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SPECIAL ISSUE

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Mechanical competence of bone-implant systems can accurately be determined by image-based micro-finite element analyses

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Abstract The precise failure mechanisms of bone implants are still incompletely understood. Micro-computed tomography in combination with finite element analysis appears to be a potent methodology to determine the mechanical stability of bone-implant constructs. To assess this microstructural finite element (μ FE) analysis approach, pull-out tests were designed and conducted on ten sheep vertebral bodies into which orthopedic screws were inserted. μ FE models of the same bone-implant constructs were then built and solved, using a large-scale linear FE-solver. μ FE calculated pull-out strength correlated highly with the experimentally measured pull-out strength ($r^2 = 0.87$) thereby statistically supporting the μ FE approach. These results suggest that bone-implant constructs can be analyzed using μ FE in a detailed and unprecedented way. This could potentially facilitate the development of future implant designs leading to novel and improved fracture fixation methods.

Keywords Bone-implant competence \cdot Micro-finite element analysis (μ FEA) \cdot Bone microstructure \cdot Peri-implant bone quality \cdot Mechanical testing \cdot Pull-out strength

1 Introduction

Osteoporosis is a bone disease characterized by a reduction in bone mineral density (BMD) and structural deterioration of bone tissue, leading to an increased risk of fracture. According to the National Osteoporosis Foundation in the United States, 10 million U.S. citizens (of which 8 million are women) already have the

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disease and almost 34 million more are estimated to be at risk for osteoporosis [1]. The estimation is that half of the women and a quarter of men aged 50 years or older will suffer an osteoporosis related fracture within their lifetime [2]. Due to the rapidly ageing American population, the annual direct costs of osteoporosis in the US are projected to reach \$25.3 billion by 2025 and even \$50 billion by 2040. This phenomenon can be directly transferred to most developed countries [3,4]. About 2 million osteoporosis-related fractures occur every year in the US in men and women aged 50 or older of which just fewer than 300,000 are hip fractures and almost 550,000 are vertebral fractures [2].

The fact, that osteoporosis leads to fractures, is known. In contrast, the assumption that osteoporosis complicates the treatment of these fractures is rather not [5], and it has not been in the focus of treatment planning up to now. For a long time orthopedic implants were developed for patients with a good bone stock. The fundamental that bone mechanical properties depend on density and structure was not really considered. Therefore, it is not surprising that implants developed for good bone quality fail in osteoporotic bone [6,7]. Furthermore, recent studies are becoming available that show a correlation between the rate of implant failure and local bone quality [8–11]. From engineering principles it can be expected that implant stability depends on implant fixation, on the amount and quality of peri-implant bone and on how that bone deforms and eventually fails during implant loading. It would equally depend on the size, location, and quality of the local bone-implant contact areas. Indeed, experiments have shown that prototypes specifically designed for severely osteoporotic bone survive significantly longer during cyclic testing than comparable conventional implants [12]. However, a detailed understanding of the mechanisms underlying implant anchorage and stability is lacking and it is not clear to what extent size, location, and quality of the local bone-implant failure and final implant failure. In order to develop better implants, a thorough understanding of factors leading to failure as well as the knowledge how to influence them is needed.

Not all these failure mechanisms can be investigated by experimental measurements, e.g. no methods exist to measure the forces acting on a screw in vivo, nor do sophisticated osteoporotic animal models exist that could allow testing orthopedic screws in low-quality bone. Furthermore, access to osteoporotic human bone is generally very limited, which limits the use of standardized tests and hinders doing proper statistics. Therefore computer simulations, finite element (FE) models in particular, have great potential to establish as an alternative for experimental biomechanical tests on bone-screw structures. FE analyses of bone-implant constructs have addressed phenomena at the apparent level, such as overall structural competence [13, 14], as to get a better understanding of load distributions when using different kinds of implant configurations. Other FE models addressed the effects of screw design, and analyzed overall geometries, thread profiles and surfaces [15, 16]. Whereas in all these models bone's macroarchitecture could be handled relatively easily, its material properties, which are tightly linked to bone's microarchitecture [17], are more difficult to model. Hence, nearly all studies have simplified cortical and trabecular bone to homogeneous and isotropic linear elastic materials. Although such simplifications may be justified for the determination of non-local phenomena [14], the application of averaged bone properties for local analysis in highly heterogeneous and anisotropic cancellous bone may not be reasonable; instead, it seems appropriate that for cases like this the discrete nature of trabecular bone has to be taken into account. At present, only very few publications exist that do not model trabecular bone as a continuum in the bone-implant constructs [18].

Finite element analyses based on micro-computed tomography (μ CT) images of bone-implant constructs appear to be promising to further enhance our knowledge of the local stresses, strains, and deformation behavior of the bone in the vicinity of the implant. μ CT has become the method of choice in quantifying 3D bone microstructure. Microarchitectural bone imaging is a nondestructive, noninvasive, and precise procedure with which both the apparent density and the trabecular microstructure of intact bones and bone samples can be assessed in a single measurement. It provides the necessary detail to accurately represent the complex microstructure of trabecular bone. Desktop μ CT is a precise and validated technique [19–21], and has been used extensively to study bone microarchitecture [21-24], demonstrating that trabecular bone can have very distinct microarchitectures that are remarkably heterogeneous throughout the skeleton [25–27]. Direct voxelto-element conversion is an easy and straight-forward approach to generate micro-structural finite element (μ FE) models. Furthermore, this method is fast and can be completely automated. It can provide insight into the load transfer through the bone architecture and help to understand how differences in bone microarchitecture influence bone strength. These models are necessarily large to capture the microstructural details of the bone, and require special solution schemes. Within the last few years μ FE analysis has become a well-established technique for analyzing the mechanical quality of bone samples [28]. For linear deformation conditions, comparison between biomechanical compression tests on excised trabecular bone samples and μFE show very good agreement ($r^2 = 0.92$) when a homogeneous, isotropic tissue modulus is applied [29, 30]; this seems

to hold true for normal as well as osteoporotic bone [31]. As well, it has been shown that at the apparent level, these μ FE models can accurately predict trabecular bone failure for bovine [32] as well as for human trabecular bone [33]; the μ FE-predicted apparent stresses and strains at failure were equal to experimentally measured values for the same bone specimens. Nevertheless the material properties for bone at the tissue level as determined by μ FE differ in some cases from those determined by other experimental techniques; systemic experimental differences such as the scale of the tests and specimen preparation can explain these differences [34].

The steady increase in computational power over the last years, using parallel processors in supercomputers, has made it possible to analyze intact human bones, or large portions thereof [35-37]. A recent implementation even allowed to solve a model with nearly 1.5 billion degrees of freedom within 30 minutes, to simultaneously increase the level of detail and the size of the analyzed bone volume (BV) [38,39]. With that, μ FE analyses have reached a level where relatively large objects can be analyzed in great detail, opening up for the first time a detailed analysis of implant behavior in trabecular bone. However, whether these μ FE models would provide accurate results for bone-implant constructs is not known, because first, bone and implant form two different entities, and second, they have largely differing material properties. Therefore, the aim of this study was to assess such models by relating computational findings to experimental biomechanical data on bone-implant constructs.

2 Methods

Four sheep spines, from a study unrelated to the present one, were provided by the slaughterhouse of the Vetsuisse Faculty at the University of Zurich and had been stored in a freezer at a temperature of -21° C. All five sheep were female between 1 and 2 years old. Prior to dissection of individual vertebrae, the spines were thawed, and refrozen immediately after. In total, twelve vertebrae from the thoracic region (T1–T3) were harvested. Two of them were used in a pilot study, leaving ten specimens for this study.

Commonly used dental screws were implanted. The screws had an outer thread diameter of 3.3 mm and a thread height of 10 mm (Fig. 1). The screws were inserted in the upper surface of the vertebral body which was fixed in a clamp. Screw insertion was performed according to the manufacturer's instructions. First, a receiving channel of 2.2 mm was drilled at 800 rpm to a depth of 18 mm after which a drill of 2.8 mm at 500 rpm enlarged this channel. After the creation of this pilot hole the screws were placed in the specimen using a torque-controlled screwdriver, according to the ASTM standard F 543. Insertion depth was 10 mm, corresponding to the thread height. To minimize inter-specimen variability, the time between thawing the samples and the insertion of the screws was standardized to 5 h. After screw insertion, all samples were frozen again at a temperature of -21° C and stored for further processing.

2.1 Experimental testing

To prevent shear stresses and bending effects during screw extraction, care was taken to align the specimens properly in the mechanical testing device. For that purpose, a polymer part was placed on top of the screw's grip fixture such that the screws were aligned vertically. With the polymer part still in place, each vertebra was put at the bottom of a special-purpose aluminum part (Fig. 2). To fixate the sample, a mixture of meth-ylmethacrylate powder (MMA) and a liquid catalyst was used (Technovit 3040, Heraeus Kulzer GmbH), a polymer resin generally used for indirect surface testing. By mixing these two substances in a ratio of two to one, fluid PMMA was created which hardened after 15 min. This fluid was poured in the aluminum part in which the vertebra was resting. The part in which the embedding took place was subsequently connected by threaded holes to a custom-made aluminum adapter, fitting around the bottom platen of a universal mechanical testing machine (5 kN Allround-Line, Zwick GmbH, Ulm, Germany). To correct minor deflections in axial alignment, a double ball joint was used, connecting to the upper platen of the testing bench where the load cell was located.

At the start of the pull-out test the crosshead of the testing bench moved at a rate of 2.5 mm/min until a preload of 10N was reached, defined as the starting point of the test. Subsequently, the crosshead's displacement rate was set to 5 mm/min, according to the ASTM standard F 543. The test ended when the measured force had dropped to 80% of the maximally measured force. The displacement of the crosshead, as well as the force acting on the load cell, was recorded. Pull-out strength was defined as the maximum force measured in the experiment. Ultimate displacement was defined as the displacement reached at maximum force. In accordance



Fig. 1 a μ CT grayscale image showing the thin trabecular bone structures, the drill canal, the implant as well as the implant bone interaction. The outer thread diameter of the implant is 3.3 mm. b Segmented 3D representation of the inserted screw into the sheep vertebra. Bone microstructure is still nicely visible, even though resolution of the image was lowered by a factor of three in each direction. One VOI with an outer radius of 3 mm is indicated

with the current methodology to quantify the stiffness of a bone sample, the stiffness of the bone-implant construct was defined as the slope of the force–displacement curve between 30 and 70% of pull-out strength.

$2.2 \ \mu CT$ scanning and analysis

Before embedding in the aluminum holders, each sample was imaged with a micro-computed tomography system μ CT 80 (Scanco Medical, Brüttisellen, Switzerland) using a 25 μ m nominal resolution to assess the trabecular bone architecture and screw geometry (Fig. 1a). The samples had been taken out of the freezer and stored in a fridge at 4°C for 22h in a saline soaked towel. The bone-implant constructs were placed in a grip fixture, which itself fitted into a custom-made polymer part, used to align the screw exactly in the center of the μ CT sample holders. Proper alignment was crucial to reduce imaging artifacts which would have hampered



Fig. 2 Setup of the mechanical testing apparatus. The load cell is the connection to the upper part, the bottom adapter the connection to the lower part of the commercially available ZWICK testing device

further image processing and analyses. While being submersed in saline, the entire vertebrae with implanted screws were scanned with the screw axis coinciding with the sample rotation axis.

The reconstructed images were filtered using a constrained three-dimensional Gaussian filter to partially suppress noise in the volumes ($\sigma = 1.2$ and support = 1), and segmented using global thresholds to obtain representations of bone, implant and PMMA (Fig. 1b). During segmentation, several image corrections were applied to reduce imaging artifacts [40].

Analyses for bone volume fraction (BV/TV) were performed in cylindrically shaped volumes of interest (VOI) around the screws. The long axes of the VOIs were aligned with the center line of the screws. In order to reduce the influences of μ CT measurement artifacts, the volume between the screw threads was neglected. The height of the VOIs was taken constant at 13 mm, hence, 3 mm higher than the screw's length (Fig. 1b). This was motivated by the stress and strain distributions seen in microstructural FE analysis of two pilot tests. The radius of the cylindrical regions was varied between the radius of the outer thread (1.65 mm) and 6.0 mm.

2.3 Microstructural FE analysis

The μ FE meshes consisted of cubic hexagonal elements. A custom in-house mesher was used to generate the FE mesh of each sample directly from the μ CT data, employing a direct voxel-to-element approach. Meshing was performed on 8 dual-core 2.6 GHz AMD Opteron processors of a Cray XT3 system of the Swiss National Supercomputing Centre (CSCS, Manno, Switzerland). To reduce computational costs, the μ CT data was downscaled by a factor of three in all directions prior to meshing.

A common approach for μ FE analyses is to consider bone to be homogeneous at the tissue level; thus, the same isotropic Young's modulus is given to every element. In comparison studies it could be shown that there is a high degree of agreement between μ FE analyses and experimental test [30,41], even though diverse values for Young's modulus have been found. This could be explained by differences in experimental setup, as well as the finesse of the mesh. Furthermore, the influence of material anisotropy at the bone tissue level



Fig. 3 Biomechanical measurements suggested that failure seems to occur as soon as the effective strain levels in a characteristic fraction of the bone volume exceed a critical threshold of 0.7%. The force, resulting from the applied 1% displacement is scaled, such that a certain volume (highly stressed volume) of all elements in distal radius have effective strain values above 0.7% strain (after Pistoia et al. [43])

seems to be negligible as such good agreement was found not only in the main material direction, but also in perpendicular directions, which indicates that the anisotropic behavior of trabecular bone is mainly governed by the orientation of the trabeculae. Therefore, linear and isotropic material behavior was assumed for all materials used in the present study. Young's moduli were defined at 5, 114 and 2 GPa for bone, implant and PMMA, respectively; the Poisson ratios were set to 0.30, 0.34 and 0.36, respectively. Material properties of the titanium implant and the PMMA were defined based on the information from the manufacturers, whereas bone mechanical properties were based on reported values [30,41]. Boundary conditions that represented the biomechanical tests were defined. Hence, a displacement of 1% of the overall height of the models was applied to the outer end of the screw, while all nodes on the bottom of the models were restrained in direction of the loading only, except for two other nodes which were restricted in additional directions in order to prevent rotation and translations. The rest of the boundary is free. The interface between implant, bone and embedding material were modeled as full contacts, resulting in a model consisting of only one body with different material properties that represented the different components. For the solution of these models a fully parallel materially and geometrically linear custom finite element package ParFE, which works with a multilevel preconditioner, was used [38,42]. The models were processed on a Cray XT3 system on 720 dual-core 2.6 AMD Opteron processors with 1.4 TB of main memory. Post-processing was done using in-house code. Visualizations were created in parallel using open source program ParaView (http://www.paraview.org/) on 4 AMD Opteron CPU nodes with a total of 32 GB of memory on an HP-XC cluster.

Stiffness was determined by dividing the calculated reaction force by the prescribed displacement. Strength was estimated based on a structural hypothesis as developed for μ FE models of human distal forearms [43]. According to this concept, failure is expected to occur as soon as the effective strain levels in a characteristic fraction of the BV exceed a certain critical threshold. In the original formulation the characteristic BV fraction was set to 2% and the effective strain threshold was set to 0.7% (Fig. 3). Because it is questionable whether the exact same characteristic values are also applicable to bone-implant constructs and because of improved image resolution we set up an automated procedure to cover all combinations of the size of the VOI and the critical BV fraction. Specifically, the effective strain was calculated for all bone elements in the VOI that were defined for the μ CT analyses. The calculated external forces on the μ FE models were then scaled such that a specific element fraction exceeded a general effective strain threshold. This was done for all possible element fractions. Such scaling was possible because the μ FEA were fully linear. To determine optimal VOI and critical BV, linear correlations were performed between FE-calculated pullout strength and mechanically measured pullout strength

2.4 Statistical analysis

It was our aim to determine how well stiffness and strength of bone-implant constructs can be determined from μ FE models. To quantify that, the coefficient of determination (r^2) based on the Pearson product-moment correlation coefficient was used. All statistical analyses were performed with Excel 2003 (Microsoft, Redmond, USA).

3 Results

3.1 Experimental testing

All experimental tests were performed successfully, and resulted in similar force–displacement curves (Fig. 4). Pull-out stiffness was determined from the linear portion of the force–displacement curves in order to omit inelastic effects related to alignment of the experimental setup at the beginning of the experiment as well as plastic deformation prior to failure. Pull-out forces ranged from 495 up to 842 N, ultimate displacements from 0.66 to 1.46 mm and stiffness from 637 to 1,212 N/mm, respectively (Table 1). The average pull-out force for all ten specimens was 643 ± 118 N. All samples were treated as independent, because statistical analyses showed no relationships between vertebrae from the same sheep, nor between vertebrae at the same level from different sheep. A relatively good correlation between the pull-out force and the ultimate displacement ($r^2 = 0.58$) was found. Stiffness did not correlate to pull-out strength ($r^2 = 0.0001$).



Fig. 4 Force–displacement curves for all ten mechanical pull-out tests. Data recording started always at an initial pre-load of 10N. Pull-out strength was taken as the peak after which the measured force dropped by at least 20%. In order to determine stiffness, only the linear part of the curves were evaluated

Specimen	Vertebra	Pull-out strength (N)	Ultimate displacement (mm)	Stiffness (N/mm)
A	T2	709.0	1.15	833.7
А	Т3	744.4	1.46	636.9
В	T2	604.2	0.66	1,212.5
В	Т3	495.3	0.79	826.1
С	T1	740.1	1.04	1,025.8
С	T2	842.5	1.20	845.2
С	Т3	677.9	1.11	763.3
D	T1	518.6	0.84	846.3
D	T2	509.7	0.86	686.1
D	T3	588.2	0.87	926.7

 Table 1 Experimental results from the ten specimens tested

3.2 Microstructural FE analysis

All ten μ FE models were successfully created and analyzed. The meshing procedure took 536s for all models together. The number of elements in the models ranged from 12.1 to 17.9 million; the degrees of freedom from 50.7 to 87.2 million. The time needed to solve the models ranged from 115 to 200s; overall processing wall clock times were in between 134 and 270s.

A visual representation of the effective strain distribution of one representative specimen is given in Fig. 5a. The strain distribution is relatively homogenous as no clear differences in opposite bone regions around the implant can be seen.

Computationally analyzed stiffness ranged from 3,138 to 11,043 N/mm, with an average stiffness and standard deviation of all ten specimens of 7,419 \pm 2,420 N/mm. Thus, the computational results are close to a factor of 9 times higher than the measured stiffness. Furthermore, measured and μ FE-derived stiffness did not correlate ($r^2 = 0.002$).

On the other hand, the pull-out forces showed high correlations. The FE-calculated pull-out strength depended on the size of the VOI (radius of VOI) and on the amount of highly stressed volume. To determine optimal parameters, linear correlations were performed between FE-calculated pull-out strength and mechanically measured pull-out strength (Fig. 5b). Best correlation ($r^2 = 0.87$) was found when taking a VOI with a



Fig. 5 a Strain distribution (effective strain) of one typical specimen. Highest strains can be found at the bone microarchitecture close to the implant. **b** Parameter study investigating the correlation between measured and estimated pull-out strength. Critical bone volume fraction and the radius of the VOI were varied



Fig. 6 a Pull-out strength prediction based on FEA and BV depends on the volume of interest, represented here by the radius of the VOI. **b** Best prediction of measured pull-out strength was achieved for the pull-out strength as estimated by the FEA resulting in an r^2 of 0.87. Critical volume fraction was taken at 80%. The tissue effective strain threshold was set to 0.25%

radius of 4.7 mm in combination with a highly stressed BV fraction of 84%. It should be noted that the obtained correlations were relatively insensitive to the specific parameter values (Fig. 5b).

Bone volume was a good predictor of measured pull-out strength as well. Best linear correlation between measured pull-out strength and BV was achieved when taking a VOI with a radius of $1.94 \text{ mm} (r^2 = 0.86)$. Correlation coefficients for two indices, BV and FE-derived pull-out strength, are depicted in Fig. 6a where they were determined as a function of the size of the VOI. Finally, Fig. 6b shows the single specimen's correlation between the estimated and the measured pull-out force, demonstrating a very strong agreement between the two.

4 Discussion

In this study we assessed μ FE analysis as a technique to determine the pull-out strength of bone screws. High correlations were found between pull-out strength as estimated from μ FE and the experimentally measured pull-out strength. This indicates that μ FE analyses can be used as a tool for the assessment of stability and strength of bone-implant constructs. Such a system could be used for the evaluation of newly developed implant designs prior to animal testing, hence, could save costs and time. The development of new implant designs

could potentially be accelerated and improved. It could prove especially beneficial in the design process of implants for low quality osteoporotic bone, because that type of bone deviates most from the currently assumed homogeneous bone properties.

Good correlations were found between the BV surrounding the implant and the measured pull-out strength. BV predicted strength best when the VOI was small (Fig. 6a). The relatively high correlation of BV and measured failure load in a small VOI close to the implant seems to indicate that the bone in close contact with the screw is important in providing good anchoring of the screw. However, it has to be realized that correlations were highest for small VOI. The outer radius of the smallest VOI was 1.94 mm such that the wall thickness of the hollow cylinder is only 0.29 mm. Potentially, this could lead to imprecise and deviating results in subsequent studies as the analyzed region is only of the thickness of one trabecula. Even higher correlations ($r^2 = 0.87$) were obtained when μ FE analyses were used to estimate pull-out strength. These results support the assumption that the estimated failure forces as well as the analyzed surrounding BVs are both good parameters to predict the measured failure force of a bone-implant construct.

A limitation of the study is that artifacts in the acquired μ CT images could influence the μ FE results. In order to study this artifact related behavior, the solution would be to scan samples without an inserted screw. Afterwards the screw would have to be digitally added to the FE-model in order to compare these results with the 'conventional' method. Especially in the case of self-tapping screws this could be very interesting, since the bone debris, taken along with the screw on its way down, could be excluded possibly yielding better results.

Since we used a strictly linear solver, friction forces cannot be modeled and taken into account in the μ FE. This holds for the interface between PMMA and bone as well as for the one between bone and implant. We obtained a good predictive value for μ FE-based strength which seems to suggest that the frictional forces are relatively small, and that load transfer between bone and implant is mainly through interconnections of bone trabeculae and the screw thread. A study using screws with larger threads and diameters could provide more in-depth information into the extent of these frictional forces.

Where μ FE-predicted pull-out strength correlated well to experimentally measured strength, μ FE-predicted stiffness did not show the same high correlation to experimentally measured stiffness. Several potential sources for this behavior were identified. First, the embedding of the vertebrae turned out to be insufficient. Although we took great care to embed them properly, and to have an accurate screw alignment, the PMMA slipped slightly within the aluminum holders, thereby decreasing the measured stiffness. Such slipping most probably has not affected all samples to the same extent. Second, it is unknown whether there has been some slipping between the screw and the surrounding bone before failure, which would have increased the compliance. Third, potential lack in the experimental system, such as in the double ball joint, would have reduced measured stiffness further. These effects could not be simulated in the μ FE analyses. Fourth, we assumed identical bone tissue level properties for all vertebrae, whereas the actual material properties may have varied from vertebra to vertebra. And fifth, we used 5 GPa for bone tissue based on studies where bone tissue modulus was backcalculated from μ FE and experimental testing [30,41], but higher tissue moduli have been reported in the literature, especially when using measurements techniques that identified tissue properties on a smaller length scale. The inclusion of a deloading step during the experimental tests would potentially have allowed a more accurate determination of the elastic behavior of the surrounding bone [44]. It has to be noted though, that the test protocol as defined by ASTM 543 did not include deloading of the screw during the biomechanical measurement. Future studies using deloading may help to quantify the inelastic mechanisms involved in implant failure. And although the use of different tissue moduli would have changed the absolute values for bone-implant stiffness, we do not expect that the it would have had a significant influence on the correlation between experimentally determined stiffness and stiffness as derived from μ FEA.

In implant fixation a distinction can be made in the stability directly after implantation (primary implant stability) and the situation after several months when bone could potentially have grown onto the screw and establish a firm connection between implant and screw (secondary implant stability). Our experimental set-up clearly considers primary stability whereas our computational model could reflect the secondary stability because micromotion was not included in the μ FE analyses. Nevertheless, even when assuming fully bonded contact areas between implant and bone we achieved a strong correlation. This likely indicates that frictional forces only play a minor role in primary implant stability, and that stability is achieved through form-locking of the threads into the bone.

Sheep vertebrae have been widely used as a model for human vertebrae for in vivo [45] as well as for in vitro [46] experiments. A morphological study showed that similarities between sheep and human vertebrae are strongest in the thoracic and lumbar regions and suggests sheep spines as a good model for the investigation of spinal implants [47].

Specimens tested in this study displayed a high BV density, not comparable to low density osteoporotic bone. For these specimens the calculated stresses close to the implant were relatively homogenously distributed along the structure. It is expected that larger differences in stress distribution will occur when testing low density osteoporotic bones. Furthermore, we hypothesize that in these cases BV alone would no longer predict implant failure sufficiently well whereas μ FE could still do as this analysis incorporates not only density but also structural information. These aspects need further experimental validation.

We inserted the screws in the proximal surface of the sheep vertebrae. This is not a physiological location; typically in spinal surgery, screws are implanted in the pedicles or the lateral mass. For this project, however, simulating a realistic clinical condition was not the main purpose. Instead we aimed for a set-up that would be reproducible. We selected the proximal surface because this allowed us to use the distal surface support during embedding of the vertebrae, which eased a proper alignment of the screws. Furthermore, the rather oriented trabecular structure as seen in humans is less pronounced in sheep which was visible on μ CT images obtained in the preliminary study; hence, we expect that in sheep implant stability will be similar for axially and laterally placed screws.

There is no established computational technique to determine the pull-out strength for screws in trabecular bone. Furthermore, currently no μ FE solver is available that includes conventional fracture mechanics. For that purpose, we adapted a method originally described by Pistoia et al. [43] to estimate strength from a linear-elastic analysis. Specifically, we varied two parameters to determine which combination would provide best estimates of pull-out strength. Best correlation was found when taking a VOI with a radius of 4.7 mm in combination with a highly stressed BV fraction of 84%. The critical volume of 84% is much higher than the 2% as in the original formulation. That, however, is to be expected, since we determined this percentage in a relatively small VOI just around the screw, hence, in a volume that is highly stressed and where failure initiation will occur; in contrast the 2% came from analyses where all bone was included. It is noteworthy that a relatively large range in parameters provided good strength estimates (Fig. 5b). Based on our analyses we would recommend using a VOI with a wall thickness of about 2–4 mm, resulting in outer radii between 3.65 and 5.65 mm when considering the outer implant thread radius of 1.65 mm. In this volume around the implant stresses and strains are considerably higher than further away from the screw. Interestingly, μ FE analyses predict measured pull-out strength better than BV alone for these representatively large VOIs, indicating that μ FE analyses also include relevant aspects of bone architecture.

In summary, we successfully used μ FE analysis as a computational technique to determine the pull-out strength of bone screws. By using μ FE analysis it has become feasible to analyze the effect of individual trabeculae and its contribution to implant stability and pull-out strength. Hence, μ FE analyses may lead to a mechanistic understanding of why low density bone offers less potential for screw fixation than normal bone, and may aid to systematically develop more appropriate screws to treat osteoporotic fractures. We expect this to speed up the implant design process, because in the initial phases the amount of complicated and time consuming mechanical testing may be reduced through use of μ FE studies.

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