# Multi-Depot Rural Postman Problems

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#### ABSTRACT

This paper studies Multi-Depot Rural Postman Problems on an undirected graph. These problems extend the well-known Undirected Rural Postman Problem to the case where there are several depots instead of just one. Linear integer programming formulations that only use binary variables are proposed for the problem that minimizes the overall routing costs and for the model that minimizes the length of the longest route. An exact branch-and-cut algorithm is presented for each considered model, where violated constraints of both types are separated in polynomial time. Despite the difficulty of the problems, the numerical results from a series of computational experiments with various types of instances illustrate a quite good behavior of the algorithms. When the overall routing costs are minimized, over 43% of the instances were optimally solved at the root node, and 95% were solved at termination, most of them with a small additional computational effort. When the length of the longest route is minimized, over 25% of the instances were optimally solved at the root node, and 99% were solved at termination.

### 1 Introduction

In this paper we present Multi-Depot Rural Postman Problems (MDRPPs) on undirected graphs. Similarly to other arc routing problems, in MDRPPs service demand is placed at a subset of edges, denoted demand or required edges. The distinguished feature of MDRPPs is that there are several depots instead of just one. In MDRPPs feasible solutions are given by sets of routes, each of them starting and ending at one of the depots, where each demand edge is traversed at least once by some route. MDRPPs involve two types of decisions: the allocation of the demand edges to the depots and the construction of the set of routes. We consider two different MDRPP models, which differ from each other in the objective function. The first model uses a min-cost objective where the goal is to determine a set of routes of minimum total cost and will be referred to as MC-MDRPP. The MC-MDRPP extends to several

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depots the well-known undirected Rural Postman Problem (RPP) introduced in [34], which considers one single depot.

The second model that we study uses a min-max objective where the goal is to minimize the length of the longest route, and will be referred to as MM-MDRPP. In contrast to the MC-MDRPP, which minimizes the overall routing costs, but may produce routes which are unbalanced in terms of their length, the MM-MDRPP can be suitable when balanced routes are sought. The MM-MDRPP is related to the min-max K-Rural Postman Problem (MM-K-RPP) that has been studied by several authors for different types of graphs [8, 9, 10, 11, 12, 36]. The MM-K-RPP is an uncapacitated arc routing problem, with one single depot and a fixed number of vehicles, K. Each vehicle must perform a tour starting and ending at the depot. The objective is to minimize the length of the longest among the K routes. It clear that the undirected MM-K-RPP is a particular case of the MM-MDRPP, by considering K depots co-located at the same vertex.

The motivation for studying MDRPPs comes not only from their theoretical interest, but also from their potential applications. Similarly to other arc routing problems, such applications appear in a wide variety of practical cases. Mail delivery, garbage collection, road maintenance or pipelines inspection are typical examples of real-life applications. When considering large application areas for the above examples, there is usually more than one depot from which service demand can be satisfied. Such depots may be vehicle stations, dump sites, replenishment points or relay boxes. For instance, in urban waste collection companies usually operate from multiple depots. A possibility for handling such problems is to decompose them in as many independent problems as depots, first allocating to the different depots demand sectors within smaller operating areas, and then finding optimal routes within each sector. Such solution strategy is indeed suboptimal, as it can be possible to obtain better solutions if a global approach is applied in which the allocation and routing decisions are jointly addressed.

The literature on Multi-Depot Arc Routing Problems (MDARP) is scarce. To the best of our knowledge, this is the first work where an exact algorithm based on a mixed integer linear programming (MILP) formulation is proposed to solve the MDRPP on an undirected graph. A directed MDARP has been considered in the recent work [20], where an exact branch-and-cut algorithm is proposed for a collaboration are routing problem. Other than this, all previous work on MDARPs we are aware of focuses on capacitated arc routing problems with multiple depots (MDCARPs). Some theoretical aspects of MDCARPs are considered in [37]. The asymmetric multi-depot capacitated arc routing problem is studied in [28] where a new formulation and exact solution algorithm are presented. Heuristic methods have been proposed for both undirected and directed MDCARPs. Sequential heuristics for the undirected MDCARP are proposed in [2, 32, 33]: A cluster-firstroute-second strategy, where the assignment of arcs to depots is established before designing the routes, is applied in [2], and a route-first-cluster-second strategy is used in [32, 33], where a single route is created first, which is later divided into smaller routes. Population based heuristics have also been used for solving MD- CARPs. For the undirected case, two different ant colony strategies are presented in [27], and a hybrid genetic algorithm with perturbation that incorporates a local search, a replacement method, and a perturbation mechanism is proposed in [26]. The directed case is addressed in [38], where an evolutionary approach is presented, which takes advantage of the extensions of the classical heuristics for the Capacitated Arc Routing Problem [23].

Multi depot routing problems are indeed related to districting, where a set of clusters or districts that suitably partition the demand set is sought. The design of good districts at an strategic level, where demand points or edges are allocated to depots, allows finding efficient routes at each district at an operational in a later phase. There exists a rich districting literature, in relation to arc routing. In fact, some of the above referenced works stem from this relation. As an example, the heuristics of [32, 33] are devised as a second phases in districting design problems. Two recent works on districting for arc routing are [13, 21]. The interested reader is addressed to [30, 31] for further reading on this topic.

In this work we exploit properties and optimality conditions of MDRPPs, when stated on undirected graphs. These properties allow us to obtain MILP formulations where all variables are binary. In its turn, using binary variables only makes it possible to model parity constraints with an adaptation of the co-circuit inequalities [6]. The resulting formulations have two families of constraints of exponential size on the number of vertices of the input graph: one set for the parity of vertices and the usual set of connectivity constraints. As we will see, the constraints in each family can be separated exactly in polynomial time with adaptations of well-known algorithms. We propose an exact branch-and-cut algorithm where the linear programming (LP) relaxation of the formulation is reinforced with several families of valid inequalities. To analyze the behavior of the proposed algorithm, we have run a series of computational experiments for both the MC-MDRPP and the MM-MDRPP, with a set of benchmark instances adapted from well-known data sets used for other arc routing problems in the literature. The results of these experiments are presented and analyzed.

The reminder of this work is structured as follows. In Section 2 we define MDRPPs whereas in Section 3 we state some properties that will be exploited in the proposed formulations. The formulations for the MC-MDRPP and the MM-MDRPP are presented in Section 4, as well as some families of valid inequalities that we use to reinforce their LP relaxations. Section 5 describes the solution algorithm and discusses the procedures used to separate violated connectivity and parity inequalities. The computational experiments and the obtained results are described in Section 6. Section 7 concludes the work with some comments and directions for future research.

### 2 Multi-Depot Rural Postman Problems

MDRPPs are defined on an undirected connected graph G = (V, E) with vertex set V, |V| = n, edge set E, |E| = m, set of depots  $D \subset V$ , and set of demand (required) edges  $R \subset E$ . Non-demand edges are denoted by  $F = E \setminus R$ . The connected components induced by demand edges are denoted by  $C_k = (V_k, R_k), k \in K$  so  $R = \bigcup_{k \in K} R_k$ . Let  $V_R = \bigcup_{k \in K} V_k$ . We assume that E contains no edge connecting two depots, and no component has more than one depot, although it is possible that a component contains no depot, i.e.  $|V_k \cap D| \leq 1$  for all  $k \in K$ . Let c denote a non-negative real cost function defined on the edges of G.

Throughout we use the term *route* to denote a closed path, not necessarily simple, that starts and ends at the same depot  $d \in D$ . When the depot of the route needs to be explicit we say that the route is *rooted* at depot d. We say that a demand edge  $e \in R$  is *served* by a route, if the route traverses e at least once. As usual, the cost of a route is the sum of the costs of the edges in the route, where the cost of each edge is counted as many times as it is traversed in the route.

We will use the following notation. For any non-empty vertex subset  $S \subset V$ ,  $\delta(S) = \{e \in E | e = (u, v), u \in S, v \in V \setminus S\} = \delta(V \setminus S)$  is the set edges in the cut between S and  $V \setminus S$  and  $\gamma(S) = \{e \in E | e = (u, v), u, v \in S \text{ or vice versa}\}$  the set of edges with both vertices in S. For a singleton  $S = \{v\}$ , with  $v \in V$ , we do not use the brackets and just write  $\delta(v) \equiv \delta(\{v\})$ . For  $H \subset E$  we use  $\delta_H(S) = \delta(S) \cap H$  and  $\gamma_H(S) = \gamma(S) \cap H$ . Furthermore, we will say that a vertex  $v \in V$  is H-odd if  $|\delta_H(v)|$  is odd; otherwise we will say that v is H-even. Finally, we use the standard compact notation  $f(A) \equiv \sum_{e \in A} f_e$  where  $A \subseteq E$ , and f is a vector or a function defined on E. If f is only defined on subset  $B \subset E$ , we use  $f(A) \equiv f(A \cap B) \equiv \sum_{e \in A \cap B} f_e$ .

In the reminder of this paper we make the following modeling assumption:

(H1) Demand edges in the same component can be served from different depots. The effect of this assumption is illustrated in Figure 1. Figure 1.a shows the input graph, which has two demand components and one depot in each of them  $(v_1 \text{ and } v_2, \text{ respectively})$ . Demand edges are represented by black lines while non demand edges are drawn in light grey. The numbers next to the edges indicate their costs. Figure 1.b shows the optimal solution when we impose that all demand edges in the same component are served from the same depot, whose total cost is 23 units. The route of depot  $v_1$  (represented with straight lines), which serves the demand edges of  $C_1$ , consists of edges  $(v_1, A)$ , (A, B), and  $(B, v_1)$ . The route of depot  $v_2$  (represented with doted lines), which serves the demand edges of  $C_2$ , consists of edges  $(v_2, E)$ , (E, C), (C, D), (D, E), (E, C)F), and  $(F, v_1)$ . Figure 1.c shows that a better solution, of value 19 units, can be obtained if we allow to serve demand edges in the same component from different depots. Now all demand edges of  $C_1$  and some demand edges of  $C_2$ are served in the route from depot  $v_1$  defined by edges  $(v_1, A)$ , (A, C), (C, E), (E, D), (D, B),and  $(B, v_1).$ The remaining demand edges of this component are served in the route from depot  $v_2$ , which consists of edges  $(v_2, E)$ , (E, F), and  $(F, v_2)$ .

The routes not necessarily have to be vertex-disjoint.

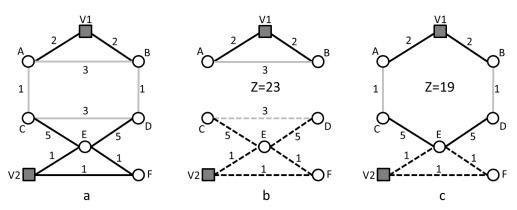


Figure 1: Example that allowing to split the demand components among routes may produce better solutions

In the following we assume that G has been simplified so that V is the set of vertices incident with edges in R, and E contains the edges in R plus additional non-demand edges, connecting every pair of vertices not connected with an edge of R, representing shortest paths in the original graph. For this, according to [14], first we add to  $G_R = (V_R, R)$  an edge between every pair of vertices of  $V_R$  having a cost equal to the shortest path length on G. Then we remove all non-demand edges  $(i, j) \in F$  for which  $c_{ij} = c_{ik} + c_{kj}$  for some  $k \in V$  and one of two edges in parallel whenever they both have the same cost. Hence the costs satisfy the triangle inequality.

#### Definition 2.1

- The MC-MDRPP is to find a set of routes that serve all the demand edges of minimum total travel cost.
- The MM-MDRPP is to find a set of routes that serve all the demand edges that minimizes the length of the longest route.

# 3 Complexity and optimality conditions

The RPP is a particular case of the MC-MDRPP with |D| = 1. Since the RPP is NP-hard [35], we also have:

#### **Proposition 3.1** The MC-MDRPP is NP-hard.

The RPP is also a particular case of the MM-MDRPP with |D|=1. Thus, we also have:

#### **Proposition 3.2** The MM-MDRPP is NP-hard.

As it is usual in other uncapacitated arc routing problems on undirected graphs the feasibility of MDRPP solutions is basically established via connectivity and parity conditions, in addition to the requirement that all demand edges are served. Thus it is not surprising that, similarly to other such problems with min-cost objectives, when non-negative costs satisfy the triangle inequality, optimality conditions hold for the MC-MDRPP that allow to derive formulations using binary variables (see, for instance, [19, 22]). These properties extend or can be adapted to the MM-MDRPP as well as explained below:

- (O1) MC-MDRPP and MM-MDRPP. There is an optimal MDRPP solution in wich each demand edge is served by exactly one route.
- (O2) MC-MDRPP and MM-MDRPP. There is an optimal solution in which no edge is traversed more than twice. Otherwise, two copies of the same edge can be removed without affecting neither the requirement that all demand edges are served, nor the parity of the vertices or the connectivity with the depot.
- (O3) MC-MDRPP and MM-MDRPP. There is an optimal solution where no non-demand edge with the two end-nodes in the same component  $(e \in \gamma_F(V_k))$  is traversed more than once. Otherwise, two copies of such an edge can be removed without affecting the feasibility of the solution. Furthermore, because of the triangle inequality, the only edges of  $\gamma_F(V_k)$ , that are used, are those connecting two R-odd vertices.
- (O4) There is an optimal solution in which the only non-demand edges that are traversed twice are of one of the following types:
  - (a) MC-MDRPP (see [22] for a similar result for the RPP). Edges of the Minimum Spanning Tree (MST) of the multigraph graph  $G_C = (V_C, E_C)$  induced by the connected components.  $V_C$  contains a node representing each connected component  $C_k$ ,  $k \in K$ . For each pair of distinct components  $C_k$  and  $C_{k'}$ ,  $E_C$  contains an edge  $(k_e, k'_e)$  associated with each original edge e linking  $C_k$  and  $C_{k'}$ , i.e. each edge  $e \in \delta_F(V_k) \cap \delta_F(V_{k'})$ , which inherits its cost from G.

It is clear that any MST of  $G_C$  will use only least cost edges between pairs of components. Let  $T^*$  be an MST of  $G_C$ , and suppose an edge  $e^* \in E$  connecting components  $C_k$  and  $C_{k'}$  is traversed twice in an optimal MC-MDRPP solution  $s^*$ , but  $(k_{e^*}, k'_{e^*})$  is not a least cost edge connecting components  $C_k$  and  $C_{k'}$ . Then, adding edge  $e^*$  to  $T^*$  produces a cycle in  $G_C$ , in which  $c_{\widehat{e}} < c_{e^*}$ , where  $\widehat{e}$  denotes a least cost edge in such cycle. Then, replacing in  $s^*$  the two copies of edge  $e^*$  by two copies of  $\widehat{e}$  produces feasible solution: the parity of the vertices of the original graph G does not change and the connectivity of the new solution is guaranteed by the two copies of  $\widehat{e}$ . It is possible that in the new solution some edges are served from a different depot than in the original solution  $s^*$ , but this does not affect to its feasibility either. The fact that the cost of the new solution is smaller than that of the original one, contradicts the optimality

of the original solution.

As shown in the example of Figure 2 this optimality condition does not apply to the MM-MDRPP, where an optimal solution may have two copies of a non-demand edge connecting two different components, which does not belong to any MST of  $G_C$ . Thus the adaptation of this condition to the MM-MDRPP must take into account all least cost edges connecting any pair of components.

(b) **MM-MDRPP.** Least cost edges connecting pairs of vertices of the multigraph graph  $G_C = (V_C, E_C)$ .

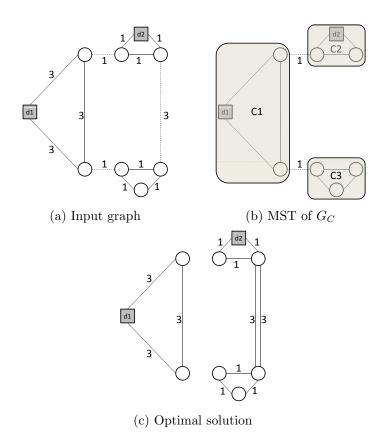


Figure 2: Optimal MM-MDRP solution using twice an edge not in the MST of  $G_C$ .

#### 4 Formulations

Below we present a MILP formulation for the MC-MDRPP that exploits the optimality conditions of the previous section. Condition (O2) implies that we only need two sets of binary variables, for the first and second traversals of edges, respectively. We denote by  $E^y \subset E$  the set of edges that can be traversed twice in an optimal MC-MDRPP solution, which consists of all demand edges plus the edges of the MST of  $G_C$  (see conditions O4(a)). In each set, variables are also associated with the depot of the route that traverses the edges. For each  $e \in E$ ,  $d \in D$ , let  $x_e^d$  be a binary

variable indicating whether or not edge e is traversed by the route of depot d. For each  $e \in E^y$ ,  $d \in D$ , let  $y_e^d$  be a binary variable that takes the value one if and only if edge e is traversed twice in the route of depot d. Then, the a MILP for the MC-MDRPP is as follows:

$$\min \sum_{d \in D} \left( \sum_{e \in E} c_e x_e^d + \sum_{e \in E^y} y_e^d \right) \tag{1}$$

$$(x^d + y^d)(\delta(d)) \ge 2, d \in D$$

$$(x^d + y^d)(\delta(S)) \ge 2x_e^d, \qquad d \in D, S \subseteq V \setminus \{d\}, \quad (3)$$

$$(x^{d} - y^{d})(\delta(S) \setminus H) + y^{d}(H) \ge x^{d}(H) - |H| + 1, \qquad S \subset V, \ H \subseteq \delta(S), \qquad (4)$$

$$|H| \text{ odd}, d \in D$$

$$\sum_{d \in D} x_e^d = 1, \qquad e \in R \tag{5}$$

$$y_e^d \le x_e^d, \qquad e \in E^y, d \in D \tag{6}$$

$$x_e^d \in \{0, 1\}, e \in E$$
  $y_e^d \in \{0, 1\}, e \in E^y$   $d \in D$  (7)

Inequalities (2) and (3) ensure that all depots are used and the connectivity of each route with its depot, respectively. This later condition is imposed by stating that if an edge is traversed by the route associated with depot  $d \in D$ , then at least two edges must cross the cut-set of any vertex set containing its two end-nodes, if it does not contain the depot d. Inequalities (4) ensure the parity (even degree) of every subset of vertices and, in particular, at every vertex. Broadly speaking, they impose that if a solution uses an odd number of edges, H, incident to a set of vertices S, then the solution uses at least one additional traversal of some edge in the cut-set  $\delta(S)$ . In our case, we further exploit the precedence relationship of the x variables with respect to y variables imposed by constraints (6). Thus, the additional edge will be either a second traversal of some edge of H or a first traversal of some edge of  $\delta(S)\backslash H$ . Inequalities (4) are an adaptation to the MDRPP of those proposed in [3, 4, 5], which were later reinforced in [18] for the Maximum Benefit Chinese Postman Problem. Inequalities (2)-(4) jointly guarantee that any solution defines |D| Eulerian circuits. Taking into account optimality condition (O1), equalities (5) ensure that each demand edge is served by one route. As mentioned, inequalities (6) impose that a route cannot traverse an edge for the second time unless it also traverses the edge for the first time. Binary conditions of the variables x and yderived from their definition are reflected in constraints (7).

The above formulation has  $|E| \times |D| x$  variables and  $|E^y| \times |D| y$  variables. There are |D| inequalities of type (2), |R| inequalities (5) and  $|E^y| \times |D|$  inequalities of type (6). The size of the families inequalities (3) and (4) is exponential on |V|.

For the formulation for the MM-MDRPP we use the same sets of decision variables x and y, taking into account that the index set  $E^y$  for the variables associated

with edges that can be traversed twice in an optimal MM-MDRPP solution must be defined according to conditions O4(b). The formulation inherits all constraints (2)-(7), In addition we define a new integer variable z representing the length of the longest route, so the objective becomes the minimization of z. A new family of constraints is needed to relate the new variable z to the lengths of the routes. These inequalities, also ensure that z represents the longest route:

$$z \ge \sum_{e \in E} c_e x_e^d + \sum_{e \in E^y} c_e y_e^d \qquad v \in D.$$
 (8)

#### 4.1 Valid Inequalities

Below we present some families of simple valid inequalities that we will use to reinforce the LP relaxations of the above formulations for the MC-MDRPP and the MM-MDRPP:

#### 1. Aggregated connectivity constraints.

By adding up over all depots the connectivity constraints (3) associated with subsets of nodes containing no depots, and taking into account that all vertices, except possibly the depots, are incident with some demand edge, and thus must be visited, we obtain:

$$\sum_{d \in D} (x^d + y^d)(\delta(S)) \ge 2, \qquad S \subset V, S \cap D = \emptyset.$$
 (9)

Even if the family (9) is implied by the general family (3) and is also of exponential size, some small sub-families associated with particular subsets S can be very useful to reinforce the initial LP relaxation when the general family (3) is relaxed:

• Singletons  $S = \{v\}$ , with  $v \in V \setminus D$ :

$$\sum_{d \in D} (x^d + y^d)(\delta(v)) \ge 2, \qquad v \in V \setminus D.$$
 (10)

For the depots  $d \in D$  the inequalities (10) are also valid, although they are dominated by the stronger constraints (2).

• End-nodes of demand edges.  $S^e = \{u, v\}$ , with  $e = (u, v) \in R$ ,  $S^e \cap D = \emptyset$ :

$$\sum_{d \in D} (x^d + y^d)(\delta(S^e)) \ge 2, \qquad e \in R, S^e \cap D = \emptyset.$$
 (11)

• Vertex sets of components without depot.  $S = V_k, k \in K, V_k \cap D = \emptyset$ :

$$\sum_{d \in D} (x^d + y^d)(\delta(V_k)) \ge 2, \qquad k \in K, V_k \cap D = \emptyset.$$
 (12)

2. **Aggregated parity constraints.** Aggregate versions of the parity constraints (4) are indeed valid for the MC-MDRPP and the MM-MDRPP. Similar inequalities (but combining binary and general integer variables) have been used for other ARPs with multiple vehicles, namely the MM-K-RPP [8, 12]. For the MC-MDRPP and the MM-MDRPP, for  $S \subset V$ ,  $H \subseteq \delta(S)$ , |H| odd. the inequality that we obtain is the following:

$$\sum_{d \in D} (x^d - y^d)(\delta(S) \setminus H) + \sum_{d \in D} y^d(H) \ge \sum_{d \in D} x^d(H) - |H| + 1.$$
 (13)

In particular, when S is R-odd, i.e.  $|\delta_R(S)|$  odd, and  $H = \delta_R(S)$ , the inequality (13) becomes

$$\sum_{d \in D} (x^d - y^d)(\delta_F(S)) + \sum_{d \in D} y^d(\delta_R(S)) \ge 1.$$
(14)

### 5 Solution Algorithm

In this section, we present the solution algorithm that we use to solve the MDRPPs, based on the formulations proposed in Section 4. It is a branch-and-cut algorithm where an iterative Liner Programming (LP) based cutting plane algorithm is applied to the nodes of the enumeration tree. For this, the families of constraints of exponential size are relaxed and, at each iteration, inequalities violated by the current LP solution are separated. Such inequalities are iteratively incorporated to the current formulation and the reinforced formulation resolved. In our case the two families of constraints of exponential size are the connectivity and the parity constraints, (3) and (4), respectively. In the following subsections, the different elements of our algorithm are described: the initial formulation that is considered and the separation procedures for inequalities (3) and (4).

#### 5.1 Initial relaxation

The algorithm starts with the integrality conditions relaxed and only a subset of constraints. Initially we include all constraints (2), (5) and (6), plus a small subset of connectivity and parity constraints. In particular, for each  $d \in D$ , we consider the inequalities (3) associated with the vertex subsets defined by the end-nodes of the edges not incident with any depot, i.e.,  $S^e = \{u, v\}$ , with  $e = (u, v) \in E$ , such that  $u, v \notin D$ . This relaxation is reinforced with the aggregated connectivity inequalities (10), (11) and (12), plus the aggregated parity constraints (14), associated with R-odd singletons, i.e.,  $S = \{v\}$  with  $v \in V$  and  $|\delta_R(v)|$  odd.

#### 5.2 Separation of inequalities

At any iteration of the algorithm the step that solves exactly the separation problem for the connectivity and parity inequalities consists of two parts. First, we look for violated connectivity inequalities (3), and then we look for violated parity inequalities (4). Throughout  $(\overline{x}, \overline{y})$  denotes the current LP solution and, for each depot  $d \in D$ ,  $(\overline{x}^d, \overline{y}^d)$  the partial LP solution associated with the depot d, i.e. the components of  $(\overline{x}, \overline{y})$  associated with d. Furthermore,  $G^d_{\overline{x}, \overline{y}} = (V^d, E_{\overline{x}^d, \overline{y}^d})$  denotes the support graph of the partial solution  $(\overline{x}^d, \overline{y}^d)$  for depot  $d \in D$ , obtained from G by eliminating all edges in E with  $\overline{x}^d_e = 0$  and all vertices that are not incident with any edge of  $E_{\overline{x}^d, \overline{y}^d}$ .

#### **5.2.1** Separation of connectivity inequalities (3)

To separate the connectivity inequalities (3), for each depot  $d \in D$ , we first check if  $G^d_{\overline{x},\overline{y}}$  is connected. If it is not, each connected component C with vertex set  $V(C) \subseteq V^d \setminus D$  defines a violated connectivity constraint (3) for depot d. When  $G^d_{\overline{x},\overline{y}}$  is connected we build the tree of min-cuts  $T^d$  (see, for instance, [24]) of  $G^d_{\overline{x},\overline{y}}$  with capacities given by  $\overline{x}^d_e + \overline{y}^d_e$ . Then, we use an adaptation of the algorithm of [7]. For each edge e = (u,v) in  $E_{\overline{x}^d,\overline{y}^d}$  with  $u,v \in V \setminus D$ , the minimum cut  $\delta(S)$  such that  $e \in \gamma(S)$  is easily obtained from the min-cut tree  $T^d$ . If the value of the min cut is smaller than  $2\overline{x}^d_e$  then the inequality (3) associated with S and d is violated by  $(\overline{x}^d,\overline{y}^d)$ . The above separation is exact and similar to the procedure used by other authors to separate constraints (3) for other arc routing problems [1, 4, 17].

#### **5.2.2** Separation of parity inequalities (4)

For a given vector  $(\overline{x}, \overline{y})$ , the separation problem for inequalities (4) is to find  $d \in D$ ,  $S \subset V$ ,  $H \subseteq \delta(S)$ , |H| odd such that the associated parity inequality (4) is violated by  $(\overline{x}, \overline{y})$ , or to prove that no such inequality exists. The algorithm that we use follows the spirit of the separation used by other authors with similar parity constraints for other arc routing problems with binary variables [4, 5, 17]. For each  $d \in D$ , the algorithm starts by building the tree of min-cuts of the support graph  $G^d_{\overline{x},\overline{y}}$ ,  $T^b$ , with capacities vector b defined as follows. Each edge  $e = (u,v) \in E_{\overline{x}^d,\overline{y}^d}$  is assigned a capacity given by  $b_e = \min\{(\overline{x}_e^d - \overline{y}_e^d), 1 - (\overline{x}_e^d - \overline{y}_e^d)\}$ . This criterion dictates whether edge e should be assigned to H or to  $\delta(S) \setminus H$  if the selected cut-set contains edge e, in order to obtain the smallest possible value of the left hand side of (4).

When  $T^b$  has a cut  $\delta(S)$  of capacity smaller than one, i.e.  $b(\delta(S)) < 1$ , we consider its vertex set S, and the set of edges  $H = \{e \in \delta(S) \mid (\overline{x}_e^d - \overline{y}_e^d) \geq 0.5\}$ , which, as explained, produces the smallest possible value on the left hand side of (4). When |H| is odd, H defines, together with S, a violated inequality of type (4). Otherwise, if |H| is even, since all capacities are non-negative, the smallest increment in the value of the left hand side of (4) that guarantees that |H| is odd is obtained by either removing one edge from H (and transferring it to  $\delta(S) \setminus H$ ) or by adding to H one edge currently in  $\delta(S) \setminus H$ . By doing so the variation in |H| is of just one unit, so the new set H will be odd. The above mentioned smallest increment can be easily computed as

$$\Delta = \min \left\{ \min \{ \overline{x}_e^d - \overline{y}_e^d : e \in \delta(S) \setminus H \}, \min \{ 1 - (\overline{x}_e^d - \overline{y}_e^d) : e \in H \} \right\},$$

where the first term represents the minimum increment in the left-hand-side if an edge of  $\delta(S) \setminus H$  is transferred to H, and the second term represents the minimum increment if an edge of H is transferred to  $\delta(S) \setminus H$ . When  $b(\delta(S)) + \Delta < 1$ , the updated set H defines a violated inequality (4) for d and S for the current solution  $(\overline{x}^d, \overline{y}^d)$ .

It is possible that the minimum cut-set of  $T^b$  does not produce a violated inequality (4) even it it exists. This is only possible if the set H associated with the minimum cut in  $T^b$  is even. Fortunately, in [29] it is proven that exploring as explained above all the cut-sets of  $T^b$  defines an exact algorithm for knowing whether or not a violated inequality (4) exists. The order of such an algorithm is dominated by that of the algorithm that obtains the min-cut tree  $T^b$ . In practice, however, this upper limit on the order of the algorithm is very seldom reached. On the one hand, each connected component of  $G^d_{\overline{x},\overline{y}}$  for the capacities vector b already defines some of the subsets S of the tree  $T^b$  and connected components can be obtained with a small computational burden. On the other hand, when  $G^d_{\overline{x},\overline{y}}$  defines one single connected component but a violated inequality exists, most often the cut-set producing the violated inequality will be identified before completing the full cut-tree  $T^b$ . Thus, in most cases, only if no violated inequality (4) exists it will be necessary to compute all the min-cuts that define  $T^b$ .

Summarizing, for a fixed depot  $d \in D$ , the exact separation for inequalities (4) reduces to finding the set S such that  $\delta(S)$  contains the best possible set H, and indicates that, in the worst case, this problem can be solved by finding the the complete tree of min-cuts of the support graph  $G^d_{\overline{x},\overline{y}}$ , for the capacities vector b defined above. It is important to recall that the smallest value of the left hand side of inequality (4) after making H odd is not necessarily associated with the smallest min-cut of the tree.

# 6 Computational Experiments

In this section, we describe the computational experiments we have run in order to evaluate the performance of the proposed algorithm. Programs have been coded in C++ using CPLEX 12.5 Concert Technology for the solution of the LP relaxations. The maximum computing time has been set to four hours. Moreover, the cuts generated by CPLEX have been disabled.

All the instances were run on an Intel Core 2 CPU, 2.67 GHz and 8.00 GB RAM. Since there were no available MDRPP benchmark instances, we have generated test instances with two and four depots from 118 well-known RPP benchmark instances. The original RPP benchmark instances are divided in five groups. The first group ALB contains two data sets ALBAIDAA and ALBAIDAB, obtained from the Albaida, Spain Graph (see [15, 16]). The second group contains the 24 instances, labeled P, of [14]. The last 3 groups contain instances from [25]: 36 instances with vertices of degree 4 and disconnected required edges sets (labeled D), 36 grid instances (labeled G), and 20 randomly generated instances (labeled R). In all cases we inherited the set of required edges and the cost function c from the original RPP instances.

	# inst	$ V_0 $	$ E_0 $	R	K	$ V / V_0 $	$ E / E_0 $
ALB	2	90-102	144-166	88-99	10-11	1.00	0.99
P	17	7-50	13-184	7-78	2-8	1.00	0.99
D16	6	16	31	3-16	2-5	0.83	0.80
D36	9	36	72	10-38	4-11	0.78	0.79
D64	9	64	128	27-75	5-15	0.82	0.83
D100	9	100	200	50-121	9-22	0.85	0.87
G16	7	16	24	3-13	3-5	0.74	0.67
G36	9	36	60	11-35	5-9	0.79	0.75
G64	9	64	112	24-68	4-14	0.80	0.78
G100	9	100	180	41-113	4-20	0.83	0.83
R20	2	20	47-75	3-7	3-4	0.48	0.36
R30	5	30	70-112	7-11	4-6	0.47	0.41
R40	5	40	82-203	8-18	5-9	0.50	0.50
R50	5	50	130-203	13-20	6-12	0.50	0.54

Table 1: Instances summary

Table 1 depicts information on these instances, which have been grouped according to their characteristics and sizes. The meaning of the columns is as follows: column under  $\sharp$  inst gives the number of instances in the group; columns under  $|V_0|$  and  $|E_0|$  give, respectively, the number of vertices and edges of the original graph; the columns under |R| and |K| give, respectively, the number of required edges and the number of connected components in the graph induced by those required edges. In the above columns, when not all the instances of the group had the same value, the minimum and maximum values of the group are given. The remaining columns in the table give information on the effect of the graph transformation. In particular, columns under  $|V|/|V_0|$  and  $|E|/|E_0|$  respectively correspond to the average ratios of the number of vertices or edges in the transformed graph related to the original graph. As it is known, the transformed graph is considerably smaller than the original graph, in terms of the number of vertices and edges.

For the computational experiments and regarding the set of depots, we have considered two different cases: two and four depots. Depots have been chosen randomly from the set of vertices, fulfilling that no connected component has more than one depot. For this, for each selected number of depots  $|D| \in \{2,4\}$  we have proceeded as follows. First, we randomly generate |D| different numbers,  $k_i$ ,  $i = 1, \ldots, |D|$ , from an integer uniform distribution U[1, |K|], which give the indices of the clusters were the depots are located. Then, for each selected cluster,  $k_i$  the index of the node of  $V_{k_i}$  that becomes the depot is obtained by randomly generating a number  $v_i$  from an integer uniform distribution  $U[1, |V_{k_i}|]$ . In order to compare the results obtained with 2 and 4 depots, the instances that have fewer than four connected components have been removed from the experiment. Finally, the experiments have been run with two groups of 103 instances each.

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	$\mathrm{cutsC}$	${\it cutsP}$	$\sharp Nod$	cpu
ALB	0/2	2.40	3568	153	2/2	0	6889.50	311	10	200.18
P	5/17	2.97	472.47	33.71	17/17	0	318.06	50.24	1.81	1.87
D16	6/6	0	56.83	8.33	-	-	-	-	0	0.03
D36	1/9	0.92	366.67	39.89	9/9	0	149	32.33	5.67	0.60
D64	0/9	1.59	1635.22	80.56	9/9	0	1516.33	178.67	20.22	16.24
D100	0/9	4.11	4392.78	135.56	8/9	0.70	26876.56	1483.89	376.67	2452.42
G16	5/7	1.52	23.14	12.29	7/7	0	12.71	7.14	1.43	0.03
G36	3/9	1.72	313.67	43.22	9/9	0	189.44	32.67	2.33	0.53
G64	2/9	1.75	1474.89	93.89	9/9	0	7733.11	662.11	164.11	156.77
G100	0/9	4.59	14368.89	422.44	7/9	2.80	59850.33	25381.78	337.44	4631.05
R20	2/2	0	7.50	5.50	-	-	-	-	-	0.02
R30	4/5	0.23	59.80	11.60	5/5	0	5.60	6.8	3	0.10
R40	4/5	0.09	330.60	23.60	5/5	0	100.40	18	3.4	0.28
R50	4/5	0.35	351.40	32.20	5/5	0	67.6	2.40	0.4	0.17

Table 2: Summary of results for MC-MDRPP for instances with two depots

#### 6.1 Minimizing the overall routing costs: Results for MC-MDRPP

The results for the MC-MDRPP for the instances with two and four depots are summarized in Tables 2 and 3, respectively. For each group of instances, columns 2-5 give information about the root node of the enumeration tree, while columns 6-11 give the results of the search tree. Column under  $\sharp opt_0$  shows the number of instances in the group that have been optimally solved in the root node. Column under  $gap_0$ gives the average percentage gap at the root node with respect to the optimal or best-known solution at termination. The following two columns, under  $cutsC_0$  and  $cutsP_0$  give the average number of connectivity (3), and parity (4) cuts generated at the root node, respectively. Similarly, the next four columns under  $\sharp opt$ , qap, cuts C and cuts P give the same information at termination: number of instances that have been optimally solved, the average percentage gap with respect to the optimal or best-known solution and the average number of connectivity and parity cuts generated after the root node, respectively. Column under  $\sharp Nod$  shows the average number of nodes that were explored in the search tree. Finally, the column under cpu gives the overall computing time in seconds. These times do not include the preprocessing time for the reduction of the graph neither the time for loading the formulation, which are negligible as compared to the solution times reported in the tables. Detailed results for each instance can be found in the Appendix.

For 36 2-depot instances, a provable optimal solution was obtained already at the root node. At termination, optimality of the current solution was proven for 100 of the 103 2-depot instances. The unsolved instances are D35, G33 and G34 with percentage optimality gaps at termination of 6.34%, 9.88% and 15.36%, respectively.

For the 4-depot instances, optimality was proven at the root node for 53 instances and at termination for 95 of the 103 benchmark instances. No feasible integer solution was found within the time limit for any of the eight unsolved instances: two instances in group D100 (D34 - D35) and six instances in group G100 (G30 - G35).

As for the number of added inequalities, there were considerably more connec-

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	$\mathrm{cutsC}$	$\operatorname{cutsP}$	$\sharp Nod$	cpu
ALB	0/2	1.8	18263	429	2/2	0	45754	1325	129	5476.70
P	11/17	0.73	455.94	49.88	17/17	0	2103.06	134.65	1.81	44.77
D16	6/6	0	0.50	1.33	-	-	-	-	-	0.01
D36	4/9	0.87	488.89	69.67	9/9	0	219.33	35.22	1.89	0.96
D64	1/9	2.27	4027	196.33	9/9	0	3509.78	1543.33	40.11	108.64
D100	0/9	24.60	17860.11	480.11	7/9	22.22	51504.33	1878.44	130	7085.23
G16	7/7	0	1.86	7.8	-	-	-	-	-	0.01
G36	5/9	1.56	340.78	69.78	9/9	0	795.22	98.22	45.44	10.50
G64	5/9	0.67	2636.67	196.89	9/9	0	16248.78	931.22	128	1835.31
G100	1/9	67.08	12813.33	548.22	3/9	66.67	56311.78	1341.67	38.33	9640.11
R20	2/2	0	1.5	7.5	-	-	-	-	-	0.02
R30	4/5	1.63	21.80	14.40	5/5	0	29.40	7.40	1.20	0.08
R40	4/5	0.13	352.60	42.20	5/5	0	20	4	1.80	0.35
R50	3/5	0.48	533.60	62.60	5/5	0	81.20	13.60	0.80	0.45

Table 3: Summary of results for MC-MDRPP for instances with four depots

tivity cuts than parity cuts, although in some cases the number of added cuts was not very large.

The computational effort required for solving the instances to optimality, can be evaluated by the required solving computing times. In this sense, only 5 instances with two depots and 14 of instances with 4 depots required more than one hour (including those instances for which no feasible solution was found within the time limit). Moreover, in 82 2-depot and 76 4-depot instances, respectively, the optimal solution was found in less than 1 minute. If we compare the difficulty in solving instances with two and four depots in terms of the required computing times, we can see that the algorithm is, in general, faster when the instances have fewer depots.

Observe that the proposed algorithm was able to solve at the root node more 4-depot than 2-depot instances, even if the former involve a larger number of variables. If we analyze those instances we can find a pattern. In general, the solved instances belong to groups of small size and, also, they have a small number of connected components.

The results of the computational experiments also allow us to observe whether in the optimal solutions, connected components are fully served by the same depot. Our results indicate that connected components are split in 22 of the 2-depot instances and in 30 of the 4-depot ones.

#### 6.2 Balancing the length of the routes: Results for MM-MDRPP

The analysis of the solutions structures shows that in some instances the routes produced by MC-MDRPP are unbalanced in terms of their length. Below we present the results of a new series of computational experiments have been run with the formulation for the MM-MDRPP. For these experiments we have considered the 78 2-depot instances with up to 50 nodes, and the set of 60 4-depot instances that consists of all instances with up to 40 nodes plus the R50 set. For the excluded instances, in most cases, it was not possible to solve them to optimality and percentage optimality

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	$\mathrm{cutsC}$	${\it cutsP}$	$\sharp Nod$	cpu
Р	1/12	8.31	319.92	27.75	12/12	0	678.58	156.42	35.58	4.43
D16	3/6	3.97	69.50	17.17	6/6	0	35.17	21.67	5.17	0.14
D36	0/9	12.59	448.78	41.78	9/9	0	1310.44	193.11	44.44	4.66
D64	0/9	11.21	2084.78	88.33	8/9	0.11	17340.33	1484.22	1688.44	1866.19
G16	4/7	9.71	38.43	13.86	7/7	0	18.43	13	3.71	0.04
G36	2/9	6.12	379.67	43.78	9/9	0	1279.56	224.56	27.78	5.25
G64	0/9	7.82	2720.33	122.44	9/9	0	25627.78	2532.00	624.56	1665.05
R20	1/2	13.11	18	5	2/2	0	55.50	23.50	7	0.16
R30	1/5	10.00	112.20	16.40	5/5	0	92.40	10.80	3.40	0.15
R40	2/5	3.47	418.20	23.40	5/5	0	650	109.20	59	2.42
R50	0/5	18.49	538.00	25.20	5/5	0	2749.40	197.60	55.80	1.41

Table 4: Summary of results for MM-MDRPP for instances with two depots

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	cutsC	cutsP	$\sharp Nod$	cpu
Р	2/12	14.24	661.83	69.58	12/12	0	4578.58	661.67	1107	1227.46
D16	4/6	5.60	38.83	21.50	6/6	0	0	1.33	1.17	0.08
D36	1/9	20.06	1153.56	122.33	9/9	0	319.56	490.78	176.56	47.03
G16	6/7	3.17	11.86	13.43	7/7	0	0	0	0.14	0.02
G36	2/9	15.90	805.78	124.78	9/9	0	3662.22	679.78	295.22	1117.09
R20	2/2	0	19.50	16	-	-	-	-	-	0.05
R30	3/5	6.73	144.20	30.20	5/5	0	82	24.20	15.50	0.38
R40	0/5	31.09	638.20	61.80	5/5	0	2370.40	306.40	120	30.25
R50	0/5	36,78	1005.60	92.80	5/5	0	5808.60	$1152,\!60$	815.2	113.81

Table 5: Summary of results for MM-MDRPP for instances with four depots

gaps at termination were quite big.

The results of the new experiments are summarized in Tables 4 and 5, where columns have the same meaning as before. It can be seen that, in general, the gap at the root node, the number of cuts, the number of explored nodes and the computing times are worse than with the MC-MDRPP. Still, the proposed algorithm found the optimal solution for all the tested MM-MDRPP instances but one, the exception being instance D26.

Comparing the optimal solutions to both models, we observe that, as could be expected, the overall routing costs are, in general, higher in optimal MM-MDRPP solutions than in optimal MC-MDRPP solutions. Even if there are 19 2-depot instances and 20 4-depot instances where the overall length of all routes is the same in both models, the average overall length increase is 13.09% for the 2-depot instances and 21.14% for the 4-depot instances. The maximum increases are 52.80% in instance R17 with two depots, and 73.69% in instance R11 with four depots.

Nevertheless, we can also observe that when using model MM-MDRPP, the length of the maximum route usually decreases noticeably with respect to the maximum length in an optimal MC-MDRPP solution. Even if there are 13 2-depot instances and 21 4-depot instances where the length of the longest route does not change, on average the length of the maximum route decreases in 19% for the 2-depot instances and 27.20% for the 4-depot instances. The maximum decreases are

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	cutsC	cutsP	$\sharp Nod$	cpu
P	0/12	24.29	788.33	39.58	12/12	0	2641.25	369.33	286.00	25.43
D16	0/6	30.80	125.00	17.67	6/6	0	317.50	117.83	52.17	0.55
D36	0/9	21.49	639.78	40.44	9/9	0	5104.67	703.89	858.00	1685.29
G16	1/7	30.43	67.86	18.29	7/7	0	135.43	37.86	27.14	0.23
G36	0/9	24.89	692.11	49.56	9/9	0	4032.22	556.00	252.67	368.37
R20	0/2	33.48	47.50	15.00	2/2	0	133.50	34.00	18.00	0.31
R30	0/5	22.35	147.60	21.40	5/5	0	473.80	77.40	57.80	0.88
R40	0/5	14.74	432.00	30.00	5/5	0	4079.40	441.60	414.80	28.81

Table 6: Summary of results for MM-K-RPP for instances with two routes

	$\sharp opt_0$	$gap_0$	$cutsC_0$	$cutsP_0$	$\sharp opt$	gap	$\operatorname{cutsC}$	cutsP	$\sharp Nod$	cpu
Р	0/12	37.57	1812.50	93.58	10/12	12.22	14981.33	1822.83	3422.25	3682.92
D16	0/6	48.76	236.17	42.50	6/6	0	1013.67	446.83	594.83	15.40
D36	0/9	36.27	2132.33	167.78	7/9	7.10	20157.67	2088.78	11910.89	3871.17
G16	1/7	32.54	153.86	57.57	7/7	0	301	112.86	72.71	2.10
G36	0/9	47.21	2974.44	204	8/9	3.54	14838.67	1694	1127	4502.25
R20	0/2	50.43	257.50	31.50	2/2	0	812.50	625	692.50	20.09
R30	0/5	47.38	448.80	47.40	5/5	0	2249.80	478.80	442.20	44.59
R40	0/5	40.99	1090	75.80	2/5	6.60	19397.40	2650	4209.40	3336.25

Table 7: Summary of results for MM-K-RPP for instances with four routes

46.15% in instance G25 with two depots, and 64.71% in instance G16 with four depots.

#### 6.3 Balancing the length of the routes from one single depot

In this section we present the results of the last series of experiments we have run. They correspond to the undirected MM-K-RPP, which considers K vehicles located at a one single depot and minimizes the length of the longest route. As mentioned in the introduction the MM-K-RPP is a particular case of the MM-MDRPP, by considering K depots co-located at the same vertex and performing one single route from each co-located depot. For our experiments, we have considered all instances with up to 40 nodes. For each instance, we have randomly selected one of the depots, which has been replicated K times, and all other previous depots have been ignored.

Tables 6 and 7 give the results obtained for  $K \in \{2,4\}$ . Comparing optimal solutions to the MM-K-RPP and the MM-MDRPP, we observe that the cost of the longest route in optimal MM-K-RPP solutions increases considerably in comparison to the MM-MDRPP. Consequently, the total routing cost increases as well. The average maximum length increases in 26.84% for the 2-depot instances and in 102% for the 4-depot instances. This represents a total increase of overall length of 31.29% and 116.50% respectively, on average.

The computational effort required for solving the MM-K-RPP instances to optimality is higher than the previous experiments, for instances of the same size and

characteristics. In comparison with the MM-MDRPP, the computing time of the MM-K-RPP increases around 1604% for 2-depot instances and 644% for 4-depot instances. Furthermore, eight 4-depots instances could not be optimality solved within the limit time. We attribute this increase in the difficulty for optimally solving the instances to the symmetry that now appears for the routes, as they can now be interchanged.

#### 7 Conclusions

In this work we have introduced Multi-Depot Rural Postman Problems on undirected graphs and studied some of its properties and dominance relations for two variants of the problem. In one model the objective is to minimize the overall routing costs, whereas the second model uses a min-max objective function aiming at minimizing the length of the longest route. MILP formulations, which only use binary variables, have been presented for both models where, as usual, the families of constraints that enforce connectivity and parity of solutions are of exponential size. We have proposed an exact branch-and-cut algorithm where the separation problem of both families is solved exactly with adaptations of well-know algorithms. The performance of the algorithm has been tested for the two proposed models. For this, in each case we have solved two sets of instances, with two and four depots, respectively, with 103 instances each of them. For the min-cost objective, 35% and 51% of the instances of the first and second sets, respectively, were optimally solved at the root node. At termination these percentages raise to 97% and 92% of instances optimally solved, for the first and second set, respectively. Regardless the difficulty of the problem, the results produced by the algorithm are quite satisfactory for the model with the min-cost objective. The numerical experiments with the model where the objective is the minimization of the longest route, indicate that computationally the new formulation becomes notably more demanding. Nevertheless, the formulation for this min-max version is indeed successful in producing balanced routes.

The proposed algorithm produces, in general, quite good results for both models although that its performance decreases as the number of depots increase. The reason is that the number of variables of the proposed formulations becomes too high so as to efficiently solve medium size instances. For both models, the performance algorithm could be enhanced with the inclusion of some ad-hoc heuristic.

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# Appendix

MC-MDRPP results

MM-MDRPP results

EPOTS		DoN# d	1100	0000	CutsCo	Cuts Po	4 L	4 Depots	CutsP	PON#	Indo
gap	187	to at	ndo	$gap_0$	catsC0	cutsro	gap	Caus	causr	to art	cbn
0  10806  268	œ	<sub>∞</sub>	258.98	2.26	15239	347	0	83422	2375	239	10398.51
0 2973 354	74	12	141.38	1.34	21286	510	0	8086	275	19	554.88
1		1	0.00	0	0	0		ı	ı	ı	0.00
1		•	0.01	0	0	0		ı	ı	ı	0.01
0 451 62	62	13	0.59	0	303	69	,	0	∞	2	0.50
	103	3 50	1.04	0	99	27	,	ı	ı	ı	0.08
	69	15	0.45	1.76	296	93	0	135	18	က	0.94
		•	0.03	0	0	∞	•	,	,		0.03
0 272 59	6.	7	0.70	0	102	25	•	ı	ı	ı	0.08
	~	က	0.11	0	94	25	·		1		0.17
0 94 40	C.	က	0.30	0	215	43		,	1	,	0.16
0 0 -	_	1	0.11	0	13	10	,	1	1	1	0.08
		1	0.14	2.85	255	52	0	23	$\infty$	2	0.27
	01	1	0.39	3.72	75	9	0	332	52	9	0.44
	118	8 10	5.84	80.0	1887	127	0	4	20	1	2.26
	٦	111	5.10	0	229	93		,	,	,	0.84
0 3042 268	265	5 26	14.10	2.67	1218	92	0	33664	2067	461	748.46
	7	2	2.18	0	1504	126		,	1	,	1.59
	1	~	0.70	1.29	746	89	0	1594	116	ಬ	5.12

Table 8: MC-MDRPP results for instances of the group ALBAIDA and P

	D17	D16	D15	D14	D13	D12	D11	D10	D09	D08	D07	D06	D05	D04	D02		
	1.23	4.17	1.09	0.05	0.58	0.36	0.55	0	0.21	0	0	0	0	0	0	$gap_0$	
	532	503	568	779	302	245	166	86	119	161	10	33	53	29	55	$cutsC_0$	
3	42	52	46	66	42	43	26	27	15	20	0	6	7	∞	9	$cutsP_0$	
)	0	0	0	0	0	0	0	ı	0		ı	ı	ı	ı	ı	gap	2 Depots
	270	949	12	0	29	70	11	ı	0	,	1	ı		ı	ı	cutsC	POTS
j	34	130	24	2	20	71	10	ı	0	,	1	ı		ı	ı	cutsP	
	3	30	2	1	1	12	1	ı	_	0	0	0	0	0	0	$\sharp Nod$	
•	0.76	2.20	0.41	1.06	0.27	0.39	0.14	0.08	0.09	0.05	0.02	0.02	0.03	0.03	0.03	cpu	
	1.19	0	1.20	0	2.61	2.28	0.54	0	0	0	0	0	0	0	0	$gap_0$	
	884	711	615	597	413	106	899	64	111	0	0	သ	0	0	0	$cutsC_0$	
j	100	114	94	66	81	33	88	28	23	0	0	4	0	0	4	$cutsP_0$	
	0		0	,	0	0	0	ı	ı		ı	ı	ı	ı	ı	gap	4 Depots
, , ,	1777		50	1	109	32	6	,	1	,		,			ı	cutsC	POTS
	220		15	1	43	21	18	,				,		ı		cutsP	
	7	1	1	ı	6	2	1	1	1	0	0	0	0	0	0	$\sharp Nod$	
	5.35	0.42	0.83	0.30	0.80	0.14	0.69	0.06	0.09	0.00	0.01	0.03	0.00	0.00	0.02	cpu	

Table 9: MC-MDRPP results for instances of the group D16 and D36

				2 D	2 Depots							4 I	4 Depots			
'	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$poN^{\sharp}$	cbn	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$^{\sharp Nod}$	cbn
D18	0.64	609	42	0	25	35	П	1.04	0.05	1148	88	0	17	16	1	2.09
D19	98.0	1321	63	0	217	61	3	1.84	3.36	1480	105	0	1870	202	10	8.92
D20	0.75	603	40	0	36	28	⊣	0.41	5.13	1106	96	0	292	84	10	2.82
D21	0.80	1816	81	0	16	22	П	12.87	0	3487	199	ı	,	ı	ı	4.60
D22	4.42	2074	94	0	3346	427	92	42.29	2.20	2044	103	0	2463	277	13	22.89
D23	1.60	1051	92	0	252	28	Н	3.76	1.87	2633	172	0	1988	83	4	13.96
D24	09.0	3073	136	0	273	20	6	8.72	1.79	13311	555	0	7654	11887	117	435.99
D25	1.66	1512	65	0	8037	089	22	58.36	2.94	3104	160	0	5357	453	74	103.49
D26	2.95	2658	112	0	1445	277	17	26.90	3.06	7930	289	0	11474	888	132	383.00
D27	3.65	1755	65	0	4687	372	25	66.42	2.18	7117	250	0	5617	217	30	150.59
D28	2.17	2899	127	0	5489	270	26	67.91	1.40	6023	202	0	3303	229	11	60.79
D29	5.03	3606	123	0	5177	464	88	127.36	3.70	222	271	0	4389	263	22	172.94
D30	2.34	5257	167	0	2157	230	9	127.89	5.72	21075	513	0	110867	4291	145	12951.47
D31	1.63	2799	94	0	2017	156	∞	48.11	2.38	14797	458	0	20902	3225	318	8933.27
D32	3.78	6158	134	0	18514	1163	149	793.22	2.34	31960	592	0	46074	1569	202	6728.62
D33	2.63	7558	321	0	4567	624	47	602.05	3.72	20318	453	0	45015	2191	292	5967.82
D34	4.57	6849	125	0	59176	3848	1284	5835.94	100	4133	159	100	113314	3543	112	14400.02
D35	11.17	2654	64	6.34	140105	6228	1757	14402.84	100	47542	1420	100	64354	1378	38	14401.53

Table 10: MC-MDRPP results for instances of the group D64 and D100

G17	G16	G15	G14	G13	G12	G11	G10	G09	G08	G07	G06	G04	G03	G02	G01		
0	3.79	3.87	0	0.93	2.03	1.56	3.33	0	3.13	0	7.50	0	0	0	0	$gap_0$	
117	456	665	263	277	547	248	155	95	17	14	104	2	18	4	သ	$cutsC_0$	
28	32	81	42	45	44	43	38	36	12	14	19	15	16	10	0	$cutsP_0$	
0	0	0	ı	0	0	0	0		0	ı	0	ı	ı	ı	ı	gap	2 Depots
ı	776	541	ı	60	227	99	2	ı	26		55 80	೮٦	ı	ı	ı	cutsC	OTS
ı	108	123	ı	20	28	10	СП	ı	10		34	6	ı	ı	ı	cutsP	
-	6	сπ	ı	<u></u>	သ	2	2	2	2		6	2	ı	ı	1	$\sharp Nod$	
0.06	1.31	1.79	0.11	0.41	0.69	0.23	0.12	0.05	0.03	0.02	0.09	0.03	0.00	0.00	0.02	cpu	
0.00	8.70	0	0.83	4.51	0	0	0	0	0	0	0	0	0	0	0	$gap_0$	
119	683	937	495	348	170	71	195	49	ω	4	0	6	4	0	0	$cutsC_0$	
54	121	154	78	54	46	46	43	32	12	17	0	16	0	0	6	$cutsP_0$	
-	0	ı	0	0	ı	ı	ı			ı	ı	ı	ı	ı	ı	gap	4 De
-	6925		2	230		ı	ı	ı	,		ı	ı	ı	ı	ı	cutsC	4 Depots
ı	841			39		ı	ı	ı	-		ı	ı	ı	ı	ı	cutsP	
ı	400		ш	œ		ı	ı	2	1		ı	ı	ı	ı	ı	$\sharp Nod$	
0.10	91.60	1.09	0.61	0.78	0.14	0.06	0.09	0.06	- 0.00	0.00	0.00	0.01	0.00	0.02	0.01	cpu	

Table 11: MC-MDRPP results for instances of the group G16 and G36  $\,$ 

				2 D;	2 Depots							4 D	4 Depots			
'	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$poN^{\sharp}$	cbn	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$^{\sharp Nod}$	cbn
G18	0	29	12	1	1	ı	ı	0.03	0	728	110		ı	ı	1	0.77
G19	1.04	716	47	0	33	13	П	0.67	0	123	35	ı	ı	ı	ı	0.09
G20	3.58	1053	79	0	511	61	3	2.06	0	269	103	ı	,	,	,	0.61
G21	0.76	779	09	0	1772	158	4	6.52	1.52	3937	251	0	4436	337	26	49.98
G22	1.52	1003	93	0	10336	1039	202	118.48	1.26	4782	299	0	44103	2825	456	1816.27
G23	0	453	94	,	ı	,	,	0.25	0	538	109	ı	ı	,	,	0.98
G24	1.67	5152	208	0	23600	1817	210	416.18	1.67	8206	520	0	75960	3825	598	13783.16
G25	3.57	2769	159	0	27857	2432	086	823.15	1.63	3611	271	0	21740	1394	72	865.65
G26	3.57	1282	93	0	5489	439	22	43.62	0	236	74	ı	ı	ı	ı	0.28
G27	3.31	2009	93	0	2809	193	∞	23.73	0.99	3113	145	0	664	51	1	11.33
G28	1.99	4411	215	0	9033	361	13	86.39	0	8279	402	0	ı	,	,	63.59
G29	2.24	2715	131	0	6850	473	36	81.68	2.76	10316	383	0	4258	239	72	284.59
G30	3.83	5569	276	0	35430	2421	1065	2563.3	100	19182	089	100	86488	2316	62	14400.31
G31	2.26	1879	26	0	54651	2565	266	1946.39	100	8586	251	100	97123	2703	52	14400.42
G32	0.85	30803	728	0	47093	2365	145	4970.55	100	13823	681	100	87876	1810	92	14400.20
G33	9.88	52647	1264	9.88	200139	4650	425	14401.01	100	26911	1082	100	96892	554	21	14400.02
G34	15.54	17147	476	15.36	153312	7559	449	14400.13	100	12452	649	100	48598	1364	11	14400.14
G35	1.41	12140	522	0	29336	2262	630	3206.24	100 0	12658	661	100	104903	3038	34	14400.36

Table 12: MC-MDRPP results for instances of the group G64 and G100

		R01	R03	R05	R06	R07	R08	R09	R10	R11	R12	R13	R14	R15	R16	R17	R18	R19
	$gap_0$	0	0	0	1.16	0	0	0	0	0	0	0.47	0	0	0	0	0	1.75
	$cutsC_0$	0	15	14	129	22	56	78	229	176	54	460	734	299	889	78	250	241
	$cutsP_0$	0	11	0	24	13	7	14	28	13	0	33	44	23	79	15	28	16
2 Depots	gap	1	1	1	0	ı	ı	1	1	ı	ı	0		ı	ı	ı	ı	0
POTS	cutsC	1	1	-	28	1	ı	1	ı	1	1	502	1		1	1	1	338
	cutsP	ı	Ì	_	34	ı	1	i	ı	ı	1	90	1		ı	1	1	12
	$\sharp Nod$	ı	1	1	15	1	1	Ì		ı	1	17	1		ı	1	1	2
	cpu	0.02	0.02	0.00	0.41	0.03	0.01	0.05	0.06	0.03	0.00	0.95	0.37	0.09	0.25	0.05	0.08	0.37
	$gap_0$	0	0	0	8.14	0	0	0	0	0	0	0.63	0	0	0	0	1.17	1.26
	$cutsC_0$	0	3	0	15	0	42	52	66	90	9	1110	488	258	1212	44	504	650
	$cutsP_0$	4	11	0	21	6	34	11	13	21	4	109	64	59	71	19	84	80
4 Depots	gap	1	1	1	0	ı	1	1	ı	,	ı	0	,	1	,	ı	0	0
POTS	cutsC	ı	1	_	147	ı	ı	ı	ı	ı	ı	100	1		ı	ı	46	360
	cutsP	ı	ı	-	37	1	1	ı	ı	ı	1	20	1		ı	1	17	51
	$\sharp Nod$	ı	i	1	6	ı	1	i	ı	ı	1	9	1		ı	1	2	2
	cpu	0.00	0.03	0.00	0.20	0.01	0.16	0.05	0.08	0.06	0.00	1.19	0.42	0.28	0.41	0.05	0.61	0.91

Table 13: MC-MDRPP results for instances of the group R20, R30, R40 and R50

			2 Depots	SLO							4 D	4 Depots			
cut	$sC_0$	$gap_0  cutsC_0  cutsP_0$	gap	cutsC	cutsP	$\sharp Nod$	cbn	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$\sharp N$	cbn
	25	10		1	1	1	0.02	0	0	0		1	1	1	0.00
	99	19	0	115	23	4	0.11	0	49	29	ı	ı	1	ı	0.11
	225	19	0	550	140	17	1.19	18.75	530	82	0	1102	253	28	6.77
	164	19	0	231	2.2	21	0.38	44.63	330	09	0	198	104	16	1.08
	361	47	0	964	171	33	1.59	23.08	736	26	0	1191	402	133	10.56
	73	25	0	12	17	∞	0.16	4.17	33	24	0	0	4	П	0.09
	495	30	0	266	183	26	3.48	60.6	289	66	0	5597	086	230	88.41
	195	16	0	40	41	24	0.48	4.56	145	36	0	45	25	4	0.31
	283	22	0	593	25	3	0.73	16.67	943	98	0	7267	1386	734	206.86
	234	23	0	324	122	75	0.97	13.83	167	30	0	137	74	23	0.50
	522	52	0	476	176	49	3.59	20.20	1012	101	0	2139	340	52	14.54
	1196	51	0	3841	905	137	40.51	15.85	3310	191	60.9	37267	4372	12051	14400.23

Table 14: MM-MDRPP results for instances of the group P

D25 D26	D24	D23	D22	D21	D20	D19	D18	D17	D16	D15	D14	D13	D12	D11	D10	D09	D08	D07	D06	D05	D04	D02		
5.79 12.33	6.64	11.92	8.32	7.44	28.67	9.60	10.23	3.70	8.15	9.79	11.85	9.29	15.94	19.23	20.11	15.23	6.46	8.26	0	9.11	0	0	$gap_0$	
2953 2799	3235	1761	1947	1980	659	2025	1404	744	511	674	577	388	390	272	282	201	196	40	46	41	36	58	$cutsC_0$	
92 119	92	172	74	93	29	77	47	53	52	47	76	37	34	19	33	25	29	11	22	17	11	13	$cutsP_0$	
$0 \\ 1.02$	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	ı	0	1		gap	2 Di
17770 $51991$	24516	9470	19848	15120	6048	5985	5315	2527	1220	578	3379	1149	414	2202	102	223	45	1	25	141	1	ı	cutsC	DEPOTS
1165 4979	1848	1126	1487	964	912	540	337	383	179	117	414	205	96	268	44	32	27	23	1	80		ı	cutsP	
$\frac{221}{12843}$	697	187	273	198	678	64	35	56	38	23	135	45	24	60	6	13	50	σı	0	21	0	0	$\sharp Nod$	
894.59 14400	580.87	444.13	258.9	136.13	48.00	20.53	12.53	9.89	4.35	2.03	18.82	2.14	1.11	4.90	0.27	0.44	0.27	0.14	0.06	0.20	0.01	0.06	cpu	
								10.06	5.34	21.78	23.90	14.39	35.32	30.25	0	39.47	0	0	17.56	16.03	0	0	$gap_0$	
								2492	1546	1625	1669	650	602	1328	202	271	0	39	51	79	29	35	$cutsC_0$	
								232	195	183	139	105	58	103	54	32	0	20	30	33	16	30	$cutsP_0$	
								0	0	0	0	0	0	0	ı	0	ı	ı	0	0	ı		gap	4 De
								8111	625	6792	7215	288	1640	3648	1	207	,		0	0		ı	cutsC	Depots
								989	134	894	1333	90	331	579		67			0	<b>∞</b>			cutsP	
								310	13	433	445	21	143	198	ı	26	0	0	2	υī	0	0	$\sharp Nod$	
								129.73	8.669	84.93	157.48	3.15	7.78	30.23	0.23	1.05	0.00	0.05	0.12	0.19	0.03	0.08	cpu	

Table 15: MM-MDRPP results for instances of the group D16, D36, and D64

				$2 D_1$	2 Depots							4 D	4 Depots			
	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$poN^{\sharp}$	cbn	$gap_0$	$cutsC_0$	$cutsP_0$	gap	cutsC	cutsP	$poN^{\sharp}$	cbn
G01	24.00	27	11	0	9	14	∞	0.05	22.22	0	10	0	0	0	П	0.01
G02	0	ಣ	7	ı	,	,	,	0.00	0	0	4	1	,	,	,	0.00
G03	0	<sub>∞</sub>	<sub>∞</sub>	ı	ı	ı	ı	0.03	0	0	0	ı	ı	ı	ı	0.00
G04	24.00	37	12	0	72	37	10	90.0	0	30	37	ı	ı	ı	,	0.05
905	0	85	19	ı	16	12	1	90.0	0	0	0	ı	ı	ı	ı	0.00
G07	0	22	30	ı	П	2	1	0.05	0	20	34	ı	ı	ı	ı	0.05
G08	20.00	51	10	0	34	26	9	0.06	0	3	6	•		-		0.01
G09	0	157	22	,	10	12	1	0.13	0	74	41		ı	ı		0.13
G10	6.25	186	24	0	312	117	<sub>∞</sub>	0.58	0	345	53	,		,	,	0.20
G11	11.11	236	43	0	106	15	2	0.28	32.19	401	75	0	202	148	13	1.83
G12	60.6	655	54	0	1949	307	33	6.44	16.67	1631	189	0	6168	1345	457	149.26
G13	5.00	279	42	0	197	62	2	0.47	28.57	614	86	0	835	311	94	7.24
G14	4.55	386	7.1	0	952	180	17	2.46	28.05	565	94	0	4161	1053	883	130.60
G15	69.2	974	29	0	3976	624	71	18.71	15.17	1461	277	0	7023	1077	429	221.77
G16	11.36	359	26	0	4014	704	116	18.11	8.33	1242	104	0	111115	1498	407	170.79
G17	0	185	45	1	1	ı	-	0.11	14.10	919	192	0	3151	989	374	9372.00
G18	21.99	435	43	0	4181	562	146	20.73	22.95	28						
G19	9.11	653	46	0	1920	173	12	3.13	23.83	56						
G20	11.91	785	52	0	7761	1128	191	63.74	25.02	28						
G21	10.20	1212	29	0	27044	2515	1420	1173.03	32.67	36						
G22	3.03	2398	78	0	10047	684	33	86.14	33.00	34						
G23	5.26	3318	180	0	30841	2667	468	1578.73	38.00	40						
G24	3.95	10772	375	0	47915	3719	412	2764.37	44.25	46						
G25	2.44	3466	172	0	49735	6175	2046	6426.29	41.00	42						
G26	2.44	1444	26	0	51206	5165	893	2869.26	41.00	42						

Table 16: MM-MDRPP results for instances of the group G16 and G36

R18 15.91				R15 12.83	R14 6.55					R09 1.87		R07 3.70		R05 0	R03 26.23	R01 0	$gap_0$	
)		238		630			133					45		19	33	ယ	$cutsC_0$	
٥	40	15	46	22	34	36	11	17	19	15	25	19	21	2	8	2	$cutsP_0$	
0	0	0	0	0	0	0	1		0	0	0	0	0	1	0	ı	gap	2 De
26.43	1184	545	756	7620	1632	1639	ı	,	24	0	429	28	сπ	ı	111	ı	cutsC	2 Depots
171	131	857	59	542	322	217			7	0	40	6	∞	ı	47	- c	cutsP	
50	28	30	6	165	120	173			2	2	9	СП	1	ı	14	ı	$\sharp Nod$	
3.34	1.15	0.48	0.67	14.81	5.88	5.84	0.08	0.08	0.20	0.06	0.38	0.14	0.12	0.05	0.31	0.00	cpu	
29.04	46.89	35.56	57.87	14.55	13.05	14.50	46.16	49.30	32.44	24.04	0	0	9.59	0	0	0	$gap_0$	
1515	1108	162	1596	647	1123	1209	96	139	624	156	276	36	253	0	39	0	$cutsC_0$	
116	126	32	125	65	99	109	28	23	50	19	66	19	47	0	28	4	$cutsP_0$	
0	0	0	0	0	0	0	0	0	0	0			0	1			gap	4 Di
6489	8216	176	9195	4967	1889	8113	80	24	1746	404	1	ı	6	ı	1	ı	cutsC	4 Depots
644	1340	46	2921	812	233	952	66	37	244	115	1	ı	6	ı		ı	cutsP	
160	705	ω	2589	619	233 89	405	19	6	81	27		,	4	ı		ı	cutsP #Nod	
50.72	105.69	0.41	361.14	51.07	12.29	131.82	0.80	0.48	5.87	1.08	0.51	0.09	0.23	0.00	0.09	0.00	cpu	

Table 17: MM-MDRPP results for instances of the group R20, R30, R40, and R50