# ACOUSTIC FREE INDUCTION IN A QUADRUPOLAR SPIN SYSTEM IN A CUBIC CRYSTAL 

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#### Abstract

The bulk magnetisation vectors;excited by an acoustic pulse at magnotic reasonance has been calculated in a cubic orystal, where each lattice site is assumed to be occupiod by a nucleus of spin 1 (one). The Hamiltoniaik has been cast in a general form, for any interaction of the form $\overrightarrow{(I \cdot \vec{D} . I)}$, and calculation hai beon dono by setting up the Rabi-Bloch matrices, and neglecting, for simplicity, the spin-spin interactions. It is found that with a longitudinal excitation in one of tho cubic axos, the traneverse components of the average macroscopic moment vectors $\left\langle M_{x}\right\rangle{ }_{a v}$ and $\left\langle M_{y}\right\rangle a v$, are practically zero, being contributed by nucloi located at thin layers (of width equal to half wavolength of the acoustic waves) at tho two ends of the sample. The results are identical with those of Kessel (Kessel, 1962) who analysed the above situation by a first ordor time-dependent perturbation method.


## INTRODUCTION

The absorption of acoustic energy at magnetic reasonance in solids, when the reasonance is excited by an impressed acoustic field [Kastler (1952), Altshulen (1955), Jacobsen and Stevens (1963)], has bcen demonstrated both in pulsed [Jacobsen, Shiren and Tucker (1959), Tucker (1961), Shiren (1962), and Guermeur, Joffrin, Levelut and Penne (1964)] and CW [Proctor and Tantilla (1956), Proctor and Robinson (1956), Menes an. .Bolef (1958), Bolef and Menes (1959), and Bolef, de Klerk and Gosser (1962)] experiments. In such experiments one particular lattice mode is strongly excited, and the energy in tha lattice mode is transmitted to the spin system via the spin-phonon interaction. There must be some relaxation mechanism (other than the so-called direct process) that will maintain the Boltzman population excess in the spin system. And since the excitation is strong, effectively equalising the upward and the downward transition probabilities of a spin, there will be a net absorption of energy from the excited lattice mode. The amount of the absorption is a measure of the direct spin-phonon interaction that couples the particular lattice mode with the magnetic spin system. This fact, together with the absence of "penetration depth" effect in metals leads to soveral interesting possibilities that can be explored by acoustic magnetic resonance experiments. Already, quite a few experiments have been done yielding important results [Bolef and Menes (1961), Shiren (1962), and Guermeur, Joffrin, Levelut and Penne (1965)]

However, there has not been any induction experiment in this field, so far. The possibility of such an expeirment, using pulse technique, was analysed by Kessel (1962) a few years back. Although the method used in the analysis is sufficient for tackling the situation with simplifying assumptions, i.e. the neglect of spin-spin interaction, it is felt that a density matrix treatment of the phenomenon will be more convenient in more general causes*. We describe such a treatment which is similar to Lowe and Norberg's (1957) analysis of free induction in electromagnetically excited NMR. In our analysis we shall consider a cubic crystal, having lattice sites occupied by nuclei of spin 1 (one). The spin system will thus be coupled to the excited lattice mode by nuclear quadrupole interaction.

## ACOUSTICALLY INDUCED NUCLEAR MAGNETIC INDUCTION IN A CUBIC CRYSTAL

(A) Spin-phonon interaction Hamiltonian in a quadrupolar spin system in an acoustically excited cubic crystal: Let us write the interaction term in the form,

$$
\begin{equation*}
H=-\hbar \overrightarrow{\hbar(\vec{I} \cdot \vec{D} \cdot \vec{I})} \tag{1}
\end{equation*}
$$

where $\vec{I}$ is the nuclear spin vector, and $\vec{D}$ is a tensor of rank two in three dimension, containing the lattice coordinates. In a rectangular coordinate system ( $X, Y, Z$ ), where $Z$ is the axis of quantisation of the spin system (that is, the direction of the D.C. magnetic field), it will be seen that the tensor, $D$, is symmetric for the particular spin-lattice system. Expanding (1), we can thus write:

$$
\begin{align*}
H^{\prime}= & -\hbar\left[\frac { 1 } { 2 } \left(D_{x x}+D_{y y} \overrightarrow{I^{2}}+\frac{1}{2}\left(2 D_{z z}+D_{\alpha x}-D_{y y}\right) I_{z}^{2}+\right.\right. \\
& +\frac{1}{2}\left(D_{x x}-D_{y y}\right)\left(I_{+}^{2}+I_{-}^{2}\right)+D_{x z}\left(I_{\infty} I_{z}+I_{z} I_{x}\right)+ \\
& \left.+D_{y z}\left(I_{y} I_{z}+I_{z} I_{y}\right)+D_{x y}\left(I_{x} I_{y}+I_{y} I_{x}\right)\right] \tag{2}
\end{align*}
$$

Dropping the terms that couple states with $\Delta m=0$, we have :

$$
\begin{align*}
H^{\prime}=-\hbar\left[\frac{1}{4}\left(D_{x \infty}-D_{y y}\right)\left(I_{+}{ }^{2}+I_{-}{ }^{2}\right)\right. & +D_{x z}\left(I_{\alpha} I_{2}+I_{z} I_{x}\right)+D_{y^{2}}\left(I_{y} I_{z}+I_{z} I_{y}\right)+ \\
& +D_{x y}\left(I_{\infty} I_{y}+I_{y} I_{x}\right) \tag{3}
\end{align*}
$$

[^0]The components of $D$ are functions of the local strain at the nuclear sites, and one can expand $D$ in terms of the strain components $e_{i j}$ in a Taylors series. Thus introducing the spin-phonon coupling constant $G$, we can write (in Voigt notation) :

$$
D_{j}=D_{j}^{(0)}+\sum_{i} G_{j i} e_{i}+\text { higher order torms. } i, j=1,2,3, \ldots, 6 .
$$

where

$$
\begin{equation*}
G_{j_{i}}=\frac{\partial}{\partial e_{i}}(D,)_{e_{i} \rightarrow 0} \tag{4}
\end{equation*}
$$

In order to define $G$ uniquely, the (4) is written in the coordinate system $\left(X_{0}, \boldsymbol{Y}_{0}, \boldsymbol{Z}_{0}\right)$ that coincides with the crystallographic axes. This also enables one to simplify the expansion (4) by using ymmetry arguments. For example, in cubic symmetry, we have the expansion:

$$
\begin{array}{ll}
D_{x_{0} x_{0}}=\frac{G_{11}}{2}\left(2 e x_{0} x_{0}-e y_{0} y_{0}-e z_{0} z_{0}\right), & D x_{0} y_{0}=G_{44} e x_{0} y_{0} \\
D y_{0} y_{0}=\frac{G_{11}}{2}\left(2 e y_{0} y_{0}-e z_{0} z_{0}-e x_{0} x_{0}\right), & D_{y_{0} z_{0}}=G_{44} e y_{0} z_{0} \\
D z_{0} z_{0}=\frac{G_{11}}{2}\left(2 e z_{0} z_{0}-e x_{0} x_{0}-e y_{0} y_{0}\right), & D z_{0} z_{0}=G_{44} e x_{0} z_{0} \tag{5}
\end{array}
$$

The components of $D$, used in the Hamiltonian (3) can then be obtained by using the following usual transformation relations:

$$
\begin{align*}
& D_{i i}=\sum_{(\nu \mu)} \alpha_{!\nu} \alpha_{i \mu} D_{v \mu} \\
& D_{i j}=\sum_{(v \mu)}\left(a_{i \nu} a_{j \mu}+\alpha_{j \nu} a_{i \mu}\right) D_{\nu \mu} \tag{6}
\end{align*}
$$

where

$$
(\nu \mu) \equiv\left(x_{0} x_{0}\right),\left(y_{0} y_{0}\right),\left(z_{0} z_{0}\right),\left(x_{0} y_{0}\right),\left(y_{0} z_{0}\right), \text { and }\left(x_{0} z_{0}\right) .
$$

and the coefficients $a$ are given in table I.

## TABLE I

Transformation coefficients. ' $a_{t \nu}$ ', for two Cartesian coordinate systems, $i$ and $\nu$, having the same origin and their mutual orientation being specified by the Eulerian angles $\theta, \phi$ and $\psi$.

| $i x_{0}$ | $y_{0}$ | $z_{0}$ |  |
| :---: | :---: | :---: | :---: |
| $x$ | $\cos \psi \cos \phi \cos \theta+\sin \psi \sin \phi$ | $\cos \psi \sin \phi \cos \theta-\sin \psi \cos \phi$ | $\cos \psi \sin \theta$ |
| $y$ | $\sin \psi \cos \phi \cos \theta-\cos \psi \sin \phi$ | $\sin \psi \sin \phi \cos \theta+\cos \psi \cos \phi$ | $\sin \psi \sin \theta$ |
| $z$ | $-\cos \phi \sin \theta$ | $-\sin \phi \sin \theta$ | $\cos \theta$ |

We will now consider a special case. Let us assume that a longittudinal acoustic wave of circular frequency $\omega$ has been improssed in the crystal with the propagation vector in the crystallographic (001) direction. We also assume that the laboratory $Y$-direction and the crystal (010) directions coincide, and the crystal has been rotated about the $Y$-axis such that the propagation vector $\overrightarrow{\boldsymbol{k}}$ (still in the crystal (001) direction) makes an angle $\theta$ with the D.C. magnetic field, ie. the Zdirection. This longitudinal wave will generate a standing wave pattern, and an axially symmetric strain field (time-dependent) in the crystal, the axis of symmetry being in the direction of $\overrightarrow{\boldsymbol{k}}$. Let us also choose the laboratory $X$-axis such that it coincides with the projection of $\vec{K}$ on the $X-Y$ plane. In such a case, we see that the only strain component is $e z_{0} z_{0}$, where the direction $z_{0}$ is the crystal (001) and thus from (5), we get :

$$
\begin{align*}
& D_{z_{0} z_{0}}=G_{11} e_{z_{0}} z_{0} \\
& D_{x_{0} x_{0}}=D_{y_{0} y_{0}}=-\frac{G_{11}}{2} e e_{0} z_{0}  \tag{7}\\
& D_{x_{0} y_{0}}=D y_{0} z_{0}=D_{z_{0} x_{0}}=0
\end{align*}
$$

Transforming (7) into the ( $X Y Z$ ) system (using (6), and the table I, with $\phi=\psi$ $=0$ ),

$$
\begin{array}{ll}
D_{z z}=\frac{G_{11}}{2} e z_{0} z_{0}\left(3 \cos ^{2} \theta-1\right), & D_{x z}={ }_{2}^{3} G_{11} e_{z_{0} z_{0}} \sin \theta \cos \theta \\
D_{x x}=\frac{G_{11}}{2} e z_{0} z_{0}\left(3 \sin ^{2} \theta-1\right), & D_{x y}=D_{y z}=0 \\
D_{y y}=-\frac{G_{11}}{2} e z_{0} z_{0} & \tag{8}
\end{array}
$$

The Hamiltonian (3) then becomes :

$$
\begin{equation*}
H^{\prime}=-\hbar\left[\frac{3}{8} G_{11} e_{z_{0} z_{0}}\left(I_{+}{ }^{2}+I_{-}{ }^{2}\right) \sin ^{2} \theta+\frac{3}{4} G_{11} e z_{0} z_{0}\left(I_{\infty} I_{2}+I_{2} I_{\infty}\right) \sin 2 \theta\right] \tag{9}
\end{equation*}
$$

The above formulation holds for any interaction of the form (1). Nuclear quadrupolar interaction is also of this form and the Hamiltonian (9) is applicalbe to this case. The constants $G_{14}$ etc. in (9) can be measured by suitable experiments,

However, to obtain the theoretical expression for $G_{11}$, one has to consider the particular interaction, in this case nuclear quadrupolar interaction, explicitly.

Writing

$$
H^{\prime}=-\hbar \overrightarrow{\vec{Q})}:(\vec{\nabla} \overrightarrow{\vec{E})}
$$

where $\vec{Q}$ is the nuclear quadrupole moment tensor, and $(\overrightarrow{\nabla E})$, the clectric field gradient tensor at the nuclear site, one obtaias in this special case.

$$
\begin{equation*}
\left.G_{11}=A e \frac{\partial}{\partial e z_{0} z_{0}}(q)\right]_{e z_{0} z_{0} \rightarrow 0} \tag{10}
\end{equation*}
$$

where
and

$$
A=\frac{e Q}{2 I(2 I-1)}
$$

and

$$
e q=\sum_{j} e_{j}\left(3 \cos ^{2} \theta_{j}-1\right) r_{j}^{-s}
$$

$Q$ is the scalar quadrupole moment of the nucleus, and 'eq' is the axial electric field gradient with the symmetry axis along the $z_{0}$-axis. In the definition of 'eq', $j$ refers to the $j$ th. charge-point external to the nucleus, and $\vec{r}_{j}$ is the vector joining this charge-point with the origin (the center of the nucleus), and $\theta_{j}$ is the angle between $\vec{r}_{j}$ and the symmetry axis.
(b) Total Hamiltonian for the spin-lattice system : The total Hamiltonian can thus be written as

$$
\begin{equation*}
H=H_{0}+H_{1}+H_{2}+H^{\prime}(t) \tag{l1}
\end{equation*}
$$

$H_{0}$ is the Zeeman Hamiltonian for the spin system, $H_{1}$ describes the magnotic dipole interaction between the spins, and $H_{2}$ stands for all other terms in the total Hamiltonian for the statistic spinlattice system. $H^{\prime}(t)$ is given by the expression (9). If. we neglect those parts of $H_{1}$ and $H_{2}$ that couples states with $\Delta m \neq 0$, we are left with the following Hamiltonian :

$$
\begin{equation*}
H=H_{0}+H^{\prime}(t) \tag{12}
\end{equation*}
$$

where

$$
H_{0}=-\hbar \sum_{n} \omega_{0} I z_{n}
$$

and

$$
H^{\prime}(t)=-\hbar \sum_{n}\left[2 \omega_{n}^{(1)}\left(I_{x_{n}} I z_{n}+I_{z_{n}} I x_{n}\right)+\omega_{n}^{(2)}\left(I^{2}+n+I^{2}-n\right)\right] \cos \omega t
$$

with

$$
\begin{align*}
\omega_{0} & =\gamma H_{0} \\
\omega^{(1)} & =\frac{3}{8} G_{11} e z_{0} z_{0}(0) \sin 2 \theta \\
\omega^{(2)} & =\frac{3}{8} G_{11} e z_{0} z_{0}(0) \sin ^{2} \theta \tag{13}
\end{align*}
$$

It has been assumed that $e z_{0} z_{0}=e x_{0} z_{0}(0) \cos w t$, and $\gamma$ is the gyromagnetic ratio for the nucleus. We shall be concerned with the cases where $H^{\prime}(t)$ can be treated as a small perturbation.
(C) Rabi-Bloch matrices for the system : The Schrodinger equation is:

$$
\begin{equation*}
i \hbar \frac{\sigma}{\partial t} \psi(t)=H(t) \psi(t) \tag{14}
\end{equation*}
$$

If we write $\psi(t)=\exp \left(-\frac{i t}{\hbar} H(0)\right) \psi^{\prime}(t)$, the equation (14) transforms into

$$
\begin{equation*}
\exp \left(\frac{i t}{\hbar} H(0)\right) H^{\prime}(t) \exp \left(-\frac{i t}{\hbar} H(0)\right) \psi^{\prime}(t)=i \hbar \frac{\partial}{\partial t} \psi^{\prime}(t) \tag{15}
\end{equation*}
$$

We now assume that the acoustic wave is impressed only for a duration $t_{\omega}$, in the form of a square pulse of carrier frequency $\omega$, and that $t_{\omega}$ is sufficiently small so that those terms in $H_{1}$ and $H_{2}$ which do not commute with $H^{\prime}(t)$ or $H(0)$ have expectation values much less than 1 when multiplied by $t_{\infty} / \hbar$. Their effect upon $H^{\prime}(t)$ may then be ignored. Thus retaining only the terms $H_{0}$ in $H(0)$ the equation (15) is approximated as :

$$
\begin{equation*}
\exp \left(-i \omega_{0} t \sum_{n} I_{z_{n}}\right) H^{\prime}(t) \exp \left(i \omega_{0} t \sum_{n} I_{z_{n}}\right) \psi^{\prime}(t)=i \hbar \frac{\partial}{\partial t} \psi^{\prime}(t) \tag{16}
\end{equation*}
$$

Using the transformation properties of the spin operators under the rotation about the $Z$-axis, the equation (16) reduces to

$$
\begin{equation*}
i L(t) \psi^{\prime}(t)=\frac{\partial}{\partial t} \psi^{\prime}(t) \tag{17}
\end{equation*}
$$

where

$$
\begin{align*}
& L(t)=\Sigma\left[2 \omega_{n}{ }^{(1)}\left\{\left(I x_{n} I_{z_{n}}+I_{z_{n}} I_{x_{n}}\right) \cos _{0} \omega_{0} t+\left(I_{y_{n}} I_{\varepsilon_{n}}+I_{z_{n}} I_{y_{n}}\right) \sin \omega_{0} t\right\}\right. \\
& \left.+2 \omega_{n}{ }^{(2)}\left\{\left(I_{x_{n}}{ }^{2}-I_{y_{n}}{ }^{2}\right) \cos 2 \omega_{0} t+\left(I_{x_{n}} I_{y_{n}}+I_{y_{n}} I_{x_{n}}\right) \sin 2 \omega_{0} t\right\}\right] \cos \omega t \tag{18}
\end{align*}
$$

The solution of (17) is

$$
\begin{equation*}
\psi^{\prime}\left(t_{\omega}\right)=\exp \left\{i \int_{-}^{t_{m}} L(t) d t\right\} \psi^{\prime}(0) \tag{19}
\end{equation*}
$$

which reduces to (neglecting small terms containing $\boldsymbol{t}_{\omega}$ ),

$$
\psi\left(t_{\omega}\right)=R_{\omega=\omega_{0}} \psi(0), \quad \text { when } \quad \omega=\omega_{0}
$$

and

$$
\begin{equation*}
\psi\left(t_{\omega}\right)=R_{\omega}=2 \omega_{0} \psi(0), \quad \text { when } \quad \omega=2 \omega_{0} \tag{20}
\end{equation*}
$$

where

$$
\begin{gather*}
R_{\omega=\omega_{0}}=\exp \left(i \theta_{1} \sum_{n} I_{z_{n}}\right) \exp \left\{i \sum_{n} \theta_{2 n}\left(I_{y_{n}} I_{x_{n}}+I_{z_{n}} I_{x_{n}}\right)\right\} \\
R_{\omega=2 \omega_{0}}=\exp \left(i \theta_{1} \sum_{n} I_{z_{n}}\right) \operatorname{ixp}\left\{i \sum_{n} \theta_{n_{n}}\left(I_{x_{n}}{ }^{2}-I_{y_{n}}{ }^{2}\right)\right\} \\
O_{1}=\omega_{0} t, \quad \theta_{2}=\omega^{(1)} t_{\omega} \text { and } \theta_{3}=\omega^{(2)} t_{\omega} . \tag{21}
\end{gather*}
$$

In a representation in which $I_{z}$ is diagonal, the matrices $R_{\omega}=\omega_{0}$ and $R_{\omega}-2 \omega_{0}$ have been evaluated. The results for spin $I=1$ are given in tables II and 111.
(D) Computation of $<M_{x}>_{a_{v}},<M_{v}>_{a_{v}}$ and $<M_{2}>_{a_{v}}$ : We know that if we assume that the solution of the time-dependent Schrodinger equation :

$$
i \hbar \frac{\partial}{\partial t} \psi_{n}(t)=H_{n}(t) \psi_{n}(t)
$$

is of the form
then

$$
\psi_{n}(t)=R_{n}(t) \psi_{n}(0)
$$

$$
\begin{equation*}
<I_{\mathbf{x}_{n}}>=\int \psi_{n}{ }^{+}(0) R_{n}^{+}(t) I_{\mathbf{x}_{n}} R_{n}(t) \psi_{n}(0) d \tau \tag{22}
\end{equation*}
$$

Expanding

$$
\psi_{n}(0)=\sum_{p} a p_{n}(0) u_{p_{n}}
$$

we have

$$
\begin{equation*}
<I_{x_{n}}>=\operatorname{Trace}\left\{\rho_{n}(0) R_{n}^{+}(t) I_{x_{n}} R_{n}(t)\right\} \tag{23}
\end{equation*}
$$

where

$$
\begin{equation*}
<u q_{n}\left|\rho_{n}(0)\right| u p_{n}>=a p_{n}{ }^{*}(0) a q_{n}(0) \tag{24}
\end{equation*}
$$

For a system of $N$ spins, if we neglect the mutual interactions between the spins, we obtain

$$
\begin{equation*}
\left\langle\vec{M}>_{a_{v}}=\sum_{n}^{1,2, . . N} \text { Trace }\left\{\frac{\left.\exp \left(\zeta I_{z_{n}}\right) R_{n}+\gamma \hbar\left(\overrightarrow{i I_{x_{n}}}+\vec{j} \vec{I}_{y_{n}}\right)+\vec{k} I_{z_{n}}\right) R_{n}}{\text { Trace }\left\{\exp \left(\zeta I I_{n}\right)\right\}}\right\} \cdots\right. \tag{25}
\end{equation*}
$$

where $\exp \left(\zeta I I_{n}\right) /$ Trace $\left\{\exp \left(\zeta I_{r_{n}}\right)\right\}$ has been taken as equal to $\rho_{n}(0) . \zeta=\gamma \hbar$ $H_{0} / k T, T$ being the temperature of the sample and $k$, the Boltzman factor. The spin
system is here assumed to be at thermal equilibrium before the application of the acoustic pulse.

We the $R$ matrices as given in tables II and III, and using the expression (25) we get the following expressions for the induced bulk nuclear magnetisation at the ond of the acoustic pulse.

## TABLE II

The matrix, $R_{\omega=\omega 0}$, for $\operatorname{spin} I=1$, in a representation in which $I_{z}$ is diagonal. The elements are $\langle q| K|p\rangle$, and $S_{0} \theta_{2} \equiv$ the sign of the angle $\theta_{2}$.

| ${ }_{9}{ }^{p}$ | 1 | 0 | -1 |
| :---: | :---: | :---: | :---: |
| 1 | $\exp \left(i \theta_{1}\right)\left(1+\cos \theta_{2}\right) / 2$ | $S_{\theta} \theta_{2}\left(i \exp \left(i \theta_{1}\right) \sin \theta_{2}\right) / \sqrt{\overline{2}}$ | $\exp \left(i \theta_{1}\right)\left(1-\cos \theta_{2}\right) / 2$ |
| 0 | $S_{9} \theta_{2}\left(i \sin \theta_{2}\right) / \sqrt{2}$ | $\cos \theta_{2}$ | $S_{g} \theta_{2}\left(-i \sin \theta_{2}\right) / \sqrt{2}$ |
| -1 | $\exp \left(i \theta_{1}\right)\left(1-\cos \theta_{2}\right) / 2$ | $S_{g} \theta_{2}\left(-i \exp \left(-i \theta_{1}\right) \sin \theta_{2}\right) / \sqrt{ } 2$ | $\exp \left(-i \theta_{1}\right)\left(1+\cos \theta_{2}\right) / 2$ |

## TABLE III

The matrix $R_{\omega=2 \omega 0}$, for spin $I=1$, in a representation in which $I_{z}$ is diagonal. The elements are $\langle q| R|p\rangle$, and $S_{g} \theta_{3} \equiv$ the sign of the angle $\theta_{3}$.

| $q$ | $p$ | 0 | -1 |
| :---: | :---: | :---: | :---: |
| 1 | $\exp \left(i \theta_{1}\right) \cos \theta_{3}$ | 0 | $\operatorname{sg} \theta_{3}\left(i \exp \left(i \theta_{1}\right) \sin \theta_{3}\right)$ |
| 0 | 0 | 1 | 0 |
| -1 | $S_{0} \theta_{3}\left(i \exp \left(-i \theta_{1}\right) \sin \theta_{3}\right)$ | 0 | $\exp \left(-i \theta_{1}\right) \cos \theta_{3}$ |

Case I. $\quad \omega=\omega_{0}$

$$
\begin{align*}
& <M_{\infty}>_{a v}=\gamma \hbar \frac{\cosh \zeta-1}{1+2 \cosh \zeta} \sin \theta_{1} \sum_{n}^{1,2, \ldots, \mathrm{~N}} S_{\rho}\left(\theta_{n}\right) \sin 2 \theta 2_{n} \\
& <M_{y}>_{a v}=\gamma \hbar \frac{\cosh \zeta-1}{1+2 \cosh \zeta} \cos \theta_{1} \sum^{1,2, \ldots, \mathrm{~N}} S_{\rho}\left(\theta_{\left.2_{n}\right)} \sin 2 \theta 2_{n}\right. \\
& <M_{z}>_{a_{v}}=\gamma \hbar \frac{\sinh \zeta}{1+2 \cosh \zeta} \sum^{1,2, \ldots} \cos \theta 2_{n} \tag{26}
\end{align*}
$$

Case II.

$$
\begin{align*}
\omega & =2 \omega_{0} \\
<M_{\infty}>_{a v} & =0 \\
<M_{y}>_{a v} & =0 \\
<M_{z}>_{a v} & =\gamma^{\hbar} \frac{2 \sinh \zeta}{1+2 \cosh \zeta} \sum^{1,2, ., \mathrm{N}} \cos 2 \theta_{3_{n}} \tag{27}
\end{align*}
$$

After the withdrawal of the pulse, the time-dependence of $\left\langle M_{x}\right\rangle_{a v}$ and $<M_{y}>_{a_{e}}$ will be given as usual by the Fourier transform of the steady NMR line shape.

Refering to (26), and from the definitions of $\theta_{2}$ as given in (21) and (13), we see that

$$
\begin{equation*}
\sum_{n} S_{0}\left(\theta 2_{n}\right) \sin 2 \theta 2_{n}=\sum_{n} S_{0}\left\{a \cdot e^{(n)} z_{z_{0} z_{0}}(0)\right\} \sin \left\{\frac{a}{2} e^{(n)} z_{z_{0}} z_{0}(0)\right\} \tag{28}
\end{equation*}
$$

where

$$
a=\left\{\frac{8}{8} G_{11} \sin 2 \theta\right\} t_{\omega} .
$$

$e^{(n)} z_{0} z_{0}(0)$, for a standing wave pattern where end surfaces of the sample are at antinodes, may be written as

$$
e^{(n)_{z_{0}} z_{0}}(0)=2 K A_{0} \sin K Z_{n}
$$

and hence we see from (28) that the main contribution to the summation will come from the two layors at the ends of the sample, layers having a thickness "l" given by

$$
k l=\pi / 2 \text { or } l=\lambda / 4
$$

As an example, for experiment at $10 \mathrm{mc} / \mathrm{s}, l \cong 10^{-2} \mathrm{~cm}$. and an insignificantly small number of nuclei aro taking effective part in contributing to $\left.<M_{\boldsymbol{x}}\right\rangle_{\text {av }}$ and $<M_{y}>{ }_{\text {av }}$.

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[^0]:    *We may note that the density-matrix method is effictively equivalent to the ordinary time-dependent perturbation method, upto certain degree of approximation. However, the former is different from the latter when the actual calculation is concerned. In the timedepondent porturbation method, one expands the time-dependent wave function in a complete set of time-independent basis functions, and solves for the expansion coefficients $a_{m}, a_{n}$ etc. from a set of coupled differential equations. One popular way of doing this is to reduce these differential equations to a set of coupled algebraic equations by making use of Laplace Transforms. In general, it is difficult to obtain these transforms. However, in density-matrix method one avoids this difficulty by calculating the products* ( $a_{n} a_{m}$ ) which are more directly useful for calculating expectation values.

