# Wavelets bases defined over tetrahedra 

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#### Abstract

In this paper we define two wavelets bases over tetrahedra which are generated by a regular subdivision method. One of them is a basis based on vertices while the other one is a Haar-like basis that form an unconditional basis for $L^{p}(T, \Sigma, \mu), 1<$ $p<\infty$, being $\mu$ the Lebesgue measure and $\Sigma$ the $\sigma$-algebra of all tetrahedra generated from a tetrahedron $T$ by the chosen subdivision method. In order to obtain more vanishing moments, the lifting scheme has been applied to both of them.


Keywords: Wavelets, multiresolution, lifting, volume modeling.

## 1. INTRODUCTION

Three dimensional scenes contain highly detailed geometric models that are rapidly emerging as the next frontier requirement for many applications such as those involving Internet 3D models for complex virtual environments, collaborative CAD, interactive visualization and multi-player video games. Therefore construction of better 3D surfaces and volume models is necessary in order to allow high quality approximations of big data sets with good storage space and better transmission time performance.
Wavelets have been making appearing in many pure and applied areas of science and engineering as a versatile tool for representing general functions or big data sets. Computer graphics, with its many and varied computational problems, is no exception to this rule since wavelets are a good approach for solving the situations described above.
An example of approximation of volumetric data in 3D using wavelets parameterized on a rectangular grid in $\mathbb{R}^{3}$ was presented in [7] for the case of applications in computer graphics. Although this
is a simple way of constructing wavelets for surface or volume representation, this method has an important drawback: it cannot be used without introducing degeneracies for representing surfaces or volumes defined on general domains of arbitrary topological type, like spherical domains.
Lounsbery [6] and Stollnitz et al. [10] were the first who introduced wavelets from a different point of view, defining them on different bounded domains with arbitrary topology through scaling refinable functions. For this purpose, the multiresolution analysis (hereafter MRA) is extended to functions defined on surfaces by creating scaling refinable function. This approach was generalized a posteriori by Sweldens ([11], [12]) using the lifting scheme. Schröder and Sweldens [9] proved later that subdivision and lifting provide an efficient methodology for costum-design construction of wavelets and focused their work on wavelet representation of functions defined on a sphere. Nielson [8] also defined Haar wavelets over the sphere. Both constructions begin with a triangular net and, using subdivision as a construction tool, generate wavelets on arbitrary topological bidimensional domains.
Following similar ideas as those ones used for surfaces, we have examined the cases of representing volumes and functions defined on a tetrahedral grid. In this paper we present two different wavelets bases: a vertex basis for a tetrahedron and a Haar like wavelet basis defined over a tetrahedron. Vertex wavelets can be found, for example, in [5]. The main difference between ours and Lorentz and Oswald's [5] is that we give an explicit expression for the wavelet filters. The vertex and Haar bases are the first step for defining each such wavelet basis over an object which is represented by tetrahedra. In both cases we applied the lifting scheme to increase the number of vanishing moments of the
wavelets. Other techniques for representing volume data are given in [2] and [4].
This paper is organized as follows: in Section 1 we describe the vertex based wavelets, we show an example and present the lifted vertex wavelets. In Section 2 we define the Haar-like wavelets, we show an example representing a density function defined on a tetrahedron using these waveletes and also apply the lifting scheme for obtaining more vanishing moments. Finally, in Section 3 we draw the conclusions and outline the future work.

## 2. VERTEX WAVELETS

For the two dimensional case, Schröeder and Sweldens in [9] present four vertex bases: lazy, linear, butterfly and quadratic. Each of them depend on the neighbors used for a given vertex. In this section we build a vertex basis for a tetrahedrical net. It does not have an analytic expression but we give the analysis and synthesis steps for computing the scaling and wavelets coefficients. The chosen tetrahedron subdivision causes the new vertex to be on the midpoint of the tetrahedron edges. Then, when passing from a resolution level $j$ to a resolution level $j+1$, six new vertices will be added on one tetrahedron. In the resolution level $j$ we have an index set $\mathcal{K}_{j}$ to index the vertices of the tetrahedron. In level $j+1$, the set of vertices is $\mathcal{K}_{j+1}=\mathcal{K}_{j} \cup \mathcal{M}_{j}$, $\mathcal{M}_{j}$ being the set of indices corresponding to the inserted ones (see Figure 1). If $m \in \mathcal{M}_{j}$ is the in-


Figure 1: Tetrahedron vertices indexation
dex of a given vertex we may think of it as being on the midpoint of some parent edge. The neighboring vertices considered for defining the vertex basis are the endpoints of that parent edge and we denote them with indices $u$ and $v$.
In what follows, we note the scaling and wavelet or detail coefficients corresponding to a given function at the resolution $j$, by $c_{j, k}$ and $d_{j, k}$ respectively. As always, the coefficients $c_{0, k}$ correspond to the coarsest approximation and the process begins with a given set of coefficients $c_{N, k}$ where $N$ is the finest resolution level. As we shall consider an interpolating scheme for deriving a vertex basis, the unlifted scaling coefficients are just subsampled in the analysis and upsampled in the synthesis. Meanwhile for computing the wavelet coefficients it will be necessary to make some calculations.

## Analysis

$$
\begin{align*}
\forall k \in \mathcal{K}_{j}, c_{j, k} & \doteq c_{j+1, k} \\
\forall m \in \mathcal{M}_{j}, d_{j, m} & \doteq c_{j+1, m}-\sum_{k \in \mathcal{K}_{m}} s_{j, k, m} c_{j, k} \tag{1}
\end{align*}
$$

## Synthesis

$$
\begin{align*}
& \forall m \in \mathcal{K}_{j}, c_{j+1, k} \doteq c_{j, k} \\
& \forall m \in \mathcal{M}_{j}, c_{j+1, m} \doteq d_{j, m}+\sum_{k \in \mathcal{K}_{m}} s_{j, k, m} c_{j, k} \tag{2}
\end{align*}
$$

Following the above scheme, we begin with a basic interpolatory form for analysis and synthesis

$$
\begin{aligned}
d_{j, m} & \doteq c_{j+1, m}-\frac{1}{2}\left(c_{j+1, u}+c_{j+1, v}\right) \\
c_{j+1, m} & \doteq d_{j, m}+\frac{1}{2}\left(c_{j, u}+c_{j, v}\right)
\end{aligned}
$$

that is $s_{j, u, m}=s_{j, v, m}=\frac{1}{2}$ in equations (1) and (2).

## Multiresolution analysis

In order to define the sequence of nested spaces $V_{j}$ needed for the MRA, we use a sequence of tetrahedra, beginning with a basic net $T_{0}$ that is a single tetrahedron $T$. Then, the spaces $V_{j}$ are defined as:

$$
\begin{aligned}
V_{j} \doteq & \left\{f: T_{j} \rightarrow \mathbb{R}: f\right. \text { is linear on each tetra- } \\
& \text { hedron of } \left.T_{j}\right\} .
\end{aligned}
$$

These are nested spaces since any linear function on the tetrahedra of $T_{j}$ is also linear on the tetrahedra of $T_{j+1}$. As the space $V_{j}$ contains only piecewise linear functions, any member of $V_{j}$ is uniquely determined by its values on the vertices of $T_{j}$. As usual, the $V_{j}$ are spanned by the the scaling functions $\varphi_{i, j}$ and the wavelets $\psi_{i, j}$ are the basis functions of the complement spaces $W_{j}$. As always, any a function $g$ defined on a tetrahedral net with vertices $c_{J, i}=\left(x_{J, i}, y_{J, i}, z_{J, i}\right)$ is defined as

$$
\begin{equation*}
g(\mathbf{x})=\sum_{i \in v\left(V T_{J}\right)} c_{J, i} \varphi_{J, i}(\mathbf{x}) \tag{3}
\end{equation*}
$$

where $\mathbf{x} \in T_{0}$ and $v\left(T_{J}\right)$ is the set of indices that indexes the $T_{J}$ vertices. Finally, we have the following wavelet decomposition of $g$ :

$$
\begin{align*}
g(\mathbf{x})= & \sum_{i \in v\left(T_{J}\right)} c_{J, i} \varphi_{J, i}(\mathbf{x})  \tag{4}\\
& +\sum_{j=0}^{J-1} \sum_{i \in\left(v\left(T_{j+1}\right)-v\left(T_{j}\right)\right)} d_{j, i} \psi_{j, i}(\mathbf{x}),
\end{align*}
$$

where the scaling functions $\varphi_{j, i}$ and the wavelets $\psi_{j, i}$ are the vertex ones while the inner product of two functions $f, g \in V_{j}\left(V T_{0}\right), j<\infty$, the inner product of $f$ and $g$ is defined by

$$
\begin{equation*}
\langle f, g\rangle \doteq \sum_{\tau \in \Delta\left(T_{j}\right)} \frac{1}{\operatorname{Volume}(\tau)} \int_{\tau} f g d V \tag{5}
\end{equation*}
$$

being $\Delta\left(T_{j}\right)$ the set of all tetrahedra of $T_{j}$ and $\tau$ a tetrahedron of $\Delta\left(T_{j}\right)$. So defined, these inner products do not depend on the geometric position of the vertices of $T$, so it is possible to pre-compute them.

## Example

We choose to represent a density function on a tetrahedron using the scaling functions approximation. This density is mapped on color on each vertex of a tetrahedra. The idea is to treat each color component (red, green and blue) as a scalar function defined on the base mesh $V T_{0}$. Each color function can be converted to multiresolution form using the filter bank analysis and the wavelet coefficients. In Figure 2 and Figure 3 we show one step in the analysis and one step in the synthesis, respectively.


Figure 2: One step in analysis


Figure 3: One step in synthesis

## Lifting the vertex wavelets

An important property of a family of wavelets $\psi_{\gamma}$, $\gamma \in \mathcal{G}, \mathcal{G}$ a set of indices, is to have vanishing moments. We say that the wavelet $\psi_{\gamma}$ has $N$ vanishing moments if there exist $N$ linearly independent polynomials $P_{i}, 0 \leq i<N$ such that:

$$
\begin{equation*}
\left\langle\psi_{\gamma}, P_{i}\right\rangle=0 \tag{6}
\end{equation*}
$$

We now proceed to use the lifting scheme in order to obtain wavelets with one vanishing moment. We
start with the wavelets proposed by Schröder and Sweldens [9] given by

$$
\begin{equation*}
\psi_{j, m}=\varphi_{j+1, m}-s_{j, u, m} \varphi_{j, u}-s_{j, v, m} \varphi_{j, v} \tag{7}
\end{equation*}
$$

That is, the wavelet on a midpoint of an edge is defined as a linear combination of the scaling function on the midpoint $(j+1, m)$ and two scaling functions defined on a coarser resolution computed on the vertices $(u, v)$. The weights $s_{j, *, m}$ are chosen in such a way that the resulting wavelet has null integral

$$
\begin{align*}
\int_{V} \psi_{j, m} d V= & \int_{V} \varphi_{j+1, m} d V-s_{j, u, m} \int_{V} \varphi_{j, u} d V \\
& -s_{j, v, m} \int_{V} \varphi_{j, v} d V \tag{8}
\end{align*}
$$

Then,

$$
\begin{equation*}
s_{j, *, m}=\frac{\int_{V} \varphi_{j+1, m} d v}{2 \int_{V} \varphi_{j, *}}=\frac{I_{j+1, m}}{2 I_{j+1, *}} \tag{9}
\end{equation*}
$$

The integral $\int_{V} \varphi d V$ can be approximated at the finest resolution level using a quadrature method and then recursively computed on the coarser levels using the refinement relationships. Then it is possible to express $\psi_{j, m}$ as follows

$$
\begin{equation*}
\psi_{j, m}=\varphi_{j+1, m}-\frac{I_{j+1, m}}{2 I_{j+1, *}} \varphi_{j, k} \tag{10}
\end{equation*}
$$

so the analysis and synthesis algorithms for computing the fast wavelet transform that give the lifted set of coefficients are the following:

## Analysis

A1. Compute the detail coefficients

$$
\begin{equation*}
\forall m \in \mathcal{M}_{j}, d_{j, m} \doteq c_{j+1, m}-\frac{1}{2}\left(c_{j+1, u}+c_{j+1, v}\right) \tag{11}
\end{equation*}
$$

A2. Calculate the coefficients $c_{j, k}$

$$
\begin{gather*}
\forall k \in \mathcal{K}_{j}, \\
\forall m \in \mathcal{M}_{j, k}=c_{j+1, k}  \tag{12}\\
\forall u, v \in \mathcal{K}_{j},
\end{gather*} \quad\left\{\begin{array}{l}
c_{j, u}=c_{j, u}+s_{j, u, m} d_{j, m} \\
c_{j, v}=c_{j, v}+s_{j, v, m} d_{j, m}
\end{array}\right.
$$

## Synthesis

S1. Compute the $c_{j+1, k}$

$$
\begin{gather*}
\forall k \in \mathcal{K}_{j}, \\
\forall m \in \mathcal{M}_{j},  \tag{13}\\
\forall u, v \in \mathcal{K}_{j},
\end{gather*} \quad\left\{\begin{array}{l}
c_{j+1, k}=c_{j, k} \\
c_{j, u}=c_{j, u}-s_{j, u, m} d_{j, m} \\
c_{j, v}=c_{j, v}-s_{j, v, m} d_{j, m}
\end{array}\right.
$$

S2. Use the $c_{j+1, k}$ already computed in order to compute the $c_{j+1, m}$

$$
\begin{align*}
\forall m \in \mathcal{M}_{j}, \quad c_{j+1, m} & \doteq \\
d_{j, m} & +\frac{1}{2}\left(c_{j+1, u}+c_{j+1, v}\right) . \tag{14}
\end{align*}
$$

## 3. HAAR-LIKE WAVELETS

In this section we build a wavelets basis on the tetrahedron following the process given by Sweldens and Girardi [3]. Throughout this section, $(T, \Sigma, \mu)$ is the measure space in which $T$ is a tetrahedron with volume $V, \Sigma$ is the $\sigma$-algebra of all tetrahedra generated by Beys subdivision method [1] and $\mu$ is the Lebesgue measure. With this procedure we shall obtain Haar-like wavelets on the measure space $(T, \Sigma, \mu)$ that form an unconditional basis for $L^{p}(T, \Sigma, \mu), 1<p<\infty$. The concepts of tree, forest, generation and root used in this section are defined in [3].
Let $\tau$ be the tree such that $\left\{T_{\alpha}: \alpha \in \tau\right\}$ is the set of all subtetrahedra obtained by the subdivision method we have considered. The collection $\left\{T_{\alpha}: \alpha \in \tau\right\}$ is a nested partition of the tetrahedron $T$ and the tree $\tau$ has only one root element $\rho$ for which $T_{\rho}=T$. As the initial tetrahedron has volume $V$, a subtetrahedron $T_{\alpha}$ of the $n$-th generation has volume $V / 8^{n}$. The wavelet basic building blocks are the scaling functions $\left\{\varphi_{\alpha}: \alpha \in \tau\right\}$, defined by:

$$
\varphi_{\alpha}=\left(\frac{V}{8^{n}}\right)^{-1 / p} \chi\left(T_{\alpha}\right)
$$

being $\chi\left(T_{\alpha}\right)$ the characteristic function of $T_{\alpha}$.
The wavelets are indexed by a set $G$ which consists of a set $G^{*}$ along with the index $\rho \in \tau$ for which $T_{\rho}=T$, being $G^{*}$ the set $G^{*}=\cup_{\alpha \in \tau} G(\alpha)$, where $G(\alpha)$ contains seven elements $\beta_{i}, i=1, \ldots, 8, \beta_{i}<$ $\beta_{i+1}$ and is constructed by building a logarithmic tree $\tilde{\tau}$ amongst the children of $\alpha$.
Then $G(\alpha)=\{(\alpha, \varsigma) \in\{\alpha\} \times \tilde{\tau}: \# C(\varsigma)=2\}$, where $C(\varsigma)$ are the children of $\varsigma$. The elements $\varsigma \in \tilde{\tau}$ are :

$$
\begin{array}{ll}
\varsigma^{1}=\alpha, & \varsigma^{2}=\left\{\beta_{1}, \beta_{2}, \beta_{3}, \beta_{4}\right\}, \\
\varsigma^{3}=\left\{\beta_{5}, \beta_{6}, \beta_{7}, \beta_{8}\right\}, & \varsigma^{4}=\left\{\beta_{1}, \beta_{2}\right\} \\
\varsigma^{5}=\left\{\beta_{3}, \beta_{4}\right\} & \varsigma^{6}=\left\{\beta_{5}, \beta_{6}\right\} \\
\varsigma^{7}=\left\{\beta_{7}, \beta_{8}\right\} . &
\end{array}
$$

As we consider a logarithmic tree, $C(\varsigma)=2, \forall \varsigma \in \tilde{\tau}$. The wavelets $\psi_{\gamma^{i}}$ generated by the elements $\gamma^{i}=$ $\left(\alpha, \varsigma^{i}\right) \in G(\alpha), i=1, \ldots, 7$, where $\varsigma_{1}^{i}$ and $\varsigma_{2}^{i}$ are the children of $\varsigma^{i}$, are defined as follows:

$$
\begin{array}{r}
\psi_{\gamma^{1}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{1}}\right)-\chi\left(N_{\gamma^{1}}\right)\right) \frac{(4 V)^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}}, \\
\left\{\begin{array}{c}
P_{\gamma^{1}}=\cup_{j \in \zeta_{1}^{1}} T_{\beta_{j}} \\
N \gamma^{1}=\cup_{j \in \zeta_{2}^{1}} T_{\beta_{j}}
\end{array}\right. \\
\psi_{\gamma^{2}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{2}}\right)-\chi\left(N_{\gamma^{2}}\right)\right) \frac{(2 V)^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}}
\end{array}\left\{\begin{array}{c}
P_{\gamma 2}=\cup_{j \in \zeta_{1}^{2}} T_{\beta_{j}} \\
N \gamma^{2}=\cup_{j \in \zeta_{2}^{2}} T_{\beta_{j}}
\end{array}\right\} \begin{aligned}
& \left\{\begin{array}{l}
P_{\gamma 3}=\cup_{j \in \zeta_{1}^{3}} T_{\beta_{j}} \\
N \gamma^{3}=\cup_{j \in \zeta_{2}^{3}} T_{\beta_{j}}
\end{array}\right.
\end{aligned}
$$

$$
\begin{aligned}
& \psi_{\gamma^{4}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{4}}\right)-\chi\left(N_{\gamma^{4}}\right) \frac{V^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}},\right. \\
& \left\{\begin{array}{c}
P_{\gamma 4}=\cup_{j \in \zeta_{1}^{4}} T_{\beta_{j}} \\
N \gamma^{4}=\cup_{j \in \zeta_{2}^{4}} T_{\beta_{j}}
\end{array}\right. \\
& \psi_{\gamma^{5}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{5}}\right)-\chi\left(N_{\gamma^{5}}\right)\right) \frac{V^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}}, \\
& \left\{\begin{array}{c}
P_{\gamma 5}=\cup_{j \in \zeta_{1}^{5}} T_{\beta_{j}} \\
N \gamma^{5}=\cup_{j \in \zeta_{2}^{5}} T_{\beta_{j}}
\end{array}\right. \\
& \psi_{\gamma^{6}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{6}}\right)-\chi\left(N_{\gamma^{6}}\right)\right) \frac{V^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}}, \\
& \left\{\begin{array}{c}
P_{\gamma^{6}}=\cup_{j \in \zeta_{1}^{6}} T_{\beta_{j}} \\
N \gamma^{6}=\cup_{j \in \zeta_{2}^{6}} T_{\beta_{j}}
\end{array}\right. \\
& \psi_{\gamma^{7}}=2^{-1 / p}\left(\chi\left(P_{\gamma^{7}}\right)-\chi\left(N_{\gamma^{7}}\right)\right) \frac{V^{-1 / p}}{\left(8^{n+1}\right)^{-1 / p}}, \\
& \left\{\begin{aligned}
P_{\gamma^{7}} & =\cup_{j \in \zeta_{1}^{7}} T_{\beta_{j}} \\
N \gamma^{7} & =\cup_{j \in \zeta_{2}^{7}} T_{\beta_{j}}
\end{aligned}\right.
\end{aligned}
$$

Graphically, the signs of the wavelets thus defined can be easily visualized in the following scheme. Each rectangle has eight squares and each square represents one of the sons of $T_{\alpha}$ :

| + | + |  |
| :--- | :--- | :---: |
| - | - |  |
| 0 | 0 |  |
| 0 | 0 |  |
| $\psi_{\gamma^{2}}$ |  |  |


| 0 | 0 |
| :---: | :---: |
| 0 | 0 |
| + | + |
| - | - |
| $\psi_{\gamma^{3}}$ |  |


| + | - |
| :---: | :---: |
| 0 | 0 |
| 0 | 0 |
| 0 | 0 |
| $\psi_{\gamma^{4}}$ |  |


| 0 | 0 |
| :---: | :---: |
| + | - |
| 0 | 0 |
| 0 | 0 |
| $\psi_{\gamma^{5}}$ |  |


| 0 | 0 |
| :---: | :---: |
| 0 | 0 |
| + | - |
| 0 | 0 |
| $\psi_{\gamma^{6}}$ |  |


| 0 | 0 |  |
| :---: | :---: | :---: |
| 0 | 0 |  |
| 0 | 0 |  |
| + | - |  |
| $\psi_{\gamma^{7}}$ |  |  |


| + | + |
| :---: | :---: |
| + | + |
| + | + |
| + | + |
| $\psi_{\rho}$ |  |

As the tree has a root element $\rho=T$, the wavelet $\psi_{\rho}$ corresponding to that element is defined by:

$$
\psi_{\rho}=(V)^{-1 / p} \chi(T)
$$

The generation function defined on $G^{*}$ is $g((\alpha, \zeta))=g(\alpha)$.
Finally we take:

$$
\Psi=\left\{\psi_{\gamma}: \gamma \in G\right\}
$$

and $\Psi$ has the following properties:

1. $\Psi$ is normalized, i.e. : $\|\Psi\|_{p}=1, \forall \gamma \in G$.
2. $\int_{T} \psi_{\gamma} d \mu=0, \forall \gamma \in G^{*}$.
3. If $\gamma, \gamma^{\prime} \in G, \int_{T} \psi_{\gamma} \psi_{\gamma^{\prime}} d \mu=0$.
4. $\Psi$ is an unconditional normalized basis for $L^{p}(T, \Sigma, \mu)$.
If $\alpha \in \tau$, then:
$\operatorname{span}\left\{\varphi_{\beta}: \beta \in C_{l}(\alpha)\right\}=\operatorname{span}\left\{\varphi_{\alpha}, \psi_{\gamma}: \gamma \in G(\alpha)\right\}$,
and this extends over several generations since $\forall i \in$ $\mathbb{N}$ is

$$
\begin{aligned}
\operatorname{span}\left\{\varphi_{\beta}: \beta \in C_{l}^{i}(\alpha)\right\}= & \operatorname{span}\left\{\varphi_{\alpha}, \psi_{\gamma}:\right. \\
& \left.\gamma \in \cup_{j=0}^{i-1} G\left(C^{j}(\alpha)\right)\right\} .
\end{aligned}
$$

## Multiresolution analysis

In this section we show how our wavelets, which are a special case of second generation wavelets, fit into the MRA concept. From now on we consider the case $p=2$ for which the basis $\left\{\varphi_{\beta}: \beta \in C_{l}(\alpha)\right\}$ and $\left\{\psi_{\gamma}: \gamma \in G\right\}$ are self duals. So if $f \in L^{2}$,

$$
\begin{equation*}
f=\sum_{\gamma \in G}\left\langle f, \psi_{\gamma}\right\rangle \psi_{\gamma} \tag{15}
\end{equation*}
$$

being the convergence unconditional. The coefficients in the expansion (15) are given by the fast wavelet transform. We must write expressions that relate the basis functions, similar to the two scale relation for wavelets, in order to compute this transform. These are given by $R_{1}$ and $R_{2}$ defined below: (R1) If $\alpha \in \tau$ and $\gamma \in G^{*}$, then:

$$
\varphi_{\alpha}=\sum_{\beta \in C_{l}(\alpha)} \frac{1}{\sqrt{8}} \varphi_{\beta}, \psi_{\gamma}=\sum_{\beta \in S(\gamma)} g_{\gamma, \beta} \varphi_{\beta}
$$

where $S(\gamma)=C_{l}(\alpha)$, if $\gamma \in G(\alpha)$ and the $g_{\gamma, \beta}$ are the following:

$$
\begin{aligned}
& \left\{\begin{array}{c}
g_{\gamma^{1}, \beta_{1}}=g_{\gamma^{1}, \beta_{2}}=g_{\gamma^{1}, \beta_{3}}=g_{\gamma^{1}, \beta_{4}}=\frac{1}{\sqrt{8}}, \\
g_{\gamma^{1}, \beta_{5}}=g_{\gamma^{1}, \beta_{6}}=g_{\gamma^{1}, \beta_{7}}=g_{\gamma^{1}, \beta_{8}}=-\frac{1}{\sqrt{8}} .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma^{2}, \beta_{1}}=g_{\gamma^{2}, \beta_{2}}=\frac{1}{2}, \\
g_{\gamma^{2}, \beta_{3}}=g_{\gamma^{2}, \beta_{4}}=-\frac{1}{2}, \\
g_{\gamma^{2}, \beta_{5}}=g_{\gamma^{2}, \beta_{6}}=g_{\gamma^{2}, \beta_{7}}=g_{\gamma^{2}, \beta_{8}}=0 .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma^{3}, \beta_{1}}=g_{\gamma^{3}, \beta_{2}}=g_{\gamma^{3}, \beta_{3}}=g_{\gamma^{3}, \beta_{4}}=0, \\
g_{\gamma^{3}, \beta_{5}}=g_{\gamma^{3}, \beta_{6}}=\frac{1}{2}, \\
g_{\gamma^{3}, \beta_{7}}=g_{\gamma^{3}, \beta_{8}}=-\frac{1}{2} .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma^{4}, \beta_{1}}=\frac{1}{\sqrt{2}}, \\
g_{\gamma^{4}, \beta_{2}}=-\frac{1}{\sqrt{2}}, \\
g_{\gamma^{4}, \beta_{3}}=g_{\gamma^{4}, \beta_{4}}=g_{\gamma^{4}, \beta_{5}}=g_{\gamma^{4}, \beta_{6}}=g_{\gamma^{4}, \beta_{7}}= \\
=g_{\gamma^{4}, \beta_{8}}=0 .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma 5, \beta_{1}}=g_{\gamma^{5}, \beta_{2}}=g_{\gamma^{5}, \beta_{5}}=g_{\gamma^{5}, \beta_{6}}=g_{\gamma^{5}, \beta_{7}}= \\
=g_{\gamma^{5}, \beta_{8}}=0 \\
g_{\gamma^{5}, \beta_{3}}=\frac{1}{\sqrt{2}}, \\
g_{\gamma^{5}, \beta_{4}}=-\frac{1}{\sqrt{2}} .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma^{6}, \beta_{1}}=g_{\gamma^{6}, \beta_{2}}=g_{\gamma^{6}, \beta_{3}}=g_{\gamma^{6}, \beta_{4}}=g_{\gamma^{6}, \beta_{7}}= \\
=g_{\gamma^{6}, \beta_{8}}=0, \\
g_{\gamma^{6}, \beta_{5}}=\frac{1}{\sqrt{2}}, \\
g_{\gamma^{6}, \beta_{6}}=-\frac{1}{\sqrt{2}} .
\end{array}\right. \\
& \left\{\begin{array}{l}
g_{\gamma^{7}, \beta_{1}}=g_{\gamma^{7}, \beta_{2}}=g_{\gamma^{7}, \beta_{3}}=g_{\gamma^{7}, \beta_{4}}=g_{\gamma^{7}, \beta_{5}}= \\
=g_{\gamma^{7}, \beta_{6}}=0, \\
g_{\gamma^{7}, \beta_{7}}=\frac{1}{\sqrt{2}}, \\
g_{\gamma^{7}, \beta_{8}}=-\frac{1}{\sqrt{2}} .
\end{array}\right.
\end{aligned}
$$

(R2) For

$$
\beta \neq \rho, \varphi_{\beta}=\frac{1}{\sqrt{8}} \varphi_{p(\beta)}+\sum_{\gamma \in S^{*}(\beta)} g_{\gamma, \beta} \psi_{\gamma}
$$

where: $S^{*}(\beta)=G(\alpha)$ if $\beta \in C_{l}(\alpha)$.
For $k \in g(\tau)$, let $G_{k}=\left\{\gamma \in G^{*}: g(\gamma)=k\right\}$ and consider the subspaces $V_{k}$ and $W_{k}$ of $L^{2}$, where:

$$
\begin{aligned}
& V_{k}=\operatorname{clos} \operatorname{span}\left\{\varphi_{\beta}: \beta \in \mathcal{F}_{k}^{*}\right\} \\
& W_{k}=\mathrm{clos} \operatorname{span}\left\{\psi_{\gamma}: \gamma \in G_{k}\right\}
\end{aligned}
$$

By viewing $\mathcal{F}_{k-1}^{*} \cup \mathcal{F}_{k}^{*}$ as a two generation tree, it follows that:

$$
V_{k}=V_{k-1}+W_{k-1}
$$

and then $V_{k}$ has another basis:

$$
\left\{\varphi_{\alpha}: \alpha \in \mathcal{F}_{k-1}^{*}\right\} \cup\left\{\psi_{\gamma}: \gamma \in G_{k-1}\right\}
$$

So a function $f \in V_{k}$ has two representations as:

$$
f=\sum_{\beta \in \mathcal{F}_{k}^{*}} a_{\beta} \varphi_{\beta}
$$

as well as:

$$
f=\sum_{\alpha \in \mathcal{F}_{k-1}^{*}} a_{\alpha} \varphi_{\alpha}+\sum_{\gamma \in G_{k-1}} c_{\gamma} \psi_{\gamma}
$$

where:

$$
\begin{gathered}
a_{\alpha}=\sum_{\beta \in C_{l}(\alpha)} \frac{1}{\sqrt{8}} a_{\beta} \quad c_{\gamma}=\sum_{\beta \in S(\gamma)} g_{\gamma, \beta} a_{\beta}, \\
a_{\beta}=\frac{1}{\sqrt{8}} a_{p(\beta)}+\sum_{\gamma \in S^{*}(\beta)} g_{\gamma, \beta} c_{\gamma},
\end{gathered}
$$

being $g(\beta)=k$ and $g(\alpha)=g(\gamma)=k-1$.

## Example

To construct the wavelets it is necessary to consider the set of children of $T_{\alpha}$, named $T_{\beta_{i}}, i=1, \ldots, 8$ and order them (see Figure 4) as follows: the bottom ones are numbered in counterclockwise sense followed at last by the top one, and the interior ones are also numbered in counterclockwise sense beginning with the tetrahedron next to $T_{\beta_{1}}$.


Figure 4: Numbered subtetrahedra

In order to show how the defined wavelets are used, we have first chosen the scaling functions approximation to represent a density function on a tetrahedon. We suppose that the data of this density
function correspond to the space $V_{3}$ and then we mapped this density on a grey colourmap whose range is between zero and one: the lowest density corresponds to the white and the highest to the black.
In Figure 5, we show the density function over a tetrahedron using the scaling functions and the wavelets at different resolutions. As in the previous example, the grey subtetrahedra represent an approximation of the density using the scaling functions while the coloured ones represent the value of the different coefficients in the wavelet decomposition. We can distinguish seven colours, each of them representing one of the details coefficients. When a coefficient is zero, the corresponding subtetrahedron is white. If two subtetrahedra have the same colour, the darker one indicates highest absolute value for its coefficient. Figure 5 shows, from top to bottom and from left to right, can see:
a) the given density function defined on $V_{3}$,
b) the density function on $V_{2}$ and the details on $W_{2}$,
c) the density function on $V_{1}$ and the details on $W_{2}$ y $W_{1}$,
d) the density function on $V_{0}$ and the details on $W_{0}$, $W_{1}$ and $W_{2}$.


Figure 5: Three consecutive steps in the multiresolution decomposition of the density function

## Lifting the Haar like wavelets

The basis functions constructed so far have only one vanishing moment but the MRA they generate is adequate for applying the lifting scheme [12]. In this section we build a new MRA in which the wavelets will have more vanishing moments. According to the lifting scheme, the new wavelets are:

$$
\begin{equation*}
\psi_{\gamma^{i}}^{l i f}=\psi_{\gamma^{i}}-\sum_{\alpha \in \mathcal{F}_{n-1}^{*}} s_{\alpha} \varphi_{\alpha} \tag{16}
\end{equation*}
$$

where $\gamma^{i}$ belongs to the $(n-1)-t h$ generation and $\alpha$ belongs to the $(n-1) t h$-generation. The coefficients $s_{\alpha}$ can be chosen so that the $\psi_{\gamma^{i}}^{l i f}$ have more
than one vanishing moment. Considering the tetrahedron with vertices in $(1,0,0),(0,1,0),(0,0,1)$ named $T_{0}$, we construct wavelets that kill the following polynomials:

$$
\begin{equation*}
x, \quad x+y+5, \quad x+z+5, \quad y, \quad z, \quad y+z, \quad x y, \quad x y z, \tag{17}
\end{equation*}
$$

leading to the equations:

$$
\begin{equation*}
\left\langle\psi_{\gamma^{i}}, P\right\rangle=\sum_{\alpha \in \mathcal{F}_{n-1}^{*}} s_{\alpha}\left\langle\varphi_{\alpha}, P\right\rangle \tag{18}
\end{equation*}
$$

being $P$ each one of the eight polynomials we have chosen. As three of them: $x, \quad x+y+5, \quad x+z+5$ are linearly independent on the tetrahedron $T_{0}$, the new wavelets will have three vanishing moments. We then obtain an $8 \times 8$ singular (but solvable) matrix problem for each $i=1, \ldots, 8$ in the unknowns $s_{\alpha}$. The entries of the linear system are integrals of the chosen polynomials over a tetrahedron specified by its vertices. These integrals were evaluated using barycentric coordinates. Beginning with the wavelet $\psi_{\gamma^{3}}$ and doing one step in the subdivision, we found the following values of $s_{\alpha}$ :

| -0.3103 | 0.0052 | 0.0883 | 0.0849 |
| :---: | :---: | :---: | :---: |
| -0.1476 | 0.0079 | 0.0469 | -0.0411 |
| -0.0742 | -0.0120 | 0.0153 | -0.0019 |
| -0.2369 | -0.0147 | 0.0567 | 0.0357 |
| 0.4080 | -0.0436 | -0.1211 | -0.0674 |
| 0.1233 | 0.1356 | 0.0167 | 0.0185 |
| 0.3018 | 0.0558 | -0.0654 | -0.0466 |
| -0.0640 | -0.1343 | -0.0375 | 0.0180 |

Table 1: Coefficients $s_{\alpha}$ of the lifted wavelets

| -0.1658 | -0.0198 | -0.0187 |
| :---: | :---: | :---: |
| -0.0678 | -0.0280 | -0.0277 |
| 0.0203 | -0.0149 | -0.0140 |
| -0.1661 | -0.0066 | -0.0050 |
| 0.2524 | 0.0325 | 0.0191 |
| 0.0252 | 0.0284 | 0.0411 |
| 0.1333 | 0.0299 | 0.0397 |
| -0.0314 | -0.0215 | -0.0345 |

Table 2: Coefficients $s_{\alpha}$ of the lifted wavelets
Each column of Tables 1 and 2 corresponds to the coefficients $s_{\alpha}$ of one of the wavelets, being the first column the coefficients that corresponds to $\psi_{\gamma^{1}}$ and so on.

## 4. CONCLUSIONS AND FUTURE WORK

Representing objects through their closure is a powerful mathematical modeling tool but this scheme has little similarity with real objects. On the other hand, modeling of solids has been made possible by constructive solid geometry (CSG). Though nowadays, both representations play an important role for modeling objects, these methods aren't good enough for modeling many real ones. Typically,
the volumetric object is represented by a regular 3D grid of volumetric elements (voxels), but the data that represent a given object are sometimes sparse or irregularly designed. These cases call for alternative representations; for example, we could represent the object on a tetrahedrical domain on which its attributes (color or density) are defined. For representing such attributes it is necessary to define bases over tetrahedrical grids. As wavelets have been proved to be a powerful tool for representing general functions and large data sets accurately, we look for such bases in the field of wavelets. In this work we have taken the first step in defining wavelets over geometrical objects which can be partitioned by a net of tetrahedra. This was done by defining a wavelet vertex basis and a Haar-like wavelet basis over a tetrahedron. In both constructions, a generalization of MRA is used and the lifting scheme is applied to obtain more vanishing moments. In principle, it is the explicit nature of the construction which may have practical value, as we have shown in the examples. We believe that many other applications would benefit from them. Now, based on this contribution, we are working on new alternatives for compression of volume models as well as in the extension to more general 3D objects.

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