# On 3-dimensional asymptotically harmonic manifolds 

Viktor Schroeder* and Hemangi Shah ${ }^{\dagger}$


#### Abstract

Let $(M, g)$ be a complete, simply connected Riemannian manifold of dimension 3 without conjugate points. We show that $M$ is a hyperbolic manifold of constant sectional curvature $\frac{-h^{2}}{4}$, provided $M$ is asymptotically harmonic of constant $h>0$.

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1. Introduction. Let $(M, g)$ be a complete, simply connected Riemannian manifold without conjugate points. Let $S M$ be the unit tangent bundle of $M$. For $v \in$ $S M$, let $\gamma_{v}$ be the geodesic with $\gamma_{v}^{\prime}(0)=v$ and $b_{v, t}(x)=\lim _{t \rightarrow \infty}\left(d\left(x, \gamma_{v}(t)\right)-t\right)$ the corresponding Busemann function for $\gamma_{v}$. The level sets $b_{v}{ }^{-1}(t)$ are called horospheres.

A complete, simply connected Riemannian manifold without conjugate points is called asymptotically harmonic if the mean curvature of its horospheres is a universal constant, that is if its Busemann functions satisfy $\Delta b_{v} \equiv h, \forall v \in S M$, where $h$ is a nonnegative constant. Then $b_{v}$ is a smooth function on $M$ for all $v$ and all horospheres of $M$ are smooth, simply connected hypersurfaces in $M$ with constant mean curvature $h$.

For example, every simply connected, complete harmonic manifold without conjugate points is asymptotically harmonic.

For more details on this subject we refer to the discussion and to the references in [2]. Important result in this context are contained in [1], [3]. In [2] the following result was proved:

[^0]Let $M$ be a Hadamard manifold of dimension 3 whose sectional curvatures are bounded from above by a negative constant (i.e. $K \leq-a^{2}$ for some $a \neq 0$ ) and whose curvature tensor satisfies $\|\nabla R\| \leq C$ for a suitable constant $C$. If $M$ is asymptotically harmonic, then $M$ is symmetric and hence of constant sectional curvature.

We prove this result without any hypothesis on the curvature tensor.
Theorem 1.1. Let $(M, g)$ be a complete, simply connected Riemannian manifold of dimension 3 without conjugate points. If $M$ is asymptotically harmonic of constant $h>0$, then $M$ is a manifold of constant sectional curvature $\frac{-h^{2}}{4}$.
2. Proof of the Theorem. The first part of the proof (Lemma 2.1 to Lemma 2.3) is a modification of the results in [2]. Therefore we recall some notations which were already used in that paper. Our general assumption is that $M$ is 3 -dimensional, has no conjugate points and is asymptotically harmonic with constant $h>0$. For $v \in S M$ and $x \in v^{\perp}$, let

$$
u^{+}(v)(x)=\nabla_{x} \nabla b_{-v} \quad \text { and } \quad u^{-}(v)(x)=-\nabla_{x} \nabla b_{v} .
$$

Thus $u^{ \pm}(v) \in$ End $\left(v^{\perp}\right)$. With $\lambda_{1}(v), \lambda_{2}(v)$ we denote the eigenvalues of $u^{+}(v)$. The endomorphism fields $u^{ \pm}$satisfy the Riccati equation along the orbits of the geodesic flow $\varphi^{t}: S M \rightarrow S M$.

Thus if $u^{ \pm}(t):=u^{ \pm}\left(\varphi^{t} v\right)$ and $R(t):=R\left(\cdot, \gamma_{v}^{\prime}(t)\right) \gamma_{v}^{\prime}(t) \in \operatorname{End}\left(\gamma_{v}^{\prime}(t)^{\perp}\right)$, then

$$
\left(u^{ \pm}\right)^{\prime}+\left(u^{ \pm}\right)^{2}+R=0
$$

We define $V(v)=u^{+}(v)-u^{-}(v)$ and correspondingly $V(t)=V\left(\varphi^{t}(v)\right)$ along $\gamma_{v}(t)$. We also define $X(v)=\frac{-1}{2}\left(u^{+}(v)+u^{-}(v)\right)$ and $X(t)=X\left(\varphi^{t}(v)\right)$. Then the Riccati equation for $u^{ \pm}(t)$ yields

$$
\begin{equation*}
X V+V X=\left(u^{-}\right)^{2}-\left(u^{+}\right)^{2}=\left(u^{+}\right)^{\prime}-\left(u^{-}\right)^{\prime}=V^{\prime} \tag{1}
\end{equation*}
$$

Lemma 2.1. For fixed $v \in S M$ the map $t \mapsto \operatorname{det} V\left(\varphi^{t} v\right)$ is constant.
Proof. Assume that $V(t)$ is invertible, then

$$
\frac{d}{d t} \log \operatorname{det} V(t)=\operatorname{tr} V^{\prime}(t) V^{-1}(t)=\operatorname{tr}(X V+V X) V^{-1}(t)=2 \operatorname{tr} X=0
$$

The last step follows as $M$ is asymptotically harmonic. Thus as long as $\operatorname{det} V(t) \neq$ 0 , it is constant along $\gamma_{v}$. Therefore det $V(t)$ is constant along $\gamma_{v}$ in any case.
Lemma 2.2. Let $v \in S M$ be such that $V(v)=\mu \mathrm{Id}$, for some $\mu \in \mathbb{R}$, then $R(t)=$ $\frac{-h^{2}}{4} \mathrm{Id}, \forall t$.

Proof. Note that if $V(v)=\mu \mathrm{Id}$, then $V\left(\gamma_{v}^{\prime}(t)\right)=h$ Id for all $t$, as $\operatorname{tr} V \equiv 2 h$ and by Lemma 2.1 the determinant of $V$ is constant along $\gamma_{v}(t)$. Now by equation (1) $V^{\prime}=X V+V X$. Hence, along $\gamma_{v}, V^{\prime}(t) \equiv 0$. Thus $2 h X=0$ and since we assume $h>0$ we have $X=0$ along $\gamma_{v}$. Therefore, $u^{+}(t)=-u^{-}(t)$. But from the
definition of $V, u^{+}(t) \equiv \frac{h}{2}$ Id i.e $u^{+}$is a scalar operator. By the Riccati equation $\left(u^{+}(t)\right)^{2}+R(t)=0$, i.e. $R(t)=\frac{-h^{2}}{4}$ Id.
Lemma 2.3. For every point $p \in M$ there exists $v \in S_{p} M$ such that $R(x, v) v=$ $\frac{-h^{2}}{4} x, \forall x \in v^{\perp}$. In particular, $\operatorname{Ric}(v, v)=\frac{-h^{2}}{2}$.

Proof. Since $T S^{2}$ is nontrivial, an easy topological argument shows, that for every $p \in M$ there exists $v \in S_{p} M$ such that the two eigenvalues of $V(v)$ coincide. Thus $V(v)=\mu \mathrm{Id}$. The result now follows from Lemma 2.2.
Lemma 2.4. For all $v \in S M$ we have $\operatorname{Ric}(v, v) \leq \frac{-h^{2}}{2}$.
Proof. The Riccati equation for $t \mapsto u^{+}(t)$ implies $\left(u^{+}\right)^{\prime}+\left(u^{+}\right)^{2}+R=0$. Hence, $\operatorname{tr}\left(u^{+}\right)^{2}+\operatorname{tr} R=0$. Thus, $\operatorname{Ric}(v, v)=-\left(\lambda_{1}{ }^{2}(v)+\lambda_{2}{ }^{2}(v)\right)$. By hypothesis $\lambda_{1}(v)+$ $\lambda_{2}(v)=h$, hence $\lambda_{1}{ }^{2}(v)+\lambda_{2}{ }^{2}(v) \geq \frac{h^{2}}{2}$. Consequently, $\operatorname{Ric}(v, v) \leq \frac{-h^{2}}{2}$.
Lemma 2.5. The sectional curvature $K$ of $M$ satisfies $K \leq-\frac{h^{2}}{4}$.
Proof. Let $p \in M$, and let $v$ be the vector in Lemma 2.3. Take $e_{1}=v$, and let $e_{2}$ and $e_{3}$ be unit vectors orthogonal to $e_{1}$ so that $\left\{e_{1}, e_{2}, e_{3}\right\}$ forms an orthonormal basis of $T_{p} M$. Then $\left\{e_{1} \wedge e_{2}, e_{1} \wedge e_{3}, e_{2} \wedge e_{3}\right\}$ forms an orthonormal basis of $\Lambda^{2} T_{p} M$. We want to show that the curvature operator, considered as map $R: \Lambda^{2} T_{p} M \rightarrow$ $\Lambda^{2} T_{p} M,\langle R(X \wedge Y), V \wedge W\rangle=\langle R(X, Y) W, V\rangle$ is diagonal in this basis.

From Lemma 2.3 we see $R\left(e_{2}, e_{1}\right) e_{1}=\frac{-h^{2}}{4} e_{2}, \quad R\left(e_{3}, e_{1}\right) e_{1}=\frac{-h^{2}}{4} e_{3}$. Thus $K\left(e_{1}, e_{2}\right)=K\left(e_{1}, e_{3}\right)=\frac{-h^{2}}{4}$ and $K\left(e_{2}, e_{3}\right) \leq \frac{-h^{2}}{4}$ as $\operatorname{Ric}\left(e_{3}, e_{3}\right) \leq \frac{-h^{2}}{2}$, where $K(v, w)$ denotes the sectional curvature of the plane spanned by $v$ and $w$. We will prove below that

$$
\begin{equation*}
\left\langle R\left(e_{1}, e_{3}\right) e_{3}, e_{2}\right\rangle=0 \text { and }\left\langle R\left(e_{1}, e_{2}\right) e_{2}, e_{3}\right\rangle=0 \tag{2}
\end{equation*}
$$

Assuming this for a moment, it follows that $R\left(e_{1} \wedge e_{3}\right) \perp \operatorname{span}\left\{e_{1} \wedge e_{2}, e_{2} \wedge e_{3}\right\}$ and $R\left(e_{1} \wedge e_{2}\right) \perp \operatorname{span}\left\{e_{1} \wedge e_{3}, e_{2} \wedge e_{3}\right\}$. Hence,

$$
R\left(e_{1} \wedge e_{2}\right)=\frac{-h^{2}}{4} e_{1} \wedge e_{2} \text { and } R\left(e_{1} \wedge e_{3}\right)=\frac{-h^{2}}{4} e_{1} \wedge e_{3}
$$

Since $e_{1} \wedge e_{2}$ and $e_{1} \wedge e_{3}$ are eigenvectors of $R$, also $e_{2} \wedge e_{3}$ is an eigenvector and we obtain

$$
R\left(e_{2} \wedge e_{3}\right)=K\left(e_{2}, e_{3}\right) e_{2} \wedge e_{3}
$$

Thus the curvature operator is diagonal in the basis $\left\{e_{1} \wedge e_{2}, e_{1} \wedge e_{3}, e_{2} \wedge e_{3}\right\}$ and all eigenvalues are $\leq \frac{-h^{2}}{4}$, which proves the result.

It remains to show (2). Consider for $t \in(-\varepsilon, \varepsilon)$ the vectors $v_{t}=\cos t e_{1}+\sin t e_{2}$. Then,

$$
\begin{array}{r}
f(t):=\operatorname{Ric}\left(v_{t}, v_{t}\right)=K\left(v_{t}, e_{3}\right)+K\left(v_{t},-e_{1} \sin t+e_{2} \cos t\right) \\
=K\left(e_{1}, e_{2}\right)+\sin ^{2} t K\left(e_{2}, e_{3}\right)+\cos ^{2} t K\left(e_{1}, e_{3}\right)+\sin 2 t\left\langle R\left(e_{1}, e_{3}\right) e_{3}, e_{2}\right\rangle .
\end{array}
$$

By Lemma $2.4 f(0)=\operatorname{Ric}(v, v)=\frac{-h^{2}}{2}$ is maximal and hence $f^{\prime}(0)=0$. This implies the first equation in (2). If we replace $e_{2}$ by $e_{3}$ in the above computation we obtain the second equation.

Finally we come to the
Proof of Theorem 1.1. Lemma 2.5 implies that $K_{M} \leq \frac{-h^{2}}{4}$. By standard comparison geometry we obtain $\lambda_{1}(v) \geq \frac{h}{2}$ and $\lambda_{2}(v) \geq \frac{h}{2}$. Now $\lambda_{1}+\lambda_{2}=h$ implies that $\lambda_{1}=\lambda_{2}=\frac{h}{2}$. Hence, $u^{+}(v)$ is a scalar operator and therefore $R(x, v) v=\frac{-h^{2}}{4} x, \forall v$ and $\forall x \in v^{\perp}$. Thus, $K_{M} \equiv \frac{-h^{2}}{4}$.
3. Final Remark. We expect that the result holds also in the case $h=0$, i.e. if all horospheres are minimal. Our argument, however, uses $h>0$ essentially in the proof of Lemma 2.2.

## References

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Viktor Schroeder, Institut für Mathematik, Universität Zürich, Winterthurerstrasse 190, CH-8057 Zürich.
e-mail: vschroed@math.unizh.ch
Hemangi Shah, School of Mathematics, Tata Institute of Fundamental Research Dr. Homi Bhabha Road, Mumbai - 400005, India.
e-mail: hema@math.tifr.res.in

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