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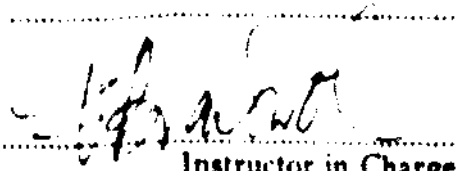
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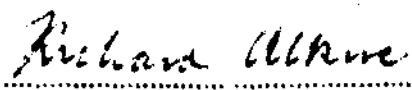
THIS IS TO CERTIFY THAT THE THESIS PREPARED UNDER MY SUPERVISION BY

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ENTITLED... A MOLECULAR DYNAMICS STUDY OF LIQUID-SOLID COEXISTENCE

IS APPROVED BY ME AS FULFILLING THIS PART OF THE REQUIREMENTS FOR THE  
DEGREE OF... BACHELOR OF SCIENCE IN CHEMICAL ENGINEERING

  
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HEAD OF DEPARTMENT OF... CHEMICAL ENGINEERING

**A Molecular Dynamics Study  
of  
Liquid-Solid Coexistence**

by

**Tom Alan Pasmore, Jr.**

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**Thesis**

**for the  
Degree of Bachelor of Science  
in  
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## Abstract

In this work we report on four different studies of fluid-crystal coexistence involving molecular dynamics simulations. The investigations described herein include wetting on structured walls, determination of the coexistence density of a fluid crystal system, prefreezing in a coexistence system, and spontaneous segregation of a highly ordered fluid into liquid and solid phases. Molecular dynamics were used in order to examine several systems which would be physically. The simulations using the hard sphere are accurate enough to permitted limited applicability. While the preliminary results demonstrate intuitive conclusions, many more simulations are required before complete characterization of these systems can actually been realized.

## Acknowledgements

I'd like to thank Spike for the help and guidance in the realization of this thesis and my graduate career, but more importantly for all the cool tunes; Frank for the chance he gave me way back in August; the rest of the group for showing me that computers really aren't out to get me, and Jess for her neverending supply of faith and encouragement. Lastly, special thanks to Frederico Zamboni, may he rest in peace.

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## Introduction

Phase transitions are a major part of the world around us, and of ongoing interest within chemical engineering. The solid-liquid transition has been one of the least studied due to the difficulty of examining the interface of the two dense phases. Studies of two coexisting phases naturally lead into the question the wetting state in the presence of a substrate. Cahn sparked a renewed interest in wetting state studies with his work [1]. Considering, most of these transitions occur on an atomic level and are experimentally difficult to study, molecular dynamics appears the easiest way to collect preliminary data on the system.

Molecular Dynamics (MD) computer simulation has been a useful tool since Alder and Wainwright introduced it in the late 50's [2,3]. Simulations have allowed scientist and engineers to probe unique systems at conditions that would difficult or impossible to physically reproduce in laboratory.

The procedures and methods of MD simulation are discussed thoroughly in Allen and Tildeseley [4]. In the these simulations the computer solves the equations of motion for each particle in the system, as a function of the potential of the system. The hard sphere potential model is one of the simplest models of atomic interactions. It states that the pair interaction is infinite when the particles are separated by a distance less than  $\sigma$ , the atomic diameter, or zero otherwise. By selecting the hard sphere potential, the system can be solved exactly using classical mechanics. Thus assigning a configuration of particles both position and velocity, the thermodynamic state of the system has been defined. The equation of state for hard spheres appears in figure 1, and is given by

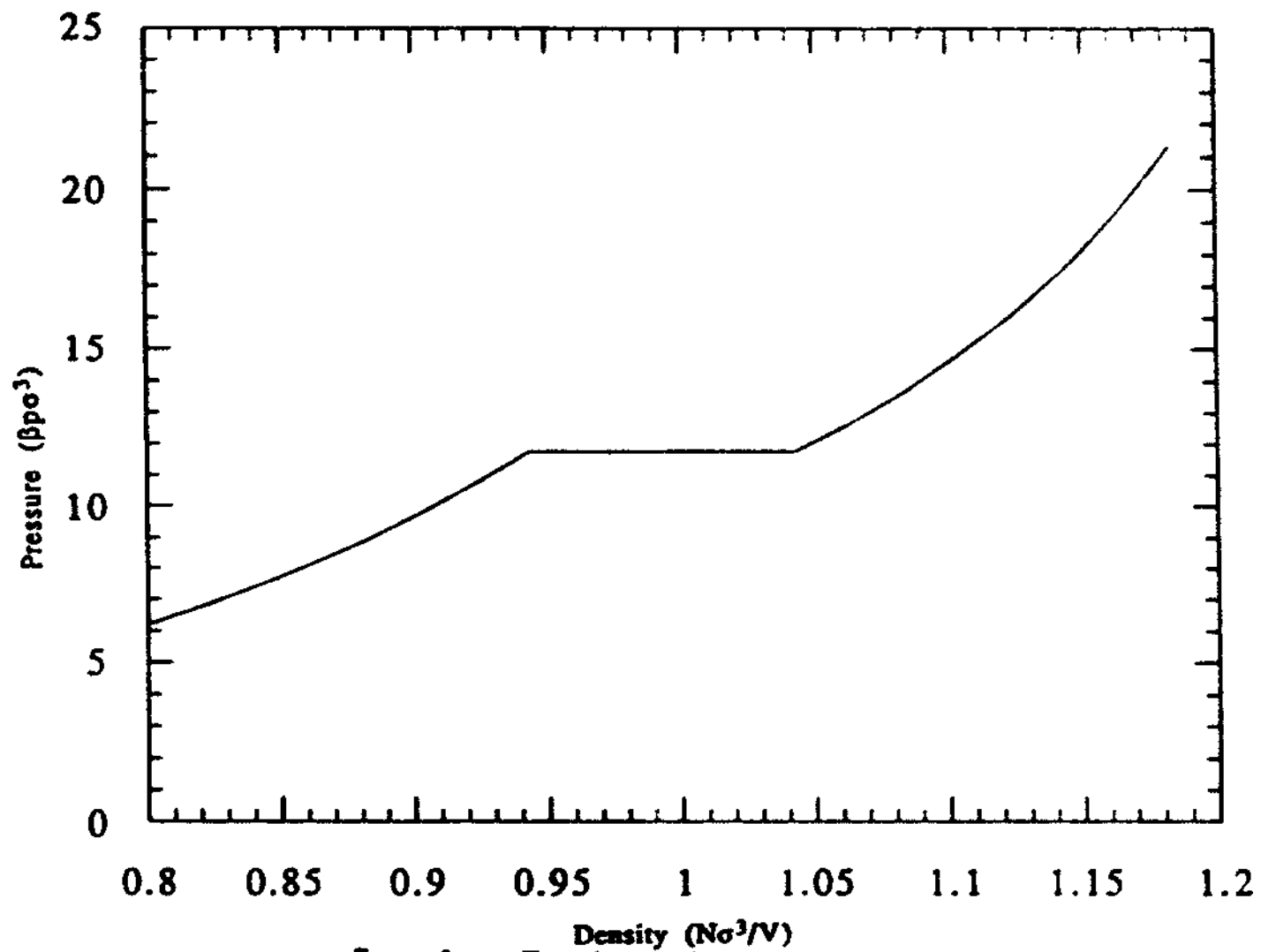


figure 1 - Equation of State for Hard Spheres

$$\frac{\beta p}{\rho^*} = \frac{1 + \eta + \eta^2}{(1 - \eta)^3} \quad \text{fluid (1)}$$

$$\frac{\beta p}{\rho^*} = \frac{1 + \eta + \eta^2 - 0.67825\eta^3 - \eta^4 - 0.5\eta^5 - 6.028e^{(\eta^2 - 2\eta)}\eta^6}{1 - 3\eta + 3\eta^2 - 1.04305\eta^3} \quad \text{solid (2)}$$

where:

$$\eta = \frac{\pi n \sigma^3}{6 V}$$

$$\xi = \pi\sqrt{2}/6 - \eta$$

Using MD with hard spheres, each particle is given a unique position and velocity vector. For the hard sphere model no forces act on any particle except upon collision, therefore all particles move in a straight line with constant velocity until such time as they come into contact with another particle. The collision time for each pair of particles,  $i$  and  $j$ , is then calculated using equation (3):

$$\Delta t_{ij} = -\frac{b_{ij} + \sqrt{b_{ij}^2 - \vec{v}_{ij} \cdot \vec{v}_{ij} \times (\vec{r}_{ij} \cdot \vec{r}_{ij} - \sigma^2)}}{\vec{v}_{ij} \cdot \vec{v}_{ij}} \quad (3)$$

where  $\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$ ,  $\vec{v}_{ij} = \vec{v}_i - \vec{v}_j$ , and  $b_{ij} = \vec{r}_{ij} \cdot \vec{v}_{ij}$ .

From all of these times the shortest one is selected and particles are advanced for this amount of time with their current velocities. Now the position for each particle is:

$$\vec{r}_{i,t+\Delta t} = \vec{r}_{i,t} + \vec{v}_i \times \Delta t \quad (4)$$



This brings the colliding particles within a distance  $\sigma$  from each other. At this point, new velocity vectors are calculated for both colliding particles from equation (5) with both momentum and kinetic energy being conserved.

$$\Delta \vec{v} = \frac{\vec{r}_{ij} \times \vec{b}_{ij}}{\sigma^2} \quad (5)$$

This equation implies that the expressions are all evaluated at the point of contact between the two particles. Now the process is repeated until the desired number of collisions have been completed.

The main disadvantage of the hard sphere potential model is the oversimplification of the system. In our studies we have explored several liquid-solid wetting and coexistence phenomena using the hard sphere potential. The choice of hard sphere potential, although eliminating all interactions between particles, is still able to capture the essential physics of the problem, and is applicable primarily to noble element systems.

### A Preliminary Study of Wetting on Structured Hard Walls

When a multi-phase system is in the presence of a substrate one phase or the other may preferentially contact the surface. Complete wetting by one phase describes the state where that phase completely covers the substrate. Partial wetting is the state where both phases are simultaneously in contact with the substrate. The wetting state can be described by the contact angle,  $\theta$ , where  $\theta$  is defined below as a function of the surface free energies [5]:

$$\gamma_{\alpha\beta} \cos(\theta) = \gamma_{\alpha\chi} - \gamma_{\beta\chi} \quad (6)$$

where  $\gamma_{\alpha\beta}$  is the surface free energy of the crystal and liquid,  $\gamma_{\alpha\chi}$  is the surface free energy of the wall and the crystal, and  $\gamma_{\beta\chi}$  is the surface free energy between the fluid and the wall.

The study conducted on the wetting of smooth walls by Courtemanche and van Swol (C&vS) [6] has laid the foundation for the current study. They demonstrated that a smooth hard wall is completely wet by crystal ( $\cos(\theta)=1$ ). We proceeded to survey various wall configurations in an effort to examine the speed of nucleation and attempt to force wetting by fluid ( $\cos(\theta)=0$ ). The unsystematic approach we have used has yielded some initial results, which will need more work to thoroughly develop.

## METHODOLOGY

The system used in the simulations contains 2100 hard sphere particles enclosed by two hard walls in the z direction and periodic boundary conditions (PBC) in both the x and y directions. The dimensions of the box were  $5.53764\sigma$  by  $9.59174\sigma$  by  $40.234752\sigma$ , where  $\sigma$  is the diameter of an individual particle. The particles are in a canonical ensemble at liquid solid coexistence pressure. The configuration was constructed from a hard sphere crystal with the fcc (111) plane aligned parallel to the walls of the box. A section of the crystal was then stretched by spreading the distance in between the crystal planes. This resulted in a lowering of density within the system and thus the decomposition of this region of the bulk crystal into bulk fluid. The densities referred to are defined by:

$$\rho^* = \frac{N\sigma^3}{V}$$

where  $N$  is the number of particles and  $V$  is the volume of the box . For hard spheres, crystal phase density,  $\rho^*$ , is equal to 1.0409 and  $\rho^*_f$  is 0.943.

The simulations were run on various wall configurations with the system described above. Those conditions surveyed included 50 particles in perfect bulk crystal arrangement on both walls, crystal on one wall and smooth surface on the other, 43 particles whose positions are randomly displaced in directions across the x-y plane, and a 43 particle configuration randomly displaced in all directions. By observing the density profiles from each simulation we can identify the type of wetting occurring.

## RESULTS

The first wall configuration to be examined was full crystal on both walls. To accommodate the structure on the wall the distance along the z axis was increased to  $40.984752\sigma$ , in order to avoid overlaps. The various simulations showed marked acceleration in the crystal formation. In the smooth walled experiments previously done by C&vS nucleation occurred in  $4 \times 10^7$  collisions with complete crystallization on both walls in  $7 \times 10^7$  collisions. The current system, however, nucleated on both walls in under  $3.5 \times 10^6$  collisions and became completely symmetric in  $19 \times 10^6$  collisions, as shown in figure 2. This growth occurred approximately ten times faster than the smooth walled system.

Next, the right wall was replaced with a smooth hard wall at the same distance used for the structured wall simulation. Although the amount of crystal decreased, both walls retained the crystal wetting This was done to

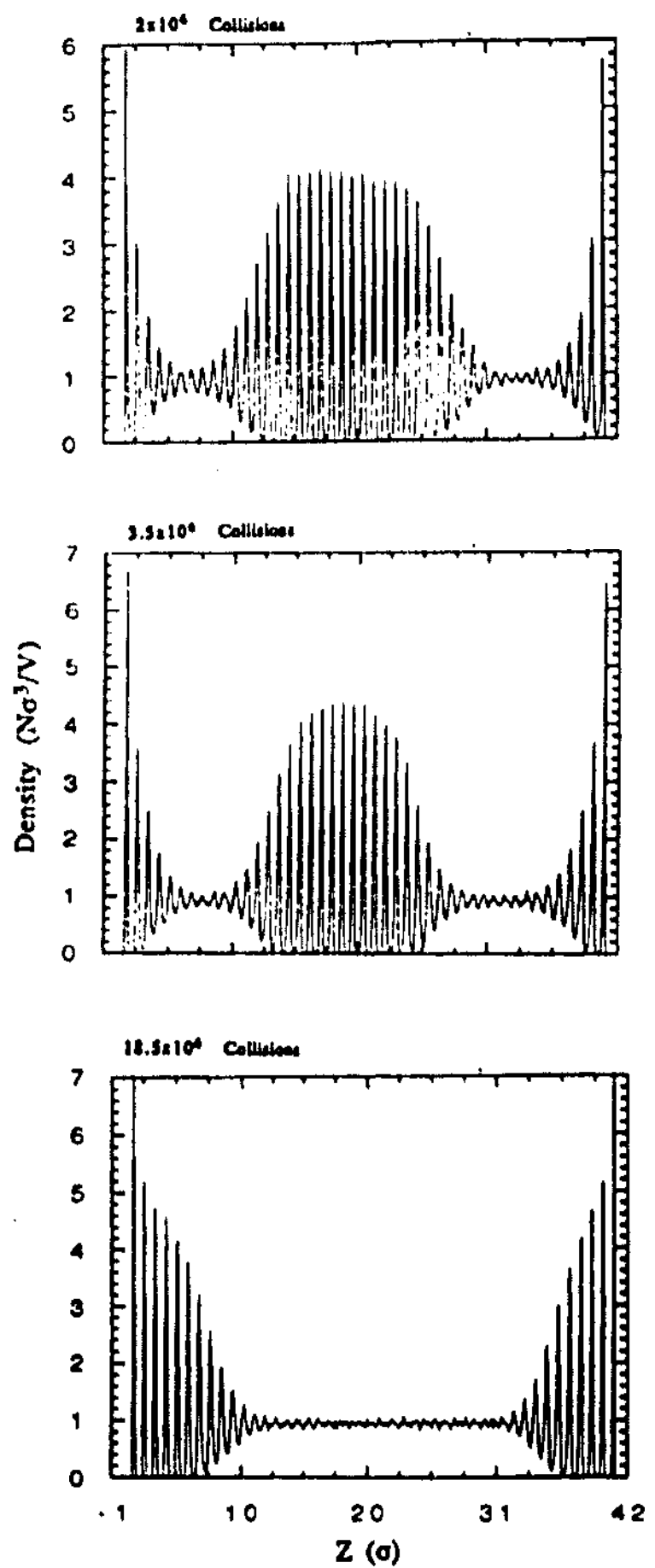


figure 2 - Density Profiles  
Wetting on Crystal Structured Walls

check that any melting that might occur in the structured wall simulation was due to the structure on the wall and not the increase in volume of the system. The volume increase by putting a smooth wall at a given position is greater than that of placing a structured wall at the same point. As shown by the graphs in figure 3, we initially lost all but one of the crystal layers, but in the end two more layers had recrystallized on the wall before equilibrium was reestablished. Thus the crystal would not completely melt due to the change in volume. Required for the introduction of structured walls would be necessary.

The second series of experiments tested the ability of a crystal to wet various surfaces. Knowing that a smooth wall provided enough order to promote nucleation, we examined surfaces that would disorder the hard spheres in the wall region to see if wetting by fluid could be induced. The first wall tested had 7 particles removed from the 50 required for a perfect crystal layer and the rest randomly distributed across the surface of the wall, while maintaining their original position in the z direction. The starting configuration, figure 4, of the system was such that the wall was already wet by crystal. This configuration was obtained from an equilibrium system where both walls had a perfect crystal structure.

The number of layers on the disordered wall was monitored by use of the density profile. The density profile in figure 4 showed that the total number of layers on the right wall never dropped below five, and thus retaining crystal wetting on the right wall. When the configuration was rerun with fluid wetting the walls instead of crystal, nucleation was not observed even after  $4 \times 10^7$  collisions. The density profiles are shown in

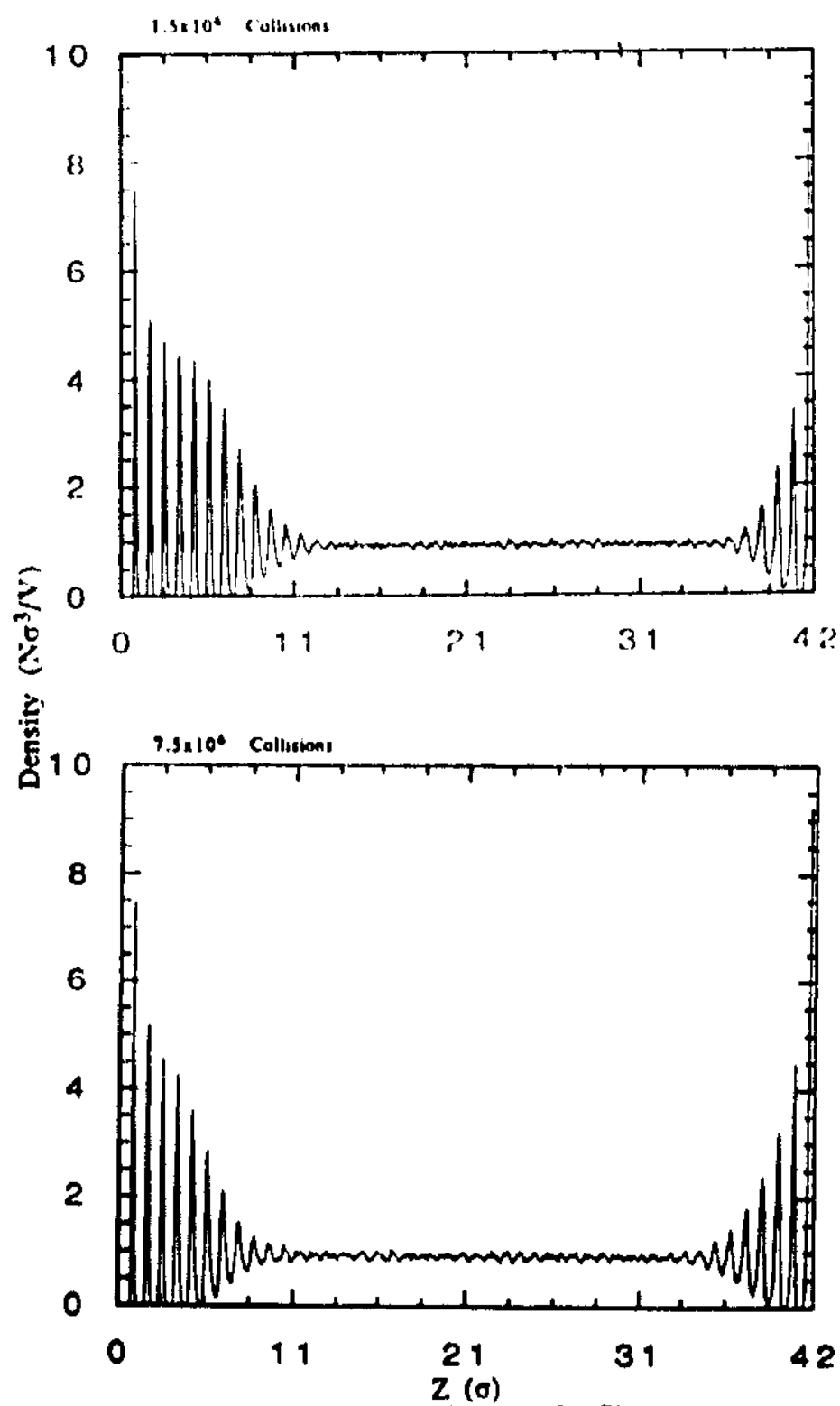


figure 3 - Density Profiles  
Wetting on a Crystal Structured Wall & Smooth Wall

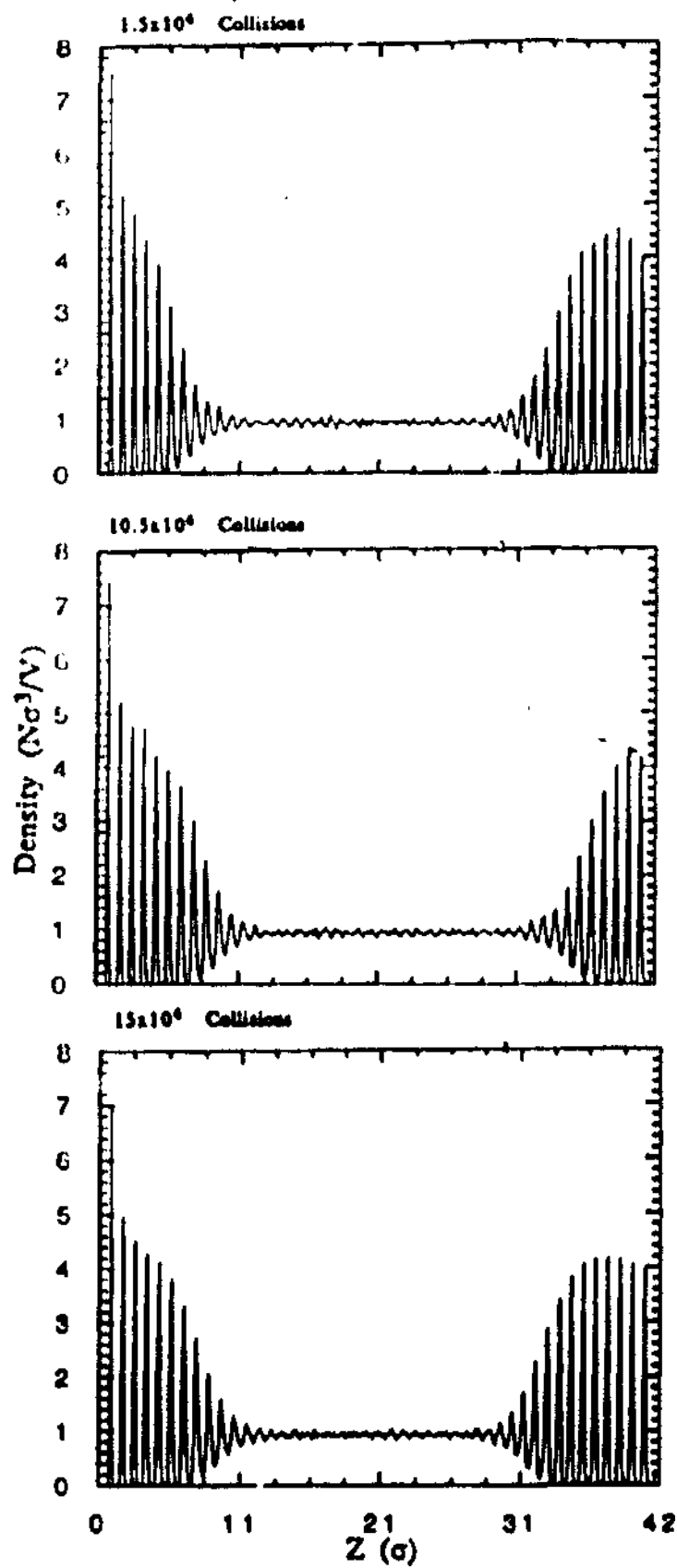


Figure 4 - Density Profiles  
Wetting on a Crystal Structured Wall &  
a Randomized Structured Wall with  
Previous Crystal Wetting

figure 5. However, it is not clear whether it is impossible for nucleation to occur against this wall or if more collisions are necessary to observe nucleation. The results are simply inconclusive due to the length of the simulation.

A system was also studied where the 43 particles on the right wall were also randomized with respect to the z direction. Although the system began with crystal wetting on the wall, the randomness of the structure forced wetting by fluid after only  $4.5 \times 10^6$ , as shown in figure 6. The completely random configuration is essentially a snapshot of amorphous static fluid and thus can only allow the wetting by fluid that we observe.

## DISCUSSION

The results of the various wall configuration shows a few initial conclusions. First, the speed of crystallization is increases with the number nucleation sites available. The bulk crystal walls nucleated the fastest because they had large numbers of sites available, while the slowest walls were the smooth walls which has no sites on the surface.

Secondly, wetting by crystal is a minimum in the surface free energy of the system. This is demonstrated by crystal wetting the smooth walls and in one case the randomized walls. From our results it appears that order in the direction perpendicular to the interface is necessary condition for crystallization to occur, but more work is needed to confirm that hypothesis.

The results from the static fluid wall make intuitive sense as it was observed that the stabilization in the z direction provided by a smooth wall was sufficient to induce nucleation. The second series of structured wall



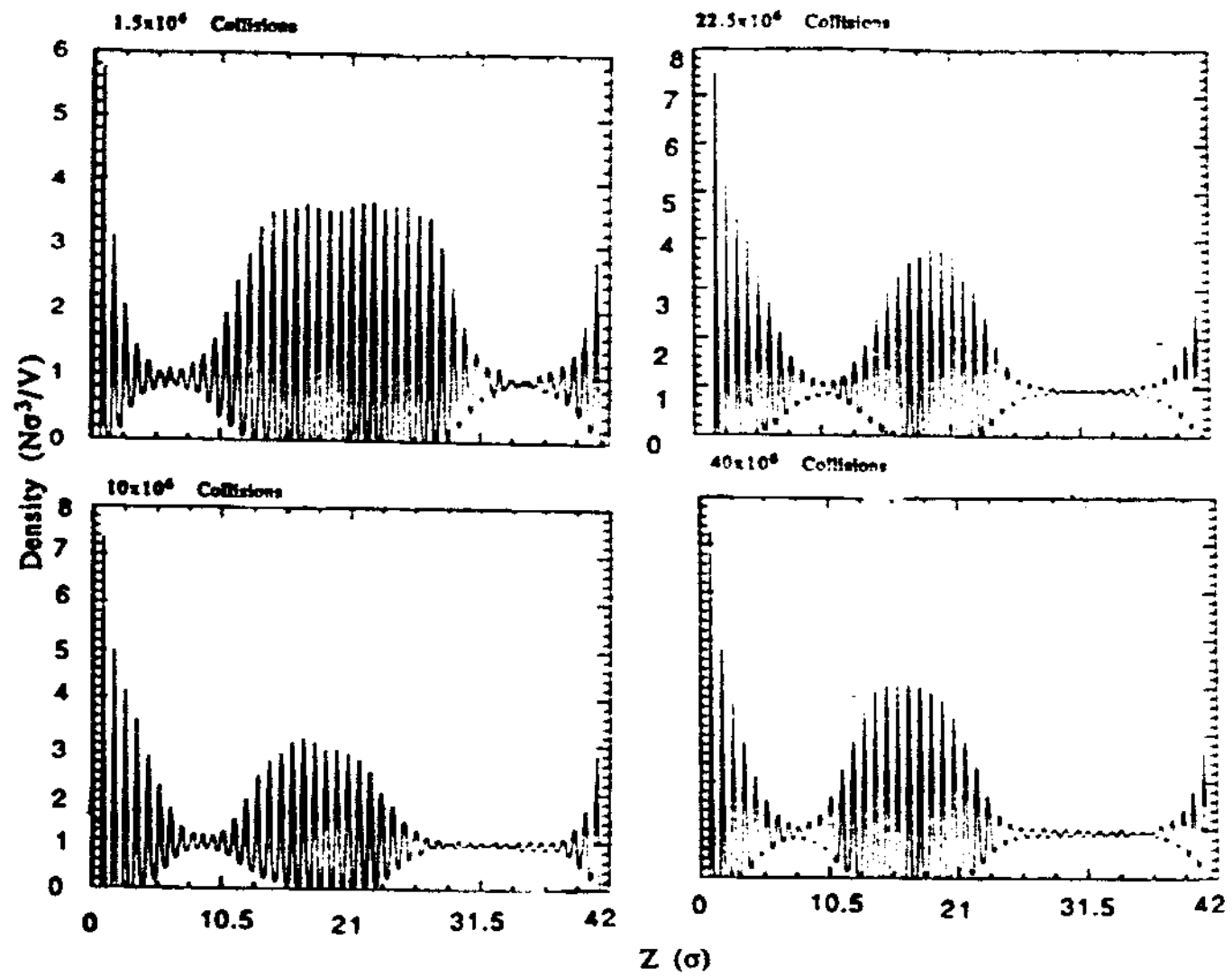


figure 5 - Density Profiles Wetting on a Crystal Structured Wall & a Randomized Structured Wall with Previous Fluid Wetting

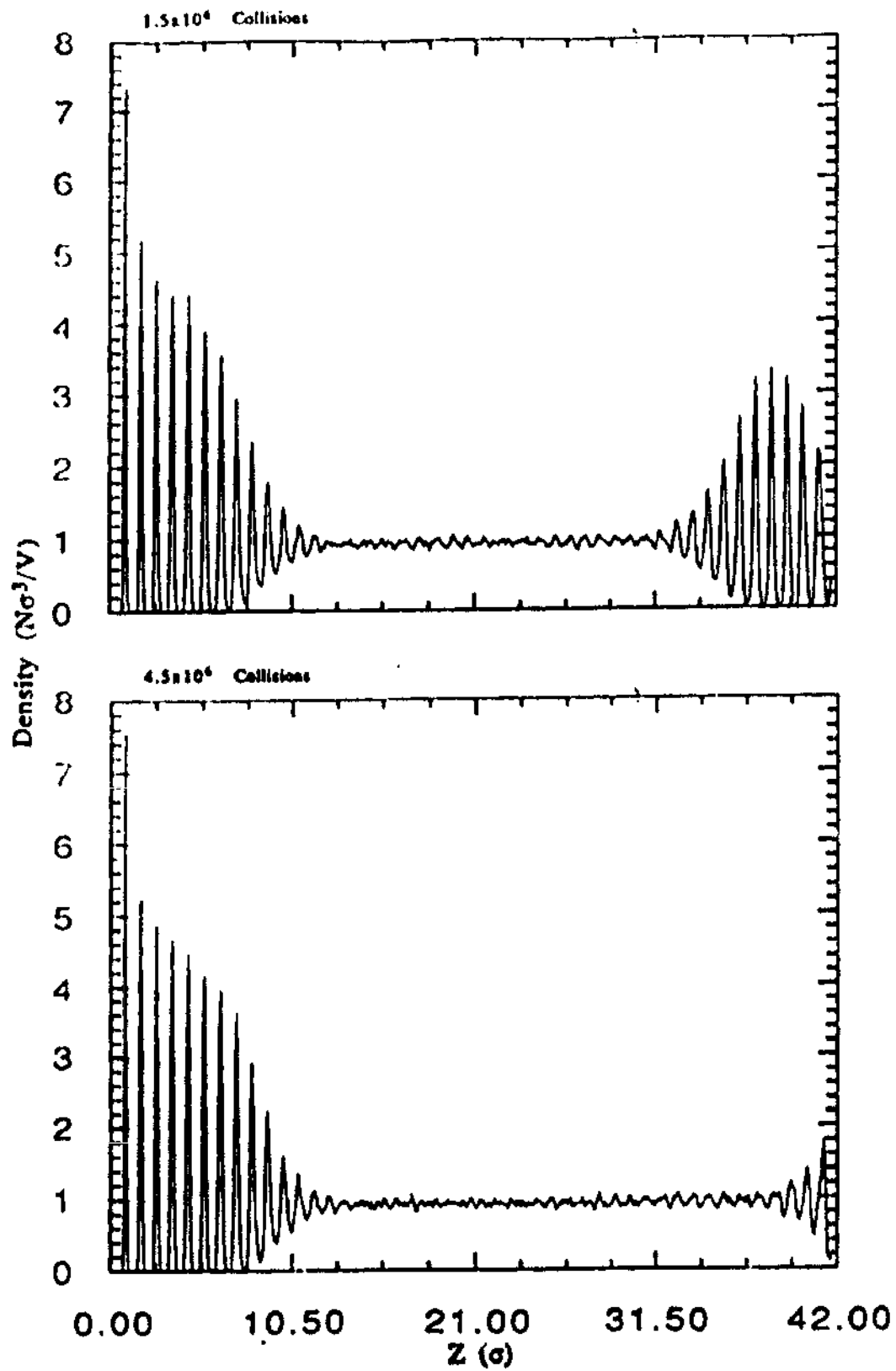


figure 6 - Density Profiles  
Wetting on a Crystal Structured Wall &  
a Fluid Structured Wall

simulations also indicated that stabilization in the z direction was the dominant factor in crystal wetting.

## Determination of Liquid-Solid Coexistence Density for Hard Spheres

By examining a plot of the equation of state for hard spheres as a function of density, there is a region of the curve where the derivative goes to zero. This is the excluded region joining the Hall equation for hard sphere solids [7] and Carnahan-Starling equation for hard sphere fluids [8], and is referred to as a tie bar. The original work on the location of the transition was done by Hoover and Ree [9,10]. They located the melting transition for hard spheres by simulating a solid crystal at various densities. The determination of the transition density was done by using pressure measurements which were used to calculate communal entropy. We wish to confirm the observations seen previously, by incorporating the simulation of a two phase coexistence system in to the study.

### METHODOLOGY

The hard sphere particles were used in two different NVT systems with PBC, both of which were involved in the experimentation. One system was a single crystal of 750 particles which were set at the specified densities and run to obtain the resulting pressures. Pressures are calculated by the relative positions and velocities of the particles colliding, as shown below:

$$p_t = k_B T n(z) - \frac{m}{\Lambda t} \sum_{\gamma} \frac{\bar{x}_{ij}^2 + \bar{y}_{ij}^2}{\sigma^2} (\bar{r}_{ij} \cdot \bar{v}_{ij}) \frac{1}{|\bar{z}_{ij}|} \theta\left(\frac{z - \bar{z}_i}{\bar{z}_{ij}}\right) \theta\left(\frac{\bar{z}_j - z}{\bar{z}_{ij}}\right) \quad (8)$$

$$p_n = k_B T n(z) - \frac{m}{At} \sum_{\gamma} \sum_{i,j}^{\nu} \frac{\bar{z}_{ij}^2}{\sigma^2} (\bar{r}_{ij} \cdot \bar{v}_{ij}) \frac{1}{|\bar{z}_{ij}|} \theta\left(\frac{z - \bar{z}_i}{\bar{z}_{ij}}\right) \theta\left(\frac{\bar{z}_j - z}{\bar{z}_{ij}}\right) \quad (9)$$

where  $\bar{r}_{ij}$  is  $\bar{r}_i - \bar{r}_j$ ,  $\bar{v}_{ij}$  is  $\bar{v}_i - \bar{v}_j$ ,  $\bar{z}_{ij}$  is  $\bar{z}_i - \bar{z}_j$  (the difference in  $z$  location),  $\theta$  is the Heaviside unit step function,  $p_t$  is the transverse component of the pressure,  $p_n$  is the normal component of the pressure, and  $\nu(t)$  is the number of collisions occurring in time  $t$ . These equations are described more thoroughly in van Swol and Henderson [11]. The bulk crystal configuration was manufactured by the simulation program for each individual density.

The second system is a 2100 particle, two phase PBC system at coexistence. It was created from earlier work by C&vS, and is shown in figure 7. It is being run simultaneously with the single phase simulation to determine system pressure. When the one phase and two phase pressures are the same, within error limits, true coexistence has been achieved. We are searching for the density or densities for which this the case.

## RESULTS

The first crystal density studied was  $1.307 N\sigma^3/V$ , which came from the PBC coexistence runs done in the wetting study. The pressure history, figure 8, for both phases was plotted after  $3 \times 10^7$  collisions to determine the mean pressure for both systems. The mean pressure of the one phase system,  $11.574 \beta p \sigma^3$ , was above the equivalent two phase pressure,  $11.489 \beta p \sigma^3$ . This indicated that this density was too high for true coexistence, so a new density was chosen.

A crystal density of 1.0361 was then selected because it was calculated to produce a coexistence system at a normal pressure of  $11.50 \beta p \sigma^3$ . However, after running this system for  $6.5 \times 10^7$  collisions, this density

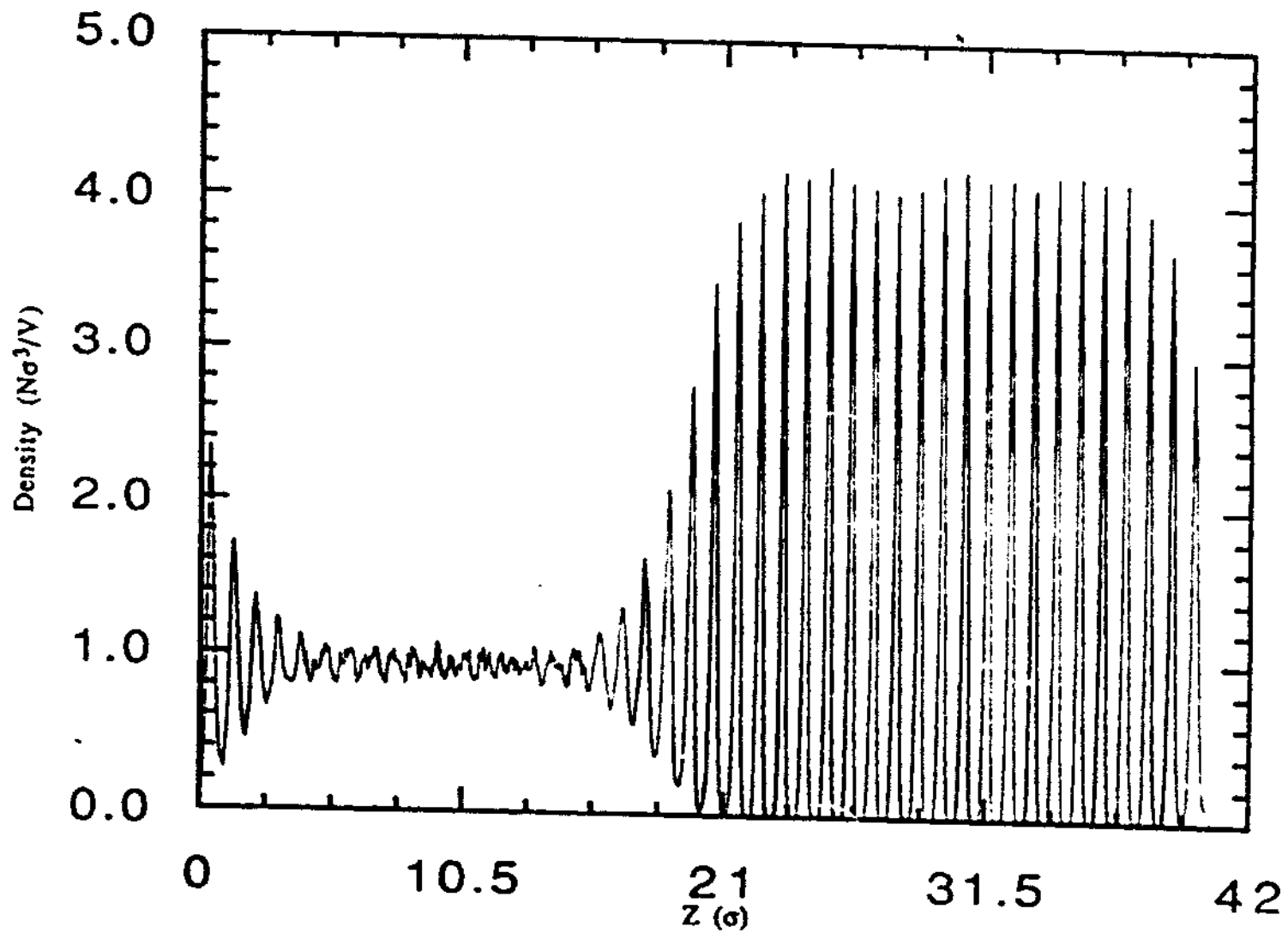
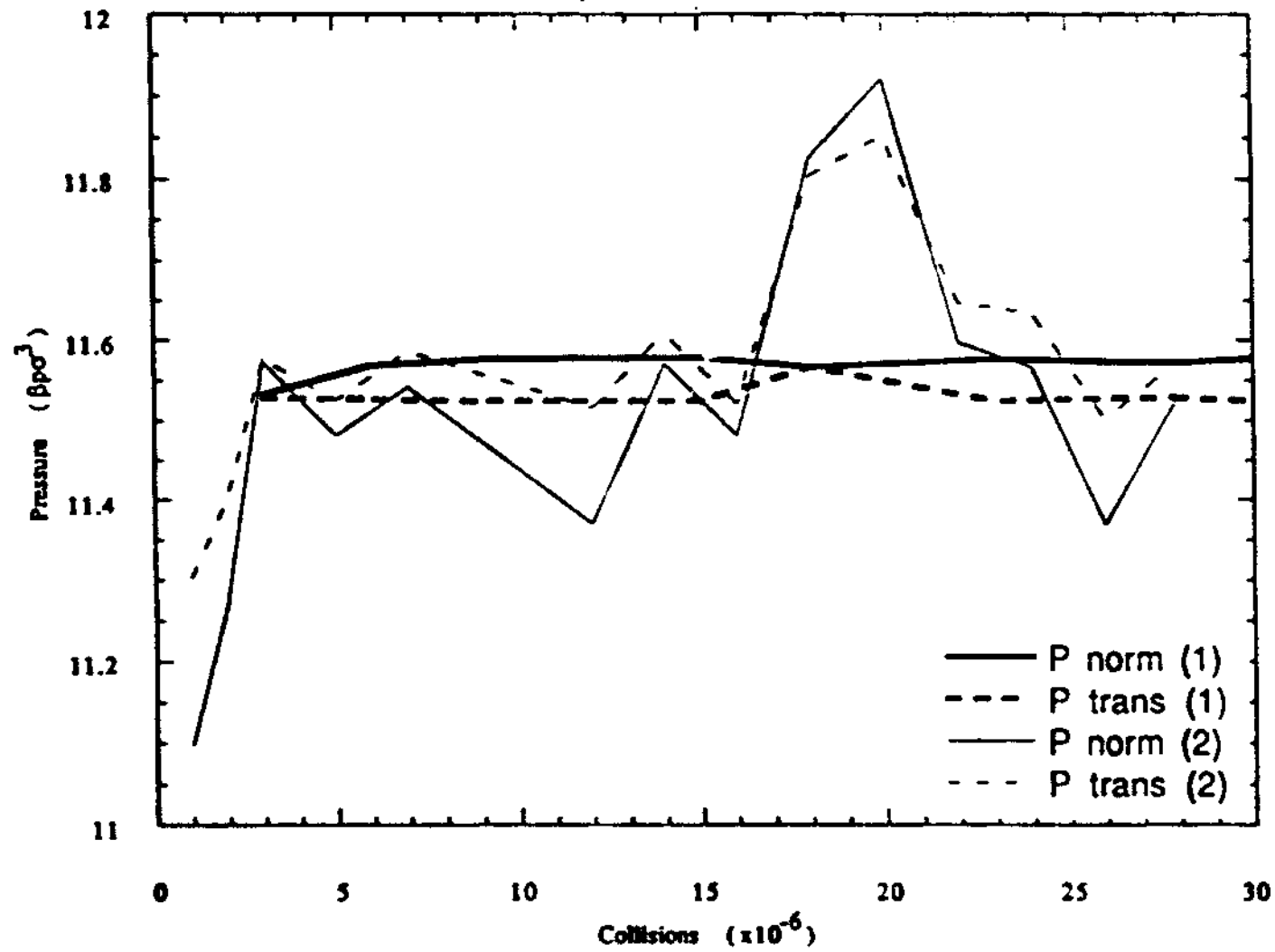


figure 7 - Density Profile  
Initial System Configuration of Two Phase PBC Experiments

figure 8  
Pressure History for the Coexistence Density Determinations  
 $\rho^* = 1.0370$



produces a mean two phase pressure that was still below the  $11.50 \beta p \sigma^3$ . The one phase system equilibrates at a normal pressure of  $11.45 \beta p \sigma^3$  while the two phase mean is  $11.39 \beta p \sigma^3$ , as shown in the pressure history, figure 9.

The last density studied was  $\rho_c^* = 1.0348$ . The resulting mean pressures, from figure 10, of  $11.48 \beta p \sigma^3$  for the one phase and  $11.44 \beta p \sigma^3$  for the two phase demonstrate, within error limits, agreement between the two systems. Therefore we believe this density is correct for true coexistence of this system.

## DISCUSSION

From the three experiments performed ( $\rho_c^* = 1.037, 1.0361, \& 1.0348$ ) we have observed that the crystal density of coexistence is equal to 1.0348. We observed the best correlation between the one and two phase pressures at this density. The fluctuations present in two phase pressure histories greatly limit the accuracy with which our two systems can be compared. Longer simulations would allow a better curve averaging and thus produce more consistent data. The study should also be expanded to include several more densities to insure thoroughness. It was observed that the normal pressure was generally less than the transverse pressures for the two phase simulations, while the one phase system demonstrated the opposite trend. This is possibly due to the non cubic shape of the box.

### Determination of Prefreezing Conditions

There exists a hysteresis loop in the curve of adsorption versus pressure (or, alternatively, chemical potential). This states that there is region of pressures where one may find wetting by either crystal or fluid,

figure 9  
Pressure History for the Coexistence Density Determinations  
 $\rho^* = 1.0361$

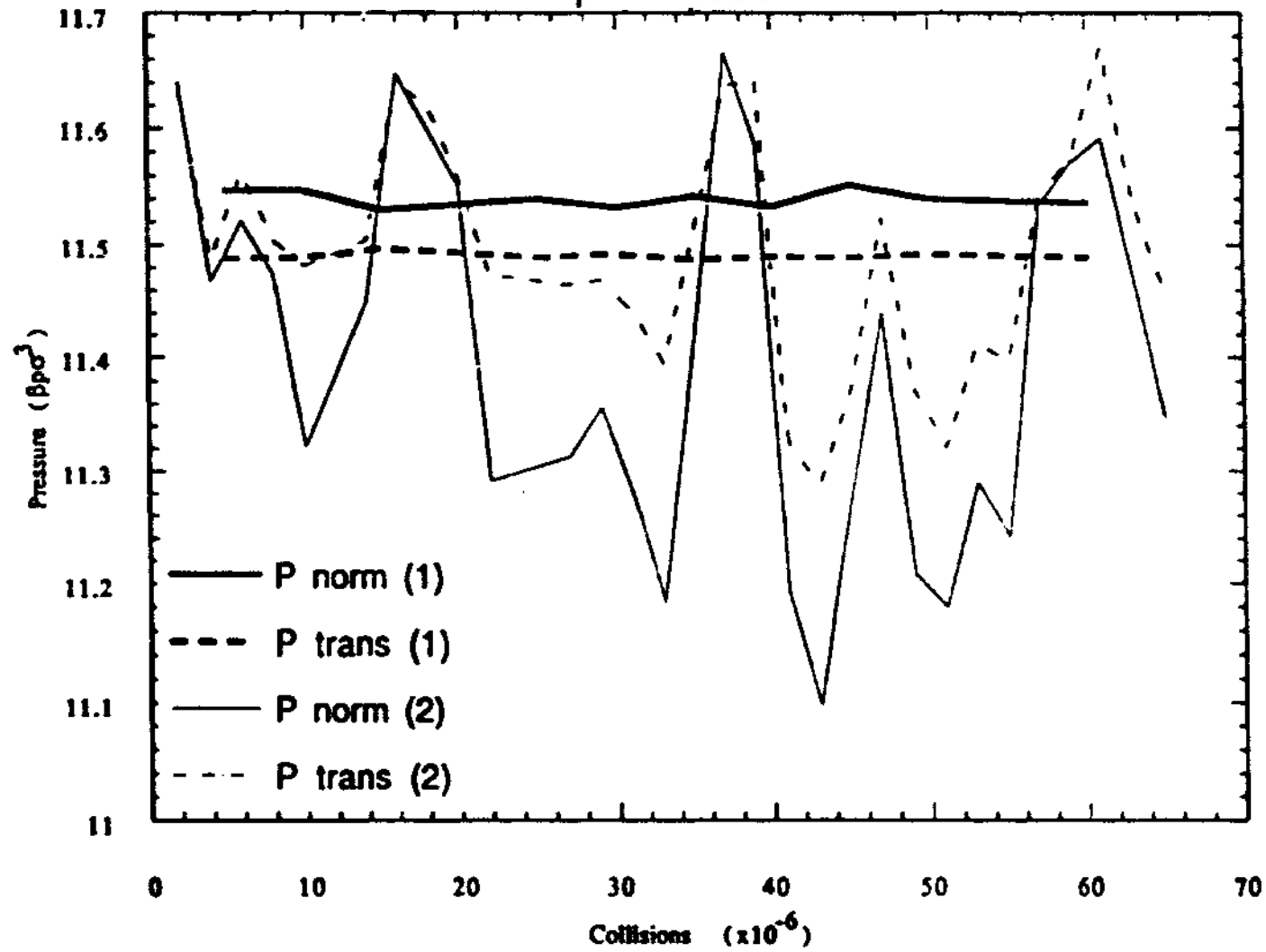
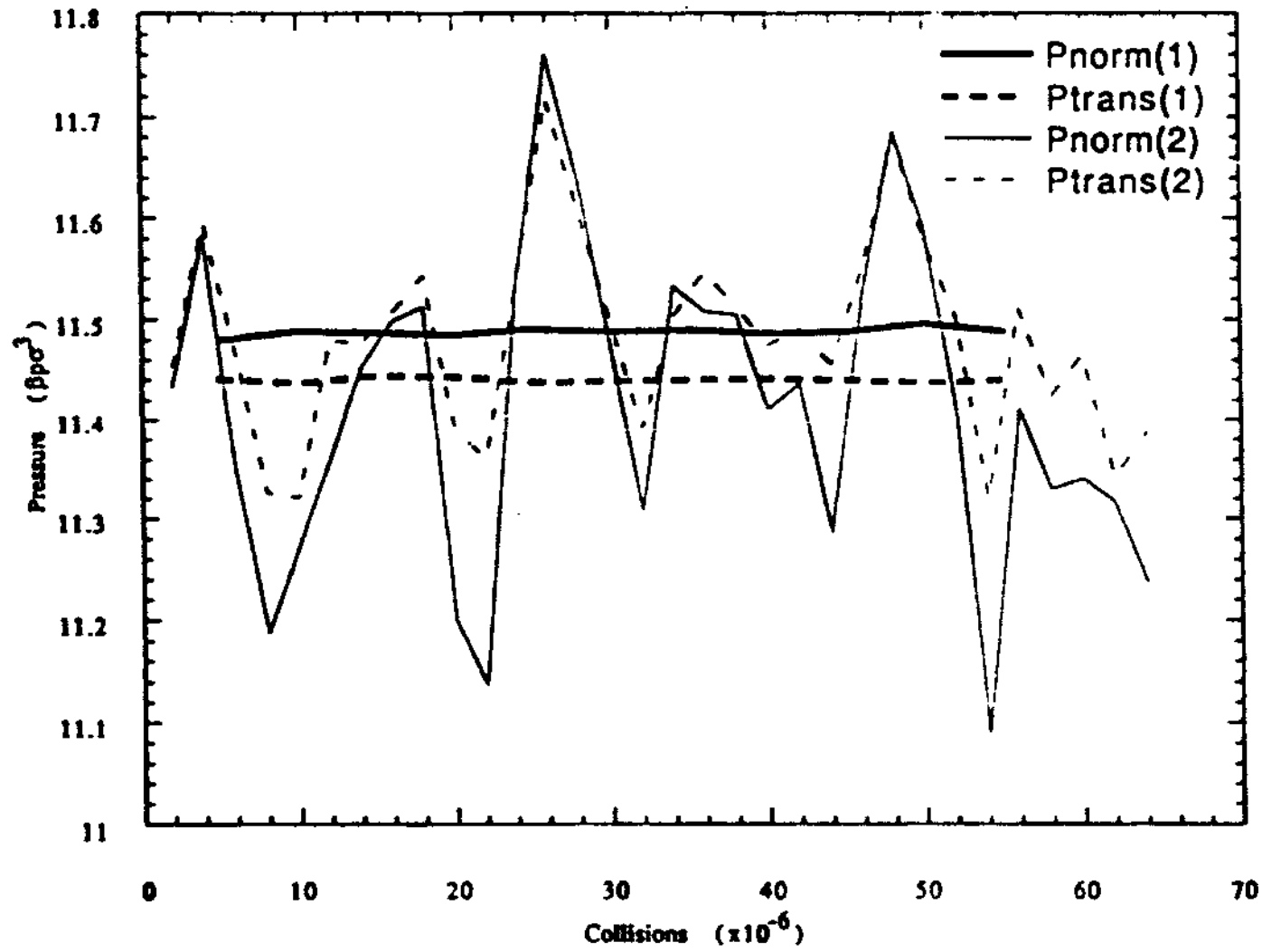




figure 10  
Pressure History for the Coexistence Density Determinations  
 $\rho^* = 1.0348$



depending upon whether that pressure has been approached from above or below.

In our study, we are looking for the point where only one crystal layer is left against the smooth hard wall after the rest have been melted off. This would be the lowest pressure exhibiting prefreezing. Prefreezing is a metastable condition which is difficult to isolate.

## METHODOLOGY

An NPT (isobaric/isothermal) ensemble was created by taking a configuration of 2100 hard spheres, between hard walls from the NVT wetting study with a density of  $\rho_c^* = 1.0409$  at a pressure of  $11.4 \beta p \sigma^3$  and allowing the walls to move under a constant external pressure. The system is able to maintain constant pressure by accelerating the walls into the system at a constant force. This force applies an equilibrating pressure on the system and adjusts the volume and density accordingly.

Various pressures were used to obtain the conditions described above. The range of pressures were 11.0 to  $11.3 \beta p \sigma^3$ , in order to cover the complete range of the hysteresis curve of the crystal phase. The simulations were run until equilibrium was obtained or the crystal disintegrated into fluid, which ever came first.

## RESULTS

The first simulations run were at  $11.3 \beta p \sigma^3$ . After  $4 \times 10^6$  collisions the density profile, figure 11, shows at least three layers of crystal on each wall. This condition persists through  $1 \times 10^7$  collisions and up to  $2 \times 10^7$  collisions. At this point it was determined that the system had equilibrated, and simulation was discontinued.

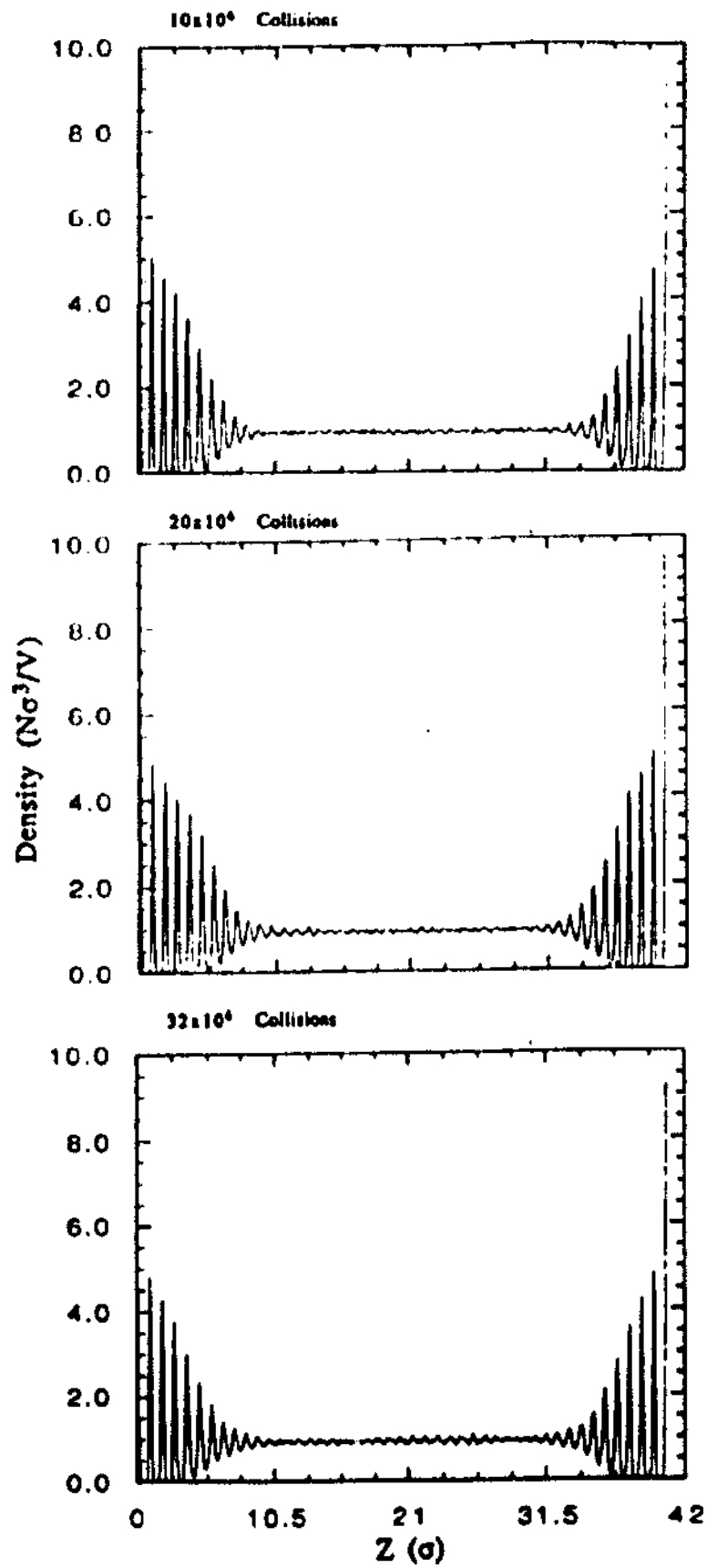


figure 11 - Density Profiles  
NPT System at  $11.3 \beta\rho^3$

The next pressure selected was chosen to cause complete melting of the crystal in order to determine a range for prefreezing conditions. We selected  $11.0 \beta p \sigma^3$  for this purpose. The starting configuration of the system was the same as that chosen for the previous pressure. After  $2.4 \times 10^7$  collisions, shown in figure 12, the system was observed to have melted. Equilibrium was then reached in  $8 \times 10^6$  more collisions and simulation was discontinued.

$11.1 \beta p \sigma^3$  was selected as the next pressure. Again, we begin the simulation with the starting configuration from the NVT simulation. At this pressure the number of crystal layers on the right wall drops to one after  $1 \times 10^7$  collisions, but a second layer of crystal quickly reformed there indicating a pressure fluctuation caused the event. After  $1.8 \times 10^7$  collisions the right wall completely melts while still retaining crystal wetting on the other wall, as shown in figure 13. Once the right wall became wet by fluid, the system equilibrated and remained unchanged after  $20 \times 10^7$  more collisions. The simulation was then discontinued.

The last pressure used was  $11.2 \beta p \sigma^3$ . This series of simulation was started from two different configurations. The first was the beginning NVT system used in the other runs. It ran for  $1.8 \times 10^7$  collisions and maintained crystal wetting upon both walls, figure 14. The second system was taken from the this study at a pressure of  $11.3 \beta p \sigma^3$  after  $1.4 \times 10^7$  collisions. However, this configuration completely melted after only  $4 \times 10^6$  collisions, figure 15. This demonstrates the large effect the starting configuration has on the outcome of the simulation, due to the metastable nature of prefreezing

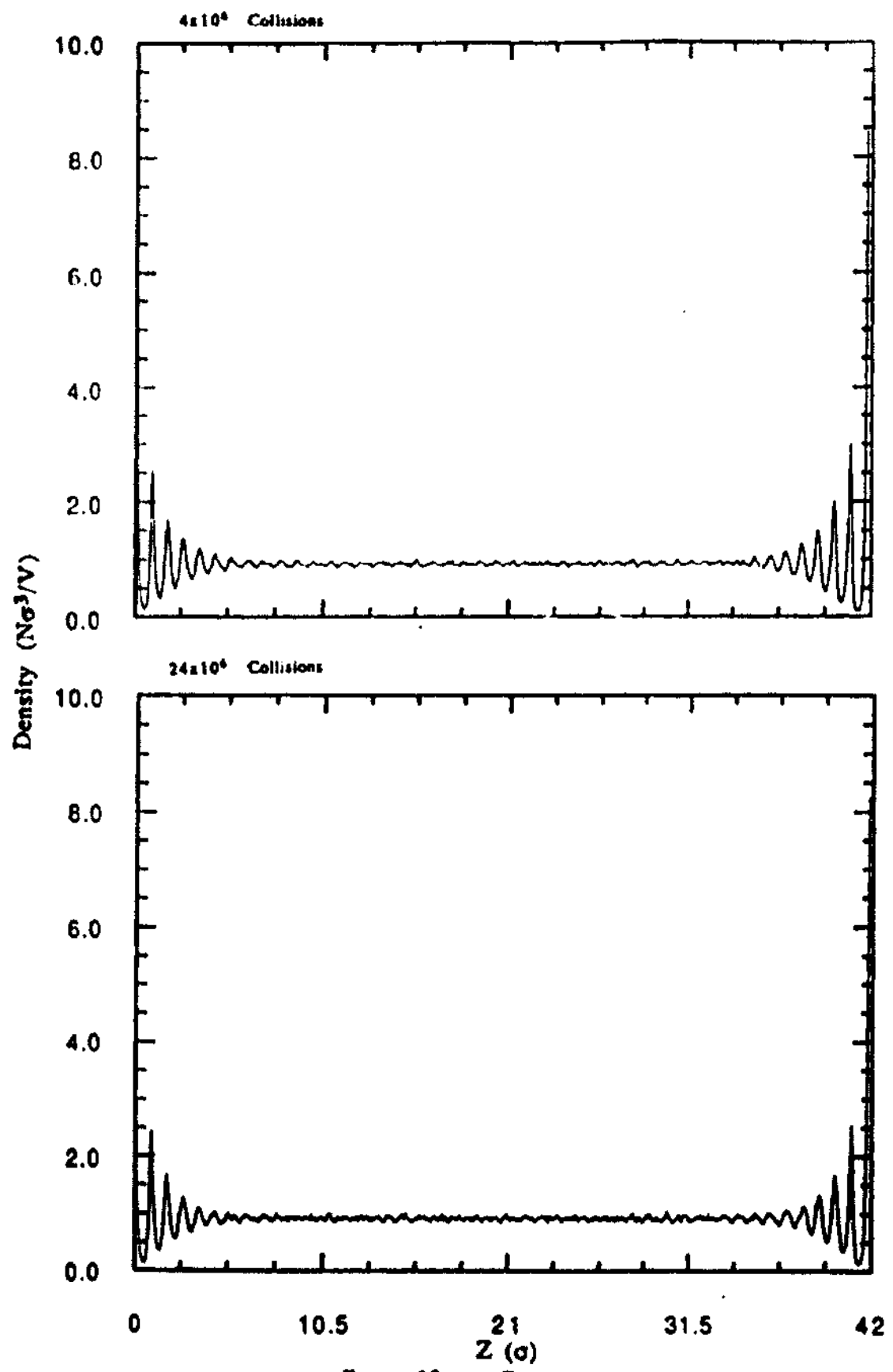


figure 12 - Density Profiles  
NPT System at  $11.0 \beta\rho\sigma^3$

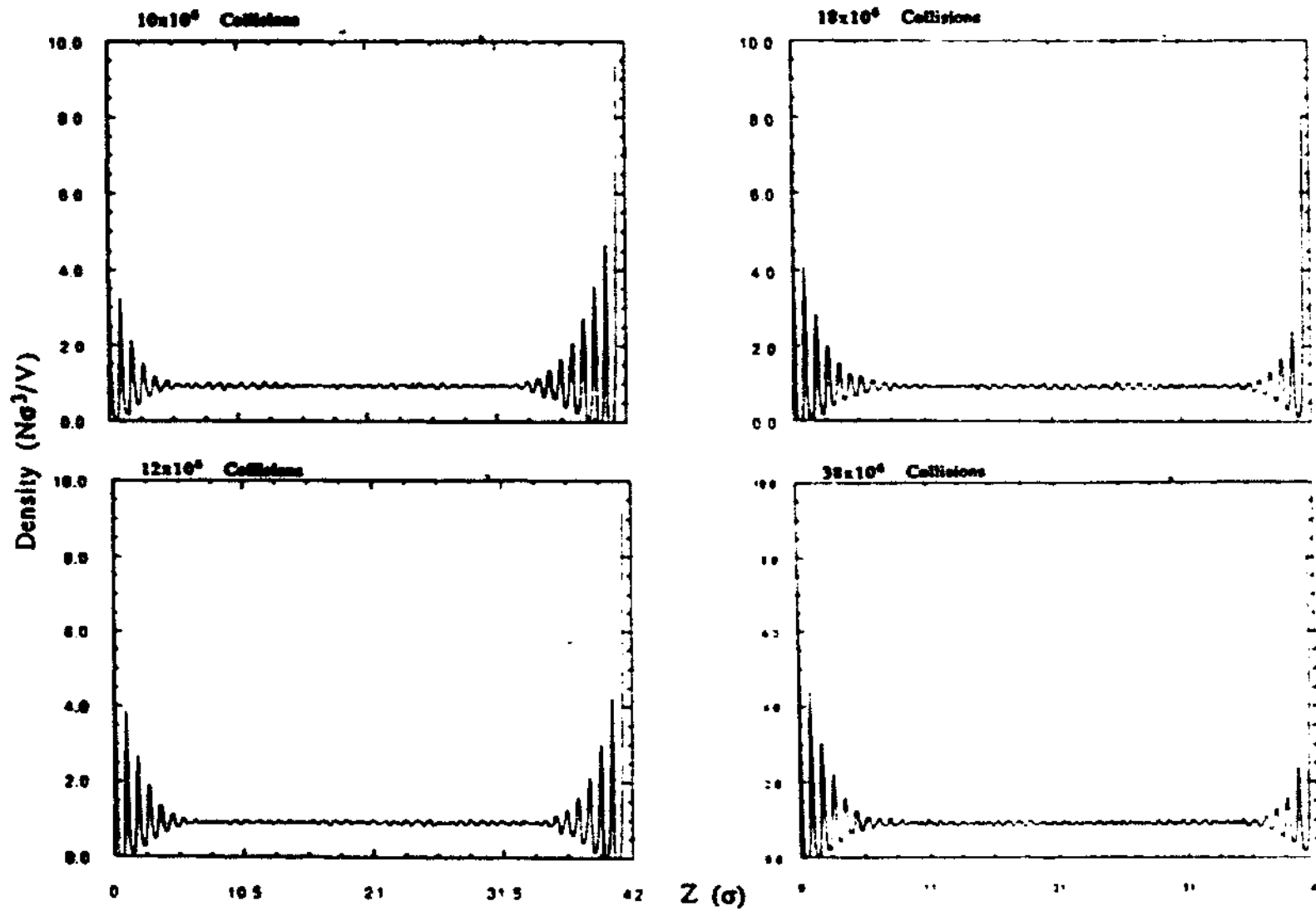


figure 13 - Density Profiles  
NPT System at 11.1  $\beta\rho^3$

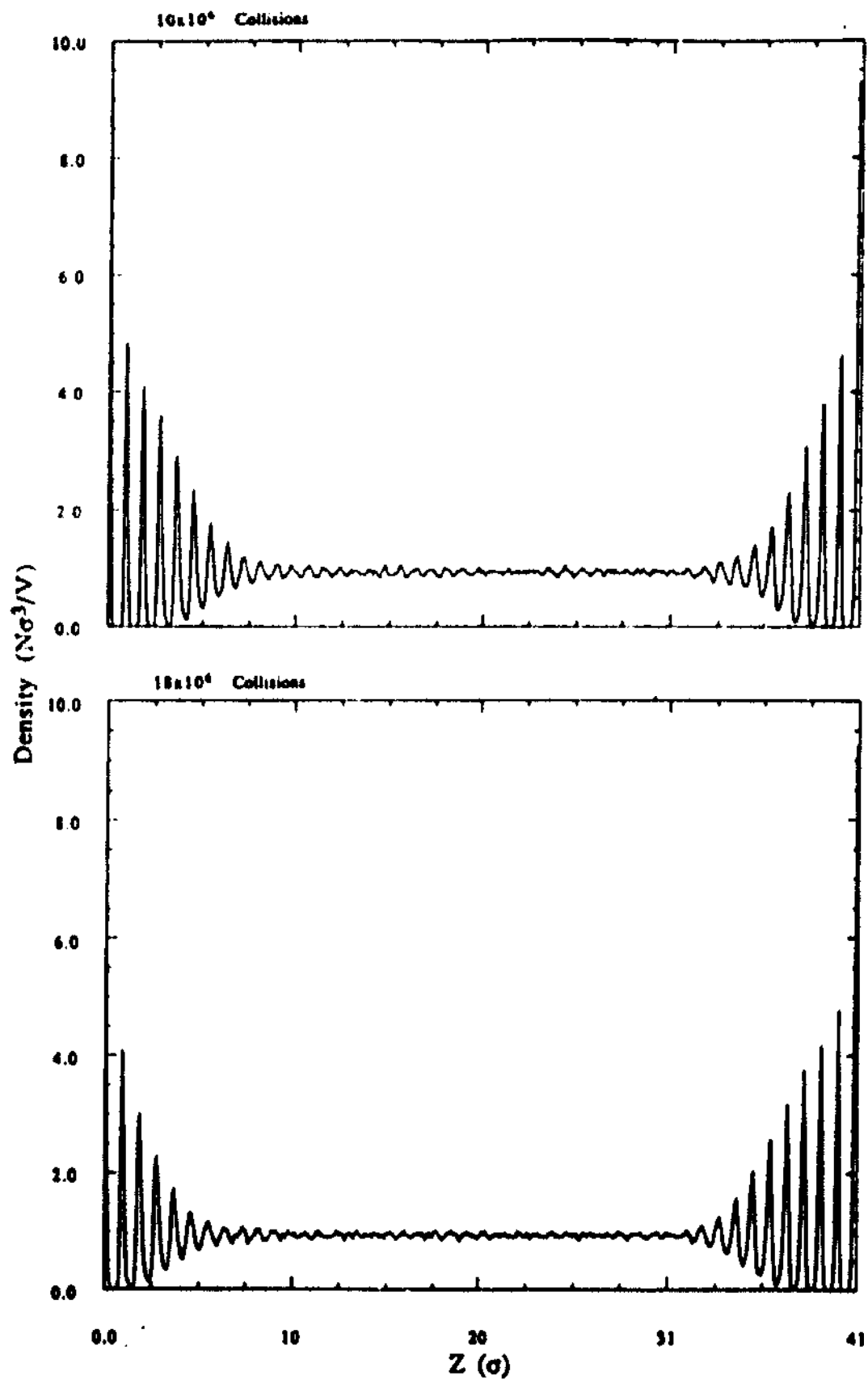


figure 14 - Density Profiles  
NPT System at  $11.2 \beta\sigma^3$ , Original Starting Configuration

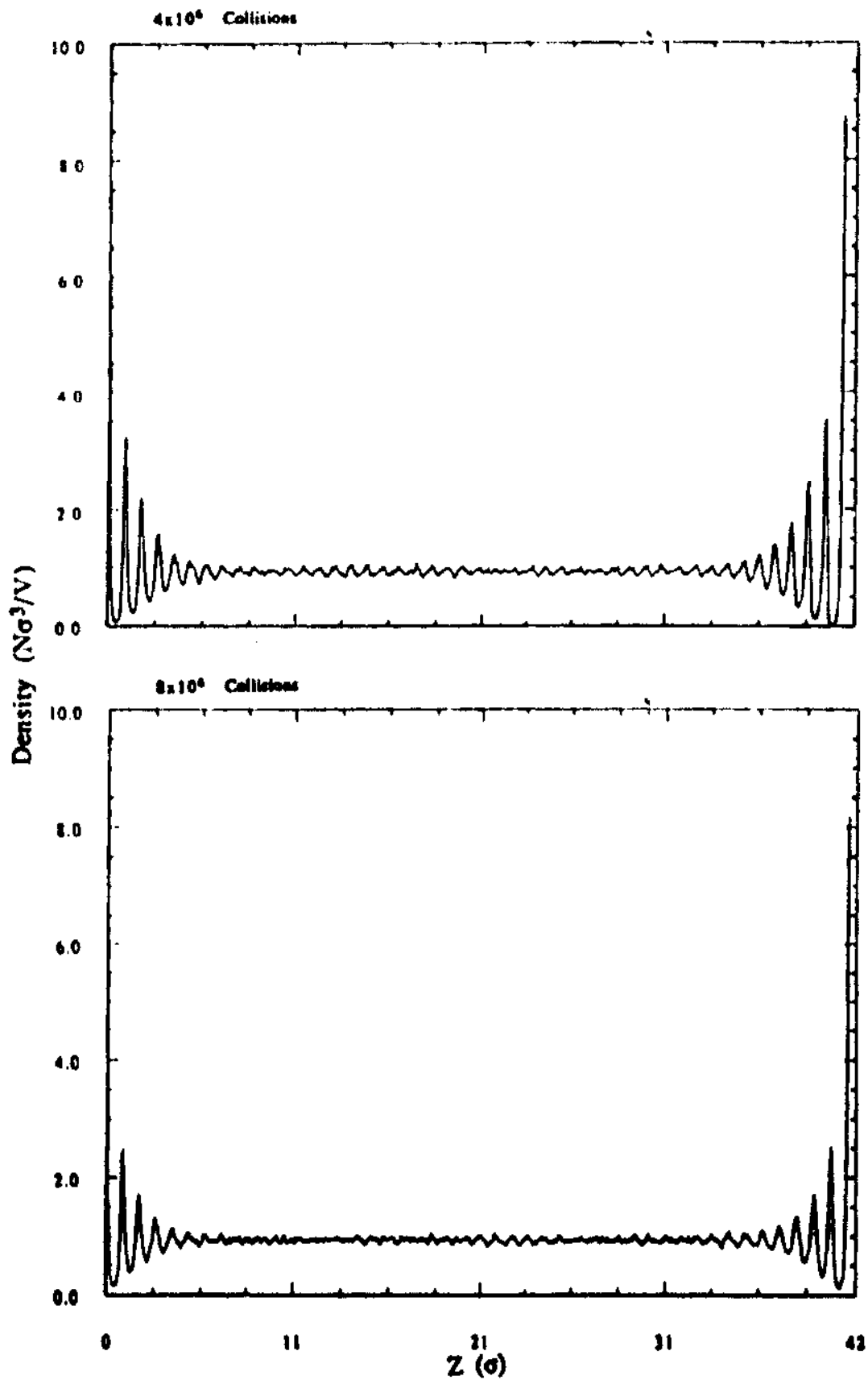


figure 15 - Density Profiles  
NPT System at 11.2 βρ<sup>3</sup>, from 11.3 βρ<sup>3</sup> NPT System



## DISCUSSION

The results from this study have so far proved inconclusive. We have been unable to locate the exact range of prefreezing from the pressures selected. In addition, various fluctuations inherent in the system may disrupt the stability of the any prefreezing we witness, as demonstrated by the results generated from the  $11.1 \beta\rho\sigma^3$  trial. More trials near  $11.1 \beta\rho\sigma^3$  are needed before the stability of the system can be determined.

These studies seem to be greatly affected by the starting configuration. This is understandable due to the instability of systems within the prefreezing region. Single layer melting and freezing events can cause fluctuations large enough to destroy coexistence.

### Study of Spontaneous Segregation

The hard sphere equations of state demonstrate a range of densities for a single melting transition. In practice the system makes sharp transitions from liquid to solid, however hysteresis has been observed in both melting and freezing transitions. In this study We wish to put a system in an unfavorable state by placing it on the tie bar at a density in between the two coexistence densities. We have then tracked the progress of the system to watch the formation of two defined coexistence phases from the ordered fluid.

## METHODOLOGY

We again used PBC conditions with a canonical ensemble to simulate bulk crystal. The crystal was stretched as in the wetting experiments, however the entire crystal was stretched as opposed to just a small region.

This effectively lowered the density from  $\rho^* = 1.0348$  to 0.99500, which is within coexistence values. The new density is constant throughout the system before the simulation begins.

During the simulation pressure and density profiles were recorded and examined for the segregation of this unstable density into the two distinct phases of coexisting crystal and fluid.

## RESULTS

The ordered fluid produced in the stretching of the bulk crystal, begins the simulation at a constant density  $\rho_c^* = 0.99500$ . Once the simulations started the system begins to experience density fluctuations which propagated through the system and began segregating the two phases. After  $1.3 \times 10^7$  collisions, the two distinct phases are noticeably apparent.

As the simulation continued to run the system reverted back to its original configuration. At  $35 \times 10^7$  collisions, the density profile is almost identical to the original profile. Currently the system is still under investigation but appears to be resegregating into the separate phases. All the density profiles from this study are shown in figure 16.

## DISCUSSION

The second law of thermodynamics states a system will spontaneously move towards maximum entropy. The ordered fluid in our system should therefore try to increase entropy by increasing the randomness of the system. By segregating into a coexisting crystal and fluid system that system trades off the increases in entropy caused by the loss in order of the fluid region with the loss of entropy caused by crystalizing the other region.

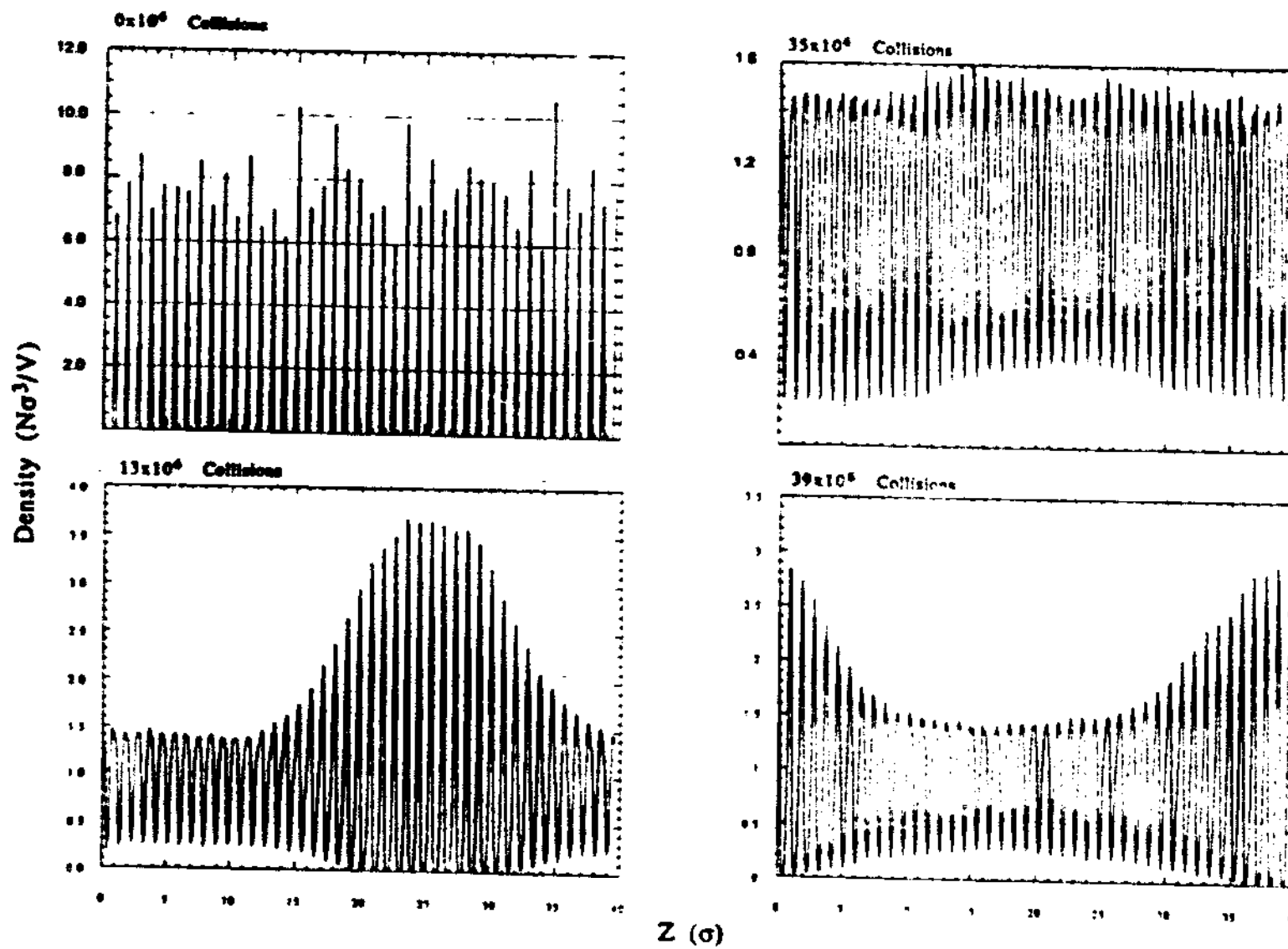


figure 16 - Density Profiles  
Spontaneous Segregation Simulations

Because this system begins in the excluded region this tradeoff results in a net increase of entropy.

The simulations reveal the driving force for the spontaneous change is smaller than predicted, allowing the observed metastability of the stretched to fluid to exist. The fluctuation back and forth between one and two phases will eventually equilibrate at two, but the number of collisions necessary will be much larger than  $4 \times 10^7$  collisions already run. An exact number of collisions is very difficult to estimate. Further study will be required to confirm the above conclusions

### Recommendations

There are several different directions these studies could go. The wetting and coexistence density investigations each need lengthier runs to confirm the conclusions already drawn. The prefreezing investigation should be expanded to examine the entire hysteresis loop about the melting transition. The stability of the region can be examined by changing the pressure subtly and watch the system adjust to the new conditions. We would also like to define the rest of loop by setting the pressure above  $11.4 \beta p \sigma^3$  attempt to compress the system to crystal. Finally the spontaneous segregation study should be done at several other densities within the excluded region for thoroughness.

New areas that are of interest as a result of these studies. An important follow up study is a comparison of box dimensions with the disparity between the normal and transverse components of the pressure.

In addition we would like to investigate the effect of non isotropic crystal structure on system pressure.

## Appendix

### Simulation Fortran Code

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PROGRAM HSPH3E
IMPLICIT REAL*8(A-H,O-Z)

C
C this program was adapted from hsp11 for
C the difference lies in the option of stretching the box
C in the z direction see ZCFAC. In addition this program
C calculates the transverse and normal pressure tensor
C components
C
C ***** VAX version ***** of HSPH11E.M
C (see the OPEN statements)
C This version contained calls to nag routines to start initial
C iteration velocities
C these calls have been replaced by calls to GAUSS
C 2) Three GOTOs have been replaced by if statements that use the
C variable JUMP in order to get rid of
C no path to this statements messages
C 3) Switched to double precision
C 4) Disabled the (unused) output of accumulators etc
C 5) writes out RWF, RWF, ZJUM
C
C          Version: 21/12/86
C
C PROGRAM HSPH3E (tape 7, tape 8, tape 9, TAP10) output/output
C
C TAP10 (output/output)
C DIMENSION NX(1200), NY(1200), NZ(1200)
C DIMENSION VX(1200), VY(1200), VZ(1200)
C DIMENSION (NSPX(1200), NSPHY(1200), NSPZ(1200)
C DIMENSION NR(1200), TR(1200)
C DIMENSION LINK(1200), R(1200), I MAX(30)
C DIMENSION LDR(770), LNR(270)
C DIMENSION XA(6), YA(6), ZA(6)
C DIMENSION DM(10), T1(110), PKX(10), PLY(10), PZZ(110)
C DIMENSION ZPKS(10), XN(10), YN(10), ZN(10), V(10)
C DATA NLIST/10/, P1/3.141592654/, MRAND/1/
C DATA FL/0.8116/, F1/2.27/9707/, CR/1/15554/, CR2/2/1719/
C DATA JUMP/1/
C
C OPEN(UNIT=1, FILE='INPUT.DAT', STATUS='OLD')
C OPEN(UNIT=2, FILE='OUTPUT.DAT', STATUS='NEW')
C OPEN(UNIT=7, FILE='XJ.DAT', STATUS='OLD')
C OPEN(UNIT=8, FILE='NEW.DAT', STATUS='NEW')
C
C DATE: 09/1981
C THIS IS A BULK VERSION
C INSERTED GOTOS 500,501,99,19,37,18
C KON=0 SO NO CORRELATIONS WRITTEN TO TAP10
C
C THIS IS A GENERAL HARD SPHERICAL PROGRAM, USING THE NEW LINK CELL
C METHOD THE PROGRAM CAN BE USED TO STUDY FLUID WALL INTERACTIONS
C THE WIDTH OF A LINK CELL SHOULD BE AT LEAST EQUAL TO 1.36 SIGMA
C CALCULATES DIFFERENT COMPONENTS OF PRESSURE TENSOR
C THIS VERSION WRITES CORRELATIONS TO TAP10 (EVERY PWR/10)
C COLLISIONS (WRITES 100 COLLISIONS TO 0.5 MEAN COLLISION TIMES)
C KON IS THE NUMBER OF CORRELATIONS PRESENT ON TAP10
C NCONF IS THE NUMBER OF CORRELATIONS WRITTEN IN THIS RUN
C READ INPUT PARAMETERS FROM TAP10 INPUT
C READ(1,*)N
C READ(1,*)RHO, acfac
C READ(1,*)NTOT, NTAL, IWRIT1
C READ(1,*)NCON
C READ(1,*)NX, NY, NZ
C WRITE(2,207)NX, NY, NZ
207 FORMAT(11,3H NX=,13,5H NY=,13,5H NZ=,13,/)
WRITE(2,209)N,RHO,IN,NTOT,NTAL,IWRIT1,KON
WRITE(2,*) acfac, acfac

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208 FORMAT(0,3H N=,16,4X,4H RHO=,18,6,4X,4H IN=,17,4X,5H NTOT=,16,4X,
15H NTAL=,16,7H IWRIT1=,16,5H IWRIT2=,16,/)
WRITE(1,*)NAC,NCX,NCY,NZ
131 FORMAT(4H)
WRITE(2,11)NAC,NCX,NCY,NZ
XCX=NCX
XCY=NCY
XCN=NCZ
READ(1,*)XA(6),YA(6),ZA(6),I,NAC
132 FORMAT(12X,18,6)
WRITE(2,133)XA(6),YA(6),ZA(6),I,NAC
133 FORMAT(11,3X,18,6)

C READ(1,*)CONTRMATION FROM TAP10
TO TIME=00
CONTRM(1)=0.00000000
CONTRM(2)=0.00000000
CONTRM(3)=0.00000000
TIME=00
76 DO 74 I=1,1001
XX=0
READ(10,*)TIME,XX,YY,PZ,DISPY,DISPY,DISPY
C the next statement has been commented out probably not standard
C CONTRM(1)=CONTRM(1)+CONTRM(1)
C CONTRM(2)=CONTRM(2)+CONTRM(2)
74 CONTINUE
C(1)=0
75 TIME=TIME+1
CONTRM(1)=CONTRM(1)+CONTRM(1)
CONTRM(2)=CONTRM(2)+CONTRM(2)
77 CON=CON+1
TIME=TIME+1
WRITE(2,255)CON,TIME
C
C SET ACCUMULATORS TO ZERO
78 NAV=0
NCON=0
XTIME=0
DO 25 J=1, NLIST
ZK(1)=0
XN(1)=0
YN(1)=0
ZN(1)=0
DM(1)=0
T1(1)=0
PKX(1)=0
PLY(1)=0
PZZ(1)=0
25 CONTINUE

C CONVERSION TO PROGRAM UNITS
VOL=3/4*PI*RHO
T=0.001
XN=N
C ... RHO*N=1.0000
NLIST=NLIST
XC=1.0
YC=0.00000000
ZC=2.0*DISOR(1.0,0.00000000)*(4.0/3.0)*PI*(RHO*N/VOL)
ZC=(2.0*DISOR(1.0,0.00000000)*XN(1)/XN(1))*ZC
YC=500*YC
ZC=500*ZC
C
FL=CONTRM(10)*YC*(ZC)**(1.0/3.0)
X1=(4.0/3.0)*PI*(RHO*N/VOL)*XN(1)
YL=X1*YC
Z1=X1*ZC
FL=41.1/FL
13.2=41.2/X1

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```

TEMP=0.0
DO 6 I=1,N
  VX(I)=VX(I)*PX/XN
  VY(I)=VY(I)*PY/XN
  VZ(I)=VZ(I)*PZ/XN
  TEMP=TEMP+VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
6 CONTINUE
C SET INITIAL TEMP
C=SQRT(XN**3*TEMP)
TEMP=0.0
PX=0.0
PY=0.0
PZ=0.0
DO 16 I=1,N
  VX(I)=VX(I)*C
  VY(I)=VY(I)*C
  VZ(I)=VZ(I)*C
  PX=PX+VX(I)
  PY=PY+VY(I)
  PZ=PZ+VZ(I)
  TEMP=TEMP+VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
16 CONTINUE
PX=PX/XN
PY=PY/XN
PZ=PZ/XN
TEMP=TEMP/XN**3.0
WRITE(2,205)TEMP,PX,PY,PZ
205 FORMAT(13H INITIAL TEMPERATURE AND INITIAL MOMENTA, 3X, F13.6)
C PRINT OUT INITIAL POSITIONS AND LINK TABLES
WRITE(2,201)
201 FORMAT(17X, 11H 1X, 21HX 9X, 21HY 9X, 21HZ, 17X, 21VX 9X, 21VY 9X, 21VZ
1X, 21LX, 21LY, 21LZ)
DO 14 I=1,20
  WRITE(2,201)R(I),R(I),R(I),VX(I),VY(I),VZ(I),LINK(I),IC(I)
201 FORMAT(16, 3X, 17X, 3 9 9) 4X, 15, 2X, 15)
14 CONTINUE
NCOUNT=0
MXX=0
PTOT=0.0
MCT=0
P=0.0
TAU=0.0
PNORM=0.0
PTRANS=0.0
C (COLLISION NUMBER) LINK TABLES
20 I=1
DT=1.000
9 CONTINUE:
C SPHERE COLLISION
IF(I EQ K)GO TO 21
IF(I EQ L)GO TO 21
IF(N(I) EQ K)GO TO 21
IF(N(I) EQ L)GO TO 21
IF(NCT EQ 0)GO TO 21
GO TO 23
21 CONTINUE:
TC(I)=99.000
IP=IC(I)
IPM1=IP-1
C CALCULATE IX,IY,IZ FROM IP
IZ=IPM1*NL2
IY=(IPM1-IZ*NL2)/NLX
IX=IP-IY*NLX-IZ*NL2
IY=IY+1
IZ=IZ+1
C CALCULATE IP
DO 40 KZ=1,3
  DO 40 KY=1,3
    DO 40 KX=1,3
      CX=0.0
      CY=0.0
      CZ=0.0
      IX=IX+KX-2
      IY=IY+KY-2
      IZ=IZ+KZ-2
      C PERFORM BOUNDARY CONDITIONS
      IF (IX .NE. 1) 371, 370, 371
        IX=1
      CX=XI
      IF (IY .NE. 1) 373, 372, 373
        IY=1
      CY=YI
      IF (IZ .NE. 1) 375, 374, 375
        IZ=1
      CZ=ZI
      IF (IX) 377, 376, 377
        IX=NLX
      CX=XI
      IF (IY) 379, 378, 379
        IY=NIY
      CY=YI
      IF (IZ) 381, 380, 381
        IZ=NIZ
      CZ=ZI
      C
      IF (IX+(IY-1)*NLX+(IZ-1)*NL2)
        I=I+2*IP)
      C (311) IP=IPM1
      IF (I EQ 0) GO TO 40
41 CONTINUE:
      IF (I EQ 0) GO TO 9
      X=RX(I)-RX(I)-CX
      Y=RY(I)-RY(I)-CY
      Z=RZ(I)-RZ(I)-CZ
      U=VX(I)-VX(I)
      V=VY(I)-VY(I)
      W=VZ(I)-VZ(I)
      B=X*U+Y*V+Z*W
      IF (B GT 0.000000) TO 7
      VY=U*U+V*V+W*W
      RR=X*X+Y*Y+Z*Z
      C=V*V*(RR SS)
      BB=B*B
      B=(C GE BB)GO TO 7
      Q=SQRT(BB-C)
      D=(B+Q)/VY
      IF (C LT 0.000000) TO 17
      IF (D GT TC(I))GO TO 7
      TC(I)=D
      NK(I)=1
7 CONTINUE:
      I=LINK(I)
      IF (I NE. 0)GO TO 41
40 CONTINUE:
21 CONTINUE:
      IF (TC(I) GT DT)GO TO 20
      DT=TC(I)
      KS=1
      LS=NK(I)
20 I=I+1
      IF (I LE. N)GO TO 9
      K=KS
      I=LS

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R1V=VY(L)*VYI
B<(REV.LT 0) YR1V(KK1)-YREV(KK1)+1
REV=VZ(L)*VZL
B<(REV.LT 0) ZR1V(KK1)-ZREV(KK1)+1
C CONTINUE FROM HERE FOR A BULK CELL CALCULATION
C *****
501 CONTINUE
C *****
NCOU=NCOU+1
T=TD+DT
TAU=TAU+DT
NCOU=NCOU
NAV=NAV+1
C *****
B<(RIMP(1)) GOTO 19
C ***** SKIPPED HERE FOR CALCULATION
DO 11 I=1,N
KK=INT(NZ(I)*XINST/ZI)+1
DL=V(KK)-DL(NKK)+1
EK=VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
T1=KK-T2=KK+1
ZPOS(KK)=ZPOS(KK)+RZ(I)
11 CONTINUE
B<(NCOU.NT.N) NWRIT(1) GOTO 19
C WRITE CONFIGURATION TO TAPE 10
TIME=TIME+TA
KON=KON+1
WRITE(10)KON,TIME,RX,RZ,DISPX,DISPY,DISPZ
NWRIT=NWRIT+1
NCON=NCON+1
C ***** (CONTINUE FROM HERE FOR BULK CELL)
19 B<(NCOU.NT.N) NWRIT(2) GOTO 29
TL=TL+DT
PX=0
PY=0
PZ=0
DO 27 I=1,N
EK=VX(I)**2+VY(I)**2+VZ(I)**2
T1=TL+EK
PX=PX+VX(I)
PY=PY+VY(I)
PZ=PZ+VZ(I)
27 CONTINUE
T1=TL+T1*(XN**2)
PX=PX/XN
PY=PY/XN
PZ=PZ/XN
C
C CALCULATE MEAN SQ DISPL FOR THE 3 REGIONS SEPARATELY
DIF1=0
DIFCR=0
DIFINT=0
XN1=0
XNCR=0
XINT=0
DO 37 I=1,N
C*****B<(RZ(I)GE 1) AND RZ(I)LE 1) GOTO 34
XN1=XN1+1
DIF1=DIF1+DISPX(I)**2+DISPY(I)**2+(DISPZ(I))**2
C *****
B<(RIMP(1)) GOTO 37
C *****
34 B<(RZ(I)LE CR) OR RZ(I)GE CR) GOTO 39
XNCR=XNCR+1
DIFCR=DIFCR+DISPX(I)**2+DISPY(I)**2+DISPZ(I)**2
39 B<(RZ(I)GT XINT) AND RZ(I)LE 1) XINT) GOTO 36
B<(RZ(I)GT XINT) AND RZ(I)LE 1) XINT) GOTO 36
GOTO 37

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36 XINT=XINT+1
DIFX=DIFX+DISPX(I)**2+DISPY(I)**2+(DISPZ(I))**2
37 CONTINUE
DIF1=DIF1/XN1**2
C*****DIFCR=DIFCR/XNCR**2
C*****DIFINT=DIFINT/XINT**2
WRITE(2,20)NCOU,NJL,T,TIME,PX,PY,PZ
202 FORMAT(10H COLLISION,6,4X,10H H-TIME,2,4X,5H AT T=,10,4X,5H
(TIME=,F10,4X,10H MOMENTA, 2X(1,1,0))
AP=10+PI*TA/30*XN*T
AP=AP*VCL
PSUBAV=10+PA/30*XN*TA(I)
PSUBAV=PSUBAV/VCL
CP=10+PI*TA*TA(I)*SQRT(PH)*SAL*(XN+10)**3
CP=CP*VCL
APN=10+PH*MM(XN*T)
APT=10+PH*ANS(20*XN**2)
WRITE(2,2005) APN*XN*SRAR(A**2), APT*XN*SRAR(A**2)
WRITE(2,2005) APN*XN*SRAR(A**2), APT*XN*SRAR(A**2)
WRITE(2,25)PSUBAV, AP, CP, DIF1, DIFCR, DIFINT
251 FORMAT(10H PRESSURE =,F10,4X,10H AT T=,F10,4X,10H
+VZ(I))
NCON=NCON+1
P=0
TAI=0
GOTO 29
C END OF THIS RUN
15 CONTINUE
WRITE(2,24)T,MCN
24 FORMAT(10H END OF RUN,3X,10H,2,4X,5H NCON =,10,4
PIUT=10+PI*TA/30*XN*T
PIUT=PIUT/VCL
WRITE(2,230)PIUT
250 FORMAT(10H AVERAGE PRESSURE,2X(1,10,4)
CP=10+PI*TA*TA(I)*SQRT(PH)*SAL*(XN+10)**3
CP=CP*VCL
WRITE(2,253) CP
APN=APN*XN*SRAR(A**2)
APT=APT*XN*SRAR(A**2)
WRITE(2,*) units of h*sigma**2) PH*MM =,apn
WRITE(2,*) units of h*sigma**2) PH*ANS =,apt
C overall density
RHO=TOT(XN*XI**2)*XN**2/XI**2
WRITE(2,*) overall density =,RHO(I)
REAL T=TS
WRITE(2,120)REAL T
120 FORMAT(20H TIME IN HARD SPH W: UNITS =,2X(1,12,9)
2005 FORMAT(7H PH*MM =,E15,2X,10H PH*ANS =,E15,8)
253 FORMAT(20H PRESSURE FROM COLLISION RATE,2X(1,10,4)
XTIME=XTIME+T
WRITE(2,254)NCON
WRITE(2,256)NCON,TIME,XTIME
WRITE(2,201)T
201 FORMAT(33H POSITIONS AND VELOCITIES AT T=,F10,4)
DO 12 I=10,100,10
WRITE(2,200)RX(I),RY(I),RZ(I),VX(I),VY(I),VZ(I),NR(I),TC(I)
200 FORMAT(16,2,3X,3,2X(1,9,4),4X,15,3X(1,8,3))
12 CONTINUE
C PUNCH OUT FINAL CONFIGURATION
WRITE(2,252)
252 FORMAT(22H PUNCHED CONFIGURATION)
C *****
RWL=0
RWR=ZC
ZDIM=RWR-RWL
WRITE(2,196)RWL,RWR,ZDIM
196 FORMAT(1X, 3R(=,F20,16, 3R(=,F20,16, ZDIM=,F20,16))
C

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PROGRAM Sphere
C
C      12/19/1989
C converted to VAX fortran
C
*MPXKT REAL*(M,A,H,0,Z)
COMMON/POSITION/ RX(2100),RY(2100),VZ(2100)
COMMON/INR(1,2,3,4) INR(2100),R(2100),LMAX(10), LDB(12),J(1817)

DIMENSION VX(2100),VY(2100),VZ(2100)
DIMENSION DISPX(2100),DISPY(2100),DISPZ(2100)
DIMENSION NK(2100),TC(2100)
DIMENSION XA(6),YA(6),ZA(6)
DIMENSION JH-N(1010),TJ(1010),PAX(1010),PYY(1010),PZZ(1010)
DIMENSION ZPOS(1010),ZINS(1010),XRV(1010),YRV(1010),ZRV(1010)
DATA N(1157/1000),J(1/),L(1592/654)
DATA L(1177/8100),L(2277/9107),C(1/)(33554),C(2/)(3319)

C THIS IS A GENERAL HARD SPHERE PROGRAM USING THE NEW LINK CELL
C METHOD THE PROGRAM CAN BE USED TO STUDY SOLID FLUID INTERACTION
C THE WIDTH OF A LINK CELL SHOULD BE AT LEAST EQUAL TO THE MAXIMA
C CALCULATED DIRECT COMPONENT OF THE SPHERE TO SPHERE
C THIS VERSION WRITES CONFIGURATIONS TO TAPE EVERY IWRITE
C CYCLE SHOWS IWRITE=100 CONFIGURATIONS TO 5 MEAN CYCLE SHOWS IWRITE
C KON IS THE NUMBER OF CONFIGURATIONS PRESENT ON TAPE
C NCON IS THE NUMBER OF CONFIGURATIONS WRITTEN ON THIS RUN
C RHO IS THE NUMBER DENSITY IN THE SPHERE
C ZC IS THE BOX LENGTH IN THE Z DIRECTION IS ACCOUNTED FOR
C ZC IS THE BOX LENGTH IN THE X AND Y DIRECTIONS (INSTRUCTED)

C READ INPUT PARAMETERS FROM INPUT FILE
READ(1,*)N
READ(1,*)RHO,IAV
READ(1,*)NTOT,NTAU,IWRITE
READ(1,*)IN,KON
READ(1,*)NLX,NLY,NLZ
WRITE(2,207)NLX,NLY,NLZ
207 FORMAT(1H,5H NLX=,I3,5H NLY=,I3,5H NLZ=,I3)
WRITE(2,209)N,RHO,IN,NTOT,NTAU,IWRITE,KON
209 FORMAT(1H,16,4X,4H RHO=,F6.4,4X,4H IN=,I3,4X,5H NTOT=,I6,4X,
15H NTAU=,I6,7H IWRITE=,I6,5H KON=,I6/)
READ(1,*)NAC,NCX,NCY,NCZ
WRITE(2,131)NAC,NCX,NCY,NCZ
131 FORMAT(4I6)
XCX=NCX
XCY=NCY
XCZ=NCZ
READ(1,*)XA(6),YA(6),ZA(6),J=L,NAC)
WRITE(2,133)XA(6),YA(6),ZA(6),J=L,NAC)
133 FORMAT(1H,32X,I8/)
READ(1,*)YC,ZC,ZC'

C READ KON CONFIGURATIONS FROM TAPE TO
C if KON=1 NO configurations read but averaging
C is assumed
C
TUTIME=0
IF(KON.EQ.1)GOTO 76
TOT=KON
TIME=0
76 DO 74 I=1,TOT
KCC=1
C.....read up
C READ(10)CON,TIME,RX,RY,NZ,DISPX,DISPY,DISPZ,
C *VX,VY,VZ
C* IF(LON(10)NE.0)GOTO 75
74 CONTINUE
GOTO 77

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75 TOT=KON+1
REWIND 10
GOTO 76
77 KON=TOT
TOTIME=TIME
WRITE(2,255)KON,TOTIME
C
C SET ACCEPTABLE RATIO TO ZRO
78 NCV=0
MAYN=0
XTIME=0

DO 257 I=1,NHIST
ZPOS(I)=0
ZINS(I)=0
XRV(I)=0
YRV(I)=0
ZRV(I)=0
INR(I)=0
TJ(I)=0
PAX(I)=0
PYY(I)=0
PZZ(I)=0
257 CONTINUE

C CYCLE AVERAGED PROGRAM DATA
VOLUME=SQRT(4/3*PI)*R**3
L=0.0
XN=5
YINT=NHIST
Y=1.0

VZ=0.0
Z=2.0
X=1.0
X1=4*PI*(2.0*Z)/N(I)*SQRT(4/3*PI)*R**3
Y1=X1*Y
Z=X1*Z1
AREA=X1*Y1
I1=I1+1
CR1=X1/X1
CR2=CR2*X1
XINT1=I1
XINT2=CR1
XINT3=CR2
XINT4=I1.2
S=1.0/X1
SS=S*S
WRITE(2,210)S
I1=Z/XHIST
NWRITE=IWRITE
NCON=NTAU
210 FORMAT(1H,22H SIGMA IS UNITS OF L=,F9.6)
WRITE(2,81)XC,YC,ZC
WRITE(2,89)X1,Y1,Z1
WRITE(2,2007)AREA
WRITE(2,2008)X1*Y1,Z1*Y1,Z1*Z1
2007 FORMAT(1H,5H AREA=,F13.8)
2008 format(1H,cell dimensions,3(2x, (13.8))
81 FORMAT(1H,35H BOX DIMENSIONS IN PROGRAM UNITS XC=,F10.6,
4H YC=,F10.6,4H ZC=,F10.6/)
89 FORMAT(1H,35H BOX DIM IN UNITS OF SIGMA X1=,F10.6,
4H Y1=,F10.6,4H Z1=,F10.6/)
C INITIAL KCC LATTICE
I=1
DO 112 J=1,NCZ
DO 111 I=1,NCX

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DO 1 IX=1,NX
DO 1 IY=1,NCY
  RX(I)=(IX-1)*XAI(1)/XNCK
  RY(I)=(IY-1)*YAI(1)/YCNKY
  RZ(I)=(IZ-1)*ZAI(1)/ZCNKZ
  RX(I)=RX(I)+0.001D0
  RY(I)=RY(I)+0.001D0
  RZ(I)=RZ(I)+0.001D0
  H(KCON EQ 0) DISPK(I)=0.0
  H(KCON EQ 0) DISPY(I)=0.0
  H(KCON EQ 0) DISPZ(I)=0.0
  I=I+1
1 CONTINUE
  U(IN EQ 0) K=1 TO 71
C READ IN CYMETER MATRICES FROM TAPE 7
  PX=0.0
  PY=0.0
  PZ=0.0
  DO 72 I=1,N
    READ(7,*) KX(I), KY(I), KZ(I), NX(I), NY(I), VZ(I)

    PX=PX+VX(I)
    PY=PY+VY(I)
    PZ=PZ+VZ(I)
72 CONTINUE
C READ IN ACCUMULATED STRESS FROM TAPE 7 *****
  U(IAY EQ 0) THEN
    READ(7,*) NAX, XITM
    DO 73 I=1,NHST
      READ(7,*) IN(I), T(I), PX(X), PY(Y), PZ(Z)
      READ(7,*) ZION(I), XRE(V), YRE(V), ZRE(V)
73 CONTINUE

  ENDD
  GOTO 10

71 CONTINUE
C INITIAL MAX WELLSIAN VIBRATIONS
  PX=0.0
  PY=0.0
  PZ=0.0
  agauss = 2 * INTEN * HHO / (ZC * YC) + 1
  DO 5 I=1,N
    NK(I)=1
    CALL GAUSS(agauss, 1.0, 0.0, VX(I))
    CALL GAUSS(agauss, 1.0, 0.0, VY(I))
    CALL GAUSS(agauss, 1.0, 0.0, VZ(I))
    WRITE(15,*) VX(I), VY(I), VZ(I)
    PX=PX+VX(I)
    PY=PY+VY(I)
    PZ=PZ+VZ(I)
5 CONTINUE
C CHAIN LINK TABLES
10 XNL=NLX
  XF=1.0
  YNL=MLY
  YF=YC
  ZNL=MLZ
  ZF=ZC
  NL2=NLX*MLY
  NL3=NLX*MLY*MLZ
  DO 320 LL=1,NL3
    LR(LL)=0
    LI(LL)=0
320 CONTINUE
  DO 321 I=1,N
    IX=INT(RX(I)*XNL/XI+1.0)
    IY=INT(RY(I)*YNL/YI)
    IZ=INT(RZ(I)*ZNL/ZI)
    B=DC+NLX*YI+P-2*IZ
    H(IP GT NL3) GOTO 26
    K(I)=IP
    ME=1+H(IP)
    B(ME EQ 0) GOTO 22
    LINK(ME)=I
    LI(IP)=I
    GOTO 121
22 CONTINUE
    LDI(I)=I
    LI(IP)=I
321 CONTINUE
C COMPUTE CHAIN
C
  DO 323 IP=1, NL3
    ME=1+H(IP)
    B(ME EQ 0) GOTO 321
    LINK(ME)=1+LDI(IP)
323 CONTINUE
  GOTO 329
26 CONTINUE
  WRITE(2,270) IX, IY, IZ, IP, I
  WRITE(2,211) KX(I), KY(I), KZ(I)
  GOTO 24
329 CONTINUE
C CHECK ON LINK ARRAYS
  WRITE(2,206)
  DO 330 IP=1, NL3
    I=1
    ME=1+LDI(IP)
31 I=MAX(I), ME
    H(ME EQ 0) GOTO 341
    I=I+1
    ME=LINK(ME)
    H(ME NE I) GOTO 311
    I=I+1
    H(IP GT 50) GOTO 336
341 continue
  WRITE(2,270) IP, (I MAX(KK) KK=1,I)
330 CONTINUE
C ZION MEMORIAL
  TTEMP=0.0
  DO 6 I=1,N
    VX(I)=VX(I)/XN
    VY(I)=VY(I)/YN
    VZ(I)=VZ(I)/ZN
    TTEMP=TTEMP+VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
6 CONTINUE
C SET INITIAL TTEMP
  C=SQRT(XN*YI/PI*MP)
  TTEMP=0.0
  PX=0.0
  PY=0.0
  PZ=0.0
  DO 16 I=1,N
    VX(I)=VX(I)*C
    VY(I)=VY(I)*C
    VZ(I)=VZ(I)*C
    PX=PX+VX(I)
    PY=PY+VY(I)
    PZ=PZ+VZ(I)
  TTEMP=TTEMP+VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
16 CONTINUE
  PX=PX/XN
  PY=PY/YN

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PZ=I/ZXN
T1M0=T1MFXN*J0)
WRITE(2,205)T1M0,PX,PY,PZ
205 FORMAT(13I10,INITIAL TIME,PJ8 4,4X,15I10,INITIAL MOMENTA,3(2X,1I10))
C PRINT OUT INITIAL POSITIONS VIA X-TIMES AND LINK TABLES
WRITE(2,201)
201 FORMAT(5X,1I10,7X,2I10X,9X,2I10Y,9X,2I10Z,12X,2I10X,9X,2I10Y,9X,2I10
1X,7I10,1N10(1),4X,2I10(1))
DO 14 I=1,20
C WRITE(2,206)J,KX(I),KY(I),KZ(I),VX(I),VY(I),VZ(I),LINK(I),K(I))
206 FORMAT(16,3(2X,3(2X,19 6)),4X,15,2X,15)
14 CONTINUE:
NCOUNT=0
NXT=0
PTOT=0.0
NCT=0
P=0.0
TAU=0.0
PINKM=0.0
PIWANS=0.0

CALL DVI3D,APNIX,NIY,NIJ,NI(1),YI,ZI,SI)
C (EJ) SKONPRIJK TO IN TABLES
29 I=1
(7T=1.010
9 CONTINUE:
C SPIN TO CURJ SKON
B(IJ) K(K) TO 21
B(IJ) L(J) TO 21
B(KM) B(K) TO 21
B(NK(I) B(J) TO 21
B(NCT) B(O) TO 21
GO TO 21
21 CONTINUE:
TC(I)=99.000
B=NCT(I)
PMI=IP - 1
C CALCULATE IX,IY,IJ FROM IP
IZ = IPMI/NLZ
IY = (IPMI - IJ*NIJ)/NIJX
IX = IP - IY*NIJX - IZ*NIJZ
IY = IY + 1
IZ = IZ + 1

C CALCULATE IP
DO 40 KZ = 1, 3
DO 40 KY = 1, 3
DO 40 KX = 1, 3
CX = 0.0
CY = 0.0
CZ = 0.0
IX = IX + KX * J
IY = IY + KY * J
IZ = IZ + KZ * J
C PERIODIC BOUNDARY CONDITIONS*****7777
IF (IX - NLX - 1) 371, 370, 371
370 IX = 1
CX = XF
371 IF (IY - NIY - 1) 373, 372, 373
372 IY = 1
CY = YF
373 IF (IZ - NLZ - 1) 375, 374, 375
374 IZ = 1
CZ = ZF
375 IF (IX) 377, 376, 377
376 IX = NLX
CX = XF
377 IF (IY) 379, 378, 379
378 IY = NIY
CY = YF
379 IF (IZ) 382, 380, 382
380 IZ = NLZ
CZ = ZF
C
I = I + DT
H (I) = H (I) - G(I) * DT
VY(I) = VY(I) + W * W
W = VY(I) * VY(I)
W = W * (MR SS)
H(I) = H(I)
Q = SQRT(H(I))
D = (B + Q * VY)
H(CLT 0.000) TO 17
B(D) DT TO 17
TC(I) = D
N(I) = I
7 CONTINUE:
J = LINK(I)
H(J) = I + DT * KX TO 41
40 CONTINUE:
21 CONTINUE:
B(TC(I) DT) TO 21
DT = TC(I)
KS = 1
IS = N(I)
20 I = I + 1
B(I) = N(I) TO 9
K = KS
I = IS
C UPDATE POSITIONS TO NEXT COLLISION
B(NCOUNT) = NCT + 0.5 * DT
DO 8 I = 1, N
X = RX(I)
Y = RY(I)
Z = RZ(I)
TC(I) = TC(I) - DT
X = X + VX(I) * DT
Y = Y + VY(I) * DT
Z = Z + VZ(I) * DT
DISPX(I) = DISPX(I) + VX(I) * DT
DISPY(I) = DISPY(I) + VY(I) * DT
DISPZ(I) = DISPZ(I) + VZ(I) * DT
C BOUNDARY CONDITIONS
IF (X .GE. 1.000) X = X - 1.000
IF (Y .GE. 1.000) Y = Y - 1.000
IF (Z .GE. 1.000) Z = Z - 1.000
IF (X .LT. 0.000) X = X + 1.000
IF (Y .LT. 0.000) Y = Y + 1.000
IF (Z .LT. 0.000) Z = Z + 1.000
RX(I) = X
RY(I) = Y

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R(1)=Z
C CALCULATE LINK Q(1)
IX = INT( RX(1) * XN1/ZI + 1.0)
IY = INT( RY(1) * YN1/ZI)
IZ = INT( RZ(1) * ZN1/ZI)
IP = IX + N1X * IY + N1Z * IZ
IF (IP EQ K(1)) GOTO 34
C
C TAKE OUT OLD LINK(1)
C
ML = K(1)
I = I(ML)
121 B = (LINK(I)) Q(1) GO TO 327
I = LINK(I)
GO TO 321
122 LINK(I) = LINK(I)
I(ML) = LINK(I)
B = (I) Q(1) (I(ML)) 0
C
C PUT I INTO NEW LINK(1)
C
I = I(ML)
B = (I(ML)) Q(1) I(1)
LINK(I) = LINK(I)
LINK(I) = I
K(I) = IP
I(ML) = I
34 CONTINUE
1 CONTINUE
NCT=1
B = (NCT) INI(1) (NCT) (NCT) (NCT)
C NEW VECTORS OF CURVING PAIR
X = RX(K) RX(L)
Y = RY(K) RY(L)
Z = RZ(K) RZ(L)
B = (X GT 0.5D0) X = X + 1.0D0
H = (Y GT 0.5) Y = Y + 1
B = (Z GT 0.5) Z = Z + 1
H = (X LT 0.5D0) X = X - 1.0D0
H = (Y LT 0.5) Y = Y - 1
B = (Z LT 0.5) Z = Z - 1
U = VX(K) VX(L)
V = VY(K) VY(L)
W = VZ(K) VZ(L)
B = X * U + Y * V + Z * W
BX = X * X * B/SS
BY = Y * Y * B/SS
BZ = Z * Z * B/SS
PTOT = PTOT + B
P = P + B
PNORM = PNORM + B/
PTRANS = PTRANS + BX + BY
C CALCULATE BINS FOR INJUNCTION POINTS
KKK = INT( RZ(K) * (XHIST/ZI) + 1)
KKL = INT( RZ(L) * (XHIST/ZI) + 1)
B(KKK) = B(KKK) GO TO 701
KMAX = MAX(KKK, KKL)
KMIN = MIN(KKK, KKL)
NBINS = KMAX - KMIN + 1
NHIST = NHIST +
B(NBINS LT NHIST) GO TO 705
C LINE JOINING THE CONTINUES ACROSS THE Z BOUNDARY
NBINS = NHIST + KMIN - KMAX + 1
WL = FLOAT( NBINS - 2) * DL1Z
ABSZ = ABS(Z)
H(Z GT 0.0) GO TO 706
C KZ(K) I T R(Z) -----
ZMIN = I( DAT(KKK) * DL1Z / RZ(K)

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ZMAX = Z - ZMIN - WL
GOTO 709
C KZ(K) I T R(Z) -----
706 ZMIN = I( DAT(KKL) * DL1Z / RZ(L)
ZMAX = Z - ZMIN - WL
709 DO 707 KK = KMAX, KMIN
I = ACT + DL1Z / ABSZ
B(KKL) Q(KMAX) / I ACT = ZMIN / ABSZ
PXX(KK) = PXX(KK) + BX * I ACT
PYY(KK) = PYY(KK) + BY * I ACT
PZZ(KK) = PZZ(KK) + BZ * I ACT
707 CY) TIRL
(I) = B(KK) + I * KMIN
I = ACT + DL1Z / ABSZ
B(KKL) Q(KMIN) / I ACT = ZMAX / ABSZ
PXX(KK) = PXX(KK) + BX * I ACT
PYY(KK) = PYY(KK) + BY * I ACT
PZZ(KK) = PZZ(KK) + BZ * I ACT
98 CONTINUE
GOTO 704
C LINE JOINING THE CONTINUES ACROSS THE Z BOUNDARY
NBINS = I( DAT(NBINS) * DL1Z /
ABSZ + ABSZ)
H(Z GT 0.0) GO TO 701
C KZ(K) I T R(Z) -----
ZMIN = I( DAT(KKK) * DL1Z / RZ(K)
ZMAX = Z - ZMIN - WL
GOTO 706
C KZ(K) I T R(Z) -----
701 ZMIN = I( DAT(KKL) * DL1Z / RZ(L)
ZMAX = Z - ZMIN - WL
99 DO 99 KK = KMIN, KMAX
I = ACT + DL1Z / ABSZ
B(KKL) Q(KMIN) / I ACT = ZMIN / ABSZ
B(KKL) Q(KMAX) / I ACT = ZMAX / ABSZ
PXX(KK) = PXX(KK) + BX * I ACT
PYY(KK) = PYY(KK) + BY * I ACT
PZZ(KK) = PZZ(KK) + BZ * I ACT
95 CONTINUE
GOTO 704
C BOTH PARTIES IN THE SAME BIN KKK
701 PXX(KKK) = PXX(KKK) + BX
PYY(KKK) = PYY(KKK) + BY
PZZ(KKK) = PZZ(KKK) + BZ
704 CONTINUE
99 B = B/SS
X = X * B
Y = Y * B
Z = Z * B
C CALCULATE REMIDIAL INJECTION
VXK = VX(K)
VYL = VY(L)
VZK = VZ(K)
VXL = VX(L)
VYL = VY(L)
VZL = VZ(L)
VX(K) = VX(K) * X
VY(K) = VY(K) * Y
VZ(K) = VZ(K) * Z
VXL = VXL * X
VYL = VYL * Y
VZL = VZL * Z
R1 = V + VX(K) * VXK
R = (REVLT 0 0) X(U) = V(KKK) + X(U) V(KKK) + I
R1 = V + VY(K) * VYK
R = (REVLT 0 0) Y(U) = V(KKK) + Y(U) V(KKK) + I
R1 = V + VZ(K) * VZK
R = (REVLT 0 0) Z(U) = V(KKK) + Z(U) V(KKK) + I

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R1V=VX(I)*VXL
R(R1V,I,T,0)XREV(KK1)=XREV(KK1)+1
REV=REV+VXL*VYL
R(R1V,I,T,0)YREV(KK1)=YREV(KK1)+1
R1V=VX(I)*VZL
R(R1V,I,T,0)ZREV(KK1)=ZREV(KK1)+1
NCON=NCON+1
T=T+DT
TAU=TAU+DT
NXT=NXT+KXZL
NAV=NAV+1

DO 11 I=1,N
KK=INT((RZ(I)*XAHSE/ZL))+1
DE=KK*DE+K(KK)+1
TAI=VX(I)*VXI+VY(I)*VYI+VZ(I)*VZI
T1=KK-T1+K(KK)+1
Z1=K(KK)+Z(KK)+RZ(I)
Z2=K(KK)+Z(KK)+RZ(I)*RZ(I)
11 CONTINUE

PUNCH(UNIT,1,1,N,NXT,TAU)
C WRITE(UNIT,1) TAU,10
TIME=T+TIME+TAU
NXT=NXT+1
C WRITE(UNIT,1) TIME, KX, KY, KZ, DISPX, DISPY, DISPZ,
  *VX, VY, VZ
C NWRITE=NWRITE+1
NCON=NCON+1
19 IF(MOD(NCON,1) .NE. 1) GO TO 29
TIME=0
PX=0
PY=0
PZ=0
DO 27 I=1,N
IKI=VX(I)**2+VY(I)**2+VZ(I)**2
TAMP=TAMP+IKI
PX=PX+VX(I)
PY=PY+VY(I)
PZ=PZ+VZ(I)
27 CONTINUE
TIME=T+TIME*KN*10.
PX=PX/KN
PY=PY/KN
PZ=PZ/KN
C CALCULATE MEAN SQ DISP. FOR THE 3 DIRECTIONS SEPARATELY
DIFL=0
DISCR=0
DIFZ=0
XNPL=0
XNCR=0
XNNT=0
DO 37 I=1,N
R(R1(I),0,FL) AND RZ(I) LT FL) GO TO 38
XNPL=XNPL+1
DIFL=DIFL+DISPX(I)**2+DISPY(I)**2+DISPZ(I)**2
38 IF(RZ(I) LEACH OR RZ(I) GE. CRZ) GO TO 39
XNCR=XNCR+1
DISCR=DISCR+DISPX(I)**2+DISPY(I)**2+DISPZ(I)**2
39 IF(RZ(I) GT XNPL AND RZ(I) LT XNNT) GO TO 38
IF(RZ(I) GT XNNT) AND RZ(I) LT XNNT) GO TO 38
GO TO 37
36 XNNT=XNNT+1
DIFNT=DIFNT+DISPX(I)**2+DISPY(I)**2+DISPZ(I)**2
37 CONTINUE
DIFL=DIFL/XNPL**55)
DISCR=DISCR/XNCR**55)

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DIFNT=DISNT/XNNT**55)
WRITE(2,20)MCON,K,I,T,TAU,APX,PY,PZ
WRITE(26,20)MCON,K,I,T,TAU,APX,PY,PZ
202 FORMAT(10H CONJ. IS ON,10,4X,11H DISTWJ N,215,4X,51AT T=J,8,4,4X,51
ITAMP=J,8,4,4X,71H)MCON,TA,2X,1,13,11)
AP=10*PTOT(10*KN**T)
AP=AP/KN.
APN=10*PNORM(KN**T)
APT=10*PTANS(20*KN**T)
PSUBAV=10+PS(0*KN**TAI)
PSUBAV=PSUBAV/KN.
CP=10*11(DATINTAI)**SQRT(IP)**SRTAUI*(KN-10)**30)
CP=CP/KN
WRITE(2,25)PSUBAV,AP,CP,DIFL,DISCR,DIFNT
251 FORMAT(10H PRESSURE FROM CONJ IS,116,4X,116,6H CONJ,1,116,
  *K(12,6)
WRITE(2,2005) APN, APT
MCON=MCON+TAI
P=0
TAU=0
GO TO 29
C) END OF THIS RUN
85 CONTINUE
WRITE(2,234)1,NCON
234 FORMAT(11H END OF RUN,3X,211,15,6,3X,51HCON=J,10)
PIU=10*PIUT(10*KN**T)
PIU=PIU/KN.
WRITE(2,250)PIUT
250 FORMAT(17H AVERAGE PRESSURE,2X,110,6,1)
CP=10*11(DATINCON)**SQRT(IP)**SRTAUI*(KN-10)**30)
CP=CP/KN.
BETAG=APN*APT*KN**20*AP(1)
WRITE(2,253) CP
WRITE(2,2003) BETAG
APN=APN*KN**SRA(A**2)
APT=APT*KN**SRA(A**2)
WRITE(2,*) units of beta*sigma**3 PNORM = ,apn
WRITE(2,*) units of beta*sigma**3 PTRANS = ,apn
C overall density
R(KTCT-KN*(X)*YI**2)*XI**KI**KI)
WRITE(2,*) overall density = ,R(KTCT)
N.A.T=1/5
WRITE(2,820)RCAI,3
820 FORMAT(20H TIME IN HARD SPHERICAL UNITS,2X,12,9,1)
253 FORMAT(16,3X,307,5,6),4X,15,3X,18,5)
12 CONTINUE
C PUNCH OUT FINAL CONFIGURATION
WRITE(2,201)T
201 FORMAT(3H POSITIONS AND VELOCITIES AT T=J,8,4,1)
DO 12 I=1,100,10
C WRITE(2,200)R X(I),Y(I),RZ(I),VX(I),VY(I),VZ(I),MCON,TCT)
200 FORMAT(16,3X,307,5,6),4X,15,3X,18,5)
12 CONTINUE
C PUNCH OUT FINAL CONFIGURATION
WRITE(2,202)
202 FORMAT(22H PUNCH'D CONFIGURATION,1)
DO 30 I=1,N
WRITE(8,249)R X(I),Y(I),RZ(I),VX(I),VY(I),VZ(I)
C
C DISPX(I),DISPY(I),DISPZ(I)
249 FORMAT(2X,3F10,0,2X),3F10,4,2X),3F12,5,1X))
IF(I GT 20) GO TO 30
C WRITE(2,249)R X(I),Y(I),RZ(I),VX(I),VY(I),VZ(I)
30 CONTINUE
C WRITE ACCUMULATORS TO TAPE
WRITE(8,401) NAV,XTIME:

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DO 33 J=1,NHIST
WRITE(8,402) DEN(J),T1(J),PKX(J),PYY(J),PZZ(J)
WRITE(8,403) ZPOS(J),XRV(J),YRV(J),ZRV(J),ZPOSX(J)
7) CONTINUE
C
C PRINT OUT PROFILES
IPRINT=0
52 IENTOT=0.0
T1TOT=0.0
Z1TOT=0.0
Z1OST=0.0
XRVTOT=0.0
YRVTOT=0.0
ZRVTOT=0.0
PXTTOT=0.0
PYTOT=0.0
PZZTOT=0.0
T1TOT=0.0
XNAV=NAV
YNAV=NAV
ZNAV=NAV
VORHIS=(Z/ZHIST)*YI*XI*XI**1

WRITE(2,291) IN,NHIST,IPRINT,MID)
WRITE(9,291) IN,NHIST,IPRINT,MID)
IX) 35 I=1, NHIST
Z = (Z)/X(HIST) * (I. 1)* XI
D = DEN(J)*XNAV * VORHIS
H(D NE.0.0) GOTO 42
Z1=0.0
T1=0.0
T=XTIME:A
XRV=0.0
YRV=0.0
ZRV=0.0
GOTO 43
42 TZ = T1Z(I, X(DEN(I)*3.0)
Z1=ZPOS(I)*XI/XHIST(I)
Z1OST=ZPOS(I)*XI/XHIST(I)
XRV=XRV(I),YRV(I)
YRV=YRV(I),ZRV(I)
ZRV=ZRV(I),XTIME
43 XPKX=PKX(I),XTIME
PYY=PYY(I),XTIME
ZPOS=ZPOS(I),XTIME
DENTOT = DENTOT + DEN(I)*XNAV
T1TOT = T1TOT + T1(I)*XNAV * 3.0
Z1TOT = Z1TOT + Z1(I)*XNAV
Z1OST = Z1OST + Z1OST(I)*XI/XNAV
ZPOSX = ZPOSX + ZPOSX(I)*XI/XNAV
ZPOSY = ZPOSY + ZPOSY(I)*XI/XNAV
PXTOT = PXTOT + PXTOT(I)*XI/XNAV
PYTOT = PYTOT + PYY(I)*XI/XNAV
PZZTOT = PZZTOT + PZZ(I)*XI/XNAV
XRVTOT = XRVTOT + XRV(I)*XI/XNAV
YRVTOT = YRVTOT + YRV(I)*XI/XNAV
ZRVTOT = ZRVTOT + ZRV(I)*XI/XNAV
PXTOT = PXTOT + PXTOT(I)*XI/XNAV
PYTOT = PYTOT + PYY(I)*XI/XNAV
PZZTOT = PZZTOT + PZZ(I)*XI/XNAV
T1TOT = T1TOT + T1(I)*XI/XNAV
IPRINT=0.0) GOTO 40
WRITE(2,290) Z,D,Z1,DENTOT,Z1OST,XPKX,YPYY,ZZ
WRITE(9,290) Z,D,Z1,DENTOT,T1TOT,XRVTOT,YRVTOT,ZRVTOT
WRITE(3,291) Z,D, ZPOSX,ZPOSY,ZPOSY,ZPOSY,ZPOSY,ZPOSY
291) format(3a,110.6,4(2a,114.6))
GOTO 35
50 CONTINUE

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C WRITE(2,290) Z,D,Z1,DENTOT,Z1OST,XPKX,YPYY,ZZ
C WRITE(9,290) Z,D,Z1,DENTOT,T1TOT,XRVTOT,YRVTOT,ZRVTOT
35 CONTINUE
IPRINT=IPRINT+1
IF(IPRINT EQ 0) GOTO 52
7) TO 10
17 WRITE(2,294) J
204 FORMAT(1,23H CATASTROPHIC COLLISION,215)
WRITE(2,231) J,D,X,Y,Z,I,V,W
WRITE(2,236) RX(I),RY(I),RZ(I),R(I),LINK(I)
WRITE(2,236) RX(I),RY(I),RZ(I),R(I),LINK(I)
233 FORMAT(216,2X,G14.6,3(2X,19.5),3X,102X,1V,5H)
234 FORMAT(1H 10 7 210)
18 CONTINUE
206 FORMAT(1H1)
211 FORMAT(1H,20H RX(I),RY(I),Z(I),R(I),R(I),R(I))
220 FORMAT(16,2X,215)
234 FORMAT(1H,110,24H CONFIGURATIONS TO FAIR 10,6)
235 FORMAT(1H,110,19H CONFIGURATIONS TO AD,2X,21H TIME = G12.6)
236 FORMAT(1H,110,24H CONFIGURATIONS ON FAIR 10,2X,21H TIME = G12.6)
237 FORMAT(1H,27H RX,RY,IZ,10,10,10,RESID,3(2X,1H))
240 FORMAT(2X,10,4,8(2X,G14.6))
291) FORMAT(1H,19.6)
401) FORMAT(120,G14.6)
402) FORMAT(5(2X,G14.6))
403) FORMAT(4(2X,G14.6))
203) FORMAT(1H,10X,121H LAGRANGIAN SQ SURFACE TENSORS = 110.6)
205) FORMAT(7H PROGRAM = 15 8 2X 4H PERANS = 115 8)
24) CONTINUE
close(2)
close(6)
close(3)
close(8)
close(15)
STOP
END

*****
SUBROUTINE OVMELANNA, N1,N2,M,Z,XI,YI,Z1,SS)
IMPLICIT REAL*8(A-H,O-Z)
COMMON/MSPTN/ RX(2100),RY(2100),RZ(2100)
COMMON/LINK/ LZ(2100),RY(2100),LMAX(10),LOR(2),L(101)
29) I=1
9) CONTINUE
IP=IC(I)
IPM1=IP-1
C CALCULATE DX,DY,DZ FROM IP
E = IPM1/L2
IY = (IPM1 - E*N1)/N1X
IX = IP - IY*N1X - E*N1Z
IY = IY + 1
E = E + 1
C CALCULATE IP
DO 40 KZ = 1, 3
DO 40 KY = 1, 3
DO 40 KX = 1, 3
CX = 0.0
CY = 0.0
CZ = 0.0
IX = IX + KX * 2
IY = IY + KY * 2
IZ = IZ + KZ * 2
C PERIODIC OR BOUNDARY CONDITIONS*****

```

```

370 H (IX - NLX 1) 371, 370, 371
      IX = I
371 CX = XI
372 IF (JY - NLY 1) 373, 372, 373
373 JY = I
374 CY = YI
375 IF (IZ - NLZ 1) 375, 374, 375
376 IZ = I
377 IF (IX) 377, 376, 377
378 IX = NLX
379 CX = XI
380 IF (JY) 379, 378, 379
381 JY = NLY
382 CY = YI
383 IF (IZ) 382, 381, 382
384 IZ = NLZ
385 CY = YI
C
382 IP = IX * (JY 1) * NLX + (IZ 1) * NLZ
C
      I = I(UP)
C
      ..... C22: H' (M)Y'
      H (I EQ 0) GO TO 40
41 CONTINUE
      H (I EQ 1) GO TO 7
C
      X = RX(I) - RX(I) - CX
      Y = RY(I) - RY(I) - CY
      Z = RZ(I) - RZ(I) - CZ
      NH = X * X + Y * Y + Z * Z
      IF (NH LT SS) THEN
        WRITE(2,*) 'CONFIGURATION HAS AN OVERLAP. I = ', I
      ENDIF
7 CONTINUE
      I = LINK(I)
      IF (I NE LINK(I)) GO TO 41
40 CONTINUE
23 CONTINUE
20 I = I + 1
      H (I LE N) GO TO 9
      RETURN
      END
C.....
SUBROUTINE gmax(XX,S,AM,V)
  IMPLICIT REAL*8 (A-H,O-Z)
  REAL*4 Y
  SUM=0.0
  DO I = 1,12
    Y=RANF(XX)
    SUM=SUM+Y
  CONTINUE
  V=(SUM-6.0)*S+AM
  RETURN
  END
C.....
      root function rand(seed)
C .....
C random no generator
C Peter Mansson
C .....
      double precision seed,d2p31m,d2p31
      data d2p31m/2147483647 ud0/
      data d2p31/2147483648 da0/

```

```

seed = @mod(16807 da0*seed,d2p31m)
rand = seed/d2p31
return
end
integer function inohink(string)
character string*100
do 100 i = len(string), 1, 1
  if (sumg(i:100) ) goto 110
100 continue
110 inohink = i
return
end
c 1950
c 0.94100000 0
c 1 1 2000
c 19 1
c 4 6 26
c 6 5 5 13
c 0 000000 0 000000 0 000000
c 0 500000 0 500000 0 000000
c 0 000000 0 333334 0 333334
c 0 500000 0 833334 0 333334
c 0 000000 0 666667 0 000000
c 0 500000 0 166667 0 666667
c 'Y',Z,S,Z'

```



```

ZPOS(1)=0.0
25 CONTINUE
NEND=NIHSTG+10
DO 4011 I=1,2
  DO 4011 J=1,NEND
    C(I,J)=0.0
    GZ(I,J)=0.0
4011 CONTINUE
C ZERO ACCUMULATORS (USED FOR FIRST AND LAST BIN
DO 4012 I=1,2
  NPAIRS(I)=0
  NX(I)=0
  NPKS(I)=0
  NT(I)=0
  NTX(I)=0
  DENSQ(I)=0.0
  RT(I)=0.0
  RT1(I)=0.0
  RT2(I)=0.0
  XT(I)=0.0
  XT1(I)=0.0
  XT2(I)=0.0
  NPAIRS3(I)=0
  NIX(I)=0
  NPKS3(I)=0
  NT3(I)=0
  NTX3(I)=0
  DENSQ3(I)=0.0
  RT3(I)=0.0
  RT13(I)=0.0
  RT23(I)=0.0
  XT3(I)=0.0
  XT13(I)=0.0
  XT23(I)=0.0
DO 4012 J=1,50
  NPART(I,J)=0
  NPART3(I,J)=0
4012 CONTINUE

```

C CONVERSION TO PROGRAM UNITS

```

VOL=SQRT(2.0)*RHO
Y=0.000
XN=N
NIHST=NIHST
NIHST1=NIHST+1
NIHST2=NIHST1-1
XIHST=NIHSTG
XC=1.0
C YC=SQRT(1.000)
C ***** ZC=1.0*SQRT(1.000)*(1.0/0.0)*RHO/SOL/RHO
C ZC=SQRT(1.000)*(mass/area)*RHO/SOL/RHO
YC=1.500*YC
ZC=1.500*ZC
C ***** XL=DIM(RHO*YC*ZC)*(1.000/1.000)
  XL=(DIM(2.000*mass))*((1.000/0.0)*area)
YL=XL*YC
ZL=XL*ZC
ZML=ZC
ZMLQ=ZL*(1.0+1.91)*XL
AREA=XL*YL
PL1=PL1/XL
PL2=PL2/XL
CR1=CR1/XL
CR2=CR2/XL
XINT1=PL1
XINT2=CR1
XINT3=CR2
XINT4=PL2
Z=1.000/XL
ZL=1.0

```

WRITE(2,210)S

C set up the piston mass and external pressure

```

C
  etc
  sm1 = 1.0 A(10*pmass)
  sm2 = pmass/(10*pmass)
  sm1 = 1.0 A(10*pmass)
  sm2 = pmass/(10*pmass)
  left = pmass*area
  left1 = left*(5*pmass)
  right = left*(5*pmass)
  if (move eq 1) then
    sm1 = 0.0
    sm2 = 1.0
    left = 0.0
  endif
  if (move eq 0) then
    sm1 = 0.0
    sm2 = 1.0
    sm1 = 0.0
    sm2 = 1.0
    left = 0.0
    right = 0.0
  endif
C
  NWRITE(1)WRITE
  NWRITE(2)WRITE
210 FORMAT(22H SIGMA IN UNITS OF 1.0E+06)
  WRITE(2,80) XC,YC,ZC
  WRITE(2,80) XL,YL,ZL
  WRITE(2,2007) AREA
2007 FORMAT(11H SHANTIA=1110)
80 FORMAT(11H 35H BOX DIMENSIONS IN PROGRAM UNITS XC=J10.6
+4H YC=F10.6,4H ZC=F10.6,)
89 FORMAT(11H 35H BOX DIM IN UNITS OF SIGMA XL=J10.6
+4H YL=F10.6,4H ZL=F10.6,)
C INITIAL CELL LATTICE
  rml = 0.0
  rml = 1.0
  vml = 0.0
  vml = 0.0
  IN1,Z=ZDIM/NIHST
  RWL,TST=RWL*.004*5
  RWL,TST=RWL*.004*5
  I=1
  DO I=1,NCZ
    DO IY=1,NCY
      DO IX=1,NCX
        RX(I)=(IX-1)*XA(I)/XMCX
        RY(I)=(IY-1)*YA(I)/YCMCY
        RZ(I)=(IZ-1)*ZA(I)/ZCMCZ
        RX(I)=RX(I)+0.00100
        RY(I)=RY(I)+0.00100
        RZ(I)=RZ(I)+0.00100
        B(I,CON EQ 0) DISP(I)=0.0
        B(I,CON EQ 0) DISP(I)=0.0
        B(I,CON EQ 0) DISP(I)=0.0
      I=I+1
    I CONTINUE
  B(I,CON EQ 0) TO 71
C READ IN CONFIGURATION FROM TAP 7
  PX=0.0
  PY=0.0
  PZ=0.0
  ZMIN=ZC
  ZMAX=0.0
C READ IN WALL POSITIONS FROM THE PREVIOUS RUN

```

```

kze=3
d(i=eq 1) kze=2
d(i=eq n2) kze=2
C CHECK WALL COLLISIONS
C
CALL WCOL(move, r, l, j, w, s, w, R/Z(i), V/Z(i), d(i), angle,
A c(i), ng(i))
C
write(1,*) ' i, j, k, k(i), ng, ng(i) '
C
C CALCULATE IP
DO 40 K/= K/S, K/Z
DO 40 KY=1, 3
DO 40 KX=1, 1
CX=0.0
CY=0.0
IX=IX+KX**2
IY=IY+KY**2
IZ=IZ+KZ**2
C IN BOUNDARY CONDITIONS IN X AND Y DIRECTIONS
IF (IX .NE. 1) 171, 170, 171
170 CX=XI
IF (IY .NE. 1) 172, 172, 173
172 IY=1
CY=YI
173 B (IX) 177, 176, 177
176 IX=NEIX
CX=XI
177 B (IY) 179, 178, 179
178 IY=NEIY
CY=YI
C
179 IP=IX+(IY-1)*NEIX+(IZ-1)*NEI2
C
J=1&XIP)
C
C CALL IP EMPLOY
H (1EQ0) GO TO 40
CONTINUE
B (1EQ0) GO TO 7
C
X=RX(i) RX(i) CX
Y=RY(i) RY(i) CY
Z=RZ(i) RZ(i)
U=VX(i) VX(i)
V=VY(i) VY(i)
W=VZ(i) VZ(i)
B=X*U+Y*V+Z*W
H<B GE.000)GO TO 7
VV=U*U+V*V+W*W
RR=X*X+Y*Y+Z*Z
C=VV*(RR-SS)
BB=B*B
H<C GE.00)GO TO 7
Q=SQRT(BB-C)
D=(B+Q)/VV
H<C1.T.0.00)GO TO 17
H<D GT TL)GO TO 7
TC(i)=D
NK(i)=2
CONTINUE
J=J&NK(i)
B(i, NEI&XIP)GO TO 41
40 CONTINUE
23 CONTINUE
B<TC(i) GT DT)GO TO 20
DT=TC(i)
KS=1

```

```

d<=and eq 0) then
VX(i)=VX(i)*C
VY(i)=VY(i)*C
VZ(i)=VZ(i)*C
endif
PX=PX+VX(i)
PY=PY+VY(i)
PZ=PZ+VZ(i)
TI MP=TI MP+VX(i)*VX(i)+VY(i)*VY(i)+VZ(i)*VZ(i)
16 CONTINUE
PX=PX/N
PY=PY/N
PZ=PZ/NMASS*(VW1+VW2)
PZ=PZ/N
TI MP=TI MP/N*10)
C
if (move .eq. 0) go to 1112
WALL TI MP=(VW1**2+VW2**2)*PRESS/MOVS1
WRITE(2,*) WALL TI MP, WALL TI MP
1112 continue
C
WRITE(2,205)TI MP,PX,PY,PZ
205 FORMAT(13H INITIAL TI MP,1E4,0X,15HINITIAL MOMENTA,10X,1E6)
PRINT OUT INITIAL POSITIONS VELOCITIES AND INK TABLES
C
WRITE(2,201)
201 FORMAT(15X,11H TX,21HX,9X,21HY,9X,21HZ,12X,21VX,9X,21VY,9X,21VZ,
1X,11H INK(i) 4X,21H /)
C
DO 14 I=1,20
C
WRITE(2,208)IX(i)RY(i)RZ(i)VX(i)VY(i)VZ(i)INK(i),B(i)
208 FORMAT(16,21X,10X,19G) 4X,15,2X,15)
14 CONTINUE
NCRINT=0
NCR=0
n=ncr+0
n=ncr+0
PCT=0.0
MT=0
P=0.0
p=0.0
p=ncr+0.0
PMASS=0.0
PTANS=0.0
TAL=0.0
t=ta+0.0
C CELL ZONE NUMBER TABLES
24 I=1
IT=1.000
9 CONTINUE
C STOP COLLISIONS
H<(IX) KX) TO 21
H<(IY) KY) TO 21
H<(NZ) KZ) TO 21
H<(NK) KQ, KR) AND NK(I), NK(I) TO 21
H<(NK) KJ, KJ) TO 21
H<(NK) KJ, KJ) TO 21
GO TO 23
21 CONTINUE
TC(i)=99.010
IP=K(i)
IPM=IP-1
C CALCULATE IX, IY, IZ FROM IP
IZ=IPM/NEI2
IY=(IPM-IZ)*NEI&X
IX=IP-IY*NEIX-IZ*NEI2
IY=IY+1
IZ=IZ+1
kz=1

```

```

READ(7,*) RWT, RWR
READ(7,*) VWL, VWR
READ(7,*) ZIMM
DO 72 I=1,N
  READ(7,*) RX(I),RY(I),RZ(I)
  READ(7,*) VX(I),VY(I),VZ(I)
  READ(7,*) DISPX(I),DISPY(I),DISPZ(I)
C  SHEET ALL THE PARTICLES TO THE 1111
C  I<(IN NL)RZ(I)+RZ(I) RWT
  PX=PX+VX(I)
  PY=PY+VY(I)
  PZ=PZ+VZ(I)
  B<(RZ(I) LT ZMIN) ZMIN=RZ(I)
  B<(RZ(I) GT ZMAX) ZMAX=RZ(I)
72 CONTINUE
C  SHEET THE TWO WALLS TO THE 1111
C  RWR=RWR RWT
C  RWT=RWT RWT
  ZIMM=RWR RWT
  WRITE(2,200) RWT, RWR, ZIMM, ZR1 Q, VWL, VWR

C  CHANGE TO NEW DIRECTIONS OF THE WALL INSECTIONS
C  RWT=RWT+S/2 0
C  RWR=RWR S/2 0
C  ZIMM=RWR RWT
C  WRITE(2,200) RWT, RWR, ZIMM, ZR1 Q, VWL, VWR

  IRTZ=ZIMM/XLIST
  RWLST=RWT*0.04*S
  RWRST=RWR*0.04*S
C  READ ACCELERATORS FROM TAP 7
  I<(AV EQ 0) GOTO 10
  READ(7,*) NAV, XTIM1, ...
  DO 70 J=1,NLIST
    read(7,*) DIR(J),TST(J),PXX(J),PYY(J),PZZ(J)
    read(7,*) ZPOS(J),PZX(J),PZY(J),PZZ(J)
70 CONTINUE
  read(7,*) RT1,RT2,NT2,NPRS,G,NPAIRS,DIRNSQ,XT1,XT2
  read(7,*) RT3,RT13,RT13,NT23,NPRS1,G,NPAIRS3,DIRNSQ3,
  &XT13,XT23
  GOTO 10
31 CONTINUE
C  INITIAL MAXIMUM JIAN VELOCITIES
  PX=0 0
  PY=0 0
  PZ=0 0
  XGAUSS=123
  DO 5 I=1,N
    NR(I)=1
    CALL GAUSS(XGAUSS,1 0 0 0,VX(I))
    CALL GAUSS(XGAUSS,1 0 0 0,VY(I))
    CALL GAUSS(XGAUSS,1 0 0 0,VZ(I))
    PX=PX+VX(I)
    PY=PY+VY(I)
    PZ=PZ+VZ(I)
5 CONTINUE
C  CHAIN LINK TABLES
  I0 XNL=NLX
  YF=1 0
  YNL=NLX
  YF=YC
  ZNL=NLZ
  ZF=ZDOM
  NLJ=NLX*NLX
  NLJ=NLX*NLX*NLX
  DO 30 LL=1,NLJ
    LQ(LL)=0
    LI(LL)=0
30 CONTINUE
  DO 321 I=1,N
    IX=INT(RX(I)*XNL/XI+1 0)
    IY=INT(RY(I)*YNL/YI)
    IZ=INT(RZ(I)*ZNL/ZI)
    IP=IX+NLX*IY+NL2*IZ
    I<(IP GT NL3) GOTO 26
    KK(I)=IP
    MI=1 1(IP)
    I<(MI EQ 0) GOTO 22
    LINK(MI)=I
    LI(IP)=1
    LI(IP)=1
  22 CONTINUE
  LQ(IP)=1
  LI(IP)=1
  321 CONTINUE
C  COMPUTE CHAIN
C
  I0 323 IP=1, NL3
  MI=1 1(IP)
  B<(MI EQ 0) GOTO 323
  LINK(MI)=LQ(IP)
  323 CONTINUE
  GOTO 329
26 CONTINUE
  WRITE(2,270) IX, IY, IZ, IP, I
  WRITE(2,210) RX(I), RY(I), RZ(I)
  GOTO 24
329 CONTINUE
C  CHECK ON LINK ARRAYS
C  WRITE(2,200)
  DO 330 IP=1, NL3
    J=1
    MI=1 1(IP)
  31  LMAX(J)=MI
    I<(MI EQ 0) GOTO 341
    J=J+1
    MI=LINK(MI)
    I<(MI NE 1 1(IP)) GOTO 31
    J=J+1
    I<(IP GT 50) GOTO 330
  341  WRITE(2,220) IP, (I MAX(KK), KK=1, J)
  330 CONTINUE
C  ZERO MOMENTUM
  TEMP=0 0
  PZ=PZ+PMASS*(VWI+VWR)
  DO 6 I=1,N
    if (cont.leq 0) then
      VX(I)=VX(I)-PX/XN
      VY(I)=VY(I)-PY/XN
      VZ(I)=VZ(I)-PZ/XN
    endif
    TEMP=TEMP+VX(I)*VX(I)+VY(I)*VY(I)+VZ(I)*VZ(I)
  6 CONTINUE
C  SET INITIAL TEMP
  C=SQRT(XN**3)/TEMP
  TEMP=0 0
  PX=0 0
  PY=0 0
  PZ=0 0
  if (cont.leq 0) then
    VWI=VWI*C
    VWR=VWR*C
  endif
  DO 16 I=1,N

```

```

15=NK(I)
20 I=I+1
B=(IJE,NK)TU9
K=KS
I=LS
C
C(UPDATE POSITIONS TO NEXT COLLISION)
C
D(MCUMPT)=(B-NIYI)*0.5*DI
C
C
C      UPDATE WALL POSITIONS AND VELOCITIES
  if (move eq 0) go to 1113
  RWK=RWK + VWK*DT + 0.5*avgh*DI**2
  vvv=vvv + avgh*dt
  if (move eq 1) go to 1117
  RWL=RWL + VWL*DI + 0.5*avcl*DI**2
  vvl=vvl + avcl*dt
1117 continue
  WALL(1)M1=(VWL**2 + VWK**2)*PMASS*DI*DI
  wlv=wlv+walltemp
1113 continue
C
C shift all the particles to the left(or to the right if
C the box was expanded) such that
C the left wall ends up at z = 0
C doing this at every collision avoids problems w/ the profiles
C
  if (move eq 2) then
    IX=IWS+1:N
    RZ(I)=RZ(I) - RWL
1915 CONTINUE
C
  now adjust the wall positions
  meaning w/ the right wall
  RWK=RWK - RWL
  RWL=0
  andif
  ZDIM=RWK - RWL
  IJLZ=ZDIM/XIHSI
  RWLTST=RWL*0.04*5
  RWRTST=RWK*0.04*5
  do 99 i = 1,N
    RZ(I)=RZ(I) + VZ(I)*DT
99 continue
C
C
DO 8 I=1,N
  X=RX(I)
  Y=RY(I)
  Z=RZ(I)
  TC(I)=TC(I) DT
  X=X+VX(I)*DT
  Y=Y+VY(I)*DT
  DISPX(I)=DISPX(I)+VX(I)*DT
  DISPY(I)=DISPY(I)+VY(I)*DT
  DISPZ(I)=DISPZ(I)+VZ(I)*DT
C BOUNDARY CONDITIONS
  B(X.GE.1.000)X=X-1.000
  B(Y.GE.YC)Y=Y-YC
  B(Z.GT.RWRTST)GOTO 2000
  B(X.LT.0.000)X=X+1.000
  B(Y.LT.0.000)Y=Y+YC
  B(Z.LT.RWLTST)GOTO 2000
  RX(I)=X
  RY(I)=Y
C CALCULATE LINK CEL
  IX = INT( RX(I) * XN1/ZI) + 1 0)
  IY = INT( RY(I) * YN1/ZI)

```

```

  IZ = INT( RZ(I) * ZN1/ZDIM)
  B(Z.LT.NLZM1)GOTO 2000
  IZ=NLZM1
  NRWR=NRWR+1
2000 IP = IX + NLX*Y + NLZ*IZ
  B (IP I Q RY)) GOTO 34
C
C TAKE OUT OLD LINK CELL
C
  MI = RY(I)
  J = IZ*IZI
  I = LINK(I) I Q I) GOTO 327
  J = LINK(I)
  GOTO 328
327 LINK(I) = LINK(I)
  IZMI = LINK(I)
  B (I I Q J) IZMI)=0
C
C PUT I INTO NEW LINK CELL
C
  I = IZ*IZI
  B ( IZMI) I Q O) I = I
  LINK(I) = LINK(I)
  LINK(I) = I
  R(I) = IP
  IZ(I) = I
34 CONTINUE
B CONTINUE
  M1=I
  D(MCUMPT)=(B-NIYI)*0.5*DI
C
C NEW VELOCITIES ON COLLIDING PAIR
C
  if (LT 0) goto 502
  X=P X(K) - X(K(I))
  Y=P Y(K) - Y(K(I))
  Z=P Z(K) - Z(K(I))
  B(X GT 0.5)X=X+1.000
  B(Y GT YC?) Y=Y+YC
  B(X LT -0.5)X=X-1.000
  B(Y LT -YC?) Y=Y+YC
  U=VX(K) - VX(I)
  V=VY(K) - VY(I)
  W=VZ(K) - VZ(I)
  B(X*U)+Y*V+Z*W
  BX=X*X*B/SS
  BY=Y*Y*B/SS
  BZ=Z*Z*B/SS
  PTOT=PTOT-B
  P =P - B
  PNORM=PNORM-BZ
  PTRANS=PTRANS BX BY
  goto 501
C
C
C perform the wall collision
C
502 if (eq(k) eq -1) then
  delv=vz(k) - vvl
  vz(k)=vz(k) - 2.0 * am12*delv
  vvl=vvvl + 2.0 * am11*delv
  absvz=abs(.2.0*am12*delv)
  else
  delv=vz(k) - vvr
  vz(k)=vz(k) - 2.0 * am12*delv
  vvr=vvvr + 2.0 * am11*delv
  absvz=abs(.2.0*am12*delv)
  andif

```







```

GO TO 29
C END OF THIS RUN
85 CONTINUE
WRITE(2,234)T,NCTX
234 FORMAT(11H END OF RUN,3X,2HT=.196,3X,51HCX=.16)
REAL T=TS
WRITE(2,235)REAL T
235 FORMAT(22H TIME IN HARD SIMULATIONS,2X,129)
PLOT=10*PI/180*(XN*PI)
PIUT=PI/180
WRITE(2,236)PIUT
236 FORMAT(17H AVERAGE PRESSURE,2X,1106)
CP=(10+11)AT(NCTX)*SQRT(PI)*XN*(XN+10)**3
CP=CP/VOX
WRITE(2,237)CP
BETAG=(APN*API)*XNAZ*O*ARI(A)
WRITE(2,238)NWTOT, BETAG
WRITE(2,*) average buslength= [bus]len
WRITE(2,*) units of beta*sigma**3 PINUM = ,apn
WRITE(2,*) units of beta*sigma**3 PIRANS = ,api
C overall density
RHO=(10+XNA)*YI*(beta**3)*XN**3
WRITE(2,239)RHO
239 FORMAT(2,29H PRESSURE FROM COLLISION WALL,2X,1106)
XTIME=XTIME+1
WRITE(2,240)XTIME
WRITE(2,241)XTIME
WRITE(2,242)RWC, RWR, ZDIM, vtot
201 FORMAT(2,36H POSITIONS AND VELOCITIES AT T=1106)
C TX(12)=10,10,10
WRITE(2,243)RX(1),RY(1),RZ(1),VX(1),VY(1),VZ(1),RHO,T(1)
243 FORMAT(6,2(1X,12X,196),4X,15,3X,185)
C17 CONTINUE
C PRINT OUT FINAL CONFIGURATION
WRITE(2,252)
252 FORMAT(2,22H PUNCHES CONFIGURATION)
C WRITE OUT FINAL POSITIONS OF THE WALLS TO TAPE
C
WRITE(2,*)RWC,RWR
WRITE(2,*)vot,vot
WRITE(2,*)ZDIM
DO 30 I=1,N
WRITE(2,*)RX(I),RY(I),RZ(I)
WRITE(2,*)VX(I),VY(I),VZ(I)
WRITE(2,*)DISPX(I),DISPY(I),DISPZ(I)
249 FORMAT(2X,3(F10.8,2X),3(10.4,2X),3(12.5,1X))
C IF GT 2000 TO 30
WRITE(2,249)RX(I),RY(I),RZ(I),VX(I),VY(I),VZ(I)
30 CONTINUE
C
C
C the wall bc should be changed so that it gives formatted output
C an agreement w/ the way we write out the positions, velocities and
C displacements
C
IF(JMP=1) THEN
C WRITE ACCUMULATIONS TO TAPE
WRITE(2,*)NAV,XTIME,bot
C DO 70 I=1,NHIST
C WRITE(2,*)DISP(I),TX(I),PX(I),PY(I),PZ(I)
C WRITE(2,*)ZPOS(I),PXX(I),PYY(I),PZZ(I)
C13 CONTINUE
C WRITE(2,*)RT,RT1,RT2,NT2,NPKS,G,NPAIRS,DI,NSQ,XT1,XT2

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C WRITE(2,*)RT1,RT2,NT2,NPKS,G,NPAIRS,DI,NSQ,XT1,XT2
C14 CONTINUE
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C500 CONTINUE

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C*** Z1Z2=VZ2(I)/X(TIME)
C*** change statement label 43 if space is used
43 XP2XX=PX(X(I),X(TIME)
  YP2YY=PY(Y(I),X(TIME)
  ZP2ZZ=PZ(Z(I),X(TIME)
  KP2XX=D+XP2XX/AR(A)*D(I)/X(I)
  YP2YY=D+YP2YY/AR(A)*D(I)/X(I)
  ZP2ZZ=D+ZP2ZZ/AR(A)*D(I)/X(I)
  DINTOT = DINTOT + D(I)*XNAV
  T1ZTOT = T1ZTOT + T1Z(I)*XNAV*10)
  Z1Z2TOT=Z1Z2TOT+Z1Z2(I)*XNAV
C*** XRVTOT=XRVTOT+XRV(I)/V
C*** YRVTOT=YRVTOT+YRV(I)/V
C*** ZRVTOT=ZRVTOT+ZRV(I)/V
C*** PXCOTOT=PXCOTOT+PXC(I)/X(TIME)
C*** PYYTOT=PYYTOT+PYY(I)/X(TIME)
C*** PZZTOT=PZZTOT+PZZ(I)/X(TIME)
  PZTOT=PZTOT+PZTOT+PZZ(I)/X(TIME)
  PZXTOT=PZXTOT+PZXT(I)/X(TIME)
  PZYTOT=PZYTOT+PZY(I)/X(TIME)
  T1ZTOT=PZTOT*0.5*(PZTOT+PZYTOT)
  I=(PRINT(IQ))GOTO 50
  WRITE(2,200)Z,D,Z(I),D(I),T1ZTOT,XP2XX,YP2YY,ZP2ZZ
C*** WRITE(2,200)Z,D,Z(I),D(I),T1ZTOT,XRVTOT,YRVTOT,ZRVTOT
  GOTO 35
50  WRITE(2,200)Z,D,Z(I),D(I),T1ZTOT,XP2XX,YP2YY,ZP2ZZ
C*** WRITE(2,200)Z,D,Z(I),D(I),T1ZTOT,XRVTOT,YRVTOT,ZRVTOT
35  CONTINUE
  HPRINT=HPRINT+1
  I=(PRINT(IQ))GOTO 52
end
C
GOTO 18
37  WRITE(2,204)I
204  FORMAT(23H CATASTROPHIC COLLISION,215,/)
  WRITE(2,233)I,D,X,Y,Z,U,V,W
  WRITE(2,236)RX(I),RY(I),RZ(I),U(I),LINK(I)
  WRITE(2,236)RX(I),RY(I),RZ(I),U(I),LINK(I)
233  FORMAT(216,2X,G14.6,(2X,1.95),3X,2X,14.5))
236  FORMAT(3H 10 7,216)
GOTO 18
2000 WRITE(2,2001) I,RZ(I)/RWE,RWV
  write(2,*) val(i), k(i), n(i)
  write(2,*) d
18  CONTINUE
206  FORMAT(11H)
211  FORMAT(11H ,RX(I), RY(I), Z(I) ARE RESP ,(2X,19 7))
220  FORMAT(16,2X,2515)
254  FORMAT(11H ,110,CONFIGURATIONS TO TAPE10,/)
255  FORMAT(11H ,110,CONFIGURATIONS READ,2X,TOTIME=G12.6)
256  FORMAT(11H ,110,CONFIGURATIONS ON TAPE10,2X,TOTIME=G12.6,
  *XTIME=G12.6,/)
270  FORMAT(11H ,1X, 1Y, 1Z, 1P, 1ARE: RESP ,(2X,18))
290  FORMAT(11H 4,8(1X,G14.8))
291  FORMAT(11H 6,F9.6)
401  FORMAT(120,G14.8)
2001  FORMAT(11H ,WALL OVERLAP,18,4(2X,G14.8),/)
2002  FORMAT(11H ,RWL=G14.8,RWR=G14.8,ZDIM=G14.8,
  *ZBQ=G14.8,VWL=G14.8,VWR=G14.8,/)
2003  FORMAT(11H ,TOTAL NUMBER OF WALL COLLISIONS=G,110,
  *SX,BETAGAMMAHQ SURFACE TENSION =,F10.6,/)
2004  FORMAT(11H ,RWL=G14.8,RWR=G14.8,ZDIM=G14.8,
  *VWL=G14.8,VWR=G14.8,/)
2005  FORMAT(11H ,PNUM=G,11) & 2, PTRANS=G,11.6,
  *7X,PWALL=G,11.6)
2006  FORMAT(11H ,OVERALL DENSITY,F14.8,/)
  WRITE(2,2008) N301,NRWR,N00
2008  FORMAT(11H ,N301=G,2X,110,2X,NRWR=G,110,

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& N00=.2X,110)
24  CONTINUE
  (loop 2)
  (loop 1)
  STOP
  END
C-----
SUBROUTINE PRINTAV(XNAV,NPAIRS,DI NSQ,NTZ,XT1,XT2,
  *RT1,RT2,NTZ,XT1,XT2,YC2,YC3)
  IMPLICIT REAL*8 (A,H,O,Z)
  COMMON/HLX/RX(2100),PY(2100),PZ(2100)
  DIMENSION RT(2),NPRS(2),N(2),NPAR(2,2),D(2,100)
  DIMENSION RTX(2),RTZ(2),NTZ(2),XT(2),XTZ(2)
C CALL ATLAS AVERAGE DISTANCE MONITOR
C USING NEAREST IMAGE COORDINATES
  NMAX=0.5
  DO 5001 M=1,2
    RT(M)=0.0
    NPRS(M)=0
    NIM=NPM+1
    NI=NRM)
    DI=SR1(I),NIM)
    I1=1
    DO 5001 J=(I1,N)
      II=NPAR(M,I)
      JJ=NPAR(M,J)
      X=RX(I),RX(J)
      Y=RY(I),RY(J)
      U(X-GT 0.5)*X-X+1.0)P
      H(X-1.1-0.5)*X+1.0)P
      H(Y-GT YC2)*Y-Y+Y
      H(Y-1.1-YC2)*Y-Y+Y
      RR=X*X+Y*Y
      R=SQRT(RR)
      II=(R-G)RMAX)GOTO 5001
      NPRS(M)=NPRS(M)+1
      RT(M)=RT(M)+RR
      I1=INT(IER 5)*XIN(100)*X+5001
      GCM(I1)=GCM(I1)+1.0
5001  CONTINUE
5002  CONTINUE
  DO 5002 M=1,2
    NPM=NPRS(M)
    N=(NPRS(M)/Q)GOTO 5002
    XNUM=0.5+0.5*SQRT(1.0+0.01*Q*(NPRS(M))
    RRAV=RT(M)/FLOAT(NPM)
    RTI(M)=RTI(M)+RRAV
    RTZ(M)=RTZ(M)+RTZ(M)
    NTZ(M)=NTZ(M)+NPRS(M)
    XT1(M)=XT1(M)+CNTM
    XTZ(M)=XTZ(M)+XNUM*XNUM
5002  CONTINUE
  RETURN
  END
C-----
SUBROUTINE PRINTAV(XNAV,NPAIRS,DI NSQ,NTZ,XT1,XT2,
  *RT1,RTZ)
  IMPLICIT REAL*8 (A,H,O,Z)
  DIMENSION NPAIRS(2),DI NSQ(2),NTZ(2),XT(2),XTZ(2)
  DIMENSION RTX(2),RTZ(2)
C PRINT OUT AVERAGES OF FIRST AND LAST BIN
C  WRITE(2,5005)
  DO 5003 M=1,2
    PRAV=FLOAT(NPAIRS(M))/XNAV
    DSQ=DENSG(M)/XNAV
    XNTAV=FLOAT(NTZ(M))/XNAV
    XXT1=XTI(M)/XNAV
    XXTZ=XTZ(M)/XNAV

```



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C .....  
.....  
double precision seed,d2p31m,d2p31  
  
c* .....  
.....  
implicit real*4 (a-h,o-s)  
  
data d2p31m/2147483647_0d0/  
data d2p31/2147483648_0du/  
  
seed = dmodr(6807_0d0)*seed d2p31m)  
ranf = seed/d2p31  
return  
end
```