FRP) composites (Ganganagoudar et al. 2016) under pure torsion. Ganganagoudar et al. (2016) have also extended the SMM based model for torsion (SMMT) for circular RC beams and validated with the experimental test results."

4. Page 3, Line 84: Bidirectional stress effects used here, but not adequately defined until page 3, line 103. Without a definition, the term is ambiguous and could mean a number of things.
Response: The authors have introduced the Poisson effect and bi-directional stress states at their first usage in the revised draft, at lines 62-65.

5. Page 5, Line 137 to 140: these four equations have been in at least one of the references cited in this paper. Reference should be given to the source.

**Response:** Included as suggested. The work of Greene and Belarbi 2009 has been referred in this context.

6. Page 6, Line 162 to 165: these four equations have been in at least one of the references cited for this paper. Reference should be given to the source.

**Response:** Included as suggested. The works of Greene and Belarbi 2009, Rahal and Collins 1995 have been referred in this context.

7. Page 7, Line 181 to 184: these four equations have been in at least one of the references cited in this paper. Reference should be given to the source.

Response: Included as suggested. The work Hsu and Zhu 2002 has been referred in this context.

8. Page 8, Line 191 and 194: Solving equation 11 into equation 12a would result in td,i equal to negative td,i. Please explain.

**Response:** The equation is corrected in the revised draft as given below. The shear flow depth 'td' is always positive. Compression strains are taken as negative in the current analysis, therefore negative of negative number gives a positive value for 'td'.

$$\Psi_i = \frac{-\overline{\varepsilon_{2s,i}}}{t_{d,i}} \tag{11}$$

$$t_{d,i} = \frac{-\overline{\varepsilon_{2S,l}}}{\psi_i} \left( \le \frac{b_o}{2} \right)$$
(12a)

9. Page 8, Line 192: Equations are given to determine td. One of the specimens used in the comparison is hollow. None of the equations appear to limit the value of td to the actual wall thickness. The calculated td could be greater than the wall thickness at low torque (and small curvature).

**Response:** The authors agree with the reviewer. The shear flow depth  $t_d$  is limited to the actual wall thickness of the specimen. The same information has been added in the revised draft by editing Eq. (12a)

$$t_{d,i} = \frac{-\overline{\varepsilon_{2s,i}}}{\psi_i} \left( \le \frac{b_0}{2} \right)$$
(12a)

The following phrase has also been added: "The calculated shear flow depth  $t_{d,i}$  should be limited to the thickness of walthe l in the case of the hollow specimen and should be limited to half of the depth of the idealized cross-section  $\left(\frac{b_0}{2}\right)$  in the case of solid cross-sections" (lines 207-209) in the revised draft.

10. Page 8, Line 205 to 209: the constituent laws for concrete in compression used in this paper were developed for flat panels. No justification is given in this paper for how the empirical relationships developed for flat panels are appropriate for the warping walls of a member under torsion.

**Response:** The authors agree with the reviewer that the constitutive laws used in this work are developed based on test results of flat panels which are 2D elements. Torsion is a 3-dimension problem.. The evaluation of constitutive laws for a 3-dimension panel is currently investigated by a very recent publication of researcher Labib et al. 2017 (referred in the revised draft). These constitutive laws for compression and tension based on a warped 3-dimension panel, Poisson effect on these 3-D panels and their application for torsion are not fully established yet. Understanding these aspects are highlighted as scope for future work. The same limitation as pointed out by the reviewer is added in the revised draft (lines 422-427).

**Reference added:** Labib, Moheb, Yashar Moslehy, and Ashraf Ayoub. (2017). "Softening coefficient of reinforced concrete elements subjected to three-dimensional loads." *Magazine of Concrete Research.* 

11. Page 9, Line 216 to 217: the constituent laws for concrete in tension used in this paper were developed for flat panels. No justification is given in this paper for how the empirical relationships developed for flat panels are appropriate for the warping walls of a member under torsion.

**Response:** The authors agree with the reviewer that the constitutive laws used in this model are developed based on flat panels which are 2D elements. Torsion is a 3-dimension problem. The same limitation as pointed out by reviewer has been added in the revised draft (lines 422-427).

**Reference added:** Labib, M, Moslehy, Y and Ayoub A. (2017). "Softening coefficient of reinforced concrete elements subjected to three-dimensional loads". *Magazine of Concrete Research.* 

12. Page 9, Line 226 to 229: these four equations have been in at least one of the references cited in this paper. Reference should be given to the source.

**Response:** Included as suggested. The previous works of Jeng 2009, and Ganagnagoudar et al. 2016 have been referred in this context.

**13.** Page 10, Line 237 to 242: the Poisson effect used in this paper were developed for flat panels. No justification is given in this paper for how the empirical relationships developed for flat panels are appropriate for the warping walls of a member under torsion.

**Response:** Limitations and justification are highlighted in the revised manuscript.

**Reference added**: Labib, M, Moslehy, Y and Ayoub A. (2017). "Softening coefficient of reinforced concrete elements subjected to three-dimensional loads". *Magazine of Concrete Research*.

14. Page 11, Line 271: It states that the principal compressive strain in panel 1 is varied from zero to failure. Equation 5a shows that the shear flows are additive in panel 1. But according to conclusion 3, shear stress is additive in panel 3. Also, figure 15 shows that the strains are largest in panel 3. Which panel has the additive shear flows? If panel one does not have the additive shear flow, it may never reach large compressive strains, so how can the compressive strains be varied for this panel? Please explain.

**Response:** The shear flow is uniform in all the panels when only torsion is applied. The shear flow due to external shear loads is added/subtracted to the existing shear flow depending upon the direction of external shear load (as depicted in Fig. 4 of the draft). The authors agree with the reviewer that the panel no. 1 will never reach large compressive strain if it does not have additive shear flow. At the same time, it has to be noted that the section failure will be governed by the compressive strain in the panel 3 in which shear flow is additive. The analysis will stop as soon as

compressive strain reaches its failure limit in any one of the four panels. In the present discussion, it is panel-3, in which shear flows are additive.

**15.** *Page 13, Line 304: no explanation is given for how the equivalent longitudinal and transverse reinforcement in each panel was determined.* 

**Response:** The following information has been added to the revised draft, in the section "Idealization of Cross-section":

"The longitudinal and transverse reinforcement in the section also has to be distributed among the shear panels. If the sections are symmetrical regarding reinforcement, then longitudinal steel and transverse steel is distributed equally among all the shear panels. The transverse reinforcement is distributed equally among all the shear panels as it is symmetric for all the specimens adopted in the current study. The longitudinal steel area is assigned to that shear panel in which the longitudinal bar is located. In the cases of overlap of steel area between two shear panels, it is distributed as a function of the width of the shear panels that are overlapping. A detailed account of the distribution of longitudinal reinforcement can be in the work of Greene and Belarbi (2009)."

16. Page 13, Line 313 to 321: This list only shows the Missouri 2 specimen as having axial force. In Table 2, Rahal- Collins 1 and Rahal- Collins 2 also have an axial force given. Which one is correct?

**Response:** The list of lines 336-339 has been corrected to avoid the mismatch of information.

17. Page 13, Line 313 to 321: If axial force is included for columns, does the model account for spalling of the cover?

**Response:** No. Spalling of concrete cover is not considered in the present work. In the present model, the cover concrete area has also been included in all the calculations of torsion, shear and also axial loads. The authors agree that the spalling phenomenon occurs when axial loads are

present. The interaction of torsional, shear and axial loading on the spalling of concrete cover is not in the gambit of the present work. It is the scope of future work.

18. Page 13, Line 326: 1) the grammar in this sentence is confusing. 2) assuming a comparison is being made between two models: the comparison is purely qualitative. Just looking at the figures 14 a through e, the CASTM is much closer to experimental data than the proposed CASMM. So the validity of your statement is questionable. Instead, the comparison should be quantified or deleted.

**Response:** The comparisons are quantified in Tables 3 and 4. There are instances in which the predictions of CASMM are better than CASTM and vice versa. The ambiguous nature of the sentence is addressed by rephrasing the sentence in the revised draft as given below:

"The peak torque and the corresponding twist are captured reasonably well by the CA-SMM. The proposed model predicted the peak torque and twist more accurately for the specimen of Missouri, Rahal and Collins while the results of CA-STM are close to experimental peak values of Greene's and Klus specimen. However, it can be observed from the Table 3 that the predictions in the peak torque and peak twist predictions of CASTM and CASMM are similar."

**19.** Page 14, Line 331: Comparison of models based on peak values is also qualitative. Looking at the figures 14 this statement is questionable. The comparison should be quantitative or deleted.

**Response:** The comparisons are quantified in Tables 3 and 4. There are instances in which the predictions of CASMM are better than CASTM and even vice versa. The ambiguous nature of the sentence is addressed by rephrasing the sentence in the revised draft as given below:

"The peak torque and the corresponding twist are captured reasonably well by the CA-SMM. The proposed model predicted the peak torque and twist more accurately for the specimen of Missouri, Rahal and Collins while the results of CA-STM are close to experimental peak values of Greene's and Klus specimen. However, it can be observed from the table 3 that the predictions in the peak torque and peak twist predictions of CASTM and CASMM are very close."

**20.** Page 14, Line 338: Reference is made to figures 14 and 15. It is unclear whether the values shown in the figures are experimental or model predictions. It is unclear how it is useful to show only the

experimental or model predictions of strain. Both need to be shown together to evaluate the adequacy of the proposed model.

**Response:** The figures depict the predictions of the model. The experimental data of strains is not available in the literature. The authors presented the predicted strains to depict that the improved model is capable of capturing the behavior at the local level as well. Due to unavailability of experimental data, the predictions are not sufficed with experimental validation. The same information and the limitation are explained elaborately in the revised draft.

**21.** Page 14, Line 352: Statement is made, "the model is capable of capturing the trend of strain variations in the section accurately." The figures 14 and 15 that are the basis for this statement do not show a comparison of experimental and prediction strain. It is unclear what the trend of strain variation is. How can you claim the model accurately predicts something without showing a comparison?

**Response:** The experimental results pertaining to the longitudinal and transverse strains are not available in the literature, due to which the comparison could not be presented. The authors want to present the strain distribution in the longitudinal and transverse steel to depict that the model is capable of calculating strains at the local level also. Depending upon the loading to which the panel is subjected to (Pure torsion/ torsion + shear/ torsion – shear), there are four different strains on four different panels, as depicted in fig. 15. Transverse steel reinforcement primarily resists loads of torsion and shear. Therefore, it is expected that the strains will increase smoothly until peak load and decreases after that. As the experimental data is not available, the authors want to depict from the graphs that the model is predicting the strains by the expected trend. The corresponding section "distribution of strains in reinforcement" has been elaborated to include the above details. The authors hope that the discussion is valid and adds value to the manuscript.

22. Page 15, Line 373: Figure 16 does not show a variation in compressive strength or longitudinal reinforcement as stated in the text

**Response:** The phrase is edited as given below. Fig. 16 depicts the parametric study of variation of concrete compressive strength, transverse and longitudinal reinforcements ratios. The authors

want to depict the same that the model can be adopted for parametric study also and the same results are presented in fig. 16.

"The parametric study of varying concrete compressive strength and longitudinal reinforcement ratio for predicting the torsion shear interaction is also presented in Fig. 16."

23. Page 16, Line 389: Conclusion number 3 was not directly discussed in the body of the paper. Not sure that the figures in this analytical study really demonstrated this conclusion as currently written.

**Response:** Conclusion 3 is drawn from the analysis of strains presented in Fig. 16. The transverse strains are more in the panels in which shear stresses due to shear and torsion are additive. Therefore, the conclusion is made that the transverse reinforcement plays a key role in improving the torque-twist behaviour for members under combined loading of torsion and shear. The conclusion could be strongly established if the results are sufficed with the experimental validation.

24. Page 25, Fig 6: this image was taken from another source and should be referenced

**Response:** The figure is modified for a rectangular cross-section to suit the type of section investigated in this work. Relevant references to highlight the behavior are included in the text.

25. Page 25, Fig 7: this image was taken from another source and should be referenced.

**Response:** Fig. 7 has been adapted by the authors based on the previous work of Jeng 2009 and Ganganagoudar et al. 2016. References are included in the revised manuscript.

*26.* Page 31, Fig 16: Rahal Collins series 2 was a single specimen in table 2, 3, and 4. In figure 16, one specimen is shown as an interaction curve of four points. Not sure how this is possible.

**Response:** The specimen is same as in table 2,3 and 4. The interaction points are calculated for different T/V ratios. For Rahal Collins specimen, the results are compared with Experimental data available for T/V ratio of 1500mm.

27. Page 31, Fig 16: Klus specimen was shown as two specimens in table 2, three specimens in table 3, and excluded from table 4. These two or three specimens became 8 points on an interaction curve in figure 16. Not sure how this is possible.

**Response:** In total, Klus has conducted tests on eight specimens, which fall under different T/V ratios. Only a few of them were validated by the authors, and the validated ones were included in the Tables 2 &3. Only three specimens are used in both the tables 2 and 3 (one under pure torsion and two other specimens of 2 different T/V ratios). In Table 4, the test data related to post-peak failure is not available for the Klus specimen and therefore it is omitted. However, all the experimental data of Klus's specimen (eight of them) for different T/V ratios are used in the validation of T-V interaction diagram (Figure 16). A note has been added to the Table 2 and 3 to convey the same information.

The manuscript has been resubmitted to your journal. We look forward to your positive response.

Sincerely,

Dr. S. Suriya Prakash.