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## MULTIPLE SOLUTIONS TO A SINGULAR LANE-EMDEN-FOWLER EQUATION WITH CONVECTION TERM

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ABSTRACT. This article concerns the existence of multiple solutions for the problem

$$\begin{aligned} -\Delta u &= K(x)u^{-\alpha} + s(\mathcal{A}u^\beta + \mathcal{B}|\nabla u|^\zeta) + f(x) & \text{in } \Omega \\ u &> 0 & \text{in } \Omega \\ u &= 0 & \text{on } \partial\Omega, \end{aligned}$$

where  $\Omega$  is a smooth, bounded domain in  $\mathbb{R}^n$  with  $n \geq 2$ ,  $\alpha, \beta, \zeta, \mathcal{A}, \mathcal{B}$  and  $s$  are real positive numbers, and  $f(x)$  is a positive real valued and measurable function. We start with the case  $s = 0$  and  $f = 0$  by studying the structure of the range of  $-u^\alpha \Delta u$ . Our method to build  $K$ 's which give at least two solutions is based on positive and negative principal eigenvalues with weight. For  $s$  small positive and for values of the parameters in finite intervals, we find multiplicity via estimates on the bifurcation set.

### 1. INTRODUCTION

Singular bifurcation problems of the form

$$\begin{aligned} -\Delta u &= K(x)u^{-\alpha} + s\mathcal{G}(x, u, \nabla u) + f(x) & \text{in } \Omega \\ u &> 0 & \text{in } \Omega \\ u &= 0 & \text{on } \partial\Omega \end{aligned} \tag{1.1}$$

where  $\alpha$  is a positive number,  $K(x)$  is a bounded measurable function,  $\mathcal{G}(x, \cdot, \cdot)$  a non-negative Carathéodory function,  $f(x)$  a non-negative bounded measurable function and  $\Omega$  a bounded domain in  $\mathbb{R}^n$ , are used in several applications. As examples, we mention: Modelling heat generation in electrical circuits [17], fluid dynamics [7, 8, 27], magnetic fields [25], diffusion in contained plasma [26], quantum fluids [18], chemical catalysis [2, 28], boundary layer theory of viscous fluids [37], super-diffusivity for long range Van der Waal interactions in thin films spreading on solid surfaces [19], laser beam propagation in gas vapors [31, 32] and plasmas [33], exothermic reactions [6, 36], cellular automata and interacting particles systems with self-organized criticality [9], etc.

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Our main concern in this paper is on the existence of multiple solutions for the problem

$$\begin{aligned} -\Delta u &= K(x)u^{-\alpha} + s(\mathcal{A}u^\beta + \mathcal{B}|\nabla u|^\zeta) + f(x) && \text{in } \Omega \\ u &> 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega, \end{aligned} \tag{1.2}$$

where  $\Omega$  is a smooth, bounded domain in  $\mathbb{R}^n$  with  $n \geq 2$ ,  $\alpha, \beta, \zeta, \mathcal{A}, \mathcal{B}$  and  $s$  are real positive numbers and  $f(x)$  is a non-negative measurable function.

We start with the case  $s = 0$  and  $f \equiv 0$ . The situation with positive  $K$  has been widely studied by several authors. For example in [4, 14, 17, 22, 24, 29], under different hypothesis on  $K$ , they prove the existence and unicity of solutions for equation (1.2). In Theorem 2.4, we build a family of  $K$ 's, such that problem (1.2), with  $s = 0$ ,  $f \equiv 0$  and  $\alpha$  positive small enough has at least two solutions. We apply the classical Lyapunov-Schmidt method to the map  $F : \mathcal{C}^+ \rightarrow \mathcal{D}$ ,

$$F(u) = -u^\alpha \Delta u \tag{1.3}$$

where  $\mathcal{C}^+$  is defined in (3.4, 3.5) and  $\mathcal{D}$  is defined in (3.6) to search a bifurcation point for  $F(u)$ . This point will be an eigenfunction corresponding to a negative principal eigenvalue of a linear weighted eigenvalue problem. To prove it, we give a Lemma concerning the localization of the maximum value of such an eigenfunction (see Lemma 2.1). We also use a Harnack inequality to establish a necessary estimate (see Lemma 2.3). A final technical matter is differentiability of  $F(u)$  (Lemma 3.1). To our knowledge there are no previous similar results for (1.2) with  $s = 0$  and  $f \equiv 0$ .

Concerning the existence of at least one solution to (1.1) or (1.2) we may recall:

For  $K(x) \equiv 1$ ,  $\mathcal{A} = 1$ ,  $\mathcal{B} = 0$ ,  $f \equiv 0$ ,  $\alpha > 0$  and  $\beta > 0$  in (1.2), Coclite-G. Palmieri [13] have shown that there exists  $0 < s^* \leq \infty$  such that this problem (1.2) has at least one solution for all  $s \in (0, s^*)$ .

Similar results for problem (1.2) can be found in Zhang and Yu [35] under the conditions  $K(x) \equiv 1$ ,  $\alpha > 0$ ,  $\mathcal{A} \equiv 0$ ,  $\mathcal{B} \equiv 1$ ,  $0 < \zeta \leq 2$  and  $f(x)$  equivalent to a non-negative constant.

In a recent work about (1.1), Ghergu and Rădulescu [20] prove existence and nonexistence results for a more general singular equation. They study

$$\begin{aligned} -\Delta u &= g(u) + \lambda|\nabla u|^\zeta + \mu f(x, u) && \text{in } \Omega \\ u &> 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega, \end{aligned} \tag{1.4}$$

where  $g : (0, \infty) \rightarrow (0, \infty)$  is a Hölder continuous function which is non-increasing and  $\lim_{s \searrow 0} g(s) = \infty$ . They prove in [20, Theorem 1.4]) that for  $\zeta = 2$ ,  $f \equiv 1$  and fixed  $\mu$ , (1.4) has a unique solution. Under the assumption  $\limsup_{s \searrow 0} s^\alpha g(s) < +\infty$ , they also prove existence of a bifurcation at infinity for some  $\lambda^* < \infty$ . In this article we also obtain bifurcations from infinity at  $s = 0$  (see Theorems 2.7 and 2.8).

Concerning existence of multiple solutions for problem (1.2), Haitao [23], using a variational method, proves existence of two classical solutions under the assumptions  $K(x) \equiv 1$ ,  $0 < \alpha < 1 < \beta \leq \frac{N+2}{N-2}$ ,  $\mathcal{A} = 1$   $s \in (0, s^*)$  for some  $s^* > 0$ ,  $\mathcal{B} \equiv 0$  and  $f \equiv 0$ . We remark that our problem (1.2) has not a variational structure because of the convection term  $\mathcal{B}|\nabla u|^\zeta$ .

Aranda and Godoy [5] proved the existence of two weak solutions for the problem, involving the  $p$ -laplacian,

$$\begin{aligned} -\Delta_p u &= g(u) + s\mathcal{G}(u) && \text{in } \Omega \\ u &> 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega, \end{aligned} \tag{1.5}$$

where  $s > 0$  is small enough. This is done under the assumptions

- (i)  $g : (0, \infty) \rightarrow (0, \infty)$  is a locally Lipschitz and non-increasing function such that  $\lim_{s \searrow 0} g(s) = \infty$ .
- (ii)  $1 < p \leq 2$ ,  $\mathcal{G}$  is a locally Lipschitz on  $[0, \infty)$ ,  $\inf_{s>0} \mathcal{G}(s)/s^{p-1} > 0$  and  $\lim_{s \rightarrow \infty} \mathcal{G}(s)/s^q < \infty$  for some  $q \in (p-1, n(p-1)/(n-p)]$ .
- (iii)  $\Omega$  is a bounded convex domain.

We remark that for  $p = 2$  and using the change of variable  $v = e^u - 1$  (see [20]), we can immediately obtain existence of two classical solutions of the singular problem with a particular convection term

$$\begin{aligned} -\Delta u &= \frac{g(e^u - 1)}{e^u} + s \frac{\mathcal{G}(e^u - 1)}{e^u} + |\nabla u|^2 && \text{in } \Omega \\ u &> 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

for  $s$  is small enough. In comparison with this result, Theorems 2.8 and 2.9 give results on the existence of two classical solutions for  $\zeta \neq 2$ . This indicates a complex relation between the convection term, the function  $f(x)$  and the domain  $\Omega$ .

For dimension  $n = 1$  results on multiplicity can be found, for example, in Agarwal and O'Reagan [1].

To prove Theorems 2.7, 2.8 and 2.9, we apply an "inverse function" strategy. We use that problem  $-\Delta u = u^{-\alpha} + f(x)$  in  $\Omega$ ,  $u = 0$  on  $\partial\Omega$ ,  $u > 0$  on  $\Omega$  (see Theorem 3.1 in [4]) has a unique solution for  $f(x) \geq 0$ . Moreover the solution operator defined by  $H(f) := u$  is a continuous and compact map from  $P$  into  $P$ , where  $P$  is the positive cone in  $C^1(\overline{\Omega})$  (see Lemma 3.2 and Lemma 3.3). Therefore, we may write the problem (1.1) as  $u = H(s\mathcal{G}(x, u, \nabla u) + f(x))$ .

Properties of  $H$  and a classical theorem on nonlinear eigenvalue problems stated in [3], give existence of an unbounded connected set of solution pairs  $(s, u)$ , in an appropriate norm, to problem (1.1). Estimates on this solution set, combined with nonexistence results, give a bifurcation from infinity at  $s = 0$ . We use similar ideas to establish Theorems 2.8 and 2.9.

## 2. STATEMENT OF THE MAIN RESULTS

Let us consider the weighted eigenvalue problem

$$\begin{aligned} -\Delta u &= \lambda m(x)u && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega, \end{aligned} \tag{2.1}$$

where  $\Omega$  is a bounded domain in  $\mathbb{R}^n$ . Suppose  $m = m^+ - m^-$  in  $L^\infty(\Omega)$ , where  $m^+ = \max(m, 0)$ ,  $m^- = -\min(m, 0)$ . Denote

$$\Omega_+ = \{x \in \Omega : m(x) > 0\}, \quad \Omega_- = \{x \in \Omega : m(x) < 0\}$$

and  $|\Omega_+|, |\Omega_-|$  its Lebesgue measures. It is well known (see [16] for a nice survey) that if  $|\Omega_+| > 0$  and  $|\Omega_-| > 0$ , then (2.1) has a double sequence of eigenvalues

$$\dots \leq \lambda_{-2} < \lambda_{-1} < 0 < \lambda_1 < \lambda_2 \leq \dots,$$

where  $\lambda_1$  and  $\lambda_{-1}$  are simple and the associated eigenfunctions  $\varphi_1 \in C(\overline{\Omega}), \varphi_{-1} \in C(\overline{\Omega})$  can be taken  $\varphi_1 > 0$  on  $\Omega, \varphi_{-1} > 0$  on  $\Omega$ . Where  $\lambda_1$  and  $\lambda_{-1}$  are the principal eigenvalues of (2.1)  $\varphi_1$  and  $\varphi_{-1}$  are the associated principal eigenfunctions. Our first result is as follows.

**Lemma 2.1.** *Suppose  $m = m^+ - m^-$  in  $L^\infty(\Omega)$  such that  $|\Omega^+| > 0, |\Omega^-| > 0$ . Then the principal eigenfunctions  $\varphi_1 > 0, \varphi_{-1} > 0$  of (2.1) satisfy*

$$\begin{aligned} \|\varphi_1\|_{L^\infty(\Omega)} &= \|\varphi_1\|_{L^\infty(\text{rmsupp } m^+, m^+ dx)} \\ \|\varphi_{-1}\|_{L^\infty(\Omega)} &= \|\varphi_{-1}\|_{L^\infty(\text{rmsupp } m^-, m^- dx)} \end{aligned} \tag{2.2}$$

where  $\|\varphi_1\|_{L^\infty(\text{rmsupp } m^+, m^+ dx)}$  (respectively  $\|\varphi_{-1}\|_{L^\infty(\text{rmsupp } m^-, m^- dx)}$ ) is the essential supremum on  $\text{rmsupp } m^+$  with respect to the measure  $m^+ dx$  (respectively on  $\text{rmsupp } m^-$  w. r. t.  $m^- dx$ ).

Here  $\text{rmsupp } m^+$  is the support of the distribution  $m^+$  in  $\Omega$ . We take  $s = 0$  in (1.1) or (1.2) and look for multiple solutions of

$$\begin{aligned} -u^\alpha \Delta u &= K(x) \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned} \tag{2.3}$$

We fix  $p > n$  and consider  $K \in L^p(\Omega)$ . It is shown in [4] that for  $\alpha > 0, 0 < K \in L^p(\Omega)$ , (2.3) has a unique solution  $u \in W_{loc}^{2,p}(\Omega) \cap C(\overline{\Omega})$ . On the other hand, for  $\alpha > 0$  and  $K < 0$ , we deduce from the Maximum Principle that (2.3) has no solution. Thus, if we want multiple solutions,  $K$  should change sign.

We give now two auxiliary results which will provide a family of  $\alpha$  and  $K$ 's giving multiple solutions to (2.3) Let  $\lambda_{\pm j}(m)$  denote the eigenvalues of the problem  $-\Delta u = \lambda m(x)u$  in  $\Omega, u = 0$  on  $\partial\Omega$ .

**Lemma 2.2.** *The function*

$$\alpha(t) := -\frac{\lambda_1((m^+ - tm^-))}{\lambda_{-1}((m^+ - tm^-))}$$

is continuous on  $(0, \infty)$  and satisfies  $\lim_{t \rightarrow 0^+} \alpha(t) = 0$  and  $\lim_{t \rightarrow \infty} \alpha(t) = \infty$ .

Our next lemma says that a weight  $m$  with ‘‘a positive and a negative bump’’ gives a bifurcation point to  $F(u)$  for the proof of Theorem 2.4.

**Lemma 2.3.** *Let  $y_+, y_-$  be fixed points of  $\Omega$ , let  $\delta > 0$  be such that the ball  $B_{20\delta}(\frac{y_+ + y_-}{2})$  with radius  $20\delta$  centered at  $\frac{y_+ + y_-}{2}$  is contained in  $\Omega$ , in such a way that the distance between  $y_+$  and  $y_-$  is  $8\delta$ . If  $\varphi_{-1}$  is the principal positive eigenfunction associated to the principal negative eigenvalue  $\lambda_{-1}$  and  $\varphi_1$  is the principal positive eigenfunction associated to the principal positive eigenvalue  $\lambda_1$  of the problem*

$$\begin{aligned} -\Delta u &= \lambda(m^+(x) - tm^-(x))u \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega, \end{aligned} \tag{2.4}$$

where  $m(x) = m^+(x) - m^-(x) \in C(\overline{\Omega})$ , is such that  $\text{rmsupp } m^+ = \overline{B_\delta(y_+)}$ ,  $\text{rmsupp } m^- = \overline{B_\delta(y_-)}$  and  $m^-(x) > 0$  in  $B_\delta(y_-)$ . Then there exists a positive

constant  $\epsilon(m^+, m^-) > 0$  depending on  $m^+, m^-$  such that for all  $t \in (0, \epsilon(m^+, m^-))$

$$\int_{\Omega} (m^+ - tm^-) \varphi_{-1}^{-1} \varphi_1^3 dx \neq 0. \quad (2.5)$$

We give now a family of  $\alpha$  and  $K$  providing multiple solutions to (2.3).

**Theorem 2.4.** *Suppose  $m = m^+ - m^-$  as in Lemma 2.3. For  $t > 0$ , denote  $m_t = m^+ - tm^-$ . Let  $\lambda_1(m_t) > 0$  in  $\mathbb{R}$ ,  $\varphi_1(t) > 0$  in  $C(\bar{\Omega})$ ,  $\lambda_{-1}(m_t) < 0$  in  $\mathbb{R}$ ,  $\varphi_{-1}(t) > 0$  in  $C(\bar{\Omega})$ , be the principal eigenvalues and eigenfunctions of*

$$\begin{aligned} -\Delta u &= \lambda m_t(x) u \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Define

$$\alpha(t) = -\frac{\lambda_1(m_t)}{\lambda_{-1}(m_t)}, \quad t > 0.$$

If  $\alpha = \alpha(t)$  in (2.3) and

$$K = K(t, \rho) = \lambda_{-1}(m_t) m_t \varphi_{-1}(t)^{\alpha(t)+1} + \rho \varphi_{-1}(t)$$

Then (2.3) has at least two solutions for  $t > 0$  and  $\rho > 0$  small enough.

**Remark 2.5.** The first term in  $K$  is a negative function on  $\Omega^+$ , the second a positive one.

**Remark 2.6.** For  $\rho = 0$ ,  $(\alpha(t), \varphi_{-1}(t)) \in \mathbb{R}^+ \times C(\bar{\Omega})^+$  could be a bifurcation pair for (2.3) since  $u = \varphi_{-1}$  is a solution for  $\alpha = \alpha(t)$  and  $K = K(t, 0)$ .

Now we consider  $K(x) \equiv 1$ . Hence for  $s = 0$ , (1.1) has a unique solution. Our next theorem is related to the topological nature of this nonlinear eigenvalue problem (1.1). Let  $P$  be the positive cone in  $C^1(\bar{\Omega})$  with its usual norm.

**Theorem 2.7.** *Suppose  $0 < \alpha < 1/n$ ,  $K(x) \equiv 1$ ,  $\mathcal{G}$  is nonnegative continuous and let  $f(x)$  be a non-negative bounded measurable function. Then, the set of pairs  $(s, u)$  of solutions of (1.1) is unbounded in  $\mathbb{R}^+ \times P$ . Moreover, if  $\mathcal{G}(x, \eta, \xi) \geq g_0 + |\xi|^2$  where  $g_0 > 0$  in  $\mathbb{R}$ . Then, we have  $s \leq 2n/\sqrt{g_0}r(\Omega)$ , where  $r(\Omega)$  is the inner radius of  $\Omega$ . As a consequence, there is bifurcation at infinity for some  $s_* < \infty$ .*

Recall that the inner radius of  $\Omega$  is given by  $\sup\{r : B_r(x) \subset \Omega\}$ .

Finally, we obtain two results dealing with multiplicity for our singular elliptic problem (1.2) with a convection term, as in our title.

**Theorem 2.8.** *Suppose that*

- (i)  $0 < \alpha < \frac{1}{n}$ ,  $1 < \beta < \frac{n+1}{n-1}$  and  $0 < \zeta < \frac{2}{n}$ .
- (ii)  $f \in L^\infty(\Omega)$ ,  $f > 0$ .
- (iii)  $K(x) \equiv 1$ .
- (iv)  $\mathcal{A} = 1$  and

$$0 \leq \mathcal{B} < C \left\{ \frac{\int_{\Omega} f \varphi_1 dx \int_{\Omega} \varphi_1^2 dx}{\int_{\Omega} \varphi_1 dx} \right\}^{\beta-1}$$

where  $\varphi_1, \lambda_1$  are the principal eigenfunction and principal eigenvalue of the operator  $-\Delta$  ( $-\Delta \varphi_1 = \lambda_1 \varphi_1$ ) with Dirichlet boundary conditions and  $C$  is a constant depending only in  $\Omega, \beta, \lambda_1$ .

Then there exist  $0 < s^{**} \leq s^* < \infty$  such that for all  $s \in (0, s^{**})$  problem (1.2) admits at least two solutions and no solutions for  $s > s^*$ . Furthermore there is bifurcation at infinity at  $s = 0$ .

For a particular form of  $f$  and for  $K$  with indefinite sign but in a more restricted class we have the following result.

**Theorem 2.9.** *Suppose that*

- (i)  $0 < \alpha < \frac{1}{n}$ ,  $1 < \beta < \frac{n+1}{n-1}$ , and  $\zeta < \frac{2}{n}$ .
- (ii)  $f = t\varphi_1$ ,  $t \geq B^{\frac{1}{1+\alpha}} [\lambda_1 (\frac{\alpha}{\lambda_1})^{\frac{1}{1+\alpha}} + (\frac{\lambda_1}{\alpha})^{\frac{\alpha}{1+\alpha}}]$ .
- (iii)  $|K(x)| \leq B\varphi_1^{1+\alpha}(x)$ .
- (iv)  $\mathcal{A} = 1$  and  $0 \leq \mathcal{B} < C$  where  $C$  is a constant depending only in  $\lambda_1$ ,  $\beta$ ,  $B$ .

Then there exists  $0 < s^{**} \leq s^* < \infty$  such that for all  $s \in (0, s^{**})$  problem (1.2) has at least two solutions and no solutions for  $s > s^*$ . Furthermore there is bifurcation at infinity for  $s=0$ .

We remark that estimate (ii) is needed at the end of the following section.

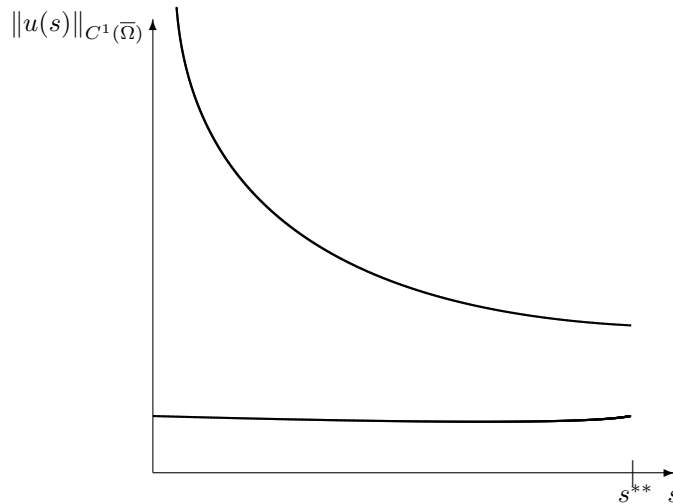


FIGURE 1. Behaviour of the two branches near  $s = 0$  in Theorem 2.9

### 3. AUXILIARY RESULTS

It is our purpose in this section to prove some preliminary results.

*Proof of Lemma 2.1.* We set  $\gamma > 2$ . Then from the identity

$$-\Delta\varphi_{-1}^{\gamma} = \gamma\lambda_{-1}(m^{+} - m^{-})\varphi_{-1}^{\gamma} - \gamma(\gamma - 1)\varphi_{-1}^{\gamma-2}|\nabla\varphi_{-1}|^2$$

and using that

$$\int_{\Omega} \Delta\varphi_{-1}^{\gamma} dx = \int_{\Omega} \operatorname{div} \nabla\varphi_{-1}^{\gamma} dx = \int_{\partial\Omega} \langle \nabla\varphi_{-1}^{\gamma}, n \rangle dx = \int_{\partial\Omega} \gamma\varphi_{-1}^{\gamma-1} \langle \nabla\varphi_{-1}^{\gamma}, n \rangle dx = 0,$$

where the last equality holds because  $\varphi_{-1}^{\gamma-1} = 0$  on  $\partial\Omega$ . So

$$\begin{aligned} -\gamma\lambda_{-1} \int_{\Omega} m^{-}\varphi_{-1}^{\gamma} dx &= -\gamma\lambda_{-1} \int_{\Omega} m^{+}\varphi_{-1}^{\gamma} dx + \gamma(\gamma - 1) \int_{\Omega} \varphi_{-1}^{\gamma-2} |\nabla\varphi_{-1}|^2 dx \\ &\geq \gamma(\gamma - 1) \int_{\Omega} \varphi_{-1}^{\gamma-2} |\nabla\varphi_{-1}|^2 dx, \end{aligned}$$

and consequently

$$\gamma^{1/\gamma}(-\lambda_{-1})^{1/\gamma} \left( \int_{\Omega} m^{-}\varphi_{-1}^{\gamma} dx \right)^{1/\gamma} \geq \gamma^{1/\gamma}(\gamma - 1)^{1/\gamma} \left( \int_{\Omega} \varphi_{-1}^{\gamma-2} |\nabla\varphi_{-1}|^2 dx \right)^{1/\gamma}.$$

Letting  $\gamma \rightarrow \infty$ , we find

$$\|\varphi_{-1}\|_{L^{\infty}(rmsupp m^{-}, m^{-} dx)} \geq \|\varphi_{-1}\|_{L^{\infty}(\Omega, |\nabla\varphi_{-1}|^2 dx)}$$

where  $\|\varphi_{-1}\|_{L^{\infty}(\Omega, |\nabla\varphi_{-1}|^2 dx)} = \text{ess sup}_{\Omega} |\varphi_{-1}|$  is taken with respect the measure  $|\nabla\varphi_{-1}|^2 dx$ . We observe that  $-\Delta\varphi_{-1} = 0$  in  $\Omega - \{rmsupp m^{-} \cup \text{supp } m^{+}\}$  to conclude that the Lebesgue's measure of thee set  $\{x \in \Omega - \{rmsupp m^{-} \cup rmsupp m^{+}\} : \nabla\varphi_{-1}(x) = 0\}$  is zero.

From  $-\Delta\varphi_{-1} < 0$  in  $rmsupp m^{+}$ , we infer that

$$\sup_{rmsupp m^{+}} \varphi_{-1} \leq \sup_{\partial rmsupp m^{+}} \varphi_{-1}$$

and find that

$$\begin{aligned} \|\varphi_{-1}\|_{L^{\infty}(\Omega, |\nabla\varphi_{-1}|^2 dx)} &\geq \|\varphi_{-1}\|_{L^{\infty}(\Omega - \{rmsupp m^{+} \cup rmsupp m^{-}\}, |\nabla\varphi_{-1}|^2 dx)} \\ &= \|\varphi_{-1}\|_{L^{\infty}(\Omega - \{rmsupp m^{+} \cup rmsupp m^{-}\})} \\ &= \|\varphi_{-1}\|_{L^{\infty}(\Omega - \{rmsupp m^{-}\})}; \end{aligned}$$

hence

$$\|\varphi_{-1}\|_{L^{\infty}(rmsupp m^{-}, m^{-} dx)} \geq \|\varphi_{-1}\|_{L^{\infty}(\Omega - \{rmsupp m^{-}\})}$$

With the aid of this last expression, we arrive to the desired conclusion. □

*Proof of Lemma 2.2.* Continuity follows from well known results ([16]). Since  $m^{+} - tm^{-} < m^{+}$  for all  $t > 0$ , we conclude that  $\lambda_1((m^{+} - tm^{-})) > \lambda_1((m^{+}))$  ([16]). Clearly

$$\lim_{t \rightarrow \infty} \lambda_{-1}((m^{+} - tm^{-})) = \lim_{t \rightarrow \infty} \frac{1}{t} \lambda_{-1}((\frac{m^{+}}{t} - m^{-})) = 0.$$

Then  $\lim_{t \rightarrow \infty} \alpha(t) = \infty$ . Using  $m^{+} - tm^{-} > -tm^{-}$ , we deduce that  $\lambda_{-1}((m^{+} - tm^{-})) < \lambda_{-1}((-tm^{-})) = \frac{1}{t} \lambda_{-1}((-m^{-}))$  and therefore

$$\lim_{t \rightarrow 0^{+}} \lambda_{-1}((m^{+} - tm^{-})) = -\infty.$$

Finally, from  $\lim_{t \rightarrow 0^{+}} \lambda_1((m^{+} - tm^{-})) = \lambda_1((m^{+}))$ , we find  $\lim_{t \rightarrow 0^{+}} \alpha(t) = 0$ . □

*Proof of Lemma 2.3.* To prove this lemma, we bound  $t|\lambda_{-1}((m^{+} - tm^{-}))|$ . From  $m^{+} - tm^{-} > -tm^{-}$ , we deduce  $\lambda_{-1}((m^{+} - tm^{-})) < \lambda_{-1}((-tm^{-}))$  ([16]) and therefore

$$-t\lambda_{-1}((m^{+} - tm^{-})) > -\lambda_{-1}((-m^{-})) > 0.$$

From the equation

$$\begin{aligned} -\Delta\varphi_{-1} &= \lambda_{-1}(m^{+} - tm^{-})\varphi_{-1} \quad \text{in } \Omega \\ \varphi_{-1} &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

we see that

$$\begin{aligned} -\Delta\varphi_{-1} &= -\lambda_{-1}(tm^- - m^+)\varphi_{-1} \quad \text{in } \Omega \\ \varphi_{-1} &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

We conclude that

$$-\lambda_{-1}((m^+ - tm^-; \Omega)) = \lambda_1((tm^- - m^+; \Omega)).$$

Using  $\text{rmsupp } m^- \subset \Omega$ , it follows that

$$\lambda_1((tm^- - m^+; \Omega)) \leq \lambda_1((tm^- - m^+; \text{rmsupp } m^-)) = \lambda_1((tm^-; \text{rmsupp } m^-))$$

Thus, we have

$$0 < -\lambda_{-1}((-m^-)) < t|\lambda_{-1}((m^+ - tm^-; \Omega))| < \lambda_1((m^-; \text{rmsupp } m^-)) \quad (3.1)$$

Our next tool is Harnack inequality. It asserts that if  $u \in W^{1,2}(\Omega)$  satisfies

$$\begin{aligned} -\Delta u + mu &= 0 \quad \text{in } \Omega \\ u &\geq 0 \quad \text{on } \Omega, \end{aligned}$$

then for any ball  $B_{4R}(y) \subset \Omega$ , we have

$$\sup_{B_R(y)} u \leq C(N)^{1+R\sqrt{\|m\|_{L^\infty(\Omega)}}} \inf_{B_R(y)} u$$

(see Theorem 8.20 [21]).

Now we are ready to deal with (2.5). We may suppose  $\|\varphi_{-1}\|_{L^\infty(\Omega)} = 1$ . From Harnack inequality and Lemma 2.1, we find

$$1 \leq C(N)^{1+R\sqrt{t|\lambda_{-1}|}} \inf_{\text{rmsupp } m^-} \varphi_{-1}.$$

Then

$$t \int_{\Omega} m^- \varphi_{-1}^{-1} \varphi_1^3 dx \leq tC(N)^{1+R\sqrt{t|\lambda_{-1}|}} \int_{\Omega} m^- \varphi_1^3 dx. \quad (3.2)$$

Assume the claim in this Lemma false, i. e.,

$$\int_{\Omega} (m^+ - tm^-) \varphi_{-1}^{-1} \varphi_1^3 dx = 0.$$

Then

$$\begin{aligned} \int_{\Omega} m^+ \varphi_1^3 dx &\leq \int_{\Omega} m^+ \varphi_{-1}^{-1} \varphi_1^3 dx \\ &= t \int_{\Omega} m^- \varphi_{-1}^{-1} \varphi_1^3 dx \\ &\leq tC(N)^{1+R\sqrt{t|\lambda_{-1}|}} \int_{\Omega} m^- \varphi_1^3 dx. \end{aligned}$$

Thus

$$\begin{aligned} \left( \inf_{\text{rmsupp } m^+} \varphi_1 \right)^3 \int_{\text{rmsupp } m^+} m^+ dx &\leq tC(N)^{1+R\sqrt{t|\lambda_{-1}|}} \int_{\Omega} m^- \varphi_1^3 dx \\ &\leq tC(N)^{1+R\sqrt{t|\lambda_{-1}|}} \left( \sup_{\text{rmsupp } m^-} \varphi_1 \right)^3 \int_{\text{rmsupp } m^-} m^- dx. \end{aligned}$$



Consequently,

$$\left( \inf_{B_{5R}(\frac{1}{2}(y_++y_-))} \varphi_1 \right)^3 \leq tC(N)^{1+R\sqrt{t|\lambda_{-1}|}} \left( \sup_{B_{5R}(\frac{1}{2}(y_++y_-))} \varphi_1 \right)^3 \frac{\int_{r_{msupp} m^-} m^- dx}{\int_{\text{supp } m^+} m^+ dx}$$

Hence

$$\frac{1}{C(N)^{(1+R\sqrt{t|\lambda_{-1}|})+3+15R\sqrt{\max(\lambda_1,t\lambda_1)}}} \frac{\int_{r_{msupp} m^+} m^+ dx}{\int_{r_{msupp} m^-} m^- dx} \leq t. \tag{3.3}$$

For small  $t$ , using (3.1), we deduce that (3.3) is a contradiction.  $\square$

Recall that the vector space

$$C(\bar{\Omega})_e = \{u \in C(\bar{\Omega}); -se \leq u \leq se \text{ for some } s > 0 \text{ in } \mathbb{R}\},$$

where  $e$  is the solution of  $-\Delta e = 1$  in  $\Omega$ ,  $e = 0$  on  $\partial\Omega$ , endowed with the norm

$$\|u\|_e = \inf\{s > 0; -se \leq u \leq se\}$$

is a Banach space [3]. We will use the Banach space

$$\mathcal{C} = W^{2,p}(\Omega) \cap C(\bar{\Omega})_e \tag{3.4}$$

for the norm  $\|\cdot\|_{\mathcal{C}} = \|\cdot\|_{W^{2,p}(\Omega)} + \|\cdot\|_e$ . Hence, the cone of positive functions

$$\mathcal{C}^+ = W^{2,p}(\Omega) \cap C(\bar{\Omega})_e^+ \tag{3.5}$$

has non empty interior  $\mathring{\mathcal{C}}^+$ . We also need

$$\mathcal{D} = \{f : fe^{-\alpha} \in L^p(\Omega)\} \tag{3.6}$$

which is a Banach space for the norm

$$\|f\|_{\mathcal{D}} = \left( \int_{\Omega} |f|^p e^{-p\alpha} dx \right)^{1/p}$$

Note that all principal eigenfunctions are in  $\mathring{\mathcal{C}}^+$ .

**Lemma 3.1.** *The map  $F : \mathring{\mathcal{C}}^+ \rightarrow \mathcal{D}$ ,*

$$F(u) = -u^\alpha \Delta u,$$

*is regular and has first and second derivatives*

$$dF(u)v = -\alpha u^{\alpha-1} v \Delta u - u^\alpha \Delta v,$$

$$d^2F(u)[v, h] = -\alpha(\alpha-1)u^{\alpha-2} v h \Delta u - \alpha u^{\alpha-1} v \Delta h - \alpha u^{\alpha-1} h \Delta v$$

*Proof.* Consider

$$\omega(t) = \frac{F(u+tv) - F(u)}{t} + \alpha u^{\alpha-1} v \Delta u + u^\alpha \Delta v \tag{3.7}$$

To prove Gateaux differentiability, we need to establish

$$\lim_{t \rightarrow 0} \|\omega(t)\|_{\mathcal{C}} = 0 \tag{3.8}$$

From the Mean-Value Theorem one has (at almost every  $x \in \Omega$ )

$$\begin{aligned} F(u+tv) - F(u) &= - \int_0^1 \frac{d}{d\xi} \{(u+\xi tv)^\alpha \Delta(u+\xi tv)\} d\xi \\ &= -t \int_0^1 \{\alpha(u+\xi tv)^{\alpha-1} v \Delta(u+\xi tv) + (u+\xi tv)^\alpha \Delta v\} d\xi. \end{aligned}$$

Thus

$$\begin{aligned} \|\omega(t)\|_{\mathcal{D}} &\leq \left\| \int_0^1 \alpha v \{u^{\alpha-1} \Delta u - (u + \xi tv)^{\alpha-1} \Delta(u + \xi tv)\} d\xi \right\|_{\mathcal{D}} \\ &\quad + \left\| \int_0^1 \Delta v \{u^\alpha - (u + \xi tv)^\alpha\} d\xi \right\|_{\mathcal{D}}. \end{aligned} \quad (3.9)$$

Using the definition of  $\|\cdot\|_{\mathcal{D}}$ , Jensen inequality and Fubini Theorem, we obtain

$$\begin{aligned} \left\| \int_0^1 \Delta v \{u^\alpha - (u + \xi tv)^\alpha\} d\xi \right\|_{\mathcal{D}}^p &= \int_{\Omega} \left| \int_0^1 \Delta v \{u^\alpha - (u + \xi tv)^\alpha\} d\xi \right|^p e^{-p\alpha} dx \\ &\leq \int_0^1 d\xi \int_{\Omega} |\Delta v \{u^\alpha - (u + \xi tv)^\alpha\}|^p e^{-p\alpha} dx. \end{aligned}$$

A similar estimate is valid for the second term in (3.9) and consequently, the Lebesgue Dominated-Convergence Theorem implies (3.8). Next we prove continuity of the map

$$d_G F : \mathring{\mathcal{C}}^+ \rightarrow L(\mathcal{C}, \mathcal{D})$$

where  $L(\mathcal{C}, \mathcal{D})$  is provided with the operator norm. Recall that

$$\|d_G F(u_j) - d_G F(u)\|_{L(\mathcal{C}, \mathcal{D})} = \sup_{v \in \mathcal{C}, \|v\|_{\mathcal{C}} \leq 1} \|d_G F(u_j)v - d_G F(u)v\|_{\mathcal{D}}.$$

Furthermore,

$$\begin{aligned} \|d_G F(u_j)v - d_G F(u)v\|_{\mathcal{D}} &= \left\| -\alpha u_j^{\alpha-1} v \Delta u_j - u_j^\alpha \Delta v + \alpha u^{\alpha-1} v \Delta u + u^\alpha \Delta v \right\|_{\mathcal{D}} \\ &\leq \|\alpha v (u^{\alpha-1} \Delta u - u_j^{\alpha-1} \Delta u_j)\|_{\mathcal{D}} + \|(u^\alpha - u_j^\alpha) \Delta v\|_{\mathcal{D}} \\ &\leq \|\alpha v \Delta u (u^{\alpha-1} - u_j^{\alpha-1})\|_{\mathcal{D}} + \|\alpha v u_j^{\alpha-1} (\Delta u - \Delta u_j)\|_{\mathcal{D}} \\ &\quad + \|(u^\alpha - u_j^\alpha) \Delta v\|_{\mathcal{D}}. \end{aligned}$$

If  $\|u - u_j\|_{\mathcal{C}}$ , that is  $|u - u_j| \leq \frac{1}{j} e$  in  $\Omega$ , we prove now that each of these last three terms tends to zero. From

$$\begin{aligned} |u(x)^{\alpha-1} - u_j(x)^{\alpha-1}| &= |(\alpha - 1) \int_0^1 (\xi u_j(x) + (1 - \xi)u(x))^{\alpha-2} d\xi (u(x) - u_j(x))| \\ &\leq \frac{|1 - \alpha|}{j} C e(x)^{\alpha-1} \end{aligned}$$

and using  $|v| \leq \varphi_{-1}$ , we get

$$\|\alpha v \Delta u (u^{\alpha-1} - u_j^{\alpha-1})\|_{\mathcal{D}} \leq C \frac{\alpha |1 - \alpha|}{j} \|e^\alpha \Delta u\|_{\mathcal{D}} = C \frac{\alpha |1 - \alpha|}{j} \|\Delta u\|_{L^p(\Omega)}.$$

Similarly,

$$\begin{aligned} \|\alpha v u_j^{\alpha-1} (\Delta u - \Delta u_j)\|_{\mathcal{D}} &\leq C \|\Delta u - \Delta u_j\|_{L^p(\Omega)}, \\ \|(u^\alpha - u_j^\alpha) \Delta v\|_{\mathcal{D}} &\leq C \frac{\alpha}{j}. \end{aligned}$$

This proves continuity of the Gateaux derivative and hence  $F$  is Fréchet differentiable. For the second derivative we proceed similarly.  $\square$

In [4, Theorem 3.1] it is stated that

$$\begin{aligned} -\Delta u &= u^{-\alpha} + f \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega \end{aligned} \quad (3.10)$$

with non-negative  $f \in L^p(\Omega)$  ( $p > n$ ), has a unique solution  $u \in W_{\text{loc}}^{2,p}(\Omega) \cap C(\bar{\Omega})$ .

**Lemma 3.2.** *Suppose  $0 < \alpha < \frac{1}{n}$ . Then the solution map of problem (3.10)  $f \rightarrow u$ , denoted  $H$  is well defined from  $\{f \in C(\bar{\Omega}) : f(x) \geq 0, x \in \Omega\}$  into  $\{u \in C^1(\bar{\Omega}) : u(x) \geq 0, x \in \Omega, u(x) = 0 \text{ and } \frac{\partial u}{\partial n}(x) < 0, x \in \partial\Omega\}$ . Moreover  $H$  is a continuous and compact map.*

*Proof.*  $0 < \alpha < \frac{1}{n}$  allow us to fix  $p > n$  such that  $\alpha p < 1$ . In the proof of this Lemma we will use this  $p$ . From the proof in [4, Theorem 1], we know that  $u_j = Hf_j \geq w$ , where  $w$  satisfies

$$\begin{aligned} -\Delta w &= u_1^{-\alpha} & \text{in } \Omega \\ w &= 0 & \text{on } \partial\Omega \end{aligned}$$

and  $u_1 \in W^{2,p}(\Omega)$  is the unique solution of the problem

$$\begin{aligned} -\Delta u_1 &= u_1^{-\alpha} + f_j & \text{in } \Omega \\ u_1 &= 1 & \text{on } \partial\Omega. \end{aligned}$$

Using the Maximum Principle, we have  $u_1^{-\alpha} \leq w_1^{-\alpha}$ , where  $w_1$  is the solution of the problem

$$\begin{aligned} -\Delta w_1 &= f_j & \text{in } \Omega \\ w_1 &= 1 & \text{on } \partial\Omega. \end{aligned}$$

Using again the Maximum Principle we see that  $u_1^{-\alpha} \leq 1$  on  $x \in \bar{\Omega}$ . We recall a Uniform Hopf Principle as it is formulated in Diaz-Morel-Oswald [15]. It asserts that there exists a constant  $C$ , depending only on  $\Omega$ , such that for all  $f \geq 0$ ,  $f \in L^1(\Omega)$ , each weak solution  $u$  of

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \\ u &= 0 & \text{on } \partial\Omega \end{aligned} \tag{3.11}$$

satisfies

$$u \geq C \left( \int_{\Omega} f e \right) e. \tag{3.12}$$

Applying this Uniform Hopf Principle, we get

$$w(x) \geq C(\Omega) \left( \int_{\Omega} u_1^{-\alpha} e dx \right) e(x).$$

Jensen inequality implies

$$\left( \int_{\Omega} u_1^{-\alpha} e dx \right)^{-\alpha} \leq \left( \int_{\Omega} e dx \right)^{\alpha-1} \left( \int_{\Omega} u_1^{\alpha^2} e dx \right).$$

As before, we have  $u_1 \leq w_j$  where  $w_j$  is the unique solution of

$$\begin{aligned} -\Delta w_j &= 1 + f_j & \text{in } \Omega \\ w_j &= 1 & \text{on } \partial\Omega. \end{aligned}$$

Thus

$$u_j(x)^{-\alpha} \leq C(\Omega)^{-\alpha} \left( \int_{\Omega} e dx \right)^{\alpha-1} \left( \int_{\Omega} w_j^{\alpha^2} e dx \right) e^{-\alpha}. \tag{3.13}$$

If  $f_j \rightarrow f$  in  $C(\bar{\Omega})$ , then there exist a constant  $C$ , independent of  $j$ , such that

$$\|u_j^{-\alpha}\|_{L^p(\Omega)} < C.$$

Then  $\|u_j\|_{W^{2,p}(\Omega)} < C$ , so Rellich-Kondrachov Theorem implies  $u_j \rightarrow u$  strongly in  $C^1(\overline{\Omega})$ . Using (3.13) we conclude that  $u_j^{-\alpha} \rightarrow u^{-\alpha}$  strongly in  $L^p(\Omega)$ , and therefore  $u$  is a solution of the problem

$$\begin{aligned} -\Delta u &= u^{-\alpha} + f \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Compactness is deduced from (3.13).  $\square$

**Lemma 3.3.** *Suppose  $\mathcal{L} = \Delta + c(x)$  satisfies the maximum principle and suppose*

$$|K(x)| \leq B\varphi_1^{1+\alpha}(x) \quad \text{for some } B > 0 \text{ in } \mathbb{R}, \quad (3.14)$$

where  $\varphi_1$  is the principal eigenfunction corresponding to the principal positive eigenvalue of the problem  $-\mathcal{L}u = \lambda u$  in  $\Omega$ ,  $u = 0$  on  $\partial\Omega$ . If  $f \in L^p(\Omega)$ ,  $p > n$ , satisfies

$$f \geq t_0\varphi_1 \quad p. \quad p.$$

where  $t_0 = B^{\frac{1}{1+\alpha}} \left[ \lambda_1 \left( \frac{\alpha}{\lambda_1} \right)^{\frac{1}{1+\alpha}} + \left( \frac{\lambda_1}{\alpha} \right)^{\frac{\alpha}{1+\alpha}} \right]$ . Then

$$\begin{aligned} -\mathcal{L}u + K(x)u^{-\alpha} &= f(x) \quad \text{in } \Omega \\ u &> 0 \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \Omega \end{aligned} \quad (3.15)$$

has a strong solution  $u \in W^{2,p}(\Omega)$ . Moreover, if  $f > t_0\varphi_1$  then  $u > \left(\frac{\alpha B}{\lambda_1}\right)^{\frac{1}{1+\alpha}} \varphi_1$  and it is unique within the set  $\{v > \left(\frac{\alpha B}{\lambda_1}\right)^{\frac{1}{1+\alpha}} \varphi_1\}$ . If instead of  $f$  we consider  $f_1 > f_2 \geq t_0\varphi_1$  in  $C(\overline{\Omega})$  with  $t > t_0$ , then corresponding solutions  $u_1, u_2$  in  $\{u \in C(\overline{\Omega}) : u \geq C(t)\varphi_1\}$  satisfy  $u_1 > u_2$ .

*Proof.* Let us consider, for  $g \in L^\infty(\Omega)$ , the solution operator  $h = (-\mathcal{L})^{-1}g$  defined by  $-\mathcal{L}h = g$  in  $\Omega$ ,  $h = 0$  on  $\partial\Omega$ . Then  $h$  lies in  $W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  for all  $1 < p < \infty$ . We define

$$G_C = \{u \in C(\overline{\Omega}) : u \geq C\varphi_1\}$$

If  $t \geq t_0$ , then there exists a unique  $C(t) \geq \left(\frac{\alpha B}{\lambda_1}\right)^{\frac{1}{1+\alpha}}$  satisfying  $t = \lambda_1 C(t) + \frac{B}{C(t)^\alpha}$ . We prove now that for  $f \in G_t$ ,  $u \in G_{C(t)}$  the operator

$$F(u) = (-\mathcal{L})^{-1}(f - Ku^{-\alpha})$$

is well defined from  $G_{C(t)}$  into  $G_{C(t)}$ . Moreover, it is continuous for the usual topology on  $C(\overline{\Omega})$ . Indeed, if  $u \in G_{C(t)}$  then  $-Ku^{-\alpha} \geq -C(t)^{-\alpha}B\varphi_1$  and consequently  $f - Ku^{-\alpha} \geq \lambda_1 C(t)\varphi_1$ . Now positivity of  $\mathcal{L}^{-1}$  implies  $(-\mathcal{L})^{-1}(f - Ku^{-\alpha}) \geq C(t)\varphi_1$ .

To see that  $F$  is a continuous map, let  $(u_n) \in G_{C(t)}$  be a sequence such that  $u_n \rightarrow u$  in  $C(\overline{\Omega})$ , then  $K(x)u_n(x)^{-\alpha} \rightarrow K(x)u(x)^{-\alpha}$ , pointwise on  $\Omega$ . Since  $|K(x)u_n^{-\alpha}(x)| \leq C(t)^{-\alpha}B\varphi_1(x)$ , Lebesgue's Dominated Convergence Theorem gives  $f - Ku_n^{-\alpha} \rightarrow f - Ku^{-\alpha}$  in  $L^p(\Omega)$ ,  $1 < p < \infty$ . Then the classical  $L^p$  theory for elliptic operators implies

$$(-\mathcal{L})^{-1}(f - Ku_n^{-\alpha}) \rightarrow (-\mathcal{L})^{-1}(f - Ku^{-\alpha})$$

in  $W^{2,p}(\Omega)$  for all  $1 < p < \infty$  and then  $F(u_n) \rightarrow F(u)$  in  $C(\overline{\Omega})$ . Moreover  $\overline{F(G_{C(t)})}$  is a compact set in  $C(\overline{\Omega})$ . In fact, we have

$$\|(-\mathcal{L})^{-1}(f - Ku^{-\alpha})\|_{W^{2,p}(\Omega)} \leq C_0 \|f - Ku^{-\alpha}\|_{L^p(\Omega)} \leq C,$$

for all  $u \in G_{C(t)}$ ,  $1 < p < \infty$ , then it is clear that  $\overline{F(G_C)}$  is compact in  $C(\overline{\Omega})$ . Since  $G_{C(t)}$  is a convex closed set, Schauder Fixed Point Theorem provides a fixed point for  $F$  in  $G_{C(t)}$ , so a solution to (3.15).

Suppose now that for  $f \in G_t$  there exist two different solutions,  $u$  and  $v$  of (3.15), then

$$\begin{aligned} -\mathcal{L}(u - v) &= -K(u^{-\alpha} - v^{-\alpha}) \\ &= \alpha K \left( \int_0^1 (ru + (1-r)v)^{-\alpha-1} dr \right) (u - v). \end{aligned}$$

We define  $m = K \int_0^1 (ru + (1-r)v)^{-\alpha-1} dr$ . Thus, we can write, recalling that  $\mathcal{L} = \Delta + c(x)$ ,

$$\begin{aligned} \Delta(u - v) + (c + \alpha m)(u - v) &= 0 \quad \text{in } \Omega \\ u - v &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

Since  $u \not\equiv v$  we may suppose  $u - v$  is positive somewhere in  $\Omega$ . Now, [10, Corollary 1.1] implies that the principal eigenvalue  $\lambda_1((\Delta + c + \alpha m))$  of the problem

$$\begin{aligned} \Delta h + (c + \alpha m)h &= \lambda h \quad \text{in } \Omega \\ h &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

is a nonpositive number. We recall Lipschitz continuity of this eigenvalue with respect to  $L^\infty$ -norm of the coefficient function  $c + \alpha m$  (see for example [10, Proposition 2.1]) and the estimate  $|m| \leq BC(t)^{-1-\alpha}$  to infer that

$$|\lambda_1((\Delta + c + \alpha m)) - \lambda_1((\Delta + c))| \leq \|c + \alpha m - c\|_{L^\infty(\Omega)} \leq \frac{\alpha B}{C(t)^{1+\alpha}}$$

Considering the choice of  $C(t)$ , we find

$$0 < \lambda_1 - \frac{\alpha B}{C(t)^{1+\alpha}} \leq \lambda_1((\Delta + c + \alpha m)),$$

and this is a contradiction.

If  $u_1 \not\geq u_2$  in our last assertion, then there exists  $x_0 \in \Omega$  such that  $u_2(x_0) \geq u_1(x_0)$ , and  $u_2 - u_1$  is a nontrivial solution of

$$\begin{aligned} \mathcal{L}(u_2 - u_1) + \alpha \tilde{m}(u_2 - u_1) &\geq 0 \quad \text{in } \Omega \\ u_2 - u_1 &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

where  $\tilde{m}$  is similar to  $m$ . From [10, Corollary 1.1] we obtain  $\lambda_1((\Delta + c + \alpha \tilde{m})) \leq 0$  and this is a contradiction, because  $0 \leq \tilde{m} \leq BC(t)^{-1-\alpha}$  and as before, we have  $\lambda_1((\Delta + c + \alpha \tilde{m})) > 0$ .  $\square$

**Remark 3.4.** When  $\mathcal{L} = \Delta$ ,  $t_0$  is sharp under condition (3.14) for  $K = B\varphi_1^{1+\alpha}$  and  $f \in \{t\varphi_1 : t > 0\}$ . Indeed

$$\begin{aligned} -\Delta u + B\varphi_1^{1+\alpha}u^{-\alpha} &= t\varphi_1 \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega \end{aligned}$$

implies

$$t \int_{\Omega} \varphi_1^2 dx \leq \int_{\Omega} \left( \lambda_1 \frac{u}{\varphi_1} + B \left( \frac{u}{\varphi_1} \right)^{-\alpha} \right) \varphi_1^2 dx = t \int_{\Omega} \varphi_1^2 dx.$$

## 4. PROOFS

*Proof of Theorem 2.4.* Consider the map  $F : \mathring{C}^+ \rightarrow \mathcal{D}$  given by  $F(u) = -u^\alpha \Delta u$ . According to Lemma 3.1,  $dF(u)v = 0$  if and only if  $v$  satisfies

$$\begin{aligned} -\Delta v &= \alpha \frac{\Delta u}{u} v \quad \text{in } \Omega \\ v &= 0 \quad \text{on } \partial\Omega. \end{aligned} \quad (4.1)$$

Suppose  $m$  is as in Lemma 2.1 and consider the eigenvalue problem

$$\begin{aligned} -\Delta u &= \lambda m u \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

At  $u = \varphi_{-1}$  and for  $\alpha = -\frac{\lambda_1}{\lambda_{-1}}$  in (4.1),  $dF(\varphi_{-1})v = 0$  is equivalent to

$$\begin{aligned} -\Delta v &= \lambda_1 m v \quad \text{in } \Omega \\ v &= 0 \quad \text{on } \partial\Omega \end{aligned} \quad (4.2)$$

which implies  $\ker dF(\varphi_{-1}) = \langle \varphi_1 \rangle$ . The equation  $dF(\varphi_{-1})v = f$  is equivalent to

$$\begin{aligned} -\Delta v &= \lambda_1 m v + \varphi_{-1}^{-\alpha} f \quad \text{in } \Omega \\ v &= 0 \quad \text{on } \partial\Omega \end{aligned} \quad (4.3)$$

By hypothesis  $f\varphi_{-1}^{-\alpha} \in L^p(\Omega)$  with  $p > n$ , hence the Fredholm alternative yields that (4.3) has a solution  $v \in H_0^{1,2}(\Omega)$  if and only if  $\int_{\Omega} \varphi_{-1}^{-\alpha} f \varphi_1 dx = 0$ . If we have a solution  $v$  since  $m \in L^\infty(\Omega)$  a Brezis-Kato result (see for example Struwe appendix B [14]) implies that  $v \in \mathcal{C}$ .

We want to solve the equation

$$F(\varphi_{-1} + \hat{v}) = F(\varphi_{-1}) + \rho\varphi_{-1} \quad (4.4)$$

Inserting Taylor formula in (4.4),

$$F(\varphi_{-1} + \hat{v}) = F(\varphi_{-1}) + dF(\varphi_{-1})\hat{v} + \Psi(\hat{v})$$

we find

$$dF(\varphi_{-1})\hat{v} + \Psi(\hat{v}) = \rho\varphi_{-1} \quad (4.5)$$

We use now the well known Lyapunov-Schmidt method. First we denote

$$\begin{aligned} \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^\perp &= \{w \in \mathcal{C} : \int_{\Omega} w \varphi_{-1}^{-\alpha} \varphi_1 dx = 0\}, \\ \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^\perp &= \{w \in \mathcal{D} : \int_{\Omega} w \varphi_{-1}^{-\alpha} \varphi_1 dx = 0\}. \end{aligned}$$

Observe that  $\int_{\Omega} \varphi_{-1} \varphi_{-1}^{-\alpha} \varphi_1 dx \neq 0$ , thus we have the decompositions as direct sums

$$\mathcal{C} = \langle \varphi_{-1} \rangle \oplus \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^\perp, \quad \mathcal{D} = \langle \varphi_{-1} \rangle \oplus \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^\perp$$

and consequently if  $\hat{v} \in \mathcal{D}$ , we get the unique decomposition

$$\hat{v} = \hat{s}\varphi_{-1} + w$$

with  $w \in \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^\perp$ . Let us denote

$$P : \mathcal{D} \rightarrow \langle \varphi_{-1} \rangle, \quad Q : \mathcal{D} \rightarrow \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^\perp$$

linear operators such that  $P\widehat{v} = \widehat{s}\varphi_{-1}$  and  $Q\widehat{v} = w$ . We can replace (4.5) by the equivalent system

$$QdF(\varphi_{-1})\widehat{v} + Q\Psi(\widehat{v}) = 0, \tag{4.6}$$

$$P\Psi(\widehat{v}) = \rho\varphi_{-1}. \tag{4.7}$$

To solve (4.6), we define the function

$$\begin{aligned} \Gamma : \mathbb{R} \times \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^{\perp} &\rightarrow \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^{\perp}, \\ \Gamma(\widehat{s}, w) &= QdF(\varphi_{-1})(\widehat{s}\varphi_{-1} + w) + Q\Psi(\widehat{s}\varphi_{-1} + w). \end{aligned}$$

This function satisfies

$$\Gamma(0, 0) = 0, \tag{4.8}$$

$$d_w\Gamma(0, 0)w_0 = QdF(\varphi_{-1})w_0, \tag{4.9}$$

$$d_{\widehat{s}}\Gamma(0, 0) = QdF(\varphi_{-1})\varphi_{-1}. \tag{4.10}$$

The operator  $d_w\Gamma(0, 0)$  has inverse from  $\langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^{\perp}$  to  $\langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^{\perp}$ . The Implicit Function Theorem applies to  $\Gamma$ : there exist an interval  $(-s^*, s^*)$  and a function

$$W : (-s^*, s^*) \rightarrow \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^{\perp}$$

such that  $\widehat{v} = s\varphi_{-1} + W(s)$  solves (4.6), with

$$W(0) = 0 \quad \text{and} \quad W'(0) = -[QdF(\varphi_{-1})]^{-1}QdF(\varphi_{-1})\varphi_{-1}.$$

Using  $\text{Im } dF(\varphi_{-1}) = \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{D}}^{\perp}$  and  $W'(0) \in \langle \varphi_{-1}^{-\alpha} \varphi_1 \rangle_{\mathcal{C}}^{\perp}$ , we conclude

$$dF(\varphi_{-1})W'(0) = -dF(\varphi_{-1})\varphi_{-1}.$$

Hence  $W'(0) + \varphi_{-1} \in \text{Ker } dF(\varphi_{-1}) = \langle \varphi_1 \rangle$ . Thus

$$W'(0) = r\varphi_1 - \varphi_{-1} \tag{4.11}$$

with  $r \neq 0$  because  $\varphi_{-1} \notin \langle \varphi_{-1}^{\alpha} \varphi_1 \rangle^{\perp}$ . From (4.7), we find

$$\rho = \int_{\Omega} \varphi_{-1} P\Psi(s\varphi_{-1} + W(s)) dx = \langle \varphi_{-1}, P\Psi(s\varphi_{-1} + W(s)) \rangle.$$

The function

$$\chi(s) = \langle \varphi_{-1}, P\Psi(s\varphi_{-1} + W(s)) \rangle$$

is regular and has first and second derivatives given by

$$\chi'(s) = \langle \varphi_{-1}, Pd\Psi(s\varphi_{-1} + W(s))[\varphi_{-1} + W'(s)] \rangle,$$

$$\begin{aligned} \chi''(s) &= \langle \varphi_{-1}, Pd^2\Psi(s\varphi_{-1} + W(s))[\varphi_{-1} + W'(s), \varphi_{-1} + W'(s)] \rangle \\ &\quad + \langle \varphi_{-1}, Pd\Psi(s\varphi_{-1} + W(s))[W''(s)] \rangle. \end{aligned}$$

From  $d\Psi(0) = 0$  and  $d^2\Psi(0) = d^2F(\varphi_{-1})$ , we obtain

$$\chi'(0) = 0,$$

$$\chi''(0) = \langle \varphi_{-1}, Pd^2F(\varphi_{-1})[r\varphi_1, r\varphi_1] \rangle.$$

Direct calculations show that

$$d^2F(\varphi_{-1})[\varphi_1, \varphi_1] = \lambda_1 \left(1 - \frac{\lambda_1}{\lambda_{-1}}\right) \varphi_{-1}^{\alpha-1} \varphi_1^2 m.$$

Using the decomposition  $d^2F(\varphi_{-1})[r\varphi, r\varphi] = s\varphi_{-1} + w$  with  $w \in \langle \varphi_{-1}^{-\alpha}\varphi_1 \rangle_{\mathcal{D}}^\perp$ , we find

$$s = r^2\lambda_1\left(1 - \frac{\lambda_1}{\lambda_{-1}}\right) \frac{\int_{\Omega} m\varphi_{-1}^{-1}\varphi_1^3 dx}{\int_{\Omega} \varphi_{-1}^{1-\alpha}\varphi_1 dx}.$$

Then  $\chi''(0) \neq 0$  is equivalent to

$$\int_{\Omega} m\varphi_{-1}^{-1}\varphi_1^3 dx \neq 0. \tag{4.12}$$

If (4.12) is true, then there exist an nonempty open interval such that the equation (4.7) has at least two solutions. Lemma 2.3 states the existence of a class  $m$ 's satisfying (4.12).  $\square$

*Proof of Theorem 2.7.* From Lemma 3.2 the operator

$$F(s, u) := H(s\mathcal{G}(x, u, \nabla u) + f)$$

is well defined and is continuous, compact from  $\mathbb{R}_{\geq 0} \times P^+$  to  $P$  where  $P$  is the cone of positive functions in  $C^1(\overline{\Omega})$  with the usual norm. Furthermore a solution  $v$  of the equation

$$F(s, v + u_*) - u_* = v \tag{4.13}$$

where  $u_*$  is the unique solution of the problem

$$\begin{aligned} -\Delta u_* &= u_*^{-\alpha} + f && \text{in } \Omega \\ u_* &= 0 && \text{on } \partial\Omega \end{aligned} \tag{4.14}$$

satisfies the equation

$$\begin{aligned} -\Delta(v + u_*) &= (v + u_*)^{-\alpha} + s\mathcal{G}(x, v + u_*, \nabla(v + u_*)) + f && \text{in } \Omega \\ v + u_* &> 0 && \text{in } \Omega \\ v + u_* &= 0 && \text{on } \partial\Omega. \end{aligned} \tag{4.15}$$

The operator  $T(s, v) := F(s, v + u_*) - u_*$  is well defined from  $\mathbb{R}_{\geq 0} \times P$  to  $P$  and is a continuous compact operator, moreover  $T(0, 0) = 0$  and since  $T(0, v) = 0$  for all  $v \in P \cup \{0\}$ ,  $v = 0$  is the unique fixed point of  $T(0, \cdot)$ . For each  $\sigma \geq 1$  and  $\rho > 0$ , we have also that  $T(0, v) \neq \sigma v$  for  $v \in P \cap \rho\partial B$  where  $B$  denotes the open unit ball centered at 0 in  $C^1(\overline{\Omega})$ . Using Theorem 17.1 in Amman's article [3] there exist a nonempty set  $\Sigma$  of pairs  $(s, v)$  in  $\mathbb{R}_{\geq 0} \times P$  that solves the equation (4.16). Moreover  $\Sigma$  is a closed, connected and unbounded subset of  $\mathbb{R}_{\geq 0} \times P$  containing  $(0, 0)$ . The nonexistence Corollary 1.1 in [34] implies the last affirmation.  $\square$

*Proof of Theorem 2.8.* We start as in the proof of Theorem 2.7. Hence, from Lemma 3.2, the operator

$$F(s, u) := H(s(\mathcal{A}u^\beta + \mathcal{B}|\nabla u|^\zeta) + f)$$

is well defined, continuous and compact from  $\mathbb{R}_{\geq 0} \times P^+$  to  $P$  where  $P$  is the cone of positive functions in  $C^1(\overline{\Omega})$  with the usual norm. We study the fixed point equation

$$F(s, v + u_*) - u_* = v \tag{4.16}$$

where  $u_*$  is the unique solution of

$$\begin{aligned} -\Delta u_* &= u_*^{-\alpha} + f && \text{in } \Omega \\ u_* &= 0 && \text{on } \partial\Omega. \end{aligned} \tag{4.17}$$



Moreover if  $v$  is a solution of (4.16),  $v + u_*$  is a solution of problem (1.2). Using Amman’s article [3, Theorem 17.1], we obtain the existence of a nonempty, closed, connected and unbounded set  $\Sigma$  of pairs  $(s, v)$  in  $\mathbb{R}_{\geq 0} \times P$  that solves (4.16).

To prove existence of two solutions we obtain a constant  $C_1$  and a estimate  $C(\delta) > 0$  for  $\delta > 0$  such that:

- (a) If  $(s, u)$  solves equation (1.2) then  $s \leq C_1$ .
- (b) If  $(s, u)$  solves (1.2) then  $\|u\|_{L^\infty(\Omega)} \leq C(\delta)$  for all  $s \geq \delta$ .

Using that  $\Sigma$  is unbounded, the conclusion of Theorem 2.8 follows.

First we prove (a). The function  $Q(u) = \lambda_1 \beta u - su^\beta$  where and  $1 < \beta < \infty$ , has a global maximum on the set of positive real numbers at  $u = (\frac{\lambda_1}{s})^{\frac{1}{\beta-1}}$ , furthermore

$$Q((\frac{\lambda_1}{s})^{\frac{1}{\beta-1}}) = C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}$$

where  $C(\beta, \lambda_1)$  is a strictly positive constant depending only on  $\beta$  and  $\lambda_1$ . From the inequality

$$\lambda_1 \beta u - su^\beta \leq C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}.$$

Using equation (1.2), we deduce

$$-\Delta u \geq \lambda_1 \beta u - C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}$$

and therefore

$$\lambda_1 \int_{\Omega} u \varphi_1 dx \geq \lambda_1 \beta \int_{\Omega} u \varphi_1 dx - C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}} \int_{\Omega} \varphi_1 dx.$$

Finally

$$\int_{\Omega} u \varphi_1 dx \leq \frac{C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}}{\lambda_1(\beta - 1)} \int_{\Omega} \varphi_1 dx. \tag{4.18}$$

From (1.2), we have  $-\Delta u \geq f$ . Using the Uniform Hopf Principle (3.11), (3.12) and (4.18), it follows that

$$s \leq \left\{ \frac{C(\beta, \lambda_1) \int_{\Omega} \varphi_1 dx}{\lambda_1(\beta - 1) C(\Omega) \int_{\Omega} f \varphi_1 dx \int_{\Omega} \varphi_1^2 dx} \right\}^{\beta-1} \tag{4.19}$$

This is the constant  $C_1$  and (a) is proved.

Now we prove (b). We establish a priori bounds for solutions of problem (1.2) using a Brezis-Turner technique (see [12]). Multiplying (1.2) by  $\varphi_1$  and integrating, we find

$$\lambda_1 \int_{\Omega} u \varphi_1 dx = s \int_{\Omega} u^\beta \varphi_1 dx + s \mathcal{B} \int_{\Omega} |\nabla u|^\zeta \varphi_1 dx + \int_{\Omega} u^{-\alpha} \varphi_1 dx + \int_{\Omega} f \varphi_1 dx.$$

From (4.18) it follows that

$$s \int_{\Omega} u^\beta \varphi_1 dx \leq \frac{\lambda_1 C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}}{\lambda_1(\beta - 1)} \int_{\Omega} \varphi_1 dx. \tag{4.20}$$

Using the hypothesis  $\zeta < \frac{2}{n}$  and Young inequality, we obtain a  $q \geq 1$  such that  $0 < \zeta q \leq 2$ ,  $\frac{1}{q} + \frac{1}{\vartheta+1} = 1$ ,  $0 \leq \vartheta < \frac{n+1}{n-1}$  and

$$|\nabla u|^\zeta u \leq \frac{|\nabla u|^{\zeta q}}{q} + \frac{u^{\vartheta+1}}{\vartheta+1} \leq |\nabla u|^2 + 1 + u^\vartheta u. \tag{4.21}$$

Using the assumption

$$\mathcal{B} < \left\{ \frac{\lambda_1(\beta-1)C(\Omega) \int_{\Omega} f \varphi_1 dx \int_{\Omega} \varphi_1^2 dx}{C(\beta, \lambda_1) \int_{\Omega} \varphi_1 dx} \right\}^{\beta-1},$$

inequalities (4.19), (4.21), and multiplying (1.2) by  $u$  and then integrating, we find

$$C_1 \int_{\Omega} |\nabla u|^2 dx \leq s \int_{\Omega} u^{\beta} u dx + sC_2 \int_{\Omega} u^{\vartheta} u dx + C_3 \|u\|_{H_0^1(\Omega)} + C_4, \quad (4.22)$$

where  $C_i$  for  $i = 1, \dots, 4$  are positive constants independent of  $s$ . Using Hölder inequality, (4.20) and the fact that if  $1 < \beta < \frac{n+1}{n-1}$  then for all  $\epsilon > 0$  there exist a positive constant  $C_{\epsilon}$  such that for all  $s > 0$  holds  $s^{\beta} \leq \epsilon s^{\frac{n+1}{n-1}} + C_{\epsilon}$ , we deduce

$$\begin{aligned} \int_{\Omega} u^{\beta} u dx &= \int_{\Omega} u^{\gamma\beta} \varphi_1^{\gamma} u^{(1-\gamma)\beta} \varphi_1^{-\gamma} u dx \\ &\leq \left( \int_{\Omega} u^{\beta} \varphi_1 dx \right)^{\gamma} \left( \int_{\Omega} u^{\beta} \varphi_1^{\frac{-\gamma}{1-\gamma}} u^{\frac{1}{1-\gamma}} dx \right)^{1-\gamma} \\ &\leq (Cs^{-1-\frac{1}{\beta-1}})^{\gamma} \left( \int_{\Omega} u^{\beta} \left( \frac{u}{\varphi_1} \right)^{\frac{1}{1-\gamma}} dx \right)^{1-\gamma} \\ &\leq Cs^{-\gamma-\frac{\gamma}{\beta-1}} \left\{ \epsilon^{1-\gamma} \left( \int_{\Omega} \frac{u^{\frac{n+1}{n-1} + \frac{1}{1-\gamma}}}{\varphi_1^{\frac{\gamma}{1-\gamma}}} dx \right)^{1-\gamma} \right. \\ &\quad \left. + C_{\epsilon}^{1-\gamma} \left( \int_{\Omega} \left( \frac{u}{\varphi_1} \right)^{\frac{1}{1-\gamma}} dx \right)^{1-\gamma} \right\}. \end{aligned}$$

For  $\gamma = 2/(n+1)$ , we find

$$\begin{aligned} \int_{\Omega} u^{\beta} u dx &\leq Cs^{-\gamma-\frac{\gamma}{\beta-1}} \epsilon^{1-\gamma} \left( \int_{\Omega} \left( \frac{u}{\varphi_1^{1/(n+1)}} \right)^{2\frac{n+1}{n-1}} dx \right)^{\frac{n-1}{2(n+1)} \cdot 2} \\ &\quad + Cs^{-\gamma-\frac{\gamma}{\beta-1}} C_{\epsilon}^{1-\gamma} \left( \int_{\Omega} \left( \frac{u}{\varphi_1^{2/(n+1)}} \right)^{\frac{n+1}{n-1}} dx \right)^{\frac{n-1}{n+1}}. \end{aligned}$$

Since

$$\frac{1}{2\frac{n+1}{n-1}} = \frac{1}{2} - \frac{1}{n} + \frac{1}{n+1}, \quad \frac{1}{q} = \frac{1}{2} - \frac{1}{n} + \frac{2}{n+1},$$

with  $q > \frac{n+1}{n-1}$ , we apply Hardy-Sobolev inequality in [12, Lemma 2.2],

$$\left\| \frac{v}{\varphi_1^{\tau}} \right\|_{L^q(\Omega)} \leq C \|v\|_{H_0^1(\Omega)} \quad \text{for all } v \text{ in } H_0^1(\Omega)$$

where  $C$  is a non-negative constant,  $0 \leq \tau \leq 1$ ,  $\frac{1}{q} = \frac{1}{2} - \frac{1}{n} + \frac{\tau}{n}$ ,  $\varphi_1$  is the principal eigenfunction of the operator  $-\Delta$  ( $-\Delta\varphi_1 = \lambda_1\varphi_1$ ) with Dirichlet boundary condition, and the Hölder inequality to obtain

$$\int_{\Omega} u^{\beta} u dx \leq Cs^{-\gamma-\frac{\gamma}{\beta-1}} \left\{ \epsilon^{1-\gamma} \|\nabla u\|_{L^2(\Omega)}^2 + C_{\epsilon}^{1-\gamma} \|\nabla u\|_{L^2(\Omega)} \right\}.$$

From (4.22), we conclude that

$$\begin{aligned} C_1 \|\nabla u\|_{L^2(\Omega)}^2 &\leq Cs^{1-\gamma-\frac{\gamma}{\beta-1}} \left\{ \epsilon^{1-\gamma} \|\nabla u\|_{L^2(\Omega)}^2 + C_{\epsilon}^{1-\gamma} \|\nabla u\|_{L^2(\Omega)} \right\} \\ &\quad + C \|\nabla u\|_{L^2(\Omega)} + C(\delta), \end{aligned} \quad (4.23)$$

where  $C$  is a non-negative constant independent of  $s$ . The condition  $\beta < \frac{n+1}{n-1}$  implies

$$1 - \gamma - \frac{\gamma}{\beta - 1} = \frac{n - 1}{n + 1} - \frac{2}{(n + 1)(\beta - 1)} < 0.$$

Therefore if  $s \geq \delta$ , we can choose  $\epsilon > 0$  such that

$$Cs^{1-\gamma-\frac{\gamma}{\beta-1}}\epsilon^{1-\gamma} \leq \frac{C_1}{2}.$$

It now follows from (4.23) that

$$\frac{C_1}{2} \|\nabla u\|_{L^2(\Omega)}^2 \leq C\{1 + C_\epsilon^{1-\gamma}s^{1-\gamma-\frac{\gamma}{\beta-1}}\} \|\nabla u\|_{L^2(\Omega)} + C(\delta). \tag{4.24}$$

Finally if  $u$  is a solution of the problem (1.2) with  $s > \delta > 0$ , there exists a constant  $C(\delta) > 0$  such that  $\|u\|_{H_0^{1,2}(\Omega)} < C(\delta)$  and using classical Hölder estimates for weak solutions (see [21]) and Sobolev imbedding theorem we conclude the proof of (b). The proof is complete.  $\square$

*Proof of Theorem 2.9.* From Lemma 3.3, the problem

$$\begin{aligned} -\Delta u &= K(x)u^{-\alpha} + f \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega \end{aligned}$$

under the conditions  $|K(x)| \leq B\varphi_1^{1+\alpha}(x)$  for some  $B > 0$  in  $\mathbb{R}$ ,  $f > t_0\varphi_1$  where  $t_0 = B^{\frac{1}{1+\alpha}} [\lambda_1(\frac{\alpha}{\lambda_1})^{\frac{1}{1+\alpha}} + (\frac{\lambda_1}{\alpha})^{\frac{\alpha}{1+\alpha}}]$ , has a unique strong solution  $u \in W^{2,p}(\Omega)$  within the set  $\{v > (\frac{\alpha B}{\lambda_1})^{\frac{1}{1+\alpha}}\varphi_1\}$ . Furthermore if we denote  $H$  the solution map  $f \rightarrow u$ , it is a continuous and compact map from the set  $\{f \in C^1(\overline{\Omega}) : f > t_0\varphi_1\}$  to  $\{u \in C^1(\overline{\Omega}) : u > (\frac{\alpha B}{\lambda_1})^{\frac{1}{1+\alpha}}\varphi_1\}$  (see Lemma 3.3). Hence the map

$$F(s, u) = H(s(u^\beta + |\nabla u|^\zeta) + t\varphi_1).$$

with  $t \geq t_0$  is well from  $\mathbb{R}_{\geq 0} \times P$  to  $P$ , where  $P$  is the cone of positive functions in  $C^1(\overline{\Omega})$ . Like in the proof of previous theorems, we study the fixed point equation

$$F(s, u + u_*) - u_* = u, \tag{4.25}$$

where  $u_*$  is the unique solution in in the set  $\{v > (\frac{\alpha B}{\lambda_1})\varphi_1\}$  (see Lemma 3.3)

$$\begin{aligned} -\Delta u_* &= Ku_*^{-\alpha} + t\varphi_1 \quad \text{in } \Omega \\ u_* &= 0 \quad \text{on } \partial\Omega. \end{aligned}$$

If  $(s, u)$  solves (4.25) then  $(s, u + u_*)$  solves equation (1.2). Now using again the Corollary 17.2 in [3], we find a connected, closed unbounded in  $\mathbb{R} \times P$  and emanating from  $(0, 0)$  set  $\Sigma$  of pairs  $(s, u)$  satisfying the equation (4.25). Since the obtained solution  $u$  of problem (1.2) satisfies  $u \geq (\frac{\alpha B}{\lambda_1})^{\frac{1}{1+\alpha}}\varphi_1$ , we deduce

$$|K|u^{-\alpha} \leq B^{\frac{1}{1+\alpha}} \left(\frac{\lambda_1}{\alpha}\right)^{\frac{\alpha}{1+\alpha}} \varphi_1$$

and from (1.2), we have

$$-\Delta u \geq su^\beta \geq \lambda_1\beta u - C(\beta, \lambda_1)s^{-\frac{1}{\beta-1}}.$$

Multiplying by  $\varphi_1$  and integrating, we find

$$\lambda_1 \int_{\Omega} u\varphi_1 dx \geq \lambda_1\beta \int_{\Omega} u\varphi_1 dx - C(\beta, \lambda_1)s^{-\frac{1}{\beta-1}} \int_{\Omega} \varphi_1 dx.$$

Thus

$$\left(\frac{\alpha B}{\lambda_1}\right)^{\frac{1}{1+\alpha}} \int_{\Omega} \varphi_1^2 dx \leq \int_{\Omega} u \varphi_1 dx \leq \frac{C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}}{\lambda_1(\beta-1)} \int_{\Omega} \varphi_1 dx.$$

Consequently,

$$s \leq \left\{ \frac{C(\beta, \lambda_1)}{\lambda_1(\beta-1)} \left(\frac{\lambda_1}{\alpha B}\right)^{\frac{1}{1+\alpha}} \frac{\int_{\Omega} \varphi_1 dx}{\int_{\Omega} \varphi_1^2 dx} \right\}^{\beta-1}.$$

Recalling that

$$\lambda_1 \int_{\Omega} u \varphi_1 dx = s \int_{\Omega} u^{\beta} \varphi_1 dx + t \int_{\Omega} \varphi_1^2 dx - \int_{\Omega} K(x) u^{-\alpha} \varphi_1 dx,$$

we see that

$$s \int_{\Omega} u^{\beta} \varphi_1 dx \leq \frac{C(\beta, \lambda_1) s^{-\frac{1}{\beta-1}}}{\beta-1} \int_{\Omega} \varphi_1 dx.$$

The rest of the proof is similar to that one of Theorem 2.8.  $\square$

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