

1 Research Paper

# 2 **Continuous Authentication of Smartphone Users Based on** 3 **Activity Pattern Recognition Using Passive Mobile Sensing**

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10 **Abstract:** Smartphones are inescapable devices, which are becoming more and more intelligent and  
11 context-aware with emerging sensing, networking and computing capabilities. They offer a captivating  
12 platform to the users for performing a wide variety of tasks including socializing, communication, sending or  
13 receiving emails, storing and accessing personal data etc. at anytime and anywhere. Nowadays, loads of people  
14 tend to store different types of private and sensitive data in their smartphones including bank account details,  
15 personal identifiers, accounts credentials, and credit card details. A lot of people keep their personal e-accounts  
16 logged in all the time in their mobile devices. Hence these mobile devices are prone to different security and  
17 privacy threats and attacks from the attackers. Commonly used approaches for securing mobile devices such as  
18 passcode, PINs, pattern lock, face recognition, and fingerprint scan are vulnerable and exposed to several  
19 attacks including smudge attacks, side-channel attacks, and shoulder-surfing attacks. To address these  
20 challenges, a novel continuous authentication scheme is presented in this study, which recognizes smartphone  
21 users on the basis of their physical activity patterns using accelerometer, gyroscope, and magnetometer sensors  
22 of smartphone. A series of experiments are performed for user recognition using different machine learning  
23 classifiers, where six different activities are analyzed for the multiple locations of smartphone on the user's  
24 body. SVM classifier achieved the best results for user recognition with an overall average accuracy of 97.95%.  
25 A comprehensive analysis of the user recognition results validates the efficiency of the proposed scheme.

26 **Keywords:** Activity Pattern Recognition, Behavioral Biometrics, Continuous Authentication, Mobile Sensing,  
27 Smartphone User Recognition, Ubiquitous Computing

## 28 **1. Introduction**

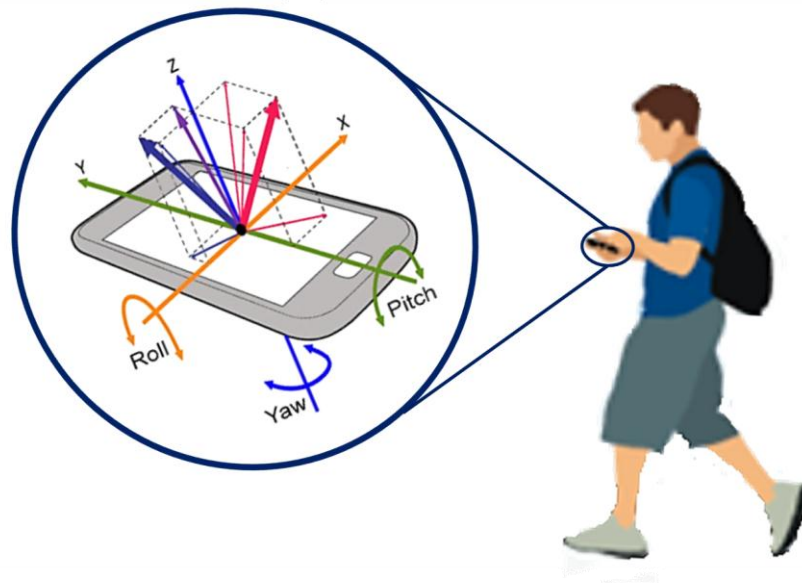
29 Smartphone and mobile technologies have become much popular in a very short span of time. We have  
30 moved from larger phones to very slim yet powerful smartphones. These devices have aided people with  
31 internet connectivity and enabled them to do their routine tasks at anytime and anywhere. At the moment, 68%  
32 of the entire world's inhabitants possesses a mobile phone and this number is anticipated to reach up to 72% by  
33 2019 ("The Statistic Portal", 2017). Smartphones have started to replace personal computers and laptops. A  
34 market research has shown that mobile phone shipments worldwide are projected to add up to 1.93 billion in  
35 2019 (Gartner, 2017). Due to the increased use of smartphones, more and more data is being produced, stored,  
36 accessed, and analyzed on these devices at homes, offices, and workplaces on daily basis. This data also  
37 includes sensitive and confidential information including personal identifiers, bank account details, and credit  
38 card information etc. As much as these mobile devices have become popular and improved worker's output, the  
39 security and privacy of sensitive data stored on these devices is still a key problem to be resolved (Krupp et al.,  
40 2017). The ever growing popularity of smartphones and mobile devices has resulted in several incentives for the  
41 attackers. The attackers are shifting their focus on mobile and hand-held devices as these devices can be stolen  
42 easily and victims' confidential data can be compromised. By stealing mobile devices, the attackers can easily  
43 reach and contaminate more machines and earn more money by misusing individuals' private details or by

44 selling their details via the black market (“Data Breaches 101: How They Happen, What Gets Stolen, and  
45 Where It All Goes”, 2018). Therefore, ensuring the privacy of sensitive information being stored on these  
46 portable devices has now become critical. Unluckily, most extensively used validation methods for  
47 smartphones and mobile devices including password, PIN (Personal Identification Number), and pattern locks  
48 provide weak authentication and have certain limitations. These schemes are subjected to several attacks, which  
49 include side-channel attacks (Spreitzer et al., 2016), smudge attacks (Meng et al., 2016), and shoulder-surfing  
50 attacks (Wakabayashi et al., 2017). Passwords and PINs need to be remembered all the time and the length of  
51 time required for their input is also frustrating (Mayron, 2015). Pattern locks may be drawn by others because of  
52 the distinctive traces of fingertip left on the phone screen after drawing a pattern. Biometric authentication  
53 schemes for mobile devices, such as face recognition and iris recognition, are influenced by the environmental  
54 conditions such as light and shelter. Fingerprint scans are subjected to spoofing and require additional hardware  
55 for their operation. Furthermore, these frequently used authentication schemes only provide entry point  
56 authentication and fail to detect and recognize a challenger after the point of entry. Hence, these methods are  
57 ineffective to apply for authenticating and recognizing a smartphone user in a continuous way.

58 To enhance the security of mobile devices and provide potential solutions to existing challenges in  
59 smartphone authentication, researchers have come up with numerous schemes, which perform authentication  
60 on the basis of behavioral biometrics (Alzubaidi and Kalita, 2016). These authentication schemes offer a way to  
61 continuously and passively authenticate different smartphone users by identifying their behavioral traits while  
62 interacting with smartphone. (Wu et al., 2016) utilized keystrokes and gestures as behavioral biometrics for  
63 continuous authentication of smartphone users. (Meng et al., 2016) proposed a touch movement based method  
64 for improving the security of pattern locks. The authors identified the users on the basis of touch movements  
65 while unlocking patterns. (Yang et al., 2015) utilized handwaving as a behavioral biometric for user  
66 authentication. (Shen et al., 2016) proposed a method to authenticate users through the action of passcode input  
67 by utilizing orientation sensors and accelerometers. (Zhang et al., 2015) identified gait pattern by using five  
68 body-worn accelerometers on different locations and utilized gait pattern as a behavioral biometric for  
69 identifying users. (Zeng, 2016) proposed the possibility of utilizing dynamic behavior based on simple activities  
70 such as walking, running, climbing, and jumping for identifying users using wearable sensors. (Cola et al.,  
71 2016) used motion data of the walking activity collected from a wrist-mounted device for user authentication.  
72 These wearable sensors and devices become a cause of interference for the users in performing their activities.  
73 Therefore, a few researchers have made use of smartphone motion sensors to develop efficient schemes for user  
74 authentication based on behavioral biometrics (Sitova et al., 2016; Neverova et al., 2016). However, the  
75 performance of these schemes is compromised by the position and orientation sensitivity of smartphone motion  
76 sensors. Moreover, the research on continuous user authentication is still very challenging due to the difficulty  
77 in collecting real time data in open and dynamic environments (Neverova et al., 2016). Therefore, it is the need  
78 of the hour to develop more efficient and reliable solutions for continuous and non-intrusive user authentication  
79 to ensure the security of mobile device.

80 In this research work, an intelligent scheme is proposed for the unobtrusive authentication and validation  
81 of smartphone users to address existing challenges in continuous authentication. The proposed scheme is based  
82 on recognition of physical activity patterns of different smartphone users for their identification. Once a user is  
83 identified, he/she can easily be validated and authorized. Our idea is to learn the activity patterns of a  
84 smartphone user to differentiate him/her from other users on the basis of his/her behavioral traits. As the  
85 authentication needs to be done in real time, therefore we have selected six real life activities of daily living for  
86 user recognition purpose. These activities include walking, sitting, standing, running, walking upstairs, and  
87 walking downstairs. These activities are likely to be performed by every normal human being for multiple times  
88 in their routine life. Moreover, people usually perform these activities in a different way from each other owing  
89 to their behavioral traits. Three smartphone embedded sensors i.e., accelerometer, gyroscope, and  
90 magnetometer, are selected to provide data corresponding to six selected activities performed by the users.  
91 These inertial sensors provide a way to recognize smartphone users based on their activity patterns as shown in  
92 Fig. 1. As in real time, the placement of smartphone on the human body is not always fixed; therefore user  
93 recognition is analyzed for five different smartphone positions on the user’s body. These positions include left  
94 thigh (left jeans pocket), right thigh (right jeans pocket), waist, upper arm, and wrist position. A smartphone  
95 needs to be in one of these positions on the user’s body for his/her recognition based on the proposed scheme.  
96 An existing dataset for physical activity recognition (Shoaib et al., 2014, 2013) is utilized for this study, which  
97 fulfills all necessary experimentation requirements. A number of time domain features are extracted from the

98 data after its preprocessing. These features are then further utilized for recognizing ten different users on the  
 99 basis of six individual activities selected in this study. For the purpose of experimentation, three different  
 100 classifiers i.e., Support Vector Machine (SVM), Decision Tree (DT), and K-Nearest Neighbors (K-NN), are  
 101 used for user recognition.



102 **Fig. 1.** Smartphone inertial sensors track the physical activity pattern of a user and provide a way to identify that  
 103 user based on activity pattern recognition

104 The significant achievements of this research work are as follow:

- 105 1. An innovative scheme is presented for continuously authenticating smartphone users, which is  
 106 based on the recognition of physical activity patterns of individual users for their identification.
- 107 2. The issue of position sensitivity of smartphone motion sensors is addressed in this study to reduce  
 108 false positives for user authentication. For this purpose, five different smartphone positions on the  
 109 user's body are analyzed for user recognition.
- 110 3. The experiments for user recognition are performed using three prevalent machine learning  
 111 classifiers and a detailed comparison is presented amongst these classifiers performance for  
 112 recognizing users. The best one provides efficient results for user identification based on activity  
 113 patten recognition.
- 114 4. As the proposed scheme is based on activity pattern recognition, a detailed analysis is presented  
 115 for six different activities, which shows the best activities and the phone positions that can be  
 116 utilized for efficient user recognition.

117 The remaining part of the paper is structured as follows: Section 2 provides a brief description of the  
 118 background and related work. Section 3 explains the methodology of research in details. Section 4 presents and  
 119 discusses the results of user recognition comprehensively and analyzes the performance of selected machine  
 120 learning algorithms for user recognition. Section 5 determines the findings of this research study and gives  
 121 recommendations for further future work.

## 122 **2. Background and Related Work**

123 With the dominant increase in computing, networking, and sensing capabilities of smartphones,  
 124 researchers have started to make use of the sensory data available from these devices to model human behavior  
 125 (Cho and Lee, 2017; Kwapisz et al., 2011; Miluzzo et al., 2010; van Deursen et al., 2015; Zhitomirsky-Geffet  
 126 and Blau, 2016) and infer certain contexts. Context-awareness has become increasingly significant as being  
 127 aware of people surroundings is very beneficial for a wide variety of pervasive applications. Human-centric  
 128 contexts, such as indoor or outdoor, at home or in office etc., have been studied extensively by the researchers  
 129 (Hoseini-Tabatabaei et al., 2013; Khan et al., 2013; Miluzzo et al., 2008; Otebolaku and Andrade, 2016). A few

130 efforts have been made on context-awareness from phones' perspective also. Sherlock framework (Yang et al.,  
131 2014) collects data from smartphone sensors and recognizes the near surroundings of the smartphone. Table 1  
132 shows a set of smartphone sensors that have been utilized in different research studies. The data acquired from  
133 these sensors have been utilized for activity recognition (Su et al., 2014; Wannenburg and Malekian, 2016) and  
134 many other aspects related to health monitoring (Lee et al., 2012; Mun et al., 2009; Pludwinski et al., 2016),  
135 social activities monitoring (Gesell et al., 2013; Harari et al., 2016; Min et al., 2013), and crowdsourcing  
136 (Chatzimilioudis et al., 2012; Consolvo et al., 2008). On-body wearable sensors have also been utilized to learn  
137 human movements and actions (Bulling et al., 2014; Ellis et al., 2013; Shoaib et al., 2016). But these wearable  
138 on-body sensors create inconvenience for the users in performing their activities. Moreover, it is hard and takes  
139 a lot of time to adjust these wearable sensors on right positions. As a result, mobile sensing has been employed  
140 for human activity recognition (Avci et al., 2010; Lockhart et al., 2012; Incel et al., 2013; Lara and Labrador,  
141 2013), which has a diversified range of significant application areas. In (Shoaib et al., 2015a), the authors  
142 provided a comprehensive survey of online activity recognition using mobile sensing. (Albert et al., 2012)  
143 utilized mobile sensing for activity recognition of Parkinson's patients. The CenceMe system (Miluzzo et al.,  
144 2008) recognizes simple physical activities like idle, walking, and running with the help of an accelerometer.  
145 Activity recognition has been further used for different applications, such as human behavior modeling  
146 (Miluzzo et al., 2010; Pei et al., 2013) and health monitoring (Mun et al., 2009). (Shoaib et al., 2015b) utilized  
147 activity recognition for the detection of bad and unusual habits of different persons. Our study aims to utilize  
148 activity pattern recognition for validating smartphone users.

149 The research on smartphone authentication is progressing and researchers have come up with some  
150 dominant work in recent years. In literature, there exist different approaches for reliable and efficient  
151 recognition of smartphone users using physiological and behavioral biometrics. (Song et al., 2016) presented a  
152 novel framework for smartphone user authentication called EyeVeri, which is based on tracking human eye  
153 movement using front camera of smartphone. The authors explored different gaze patterns i.e., volitional and  
154 non-volitional, using pattern matching algorithms to provide access authentication. An in-depth analysis of the  
155 evaluation results showed that the proposed scheme works effectively. (Alzubaidi and Kalita, 2016) provided a  
156 detailed review of seven different types of behavioral biometrics, including walking style, touchscreen  
157 interaction, signature, handwaving, keystroke dynamic, voice, and behavior sketching. (Yang et al., 2015)  
158 proposed OpenSesame, a scheme to authenticate users on the basis of handwaving patterns. SVM classifier was  
159 used for classifying a user as authorized or unauthorized. (Shrestha et al., 2013) proposed a scheme called  
160 Wave-to-Access, which is based on recognition of handwaving gestures. An embedded smartphone sensor i.e.,  
161 ambient light sensor, was used to examine phone dialing behavior for authentication purposes. Using  
162 handwaving scheme for authentication purposes has certain limitations, for example, it cannot authenticate a  
163 user continuously and passively all the time. (Papadopoulos et al., 2017) addressed the challenges of  
164 shoulder-surfing attacks in their study. The authors proposed IllusionPin (IPIN) for user authentication, which  
165 utilized hybrid images for blending two keypads for keypad illusion. (Sitova et al., 2016) introduced a  
166 behavioral authentication scheme based on Hand Movement, Orientation, and Grasp (HMOG) features for  
167 continuous and unobtrusive user authentication. HMOG features keep track of how a user grasps, holds, and  
168 taps on the smartphone. The authors achieved an EER (Equal Error rate) as minimum as 7.16%, which shows  
169 the effectiveness of their proposed scheme. (Draffin et al., 2014) presented KeySens, in which the behavior of  
170 the user was learnt by utilizing the pattern of user's interaction with the keyboard. The authors examined  
171 touchscreen interactions of the smartphone users based on the movement of fingers, touch force, and the area  
172 enclosed by the fingers. (Feng et al., 2013) came up with Typing Authentication and Protection (TAP) scheme  
173 for user authentication. TAP included login and post log-in phases to validate a user by exploiting the password  
174 and biometric information. The experimental results were validated using three different classifiers out of which  
175 Random Forest gave lowest False Acceptance Rate (FAR) of 8.93%. (Frank et al., 2013) also validated the use  
176 of touchscreen interactions as a behavior biometric for user verification. (Trojahn and Ortmeier, 2013) used a  
177 combination of keystroke and handwriting analysis for authentication purpose. (Zheng et al., 2014) utilized a  
178 combination of smartphone inertial and touchscreen sensors for validating a smartphone user. (Shahzad et al.,  
179 2013) proposed a gesture based user authentication approach to provide safe unlocking facility for touchscreen  
180 devices. Different features including finger velocity, device acceleration, and stroke time were used to learn  
181 how a user input data. The authentication schemes based on keystrokes and touchscreen interactions take a lot  
182 of time for training and learning the keystroke and touchscreen interaction patterns for a user. Moreover,  
183 keystrokes or touchscreen patterns of a user change with the passage of time as the behavior of the user changes.

**Table 1.** A set of smartphone embedded sensors

Sensor	Description
Accelerometer	Measures the acceleration force applied to the device including the force of gravity
Linear Accelerometer	Measures the acceleration force applied to the device excluding the force of gravity
Gyroscope	Measures the device rotation by using the roll, pitch, and yaw motions of the smartphone along three axes (x, y, z)
Magnetometer	Measures the ambient geomagnetic field in three axes (x, y, z)
Light Sensor	Measures the ambient light level i.e., illumination
Humidity Sensor	Measures the humidity of ambient environment
Proximity Sensor	Measures the closeness of an object relative to device screen
Barometer	Measures the ambient air pressure

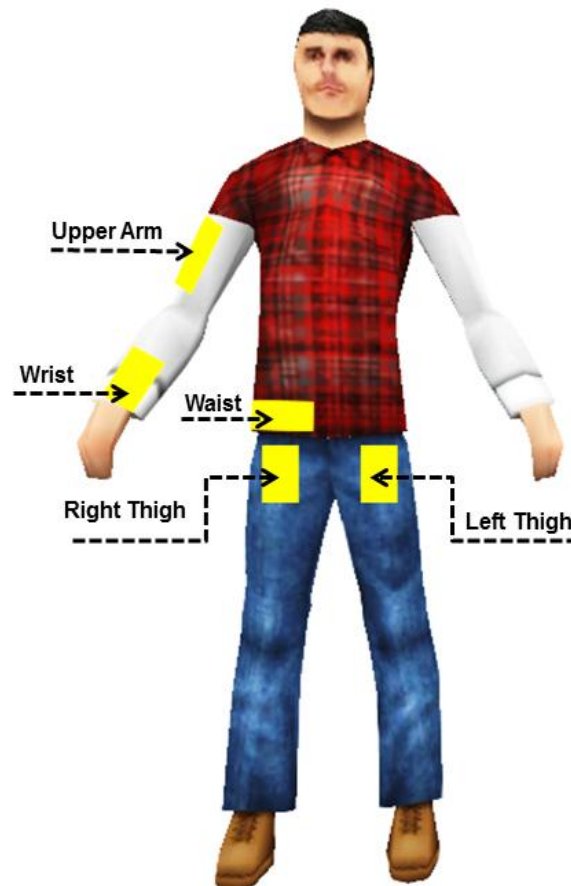
185 A few researchers have worked on utilizing physiological sensors for identity authentication. (Camara et  
 186 al., 2015) formulated a scheme that identifies a user by utilizing Electrocardiogram (ECG) signals. Different  
 187 features were extracted from ECG signals and K-NN classifier was applied for the purpose of user  
 188 identification. The experiments reported that their proposed scheme achieved a mean accuracy of 97%. Another  
 189 identity authentication approach was proposed by (Hejazi et al., 2016), where the authors used a multi-class  
 190 SVM for user identification after applying Discrete Wavelet Transform (DWT) on ECG signals. The  
 191 experiments reported 3.97% false match rate. (Kang et al., 2016) utilized smartwatch sensors for recording the  
 192 ECG signals of different participants. The participants were kept in an exact motion state, which restricted the  
 193 practical application of the proposed scheme. The experimental results presented an FAR of around 5%. These  
 194 research studies proved that the ECG signals provide an impending solution of user authentication problem.  
 195 However, the placement of ECG sensors and equipment on the user's body, such as at chest or hand, creates  
 196 inconvenience for the user.

197 Another approach for validating smartphone users is the use of smartphone inertial sensors for obtaining  
 198 data related to behavioral traits of different users. (Zhu et al., 2017) proposed a novel user authentication  
 199 scheme called ShakeIn, which learns how a smartphone user shakes the phone to lock/unlock it. The biometric  
 200 features of the users' shaking behavior were captured with the help of embedded motion sensors of the  
 201 smartphone. The experiments were performed on 20 participants with 530,555 shaking samples in total. The  
 202 results described an Equal Error Rate (EER) of 1.2% on average. (Buriro et al., 2017) made use of user's hand  
 203 movement patterns for authentication purpose. The data was collected using smartphone embedded sensors and  
 204 Random Forest (RF) classifier was used for evaluating the results. An EER rate of 96% was achieved by the  
 205 system. Gait recognition with motion sensors provides a gateway for user authentication. It tends to identify and  
 206 recognize the walking pattern of a person, e.g. walking style of a user under different conditions. (Damaševičius  
 207 et al., 2016; Fernandez-Lopez et al., 2016) utilized smartphone internal motion sensors for validating users  
 208 based on gait characteristics. (San-Segundo et al., 2016) used smartphone inertial sensors to develop a  
 209 Gait-based Person Identification (GPI) scheme based on a Gaussian Mixture Model-Universal Background  
 210 Model (GMM-UBM). The results showed a User Recognition Error Rate (URER) of 34%. (Derawi et al., 2010)  
 211 exploited smartphone motion sensors for extracting information about walking cycles. They achieved an EER  
 212 of 20.1%. (Mäntyjärvi et al., 2005) recognized users by utilizing their walking style using data from  
 213 accelerometer. The research work on gait recognition and walking pattern detection is extended to recognize  
 214 more physical activities for user identification. A number of studies focused on recognizing activities and  
 215 gestures using motion sensors, including approaches based on deep learning. (Neverova et al., 2016) proposed a  
 216 scheme for learning human identity based on their motion patterns using deep neural networks. This scheme  
 217 achieved and EER of 20%.

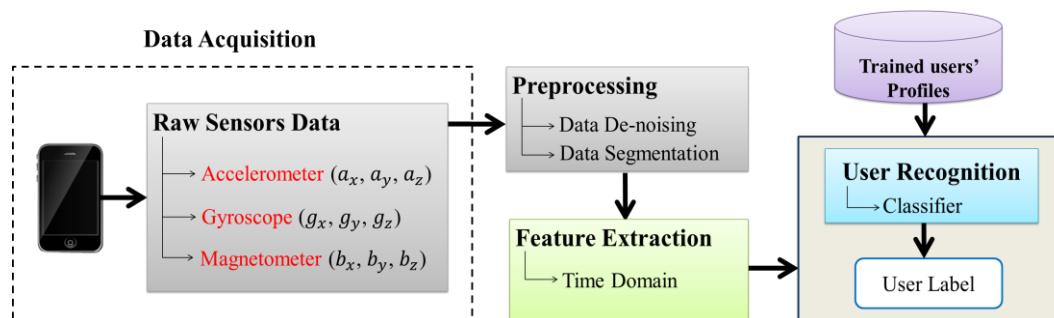
218 In our study, we analyzed the existing challenges in smartphone user authentication and presented a  
 219 reliable and applicable solution for continuous user authentication. We used smartphone inertial sensors for  
 220 learning and recognizing the physical activity patterns of individual users for six different activities of daily  
 221 living. Hence, the users are identified on the basis of their behavioral traits.

### 222 3. Methodology of Research

223 This research study primarily focuses on learning, identifying, and recognizing behavioral patterns of  
224 different users whilst they are using their smartphones. In this work, six different daily living activities i.e.,  
225 walking, running, standing, sitting, walking upstairs, and walking downstairs, are used for the purpose of user  
226 validation. Numerous researches have been carried out on identifying and recognizing these activities from each  
227 other (Su et al., 2014; Anguita et al., 2013; Avci et al., 2010; Lockhart et al., 2012; Incel et al., 2013), where the  
228 motivation is to learn and differentiate between these individual activities. This research work focuses on  
229 recognizing the pattern of these activities for individual users. The aim is to recognize the differences among the  
230 behavioral patterns of different users for the same activity. For this purpose, we trained the system to learn the  
231 behavioral patterns of individual users for six different activities. Smartphone users are then identified by the  
232 system on the basis of the way they perform a certain activity. To avoid false positives occurring because of the  
233 changing location of smartphone on the user's body, we trained the system to identify users for five different  
234 and commonly used smartphone positions. These positions are shown in Fig. 2. As behavioral authentication  
235 involves continuous collection of a user's motion data from the device, therefore, the proposed system  
236 continuously collects and processes small portion of sensors data in a passive way in order to authenticate a user  
237 in real time scenarios. The proposed system recognizes the user from the collected portion of data on the basis of  
238 his/her activity pattern. The proposed research methodology is shown in Fig.3, which consists of following  
239 steps: raw data collection, preprocessing (data-denoising and segmentation), feature extraction, and user  
240 recognition.



241 **Fig. 2.** Possible positions for the placement of smartphone on the user's body. A smartphone user is required to  
242 place his/her phone in one of these body positions to get identified according to the proposed scheme.



243 **Fig. 3.** Proposed scheme for smartphone user recognition

244 **Table 2.** Details of the dataset selected in this study for experimentation

Property	Details						
	<b>Total</b>	<b>Activity names</b>					
Activities	<b>06</b>	Walking	Sitting	Standing	Running	Walking upstairs	Walking downstairs
	<b>Total</b>	<b>Gender</b>				<b>Age</b>	
Actors	<b>10</b>	Male				25-30	
Activity duration	03 minutes per actor for a single position of smartphone on actor's body						
	<b>Total</b>	<b>Position names</b>					
Smartphone positions	<b>05</b>	Left pocket	Right pocket	Waist	Upper arm	Wrist	
Data collection device	Samsung Galaxy S-II (i9100) smartphones						
Sampling rate	50 Hz						
sensors	Accelerometer, Gyroscope, and Magnetometer						

### 245 3.1. Raw Data Collection : Dataset

246 To validate the proposed scheme, an existing dataset for physical activity recognition (Shoaib et al., 2013,  
 247 2014) was used. This dataset was selected because it was consistent to the pipeline of the proposed scheme.  
 248 Table 2 describes the properties of this dataset. Three sensors were used for the purpose of data collection as  
 249 shown in Table 2. The accelerometer was used to measure acceleration in meter per second square ( $m/s^2$ ), the  
 250 magnetometer was employed to report magnetic field in micro tesla ( $\mu T$ ), and the gyroscope was used to  
 251 measure the angular rotation in radians per second ( $rad/s$ ) along each axis. The data collected from smartphone  
 252 sensors had the form  $\{a_x, a_y, a_z, g_x, g_y, g_z, b_x, b_y, b_z\} \in \mathbb{R}^9$ , where 'a' and 'g' represent the acceleration, and  
 253 rotation respectively whereas, 'b' represents the strength of the magnetic field along x, y and z axes.

### 254 3.2. Preprocessing : Data De-noising and Segmentation

255 Inertial sensors of the smartphone are sensitive to interferences such as noise. The signals acquired from  
 256 these sensors are subjected to undesirable noise produced by unanticipated and vibrant movements of the  
 257 participants. This noise corrupts useful information contained in the signal. Therefore, the removal of unwanted  
 258 noise from the signal is necessary before further processing. In our case, the noisy data obtained from  
 259 smartphone inertial sensors was de-noised using an average smoothing filter of size  $1 \times 3$ . Noise was removed  
 260 from whole sample data by applying the averaging filter separately along all three dimensions of accelerometer,  
 261 gyroscope, and magnetometer. As smartphone inertial sensors are orientation sensitive, therefore the magnitude

262 of the sensor that is independent of the sensor orientation was also concatenated with the existing three  
 263 dimensions of each sensor. After adding fourth dimension, each sensor data was of the form  $(x, y, z, \text{mag})$ . For  
 264 each sensor, magnitude is simply calculated as:  $\text{mag} = \sqrt{x^2 + y^2 + z^2}$ .

265 Before feature extraction from the preprocessed data, the sensors data was divided into smaller segments  
 266 using a fixed-size sliding window. The selection of the length of sliding window is crucial as the final accuracy  
 267 of recognition is affected by the length of the sliding window. Different researchers (Shoaib et al., 2013; Anjum  
 268 and Ilyas, 2013) have shown that simple physical activity patterns can be recognized within 5 seconds duration.  
 269 This led us to use a fixed-size slicing window having a length of 5 seconds in time with 250 samples at the rate  
 270 50 Hz. A 50% overlap was selected between the samples during the segmentation and the whole sensors data  
 271 along each dimension was divided into small chunks of 5 seconds for feature extraction.

272 **Table 3.** A set of time domain features for user recognition

Features	Formula
Maximum Amplitude	$s_{\max} = \max\{s(n)\}$
Minimum Amplitude	$s_{\min} = \min\{s(n)\}$
Mean	$\mu = \frac{1}{N} \sum s(n)$
Variance	$\sigma^2 = \frac{1}{N} \sum (s(n) - \mu)^2$
Kurtosis	$K = (m_4/m_2^2)$ , where $m_2$ and $m_4$ are the 2 <sup>nd</sup> and 4 <sup>th</sup> moment about the mean
Skewness	$S = (m_3)/(m_2^{3/2})$ , where $m_3$ is the 3 <sup>rd</sup> moment about the mean
Energy	$E = \sum  S(n) ^2$
Entropy	$H(S(n)) = - \sum_{i=1}^N p_i(S(n)) \log_2 p_i(S(n))$
Mean of Absolute Value of First Difference	$\mu_{\nabla} = \frac{1}{N} \sum  s(n) - s(n-1) $
Mean of Absolute Value of Second Difference	$\mu_{\Delta} = \frac{1}{N} \sum  s(n+1) - 2s(n) + s(n-1) $
Peak-to-Peak Signal Value	$s_{pp} = s_{\max} - s_{\min}$
Maximum Latency	$n_{s_{\max}} = \{n   s(n) = s_{\max}\}$
Minimum Latency	$n_{s_{\min}} = \{n   s(n) = s_{\min}\}$
Peak-to-Peak Time	$t_{pp} = n_{s_{\max}} + n_{s_{\min}}$
Peak-to-Peak Slope	$s_{pps} = \frac{s_{pp}}{t_{pp}}$
Absolute Latency to Amplitude Ratio	$ALAR = \left  \frac{n_{s_{\max}}}{s_{\max}} \right $



### 273 3.3. Feature Extraction

274 Once the data was preprocessed, next step was to extract suitable features that can discriminate between the  
275 activity patterns of different users so that the users can be identified accurately. For this purpose, we selected  
276 sixteen different features from the time domain. Most of these features have been utilized by the earlier studies  
277 for physical activity recognition (Anjum and Ilyas, 2013; Incel et al., 2013; Shoaib et al., 2014, 2013; Su et al.,  
278 2014). These studies have demonstrated the excellent performance of these features for recognizing the activity  
279 patterns. First and second difference of the signal highlights the varying information in the signal and provides  
280 the edges and sharp changes in the signal. Similarly, maximum and minimum latency, peak-to-peak time,  
281 peak-to-peak slope, and latency to amplitude ratio also gives us useful information about the signal. Hence these  
282 features are useful descriptors of the signal and helpful in recognizing different activity patterns. Table 3  
283 provides the details of the features selected in this study. All of these features were extracted for each  
284 partitioned data segment i.e.,  $s[n]$ , along all four channels of three sensors.

### 285 3.4. User Recognition

286 After feature extraction, next step was to choose a suitable classifier for the purpose of user recognition  
287 based on extracted features. In this work, different supervised machine learning approaches were used. As there  
288 were ten participants in the experiment, therefore the recognition of each individual participant was a  
289 multi-class classification problem. Three prevalent classifiers i.e., Support Vector Machine (SVM), Decision  
290 Tree and K-Nearest Neighbors (K-NN) were used to recognize individual users from their activity patterns.  
291 These classifiers were trained separately for different activity patterns of all the participants. The main reason  
292 for the selection of these classifiers was their efficient performance in existing studies pertinent to physical  
293 activity recognition (Anjum and Ilyas, 2013; Incel et al., 2013; Shoaib et al., 2014, 2013; Su et al., 2014).  
294 Moreover, we intended to provide a performance comparison of these classifiers for recognizing users from  
295 their activity patterns, which is given in Section 4. These classifiers are described in the following sections.

#### 296 3.4.1. Decision Tree

297 Decision Tree (Kohavi, 1996) is a non-parametric supervised machine learning approach used  
298 for classification and regression. This approach aims to build up a model that envisages the value of a target  
299 variable by learning simple rules for decisions. These rules are deduced from the features extracted from the  
300 input data. Decision tree uses an if-then-else structure for making decisions about classification. It is  
301 computationally cheap with excellent interpretation, therefore it is considered as one of the key classifiers in  
302 numerous activity recognition studies (Su et al., 2014; Shoaib et al., 2013). The problem in using Decision Tree  
303 as a classifier lies in updating the already built model to accommodate new training samples as it might be very  
304 expensive (Su et al., 2014).

#### 305 3.4.2. K-Nearest Neighbors

306 K-Nearest Neighbors (Guo et al., 2003) is an instance-based classifier, which is based on the majority  
307 voting of its neighbors (Peterson, 2009). It is one of the most commonly used algorithms for recognizing  
308 patterns. It works by assigning a feature vector extracted from the input data to a class according to its nearest  
309 neighbor(s). The neighbor can be a class prototype or a feature vector from the training set. The nearest  
310 neighbor is determined by calculating the distance between the feature vectors. It is a discriminative non-linear  
311 classifier. A number of distance measures can be used in K-NN classification like Chebyshev, Manhattan or  
312 Minkowski but Euclidean distance is usually the default measure used.

#### 313 3.4.3. Support Vector Machine

314 Support Vector Machine (Cortes and Vapnik, 1995) is a non-probabilistic classifier that has successful  
315 applications in classification and regression. Support Vector Machine utilizes decision planes for outlining  
316 decision boundaries. A decision plane is capable of separating a set of objects with different class associations.  
317 Given a set of labeled training examples for the two classes, the training algorithm of SVM formulates a model  
318 that allocates new samples to one of the two classes. An SVM model denotes different examples as points in  
319 space, which are dispersed such that the examples pertaining to different classes are separated by a clear gap  
320 using support vectors. New examples are then mapped into the same space and assigned to a class depending  
321 upon which side of the gap they fall. SVM resists the overtraining problem and ultimately achieves a high  
322 generalization performance.

## 323 4. Experimental Results

324 In order to perform continuous authentication of smartphone users, the proposed scheme performed the  
 325 recognition of activity patterns for individual users. Hence, the users were identified based on their activity  
 326 patterns. The performance of the proposed scheme was evaluated using three different classifiers: SVM, DT,  
 327 and KNN. These classifiers were trained and tested on the dataset for six activities. The dataset was pre-labeled  
 328 for all six activities performed by ten different users. The users who performed these activities were labeled as  
 329 well. It means that the ground truth was available for the activities as well as for the users performing those  
 330 activities. So, our idea was to exploit the dataset for recognizing individual users from this labeled activity data.  
 331 For this reason, we combined the data of all the users related to same activity at the same body position and  
 332 assigned user labels to the data according to the ground truth. For example, the labeled data of the walking  
 333 activity for a single body position was combined for all the participants and the user labels were assigned to the  
 334 data. These user labels were representing the walking activity patterns of different participants. This process  
 335 was repeated for each activity data for all body positions. It was done in order to train the selected classifiers for  
 336 activity patterns of individual users. For every activity, the classifiers were trained for all five body positions  
 337 separately to recognize ten different users. For this purpose, sixteen different features (as described in Table 3)  
 338 were extracted for all four dimensions of accelerometer, gyroscope, and magnetometer. These sixteen features,  
 339 extracted from four dimensions of three sensors, were concatenated into a single feature vector of size  
 340  $16 \times 4 \times 3 = 192$  computed over a data segment of 5 seconds (250 samples with 50 Hz sampling rate) in time.  
 341 As mentioned earlier, the duration of each activity data was 3 minutes (180 seconds), therefore using a 50%  
 342 overlapping sliding window, total  $\frac{180}{2.5} - 1 = 71$  feature vectors were computed related to each activity for a  
 343 single body position. For total ten participants,  $71 \times 10 = 710$  feature vectors were computed for each activity.  
 344 The feature vectors computed for each activity were passed as input to the selected classifiers along with the  
 345 user labels for classifiers training to recognize users from their activity patterns.

### 346 4.1. Evaluation Approach and Performance Metrics

347 To validate the performance of different classifiers, the data was divided into training and testing splits  
 348 using k-fold cross validation scheme with  $k=10$ , and the classifiers were evaluated. For K-NN classifier, the  
 349 nearest neighbor parameter K was set equal to 1 and Euclidean distance metric with equal weight was used for  
 350 similarity measure. In case of DT classifier, the standard Classification and Regression Trees (CART)  
 351 algorithm (Breiman et al., 1984) was used for creating the decision tree and the nodes were split using Gini's  
 352 diversity index as a split criterion. A linear kernel was used for SVM classifier and one-vs-one multi-class  
 353 method was used for classification. In Table 4, different performance metrics are given on the basis of which the  
 354 performance of these classifiers was measured for user recognition. These performance measures are computed  
 355 separately pertaining to each activity for five different body positions. .

356 **Table 4.** Performance metrics for evaluating classifiers performance for user recognition are: Accuracy (A),  
 357 Precision (P), Recall (R), F-measure (F), and Error Rate (E). Here  $t_p$ ,  $t_n$ ,  $f_p$ , and  $f_n$  represent true positives,  
 358 true negatives, false positives, and false negatives respectively.

Metric	Formula
Accuracy	$A = \frac{t_p + t_n}{t_p + t_n + f_p + f_n}$
Precision	$P = \frac{t_p}{t_p + f_p}$
Recall	$R = \frac{t_p}{t_p + f_n}$
F-measure	$F = 2 \left( \frac{P \cdot R}{P + R} \right)$
Error Rate	$E = 1 - A$

359 **4.2. Performance Analysis of User Recognition**

360 This section provides the results of user recognition based on six selected activities. For every activity, the  
 361 results are presented for five different positions of the smartphone on the user's body. To make a comparison  
 362 between the classifiers performance in recognizing the users, the results are computed for each selected  
 363 classifier i.e., DT, K-NN, and SVM. Table 5 to Table 10 summarizes the results of user recognition based on  
 364 walking, running, standing sitting, walking upstairs, and walking downstairs activity respectively. It can be  
 365 observed from these tables that overall performance of SVM classifier is better than DT and K-NN classifiers in  
 366 recognizing the users from their activity patterns.

367 **Table 5.** Performance measures of selected classifiers for user recognition based on *walking* activity

Classifier	Accuracy	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.989	0.989	0.989	0.989	0.011	Waist
K-NN	0.989	0.989	0.989	0.989	0.011	
SVM	0.996	0.996	0.996	0.996	0.004	
DT	0.966	0.966	0.966	0.966	0.034	Left Pocket
K-NN	0.976	0.976	0.976	0.976	0.024	
SVM	1	1	1	1	0	
DT	0.986	0.986	0.986	0.986	0.014	Right Pocket
K-NN	0.974	0.975	0.973	0.974	0.026	
SVM	1	1	1	1	0	
DT	0.945	0.946	0.945	0.946	0.055	Upper Arm
K-NN	0.973	0.973	0.973	0.973	0.027	
SVM	0.994	0.994	0.994	0.994	0.006	
DT	0.983	0.983	0.983	0.983	0.017	Wrist
K-NN	0.989	0.989	0.989	0.989	0.011	
SVM	0.994	0.994	0.994	0.994	0.006	

368 **Table 6.** Performance measures of selected classifiers for user recognition based on *running* activity

Classifier	Accuracy	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.982	0.982	0.982	0.982	0.018	Waist
K-NN	0.972	0.972	0.972	0.972	0.028	
SVM	0.997	0.997	0.997	0.997	0.003	
DT	0.972	0.972	0.972	0.972	0.0280	Left Pocket
K-NN	0.989	0.989	0.989	0.989	0.011	
SVM	0.999	0.999	0.999	0.999	0.001	
DT	0.966	0.967	0.966	0.967	0.034	Right Pocket
K-NN	0.983	0.983	0.983	0.983	0.017	
SVM	1	1	1	1	0	
DT	0.975	0.975	0.975	0.975	0.025	Upper Arm
K-NN	0.975	0.975	0.975	0.975	0.025	
SVM	0.993	0.993	0.993	0.993	0.007	
DT	0.963	0.963	0.963	0.963	0.037	Wrist
K-NN	0.975	0.975	0.975	0.975	0.025	

SVM	0.996	0.996	0.996	0.996	0.004
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369

**Table 7.** Performance measures of selected classifiers for user recognition based on *standing* activity

Classifier	Accuracy	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.990	0.991	0.990	0.990	0.010	Waist
K-NN	0.879	0.880	0.879	0.880	0.121	
SVM	0.994	0.994	0.994	0.994	0.006	
DT	0.975	0.975	0.975	0.975	0.025	Left Pocket
K-NN	0.766	0.770	0.766	0.768	0.234	
SVM	0.959	0.963	0.959	0.961	0.041	
DT	0.954	0.954	0.954	0.954	0.046	Right Pocket
K-NN	0.845	0.847	0.845	0.846	0.155	
SVM	0.966	0.967	0.966	0.967	0.034	
DT	0.951	0.951	0.951	0.951	0.049	Upper Arm
K-NN	0.734	0.755	0.734	0.744	0.266	
SVM	0.954	0.955	0.954	0.954	0.046	
DT	0.952	0.953	0.952	0.952	0.048	Wrist
K-NN	0.841	0.840	0.841	0.841	0.159	
SVM	0.970	0.970	0.970	0.970	0.030	

370

**Table 8.** Performance measures of selected classifiers for user recognition based on *sitting* activity

Classifier	Accuracy	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.991	0.991	0.991	0.991	0.009	Waist
K-NN	0.811	0.817	0.811	0.814	0.189	
SVM	0.989	0.989	0.989	0.989	0.010	
DT	0.992	0.992	0.992	0.992	0.008	Left Pocket
K-NN	0.904	0.906	0.904	0.905	0.096	
SVM	0.993	0.993	0.993	0.993	0.007	
DT	0.986	0.986	0.986	0.986	0.014	Right Pocket
K-NN	0.934	0.936	0.934	0.935	0.066	
SVM	0.992	0.992	0.992	0.992	0.008	
DT	0.955	0.955	0.955	0.955	0.045	Upper Arm
K-NN	0.844	0.849	0.844	0.846	0.156	
SVM	0.983	0.983	0.983	0.983	0.017	
DT	0.945	0.945	0.945	0.945	0.055	Wrist
K-NN	0.863	0.870	0.863	0.867	0.137	
SVM	0.968	0.968	0.968	0.968	0.032	

371

**Table 9.** Performance measures of selected classifiers for user recognition based on *walking upstairs* activity

Classifier	Accuracy	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.963	0.963	0.963	0.963	0.0370	Waist

K-NN	0.966	0.968	0.966	0.967	0.0340	
SVM	0.986	0.986	0.986	0.986	0.0140	
DT	0.903	0.905	0.903	0.904	0.0970	
K-NN	0.911	0.913	0.911	0.912	0.0890	Left Pocket
SVM	0.986	0.986	0.986	0.986	0.0140	
DT	0.901	0.903	0.901	0.902	0.0990	
K-NN	0.925	0.926	0.925	0.926	0.0750	Right Pocket
SVM	0.987	0.988	0.987	0.988	0.0130	
DT	0.858	0.865	0.858	0.861	0.142	
K-NN	0.883	0.891	0.883	0.887	0.117	Upper Arm
SVM	0.975	0.977	0.975	0.976	0.0250	
DT	0.862	0.865	0.862	0.864	0.138	
K-NN	0.858	0.860	0.858	0.859	0.142	Wrist
SVM	0.969	0.970	0.969	0.970	0.0310	

372  
373

**Table 10.** Performance measures of selected classifiers for user recognition based on *walking downstairs* activity

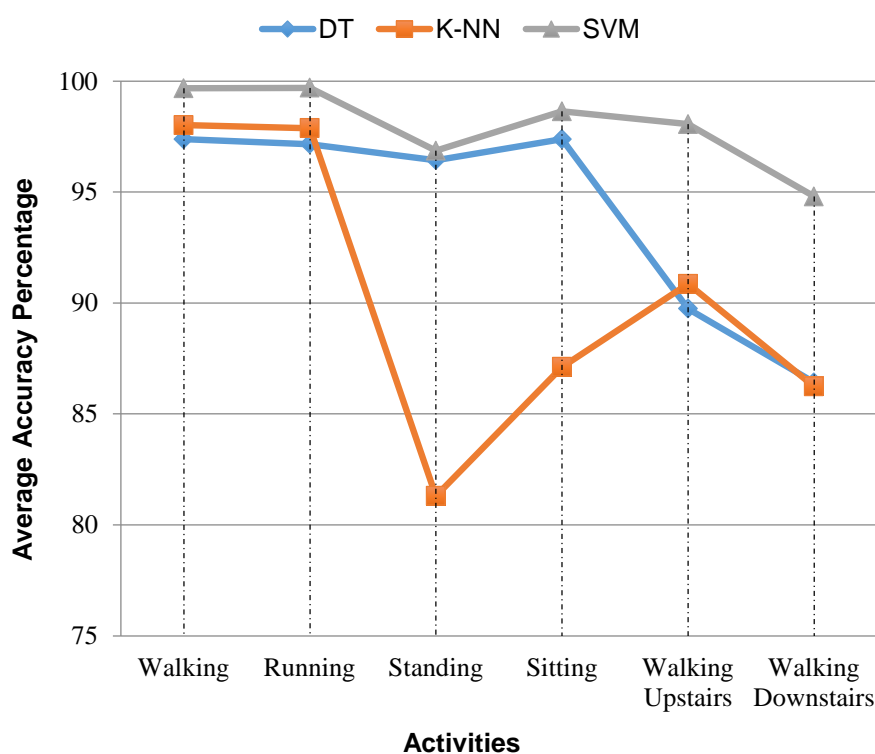
Classifier	Average	Precision	Recall	F-measure	Error Rate	Phone Position
DT	0.911	0.914	0.911	0.912	0.0890	
K-NN	0.918	0.919	0.918	0.919	0.0820	Waist
SVM	0.952	0.954	0.952	0.953	0.0480	
DT	0.901	0.903	0.901	0.902	0.0990	
K-NN	0.877	0.888	0.877	0.883	0.123	Left Pocket
SVM	0.959	0.961	0.959	0.960	0.0410	
DT	0.904	0.905	0.904	0.904	0.0960	
K-NN	0.863	0.866	0.863	0.864	0.137	Right Pocket
SVM	0.965	0.968	0.965	0.966	0.035	
DT	0.811	0.820	0.811	0.815	0.189	
K-NN	0.813	0.818	0.813	0.815	0.187	Upper Arm
SVM	0.927	0.931	0.927	0.929	0.073	
DT	0.794	0.804	0.794	0.799	0.206	
K-NN	0.841	0.850	0.841	0.846	0.159	Wrist
SVM	0.937	0.937	0.937	0.937	0.063	

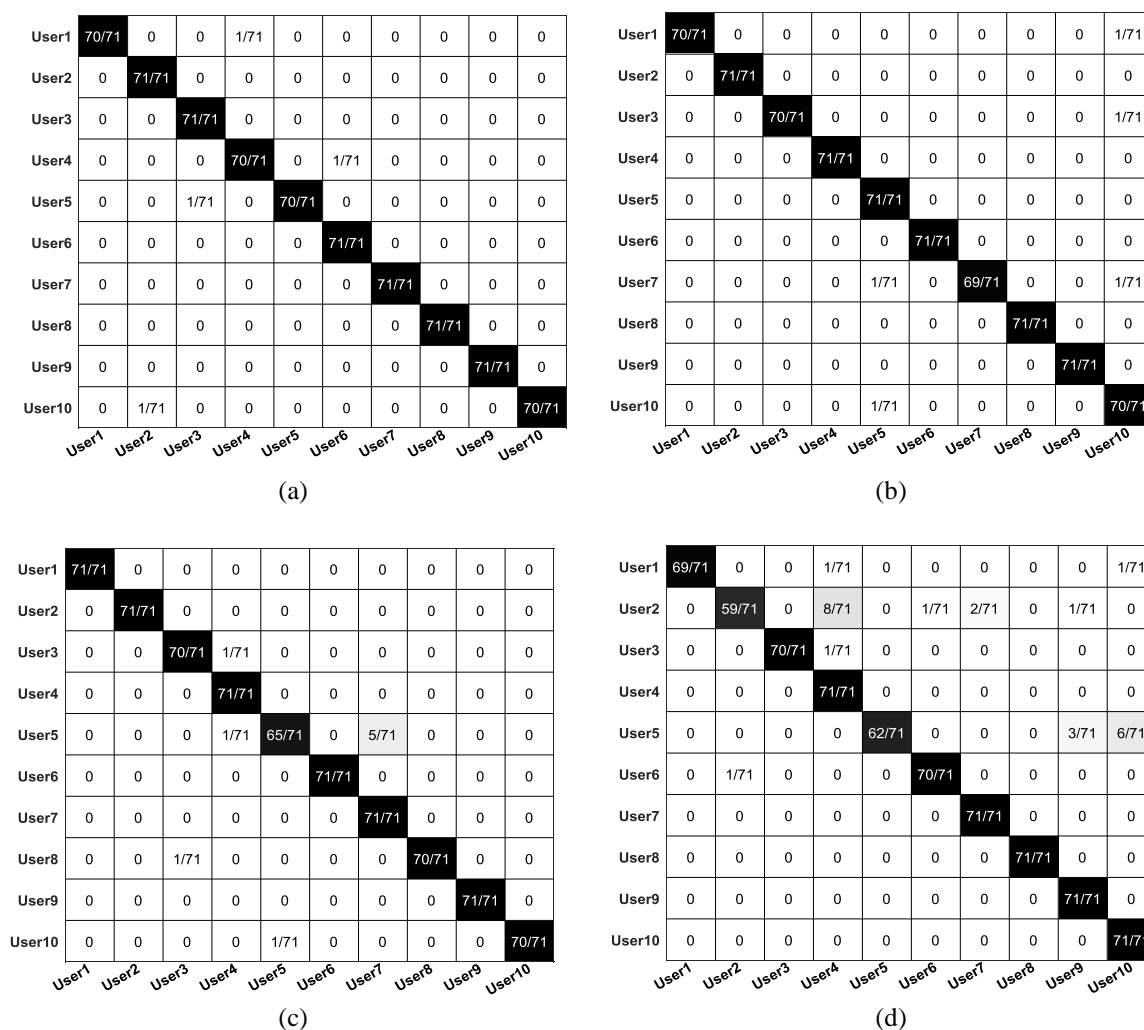
374 In case of walking activity, SVM classifier achieved an accuracy of 100% in recognizing the users when the  
375 smartphone was placed in their left jeans pocket or right jeans pocket. For the same activity, DT and K-NN  
376 classifiers achieved 96.6% and 97.6% accuracy for the left pocket position and an accuracy of 98.6% and 97.3%  
377 for the right pocket position respectively. The values of other performance metrics i.e., precision, recall, and  
378 f-measure were also better for SVM classifier. For the waist and wrist positions, SVM classifier achieved 99.6%  
379 accuracy. However, the recognition accuracies obtained for DT and K-NN classifiers are 98.9% for the waist  
380 position, and 98.9% and 98.3% for the wrist position respectively. The worst accuracy achieved by SVM, DT,  
381 and K-NN classifiers in recognizing users from walking activity is for upper arm position as shown in Table 5.  
382 These results state that recognizing users from their walking activity is easier if the phone is kept in their left or  
383 right pocket as compare to other positions. Keeping phone at upper arm position makes it difficult to recognize

384 a user based on walking pattern. The same thing can be said for identifying users on the basis of running activity  
 385 as indicated by the results in Table 6.

386 On the basis of standing activity, the users are best recognized for the case when the smartphone was  
 387 hanged with a belt clipper. The best accuracy rate achieved in this case is 99.4% for the waist position using  
 388 SVM classifier. The accuracy rate obtained using DT and K-NN classifier for the same position is 99% and  
 389 87.6% respectively as given in Table 7. Table 8 shows that for sitting activity, the best accuracy rate achieved is  
 390 99.3% for the left pocket position using SVM classifier. On the other hand, DT and K-NN classifier achieved  
 391 99.2% and 90.4% accuracy for the left pocket position. The worst accuracy rate achieved by SVM for standing  
 392 activity is 95.4% for the upper arm position, whereas in case of sitting activity it is 97% for the wrist position.  
 393 These results depict that it is possible to identify a user based upon standing and sitting activities. In case of  
 394 these two activities, the users are distinguished from each other because of the differences in their standing and  
 395 sitting postures. This difference is detected by the inertial sensors of the smartphone placed on the user's body.  
 396 The orientation of smartphone inertial sensors changes when a user stands or sits in a different pattern/posture  
 397 as compare to other persons. Hence, the readings of these sensors change, which leads to identification of that  
 398 user. From the results obtained from Table 7, it can be said that it is easier to recognize a user on the basis of  
 399 his/her standing posture/stance if the smartphone is hanged near waist position. On the other hand, it is very  
 400 hard to recognize the user if the smartphone is placed on the upper arm position. Similarly, results from Table 8  
 401 report that the identification of a user based on sitting activity is easier if the phone is placed in the jeans pocket  
 402 as compare to other phone positions.

403 For the case of recognizing users from walking upstairs and walking downstairs activities also, the best  
 404 results are also obtained using SVM classifier. The highest accuracy achieved for walking upstairs and walking  
 405 downstairs activity is 98.7% and 96.5% respectively for the right pocket position using SVM classifier as shown  
 406 in Table 9 and Table 10 respectively. The accuracy achieved by DT and K-NN classifier for walking upstairs  
 407 activity is 90.1% and 92.5% respectively for the right pocket position. For downstairs activity for similar phone  
 408 position, DT and K-NN classifiers attained an accuracy rate of 90.4% and 86.3% respectively. The results of  
 409 these activities, i.e., walking upstairs and walking downstairs, obtained for the waist position are comparable  
 410 to the results obtained for pocket positions as given in Table 9 and Table 10. Moreover, it can be observed from the  
 411 results reported in these tables that upper arm and wrist position provides lower user recognition accuracies.  
 412 Hence, it can be stated that the recognition of a user on the basis of walking upstairs and walking downstairs  
 413 activity is easier if the smartphone is kept in pocket of the user or hanged at the waist position.





415 Fig. 5. Confusion matrices of user recognition (performed using SVM classifier) based on four different  
 416 activities: (a) standing with phone at waist position, accuracy = 99.4%, (b) sitting with phone in left pocket  
 417 position, accuracy = 99.3% (c) walking upstairs with phone in right pocket, accuracy = 98.7 (d) walking  
 418 downstairs with phone in right pocket, accuracy = 96.5%.

419 Fig. 4 shows and compares the average accuracy rate achieved by the selected classifiers in recognizing the  
 420 users on the basis of six different activities. For each activity, average accuracy percentage calculated over five  
 421 body positions is shown in the figure. It can be observed that for all six activities, SVM classifier obtained the  
 422 best average accuracy percentage for user recognition. The overall performance of K-NN classifier was better  
 423 than DT classifier in recognizing the users based on walking, running and walking upstairs activities. For the  
 424 remaining activities i.e., sitting, standing, walking downstairs, DT classifiers achieved better results than K-NN  
 425 classifier. The overall average recognition accuracy achieved for SVM classifier is 97.95%, which is 3.87% and  
 426 7.72% more than the overall average accuracy obtained for DT and K-NN classifiers respectively. Moreover,  
 427 the precision, recall, f-measure, and error rate are also better for SVM classifiers as depicted in Table 5 to Table  
 428 10. So, it can be concluded based on the above results and discussions that the performance of SVM classifier is  
 429 better for user recognition based on activity patterns recognition. It suggests SVM classifier as the best choice  
 430 for on-device user recognition based on recognizing the activity patterns for individual users.

431 To find out the best individual accuracies of recognition for different users, the confusion matrices for user  
 432 recognition are provided in Fig. 5 ((a)-(d)). For every activity except walking and running, only one confusion  
 433 matrix is shown for the position where the best performance metrics were achieved for user recognition using  
 434 SVM classifier. In case walking and running activities, the best value of accuracy, precision, recall, and  
 435 f-measure obtained for user recognition using SVM classifier is 100% for each (as shown in Table 5 and Table  
 436 6). It means that no user was misclassified or wrongly identified as any other user; hence the individual  
 437 recognition accuracy achieved for every user is 100%. From Table 7 to Table 10, it is clear that for recognizing

438 a user based on the walking upstairs and walking downstairs activity, the best position to keep smartphone is the  
439 right jeans pocket. On the other hand, for standing and sitting activities, the best positions are waist and left  
440 pocket respectively. As discussed earlier, there were total 71 samples for all individual users corresponding to  
441 each activity for a single position. Therefore the confusion matrices in Fig. 5 ((a)-(d)) are presented in terms of  
442 recognized over total number of samples (i.e. 71) for the all the users. The rows of the confusion matrices are  
443 representing actual users while columns are representing the predicted users. It can be seen from Fig. 5 ((a)-(d))  
444 that there are a few misclassifications where the actual user of the smartphone is identified as any other user.  
445 However, for each user, the value of correctly classified samples is very high. It means that every user is  
446 correctly identified with a very high accuracy. From these promising results, it is worth mentioning that it is  
447 possible to efficiently recognize different users on the basis of their activity patterns because of their behavioral  
448 differences.

449 Typically, there is only a single owner of a smartphone who is called as the authenticated user of that  
450 phone. The owner of the phone has full access to each and everything on his/her phone. However, a smartphone  
451 is not necessarily to be used by a single person only. An owner of a mobile device may share his/her phone with  
452 other people, who can use that phone for performing any of their tasks as allowed by the phone owner. All such  
453 users of the phone are supplementary users. The device owner may set different levels of access to his/her  
454 smartphone data and services for different supplementary users. Other than authenticated and supplementary  
455 users, any other user of the phone is treated as an impostor with no access given to phone data. To ensure the  
456 privacy of any confidential information and data stored on the owner phone, it is necessary to identify the phone  
457 user. The proposed system for user recognition identifies a user on the basis of his/her behavioral traits while  
458 using smartphone. Once the user is identified by the system, the system assigns the user a respective level of  
459 access privileges. The system can only identify a user on the basis of the activities for which the system is  
460 trained. In real time, if a user performs a random activity for which is unknown to the system, the system is  
461 improbable to be capable of identifying the user in an accurate way as there is no training of the system.  
462 However, the proposed system can be trained for the new activity by collecting raw data from the motion  
463 sensors of the smartphone. The system can then quickly learn the behavioral patterns of different users for the  
464 new activity and adapt itself to identify users based on new activity. In this way, adaptive behavioral  
465 authentication is also incorporated in the proposed system.

## 466 5. Conclusions

467 In this paper, we analyzed continuous authentication of smartphone users based on their behavioral traits  
468 using activity pattern recognition. For this purpose, we proposed a novel scheme for validating smartphone  
469 users, which identifies the users based on the way they perform certain activities using mobile sensing. Six  
470 activities of daily life i.e., walking, running, sitting, standing, walking upstairs, and walking downstairs, are  
471 used to distinguish between different users based on sixteen different features extracted from the time domain.  
472 For each activity, five different positions are employed for keeping a smartphone on the user's body and the  
473 user recognition results are analyzed for all these positions. It is noted that the performance of the user  
474 recognition based on a particular activity is different for varying positions of the smartphone on the user's body.  
475 A user can be easily and efficiently recognized on the basis of his/her walking pattern if the phone is placed in  
476 his/her jeans pocket. In contrast, keeping the phone at the upper arm position makes it very difficult to recognize  
477 a user based on the walking activity. Similarly, on the basis of standing posture, a user can be easily recognized  
478 if he/she keeps the phone at the waist position, whereas in case of sitting activity, the jeans pocket is the best  
479 place for user recognition. In the same way, the activities of walking upstairs and walking downstairs can easily  
480 distinguish between different users if the phone is kept in the jeans pocket or hanged with a belt clipper at the  
481 waist. Three different machine learning algorithms i.e., Decision Tree, K-Nearest Neighbors, and Support  
482 Vector Machine, are used for the purpose of user recognition. It is observed that Support Vector Machine  
483 classifier provides the best performance for on-device user identification. Hence, it is an ideal choice for  
484 on-device user identification based on activity pattern recognition.

485 To further extend this work, more sensors and activities can be incorporated into the system for recognizing  
486 users. Physiological sensors can be used along with the motion sensors for identity authentication. The  
487 emotional state of the users can also be recognized along with activity pattern recognition using physiological  
488 sensors. As the behavior of the user may change in a random way in different settings; hence an un-supervised  
489 machine learning approach can be used for user recognition, which will be helpful in adapting the system to  
490 random activity patterns. Contextual information is of very much importance while recognizing a user based on



491 his/her behavioral traits as the behavior of the user changes with different contexts. Hence, context-awareness  
 492 can be incorporated into the system to efficiently recognize a smartphone user keeping in view the contextual  
 493 information. Once a user is identified, we can keep track of his/her activities for health monitoring, social  
 494 interaction monitoring, and behavior prediction and modeling.

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