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On a class of Darboux-integrable semidiscrete equations

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Abstract

We consider a classification problem for Darboux-integrable hyperbolic semidiscrete equations. In particular, we obtain a complete description for a special class of equations admitting four-dimensional characteristic x-rings and two-dimensional characteristic n-rings. For all described equations, the corresponding x- and n-integrals are constructed.

Keywords: semidiscrete equations; Darboux integrability; characteristic rings

1 Introduction

Classification problems play an important role in the study of integrable equations. For classification of hyperbolic equations, it is convenient to define integrability in terms of characteristic rings. The notion of a characteristic ring was introduced by Shabat for integrable hyperbolic equations of exponential type (see [1, 2]) and then used by Zhiber to study general integrable hyperbolic equations (see [3–7]). Later, Habibullin extended this notion to the case of semidiscrete and discrete equations (see [8–16]). For more details on characteristic rings, see survey paper [17].

We consider semidiscrete hyperbolic equations that admit nontrivial x- and n-integrals, so-called Darboux-integrable equations [18]. It was proved in [9] that a semidiscrete hyperbolic equation is Darboux integrable if and only if its characteristic x- and n-rings are finite-dimensional. Description of all equations with characteristic x- and n-rings of finite dimensions is a very difficult classification problem. The majority of known Darboux-integrable semidiscrete equations possess x- and n-rings of dimensions not exceeding five (see [14, 16, 19]). Necessary and sufficient conditions for a characteristic x-ring to be four-dimensional were obtained in [20] (also see [21] for a characterization of five-dimensional characteristic x-rings). In [12] the conditions for a two-dimensional characteristic n-ring were obtained. We use these conditions to explicitly derive integrable equations with four-dimensional characteristic x-rings and two-dimensional characteristic n-rings.

Consider the equation

$$t_{1x} = f(x, t, t_1, t_x), \qquad (1)$$

where the function $t(n, x)$ depends on the discrete variable n and continuous variable x. We use the notations $t_x = \frac{\partial}{\partial x} t$ and $t_1 = t(n + 1, x)$. It is also convenient to denote $t_{[k]} = \frac{\partial^k}{\partial x^k} t$,

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$k \in \mathbb{N}$, and $t_m = t(n + m, x)$, $m \in \mathbb{Z}$. It was proved in [20] that if equation (1) has a four-dimensional characteristic x-ring, then the function f has the form

$$f = A(x, t, t_1)M(x, t, t_x) + B(x, t, t_1)t_x + C(x, t, t_1). \tag{2}$$

In this work, we assume that the function M depends only on t_x and f does not depend on x, that is, we study equations of the form

$$t_{1x} = A(t, t_1)M(t_x) + B(t, t_1)t_x + C(t, t_1). \tag{3}$$

It turns out that we have to consider two cases of f linear and nonlinear in t_x. The results of our investigation are given in the following theorems.

Theorem 1 *Let f be a linear function of t_x. Equation (3) has a four-dimensional characteristic x-ring and a two-dimensional characteristic n-ring if and only if*

$$f = \frac{\gamma(t)}{\gamma(t_1)}t_x - \frac{\gamma(t)}{\gamma(t_1)}\sigma(t) + \sigma(t_1),$$

where the functions γ and σ satisfy either of the relations

$$\big(\gamma(t)\sigma(t)\big)' = \gamma(t)\sqrt{B_1 + B_2\gamma(t)\sigma(t)}$$

or

$$\big(\gamma(t)\sigma(t)\big)' = \gamma(t)\sqrt{B_1 + B_2\big(\gamma(t)\sigma(t)\big)^2}$$

with arbitrary constants B_1 and B_2.

Theorem 2 *Let f be a nonlinear function of t_x. Equation (3) has a four-dimensional characteristic x-ring and a two-dimensional characteristic n-ring if and only if*

$$f = \frac{c_1\eta(t)\eta(t_1)}{t_x} \quad or \quad f = \frac{c_1e^{c_2(t+t_1)}}{t_x + P} - P,$$

where c_1, c_2, and P are arbitrary constants, and η is an arbitrary function of one variable, or

$$f = \sqrt{B^2 - 1}\sqrt{t_x^2 + Pt_x + Q} + Bt_x + \frac{1}{2}P(B - 1),$$

where B, P, and Q are arbitrary constants.

The paper is organized as follows. First, we give proofs of Theorems 1 and 2, and in the last section, we provide x- and n- integrals for equations found in Theorems 1 and 2.

2 Proofs of Theorem 1 and Theorem 2

2.1 Preliminary results

In what follows, all calculations are done on the set of solutions of equation (1), that is, we consider $\dots, t_{-1}, t_0, t_1, \dots$ and $t_x, t_{xx}, t_{xxx}, \dots$ as independent dynamical variables. The derivatives of $\dots, t_{-1}, t_0, t_1, \dots$ and shifts of $t_x, t_{xx}, t_{xxx}, \dots$ are expressed in terms of the dynamical variables using (1).

Let us formulate necessary and sufficient conditions so that equation (3) has a characteristic x-ring of dimension four and a characteristic n-ring of dimension two. First, we consider the n-ring. The following theorem was proved in [12].

Theorem 3 *Equation* (1) *has a characteristic n-ring of dimension two if and only if*

$$D\left(\frac{f_t}{f_{t_x}}\right) = -f_{t_1},\tag{4}$$

where D is the shift operator: $Dg(n, x) = g(n + 1, x)$.

We remark that equality (4) implies that

$$\frac{\partial}{\partial t_1}\left(\frac{f_t}{f_{t_x}}\right) = 0\tag{5}$$

since f_{t_1} does not depend on t_2. We use this observation later.

For the characteristic x-ring, we have to consider two cases: $f_{t_x t_x} = 0$, that is, f is a linear function of t_x, and $f_{t_x t_x} \neq 0$, that is, f is a nonlinear function of t_x.

The following theorems were proved in [20].

Theorem 4 *Equation* (1) *with* $f_{t_x t_x} = 0$ *has a characteristic ring* L_x *of dimension four if and only if*

$$D\left(\frac{K(m)}{m} - m + \frac{f_t}{f_{t_x}}\right) = \frac{K(m)}{m} + m - f_{t_1},\tag{6}$$

where K is the vector field

$$K = \frac{\partial}{\partial x} + t_x\frac{\partial}{\partial t} + f\frac{\partial}{\partial t_1} + \cdots,$$

and $m = \frac{-(f_{xt_x} + t_x f_{t_x t} + f f_{t_x t_1}) + f_t + f_{t_x} f_{t_1}}{f_{t_x}}$.

Theorem 5 *Equation* (1) *with* $f_{t_x t_x} \neq 0$ *has a characteristic ring* L_x *of dimension four if and only if*

$$D\left(\frac{f_{t_x t_x t_x}}{f_{t_x t_x}}\right) = \frac{f_{t_x t_x t_x} f_{t_x} - 3f_{t_x t_x}^2}{f_{t_x t_x} f_{t_x}^2}\tag{7}$$

and

$$D\tilde{m} = \tilde{m}f_{t_x} - (f_x + t_x f_t + f_{t_1} f),\tag{8}$$

where $\tilde{m} = \frac{f_{xt_x} + t_x f_{t_x t} + f f_{t_x t_1} - f_t - f_{t_x} f_{t_1}}{f_{t_x t_x}}$.

In the same way as in equation (5), we have

$$\frac{\partial}{\partial t_1} m = 0 \quad \text{and} \quad \frac{\partial}{\partial t_1} \tilde{m} = 0. \tag{9}$$

For convenience of the reader, let us give definitions of x- and n-integrals and of Darboux-integrable semidiscrete equations.

Definition 6 A function $F(x, t, t_1, \ldots, t_k)$ is called an x-integral of equation (1) if

$$D_x F(x, t, t_1, \ldots, t_k) = 0$$

for all solutions of (1). Here D_x is the operator of total differentiation with respect to x: $D_x g(n, x) = (d/dx) g(n, x)$.

A function $G(x, t, t_x, \ldots, t_{[m]})$ is called an n-integral of equation (1) if

$$DG(x, t, t_x, \ldots, t_{[m]}) = G(x, t, t_x, \ldots, t_{[m]})$$

for all solutions of (1).

Equation (1) is called Darboux integrable if it admits a nontrivial x-integral and a nontrivial n-integral.

2.2 Proof of Theorem 1

We assume that f is a linear function of t_x. Thus

$$f(t, t_1, t_x) = A(t, t_1) t_x + B(t, t_1), \tag{10}$$

and equation (1) becomes

$$t_{1x} = A(t, t_1) t_x + B(t, t_1). \tag{11}$$

The proof of the Theorem 1 is based on the following lemmas.

Lemma 7 *Let $f_{t_x t_x} = 0$. Then the characteristic n-ring of equation* (11) *has dimension two if and only if*

$$f(t, t_1, t_x) = \frac{c_1 \gamma(t)}{\gamma(t_1)} t_x + \frac{c_2}{\gamma(t_1)} - \frac{c_1 \gamma(t) \sigma(t)}{\gamma(t_1)} + \sigma(t_1), \tag{12}$$

where γ and σ are functions of one variable, and c_1, c_2 are constants.

Proof It follows from condition (4) that

$$\frac{f_t}{f_{t_x}} = \frac{A_t}{A} t_x + \frac{B_t}{A} \tag{13}$$

does not depend on t_1. Hence $\frac{A_t}{A}$ and $\frac{B_t}{A}$ do not depend on t_1. So we can write $A(t, t_1) = \gamma(t) \varphi(t_1)$ and $B(t, t_1) = l(t) \varphi(t_1) + \sigma(t_1)$ for some functions γ, φ, and σ. The function f takes

form

$$f(t, t_1, t_x) = \gamma(t)\varphi(t_1)t_x + l(t)\varphi(t_1) + \sigma(t_1). \tag{14}$$

Applying condition (4) to f given by (14), we get

$$\frac{\gamma'(t_1)}{\gamma(t_1)}\big(\gamma(t)\varphi(t_1)t_x + l(t)\varphi(t_1) + \sigma(t_1)\big) + \frac{l'(t_1)}{\gamma(t_1)}$$

$$= -\gamma(t)\varphi'(t_1)t_x - l(t)\varphi'(t_1) - \sigma'(t_1). \tag{15}$$

By comparing the coefficients of t_x in (15) we get

$$\frac{\gamma'(t_1)}{\gamma(t_1)} + \frac{\varphi'(t_1)}{\varphi(t_1)} = 0,$$

so that $\varphi(t_1) = \frac{c_1}{\gamma(t_1)}$, where c_1 is some constant. Substituting this φ into equation (15) and collecting the terms independent of t_x, we get

$$\gamma'(t_1)\sigma(t_1) + \gamma(t_1)\sigma'(t_1) + l'(t_1) = 0. \tag{16}$$

Solving (16), we find

$$l(t) = -\gamma(t)\sigma(t) + \tilde{c}_2, \tag{17}$$

where c_2 is some constant. Substituting φ and l found into equation (14), we get equation (12). We can check that condition (4) is satisfied for function (12). □

Now we can rewrite equation (11) as

$$t_{1x} = \frac{c_1\gamma(t)}{\gamma(t_1)}t_x + \frac{c_2}{\gamma(t_1)} - \frac{c_1\gamma(t)\sigma(t)}{\gamma(t_1)} + \sigma(t_1), \tag{18}$$

where γ and σ are functions of one variable, and c_1, c_2 are constants. The equation can be simplified by introducing the new variable

$$\tau = L(t), \tag{19}$$

where L satisfies $L'(t) = \gamma(t)$. Equation (18) becomes

$$\tau_{1x} = c_1\tau_x + c_2 - c_1 Q(\tau) + Q(\tau_1) \tag{20}$$

for some function Q of one variable. We can check that condition (4) is satisfied for the new equation. Hence our change of variable does not affect the dimension of the characteristic n-ring.

In the next lemma, we give conditions for equation (20) to have a four-dimensional characteristic x-ring.

Lemma 8 *Equation* (20) *has a four-dimensional characteristic x-ring if and only if*

$$Q(\tau) = A_1\tau^2 + A_2\tau \quad or \quad Q(\tau) = A_1 e^{\alpha\tau} + A_2 e^{-\alpha\tau} \tag{21}$$

for some constants A_1, A_2, and α.

Proof Applying condition (6) to function $f = c_1\tau_x + c_2 - c_1 Q(\tau) + Q(\tau_1)$, we get

$$\frac{c_1\tau_x + c_2 - c_1 Q(\tau) + Q(\tau_1)}{Q'(\tau_2) - Q'(\tau_1)}\left(c_1 Q''(\tau_2) - Q''(\tau_1)\right)$$
$$+ \frac{Q''(\tau_2)(c_2 - c_1 Q(\tau_1) + Q(\tau_2))}{Q'(\tau_2) - Q'(\tau_1)} - Q'(\tau_2) + Q'(\tau_1)$$
$$= \frac{c_1 Q''(\tau_1) - Q''(\tau)}{Q'(\tau_1) - Q'(\tau)}\tau_x + \frac{Q''(\tau_1)(c_2 - c_1 Q(\tau) + Q(\tau_1))}{Q'(\tau_1) - Q'(\tau)} + Q'(\tau_1) - Q'(\tau).$$

By comparing the coefficients of τ_x in this equality, we get

$$c_1 D\left(\frac{c_1 Q''(\tau_1) - Q''(\tau)}{Q'(\tau_1) - Q'(\tau)}\right) = \frac{c_1 Q''(\tau_1) - Q''(\tau)}{Q'(\tau_1) - Q'(\tau)},$$

which implies that either $c_1 = 1$ and $\frac{c_1 Q''(\tau_1)-Q''(\tau)}{Q'(\tau_1)-Q'(\tau)}$ is constant or $c_1 Q''(\tau_1) - Q''(\tau) = 0$. In the second case, we also get $c_1 = 1$. Thus, equation (20) has the form

$$\tau_{1x} = \tau_x + d(\tau, \tau_1). \tag{22}$$

Equations of this form were completely classified in [14] (together with their $x-$ and n-characteristic rings). It follows from [14] that Q must have the form given in the statement of the lemma. □

Returning to the original variable t in equation (20) with Q given by equation (21), we get Theorem 1.

2.3 Proof of Theorem 2
We assume that f is a nonlinear function of t_x. Thus

$$f(t, t_1, t_x) = A(t, t_1)M(t_x) + B(t, t_1)t_x + C(t, t_1), \tag{23}$$

and equation (1) becomes

$$t_{1x} = A(t, t_1)M(t_x) + B(t, t_1)t_x + C(t, t_1). \tag{24}$$

The proof of the Theorem 2 is based on the following lemmas.

Lemma 9 *Let equation* (24) *have a characteristic n-ring of dimension two, and let M be a nonlinear function. Then the function M satisfies*

$$M' = -\frac{\alpha_2 M + \alpha_4 t_x + \alpha_6}{\alpha_1 M + \alpha_3 t_x + \alpha_5}, \tag{25}$$

where $\alpha_1 M + \alpha_3 t_x + \alpha_5 \neq 0$.

Proof If the dimension of the characteristic n-ring is two, then $\left(\frac{f_t}{f_{t_x}}\right)_{t_1} = 0$. Hence, for f given by equation (23), we have

$$
\left(\frac{A_t M + t_x B_t + C_t}{AM' + B}\right)_{t_1}
$$

$$
= \frac{(A_{tt_1} M + t_x B_{tt_1} + C_{tt_1})(AM' + B) - (A_{t_1} M' + B_{t_1})(A_t M + t_x B_t + C_t)}{(AM' + B)^2} = 0.
$$

This can be rewritten as

$$
M'(\alpha_1 M + \alpha_3 t_x + \alpha_5) = -(\alpha_2 M + \alpha_4 t_x + \alpha_6) \tag{26}
$$

for some constants α_i, $i = 1, 2, \ldots, 5$. Note that if $\alpha_1 M + \alpha_3 t_x + \alpha_5 = 0$, then either $M' = 0$ or $\alpha_2 M + \alpha_4 t_x + \alpha_6 = 0$. In both cases, we get that f is a linear function of t_x. Hence we can assume that $\alpha_1 M + \alpha_3 t_x + \alpha_5 \neq 0$, and we can write equality (25). □

The above lemma allows us to express the derivative M' in terms of M. We can also express the shift DM in terms of M. Indeed, as it was proved in [20] (see Lemma 12), if equation (1) has a four-dimensional characteristic x-ring and $f_{t_x t_x} \neq 0$, then

$$
Df = -H_1(t, t_1, t_2)t_x + H_2(t, t_1, t_2)f + H_3(t, t_1, t_2) \tag{27}
$$

for some functions H_1, H_2, and H_3. Therefore,

$$
D(AM + Bt_x + C) = -H_1 t_x + H_2(AM + Bt_x + \widetilde{C}), \tag{28}
$$

and

$$
DM = Q_1(t, t_1, t_2)M + Q_2(t, t_1, t_2)t_x + Q_3(t, t_1, t_2) \tag{29}
$$

for some functions Q_1, Q_2 and Q_3.

We use expressions (25) and (29) for the derivative and shift of M in the next lemma.

Lemma 10 *Let equation* (24) *have a characteristic n-ring of dimension two. Then M has either of the forms* $M = \frac{1}{t_x + P}$, *or* $M = \sqrt{t_x^2 + P t_x + Q}$, *or* $M = t_x^2$.

Proof Consider the vector field $X = \frac{\partial}{\partial t_x}$. We can easily check that $DX = \frac{1}{f_{t_x}} XD$. Thus $DX(M) = \frac{1}{f_{t_x}} X(DM)$. Using equation (25) for $X(M)$ and equation (29) for DM, we get

$$
-D\left(\frac{\alpha_2 M + \alpha_4 t_x + \alpha_6}{\alpha_1 M + \alpha_3 t_x + \alpha_5}\right) = \frac{1}{AM' + B} X(Q_1 M + Q_2 t_x + Q_3).
$$

Using equation (25) and equation (29) once more, we get

$$
-\frac{\tilde{\alpha_2}(Q_1 M + Q_2 t_x + Q_3) + \tilde{\alpha_4}(AM + Bt_x + C) + \tilde{\alpha_6}}{\tilde{\alpha_1}(Q_1 M + Q_2 t_x + Q_3) + \tilde{\alpha_3}(AM + Bt_x + C) + \tilde{\alpha_5}}
$$

$$
= \frac{Q_2 - Q_1 \frac{\alpha_2 M + \alpha_4 t_x + \alpha_6}{\alpha_1 M + \alpha_3 t_x + \alpha_5}}{B - A \frac{\alpha_2 M + \alpha_4 t_x + \alpha_6}{\alpha_1 M + \alpha_3 t_x + \alpha_5}},
$$

where $D\alpha_k = \tilde{\alpha}_k$. Hence we can write

$$R_1 M^2 - (R_2 t_x + R_3)M + \left(R_4 t_x^2 + R_5 t_x + R_6\right) = 0 \tag{30}$$

for some functions R_k, $k = 1, 2, \ldots, 6$. Then, we find that

$$M = \frac{(R_2 t_x + R_3) \pm \sqrt{(R_2 t_x + R_3)^2 - 4R_1(R_4 t_x^2 + R_5 t_x + R_6)}}{2R_1} \quad \text{if } R_1 \neq 0$$

or

$$M = \frac{R_4 t_x^2 + R_5 t_x + R_6}{R_2 t_x + R_3} \quad \text{if } R_1 = 0.$$

Since the function $f = AM + Bt_x + C$ has a linear term Bt_x and a free term C, we can assume that M has the form given in the statement of the lemma. □

Now we consider each value of M obtained in the lemma, separately. We start with the simple case $M = t_x^2$.

Lemma 11 *Equation* (24) *cannot have a four-dimensional characteristic x-ring if $M = t_x^2$.*

Proof We can easily check that, for any

$$f = A(t, t_1)t_x^2 + B(t, t_1)t_x + C(t, t_1),$$

condition (7) is not satisfied. Hence equation (24) cannot have a four-dimensional characteristic x-ring if $M = t_x^2$. □

Let us consider the case $M = \frac{1}{t_x + P}$.

Lemma 12 *Let $M = \frac{1}{t_x + P}$, and let equation* (24) *have a four-dimensional characteristic x-ring and a two-dimensional characteristic n-ring. Then equation* (24) *takes either of the forms*

$$t_{1x} = \frac{c^* \eta(t)\eta(t_1)}{t_x} \quad \text{or} \quad t_{1x} = \frac{c^* e^{c^{**}(t+t_1)}}{t_x + P} - P. \tag{31}$$

Proof We have

$$f(t, t_1, t_x) = \frac{A(t, t_1)}{t_x + P} + B(t, t_1)t_x + C(t, t_1). \tag{32}$$

Applying condition (7) to f, we get

$$\frac{3(t_x + P)}{B(t_x + P)^2 + (C + P - BP)(t_x + P) + A} = \frac{3(t_x + P)(B(t_x + P)^2 + A)}{(B(t_x + P)^2 - A)^2}.$$

From this equality we get

$$B(C + P - BP)(t_x + P)^3 + 4AB(t_x + P)^2$$
$$+ A(C + P - BP)(t_x + P) = 0.$$

In this equality the coefficients of $(t_x + P)^k$, $k = 1, 2, 3$, must be zero. So we find

$$B(C + P - BP) = 0, \qquad 4AB = 0, \quad \text{and} \quad A(C + P - BP) = 0.$$

Since $A(t, t_1) \neq 0$ (otherwise $f_{t_x t_x} = 0$), we find $B = 0$ and $C = -P$. Thus we have

$$f(t, t_1, t_x) = \frac{A(t, t_1)}{t_x + P} - P. \tag{33}$$

Using condition (4), we get

$$\frac{A_{t_1}(t_1, t_2)A(t, t_1)}{A(t_1, t_2)(t_x + P)} = \frac{A_{t_1}(t, t_1)}{t_x + P}$$

or

$$\frac{A_{t_1}(t_1, t_2)}{A(t_1, t_2)} = \frac{A_{t_1}(t, t_1)}{A(t, t_1)}. \tag{34}$$

It follows that $\frac{A_{t_1}(t_1, t_2)}{A(t_1, t_2)}$ does not depend on t_2, so $\frac{\partial^2}{\partial t_2 \partial t_1} \ln A(t_1, t_2) = 0$, and $\frac{A_{t_1}(t, t_1)}{A(t, t_1)}$ does not depend on t, so $\frac{\partial^2}{\partial t \partial t_1} \ln A(t, t_1) = 0$.

Hence we get $A(t, t_1) = \varphi(t)\eta(t_1)$ for some functions φ and η. Using equation (34), we obtain $\frac{\varphi'(t_1)}{\varphi(t_1)} = \frac{\eta'(t_1)}{\eta(t_1)}$, which implies that $\varphi(t_1) = c^*\eta(t_1)$, where c^* is some constant. Hence we have

$$f = \frac{c^*\eta(t)\eta(t_1)}{t_x + P} - P. \tag{35}$$

From condition (8) it follows that

$$\tilde{m} = \left(-\frac{P\eta'(t)}{2\eta(t)} + \frac{P\eta'(t_1)}{2\eta(t_1)} \right)(t_x + P) - \frac{(t_x + P)^2 \eta'(t)}{2\eta(t)} \tag{36}$$

does not depend on t_1. So, either $P = 0$ or $\eta'(t_1) = c^{**}\eta(t_1)$, which implies $\eta(t_1) = e^{c^{**}t_1}$ with some constant c^{**}. Thus we obtain equations (31). We can easily check that these equations have a two-dimensional characteristic n-ring and a four-dimensional characteristic x-ring. $\qquad\square$

Let us consider the case $M = \sqrt{t_x^2 + Pt_x + Q}$.

Lemma 13 *Let $M = \sqrt{t_x^2 + Pt_x + Q}$, and let equation (24) have a four-dimensional characteristic x-ring and a two-dimensional characteristic n-ring. Then equation (24) takes the form*

$$t_{1x} = \sqrt{B^2 - 1}\sqrt{t_x^2 + Pt_x + Q} + Bt_x + \frac{1}{2}P(B - 1), \tag{37}$$

where B, Q, P are constants, and $B^2 \neq 1$.

Proof We have

$$f = A(t, t_1)\sqrt{t_x^2 + Pt_x + Q} + B(t, t_1)t_x + C(t, t_1). \tag{38}$$

Applying condition (7), we find

$$-\frac{6BP + 12t_x + 12A\sqrt{t_x^2 + t_xP + Q}}{(AP + 2At_x + 2B\sqrt{t_x^2 + t_xP + Q})^2}$$

$$= \frac{-3P - 6C - 6Bt_x - 6A\sqrt{t_x^2 + Pt_x + Q}}{2Q + 2(C + Bt_x + A\sqrt{t_x^2 + Pt_x + Q})(C + P + Bt_x + A\sqrt{t_x^2 + Pt_x + Q})},$$

or

$$4\left(Q + \left(C + Bt_x + A\sqrt{t_x^2 + Pt_x + Q}\right)\left(C + P + Bt_x + A\sqrt{t_x^2 + Pt_x + Q}\right)\right)$$

$$\cdot \left(BP + 2t_x + 2A\sqrt{t_x^2 + t_xP + Q}\right)$$

$$= \left(AP + 2At_x + 2B\sqrt{t_x^2 + t_xP + Q}\right)^2 \left(P + 2C + 2Bt_x + 2A\sqrt{t_x^2 + Pt_x + Q}\right).$$

Comparing the coefficients of $(\sqrt{t_x^2 + Pt_x + Q})^i (t_x)^j$ for $i, j = 0, 1, 2$, we get

$$AB(2C + P - BP) = 0,$$

$$A\left(-4C^2 - 4CP + A^2\left(P^2 - 4Q\right) + 4\left(B^2 - 1\right)Q\right) = 0,$$

$$\left(A^2 + B^2\right)\left(-2C + (B - 1)P\right) = 0,$$

$$-2A^2P(2C + P) + 4B^3Q - B\left(4C^2 + 4CP + 4Q + A^2\left(-3P^2 + 4Q\right)\right) = 0,$$

$$A^2(2C + P)\left(P^2 - 8Q\right) + 4B^2(2C + P)Q - 4BP\left(C^2 + CP + Q - A^2Q\right) = 0.$$

We can check that these equalities are satisfied if and only if

$$2C = PB - P \quad \text{and} \quad 4C^2 + 4CP = A^2\left(P^2 - 4Q\right) - 4Q + 4B^2Q.$$

Simplifying, we get

$$2C = PB - P, \quad \text{and either} \quad B^2 = A^2 + 1 \quad \text{or} \quad P^2 = 4Q.$$

In the case $P^2 = 4Q$, we have that $M = \sqrt{t_x^2 + Pt_x + Q}$ is a linear function of t_x. Therefore we have to study only the case $B^2 = A^2 + 1$. Thus we have

$$f = \sqrt{B(t, t_1)^2 - 1}\sqrt{t_x^2 + Pt_x + Q} + B(t, t_1)t_x + \frac{P}{2}\left(B(t, t_1) - 1\right), \tag{39}$$

where $B \neq 1$. In the same way, we check that condition (4) in the form $(D\frac{f_t}{f_{t_x}})^2 - (f_{t_1})^2 = 0$ is satisfied for this function f if and only if

$$\frac{B_{t_1}^2(t, t_1)}{B^2(t, t_1) - 1} = \frac{B_{t_1}^2(t_1, t_2)}{B^2(t_1, t_2) - 1}. \tag{40}$$

Hence we can write

$$B_{t_1}(t, t_1) = A(t, t_1)\varphi(t_1), B_t(t, t_1) = \pm A(t, t_1)\varphi(t) \tag{41}$$

for some function φ.

Using condition (8), let us show that B can only be a constant function. We have

$$\tilde{m} = \mu_1 t_x\left(t_x^2 + pt_x + q\right) + \mu_2\left(t_x^2 + pt_x + q\right)^{\frac{3}{2}} + \mu_3\left(t_x^2 + pt_x + q\right), \tag{42}$$

where

$$\mu_1 = \frac{2PB(B_{t_1} + B_t)}{(P^2 - 4Q)(B^2 - 1)}, \tag{43}$$

$$\mu_2 = \frac{2P\sqrt{B^2 - 1}(B_{t_1} + B_t)}{(P^2 - 4Q)(B^2 - 1)}, \tag{44}$$

$$\mu_3 = \frac{(4Q - P^2 + P^2B)B_{t_1} + 4QBB_t}{(P^2 - 4Q)(B^2 - 1)}. \tag{45}$$

Since $\tilde{m}$ does not depend on t_1, we have that μ_1, μ_2, and μ_3 also do not depend on t_1. Using (41), we have

$$\mu_2 = \frac{2P(\varphi(t_1) \pm \varphi(t))}{P^2 - 4Q}. \tag{46}$$

Since μ_2 does not depend on t_1, either φ is a constant function or $P = 0$. Note that in both cases, we get $\mu_1 = 0$ and $\mu_2 = 0$. We start with the case where ϕ is some constant C. Using equation (41), we have

$$\mu_3 = \frac{C(4Q - P^2) + C(P^2 \pm 4Q)B}{(P^2 - 4Q)\sqrt{B^2 - 1}}. \tag{47}$$

Differentiating this equality with respect to t_1, we get

$$0 = \frac{CB_{t_1}((P^2 \pm 4Q) + (4Q - P^2)B)}{(P^2 - 4Q)(B^2 - 1)^{\frac{3}{2}}}, \tag{48}$$

which gives $B_{t_1} = 0$ or $((P^2 \pm 4Q) + (4Q - P^2)B) = 0$. Both equalities imply that B is a constant.

Now we consider the case $P = 0$. Then, using equation (41), we have

$$\mu_3 = \frac{4Q(B_{t_1} + BB_t)}{-4Q(B^2 - 1)} = -\frac{\varphi(t_1) \pm B\varphi(t)}{\sqrt{B^2 - 1}}. \tag{49}$$

Differentiating this equality with respect to t_1, we get

$$0 = \frac{B_{t_1}(B\varphi(t_1) \pm \varphi(t))}{(B^2 - 1)^{\frac{3}{2}}}, \tag{50}$$

which implies that either $B_{t_1} = 0$ or $B = \pm\frac{\varphi(t)}{\varphi(t_1)}$. In both cases, we get that B is a constant function. Indeed, if $B_{t_1} = 0$, then $B_t = 0$ by equation (41), so B is a constant function, and if

$B = \pm \frac{\phi(t)}{\phi(t_1)}$, then $\mu_3 = \pm \sqrt{\varphi^2(t) - \varphi^2(t_1)}$, and since μ_3 does not depend on t_1, we get that ϕ is a constant function, and hence B is a constant function. Using the equality $B^2 = A^2 + 1$, we get the statement of the lemma. $\qquad \square$

The proof of Theorem 2 easily follows from the above lemmas.

3 Examples

The functions f given in the Theorem 1 lead to the following examples.

Example 14 The equation

$$t_{1x} = \frac{\gamma(t)}{\gamma(t_1)}t_x - \frac{\gamma(t)}{\gamma(t_1)}\sigma(t) + \sigma(t_1),$$

where functions γ and σ satisfy the relation

$$\left(\gamma(t)\sigma(t)\right)' = \gamma(t)\sqrt{B_1 + B_2\left(\gamma(t)\sigma(t)\right)}, \quad B_1, B_2 \in \mathbb{R},$$

has an x-integral $F = \frac{(L(t_3)-L(t_1))(L(t_2)-L(t))}{(L(t_3)-L(t_2))(L(t_2)-L(t_1))}$, where $L(t) = \int_0^t \gamma(\tau)\,d\tau$, and an n-integral $I = \gamma(t)t_x - \sigma(t)$.

Example 15 The equation

$$t_{1x} = \frac{\gamma(t)}{\gamma(t_1)}t_x - \frac{\gamma(t)}{\gamma(t_1)}\sigma(t) + \sigma(t_1),$$

where functions γ and σ satisfy the relation

$$\left(\gamma(t)\sigma(t)\right)' = \gamma(t)\sqrt{B_1 + B_2\left(\gamma(t)\sigma(t)\right)^2}, \quad B_1, B_2 \in \mathbb{R},$$

has an x-integral $F = \frac{(e^{L(t)}-e^{L(t_2)})(e^{L(t_1)}-e^{L(t_3)})}{(e^{L(t)}-e^{L(t_3)})(e^{L(t_1)}-e^{L(t_2)})}$, where $L(t) = \int_0^t \gamma(\tau)\,d\tau$, and an n-integral $I = \gamma(t)t_x - \sigma(t)$.

The functions f given in the Theorem 2 lead to the following examples.

Example 16 The equation

$$t_{1x} = \frac{c_1\eta(t)\eta(t_1)}{t_x}$$

has an x-integral $F = \int_0^{t_3} \eta^{-1}(\tau)\,d\tau - \int_0^{t_1} \eta^{-1}(\tau)\,d\tau$ and an n-integral $I = \frac{t_x}{c_1\eta(t)} + \frac{\eta(t)}{t_x}$.

Example 17 The equation

$$t_{1x} = \frac{c_1 e^{c_2(t+t_1)}}{t_x + P} - P$$

has an x-integral $F = e^{-c_2 t_3 + c_2 P x} - e^{-c_2 t_1 + c_2 P x}$ and an n-integral $I = \frac{t_x + P}{c_1 e^{c_2 t}} + \frac{e^{c_2 t}}{t_x + P}$.

Example 18 The equation

$$t_{1x} = \sqrt{B^2 - 1}\sqrt{t_x^2 + Pt_x + Q} + Bt_x + \frac{1}{2}P(B-1)$$

has an x-integral

$$F = \left(-8B^3 - 4B^2 + 4B - 1\right)t + \left(8B^3 - 2B + 1\right)t_1 + \left(-4B^2 + 2B - 1\right)t_2 + t_3$$

and an n-integral

$$I = \left(B - \sqrt{B^2 - 1}\right)^n\left(\sqrt{t_x^2 + Pt_x + Q} + t_x + 0.5P\right).$$

In all examples, we can check that F is an x-integral and I is an n-integral by direct calculations.

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