Malaysian Journal of Mathematical Sciences 5(1): 45-60 (2011)

# $\Lambda_r$ .Sets and Separation Axioms

<sup>1</sup>M. J. Jeyanthi, <sup>2</sup>Adem Kilicman, <sup>3</sup>S. Pious Missier and <sup>4</sup>P.Thangavelu <sup>1</sup>Aditanar College of Arts and Science, Tiruchendur-628 216 (T.N.), India. <sup>2</sup>Institute of Mathematical Research and Department of Mathematics, Universiti Putra Malaysia, 43400 UPM Serdang, Selangor, Malaysia <sup>3</sup>Post Graduate and Research Department of Mathematics, V.O.Chidambaram College, Thoothukudi-628 008 (T.N.), India <sup>4</sup>Department of Mathematics, Aditanar College of Arts and Science, Tiruchendur-628 216 (T.N.), India E-mail: <sup>1</sup>jeyanthimanickaraj@gmail.com, <sup>2</sup>akilicman@putra.upm.edu.my, <sup>3</sup>spmissier@gmail.com and <sup>4</sup>ptvelu12@gmail.com

# ABSTRACT

Separation axioms are among the most common and important and interesting concepts in topology as well as in bitopologies. In this paper, we introduce  $\Lambda_r$ -sets and some weak separation axioms using  $\Lambda_r$ -open sets and  $\Lambda_r$ -closure operator.

Keywords:  $\Lambda_r$  -sets,  $\Lambda_r$  -open sets and  $\Lambda_r$  -  $T_k$ , k = 0,1,2 spaces.

2000 Mathematics Subject Classification: 54D10

# INTRODUCTION AND PRELIMINARIES

The separation axioms are important and interesting concepts among the topological spaces. Most of the definitions appeared simple, however the topological structure and properties might be complex and not always that easy to comprehend. For example, in digital topology, several spaces that fails to satisfy to be  $T_1$  which are important in the study of the geometric and topological properties of digital images. Caldas and Dontchev (2000) characterized the concepts of  $\Lambda_s$ -sets and  $V_s$ -sets in topological spaces. By using the regularly open and regularly closed sets these structures can also be extended to the bitopological spaces. For more details on regularly pairwise open and closed sets, see for example, Fawakhreh and Kilicman (2002), Kilicman and Salleh (2007a), Kilicman and Salleh (2007b) and Kilicman and Salleh (2008). The purpose of this paper is to continue the research along these directions but this time by utilizing regularly-open sets. For details, see Fawakhreh and Kilicman (2004), Fawakhreh and Kilicman (2006) and Kilicman and Salleh (2009). Caldas and Jafari (2004) introduced the notions of  $\Lambda_{\delta} - T_0$ ,  $\Lambda_{\delta} - T_1$ , and  $\Lambda_{\delta} - T_2$  topological spaces. In this paper, we introduce some  $\Lambda_r$ -separation axioms in topological spaces. To define and investigate the axioms, we use the  $\Lambda_r$ -open sets. We call these axioms as  $\Lambda_r - T_0$ ,  $\Lambda_r - T_1$ , and  $\Lambda_r - T_2$ .

Throughout the paper  $(X, \tau)$  (or simply X) will always denote a topological space. Let  $(X, \tau)$  be a topological space and S be a subset of X. Then S is called regularly-open if S = Int(cl S). The complement  $S^{c}(=X-S)$  of a regularly-open set S is called the regularly-closed set. The family of all regularly-open sets (resp. regularly-closed sets) will be denoted by  $RO(X, \tau)$  (resp.  $RC(X, \tau)$ ). A subset S of X is called  $\Lambda$ -set if it is the intersection of open sets containing S. The complement of  $\Lambda$ -set is called the V-set.

# $\Lambda_r$ -SETS AND $V_r$ -SETS

**Definition 2.1** Let S be a subset of a topological space  $(X, \tau)$ . We define the sets  $\Lambda_r(S)$  and  $V_r(S)$  as follows:

$$\Lambda_{r}(S) = \bigcap \{ G/G \in \operatorname{RO}(X,\tau) \text{ and } S \subseteq G \}$$
  
$$V_{r}(S) = \bigcup \{ F/F \in \operatorname{RC}(X,\tau) \text{ and } S \supseteq F \}$$

**Lemma 2.2** For subsets S,Q and S<sub>i</sub>,  $i \in I$ , of a topological space  $(X, \tau)$ , the following properties hold:

- (1)  $S \subseteq \Lambda_r(S)$
- (2)  $Q \subseteq S \Longrightarrow \Lambda_r(Q) \subseteq \Lambda_r(S)$
- (3)  $\Lambda_r(\Lambda_r(S)) = \Lambda_r(S)$
- (4) If  $S \in RO(X, \tau)$ , then  $S = \Lambda_r(S)$
- (5)  $\Lambda_{r}(\bigcup_{i\in I} S_{i}) \supseteq \bigcup_{i\in I} \Lambda_{r}(S_{i})$

- (6)  $\Lambda_{r}(\bigcap_{i\in I} S_{i}) \subseteq \bigcap_{i\in I} \Lambda_{r}(S_{i})$
- (7)  $\Lambda_r(S^c) = (V_r(S))^c$

Proof.

- (1) Let  $x \notin \Lambda_r(S)$ . Then there exists a regularly-open set G such that  $S \subseteq G$  and  $x \notin G$ . Hence  $x \notin S$  and so  $S \subseteq \Lambda_r(S)$ .
- (2) Let x ∉ Λ<sub>r</sub>(S). Then there exists a regularly-open set G such that S ⊆ G and x ∉ G. By our assumption Q ⊆ S, Q ⊆ G and hence x ∉ Λ<sub>r</sub>(Q). This shows (2).
- (3) From (1) and (2), Λ<sub>r</sub>(S) ⊆ Λ<sub>r</sub>(Λ<sub>r</sub>(S)). If x ∉ Λ<sub>r</sub>(S), then there exists a regularly-open set G such that S ⊆ G and x ∉ G. From the definition of Λ<sub>r</sub>(S), Λ<sub>r</sub>(S) ⊆ G and hence x ∉ Λ<sub>r</sub>(Λ<sub>r</sub>(S)). Therefore Λ<sub>r</sub>(Λ<sub>r</sub>(S)) ⊆ Λ<sub>r</sub>(S). This proves (3).
- (4) It directly follows from the definition of  $\Lambda_r(S)$  and lemma 2.2(1).
- (5) From (2),  $\Lambda_r(S_i) \subseteq \Lambda_r(S)$  for each  $i \in I$  where  $S = \bigcup_{i \in I} S_i$  and hence  $\bigcup_{i \in I} \Lambda_r(S_i) \subseteq \Lambda_r(S) = \Lambda_r(\bigcup_{i \in I} S_i).$
- (6) From (2),  $\Lambda_r(S) \subseteq \Lambda_r(S_i)$  for each  $i \in I$  where  $S = \bigcap_{i \in I} S_i$  and hence  $\Lambda_r(S) = \Lambda_r(\bigcap_{i \in I} S_i) \subseteq \bigcap_{i \in I} (S_i)$ .
- (7) Let  $x \in \Lambda_r(S^c)$ . Then for every regularly-open set G containing  $S^c, x \in G$ . Hence  $x \notin G^c$ , for every regularly-closed set  $G^c \subseteq S$ . Therefore  $x \notin V_r(S)$  and hence  $x \in (V_r(S))^c$ . Similarly,  $(V_r(S))^c \subseteq \Lambda_r(S^c)$ . Hence (7) is proved.

By using the above lemma, we can easily verify the next result.

**Lemma 2.3** For subsets S, Q and S<sub>i</sub>,  $i \in I$ , of a topological space  $(X, \tau)$ , the following properties hold:

- (1)  $V_r(S) \subseteq S$
- (2)  $Q \subseteq S \Rightarrow V_r(Q) \subseteq V_r(S)$
- (3)  $V_r(V_r(S)) = V_r(S)$
- (4) If  $S \in RC(X, \tau)$ , then  $S = V_r(S)$

M.J.Jeyanthi, Adem Kilicman, S.Pious Missier & P.Thangavelu

(5)  $V_{r}(\bigcap_{i \in I}(S_{i}) \subseteq \bigcap_{i \in I} V_{r}(S_{i})$ (6)  $V_{r}(\bigcup_{i \in I} S_{i}) \supseteq \bigcup_{i \in I} V_{r}(S_{i})$ 

In general, we have

 $\Lambda_r(S \cap Q) \neq \Lambda_r(S) \cap \Lambda_r(Q) \quad \text{and} \quad \Lambda_r(S \cap Q) \neq \Lambda_r(S) \cup \Lambda_r(Q) \quad \text{as} \quad \text{the} \\ \text{following examples show.}$ 

#### Example 2.4

Let  $X = \{a, b, c\}$  and  $\tau = \{X, \phi, \{a\}, \{b, c\}\}.$ 

Then  $RO(X, \tau) = \{X, \phi, \{a\}, \{b, c\}\}$ . Take  $S = \{b\}$  and  $Q = \{c\}$ . Then  $\Lambda_r(S) = \{b, c\}, \Lambda_r(Q) = \{b, c\}, \Lambda_r(S) \cap \Lambda_r(Q) = \{b, c\}$  but  $\Lambda_r(S \cap Q) = \phi$ .

#### Example 2.5

Let 
$$X = \{a, b, c\}$$
 and  $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}.$   
Then  $RO(X, \tau) = \{X, \phi, \{a\}, \{b\}\}.$  Take  $S = \{a\}$  and  $Q = \{b\}.$   
Then  $\Lambda_r(S) = \{a\}, \Lambda_r(Q) = \{b\}, \Lambda_r(S) \cup \Lambda_r(Q) = \{a, b\}$  but  $\Lambda_r(S \cup Q) = X.$ 

**Definition 2.6** A subset S of a space  $(X, \tau)$  is called a

(1) regular-  $\Lambda$  -set, briefly  $\Lambda_r$  -set if  $S = \Lambda_r(S)$ 

(2) regular-V-set, briefly  $V_r$ -set if  $S = V_r(S)$ 

The set of all  $\Lambda_r$  -sets (resp.  $V_r$  -sets) is denoted by  $\Lambda_r(X,\tau)$  (resp.  $V_r(X,\tau)$ ).

**Remark 2.7** Clearly regular- $\Lambda$ -sets are  $\Lambda$ -sets and regular-V-sets are V-sets. Observe that a subset S is a regular- $\Lambda$ -set if S<sup>c</sup> is a regular-V-set. Also observe that every regular- $\Lambda$ -set is a regularly-open set.

**Proposition 2.8** For a space  $(X, \tau)$ , the following statements hold:

- (1)  $\phi$  and X are  $\Lambda_r$  -sets and  $V_r$  -sets
- (2) Every union of  $V_r$  -sets is a  $V_r$  -set
- (3) Every intersection of  $\Lambda_r$  -sets is a  $\Lambda_r$  -set.

Proof.

- (1) It is obvious.
- (2) Let  $\{S_i / i \in I\}$  be a family of  $V_r$  -sets in  $(X, \tau)$ . Then  $S_i = V_r(S_i)$  for each  $i \in I$ . Let  $S = \bigcup_{i=I} S_i$ . Then  $V_r(S) = V_r(\bigcup_{i=I} S_i) \supseteq \bigcup_{i=I} V_r(S_i) = \bigcup_{i=I} S_i = S$ . Also  $V_r(S) \subseteq S$  and hence S is a  $V_r$  -set.
- (3) By using lemma 2.2(6) and 2.2(1), we get (3).

The following example shows that union of  $\Lambda_r$  -sets need not be a  $\Lambda_r$  -set.

## Example 2.9

Let  $X = \{a, b, c\}$  and  $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ . Then  $RO(X, \tau) = \{X, \phi, \{a\}, \{b\}\}$  and  $\Lambda_r(X, \tau) = \{X, \phi, \{a\}, \{b\}\}$ . Here  $\{a\}$  and  $\{b\}$  are  $\Lambda_r$  -sets but  $\{a\} \cup \{b\} = \{a, b\}$  is not a  $\Lambda_r$  -set.

Similar to the previous case the following example shows that intersection of  $V_r$ -sets need not be a  $V_r$ -set.

### Example 2.10

Let X and  $\tau$  be defined as in example 2.9. Then  $V_r(X,\tau) = \{X, \phi, \{b,c\}, \{a,c\}\}$ . Here  $\{b,c\}$  and  $\{a,c\}$  are  $V_r$ -sets but  $\{b,c\} \cap \{a,c\} = \{c\}$  is not a  $V_r$ -set.

In order to achieve our purpose, we recall the following definition (Jain (1980)).

**Definition 2.11** Let  $(X, \tau)$  be a topological space. Then the regular-closure of A, denoted by rcl(A) is defined by

$$\operatorname{rcl}(A) = \bigcap \{ F/F \in \operatorname{RC}(X, \tau) \text{ and } F \supset A \}.$$

**Lemma 2.12** Let  $(X,\tau)$  be a topological space and  $x \in X$ . Then  $y \in \Lambda_r(\{x\})$  if  $x \in rcl(\{y\})$ .

Proof.

Suppose  $y \in \Lambda_r(\{x\})$ . Then for every regularly-open set  $G \supseteq \{x\}$ ,  $y \in G$ . If  $x \notin rcl(\{y\})$ , then  $\exists H \in RC(X, \tau)$  such that  $\{y\} \subset H$  and  $x \notin H$ . That implies  $x \in X - H$ ,  $X - H \in RO(X, \tau)$  and  $y \notin X - H$ . Take X - H = G.

Then  $G \in RO(X, \tau), \{x\} \subseteq G$  and  $y \notin G$ . By this contradiction, we get  $x \in rcl(\{y\})$ . Conversely, suppose  $x \in rcl(\{y\})$ . Then for every regularlyclosed set  $G \supset \{y\}, x \in G$ . If  $y \notin \Lambda_r(\{x\})$ , then  $\exists H \in RO(X, \tau)$  such that  $\{x\} \subseteq H$  and  $y \notin H$ . Take X - H = G. Then  $G \in RC(X, \tau), y \in G$  and  $x \notin G$ . So there exists a regularly-closed set  $G \supset \{y\}$  such that  $x \notin G$ . By this contradiction, we get  $y \notin \Lambda_r(\{x\})$ .

**Theorem 2.13** The following statements are equivalent for any points x and y in a topological space  $(X, \tau)$ 

- (1)  $\Lambda_r(\{x\}) \neq \Lambda_r(\{y\})$
- (2)  $\operatorname{rcl}(\{x\}) \neq \operatorname{rcl}(\{y\})$

Proof.

 $\begin{array}{ll} (1) \rightarrow (2): & \text{Suppose} \quad \Lambda_r(\{x\}) \neq \Lambda_r(\{y\}). \text{ Then } \quad \exists z \in X \quad \text{such that} \\ z \in \Lambda_r(\{x\}) \text{ and } z \in \Lambda_r(\{y\}). \text{ Therefore } x \in \operatorname{rcl}(\{z\}) \text{ and } y \in \operatorname{rcl}(\{z\}). \text{ Hence} \\ \{x\} \cap \operatorname{rcl}(\{z\}) \neq \phi \quad \text{and} \quad \{y\} \cap \operatorname{rcl}(\{z\}) \neq \phi. \text{ Since } x \in \operatorname{rcl}(\{z\}), \\ \operatorname{rcl}(\{x\}) \subset \operatorname{rcl}(\{z\}) \text{ and hence } \{y\} \cap \operatorname{rcl}(\{x\}) \neq \phi. \text{ Thus } \operatorname{rcl}(\{x\}) \neq \operatorname{rcl}(\{y\}). \end{array}$ 

 $(2) \rightarrow (1)$ : Suppose  $rcl(\{x\}) \neq rcl(\{y\})$ . Then  $\exists z \in X$  such that  $z \in rcl(\{x\})$ and  $z \notin rcl(\{y\})$ . Therefore  $x \in \Lambda_r(\{z\})$  and  $y \notin \Lambda_r(\{z\})$ . So there exists a regularly-open set  $G \supset \{z\}$  such that  $x \in G$  and  $y \notin G$ . Hence  $y \notin \Lambda_r(\{x\})$ and hence  $\Lambda_r(\{x\}) \neq \Lambda_r(\{y\})$ .

**Lemma 2.14** Let  $(X,\tau)$  be a topological space and  $A \in RO(X,\tau)$ . Then  $\Lambda_r(A) = \{x \in X/rcl(\{x\}) \cap A \neq \phi\}.$ 

Proof.

Let  $x \in \Lambda_r(A)$ . Since  $A \in RO(X, \tau)$ ,  $A = \Lambda_r(A)$ . Also  $x \in rcl(\{x\})$  and hence  $rcl(\{x\}) \cap A \neq \phi$ . Conversely, let  $x \in X$  such that  $rcl(\{x\}) \cap A \neq \phi$ . If  $x \notin \Lambda_r(A)$ , then there exists  $V \in RO(X, \tau)$  such that  $A \subseteq V$  and  $x \notin V$ . Let  $y \in rcl(\{x\}) \cap A$ . Since  $y \in rcl(\{x\})$ ,  $x \in \Lambda_r(\{y\})$ . Therefore for every regularly-open set  $G \supseteq \{y\}$  in  $(X, \tau)$ ,  $x \in G$ . Since  $y \in A$  and  $A \subseteq V$ ,  $y \in V$  where  $V \in RO(X, \tau)$ . Hence  $x \in V$ . By this contradiction, we get  $x \in \Lambda_r(A)$ .

Recall that a topological space  $(X, \tau)$  is called a  $r - R_0$  space (Jain (1980)) if for every regularly-open set G,  $x \in G \Rightarrow rcl(\{x\}) \subset G$ .

**Theorem 2.15** For a topological space  $(X, \tau)$ , the following properties are equivalent

- (1)  $(X,\tau)$  is a  $r R_0$  space
- (2) For any  $x \in X$ , rcl( $\{x\}$ )  $\subset \Lambda_r(\{x\})$

Proof.

 $(1) \rightarrow (2)$ : Let  $y \notin \Lambda_r(\{x\})$ . Then there exists  $V \in RO(x, \tau)$  such that  $V \supseteq \{x\}, y \notin V$ . Since  $x \in V \in RO(X, \tau)$ , by (1)  $rcl(\{x\}) \subset V$ . Hence  $y \notin rcl(\{x\})$ . Therefore  $rcl(\{x\}) \subset \Lambda_r(\{x\})$ .

 $(2) \rightarrow (1)$ :Let  $V \in RO(X, \tau)$  and  $x \in V$ . Suppose  $y \in \Lambda_r(\{x\})$ . Then for every regularly-open set  $G \supseteq \{x\}, y \in G$ . Hence  $y \in V$  and hence  $\Lambda_r(\{x\}) \subset V$ . By (2),  $rcl(\{x\}) \subset V$ . Hence  $(X, \tau)$  is a  $r - R_0$  space.

**Result 2.16** If F is regularly-open in  $(X, \tau)$  and  $x \in F$ , then  $\Lambda_r(\{x\}) \subset F$ .

Proof. It directly follows from the definition of  $\Lambda_r(\{x\})$ .

# $\Lambda_r$ -CLOSED SETS AND ITS PROPERTIES

#### Definition 3.1

- (1) Let A be a subset of a space  $(X, \tau)$ . Then A is called a  $\Lambda_r$  -closed set if  $A = S \cap C$  where S is a  $\Lambda_r$  -set and C is a closed set.
- (2) The complement of a  $\Lambda_r$  -closed set is called a  $\Lambda_r$  -open set.
- (3) The collection of all  $\Lambda_r$  -open sets in  $(X,\tau)$  is denoted by  $\Lambda_r O(X,\tau)$ . The collection of all  $\Lambda_r$  -closed sets in  $(X,\tau)$  is denoted by  $\Lambda_r C(X,\tau)$ .
- (4) A point  $x \in X$  is called a  $\Lambda_r$ -cluster point of A if for every  $\Lambda_r$ -open set U containing x,  $A \cap U \neq \phi$ .
- (5) The set of all  $\Lambda_r$  -cluster points of A is called the  $\Lambda_r$  -closure of A and is denoted by  $\Lambda_r$  cl(A).

Let  $(X,\tau)$  be a topological space and A, B and A<sub>k</sub> where  $k \in I$ , subsets of X. Then we have the following properties.

**Property 3.2**  $A \subset \Lambda_r - cl(A)$ .

Proof. Let  $x \notin \Lambda_r$  - cl(A). Then x is not a  $\Lambda_r$  -cluster point of A. So there exists a  $\Lambda_r$  -open set U containing x such that  $A \cap U = \phi$  and hence  $x \notin A$ .

**Property 3.3**  $\Lambda_r - cl(A) = \bigcap \{F/A \subset F \text{ and } F \text{ is } \Lambda_r - closed \}.$ 

Proof. Let  $x \notin \Lambda_r - cl(A)$ . Then there exists a  $\Lambda_r$ -open set U containing x such that  $A \cap U = \phi$ . Take  $F = U^c$ . Then F is  $\Lambda_r$ -closed,  $A \subset F$  and

 $x \notin F$  and hence  $x \notin \cap \{F/A \subset F \text{ and } F \text{ is } \Lambda_r \text{ - closed}\}$ . Similarly,  $\Lambda_r \text{ - cl}(A) \subset \cap \{F/A \subset F \text{ and } F \text{ is } \Lambda_r \text{ - closed}\}.$ 

**Property 3.4** If  $A \subset B$ , then  $\Lambda_r - cl(A) \subset \Lambda_r - cl(B)$ .

Proof. Let  $x \notin \Lambda_r - cl(B)$ . Then there exists a  $\Lambda_r$  - open set U containing x such that  $B \cap U = \phi$ . Since  $A \subset U$ ,  $A \cap U = \phi$  and hence x is not a  $\Lambda_r$  -cluster point of A. Therefore  $x \notin \Lambda_r - cl(A)$ .

**Property 3.5** A is  $\Lambda_r$  - closed if  $A = \Lambda_r - cl(A)$ .

Proof.

Suppose A is  $\Lambda_r$  - closed. Let  $x \notin A$ . Then  $x \in A^c$  and  $A^c$  is  $\Lambda_r$  -open. Take  $A^c = U$ . Then U is a  $\Lambda_r$  -open set containing x and  $A \cap U = \phi$  and hence  $x \notin \Lambda_r$  - cl(A). By using Property 3.2, we get  $A = \Lambda_r$  - cl(A). Conversely, suppose  $A = \Lambda_r$  - cl(A). Since  $A = \bigcap \{F/A \subset F \text{ and } F \text{ is } \Lambda_r \text{ - closed}\}$  by Property 3.3, A is  $\Lambda_r$  -closed.

**Property 3.6**  $\Lambda_r - cl(A)$  is  $\Lambda_r$  -closed.

Proof.

By using the Properties 3.2 and 3.4, we have  $\Lambda_r - cl(A) \subset \Lambda_r - cl(\Lambda_r - cl(A))$ . Let  $x \in \Lambda_r - cl(\Lambda_r - cl(A))$ . That implies x is a  $\Lambda_r$ -cluster point of  $\Lambda_r - cl(A)$ . That implies for every  $\Lambda_r$ -open set U containing x,  $(\Lambda_r - cl(A)) \cap U \neq \phi$ . Let  $y \in \Lambda_r - cl(A) \cap U$ . Then y is a  $\Lambda_r$ -cluster point of A. Therefore for every  $\Lambda_r$ -open set G containing y,  $A \cap G \neq \phi$ . Since U is  $\Lambda_r$ -open and  $y \in U$ ,  $A \cap U \neq \phi$  and hence  $x \in \Lambda_r - cl(A)$ . Hence  $\Lambda_r - cl(A) = \Lambda_r - cl(\Lambda_r)$ . By Property 3.5,  $\Lambda_r - cl(A)$  is  $\Lambda_r$ -closed.

#### Remark 3.7

- (1) X and  $\phi$  are both  $\Lambda_r$ -open and  $\Lambda_r$ -closed.
- (2) By using the Properties 3.3 and 3.6,  $\Lambda_r cl(A)$  is the smallest  $\Lambda_r closed$  set containing A.

**Property 3.8** If  $A_k$  is  $\Lambda_r$ -closed for each  $k \in I$ , then  $\bigcap_{k \in I} A_k$  is  $\Lambda_r$ -closed. Proof.

Let  $A = \bigcap_{k \in I} A_k$  and  $x \in \Lambda_r - cl(A)$ . Then x is a  $\Lambda_r$ -cluster point of A. Hence for every  $\Lambda_r$ -open set U containing x,  $A \cap U \neq \phi$ . That implies  $(\bigcap_{k \in I} A_k) \cap U \neq \phi$ . That implies  $A_k \cap U \neq \phi$  for each  $k \in I$ . If  $x \notin A$ , then for some  $i \in I$ ,  $x \notin A_i$ . Since  $A_i$  is  $\Lambda_r$ -closed,  $A_i = \Lambda_r - cl(A_i)$  and hence  $x \notin \Lambda_r - cl(A_i)$ . Therefore x is not a  $\Lambda_r$ -cluster point of  $A_i$ . So there exists a  $\Lambda_r$ -open set V containing x such that  $A_i \cap V = \phi$ . By this contradiction,  $x \in A$ . Therefore  $\Lambda_r - cl(A) \subset A$  and hence  $A = \Lambda_r - cl(A)$ . By using the Property 3.5, A is  $\Lambda_r$ -closed. That is,  $\bigcap_{k \in I} A_k$  is  $\Lambda_r$ -closed.

**Remark 3.9** The union of  $\Lambda_r$ -closed sets need not be  $\Lambda_r$ -closed. For example, let X = {a,b,c,d} and  $\tau = \{X, \phi\{a\}, \{b\}, \{a,b\}\}$ . Then {a} and {b} are  $\Lambda_r$ -closed but {a}  $\cup$  {b} = {a,b} is not a  $\Lambda_r$ -closed set.

**Property 3.10** If  $A_k$  is  $\Lambda_r$ -open for each  $k \in I$ , then  $\bigcup_{k \in I} A_k$  is  $\Lambda_r$ -open.

**Definition 3.11** Let  $(X, \tau)$  be a topological space,  $A \subset X$ . Then  $\Lambda_r$ -kernel of A is defined by  $\Lambda_r$ -ker $(A) = \bigcap \{G/G \in \Lambda_r O(X, \tau) \text{ and } A \subset G \}$ .

Let  $(X,\tau)$  be a topological space and A,B be subsets of X. Let  $x, y \in X$ . Then we have the following lemmas.

**Lemma 3.12**  $A \subset \Lambda_r - ker(A)$ 

Proof. Let  $x \notin \Lambda_r$ -ker(A). Then there exists  $V \in \Lambda_r O(X, \tau)$  such that  $A \subset V$  and  $x \notin V$  and hence  $x \notin A$ .

**Lemma 3.13** If  $A \subset B$ , then  $\Lambda_r - \ker(A) \subset \Lambda_r - \ker(B)$ .

Proof. Let  $x \notin \Lambda_r$  - ker(B). Then there exists  $G \in \Lambda_r O(X, \tau)$  such that  $B \subset G$  and  $x \notin G$ . Since  $A \subset B$ ,  $A \subset G$  and hence  $x \notin \Lambda_r$  - ker(A).

**Lemma 3.14**  $\Lambda_r - \ker(A) = \Lambda_r - \ker(\Lambda_r - \ker(A)).$ 

Proof. Let  $x \in \Lambda_r$  - ker( $\Lambda_r$  - ker( $\Lambda$ )). Then for every  $\Lambda_r$  -open set  $G \supset \Lambda_r$  - ker(A),  $x \in G$ . Since  $A \subset \Lambda_r$  - ker(A), for every  $\Lambda_r$  - open set  $G \supset A$ ,  $x \in G$ .

Hence  $x \in \Lambda_r - \ker(A)$ . Therefore  $\Lambda_r - \ker(\Lambda_r - \ker(A)) \subset \Lambda_r - \ker(A)$ . Also  $\Lambda_r - \ker(A) \subset \Lambda_r - \ker(\Lambda_r - \ker(A))$ . Hence  $\Lambda_r - \ker(A) = \Lambda_r - \ker(\Lambda_r - \ker(A))$ .

**Lemma 3.15**  $y \in \Lambda_r - ker(\{x\})$  if  $x \in \Lambda_r - cl(\{y\})$ .

Proof.  $y \notin \Lambda_r - \ker(\{x\}) \Leftrightarrow \exists a \ \Lambda_r$ -open set  $V \supset \{x\}$  such that  $y \notin V \Leftrightarrow \exists a \ \Lambda_r$ -open set  $V \supset \{x\}$  such that  $\{y\} \cap V = \phi \Leftrightarrow x$  is not a  $\Lambda_r$ -cluster point of  $\{y\} \Leftrightarrow x \notin \Lambda_r$ -cl( $\{y\}$ ).

**Lemma 3.16**  $\Lambda_r - \ker(A) = \{x / \Lambda_r - \operatorname{cl}(\{x\}) \cap A \neq \phi\}.$ 

Proof. Let  $x \in \Lambda_r \operatorname{-ker}(A)$ . Then for every  $\Lambda_r$ -open set  $G \supset A, x \in G$ . Suppose  $\Lambda_r \operatorname{-cl}(\{x\}) \cap A \neq \phi$ . Then  $A \subset X \operatorname{-}(\Lambda_r \operatorname{-cl}(\{x\}))$ . Take  $V = X \operatorname{-}(\Lambda_r \operatorname{-cl}(\{x\}))$ . Then V is a  $\Lambda_r$ -open set containing A and  $x \notin V$ . By this contradiction, we get  $\Lambda_r \operatorname{-cl}(\{x\}) \cap A \neq \phi$ . Conversely, let  $x \in X$  such that  $\Lambda_r \operatorname{-cl}(\{x\}) \cap A \neq \phi$ . Let  $y \in \Lambda_r \operatorname{-cl}(\{x\}) \cap A$ . Then y is a  $\Lambda_r$ -cluster point of  $\{x\}$ . Therefore for every  $\Lambda_r$ -open set U containing y,  $U \cap \{x\} \neq \phi$  and hence  $x \in U$ . If  $x \notin \Lambda_r \operatorname{-ker}(A)$ , then  $\exists$  a  $\Lambda_r$ -open set  $V \supset A$  such that  $x \notin V$ . Since  $y \in A$ , V is a  $\Lambda_r$ -open set containing y and  $x \notin V$ . By this contradiction, we get  $x \in \Lambda_r \operatorname{-ker}(A)$ .

# $\Lambda_r - T_k$ SPACES

**Definition 4.1** (X, $\tau$ ) is  $\Lambda_r - T_0$  if for each pair of distinct points x, y of X,  $\exists a \Lambda_r$ -open set containing one of the points but not the other.

**Theorem 4.2**  $(X,\tau)$  is  $\Lambda_r - T_0$  if for each pair of distinct points x, y of X,  $\Lambda_r - cl(\{x\}) \neq \Lambda_r - cl(\{y\}).$ 

Proof.

Necessity: Let  $(X, \tau)$  be a  $\Lambda_r - T_0$  space. Let  $x, y \in X$  such that  $x \neq y$ . Then  $\exists$  a  $\Lambda_r$ -open set V containing one of the points but not the other, say  $x \in V$  and  $y \notin V$ . Then  $V^c$  is a  $\Lambda_r$ -closed set containing y but not x. But  $\Lambda_r - cl(\{y\})$  is the smallest  $\Lambda_r$ -closed set containing y. Therefore  $\Lambda_r - cl(\{y\}) \subset V^c$  and hence  $x \notin \Lambda_r - cl(\{y\})$ . Thus  $\Lambda_r - cl(\{x\}) \neq \Lambda_r - cl(\{y\})$ .

Sufficiency: Suppose  $x, y \in X$ ,  $x \neq y$  and  $\Lambda_r - cl(\{x\}) \neq \Lambda_r - cl(\{y\})$ . Let  $z \in X$  such that  $z \in \Lambda_r - cl(\{x\})$  but  $z \notin \Lambda_r - cl(\{y\})$ . If  $x \in \Lambda_r - cl(\{y\})$ , then  $\Lambda_r - cl(\{x\}) \subset \Lambda_r - cl(\{y\})$  and hence  $z \in \Lambda_r - cl(\{y\})$ . This is a contradiction. Therefore  $x \notin \Lambda_r - cl(\{y\})$ . That implies  $x \in (\Lambda_r - cl(\{y\}))^c$ . Therefore  $(\Lambda_r - cl(\{y\}))^c$  is a  $\Lambda_r$ -open set containing x but not y. Hence  $(X, \tau)$  is  $\Lambda_r - T_0$ .

**Definition 4.3**  $(X,\tau)$  is  $\Lambda_r - T_1$  if for any pair of distinct points x, y of X, there is a  $\Lambda_r$ -open set U in X such that  $x \in U$  and  $y \notin U$  and there is a  $\Lambda_r$ -open set V in X such that  $y \in U$  and  $x \notin V$ .

**Remark 4.4** Every  $\Lambda_r - T_1$  space is  $\Lambda_r - T_0$  space. But the converse need not be true. For example, let  $X = \{a, b, c\}$  and  $\tau = \{X, \phi, \{a\}, \{a, b\}\}$ . Then  $(X, \tau)$  is  $\Lambda_r - T_0$  space but not  $\Lambda_r - T_1$  space.

**Theorem 4.5** For a space  $(X, \tau)$ , the following are equivalent

- (1)  $(\mathbf{X}, \tau)$  is  $\Lambda_r \mathbf{T}_1$
- (2) For every  $x \in X$ ,  $\{x\} = \Lambda_r cl(\{x\})$
- (3) For each  $x \in X$ , the intersection of all  $\Lambda_r$ -open sets containing x is  $\{x\}$ .

Proof.

 $(1) \rightarrow (2)$ : Suppose  $y \neq x$  in X. Then  $\exists a \Lambda_r$ -open set V such that  $x \in V$ and  $y \notin V$ . If  $x \in \Lambda_r - cl(\{y\})$ , then x is a  $\Lambda_r$ -cluster point of  $\{y\}$ . That implies for every  $\Lambda_r$ -open set U containing  $x, \{y\} \cap U \neq \phi$ . Here V is a  $\Lambda_r$ -open set containing x. Therefore  $\{y\} \cap V \neq \phi$  implies  $y \in V$ . This is a contradiction. Thus  $x \notin \Lambda_r - cl(\{y\})$ . Hence for a point  $x, y \notin \Lambda_r - cl(\{x\})$ . Thus  $\{x\} = \Lambda_r - cl(\{x\})$ .

 $(2) \to (3): x \in \Lambda_{r} - cl(\{y\}) \Leftrightarrow x \text{ is a } \Lambda_{r} \text{-cluster point of } \{x\} \Leftrightarrow \text{ for every } \Lambda_{r} \text{-open set } U \text{ containing } x, \{x\} \cap U \neq \phi \Leftrightarrow x \in \cap \{G/G \in \Lambda_{r} O(X, \tau) \text{ and } \{x\} \subset G\}.$   $\{x\} \subset G\}. \text{ Therefore } \Lambda_{r} - cl(\{x\}) = \cap \{G/G \in \Lambda_{r} O(X, \tau) \text{ and } \{x\} \subset G\}.$  $(2), \{x\} = \cap \{G/G \in \Lambda_{r} O(X, \tau) \text{ and } \{x\} \subset G\}.$ 

 $(3) \rightarrow (1)$ : Let  $x \neq y$  in X. By (3), and  $\{\{x\} \subset G\}$ . Hence  $\exists$  one  $\Lambda_r$ -open set V containing x but not y. Similarly,  $\exists$  one  $\Lambda_r$ -open set U containing y but not x. Hence  $(X, \tau)$  is  $\Lambda_r - T_1$ .

**Theorem 4.6** A space  $(X, \tau)$  is  $\Lambda_r - T_1$  if the singletons are  $\Lambda_r$ -closed sets.

Proof. Suppose  $(X,\tau)$  is  $\Lambda_r - T_1$ . Let  $x \in X$  and  $y \in \{x\}^c$ . Then  $x \neq y$  and so  $\exists$  a  $\Lambda_r$ -open set  $U_y$  such that  $y \in U_y$  but  $x \notin U_y$ . Therefore  $y \in U_y \subset \{x\}^c$ . That is,  $\{x\}^c = \bigcup \{U_y/y \in \{x\}^c$  is  $\Lambda_r$ -open. Hence  $\{x\}$  is  $\Lambda_r$ -closed. Conversely, let  $x, y \in X$  with  $x \neq y$ . Then  $y \in \{x\}^c$  and  $\{x\}^c$  is a  $\Lambda_r$ -open set containing y but not x. Similarly,  $\{y\}^c$  is a  $\Lambda_r$ -open set containing x but not y. Hence  $(X,\tau)$  is a  $\Lambda_r$ -T<sub>1</sub> space.

**Definition 4.7**  $(X, \tau)$  is  $\Lambda_r - T_2$  if for each pair of distinct points x and y in X,  $\exists a \Lambda_r$ -open set U and a  $\Lambda_r$ -open set V in X such that  $x \in U$ ,  $y \in V$  and  $U \cap V = \phi$ .

M.J.Jeyanthi, Adem Kilicman, S.Pious Missier & P.Thangavelu

**Remark 4.8** Every  $\Lambda_r - T_2$  space is  $\Lambda_r - T_1$ .

**Theorem 4.9** For a topological space  $(X, \tau)$ , the following are equivalent:

- (1)  $(\mathbf{X}, \tau)$  is  $\Lambda_r T_2$
- (2) If  $x \in X$ , then for each  $y \neq x$ , there is a  $\Lambda_r$ -open set U containing x such that  $y \notin \Lambda_r$ -cl(U)
- (3) For each  $x \in X$ ,  $\{x\} = \bigcap \{\Lambda_r cl(U)/U \text{ is a } \Lambda_r \text{ -open set containing } x\}$

Proof.

 $\begin{array}{l} (1) \rightarrow (2) \colon \text{Let } x \in X. \text{ Then for each } y \neq x, \ \exists \ \Lambda_r \text{ -open sets } A \text{ and } B \text{ such } \\ \text{that } x \in A, \ y \in B \text{ and } A \cap B = \phi. \text{ Then } x \in A \subset X \text{ - } B. \text{ Take } X \text{ - } B = F. \\ \text{Then } F \text{ is } \Lambda_r \text{ -closed, } A \subset F \text{ and } y \notin F. \text{ That implies } y \notin \cap \{F/F \text{ is } \Lambda_r \text{ -closed and } A \subset F\} = \Lambda_r \text{ -cl}(A). \end{array}$ 

(2)  $\rightarrow$  (1): Let  $x, y \in X$  and  $x \neq y$ . By (2),  $\exists a \Lambda_r$ -open set U containing x such that  $y \notin \Lambda_r - cl(U)$ . Therefore  $y \in X - (\Lambda_r - cl(U))$ ,  $X - (\Lambda_r - cl(U))$  is  $\Lambda_r$ -open and  $x \notin X - (\Lambda_r - cl(U))$ . Also  $U \cap X - (\Lambda_r - cl(U)) = \phi$ . Hence  $(X, \tau)$  is  $\Lambda_r - T_2$ .

 $(2) \leftrightarrow (1)$ : It is obvious.

#### ACKNOWLEDGEMENT

The authors gratefully acknowledge that this research was partially supported by the Ministry of Science, Technology and Innovations (MOSTI), Malaysia under the e-Science Grant 06-01-04-SF0115. The authors also wish to thank the referees for their constructive comments and suggestions.

#### REFERENCES

Athisayaponmani, S. and Thivagar, M. Lellis. 2007. Another form of separation axioms. *Methods of Functional Analysis and Topology*, 13(4): 380-385.

- Caldas, M. and Dontchev, J. G. 2000.  $\Lambda_s$  -sets and  $V_s$  -sets. *Mem. Fac. Sci. Kochi Univ. Math.*, **21**: 21-30.
- Caldas, M., Ganster, M., Jafari, S. and Noiri, T. 2004. On Λ<sub>p</sub>-sets and functions. *Mem.Fac.Sci.Kochi Univ.(Math.)*, 25: 1-8.
- Caldas, M. and Jafari, S. 2003. On some low separation axioms in topological space. *Houston Journal of Math.*, **29**: 93-104.
- Fawakhreh, A. J. and Kilicman, A. 2002. Mappings and some decompositions of continuity on nearly Lindelof spaces. Acta Math. Hungar., 97(3): 199-206.
- Fawakhreh, A. J. and Kilicman, A. 2004. Some Semiregular properties and generalizations of Lindelof Spaces, *Matematicki Vesnik*, 56(3-4), 77-80.
- Fawakhreh, A. J. and Kilicman, A. 2006. Mappings and decompositions of continuity on almost Lindelof spaces. *Int. J. Math. Math. Sci.*, Art. ID 98760: 7 pages.
- Ganster, M., Jafari, S. and Noiri, T. 2002. On pre- $\Lambda$ -sets and pre-V-sets. *Acta Math. Hungar.*, **95**(4): 337-343.
- Jain, R. C. 1980. *The role of regularly open sets in general topology spaces*, Ph.D. Thesis, Meerut Univ. Inst. Adv. Stud. Meerut, India.
- Kar, A. and Bhattacharyya, Paritosh. 1990. Some weak separation axioms, Bull. Call. Math. Soc., 82: 415-422.
- Kilicman, A. and Salleh, Z. 2007a. On pairwise Lindelof bitopological spaces. *Topology Appl.*, **154**(8):1600-1607.
- Kilicman, A. and Salleh, Z. 2007b. Pairwise almost Lindelof bitopological spaces. *Malaysian Journal of Mathematical Sciences*, **1**(2): 227-238.
- Kilicman, A. and Salleh, Z. 2008. Pairwise weakly regular-Lindelof spaces. *Abstr. Appl. Anal.*, Art. ID 184243: 13 pages.
- Kilicman, A. and Salleh, Z. 2009. A note on pairwise continuous mappings and bitopological spaces. *Eur. J. Pure Appl. Math.*, **2**(3): 325-337.

M.J.Jeyanthi, Adem Kilicman, S.Pious Missier & P.Thangavelu

Nour, T. M. 1995. A Note on five separation axioms in bitopological spaces. *Indian J. Pure Appl. Math.*, **26**(7): 669-674.