Fly Swarms & Complexity

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Introduction

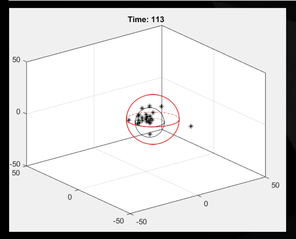
A system is considered complex if it is composed of individual parts that abide by their own set of rules while the system, as a whole, exhibits often unexpected properties. The motivation for studying complexity spurs from the fact that it is a fundamental aspect of many systems, including forest fires, earthquakes, stock markets, fish schools, plant root growth, and fly swarms. We are particularly interested in fly swarms and the possible inertial and thermodynamic properties that the swarm exhibits, arising from the individual flies.

Language of Complexity

Properties of a swarm:

- Inertia
- Thermodynamic (pressure, temperature, volume)
- Diffusion, distance from center of mass, distance between flies

Visualization of swarm surface area



Black sphere: average distance from center of mass

Red sphere: average between the black sphere and furthest out fly

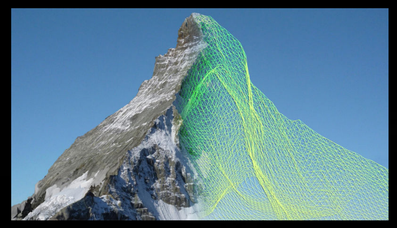
Red sphere typically used in pressure and volume calculation.

Possible phases of a swarm:

- Gas: highly dispersed fly system. Non-swarm state
- Liquid: low density swarm state
- Solid: Tightly clustered fly system. High density swarm

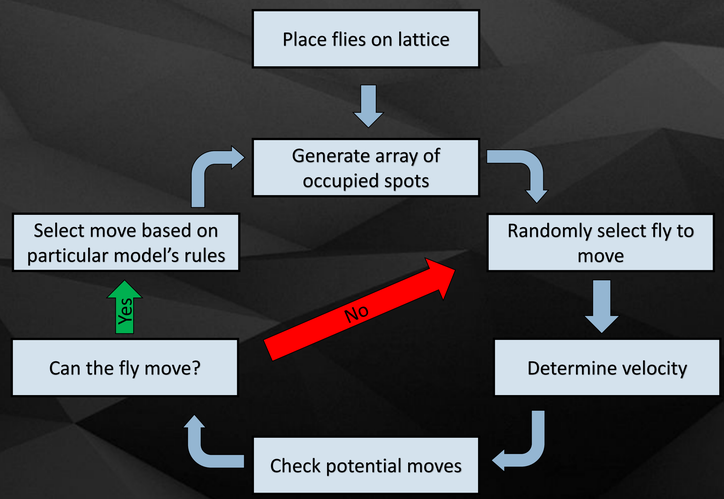
Practical Applications

- Artificial swarms (drones, etc.)
  - ❖ Mapping landscapes
  - ❖ Military applications
  - ❖ Effective in disaster zone
- Medical nanobots
  - ❖ Combat diseases

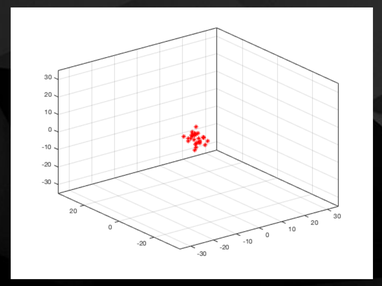


The Matterhorn mountain in the Alps was 3D-mapped in 6 hours by drones.

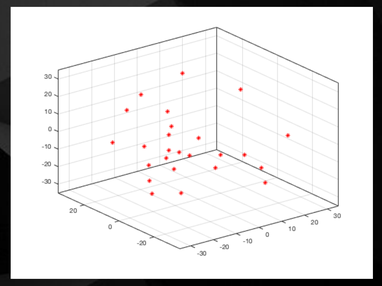
The Algorithm and Models



Initializing Flies



High initial density

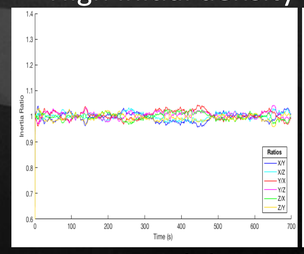
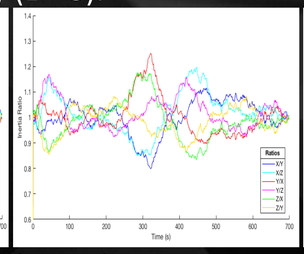
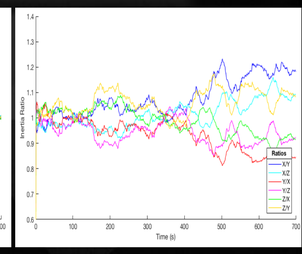
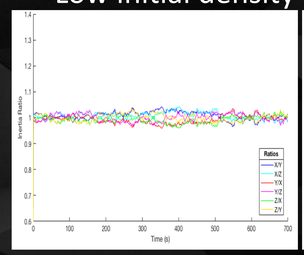
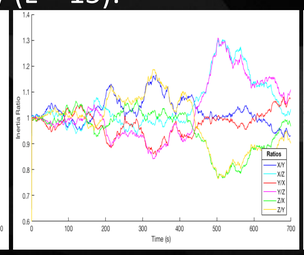
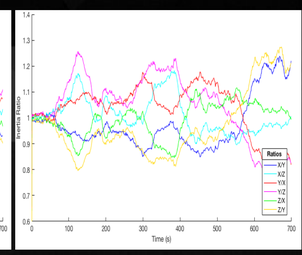


Low initial density

The Models

- Base (random walkers)
- Global (absolute) Center of Mass
- Local (relative) Center of Mass
- Combination Center of Mass
- Desired Separation
- Multi (Global, Local, and Desired Sep.)

Results and Analysis

	Base	Global COM	Local COM
High initial density (L = 5):			
Low initial density (L = 15):			

- Data was collected for 25 flies & averaged over 100 iterations
- Base model: no asymmetry in fly system shape for both initial densities
- Global & Local COM: some asymmetry for certain directions emerges over time

Future Research

- How is swarming quantitatively defined? Is the definition discrete or continuous?
- Look further into the thermodynamic perspective on fly swarms
- Examine inertia for various swarm sizes
- Compare data with other models and actual fly swarm data
- Improve upon the current models to form the most realistic model
- Do fly swarms exhibit properties associated with self-organized criticality (SOC)?

http://iopscience.iop.org/article/10.1088/1367-2630/18/7/073042
https://www.newscientist.com/article/2098307-forest-flying-takes-drone-swarms-to-places-once-off-limits/
Gorbonos, D., Ianconescu, R., Puckett, J., Ni, R., Ouellette, N. and Gov, N. Long-range acoustic interactions in insect swarms: an adaptive gravity model. *New J. Phys.*, **18(7)**, p.073042. (2016).