# Determination of (0,2)-regular sets in graphs 

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## ABSTRACT

An eigenvalue of a graph is main iff its associated eigenspace is not orthogonal to the all-one vector $j$.
The main characteristic polynomial of a graph $G$ with $p$ main distinct eigenvalues is $m_{G}(\lambda)=\lambda^{p}-c_{0} \lambda^{p-1}-c_{1} \lambda^{p-2}-\ldots-$ $c_{p-2} \lambda-c_{p-1}$ and it has integer coefficients. If $\mathbf{G}$ has n vertices, the $n x k$ walk matrix of $G$ is $W_{k}=\left(\mathrm{j}, A_{G} \mathrm{j}, A_{G}^{2} \mathrm{j}, \ldots, A_{G}^{k-1} \mathrm{j}\right)$ and W , the walk matrix of G , is $W_{k}$ for which $\operatorname{rank}\left(W_{k}\right)=k$. The number $k$ coincides with the number of distinct main eigenvalues of $G$. In [2] it was proved that the coefficients of the main characteristic polynomial of $G$ are the solutions of $W X=A_{G}^{p}$. $\mathrm{A}(\kappa, \tau)$ regular set [3] is a subset of the vertices of a graph inducing a $\kappa$ regular subgraph such that every vertex not in the subset has $\tau$ neighbors in it. In [1], a strategy for the determination of $(0,1)$ regular sets is described and we generalize it in order to solve the problem of the determination of (0,2)-regular sets in arbitrary graphs. An algorithm for deciding whether or not a given graph has a ( 0,2 )-regular set is described. Its complexity depends on the multiplicity of $\mathbf{- 2}$ as an eigenvalue of the adjacency matrix of the graph. When such multiplicity is low, the generalization of the results in [1] assure that the algorithm is polynomial. An example of application of the algorithm to a graph for which this multiplicity is low is also presented.

Cardoso, Sciriha and Zerafa [2] introduced the parametric
vector $g_{G}(\kappa, \tau)=\sum_{j=0}^{p-1} \alpha_{j} A_{G}^{j}$ j where $\alpha_{0}, \ldots, \alpha_{p-1}$ are the solutions of system (1)

$$
\left(\begin{array}{ccccc}
\kappa-\tau & 0 & \ldots & 0 & -c_{p-1} \\
-1 & \kappa-\tau & \ldots & 0 & -c_{p-2} \\
0 & -1 & \ldots & 0 & -c_{p-3} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & \ldots & -1 & \kappa-\tau-c_{0}
\end{array}\right)\left(\begin{array}{c}
\alpha_{0} \\
\alpha_{1} \\
\vdots \\
\alpha_{p-2} \\
\alpha_{p-1}
\end{array}\right)=-\tau\left(\begin{array}{c}
1 \\
0 \\
\vdots \\
0 \\
0
\end{array}\right)
$$

Necessary and sufficient condition for the existence of a ( $\kappa, \tau$ )- regular set

Theorem [2]: If $G$ is a graph with $p$ distinct main eigenvalues, then a set of vertices $S$ is $(\kappa, \tau)$-regular iff $x_{S}=g_{G}(\kappa, \tau)+\mathrm{q}$,
with $\left\{\begin{array}{c}q=0 \Leftarrow(\kappa-\tau) \notin \sigma(G) \\ q \in \mathcal{E}(\kappa-\tau) \Leftarrow(\kappa-\tau) \in \sigma(G)\end{array}\right.$

## (0,2)-feasible tuples

Considering a set of vertices $I=\left\{i_{1}, \ldots, i_{m}\right\} \subset V(G)$, vector $x^{I}=\left(x_{i_{1}}, \ldots, x_{i_{m}}\right) \in\{0,1\}^{n}$ is $(0,2)$-feasible if it verifies:

- $\left(\exists i_{r} \in I: x_{i_{r}}=1\right) \Rightarrow\left(\forall i_{j} \in N_{G}\left(i_{r}\right) \cap I, x_{i_{j}}=0\right)$.
- $\left(\exists i_{s} \in I: N_{G}\left(i_{s}\right) \subset I\right) \Rightarrow\left(\sum_{j \in N_{G}\left[i_{s}\right]} x_{j}=2\right)$.
- $\left(\exists i_{r} \in I: x_{i_{r}}=1\right) \Rightarrow\left(\forall j \in N_{G}\left(i_{r}\right), \sum_{k \in\left(N_{G}[j] \cap I\right) \backslash\left\{i_{r}\right\}} x_{k}=1\right)$.


## ALGORITHM

Input: Graph G of order $\mathrm{n}, \mathrm{m}=$ mult(-2) and matrix Q whose columns are the vectors of a basis of $\varepsilon(-2)$.
Output: $\mathrm{A}(0,2)$-regular set of G or the conclusion that it does not exist.

1. If $g_{G}(0,2) \notin \mathbb{N}$ then $\mathbf{S T O P}$ (there is no solution) End If;
2. If $m=0$ then $\operatorname{STOP}\left(x_{S}=g_{G}(0,2)\right)$ End If;
3. If $\exists \boldsymbol{v} \in V(G): \operatorname{rank}\left(Q^{N}\right) \leq d_{G}(v)+1 \quad\left(N=N_{G}[v]\right)$ then STOP ([1]);
4. Determine $I=\left\{i_{1}, \ldots, i_{m}\right\} \subset V(G): \operatorname{rank}\left(Q^{I}\right)=m$ and set $g:=g_{G}(0,2)$;
5. Set NoSolution := TRUE;
6. Set $X:=\left\{\left(x_{i_{1}}, \ldots, x_{i_{m}}\right)\right.$ that are ( 0,2 )-feasible for G$\}$;
7. While NoSolution $\wedge X \neq \varnothing$ do
a) $\left(x_{i_{1}}, \ldots, x_{i_{m}}\right) \in X$ and set $x^{I}:=\left(x_{i_{1}}, \ldots, x_{i_{m}}\right)^{T}$;
b) Set $X:=X \backslash\left\{x^{I}\right\}$ and determine $\beta: x^{I}=g^{I}+Q^{I} \beta$;
c) If $g+Q \beta \in\{0,1\}^{n}$ then NoSolution := FALSE End If;
8. End While;
9. If NoSolution := FALSE then $x:=g+Q \beta$ else return NoSolution; 10.End.

## EXAMPLE



Fig. 1 Graph CLP
The walk matrix for CLP is $W=\left(\mathbf{j}, A_{C L P} \mathbf{j}, A_{C L P}^{2} \mathbf{j}\right)$.
The solutions of $W X=A_{C L P}^{3} \mathbf{j}$ are $\left\{\begin{array}{c}c_{2}=0 \\ c_{1}=-5 \\ c_{0}=5\end{array}\right.$
The solution of (1) is $\left\{\begin{array}{c}\alpha_{0}=1 \\ \alpha_{1}=-\frac{7}{19} \\ \alpha_{2}=\frac{1}{19}\end{array}\right.$ and so the
parametric vector $g_{C L P}(0,2)$ is equal to $\mathbf{j}-\frac{7}{19} A_{C L P}$ $\mathbf{j}+\frac{1}{19} A_{C L P}^{2} \mathbf{j}$.

Matrix $Q=\left(q_{1}, \ldots, q_{4}\right)$ has the vectors of a basis of the eigenspace associated to -2 as columns.

Looking for a vertex $v$ of degree $\geq 3$ for which the submatrix of $Q$ corresponding to $N_{C L P}[v]$ has full rank, we find that no such vertex exists.

## How to proceed?

To the closed neighbourhood of an arbitrarily chosen vertex, another vertex is added. Does the corresponding submatrix of $Q$ have full rank?
It is easily checked that the submatrix of $Q$ corresponding to $N_{C L P}[2] \cup\{4\}$ has full rank so, to proceed, compute the subvector of g corresponding to
$I=N_{C L P}[2] \cup\{4\}=\{1,2,3,4,6,7\}$.
Next, supposing that $2 \in S$ and $4 \notin S$ and solving the subsystem $x_{S}^{I}=g^{I}+\sum_{i=1}^{4} \beta_{i} q_{i}^{I}$, the values of the $\beta$ s are obtained and the solution of the complete system $x_{S}=g+\sum_{i=1}^{4} \beta_{i} q_{i}-\mathrm{a}(0,2)$-regular set of CLP - is computed:
$x_{S}=(0100100110100)^{T}$.

## REFERENCES:

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