

Nuanced Robustness Analysis with Limited Information

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Abstract

This paper presents a nuanced robustness analysis for structures when only limited information is available. A new methodology based on fuzzy set theory is proposed to cope with scarce information as a major problem in the performance assessment of existing structures. The developed robustness measure provides information on the relationship between structural robustness and the magnitude of uncertainty in the damage of the structure. This feature is enabled through a nuanced consideration of imprecision in the damage assessment via alpha-level discretization. An entropy-based robustness measure is formulated as a function of imprecision in the damage state. On this basis different design solutions can be compared, in a one-swoop analysis, with respect to their robustness for different magnitudes of damage. This approach can, further, be used to assess effort for inspection versus gain in precision of the predicted structural performance. The development is of a general nature. Herein, it is elucidated in the context of a typical offshore en-

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gineering problem in order to demonstrate its application in practical cases. Fixed offshore platforms with different brace configurations are compared in view of robustness with respect to damage from corrosion.

Keywords: Robustness assessment; Imprecision; Entropy measure; Fuzziness; Alpha-level discretization; Marine corrosion; Fuzzy modeling

1. Introduction

2 A nuanced robustness assessment is developed to compare structural de-
3 sign solutions regarding their performance in dependence on the magnitude
4 of uncertainty in the assessed damage of the structures. To address the partic-
5 ular relevance of the development to current industrial challenges, we focus
6 on offshore structures under only vaguely known corrosion damage. In this
7 context, robustness is a measure to assess a jacket structure's ability to sus-
8 tain damage with a limited loss of ultimate capacity and, therefore, reliability
9 [1]. A "robust" structure has inherent redundancies in terms of alternative
10 load paths that allow the structure to withstand global damage caused by
11 various events such as ship impact, extreme storms, explosions, etc. For less
12 robust structures, however, a small damage event may significantly dimin-
13 ish the platform's global capacity resulting in a high-risk situation which
14 requires immediate response such as platform de-manning, platform shut-
15 down, or emergency repair. Robustness consideration in this context usually
16 aims to mitigate the risk from disproportionate failure or progressive collapse
17 due to damage caused by extreme loads or accidental loads. In the litera-
18 ture, robustness of fixed offshore platforms is usually evaluated through the
19 ultimate strength analysis of structures in both intact and damaged states,

20 which leads to a number of deterministic performance measures using the
21 concept of reserve strength and residual strength, see [2]. The prescribed
22 damage scenarios are frequently associated with removal of one critical mem-
23 ber or several members in the intact state, see [3]. However, there are other
24 sources of damage that, in contrast to damage suddenly provoked by ac-
25 cidental actions, arise gradually in time from aging of structures and may
26 also involve disproportionate effects, including marine corrosion, see [4]. Be-
27 sides the deterministic performance measures, the inevitable uncertainty in
28 engineering practice has led to the development of probabilistic robustness
29 measures based on reliability and risk analysis of structures, see [5, 6, 7]. A
30 brief review of these measures is given in Section 2.

31 Robustness can also be understood as a structure's capacity to withstand
32 the normal fluctuations of environmental conditions without noticeable ef-
33 fects on its serviceability. In this context, robustness denotes a high degree
34 of independence between the uncertainty of structural parameters and the
35 associated uncertainty in structural responses. Assessments of this type of
36 robustness are devoted to obtaining global statements about the degree of
37 structural response variation with respect to input fluctuations at once. Com-
38 monly, all uncertain parameters are described as random variables, which
39 enables the application of probabilistic measures to assess structural robust-
40 ness. As pertinent developments in robustness assessment in this context rely
41 heavily on probabilistic models, a proper treatment of uncertainty is of vital
42 importance for this point of view in understanding robustness. This includes
43 the characterization of the deterioration of structural strength due to marine
44 corrosion, which has adverse effects on the safety of offshore structures. The

45 corrosion effects on the reliability of offshore structures has been studied in
46 [8] where the probabilistic corrosion model from [9] for mild steel immersed
47 in seawater was adopted to estimate the uncertainty in the corrosion depth
48 for a relatively short period.

49 In engineering applications, the knowledge about the fluctuations of the
50 structural parameters can be quite limited so that a clear probabilistic spec-
51 ification of uncertainty can be problematic. This is associated with rare and
52 imprecise data. Examples are uncertain quantities for which mere bounds or
53 linguistic expressions are known. For this type of information, alternative,
54 non-probabilistic and mixed models provide reasonable properties [10]. Mea-
55 sures for the associated information content are available [11]. The usefulness
56 and capabilities of these models and approaches, such as interval analysis,
57 fuzzy set theory, evidence theory, imprecise probabilities and fuzzy random
58 variables, have already been demonstrated in the solution of practical prob-
59 lems in civil and mechanical engineering [12, 8, 13, 14]. For the envisaged
60 development the concept of fuzziness is selected to cater for the subjective
61 character of the assessment of deterioration due to imprecise marine corro-
62 sion. This selection is motivated by the growing demand for quick structural
63 performance assessments based on quite limited information from coarse in-
64 spections without detailed measurements as quantification basis. In such
65 cases, the available information does not provide a proper basis for a prob-
66 abilistic modeling but can still be sufficient to derive reasonable decisions
67 when it is coarsely translated into effects on structural performance.

68 In this paper, we propose a nuanced robustness assessment based on fuzzy
69 set theory and an assessment of fuzziness using an analog to SHANNON's en-

70 tropy [15]. We tap on the robustness measure proposed in [16] and expand
71 the concept from assessing robustness with a static number to the formula-
72 tion of a robustness function depending on the magnitude of uncertainty in
73 the structural conditions. This function enables the exploration of depen-
74 dencies between structural robustness and the magnitude of uncertainty in
75 the structural damage, which opens a new kind of insight into the structural
76 problem and may facilitate a trade-off assessment for inspection effort versus
77 gain in confidence for performance, safety and robustness predictions. The
78 developments are elucidated by means of robustness assessment of aging off-
79 shore structures under marine corrosion with reference to the data provided
80 in [17]. In the sequel, robustness measures from the literature are reviewed in
81 Section 2. Section 3 is devoted to the development of the proposed nuanced
82 robustness assessment. The usefulness of the proposed method is demon-
83 strated in Section 4 by way of investigations of fixed offshore platforms with
84 different brace configurations.

85 **2. Review of Robustness Measures**

86 *2.1. Deterministic performance measures*

87 Robustness is a measure to assess a platform's ability to sustain damage
88 caused by extreme loads or accidental loads without disproportionate failure
89 with respect to the causes of the damage itself. According to this under-
90 standing of structural robustness, deterministic performance measures are
91 developed through comparing the structural performance in both intact and
92 damaged states based on ultimate strength analysis. For the investigated
93 frame structures, the ultimate strength depends on the nonlinear response

94 of components of the frame and the nonlinear structural interaction between
 95 components through plastic deformation and load redistribution. The frames
 96 with different bracing configurations have different overall structural perfor-
 97 mance, usually described as “brittle” or “ductile” behavior. The concept
 98 of reserve strength and residual strength can be used to evaluate structural
 99 robustness associated with the ultimate conditions. The following three de-
 100 terministic performance measures have been tested for a range of structural
 101 frames in [2].

102 Reserve strength can reflect the ability of an intact structure to sustain
 103 loads in excess of the design value. The Reserve Strength Ratio (RSR) is
 104 defined as

$$\text{RSR} = \frac{\text{ultimate resistance of intact structure}}{\text{design environmental load}}. \quad (1)$$

105 Similarly, the Damage Strength Ratio (DSR) is defined to measure the ability
 106 of a damaged structure to sustain loads in excess of the design value,

$$\text{DSR} = \frac{\text{ultimate resistance of damaged structure}}{\text{design environmental load}}. \quad (2)$$

107 The residual strength reflects the ability of having alternative load paths to
 108 carry loads shed from damaged members (i.e. redundancy). The Residual
 109 Resistance Factor (RRF) is defined as

$$\text{RRF} = \frac{\text{ultimate resistance of damaged structure}}{\text{ultimate resistance of intact structure}}. \quad (3)$$

110 In addition, because the value of the residual strength corresponds to a par-
 111 ticular displacement and different values may be achieved if the load is in-
 112 creased further, the following non-dimensional measure R_{twice} can be utilized
 113 when comparing structures with different brace configurations,

$$R_{twice} = \frac{\text{environmental load at twice the ultimate deflection}}{\text{environmental load at ultimate deflection}}. \quad (4)$$

114 As previously pointed out that damage could also arise gradually in time
115 from aging of structures, a general approach is presented in [18] to formulate
116 a measure of time-variant structural robustness of concrete structures sub-
117 jected to diffusive attacks from environmental aggressive agents based on the
118 ultimate strength analysis. The amount of local damage is firstly obtained at
119 the member level by means of a dimensionless damage index $0 \leq \delta \leq 1$ (for
120 uniform corrosion c and original material thickness d , $\delta = \frac{c}{d}$) associated with
121 the progressive deterioration of the material properties for steel bars $\delta_s(x, t)$
122 and concrete $\delta_c(x, t)$ at the spatial point x and time instant t . Then a global
123 measure of damage $\Delta(t)$ at the cross-sectional level is evaluated by means of
124 a weighted average of the local damage over the volume of the materials, as
125 follows:

$$\Delta(t) = [1 - \omega(t)]\Delta_c(t) + \omega(t)\Delta_s(t) \quad (5)$$

$$\Delta_c(t) = \frac{\int_{A_c} w_c(x, t)\delta_c(x, t)dx}{\int_{A_c} w_c(x, t)dx} \quad (6)$$

$$\Delta_s(t) = \frac{\sum_m w_{sm}(x, t)\delta_{sm}(x, t)A_{sm}}{\sum_m w_{sm}(x, t)A_{sm}} \quad (7)$$

128 where $\omega(t)$, $w_c(x, t)$, $w_{sm}(x, t)$ are weight functions (see [18]), A_c is the area of
129 the concrete, and the A_{sm} is the area of the m^{th} steel bar. This cross-section
130 formulation is finally extended at the structural level by an integration over
131 all members of the system. By comparing the system performance in the
132 intact state and in a damaged state, the time-variant measure of structural
133 performance $\rho(t)$ is derived as,

$$\rho(t) = \frac{\lambda_c(t)}{\lambda_c(0)} \quad (8)$$

134 where the limit load multiplier $\lambda_c(t)$ corresponds to the ultimate capacity
 135 in a damaged state, and its initial value $\lambda_c(0)$ indicates the ultimate capac-
 136 ity in the intact state. Then, the structural robustness can be evaluated
 137 based on the relationship between $\rho(t)$ and the global damage $\Delta(t)$. In this
 138 approach damage can be defined in any way and gradually. The lambda re-
 139 flects (quantifies) the degree of damage in the load carrying capacity through
 140 the structural analysis indirectly.

141 2.2. Probabilistic robustness measures

142 In order to take account of the unavoidable uncertainties in the environ-
 143 mental loading and structural resistance, probabilistic robustness measures
 144 have been developed based on either reliability analysis or risk assessment.

145 Based on system reliability analysis, the probabilistic measure of redun-
 146 dancy R_β is proposed in [5]

$$R_\beta = \frac{\beta_{\text{intact}}}{\beta_{\text{intact}} - \beta_{\text{damaged}}}, \quad (9)$$

147 where β_{damaged} is the reliability index of the damaged structural system and
 148 β_{intact} is the reliability index of the intact system. Similarly, a probabilistic
 149 measure called “damage factor” of a system was proposed in [7] as

$$R_d = \frac{P_{f,\text{intact}}}{P_{f,\text{damaged}}} \quad (10)$$

150 to assess its capacity to withstand damage without undesirable response.
 151 $P_{f,\text{damaged}}$ and $P_{f,\text{intact}}$ are the failure probabilities corresponding to damage
 152 and no damage in the system, respectively.

153 A framework of robustness assessment based on decision analysis theory
 154 has been proposed in [19], where the robustness is evaluated by computing

155 both direct risk (R_{Dir}), which is associated with the direct consequences
 156 (C_{Dir}) of potential damages (D) to the system when an exposure (EX_{BD})
 157 occurs, and indirect risk (R_{Ind}), which corresponds to indirect consequences
 158 (C_{Ind}) associated with subsequent system failure (F). A quantitative measure
 159 of robustness is then defined as,

$$I_{Rob} = \frac{R_{Dir}}{R_{Dir} + R_{Ind}}, \quad \text{with} \quad (11)$$

160

$$R_{Dir} = \int_x \int_y C_{Dir} f_{D|EX_{BD}}(y|x) f_{EX_{BD}}(x) dy dx \quad (12)$$

$$R_{Ind} = \int_x \int_y C_{Ind} P(F|D=y) f_{D|EX_{BD}}(y|x) f_{EX_{BD}}(x) dy dx \quad (13)$$

161 where $f_Z(z)$ is the probability density function of a random variable Z .

162 2.3. Entropy-based robustness measures

163 For uncertainty specified with the aid of fuzzy sets, as investigated in
 164 this study, an entropy-based robustness measure $R(\cdot)$ as proposed in [16] is
 165 useful. This is based on an analog to SHANNON's entropy. This analog to
 166 SHANNON's entropy provides features, which make uncertainties calculated
 167 for random variables and fuzzy variables somewhat related to one another.

168 In classical probability theory, SHANNON's entropy is a measure of the
 169 amount of uncertainty and the associated information, see [11]. Information
 170 comprises the elements x selected from a declared character set representing
 171 the fundamental set \mathbf{X} . The SHANNON's entropy H can be expressed by
 172 a probability distribution function $P(x)$ on a finite set using a functional of
 173 the form

$$H = - \sum_{x \in \mathbf{X}} P(x) \log_2 P(x) . \quad (14)$$

174 And for the case of an infinite set,

$$H = - \int_{-\infty}^{+\infty} f(x) \cdot \log_2 f(x) dx \quad (15)$$

175 applies. In fuzzy set theory, for assessing the fuzziness of the fuzzy set \tilde{A} on
 176 \mathbf{X} , the functional values of the membership function $\mu(x)$ of \tilde{A} are applied
 177 as measure values of the elements. An entropy measure of fuzziness $H(\tilde{A})$
 178 analog to Shannon's entropy is introduced in [15] as

$$H(\tilde{A}) = -k \cdot \int_{-\infty}^{+\infty} [\mu(x) \cdot \ln(\mu(x)) + (1 - \mu(x)) \cdot \ln(1 - \mu(x))] dx. \quad (16)$$

179 The coefficient k is introduced when transforming the dyadic logarithm in
 180 the Shannon's entropy in Eq. (15) into the natural logarithm in Eq. (16).
 181 That is, $\log_2(\mu(x)) = k \cdot \ln(\mu(x))$ and $k = \frac{1}{\ln(2)}$. Since entropies appear as
 182 ratios in our approach, k is cancelled out and does not have any influence.
 183 The entropy in Eq. (16) has the following properties:

- 184 • $H(\tilde{A}) = 0$ if $\mu(x) = 0$ or $\mu(x) = 1.0$ for all x ;
- 185 • $H(\tilde{A})$ reaches maximum if $\mu(x) = 0.5$ for all x ;
- 186 • If \tilde{A}_i is any sharpened version of \tilde{A}_j (that is, if $\mu_{A_j}(x) \leq 0.5$, then
 187 $\mu_{A_i}(x) \leq \mu_{A_j}(x)$, and if $\mu_{A_j}(x) \geq 0.5$, then $\mu_{A_i}(x) \geq \mu_{A_j}(x)$), then
 188 $H(\tilde{A}_i) \leq H(\tilde{A}_j)$;
- 189 • The symmetry property holds, i.e. $H(\tilde{A}) = H(\tilde{A}^c)$ where \tilde{A}^c is the
 190 complement of \tilde{A} and defined as $\tilde{A}^c = \{(x, \mu_{A^c}(x)) | x \in \mathbf{X}; \mu_{A^c}(\mathbf{x}) =$
 191 $\mathbf{1} - \mu_{\mathbf{A}}(\mathbf{x})\}$.

192 For example, $H(\tilde{z}_j)$ of the fuzzy sets \tilde{z}_j shown in Fig. 3(b) are $H(\tilde{z}_1) =$
193 0.72 , $H(\tilde{z}_2) = 0.60$, $H(\tilde{z}_3) = 0.60$, $H(\tilde{z}_4) = 0.30$ and $H(\tilde{z}_5) = 0.30$. These
194 examples represent common shapes of membership functions in practical ap-
195 plications. Generally, this entropy measure evaluates the “steepness” of the
196 membership function $\mu(x)$, which indicates $H = 0$ for a crisp set and H is
197 maximum if $\mu(x) = 0.5$. In information theory the elements with $\mu_A(x) = 0.5$
198 represent the most interesting range of a fuzzy set \tilde{A} because $\mu(x) = 0.5$ char-
199 acterizes the highest uncertainty in the decision to consider the associated
200 element x either as belonging to \tilde{A} or as not belonging to \tilde{A} .

201 The derivation of Eq. (16) from a probabilistic basis in information the-
202 ory ensures reasonable compliance with probabilistic uncertainty measures.
203 Let X be a random variable with normal distribution, and its uncertainty
204 be measured in terms of the standard deviation σ_X . If the cumulative distri-
205 bution function (CDF) $F_X(x)$ is substituted in Eq. (16) for the membership
206 function $\mu(x)$, then a change of the standard deviation σ_X is associated with
207 a proportional change of the entropy H . For example, let $X_i \sim (\mu_X, \sigma_{X_i}^2)$
208 and $X_j \sim (\mu_X, \sigma_{X_j}^2)$ be two normal random variables with $\sigma_{X_j} = 2\sigma_{X_i}$. If
209 \tilde{A}_i and \tilde{A}_j are two fuzzy sets with their membership functions having values
210 as the CDF of X_i and X_j , i.e., $\mu_{A_i}(x) = F_{X_i}(x)$ and $\mu_{A_j}(x) = F_{X_j}(x)$, then
211 $H(\tilde{A}_j) = 2H(\tilde{A}_i)$.

212 According to [16], the robustness of a structural system $R(\cdot)$ can be de-
213 fined as the ratio between the entropy of input parameters \tilde{x} and the entropy
214 of associated structural responses \tilde{z} when the uncertainty of structural pa-
215 rameters is quantified as fuzziness,

$$R(\tilde{x}, \tilde{z}) = \frac{H(\tilde{x})}{H(\tilde{z})}. \quad (17)$$

216 And the following properties hold,

- 217 • $R(\cdot) \geq 0 \forall H(\tilde{x}), H(\tilde{z}) > 0$;
- 218 • $H(\tilde{z}_2) \leq H(\tilde{z}_1) \Rightarrow R_2(\cdot) \geq R_1(\cdot) \mid H(\tilde{x}_1) = H(\tilde{x}_2)$;
- 219 • $H(\tilde{x}) \rightarrow 0 \Rightarrow R(\cdot) \rightarrow 0 \mid H(\tilde{z}) > 0$;
- 220 • $H(\tilde{z}) \rightarrow 0 \Rightarrow R(\cdot) \rightarrow \infty \mid H(\tilde{x}) > 0$.

221 This robustness measure results in a global statement about the degree of
222 variations in system output with respect to fluctuations in system input at
223 once. The second property indicates that the smaller the uncertainty of the
224 fuzzy outputs is obtained in relation to the uncertainty of the fuzzy inputs,
225 the bigger the robustness of the structures is assessed. In practice, this
226 means that moderate changes applied to structural parameters, for example
227 as changes of design parameters or through quite common deviations from
228 plans and moderate errors, affect the structural response (i.e. the structural
229 performance) only marginally. Further, in the case that result uncertainty
230 occurs even for crisp input, which represents instabilities, the robustness is
231 zero. Robustness is not defined for the case that both the input uncertainty
232 and the result uncertainty are zero. For further detailed explanations we
233 refer to [16].

234 **3. Nuanced Robustness Analysis**

235 While deterministic performance measures and probabilistic robustness
236 measures assess a structure under given conditions and uncertainties, the

237 entropy-based robustness measure considered in Section 2.3 provides a po-
 238 tential to develop a nuanced robustness assessment in form of a robustness
 239 function depending on the magnitude of uncertainty in the structural con-
 240 ditions. Hence, a trade-off assessment for inspection effort versus gain in
 241 confidence for performance, safety and robustness predictions can be devel-
 242 oped. We develop this nuanced robustness assessment based on the general
 243 idea of an entropy-based robustness measure.

244 3.1. Practical considerations

245 3.1.1. Applicability of entropy measure

246 One (first) problem that has been addressed by Section 2.3 is associated
 247 with the applicability of the entropy measure when considering the difference
 248 between an interval variable and a singleton. Mathematically, they have the
 249 same entropy values (i.e., $H = 0$), but it is counterintuitive as the interval
 250 possesses clearly a larger imprecision.

251 A similar (second) problem arises, as shown in Fig. 1, when the fuzzy
 252 output \tilde{z}_1 associated with the fuzzy input \tilde{x} for system (1) and the fuzzy
 253 output \tilde{z}_2 associated with the same fuzzy input \tilde{x} for system (2), have similar
 254 entropy values but quite different width of the system output at various
 255 membership levels with respect to same degrees of imprecision in the fuzzy
 256 input, i.e. $w(z_{1,\alpha_k}) > w(z_{2,\alpha_k})$. For example, mapping of the same fuzzy
 257 input \tilde{x} in Fig. 3(a) through two systems (functions $f_2(x)$ and $f_3(x)$) gives
 258 two fuzzy outputs \tilde{z}_2 and \tilde{z}_3 in Fig. 3(b), with $H(\tilde{z}_2) = H(\tilde{z}_3) = 0.60$ but
 259 $w(z_{3,\alpha_k=0.5}) = 0.94 > 0.29 = w(z_{2,\alpha_k=0.5})$.

260 A third problem of the entropy measure, and hence of the robustness
 261 measure, concerns its dependence on scale and transformations. Since it is

262 not invariant in this sense, an interpretation on the ratio scale is critical.

263 *3.1.2. Suggested assumptions and extensions*

264 The first problem is circumvented in this study; we assume that typical
265 shapes of membership functions, such as triangular or quadratic, are adopted
266 for the fuzzy inputs (as usually used in practical cases) and that the asso-
267 ciated fuzzy outputs are obtained as fuzzy sets as well and not as precise
268 numbers. A polygonal approximation of the shape of the fuzzy outputs us-
269 ing only a few membership levels is sufficient in most cases. If the analysis
270 indicates strong nonlinearities in the membership functions, a more detailed
271 alpha-discretization may be useful. Associated with this assumption, an-
272 other restriction is made; the fuzzy variables \tilde{x} considered herein possess one
273 element $x \in \tilde{x}$ with $\mu(x) = 1$.

274 Next, the second problem raised above is considered. Robustness assess-
275 ment based on the robustness measure in Eq. (17) leads to the same results
276 for system (1) and system (2), $H(\tilde{z}_1) \approx H(\tilde{z}_2)$, i.e. to the conclusion that
277 system (1) is as robust as system (2). However, this conclusion is only lim-
278 ited to a global view at the robustness of the two systems without reflection
279 of the degree of independence between the imprecision of fuzzy inputs and
280 the associated imprecision of fuzzy outputs at different membership levels.
281 To implement this relationship between the α -level sets, the assessment from
282 [16] is modified by utilizing alpha-level discretization as proposed in Section
283 3.2. This enables a consideration of a trade-off between additional informa-
284 tion and an associated reduction of imprecision in the predicted structural
285 response or reliability. Additional information and reduction of input impre-
286 cision can be understood as limitation of the analysis to the set of values

287 $\{x \in \mathbf{X} | \mu(x) \geq \alpha_k\}$ for the fuzzy input \tilde{x} and the associated set of values
288 $\{z | \mu_j(z) \geq \alpha_k\}$ for the fuzzy output \tilde{z}_j in the assessment of robustness. Sub-
289 sequently, the two systems may not exhibit similar robustness corresponding
290 to the reduced imprecision in the fuzzy inputs.

291 The third problem concerning lack of invariance is circumvented by us-
292 ing this robustness measure on an ordinal scale rather than on a ratio scale.
293 Although the meaning of the ratio value obtained for the robustness of an
294 individual structure is not meaningful, it provides a useful basis for the com-
295 parison with a second structure, evaluated for the same problem with the
296 same input and looking the same responses, in terms of robustness. Relat-
297 ing the robustness measures of two structures to one another in this manner
298 translates the assessment to an ordinal scale, which is sufficient to decide
299 which structure is more robust than the other one - without assessing nu-
300 merically how big the difference in robustness is. Still, this difference in
301 robustness between the structures related to the absolute robustness of one
302 of the structures provides at least a rough sense about the magnitude of this
303 difference. One can then see whether this difference is significant or not.
304 Although this is a reasonable basis for deriving decisions in many practical
305 cases, further research is needed to address this issue more rigorously.

306 *3.2. Proposed approach*

307 *3.2.1. General description*

308 The inconsistency explained in Section 3.1, see Fig. 1, can be resolved
309 by computing the entropy-based robustness $R(\alpha_k)$ at various membership
310 levels with respect to the degrees of imprecision in the fuzzy inputs and the
311 associated imprecision of the fuzzy outputs.

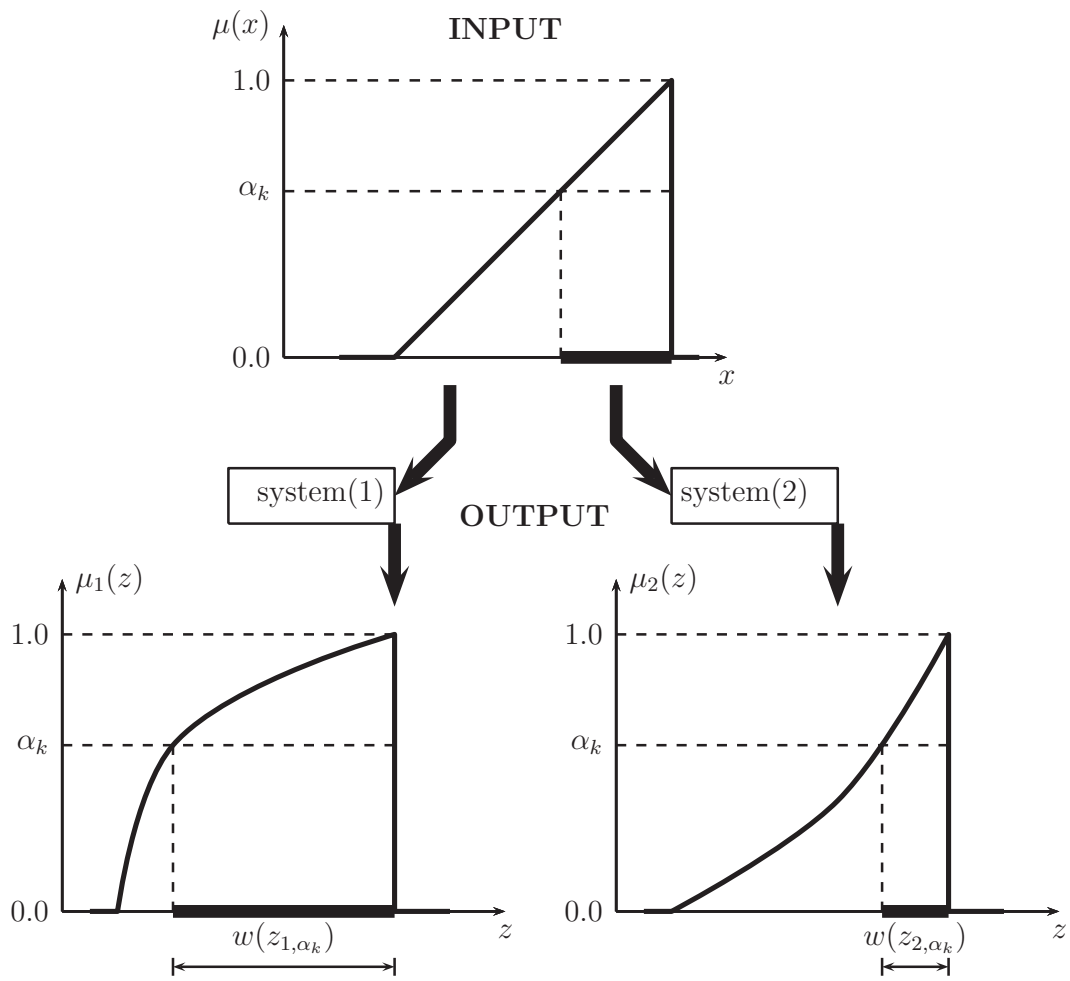


Figure 1: Illustration of problems with the existing robustness measure R

312 Given a fuzzy set \tilde{A} , at each alpha level $\alpha_k \in (0, 1]$, the crisp set A_{α_k}

$$A_{\alpha_k} = \{x \in \mathbf{X} | \mu_A(x) \geq \alpha_k\} \quad (18)$$

313 is called α -level set. Given another fuzzy set \tilde{B} , the *intersection* \tilde{D} of the
314 fuzzy sets \tilde{A} and \tilde{B} on \mathbf{X} is obtained from

$$\tilde{D} = \tilde{A} \cap \tilde{B} = \{(x, \mu_D(x)) | x \in \mathbf{X}; \mu_D(x) = \min[\mu_A(x), \mu_B(x)]\}. \quad (19)$$

315 Since the fuzzy set theory, which permits the gradual assessment of the mem-
316 bership of elements in relation to a set, is a generalization of the classical set
317 theory, the α -level set A_{α_k} can be viewed as a special fuzzy set. Thus, a new
318 fuzzy set can be defined as the intersection of fuzzy set \tilde{A} and its α -level set
319 A_{α_k} , denoted as \tilde{A}_{α_k} ,

$$\tilde{A}_{\alpha_k} = \tilde{A} \cap A_{\alpha_k}, \quad (20)$$

320 as illustrated in Fig. 2. This concept is then applied to the fuzzy input \tilde{x}
321 and fuzzy output \tilde{z} of the structural problem. The entropy-based robustness
322 $R(\cdot)$ in Eq. (17) is calculated for each \tilde{A}_{α_k} as the ratio between the entropy
323 of $\tilde{x}_{\alpha_k} = \tilde{x} \cap x_{\alpha_k}$ of the fuzzy input \tilde{x} and the entropy of $\tilde{z}_{\alpha_k} = \tilde{z} \cap z_{\alpha_k}$ of the
324 fuzzy output \tilde{z} ,

$$R(\alpha_k) = \frac{H(\tilde{x}_{\alpha_k})}{H(\tilde{z}_{\alpha_k})}. \quad (21)$$

325 The robustness $R(\cdot)$ in [16] is obtained as a special case of Eq. (21) for
326 $\alpha_k = 0 + \varepsilon$ when $\varepsilon \rightarrow 0$. The robustness $R(\alpha_k)$ is not defined at $\alpha_k = 1$
327 because $H(\tilde{x}_{\alpha_k=1})$ and $H(\tilde{z}_{\alpha_k=1})$ are normally both equal to zero.

328 3.2.2. Illustrative example

329 The features of the modified robustness measure in Eq. (21) are demon-
330 strated in the following illustrative example by means of analytical functions

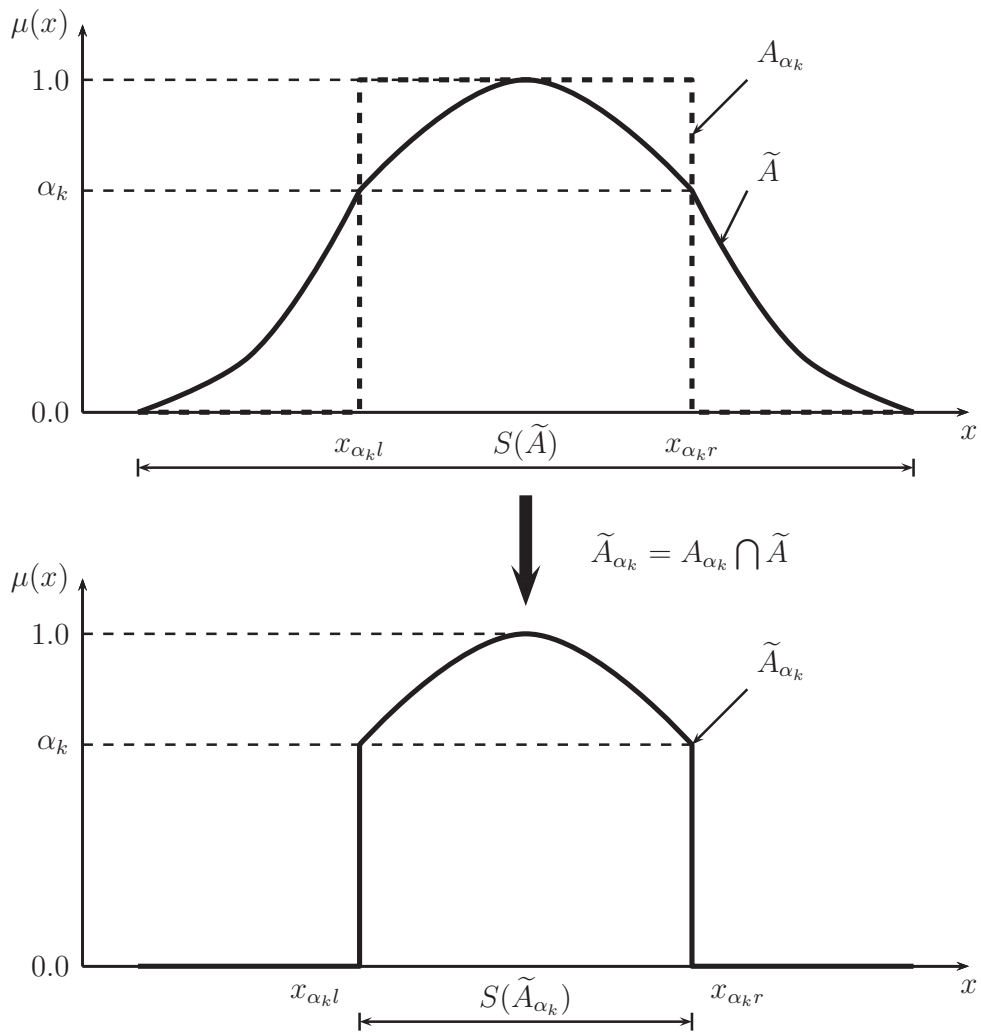


Figure 2: Intersection of the fuzzy set \tilde{A} with the α -level set A_{α_k}

331 specifically selected for this purpose. Consider the mapping of fuzzy input
 332 \tilde{x} in Fig. 3(a) into the fundamental set \mathbf{Z} with the aid of the following five
 333 mapping models $f_j(x)$:

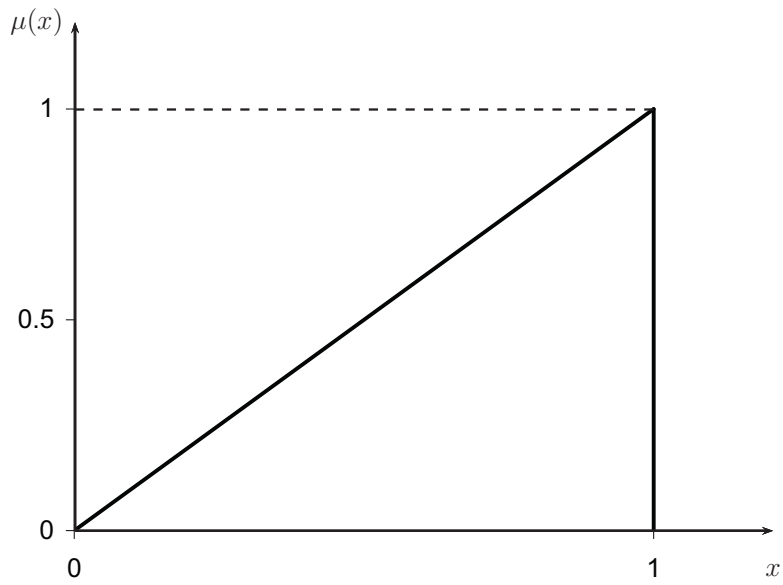
$$\begin{aligned} f_1(x) &= x , \\ f_2(x) &= x^{0.5} , \\ f_3(x) &= x^4 , \\ f_4(x) &= 0.5x^4 + 0.5 , \\ f_5(x) &= 0.5x^{0.5} + 0.5 . \end{aligned}$$

334 The membership functions for the fuzzy outputs \tilde{z}_j can be obtained ana-
 335 lytically,

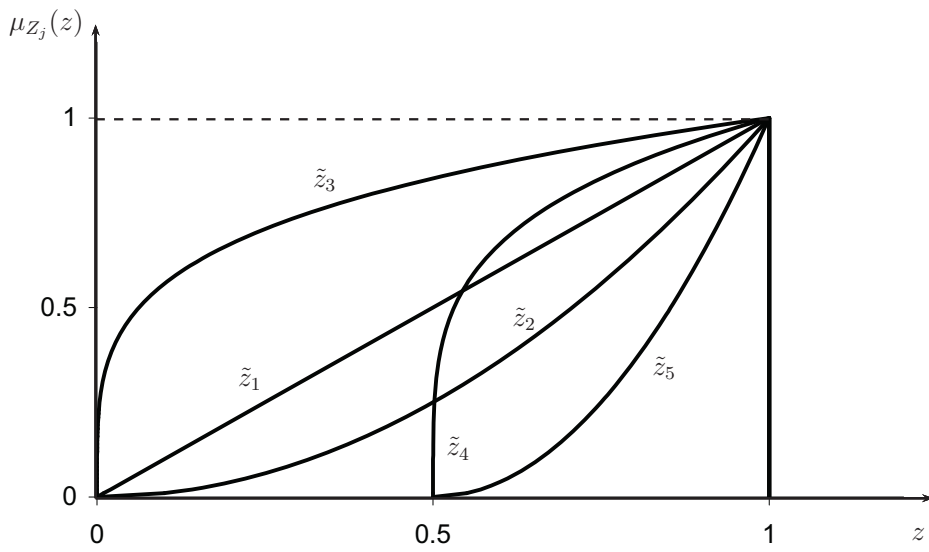
$$\begin{aligned} \mu_1(z) &= z, \quad z \in [0, 1] \\ \mu_2(z) &= z^2, \quad z \in [0, 1] \\ \mu_3(z) &= z^{0.25}, \quad z \in [0, 1] \\ \mu_4(z) &= (2z - 1)^{0.25}, \quad z \in [0.5, 1] \\ \mu_5(z) &= (2z - 1)^2, \quad z \in [0.5, 1] \end{aligned}$$

336 where $\mu_j(z) = 0$ for other values. The results are shown in Fig. 3(b).

337 The functions $f_i(x)$ have been chosen to illustrate the effects discussed
 338 below, which possess particular practical relevance and address the problem
 339 in Fig. 1. Specifically, $f_2(x)$ and $f_3(x)$ are selected to show that the associ-
 340 ated fuzzy outputs \tilde{z}_2 and \tilde{z}_3 have similar entropy values but different shapes.
 341 The same applies to the selection of $f_4(x)$ and $f_5(x)$, but with a smaller un-
 342 certainty in the associated results \tilde{z}_4 and \tilde{z}_5 to work out discussion on this
 343 effect, as well. One could use further functions, as well, for this study.



(a) Fuzzy input \tilde{x}



(b) Fuzzy outputs \tilde{z}_j

Figure 3: Mapping $\tilde{x} \rightarrow \tilde{z}_j$: 3a fuzzy input \tilde{x} and 3b fuzzy outputs \tilde{z}_j associated with the mapping model $z_j = f_j(x)$

344 The entropy values associated with α_k of \tilde{x} and \tilde{z}_j , normalized by $H(\tilde{x})$,
 345 are shown in Fig. 4. It clearly indicates a reduction of imprecision in the
 346 fuzzy input \tilde{x} as α_k increases (i.e., collection of additional information) and
 347 the corresponding reduction of imprecision in the fuzzy outputs \tilde{z}_j . In an en-
 348 gineering context, it means that collection of additional information to reduce
 349 input imprecision has a trade-off in a reduction in imprecision of computa-
 350 tional results, i.e., in predictions regarding structural behavior and reliability.
 351 However, for different mapping models, the reduction of imprecision in the
 352 outputs exhibits very different characteristics. For example, the imprecision
 353 in \tilde{z}_{2,α_k} and \tilde{z}_{5,α_k} decreases much faster than the imprecision in \tilde{z}_{3,α_k} and \tilde{z}_{4,α_k}
 354 for smaller values of α_k . It indicates that just a small reduction of imprecision
 355 in \tilde{x} (i.e., low effort spent on collecting additional information) can result in a
 356 significant reduction in imprecision of \tilde{z}_2 and \tilde{z}_5 . Thus, the mapping models
 357 f_2 and f_5 have more desirable properties than f_3 and f_4 . They represent
 358 economical engineering design in the sense that only little effort in collecting
 359 input information has a significant trade-off in a substantial quality improve-
 360 ment of predictions regarding structural performance and reliability. This
 361 feature is reflected in the robustness measure in Eq. (21), which provides a
 362 quantitative assessment of the properties of the systems.

363 The entropy-based robustness $R(\alpha_k)$ is shown in Fig. 5 as a function of
 364 α_k . Several interesting conclusions can be drawn from the results:

- 365 • $R(\tilde{x}, \tilde{z}_2) = 1.22 \approx R(\tilde{x}, \tilde{z}_3) = 1.20 > R(\tilde{x}, \tilde{z}_1) = 1.00$ at $\alpha_k = 0 + \varepsilon$
 366 when $\varepsilon \rightarrow 0$. This observation produces the robustness assessment in
 367 [16] as a special case. That is, if only the values of $R(\cdot)$ with respect
 368 to $\alpha_k = 0 + \varepsilon$ when $\varepsilon \rightarrow 0$ are considered to make a decision, it would

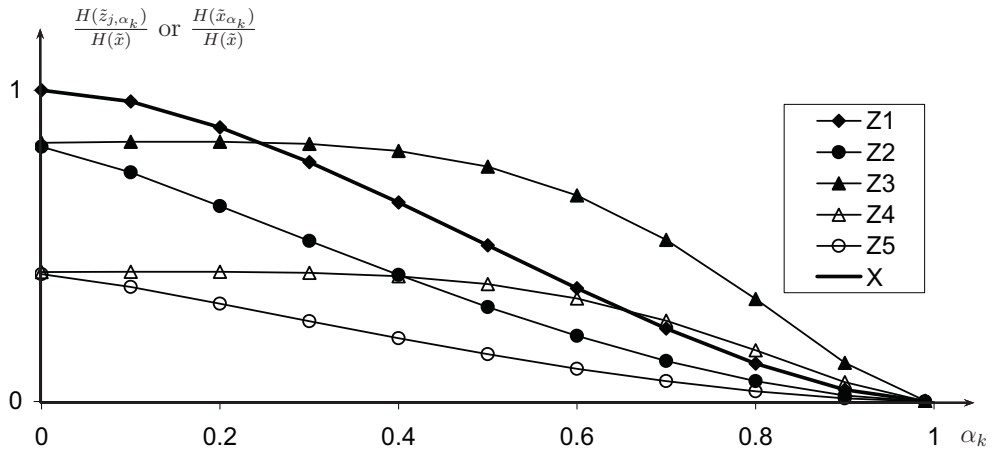


Figure 4: A reduction of imprecision in the fuzzy input \tilde{x} as α_k increases and the corresponding reduction of imprecision in the fuzzy outputs \tilde{z}_j (note: the curve for \tilde{x} overlaps with that for \tilde{z}_1)

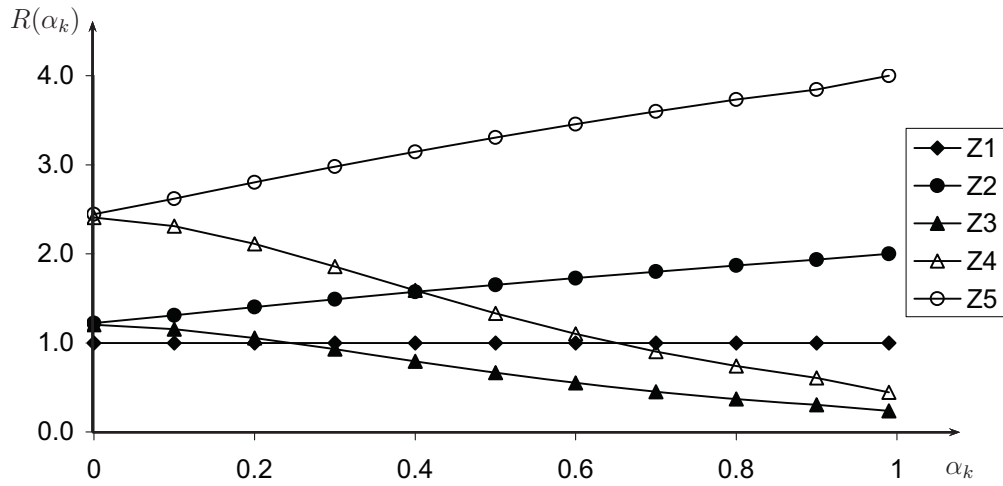


Figure 5: Robustness $R(\tilde{x}, \tilde{z}_j)$ associated with each mapping model $f_j(x)$ with alpha-level (α_k) discretization

369 be concluded that the mapping models $f_2(x)$ and $f_3(x)$ have a similar
 370 robustness and are both more robust than mapping model $f_1(x)$.

371 • Fig. 5 shows significant differences of the values $R(\cdot)$ corresponding
 372 to different values of α_k . As α_k is increased, $R(\tilde{x}, \tilde{z}_3)$ keeps decreasing
 373 while $R(\tilde{x}, \tilde{z}_2)$ keeps increasing. This indicates that the mapping
 374 models will exhibit different properties with respect to robustness when
 375 considering an increase of membership values $\alpha_k > 0$, i.e., a reduction
 376 of imprecision in the fuzzy input. The imprecision in the uncertain
 377 inputs can be reduced when more information is made available. This
 378 facilitates a trade-off analysis between collection of additional informa-
 379 tion and decision for a specific design variant. For example, at $\alpha_k = 0.4$,
 380 $R(\tilde{x}, \tilde{z}_2) = 1.57 > R(\tilde{x}, \tilde{z}_1) = 1.00 > R(\tilde{x}, \tilde{z}_3) = 0.79$. Thus, it would
 381 be concluded that mapping model $f_2(x)$ is the most robust system
 382 when input imprecision can be reduced to a degree corresponding to
 383 membership level 0.4. Furthermore, when considering all the values of
 384 $\alpha_k \in (0, 1]$, the mapping model $f_2(x)$ is more robust in overall than
 385 $f_3(x)$ although they have similar robustness values at $\alpha_k = 0 + \varepsilon$. The
 386 same situation appears when comparing the mapping models $f_4(x)$ and
 387 $f_5(x)$. Obviously, the mapping model $f_5(x)$ is a better choice.

388 • The mapping model $f_4(x)$ is more robust than $f_2(x)$ when $\alpha_k \leq 0.4$,
 389 especially, $R(\tilde{x}, \tilde{z}_4) = 2.41 \approx 2R(\tilde{x}, \tilde{z}_2) = 2.44$ at $\alpha_k = 0 + \varepsilon$. How-
 390 ever, the values of $R(\cdot)$ associated with $\alpha_k \geq 0.4$ lead to the opposite
 391 conclusion that the mapping model $f_2(x)$ is more robust than $f_4(x)$.
 392 Again, the trade-off between collection of additional information and

393 decision for a variant or improvement of the robustness assessment can
394 be considered. If the collection of additional information is easy to
395 facilitate, $f_2(x)$ would be the preferred model; otherwise $f_4(x)$. And
396 the other may round, if $f_2(x)$ is selected, collection of additional infor-
397 mation would be very useful and paid off; whilst for $f_4(x)$ collection of
398 additional information does not lead to a benefit.

399 Hence, it is of vital importance to compute the structural robustness
400 at various membership levels α_k . Robustness is not only a property
401 of the structure, it is also dependent on the magnitude of impreci-
402 sion/uncertainty in the input. It is a relative measure. Reduction of
403 input imprecision can so lead to both increase and decrease in robust-
404 ness depending on whether sensitivities are associated with the value
405 ranges cut away in the reduction of imprecision or not. This consid-
406 eration can substantially support design decisions in the context of
407 availability of information and inspection cost.

408 It is noted that the membership functions of the result can be found in
409 a closed form in the case of the simple illustrative example. In a practical
410 structural analysis it is normally not possible to determine result membership
411 functions in a closed form. However, they can be found in general via a
412 numerical fuzzy analysis. A variety of intrusive and non-intrusive numerical
413 approaches are available to perform this analysis, see [20, 21, 22, 23, 24].

414 4. Application to Offshore Structures

415 4.1. Structural models

416 Based on the environmental conditions and the information about the
417 reference jackets provided in [3], two 2D frames are designed using software
418 USFOS with some simplifications as well as some changes to the dimensions
419 of members. USFOS (an acronym for Ultimate Strength for Frame Offshore
420 Structure) is a numerical tool for nonlinear pushover analysis which helps to
421 compute the reserve strength and residual strength of the frame structures
422 before and after damage. The topologies for the X-bracing and K-bracing
423 jacket structures are shown in Fig. 6. All structures are two-bay frames
424 in water depth of $37m$. The environmental design loads are applied at the
425 top two elevations of the frames with the values of 1334.5 kN and 667.2 kN,
426 respectively. The diameter D and thickness t of all tubular members are
427 listed in Table 1.

428 An assumption of fixed boundary conditions is made and all the tubular
429 joints are assumed to be rigid. The structures are modelled with beam ele-
430 ments and material non-linearities are modelled by plastic hinges at element
431 mid-span and element ends. Element formulation of this program also allows
432 the considerations of large displacement effects and the coupling of lateral
433 deflection and axial strain. This supports a realistic representation of the
434 element behavior including column buckling. Nonlinear ultimate strength
435 analysis can be carried out to determine the reserve and residual strength
436 representing the degree of redundancy of the jacket structure. In the analy-
437 sis, the load is applied incrementally until the ultimate resistance is reached
438 and the load increment is automatically reversed when global instability is

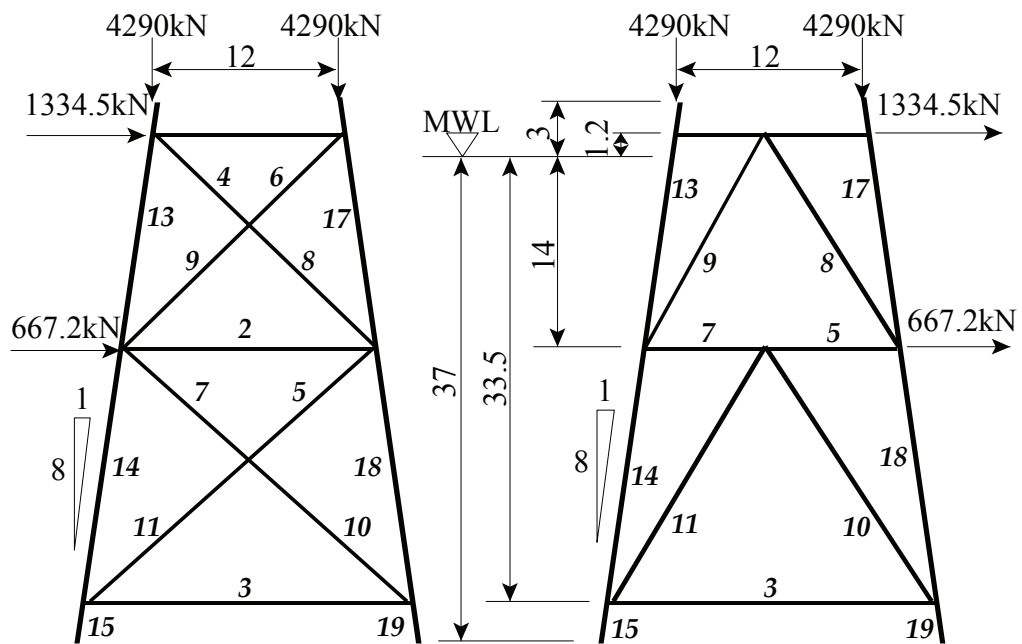


Figure 6: Structural models of the fixed offshore platforms (unit of length: m)

Table 1: Member sizes of the X-frame and K-frame

member	X-	frame	K-	frame
no.	$D(m)$	$t(m)$	$D(m)$	$t(m)$
2	0.32385	0.00953	-	-
3	0.3556	0.00953	0.508	0.0127
4	0.4572	0.0127	-	-
5	0.4572	0.0127	0.559	0.0127
6	0.4572	0.0127	-	-
7	0.4572	0.0127	0.559	0.0127
8	0.4572	0.0127	0.508	0.01588
9	0.4572	0.0127	0.508	0.01588
10	0.4572	0.0127	0.559	0.01715
11	0.4572	0.0127	0.559	0.01715
13	1.1684	0.0254	1.1684	0.0254
14	1.1684	0.03175	1.1684	0.03175
15	1.1684	0.03175	1.1684	0.03175
17	1.1684	0.0254	1.1684	0.0254
18	1.1684	0.03175	1.1684	0.03175
19	1.1684	0.03175	1.1684	0.03175

439 detected. The size of the increments may be varied along the deformation
440 path, i.e. large steps in the linear range, and smaller steps with increasingly
441 nonlinear behavior.

442 *4.2. Damage modeling under imprecise marine corrosion*

443 In this practical example, the fixed offshore platforms are assumed to be
444 subjected to gradual deterioration caused by uniform corrosion. In order to
445 investigate the corrosion effects with a longer period, the immersion corrosion
446 data collected until 1994 provided in [17] are taken to specify the corrosion
447 depth. With this approach we follow the general practise to consider only
448 uniform corrosion when analyzing structural strength or structural capacity,
449 see [25]. However, the proposed nuanced robustness analysis is not limited to
450 this corrosion model. It can also be applied in association with non-uniform
451 corrosion models. One may consider that corrosion tends to concentrate in
452 the heat affected zone of the welds, and that stress-concentrations exists at
453 the same spots. Hence, the damage maybe defined as an accumulation of
454 those local damages in the connections.

455 Herein, we focus on uniform corrosion and define a fuzzy corrosion depth
456 $\tilde{c}(t)$ associated with the exposure time t coarsely derived from the data in
457 conjunction with a subjective assessment of deterioration, as shown in Fig. 7.
458 The membership values $\mu(c)$ express the degree of subjective plausibility that
459 particular values of $c(t)$ actually occur. That is, the membership values reflect
460 a subjective assessment and the specification of the values are characterized
461 by highly subjective factors. In this example, $\tilde{c}(t = 16)$ is considered and
462 subjectively constructed according to the data points plotted in Fig. 7. A
463 rational approach is to weigh the mean value 0.68 mm with a membership

464 of $\mu(0.68) = 1.0$. The 5% and 95% bounds $[0.32, 1.40]$ mm at $t = 16$ provide
 465 a reasonable interval for the support of the fuzzy set $\tilde{c}(t = 16)$. However,
 466 it is observed that there are some outliers at $t = 15$, which are considered
 467 to be possible values but with lower degree of possibility, i.e., $\mu(c) \leq 0.1$ for
 468 $c \geq 1.40$ mm. Since the membership function is only a subjective assessment,
 469 complicated descriptions are often not necessary for practical purpose. It is
 470 appropriate to choose linear functional formulations for $\mu(c)$, as shown in
 471 Fig. 8.

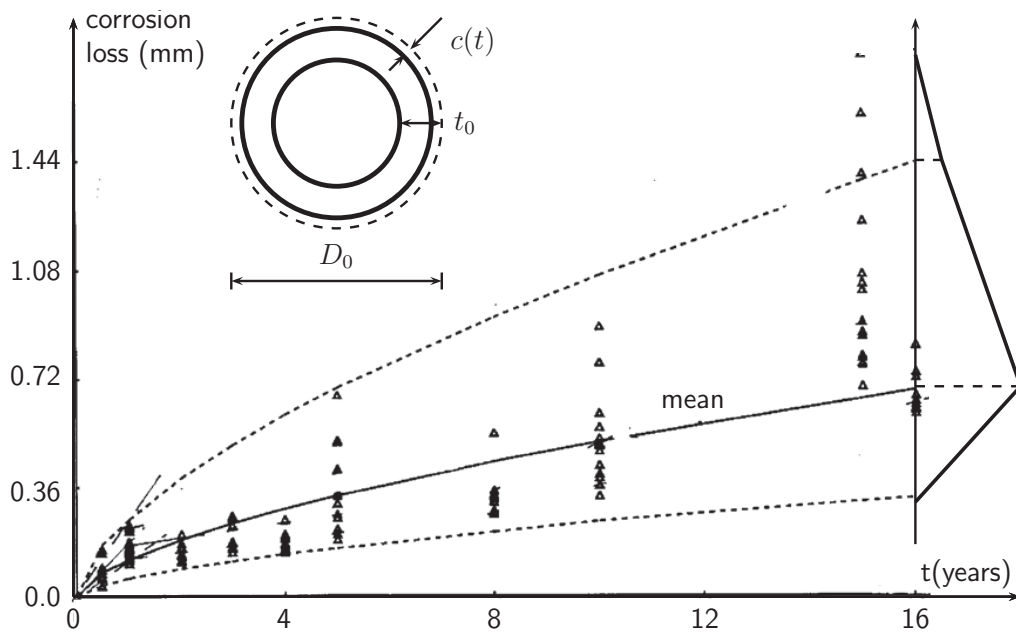


Figure 7: Immersion corrosion data for mild-steel coupons pooled from all available sources until 1994 subjected to an approximate temperature correction in [17] with 5 and 95 percentile bands

472 The concept of structural damage modeling from [4] is utilized herein to
 473 specify the amount of damage at the member level for a circular cross-section.

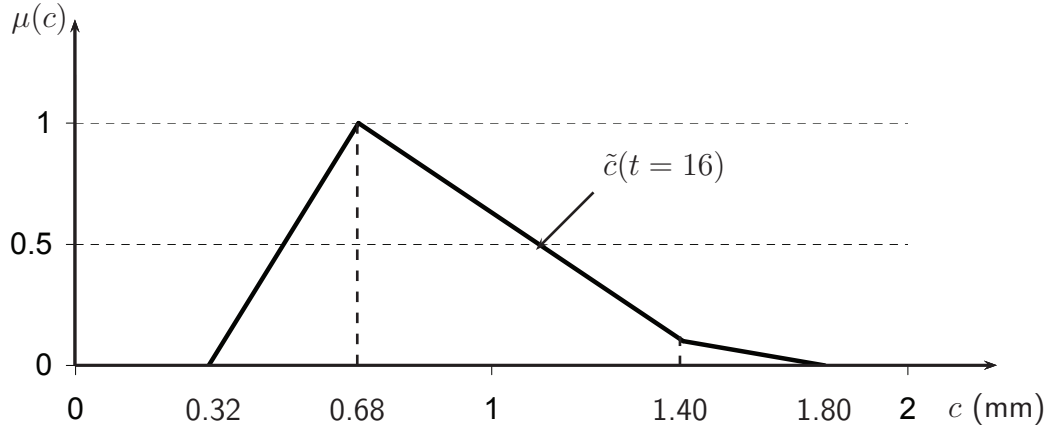


Figure 8: Fuzzy corrosion depth \tilde{c} at $t = 16$ years according to the immersion corrosion data in Fig. 7

474 For the hollow steel tubes which are typically used in building offshore plat-
 475 forms, the damage at cross-sectional level can be represented by a ratio of
 476 the corroded area A_c and the original area A_0 ,

$$\beta = \frac{A_c}{A_0} = \frac{D_0}{(D_0 - t_0)t_0}c - \frac{1}{(D_0 - t_0)t_0}c^2 \quad (22)$$

477 where D_0 and t_0 are the diameter and wall-thickness, respectively, before
 478 deterioration. Finally, the formulation at the cross-sectional level is extended
 479 to obtain the total damage at the structural level by integration over all
 480 structural members, which is calculated as β_{total} ,

$$\beta_{\text{total}} = \frac{\sum \beta_i A_i L_i}{\sum A_i L_i} = \sum \omega_i \beta_i \quad (23)$$

481 where $\omega_i = A_i L_i / \sum A_i L_i$, and A_i is the cross-sectional area of a structural
 482 member with length L_i before deterioration.

483 As the corrosion depth is modeled as fuzzy variable $\tilde{c}(t = 16)$ as shown in
 484 Fig. 8, the total damage due to the marine corrosion is also a fuzzy variable

485 and represented by $\tilde{\beta}_{\text{total}} = \sum \omega_i \tilde{\beta}_i$. Based on Eq. (22), $\tilde{\beta}_i$ can be calculated.
 486 It can be observed from the plot of $\beta = \beta(c)$ in Fig. 9 that there exists
 487 monotonic relationship between β and c when $0 \leq c \leq t_0$. Hence, the fuzzy
 488 result $\tilde{\beta}$ can be easily obtained by computing the alpha-level sets $[\beta_{\alpha_k l}, \beta_{\alpha_k r}]$
 489 for $\alpha_k \in (0, 1]$, that is,

$$\beta_{\alpha_k l} = \frac{D_0}{(D_0 - t_0)t_0} c_{\alpha_k l} - \frac{1}{(D_0 - t_0)t_0} (c_{\alpha_k l})^2 \quad (24)$$

$$\beta_{\alpha_k r} = \frac{D_0}{(D_0 - t_0)t_0} c_{\alpha_k r} - \frac{1}{(D_0 - t_0)t_0} (c_{\alpha_k r})^2 \quad (25)$$

490 where $[c_{\alpha_k l}, c_{\alpha_k r}]$ is the alpha-level set at $\alpha_k \in (0, 1]$ of the fuzzy corrosion
 491 depth \tilde{c} . Based on Eq. (24) and Eq. (25), together with the linear function
 492 $\tilde{\beta}_{\text{total}} = \sum \omega_i \tilde{\beta}_i$, the total damage represented by $\tilde{\beta}_{\text{total}}$ can be obtained for
 the K-braced and X-braced frames, as shown in Fig. 10.

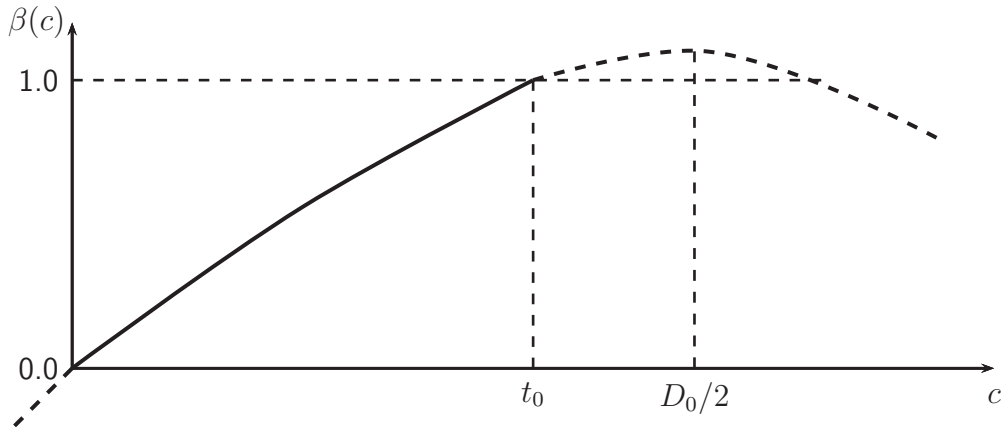


Figure 9: Plot of the damage represented by $\beta(c)$ for a hollow cross-section with diameter D_0 and thickness t_0 . Note: $0 \leq c \leq t_0$

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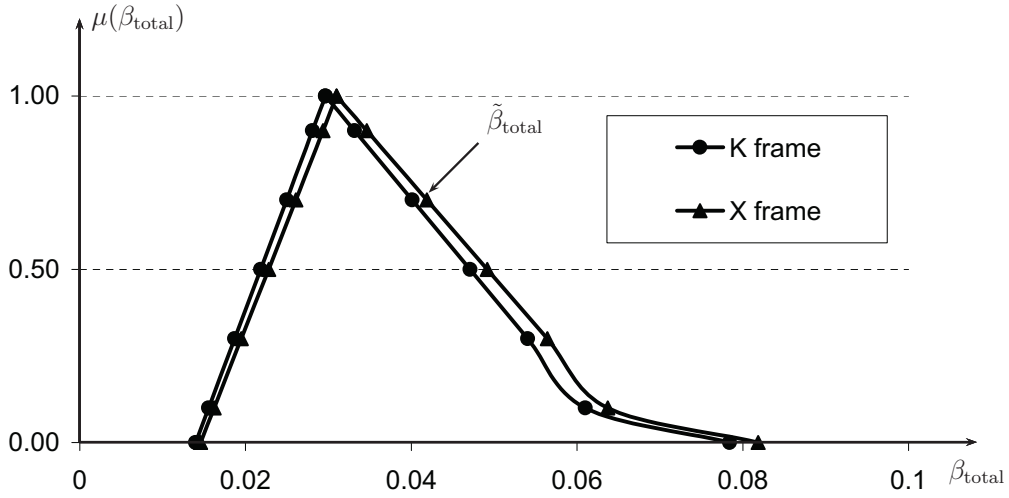


Figure 10: Total damage represented by $\tilde{\beta}_{total}$ for the K-braced and X-braced frames

494 *4.3. Robustness assessment of fixed offshore platforms*

495 The specified fuzzy variable $\tilde{c}(t = 16)$ for the corrosion depth is processed
496 through the fuzzy structural analysis according to [26], which requires a re-
497 peated calculation of the fuzzy result values for varying corrosion depth. In
498 this example, the non-dimensional measures based on ultimate strength anal-
499 ysis, RRF in Eq. (3) and R_{twice} in Eq. (4), are selected as fuzzy result values
500 for each platform, respectively. For this purpose, the fuzzy structural analy-
501 sis is coupled to the USFOS software and the fuzzy result values, \widetilde{RRF} and
502 \widetilde{R}_{twice} , are found by means of an optimization in the kernel of fuzzy structural
503 analysis. The overall procedure includes two successive steps. First, a fuzzy
504 structural analysis is performed with USFOS as a deterministic mapping
505 model, as illustrated in Fig. 11. This deterministic mapping model provides
506 the nonlinear ultimate strength analysis. And the fuzzy structural analysis

507 delivers the fuzzy outputs to the second step. In the second step the entropy
508 is calculated for different alpha-levels with the intersection of membership
509 functions of both fuzzy inputs and outputs. Numerical sensitivities in the
510 fuzzy structural analysis and in USFOS with respect to the fuzzy outputs can
511 be minimized by appropriate selection of the algorithm parameters so that
512 the corrosion effects can be well captured in the fuzzy outputs. The intersec-
513 tion of member functions, in the second step, is based on the mathematical
514 operation of fuzzy sets and no additional effects will be introduced during
515 this operation. Effects from entropy calculation by numerical integration of
516 Eq. (16) are insignificant. Thus, the corrosion effects can be well reflected
517 in the main results, which provide a sound basis to the application of the
518 proposed approach.

519 $\widetilde{\text{RRF}}$ reflects the imprecision of the ultimate capacity of the damaged
520 platforms under corrosion at different membership levels, see Fig. 12. The
521 entropy values associated with α_k of $\tilde{\beta}_{\text{total},\alpha_k}$ and $\widetilde{\text{RRF}}_{\alpha_k}$, normalized by
522 $H(\tilde{\beta}_{\text{total}})$, are shown in Fig. 13. It shows that the imprecision in $\widetilde{\text{RRF}}_{\alpha_k}$
523 of the K frame decreases much faster than the imprecision in $\widetilde{\text{RRF}}_{\alpha_k}$ of the
524 X frame, especially for larger values of α_k . Thus, the K frame has advanta-
525 geous properties over the X frame in view of the effects of imprecise marine
526 corrosion on the ultimate capacity.

527 Based on the proposed approach for robustness assessment in Eq. (20)
528 and Eq. (21), the entropy-based robustness $R(\alpha_k)$ at each alpha-level is
529 calculated as the ratio between the entropy of $\tilde{\beta}_{\text{total},\alpha_k} = \tilde{\beta}_{\text{total}} \cap \beta_{\text{total},\alpha_k}$ of
530 the fuzzy input $\tilde{\beta}_{\text{total}}$ and the entropy of $\widetilde{\text{RRF}}_{\alpha_k} = \widetilde{\text{RRF}} \cap \text{RRF}_{\alpha_k}$ of the
531 fuzzy output $\widetilde{\text{RRF}}$. The result is shown in Fig. 14, which indicates that

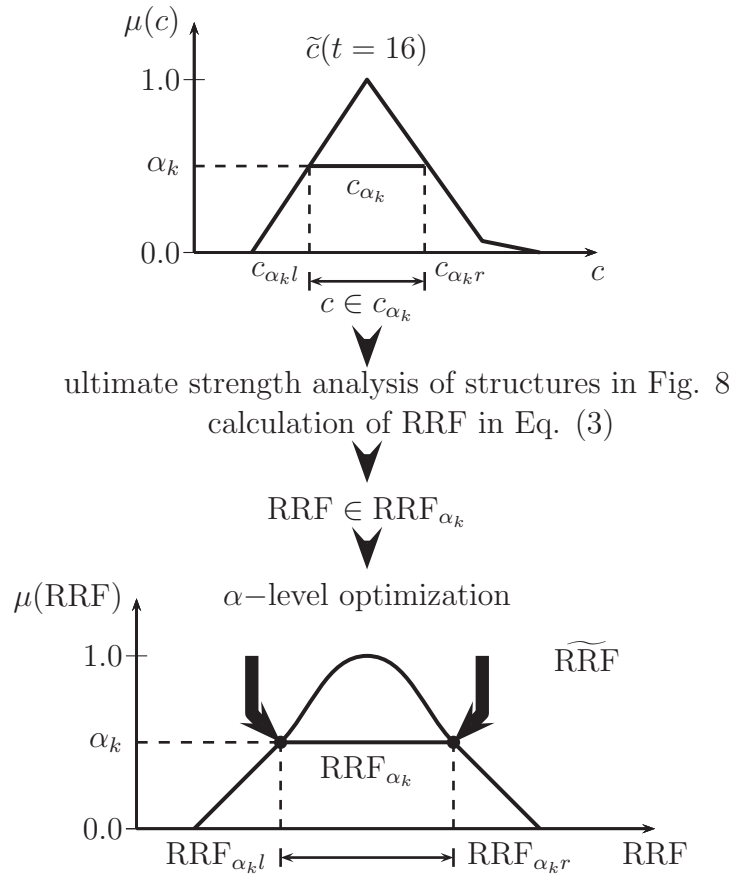


Figure 11: Fuzzy structural analysis with the nonlinear ultimate strength analysis as the deterministic mapping model

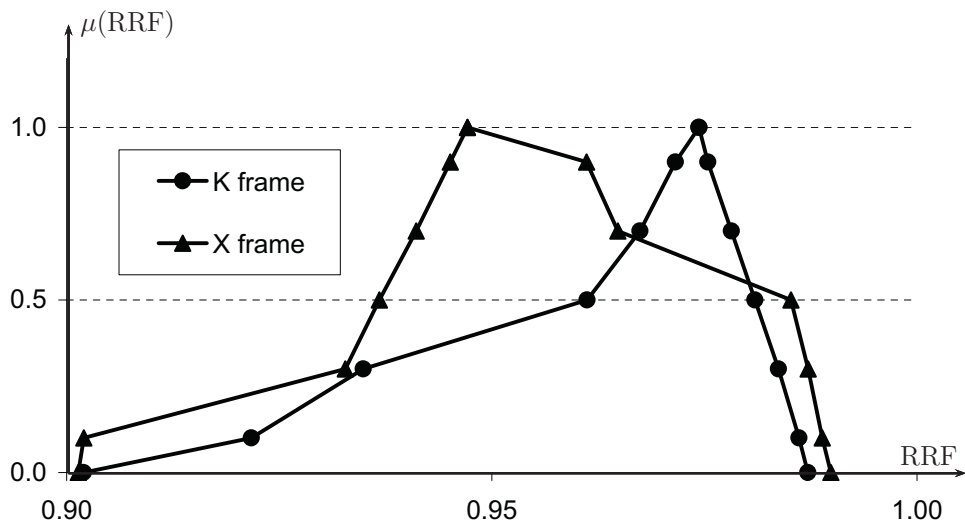


Figure 12: The membership functions of fuzzy RRF for the K-braced and X-braced frames

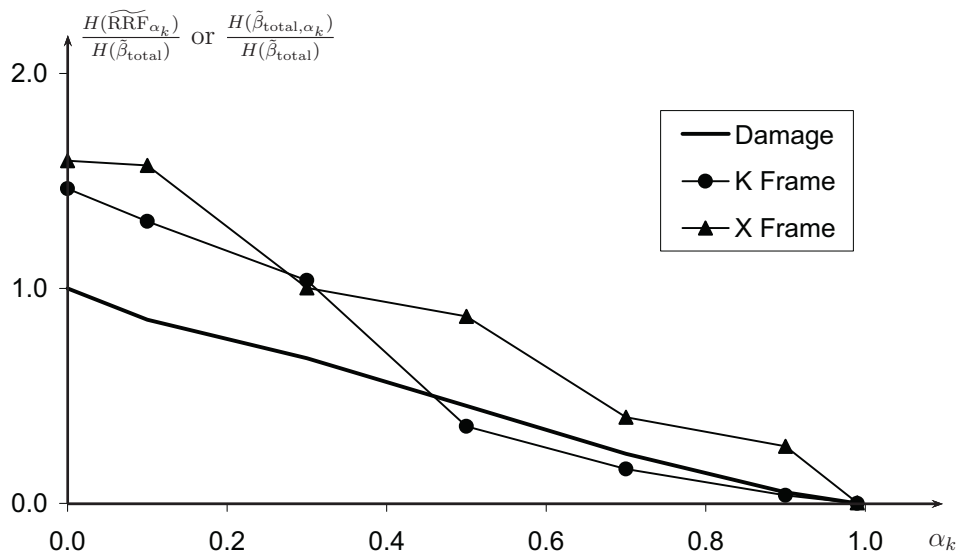


Figure 13: A reduction of imprecision in the fuzzy damage $\tilde{\beta}_{total}$ as α_k increases and the corresponding reduction of imprecision in the fuzzy output \widetilde{RRF}

532 the K-frame and the X-frame have a similar robust behavior with respect
533 to imprecise corrosion effects when $\alpha_k \leq 0.3$. However, the K-frame shows
534 a greater robustness than the X-frame when $\alpha_k > 0.3$. This result suggests
535 that the robustness assessment for the K-frame can be significantly improved
536 by collecting additional information about the corrosion, i.e. by reduction
537 of input imprecision. However, collection of additional information regard-
538 ing long time marine corrosion may be very difficult in offshore engineering
539 practice. For the K-frame additional effort pays off, whereas for the X-frame,
540 no clear benefit can be observed. This conclusion illustrates the potential of
541 the proposed robustness measure for cost reduction and optimal resource
542 allocation in inspection scheduling.

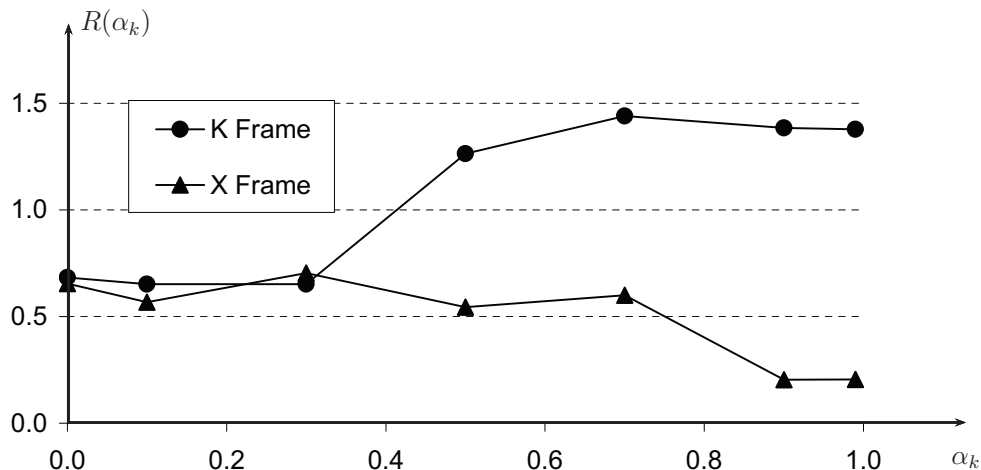


Figure 14: Robustness $R(\tilde{\beta}_{\text{total}}, \widetilde{\text{RRF}})$ associated with each frame with alpha-level (α_k) discretization

543 This observation that the K-frame shows a similar robust behavior as the
544 X-frame when $\alpha_k \leq 0.3$ and a greater robustness when $\alpha_k > 0.3$ is quite dif-
545 ferent from the statement that the X-frame is more robust than the K-frame

546 using the deterministic performance measures in [1, 2]. Furthermore, it is also
 547 known that the X-frame shows ductile behavior while the K-frame shows brittle
 548 behavior. However, these two statements are not conflicting with the new
 549 results as they refer to different aspects. While the deterministic investigation
 550 refers to ductility, the robustness assessment considered herein refers to the
 551 corrosion effects on the ultimate strength of the structure. A consideration of
 552 the residual load carrying capacity leads to an agreement in the conclusions.
 553 This can be observed in Fig. 15 by comparing the nominal distances of \tilde{R}_{twice}
 554 from the value 1.0, $d_X(\tilde{R}_{twice})$ and $d_K(\tilde{R}_{twice})$. In this result, \tilde{R}_{twice} reflects the
 555 imprecision of the residual strength of the damaged platforms under corro-
 556 sion corresponding to twice the ultimate deflection at different membership
 557 levels. A smaller value of the distance indicates a smaller drop in the post
 558 ultimate strength, i.e., more ductility. This effect can be included in the
 559 robustness measures as constraint distance as proposed in [16]. Although
 560 the X-frame shows a better ductile behavior than the K-frame, as observed
 561 in Fig. 15, both frames show a similar robustness in view of the imprecise
 562 damage due to corrosion and the associated imprecision in R_{twice} , see Fig.
 563 16. Further, it is indicated in Fig. 16 that $R(\tilde{\beta}_{total}, \tilde{R}_{twice})$ keeps decreasing
 564 as α_k is increased. This indicates that the residual resistance \tilde{R}_{twice} is insen-
 565 sitive with respect to extreme values of the corrosion depth and rather shows
 566 sensitivities when the corrosion depth varies around the mean.

567 It is noted that the entropy results mainly reflect the sensitivities of the
 568 selected non-dimensional measures RRF and R_{twice} with respect to the un-
 569 certainty in corrosion depth. The interpretation of the results is focused on
 570 the trade-off between the effort for collection of additional information re-

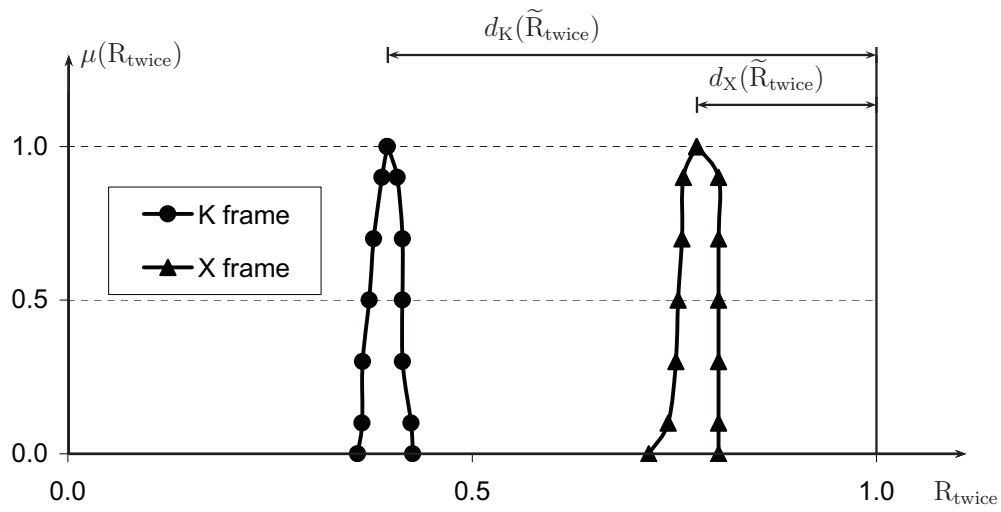


Figure 15: Membership function of \tilde{R}_{twice} for the K-braced and X-braced frames

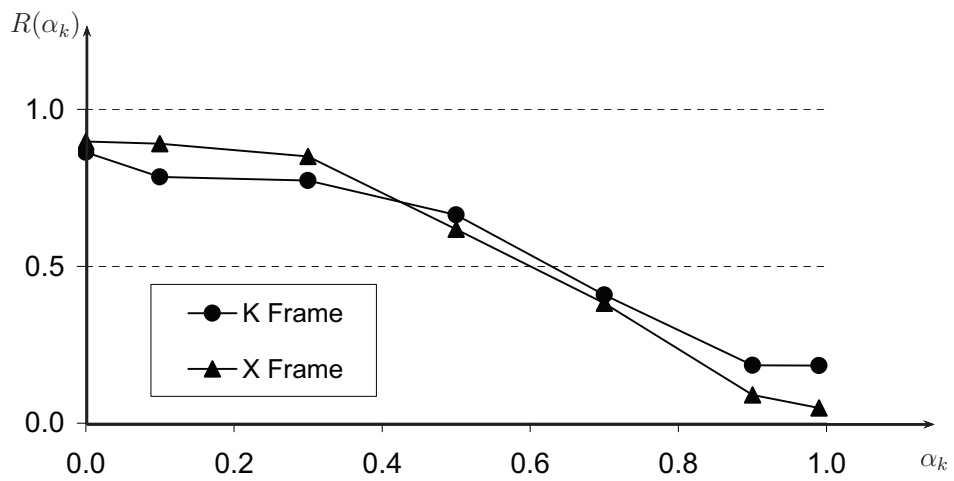


Figure 16: Robustness $R(\tilde{\beta}_{total}, \tilde{R}_{twice})$ associated with each frame with alpha-level (α_k) discretization

571 guarding the corrosion damage and the gain for the robustness assessment of
572 the structures. However, the fuzzy outputs \widetilde{RRF} and $\widetilde{R}_{\text{twice}}$ are related to the
573 frame behaviors, which becomes particularly clear in Fig. 15. The results
574 show both the imprecision of the residual strength under corrosion damage
575 and the property of structural redundancy.

576 The derived statements regarding to the effects of marine corrosion on
577 the robustness of the two platforms designed in this numerical example may
578 not be generalized to other gradual effects on the robustness or an alternative
579 design. But the proposed approach provides a general basis for the robust-
580 ness assessment of any newly designed or existing platforms with respect to
581 imprecise effects of deterioration.

582 In summary, the different effects discussed and observed in Fig. 14~16 are
583 not conflicting with each other but are complementary to formulate diverse
584 views at the robustness of the X-frame and the K-frame. The influence of
585 the framing configuration on the robustness of the fixed offshore platforms
586 can be understood in a comprehensive way based on the proposed approach.

587 **5. Conclusions**

588 An improved methodology for nuanced robustness assessment of struc-
589 tures was proposed and demonstrated for aging offshore structures subjected
590 to uncertain damage due to imprecise marine corrosion. Fuzzy variables
591 were utilized to cater for the subjective character of the assessment of the
592 corrosion effect. Structural robustness was evaluated at various membership
593 levels to reflect various degrees of imprecision in the damage. It was shown
594 that diverse views at the structural robustness can be formulated to provide

595 more comprehensive understanding of the influence of the structural layout
596 on the robustness. Engineering decisions for the design and re-analysis of
597 structures can so be generated on a broader basis. In the assessment of ex-
598 isting structures, an improved optimal resource allocation for inspection can
599 be obtained. The proposed approach provides a general basis for the assess-
600 ment of structural robustness under the consideration of fuzzy uncertainty
601 in the structural parameters. It can also be applied to robust design. For
602 a practical application one needs to implement a fuzzy structural analysis,
603 as well, which can be numerically demanding for large structures. Further
604 development on this side would benefit applications. Also, further develop-
605 ment is needed to address the invariance issue of the entropy measure for
606 fuzzy sets.

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