

NUMERICAL METHOD TO PREDICT VOID FORMATION DURING THE LIQUID COMPOSITE MOLDING PROCESS

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SUMMARY: Void formation during the injection phase of the liquid composite molding process can be explained as a consequence of the non-uniformity of the flow front progression. This is due to the dual porosity within the fiber perform (spacing between the fiber tows is much larger than between the fibers within in a tow) and therefore the best explanation can be provided by a mesolevel analysis, where the characteristic dimension is given by the fiber tow diameter of the order of millimeters. In mesolevel analysis, liquid impregnation along two different scales; inside fiber tows and within the open spaces between the fiber tows must be considered and the coupling between the flow regimes must be addressed. In such cases, it is extremely important to account correctly for the surface tension effects, which can be modeled as capillary pressure applied at the flow front. Numerical implementation of such boundary conditions leads to ill-posing of the problem, in terms of the weak classical as well as stabilized formulation. As a consequence, there is an error in mass conservation accumulated especially along the free flow front. A numerical procedure was formulated and is implemented in an existing Free Boundary Program to reduce this error significantly.

KEYWORDS: void formation, surface tension, capillary pressure, mass conservation, free boundary flow, mesolevel analysis, dual porosity.

INTRODUCTION

Liquid Composite Molding is a composite manufacturing process in which fiber preforms consisting of stitched or woven bundles of fibers, known as fiber tows, are stacked in a closed mold and a polymeric resin is injected to impregnate all the empty spaces between the fibers. Fiber tows are usually millimeters in diameter and consist of bundles of 2000 to 5000 fibers [1]. An important step is to ensure saturation of all the fiber tows and regions in between them in order to avoid voids formation. Due to the dual porosity in woven fiber preforms, resin progression is not uniform, and a transition region where the flow has not yet stabilized and saturated, is formed along the macroscopic flow front. This region is very sensitive to voids formation. The best way to analyze this flow is at the mesolevel, i.e at the scale of fiber tows.

MESOLEVEL ANALYSIS

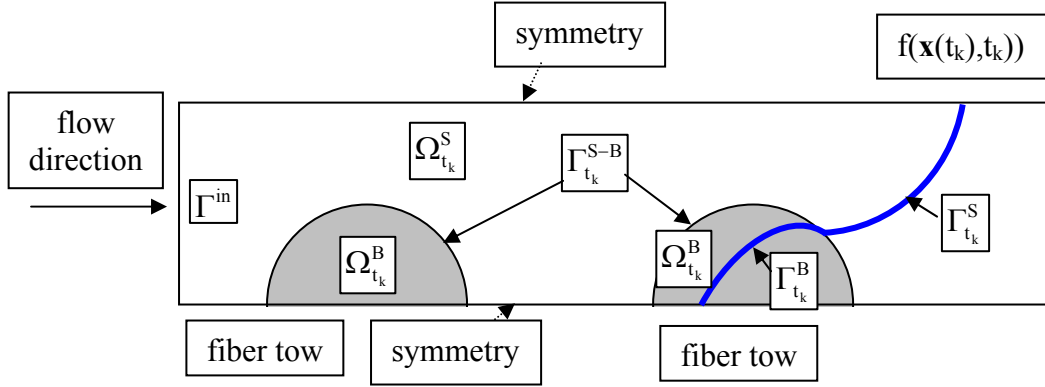


Fig.1 Flow domain, regions and boundaries designation

In mesolevel analysis, liquid flowing along two different scales must be considered. Single scale porous media (fiber tows represented in Fig. 1 by grey half-circles) and open spaces (white spaces) are presented in the same unit cell which will allow one to couple the flow in these two different regimes. Fiber tows have uniformly distributed pores, therefore sharp flow front can be assumed as the resin impregnates. Moreover quasi steady state assumption can be exploited. As the flow is slow, inertia terms can be neglected, implying that one can assume Stokes flow in the inter-tow spaces $\Omega_{t_k}^S$ (white space between Γ^{in} and $\Gamma_{t_k}^S$) and Darcy's flow in saturated intra-tow region $\Omega_{t_k}^B$ which need to be solved at each discretized time t_k . In fact, Darcy's law must be modified to Brinkman's equations, in order to account for viscous stress at the interface between these two regions ($\Gamma_{t_k}^{S-B}$), which rapidly decreases with the distance from $\Gamma_{t_k}^{S-B}$. In summary, the following equations must be satisfied at each time step, t_k :

$$\text{in inter-tow spaces: } \nabla \cdot \mathbf{v} = 0 \text{ and } \nabla p = \mu \Delta \mathbf{v} \quad \text{in } \Omega_{t_k}^S \quad (1)$$

(Stokes equations),

$$\text{in intra-tow spaces: } \nabla \cdot \mathbf{v}^D = 0 \text{ and } \nabla p^f = \mu \Delta \mathbf{v}^D - \mu \mathbf{K}^{-1} \cdot \mathbf{v}^D \quad \text{in } \Omega_{t_k}^B \quad (2)$$

(Brinkman's equations),

where \mathbf{v} is local velocity vector, p is local pressure, μ is resin viscosity and ∇ stands for spatial gradient, $\Delta = \nabla \cdot \nabla$. \mathbf{v}^D is Darcy's velocity vector, i.e. the phase averaged velocity related to the intrinsic phase average \mathbf{v}^f by $\mathbf{v}^D = \phi_t \mathbf{v}^f$, where ϕ_t is intra-tow porosity. p^f stands for intrinsic phase average of the local pressure and \mathbf{K} is absolute permeability tensor.

If fibers inside the tows are rigid, impermeable and stationary, the following boundary conditions, under usual omission of the air pressure, must be fulfilled at the free front:

$$\boldsymbol{\sigma}_t^v = \mathbf{0} \text{ and } (\boldsymbol{\sigma}^v \cdot \mathbf{n}) \cdot \mathbf{n} - p = \sigma_n^v - p \approx -p = -p_c = -2\gamma H \quad \text{at } \Gamma_{t_k}^S, \quad (3)$$

$$p^f = P_c \quad \text{at } \Gamma_{t_k}^B. \quad (4)$$

Here $\boldsymbol{\sigma}^v$ is local viscous stress, $\boldsymbol{\sigma}_t^v$ tangential vector of the viscous stress vector, σ_n^v normal component of the viscous stress and \mathbf{n} the outer unit normal vector to the free front in Stokes region $\Gamma_{t_k}^S$. p_c and P_c stand for local and global (homogenized) capillary pressure, γ is resin

surface tension and H is mean curvature. Progression of the free boundary can be determined according to:

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \mathbf{v} \cdot \nabla f = 0 \quad \text{at } \Gamma_{t_k}^S, \quad (5)$$

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \frac{\mathbf{v}^D}{\phi_t} \cdot \nabla f = 0 \quad \text{at } \Gamma_{t_k}^B, \quad (6)$$

where $f(\mathbf{x}(t),t)=0$ is implicit function describing the moving sharp flow front (dark line in Fig. 1), \mathbf{x} is spatial variable and t is time. Other boundary conditions such as symmetry, periodicity and inlet conditions at Γ^{in} are related to the particular problem under consideration.

We have formulated the governing equations for free boundary flows in intra- as well as inter-tow spaces and developed numerical techniques to address the movement of the flow at the mesolevel scale which we call the Free Boundary Program (FBP). Numerical simulations can track the advancement of the resin front promoted by both hydrodynamic pressure gradient and capillary action [2-5]. In such simulations it is extremely important to account correctly for the surface tension effects, which can be modeled as capillary pressure applied at the flow front. Unfortunately essential boundary conditions of this kind make the problem ill-posed, in terms of the weak classical as well as stabilized formulation. As a consequence there is an error in mass conservation accumulated especially along the free front. This can affect significantly normal velocities at the free front and distort the next front shape. Due to the explicit integration along the time scale, such errors are irreversible. Several stabilization techniques were implemented in FBP to eliminate this effect [3-5]. In this article we will present more appropriate techniques for stabilization, based on weak formulation of the problem. The methodology implemented in Darcy's region is well-known, although rarely used in real simulations. It is presented e.g. in [6]. The recalculated outlet velocities have superior convergence properties [7]. In Stokes region the correction of the outlet velocities we are presenting have not yet been published to our knowledge. Both methodologies are implemented in FBP.

FLOW FRONT RECALCULATION AND CORRECTION

Following [6], outlet normal velocities can be recalculated in Darcy's region according to:

$$\left(q^h, \tilde{v}_n^{D,h} \right)_{\Gamma_k^B} = B(q^h, p^{f,h}) - L(q^h) \quad \forall q^h \in \hat{P}^h. \quad (7)$$

B and L represent bi-linear and linear form of the weak formulation, new outlet velocities with superior convergence properties are $\tilde{v}_n^{D,h}$, q^h is trial pressure and $p^{f,h}$ is the solution already obtained in a standard way. Trial pressures space, \hat{P}^h , consists now solely from functions originally omitted because of the pressure essential boundary condition. Efficiency of this technique can be shown on a simple example:

$$\begin{aligned} \Delta u &= 1 \quad \text{in } [-1,1] \times [-1,1], \\ u &= 0 \quad \text{at the boundary } \partial([-1,1] \times [-1,1]). \end{aligned} \quad (8)$$

Numerical results were obtained by thermal analysis in ANSYS (u thus represent temperature). In Fig. 2 results are compared on one of the straight boundaries. Mesh of quad elements was used as 6×6 (tf 6), 10×10 (tf 10) e 200×200 (tf 200). Normal heat flux tf 200 for 200×200 mesh can be already assumed as exact. Recalculated normal flux on 6×6 and 10×10 meshes is designated as "tf-cal 6" and "tf-cal 10". It is seen that the coincidence with the exact values is just excellent.

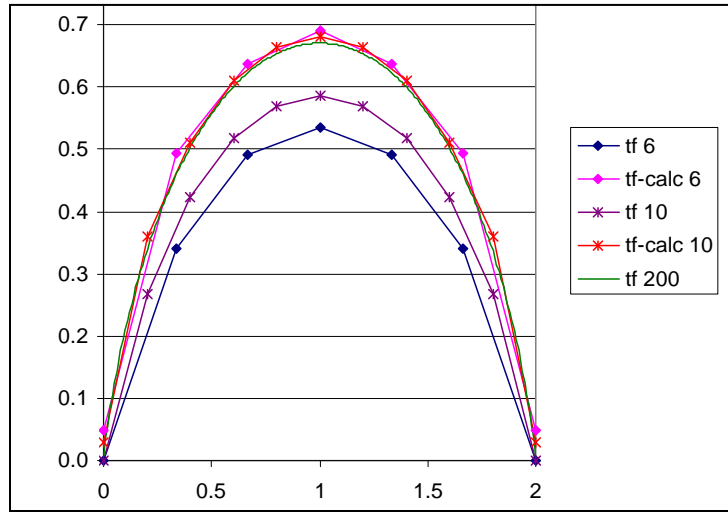


Fig. 2 Normal thermal fluxes of the problem specified in (8). Notice that recalculated fluxes on 6x6 and 10x10 meshes (tf-calc 6 and tf-calc 10) do as good a job as a mesh of 200x200 (tf 200)

In the Stokes region the following scheme is used:

$$\begin{aligned} (\mathbf{q}^h, \mathbf{w}_n^h)_{\Gamma_{ik}^s} &= (\mathbf{q}^h, \nabla \cdot \mathbf{v}^h) \quad \forall \mathbf{q}^h \in \hat{\mathbf{P}}^h, \\ \tilde{\mathbf{v}}_n^h &= \mathbf{v}_n^h - \mathbf{w}_n^h, \end{aligned} \tag{9}$$

where \mathbf{w}_n^h is an auxiliary value of the normal velocity, used to correct the originally obtained normal velocities, \mathbf{v}_n^h . In this case incompressibility condition is completely separated from the weak formulation. Efficiency was verified directly on ANSYS fluid element FLUID 141, where pressure and velocities are nodal variables. Test problem for unit viscosity and mass free fluid is specified in Fig. 3a) and results are shown in Fig. 3b).

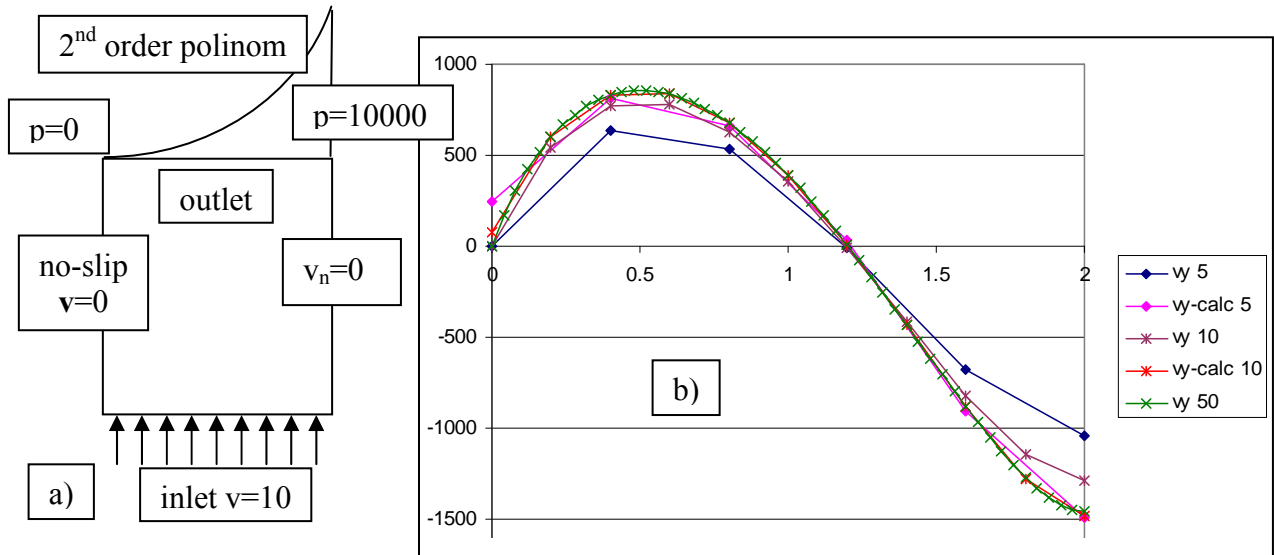


Fig. 3 (a) Fluid problem definition, (b) original values v_y 5, v_y 10 and v_y 50 on 5x5, 10x10 and 50x50 quad meshes and recalculated v_y -calc 5 and v_y -calc 10 outlet normal velocities

Also here the recalculated outlet normal velocities fit the solution well for the very fine mesh. In this test problem pressure does not correspond to the capillary pressure, because the aim was only to test the efficiency of such methodology.

CONCLUSION

Presented stabilization techniques are very efficient as shown in the simple test examples. They permit calculation of frontal normal velocities with sufficient precision even for coarse meshes. They are included in the post-processing part of FBP. Their implementation ensures better mass conservation at the global as well as the local level. It makes it possible to obtain a front shape that is not only more exact but also smoother. The computational time is reduced as coarser meshes can be used to obtain stable and accurate answers and it also allows one to step through larger time steps during the impregnation process.

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