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1 Measures of Cardiac Function in Theraphosidae Spiders using *in vivo*

- 2 Magnetic Resonance Imaging
- 3

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- 24 Keywords

MRI, cardiac function, Theraphosidae, tarantula, ejection fraction, *in vivo*, magnetic

- resonance, heart rate
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30

31 Abstract

32

We present the first in vivo cardiac Magnetic Resonance Imaging (MRI) 33 measurements of Theraphosidae spiders. MRI scanning was performed on six 34 spiders under isoflurane-induced anaesthesia. Retrospective Self-Gating Cine-35 Cardiac MRI (RG-CINE-MRI) was used to overcome the difficulties of prospective 36 cardiac gating in this species. The resulting RG-CINE-MRI images were successfully 37 38 analysed to obtain functional cardiac parameters from live spiders at rest. Cardiac ejection fraction was found to increase with animal mass (Pearson correlation 0.849, 39 p= 0.03) at a faster rate than myocardial tissue volume, while heart rate stayed 40 constant across animals. Suggesting the spider heart undergoes additional 41 biomechanical loading with age. The acquisition of these results demonstrates the 42 potential for retrospective gating to evaluate aspects of cardiac function in a wide 43 range of previously inaccessible species. 44

47 Introduction

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To date, the cardiac physiology of invertebrates in general, and spiders in particular, 49 has been comparatively little studied next to the great volume of cardiac literature 50 amassed for rodents and humans, particularly in the medical sciences. Additionally 51 for spiders the techniques used have been restricted to measurements of heart 52 action potential via electrocardiogram (ECG) (Dunlop et al., 1992) or monitoring 53 exterior cuticle movement as a proxy for cardiac motion (Bromhall, 1987; Coelho and 54 Amaya 2000). These latter observations have included both visual observation and 55 the use of attached magnets and sensors to gauge movement. Many of these 56 methods involve either attaching experimental apparatus to the animal, penetrating 57 the outer cuticle (which could potentially lead to lowering of the internal 58 hydrodynamic pressure) or indirect observations of heart function. Therefore, there 59 is little quantitative information on spider cardiac function and outputs in the 60 literature. 61

62

This is in contrast to many vertebrates where cardiovascular Magnetic Resonance 63 Imaging (MRI) routinely provides a non-invasive method of assessing both function 64 and structure in live subjects. MRI is widely used for clinical assessment of 65 cardiovascular disease in humans, providing measurements such as myocardial 66 mass, ventricular volumes, stroke volume, ejection fraction (Epstein, 2007) and 67 even guantitative myocardial perfusion (Jerosch-Herold, 2010) and blood flow maps 68 (Markl M, 2007) . Applications of cardiovascular MRI to other vertebrates, such as 69 rodents, are predominately focussed on biomedical research using disease models. 70 This research has driven the development of specialised MRI systems optimised for 71 mice and rats. The data needed for an MR image generally needs to be acquired 72 over several separate acquisitions. For cardiac MRI where the heart is in continual 73 motion, the MRI scanner typically needs to be triggered/gated by an ECG signal 74 identifying the phase of the cardiac cycle. This is called prospective gating. 75

76

Although MRI has been used previously to acquire basic MRI images of spider anatomy (Pohlmann et al., 2007) it has never been used to study the cardiac function of spiders. Indeed, conventional prospective gating with its need for ECG electrodes and respiration probes is not practical for spiders due to the difficulty of

attaching electrode pads or needles. However, the recent development of 81 retrospectively gated cardiac cine-MRI (RG-CINE-MRI) (Heijman et al., 2006) has 82 simplified cardiac MRI experiments by removing the need for ECG and respiratory 83 contact probes (Holmes 2008, 2009). Here we seek to demonstrate this technology 84 to acquire the first in vivo cardiac images of a spider heart and obtain quantitative 85 measures of cardiac function. The Theraphosidae family and Grammostola genus 86 were chosen as subjects, being a good fit in terms of physical size for existing 87 commercial rat cardiac MRI coils. In addition, possessing hearts of comparable size 88 to rodent hearts helps produce good quality MRI images for quantitative analysis. 89 However it should be noted that the cardiac method described here would be equally 90 applicable to smaller spiders, if an appropriately sized MRI coil was used (Merrifield 91 et al 2017). With the advent of coil-on-a-chip technology, the size of MRI coils now 92 ranges from several tens of centimetres down to just 50microns diameter (Webb 93 2013). 94

- 95
- 96 RG-CINE-MRI

97 Materials and Method

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99 Animal Ethics

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Experiments were conducted according to UK legislation (UK Animals (Scientific Procedures) Act (1986)). Subjects were anaesthetised throughout scanning for immobilisation and to reduce potential subject stress. Efforts were made to avoid direct handling of subjects.

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106 Animal Details and Housing

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Six captive bred adult spiders (gender undetermined, exact age unknown but of adult size, n = 4 *Grammostola rosea (Walcknenaer), n* = 2 *Grammostola porteri (Mello-Leitao)*, Mean Mass = 15.7 g \pm 1.75) were obtained from a UK-based supplier (Virginia Cheeseman, High Wycombe, UK). Spiders were individually housed in plastic vivariums (Length = 29 cm, Width = 19 cm, Height = 23 cm). Sterilised vermiculite substrate was provided (~4 cm deep) along with a retreat. A one week acclimatisation period followed delivery of spiders before subsequent scanning. Free access to water was provided. Food was withheld until after full recovery from
 scanning and anaesthesia.

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118 Animal Anaesthesia, Handling and Positioning

119

Following standard procedures in animal MRI research, subjects were anaesthetised using 5% isoflurane delivered in a 30%/70% mixture of O₂/N₂O gas (1000 ml min⁻¹) to minimise subject motion derived imaging artefacts (Fig 1B). Under anaesthesia all measurements would also be taken at a physiological baseline, eliminating variation due to involuntary movement or behaviour.

125

Subjects were positioned in an MRI compatible animal cradle, lying supine with the heart close to the MRI coil (Fig. 1C). Restraints were cushioned by folded medical gauze swabs that were placed along the length and width of the spider. The assembly was then enclosed in a sealed clear plastic chamber to allow maintenance of anaesthesia and for visual observation of the subject (Fig. 1D). This was then placed into the MRI scanner.

132

After scanning was complete (>1 hour) subjects were in an unresponsive state suggesting deep anaesthesia had been achieved. Locator scans performed before and after cardiac scanning confirmed animals had remained in position during the scanning procedure. Activity returned to normal over a subsequent 24-48 hour period. After recovery no adverse health effects or anomalous behaviours were noted.

139

140 MRI Scanning

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Animals were scanned in a 7T Bruker Biospec MRI scanner (Figure 1A) equipped with a 400 mTm⁻¹ gradient insert and 4-channel phased array cardiac coil (Rapid Biomedical GmbH, Germany). Ambient room temperature during scanning was 18-21°C. The animal was not directly heated by any additional equipment in this time.

146

Anatomical MRI scans were obtained to set up imaging slice prescriptions for Fast Low Angle Shot (FLASH) based retrospective RG-CINE-MRI scans (repetition time

 T_R = 8.00ms, echo time T_E = 3.30ms, field of view (FOV) = 30.0mm x 30.0mm, 149 matrix = 256 x 256, in-plane resolution 117μ m x 117μ m, slice yhickness = 1.50mm, 150 14-18 slices depending on size of individual spider, 300 continuous k-space 151 acquisitions, 5mins 7secs imaging time per slice). These were obtained using an in-152 slice navigator echo as part of the Intragate software package on the scanner 153 (Paravision v.4, Bruker). This navigator is used retrospectively to determine the 154 phase of the cardiac cycle associated with each k space acquisition, allowing images 155 to be created for 10 different phases of the cardiac cycle [Heijman et al., 2006; 156 157 Bovens SM et al., 2011]. Axial image slices along the length of the heart were obtained sequentially until the whole heart was scanned marked by the distal and 158 proximal aortas. 159

160

161 Image Reconstruction and Analysis

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163 Cardiac images were reconstructed using the software tools available in Bruker's 164 Intragate software. Residual navigator pulse trace discontinuities were excluded. 165 Heart rates for each acquired slice were individually outputted as part of this 166 process. Images were analysed using Image J (Schneider et al., 2012). Three 167 independent researchers were trained in cardiac image analysis and then each 168 conducted a separate analysis of all images. Researchers were blinded to which 169 subjects the images came from.

170

For each slice, images were acquired for 10 different phases of the cardiac cycle. 171 From the 10 images of the cardiac cycle for the central chamber, the images 172 corresponding to the diastolic and systolic phases were identified. For each slice at 173 diastole and systole, a region of interest was manually drawn around the heart 174 perimeter giving the area of the ventricle at diastole and systole. This area is then 175 converted to a volume for that slice by multiplying by the image slice thickness of 176 1.5mm. The total ventricular volume of the heart, the end diastolic volume (EDV) and 177 end systolic volume (ESV) are then given by summing the volumes from each slice. 178 The cardiac ejection fraction (EJ) was then determined by, 179

$$EJ = \frac{(EDV - ESV)}{EDV}$$

182 . Calculations of global heart parameters were then made from these measurements.

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186 Statistical Analysis

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Where group averages are given they are presented with plus/minus the standard 188 deviation. In Figure 3a the error bars represent the range of values of the 189 190 measurement made by the three independent researchers. Researchers were blinded to which spider the images had come from and slice ordering was 191 randomised for each researcher. From the RG-CINE-MRI navigator signal a heart 192 rate is measured for each of the (14 to 18) slices acquired. The heart rate was then 193 presented as the mean and standard deviation of these values (figure 3b). 194 Correlations were performed using Pearson correlation coefficient and a 2-tailed test 195 of significance (OriginPro 8, OriginLab Corporation). 196

197

198 199

200 **Results**

201

202 Cardiac Anatomy

203

Scans revealed anatomy matching that broadly outlined for spiders in existing literature (Paul et al. 1994, Foelix 1996, Huckstorf K 2013). Figures 2a and 2b show typical image slices acquired from the RG-CINE-MRI scans. Figure 2c shows a set of ostia in the open position as the heart chamber fills with blood. Figure 2d shows the same slice but with the heart now filled and the ostia closed. Blood pooling between the myocardium and pericardium prior to injection to the interior of the myocardium was also visible.

211

212 Heart Rate

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214 Resting heart rates were measured via the RG-CINE-MRI technique as outputted by 215 navigator signal data. Multiple samplings on each spider were yielded by measuring the heart rate in each image slice. The mean heart rate for the group of spiders was 20 bpm \pm 2 and showed good consistency between subjects using this method (Fig. 3B). No significant correlation was found between body mass and heart rate (Pearson correlation -0.256, p=0.62).

220

221 Cardiac function

222

Table 1 shows quantitative measurements of cardiac function derived from the RG-223 224 CINE-MRI datasets for each spider. As may be expected there was a significant correlation between body mass and total heart volume (Pearson correlation 0.882, 225 p=0.02) and between body mass and end diastolic ventricular volume (EDV) 226 (Pearson correlation 0.956, p= 0.006). The fraction of blood ejected from the heart 227 with each heart beat (the cardiac ejection fraction (EJ)) was successfully measured 228 in each spider as a measure of cardiac function (Fig. 3A). These are the first 229 measurements of *in vivo* ejection fraction in spiders that we were able to find in the 230 literature. Interestingly, we find a significant correlation between body mass and EJ 231 (Pearson correlation 0.849, p= 0.03). The difference in measurement of EJ between 232 the three researchers gave a mean observer difference of EJ = 5.9%. This mirrors 233 accepted levels of observer variability in corresponding rodent cardiac MRI (Heijman 234 et al., 2008). The motion of the heart over the full cardiac cycle at different positions 235 along the axis of the heart can clearly be seen in Supplementary Information 1-3. 236

237

238 Discussion

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The spider heart differs in many structural and biochemical aspects to those of vertebrates previously studied with MRI. However, the spider's contiguous nested two chamber system - the heart myocardium surrounded by a pericardium (Paul et al., 1994; Huckstorf et al., 2013) - provides a resultant MRI image similar to that of a standard human/rodent short-axis view (Figure 2). Hence we used similar image analysis methods to quantify cardiac function.

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247

As might be expected we found a significant positive correlation between body mass and both heart volume and ventricular volume. However, we also found a significant

positive correlation between body mass and ejection fraction. This is interesting as 250 in humans there is no significant correlation between body mass and ejection 251 fraction (Dorbala S. et al., 2006; Seo J.et al., 2017), but there is some correlation 252 between age and ejection fraction (Gebhard C. et al., 2012). A possible explanation 253 for this is that as spiders grow by iterative stages of moulting, a spider's mass can 254 serve as an approximate proxy for age (Foelix 1996). Therefore the correlation 255 observed between EJ and mass can also be broadly considered to be one of EJ and 256 257 age.

258

While the cardiac ventricular volume and to a lesser extent the total heart volume changes between diastolic and systolic phases of the cardiac cycle as expected, the total volume of the myocardial tissue remains largely unchanged in each spider and between systolic and diastolic phases of the cardiac cycle. This suggests that the material is being expanded and compressed across the cardiac cycle as would be expected. No obvious trend for increase in myocardial material over animal mass was observed in contrast to the trend observed for ventricular ejection fraction.

266

It can be speculated that if the growth of the heart volume and/or myocardial tissue 267 from one moulting instar to the next is less than that of the overall animal's volume 268 then a corresponding increase in EJ would be required. This means that the heart 269 would have to pump a larger volume of blood as it aged in order to maintain 270 adequate cardiac function, just as we observed. Further assessment of spiders of 271 different masses (and so at different ages or developmental instars at least) would 272 provide a more complete understanding of this relationship as well as potentially 273 revealing any additional physiological costs of this increased output as subjects age. 274 These costs might mirror mechanical heart degradation and disease in vertebrate 275 animals but could be of novel interest to cardiac researchers given the evolutionary 276 independent nature of the spider cardiac system as an invertebrate. Additionally, if 277 measurements of the mechanical properties of the spider heart could be conducted 278 ex vivo, then it would be possible to combine these with MRI to calculate the 279 biomechanical forces at work in the spider heart in vivo. Spider growth gradually 280 tapers off both physically and with frequency dependent on species, age and food 281 availability (Foelix 1996). It is conceivable that the end point to this process might be 282 marked or triggered by the condition of the heart, precluding further growth when 283

specific mechanical limits have been reached. The MRI technique we have
 demonstrated here would be suitable for investigating this further.

286

The consistency of mean heart rate across subjects supports the use of non-contact 287 methods to assess heart function in spiders. Although some reports suggest that 288 heart rate across all spider species is correlated with animal mass (Carrel and 289 Heathcote 1976) this was not found to be the case for the subjects involved in our 290 study. However, the Carrel and Heathcote study treats multiple spider types in a 291 292 collective fashion, combining measurements from them all into a single trend for heart rate and mass. This is despite known differences between these spiders in 293 terms of behaviour, environmental conditioning and physiology. This variation 294 between types is visible in the Carrel and Heathcote study itself. Our study suggests 295 that within groupings of spider type heart rate does not vary - certainly within the 296 Theraphosidae species. Comparative study of different types of spiders using MRI 297 would clarify this situation further. 298

299

A wider range of heart rate values was observed in two subjects in this study. These two animals were scanned first. This greater range of obtained heart rates could be explained by a poorer quality Intragate navigator signal resulting from increased animal motion. In turn this could be due to less restrictive restraints used on these initial two subjects as we finalised the experimental set up. However, mean values are still acceptably consistent with those found in the subsequent scanned subjects.

306

We were unable to absolutely determine the gender of the subjects scanned, but their large size (indicating greater age) and continued life-span post-scanning (years) suggests they were all female. This would also tally with the assessment of the supplier. It is possible that our group of subjects included a mix of both male and female subjects which may have resulted in some of the variation in results. However, sexing of spiders is notoriously difficult until males reach sexual maturity in the final instar of growth and so may continue to be difficult to determine.

314

Despite reports of the effectiveness of isoflurane-based inhalation anaesthesia induction in spiders (Zachariah et al., 2009; Dombrowski et al., 2013) we found it to have variable performance (Pizzi 2012). Some spiders were rendered lethargic after 5-10 minutes. In others it appeared to have minimal effect even for induction times greater than 30 minutes. The brief time needed to move the animal from the induction chamber to the scanning chamber (<15 seconds) was often sufficient for recovery from the initial lethargic state.

322

Although alternative injectable anaesthetics have been studied recently in spiders (Gjeltema 2014) more effective inhalation anaesthesia agents should be investigated for future use. Additionally, the design and use of a combined induction/scanning chamber is recommended to avoid the need to remove spiders from the anaesthesia environment. Placement of the spiders in an oxygen enriched environment postscanning is recommended to potentially accelerate recovery from the deep level of anaesthesia induced in subjects over the scan duration.

330

331

The RG-CINE-MRI sequence used was designed for rodent hearts beating at much 332 higher rates compared to spiders (~20 beats per minute (bpm) compared to 333 ~350bpm in rats and ~550 bpm in mice). Therefore, a potential concern was that the 334 spider heart rate would be insufficient and provide too few complete cardiac cycles 335 for the reconstruction algorithms of the RG-CINE-MRI software to work. This did not 336 prove as problematic as originally thought and the reconstruction appeared robust 337 and consistent with experience in house.. Our own particular scan settings may not 338 be optimal in terms of balancing total scan time (and so cost) against the obvious 339 benefits of *in vivo* MRI as a technique. Fewer image averages and Intragate cardiac 340 cycles should be possible to speed up the imaging process without compromising 341 the final measurement quality. Our high imaging resolution enabled us to see the 342 operation of the heart ostia, but for simple analysis of heart function the image 343 resolution could also be reduced, speeding up image acquisition further. It should be 344 noted that in these experiments the RG-CINE-MRI for each slice was acquired 345 sequentially. We found this gave stable pseudo cardiac and respiratory gating 346 signals that are needed for the retrospective reconstruction of the cardiac images. 347 However, a more efficient multi-slice approach is often used in rodent cardiac 348 studies, which could be potentially applied to spiders (Heijman et al., 2006). 349

350

351 These results suggest that RG-CINE-MRI can potentially be applied to spiders and

other invertebrates. The availability of MRI micro-coils, from just 50um diameter (Webb 2013), would allow even small invertebrates to be studied. However, it is worth noting that the centralised, cohesive heart structure of spiders is comparatively rare. Amongst both arachnids and insects, a chain of small 'pseudo-hearts' that act collectively is more the norm (Klowden 2007). Though, the application of RG-CINE-MRI to such a chain of pseudo hearts should be technically possible, it would need to be practically tested.

359

In summary, we acquired the first in vivo cinematic cardiac MRI images from spiders. 360 From these images we were able to directly measure common cardiac functional 361 parameters for the first time in an identical manner to existing human and rodent 362 cardiac MRI. Cardiac ejection fraction was found to increase with animal mass at a 363 faster rate than myocardial tissue volume while heart rate stayed constant across 364 animals, suggesting the spider heart undergoes additional biomechanical loading 365 with age. The RG-CINE-MRI technique provides much potential for in vivo cardiac 366 MRI research to be expanded into a wider range of novel species. 367

368

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370

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373

374 Supporting Information

- Additional Supporting Information may be found in the online version of this article.
- 376 Movie M1 Example CINE cardiac movie
- 377 Movie M2 Example CINE cardiac Movie
- 378 Movie M3 Example CINE cardiac Movie
- 379

380 Contributions

- 381
- 382 GM and WMH conceived and designed the experiments. GM, JM, LG, RP and WMH
- ³⁸³ performed the experiments. GM, NB and LH analysed the resultant images and data.
- GM, NB and WMH prepared the manuscript
- 385

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anesthesia of wild-caught goliath birdeater spiders (Theraphosa blondi) and Chilean

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Spider	1	2	3	4	5	6	Mean ± std
Body Mass (g)	11.7	12.00	12.00	15.10	16.09	18.8	14 ± 3
Heart Rate (beats/min)	20.2	20.6	21.1	22.9	16.0	20.6	20 ± 2
	(±1)	(±1)	(±2)	(±4)	(±3)	(±6)	
End systolic ventricular	29.6	50.0	30.7	28.6	53.7	49.4	40 ± 12
Volume (ESV) (mm ³)							
End Diastolic ventricular	42.5	57.5	51.1	59.9	96.5	115.1	70 ± 29
Volume (EDV) (mm ³)							
Ejection Fraction (EJ)	0.25	0.13	0.37	0.52	0.48	0.57	0.38 ± 0.17
	(±0.04)	(±0.02)	(±0.04)	(±0.02)	(±0.04)	(±0.01)	
Heart volume (systole) (mm ³)	114	134	91.8	135	176	184	139 ± 35
Heart volume (diastole)	122	140	114	170	213	232	165 ± 48
(mm³)							
Volume of Myocardium	84.0	83.7	61.1	106	123	135	99 ± 28
(systole) (mm ³)							
Volume of Myocardium	79.3	82.6	63.1	110	116	117	95 ± 23
(diastole) (mm ³)							
Change in myocardium	0.06	0.01	-0.02	-0.03	0.08	0.15	0.04 ± 0.07
Thickness (mm ³)							

Table 1. Cardiovascular physiological measurements made on each of the six
spiders from the cine MRI datasets. The mean values from all six spiders is given in
the end column

499 Figure Legends

- **Figure 1. Experimental set up for scanning. A**. 7T preclinical MRI scanner used in 503 the experiments, **B.** Spider in anaesthetic chamber undergoing anaesthesia

induction, **C.** Anaesthetised spider lying prone on back in place above MRI coil, **D.** Spider ready for scanning now with restraints in place and with plastic sleeve in
 place over the coil and cradle.



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508 509

Figure 2. Example cardiac images from RG-CINE-MRI data. Axial image slices showing **A**. Diastolic phase (heart arrowed), B. Systolic phase (heart arrowed), **C**. Heart with ostia (arrowed) in the open position, **D**. Heart with ostia (arrowed) in the closed position.



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- 516

Figure 3. Results of Cardiac MRI Analysis showing A. Mean and standard 517 deviation of measurements of cardiac ejection fraction determined between three 518 independent researchers (for n=6 spiders). B. RG-CINE-MRI navigator sourced 519 mean heart rates in Beats Per Minute (BPM) with s.d. error bars. After RG-CINE-MRI 520 navigator signal processing the mean heart rate for each slice of cardiac data from 521 an individual subject is estimated and then a mean heart rate is generated for the 522 entire heart (n=6). 523

