Photodetachment of O⁻ yielding O(${}^{1}D_{2}, {}^{3}P$) atoms, viewed with velocity-map imaging

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- Photodetachment/VMI
- PES/PAD $O^- \rightarrow O({}^{3}P_J)$
- *R*-Matrix calculation
- PES/PAD $O^- \rightarrow O(^1D_2)$







Spectrometer - photodetachment/photofragmentation





Velocity-map imaging







STG ANU 4



Atomic fine-structure intensities Scharf and Godefroid arXiv:0808.3529v1

$$\sigma^{TI}(J_{a}J_{i}) = \frac{4\pi^{2}\omega}{3c} \sum_{\ell_{c}} \left(\begin{array}{cc} \ell_{c} & 1 & \ell_{i} \\ 0 & 0 & 0 \end{array} \right)^{2} (\epsilon\ell_{c}|r|n_{i}\ell_{i})^{2} [J_{a}, S_{i}, L_{i}] \times \\ N(S_{a}L_{a}, \ell_{i}|\}S_{i}L_{i})^{2} \sum_{j_{i}} [j_{i}] \left\{ \begin{array}{cc} S_{a} & L_{a} & J_{a} \\ s & \ell_{i} & j_{i} \\ S_{i} & L_{i} & J_{i} \end{array} \right\}^{2},$$

For oxygen atom: 3

$${}^{3}P_{2,1,0}: L_{a} = 1 \quad S_{a} = 1 \quad J_{a} = 2, 1, 0$$

 ${}^{2}P_{\frac{1}{2},\frac{3}{2}}: L_{i} = 1 \quad S_{i} = \frac{1}{2} \quad J_{i} = \frac{1}{2}, \frac{3}{2}$

27,653 cm⁻¹ 12,012 cm⁻¹ 11,785 cm⁻¹ 11,785 cm⁻¹ 12,012 cm⁻¹ 11,785 cm⁻¹ 12,012 cm⁻¹ 12,012

and the 9*j* symbol sum gives:

$${}^{3}P_{2} \leftarrow {}^{2}P_{\frac{3}{2}} : {}^{3}P_{1} : {}^{3}P_{0} = 1 : 0.36 : 0.08$$

³*P* ratio
$${}^{2}P_{\frac{1}{2}} : {}^{2}P_{\frac{3}{2}} = 0.4$$
 Temperature (O⁻) = $\frac{-177.13 \times hc}{k \ln(5 \times \frac{l_{\frac{1}{2}}}{l_{\frac{3}{2}}})}$



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"... have reached a level of stability and robustness ... used to solve a wide variety of low electron and positron scattering problems" Morgan *et al* Comp Phys Comm **114** 120-128 (1998)



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Calculations *R*-matrix



Issue with R-matrix code

Oleg (Drake): I still get positive values for β_{1D} , even after double check of possible bugs in the program Klaus (Drake): The Belfast *R*-matrix code ... had some interesting troubles Mabbs (Wash U): ... to get a sensible low eKE curve we have to change a sign in the calculation



Back to basics: Zero-core-contribution model Stehman and Woo Phys Rev A20 281-290 (1979)

- Evaluate R_s and R_d matrix elements using H-atom ground-state wavefunction for initial state and plane-wave for free electron
- Simple analytical expressions for R_s and R_d
- Two parameter model: r_0 and $\gamma = \cos(\Delta)$ •



 $\sigma \propto R_s^2 + 2R_d^2$

 $\beta \propto \frac{2(R_d^2 - \gamma R_d R_s)}{2}$



Conclusions

- VMI provides μ eV electron kinetic-energy resolution and full angular distribution
- R-matrix computational code predicts $\beta_{1D_2} > 0$
- Experiment
 - $\beta_{^1\!D_2}$ same sign as $\beta_{^3\!P}$
 - $\beta_{^1\!D_2}$ different energy dependence to $\beta_{^3\!P}$
- Measurements consistent with "simple" s- and d-wave detachment model
- "Black box" R-matrix computational code may have problems ...





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End



Appendix

- PyAbel: Abel transforms
- Cooper-Zare angular distribution of photoelectrons



PyAbel: Abel transform software https://github.com/PyAbel

README.rst

PyAbel README

build error 📀 BUILD PASSING

Note: This readme is best viewed as part of the PyAbel Documentation.

Introduction

PyABE3 is a Python package that provides functions for the forward and inverse Abel transforms. The forward Abel transform takes a slice of a cylindrically symmetric 3D object and provides the 2D projection of that object. The inverse abel transform takes a 2D projection and reconstructs a slice of the cylindrically symmetric 3D distribution.

Inverse Abel transforms play an important role in analyzing the projections of angle-resolved photoelectron/photolon spectra, plasma plumes, flames, and solar occultation.

PyAbel provides efficient implementations of several Abel transform algorithms, as well as related tools for centering imager symmetrizing images, and calculating properties such as the radial intensity distribution and the anisotropy parameters.



Transform Methods

The outcome of the numerical Abel Transform depends on the exact method used. So far, PyAbel includes the following transform methods:

- 1. basex Gaussian basis set expansion of Dribinski and co-workers.
- 2. hansen1aw recursive method of Hansen and Law.
- 3. direct numerical integration of the analytical Abel transform equations.
- 4. two_point the "two point" method of Dasch and co-workers.
- 5. three_point the "three point" method of Dasch and co-workers.
- 6. onion_peeling the "onion peeling" deconvolution method of Dasch and co-workers.
- 7. onion_bordas "onlon peeling" or "back projection" method of Bordas et al. based on the MatLab code by Rallis and Wells et al.
- 8. linbasex the 1D-spherical basis set expansion of Gerber et al.
- 9. fh Fourier-Hankel method (not yet implemented).
- 10. pop polar onion peeling method (not yet implemented).



Cooper and Zare J Chem Phys 48 942 (1968)

$$\beta_{\ell} = \frac{\ell(\ell-1)R_{\ell-1}^2 + (\ell+1)(\ell+2)R_{\ell+1}^2 - 6\ell(\ell+1)R_{\ell+1}R_{\ell-1}\cos(\delta_{\ell+1} - \delta_{\ell-1})}{3(2\ell+1)[\ell R_{\ell-1}^2 + (\ell+1)R_{\ell+1}^2]}$$