# Mutiple Curved Crack Problems in Antiplane Elasticity for Circular Region with Traction Free Boundary 

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#### Abstract

The multiple curved cracks in a circular region problem in antiplane elasticity is formulated in terms of hypersingular integral equation in conjunction with the complex variable function method. The obtained hypersingular integral equations are solved numerically using the curve length coordinate method, where the curved crack configurations are mapped on the real axes $s$ with intervals $\left(-a_{i}, a_{i}\right)=1,2, \ldots, n$. . Suitable scheme is used for the determination of the unknown functions. For numerical purposes only a particular case of doubly circular arc cracks is considered, and it is found that the stress intensity factors (SIFs) are higher as the cracks become closer to the circular boundary.


Keywords: antiplane elasticity, hypersingular integral equation, crack opening displacement, stress intensity factors.

## 1. INTRODUCTION

The crack problems in plane elasticity have been studied extensively by many researchers using various approaches. The stress intensity factor (SIF) is the main interests as the data are imperative predicting the stability of cracked components. The pertubation method is used for solving the various set of slightly curved and kinked cracks problems in plane elasticity by Cotterell et al. (1980), Martin (2000) and Chen (1999). Single and multiple cracks problems, formulated in terms of singular and hypersingular integral equations, are found in Chen (2003), Ang (2001), Chen et al. (1995), Gray et al. (1990), Yan et al. (2010), Chen et al. (1992) and Nik Long et al. (2009), and the interaction between the curved crack and a circular inclusion is studied in Cheesman et al. (2000),

Chao (1996), Dong (2005) and Hasebe et al. (1984). On the other hand, many authors dealt with the problem of cracks inside and outside a circular region by formulating into singular integral equations ((Lin et al. (1989), Hong-shan et al. (1989)), hypersingular integral equation (Jian et al. (2004) and Chen et al. (2005)) and for the antiplane problems (Chen et al. (2004), Chen et al. (1986), Chen (1993), Shen et al. (1998) and Zhong-xian (2006)).

In this paper, the system of hypersingular integral equations for multiple curved cracks in antiplane elasticity for a circular region with traction free is formulated, and solved numerically using curved length technique. Some numerical examples are given to demonstrate the behaviour of SIF for different cracks positions inside and outside of a circular boundary.

## 2. FUNDAMENTAL FORMULAE AND PROBLEM FORMULATION

In antiplane elasticity, the displacement $w$ is everywhere perpendicular to the $x y$ plane. Thus, the displacements are assumed to be in the form of $u=0, v=0, w=w(x, y)$. Hence, the non-vanishing stresses components $\sigma_{z x}$ and $\sigma_{z y}$ can be expressed by

$$
\sigma_{z x}=G \frac{\partial w}{\partial x}, \sigma_{z y}=G \frac{\partial w}{\partial y},
$$

where $G$ is shear modulus of elasticity.
It is not difficult to show that the displacement component $w(x, y)$ is a harmonic function. Let the complex potential $\phi(z)$ takes the form

$$
\begin{equation*}
\phi(z)=G w(x, y)+i f(x, y) \tag{1}
\end{equation*}
$$

where $f(x, y)$ is an analytic function. It is obvious from (1) that

$$
G w(x, y)=\frac{1}{2}(\phi(z)+\overline{\phi(z)})
$$

and

$$
f(x, y)=\frac{1}{2 i}(\phi(z)-\overline{\phi(z)}) .
$$

From the Cauchy-Riemann condition, the stress components can be written as

$$
\begin{equation*}
\sigma_{z x}=G \frac{\partial w}{\partial x}=\frac{\partial f}{\partial y}, \sigma_{z y}=G \frac{\partial w}{\partial y}=-\frac{\partial f}{\partial x} . \tag{2}
\end{equation*}
$$

From Equations (1) and (2), it is easy to see that

$$
\begin{equation*}
\Phi(z)=\phi^{\prime}(z)=\sigma_{z x}-i \sigma_{z y}=\frac{\partial f}{\partial y}+i \frac{\partial f}{\partial x}, \tag{3}
\end{equation*}
$$

which gives

$$
\begin{equation*}
f(x, y)=\int_{z_{0}}^{z}\left(\sigma_{z x} d y-\sigma_{z y} d x\right) . \tag{4}
\end{equation*}
$$

In Equation (4), the domain of integration is a path connecting the fixed point $z_{0}=x_{0}+i y_{0}$ and the generic point $z=x+i y$ (Muskhelishvilli et al. (1958)).

By placing a continuous distribution of doublet dislocation along the curve $L$, the appropriate complex potential $\phi_{p}(z)$ takes the form (Chen (2004))

$$
\begin{equation*}
\phi_{p}(z)=\frac{1}{\pi i} \int_{L} \frac{g(t) d t}{t-z} . \tag{5}
\end{equation*}
$$

Letting the point $z$ approaches $t_{0}^{+}$and $t_{0}^{-}$, which are located on the upper and lower side of crack faces, the following result is obtained

$$
\begin{aligned}
& \phi_{p}^{+}\left(t_{0}\right)-\phi_{p}^{-}\left(t_{0}\right)=2 g\left(t_{0}\right) \text { or } \\
& G\left(w^{+}\left(t_{0}\right)-w^{-}\left(t_{0}\right)\right)=2 g\left(t_{0}\right) .
\end{aligned}
$$

The function $g(t)$ represents the crack opening displacement (COD) function at the crack tips.

For a curved crack in a circular region with the traction free condition on the circular boundary $C_{R}$, the appropriate complex potential is

$$
\begin{equation*}
\phi(z)=\phi_{p}(z)+\phi_{h}(z) \tag{6}
\end{equation*}
$$

where $\phi(z)$ and $\phi_{p}(z)$ represent the modified and original complex potentials, respectively.

Since the circular boundary is traction free, we have $\operatorname{Im}(z)=0, z \in C_{R}$ and from (6), gives

$$
\begin{equation*}
\phi_{p}(z)+\phi_{h}(z)-\left(\overline{\phi_{p}(z)}+\overline{\phi_{h}(z)}\right)=0, \quad z \in C_{R} \tag{7}
\end{equation*}
$$

which leads to

$$
\begin{equation*}
\phi_{h}(z)=\overline{\phi_{p}}\left(\frac{R^{2}}{z}\right)=\frac{1}{\pi i} \int \frac{z g(t) d \bar{t}}{R^{2}-\overline{t z}} . \tag{8}
\end{equation*}
$$

A derivative of the complex potential $\phi(z)=G w+$ if in a specified direction of the point $z$ is

$$
\begin{equation*}
\frac{\partial(G w+i f)}{\partial n}=\frac{1}{\pi} \int_{L} \frac{\exp (i \alpha) g(t) d t}{(t-z)^{2}}+\frac{1}{\pi} \int_{L} \frac{\exp (i \alpha) R^{2} g(t) d \bar{t}}{\left(R^{2}-\bar{t} z\right)^{2}} \tag{9}
\end{equation*}
$$

where $\alpha$ denotes an inclined angle for $d z$ with respect to the x -axis.
From Equation (9), for a point $z$ on the segment $\overline{z z+d z}$, we obtain the following stress components $\sigma_{z n}$

$$
\begin{equation*}
\sigma_{z n}=G \frac{\partial w}{\partial n}=\frac{1}{\pi} \operatorname{Re} \int_{L} \frac{\exp (i \alpha) g(t)}{(t-z)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L} \frac{\exp (i \alpha) R^{2} g(t) d \bar{t}}{\left(R^{2}-\overline{t z}\right)^{2}} \tag{10}
\end{equation*}
$$

For a single curved crack in a circular region with traction free circular boundary, by letting $z \rightarrow t_{0}$ and $\alpha \rightarrow \alpha_{0}$ in (11), a hypersingular integral equation for a curved crack problem in circular region is obtained as follows (Chen (2003))

$$
\begin{equation*}
\frac{1}{\pi} f \cdot p \operatorname{Re} \int_{L} \frac{\exp \left(i \alpha_{0}\right) g(t) d t}{\left(t-t_{0}\right)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L} \frac{\exp \left(i \alpha_{0}\right) R^{2} g(t) d \bar{t}}{\left(R^{2}-\bar{t} t_{0}\right)^{2}}=\bar{P}\left(t_{0}\right), t_{0} \in L . \tag{11}
\end{equation*}
$$

where $\alpha_{0}$ is the angle at the point $t_{0}$ on the curve configuration and $R$ is a radius of a circular region. In Equation (11), $\bar{P}\left(t_{0}\right)$ denotes the loading on the crack faces, which is given beforehand.

Consider two curved cracks in a circular region with traction free along the outer circular boundary, and some loading $\sigma_{z n}\left(=G \frac{\partial w}{\partial n}\right)$ is applied on the crack faces (Figure 1). The boundary conditions along two crack faces are

$$
\begin{equation*}
\sigma_{z n}\left(t_{j 0}\right)=\bar{P}_{j}\left(t_{j 0}\right), \quad\left(t_{j 0} \in L_{j}, j=1,2\right) \tag{12}
\end{equation*}
$$

where $\bar{P}_{j}\left(t_{j_{0}}\right)\left(t_{j_{0}} \in L_{j}, j=1,2\right)$ are the loading applied on the crack faces.The formulation of the hypersingular integral equation for crack-1 is introduced below. If the COD is placed at point $z=t_{1}, d z=d t_{1}$, and $g_{1}\left(t_{1}\right)$ is the COD for crack-1, after using Equation (11) and making integration, the traction influence at the point $t_{10}$ denoted by $p_{11}\left(t_{10}\right)$ can be expressed as follows

$$
\begin{align*}
& \frac{1}{\pi} f \cdot p \operatorname{Re} \int_{L 1} \frac{\exp \left(i \alpha_{10}\right) g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{10}\right)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L} \frac{\exp \left(i \alpha_{10}\right) R^{2} g_{1}\left(t_{1}\right) d \overline{t_{1}}}{\left(R^{2}-\bar{t}_{1} t_{10}\right)^{2}} \\
& =p_{11}\left(t_{10}\right), t_{10} \in L \tag{13}
\end{align*}
$$

In addition, from Equation (10), the traction influence at the point $t_{10}$ from COD function $g_{2}\left(t_{2}\right)$ for crack-2 is

$$
\begin{align*}
& \frac{1}{\pi} \operatorname{Re} \int_{L 2} \frac{\exp \left(i \alpha_{10}\right) g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{10}\right)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L 2} \frac{\exp \left(i \alpha_{10}\right) R^{2} g_{2}\left(t_{2}\right) d \overline{t_{2}}}{\left(R^{2}-\overline{t_{2}} t_{10}\right)^{2}} \\
& =p_{12}\left(t_{10}\right), t_{10} \in L \tag{14}
\end{align*}
$$

By superposition of the COD for the curved crack-1, $g_{1}\left(t_{1}\right)$ and the COD for the curved crack-2, $g_{2}\left(t_{2}\right)$, we obtain the hypersingular integral equation for crack-1 which is

$$
\begin{align*}
& \frac{1}{\pi} \operatorname{Re} f \cdot p \cdot \int_{L 1} \frac{\exp \left(i \alpha_{10}\right) g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{10}\right)^{2}}-\frac{1}{\pi} \operatorname{Re} \int_{L 1} \frac{\exp \left(i \alpha_{10}\right) R^{2} g_{1}\left(t_{1}\right) d \overline{t_{1}}}{\left(R^{2}-\bar{t}_{1} t_{10}\right)^{2}} \\
& +\frac{1}{\pi} \operatorname{Re} \int_{L 2} \frac{\exp \left(i \alpha_{10}\right) g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{10}\right)^{2}}-\frac{1}{\pi} \operatorname{Re} \int_{L 2} \frac{\exp \left(i \alpha_{10}\right) R^{2} g_{2}\left(t_{2}\right) d \bar{t}_{2}}{\left(R^{2}-\overline{t_{2}} t_{10}\right)^{2}} \\
& =\bar{P}_{1}\left(t_{10}\right), t_{10} \in L_{1} \tag{15}
\end{align*}
$$

where $\bar{P}_{1}\left(t_{10}\right)$ is the given boundary traction shown in Equation (12).
Similarly, the hypersingular integral equation for crack is

$$
\begin{align*}
& \frac{1}{\pi} \operatorname{Re} f \cdot p \cdot \int_{L 2} \frac{\exp \left(i \alpha_{20}\right) g_{2}\left(t_{2}\right) d t_{2}}{\left(t_{2}-t_{20}\right)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L 2} \frac{\exp \left(i \alpha_{20}\right) R^{2} g_{2}\left(t_{2}\right) d \overline{t_{2}}}{\left(R^{2}-\bar{t}_{2} t_{20}\right)^{2}} \\
& +\frac{1}{\pi} \operatorname{Re} \int_{L 1} \frac{\exp \left(i \alpha_{20}\right) g_{1}\left(t_{1}\right) d t_{1}}{\left(t_{1}-t_{20}\right)^{2}}+\frac{1}{\pi} \operatorname{Re} \int_{L 1} \frac{\exp \left(i \alpha_{20}\right) R^{2} g_{1}\left(t_{1}\right) d t_{1}}{\left(R^{2}-\overline{t_{1}} t_{20}\right)^{2}} \\
& =\overline{P_{2}}\left(t_{20}\right), t_{20} \in L_{2} . \tag{16}
\end{align*}
$$

In the present study, constant loadings are applied on the faces of two cracks, which take the following form

$$
\begin{equation*}
\overline{P_{j_{0}}}=-p_{0},\left(t_{j_{0}} \in L_{j}, j=1,2\right) . \tag{17}
\end{equation*}
$$

Clearly, the formulation can be extended to the case of $\mathrm{N}(\mathrm{N}>2)$ curved cracks with traction free condition along circular boundary.


Figure 1: Curve cracks in circular region

## 3. SOLUTION APPROACH

For the numerical computation of the hypersingular integral equation, the curve length method is suggested (Chen (2003)). For the solution approaches, we consider a particular case of doubly circular arc cracks (Figure 1). The curved configurations are mapped on the real axis $s$ with an interval of length $2 a$ and $2 b$ respectively. The mapping relation is expressed by the functions $t_{1}\left(s_{1}\right)$ and $t_{2}\left(s_{2}\right)$ as follows

$$
\begin{equation*}
\left.g_{1}\left(t_{1}\right)\right|_{t_{1}=t_{1}\left(s_{1}\right)}=\sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right) \text { where } H_{1}\left(s_{1}\right)=H_{11}\left(s_{1}\right)+i H_{12}\left(s_{1}\right) \tag{18}
\end{equation*}
$$

and

$$
\begin{equation*}
\left.g_{2}\left(t_{2}\right)\right|_{t_{2}=t_{2}\left(s_{2}\right)}=\sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) \text { where } H_{2}\left(s_{2}\right)=H_{21}\left(s_{2}\right)+i H_{22}\left(s_{2}\right) \text {. } \tag{19}
\end{equation*}
$$

In Equations (18) and (19), $g_{1}\left(t_{1}\right)$ and $g_{2}\left(t_{2}\right)$ are chosen in such way that they must satisfy the behaviour of the COD at the vicinity of crack tips. The following substitutions are used:

$$
\begin{equation*}
\left.p(t)\right|_{t=t(s)}=P(s), d t=\exp (i \alpha) d s, d \bar{t}=\exp (-i \alpha) d s \tag{20}
\end{equation*}
$$

Using (18), (19) and (20), Equations (15) and (16) can be written as

$$
\begin{equation*}
I_{1}\left(s_{10}\right)+I_{2}\left(s_{10}\right)+I_{3}\left(s_{10}\right)+I_{4}\left(s_{10}\right)=P_{1}\left(s_{10}\right) \tag{21}
\end{equation*}
$$

and

$$
\begin{equation*}
L_{1}\left(s_{20}\right)+L_{2}\left(s_{20}\right)+L_{3}\left(s_{20}\right)+L_{4}\left(s_{20}\right)=P_{2}\left(s_{20}\right) \tag{22}
\end{equation*}
$$

where

$$
\begin{aligned}
& I_{1}\left(s_{10}\right)=\frac{1}{\pi} f \cdot p \cdot \int_{-a}^{a} \sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right) \frac{D_{1}\left(s_{1}, s_{10}\right) d s_{1}}{\left(s_{1}-s_{10}\right)^{2}} ; \\
& I_{2}\left(s_{10}\right)=\frac{1}{\pi} \int_{-a}^{a} \sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right) D_{2}\left(s_{1}, s_{10}\right) d s_{1} ; \\
& I_{3}\left(s_{10}\right)=\frac{1}{\pi} \int_{-a}^{a} \sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) \frac{D_{3}\left(s_{2}, s_{10}\right) d s_{2}}{\left(s_{2}-s_{10}\right)^{2}} ; \\
& I_{4}\left(s_{10}\right)=\frac{1}{\pi} \int_{-a}^{a} \sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) D_{4}\left(s_{2}, s_{10}\right) d s_{2} ;
\end{aligned}
$$

and

$$
\begin{aligned}
& L_{1}\left(s_{20}\right)=\frac{1}{\pi} f \cdot p \cdot \int_{-b}^{b} \sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) \frac{E_{1}\left(s_{2}, s_{20}\right) d s_{2}}{\left(s_{2}-s_{20}\right)^{2}} ; \\
& L_{2}\left(s_{20}\right)=\frac{1}{\pi} \int_{-b}^{b} \sqrt{b^{2}-s_{2}^{2}} H_{2}\left(s_{2}\right) E_{2}\left(s_{2}, s_{20}\right) d s_{2} ; \\
& L_{3}\left(s_{20}\right)=\frac{1}{\pi} \int_{-b}^{b} \sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right) \frac{E_{3}\left(s_{1}, s_{20}\right) d s_{1}}{\left(s_{1}-s_{20}\right)^{2}} ; \\
& L_{4}\left(s_{20}\right)=\frac{1}{\pi} \int_{-b}^{b} \sqrt{a^{2}-s_{1}^{2}} H_{1}\left(s_{1}\right) E_{4}\left(s_{1}, s_{20}\right) d s_{1} ;
\end{aligned} .
$$

$D_{1}, D_{2}, D_{3}, D_{4}$ and $E_{1}, E_{2}, E_{3}, E_{4}$ are respectively given by

$$
\begin{aligned}
& D_{1}\left(s_{1}, s_{10}\right)=\operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{1}+\alpha_{10}\right)\right)\left(s_{1}-s_{10}\right)^{2}}{\left(t_{1}-t_{10}\right)^{2}}\right) ; \\
& D_{2}\left(s_{1}, s_{10}\right)=R^{2} \operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{10}-\alpha_{1}\right)\right)}{\left(R^{2}-\overline{t_{1}} t_{10}\right)^{2}}\right) ; \\
& D_{3}\left(s_{2}, s_{10}\right)=\operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{2}+\alpha_{10}\right)\right)\left(s_{2}-s_{10}\right)^{2}}{\left(t_{2}-t_{10}\right)^{2}}\right) ; \\
& D_{4}\left(s_{2}, s_{10}\right)=R^{2} \operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{10}-\alpha_{2}\right)\right)}{\left(R^{2}-\overline{t_{2}} t_{10}\right)^{2}}\right) ; \\
& E_{1}\left(s_{2}, s_{20}\right)=\operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{2}+\alpha_{20}\right)\right)\left(s_{2}-s_{20}\right)^{2}}{\left(t_{2}-t_{20}\right)^{2}}\right) ; \\
& E_{2}\left(s_{2}, s_{20}\right)=R^{2} \operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{20}-\alpha_{2}\right)\right)}{\left(R^{2}-\overline{t_{2}} t_{20}\right)^{2}}\right) ; \\
& E_{3}\left(s_{1}, s_{20}\right)=\operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{1}+\alpha_{20}\right)\right)\left(s_{1}-s_{20}\right)^{2}}{\left(t_{1}-t_{20}\right)^{2}}\right) ; \\
& E_{4}\left(s_{1}, s_{20}\right)=R^{2} \operatorname{Re}\left(\frac{\exp \left(i\left(\alpha_{20}-\alpha_{1}\right)\right)}{\left(R^{2}-\overline{t_{1}} t_{20}\right)^{2}}\right) ;
\end{aligned}
$$

Equations (21) and (22) are to be solved numerically. For the numerical computation, the following integration rules developed by Mayrofer and Fisher (1992) are used, which are

$$
\begin{equation*}
\frac{1}{\pi} f \cdot p \cdot \int_{-a}^{a} \frac{\sqrt{a^{2}-s^{2}} G(s) d s}{\left(s-s_{0}\right)}=\sum_{j=1}^{M+1} W_{j}\left(s_{0}\right) G\left(s_{j}\right) \quad\left(\left|s_{0}\right|<a\right) \tag{23}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{1}{\pi} \int_{-a}^{a} \sqrt{a^{2}-s^{2}} G(s) d s=\frac{1}{M+2} \sum_{j=1}^{M+1}\left(a^{2}-s_{j}^{2}\right) G\left(s_{j}\right) \tag{24}
\end{equation*}
$$

where $G(s)$ is a given regular function, $M \in \mathrm{Z}$,

$$
s_{j}=s_{o j}=a \cos \left(\frac{j \pi}{M+2}\right), \quad j=1,2,3, \ldots, M+1
$$

and

$$
W_{j}\left(s_{0}\right)=-\frac{2}{M+2} \sum_{n=0}^{M}(n+1) \sin \left(\frac{j \pi}{M+2}\right) \sin \left(\frac{(n+1) j \pi}{M+2}\right) U_{n}\left(\frac{s_{0}}{a}\right) .
$$

Here $U_{n}(t)$ is a Chebyshev polynomial of the second kind, defined by

$$
U_{n}(t)=\frac{\sin ((n+1) \theta)}{\sin \theta}, t=\cos \theta
$$

Denote

$$
V_{j}^{n}=\sin \left(\frac{j \pi}{M+2}\right) \sin \left(\frac{(n+1) j \pi}{M+2}\right),
$$

$H_{1}(s)$ and $H_{2}(s)$ are evaluated using

$$
H_{1}(s)=\sum_{n=0}^{M} c_{1 n} u_{n}\left(\frac{s}{a}\right),|s| \leq a
$$

and

$$
H_{2}(s)=\sum_{n=0}^{M} c_{2 n} u_{n}\left(\frac{s}{b}\right),|s| \leq b
$$

where

$$
\begin{aligned}
& c_{1 n}=\frac{2}{M+2} \sum_{j=1}^{M+1} V_{j}^{n} H_{1}\left(s_{1}\right), \\
& c_{2 n}=\frac{2}{M+2} \sum_{j=1}^{M+1} V_{j}^{n} H_{2}\left(s_{2}\right) .
\end{aligned}
$$

and $H_{1}\left(s_{1}\right)$ and $H_{2}\left(s_{2}\right)$ are define in (18) and (19) respectively.

## 4. NUMERICAL EXAMPLES

### 4.1 Example 1

In this example, two half circular arc cracks in circular region is considered Figure 2(a). The calculated results for SIFs at the crack tips of inner and outer crack are expressed as

$$
\begin{align*}
& K_{3, A 1}=K_{3, A 2}=F_{3, A 1}\left(k_{1}\right) \sqrt{\pi b_{2}}  \tag{25}\\
& K_{3, A 1}=K_{3, A 2}=F_{3, A 1}\left(k_{1}\right) \sqrt{\pi b_{2}} \tag{26}
\end{align*}
$$

where $b_{1}=r_{1} \sin \theta$ and $b_{2}=r_{2} \sin \theta$
For comparison purposes, we use Fredholm integral equation (FIE) of theas in Chen (1993), subjected to the remote stress $\sigma_{n z}=-p_{0}$. The numerical results are tabulated in Table 1, as well as in Figure (3), with $k_{1}=k_{2}=0.5$ where $k_{1}=r_{1} / r_{2}$ and $k_{2}=r_{2} / R$.

Figures 4 and 5 show the effect of distance between two cracks and a circular Boundary $C_{R}$. It is found that for different values of $k_{1}$. SIFs for crack-1 (Figure 4(a)) is higher than those of crack-2 (Figure 4(b)). Similar behaviour is observed for different values of $k_{2}$ (Figure 5). It is also observed that the SIF increases as the distance between two cracks (with $k_{2}=0 \cdot 5$ ) (Figure 4) and the distance between crack and boundary with (with $k_{2}=0 \cdot 5$ ) (Figure 5) decrease ( $k_{2}$ and $k_{1}$ increase).

### 4.2 Example 2

Consider two circular arc cracks placed eccentrically inside the circular region (Figure (2b)). The boundary traction is assumed to be $\sigma_{n z}=-p_{0}$ and the calculated results for SIFs at the crack tips $A_{1}, A_{2}, B_{1}$ and $B_{2}$ are respectively, expressed as

$$
\begin{align*}
& K_{3, A_{1}}=F_{3 \cdot A_{1}}\left(d_{1} / r_{1}\right) \sigma_{z n} \sqrt{\pi r_{1}}  \tag{27}\\
& K_{3, A_{2}}=F_{3 \cdot A_{2}}\left(d_{1} / r_{1}\right) \sigma_{z n} \sqrt{\pi r_{1}}
\end{align*}
$$

and

$$
\begin{align*}
& K_{3, B_{1}}=F_{3 . B_{1}}\left(d_{2} / r_{2}\right) \sigma_{z n} \sqrt{\pi r_{2}}  \tag{28}\\
& K_{3, B_{2}}=F_{3 . B_{2}}\left(d_{2} / r_{2}\right) \sigma_{z n} \sqrt{\pi r_{2}}
\end{align*}
$$

The calculated values are shown in Figure 6. Observably, as the values of $d_{1} / r_{1}$ and $d_{2} / r_{2}$ increase, the SIF increases (Figures 6(a) and (b), respectively). At $\theta=\pi / 2$, the values of the stress intensity factor for $F_{B_{1}}$ are greater than $F_{B_{2}}$ decrease, with $d_{1} / r_{1}=0 \cdot 5$ (Figure 6(c)).


Figure 2(a): Two half circular are cracks in a circular region


Figure 2(b): Eccentrically half circular are cracks in a circular region


Figure 2(c): Eccentrically half circular are cracks outside a circular hole

### 4.3 Example 3

Consider two half circular arc cracks placed eccentrically outside the circular region (Figure 2(c)) and the calculated results are shown in Figure (7). The stress is subjected to $\sigma_{n z}=-p_{0}$ and the SIFs at the crack tips are defined as Equations (27) and (28). The SIF at the cracks tips decrease as the value of $d_{1} / r_{1}$ increases, with $d_{2} / r_{2}=0 \cdot 5$ (Figure 7(a)). Similar behaviour can be seen as $d_{12} / r_{2}$, with $d_{1} / r_{1}=0.5$ (Figure 7(b)).

TABLE 1: SIFs for $k_{1}=0.5$ and $k_{2}=0.5$

|  | $F_{A_{1}}=F_{A_{2}}$ |  | $F_{B_{1}}=F_{B_{2}}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| $\sigma$ | In this paper | Chen et al. <br> (2004) | In this paper | Chen et al. <br> $(\mathbf{2 0 0 4})$ |
| 0 | -0.6068 | -0.6062 | 0.4125 | 0.4105 |
| 10 | -0.4080 | -0.4075 | 0.6064 | 0.6045 |
| 20 | -0.1968 | -0.1962 | 0.8122 | 0.8118 |
| 30 | 0.0203 | 0.0201 | 1.0238 | 1.0236 |
| 40 | 0.2369 | 0.2362 | 1.2346 | 1.2341 |
| 50 | 0.4463 | 0.4459 | 1.4383 | 1.4379 |
| 60 | 0.6421 | 0.6401 | 1.6287 | 1.6274 |
| 70 | 0.8184 | 0.8182 | 1.8002 | 1.7991 |
| 80 | 0.9698 | 0.9695 | 1.9469 | 1.9464 |
| 90 | 1.0918 | 1.902 | 2.0651 | 2.0646 |



Figure 3: SIFs at cracks tips for $k_{1}=0.5$ and $k_{2}=0.5$


Figure 4 (a): Nondimensionalise SIFs for different values of $k_{1}$, and $k_{2}=0.5$ for $F_{B_{1}}$ and $F_{B_{2}}$


Figure 4 (b): Nondimensionalise SIFs for different values of $k_{1}$,

$$
\text { and } k_{2}=0.5 \text { for } F_{A_{1}} \text { and } F_{A_{2}}
$$



Figure 5 (a): Non dimensionalise SIFs for different values of $k_{2}, k_{1}=0.5$ for $F_{B_{1}}$ and $F_{B_{2}}$,


Figure 5 (b): Non dimensionalise SIFs for different values of $k_{2}, k_{1}=0.5$

$$
\text { for } F_{A_{1}} \text { and } F_{A_{2}}
$$



Figure 6 (a): Nondimesionalise SIFs for different values of $d_{1} / r_{1}$ and

$$
d_{2} / r_{2}=0.5
$$



Figure 6 (b): Nondimesionalise SIFs for $d_{2} / r_{2}$ and $d_{1} / r_{1}=0.5$

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Figure 6 (c): SIFs at $\pi / 2$ when $d_{2} / r_{2}$ varies and $d_{1} / r_{1}=0.5$


Figure 7 (a): Nondimensionalise SIFs for different values of $d_{1} / r_{1}$ and

$$
d_{2} / r_{2}=0.5
$$



Figure 7 (b): Nondimensionalise SIFs for different values of $d_{2} / r_{2}$ and $d_{1} / r_{1}=0.5$.

## 5. CONCLUSION

In this paper, the problem of antiplane multiple curved cracks and a circular region is studied. The hypersingular integral equation is formulated by using the complex variable function method. The obtained integral equations are solved numerically. It is found that the SIF increases as the cracks become closer to the circular boundary.

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