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# Ensemble Kalman Filter with a Square Root Scheme (EnKF-SR) for Trajectory Estimation of AUV SEGOROGENI ITS

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- 2** Ermayanti, Zunif, Erna Apriliani, Hendro Nurhadi, and Teguh Herlambang. "Estimate and control position autonomous Underwater Vehicle based on determined trajectory using Fuzzy Kalman Filter method", 2015 International Conference on Advanced Mechatronics Intelligent Manufacture and Industrial Automation (ICAMIMIA), 2015. 6%

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