# Schwarz operators of minimal surfaces spanning polygonal boundary curves 

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#### Abstract

$\underline{\text { Abstract }}$ This paper examines the Schwarz operator $A$ and its relatives $\dot{A}, \bar{A}$ and $\overline{\dot{A}}$ that are assigned to a minimal surface $X$ which maps consequtive arcs of the boundary of its parameter domain onto the straight lines which are determined by pairs $P_{j}, P_{j+1}$ of two adjacent vertices of some simple closed polygon $\Gamma \subset \mathbb{R}^{3}$. In this case $X$ possesses singularities in those boundary points which are mapped onto the vertices of the polygon $\Gamma$. Nevertheless it is shown that $A$ and its closure $\bar{A}$ have essentially the same properties as the Schwarz operator assigned to a minimal surface which spans a smooth boundary contour. This result is used by the author to prove in [Jakob, Finiteness of the set of solutions of Plateau's problem for polygonal boundary curves. I.H.P. Analyse Non-lineaire (in press)] the finiteness of the number of immersed stable minimal surfaces which span an extreme simple closed polygon $\Gamma$, and in [Jakob, Local boundedness of the set of solutions of Plateau's problem for polygonal boundary curves (in press)] even the local boundedness of this number under sufficiently small perturbations of $\Gamma$.


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## 1 Introduction and main results

This paper is concerned with the Schwarz operator

$$
\begin{equation*}
A \equiv A^{X}:=-\triangle+2 K E \tag{1}
\end{equation*}
$$

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for a minimal surface $X$ which maps consequtive arcs of the boundary of its parameter domain onto the straight lines that are determined by pairs $P_{j}, P_{j+1}$ of two adjacent vertices of an arbitrarily fixed simple closed polygon $\Gamma \subset \mathbb{R}^{3}$ with $N+3$ vertices. Such a surface is given by a continuous $H^{1,2}$-mapping $X: \bar{B} \longrightarrow \mathbb{R}^{3}$ of the closure of the unit disc $B:=\left\{w=(u, v) \in \mathbb{R}^{2}| | w \mid<1\right\}$ into $\mathbb{R}^{3}$ which is harmonic on $B$, satisfies

$$
\begin{equation*}
\left|X_{u}\right|=\left|X_{v}\right|, \quad\left\langle X_{u}, X_{v}\right\rangle=0 \quad \text { on } B \tag{2}
\end{equation*}
$$

and meets the boundary conditions $X\left(e^{i \theta}\right) \in \Gamma_{j}$ for $\theta \in\left[\tau_{j}, \tau_{j+1}\right], j=1, \ldots, N+3$, where $\Gamma_{j}$ denotes the line $\left\{P_{j}+t\left(P_{j+1}-P_{j}\right) \mid t \in \mathbb{R}\right\}$ and where the $\tau_{j}$ are consequtive angles in $(0,2 \pi]$. We denote by $\tilde{\mathcal{M}}(\Gamma)$ the set of such surfaces. Furthermore $K$ in (1) is the Gauss curvature of $X$ and $E:=\left|X_{u}\right|^{2}$. For minimal surfaces $X$ bounded by some smooth contour $\Gamma$ the behaviour of $A^{X}$ is well known. The aim of this paper is to show that $A^{X}$ respectively its closure $\overline{A^{X}}$ have essentially the same properties for minimal surfaces $X$ with those "overshooting", piecewise linear boundary values, as explained above. The author is using this result in $[7,8]$ for his proof of the boundedness of the number of immersed stable minimal surfaces spanning a simple closed polygon which is contained in a sufficiently small neighborhood of any fixed extreme simple closed polygon. The difficulty in studying $A^{X}$ for a minimal surface $X$ with overshooting, piecewise linear boundary constraints is caused by the fact that $X$ is "singular" at the boundary points $e^{i \tau_{j}}$ which are mapped onto the corners $P_{j}$ of $\Gamma$. Consequently the perturbing term $K E$ of $A^{X}$ is only of class $L^{p}(B)$ for some $p>1$ on account of estimate (5) below. For some fixed $X \in \tilde{\mathcal{M}}(\Gamma)$ we shall consider $A \equiv A^{X}$ on

$$
\operatorname{Domain}(A):=\left\{\varphi \in C^{2}(B) \cap \dot{H}^{1,2}(B) \mid A(\varphi) \in L^{2}(B)\right\} .
$$

By $\dot{A}$ and $\dot{\triangle}$ we denote the minimal Schwarz and minimal Laplace operator on the domain $H^{2,2}(B) \cap C_{0}^{2}(B)$, respectively, where we set

$$
C_{0}^{2}(B):=\left\{\varphi \in C^{2}(B) \cap C^{0}(\bar{B})|\varphi|_{\partial B} \equiv 0\right\} .
$$

Furthermore let $\bar{A}, \bar{A}$ and $\bar{\triangle}$ denote the $L^{2}(B)$-closures of $A, \dot{A}$ and $\dot{\triangle}$, respectively. Finally we consider the assigned quadratic form

$$
J(\varphi) \equiv J^{X}(\varphi):=\int_{B}|\nabla \varphi|^{2}+2 K E \varphi^{2} \mathrm{~d} w
$$

which is defined for any $\varphi \in \stackrel{\circ}{H}^{1,2}(B)$ due to $K E \in L^{p}(B)$ for some $p>1$. To study the spectra of $A$ and $\bar{A}$ we investigate $J$ on the function space

$$
S \dot{H}^{1,2}(B):=\left\{\varphi \in \dot{H}^{1,2}(B)\|\varphi\|_{L^{2}(B)}=1\right\} .
$$

Similarly we denote by $S\left(H^{2,2}(B) \cap H^{1,2}(B)\right)$ and $S \operatorname{Dom}(A)$ the intersections of the " $L^{2}(B)$-sphere" with the respective function spaces. Then we shall prove

Theorem 1 (i) The spectra of $A$ and $\bar{A}$ coincide. They are discrete and accumulate only at $\infty$; thus their eigenspaces are finite dimensional. Furthermore for their common smallest eigenvalue $\lambda_{\min }:=\lambda_{\min }(A)=\lambda_{\min }(\bar{A})$ we have

$$
\begin{equation*}
\lambda_{\text {min }}=\inf _{S \operatorname{Dom}(A)} J=\inf _{S \hat{H}^{1,2}(B)} J=\inf _{S\left(H^{2,2}(B) \cap H^{1,2}(B)\right)} J \tag{3}
\end{equation*}
$$

(ii) For an eigenfunction $\varphi^{*}$ in the eigenspace $\mathrm{ES}_{\lambda_{\text {min }}}(\bar{A})$ there holds $\left|\varphi^{*}\right|>0$ on $B$, whence:

$$
\begin{equation*}
\operatorname{dim} \mathrm{ES}_{\lambda_{\min }}(\bar{A})=\operatorname{dim} \mathrm{ES}_{\lambda_{\min }}(A)=1 \tag{4}
\end{equation*}
$$

Especially an eigenfunction $\varphi^{*} \in \mathrm{ES}_{\lambda_{\text {min }}}(A)$ satisfies $\left|\varphi^{*}\right|>0 \quad$ on $B$.
To prove this theorem we need some of Heinz' results (see [3,4]) about minimal surfaces with overshooting, piecewise linear boundary values. To this end we need some definitions:
Let $\Gamma$ be some simple closed polygon in $\mathbb{R}^{3}$ with $N+3$ vertices $(N \in \mathbb{N})$

$$
\left(P_{1}, P_{2}, \ldots, P_{N+3}\right)
$$

where we require the pairs of vectors $\left(P_{j+1}-P_{j}, P_{j}-P_{j-1}\right)$ to be linear independent for $j=1, \ldots, N+3$, with $P_{0}:=P_{N+3}$ and $P_{N+4}:=P_{1}$. We consider the open bounded convex set $T$ of $N$-tuples

$$
\left(\tau_{1}, \tau_{2}, \ldots, \tau_{N}\right)=: \tau \in(0, \pi)^{N}
$$

which meet $0<\tau_{1}<\cdots<\tau_{N}<\pi$. Moreover we fix the three angles $\tau_{N+k}:=\frac{\pi}{2}(1+k)$, $k=1,2,3$. Now to any $\tau \in T$ we assign the set of surfaces
$\tilde{\mathcal{U}}(\tau):=\left\{X \in C^{0}\left(\bar{B}, \mathbb{R}^{3}\right) \cap C^{2}\left(B, \mathbb{R}^{3}\right) \mid X\left(e^{i \theta}\right) \in \Gamma_{j} \quad\right.$ for $\left.\theta \in\left[\tau_{j}, \tau_{j+1}\right], 1 \leq j \leq N+3\right\}$,
where $\Gamma_{j}:=\left\{P_{j}+t\left(P_{j+1}-P_{j}\right) \mid t \in \mathbb{R}\right\}, P_{N+4}:=P_{1}$ and $\tau_{N+4}:=\tau_{1}$. On account of Satz 1 in [3] one can define the map

$$
\tilde{\psi}(\tau):=\text { unique minimizer of } \mathcal{D} \text { within } \tilde{\mathcal{U}}(\tau)
$$

where $\mathcal{D}$ denotes Dirichlet's integral. We will also use the notation $X(\cdot, \tau)$ for $\tilde{\psi}(\tau)$. From Satz 1 in [3] and Satz 1 in [4] we quote the following result:

Proposition 1 (i) The surfaces $\tilde{\psi}(\tau)$ are harmonic on $B \quad \forall \tau \in T$.
(ii) The function $\tilde{f}:=\mathcal{D} \circ \tilde{\psi}$ is of class $C^{\omega}(T)$.
(iii) A surface $\tilde{\psi}(\tau)$ is conformally parametrized on B, thus a minimal surface in $\tilde{\mathcal{U}}(\tau)$, if and only if $\tau$ is contained in $K(\tilde{f})$, the set of critical points of $\tilde{f}$.

Point (i) of the above theorem and the Courant-Lebesgue Lemma imply (cf. [6, Chap. 4]) that

$$
\begin{aligned}
\tilde{\mathcal{M}}(\Gamma) & \equiv\{\text { set of minimal surfaces on } B\} \cap \bigcup_{\tau \in T} \tilde{\mathcal{U}}(\tau) \cap H^{1,2}\left(B, \mathbb{R}^{3}\right) \\
& =\{X \in \operatorname{image}(\tilde{\psi}) \mid X \text { is also conformally parametrized on } B\} .
\end{aligned}
$$

In the sequel we will only consider points $\tau \in K(\tilde{f})$, thus minimal surfaces $X(\cdot, \tau) \in$ $\tilde{\mathcal{M}}(\Gamma)$, and will denote $A^{\tau}:=-\triangle+2(K E)^{\tau}$ and $J^{\tau}$ for the assigned Schwarz operators and quadratic forms. From [5], (3.3), resp. (34) in [7] we quote that there is some constant const. $(\tau)$, depending on $\tau$ and $\Gamma$ only, such that

$$
\begin{equation*}
\left|(K E)^{\tau}(w)\right| \leq \operatorname{const} .(\tau) \sum_{k=1}^{N+3}\left|w-e^{i \tau_{k}}\right|^{-2+\alpha} \quad \forall w \in B, \tag{5}
\end{equation*}
$$

for any $\tau \in K(\tilde{f})$ and some fixed $\alpha>0$ that depends only on $\Gamma$. Moreover we are going to use the properties of the Green function (see [6, Proposition 6.1])

$$
\begin{equation*}
\tilde{G}(w, y):=\frac{1}{2 \pi} \log \left(\frac{|1-\bar{w} y|}{|w-y|}\right), \tag{6}
\end{equation*}
$$

which we consider on $(\bar{B} \times \bar{B}) \backslash \Lambda$ with $\Lambda:=\{(w, y) \in \bar{B} \times \bar{B} \mid w=y\}$. In Proposition 6.2 in [6] the author proved that $\tilde{G}(\cdot, y)$ coincides with the weak $H^{1, S}(B)$-limit (for $s \in(1,2))$ and $L^{p}(B)$-limit [for $\left.p \in(1, \infty)\right] G(\cdot, y)$ of some sequence $G^{\rho_{j}}(\cdot, y)$ of so-called mollified Green functions, for any $y \in B$ (see [6, (5.9), (5.10)]). Moreover we are going to use the assigned potential

$$
\mathcal{G}(\varphi)(w):=\int_{B} \tilde{G}(w, y) \varphi(y) \mathrm{d} y \quad \text { for } w \in \bar{B}
$$

which is well defined for any $\varphi \in L^{r}(B)$, with $r>1$, on account of $\tilde{G}(w, \cdot) \in L^{p}(B)$, $\forall p \in[1, \infty), \forall w \in B$, and $\tilde{G}(w, \cdot) \equiv 0$ on $B, \forall w \in \partial B$, by Proposition 6.1 in [6]. Its most important features are Green's identity for any $\varphi \in H^{2,2}(B) \cap C_{0}^{2}(B)$ and $w \in B$ :

$$
\begin{equation*}
-\varphi(w)=\int_{B} G(w, y) \dot{\Delta} \varphi(y) \mathrm{d} y \equiv \mathcal{G}(\dot{\Delta} \varphi)(w) \tag{7}
\end{equation*}
$$

and the estimate

$$
\begin{equation*}
\|\mathcal{G}(\varphi)\|_{H^{2,2}(B)} \leq \text { const. }\|\varphi\|_{L^{2}(B)}, \tag{8}
\end{equation*}
$$

for any $\varphi \in L^{2}(B)$. Now on account of the equality $\tilde{G}(\cdot, y) \equiv G(\cdot, y)$ one can combine properties of $\tilde{G}$ with the $L^{p}(B)$-estimate (5.11) in [6] for $G(\cdot, y)$ in order to prove the important assertion (3.11) in [5] (see [6, Proposition 7.1] for the proof), which states that for any $\varphi \in H^{2,2}(B) \cap C_{0}^{2}(B)$ and any $\tau \in K(\tilde{f})$ there holds the estimate

$$
\begin{equation*}
\left|(K E)^{\tau} \varphi(w)\right| \leq c(\tau, \alpha) \sum_{k=1}^{N+3}\left|w-e^{i \tau_{k}}\right|^{-1+\frac{\alpha}{2}}\|\Delta \varphi\|_{L^{2}(B)} \quad \forall w \in B \tag{9}
\end{equation*}
$$

By a well-known method (see e.g. [1, p. 108, Satz 2.23]) one proves that $H^{2,2}(B) \cap$ $C_{0}^{2}(B)$ is densely contained in $H^{2,2}(B) \cap \grave{H}^{1,2}(B)$ w. r. to the $H^{2,2}(B)$-norm. Hence, since the embedding $H^{2,2}(B) \hookrightarrow C^{0}(\bar{B})$ is continuous this implies

Proposition 2 The estimate (9) holds for any $\varphi \in H^{2,2}(B) \cap{ }_{H}^{1,2}(B)$ and for any $\tau \in K(\tilde{f})$.

Now a straight forward reasoning leads to (see [6, Proposition 7.3])
Proposition 3 For any $\varphi \in H^{2,2}(B) \cap \circ^{1,2}(B)$ and any $\tau \in K(\tilde{f})$ there holds:

$$
\begin{equation*}
\left\|2(K E)^{\tau} \varphi\right\|_{L^{2}(B)} \leq \frac{1}{2}\|\Delta \varphi\|_{L^{2}(B)}+c\|\varphi\|_{L^{2}(B)}, \tag{10}
\end{equation*}
$$

for some constant $c=c(\tau)$ that only depends on $\tau$.
We will abbreviate $A^{\tau}:=A^{X(\cdot, \tau)}$ and $\dot{A}^{\tau}:=\dot{A}^{X(\cdot, \tau)}$ in the sequel. From Proposition 3 we can derive firstly that $\operatorname{Dom}\left(\dot{A}^{\tau}\right)=H^{2,2}(B) \cap C_{0}^{2}(B)$ is contained
in $\operatorname{Dom}\left(A^{\tau}\right)$, thus $\dot{A}^{\tau} \subset A^{\tau}$, and especially that $A^{\tau}$ is densely defined in $L^{2}(B)$, $\forall \tau \in K(\tilde{f})$. Moreover we have

Proposition $4 A^{\tau}$ is symmetric w. r. to $\langle\cdot, \cdot\rangle_{L^{2}(B)}$, i.e., $A^{\tau} \subset\left(A^{\tau}\right)^{*} \forall \tau \in K(\tilde{f})$.
Proof We fix some $\tau \in K(\tilde{f})$. For any $\varphi \in \operatorname{Dom}\left(A^{\tau}\right)$ and $\psi \in C_{c}^{\infty}(B)$ we have $\nabla \varphi \psi \in C_{c}^{1}(B)$. Hence, by the divergence theorem we obtain

$$
\begin{equation*}
\left\langle A^{\tau}(\varphi), \psi\right\rangle_{L^{2}(B)}=\int_{B} \nabla \varphi \cdot \nabla \psi+2(K E)^{\tau} \varphi \psi \mathrm{d} w=: \mathcal{L}^{\tau}(\varphi, \psi) \tag{11}
\end{equation*}
$$

Now let $\psi \in \grave{H}^{1,2}(B)$ be arbitrarily chosen and $\left\{\psi_{j}\right\} \subset C_{c}^{\infty}(B)$ with $\psi_{j} \longrightarrow \psi$ in ${ }^{1}{ }^{1,2}(B)$. By Hölder's inequality and Sobolev's embedding theorem we achieve due to $1-\frac{2}{2}=0>0-\frac{2}{q}, \forall q \in[1, \infty)$ :

$$
\begin{aligned}
\left\|(K E)^{\tau} \varphi\left(\psi_{j}-\psi\right)\right\|_{L^{1}(B)} & \leq\left\|(K E)^{\tau}\right\|_{L^{p^{*}(B)}}\|\varphi\|_{L^{r}(B)}\left\|\psi_{j}-\psi\right\|_{L^{q}(B)} \\
& \leq\left\|(K E)^{\tau}\right\|_{L^{p *}(B)}\|\varphi\|_{L^{r}(B)} \text { const. }(q)\left\|\psi_{j}-\psi\right\|_{H^{1,2}(B)} \longrightarrow 0,
\end{aligned}
$$

for $j \rightarrow \infty$, with $\frac{1}{p^{*}}+\frac{1}{r}+\frac{1}{q}=1$ and $p^{*} \in\left(1, \frac{2}{2-\alpha}\right)$. Hence, recalling that $A^{\tau}(\varphi) \in L^{2}(B)$ we gain (11) in the limit also for $\psi \in \grave{H}^{1,2}(B)$, thus especially for any $\psi \in \operatorname{Dom}\left(A^{\tau}\right)$. Together with the symmetry of $\mathcal{L}^{\tau}(\cdot, \cdot)$ this yields for an arbitrary $\varphi \in \operatorname{Dom}\left(A^{\tau}\right)$ :

$$
\begin{equation*}
\left\langle A^{\tau}(\varphi), \psi\right\rangle_{L^{2}(B)}=\mathcal{L}^{\tau}(\varphi, \psi)=\mathcal{L}^{\tau}(\psi, \varphi)=\left\langle\varphi, A^{\tau}(\psi)\right\rangle_{L^{2}(B)} \tag{12}
\end{equation*}
$$

$\forall \psi \in \operatorname{Dom}\left(A^{\tau}\right)$, which shows indeed $\operatorname{Dom}\left(A^{\tau}\right) \subset \operatorname{Dom}\left(\left(A^{\tau}\right)^{*}\right)$ and $\left(A^{\tau}\right)^{*}(\varphi)=$ $A^{\tau}(\varphi)$, just as asserted.

From this and the symmetry of $\dot{A}^{\tau}$ and $\dot{\Delta}$ on $H^{2,2}(B) \cap C_{0}^{2}(B)$ one can easily derive that $A^{\tau}, \dot{A}^{\tau}$ and $\dot{\Delta}$ are closable in $L^{2}(B), \forall \tau \in K(\tilde{f})$. Now we can prove

Proposition 5 There holds $\operatorname{Dom}(\overline{\dot{\Delta}})=\operatorname{Dom}\left(\overline{\dot{A}^{\tau}}\right)=H^{2,2}(B) \cap \stackrel{\circ}{1}^{1,2}(B) \forall \tau \in K(\tilde{f})$.
Proof We fix some $\tau \in K(\tilde{f})$ arbitrarily and choose some $\varphi \in \operatorname{Dom}(\overline{\dot{\Delta}})$. Thus there is a sequence $\left\{\varphi_{m}\right\} \subset H^{2,2}(B) \cap C_{0}^{2}(B)=\operatorname{Dom}(\dot{\Delta})$ such that

$$
\begin{equation*}
\varphi_{m} \longrightarrow \varphi \text { and } \dot{\Delta} \varphi_{m} \longrightarrow \overline{\dot{\Delta}}(\varphi) \quad \text { in } L^{2}(B) \tag{13}
\end{equation*}
$$

By (10) we see that

$$
\begin{equation*}
\left\|2(K E)^{\tau}\left(\varphi_{n}-\varphi_{m}\right)\right\|_{L^{2}(B)} \leq \frac{1}{2}\left\|\dot{\Delta} \varphi_{n}-\dot{\Delta} \varphi_{m}\right\|_{L^{2}(B)}+c\left\|\varphi_{n}-\varphi_{m}\right\|_{L^{2}(B)}, \tag{14}
\end{equation*}
$$

thus that $\left\{2(K E)^{\tau} \varphi_{m}\right\}$ is a Cauchy sequence in $L^{2}(B)$. Now from (13) we can deduce the pointwise convergence

$$
\begin{equation*}
(K E)^{\tau} \varphi_{m_{k}}(w) \longrightarrow(K E)^{\tau} \varphi(w) \quad \text { for a.e. } w \in B \tag{15}
\end{equation*}
$$

for some suitable sequence $\left\{m_{k}\right\}$, which shows that $(K E)^{\tau} \varphi_{m} \longrightarrow(K E)^{\tau} \varphi$ in $L^{2}(B)$ and therefore again with (13):

$$
\dot{A}^{\tau}\left(\varphi_{m}\right)=-\dot{\Delta} \varphi_{m}+2(K E)^{\tau} \varphi_{m} \longrightarrow-\overline{\dot{\Delta}}(\varphi)+2(K E)^{\tau} \varphi=\overline{\dot{A}}^{\tau}(\varphi)
$$

in $L^{2}(B)$, which proves that $\varphi \in \operatorname{Dom}\left(\overline{\dot{A}}^{\tau}\right)$.

Now let some $\varphi \in \operatorname{Dom}\left(\overline{\dot{A}^{\tau}}\right)$ be given arbitrarily, which means that there exists a sequence $\left\{\varphi_{m}\right\} \subset H^{2,2}(B) \cap C_{0}^{2}(B)$ satisfying

$$
\begin{equation*}
\varphi_{m} \longrightarrow \varphi \text { and } \dot{A}^{\tau}\left(\varphi_{m}\right) \longrightarrow \overline{\dot{A}^{\tau}}(\varphi) \quad \text { in } L^{2}(B) \tag{16}
\end{equation*}
$$

For some arbitrary $\psi \in H^{2,2}(B) \cap C_{0}^{2}(B)$ we have by (10):

$$
\left\|\dot{A}^{\tau}(\psi)\right\|_{L^{2}(B)} \geq\|\dot{\Delta} \psi\|_{L^{2}(B)}-\left\|2(K E)^{\tau} \psi\right\|_{L^{2}(B)} \geq \frac{1}{2}\|\dot{\Delta} \psi\|_{L^{2}(B)}-c\|\psi\|_{L^{2}(B)}
$$

and therefore $\|\dot{\Delta} \psi\|_{L^{2}(B)} \leq 2\left\|\dot{A}^{\tau}(\psi)\right\|_{L^{2}(B)}+2 c\|\psi\|_{L^{2}(B)}$. Combining this with (16) we conclude that $\left\{\dot{\Delta} \varphi_{m}\right\}$ is a Cauchy sequence in $L^{2}(B)$, and therefore also $\left\{2(K E)^{\tau} \varphi_{m}\right\}=\left\{\dot{\Delta} \varphi_{m}+\dot{A}^{\tau}\left(\varphi_{m}\right)\right\}$ due to the second convergence in (16). Now due to the first convergence in (16) we conclude again (15) and thus (KE) ${ }^{\tau} \varphi_{m} \longrightarrow(K E)^{\tau} \varphi$ in $L^{2}(B)$ and therefore again with the second convergence in (16):

$$
\dot{\triangle} \varphi_{m}=-\dot{A}^{\tau}\left(\varphi_{m}\right)+2(K E)^{\tau} \varphi_{m} \longrightarrow-\overline{\dot{A}}^{\tau}(\varphi)+2(K E)^{\tau} \varphi=\overline{\dot{\Delta}} \varphi
$$

in $L^{2}(B)$, i.e., that $\varphi \in \operatorname{Dom}(\overline{\bar{\Delta}})$.
Finally we have to prove that $\operatorname{Dom}(\overline{\dot{\Delta}})=H^{2,2}(B) \cap \stackrel{\circ}{H}^{1,2}(B)$. Firstly let $\varphi \in \operatorname{Dom}(\overline{\dot{\Delta}})$ be chosen arbitrarily, thus there exists a sequence $\left\{\varphi_{m}\right\} \subset H^{2,2}(B) \cap C_{0}^{2}(B)=\operatorname{Dom}(\dot{\Delta})$ satisfying (13). By (7), inequality (8) and (13) we achieve:

$$
\begin{equation*}
\left\|\varphi_{m}\right\|_{H^{2,2}(B)}=\left\|\mathcal{G}\left(\dot{\triangle} \varphi_{m}\right)\right\|_{H^{2,2}(B)} \leq \text { const. }\left\|\dot{\Delta} \varphi_{m}\right\|_{L^{2}(B)} \leq \text { const. } \tag{17}
\end{equation*}
$$

$\forall m \in \mathbb{N}$. Hence, together with the compactness of the embedding $H^{2,2}(B) \hookrightarrow L^{2}(B)$ and (13) we achieve the existence of a subsequence $\left\{\varphi_{m_{k}}\right\}$ such that $\varphi_{m_{k}} \rightharpoonup \varphi$ weakly in $H^{2,2}(B)$. This shows indeed $\varphi \in H^{2,2}(B) \cap \grave{H}^{1,2}(B)$ due to $\grave{H}^{1,2}(B) \supset \operatorname{Dom}(\dot{\Delta})$. Finally the inclusion $H^{2,2}(B) \cap \dot{H}^{1,2}(B) \subset \operatorname{Dom}(\overline{\dot{\Delta}})$ follows immediately from the fact that $H^{2,2}(B) \cap C_{0}^{2}(B)$ is densely contained in $H^{2,2}(B) \cap \grave{H}^{1,2}(B)$ w. r. to the $H^{2,2}(B)$-norm.

Now we are going to prove the essential self-adjointness of $A^{\tau}$. By means of the continuity of $\mathcal{G}: L^{2}(B) \longrightarrow H^{2,2}(B)$ and (7) one can prove as in [10], p. 59, that $\dot{\Delta}$ is essentially self-adjoint w. r. to $\langle\cdot, \cdot\rangle_{L^{2}(B)}$, i.e., $\overline{\dot{\Delta}}=(\overline{\dot{\Delta}})^{*}$. Together with estimate (10), for $\tau \in K(\tilde{f})$, and the obvious symmetry of $(K E)^{\tau}$ we infer from Theorem 4.4 in [9, p. 288]:

Proposition $6 \dot{A}^{\tau}=-\dot{\Delta}+2(K E)^{\tau}$ is essentially self-adjoint w. r. to $\langle\cdot, \cdot\rangle_{L^{2}(B)}$, i.e., $\overline{\dot{A}^{\tau}}=\left(\overline{\dot{A}^{\tau}}\right)^{*}, \forall \tau \in K(\tilde{f})$.

Now combining Proposition 4 with the fact that $\operatorname{Dom}\left(A^{\tau}\right)$ is densely contained in $L^{2}(B)$ w. r. to $\|\cdot\|_{L^{2}(B)}$ we can derive by twice applying Theorem 5.29 in [9, p. 168]:

Proposition $7\left(A^{\tau}\right)^{*}$ is densely defined in $L^{2}(B)$ and closed, $\left(A^{\tau}\right)^{* *}=\bar{A}^{\tau}$ and $\left(A^{\tau}\right)^{*}=$ $\overline{\left(A^{\tau}\right)^{*}}=\left(\left(A^{\tau}\right)^{*}\right)^{* *} \forall \tau \in K(\tilde{f})$.

Summarizing we obtain
Proposition $8\left(\dot{A}^{\tau}\right)^{*}=\overline{\dot{A}^{\tau}}=\bar{A}^{\tau}=\left(A^{\tau}\right)^{*}$ are self-adjoint operators with domain $H^{2,2}(B) \cap \dot{H}^{1,2}(B), \forall \tau \in K(\tilde{f})$.

Proof We fix some $\tau \in K(\tilde{f})$. Firstly there holds by Proposition 4: $\dot{A}^{\tau} \subset A^{\tau} \subset\left(A^{\tau}\right)^{*}$. Combining this with Propositions 6 and 7 we achieve:

$$
\left(\overline{\dot{A}^{\tau}}\right)^{*}=\overline{\dot{A}^{\tau}} \subset \bar{A}^{\tau} \subset \overline{\left(A^{\tau}\right)^{*}}=\left(\left(A^{\tau}\right)^{*}\right)^{* *}=\left(\left(A^{\tau}\right)^{* *}\right)^{*}=\left(\bar{A}^{\tau}\right)^{*} \subset\left(\overline{\dot{A}^{\tau}}\right)^{*} .
$$

Hence, also noting that $\overline{\left(A^{\tau}\right)^{*}}=\left(A^{\tau}\right)^{*}$ by Proposition 7, we can conclude that $\overline{\dot{A}^{\tau}}=$ $\bar{A}^{\tau}=\left(A^{\tau}\right)^{*}$ are self-adjoint operators with domain $H^{2,2}(B) \cap \check{H}^{1,2}(B)$ by Proposition 6. Furthermore applying Theorem 5.29 in [9, p. 168], to the densely defined and closable operator $\dot{A}^{\tau}$ we obtain that $\left(\dot{A}^{\tau}\right)^{*}$ is densely defined in $L^{2}(B)$, closed, i.e., $\left(\dot{A}^{\tau}\right)^{*}=\overline{\left(\dot{A}^{\tau}\right)^{*}}$, and $\left(\dot{A}^{\tau}\right)^{* *}=\dot{\dot{A}}^{\tau}$. Now applying it to the densely defined and closed operator $\left(\dot{A}^{\tau}\right)^{*}$ again we gain that $\left(\left(\dot{A}^{\tau}\right)^{*}\right)^{* *}=\overline{\left(\dot{A}^{\tau}\right)^{*}}$. Hence, we achieve together with Proposition 6 that

$$
\overline{\dot{A}^{\tau}}=\left(\overline{\dot{A}^{\tau}}\right)^{*}=\left(\left(\dot{A}^{\tau}\right)^{* *}\right)^{*}=\left(\left(\dot{A}^{\tau}\right)^{*}\right)^{* *}=\overline{\left(\dot{A}^{\tau}\right)^{*}}=\left(\dot{A}^{\tau}\right)^{*} .
$$

Now we are going to prove Theorem 1. As in (11) we will use the bilinear form

$$
\mathcal{L}^{\tau}(\varphi, \psi):=\int_{B} \nabla \varphi \cdot \nabla \psi+2(K E)^{\tau} \varphi \psi \mathrm{d} w,
$$

for $\varphi, \psi \in \grave{H}^{1,2}(B)$ assigned to some $\tau \in K(\tilde{f})$, thus especially $J^{\tau}(\varphi) \equiv \mathcal{L}^{\tau}(\varphi, \varphi)$. In the sequel we fix some $\tau \in K(\tilde{f})$, thus some minimal surface $X(\cdot, \tau) \in \tilde{\mathcal{M}}(\Gamma)$, and $p^{*} \in\left(1, \frac{2}{2-\alpha}\right)$ arbitrarily and abbreviate $A:=A^{\tau}, \mathcal{L}:=\mathcal{L}^{\tau}$ and $J:=J^{\tau}$. The final tool of the proof of Theorem 1 is

Proposition 9 There exists some constant $C\left(p^{*}\right)$ such that:

$$
\begin{equation*}
J(\varphi) \geq \frac{1}{2} \int_{B}|\nabla \varphi|^{2} \mathrm{~d} w-C\left(p^{*}\right)\|K E\|_{L^{p^{*}}(B)} \quad \forall \varphi \in S \dot{H}^{1,2}(B) . \tag{18}
\end{equation*}
$$

Proof We consider the continuous embeddings $\dot{H}^{1,2}(B) \hookrightarrow L^{q}(B) \hookrightarrow L^{2}(B)$, for any $q \geq 2$, where the first one is compact due to Sobolev's embedding theorem. Hence, we may apply Ehrling's interpolation lemma, yielding

$$
\|\varphi\|_{L^{q}(B)} \leq \epsilon\|\varphi\|_{\dot{H}^{1,2}(B)}+C(q, \epsilon) \quad \forall \varphi \in S \dot{H}^{1,2}(B)
$$

for any $\epsilon>0$ and any $q \geq 2$, where we used the requirement $\|\varphi\|_{L^{2}(B)}=1$. Hence, together with Hölder's, Cauchy-Schwarz' and Poincaré's inequalities we achieve for any $\epsilon>0$ :

$$
\begin{aligned}
\left\|K E \varphi^{2}\right\|_{L^{1}(B)} & \leq\|K E\|_{L^{p^{*}(B)}}\|\varphi\|_{L^{2 p^{\prime}(B)}}^{2} \leq\|K E\|_{L^{p^{*}}(B)}\left(\epsilon\|\varphi\|_{\dot{H}^{1,2}(B)}+C\left(p^{\prime}, \epsilon\right)\right)^{2} \\
& \leq\|K E\|_{L^{p^{*}(B)}} 2\left(\epsilon^{2}\left(C_{P}+1\right) \int_{B}|\nabla \varphi|^{2} \mathrm{~d} w+C\left(p^{\prime}, \epsilon\right)^{2}\right),
\end{aligned}
$$

with $\frac{1}{p^{*}}+\frac{1}{p^{\prime}}=1$, and therefore by the definition of $J$ :

$$
J(\varphi) \geq\left(1-4\|K E\|_{L^{p^{*}(B)}}\left(C_{P}+1\right) \epsilon^{2}\right) \int_{B}|\nabla \varphi|^{2} \mathrm{~d} w-4\|K E\|_{L^{p^{*}}(B)} C\left(p^{\prime}, \epsilon\right)^{2},
$$

for any $\varphi \in S H^{1,2}(B)$, which yields our assertion by a suitable choice of $\epsilon$.

In order to prove Theorem 1 we shall apply Courant's technique for obtaining eigenvalues and eigenfunctions of $A$ by minimizing the quadratic form $J$ on $S \dot{H}^{1,2}(B)$ with respect to subsidiary conditions. We shall only sketch the necessary steps.

Proof of Theorem 1 Firstly the above proposition guarantees the existence of $\inf _{S H^{1,2}(B)} J$. Hence, we may consider some sequence $\left\{\varphi_{j}\right\} \subset S H^{1,2}(B)$ such that $J\left(\varphi_{j}\right) \searrow \inf _{S H^{1,2}(B)} J$, and again using (18) we conclude together with Poincaré's inequality that $\left\|\varphi_{j}\right\|_{H^{1,2}(B)} \leq$ const. Thus we can extract some subsequence $\left\{\varphi_{j_{k}}\right\}$ such that

$$
\varphi_{j_{k}} \rightharpoonup \varphi^{*} \quad \text { weakly in } H^{1,2}(B)
$$

for some $\varphi^{*} \in \dot{H}^{1,2}(B)$. Since this implies $\varphi_{j_{k}} \longrightarrow \varphi^{*}$ in $L^{q}(B)$, for any $q \geq 1$, we infer $\varphi^{*} \in S \grave{H}^{1,2}(B)$. Furthermore this implies:

$$
\left\|K E\left(\varphi_{j_{k}}^{2}-\left(\varphi^{*}\right)^{2}\right)\right\|_{L^{1}(B)} \leq\|K E\|_{L^{p^{*}}(B)}\left\|\varphi_{j_{k}}^{2}-\left(\varphi^{*}\right)^{2}\right\|_{L^{p^{\prime}}(B)} \longrightarrow 0
$$

with $\frac{1}{p^{*}}+\frac{1}{p^{\prime}}=1$. Hence, $J$ inherits the weak lower semicontinuity of the Dirichlet integral:

$$
\begin{align*}
J\left(\varphi^{*}\right) & =\int_{B}\left|\nabla \varphi^{*}\right|^{2}+2(K E)^{\tau}\left(\varphi^{*}\right)^{2} \mathrm{~d} w  \tag{19}\\
& \leq \liminf _{k \rightarrow \infty} \int_{B}\left|\nabla \varphi_{j_{k}}\right|^{2} \mathrm{~d} w+2 \lim _{k \rightarrow \infty} \int_{B} K E \varphi_{j_{k}}^{2} \mathrm{~d} w=\liminf _{k \rightarrow \infty} J\left(\varphi_{j_{k}}\right)=\inf _{\operatorname{SH}^{1,2}(B)} J,
\end{align*}
$$

thus $J\left(\varphi^{*}\right)=\inf _{S H^{1,2}(B)} J$. Now we construct recursively a filtration of subspaces $\grave{H}^{1,2}(B)=: U_{1} \supset U_{2} \supset U_{3} \cdots$ of $H^{1,2}(B)$ by

$$
\begin{equation*}
U_{i}:=\left\{\eta \in \stackrel{\circ}{H}^{1,2}(B) \mid\left\langle\eta, \varphi_{j}^{*}\right\rangle_{L^{2}(B)}=0, j=1, \ldots, i-1\right\}, \tag{20}
\end{equation*}
$$

for $i \geq 2$, and $S U_{i}:=U_{i} \cap S \dot{H}^{1,2}(B)$, where we set $\varphi_{1}^{*}:=\varphi^{*}$ and the $\varphi_{i}^{*} \in S U_{i}$ have to minimize $J$ :

$$
\begin{equation*}
J\left(\varphi_{i}^{*}\right) \stackrel{!}{=} \inf _{S U_{i}} J=: \lambda_{i} \tag{21}
\end{equation*}
$$

We obtain those minimizers $\varphi_{i}^{*}, i \geq 2$, exactly by the same procedure which yielded $\varphi^{*}$ above since the $U_{i}$ 's are closed w. r. to weak $H^{1,2}(B)$-convergence and non-trivial, otherwise there would hold $\operatorname{Span}\left(\varphi_{1}^{*}, \ldots, \varphi_{i-1}^{*}\right)^{\perp}=\{0\}\left[\perp\right.$ w. r. to $\langle\cdot, \cdot\rangle_{L^{2}(B)}$ in $\left.H^{1,2}(B)\right]$ which contradicts $\operatorname{dim} \dot{H}^{1,2}(B)=\infty$ due to the projection theorem. By construction of our filtration the sequence $\left\{\lambda_{i}\right\}$ is increasing. Furthermore $\{\infty\}$ is its only point of accumulation since if there was a bounded subsequence $\left\{\lambda_{i_{k}}\right\}$ then we would conclude by (21), (18) and Poincaré's inequality that $\left\|\varphi_{i_{k}}^{*}\right\|_{H^{1,2}(B)} \leq$ const. $\forall k \in \mathbb{N}$. Hence, since the embedding $H^{1,2}(B) \hookrightarrow L^{2}(B)$ is compact, $\left\{\varphi_{i_{k}}^{*}\right\}$ would possess a Cauchysubsequence w. r. to \| $\cdot \|_{L^{2}(B)}$, which contradicts the fact that

$$
\left\langle\varphi_{i}^{*}-\varphi_{j}^{*}, \varphi_{i}^{*}-\varphi_{j}^{*}\right\rangle_{L^{2}(B)}=\left\|\varphi_{i}^{*}\right\|_{L^{2}(B)}^{2}-2\left\langle\varphi_{i}^{*}, \varphi_{j}^{*}\right\rangle_{L^{2}(B)}+\left\|\varphi_{j}^{*}\right\|_{L^{2}(B)}^{2}=2-2 \delta_{i j}
$$

$\forall i, j \in \mathbb{N}$, by (20) and $\varphi_{i}^{*} \in S U_{i}$. Now we are going to prove that the $\varphi_{i}^{*}$ and $\lambda_{i}$ are indeed eigenfunctions and eigenvalues of $A$ and $\bar{A}$. For some fixed $i$ we consider an arbitrary $\psi \in U_{i}$ and the function

$$
f_{i}(\epsilon):=J\left(\varphi_{i}^{*}+\epsilon \psi\right)-\lambda_{i}\left\|\varphi_{i}^{*}+\epsilon \psi\right\|_{L^{2}(B)}^{2} \quad \text { on }\left[-\epsilon_{0}, \epsilon_{0}\right],
$$

for $\epsilon_{0}>0$ that small such that $\left\|\varphi_{i}^{*}+\epsilon \psi\right\|_{L^{2}(B)}>0 \forall \epsilon \in\left[-\epsilon_{0}, \epsilon_{0}\right]$. Then we obtain for any $\psi \in U_{i}$ and any $i \in \mathbb{N}$, abbreviating $\langle\cdot, \cdot\rangle:=\langle\cdot, \cdot\rangle_{L^{2}(B)}$ :

$$
0=\left.\frac{\mathrm{d}}{\mathrm{~d} \epsilon} f_{i}(\epsilon)\right|_{\epsilon=0}=2\left(\mathcal{L}\left(\varphi_{i}^{*}, \psi\right)-\lambda_{i}\left\langle\varphi_{i}^{*}, \psi\right\rangle\right) .
$$

Next a standard reasoning yields $\mathcal{L}\left(\varphi_{i}^{*}, \psi\right)=\lambda_{i}\left\langle\varphi_{i}^{*}, \psi\right\rangle$ even for any $\psi \in \grave{H}^{1,2}(B)$, i.e.,

$$
\begin{equation*}
A\left(\varphi_{i}^{*}\right)=\lambda_{i} \varphi_{i}^{*} \quad \text { weakly on } B \tag{22}
\end{equation*}
$$

$\forall i \in \mathbb{N}$. Now we know that our coefficients $2(K E)^{\tau}-\lambda_{i}$ are of class $C^{\infty}(B)$ for any $\tau \in K(\tilde{f})$ (see [7, (35)]). Thus the $\mathrm{L}^{2}$-regularity theory, Theorem 8.13 in [2], yields that $\varphi_{i}^{*} \in C^{\infty}(B) \forall i \in \mathbb{N}$. Hence, if we test (22) with an arbitrary $\psi \in C_{c}^{\infty}(B)$ and apply the divergence theorem to $\nabla \varphi_{i}^{*} \psi \in C_{c}^{\infty}(B)$, then we obtain:

$$
\left\langle A\left(\varphi_{i}^{*}\right), \psi\right\rangle=\mathcal{L}\left(\varphi_{i}^{*}, \psi\right)=\lambda_{i}\left\langle\varphi_{i}^{*}, \psi\right\rangle
$$

Thus the fundamental lemma of the calculus of variations yields the Eq. 22 even in the classical sense on $B$. In particular we see that $\varphi_{i}^{*} \in \operatorname{Dom}(A)$, thus indeed the $\varphi_{i}^{*}$ 's and the $\lambda_{i}$ 's are eigenfunctions and eigenvalues of $A$ and therefore also of $\bar{A} \forall i \in \mathbb{N}$. Next a standard reasoning yields $\|\psi\|_{L^{2}(B)}^{2}=\sum_{j=1}^{\infty}\left\langle\varphi_{j}^{*}, \psi\right\rangle^{2}$ for any $\psi \in \dot{H}^{1,2}(B)$. Now we suppose that $\lambda \notin\left\{\lambda_{i}\right\}$ is a further eigenvalue of $\bar{A}$ and $\phi \in E S_{\lambda}(\bar{A})$ a corresponding eigenfunction. Since $\phi \in H^{2,2}(B) \cap \dot{H}^{1,2}(B)=\operatorname{Dom}(\bar{A})$ by Theorem 8 we have $\nabla \phi \psi \in \stackrel{\circ}{H}^{1,1}(B)$ for any $\psi \in C_{c}^{\infty}(B)$. Hence, applying the divergence theorem to $\nabla \phi \psi$ we obtain

$$
\begin{equation*}
\mathcal{L}(\phi, \psi)=\langle\bar{A}(\phi), \psi\rangle=\lambda\langle\phi, \psi\rangle, \tag{23}
\end{equation*}
$$

and we achieve this equality also for any $\psi \in \grave{H}^{1,2}(B)$ exactly as in the proof of Proposition 4 by approximation. Now testing this weak equation with $\psi:=\varphi_{i}^{*}$ for an arbitrary $i \in \mathbb{N}$ we conclude together with (22):

$$
\lambda\left\langle\phi, \varphi_{i}^{*}\right\rangle=\mathcal{L}\left(\phi, \varphi_{i}^{*}\right)=\mathcal{L}\left(\varphi_{i}^{*}, \phi\right)=\lambda_{i}\left\langle\varphi_{i}^{*}, \phi\right\rangle,
$$

hence, $0=\left(\lambda-\lambda_{i}\right)\left\langle\varphi_{i}^{*}, \phi\right\rangle, \forall i \in \mathbb{N}$, which would imply that all the coordinates $\left\langle\varphi_{i}^{*}, \phi\right\rangle$ of $\phi$ would vanish and therefore $0=\sum_{j=1}^{\infty}\left\langle\varphi_{j}^{*}, \phi\right\rangle^{2}=\|\phi\|_{L^{2}(B)}^{2}$. But $\phi$ is an eigenfunction. Hence, we have proved so far $\left\{\lambda_{i}\right\}=\operatorname{Spec}(\bar{A}) \supset \operatorname{Spec}(A) \supset\left\{\lambda_{i}\right\}$ and therefore also $\left\{\lambda_{i}\right\}=\operatorname{Spec}(A)$. Finally we infer from $\operatorname{Dom}(A) \subset \operatorname{Dom}(\bar{A})=H^{2,2}(B) \cap \check{H}^{1,2}(B)$, $\varphi^{*} \in S \operatorname{Dom}(A)$ and (19):

$$
\inf _{S \mathscr{H}^{1,2}(B)} J \leq \inf _{S\left(H^{2,2}(B) \cap H^{1,2}(B)\right)} J \leq \inf _{S D o m(A)} J \leq J\left(\varphi^{*}\right)=\inf _{S \mathscr{H}^{1,2}(B)} J,
$$

which together with $\inf _{S H^{1,2}(B)} J=\lambda_{1}=\lambda_{\text {min }}(A)=\lambda_{\text {min }}(\bar{A})$ completes also the proof of (3). The second part of the theorem now follows along usual lines by employing Harnack's inequality. Let $\varphi^{*} \in E S_{\lambda_{\text {min }}}(\bar{A}) \subset H^{2,2}(B) \cap \dot{H}^{1,2}(B)$ with $\left\|\varphi^{*}\right\|_{L^{2}(B)}=1$ be given arbitrarily. We assume the existence of some point $w_{0} \in B$ with $\varphi^{*}\left(w_{0}\right)=0$. Firstly we note that $\left|\varphi^{*}\right| \in \grave{H}^{1,2}(B)$ and that $\int_{B}|\nabla| \varphi^{*}| |^{2} \mathrm{~d} w=\int_{B}\left|\nabla \varphi^{*}\right|^{2} \mathrm{~d} w$. Moreover applying (23) to $\phi:=\varphi^{*}$ and $\psi:=\varphi^{*}$ we obtain by (3):

$$
J\left(\left|\varphi^{*}\right|\right)=J\left(\varphi^{*}\right)=\left\langle\bar{A}\left(\varphi^{*}\right), \varphi^{*}\right\rangle_{L^{2}(B)}=\lambda_{\min }\left\langle\varphi^{*}, \varphi^{*}\right\rangle_{L^{2}(B)}=\lambda_{\min }=\inf _{S \dot{H}^{1,2}(B)} J
$$

Hence, exactly as we achieved (22) we conclude now due to $\left|\varphi^{*}\right| \in H^{1,2}(B)$ :

$$
A\left(\left|\varphi^{*}\right|\right)=\lambda_{\min }\left|\varphi^{*}\right| \quad \text { weakly on } B .
$$

Now we may apply Harnack's inequality, Theorem 8.20 in [2], to $\left|\varphi^{*}\right| \geq 0$ on any disc $B_{4 R}\left(w_{0}\right) \subset \subset B$, yielding $\sup _{B_{R}\left(w_{0}\right)}\left|\varphi^{*}\right| \leq \operatorname{const} . \inf _{B_{R}\left(w_{0}\right)}\left|\varphi^{*}\right|$. Hence, from $\varphi^{*}\left(w_{0}\right)=$ 0 we can conclude now that $\varphi^{*} \equiv 0$ on $B_{R}\left(w_{0}\right)$ and thus that $\varphi^{*} \equiv 0$ on $B$ by a successive use of Harnack's inequality, which contradicts our assumption $\left\|\varphi^{*}\right\|_{L^{2}(B)}=1$. Thus we have proved indeed for an arbitrary eigenfunction $\varphi^{*} \in E S_{\lambda_{\min }}(\bar{A})$ that $\varphi^{*}>0$ or $<0$ on $B$. Now we assume that $\operatorname{dim} E S_{\lambda_{\min }}(\bar{A})>1$. On account of the projection theorem we could choose two $\mathrm{L}^{2}(B)$-orthogonal eigenfunctions $\varphi^{*}, \bar{\varphi}^{*}$ in $E S_{\lambda_{\text {min }}}(\bar{A})$, i.e., with $\left\langle\varphi^{*}, \bar{\varphi}^{*}\right\rangle_{L^{2}(B)}=0$, in contradiction to $\left\langle\varphi^{*}, \bar{\varphi}^{*}\right\rangle_{L^{2}(B)}>0$ or $<0$. As we have $\{0\} \neq E S_{\lambda_{\text {min }}}(A) \subset E S_{\lambda_{\text {min }}}(\bar{A})$ we arrive at (4).

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